

KHaR: Knowledge Harvesting and Refinement for multimodal sentiment analysis

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Abstract

Multimodal sentiment analysis deduces a user’s sentiment by integrating information from different modalities. Previous methods mainly focus on using complex fusion networks to learn effective joint embeddings and achieved significant improvement, while ignoring refined processing within modalities, resulting in models that achieve suboptimal results on more delicate sentiment analysis. In this paper, we propose a novel framework KHaR, which harvests rich intra-modality knowledge through domain-specific adapters and utilizes mixture of experts to refine the knowledge to capture more detailed intra-modality information. In addition, we design a contrastive learning to further explore the information correlation between samples of similar sentiment intensity. To fuse the extracted features effectively, we employ the multimodal information bottleneck to filter out irrelevant information and retain the most salient features for sentiment analysis. Extensive experiments show that KHaR achieves superior performance on four benchmark datasets, and especially achieves significant improvement on the more refined sentiment analysis(e.g.Acc-7, Acc-5).

1 Introduction

With the rapid progress of deep learning, significant breakthroughs have been made in the field of MSA. Contemporary studies in MSA predominantly concentrate on developing advanced fusion methodologies to effectively integrate cross-modal information. The simplest approach, concatenation or early fusion, directly stacked the unimodal representations from different modalities(Poria et al., 2016; Kampman et al., 2018; Wu and Liang, 2010). Outer product-based fusion captures pairwise feature correlations at the cost of quadratic computational complexity(Zadeh et al., 2017). Attention-based fusion mechanisms dynamically weight the contribution of each modality, allowing for more

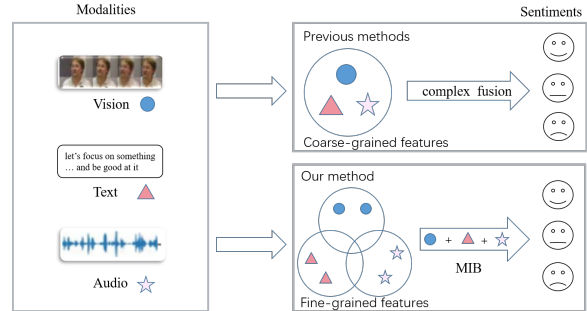


Figure 1: The previous methods and our method.

flexible and adaptive integration(Tsai et al., 2019; Zhang et al., 2023; Feng et al., 2024; Sun and Tian, 2025). Graph-based fusion methods model the relationships between different modalities as a graph, enabling more complex interactions and dependencies(Huang et al., 2024; Lin et al., 2022).

Although these methods are quite successful, they neglect fine-grained intra-modal representation learning. Most methods rely on coarse-grained features, such as using the first token extracted by BERT to represent the text modality(Devlin et al., 2019; Hazarika et al., 2020; Niu et al., 2021). Averaging of all tokens or max pooling are used to represent the audio and video modalities(Tsai et al., 2019; Zong et al., 2023). As a result, when evaluated on fine-grained sentiment tasks (e.g.Acc-7, Acc-5), such approaches yield suboptimal performance as they fail to capture subtle but decisive sentiment signals in individual modalities before fusion. For example, subtle changes in mouth movement or body language in a video can significantly enhance sentiment analysis(Luo et al., 2021; Hjelm et al., 2018). Figure 1 illustrates the difference between previous methods and our method.

To overcome these limitations, we propose a novel framework KHaR (Knowledge Harvesting and Refinement), which learns noise-robust representations by knowledge harvesting and refinement.

071 First, domain-specific adapters are injected into
072 BERT/Transformer encoders to extract modality-
073 aware features(textual semantic, acoustic patterns,
074 and facial dynamics). These features are then pro-
075 cessed by a Mixture of Experts(MoE) layer that
076 dynamically activates domain-specialized MLPs
077 to refine modality-specific information. Crucially,
078 we design a threshold-based contrastive learning
079 mechanism where samples with sentiment intensity
080 difference $\leq \kappa$ (empirically set to 0.4) form positive
081 pairs, while others are treated as negative pairs, en-
082 abling fine-grained discrimination between similar
083 emotions(e.g., $\kappa=0.4$ groups $y=1.0$ with $y=1.3$ but
084 separates from $y=2.0$). Finally, we employ the mul-
085 timodal information bottleneck to compress cross-
086 modal features by theoretically eliminating redun-
087 dant inter-modal correlations while preserving the
088 sentiment-discriminative patterns for compact and
089 sufficient fusion.

090 The main contributions of our work can be sum-
091 marized as follows:

- 092 • We propose the KHaR framework to systemat-
093 ically address fine-grained intra-modality fea-
094 ture extraction, which ensures the preservation
095 and enhancement of subtle emotional signals
096 before fusion through knowledge harvesting
097 from domain adapters and refinement of MoE.
- 098 • A dynamic contrastive mechanism is designed
099 to align cross-modal features based on contin-
100 uous sentiment intensity levels, significantly
101 improving fine-grained emotion differentia-
102 tion compared to traditional binary polarity-
103 based approaches.
- 104 • Empirical evaluations across four benchmark
105 datasets consistently show KHaR outperform-
106 ing current state-of-the-art approaches. Ab-
107 lation studies further confirmed the need for
108 each component.

