# MOP: Efficient Low-rank PHM Mixture of Experts for Prefix-based Multi-scenario Dialogue Summarizaton

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### Abstract

 As large-scale pre-training models (PLMs) ex- pand, efficient fine-tuning becomes crucial for rapid adaptation and deployment. We pro- pose MOP, a low-rank Mixture of Experts (MOE) network for Prompt reparameteriza- tion in multi-scenario summarization based on prefix-tuning. MOP assigns specific experts for summarization in each particular scenario and incorporates an efficient knowledge decou- pling mechanism. Specifically, Expert weight matrices are learned as a sum of Kronecker products of shared global and specific local weights, capturing general and task-specific knowledge. We further decompose global weights into low-rank layer-share (LoRL) and 016 expert-share (LoRE) weights, enhancing flex- ibility and generality. By updating only the **MOP**, our method outperforms strong baselines across all scenarios on the MultiSum bench- mark, using just 2.93% of a pretrained model's parameters, demonstrating MOP's effective- ness in improving multi- scenarios learning per-formance with fewer parameters.

# **<sup>024</sup>** 1 Introduction

 Recently, the rapid development of ever-larger pre- trained language models has been pushing the boundaries of possibility across various NLP bench- [m](#page-9-1)arks[\(Brown et al.,](#page-8-0) [2020a\)](#page-8-0) [\(Wei et al.,](#page-9-0) [2021\)](#page-9-0) [\(Sanh](#page-9-1) [et al.,](#page-9-1) [2021\)](#page-9-1). For models with large-scale param- eters, deploying a separate instance of the model for each downstream task, saving and updating separate replicas of these separate model param- eters would be more time-consuming and space- consuming. Multi-task frameworks have been pro- posed to use the same model to handle multiple tasks[\(Caruana,](#page-8-1) [1998\)](#page-8-1) [\(Wang et al.,](#page-9-2) [2018\)](#page-9-2). In partic- ular, there are many scenarios in dialogue summa- rization and more business requirements are pro- posed in practical applications, such as Take-out, Taxi, etc. Therefore, it is of great significance to

explore multi-task learning for multi-scenario dia- **041** logue summarization. 042

There exist some works for multi-task learning in **043** dialogue summarization. They either rely on addi- **044** tional heavy pre-training and fine-tuning[\(Sun et al.,](#page-9-3) **045** [2022\)](#page-9-3) [\(Vu et al.,](#page-9-4) [2021\)](#page-9-4), or employ a large number **046** of task-specific non-shared structures and param- **047** eters, which cost grows linearly with the number **048** of tasks [\(Liu et al.,](#page-9-5) [2018\)](#page-9-5). Some researches have **049** demonstrated that prefix-tuning is a lightweight **050** method [\(Li and Liang,](#page-9-6) [2021a\)](#page-9-6) [\(Liu et al.,](#page-9-7) [2021\)](#page-9-7), **051** which prepends tunable prefix vectors to the keys  $052$ and values of multi-head attention at each layer, **053** and fixes the original PLM parameters. However, **054** most of them only focus on a single task and can- **055** not outperform full-parameter fine-tuning methods **056** when faced with more challenging tasks like summarization. Besides, reparameterizing the prefix **058** via simple MLP structures cannot effectively alle- **059** viate the instability of the model due to the com- **060** plexity of PLMs[\(Ding et al.,](#page-8-2) [2022\)](#page-8-2). When prefix- **061** tuning is applied in multi-task learning, task inter- **062** [f](#page-8-3)erence or negative transfer often occurs[\(Haddow](#page-8-3) **063** [and Koehn,](#page-8-3) [2012\)](#page-8-3) [\(Kokkinos,](#page-8-4) [2016\)](#page-8-4) [\(Kendall et al.,](#page-8-5) **064** [2017\)](#page-8-5) [\(Sener and Koltun,](#page-9-8) [2018\)](#page-9-8), i.e. achieving **065** good performance on one task can hinder perfor- **066** mance on another. How to improve the performance of the model on multiple tasks while reduc- **068** ing the amount of model parameters and improving **069** the efficiency of model deployment is still an open **070** problem to be explored.  $071$ 

In this paper, we aim to train a unified model **072** for multiple scenario-related dialogue summariza- **073** tion tasks from the perspective of parameter ef- **074** ficiency to reduce model deployment and main- **075** tenance. Considering cost constraints and per- **076** formance requirements, we resort to MOE to ex- **077** pand model capacity with nearly constant com- **078** [p](#page-8-6)utational overhead [\(Shazeer et al.,](#page-9-9) [2017a\)](#page-9-9) [\(Lep-](#page-8-6) **079** [ikhin et al.,](#page-8-6) [2020\)](#page-8-6). We propose **MOP**, an efficient **080** Multi-task Prompt Reparameterization Network for **081**

 multi-scenario summarization, which uses MOEs for task-aware prefix learning. Here, each expert in MOEs is considered to correspond to scenario. It is worth noting that we design an efficient knowledge decoupling mechanism, which enables the model to learn a better representation for each task.

