DA-BENCH: BENCHMARKING UNSUPERVISED DO MAIN ADAPTATION METHODS WITH REALISTIC VALI DATION ON DIVERSE MODALITIES

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ABSTRACT

Unsupervised Domain Adaptation (DA) consists of adapting a model trained on a labeled source domain to perform well on an unlabeled target domain with some data distribution shift. While many methods have been proposed in the literature, fair and realistic evaluation remains an open question, particularly due to methodological difficulties in selecting hyperparameters in the unsupervised setting. With DA-Bench, we propose a framework to evaluate DA methods on diverse modalities, beyond computer vision task that have been largely explored in the literature. We present a complete and fair evaluation of existing shallow algorithms, including reweighting, mapping, and subspace alignment. Realistic hyperparameter selection is performed with nested cross-validation and various unsupervised model selection scores, on both simulated datasets with controlled shifts and real-world datasets across diverse modalities, such as images, text, biomedical, and tabular data. Our benchmark highlights the importance of realistic validation and provides practical guidance for real-life applications, with key insights into the choice and impact of model selection approaches. DA-Bench is open-source, reproducible, and can be easily extended with novel DA methods, datasets, and model selection criteria without requiring re-evaluating competitors.

1 INTRODUCTION

Given some training –or *source*– data, supervised learning consists in estimating a function that makes
good predictions on *target* data. However, performance often drops when the source distribution used
for training differs from the target distribution used for testing. This shift can be due, for instance,
to the collection process or non-stationarity in the data, and is ubiquitous in real-life settings. It has
been observed in various application fields, including tabular data (Gardner et al., 2023), clinical
data (Harutyunyan et al., 2019), or computer vision (Ganin et al., 2016b).

Domain adaptation. Unsupervised Domain Adaptation (DA) addresses this problem by adapting a 040 model trained on a labeled source dataset -- or *domain*- so that it performs well on an unlabeled target 041 domain, assuming some distribution shifts between the two (Ben-David et al., 2006; Quinonero-042 Candela et al., 2008; Redko et al., 2022). As illustrated in Figure 1, source and target distributions 043 can exhibit various types of shifts (Moreno-Torres et al., 2012): changes in feature distributions 044 (covariate shift), class proportions (target shift), conditional distributions (conditional shift), or in 045 distributions in particular subspaces (subspace shift). Depending on the type of shift, existing DA 046 methods attempt to align the source distribution closer to the target using reweighting (Sugiyama 047 & Müller, 2005; Shimodaira, 2000), mapping (Sun et al., 2017; Courty et al., 2017b), or dimension 048 reduction (Pan et al., 2011; Fernando et al., 2013) methods. More recently, it has been proposed to mitigate shifts in a feature space learned by deep learning (Ganin et al., 2016b; Sun & Saenko, 2016; Long et al., 2015a; Damodaran et al., 2018b), primarily focusing on computer vision applications. 051 Regardless of the core algorithm used to address the domain shift, hyperparameters must be tuned for optimal performance. Indeed, a critical challenge in applying DA methods to real-world cases is 052 selecting the appropriate method and tuning its hyperparameters, especially given the unknown shift type and the absence of labels in the target domain.



Figure 1: Illustration of the different data shifts and assumptions studied in the DA literature and used in the simulated datasets used in the numerical experiments. The colors indicate the classes, with solid colors representing target and transparent colors representing source in the target data plot.

064 Model selection in DA settings. Without distribution shifts, classical model selection strategies 065 -including hyperparameter optimization- rely on evaluating the generalization error with an indepen-066 dent labeled validation set. However, in DA, validating the hyperparameters in a supervised manner 067 on the target domains is impossible due to the lack of labels. While it is possible to validate the 068 hyperparameters on the source domain, it generally leads to a suboptimal model selection because of 069 the distribution shift. In the literature, this problem is often raised but not always addressed. Some papers choose not to validate the parameters (Pan et al., 2011), while others validate on the source domain (Sun et al., 2017) or propose custom cross-validation methods (Sugiyama et al., 2007b). Few 071 papers focus specifically on DA model selection criteria, which we will call scorers in this paper. 072 These scorers are used to select the methods' hyperparameters, and mainly consists of reweighting 073 methods on source (Sugiyama et al., 2007a; You et al., 2019), prediction entropy (Morerio et al., 074 2017; Saito et al., 2021) or circular validation (Bruzzone & Marconcini, 2010a). One of the goals of 075 our benchmark is to evaluate these approaches in diverse and realistic scenarios. 076

077 **Benchmarks of DA.** As machine learning continues to flourish, new methods constantly emerge, making it essential to develop benchmarks that facilitate fair comparisons (Hutson, 2018; Pineau et al., 2019; Mattson et al., 2020; Moreau et al., 2022). In DA and related fields, several benchmarks 079 have been proposed. Numerous papers focus on Out-of-distribution (OOD) datasets for different modalities: computer vision, text, graphs (Koh et al., 2021; Sagawa et al., 2022), time-series (Gagnon-081 Audet et al., 2023), AI-aided drug discovery (Ji et al., 2023) or tabular dataset (Gardner et al., 2023). Due to the type of data considered, existing benchmarks are mainly focused on Deep DA methods 083 (Musgrave et al., 2021; Wang, 2018; Jiang et al., 2022; Fawaz et al., 2023), offering an incomplete 084 evaluation of DA literature. Moreover, only a few benchmarks propose a comparison of Deep 085 unsupervised DA methods with realistic parameters selection, on computer vision (Hu et al., 2023; Musgrave et al., 2021) and time series (Fawaz et al., 2023) data. Those benchmarks have shown the 087 importance of validating with unsupervised scores and reveal that Deep DA methods achieve much lower performance in realistic scenarios. 088

Contributions. In the following, we propose DA-Bench, an ambitious and fully reproducible benchmark with the following features: 1. A set of 4 simulated and 8 real-life datasets with different modalities (computer vision, NLP, tabular, biomedical) totaling 51 realistic shift scenarios, 2. A wide range of 20 Shallow DA methods designed to handle different types of shifts, 3. An evaluation of 3 deep DA methods on 4 real-world datasets from the computer vision and biomedical modalities, 4. A realistic model selection procedure using 5 different unsupervised scorers with nested cross-validation for hyperparameter selection, 5. An open-source implementation and publicly available datasets, easy to extend for new DA methods and datasets without the need to re-run the whole experiment.

In addition, we provide a detailed analysis of the results and derive guidelines for practitioners to select the best methods depending on the type of shifts, and the best scorer to perform unsupervised model selection. In particular, the effects of model selection and the scorer's choice on the final performances are highlighted, showing a clear gap between the unsupervised realistic scorers versus using target labels for supervised validation.

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2 DOMAIN ADAPTATION AND MODEL SELECTION WITHOUT TARGET LABELS

In this section, we first discuss the specificities of the unsupervised domain adaptation problem and
 introduce several types of data shifts and their corresponding DA methods. Next, we discuss the
 different validation strategies used in the literature and the need for realistic scorers to compare DA
 methods.

108 2.1 DATA SHIFTS AND DA STRATEGIES

110 **Domain Adaptation problem and theory.** The theoretical framework of DA is well established 111 (Ben-David et al., 2006; Quinonero-Candela et al., 2008; Redko et al., 2022). The main results 112 highlight that the performance discrepancy of an estimator between the source and target domains is linked to the divergence between both distributions. This has motivated the majority of DA methods 113 to search for a universal (or domain invariant) predictor by minimizing the divergence between the 114 two domains through the adaptation of the distributions. This is done in practice by modeling and 115 estimating the shift between the source and target distributions and then compensating for this shift 116 before training a predictor. 117

Data Shifts and DA methods. A wide variety of shifts between the source and target distributions are possible. They are usually expressed as a relation between the joint distributions $P^s(x,y) = P^s(x|y)P_{\mathcal{Y}}^s(y) = P^s(y|x)P_{\mathcal{X}}^s(x)$ in the source domain and $P^t(x,y) = P^t(x|y)P_{\mathcal{Y}}^t(y) = P^t(y|x)P_{\mathcal{X}}^t(x)$ in the target domain. We now discuss the main types of shifts and the strategies proposed in the literature to mitigate them. Figure 1 illustrates these shifts.

In **Covariate shift** the conditionals probabilities are equal (*i.e.*, $P^s(y|x) = P^t(y|x)$), but the feature marginals change (*i.e.*, $P^s_{\mathcal{X}}(x) \neq P^t_{\mathcal{X}}(x)$). **Target shift** is similar, but the label marginals change $P^s_{\mathcal{Y}}(y) \neq P^t_{\mathcal{Y}}(y)$ while the conditionals are preserved. For classification problems, it corresponds to a change in the proportion of the classes between the two domains. Both of those shifts can be compensated by **reweighting methods** that assign different weights to the samples of the source domain to make it closer to the target domain (Sugiyama & Müller, 2005; Shimodaira, 2000).

In Conditional shift, conditional probabilities differ between domain (*i.e.*, $P^s(x|y) \neq P^t(x|y)$ or $P^s(y|x) \neq P^t(y|x)$). This shift is typically harder to compensate for, necessitating explicit modeling to address it effectively. For instance, several approaches model the shift as a **mapping** *m* between the source and target domain such that $P^s(y|m(x)) = P^t(y|x)$ (Sun et al., 2017; Courty et al., 2017b). The estimated mapping is then applied to the source data before training a predictor.

Subspace shift assumes that while probabilities are different between the domains $(P_{\mathcal{X}}^s(x) \neq P_{\mathcal{X}}^t(x))$ and $P^s(x|y) \neq P^t(x|y)$, there exists a subspace \mathcal{Z} and a function $\phi : \mathcal{X} \to \mathcal{Z}$ such that $P_{\mathcal{Z}}^s(\phi(x)) = P_{\mathcal{Z}}^t(\phi(x))$ and $P^s(y|\phi(x)) = P^t(y|\phi(x))$. Note that this means the shift occurs in the orthogonal complement of \mathcal{Z} . This implies that a classifier trained on \mathcal{Z} will perform well across both domains. Subspace methods are specifically designed towards identifying the subspace \mathcal{Z} and the function ϕ , as developed in Pan et al. (2011); Fernando et al. (2013). Note that, as discussed in the introduction, a natural extension of this idea is to learn an invariant feature space using Deep learning (Ganin et al., 2016b; Sun & Saenko, 2016).

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2.2 DA MODEL SELECTION STRATEGIES

As seen above, DA methods are typically designed to correct a specific type of shift. However, in
 real-world scenarios, the nature of the shift is often unknown. This presents a challenge in selecting
 the appropriate method and tuning its parameters when facing a new problem. In this section, we
 discuss the validation strategies proposed in the literature to compare DA methods, focusing on
 realistic scorers that do not use target labels.

148 **Realistic DA scorers.** In the literature, few papers propose realistic DA scorers to validate the 149 parameters of the methods, *i.e.*, unsupervised scorers that **do not require target labels**. The 150 Importance Weighted (IW) scorer (Sugiyama et al., 2007a) computes the score as a reweighted 151 accuracy on labeled sources data. The Deep Embedded Validation (DEV) (You et al., 2019) can be 152 seen as an IW in the latent space with a variance reduction strategy. DEV was originally proposed 153 for Deep learning models but can be used on shallow DA methods that compute features from the data (mapping/subspaces). The Prediction Entropy (PE) scorer (Morerio et al., 2017) measures 154 the uncertainty associated with model predictions on the target data. Soft Neighborhood Density 155 (SND) (Saito et al., 2021) also computes an entropy but on a normalized pairwise similarity matrix 156 between probabilistic predictions on target. The Circular Validation (CircV) scorer (Bruzzone & 157 Marconcini, 2010a) performs DA by first adapting the model from the source to the target domain and 158 predicting the target labels. Next, it adapts back from the target to the source using these estimated 159 labels. Performance is measured as the accuracy between the recovered and true source labels. 160

161 The *MixVal* scorer (Hu et al., 2023) also performs domain adaptation by first adapting the model from the source to the target domain and predicting the target labels. Then, it generates mixed target

162 Target Data Source Data 163 Label available Label not available 164 Outer loop 165 Final hyperparameters Target test set 166 Source test set 167 Nested loop Hyperparameters s lection 168 Target train set Target validation set Source validation set Source train set 169

Figure 2: Visualization of nested cross-validation strategy. Both source and target data are split into an outer loop and then a nested loop. The nested loop tunes hyperparameters for the domain adaptation method, while the outer loop trains a final classifier with the best hyperparameters and evaluates its accuracy on both source and target data. Note: Target sets have no labels during the nested loop, reflecting unsupervised Domain Adaptation.

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samples by probing intra-cluster samples to assess neighborhood density and inter-cluster samples to
 examine classification boundaries. The score is the accuracy between the generated targets labels and
 their predictions to evaluate the consistency.

180 DA validation in the literature. The model selection problem in DA has been widely discussed in 181 the literature. Yet, this literature constitutes a subfield of DA and has seldom been used to validate 182 new DA methods. Indeed, there is no consensus on the best validation strategy and many papers do not properly validate their methods, leading to over-estimated performances. Some authors do not 183 discuss the validation procedure (Sugiyama & Müller, 2005; Shimodaira, 2000) or consider fixed 184 hyperparameters (Huang et al., 2006). While some methods rely on custom validation techniques 185 (Sugiyama et al., 2007b), others use cross-validation, either on the source or the target (Sun et al., 2017; Courty et al., 2017b), or alternatively other validation strategies proposed in the literature (Courty 187 et al., 2017a; Bruzzone & Marconcini, 2010a). A complete picture of the model selection procedures 188 used to validate the methods considered in DA-Bench in their original papers is presented in Table 4 189 in Appendix A. The goal of DA-Bench is therefore to constitute a dedicated benchmark to compare 190 scorers from the literature and report performances that can be expected in real use cases for the 191 considered methods.

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3 A REALISTIC BENCHMARK FOR DA

In this section, we present our benchmark framework. First, we introduce the parameter validation strategies. Then, we present the compared DA methods followed by a description of the datasets used in the benchmark.

