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# Towards Long-Context Time Series Foundation Models

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## Abstract

Time series foundation models have shown impressive performance on a variety of tasks, across a wide range of domains, even in zero-shot settings. However, most of these models are designed to handle short univariate time series as an input. This limits their practical use, especially in domains such as healthcare with copious amounts of long and multivariate data with strong temporal and intra-variate dependencies. Our study bridges this gap by cataloging and systematically comparing various context expansion techniques from both language and time series domains, and introducing a novel compressive memory mechanism to allow encoder-only TSFMs to effectively model intra-variate dependencies. We demonstrate the benefits of our approach by imbuing MOMENT, a recent family of multi-task time series foundation models, with the multivariate context.

## 1 Introduction

Large Language and Vision Models (LLMs and LVMs) have revolutionized text and image modeling, enabling a wide range of applications with both limited data and expert supervision. Time series foundation models (TSFMs) [8, 7, 1, 19, 21, 6, 4, 12] promise to bring similar transformative advancements to modeling time series. However, most of these models, barring MOIRAI [21] and TTMs [6], can only model short univariate time series, limiting their widespread use in applications such as healthcare where long and multivariate time series are common. Most of these approaches downsample long time series to handle extended context lengths and model different varieties (or channels) independently to manage multivariate inputs, which limits their ability to capture potentially informative high-frequency and intra-variate dependencies.

A straightforward solution to modeling both long and multivariate inputs is to re-design and pre-train TSFMs with longer context lengths and to concatenate multiple variates sequentially [21]. However, this naive solution drastically increases computational complexity as Transformer-based foundation models [8, 7, 1, 19, 21, 4, 12] are constrained by context-dependent memory, due to their quadratic complexity in the length of the input. Recent studies have explored the use of compressive memory to enable Transformer-based LLMs to process very long sequences with bounded memory and computation [14]. We adapt these techniques to design a novel compressive memory mechanism which we call **Infini-Channel Mixer (ICM)**, that can allow encoder-only Transformers [8, 21, 15] to efficiently model intra-variate dependencies. We use Infini-Channel Mixer to imbue MOMENT, a recent family of multi-task TSFMs, with multivariate context.

Our contributions include: **(1)** We outline the *design space* of context expansion techniques from both language and time series modeling; **(2)** We propose Infini-Channel Mixer, a *novel compressive memory mechanism* to enable encoder-only Transformers to model multivariate time series; and **(3)** We systematically compare various context expansion techniques with increasing levels of complexity on multivariate long-horizon forecasting to demonstrate that our proposed approach can improve forecasting performance and efficacy for the MOMENT [8] TSFM family.

## 2 Design Space of Multivariate Time Series Models

**Channel Independence.** Many multivariate time series models [15], including foundation models [8, 19, 4, 1], treat different channels (variates) independently. These approaches are simple, scalable, and typically perform well on real-world data and academic benchmarks [24] without substantial inter-variate dependencies.

To capture informative inter-variate dependencies in real-world time series, various *channel-mixing* approaches have been proposed in the literature:

**Adapters.** Approaches in this family usually first learn representations for each variate using a univariate backbone and then combine them using a multi-channel adapter. Examples include multivariate decoders [6] and Graph Transformer layers [23].

**End-to-End Channel Mixers.** These approaches tightly integrate channel mixing throughout the architecture. For instance, MOIRAI [21] flattens variates and uses relative variate encodings to distinguish information from different variates. *iTransformer* [13] attends to the inverted “variate” tokens which capture multi-variate correlations. In each of these approaches, every layer of the model is *homogeneous* and performs the same computation. Other methods such as *Crossformer* [22] are *non-homogeneous* as they use different attention matrices to model inter-sequence and intra-channel information. Our proposed *Infini-Channel Mixer* method attaches compressive memory to each Transformer layer and is therefore a homogeneous end-to-end channel mixer by design.

We defer detailed discussion of related work to the Appendix A.

## 3 Infini-Channel Mixer: Unlocking Multivariate Context using Compressive Memory

**Requirements.** Our goal is to modify the standard transformer architecture minimally to accommodate multivariate time series. To simplify development and keep multivariate context expansion our primary focus, we fix the maximum length of time series that can be processed by our model. Given the prevalence of encoders in time series foundation models [8, 21, 1], the proposed architecture should be amenable to bidirectional self-attention.

**Infini-Channel Mixer (ICM).** To aggregate information from an arbitrary number of channels, we propose incorporating compressive memory into Transformers. Compressive memory systems use a fixed number of parameters to store and retrieve information efficiently. Our approach is inspired by *Infini-attention* [14], a recent compressive memory-based attention mechanism that has enabled *decoder-only* LLMs to, in theory, scale to infinitely long input sequences. Unlike *Infini-attention*, our approach uses memory to process multiple variates in transformers with encoders.