 Inspired by[\(Mahabadi et al.,](#page-9-10) [2021\)](#page-9-10), each expert weight matrix is computed as the sum of Kronecker products[\(Zhang et al.,](#page-9-11) [2021\)](#page-9-11) between shared global weights and local weights defined per MOP. This enables MOP to aggregate common knowledge across tasks into global weights and store spe- cific information in local weights. We also intro- duce a low-rank sharing mechanism, decomposing global weights into low-rank layer-share (LoRL) and expert-share (LoRE) weights, enhancing flexi- bility in capturing general information. LoRL cap- tures information common to all layers of the same expert, while LoRE obtains information shared by all experts at the same layer. This mechanism reduces shared parameters, improving efficiency. Consequently, MOP achieves paramter complexity 104 of  $\mathcal{O}(d + d_{mid})$  instead of  $\mathcal{O}(dd_{mid})$  for regular prefix-tuning, where the reparameterization matrix 106 is of size  $d \times d_{mid}$ .

 We evaluate our approach on MultiSum, a large- scale customer-service dialogue summarization datasets. Experimental results demonstrate that **our MOP** is significantly better than all methods. In particular, it can go far beyond the performance of the strongest fine-tuning baseline. We further explore the effectiveness of the MoE network and the sharing mechanism in the low-rank decomposi- tion. Additionally, we analyze the trainable param- eter scale to verify the efficiency. To sum up, the contributions of this paper are three folds:(1) To the best of our knowledge, we are the first to pro- pose a PHM based mixture of experts for prompt reparameterization to explore multi-scenario sum- marization. (2) We decompose the share weights into low-rank layer-share weights and expert-share weights, which enable flexible and fine-grained sharing by capturing layer-share information and expert-share knowledge separately. (3) A plenty of experiments and qualitative analysis are conducted to prove the effectiveness of our methods.

# **<sup>128</sup>** 2 METHODOLOGY

**129** In this section, we present MOP, a low-rank MOE **130** network for scenario-conditioned prompt reparam-**131** eterization. Instead of routing mechanisms, we assign experts to handle each scenario, which ef- **132** fectively avoids the problem of load imbalance. **133** Furthermore, we adopt PHM to reduce redundant 134 parameters and design an effective low-rank shar- **135** ing mechanism to achieve the sharing of common **136** knowledge among different experts. **137**

# 2.1 Sparse Mixture of Experts **138**

To increase model capacity without a proportional **139** increase in computational costs, we use the SMoE **140** to explicitly model the scenario relationships and **141** [l](#page-9-9)earn features relevant to specific scenario[\(Shazeer](#page-9-9) **142** [et al.,](#page-9-9) [2017a\)](#page-9-9). The original expert network is imple- **143** mented as stacked feed-forward networks(FFN): **144**

$$
f_k(\mathbf{h}) = \sigma(\mathbf{h} \mathbf{W}_{\mathbf{down}}) \mathbf{W}_{\mathbf{up}} \tag{1}
$$

where  $W_{down} \in \mathbb{R}^{d \times d_{mid}}$  is the down-project 146 mapping and  $W_{up} \in \mathbb{R}^{n \times d}$  is the up-project map-<br>147 ping, σ means ReLU activation function. **148**

**PHM Layer** To reduce computation overhead 149 with almost no damage to model performance, we **150** substitute the parameterized hypercomplex mul- **151** tiplication (PHM) layer [\(Mahabadi et al.,](#page-9-10) [2021\)](#page-9-10) **152** [\(Zhang et al.,](#page-9-11) [2021\)](#page-9-11) , which is on the basis of Kro- **153** necker product, for linear FFN layer in SMoE. To **154** the best of our knowledge, we are the first to ex- **155** ploit PHM layers for efficient fine-tuning of SMoE **156** networks. Assume that  $d$  and  $d_{mid}$  are both divis-  $157$ ible by self-defined hyperparameter  $p \in \mathbb{Z}_{>0}$  and 158  $q \in \mathbb{Z}_{>0}$  respectively.  $W_{down}$  and  $W_{up}$  of PHM 159 experts can be computed as the sum of Kronecker **160** product as follows: 161

$$
W_{down} = \sum_{i=1}^{p} A_i \otimes B_i
$$
  

$$
W_{up} = \sum_{i=1}^{q} C_i \otimes D_i
$$
 (2) 162

**163**

where 
$$
\mathbf{A_i} \in \mathbb{R}^{p \times p}
$$
,  $\mathbf{B_i} \in \mathbb{R}^{\frac{d}{p} \times \frac{d_{mid}}{p}}$ ,  $\mathbf{C_i} \in \mathbb{R}^{q \times q}$  163  
and  $\mathbf{D_i} \in \mathbb{R}^{\frac{d_{mid}}{q} \times \frac{d}{q}}$ .