109 2 Related Work

110 In this part, we review the previous works in the
111 field of MSA, focusing on two main aspects: multi-
112 modal sentiment analysis and contrastive learning.

113 2.1 Multimodal Sentiment Analysis

114 Previous research on MSA mainly focuses on intra-
115 modality representation learning and inter-modality
116 fusion. For intra-modality representation learn-
117 ing methods, [Mai et al. \(2020\)](#) and [Hazarika et al. \(2020\)](#)
118 utilized adversarial learning to learn the

119 common and specific features of each modality.
120 [Zhang et al. \(2023\)](#) designed an Adaptive Hyper-
121 modality Learning(AHL) module that, with the
122 aid of language features at various scales, learns
123 to create a representation capable of suppressing
124 irrelevancies and conflicts present in visual and au-
125 dio features. For inter-modality fusion methods,
126 [Zadeh et al. \(2017\)](#) proposed a tensor fusion net-
127 work method to effectively capture and analyze the
128 interactions between different modalities by com-
129 puting the cartesian product. [Feng et al. \(2024\)](#)
130 proposed a dynamic attention fusion method based
131 on the contribution of each modality. Unlike the
132 previous works, we extract more detailed represen-
133 tation information within modalities by harvesting
134 with refinement.

135 2.2 Contrastive Learning

136 Contrastive learning learns discriminative repre-
137 sentations by pulling positive pairs closer while
138 pushing away negative pairs. Recent researches on
139 contrastive learning in multimodal sentiment anal-
140 ysis are mainly focused on two aspects: supervised
141 contrastive learning([Zha et al., 2023](#); [Mai et al., 2022](#);
142 [Yang et al., 2024](#); [Khosla et al., 2020](#)) and
143 self-supervised contrastive learning([Akbari et al., 2021](#);
144 [Chen et al., 2020](#); [He et al., 2020](#)). The
145 core difference between them is whether to use la-
146 bel information to construct positive and negative
147 sample pairs. For example,[Chen et al. \(2020\)](#) pro-
148 posed a self-supervised contrastive learning frame-
149 work, SimCLR, which learns representations by
150 maximizing agreement between augmented views
151 of the same image. [Khosla et al. \(2020\)](#) intro-
152 duced a supervised contrastive loss, which exploits
153 the similarity of label information to maximize
154 the consistency of samples in the same class. In-
155 spired by [Yang et al. \(2024\)](#), we propose a dynamic
156 contrastive learning mechanism that aligns cross-
157 modal features based on the sentiment intensity
158 levels, significantly improving fine-grained emo-
159 tion differentiation compared to traditional binary
160 polarity-based approaches.

161 3 Methodology

162 3.1 Overall Architecture

163 As shown in Figure 2, the KHaR framework first ex-
164 tracts unimodal features from raw video, text, and
165 audio inputs. An adapter and encoder jointly learn
166 modality-specific representations enriched with af-
167 fective knowledge. A MoE module then dynami-