3.1 NESTED CROSS-VALIDATION LOOP AND IMPLEMENTATION

We discuss below the nested cross-validation and the implementation details of the benchmark.

Hyperparameter validation loop. We propose a nested loop cross-validation procedure, depicted in
Figure 2. First, the source and target data are split into multiple outer test and train sets (outer loop in
Figure 2). The test sets are kept to compute the final accuracy for both the source and target domains.
For each split in the outer loop, we use a nested loop to select the DA methods' parameters. Here,
the training sets are further divided into nested train and validation sets (nested loop in Figure 2).
Note that no labels are available for the target nested train and validation sets in this loop. The target
training set is used to train the DA method, while the target validation set allows to compute the
unsupervised score and select the best model.

For both loops, the data is split randomly 5 times using stratified sampling with an 80%/20% train/test split, except for Deep DA methods, where only one split is computed for the outer loop due to computation time. For one given method, we evaluate all the unsupervised scorers discussed earlier, as well as a supervised scorer that uses target labels, over all the nested splits. After averaging, the scores over the splits, the best hyperparameters are selected according to each scorer and then used to train a final classifier on the outer training sets. Although the supervised scorer cannot be used in practice, it is included in our results to actually evaluate the performance drop due to the absence of target labels. To limit complexity and perform a fair comparison of the methods, we set a timeout of
 4 hours for performing the nested loop. Additionally, we chose not to use the CircV scorer for Deep
 DA methods, as training neural networks twice is computationally expensive.

219 Base estimators and neural networks. Existing shallow domain adaptation methods typically rely 220 on either a base estimator trained on the adapted data or an iterative estimation process to adapt this 221 estimator to the target data. The choice of the base estimator is crucial, as it significantly impacts the 222 final performance. Before validating the hyperparameters of the DA methods, we determined the best 223 estimator for each dataset using a grid-search on the source data. We tested multiple hyperparameters 224 for Logistic Regression, SVM with RBF kernel, and XGBoost (Chen & Guestrin, 2016), selecting 225 the ones that maximize the average accuracy on the source test sets. Note that for some methods that 226 specifically require an SVM estimator (*i.e.*, JDOT and DASVM), we only validate SVM as the base estimator. We validated the base estimator separately from the DA methods parameters to reduce 227 computational complexity and avoid too complex hyperparameter grids that can compromise the 228 reliability of DA scorers. For Deep DA methods, we similarly select an appropriate architecture and 229 experimental setup for training on the source data for each dataset: a two-layer convolutional neural 230 network for MNIST/USPS, a ResNet50 (He et al., 2016) pretrained on ImageNet (Deng et al., 2009) 231 for Office31 and Office Home, and a ShallowFBCSPNet (Schirrmeister et al., 2017) for BCI. 232 These architectures are widely used and well-supported in the literature of computer vision (Musgrave 233 et al., 2021) and BCI (Schirrmeister et al., 2017). During the nested loop, only the DA parameters for 234 each method are validated. 235

Best scorer selection and statistical test. For all methods, we select the best validation scorer as the 236 one that maximizes the averaged accuracy on the target domains for all real datasets. This provides a 237 reasonable and actionable choice of scorer for each DA method for practitioners. For all methods and 238 datasets, we perform a paired Wilcoxon signed-rank test at the 0.05 level to detect significant gain or 239 drop in performance with respect to the no DA approach, denoted by "Train Src" in the following. 240 The test is done using the accuracy measures of the DA method with the selected scorer and the Train 241 Src for all shifts and outer splits, ensuring between 10 and 60 values depending on the dataset. Note 242 that these statistical tests are not performed on Deep DA methods, as the number of splits is too 243 limited for meaningful testing.

244 Python implementation. The benchmark code will be made available on GitHub upon publication 245 of the paper.¹ Our benchmark is implemented following the benchopt framework (Moreau et al., 246 2022), which provides standardized ways of organizing and running benchmarks for ML in Python. 247 This framework facilitates reproducing the benchmark's results, with tools to install the dependencies, 248 run the methods in parallel, or cache the results to prevent redundant computations. It also makes it 249 easy to extend the benchmark with additional datasets and methods, enabling it to evolve to account 250 for the advances in the field. In the supplementary materials, we provide examples demonstrating how 251 to add DA methods or datasets to the benchmark. Using this framework, we aim to make DA-Bench a reference benchmark to evaluate new DA methods in realistic scenarios with valid performance 252 estimations. 253

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3.2 COMPARED DA METHODS

In this section, we present the different families of domain adaptation methods that we compare in our
 benchmark. The shallow methods are grouped into four categories: reweighting methods, mapping
 methods, subspace methods, and others. For Deep DA methods, we consider three domain invariant
 feature methods. We provide a brief description of each method and the corresponding references.

Reweighting methods. These methods aim to reweight the source data to make it closer to the 261 target data. The weights are estimated using different methods such as kernel density estimation 262 (Dens. RW) (Sugiyama & Müller, 2005), Gaussian estimation (Gauss. RW) (Shimodaira, 2000), 263 discriminative estimation (Discr. RW) (Shimodaira, 2000), or nearest-neighbors (NN RW) (Loog, 264 2012). Other reweighting estimate weights by minimizing a divergence between the source and 265 target distributions such as Kullback-Leibler Importance Estimation Procedure (KLIEP) (Sugiyama 266 et al., 2007b) or Kernel Mean Matching (KMM) (Huang et al., 2006). Finally, we also include the 267 MMDTarS method (Zhang et al., 2013) that uses a Maximum Mean Discrepancy (MMD) to estimate 268 the weights under the target shift hypothesis.

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¹Our code is available in supplementary materials.

270 **Mapping methods.** These methods aim to find a mapping between the source and target data that 271 minimizes the distribution shift. The Correlation Alignment method (CORAL) (Sun et al., 2017) 272 aligns the second-order statistics of source and target distributions. The Maximum Mean Discrepancy 273 (MMD-LS) method (Zhang et al., 2013) minimizes the MMD to estimate an affine Location-Scale 274 mapping. Finally, the Optimal Transport (OT) mapping methods (Courty et al., 2017b) use the optimal transport plan to align with a non-linear mapping of the source and target distributions with 275 exact OT (MapOT), entropic regularization (EntOT), or class-based regularization (ClassRegOT). 276 Finally, the Linear OT method (Flamary et al., 2020) uses a linear mapping to align the source and 277 target distributions, assuming Gaussian distributions. 278

279 Subspace methods. These methods aim to learn a subspace where the source and target data have 280 the same distribution. The Transfer Component Analysis (TCA) method (Pan et al., 2011) searches for a kernel embedding that minimizes the MMD divergence between the domains while preserving 281 the variance. The Subspace Alignment (SA) method (Fernando et al., 2013) aims to learn a subspace 282 where the source and target have their covariance matrices aligned. The Transfer Subspace Learning 283 (TSL) method (Si et al., 2010) aims to learn a subspace using classical supervised loss functions on 284 the source (e.g., PCA, Fisher LDA) but regularized so that the source and target data have the same 285 distribution once projected on the subspace. Finally, the Joint Principal Component Analysis (JPCA) 286 method is a simple baseline that concatenates source and target data before applying a PCA. 287

Others. We also include other methods that do not fit into the previous categories. The Domain Adaptation SVM (DASVM) method (Bruzzone & Marconcini, 2010a) is a self-labeling method that iteratively updates SVM estimators by adding new target samples with predicted labels and removing source samples. The Joint Distribution Optimal Transport (JDOT) method (Courty et al., 2017a) aims to learn a target predictor that minimizes an OT loss between the joint source and target distributions. The Optimal Transport Label Propagation (OTLabelProp) method (Solomon et al., 2014) uses the optimal transport plan to propagate labels from the source to the target domain.

Deep DA methods. These methods aim to reduce the divergence between the source and target data 295 distributions within the learned feature space while simultaneously learning a classifier on source data. 296 The training loss consists in a traditional supervised loss on labeled source data and a second term 297 measuring the discrepancy between the source and target distributions. The methods implemented in 298 the Deep DA Benchmark use different discrepancies, such as covariance distance (Sun & Saenko, 299 2016) for DeepCORAL, adversarial loss (Ganin et al., 2016a) for DANN and optimal transport 300 distance (Damodaran et al., 2018a) for DeepJDOT. Note that these approaches are not part of the 301 main shallow DA benchmark but have been added to provide an interesting comparison of DA 302 performances between shallow and Deep methods on computer vision and biomedical data.

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3.3 COMPARED DATASETS

In this section, we present the datasets used in our experiments. We first introduce the synthetic datasets that implement different known shifts. Then, we describe the real-world datasets from various modalities and tasks such as Computer Vision (CV), Natural language Processing (NLP), tabular data, and biosignals.

Simulated datasets. The objective of the simulated datasets is to evaluate the performance of the DA methods under different types of shifts. Knowing that multiple DA methods have been built to handle specific shifts, evaluating them with this dataset will demonstrate whether they perform as expected and if they are properly validated.

314 The four simulated shifts in 2D, covariate (Cov. shift), target (Tar. shift) conditional (Cond. shift) 315 and Subspace (Sub. shift) shift are illustrated in Figure 1. The source domain is represented by two non-linearly separable classes generated from one large and several smaller Gaussian blobs. 316 In the experiments, the level of noise has been adjusted from Figure 1 to make the problem more 317 difficult. For the subspace shift scenario, the source domain consists of one class represented by a 318 large Gaussian blob and another class comprising Gaussian blobs positioned along the sides of the 319 large one. The target domain is flipped along the diagonal, making the task challenging in the original 320 space but feasible upon diagonal projection. 321

322 Real-word datasets. The real-world datasets used in our benchmark are summarized in Table 1. We 323 select 8 datasets from different modalities and tasks: Computer Vision (CV) with Office31 (Koniusz et al., 2017), Office Home (Venkateswara et al., 2017), and MNIST/USPS (Liao &

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226	Dataset	Modality	Preprocessing	# adapt	# classes	# samples	# features
520	Office 31	CV	Decaff + PCA	6	31	470 ± 350	100
327	(Koniusz et al., 2017)		(Donahue et al., 2014)	0	51	470 ± 550	100
200	Office Home	CV	ResNet + PCA	12	65	3897 ± 850	100
320	(Venkateswara et al., 2017)		(He et al., 2016)				
329	(Liao & Carneiro 2015)	CV	Vect + PCA	2	10	3000 / 10000	50
220			LLM + PCA				
330	20 Newsgroup (Lang 1005)	NLP	(Reimers & Gurevych (2019),	6	2	3728 ± 174	50
331	(Lang, 1993)		Xiao et al. (2023a))				
222	Amazon Review		LLM + PCA				
332	(McAuley & Leskovec (2013),	NLP	(Reimers & Gurevych (2019),	12	4	2000	50
333	McAuley et al. (2015))		X1ao et al. (2023a))				
224	(Dai et al. 2007)	Tabular	One Hot Encoding	2	2	4062 ± 546	117
334	Phishing						
335	(Mohammad et al., 2012)	Tabular	NA	2	2	5527 ± 1734	30
220	BCI	Dissignals	Cov+TS	0	4	200	252
330	(Tangermann et al., 2012)	Biosignais	(Barachant et al., 2012)	9	4	200	235

Table 1: Characteristics of the real-world datasets used in DA-Bench.

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Carneiro, 2015), Natural Language Processing (NLP) with 20Newsgroup (Lang, 1995) and
 Amazon Review (McAuley et al., 2015), Tabular Data with Mushrooms (Dai et al., 2007) and
 Phishing (Mohammad et al., 2012), and Biosignals with BCI Competition IV (Tangermann
 et al., 2012). The datasets are chosen to represent a wide range of shifts and to evaluate the performance of the methods on different types of data.

342 Before using shallow DA methods, the datasets are preprocessed with feature extraction to ensure 343 reasonable performance when trained on each domain. For example, images are embedded using 344 Deep pre-trained models followed by a PCA (except MNIST/USPS where only PCA is used), and 345 textual data is embedded using Large Language Models (LLM) (Reimers & Gurevych, 2019; Xiao 346 et al., 2023a) before applying a PCA. The tabular data are one-hot encoded to transform categorical 347 data into numerical data. The biosignals from Brain-Computer Interface (BCI) data are embedded using the state-of-the-art tangent space representation proposed in Barachant et al. (2012). For Deep 348 DA methods, only 4 datasets are used: Office31, Office Home, MNIST/USPS and BCI. Since 349 these methods focus on learning feature representations, the data are used in their raw form. The 350 datasets are split into pairs of source and target domains totaling 51 adaptation tasks in the benchmark. 351 More details about the datasets and pre-processing are available in Appendix B. 352

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4 BENCHMARK RESULTS

We now present the results of the benchmark. Training and evaluation across all shallow experiments required 1,215 CPU-hours on a standard Slurm (Yoo et al., 2003) cluster, while the Deep DA experiments required 244 GPU-hours. We first discuss and compare the performances of the methods on the different datasets. Then, a detailed study of the unsupervised scorers is provided.

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4.1 PERFORMANCE OF THE DA METHODS

362 **Results table.** First, we report the realistic performances of the different methods when using 363 their selected scorer on the different datasets in Table 2. The cells showcasing a significant change 364 in performance with the Wilcoxon test are highlighted with colors. Blue indicates an increase in performance, while red indicates a loss. The intensity of the color corresponds to the magnitude of the 366 gain or loss - the darker the shade, the larger the positive or negative change. Cells with a NA values 367 indicate that the method was not applicable to the dataset (DASVM is limited to binary classification) 368 or that the method has reached a timeout. We also report the best scorer and the average rank of the methods for all real datasets. In addition to Table 2 providing realistic performance estimations 369 with the best realistic scorer, we also report in Table 20 (Appendix D) the results when using the 370 non-realistic supervised scorer. 371

Simulated data with known shifts. DA methods tend to show a significant gain on the shift they
were designed for. It is especially true for mapping methods which greatly outperforms the Train
Src approach under conditional shift (Cond. shift), almost reaching the Train Tgt performance for
EntOT and ClassRegOT. The results also highlight that the mapping methods struggle with target
shift (Tar. shift), which is a well-known limitation of this kind of approach (Redko et al., 2019). On
the contrary, reweighting methods provide robust performance on target shift. Regarding covaratiate
shift (Cov. shift), the improvement with reweighting methods is very limited although reweighting is

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Table 2: Accuracy score for all datasets compared for all the shallow methods for <u>simulated</u> and
real-life datasets. The color indicates the amount of the improvement. A white color means the
method is not statistically different from Train Src (Train on source). Blue indicates that the score
improved with the DA methods, while red indicates a decrease. The darker the color, the more
significant the change.