### 2.2 Low-Rank Sharing Mechanism **165**

Considering that each expert needs to deal with **166** the shared features between different tasks and the **167** features specific to each task, we define  $A_i$  and  $C_i$  168 as global matrices, which aggregate shared infor- **169** mation to reflect task commonality, and  $B_i$  and  $D_i$  **170** are as local matrices, which serve to capture spe- **171** cific task information. Because low-dimensional **172** reparameterization can significantly improve the **173**

<span id="page-2-1"></span>

Figure 1: Overiew of MOP Reparameterization Network. The reparameterized prefixes are prepended to selfattention modules of the decoder.

 stability of prefix-tuning, we propose to decom-**pose central matrices, e.g.,**  $A_i \in \mathbb{R}^{\frac{d}{p} \times \frac{d_{mid}}{p}}$  is decomposed into two low-rank weights  $l_i \in \mathbb{R}^{\frac{d}{p} \times r}$ **176** 177 and  $e_i \in \mathbb{R}^{r \times \frac{d_{mid}}{p}}$ , where r is the rank of the ma-178 trix. We name  $l_i$  as LoRL (Low-rank layer-share) weight, which is shared by all layers of the same ex-**perts.** The  $e_i$  is named as LoRE (low-rank expert- share) weight, which is shared by all experts of the same layer. This low-rank sharing mechanism can effectively reduce the sharing of parameters between different experts, which can also greatly improve the efficiency of the model.

 Based on the above formulation, we introduce MOP, which is a low-rank mixture of experts based on PHM, the weights of experts in MOP can be defined as:

$$
W_{down} = \sum_{i=1}^p A_i \otimes B_i = \sum_{i=1}^p (l_i e_i^T) \otimes B_i
$$
  

$$
W_{up} = \sum_{i=1}^q C_i \otimes D_i = \sum_{i=1}^q (l_i e_i^T) \otimes D_i
$$
  

$$
\xrightarrow[\qquad \qquad 190 \qquad \qquad (3)
$$

# **191** 2.3 MOE for Prompt reparameterization

 Prefix-tuning prepends tunable prefix vectors to the parameters of multi-head attention (i.e. keys and values) at each Transformer layer. In the original setting, the prefix vectors  $P^{l_i}$  of the *i*-th attention head in the l-th layer are reparameterized by a twolayer feed-forward network: **197**

<span id="page-2-0"></span>
$$
P^{l_i} = MLP^{l_i}(X') = W^{l_i}_{up} \phi(W^{l_i}_{down}(X')) \quad (4)
$$

where  $W_{down} \in \mathbb{R}^{d \times d_{mid}}$ ,  $W_{up} \in \mathbb{R}^{d_{mid} \times d_h}$ , and 199  $X' \in \mathbb{R}^{n \times d}$  is the randomly initialized embedding 200 matrix of the prefix  $X$ . The prefixes are trans-  $201$ formed two times by Eq. [4](#page-2-0) to get the expanded **202** key  $P_K^{l_i}$  and expanded value  $P_V^{l_i}$ . Then, they are **203** concatenated with the original key and value, and **204** the output of the attention layer is computed as: **205**

$$
Ai = Attn(Qli, concat(Pli, Kli), concat(Pli, Vli))
$$
\n(5)

(5) **206**

where  $Q^{l_i} \in \mathbb{R}^{m \times d_h}, K^{l_i} \in \mathbb{R}^{m \times d_h}, V^{l_i} \in$  207  $\mathbb{R}^{m \times d_h}$  are original query, key and value, Fig [2\(b\)](#page-3-0) 208 shows the details. For prefix-tuning, there are three 209 types of attention: the self-attention of encoder, the **210** self-attention of decoder, and the cross-attention of **211** decoder. According to the experiments, we choose **212** to use the MOP instead of MLP in the self-attention **213** of decoder. While for the remaining two attentions, **214** we still use the original MLP network. In this **215** way, the model can perform multi-task learning **216** in a parameter-efficient form. Figure [1](#page-2-1) shows our **217** overall model framework. **218**

# 2.4 Training Objective **219**

Given input dialogue context X, parameters of 220 PLM  $\theta$ , trainable prefix parameters  $\theta_p$ , the summarization optimization objective is to minimize **222** the negative log-likelihood of generating the target **223**



