

SALSA: Single-pass Autoregressive LLM Structured Classification

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Abstract

Despite their impressive generalization capabilities, instruction-tuned Large Language Models often underperform on text classification benchmarks. We introduce SALSA, a coherent pipeline that combines structured prompting, class-to-token mapping, and parameter-efficient fine-tuning, thereby avoiding cold-start training. Each class label is mapped to a distinct output token, and prompts are constructed to elicit a single-token response. During inference, the model’s output is projected only onto the logits of the relevant class tokens, enabling efficient and accurate classification in a single forward pass. SALSA achieves state-of-the-art results across diverse benchmarks, demonstrating its robustness and scalability for LLM-based classification applications.

1 Introduction

Text classification is fundamental in natural language processing (NLP), underpinning applications such as spam detection, sentiment analysis, dialogue safety, and content moderation. Traditional methods involving handcrafted rules and features were limited by scalability and labor intensity. The emergence of deep learning transformed the field by enabling automated feature extraction through models such as word2vec (Mikolov et al., 2013), ELMo (Peters et al., 2018), and transformer-based architectures such as BERT (Devlin et al., 2019) and GPT (Brown et al., 2020), which deliver exceptional performance.

With the advent of Large Language Models (LLMs), particularly open-ended generative models, the capabilities of NLP systems have expanded significantly. These models, pre-trained on extensive corpora, encapsulate a wealth of transferable knowledge that can be leveraged for diverse downstream tasks, including text classification. Despite this, the effective adaptation of open-ended generative LLMs for classification still poses challenges,

requiring efficient input representation and fine-tuning strategies.

Recent methods commonly utilize chain-of-thought (CoT) prompting (Wei et al., 2022), effective for reasoning, but computationally inefficient for classification. Such approaches also neglect valuable information in output distribution. In contrast, discriminative approaches (e.g., Pawar et al., 2024) remain underexplored.

In this paper, we introduce SALSA (Single-pass Autoregressive LLM Structured Classification), a method that adapts instruction-tuned, decoder-only LLMs for text classification. SALSA integrates structured prompt construction, targeted logit analysis, and fine-tuning into a unified pipeline. Its prompt-driven design enables strong zero-shot performance, providing a favorable initialization for subsequent tuning. Though built for generation, decoder-only LLMs can act as effective classifiers—matching or exceeding state-of-the-art results across benchmarks. By relying on a single forward pass, SALSA also offers a more efficient alternative to generation-based methods.

2 Background

Early NLP approaches used handcrafted features, deep learning then introduced RNNs and CNNs, improving classification (Kim, 2014). Transformer-based models, introduced by Vaswani et al. (Vaswani et al., 2017), revolutionized NLP by utilizing self-attention mechanisms for contextualized embeddings. Models like BERT represented a major leap forward by introducing bidirectional context understanding through unsupervised pre-training on large-scale corpora. Autoregressive transformer models like XLNet (Yang et al., 2019) demonstrated the benefits of autoregressive pre-training, outperforming traditional methods in classification tasks.

It has since been shown that large language mod-

els implicitly encode world knowledge, which can be extracted via their output logits (Petroni et al., 2019). Reformulating cloze-style tasks as multiple-choice classification has proven effective (Robinson et al., 2022), but the reliability of such approaches is highly sensitive to prompt structure (Cao et al., 2021).

Instruction tuning was a key breakthrough in demonstrating that language models can generalize across tasks when aligned with task-specific instructions (Wei et al., 2021). Building on this insight, decoder-only LLMs such as GPT (Brown et al., 2020), LLaMA (Touvron et al., 2023; Grattafiori et al., 2024), and Gemma (Team et al., 2024) have redefined the field, supporting zero-shot and in-context learning with strong generalization capabilities across a wide range of NLP tasks.