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	Train Src	0.88	0.85	0.66	0.19	0.65	0.56	0.54	0.59	0.7	0.72	0.91	0.55		10.66	
	Train Tgt	0.92	0.93	0.82	0.98	0.89	0.8	0.96	1.0	0.73	1.0	0.97	0.64		1.55	
	Dens. RW	0.88	0.86	0.66	0.18	0.62	0.56	0.54	0.58	0.7	0.71	0.91	0.55	IW	12.20	
<u></u>	Disc. RW	0.85	0.83	0.71	0.18	0.63	0.54	0.5	0.6	0.68	0.75	0.91	0.56	CircV	8.75	
j.	Gauss. RW	0.89	0.86	0.65	0.21	0.22	0.44	0.11	0.54	0.55	0.51	0.46	0.25	CircV	16.45	
<u>6</u> .	KLIEP	0.88	0.86	0.66	0.19	0.65	0.56	0.54	0.6	0.69	0.72	0.91	0.55	CircV	10.56	
Me	KMM	0.89	0.85	0.64	0.16	0.64	0.54	0.52	0.7	0.57	0.74	0.91	0.52	CircV	11.74	
Re	NN RW	0.89	0.86	0.67	0.15	0.65	0.55	0.54	0.59	0.66	0.71	0.91	0.54	CircV	9.15	
	MMDTarS	0.88	0.86	0.64	0.2	0.6	0.56	0.54	0.59	0.7	0.74	0.91	0.55	IW	10.81	
	CORAL	0.74	0.7	0.76	0.18	0.65	0.57	0.62	0.73	0.7	0.72	0.92	0.62	CircV	5.08	
ьo	MapOT	0.72	0.57	0.82	0.02	0.6	0.51	0.61	0.76	0.68	0.63	0.84	0.47	PE	10.21	
pin	EntOT	0.71	0.6	0.82	0.12	0.64	0.58	0.6	0.83	0.62	0.75	0.86	0.54	CircV	9.40	
apj	ClassRegOT	0.74	0.58	0.81	0.11	NA	0.53	0.62	0.97	0.68	0.82	0.89	0.52	IW	8.25	
$ \Sigma $	LinOT	0.73	0.73	0.76	0.18	0.66	0.57	0.64	0.82	0.7	0.76	0.91	0.61	CircV	4.06	
	MMD-LS	0.78	0.72	0.76	0.56	0.65	0.56	0.55	0.97	0.63	0.85	NA	0.5	MixVal	8.22	
မ	JPCA	0.88	0.85	0.66	0.15	0.62	0.48	0.51	0.77	0.69	0.78	0.9	0.54	PE	8.98	
bac	SA	0.74	0.68	0.8	0.11	0.65	0.57	0.56	0.88	0.67	0.78	0.89	0.53	CircV	7.80	
lsq	TCA	0.52	0.47	0.51	0.62	0.04	0.02	0.07	0.61	0.61	0.49	0.48	0.26	DEV	17.58	
Su	TSL	0.88	0.85	0.66	0.2	0.63	0.48	0.45	0.63	0.69	0.45	0.89	0.26	IW	15.09	
5	JDOT	0.72	0.58	0.82	0.13	0.6	0.42	0.59	0.79	0.67	0.65	0.79	0.47	IW	11.42	
the	OTLabelProp	0.72	0.59	0.8	0.07	0.66	0.56	0.62	0.86	0.67	0.64	0.86	0.5	CircV	10.01	
0	DASVM	0.89	0.86	0.65	0.15	NA	NA	NA	0.87	NA	0.83	0.85	NA	MixVal	7.29	

specifically designed for this kind of shift. We believe that using a complex base estimator (here an
SVM with an RBF kernel) enables us to train an estimator that works well on both source and target,
reducing the impact of importance weighting as previously highlighted in (Byrd & Lipton, 2019)
for deep neural networks. The results reported in Table 17 of Appendix D reveal that reweighting
methods significantly outperform Train Src when using a linear base classifier.

Real data with unknown shift. The performance of reweighting methods is often close to Train Src
baseline on real datasets. This result can be be due to the violations of the same-support assumption,
which is crucial for reweighting to work effectively (Segovia-Martín et al., 2023) which is likely true
for the three CV datasets. In this case, hyperparameter tuning frequently select configurations leading
to near-uniform weighting, which explain the close performance to Train Src.

 The performance of mapping methods is dataset-dependent, potentially due to the number of classes and presence of target shift. Mapping methods excel on MNIST/USPS and 20NewsGroup which respectively contain 10 and 2 classes, but failing on Office31 and OfficeHome with 31 and 60 classes. Additionally, while mapping performs well on the NLP dataset 20NewsGroup, it results in negative transfer on Amazon Reviews which has target shifts.

It is notable that simple transformations are the best in average across all modalities. Indeed most
 methods that significantly outperform Train Src in ranking average across all modalities are LinOT,
 CORAL, JPCA, and SA, which all rely on linear transformations such as scaling, linear projection or
 rotations. These methods are robust across datasets and modalities, offering effective alignment with
 minimal risk of negative DA.

Take-away for DA users. Reweighting methods are best suited for scenarios where the same-support assumption holds and perform particularly well when paired with regularized hypotheses like linear models. Even when assumptions are not fully satisfied, reweighting tends to be robust to negative transfer. Mapping methods are highly effective under moderate numbers of classes and in the absence of target shift but carry a significant risk of negative transfer if target shift is present. When the type of distribution shift is uncertain, simpler transformation-based methods like LinOT, CoRAL, JPCA, and SA provide modest performance improvements while minimizing risks of negative DA, making them reliable and safe default options.



Figure 3: Cross-val score as a function of the accuracy for different supervised and unsupervised scorers. The Pearson correlation coefficient is reported for each scorer by ρ . Each point represents an inner split with a DA method (color of the points) and a dataset. A good score should correlate with the target accuracy.

Selected scorer per DA method. We observe that the best scorer differs across methods, Circular Validation has been selected 10 out of 20 times as the best scorer, followed by Importance Weighting 4 out of 20 times. Table 20 in the supplementary material provides the non-realistic accuracy results with the supervised scorer. It is worth noting that the supervised scorer generally outperforms the unsupervised ones, and several methods significantly outperform Train Src in each dataset. It is crucial to choose the model realistically to avoid producing overly optimistic results, as many data analysis papers have done (see Table 4).

These results show the methods' sensitivity to parameter selections and the difficulty of using realistic scorers. This might also explain why DA methods are not widely used in practice: they are very difficult to tune and might decrease performances compared with no adaptation.

4.2 STUDY OF VALIDATION SCORERS

We now investigate the performance of the various scorers to select hyperparameters of the DA method. First, we consider the relationship between the cross-val score and the accuracy for each inner split. In Figure 3, we plot for each scorer the cross-val score as a function of the accuracy computed on the test set and report the Pearson correlation coefficient ρ . As expected, the supervised scorer is highly correlated with the accuracy ($\rho = 0.98$), as it has access to the target labels. We observe that SND, DEV, and PE do not provide a good proxy to select hyperparameters that give the best-performing models ($\rho \leq 0.06$). On the contrary, MixVal, IW and CircV are correlated with the accuracy, $\rho = 0.34$, $\rho = 0.56$ and $\rho = 0.71$ respectively. This is coherent with their selection as the best scorer in most scenarios in Table 2. Still, while those scorers are well correlated with the target accuracy, it is important to note that they have a large variance. For instance, a score close to 1 in IW or CircV corresponds to an accuracy between 0.5 and 1.0.

Furthermore, we provide in Figures 8 and 9, from Appendix D, several visualizations that illustrate the
relationship between the accuracy achieved when using a supervised scorer and the accuracy obtained
when using different unsupervised scorers. We also visualize in Figure 7 the drop in performance
when using the best-unsupervised scorer instead of the supervised scorer. Interestingly some methods
such as KMM, EntOT, and ClassRegOT can lose up to 10% accuracy when using realistic scorers,
which might come from their higher number of parameters or their sensitivity to them.

Our results thus show that most scorers have poor results when evaluated on many datasets. Of the
 five methods under consideration, only two achieve satisfactory performance, although incurring large
 variance in their results. This shows that proper hyperparameter selection is still an open question,
 that needs attention from the research comunity to guide practitioners toward real life applications of
 unsupervised DA technics.

486 4.3 DEEP DA METHODS

488 Although most of the recent work on domain adaptation 489 focus on Deep methods for 490 computer vision tasks, shal-491 low methods are competi-492 tive in many applications 493 such as tabular data (Grinsz-<u>191</u> tajn et al., 2022) or datasets 495 with a relatively small num-496 ber of training examples 497 such as BCI (Chevallier 498 et al., 2024). Moreover, 499 shallow methods can also benefit from recent ad-500 vances in Deep learning by 501 using Deep pre-trained fea-502

Table 3: Accuracy scores for Deep methods on selected real-life datasets using DA scorers. LinOT is reported as the overall top-performing shallow method. Green indicates that the score improved with the DA methods. The darker the color, the more significant the change.

		(N383	S .	10me	255	.or
	MME	office	office	RC1	Selecter	Rank
Train Src	0.85	0.77	0.58	0.54		6.19
Train Tgt	0.98	0.96	0.83	0.56		2.07
DeepCORAL (Sun & Saenko, 2016)	0.93	0.77	0.59	0.54	MixVal	3.29
DAN (Long et al., 2015b)	0.86	0.75	0.56	0.53	IW	4.76
DANN (Ganin et al., 2016a)	0.9	0.79	0.59	0.41	MixVal	4.98
DeepJDOT (Damodaran et al., 2018b)	0.9	0.82	0.62	0.54	PE	2.92
MCC (Jin et al., 2020)	0.93	0.83	0.66	0.53	MixVal	2.38
MDD (Zhang et al., 2019)	0.87	0.78	0.56	0.4	MixVal	4.96
SPA (Xiao et al., 2023b)	0.91	0.78	0.56	0.41	DEV	5.39
LinOT (Flamary et al., 2020)	0.64	0.6	0.57	0.61	CircV	

ture extraction (transfer learning). However, to the best of our knowledge, the literature lacks
quantitative comparison between shallow methods applied on Deep pre-trained feature extraction and
Deep DA methods. To this end, we ran a benchmark using the same pipeline as in Table 2 with three
Domain Invariant Deep DA methods on the CV and BCI datasets.

The results are available in Table 3 with a comparison to the best performing shallow method from 507 Table 2. One of the most notable and expected difference is on MNIST/USPS. Shallow methods 508 struggle to achieve good performances, even on Train Tgt, as they rely on PCA for feature extraction. 509 Deep methods, on the other hand, use CNNs, leading to large accuracy gains on train on Src and 510 Tgt but also on Deep DA methods. However, it is important to note that while DeepJDOT, DANN 511 and MCC improve performance on all datasets, they remain far from the train on Tgt accuracies, 512 partly due to the difficulty in tuning their parameters (see Appendix D.3 with the supervised scorer). 513 The superior performance of Deep DA methods on CV datasets can be attributed to the relationship 514 between classification in the DA subspace and the disentanglement of semantic (discriminant) content 515 from style (domain shift) (Gonzalez-Garcia et al., 2018; Gabbay et al., 2021). Numerous studies 516 have demonstrated that semantic embeddings can be effectively recovered, supporting the assumption 517 that a (nonlinear) subspace shift is reasonable for CV tasks. However, for the BCI dataset, where the amount of data is limited, the performances of Deep DA methods are inferior to some other 518 shallow methods (i.e., LinOT for example). Finally, a method like DANN, which is often considered 519 as a baseline in the community, has been shown to be hard to validate and requires setup that 520 can be difficult to determine across different settings. These results emphasize, that while Deep 521 invariant DA methods can be effective, they do not consistently yield good results across modalities, 522 whereas shallow DA methods can achieve similar or superior performances with less effort and fewer 523 computational resources in low data regimes. 524

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5 CONCLUSION

In this work, we introduced DA-Bench, a extensive benchmark for unsupervised domain adaptation, 528 carefully evaluating the impact of the model selection criteria and covering diverse modalities: 529 computer vision, natural language processing, tabular data and biosignals. While being quite 530 comprehenvise on shallow methods, our results also provide a comparison of three common deep 531 DA baselines on computer vision and biosignals. Importantly DA-Bench can be easily extended 532 with new datasets and methods to push further the state-of-the-art. Our findings reveal that few 533 shallow DA methods consistently perform well across diverse datasets and that model selection 534 scorers significantly influence their effectiveness. While deep DA methods show similar trends, they often require more extensive hyperparameter tuning and architectures tailored to each modality. 536 Notably, they tend to perform significantly better than shallow methods on some modalities, such 537 as computer vision, while facing challenges on others such as biosignals. For each DA method, we provide the optimal model selection scorer for unsupervised hyperparameter tuning based on our 538 experiments.

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Appendix

Reproducibility. The entire code and results of DA-Bench will be open-sourced and available online. The implementation of the DA methods and scorers is provided along with access to the simulated and real-world datasets. All the performance tables and figures can be reproduced effortlessly, and guidelines with minimal working examples are given to add new DA methods and datasets.