Figure 2: MOP frameweork:(a) in MOP,  $W_{down}$  and  $W_{up}$  are used to do down projection and up projection, respectively. They can be calculated as a sum of Kronecker products of a series of global matrices and local matrices. The global matrix can be divided into two rank-one weights LoRE(low-rank expert-share) and LoRL(low-rank layer-share), LoRE is shared by all experts at the same level, and LoRL is shared by the same experts across levels; The local matrix is unique to each expert at each level. This mechanism allows us to achieve highly flexible adjustment. (b) in each Transformer block,  $P_K$ ,  $P_V$  generated via MOP are prepended to the original key K and value V for the query Q to attend to.

$$
summary Y = \{y_i, \cdots, y_{|Y|}\}:
$$

225 
$$
L_{nll}(\theta, \theta_p) = \sum_{i}^{|Y|} log \mathbb{P}(y_0 | X, y_1, \dots, y_{i-1}) \quad (6)
$$

226 In training stage, we keep  $\theta$  frozen and only opti-227 mize  $\theta_n$ .

# **<sup>228</sup>** 3 EXPERIMENTAL SETUP

# **229** 3.1 Dataset

 We collect our dialogue-summary datasets, Mul- tiSum, from the logs on a large-scale customer service corpus. The dialogues are between users and customer service agents, and the summaries are written by agents. To perform multi-scenario learning, we choose 5 different business scenar- ios, including *Taxi*, *Ticket*, *E-Commerce*, *Take-out*, *Food*. The statistics of the data are given in Table [1.](#page-3-1) We divide the sizes of training, valid and test set to 8:1:1. To the best of our knowledge, MultiSum is the first to explore multi-task/domain summariza- tion generation. We will release our data, code and pre-trained models after blind review.

# **243** 3.2 Backbone and Baselines

 Considering the deployment cost and model per- formance, we choose the Chinese generative pre- training language model T5-pegasus-base as the backbone network, which takes mT5 as the in- frastructure and initial weight and pre-trains in a way similar to PEGASUS. Based on the public

<span id="page-3-1"></span><span id="page-3-0"></span>

<b>Domains</b>	<b>Size</b>	Dialog.len	Summ.len
<b>Taxi</b>	31,258	299.49	27.79
<b>Ticket</b>	10,869	204.64	22.60
<b>E-Commerce</b>	35,795	255.91	16.47
<b>Take-out</b>	28,707	189.925	42.37
Food	20,824	241.30	27.02

Table 1: Details of MultiSum. "Dialog.len" denotes the average length of dialogues, "Summ.len" denotes the average length of summaries.

available pre-trained checkpoints, we conducted **250** experiments to compare MOP with several gen- **251** eral multi-task learning baselines and some novel **252** parameter-efficient proposals: **253**

MTL-vanilla: The standard practice of full- **254** parameter fine-tuning T5-pegasus-base for multi- **255** task summarization, which we refer to as MTL- **256** vanilla[\(Raffel et al.,](#page-9-12) [2019\)](#page-9-12). **257**

MTL: On the basis of the MTL-vanilla, we **258** have designed templates manually, which are **259** the natural language descriptions of conversation **260** scenes[\(Brown et al.,](#page-8-7) [2020b\)](#page-8-7). For example, for the **261** dialogue in the Take-out scenario, we designed **262** the template as "The conversation comes from the **263** Take-out business". Similar to MTL-vanilla, we **264** perform full-parameter fine-tuning on the Multi- **265** Sum dataset and we refer this kind of multi-task **266** learning model as MTL. **267**

prefix-tuning: We take T5-pegasus-base **268** as the backbone network and fine-tune the **269** model for multi-task learning under prefix-tuning **270**

 paradigm[\(Li and Liang,](#page-9-6) [2021a\)](#page-9-6), which only tunes a small number of prefix vectors while keeping the PLM frozen during training stage. The prefix vec- tors are initialized in random and all samples share the prefix vectors with a length of 40.

 MTL-prompt: Prompt-tuning is proposed by Lester et al[\(Lester et al.,](#page-8-8) [2021\)](#page-8-8). , which prepends a sequence of soft prompt tokens to the input and only tunes the soft prompt for adaptation. We set the prompt length to 40, which is shared by all samples for multi-domain learning.

 **HyperFormer++:** We compare our method with HyperFormer++ [\(Karimi Mahabadi et al.,](#page-8-9) [2021\)](#page-8-9), the state-of-the-art adapter-based method for multi- task learning, which use HyperNetwork to generate adapters for each task and add them after the feed-forward modules.[\(Houlsby et al.,](#page-8-10) [2019\)](#page-8-10)

 HyperPrefix: HyperPrefix is a fresh approach proposed recently[\(Zhang et al.,](#page-9-13) [2022\)](#page-9-13). On the ba- sis of prefix-tuning and hypernetwork, it uses a shared hypernetwork that takes trainable hyper- embeddings as input and outputs weights as prefix vectors. Since the position and task information have been considered in the embedding stage, this method can conduct multi-domain learning in a lightweight way.