Parameter-efficient methods like BitFit (Ben Zaken et al., 2022) and Low-Rank Adaptation, LoRA (Hu et al., 2021), further limit overfitting by reducing the number of trainable parameters, ensuring stable fine-tuning especially in low-data scenarios. They also enable cost-effective deployment across tasks, requiring only minimal parameter swaps while leaving the base model intact.

When comparing results, fine-tuned encoder-based LLMs have achieved better performance in classification tasks, such as in the GLUE benchmark (Wang et al., 2018). Surprisingly, the much larger instruction decoder-only LLMs, which often outperform encoder-based LLMs in several tasks, generally fail to achieve competitive classification results (Bucher and Martini, 2024).

Our work aims to bridge the gap between the potential of instruction-decoder-only LLMs and the performance of classification tasks, both in terms of quality and efficiency.

3 Method

SALSA leverages the internal knowledge of LLMs by using their output estimated distribution to perform classification in a single forward pass per query. Our method employs LoRA for efficient parameter updates and knowledge exposure, allowing SALSA to deliver competitive performance.

Prompt Construction. We design a structured instruction prompt that encapsulates the task. The prompt first provides a clear task description, then maps each class to a unique single-token representation, and finally specifies the expected answer format, including fixed prefix and suffix elements. A

structured response containing a placeholder token is appended to complete the prompt. This process is illustrated in Figure 1. A detailed example is provided in A.4

Forward Pass, Filtering, and Classification.

We perform a single forward pass through the LLM to extract the logits for the placeholder token, which represent the model’s predictions. These logits are then filtered based on the prompt’s mapping and normalized via softmax to yield an estimated probability distribution over the classes. The final prediction corresponds to the class with the highest probability.

Training. We optimize our model using a backpropagation-based procedure (see A.2). In particular, we employ LoRA in conjunction with a cross-entropy loss function. The loss is defined as follows:

$$\mathcal{L} = -\frac{1}{N} \sum_{i=1}^N \sum_{c=1}^C y_{i,c} \log(\hat{P}_{i,c}) \quad (1)$$

where N is the number of samples, C is the number of classes, $y_{i,c}$ represents the ground truth labels, and $\hat{P}_{i,c}$ denotes the predicted probabilities. See A.3 for more details.

Controlling the Precision–Recall Trade-off.

Adjusting decision threshold values offers precise control over the trade-off between precision and recall. This flexibility allows the model to be tailored to specific application needs, enabling tuning to optimize performance based on the desired balance.

Efficient Single-Pass Inference. SALSA eliminates autoregressive overhead by computing all logits in a single forward pass, reducing latency, resource use and cost. Mapping classification to a single-token output ensures only valid class tokens are considered, enhancing efficiency and correctness.

4 Experiments and Results

4.1 Datasets

We evaluated SALSA on multiple text classification datasets, including a subset of GLUE (Wang et al., 2018), covering SST-2 (Socher et al., 2013), MRPC (Dolan and Brockett, 2005), QQP (Iyer et al., 2017), MNLI (Bowman et al., 2015), QNLI (Rajpurkar et al., 2016), and RTE (Dagan et al., 2005). Additional datasets included AG’s News (Zhang et al., 2015) for topic classification, IMDb (Maas et al., 2011) for binary sentiment analysis, and Yelp-5