*Infini-Channel Mixer* extends a standard self-attention layer with a *compressive memory matrix* allowing it to attend to both local (intra-channel) and global (inter-channel) information. The memory matrix is computed by reusing the key (**K**), query (**Q**), and value (**V**) matrices from the dot product attention as shown in Fig. 2, which accelerates training and inference and acts as a regularizer. A

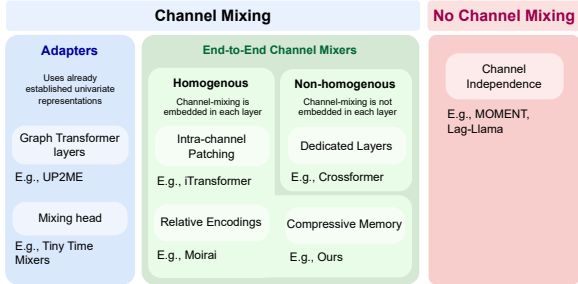


Figure 1: A design space of multivariate time series models. The proposed *Infini-Channel Mixer* is a homogeneous end-to-end channel mixing method.

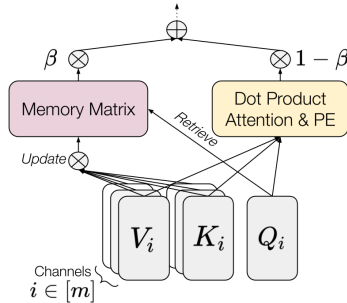


Figure 2: *Infini-Channel Mixer* (ICM) uses a learned scalar  $\beta$ , to balance local information from dot product attention with global information from the compressive memory matrix which aggregates cross-variate information.

learned gating scalar  $\beta$  regulates the trade-off between global information queried from the memory matrix and local information from the dot-product attention of a specific variate. This memory mechanism is replicated for each attention head and layer.

**Step 1: Aggregate Cross-channel Information into Compressive Memory.** The compressive memory matrix,  $\mathbf{M} \in \mathbb{R}^{h \times d_k \times d_k}$ , and the normalization term,  $\mathbf{z} \in \mathbb{R}^{h \times d_k \times 1}$ , are initially set to zero. Here,  $h$  is the number of attention heads, and  $d_k$  is the key dimension. We store information from each variate,  $i \in [m]$ , by reusing its local  $\mathbf{KV}$  entries. To ensure training stability, we follow prior work, and set the normalization term to the sum of key entries from all variates [14, 10], and use element-wise (Exponential Linear Unit)  $\text{ELU} + 1$  as a non-linear projection function  $\sigma$ . We define  $n$  as sequence length and  $\mathbf{K}_j^i$  denotes the key entries of the  $i^{\text{th}}$  variate and the  $j^{\text{th}}$  input token.

$$\mathbf{M} \leftarrow \mathbf{M} + \sigma(\mathbf{K}^i)^\top \mathbf{V}^i \quad \mathbf{z} \leftarrow \mathbf{z} + \sum_j^n \sigma(\mathbf{K}_j^i) \quad (1)$$

**Step 2: Conditioning on Inter-channel and Intra-Channel Information.** We use the query matrix to retrieve the cross-channel information  $\mathbf{A}_{\text{mem}^i}$  from the memory. This retrieved information is then combined with the local attention state  $\mathbf{A}_{\text{dot}^i}$  using the learned gating scalar  $\beta$ . This design adds only a single trainable parameter per head to regulate the trade-off between local and global information.

$$\mathbf{A}_{\text{mem}^i} = \frac{\sigma(\mathbf{Q}^i)\mathbf{M}}{\sigma(\mathbf{Q}^i)\mathbf{z} + \epsilon} \quad \mathbf{A}_i = \text{sigmoid}(\beta) \odot \mathbf{A}_{\text{mem}^i} + (1 - \text{sigmoid}(\beta)) \odot \mathbf{A}_{\text{dot}^i} \quad (2)$$

## 4 Experiments and Results

The goals of our experiments are twofold: (1) to systematically compare ICM against alternative context expansion techniques, and (2) to assess its impact on pre-training. To evaluate context expansion techniques outlined in Section 2, we conduct several small-scale supervised experiments focusing on the long-horizon forecasting task. Then to study the impact of ICM on pre-training, we pre-train the same model both with and without ICM and then evaluate the resulting models on two downstream tasks: long-horizon forecasting and multivariate classification.