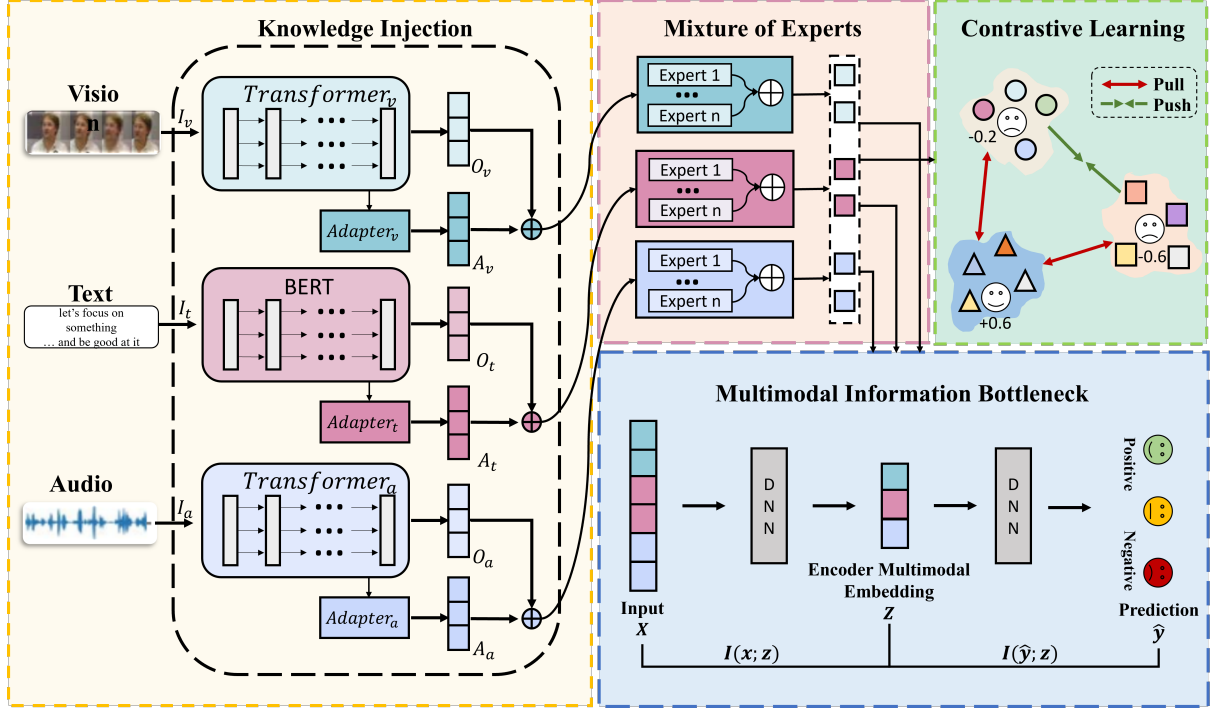


Figure 2: The overall architecture of KHaR. The blue, pink and purple modules represent the relevant operations of vision, text and audio.

cally selects domain-specific experts (each of which is an MLP) to compress and refine critical features. To capture emotional differences across modalities, a dynamic contrastive learning mechanism adjusts the similarity distribution accordingly. Finally, an information bottleneck module constrains the fusion process by filtering out irrelevant information while preserving sentiment-relevant cues.

3.2 Problem Definition

MSA task typically processes visual, textual, and acoustic data streams as input features. The sequences of three modalities are represented as triplet (I_v, I_t, I_a) , which include $I_v \in \mathbb{R}^{T_v \times d_v}$, $I_t \in \mathbb{R}^{T_t \times d_t}$, and $I_a \in \mathbb{R}^{T_a \times d_a}$, where $T_m, m \in \{v, t, a\}$ is the corresponding modal sequence length, d_m represents the vector dimension. Our main task is to accurately predict the sentiment intensity through feature extraction and fusion.

3.3 Knowledge of Harvest

In order to harvest a large amount of knowledge, we use encoders and adapters to encode each modality input $I_{m \in \{v, t, a\}}$, and obtain two types of representations: a comprehensive-level representation $O_m \in \mathbb{R}^{T_m \times d_m}$ and the knowledge-enhanced affective representations $A_m \in \mathbb{R}^{T_m \times d_m}$.

Comprehensive-level Representation. To ob-

tain hierarchical semantic features and a solid foundation for subsequent sentiment-aware knowledge injection via the adapter, we extract comprehensive-level representations O_m from each modality. For text input I_t , we employ a pretrained BERT encoder, while for visual and audio inputs I_v and I_a , we use modality-specific stacked Transformer encoders (Vaswani et al., 2017):

$$O_m, H_m = \text{Encoder}_m(I_m; \theta_m^{\text{encoder}}) \quad (1)$$

where O_m denotes the final output of the encoder, serving as the comprehensive-level representation, and H_m represents the intermediate hidden states that capture modality-specific general or commonsense information.

Knowledge-Enhanced Affective Representation. To obtain richer affective feature information, we introduce external Adapter modules in the encoder layers to inject affective knowledge into the modality-specific representations.

As illustrated in Figure 3, we insert stacked Adapter blocks into the encoder architecture of visual, text, and audio modalities to construct the knowledge-enhanced affective representation A_m :

$$A_m = \text{Adapter}_m(I_m, H_m; \theta_m^{\text{adapter}}) \in \mathbb{R}^{T_m \times d_m} \quad (2)$$

where $\theta_m^{\text{adapter}}$ denotes the pretrained parameters of the Adapter module corresponding to modality.

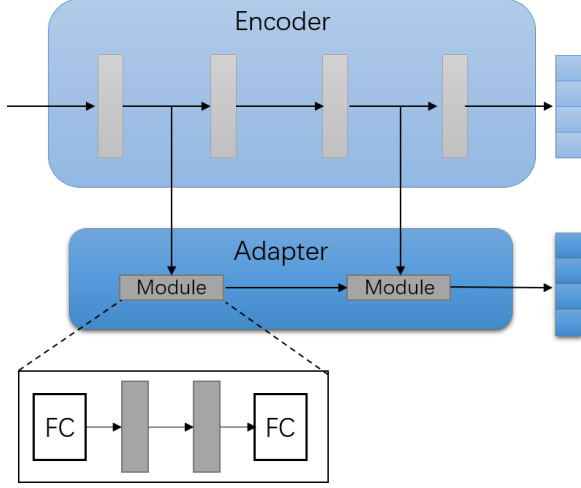


Figure 3: The architecture of BERT and Transformer encoders, Adapters, and their interconnections.