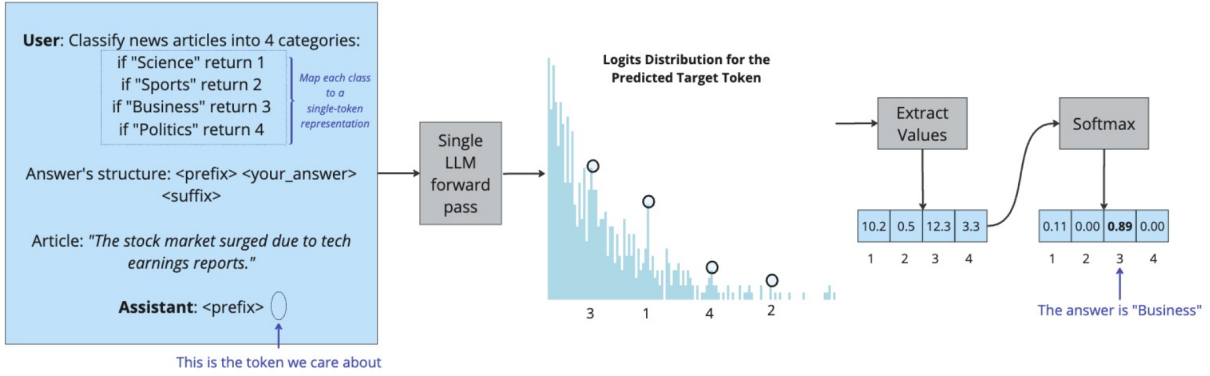


Figure 1: SALSA single-token classification pipeline: each category is mapped to a distinct token, and the LLM’s logits determine the predicted label in one forward pass.

(Zhang et al., 2015) for multi-class sentiment analysis. We further included MedNLI (Romanov and Shivade, 2018) for clinical natural language inference, MedMCQA (Pal et al., 2022) for multiple-choice medical question answering, and HateXplain (Mathew et al., 2020) for hate speech and offensive language detection. For more details see section A.1.

4.2 Analysis

In this section, we delve into a comprehensive analysis of SALSA by examining performance metrics, convergence efficiency, and other key aspects across various benchmarks.

State-of-the-Art Results. SALSA demonstrates state-of-the-art performance across multiple text classification benchmarks, as outlined in Table 4.2 (and Table 2).

The method consistently outperforms existing models, including T5-11B (Raffel et al., 2020), XLNet (Yang et al., 2019), RoBERTa_{LARGE} (Liu et al., 2019), and ALBERT (Lan et al., 2019). Furthermore, we compared SALSA against the top three performers on the GLUE benchmark, Turing ULR v6 (Team, 2022), Vega v1 (Zhong et al., 2023), and Turing ULR v5 (Tiwarly and Zhou, 2021), and SALSA outperforms them all in 3 of 7 tasks.

Furthermore, we evaluated SALSA on three domain-specific benchmarks: MedNLI, MedMCQA, and HateXplain. As shown in Table 3, SALSA outperforms previous SOTA, demonstrating strong generalization in diverse NLP tasks.

For each validation set experiment, we train the model five times with different random seeds and report the average performance on the validation set. For test set experiments, we evaluate the model that achieves the highest results on the vali-

dation set using the GLUE test set evaluation server. These findings validate the efficiency and robustness of SALSA in leveraging generative LLMs for classification tasks.

Zero-Shot and Few-Shot Classification. To further evaluate SALSA, we conducted zero-shot and few-shot classification experiments using Meta’s Instruct LLaMA 3.3 70B model.

In the zero-shot setting, the model received structured prompts containing task instructions and class options, without labeled examples. For few-shot classification, we added ten balanced random examples as in-context demonstrations. In both cases, the model generated open-ended responses that we parsed to extract the predicted classes.

We also applied SALSA in both settings, without fine-tuning. The zero-shot variant included only task instructions and class labels; the few-shot variant appended a few formatted examples. As shown in Table 4.2, SALSA clearly outperforms standard prompting approaches.

Efficient Optimization and Convergence. To evaluate optimization efficiency, we compared SALSA to standard fine-tuning, where a linear classification head is added atop the base LLM’s final token output. Both methods were trained with identical hyperparameters to minimize cross-entropy loss. As shown in Figure 2, SALSA achieves faster convergence and consistently higher training and validation accuracy across steps. These results underscore its ability to reduce training time while improving generalization, making it well-suited for resource-constrained settings.