Model / Example	Class	Design	Exchange	ETTh1	ETTh2	ETTm1	ETTm2	Weather
N-BEATS [16]	No Channel	Channel	0.524	0.461	0.410	0.346	0.278	0.211
MOMENT-Tiny [8]	Mixing	Independence	0.249	<u>0.418</u>	0.359	<u>0.339</u>	<b>0.234</b>	0.206
UP2ME [23]	Adapter	Graph Transformer	<u>0.240</u>	0.435	0.367	0.340	<u>0.237</u>	<b>0.204</b>
Crossformer [22]	Non-homogeneous End-to-End Mixer	Dedicated Intra-Channel Attention	0.559	0.571	0.654	0.390	0.515	0.227
iTransformer [13]	Homogeneous End-to-End	Multivariate Patching Concatentation	0.245	0.429	0.380	0.353	0.251	0.212
MOIRAI [21]	Channel Mixer	+ Relative Encoding	0.243	0.426	<u>0.357</u>	0.340	0.249	0.216
ICM (Ours)		Compressive Memory	<b>0.232</b>	<b>0.416</b>	<b>0.349</b>	<b>0.333</b>	<b>0.234</b>	<u>0.205</u>

Table 1: Forecasting MSE of all models averaged over 3 different horizons [96, 192, 384]. The best models are shown in **bold** and the second best ones are underlined. In most cases, Infini-Channel Mixer (ICM) outperforms considered alternatives. Complete results in Table 4 (Appendix D).

**Supervised Long-horizon Forecasting Experiments.** Due to variations in architectures and experimental setups, findings from prior work are inconclusive on how to best endow multivariate context to time series models. We address this by carefully implementing all context expansion techniques from Figure 1 on the same model architecture and experimental settings of long-horizon forecasting [24]. We use MOMENT, a recent open-source multi-task foundation model as the base architecture for all our experiments. To accelerate the process, we introduce a Tiny variant of it based on T5-Efficient-Tiny architecture [20]. All model variants take time series of length 256 as input (lookback window) and forecast the next 96, 192, and 384 time steps. As is common practice, models are trained and evaluated using Mean Squared Error (MSE). The exact details of model architecture, experimental settings, and hyper-parameters are outlined in Appendix C.

Results summarized in Table 1 show that our proposed approach outperforms alternative context expansion techniques on average in most cases.

Model name	Fine-tune $\beta$	Exchange	ETTh1	ETTh2	ETTm1	ETTm2	Weather
MOMENT-Tiny	–	0.250	<u>0.437</u>	0.343	0.333	<u>0.230</u>	0.222
+Infini-Channel	×	<u>0.249</u>	0.439	<b>0.336</b>	<u>0.332</u>	<u>0.230</u>	<u>0.219</u>
Mixer	✓	<b>0.247</b>	<b>0.436</b>	<u>0.337</u>	<b>0.330</b>	<b>0.228</b>	<b>0.214</b>

Table 2: Forecasting MSE averaged over 3 horizons [96, 192, 384]. MOMENT-Tiny with Infini-Channel Mixer outperforms its vanilla variant on all datasets. Additionally, fine-tuning the  $\beta$  parameters along with the forecasting head most often results in improved performance.

**Pre-training Experiments.** We pre-train 2 variants on MOMENT-Tiny: one with Infini-Channel Mixer and one without it. Pre-training multivariate foundation models is challenging due to the scarcity of public benchmark multivariate datasets and the complexity of managing time series with varying numbers of variates. To address these issues, we pre-train our models for one epoch on the Time Series Pile [8], using a mix of univariate and multivariate datasets. To manage memory consumption during training, we fix the maximum number of variates (= 8) per batch and sub-sample time series with more variates. Both models are trained with a maximum sequence length of 256 time steps.

We evaluate the pre-trained models on two downstream tasks: long-horizon forecasting and unsupervised representation learning for classification. For the forecasting task, we fine-tune a simple linear forecasting head on the representations learned by our models, while keeping all other model parameters frozen, except for those in the forecasting head and the  $\beta$  coefficients. We use the same 6 datasets as in the previous experiment. For classification, following standard practice [8], we obtain representations of time series in a zero-shot setting (without access to labels) and use these representations to train a Support Vector Machine. For these experiments, we use the UCR/UEA classification repository [3] which comprises both univariate and multivariate datasets, frequently used to benchmark classification algorithms.

Tables 2 and 3 summarize forecasting and classification results, details in Appendix D.

**Discussion.** Our experiments demonstrate the potential of the Infini-Channel Mixer as an effective context expansion mechanism. Despite adding only 16 new parameters (one for each of the 16 attention heads in MOMENT-Tiny), our approach consistently outperformed alternative methods on datasets with cross-channel dependencies. Interestingly, on some datasets like ETTm2 and Weather, treating variates independently yielded better performance than many multivariate methods. This finding suggests that current academic benchmarks might not fully capture the benefits of multivariate modeling. The promising performance of the UP2ME [23] approach, which models a subset of variates with substantial cross-correlation, supports this observation. Additionally, the substantial performance gains achieved by fine-tuning the  $\beta$  coefficients further indicate that they function as a soft-gating mechanism, enabling the model to focus on the most informative cross-channel information.