Through this design, we combine the above two representations to obtain the knowledge-enhanced representation X_m :

$$X_m = [A_m; H_m] \in \mathbb{R}^{T_m \times 2d_m} \quad (3)$$

3.4 Knowledge Refinement

To achieve fine-grained processing of widely harvested multimodal knowledge, KHaR adopts a modality-specific MoE layer, where each expert is an MLP network optimized for discriminative sub-features. Gated network mechanisms dynamically activate specialized experts, for example, in text, different experts may focus on sentiment phrases, negation, or syntactic structures; In the video, experts locate local cues such as microexpressions or lip movements; While in audio, pitch change experts or spectrum pattern experts are selectively involved. This architecture ensures that only the most relevant experts deal with the nuances of a particular pattern, allowing the model to extract knowledge with high accuracy from a wide and noisy feature space.

Specifically, for each modality m , we construct an independent MoE layer comprising s expert networks $\{E_1, E_2, \dots, E_s\}$ and a gating network G . All MoE layers across modalities share the same number of experts to ensure structural consistency. Given the unimodal feature X_m . The gating weights are computed as:

$$G(X_m) = \text{Softmax}(\text{KeepTopK}(W_g X_m, k)) \quad (4)$$

where $W_g \in \mathbb{R}^{d \times s}$ is a training weight parameter matrix, d is the modal feature dimension, and

$\text{KeepTopK}(\cdot)$ denotes the sparse operation that retains the top k gating weights for each input. The final gated representation $\hat{X}_m \in \mathbb{R}^d$ is obtained by weighted aggregation of expert outputs:

$$\hat{X}_m = \sum_{i=1}^s G(X_m)_i \cdot E_i(X_m) \quad (5)$$

where $G(X_m)_i$ is the gating weight of the i -th expert and $E_i(X_m)$ is the output of the corresponding expert network.

To mitigate expert collapse—where a few experts dominate the activation distribution—we introduce a regularization term $\mathcal{L}_{\text{MoE}}^m(X_m)$ to encourage balanced expert utilization:

$$\mathcal{L}_{\text{MoE}}^m(X_m) = \omega \cdot (\text{CV}(I(X_m))^2 + \text{CV}(L(X_m))^2) \quad (6)$$

where $\text{CV}(\cdot)$ denotes the coefficient of variation, $I(\cdot)$ measures the overall activation importance of each expert across the batch, $L(\cdot)$ quantifies the expert usage frequency, and ω is a hyperparameter controlling the strength of the regularization.

3.5 Multimodal Fusion

In information theory, Mutual Information (MI) is used to measure the degree of interdependence between two random variables. Specifically, considering two variables x and y with marginal distributions $p(x)$ and $p(y)$ and joint distribution $p(x, y)$, MI is defined as the Kullback-Leibler (KL) divergence between the product of the marginal and joint distributions. The formal definition of MI is:

$$\begin{aligned} I(x; y) &= D_{\text{KL}}(p(x, y) \parallel p(x)p(y)) \\ &= \int dx dy p(x, y) \log \frac{p(x, y)}{p(x)p(y)} \\ &= \mathbb{E}_{(x, y) \sim p(x, y)} \left[\log \frac{p(x, y)}{p(x)p(y)} \right] \end{aligned} \quad (7)$$

To extend this principle to multimodal scenarios, we design a multimodal information bottleneck (MIB) module that refines the fused representation derived from independent single-modality encoders. The MIB module is designed to: (1) Redundancy filtering: suppress cross-modal redundancy; (2) Discriminative preservation: preserve discriminative cues necessary for prediction.

In the MIB module, we introduce the intermediate variable z and construct this objective function:

$$L_{\text{MIB}} = I(y; z) - \beta I(x; z) \quad (8)$$

where $I(\cdot; \cdot)$ denotes MI, and the parameter $\beta \geq 0$ determines the intensity of the compression. Our approach focuses on maximizing the objective function.

Since MI itself is difficult to calculate directly, we usually use variational methods to estimate it. Regarding the first term $I(y; z)$, we introduce an auxiliary distribution $q(y | z)$ to approximate the genuine posterior distribution $p(y | z)$, thereby obtaining its lower bound:

$$I(y; z) \geq \int dx dy dz p(z | x) p(y | x) p(x) \log q(y | z) \quad (9)$$

Similarly, for the second term $I(x; z)$, we use the approximate distribution $q(z | x)$ to estimate the genuine posterior distribution $p(z | x)$, and obtain its upper bound form:

$$I(x; z) \leq \int dx dz p(x) p(z | x) \log \frac{p(z | x)}{q(z)} \quad (10)$$

where $q(z)$ is a variational approximation to the marginal distribution $p(z)$ which is often fixed to a standard normal Gaussian distribution. Combining these two estimates, we obtain the variational lower bound of the objective function:

$$\begin{aligned} L_{MIB} &= I(y; z) - \beta I(x; z) \geq J_{MIB} \\ &= \mathbb{E} [\log q(y | z) - \beta \cdot KL(p(z | x) \| q(z))] \end{aligned} \quad (11)$$

where the expectation \mathbb{E} is taken over $(x, y) \sim p(x, y)$ and $z \sim p(z | x)$. J_{MIB} is a variational lower bound of L_{MIB} . See the Appendix C for the specific formula derivation. Finally, by maximizing the objective function L_{MIB} , we equivalently minimize the loss \mathcal{L}_{MIB} , which is defined as follows:

$$\mathcal{L}_{MIB} = \mathbb{E} [\beta \cdot KL(p(z | x) \| q(z)) - \log q(y | z)] \quad (12)$$