Roadmap. In this appendix, we provide additional information regarding the validation procedure used in the literature for each DA method implemented in DA-Bench in Section A. We provide a detailed description of the data and preprocessing used in DA-Bench in Section B. In Section C, we give minimal working Python examples to add a new DA method and dataset in DA-Bench. Finally, we provide the detailed benchmark results in Section D. In particular, the results per dataset can be found in Section D.1. We discuss in Section D.2 the impact of the choice of base estimator on the performance of DA methods for the simulated datasets. The results of each DA method with the supervised scorer on all the datasets are given in Table 20 of Section D.3, which parallels Table 2. A thorough analysis of the effect of using realistic unsupervised scorers is also provided in Section D.6. Finally, the computational efficiency of each DA method is studied in Section D.7 and the hyperparameters used for grid search are given in Section D.8. We display the corresponding table of contents below.

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A MODEL SELECTION IN DOMAIN ADAPTATION

Table 4: Validation procedure in Domain Adaptation methods. NA stands for *not applicable* and means that there are no hyperparameters. None means that no validation procedure has been conducted or that it is not specified in the original paper.

	Method	Validation Procedure	Comment
ß	Density Reweight (Sugiyama & Müller, 2005)	None	Bandwidth fixed by Silverman method
ightir	Discriminative Reweight (Shimodaira, 2000)	NA	No hyperparameters
Rewe	Gaussian Reweight (Shimodaira, 2000)	None	Not specified in (Shimodaira, 2000)
	KLIEP (Sugiyama et al., 2007b)	Integrated CV	Likelihood CV (Sugiyama et al., 2007b)
	KMM (Huang et al., 2006)	None	on target Fixed data-dependent hyperparameters
	NN Reweight (Loog, 2012)	None	Number of neighbors fixed to one
	MMDTarS (Zhang et al., 2013)	CV	Not specified if done on source or target
ing	Coral (Sun et al., 2017)	NA	No hyperparameters
Mappi	OT mapping (Courty et al., 2017b)	CV target/CircCV	Unclear in the text
	Lin. OT mapping (Flamary et al., 2020)	NA	No hyperparameters
	MMD-LS (Zhang et al., 2013)	CV	Not specified if done on source or target
sp.	SA (Fernando et al., 2013)	2-fold CV on source	-
Sub	TCA (Pan et al., 2011)	Validation on target	Target subset used to tune parameters
	TSL (Si et al., 2010)	None	Not specified in (Si et al., 2010)
ler	JDOT (Courty et al., 2017a)	Reverse CV (Zhong et al., 2010)	-
Off	OT label prop (Solomon et al., 2014)	NA	No hyperparameters
	DASVM (Bruzzone & Marconcini, 2010a)	Circular Validation (Bruzzone & Marconcini, 2010a)	-

In Table 4, we provide additional information on the validation procedures used in the original papers that proposed the different domain adaptation methods implemented in DA-Bench. The first column is the name of the method, the second column contains the procedure used to select hyperparameters and the last column provides additional details. What is striking is that many methods do not conduct or specify a validation procedure to select the hyperparameters, which limits the performance of the proposed method on a novel dataset. Several others rely on cross-validation using target data. However, since target labels are typically unavailable in practical scenarios, this validation approach is unrealistic. Overall, many methods have been evaluated with unrealistic or not reproducible validation procedures, making the performance of the proposed methods appear over-optimistic. A key contribution of our work is the extensive comparison of realistic, unsupervised scorers for selecting optimal hyperparameters and base estimators in DA methods.

В

The simulated dataset proves that DA methods can work well under the proper shift (see Table 2).
 However, in real-world applications, we do not have prior knowledge of the type of data shift. Hence, finding the appropriate domain-adaptation method between reweighting, mapping, and subspace

DATASETS DESCRIPTION AND PREPROCESSING

methods is a challenging task. In this section, we introduce 8 real-world datasets coming from different fields. Table 1 summarizes the 8 classification datasets used in this benchmark with the corresponding data modality, preprocessing, number of source-target pairs (# adapt), number of classes, samples, and feature dimensions.

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977 **Computer Vision.** First, three computer vision datasets are proposed: Office31 (Koniusz et al., 2017), Office Home (Venkateswara et al., 2017), and MNIST/USPS (Liao & Carneiro, 2015). We 978 create embeddings for Office31 using the Decaff preprocessing method (Donahue et al., 2014) and for 979 Office Home using a pre-trained ResNet50 (He et al., 2016). These embeddings, as well as vectorized 980 MNIST/USPS, are dimensionally reduced with a Principal Component Analysis (PCA). These three 981 datasets encompass 3, 4, and 3 domains, respectively and all pairs of adaptations are used as DA 982 problems. MNIST/USPS contain clear and blurry images digits, Office31 differentiates between 983 images captured by various devices, while for OfficeHome, its by image style. 984

NLP. The second task is Natural Language Processing (NLP). Two datasets are studied: 20News-group (Lang, 1995) and Amazon Review (McAuley et al., 2015). The 20Newsgroup dataset contains 20.000 documents categorized into 4 categories: *talk, rec, comp*, and *sci*. The learning task is to classify documents across categories. First, the documents are embedded using a Large Language Model (LLM) (Reimers & Gurevych, 2019; Xiao et al., 2023a), and then PCA is applied for dimensionality reduction.

For the Amazon Review dataset, the task is to classify comment ratings. This dataset spans four domains (Books, DVDs, Kitchen, Electronics), and the domain shift results from these varying types of objects. Similar to the 20Newsgroup dataset, comments are embedded using the same LLM and then reduced in dimensionality using a PCA.

Tabular data. We propose two tabular datasets. The first one is the Mushroom dataset (Dai et al., 2007), where the task is to classify whether a mushroom is poisonous or not. The two domains are separated according to the mushroom's stalk shape (enlarging vs. tapering). The tabular data are one-hot-encoded to transform categorical data into numerical data. The second dataset is Phishing (Mohammad et al., 2012). The classification problem involves determining whether a webpage is a phishing or a legitimate one. The domains are separated according to the availability of the IP address. Since the data are already numerical, no preprocessing is done on this dataset.

1003 Biosignals. The last task is BCI Motor Imagery. The dataset used is BCI Competition IV (Tanger-1004 mann et al., 2012), often used in the literature (Barachant et al., 2012) and available in MOABB 1005 (Aristimunha et al., 2023). The task is to classify four kinds of motor imagery (right hand, left 1006 hand, feet, and tongue) from EEG data. In this dataset, nine subjects are available. The domains are 1007 separated based on session number. For each subject, session 1 is considered as the source domain 1008 and session 2 is considered as the target domain. The data are multivariate signals. To embed the data, 1009 we first compute the covariance and then project this covariance on the Tangent Space as proposed in 1010 Barachant et al. (2012).

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C ADDING NEW METHODS AND DATASETS TO DA-BENCH

Using the benchopt framework for this benchmark allows users to easily add novel domain adaptation (DA) methods and datasets. To that end, users should adhere to the benchopt (Moreau et al., 2022) conventions. We provide below the guidelines with examples in Python to add a new DA method and a new dataset to DA-Bench.

1019 C.1 ADDING A NEW DA METHOD

1021 A new DA method can be easily added with the following:

- Create file with a class called Solver that inherits from DASolver and place it in the solvers folder.
- This class should implement a get_estimator() function, which returns a class inheriting from sklearn.BaseEstimator and accepts sample_weight as fit parameter.

In the benchmark we used the Domain Adaptation toolbox SKADA (Gnassounou et al., 2024) that provides many DA estimatos with correct interface.

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We provide below an example of Python implementation to add a new DA method to DA-Bench.

Python snippet code to add a DA method from benchmark_utils.base_solver import DASolver from sklearn.base import BaseEstimator class MyDAEstimator (BaseEstimator): def __init__(self, param1=10, param2='auto'): self.param1 = param1 self.param2 = param2 def fit(self, X, y, sample_weight=None): # sample_weight<0 are source samples</pre> # sample_weight>=0 are target samples # y contains -1 for masked target samples # Your code here : store stuff in self for later predict return self def predict(self, X): # do prediction on target domain here return ypred def predict_proba(self, X): # do probabilistic prediction on target domain here return proba class Solver(DASolver): name = "My_DA_method" # Param grid to validate default_param_grid = { 'param1': [10, 100], 'param2': ['auto', 'manual'] } def get_estimator(self): return MyDAEstimator()

C.2 ADDING A NEW DATASET

1070 A new DA dataset can be easily added with the following:

- Create a file with a class called Dataset that inherits from BaseDataset and place it in the datasets folder.
- This class should implement a get_data() function, which returns a dictionary with keys X, y, and sample_domain.

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We provide below an example of Python implementation to add a new dataset to DA-Bench.

Python snippet code to add a dataset

from sklearn.datasets import make_blobs

X_source, y_source = make_blobs(

X_target, y_target = make_blobs(

sample_domain=sample_domain

n_features=2, random_state=42

n_samples=100, centers=3,

n_samples=100, centers=5,

for source

X_target))

return dict(

n_features=2, random_state=0

from benchopt import BaseDataset

class Dataset(BaseDataset):
 name = "example_dataset"

def get_data(self):

import numpy as np

)

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By following these guidelines, users can seamlessly integrate their own datasets and DA methods into DA-Bench. It results in a user-friendly benchmark that enables fast, reproducible, and reliable comparisons of common and novel DA methods and datasets. We will provide users with precomputed result files and utilities, allowing them to run only the new methods or datasets. This will speed up new comparisons and avoid unnecessary computations.

sample_domain is negative for target sampels and positive

sample_domain = np.array([1] *len(X_source) + [-2] *len(

X=np.concatenate((X_source, X_target), axis=0)

y=np.concatenate((y_source, y_target))

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D BENCHMARK DETAILED RESULTS

1116 D.1 RESULTS PER DATASETS

In Table 2 of the main paper, the reported performance for each method on a given dataset is an average over the number of shifts, i.e., the number of source-target pairs denoted by #adapt in Table 1.
In this section, we provide additional details on the performance of methods for each shift in each dataset. These results are presented in separate tables for each dataset

These detailed tables where cell in green denote a gain wrt Train Src (average outside of standard 1122 deviation of Train Src) better illustrate the challenges of domain adaptation (DA) methods. They 1123 show that not all shifts are equivalent within a given dataset. For example, Table 12 reveals that only 3 1124 shifts in the AmazonReview dataset present a DA problem (defined as a > 3% difference in accuracy 1125 between Train Src and Train Tgt). While for the other shifts, we achieve similar performance whether 1126 we train on source or target data. Additionally, some specific shifts present a DA problem that no 1127 method can successfully address. This can be seen in the dsl \rightarrow amz shift in the Office31 dataset, as 1128 shown in Table 7. Finally, some DA methods perform consistently across all shifts within a dataset, 1129 as demonstrated by the results for the 20Newsgroup dataset in Table 11.

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Table 5: Accuracy score for MNIST/USPS dataset for each shift compared for all the methods. A
white color means the method does not increase the performance compared to Train Src (Train on the
source). Green indicates that the performance improved with the DA methods. The darker the color,
the more significant the change.

		USPS	MIST		
		MAIST	USPS	Mean	Rank
	Train Src	0.66 ± 0.02	0.43 ± 0.02	0.54 ± 0.02	12.00
	Train Tgt	0.96 ± 0.0	0.96 ± 0.01	0.96 ± 0.01	1.00
	Dens. RW	0.66 ± 0.02	0.42 ± 0.02	0.54 ± 0.02	13.25
ы 1 20	Disc. RW	0.6 ± 0.02	0.4 ± 0.02	0.5 ± 0.02	19.00
hti	Gauss. RW	0.11 ± 0.01	0.11 ± 0.01	0.11 ± 0.01	20.00
<u>1</u> g	KLIEP	0.66 ± 0.02	0.43 ± 0.02	0.54 ± 0.02	13.25
Me	KMM	0.64 ± 0.02	0.41 ± 0.03	0.52 ± 0.02	18.00
Re	NN RW	0.66 ± 0.02	0.42 ± 0.02	0.54 ± 0.02	12.00
	MMDTarS	0.66 ± 0.02	0.42 ± 0.02	0.54 ± 0.02	12.75
	CORAL	0.74 ± 0.01	0.51 ± 0.01	0.62 ± 0.01	5.50
00	МарОТ	0.69 ± 0.02	0.54 ± 0.02	0.61 ± 0.02	4.00
jin l	EntOT	0.66 ± 0.02	0.54 ± 0.02	0.6 ± 0.02	5.00
apl	ClassRegOT	0.66 ± 0.01	0.53 ± 0.06	0.59 ± 0.04	11.50
Σ	LinOT	0.74 ± 0.02	0.53 ± 0.02	0.64 ± 0.02	3.25
	MMD-LS	0.66 ± 0.02	0.47 ± 0.02	0.56 ± 0.02	8.25
e.	JPCA	0.66 ± 0.02	0.43 ± 0.02	0.54 ± 0.02	12.00
pac	SA	0.71 ± 0.03	0.36 ± 0.11	0.54 ± 0.07	12.00
lsq	TCA	0.08 ± 0.07	0.11 ± 0.02	0.09 ± 0.05	21.00
Su	TSL	0.66 ± 0.02	0.43 ± 0.02	0.54 ± 0.02	10.50
ler	JDOT	0.73 ± 0.02	0.53 ± 0.02	0.63 ± 0.02	3.50
Oth	OTLabelProp	0.71 ± 0.03	0.53 ± 0.02	0.62 ± 0.02	6.50

Table 6: Accuracy score for MNIST/USPS dataset for each shift compared for all the Deep DA methods. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

		15RE	MAIST	
	MIS	USPS	Mean	Rank
Train Src	0.94	0.76	0.85	5.0
Train Tgt	0.99	0.99	0.99	1.0
DANN	0.94	0.88	0.91	4.0
DeepCORAL	0.97	0.89	0.93	2.5
DeepJDOT	0.96	0.9	0.93	2.5

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Table 8: Accuracy score for Office31 dataset for each shift compared for all the deep DA methods. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

	x	15) ×	AND OF	mi	e e	and r	lej	
	aml	aml	931 21	931	AND .	WED	Mean	Rank
Train Src	0.72	0.75	0.61	0.94	0.63	0.99	0.77	4.17
Train Tgt	0.99	1.0	0.87	0.99	0.88	0.99	0.95	1.25
DANN	0.75	0.8	0.64	0.96	0.62	0.98	0.79	3.75
DeepCORAL	0.77	0.77	0.61	0.98	0.63	0.99	0.79	3.33
DeepJDOT	0.79	0.8	0.68	0.97	0.69	1.0	0.82	2.17