 We use the ROUGE metrics[\(Li and Liang,](#page-9-14) [2021b\)](#page-9-14) to quantitatively evaluate the performance of models. ROUGE (Recall-Oriented Understudy for Gisting Evaluation) evaluates the n-gram over- lap in the generated summary against the reference. We report F-1 scores of ROUGE-1 (R-1), ROUGE-2 (R-2) and ROUGE-L (R-L) on MultiSum.

### **304** 3.3 Implementation Details

 Our models are built on T5-pegasus-base (220M) and use jieba as the tokenizer to tokenize the input dialogue. During prefix reparameterization, we 308 set  $d = 768$ ,  $d_{mid} = 128$  for all the experiments. [F](#page-8-11)or MOE network, following the recipe from [\(Chi](#page-8-11) [et al.,](#page-8-11) [2022\)](#page-8-11), we set the number of experts to 5. For model training, we set maximum number of epochs as 50 and use early stopping to prevent over-fitting. For multi-task learning, we combine the training data of all tasks with temperature mixing (we set the temperature as 2). We save a checkpoint every 1000 steps and report results on a single checkpoint with the highest average validation performance across all tasks. Appendix will provide the detailed hyperparameters for MOP training.

# 3.4 Main Results **320**

Table [2](#page-5-0) presents the results of our experiments **321** on MultiSum, where we treat each business sce- **322** nario as a separate task and train a joint model for **323** multi-task learning. We compare our approach with **324** some strong full-parameter fine-tuning summariza- **325** tion models and some parameter-efficient baselines, **326** including HyperFormer++ and HyperPrefix. Our **327** results show that MTL with additional auxiliary in- **328** formation achieves higher ROUGE scores on most **329** scenarios compared to MTL-vanilla, at the cost of **330** increased parameter quantity. Prefix-tuning and **331** MTL-prompt perform worse than full-parameter **332** fine-tuning, due to the lack of effective strategies **333** for adapting to complex multi-scenario summa- **334** rization and the difficulty of achieving good per- **335** formance with limited parameters. Recent works **336** have attempted to conduct multi-task learning in  $337$ a parameter-effective way, such as combining hy- **338** pernet with prefix-tuning or adapter, which have **339** shown promising results. Compared to the best  $340$ performing hyper-based model, our model im- **341** proves by 7.73%, 10.57%, 8.27% for *Ticket* do- **342** main, 5.13%, 8.28%, 5.45% for *Food* domain, **343** 3.49%, 4.38%, 3.62% for *Taxi* domain, 2.88%, **344** 3.87%, 3.01% for *Take-out* domain and 3.69%, **345** 4.89%, 4.20% for *E-Commerce* domain. Relative **346** to MTL-vanilla , our model improves by 9.28%, **347** 13.28%, 9.89% for *Ticket* domain, 8.67%, 16.55%, **348** 8.50% for *Food* domain, 1.82%, 3.66%, 1.85% for **349** *Taxi* domain, 2.89%, 5.29%, 1.88% for *Take-out* do- **350** main and 6.24%, 8.12%, 5.48% for *E-Commerce* **351** domain. In addition, our MOP still has higher **352** ROUGE scores than strong baseline MTL in all **353** scenarios . All results suggest that the performance **354** of our model reaches new state-of-the-art. **355**

# 4 QUALITATIVE ANALYSIS **<sup>356</sup>**

We design a series of experiments to verify the **357** effectiveness of our proposed framework compared **358** to existing methods. **359**

# 4.1 Effect of Sparse Mixture of Experts **360**

To shed light on how the MOP benefits multi- **361** scenario dialogue summarization, we peek into the **362** MOP by visualizing the generated prefix vectors. **363** Here, the prefix vectors are mapped to the 2D pro- **364** jections via PCA. We use the same 5000 examples **365** which are randomly selected from MultiSum  $D_{dev}$ . **366** Fig [3](#page-5-1) shows the visualization of the prefix vec- **367** tors parameterized through MOP and Fig [4](#page-5-2) is the **368**