## 5 Conclusion and Future Work

We introduced Infini-Channel Mixer (ICM), a novel compressive memory mechanism that enables encoder-based TSFMs to effectively handle multivariate time series data. We systematically compared our proposed approach with multiple context expansion techniques proposed in the literature. We demonstrated that ICM, with only a few additional parameters, can improve the performance of time series models on two important tasks: long-horizon forecasting and classification. Future work should focus on rigorously evaluating our approach on larger models, across a wider range of datasets and tasks. Additionally, there is a pressing need for more multivariate datasets with strong cross-channel dependencies to better pre-train and evaluate large-scale models. It will also be important to explore whether Infini-Channel Mixer can be effectively adapted to handle extremely long time series.

	MOMENT-Tiny	+ ICM
Mean	0.625	0.632
Std.	0.254	0.268
Median	0.616	0.704
Wins/Ties/Losses	12/2/12	12/2/12

Table 3: Accuracy of MOMENT-Tiny with and without ICM across 24 UEA multivariate classification datasets. Complete results in Table 6. The addition of compressive memory does not substantially change multivariate classification accuracy.

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## A Related Work

### A.1 Foundation Models

Foundation models have significantly influenced several domains, particularly natural language processing and computer vision. These models typically rely on large-scale pre-training on vast, unlabeled datasets. For example, GPT models [17, 2] introduced autoregressive language modeling, while BERT [5] and RoBERTa [11] popularized masked language modeling with Transformer-based architectures. Most of these models are Transformer-based and designed for long-context tasks, with typical context lengths between 512 and 5000 tokens. The encoder-only architectures like BERT excel at representation learning, whereas autoregressive models such as GPT perform well in generative tasks.

## A.2 Time Series Foundation Models

The domain of time series analysis has also seen the rise of foundation models, which share many similarities with NLP models, particularly in their use of Transformer architecture. TimeGPT [7] was the first time series foundation model, setting a foundation for using pre-training in time series forecasting. Time-LLM [9] demonstrated the potential for adapting LLMs to time series tasks. PatchTST [15] introduced the concept of patching time series data, enabling the models to handle longer sequences efficiently. MOMENT Goswami et al. [8], stands out for its ability to solve multiple time series tasks, within a unified framework. MOMENT is open-source, with access to training data and code, making it accessible for a wide range of applications.

Our work builds on the advances of these foundation models, particularly leveraging the flexible, multitask capabilities of MOMENT. Most existing time series foundation models are Transformer-based, with either encoder-only or autoregressive architectures. Our proposed Infini-Channel Mixer extends the encoder-only architecture to better handle multichannel data, improving performance on time series forecasting tasks while maintaining model simplicity.

## B Channel Mixing

### B.1 Concatenation Approach

In order to perform information exchange between the multiple variates, they have to be processed either at the same time, producing a higher memory cost, or sequentially, producing a higher computational cost. The default way of processing multiple variates is related to flattening the data from all variates, concatenating it, and producing an attention matrix with two dimensions equal to (*channel number*  $\times$  *sequence length*). Woo et al. [21] implements a similar approach with inter- and intra-channel bias scalars, akin to the concept of relative positional biases in Raffel et al. [18]. The approach of concatenating [21] all of the variates is expressed in 3. To be able to ablate the approach, we do not apply the proposed rotary positional encoding, we stick to the sinusoidal position encoding.

$$E_{ij,mn} = (\mathbf{x}_{i,m} \mathbf{W}^Q) (\mathbf{x}_{j,n} \mathbf{W}^K)^\top + \delta_{mn} \cdot u^{(1)} + (1 - \delta_{mn}) \cdot u^{(2)} \quad (3)$$

where:

- $\mathbf{x}_{i,m}$  and  $\mathbf{x}_{j,n}$  are the input vectors for tokens  $i$  and  $j$  of variates  $m$  and  $n$ , respectively.
- $\mathbf{W}^Q$  and  $\mathbf{W}^K$  are the weight matrices for queries and keys.
- $u^{(1)}$  and  $u^{(2)}$  are scalar bias terms.  $u^{(1)}$  is added when  $m = n$ , and  $u^{(2)}$  is added when  $m \neq n$ .
- $\delta_{mn}$  is the Kronecker delta function, which is 1 if  $m = n$  and 0 otherwise.
- $E_{ij,mn}$  represents the attention score between tokens  $i$  and  $j$  of variates  $m$  and  $n$ , respectively.