3.6 Dynamic Contrastive Learning Based on Sentiment Intensity

Traditional contrastive learning methods (e.g., SimCLR or supervised contrastive learning) primarily focus on broad category-level separation, grouping all positive sentiment samples (sentiment intensity > 0) together and all negative ones (< 0) apart, while maximizing the distance between positive and negative representations. However, such methods often ignore the continuity and nuance of sentiment intensity, which may lead to semantic distortion. For example, traditional methods will classify samples with sentiment intensity +3 and sentiment intensity +0.1 as positive sample pairs, and samples with sentiment intensity +0.1 and sentiment

intensity -0.1 as negative sample pairs, depending on whether the sentiment intensity is both positive and negative, which leads us to ignore the more detailed relationship between sentiment intensity. As a result, the previous studies (Lin et al., 2022; Yu et al., 2023) have achieved suboptimal results on more difficult multi-classification tasks.

Inspired by the previous work (Yang et al., 2024), we introduce a dynamic contrastive learning strategy that adapts sample pairing based on their sentiment intensity differences, thereby preserving the semantic continuity inherent to sentiment tasks. Specifically, for any two samples i and j in the batch, we define their emotion intensity gap as:

$$G(i, j) = |y_i - y_j|, \quad j \in \text{batch}, j \neq i \quad (13)$$

where y_i and y_j denote the actual sentiment intensity of sample i and j , respectively. Considering a threshold κ (set to 0.4), sample pairs are categorized as follows:

$$\begin{aligned} G(i, j) \leq \kappa &\Rightarrow (i, j) \in \text{pos pairs} \\ G(i, j) > \kappa &\Rightarrow (i, j) \in \text{neg pairs} \end{aligned} \quad (14)$$

Based on the above steps, for sample i , the inter-modal positive and negative sample pairs can be obtained as follows:

$$\begin{aligned} P_{inter}^i &= \{(V^i, T^i), (V^i, A^i), (T^i, A^i)\} \cup \\ &\quad \{(V^i, T^j), (V^i, A^j), (T^i, A^j), \\ &\quad (T^i, V^j), (A^i, V^j), (A^i, T^j) \\ &\quad | (i, j) \in \text{pos pairs}\} \end{aligned} \quad (15)$$

$$\begin{aligned} N_{inter}^i &= \{(V^i, T^k), (V^i, A^k), (T^i, A^k), \\ &\quad (T^i, V^k), (A^i, V^k), (A^i, T^k) \\ &\quad | (i, k) \in \text{neg pairs}\} \end{aligned} \quad (16)$$

The intra-modal positive and negative sample pairs can be obtained as follows:

$$\begin{aligned} P_{intra}^i &= \{(V^i, V^j), (T^i, T^j), (A^i, A^j), \\ &\quad | (i, j) \in \text{pos pairs}\} \end{aligned} \quad (17)$$

$$\begin{aligned} N_{intra}^i &= \{(V^i, V^k), (T^i, T^k), (A^i, A^k), \\ &\quad | (i, j) \in \text{neg pairs}\} \end{aligned} \quad (18)$$

Then, we can get the P^i and N^i as follows:

$$P^i = P_{inter}^i \cup P_{intra}^i \quad (19)$$

$$N^i = N_{inter}^i \cup N_{intra}^i \quad (20)$$

For each anchor sample a , the model is trained to minimize the distance to positive samples and

Methods	CH-SIMS						CH-SIMSV2					
	MAE	Corr	Acc-5	Acc-3	Acc-2	F1	MAE	Corr	Acc-5	Acc-3	Acc-2	F1
TFN	0.432	0.591	39.30	65.12	78.38	78.62	0.303	0.707	52.55	72.21	80.14	80.14
LMF	0.441	0.576	40.53	64.68	77.77	77.88	0.367	0.557	47.79	64.90	74.18	73.88
MuT	0.453	0.564	37.94	64.77	78.56	79.66	0.291	0.738	54.81	73.19	80.68	80.73
BBFN*	0.430	0.564	40.92	61.05	78.12	77.88	0.300	0.708	53.29	71.47	78.53	78.41
Self-MM	0.425	0.595	41.53	65.47	80.04	80.44	0.311	0.695	52.77	72.61	79.69	79.76
CubeMLP*	0.419	0.593	41.79	65.86	77.68	77.59	0.334	0.648	52.90	71.95	78.53	78.53
CENet	0.471	0.534	33.92	62.58	77.90	77.53	0.310	0.699	53.04	73.10	79.56	79.63
TETFN	0.420	0.577	41.79	63.24	81.18	80.24	0.310	0.695	54.47	73.65	79.73	79.81
ALMT*	0.408	0.594	43.11	65.86	78.77	78.71	0.308	0.700	52.90	71.86	79.59	79.51
TMBL*	0.429	0.592	41.58	65.43	79.12	78.75	0.313	0.706	52.03	73.02	80.46	80.36
KHaR	0.408	0.622	45.30	65.43	79.43	79.52	0.287	0.735	56.29	73.89	80.85	80.78