<span id="page-5-0"></span>

Models	Taxi		Ticket		F-Commerce		Take-out		Food		Average							
	$R-1$	$R-2$	$R-I$ .	$R-1$	$R-2$	R-L	$R-1$	$R-2$	$R-L$	$R-1$	$R-2$	$R-L$	$R-1$	$R-2$	R-L	$R-1$	$R-2$	$R-L$
MTL-vanilla	52.61	38.36	49.14		31 .16	39.79	41.75	25.64	38.99	36.25	23.50	34.69	48.05	32.29	46.29	43.98	30.19	41.78
<b>MTL</b>	51.83	38.72	48.49	42.99	33.92	41.64	43.10	26.86	39.77	36.03	24.56	34.60	51.14	36.30	49.04	45.02	32.07	42.71
prompt-tuning	45.49	31.67	42.37	30.59	20.25	29.29	36.38	20.69	33.55	32.19	20.63	30.85	37.84	24.70	36.60	36.50	23.59	34.53
prefix-tuning	50.49	36.54	47.14	40.01	30.32	38.67	42.29	25.72	38.87	34.31	22.71	32.52	48.10	32.56	46.09	43.04	29.57	40.66
HyperFormer++	51.99	37.74	48.61	41.41	30.90	39.84	42.84	26.45	39.67	36.03	23.43	34.20	49.02	33.74	46.98	44.26	30.46	41.86
<b>HyperPrefix</b>	51.78	38.09	48.30	41.82	31.92	40.38	42.77	26.43	39.47	36.25	23.82	34.31	49.66	34.76	47.63	44.46	31.00	42.02
<b>MOP</b> (ours)	53.58	39.76	50.04	45.05	35.29	43.72	44.35	27.72	41.12	37.30	24.75	35.34	52.21	37.63	50.22	46.50	33.03	44.09
w/o low-rank	52.88	39.26	49.51	43.35	33.83	42.10	42.38	26.08	39.31	38.04	25.00	36.29	50.42	35.73	48.46	45.41	31.98	43.13

Table 2: ROUGE scores of all models for multi-scenario summarization on MultiSum.

<span id="page-5-1"></span>

Figure 3: Visualization of prefix representations reparameterized by MOPs.

<span id="page-5-2"></span>

Figure 4: Visualization of prefix representations reparameterized by MLP.

 visualization of MLP. We can see that the prefix vectors generated by MOP present a more sparse distribution in space, and we can also observe the clustering. While the M LP-reparameterized pre- fix vectors still reside in a narrow subset of the entire space. Previous work [\(Su et al.,](#page-9-15) [2022\)](#page-9-15) has proved that congestion in the representation space (anisotropic distrbution) will lead to the degenera- tion of neural language models, which is because that the model devotes most attention to a small part local features while ignoring other global aux- iliary information. Conversely, MOPs disperse the prefix vectors in a relatively sparse space, which encourages the model to obtain global features, identify specific information, which is beneficial to multi-task learning. Specifically, the dispersed prefix vectors enable the model to capture a wider range of information and avoid overfitting to spe- cific tasks. Overall, the design of MOPs promotes the model's ability to achieve feature differentia-

<span id="page-5-3"></span>

Model	$R-1$	$R-2$	- R-L
<b>MOP(ours)</b>		46.50 33.03 44.09	
w/o LoRL		45.48 31.94 43.12	
w/o LoRE		45.29 31.81 42.94	
w/o LoRL & LoRE   44.75 31.45 42.41			

Table 3: Average F1 scores on 5 domains of MultiSum dataset."LoRL" denotes low-rank layer-share weights and "LoRE" means low-rank expert-share weights, "w/o LoRL and LoRE" means the removal of low-rank sharing mechanism.

tion, and improve its performance in multi-task **389** learning. 390

### 4.2 Effect of the Sharing Mechanism **391**

Table [3](#page-5-3) shows the effect of two sharing mecha- **392** nisms, i.e., LoRL and LoRE. We remove LoRL **393** and LoRE one-by-one from our model. As we can **394** see, the removal of the LoRL makes the R-1, R-2, **395** and R-L drop by 3.03, 1.09, 0.97 points, which sug- **396** gests that low-rank layer-share features can effec- **397** tively accumulate the "layer inherent knowledge" **398** by allowing all layers of the same expert to mod- **399** ify according to optimization objectives. Besides, **400** after we get rid of the LoRE, R-1, R-2, and R-3  $401$ drop by 1.21, 1.23, 1.15 points respectively, which **402** demonstrates that low-rank expert-share features **403** can effectively obtain the common features among **404** experts, so as to realize the communication across **405** experts. After removing the LoRE, the connection **406** between experts would be interrupted, our experts **407** will work in complete isolation, making it unable 408 to perform multi-scenario sharing well. Finally, **409** we remove the LoRL and LoRE at the same time, **410** which leads to 44.75%, 31.45%, and 42.41% for  $411$ R-1, R-2, and R-L. **412**

### 4.3 Robustness Analysis **413**

Prefix-tuning is sensitive to the initialization of **414** the prefix, particularly random initialization. Fig **415** [5](#page-6-0) shows the robustness of MOP, MOP w/o low- **416** rank, and prefix-tuning. We conduct experiments **417**

<span id="page-6-0"></span>

Figure 5: Average variance of F1 scores on MultiSum. "w/o low-rank" means the removal of low-rank decomposition.