### B.2 Infini-Channel Mixer + Static

We would like to point out, that the novel concept of a memory matrix opens up possibilities to query a matrix differently, based on the inter-channel relations. A simple, but naive way of ensuring that is to add channel embeddings to each patch embedding in the embedding layer.

Let  $\mathbf{E}_{\text{channel}} \in \mathbb{R}^{\text{channel\_num} \times d_{\text{model}}}$  be the matrix of static channel embeddings, where each row represents a unique embedding for a channel. The channel embeddings are broadcasted to match the dimensions of the input tensor and added to the patch embeddings. This operation can be mathematically represented as:

$$\mathbf{x}'_{b,c,t,d} = \mathbf{x}_{b,c,t,d} + \mathbf{E}_{\text{channel},c,d} \quad (4)$$

Where:

- $\mathbf{x}_{b,c,t,d}$  is the patched and embedded input

- $\mathbf{E}_{\text{channel},c,d}$  is the learned static channel embedding for the  $c$ -th channel and  $d$ -th dimension,
- $\mathbf{x}'_{b,c,t,d}$  is the updated embedding after adding the channel embedding.

This method is denoted as "Infini-Channel Mixer + Static" in the supervised setting in the table 5

## C Training Experimental Setup

### C.1 Supervised Setting

In the supervised setting, we evaluate the following models using a consistent training setup:

- **N-BEATS:** For training N-BEATS, we use the following configuration: Stack Types (Trend and Seasonality), Number of Blocks per Stack (3), Theta Dimensions (4 and 8), and Hidden Layer Units (256). The training is conducted for 10 epochs with a batch size of 64, and is directly copied from Goswami et al. [8].
- **Concatenation and Infini-Channel Mixer:** For the Concatenation, Infini-Channel Mixer, and Infini-Channel Mixer + Static models, we employ the T5-Efficient-TINY backbone. This backbone comprises 4 encoder blocks, a model dimension of 256, 4 attention heads, and feed-forward dimensions of size 1024. Detailed specifications for the concatenation method are included in the appendix B.1.
- **MT + Graph Transformer Layer:** For the MT model with an added Graph Transformer layer, we use the MOMENT-Tiny backbone, incorporating a Graph Transformer layer as detailed in Zhang et al. [23].
- **Crossformer:** We use the original parameters of the Crossformer including patch size 12, 3 encoder block layers, the feed-forward dimension of 128, model dimension of 256, and 4 attention heads.

## D Forecasting and classification task

**Pre-training** We use the pre-trained models: MOMENT-Tiny, MOMENT-Tiny + Infini-Channel Mixer. Both are pre-trained for one epoch and with the same amount of data. We want to ensure a constant number of variates in a single batch (either 1 or 8), thus for multivariate datasets, we divide them into subdatasets of 8 variates. In case we end up with less than 8 variates in a subdataset, we oversample the remaining variates. This yields two types of batches - univariate and multivariate. We then use them in the pre-training.

### D.1 Forecasting

Since MOMENT can handle multiple tasks, we test our approach on forecasting (supervised 5 and pre-trained 4) and classification tasks (multivariate and univariate pre-trained models). After pre-training the MOMENT-Tiny + Infini-Channel Mixer models, we fine-tune the linear head, as well as the  $\beta$  parameters.

Model name	Horizon	Exchange		ETTh1		ETTh2		ETTm1		ETTm2		Weather	
		MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE
Pre-trained MT + Infini-Channel Mixer (8 folds)	96	<u>0.229</u>	<u>0.104</u>	<b>0.407</b>	<b>0.403</b>	<b>0.344</b>	<b>0.288</b>	<b>0.347</b>	<b>0.293</b>	<b>0.257</b>	<b>0.171</b>	<u>0.217</u>	<u>0.166</u>
	192	<b>0.326</b>	<b>0.207</b>	<b>0.427</b>	<b>0.438</b>	<b>0.388</b>	<b>0.351</b>	<b>0.367</b>	<b>0.327</b>	<b>0.295</b>	<b>0.224</b>	<b>0.252</b>	<b>0.207</b>
	384	0.482	0.430	0.447	0.467	0.413	<b>0.371</b>	<b>0.391</b>	<b>0.369</b>	0.340	<b>0.291</b>	<b>0.299</b>	<b>0.271</b>
Pre-trained MT + Infini-Channel Mixer (4 folds)	96	<b>0.227</b>	<b>0.102</b>	<b>0.407</b>	<b>0.399</b>	0.348	<u>0.292</u>	0.348	<b>0.291</b>	<u>0.259</u>	<b>0.171</b>	<b>0.216</b>	<b>0.164</b>
	192	<u>0.328</u>	<u>0.209</u>	<b>0.427</b>	<b>0.436</b>	0.391	<u>0.358</u>	0.371	<b>0.327</b>	0.297	0.227	<b>0.252</b>	<b>0.205</b>
	384	0.482	0.432	<b>0.445</b>	0.464	0.415	0.374	0.395	<b>0.367</b>	0.345	0.297	<b>0.298</b>	<b>0.268</b>
Pre-trained Univariate MT	96	0.236	0.109	0.413	0.410	0.348	0.296	0.348	0.295	0.260	0.173	0.222	0.173
	192	0.338	0.217	0.432	0.442	0.390	0.359	0.369	0.331	0.296	0.226	0.258	0.217
	384	<b>0.479</b>	<b>0.425</b>	<b>0.445</b>	<b>0.459</b>	<b>0.408</b>	0.374	0.393	0.373	<b>0.339</b>	<b>0.291</b>	0.301	0.277