5 Conclusion

SALSA exhibits consistent performance across its pipeline. As shown in Tables 4.2, it achieves strong

		QQP	SST-2	RTE	MRPC	QNLI	MNLI _M	MNLI _{MM}
(V)	Zero Shot	81.4	94.9	86.3	77.0	90.7	81.9	80.9
(V)	Few Shot	81.5	96.1	85.2	77.2	91.4	80.1	80.2
(V)	RoBERTa _{LARGE}	92.2	96.4	86.6	90.9	94.7	90.2	90.2
(V)	ALBERT	92.2	96.9	89.2	90.9	95.3	90.8	90.8
(V)	XLNet	92.3	97.0	85.9	90.8	94.9	90.8	90.8
(V)	SALSA Zero Shot [†]	82.1	95.0	90.6	76.4	92.7	84.1	83.1
(V)	SALSA Few Shot [†]	83.3	95.4	92.0	80.1	92.9	86.7	86.3
(V)	SALSA	92.4±0.2	97.1±0.2	94.2±0.4	91.7±0.5	96.7±0.2	92.8±0.3	92.6±0.2
(T)	BERT _{LARGE}	89.3	94.9	70.1	85.4	92.7	86.7	85.9
(T)	T5-11B	90.6	97.5	92.8	90.4	96.9	92.2	91.9
(T)	Turing ULR v6	90.9	97.5	93.6	92.3	96.7	92.5	92.1
(T)	Vega v1	91.1	97.9	92.4	92.6	96.7	92.2	91.9
(T)	Turing ULR v5	91.1	97.6	94.1	91.7	97.9	92.6	92.4
(T)	SALSA	90.9	97.9	94.8	91.1	97.1	92.7	92.0

Table 1: Performance metrics of SALSA compared to baseline models across multiple GLUE Benchmark datasets. Results are reported separately for the validation (V) and test (T) sets, with accuracy as the key evaluation metric. SALSA achieves state-of-the-art performance on all validation tasks and outperforms competitors on 3 out of 7 test tasks. Test set results are benchmarked against the top 3 GLUE leaderboard models as of January 27, 2025. [†]No fine-tuning applied.

	AG News	IMDb	Yelp-5
Zero Shot	88.8	95.2	62.7
XLNet	95.5	96.8	72.9
SALSA	95.9±0.1	97.6±0.1	74.2±0.2

Table 2: Accuracy on AGNews, IMDb, and Yelp-5 test datasets.

	MedNLI	MedMCQA	HateXplain
Zero-Shot	83.4	70.3	51.5
SOTA	90.2 [†]	73.6 [†]	70.4 [†]
SALSA	91.3±0.4	74.1±0.3	71.8±0.4

Table 3: Accuracy on MedNLI, MedMCQA, and HateXplain test datasets. [†]SOTA sources: GatorTron-large for MedNLI (Yang et al., 2022), GPT-4 for MedMCQA (Nori et al., 2023), and BERT-MRP for HateXplain (Kim et al., 2022).

zero-shot results even without tuning. With fine-tuning, SALSA improves further without the instability often seen in cold-start training (Figure 2). It also reaches state-of-the-art accuracy across diverse tasks—sentiment analysis, medical QA, and hate speech detection—demonstrating broad applicability and strong generalization (Tables 2).

By reducing classification to a single forward pass, SALSA enables high-throughput use of large models, offering a more efficient alternative to generation-based approaches. Its use of LoRA adapters also preserves the base model’s capabili-

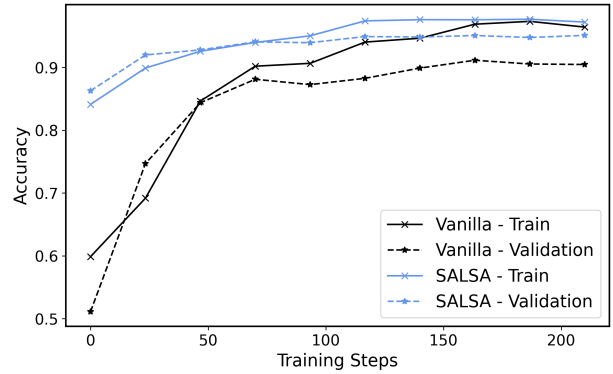


Figure 2: Convergence comparison between SALSA and Vanilla fine-tuning on RTE (Dagan et al., 2005). SALSA achieves faster convergence with higher accuracy on both training and validation sets, indicating better generalization and training efficiency.

ties for other LLM tasks.