<span id="page-6-1"></span>

<b>Model</b>	#Total	<b>Trained</b>	$R-L$	
	params	params		
MTL-vanilla	1.000	$100\%$	41.78	
prefix-tuning	1.027	2.734%	40.66	
prompt-tuning	1.001	0.112%	31.54	
HyperFormer++	1.023	2.320%	41.86	
<b>MOP</b> (ours)	1.025	2.514%	44.09	

Table 4: Proportion of different models' trainable parameter quantity to MTL-vanilla and their average F1 scores on MultiSum.

 on three models with three different random seeds in the same setting. The low-rank decomposition significantly enhances the robustness and stability of MOP for initialization, as evidenced by the much lower average variance of F1 scores compared to prefix-tuning and MOP without low-rank. In ad- dition, we find the average variance of MOP w/o low-rank is also slightly lower than that in prefix- tuning. We contribute this reduction of sensitivity to initialization to the strong learning ability of SMOE structure. The experiment proves that our MOP has high robustness.

### **430** 4.4 Parameter Scale of Models

 In this section, we compare the number of param- eters of MOP with other baseline multi-domain joint models. Taking the parameter quantity of T5- pegasus-base (275M) as a reference, we show the proportions of total parameter quantity and train- able parameter quantity of each method and their average ROUGE scores on the 5 domains of Mul- tiSum (*Food, Ticket, Taxi, Take-out, E-Commerce*) in Table [4.](#page-6-1) Among the parameter efficient meth- ods, prompt-tuning only tunes the continues vectors prepended before input embeddings and require the least trainable parameters, only 0.112%, but its per- formance is more than poor. prefix-tuning, Hyper-Former++ and our MOP greatly reduce the storage

space of the model with frozen PLM and a small **445** number of trainable parameters, which are applied **446** to each layer of the model and contribute to a trade- **447** off between performance and parameter quantity. **448** Additionally, our method, achieves better results **449** with fewer parameters compared with prefix-tuning  $450$ and also greatly outperforms full-parameter fine- **451** tuning model. Specifically, our MOP performs **452** 5.55% better on R-L than MTL-vanilla, using only **453** 2.51% of its parameters. In addition, we compare **454** MOP with the state-of-the-art lightweight multi- **455** task learning model HyperFormer++. Please note **456** that our model takes into account the total num- **457** ber of all experts' parameters when calculating the **458** trainable parameters. Even so, the number of pa- **459** rameters of our MOP is only slightly higher than **460** that of HyperFormer++, and the performance of **461** our method is superior. All these points show our **462** MOP has achieved a better trade-off between pa- **463** rameter efficiency and performance. **464**

#### 4.5 Impact of Prefix Length **465**

We set different lengths of continuous prefix vec-  $466$ tors to test the performance of MOP and prefix- **467** tuning on MultiSum dataset and report their aver- **468** age F1 scores. As shown in Fig [6,](#page-7-0) among these **469** setting candidates, we find 40 is the best length to  $470$ make the F1 scores of two models reach the peak.  $471$ Before reaching the optimal length, we observe that **472** the performance of the model shows a positive cor- **473** relation with the length of prefix. We attribute this **474** phenomenon to the insufficient trainable parame- **475** ters. Moreover, we find the increase of the prefix **476** length has a greater impact on improving the per- **477** formance of our MOP model, which indicates that **478** MOP has stronger learning ability. When exceed- **479** ing the optimal length, the trainable parameters **480** of the model reach saturation, at this point the in- **481** crease of length will increase burden of the model, **482** and eventually cause the decline of the model per- **483** formance, while this degradation is less obvious in **484** MOP model, which proves the robustness of our **485** model. **486**

### **4.6 Case Study 487 487**

Fi[g1](#page-10-0) in appendix [A](#page-9-16) shows two examples from Mul- **488** tiSum, For example one from *Take-out* domain, **489** summary generated by MTL omits the final solu- **490** tion, i.e. merchant refund. Prefix-tuning gener- **491** ates incorrect solution, distorts the fact that cus- **492** tomers do not accept red envelopes. These factual **493** errors significantly affect the quality of the sum- **494**

<span id="page-7-0"></span>

Figure 6: Average F1 scores of MOP and prefix-tuning with different lengths of the continuous prefix on Multi-Sum.

 mary. For example two, both summaries generated by MTL and prefix-tuning include the error mes- sage of "punishing the driver", which shows that summaries generated by these two methods fail to comprehensively cover all important information.

 Compared to the above two models, our method generates summaries with similar events and faith- ful descriptions compared with the gold summary. In example one, MOP accurately shows the "mer- chant refund" scheme, and in example 2, our method reflects the relevant content of "don't pun- ish the driver". This indicates that summaries gen- erated by MOP are more reliable, thanks to the effectiveness of MoE and efficient low-rank shar-ing mechanism.