Table 4: MAE and MSE for various models across different datasets and horizons. The best metric for each dataset and horizon is highlighted, results better than MOMENT-Tiny are underlined. MT means MOMENT-Tiny as a backbone architecture, each model is pre-trained on **ONE Epoch** of the Time Series Pile.



Model name	Horizon	Exchange		ETTh1		ETTh2		ETTh1		ETTh2		Weather	
		MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE	MSE
MT + Graph Transformer layer	96	0.210	0.089	0.409	<b>0.382</b>	0.365	0.316	<u>0.349</u>	0.304	0.256	0.170	<b>0.197</b>	<u>0.151</u>
	192	0.335	0.222	0.436	0.435	0.413	0.385	<u>0.372</u>	0.339	<u>0.299</u>	<u>0.231</u>	<b>0.241</b>	<u>0.196</u>
	384	<u>0.470</u>	<u>0.409</u>	0.477	0.489	0.429	0.399	<u>0.397</u>	<u>0.376</u>	0.354	0.310	<b>0.292</b>	<u>0.264</u>
NBeats	96	0.316	0.173	0.422	0.407	0.377	0.334	0.357	0.304	0.268	0.180	0.207	<u>0.152</u>
	192	0.527	0.467	0.456	0.453	0.422	0.392	0.379	0.339	0.320	0.266	0.273	0.208
	384	0.739	0.933	0.500	0.523	0.500	0.503	0.413	0.394	0.394	0.329	0.323	0.273
CrossFormer	96	0.385	0.260	0.448	0.427	0.540	0.575	0.365	0.317	0.383	0.312	0.218	<b>0.148</b>
	192	0.606	0.644	0.508	0.515	0.573	0.640	0.380	0.353	0.589	0.632	0.281	0.204
	384	0.704	0.774	0.668	0.770	0.644	0.746	0.507	0.501	0.573	0.601	0.378	0.329
iTransformer	96	0.231	0.104	0.408	0.391	0.373	0.325	0.361	0.311	0.268	0.186	0.207	0.160
	192	0.332	0.208	0.434	0.434	0.417	0.400	0.383	0.350	0.315	0.258	0.250	0.206
	384	<u>0.480</u>	<u>0.423</u>	0.452	0.462	0.434	0.414	0.409	0.397	0.353	0.310	0.299	0.272
Infini-Channel Mixer MT (Ours)	96	0.219	0.096	<b>0.400</b>	<u>0.383</u>	<b>0.346</b>	<b>0.295</b>	<u>0.348</u>	<b>0.298</b>	0.255	0.170	0.203	<u>0.154</u>
	192	<b>0.316</b>	<b>0.193</b>	<b>0.421</b>	<b>0.420</b>	<b>0.396</b>	<u>0.368</u>	<b>0.369</b>	<b>0.330</b>	<u>0.296</u>	<u>0.229</u>	0.244	<u>0.197</u>
	384	<b>0.467</b>	<b>0.407</b>	<b>0.440</b>	0.446	<b>0.417</b>	<b>0.385</b>	<b>0.394</b>	<b>0.372</b>	0.345	0.304	0.295	<u>0.263</u>
Infini-Channel Mixer + Static MT (Ours)	96	0.224	0.100	<u>0.405</u>	0.390	0.354	0.300	<b>0.346</b>	<b>0.298</b>	<b>0.252</b>	<b>0.167</b>	0.201	<b>0.148</b>
	192	<u>0.322</u>	0.204	0.428	0.427	<u>0.398</u>	<b>0.362</b>	<b>0.369</b>	<b>0.330</b>	<b>0.294</b>	<b>0.224</b>	0.244	<b>0.192</b>
	384	<u>0.483</u>	<u>0.437</u>	<u>0.441</u>	0.448	0.438	0.409	<u>0.395</u>	<u>0.373</u>	0.346	0.303	0.293	<b>0.258</b>
Channel Concatenation	96	0.223	0.099	0.410	0.393	0.356	0.303	0.353	0.302	0.264	0.180	0.211	0.166
	192	0.329	0.213	0.430	0.429	<b>0.396</b>	<u>0.370</u>	0.377	0.339	0.305	0.238	0.251	0.210
	384	<u>0.478</u>	<u>0.418</u>	0.448	0.456	0.428	0.399	0.400	0.380	0.364	0.329	0.297	0.273
Univariate MT	96	<b>0.204</b>	<b>0.084</b>	0.407	0.388	0.354	0.300	0.351	0.300	0.254	<b>0.167</b>	0.201	0.155
	192	0.323	0.202	0.425	0.422	0.399	0.376	0.374	0.338	0.303	0.235	0.242	0.198
	384	0.499	0.460	0.442	<b>0.445</b>	0.420	0.399	0.399	0.379	<b>0.344</b>	<b>0.301</b>	<b>0.292</b>	0.264