Table 1: Results on CH-SIMS and CH-SIMSV2 datasets. The best result is in bold; * means the results are from (Feng et al., 2024), while other results are from (Mao et al., 2022).

Methods	MOSI						MOSEI					
	MAE	Corr	Acc-7	Acc-5	Acc-2	F1	MAE	Corr	Acc-7	Acc-5	Acc-2	F1
TFN [†]	0.947	0.673	34.46	-	77.99/79.08	77.95/79.11	0.572	0.714	51.60	-	78.50/81.89	78.96/81.74
LMF [†]	0.950	0.651	33.82	-	77.90/79.18	77.80/79.15	0.576	0.717	51.59	-	80.54/83.48	80.94/83.36
MAG-BERT	0.727	0.781	43.62	-	82.37/84.43	82.50/84.61	0.543	0.755	52.67	-	82.51/84.82	82.77/84.71
BBFN*	0.796	0.744	43.88	-	80.32/82.47	80.21/82.44	0.545	0.760	52.88	-	82.87/85.73	83.13/85.56
MMIM*	0.744	0.780	44.75	-	82.51/84.30	82.38/84.23	0.550	0.761	51.88	-	83.75/85.42	83.93/85.26
CubeMLP*	0.755	0.772	43.44	-	80.76/82.32	81.77/84.23	0.537	0.761	53.35	-	82.36/85.23	82.61/85.04
PS-Mixer	0.794	0.748	44.31	-	80.3/82.1	80.3/82.1	0.537	0.765	53.0	-	83.1/86.1	83.10/86.10
ALMT*	0.712	0.793	46.79	-	83.97/85.82	84.05/85.86	0.530	0.774	53.62	-	81.54/85.99	81.05/86.05
SFTTR	0.709	0.795	46.5	-	82.94/84.6	82.92/84.63	0.536	0.772	53.7	-	82.89/85.99	83.15/85.92
MuT [†]	-	-	-	42.68	-/-	-/-	-	-	-	54.18	-/-	-/-
MISA [†]	-	-	-	47.08	-/-	-/-	-	-	-	53.63	-/-	-/-
Self-MM [†]	-	-	-	53.47	-/-	-/-	-	-	-	55.53	-/-	-/-
KHaR	0.698	0.8	49.13	55.39	84.45/86.13	84.48/86.15	0.526	0.777	54.43	56.30	83.37/86.49	83.02/86.60

Table 2: Results on MOSI and MOSEI datasets. The best result is in bold; * means the results are from (Feng et al., 2024), [†] means the results are from (Mao et al., 2022).

maximize the distance to negative samples. The contrastive learning loss is formulated as:

$$\mathcal{L}_{CL} = -\mathbb{E}_{i \in B} \log \left(\frac{\sum_{(a,p) \in P^i} \delta(a,p)}{\sum_{(a,q) \in P^i \cup N^i} \delta(a,q)} \right) \quad (21)$$

where $\delta(a,p) = \exp\left(\frac{\text{sim}(a,p)}{\tau}\right)$, which is used to measure the similarity between the anchor sample a and the positive sample p .

3.7 Optimization Objective

To achieve effective multimodal fusion and compact representation learning, the overall training objective of KHaR is formulated as the minimization of the following total loss function:

$$\mathcal{L} = \mathcal{L}_{MoE} + \mathcal{L}_{MIB} + \lambda \mathcal{L}_{CL} + \mathcal{L}_{Task} \quad (22)$$

where λ is a hyperparameter that controls the strength of contrastive learning, \mathcal{L}_{Task} is to minimize the MAE between the predicted sentiment intensity \hat{y} and the ground truth y .

4 Experiments

4.1 Datasets and Metrics

To fully evaluate the performance of KHaR, we employ four benchmark datasets: CMU-MOSI (Zadeh et al., 2016), CMU-MOSEI (Zadeh et al., 2018), CH-SIMS (Yu et al., 2020) and CH-SIMSV2 (Liu et al., 2022). Appendices A and B describe the details of these datasets and the experimental setup.