6.50 19.17 16.75 9.25

0.56

 0.74 ± 0.02

 0.43 ± 0.01

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 0.63 ± 0.01

 0.51 ± 0.02

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± 0.01

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JDOT OTLabelProp

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Table 10: Accuracy score for OfficeHome dataset for each shift compared for all the deep DA methods. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

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381	Train Tgt	0.78	0.91	0.86	0.8	0.93	0.85	0.8	0.78	0.86	0.78	0.76	0.92	0.83	1.00
001	DANN	0.44	0.63	0.73	0.58	0.61	0.62	0.54	0.38	0.75	0.67	0.44	0.76	0.6	4.25
382	DeepCORAL	0.47	0.64	0.75	0.63	0.59	0.65	0.59	0.39	0.76	0.7	0.45	0.78	0.62	3.00
383	DeepJDOT	0.47	0.65	0.74	0.63	0.65	0.66	0.59	0.44	0.77	0.71	0.47	0.79	0.63	2.33
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	Train Src Train Tgt	0.65 ± 0.03 0.71 ± 0.02	0.71 ± 0.02 0.77 ± 0.01	0.72 ± 0.01 0.74 ± 0.01	0.66 ± 0.02 0.69 ± 0.03	0.72 ± 0.01 0.76 ± 0.01	0.69 ± 0.01 0.72 ± 0.01	0.71 ± 0.01 0.72 ± 0.02	0.75 ± 0.01 0.76 ± 0.01	0.71 ± 0.02 0.72 ± 0.01	0.7 ± 0.02 0.72 ± 0.01	0.71 ± 0.01 0.71 ± 0.01	0.7 ± 0.01 0.73 ± 0.01	3.45 1.00
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	Dens. RW	0.65 ± 0.03	0.71 ± 0.02	0.72 ± 0.01	0.65 ± 0.02	0.72 ± 0.01	0.69 ± 0.01	0.71 ± 0.01	0.74 ± 0.01	0.71 ± 0.02	0.7 ± 0.02	0.71 ± 0.01	0.7 ± 0.02	6.82
ສີເ	Disc. RW	0.63 ± 0.01	0.71 ± 0.01	0.72 ± 0.01	0.64 ± 0.02	0.7 ± 0.01	0.68 ± 0.03	0.62 ± 0.05	0.73 ± 0.01	0.7 ± 0.02	0.69 ± 0.01	0.7 ± 0.01	0.68 ± 0.02	7.32
iin	Gauss. RW	0.53 ± 0.01	0.62 ± 0.01	0.54 ± 0.06	0.38 ± 0.06	0.51 ± 0.15	NA	NA	0.62 ± 0.01	NA	NA	NA	0.53 ± 0.05	19.33
lgi	KLIEP	0.65 ± 0.03	0.69 ± 0.04	0.72 ± 0.01	0.66 ± 0.02	0.72 ± 0.01	0.69 ± 0.03	NA	0.75 ± 0.01	0.65 ± 0.06	0.68 ± 0.03	0.71 ± 0.01	0.69 ± 0.02	6.30
9M3	KMM	0.52 ± 0.04	0.63 ± 0.01	0.6 ± 0.04	0.5 ± 0.02	0.64 ± 0.04	0.28 ± 0.2	NA	0.63 ± 0.05	0.66 ± 0.03	0.64 ± 0.03	0.58 ± 0.02	0.57 ± 0.05	16.10
Ъ	NN RW	0.59 ± 0.05	0.69 ± 0.01	0.71 ± 0.03	0.51 ± 0.1	0.66 ± 0.06	0.68 ± 0.03	NA	0.71 ± 0.04	0.7 ± 0.02	0.65 ± 0.02	0.68 ± 0.02	0.66 ± 0.04	10.65
	MMDTarS	0.65 ± 0.03	0.7 ± 0.02	0.72 ± 0.01	0.67 ± 0.01	0.72 ± 0.01	0.7 ± 0.01	0.71 ± 0.02	0.74 ± 0.01	0.7 ± 0.03	0.7 ± 0.02	0.71 ± 0.02	0.7 ± 0.02	7.55
	CORAL	0.62 ± 0.03	0.72 ± 0.01	0.73 ± 0.01	0.61 ± 0.01	0.72 ± 0.01	0.69 ± 0.01	NA	NA	0.7 ± 0.01	0.7 ± 0.01	0.7 ± 0.02	0.69 ± 0.01	4.56
3	MapOT	0.6 ± 0.01	0.7 ± 0.0	0.71 ± 0.01	0.59 ± 0.01	0.7 ± 0.0	0.68 ± 0.01	0.69 ± 0.01	0.73 ± 0.02	0.69 ± 0.01	0.69 ± 0.01	0.64 ± 0.01	0.67 ± 0.01	9.36
uiq	EntOT	0.53 ± 0.01	0.62 ± 0.0	0.64 ± 0.0	0.53 ± 0.0	0.62 ± 0.0	0.65 ± 0.0	0.66 ± 0.01	0.74 ± 0.01	0.64 ± 0.0	0.64 ± 0.0	0.54 ± 0.0	0.62 ± 0.0	13.86
dej	ClassRegOT	0.68 ± 0.02	0.72 ± 0.02	0.69 ± 0.03	0.67 ± 0.02	0.72 ± 0.02	0.61 ± 0.01	0.61 ± 0.02	0.69 ± 0.03	0.65 ± 0.02	0.65 ± 0.02	0.7 ± 0.02	0.67 ± 0.02	9.00
M	LinOT	0.64 ± 0.03	0.73 ± 0.02	0.73 ± 0.01	0.61 ± 0.01	0.73 ± 0.0	0.69 ± 0.02	NA	0.74 ± 0.01	0.71 ± 0.02	0.7 ± 0.02	0.7 ± 0.02	0.7 ± 0.02	3.60
	MMD-LS	0.56 ± 0.02	0.54 ± 0.03	0.72 ± 0.01	0.63 ± 0.06	0.61 ± 0.16	0.65 ± 0.1	0.55 ± 0.15	NA	0.63 ± 0.11	0.48 ± 0.01	0.71 ± 0.01	0.61 ± 0.07	14.30
ə:	JPCA	0.61 ± 0.0	0.69 ± 0.01	0.69 ± 0.01	0.63 ± 0.01	0.69 ± 0.0	0.68 ± 0.01	0.68 ± 0.01	0.7 ± 0.01	0.67 ± 0.01	0.68 ± 0.01	0.64 ± 0.01	0.67 ± 0.01	10.14
bed	SA	0.62 ± 0.02	0.72 ± 0.01	0.73 ± 0.02	0.62 ± 0.01	0.72 ± 0.01	0.69 ± 0.01	0.69 ± 0.01	0.74 ± 0.02	0.71 ± 0.02	0.7 ± 0.01	0.69 ± 0.03	0.69 ± 0.02	8.27
squ	TCA	0.52 ± 0.0	0.62 ± 0.0	0.64 ± 0.0	0.52 ± 0.0	0.62 ± 0.0	0.64 ± 0.0	0.64 ± 0.0	0.62 ± 0.0	0.64 ± 0.0	0.64 ± 0.0	0.52 ± 0.0	0.6 ± 0.0	18.45
۱S	TSL	0.65 ± 0.03	0.71 ± 0.02	0.72 ± 0.01	0.66 ± 0.02	0.72 ± 0.01	NA	NA	0.75 ± 0.01	0.71 ± 0.02	0.7 ± 0.02	0.71 ± 0.01	0.7 ± 0.02	5.94
JGL	JDOT	0.61 ± 0.01	0.71 ± 0.01	0.72 ± 0.01	0.6 ± 0.01	0.7 ± 0.0	0.63 ± 0.01	NA	0.71 ± 0.02	0.69 ± 0.02	0.69 ± 0.01	0.67 ± 0.03	0.67 ± 0.01	8.75
₽С	OTLabelProp	0.6 ± 0.01	0.69 ± 0.01	0.7 ± 0.01	0.59 ± 0.01	0.69 ± 0.01	0.68 ± 0.02	0.69 ± 0.02	0.74 ± 0.01	0.69 ± 0.01	0.69 ± 0.0	0.64 ± 0.01	0.67 ± 0.01	9.32
,					-					-				

Table 13: Accuracy score for Mushrooms dataset for each shift compared for all the methods. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

		871-X29	tap enl	Mean	Rank
	Train Src	0.67 ± 0.01	0.77 ± 0.01	0.72 ± 0.01	8.50
	Train Tgt	1.0 ± 0.0	1.0 ± 0.0	1.0 ± 0.0	1.00
	Dens. RW	0.67 ± 0.01	0.76 ± 0.0	0.71 ± 0.01	9.00
<u></u>	Disc. RW	0.73 ± 0.06	0.78 ± 0.01	0.75 ± 0.04	4.50
ltir	Gauss. RW	0.56 ± 0.0	0.46 ± 0.0	0.51 ± 0.0	17.50
<u>1</u> 2	KLIEP	0.66 ± 0.02	0.77 ± 0.01	0.72 ± 0.01	10.75
N N	KMM	0.7 ± 0.02	0.78 ± 0.01	0.74 ± 0.01	6.00
Re	NN RW	0.67 ± 0.05	0.75 ± 0.01	0.71 ± 0.03	12.00
	MMDTarS	0.7 ± 0.02	0.77 ± 0.01	0.74 ± 0.01	6.00
	CORAL	0.66 ± 0.02	0.77 ± 0.01	0.72 ± 0.02	11.50
ac	MapOT	0.65 ± 0.01	0.62 ± 0.02	0.63 ± 0.01	14.00
pin	EntOT	0.82 ± 0.01	0.67 ± 0.01	0.75 ± 0.01	8.00
apj	ClassRegOT	0.63 ± 0.01	0.62 ± 0.01	0.62 ± 0.01	15.50
	LinOT	0.72 ± 0.01	0.81 ± 0.01	0.76 ± 0.01	4.00
	MMD-LS	0.85 ± 0.01	NA	0.85 ± 0.01	4.00
ce	JPCA	0.64 ± 0.02	0.78 ± 0.02	0.71 ± 0.02	10.00
spa	SA	0.53 ± 0.02	0.86 ± 0.01	0.7 ± 0.02	10.00
OtBab	OTLabelProp	0.68 ± 0.01	0.61 ± 0.01	0.64 ± 0.01	11.50

Table 14: Accuracy score for Phishing dataset for each shift compared for all the methods. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

		÷.	2-attess si	2-attess	
		iP-adress-no-	10 Patters 1	Mean	Rank
	Train Src	0.94 ± 0.01	0.88 ± 0.01	0.91 ± 0.01	7.0
	Train Tgt	0.97 ± 0.01	0.97 ± 0.01	0.97 ± 0.01	1.0
	Dens. RW	0.94 ± 0.01	0.88 ± 0.01	0.91 ± 0.01	6.5
ng	Disc. RW	0.94 ± 0.01	0.88 ± 0.01	0.91 ± 0.01	9.5
hti	Gauss. RW	0.51 ± 0.0	0.41 ± 0.0	0.46 ± 0.0	20.0
eig	KLIEP	0.94 ± 0.01	0.89 ± 0.01	0.91 ± 0.01	5.0
6 M	KMM	0.94 ± 0.01	0.89 ± 0.02	0.91 ± 0.01	6.5
R	NN RW	0.94 ± 0.01	0.89 ± 0.01	0.91 ± 0.01	6.5
	MMDTarS	0.94 ± 0.01	0.88 ± 0.01	0.91 ± 0.01	5.5
	CORAL	0.93 ± 0.01	0.91 ± 0.01	0.92 ± 0.01	5.5
50	MapOT	0.83 ± 0.01	0.84 ± 0.03	0.84 ± 0.02	15.0
pin	EntOT	0.87 ± 0.04	0.85 ± 0.03	0.86 ± 0.04	16.0
apj	ClassRegOT	0.87 ± 0.02	0.89 ± 0.02	0.88 ± 0.02	9.0
Σ	LinOT	0.91 ± 0.01	0.9 ± 0.02	0.91 ± 0.02	7.0
	MMD-LS	NA	0.88 ± 0.01	0.88 ± 0.01	11.5
ce	JPCA	0.92 ± 0.01	0.89 ± 0.01	0.9 ± 0.01	8.0
spa	SA	0.9 ± 0.02	0.88 ± 0.02	0.89 ± 0.02	11.0
nbs	TSL	0.88 ± 0.02	0.84 ± 0.02	0.86 ± 0.02	14.0
S S	JDOT	0.8 ± 0.02	0.8 ± 0.01	0.8 ± 0.02	18.0
the	OTLabelProp	0.86 ± 0.01	0.86 ± 0.01	0.86 ± 0.01	16.0
0	DASVM	NA	0.88 ± 0.01	0.88 ± 0.01	15.0