Table 5: MAE and MSE for various models, forecasting, supervised setup, across different datasets and horizons. The best metric for each dataset and horizon is highlighted, results better than MOMENT-Tiny are underlined. MT means MOMENT-Tiny as a backbone architecture. Our method shows promising results, with notably the moment backbone paired with the Graph Transformer layer showing good results on the Weather dataset.

## D.2 Classification

In the multivariate case, MOMENT-Tiny + Infini-Channel Mixer achieves comparable results to MOMENT-Tiny 3, although mean and median accuracy is higher, the number of wins/losses for MOMENT-Tiny with Infini-Channel Mixer is 9155 / 6512, which is worse than for MOMENT-Tiny 9497 / 6170. We hypothesize that this happens because the  $\beta$  parameters allow the model backbone to adjust during the fine-tuning stage. In the univariate case, our model with Channel-Mixing performs worse than the vanilla one. This points towards the hypothesis that meaningful filtering of the aggregated memory is an important direction of future work. 6 7.

Dataset	MOMENT-Tiny	MOMENT-Tiny + Infini-Channel Mixing Mixer
ArticulatoryWordRecognition	0.923	<b>0.943</b>
AtrialFibrillation	<b>0.400</b>	0.333
BasicMotions	0.550	<b>0.875</b>
Cricket	<b>0.972</b>	<b>0.972</b>
DuckDuckGeese	<b>0.540</b>	0.340
EigenWorms	<b>0.557</b>	0.542
Epilepsy	0.949	<b>0.971</b>
ERing	<b>0.852</b>	0.811
EthanolConcentration	<b>0.346</b>	0.281
FingerMovements	0.500	<b>0.650</b>
HandMovementDirection	0.230	<b>0.284</b>
Handwriting	<b>0.212</b>	0.179
Heartbeat	<b>0.722</b>	<b>0.722</b>
JapaneseVowels	0.676	<b>0.692</b>
Libras	<b>0.850</b>	0.822
LSST	<b>0.329</b>	0.266
MotorImagery	0.480	<b>0.520</b>
NATOPS	0.772	<b>0.828</b>
PEMS-SF	<b>0.879</b>	0.855

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Dataset	MOMENT-Tiny	MOMENT-Tiny + Infini-Channel Mixing Mixer
PenDigits	0.959	<b>0.971</b>
PhonemeSpectra	<b>0.212</b>	0.175
RacketSports	0.697	<b>0.717</b>
SelfRegulationSCP1	<b>0.785</b>	0.724
SelfRegulationSCP2	0.489	<b>0.550</b>
SpokenArabicDigits	<b>0.966</b>	0.928
StandWalkJump	0.400	<b>0.467</b>

Table 6: Accuracy for multivariate datasets (UCR/UEA) classification for MOMENT-Tiny and MOMENT-Tiny + Infini-Channel Mixing.