For a more comprehensive comparison, we divide our reporting results into regression and classification. For regression, we use the mean absolute error (MAE) and Pearson correlation (Corr) as evaluation metrics. For classification, we use the multi-class accuracy and F1-score as evaluation metrics. we report the accuracy of 2-class (Acc-2), 3-class (Acc-3) and 5-class (Acc-5) for CH-SIMS and CH-SIMSV2, and the accuracy of 2-class (Acc-2), 5-class (Acc-5) and 7-class (Acc-7) for MOSI and MOSEI. In addition, for MOSI and MOSEI, the Acc-2 and F1 score are computed for negative/positive(excluding 0) and negative/non-negative(including 0) classes.

4.2 Baselines

We compare the KHaR framework with state-of-the-art multimodal sentiment analysis methods, including: TFN(Zadeh et al., 2017), LMF(Liu et al., 2018), MulT(Tsai et al., 2019), MISA(Hazarika et al., 2020), MAG-BERT(Rahman et al., 2020), Self-MM(Yu et al., 2021), MMIM(Han et al., 2021b), BBFN(Han et al., 2021a), CENet(Wang et al., 2022), CubeMLP(Sun et al., 2022), PS-Mixer(Lin et al., 2023), TETFN(Wang et al., 2023), ALMT(Zhang et al., 2023), TMBL(Huang et al., 2024), and SFTTR(Sun and Tian, 2025).

4.3 Performance Comparison

We evaluate KHaR on four benchmark datasets and compare it with state-of-the-art methods. The results are shown in Table 1 and Table 2.

As shown in Table 1, for the Chinese datasets CH-SIMS and CH-SIMSv2, KHaR achieves the best results on most evaluation metrics. For example, on the CH-SIMSv2 dataset, compared with the MulT model, KHaR achieves 1.37% improvement on the regression task MAE, and 2.7% improvement on the multi-classification task Acc-5, indicating that KHaR can extract effective feature information on complex datasets and make more accurate actual predictions.

For the English datasets MOSI and MOSEI, KHaR also achieves good experimental results. On the MOSI dataset, our model achieves the best results on all evaluation metrics. Compared with the second best result, KHaR improves by 1.55% in MAE and 0.62% in Corr. It is worth noting that on the more difficult and more detailed classification task Acc-7, our model achieves a significant improvement with a relative improvement of 5%. Similarly, on the MOSEI dataset, we achieve a relative improvement of 1.36% on the Acc-7 classification task, indicating that our model has a significant improvement in fine-grained sentiment capture.

4.4 Ablation Study and Analysis

To validate the effectiveness of different components in our proposed KHaR model, we conduct comprehensive ablation studies on two benchmark datasets: CH-SIMS and MOSI. The evaluations cover the role of each modality, the impact of the MoE module, the contribution of contrastive learning, and the effects of MIB strategies. All results are reported in terms of MAE, correlation, Acc-5 for CH-SIMS and Acc-7 for MOSI.

Methods	CH-SIMS			MOSI		
	MAE	Corr	Acc-5	MAE	Corr	Acc-7
Role of Each Modality						
V+T	0.420	0.571	42.64	0.714	0.799	47.23
V+A	0.587	0.209	21.23	1.366	0.208	19.68
A+T	0.424	0.556	43.98	0.718	0.783	47.96
V+A+T	0.408	0.622	45.30	0.698	0.8	49.13
Role of the MoE						
MLP _m	0.425	0.567	42.01	0.724	0.783	46.79
ATTN _m	0.415	0.589	41.36	0.746	0.775	46.06
CNN _m	0.420	0.578	43.11	0.711	0.789	46.21
Role of Contrastive Learning						
w/o CL	0.436	0.546	42.89	0.713	0.796	47.23
Role of Fusion						
SUM	0.412	0.603	43.98	0.727	0.786	47.81
CON	0.425	0.585	41.79	0.717	0.792	47.52
ATTN	0.416	0.586	42.89	0.707	0.798	47.52
MUL	0.427	0.567	42.23	0.706	0.798	46.36

Table 3: Result of ablation experiments for different components of KHaR on CH-SIMS and MOSI datasets. V=video, T=text, A=audio. The best result is in bold.

4.4.1 Role of Modalities

We evaluate the contribution of each modality by comparing different combinations: bi-modal (V+T, V+A, A+T) versus tri-modal (V+A+T) inputs. As shown in Table 3, the tri-modal setting consistently achieves superior performance across all metrics, confirming the complementary nature of visual, acoustic, and textual information in affective understanding. In contrast, bi-modal configurations yield suboptimal results, with V+A particularly underperforming on MOSI, suggesting the insufficiency of non-verbal cues in capturing nuanced sentiment without textual grounding.

4.4.2 Role of the MoE

In order to verify the effectiveness of the MoE layer, we use different feature extraction methods to replace the MoE layer for comparison. As shown in Table 3, MLP_m denotes a multilayer perceptron, ATTN_m adopts a standard attention mechanism, and CNN_m introduces convolutional operations for feature extraction. Experimental results show that replacing MoE layer with these methods leads to performance degradation, which indicates that dynamic routing and modal-specific experts of MoE layer are essential for capturing complex patterns and handling different data distributions efficiently.