1620	red																				
1621	e.		9	4	- 0	4	~	6	<u> </u>		5	_	6	n o		∞	ε	0	0	0	_
1622	- ngu	Up .	8.5	1.4	9.6 8 8	0.4. 1.4.	8.1	0.8	0.6 1	8.1	2.6	1.1	9.3	5. 1.0	0.1	2.7	6.3	9.5	0.0	2.0	3.1
1623	e c cha	Ŷ				10		—	—	_		_		_			_	_	2	_	
1624	he		90	05	90	010	90	90	90	8	07	05	05	90	.1	8	07	07	05	8	8
1625	ut t		0.0	0.	0.0	\sim	0.	0	<u>.</u>	<u>o</u>	0.	0.		0.0	; +	<u> 0</u>	0.	0.	0.	0.1	<u>.</u>
1626	s ica	8	5 1	4	5 1	1 ⊡	5	<u>п</u>	4	5	2 1	F L.	4		51		F 6		5	- 9	⊓
1627	pe	¥	0.5	0.6	0.5	0.2	0.5	0.5	0.5	0.5	0.6	0.4	0.5	0.5	; o	0.5	0.5	0.2	0.2	0.4	
1628	sig		_ `	9	6 0	、 <u></u>	8	7	<u> </u>	8	9	S	9	9 6	- 00	6	9	_	З	S	6
1629	re re		0.0	0.0	0.0	0.0	0.0	0.0	0.0 1	<u>:</u>	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.	0.0	0.0	0.0
1630	rea mo		4	H	++ ++	+	+	H	++ •	+	+	╢	++ •	+++++++++++++++++++++++++++++++++++++++	+++		H	± 6	++	++	H
1631	inc he	6	0.5	.61	.53	.25	.55	.52	5.	.54	.56	.49	.52	64. 67	64.	164.	.54	0.2	.22	.49	0.5
1632	iot r, t	0					0	0		_	$^{\circ}$	0				II-	0	_	_	<u> </u>	_
1633	ss n olo		.08	.03	90.5	50.	.08	0.	<u> </u>	6	0.1	.08	.07	02	.12	12	.07	0.1	60.	.05	3
1634	doe e c			0	юс + +		0	0	0 (+ -	-	+	0 +	0				0	H			-
1635	c th		69	∞	5	32	69	4	80	69	.75	61	4	2.7	. 99	80	73	.31	2	62	g
1636	eth. ike	Ք	ö		o c	; ;	õ	õ	õ	õ		ö	0		õ	ō	ö		0	ö	õ
1637	dar		50	03	90	35	07	60	10	5	05	4	01	82	8	90	.1	90	01	60	9
1638	the		0.0	0.	0.0	0	0.0	0.0	0.0	õ	0.0	0.0	0.0	0.0	0.0	0.0	0	0.0	0.0	0.	õ
1639	ns . T		15	5 +	+ +	- ++	33	4	$\frac{1}{2}$	11	3	3 +	+	+ + 	- + -	4	99	4	€	$\frac{3}{10}$	ام ا
1640	nea	<	0.0	0.7	0.6	0.2	0.6	0.6	0.6	0.6	0.7	0.5	0.6	0.0	0.6	0.6	0	0.2	0.2	0.5	0.5
1641	or r ethe		9	9	Γx		8	~	ŝ	9	9	Ś	21			ω	9	~	4	3	9
1642	in me		0.0	0.0	0.0	0.0	0.0	0.0	0.0 î	0:0	0.0	0.0	0.0	0.0	<u>;</u> 0	0.0	0.0	0.0	0.0	0.0	0.0
1643	DA		++ -	H	++ +	+++	$+\!\!\!+\!\!\!$	H	÷H	++	H	╢	++ •	++ +	14	H	H	+	+	++ -	H
1644	vhi Je J	.0	.41	.47	4.0	.25	.41	4.0	<u>4</u>	<u>4</u>	.44	.29	.33	.31 74	0.3	.33	0.4	.26	.27	0.3	
1645	Αv htł			-			0		0	0	0	0	-		>			0	0		-
1646	ls. wit		9.0	.08	40.0	0.01	6.0	60.0	90. 100	<u>5</u>	.05	.04	.06	40. 2	.05	05	. 04	.05	.07	2	6
1647	pou ed r			0			0	0	0 (+ -	-		0	0 (+ -				0	0			-
1648	ove 10		39	41	39 :	52	39	31	30	39	45	32	33	35	39	31	39	57	23	58	33
1649	e n npr	r	o,	0	<u> </u>	<u> </u>	o.	o.	<u>.</u>	o'	Ö	o.	<u>o</u>	o c	0	lo.	o.	o.	<u>.</u>	o.	o'
1650	l th e ir		90	40	90	55	50	2	60	90	08	03	23	5 8	3 =	5	07	.1	03	50	3
1651	r al inc		0	Ö	0.0	ò	ö	ö	ö	Ö	Ö	ö	ö	o e	ò	lo.	ö	+	Ö	Ö,	õ
1652	foi		± 6	$\frac{2}{1}$	5 + 6	1 + 1	*	4		5	16	+	++ ·	4 ×	2 H		∞ ++	24	79	6	+
1653	for	۵	4.0	0.5	0.0	0.7	0.4	4.0	4.0	o	0.4	0.3	0.3	o 2	0.3	0.4	0.4	0	0.2	0.3	0. 4.
1654	per		S	3	4 v	, - -	4	5	ŝ	S	4	S	9		- 9	9	3	7	5	S	2
1655	he		0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.0
1656	ft c at t		++ •	H	++ ++	+	+	+H	++ -	+	H	++	++ -	++ ++	+	1	$+\!\!+\!\!$	÷	+	++ ·	Η
1657	shi sth	£	.72	.82	772		.71	.74	.69	.73	.81	.64	.79	17.(07.(.63	.72	0.8	.24	.27	.61	.04
1658	ates	C	E	_				-									_	-			_
1659	r ea dic:		0.05	.01	0.05	5 0 0	.04	30.0	0.05	0.0	0.06	0.04	0.05	10.0).13	0.05	50'(0.03	0.05	90.0	Š.
1660	inc inc		\mathbb{H}	— —	+++	- H	+	+	+	+	+	+	++ -	+++++++++++++++++++++++++++++++++++++++	- H		+	+	+	H	
1661	iset een		51	61	515	52	52	45	45	52	56	35	42	43 7 43	46	39	58	26	26	37	.
1662	Gre	6	0.	o.	o c	<u> </u>	o.	o.	<u>.</u>	o.	o.	o.	<u> </u>	<u> </u>	<u> </u>	lo.	o.	o.	0	0	
1663	J d (05	05	90	50	05	90	8	8	08	08	01	5		10).1	60	8	5	90
1664	BC BC		0.0	0.	0.0	\sim	0.	0.	<u>.</u>	<u>o</u>	0.	0.		0. H			+	0.	0.	0.	<u>.</u>
1665	for sou		F 6	4	± 6		∓ 6	1	x	6	T H	1		1]	.66		74	T	4	ΨL	$\frac{\alpha}{1}$
1666	he	1	0.5	0.7	0.5	0.2	0.5	0.6	0.5	0.5	0.7	0.6	0.6	0.6	õ	0.5	0	0.3	0.2	0.5	0.6
1667	sco n t			_		-		_		=	-	_	_			╞					0.
1668	с Ц				5.	ß			ı	s				OT							<u>E</u>
1669	ura Irai		Src	Γ_{g}	RV	R.	۵.		≥ 1	Tar	F	F	L	Şeg	F						bell
1670	s (J		ling .	un	us.	uss.	Έ	Ą	N I	θI	NR^	Ođ	ē,	asst	ξĘ			Ą	Ц	5	La
1671	Sr(Ľ,	Tr		g B	R	\mathbf{Z}	Ź,	Ξ	Ы	ũ	Ξ	ij.	Ξ	Į	SA	Ę	SL	Ŕ	5
1672	s 15 ain				5	lum	នោះ) Ma	ы			gı	пd	IEIN		a l	bgc	sor	າຕ	ເວເ	10
1673	lble Tr:					ite	1~:*		d			51	-;	~°J/\			u	- 41	.2	-94	ΨU
	Ta to																				

Table 16: Accuracy score for BCI dataset for each shift compared for all the deep DA methods. A
white color means the method does not increase the performance compared to Train Src (Train on the
source). Green indicates that the performance improved with the DA methods. The darker the color,
the more significant the change.

	~	S	ი	\triangleright	5	6	1	Φ	9	Mean	Rank
Train Src	0.59	0.29	0.67	0.43	0.38	0.29	0.67	0.76	0.67	0.53	2.61
Train Tgt	0.57	0.43	0.71	0.53	0.34	0.29	0.62	0.69	0.79	0.55	2.17
DANN	0.52	0.24	0.55	0.38	0.4	0.22	0.38	0.66	0.64	0.44	4.44
DeepCORAL	0.55	0.26	0.66	0.36	0.48	0.33	0.57	0.72	0.66	0.51	2.72
DeepJDOT	0.53	0.34	0.64	0.43	0.43	0.43	0.57	0.62	0.6	0.51	3.17

D.2 IMPACT OF THE BASE ESTIMATORS ON THE SIMULATED DATASETS

As mentioned in the main paper, it is possible to partly compensate for the shift by choosing the right base estimator. In this part, we provide the results on the Simulated dataset for three different base estimators: Logistic Regression (LR) in Table 17, SVM in Table 18, and XGBoost in Table 19. Observing the two first rows for covariate shift, we see that with LR (Table 17), there is a significant drop in performance between training on the source v.s. training on the target ($\sim 10\%$), while using SVC (Table 18) only leads to a drop ($\sim 3\%$). Finally, using XGBoost (Table 19) maintains the performance. The reweighting DA methods help compensate for the shift when using a simpler LR estimator. However when using an SVC, as shown in the main paper, the reweighting does not help to compensate for the covariate shift. If we look at the other shifts, the problem is harder. The subspace methods help with subspace shift, and the mapping methods help with the conditional shift.

1698 These Tables show the importance of choosing the right base estimator. It is clear that choosing an 1699 appropriate base estimator can partially compensate for some shifts.

Table 17: Accuracy score for simulated datasets compared for all the methods with LR. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

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		Shift	hill	a. shile	shift	•	•1
		CON	~31. ³	Cond	540.	Mean	Rank
	Train Src	0.8 ± 0.02	0.81 ± 0.03	0.68 ± 0.03	0.06 ± 0.01	0.59 ± 0.02	10.50
	Train Tgt	0.91 ± 0.02	0.92 ± 0.01	0.79 ± 0.03	0.97 ± 0.01	0.9 ± 0.02	2.00
	Dens. RW	0.88 ± 0.03	0.84 ± 0.04	0.66 ± 0.03	0.07 ± 0.02	0.61 ± 0.03	7.50
g	Disc. RW	0.55 ± 0.02	0.78 ± 0.05	0.7 ± 0.04	0.06 ± 0.01	0.52 ± 0.03	13.25
lti	Gauss. RW	0.89 ± 0.02	0.85 ± 0.03	0.64 ± 0.03	0.06 ± 0.01	0.61 ± 0.02	8.00
igl	KLIEP	0.8 ± 0.02	0.81 ± 0.04	0.69 ± 0.03	0.07 ± 0.02	0.59 ± 0.03	8.25
Me	KMM	0.84 ± 0.03	0.82 ± 0.05	0.66 ± 0.04	0.07 ± 0.02	0.6 ± 0.04	7.88
Re	NN RW	0.81 ± 0.02	0.82 ± 0.04	0.67 ± 0.03	0.07 ± 0.01	0.59 ± 0.03	7.75
	MMDTarS	0.8 ± 0.02	0.84 ± 0.04	0.66 ± 0.03	0.07 ± 0.02	0.59 ± 0.03	10.75
	CORAL	0.73 ± 0.05	0.68 ± 0.11	0.75 ± 0.08	0.04 ± 0.02	0.55 ± 0.06	12.25
00	MapOT	0.73 ± 0.03	0.6 ± 0.04	0.79 ± 0.03	0.03 ± 0.01	0.54 ± 0.03	13.75
pin	EntOT	0.72 ± 0.05	0.61 ± 0.04	0.79 ± 0.03	0.03 ± 0.01	0.54 ± 0.03	12.50
ap	ClassRegOT	0.87 ± 0.08	0.59 ± 0.04	0.79 ± 0.03	0.03 ± 0.01	0.57 ± 0.04	11.50
Σ	LinOT	0.77 ± 0.03	0.65 ± 0.06	0.76 ± 0.04	0.04 ± 0.02	0.56 ± 0.04	12.00
	MMD-LS	0.7 ± 0.1	0.64 ± 0.06	0.78 ± 0.04	0.38 ± 0.22	0.63 ± 0.1	10.75
e	JPCA	0.8 ± 0.02	0.81 ± 0.03	0.68 ± 0.03	0.06 ± 0.01	0.59 ± 0.02	11.25
pac	SA	0.8 ± 0.02	0.62 ± 0.04	0.78 ± 0.03	0.04 ± 0.02	0.56 ± 0.03	11.25
bs]	TCA	0.44 ± 0.29	0.49 ± 0.06	0.54 ± 0.11	0.54 ± 0.23	0.5 ± 0.17	15.50
Su	TSL	0.8 ± 0.02	0.81 ± 0.03	0.68 ± 0.03	0.06 ± 0.01	0.59 ± 0.02	11.00
Other	OTLabelProp	0.73 ± 0.03	0.59 ± 0.04	0.79 ± 0.03	0.03 ± 0.01	0.53 ± 0.03	13.50

Table 18: Accuracy score for simulated datasets compared for all the methods with SVC. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