While prompt design remains partly empirical, our ablation study (Section A.5) shows that fine-tuning mitigates label-token sensitivity. SALSA further supports regression tasks via discrete class ensembles (Section A.6), extending its scope.

Future directions include systematic prompt optimization, adaptive thresholding, and unified extensions for multi-label and multi-task settings (Section A.7). Overall, SALSA offers a flexible and efficient framework for robust, general-purpose classification with generative LLMs.

6 Limitations

One key limitation of SALSA is its reliance on accessing the internal logit distribution of large language models (LLMs), which restricts its use to models or third-party services that expose such information. Additionally, the structured prompt design used to map classes to single tokens may not be applicable in all scenarios, particularly in tasks with more complex or nuanced label representations. Another concern is model contamination. Since we have no control over the data used to train the underlying LLM there is the possibility that some test examples may have been inadvertently incorporated during unsupervised training. Finally, SALSA inherits the biases and ethical concerns of its underlying LLM. As these models are trained on large-scale web corpora, they may encode and propagate societal biases, necessitating responsible use in real-world applications.

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A Appendices

A.1 Datasets

We used multiple datasets to evaluate SALSA, focusing on text classification tasks.

GLUE Benchmark. We evaluated SALSA on a subset of tasks from the GLUE benchmark (Wang et al., 2018) and report both the task details and evaluation metrics. Specifically, we tested on the following tasks: the Stanford Sentiment Treebank (SST-2; Socher et al. (2013)), the Microsoft Research Paraphrase Corpus (MRPC; Dolan and Brockett (2005)), the Quora Question Pairs (QQP; Iyer et al. (2017)), the Multi-Genre Natural Language Inference Corpus (MNLI; Bowman et al. (2015)), the Stanford Question Answering Dataset (QNLI; Rajpurkar et al. (2016)), and Recognizing Textual Entailment (RTE; Dagan et al. (2005)).

AG’s News. The AG’s News dataset (Zhang et al., 2015) includes 120,000+ news articles across four categories (World, Sports, Business, Science/Technology), testing LLM robustness with diverse topics and journalistic tones.

IMDb. The IMDb data set (Maas et al., 2011) is a benchmark for binary sentiment analysis with positive or negative movie reviews, testing classification models on diverse styles of writing, topics, and sentiment intensities.

Yelp-5. The Yelp-5 dataset (Zhang et al., 2015), used for multi-class sentiment analysis, contains customer reviews rated 1-5 stars, challenging models with varied review lengths, tones, and topics.

HateXplain. HateXplain (Mathew et al., 2020) is a benchmark dataset for explainable hate speech detection, sourced from social media platforms. Each post in the dataset is annotated from three perspectives: a three-class classification (hate, offensive, or normal), the targeted community, and rationales highlighting the specific text spans that justify the annotations.

MedNLI. MedNLI (Romanov and Shivade, 2018) is a specialized natural language inference (NLI) dataset tailored for the clinical domain. It comprises sentence pairs extracted from the Past Medical History sections of MIMIC-III clinical notes, annotated by physicians to determine

whether a given hypothesis can be inferred from a premise.

MedMCQA. MedMCQA (Pal et al., 2022) is a comprehensive multiple-choice question answering dataset designed to emulate real-world medical entrance examinations. Each question is accompanied by multiple answer options and detailed explanations.