# **<sup>510</sup>** 5 RELATED WORK

 Multi-scenario Dialogue Summarization Multi- task learning jointly optimizes models on several tasks[\(Vandenhende et al.,](#page-9-17) [2020\)](#page-9-17). By sharing repre- sentations between these tasks, we enable model to generalize better on each task. Particularly, multi- scenario summarization is a kind of multi-task learning[\(Wang et al.,](#page-9-18) [2021\)](#page-9-18), which trains model on mixed multi-scenario data to achieve good perfor- mance in each scenario. Despite efforts on design- ing models for improved joint learning[\(Kokkinos,](#page-8-4) [2016\)](#page-8-4) [\(Misra et al.,](#page-9-19) [2016\)](#page-9-19) [\(Rosenbaum et al.,](#page-9-20) [2017\)](#page-9-20), the scope of this study is rather limited. For in- stance, in the LLM area, fine-tuning large-scale language models with full parameters is still the [m](#page-9-21)ainstream paradigm.[\(Raffel et al.,](#page-9-12) [2019\)](#page-9-12) [\(Zhang](#page-9-21) [et al.,](#page-9-21) [2019\)](#page-9-21). Our work explores a lightweight ap- proach tomulti-scenario summarization, effectively addressing the issue of over-parameterization and

filling a gap in relevant research. **529**

Prompt learning for Text Generation The **530** idea of prompt learning is first proposed in **531** GPT3[\(Brown et al.,](#page-8-0) [2020a\)](#page-8-0), where it guides a large **532** language model to different tasks by prepending **533** task-related natural languague description. Prefix- **534** tuning[\(Li and Liang,](#page-9-6) [2021a\)](#page-9-6) extends this idea to **535** continuous tokens. It prepends trainable continu- **536** ous tokens (prefix) to the input and hidden stats of **537** each Transformer layer. Each prefix is drawn from **538** a newly initialized trainable matrix P, while other **539** parameters of the PLM remain unchanged during **540** training. To further simplify prompt-tuning, Lester **541** et al[\(Lester et al.,](#page-8-8) [2021\)](#page-8-8). proposes a strategy that **542** only adds soft prompts to the input layer. While **543** prompt-based methods show promise for adapting **544** PLMs, challenges remain. Prefix-tuning is sensi- **545** tive to initialization and unstable during training. **546** To address these issues, we conduct multi-scenario **547** summarization using prefix-tuning, stabilize the 548 training process through inherent bias representa- **549** tion in multi-task learning, and introduce low-rank **550** decomposition to enhance robustness. **551**

Prompt learning with MoE Numerous studies **552** have shown that models with more parameters typ- **553** ically yield better performance. To increase model **554** capacity without added computational overhead, **555** exploring scaling properties with MoE, introduced **556** by [\(Jacobs et al.,](#page-8-12) [1991\)](#page-8-12), is a promising direction. **557** There have been many existing works that com- **558** bine MoE and PLMs for research[\(Shazeer et al.,](#page-9-22) **559** [2017b\)](#page-9-22) [\(Fedus et al.,](#page-8-13) [2021\)](#page-8-13) [\(Lepikhin et al.,](#page-8-14) [2021\)](#page-8-14) **560** [\(Lewis et al.,](#page-8-15) [2021\)](#page-8-15). However, few of them fo- **561** cus on parameter-efficient MoE. Also, there are **562** few works that attemp to combine the MoE with **563** prompt learning. **564**

# 6 CONCLUSION **<sup>565</sup>**

In this paper, We propose a lightweight low-rank **566** MOE network for Prompt reparameterization in **567** multi-scenario summarization, which integrates **568** MoE into the prefix reparameterization process **569** and achieves expert integration. Our proposed **570** low-rank sharing weights (LoRL and LoRE) en- **571** able cross-layer and cross-expert knowledge shar- **572** ing, effectively reducing the number of parameters **573** while improving performance. Experimental re-  $574$ sults demonstrate that our model outperforms all **575** strong baselines and achieves significant progress **576** in multi-scenario summarization. **577**

# **<sup>578</sup>** 7 Limitations

**579** Our work still has certain limitations.

 First, although we designed an effective MOP mechanism, the performance of the joint model trained on multiple scenarios still has a gap com- pared to models fine-tuned for each specific sce- nario. This suggests that interference still exists due to the differences in data distribution across scenarios.

 Second, reparameterizing prompts using a mix- ture of experts network reduces the number of train- able parameters, but it inevitably increases the de- ployment cost of the mixture of experts' parame-**591** ters.

 Finally, our mixture of experts reparameteriza- tion network can be applied to various parameter- efficient fine-tuning methods. We only explored reparameterizing prompts using a mixture of ex- perts network, and further experiments are needed to verify the role of the mixture of experts network in other parameter-efficient fine-tuning methods.

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- <span id="page-9-16"></span>A Appendix **<sup>784</sup>**

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 $\mathcal{L}_{\mathcal{A}}$ 

Figure 1: Case study for two examples from MultiSum dataset. We present the dialogue context, ground truth, MTL prediction, prefix-tuning prediction and our MOP prediction.