Dataset	MOMENT-Tiny	MOMENT-Tiny + Infini-Channel Mixing
GestureMidAirD2	<b>0.538</b>	0.515
UWaveGestureLibraryX	<b>0.790</b>	0.745
GesturePebbleZ2	<b>0.791</b>	0.722
ECG5000	0.921	<b>0.934</b>
OSULeaf	<b>0.802</b>	0.719
MedicalImages	<b>0.759</b>	0.658
Ham	0.543	<b>0.581</b>
DistalPhalanxTW	0.612	<b>0.619</b>
ProximalPhalanxOutlineCorrect	<b>0.842</b>	0.838
FreezerRegularTrain	<b>0.961</b>	0.946
TwoLeadECG	0.748	<b>0.838</b>
GunPointMaleVersusFemale	0.975	<b>0.984</b>
Trace	<b>0.980</b>	0.940
SmoothSubspace	0.793	<b>0.867</b>
MiddlePhalanxTW	<b>0.558</b>	0.552
SyntheticControl	<b>0.950</b>	0.880
ShapesAll	<b>0.772</b>	0.725
AllGestureWiimoteX	<b>0.627</b>	0.520
Wafer	<b>0.996</b>	0.994
FaceFour	<b>0.557</b>	0.443
CricketX	<b>0.641</b>	0.541
DistalPhalanxOutlineCorrect	<b>0.714</b>	0.707
ChlorineConcentration	0.671	<b>0.702</b>
Chinatown	<b>0.980</b>	0.971
GestureMidAirD1	<b>0.623</b>	0.523
MiddlePhalanxOutlineAgeGroup	<b>0.526</b>	0.468
UMD	<b>0.965</b>	0.917
Crop	<b>0.701</b>	0.701
GesturePebbleZ1	<b>0.901</b>	0.797
WordSynonyms	<b>0.577</b>	0.475
ArrowHead	<b>0.571</b>	0.520
Wine	<b>0.556</b>	0.500
Coffee	<b>0.821</b>	0.536
Earthquakes	<b>0.748</b>	<b>0.748</b>
Herring	<b>0.594</b>	<b>0.594</b>
Beef	0.667	<b>0.700</b>
MiddlePhalanxOutlineCorrect	0.526	<b>0.591</b>
ECGFiveDays	<b>0.844</b>	0.742
Yoga	0.742	<b>0.751</b>
Adiac	<b>0.627</b>	0.619

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Dataset	MOMENT-Tiny	MOMENT-Tiny + Infini-Channel Mixing
MoteStrain	0.654	<b>0.712</b>
Strawberry	0.922	<b>0.924</b>
InsectWingbeatSound	<b>0.563</b>	0.508
DodgerLoopWeekend	<b>0.848</b>	0.703
Meat	<b>0.833</b>	<b>0.833</b>
MelbournePedestrian	0.870	<b>0.872</b>
FaceAll	<b>0.666</b>	0.615
FacesUCR	<b>0.652</b>	0.606
AllGestureWiimoteY	<b>0.671</b>	0.589
ShakeGestureWiimoteZ	<b>0.760</b>	0.720
BME	0.947	<b>0.960</b>
FordB	<b>0.810</b>	0.786
Fish	<b>0.777</b>	0.629
SonyAIBORobotSurface2	<b>0.821</b>	0.753
FiftyWords	<b>0.677</b>	0.589
ToeSegmentation1	<b>0.925</b>	0.851
FreezerSmallTrain	0.744	<b>0.747</b>
TwoPatterns	<b>0.964</b>	0.821
ShapeletSim	<b>0.650</b>	0.594
Plane	<b>0.952</b>	0.933
GestureMidAirD3	<b>0.315</b>	0.292
DiatomSizeReduction	<b>0.784</b>	0.765
CricketZ	<b>0.669</b>	0.564
Lightning7	<b>0.589</b>	0.548
UWaveGestureLibraryY	<b>0.723</b>	0.633
GunPointAgeSpan	0.949	<b>0.965</b>
DistalPhalanxOutlineAgeGroup	<b>0.683</b>	0.676
SwedishLeaf	<b>0.875</b>	0.840
CBF	<b>0.864</b>	0.671
BeetleFly	<b>0.750</b>	0.650
AllGestureWiimoteZ	<b>0.569</b>	0.466
DodgerLoopDay	<b>0.400</b>	0.263
GunPointOldVersusYoung	<b>0.933</b>	0.889
FordA	<b>0.934</b>	0.913
ItalyPowerDemand	<b>0.935</b>	0.900
ProximalPhalanxOutlineAgeGroup	<b>0.839</b>	0.829
GunPoint	<b>0.960</b>	0.940
ProximalPhalanxTW	<b>0.737</b>	0.732
PickupGestureWiimoteZ	<b>0.640</b>	0.480
SonyAIBORobotSurface1	0.626	<b>0.687</b>
PowerCons	<b>0.894</b>	0.833
PhalangesOutlinesCorrect	<b>0.699</b>	0.650
BirdChicken	<b>0.900</b>	0.750
ToeSegmentation2	<b>0.938</b>	0.869
CricketY	<b>0.585</b>	0.482
ElectricDevices	0.634	<b>0.638</b>
DodgerLoopGame	<b>0.623</b>	0.551
Fungi	<b>0.887</b>	0.806
Symbols	<b>0.857</b>	0.842
UWaveGestureLibraryZ	<b>0.750</b>	0.678
ECG200	<b>0.840</b>	<b>0.840</b>

Table 7: Accuracy for univariate datasets (UCR/UEA) classification for MOMENT-Tiny and MOMENTiTiny + Infini-Channel Mixing