For the train:validation:test size split and the number of samples in each dataset used for the evaluation, see Table 4.

Dataset	Train Size	Val. Size	Test Size
SST-2	67.3k	0.8k	1.8k
MRPC	3.6k	0.4k	1.7k
QQP	363.8k	40.4k	390.9k
MNLI _m	392.7k	9.8k	9.8k
MNLI _{mm}	392.7k	9.8k	9.8k
QNLI	104.7k	5.4k	5.4k
RTE	2.4k	0.3k	3.0k
AG News	120.0k	7.6k	–
IMDb	25.0k	25.0k	–
Yelp-5	650.0k	50.0k	–
MedNLI	11.2k	1.4k	1.4k
MedMCQA	182.8k	4.2k	6.2k
HateXplain	16.0k	2.0k	2.0k

Table 4: Dataset Sizes

A.2 Detailed Inference and Tuning Algorithm

The algorithm 1 outlines the explicit steps of SALSA’s approach, covering both the training and inference flows. While using LLMs for classification at inference time is not a novel concept, steps 5 and 6 distinguish SALSA by showing how it leverages LLMs not just for auto-generation, but also for their underlying statistical properties - resulting in a richer and more informative output representation, and consequently, better performance. During training, SALSA goes beyond the generic objective of predicting the correct next token for every position. Instead, it focuses specifically on the task-related tokens and updates the model weights based solely on the loss computed from these tokens, making the training process more efficient and better aligned with the classification objectives.

A.3 Training Details

The base model was Meta’s Instruct LLama 3.3 70b (Meta’s license). It was tuned for a total of 6 epochs, and gradient accumulation steps set to

Algorithm 1 SALSA’s [Training](#) and Inference for Single-Task, Single-Label, Multi-Class Classification

Require: instructions, answer template, answer’s start ▷ Input parameters

```
1: Definition: Let  $N$  be the vocabulary size.
2: for each  $s$  in samples-to-classify do
3:    $x \leftarrow$  wrap in the method’s notation and tokenize( $s, input\_parameters$ )
4:   logits  $\leftarrow$  model’s forward_pass( $x$ ) ▷ logits’ size =  $|input| \times N$ 
5:    $y_{placeholder} \leftarrow$  logits[placeholder] ▷  $y_{placeholder}$ ’s size =  $N$ 
6:    $y_{relevant} \leftarrow y_{placeholder}[categories]$  ▷  $y_{relevant}$ ’s size =  $|categories|$ 
7:    $y_{prob} \leftarrow$  softmax( $y_{relevant}$ )
8:    $y_{true} \leftarrow$  one_hot(true_label, |categories|)
9:   loss  $\leftarrow$  cross_entropy( $y_{prob}, y_{true}$ )
10:  model.backward_pass(loss)
11:  update_parameters()
12:  report arg max( $y_{prob}$ )
13: end for
```

Note: The blue-colored lines correspond to training-specific steps.

50 with batch size 1 to effectively handle large batch sizes in limited memory environment. To ensure reproducibility, a fixed random seed was used throughout the experiments.

LoRA(Hu et al., 2021) was used for fine-tuning, the rank was set to 8, the alpha parameter to 16, and a dropout rate of 0.05. It is 103M trainable parameters.

Optimization was carried out using the Adam optimizer (Kingma, 2014) with default parameter settings, where beta1=0.9, beta2=0.999, and epsilon=1E-8. A linear learning rate scheduler was employed, incorporating 100 warmup steps to progressively increase the learning rate at the beginning of training to 1E-4. After warmup the learning rate was reduced linearly to 0. For each experiment, the best-performing validation epoch was identified, and the experiment was repeated five times with different data shuffling seeds to ensure robustness of results.

Empirical observations revealed that optimal validation performance was typically achieved within the first 2 to 3 epochs. Training beyond this point, particularly when each sample was seen more than three times, often resulted in overfitting for small size datasets. The hardware used for this work was the Nvidia DGX system with eight H100 80GB GPU blades, and each model training run lasted between 1 and 36 hours. In this work, no hyperparameter optimization was conducted.