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1746				·X.	niff.	:85/		
1747			N: 311	- Shir	nd.3	N. 301	2311	N.
1748			007	7 31.	COF	SIL	Ave.	Par
1749		Train Src	0.88 ± 0.03	0.85 ± 0.04	0.66 ± 0.02	0.19 ± 0.03	0.65 ± 0.03	9.38
1750		Train Tgt	0.92 ± 0.02	0.93 ± 0.02	0.82 ± 0.03	0.98 ± 0.01	0.91 ± 0.02	1.25
1751		Dens. RW	0.88 ± 0.03	0.86 ± 0.04	0.66 ± 0.02	0.18 ± 0.04	0.64 ± 0.03	8.88
1752	Зg	Disc. RW	0.85 ± 0.04	0.83 ± 0.04	0.72 ± 0.04	0.18 ± 0.03	0.64 ± 0.04	10.75
1753	htiı	Gauss. RW	0.89 ± 0.03	0.86 ± 0.04	0.65 ± 0.02	0.21 ± 0.04	0.65 ± 0.03	7.00
1754	eig]	KLIEP	0.88 ± 0.03	0.86 ± 0.04	0.66 ± 0.02	0.19 ± 0.03	0.65 ± 0.03	8.12
1755	ewe	KMM	0.89 ± 0.03	0.87 ± 0.04	0.64 ± 0.04	0.15 ± 0.05	0.64 ± 0.04	9.50
1756	Re	NN RW	0.89 ± 0.03	0.86 ± 0.04	0.67 ± 0.02	0.15 ± 0.04	0.64 ± 0.03	9.12
1757		MMDTarS	0.88 ± 0.03	0.86 ± 0.04	0.64 ± 0.03	0.2 ± 0.04	0.65 ± 0.03	9.12
1758		CORAL	0.74 ± 0.04	0.7 ± 0.11	0.76 ± 0.08	0.18 ± 0.04	0.59 ± 0.07	11.50
1759	50	МарОТ	0.72 ± 0.04	0.57 ± 0.04	0.82 ± 0.03	0.02 ± 0.01	0.53 ± 0.03	14.25
1760	pin	EntOT	0.71 ± 0.04	0.6 ± 0.04	0.82 ± 0.03	0.12 ± 0.06	0.56 ± 0.05	12.75
1761	ap	ClassRegOT	0.74 ± 0.09	0.58 ± 0.04	0.81 ± 0.03	0.11 ± 0.06	0.56 ± 0.06	12.75
1701	Μ	LinOT	0.73 ± 0.05	0.73 ± 0.08	0.76 ± 0.06	0.18 ± 0.04	0.6 ± 0.06	11.75
1762		MMD-LS	0.65 ± 0.08	0.68 ± 0.11	0.79 ± 0.05	0.55 ± 0.31	0.67 ± 0.14	10.75
1763	e	JPCA	0.88 ± 0.03	0.85 ± 0.04	0.66 ± 0.02	0.15 ± 0.05	0.64 ± 0.04	11.25
1764	pac	SA	0.74 ± 0.04	0.68 ± 0.04	0.8 ± 0.03	0.11 ± 0.03	0.58 ± 0.03	12.50
1765	lsq	TCA	0.46 ± 0.21	0.48 ± 0.09	0.55 ± 0.11	0.56 ± 0.2	0.51 ± 0.15	15.62
1766	Su	TSL	0.88 ± 0.03	0.85 ± 0.04	0.66 ± 0.02	0.19 ± 0.03	0.65 ± 0.03	9.62
1767	er							
1768	Oth	OTLabelProp	0.72 ± 0.04	0.58 ± 0.04	0.81 ± 0.04	0.04 ± 0.05	0.54 ± 0.04	14.00

Table 19: Accuracy score for simulated datasets compared for all the methods with XGBoost. A white color means the method does not increase the performance compared to Train Src (Train on the source). Green indicates that the performance improved with the DA methods. The darker the color, the more significant the change.

		mill		shift	nift		
		C04.51	(131: SI	Condi	540.51	Mean	Rank
	Train Src	0.89 ± 0.02	0.84 ± 0.04	0.66 ± 0.03	0.21 ± 0.03	0.65 ± 0.03	9.25
	Train Tgt	0.89 ± 0.02	0.93 ± 0.02	0.77 ± 0.03	0.98 ± 0.01	0.89 ± 0.02	2.25
	Dens. RW	0.88 ± 0.03	0.84 ± 0.03	0.67 ± 0.03	0.22 ± 0.04	0.65 ± 0.03	8.25
<u></u>	Disc. RW	0.68 ± 0.06	0.84 ± 0.03	0.66 ± 0.03	0.2 ± 0.03	0.6 ± 0.04	12.25
hti	Gauss. RW	0.87 ± 0.03	0.84 ± 0.03	0.67 ± 0.03	0.22 ± 0.03	0.65 ± 0.03	9.12
<u>16</u>	KLIEP	0.88 ± 0.03	0.84 ± 0.03	0.67 ± 0.03	0.21 ± 0.03	0.65 ± 0.03	7.12
- Mo	KMM	0.87 ± 0.04	0.84 ± 0.04	0.67 ± 0.04	0.22 ± 0.04	0.65 ± 0.04	7.62
Re	NN RW	0.88 ± 0.03	0.84 ± 0.04	0.66 ± 0.03	0.2 ± 0.03	0.65 ± 0.03	10.50
	MMDTarS	0.88 ± 0.03	0.86 ± 0.04	0.63 ± 0.03	0.22 ± 0.03	0.65 ± 0.03	7.50
	CORAL	0.71 ± 0.04	0.71 ± 0.11	0.74 ± 0.08	0.17 ± 0.05	0.58 ± 0.07	12.75
a	MapOT	0.7 ± 0.04	0.59 ± 0.03	0.8 ± 0.03	0.17 ± 0.05	0.56 ± 0.04	13.25
pin	EntOT	0.69 ± 0.05	0.61 ± 0.04	0.8 ± 0.03	0.2 ± 0.02	0.57 ± 0.04	12.25
ap	ClassRegOT	0.82 ± 0.11	0.59 ± 0.03	0.8 ± 0.03	0.16 ± 0.04	0.59 ± 0.05	12.00
Σ	LinOT	0.72 ± 0.04	0.68 ± 0.06	0.76 ± 0.04	0.19 ± 0.04	0.59 ± 0.05	12.00
	MMD-LS	0.64 ± 0.07	0.68 ± 0.08	0.78 ± 0.04	0.59 ± 0.25	0.67 ± 0.11	10.25
e e	JPCA	0.88 ± 0.03	0.84 ± 0.03	0.67 ± 0.03	0.14 ± 0.05	0.63 ± 0.03	10.50
pac	SA	0.72 ± 0.04	0.69 ± 0.04	0.78 ± 0.03	0.13 ± 0.04	0.58 ± 0.04	11.75
ps	TCA	0.48 ± 0.05	0.5 ± 0.05	0.51 ± 0.05	0.51 ± 0.06	0.5 ± 0.05	15.50
Su	TSL	0.89 ± 0.02	0.84 ± 0.04	0.66 ± 0.03	0.21 ± 0.03	0.65 ± 0.03	9.25
Other	OTLabelProp	0.72 ± 0.05	0.59 ± 0.04	0.81 ± 0.04	0.04 ± 0.05	0.54 ± 0.04	13.00

D.3 UNREALISTIC VALIDATION WITH SUPERVISED SCORER

Table 20 shows the results when we choose the supervised scorer that is when validating on target labels. It is important to highlight that this choice is impossible in real life applications due to the lack of target labels. When using the target labels, the method's parameters are better validated. This can be seen by the significant increase in the table (blue values), which are numerous in this table compared to the one with the selected realistic scorer. For example, the method MMDTarS, which is made for Target shift, compensates all the shift simulated covariate shifts when we select the model with a supervised scorer. When looking at the rank, 11 DA methods have a higher rank than Train Src compared to 9 when using realistic scorer. The findings hold for Deep DA where the accuracy in Table 21 is overall better than when using unsupervised scorers.

Table 20: Accuracy score for all datasets compared for all the methods for simulated and real-life datasets. In this table, each DA method is validated with the supervised scorer. The color indicates the amount of the improvement. A white color means the method is not statistically different from Train Src (Train on source). Blue indicates that the performance improved with the DA methods, while red indicates a decrease. The darker the color, the more significant the change.

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		co3.	57 - 53 5 - 53	il ond	, 	it office	" office	1 Male	, ofer	N' Mal	s. Mish	ohishi	no Cl	ant
	True in Case		<u>`\%</u>		√	0	0.50	<u> </u>		V7	5	x ⁷	V 0.55	₩ 10((
	Train Src	0.88	0.85	0.66	0.19	0.65	0.56	0.54	0.59	0.7	0.72	0.91	0.55	10.66
	Irain Igt	0.92	0.93	0.82	0.98	0.89	0.8	0.96	1.0	0.73	1.0	0.97	0.64	1.55
	Dens. RW	0.89	0.87	0.67	0.2	0.65	0.56	0.54	0.59	0.7	0.76	0.91	0.55	12.20
ng ng	Disc. RW	0.86	0.84	0.73	0.23	0.64	0.54	0.54	0.62	0.69	0.78	0.91	0.56	8.75
hti	Gauss. RW	0.89	0.86	0.65	0.21	0.22	0.44	0.11	0.54	0.55	0.51	0.46	0.25	16.45
.5 .1 0	KLIEP	0.89	0.88	0.66	0.2	0.65	0.56	0.54	0.58	0.7	0.75	0.92	0.55	10.56
Mé	KMM	0.89	0.87	0.67	0.19	0.64	0.55	0.53	0.71	0.66	0.75	0.92	0.54	11.74
Re	NN RW	0.89	0.86	0.67	0.15	0.65	0.55	0.55	0.59	0.66	0.72	0.91	0.54	9.15
	MMDTarS	0.88	0.93	0.66	0.27	0.65	0.56	0.54	0.59	0.7	0.74	0.91	0.56	10.81
	CORAL	0.74	0.84	0.82	0.19	0.66	0.57	0.62	0.75	0.7	0.72	0.92	0.62	5.08
ac	MapOT	0.87	0.63	0.82	0.14	0.6	0.51	0.6	0.77	0.68	0.63	0.84	0.47	10.21
jin	EntOT	0.89	0.61	0.82	0.47	0.66	0.58	0.63	0.88	0.68	0.81	0.87	0.53	9.40
api	ClassRegOT	0.91	0.59	0.82	0.15	NA	0.59	0.66	0.98	0.68	0.89	0.9	0.52	8.25
Ϊ	LinOT	0.89	0.81	0.81	0.19	0.66	0.58	0.65	0.88	0.71	0.81	0.91	0.61	4.06
	MMD-LS	0.88	0.85	0.81	0.73	0.65	0.56	0.56	0.98	0.69	0.89	NA	0.58	8.22
e	JPCA	0.88	0.85	0.66	0.19	0.65	0.56	0.56	0.84	0.7	0.8	0.9	0.55	8.98
ac	SA	0.74	0.81	0.8	0.13	0.66	0.57	0.56	0.93	0.7	0.91	0.89	0.59	7.80
dsc	TCA	0.4	0.46	0.5	0.58	0.04	0.02	0.11	0.49	0.61	0.46	0.49	0.27	17.58
Sul	TSL	0.88	0.85	0.66	0.86	0.62	0.48	0.45	0.7	0.69	0.57	0.9	0.26	15.09
	IDOT	0.72	0.57	0.82	0.00	0.61	0.41	0.15	0.8	0.67	0.63	0.8	0.46	11 42
her	OTL abelProp	0.12	0.76	0.81	0.14	0.61	0.56	0.64	0.89	0.67	0.69	0.86	0.51	10.01
B	DASVM	0.9	0.70	0.61	0.12	NA	NA	NA	0.83	NA	0.09	0.86	NA	7 20
_		0.09	0.80	0.04	0.12	T # 1-1	T N T-I	T # 1-1	0.85	TALE	0.70	0.80	TALE	1.29

Table 21: Accuracy score compared for the Deep methods with the supervised scorer for a selection of real-life datasets.

		CNSPS	N .	tome	
	MMS	Office	office	BCI	Rank
Train Src	0.85	0.77	0.58	0.54	6.19
Train Tgt	0.98	0.96	0.83	0.56	2.07
DeepCORAL	0.93	0.82	0.63	0.54	3.29
DAN	0.91	0.79	0.61	0.55	4.76
DANN	0.9	0.76	0.6	0.42	4.98
DeepJDOT	0.93	0.83	0.63	0.54	2.92
MCC	0.94	0.81	0.66	0.55	2.38
MDD	0.91	0.83	0.58	0.42	4.96
SPA	0.92	0.78	0.56	0.4	5.39

Table 22: F1 score for all datasets compared for all the shallow methods for <u>simulated</u> and real-life datasets. The color indicates the amount of the improvement. A white color means the method is not statistically different from Train Src (Train on source). Blue indicates that the score improved with the DA methods, while red indicates a decrease. The darker the color, the more significant the change.

			.x.	~	.:87	a.		me	15PS	CLOID	Devier	-1715		. 9	orer
		(A)		ili ond		ill's fice	SI office	HUMAN	ile nter	NSC Mal	on nicht	.00, mishi	18 18	, elected.	ank
		9	$\underline{\mathcal{V}}$	<u> </u>	5%	0,	0'	4,	<i>∿</i>	P.	4,	<u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u></u>	\$\$ ⁻	<u>چ</u>	*
	Train Src	0.88	0.87	0.62	0.17	0.64	0.56	0.52	0.56	0.65	0.72	0.91	0.53		10.95
	Train Tgt	0.92	0.92	0.82	0.98	0.89	0.8	0.96	1.0	0.69	1.0	0.97	0.63		1.70
	Dens. RW	0.88	0.88	0.62	0.16	0.61	0.56	0.52	0.55	0.65	0.72	0.91	0.52	IW	12.71
ы В	Disc. RW	0.85	0.86	0.7	0.16	0.63	0.53	0.48	0.56	0.63	0.76	0.91	0.54	CircV	8.39
hti	Gauss. RW	0.89	0.88	0.61	0.18	0.15	0.4	0.03	0.43	0.49	0.35	0.29	0.1	CircV	16.53
	KLIEP	0.88	0.88	0.62	0.17	0.64	0.55	0.52	0.56	0.65	0.72	0.91	0.52	IW	10.66
Me	KMM	0.89	0.87	0.6	0.15	0.63	0.54	0.51	0.69	0.5	0.74	0.91	0.49	CircV	11.58
R	NN RW	0.89	0.88	0.63	0.14	0.64	0.55	0.52	0.56	0.64	0.71	0.91	0.5	CircV	8.22
	MMDTarS	0.88	0.88	0.6	0.17	0.57	0.56	0.52	0.56	0.65	0.74	0.91	0.53	IW	11.02
	CORAL	0.74	0.76	0.74	0.16	0.65	0.57	0.62	0.72	0.65	0.72	0.92	0.62	CircV	5.00
ър	MapOT	0.72	0.65	0.82	0.02	0.59	0.5	0.61	0.76	0.59	0.63	0.84	0.47	PE	10.49
-iii	EntOT	0.71	0.67	0.82	0.12	0.63	0.57	0.59	0.83	0.49	0.75	0.85	0.53	CircV	10.15
apj	ClassRegOT	0.74	0.66	0.81	0.11	NA	0.53	0.62	0.97	0.67	0.82	0.89	0.52	IW	6.49
Σ	LinOT	0.73	0.78	0.75	0.16	0.65	0.57	0.64	0.81	0.65	0.76	0.91	0.61	CircV	4.20
	MMD-LS	0.77	0.77	0.75	0.54	0.64	0.56	0.54	0.97	0.6	0.85	NA	0.48	MixVal	7.58
e	JPCA	0.88	0.87	0.62	0.14	0.61	0.47	0.5	0.76	0.61	0.78	0.9	0.51	PE	9.55
pac	SA	0.73	0.74	0.8	0.1	0.64	0.57	0.55	0.88	0.56	0.77	0.89	0.52	CircV	7.95
lsq	TCA	0.51	0.56	0.5	0.61	0.0	0.0	0.02	0.53	0.46	0.44	0.47	0.19	DEV	17.94
Su	TSL	0.88	0.87	0.63	0.17	0.63	0.47	0.45	0.59	0.58	0.28	0.9	0.21	PE	15.46
	JDOT	0.72	0.66	0.82	0.13	0.59	0.41	0.59	0.8	0.61	0.65	0.79	0.46	IW	10.74
the	OTLabelProp	0.72	0.67	0.8	0.07	0.65	0.54	0.62	0.86	0.58	0.64	0.86	0.49	CircV	10.80
0	DASVM	0.89	0.88	0.61	0.13	NA	NA	NA	0.87	NA	0.82	0.85	NA	MixVal	7.12

1917 D.4 F1-SCORE OF BENCHMARK

We provide in Table 22 a version of Table 2 where the performance measure reported is the F1-score.
It is interesting to note that the dynamic of which methods work best and are the more robust is very similar to the accuracy performance which illustrate the robustness of the benchmark.