A.4 Prompt Construction Example

Figure 3 shows a sample prompt compiled from the RTE dataset. The prompt follows the default chat

template of Instruct LLaMA 3.3, beginning with a default system prompt, followed by a user prompt containing task-specific instructions and data, and ending with the assistant response template. The compiled prompt is tokenized and processed in a single forward pass through the LLM to produce a classification output.

A.5 Ablation Study on Label Mapping Strategies

We performed an ablation study on the RTE dataset to evaluate how different label mapping schemes affect classification performance. Specifically, we tested six mappings: numerical (‘0’, ‘1’), reverse numerical (‘1’, ‘0’), alphabetical (‘A’, ‘B’), reverse alphabetical (‘B’, ‘A’), semantic (‘Y’, ‘N’), and reverse semantic (‘N’, ‘Y’).

The inclusion of “Y” and “N” label tokens was motivated by their implicit alignment with natural language concepts of affirmation and negation (“Yes”/“No”). We hypothesized that when the token aligns semantically with the correct label—e.g., “Y” for entailment—the model may perform better in a zero-shot setting. Conversely, using misleading or contradictory mappings, such as assigning “N” to entailment, could degrade performance due to interference with prior token associations.

Table 5 summarizes the average accuracy (mean \pm standard deviation over 5 runs) for each mapping strategy, evaluated in both zero-shot and fine-tuned conditions.

In the zero-shot setting, we observe substantial variation in performance across mappings. Reversing the labels (“N/Y”) led to the poorest perfor-

System prompt	{	< begin_of_text >
		< start_header_id >system < end_header_id >
		Cutting Knowledge Date: December 2023 Today Date: 26 Jul 2024 < eot_id >
		< start_header_id >user < end_header_id >
Task + input	{	Given the premise:
		<PREMISE> Mangla was summoned after Madhumita's sister Nidhi Shukla,
		who was the first witness in the case. </ PREMISE>
		and hypothesis:
		<HYPOTHESIS> Shukla is related to Mangla. </ HYPOTHESIS>
		Is the hypothesis entailed by the premise?
		Provide answer in format: <ANSWER>#Number</ANSWER>
		where the number is one of the following:
Class mapping	{	0 - entailment
		1 - not entailment
		< eot_id >
Answer format	{	< start_header_id >assistant < end_header_id >
with masked token	{	<ANSWER>X </ANSWER>
		< eot_id >

Figure 3: A compiled prompt from RTE dataset before applying a forward pass.

Mapping Strategy	Zero-Shot(%)	Finetuned (%)
Numerical (0/1)	90.6	95.1 ± 0.4
Reverse Numerical (1/0)	89.1	94.4 ± 0.2
Alphabetical (A/B)	91.3	94.5 ± 0.3
Reverse Alphabetical (B/A)	90.2	94.2 ± 0.3
Semantic (Y/N)	85.5	95.4 ± 0.7
Reverse Semantic (N/Y)	44.7	94.0 ± 0.2
Mean	81.9 ± 18	94.9 ± 0.5

Table 5: Ablation study on different label mapping strategies for the RTE dataset. Accuracy is reported as mean ± std over 5 runs.

mance, suggesting that mismatches between token semantics and label intent can confuse the model. After finetuning the differences between mappings diminish considerably, with all variants converging to similar accuracy levels. These findings confirm that the finetuning process effectively suppresses sensitivity to the mapping choices and enables the model to adapt even in the presence of initially misleading token associations.

A.6 Discrete to Continuous Extension

For tasks involving continuous value estimation, such as the STS-B benchmark (Cer et al., 2017) from the GLUE, we adapt our method to produce scalar outputs through a discretization-based approach.

We represent the predicted score as the expected value over a fixed set of discrete scalar values. Each value corresponds to a predefined class token and is associated with a probability derived from the model’s output distribution. Formally, let $\mathcal{S} = \{s_1, s_2, \dots, s_n\}$ denote the set of discrete values (e.g., $[0.0, 0.2, \dots, 5.0]$), and let $P(s_i | x)$ be the

probability assigned to state s_i given input x . The model prediction \hat{y} is computed as:

$$\hat{y} = \sum_{i=1}^n P(s_i | x) \cdot s_i \quad (2)$$

During training on STS-B, we perform the inverse operation. Given a scalar label $y \in [0, 5]$, we identify the two discrete values s_i and s_{i+1} such that $s_i \leq y \leq s_{i+1}$, and assign probabilities:

$$y = \alpha \cdot s_i + (1 - \alpha) \cdot s_{i+1}, \quad (3)$$

$$P(s_i | x) = \alpha, \quad (4)$$

$$P(s_{i+1} | x) = 1 - \alpha \quad (5)$$

This construction ensures that the expected value of the predicted distribution matches the ground truth during supervision, while keeping the label space discrete and aligned with our logit-based framework.

Our method achieves a Pearson/Spearman correlation of **93.8/93.6** on the STS-B test set, compared to Turing v5’s **93.7/93.3**, representing a new state-of-the-art result.

A.7 Possible extention

SALSA’s framework can be naturally extended to more complex scenarios. For multi-label classification, one can replace the softmax layer with a sigmoid function and apply a probability threshold to select all relevant classes. For multi-task classification, a prompt with placeholders for each task enables the extraction of separate logits distributions, allowing simultaneous classification across multiple tasks in a single forward pass (see Figure 4).

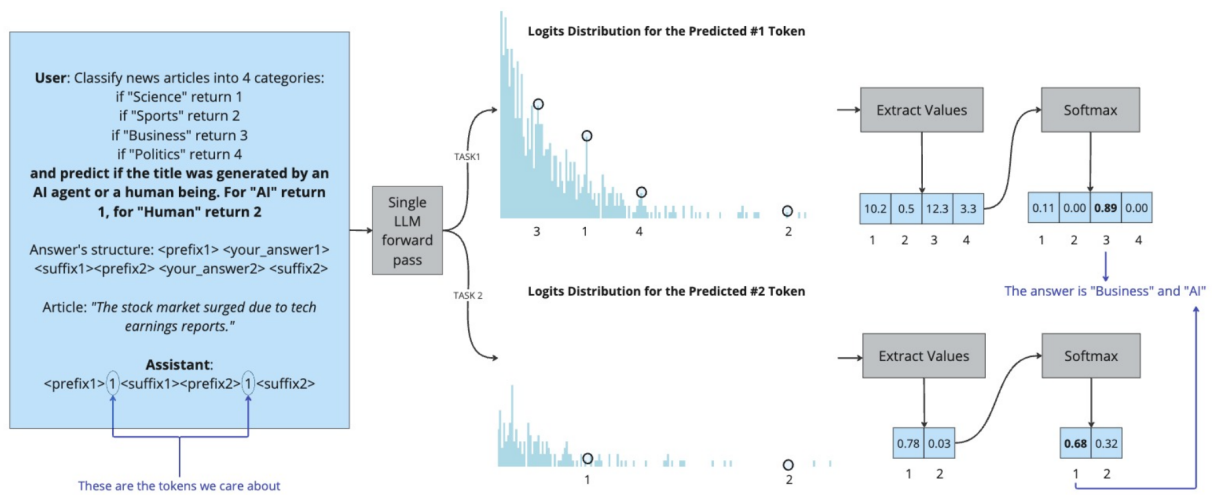


Figure 4: SALSA two-token classification pipeline: the LLM’s logits are used in a single pass to predict both the article’s topic (1–4) and its source (AI=1 or Human=2).