D.5 COMPARISON OF THE RANK OF DA SCORER

To provide a more detailed assessment of the scorers' performance, we present a critical difference diagram of their rankings in Figure 4. The diagram highlights that the unrealistic supervised scorer significantly outperforms all others. Among the unsupervised scorers, CircV and IW achieve the best performance, with their rankings being very close and not statistically different according to a statistical test. Next, we observe a group comprising PE, DEV, and MixVal, where DEV and MixVal are also not statistically distinguishable. Finally, SND emerges as the worst-performing scorer in the benchmark.

To give a more detailed perspective, we present a visualization in Figure 5, showing the rank of each scorer for each DA method. In the right part of the figure, the supervised scorer (in pink) is consistently the top-ranked, as expected, across all methods. Similarly, CircV (in red) and IW (in orange) consistently outperform other scorers.

D.6 COMPARISONS BETWEEN SUPERVISED AND UNSUPERVISED SCORERS

1938 Impact on the cross-validation score. We observe in Figure 6 the cross-validation score as a 1939 function of the final accuracy for various DA methods type and for both supervised and unsupervised 1940 scorers. As expected, we observe a good correlation between accuracy and cross-validation score 1941 with the supervised scorer. An important remark is that the Circular Validation (CircV) (Bruzzone & 1942 Marconcini, 2010b) shows some correlation between accuracy and cross-validation score. It indicates 1943 that this unsupervised scorer might be the most suitable choice for hyperparameter selection. This is 1943 supported by our extended experimental results in Table 2 for which the CircV is selected as the best



Figure 4: Critical difference diagram of average ranks for scorers, computed across shallow methods and shifts (lower ranks indicate better performance). Black lines between scorers indicate pairs that are not statistically different based on the Wilcoxon test.



Figure 5: Illustrations as spider plots for all methods of the accuracy on each dataset (left) and the scorers rankings (right). For methods with no accuracy results (NA in Table 2) we replace the value by 0. We provide both spider plot in the same Figure to allow a comparison of the scorer ranking while having the possibility to check the performance for each method.

scorer the most often. A similar trend can be observed for the Importance Weighted (IW) (Sugiyama et al., 2007a) which is also confirmed in Table 2.

DEV MixVal Supervised IW SND CircV 문 인 인 인 인 L.00 0.0 Reweighting s-validation sc 0.20 550 0.75 0.75 -0.5 -0.: 0.8 0.50 -1.0 0.50 -0.2 0.25 South Contraction Contrac 0.25 -1.5 0.25 0.00 00 1.00 1.00 0.0 1.00 Mapping -validation so 0.75 62-10 0.75 -0.5 -0.3 0.8 0.50 Cross-validat 0.25 0.25 0.50 4 -1.0 0.50 -0.2 0.25 0.25 0.7 -1.5 2 a 1.00 1.00 0.0 0.0 1.00 Subspace Subspace Validation Subspace 0.8 0.75).75 -0.5 -0.1 65 5 0.50 0.50 5 -1.0 -0.2 0.6 0.25 Cross-val 0.25 0.25 -1.5 -0.3 0.00 0.00 0.0 1.0 1.0 0.0 - 200 5 ٧. 0.8 ₹Ç¢ 0.8 0.8 0.8 -0.5 -0.1 3 Other 9'0 alidati 0.7 0.6 ŝ. 0.6 -1.0 ž -0.2 0.4 -1.5 Cross-0.4 2 2.2% 0.4 0.3 Target accuracy -Target Target accuracy -Target accuracy Target accuracy accuracy Target accuracy

1993 Figure 6: Cross-val score as a function of the accuracy for various DA methods and different supervised and unsupervised scorers. Each point represents an inner split with a DA method (color of the points) and a dataset. A good scorer should have a score that correlates with the target accuracy. 1996

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Figure 7: Change of accuracy of the DA methods with the best realistic unsupervised scorer (Table 2) w.r.t. the supervised scorer.

Supervised scorer v.s. the best realistic unsupervised scorer. We plot the loss in performance of the DA methods with the best realistic unsupervised scorer compared to using the supervised scorers in Figure 7.

Supervised scorer v.s. realistic unsupervised scorers. We present a scatter plot in Figure 8 and Figure 9, the accuracy of different DA methods using both supervised scorer and unsupervised scorer. In this figure, points below the diagonal indicate a decrease in performance when using the unsupervised scorer compared to the supervised one. The colors represent different types of DA methods. We can see that the SND, DEV and PE scorers all lead to a large performance loss compared to the supervised scorer. While IW and CircV results are much more concentrated near the diagonal, indicating a small loss in performance. This concentration explains why these two scorers have been selected as the best scorers for most of the methods in Table 2.



Figure 8: Accuracy of the DA methods using unsupervised scorers as a function of the accuracy with the supervised scorer. Colors represent the type of DA methods.



Figure 9: Accuracy of the DA methods using unsupervised scorers as a function of the accuracy with the supervised scorer for the different types of DA methods. Points below the diagonal represent a decrease in performance when using the unsupervised scorer compared to the supervised one. Colors represent the dataset on which the DA method is applied.

D.7 COMPUTATIONAL EFFICIENCY OF THE DA METHODS

Figure 10 shows the average computation time for training and testing each method. These results are based on one outer split, while we ran the benchmarks for five outer splits. Each method has a different time complexity. Interestingly, more time-consuming methods are not necessarily more performant than others. For instance, the highest-ranked methods-LinOT, CORAL, and SA-also have some of the lowest training and testing times. It's also worth noting that during the experiments, we enforced a 4-hour timeout. Thus, the more time-intensive methods might have been even slower without this timeout.

2106 10³ 2107 NO DA sec) 2108 Reweighting 2109 Mean computational time (in Mapping Subspace 2110 Other 2111 10² 2112 2113 2114 2115 2116 10¹ 2117 Dens. RW ofLabelProp Disc. RW Gauss RW Entor MMDTars Mapor ClassReg0T TrainTot 4LIEP trun Linot MMDILS " por DASYM TOT SIC AND CORAL PCA 2118 15× 100 SP 2119 2120 2121 2122 2123 Figure 10: Mean computing time to train and test each method for every experiment outer split. 2124 2125 2126 HYPERPARAMETERS GRID SEARCH FOR THE DA METHODS AND NEURAL NETWORKS D.8 2127 TRAINING 2128 2129 In this section, we first report the grids of hyperparameters used in our grid search for each DA method. 2130 2131 We also detail the configuration and hyperparameter grids for training neural networks in our Deep 2132 DA benchmark. We provide an overview of the key settings for each dataset, including batch sizes, 2133 optimizer parameters, learning rates, and the number of training epochs. Additionally, we outline the 2134 hyperparameter grids used for grid search across the Deep DA methods. 2135 2136 2137 2138 2139 2140 2141 2142 2143 2144 2145 2146 2147 2148 2149 2150 2151 2152 2153 2154 2155 2156 2157 2158 2159

2160Table 23: Hyperparameter grids used in the grid search for each DA method. The hyperparameter2161grids were designed to be minimal yet expressive, allowing each method to perform optimally. We2162selected parameters based on what seemed most reasonable, according to our best knowledge.

Wiethod	Hyperparameter Orld
KLIEP	'cv': [5],
	'gamma': [0.0001, 0.001, 0.01, 0.1, 1.0, 10.0, 100.0, 1000.0, 'auto', 'scale']
	'max_iter': [1000],
	'n_centers': [100],
	'random_state': [0],
	'tol': [1e-06]
KMM	'B': [1000.0],
	'gamma': [0.0001, 0.001, 0.01, 0.1, 1.0, 10.0, 100.0, 1000.0, None],
	'max_iter': [1000],
	'smooth_weights': [False],
	'tol': [1e-06]
NN RW	'laplace_smoothing': [True, False]
MapOT	'max_iter': [1000000],
	'metric': ['sqeuclidean', 'cosine', 'cityblock'],
	'norm': ['median']
JPCA	'n_components': [1, 2, 5, 10, 20, 50, 100]
SA	'n components': [1, 2, 5, 10, 20, 50, 100]
TCA	'kernel': ['rbf'].
	'mu': [10, 100].
	'n components': [1, 2, 5, 10, 20, 50, 100]
CORAL	'assume centered': [False, True].
	'reg': ['auto']
MMDTarS	'gamma': [0.0001, 0.001, 0.01, 0.1, 1.0, 10.0, 100.0, 1000.0, None].
inite inite	'max iter': [1000].
	'reg': [1e-06].
	'tol': [1e-06]
ClassRegOT	'max inner iter': [1000]
chussillegor	'max_iter': [10].
	'metric': ['squuclidean', 'cosine', 'cityblock'].
	'norm': ['lpl1']
	'tol': [1e-06]
	'(reg cl. reg e)': [([0,1], [0,1]), ([0,5], [0,5]), ([1,0], [1,0])]
Dens, RW	'bandwidth': [0.01, 0.1, 1.0, 10.0, 100.0, 'scott', 'silverman']
Disc. RW	'domain_classifier': ['LR' 'SVC' 'XGB']
Gauss RW	'reg': ['auto']
DASVM	'max_iter': [200]
IDOT	'alnha': [01 03 05 07 09]
3001	'n iter max': $[100]$
	'the weights': [1e.07]
	'tol': [1e-06]
EntOT	'max_iter': [1000]
Liitor	'metric': ['sqeuclidean' 'cosine' 'cityblock']
	'norm': ['median']
	$r_{rag} = a^2 \cdot [0, 1, 0, 5, 1, 0]$
	102 - 1000 - 1
LinOT	/bios': [True Folce]
LIIOI	$\frac{1}{2}$ $\frac{1}$
TOI	[10g . [10-00, 10-00, 0.1, 1, 10]
ISL	Vase_Inculou . [Inua],
	lengui_scale . [2],
	$\max_{i=1}^{1} [100],$
	$\begin{array}{c} \text{mu} : [0.1, 1, 10], \\ \text{'a summary track's [1, 2, 5, 10, 20, 50, 100]} \end{array}$
	$n_{components} : [1, 2, 5, 10, 20, 50, 100],$
	reg : [0.0001],
10010	
MMD-LS	gamma': [0.01, 0.1, 1, 10, 100],
	[max_iter': [20],
	'reg_k': [le-08],
	'reg_m': [1e-08],
	'tol': [1e-05]
OTLabelProp	'metric': ['sqeuclidean', 'cosine', 'cityblock'],

Dataset	Configuration
mnist_usps	Neural net: 2-layer CNN
	• Batch size: 256
	• Optimizer : SGD, momentum=0.6, weight_decay=1e-5
	• Learning rate: 0.1
	• Epochs : 20
	• Learning rate scheduler: LRSched- uler(StepLR, step_size=10, gamma=0.2)
office31	Neural net: ResNet50
	Batch size: 128
	• Optimizer : SGD, momentum=0.2, weight_decay=1e-5
	• Learning rate: 0.5
	• Epochs: 30
	• Learning rate scheduler: StepLR, step_size=10, gamma=0.2
officehome	Neural net: ResNet50
	Batch size: 128
	• Optimizer : SGD, momentum=0.6, weight_decay=1e-5
	• Learning rate: 0.05
	• Epochs : 20
	• Learning rate scheduler: StepLR, step_size=10, gamma=0.2
bci	Neural net: FBCSPNet
	• Batch size: 64
	• Optimizer : AdamW
	• Learning rate: 0.000625
	• Epochs: 200
	• Learning rate scheduler: CosineAnneal- ingLR

Table 25: Hyperparameter grids used in the grid search for each Deep DA method. The hyperparameter grids were designed to be minimal yet expressive, allowing each method to perform optimally. We selected parameters based on what seemed most reasonable, according to our best knowledge.

Mathad	Unarramator Grid
Method	Hyperparameter Onu
DANN	'reg': [0.001, 0.01, 0.1, 1.0]
DeepCORAL	'reg': [0.00001, 0.0001, 0.001, 0.01, 0.1, 1.0, 10.0, 100.0, 1000.0]
DeepJDOT	'reg_cl': [0.0001, 0.001, 0.01]
	'reg_dist': [0.0001, 0.001, 0.01]
DAN	'reg': [0.00001, 0.0001, 0.001, 0.01, 0.1, 1.0, 10.0, 100.0, 1000.0]
MCC	'reg': [0.01, 0.1, 1]
	'temperature': [1, 2, 3]
MDD	'reg': [0.001, 0.01, 0.1]
	'gamma': [1, 3]
SPA	'reg': [0.001, 0.01, 0.1, 1]
	'reg_nap': [0, 1]