4.4.3 Role of Contrastive Learning

To evaluate the effectiveness of contrastive learning component, we present an ablation analysis in Table 3, where “w/o CL” denotes the removal of contrastive loss from the training objective. When removing the contrastive learning module, we ob-

serve consistent performance degradation across both SIMS and MOSI datasets, with the most pronounced drops occurring in the 5-class classification task on SIMS and the 7-class classification task on MOSI. This significant decrease demonstrates that the contrastive learning component effectively captures subtle relationships between sentiment intensities, enabling the model to better distinguish closely-related sentiment categories. The results suggest that explicitly modeling intra-modal and inter-modal feature distributions through contrastive learning is essential for maintaining discriminative power in complex sentiment identify scenarios, where traditional comtrastive learning approaches often fail to preserve these nuanced emotional relationships.

4.4.4 Role of Fusion

We compare MIB-based fusion strategy against several alternative fusion mechanisms. Among them, SUM represents the addition of different modal representations, CON represents the concatenation of different modal representations, ATTN represents the fusion using the attention mechanism, and MUL represents the multiplication of the representations of different modalities. The MIB fusion consistently achieves superior performance across most metrics, particularly on CH-SIMS. These results demonstrate that the information bottleneck encourages the extraction of task-relevant and compact representations by discarding redundant or noisy modality-specific features. This selective fusion mechanism proves more effective than naive aggregation strategies.

4.4.5 Visualizing Representations

In this section, we utilize t-SNE(Van der Maaten and Hinton, 2008) for a more intuitive visual presentation of the multimodal representation, as shown in Figure 4. Figure 4a shows the representation generated by KHaR, Figure 4b shows the representation using the MLP layers to replace the MoE layer, Figure 4c shows the representation without contrastive learning, and Figure 4d shows the representation without MIB. When the MLP layer is used to replace the MoE layer, it can be obviously seen that the representation distribution of similar samples is loose, indicating that the MoE layer can better capture the specific information within the modality and enhance the discrimination of the representation. The sample representation distribution without contrastive learning is mixed, the

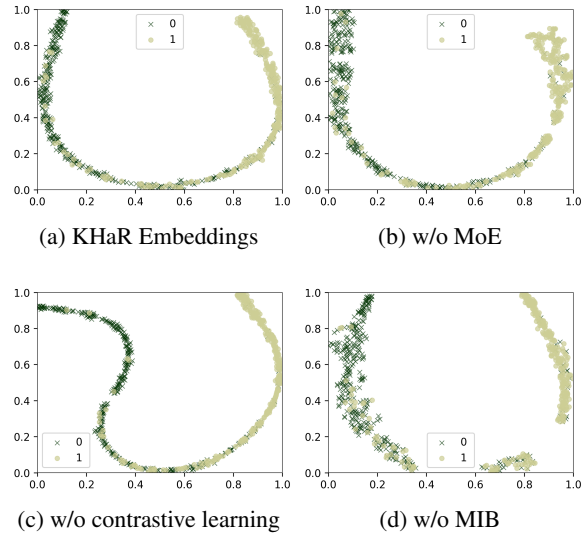


Figure 4: Visualization of multimodal representations on CMU-MOSI. Where '0' and '1' represent positive and negative sentiment respectively.

overlap area is large, and the lack of clear boundary, which indicates that contrastive learning makes different categories easier to distinguish after dimension reduction by bringing similar samples closer and pushing away heterogeneous samples. Samples without MIB have a more chaotic representation distribution with local small clusters, indicating poor feature consistency, and the model may overfit noise or local patterns. It shows that MIB can better filter noise information while retaining the most relevant information, and improve the generalization ability and robustness of the model.

5 Conclusion

In this paper, we propose a novel multimodal sentiment analysis framework KHaR, which is the first to extract the fine-grained information within a modality by using two steps of knowledge harvesting and refinement. This design helps the model to better capture the detailed information of a specific modality before fusion. Moreover, we introduce a dynamic contrastive mechanism based on sentiment intensity, enabling fine-grained and semantically aligned cross-modal representations. Extensive experiments across four benchmark datasets show that KHaR consistently outperforms state-of-the-art methods, achieving superior results in both accuracy and robustness. Ablation studies further highlight the indispensable role of each component. These findings position KHaR as one of the most promising and effective solutions in the field.

571 Limitations

572 Although KHaR achieves strong performance on
573 multiple datasets, it still has some limitations.
574 Firstly, we can consider using domain adapters and
575 other external domain knowledge to further inject
576 more relevant knowledge into the model. Secondly,
577 we mainly strengthen the model’s learning of fine
578 knowledge. In the future, we can consider how to
579 better integrate coarse-grained knowledge and fine
580 knowledge for multimodal sentiment analysis.

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A Datasets

CMU-MOSI is a multimodal dataset, which includes 3 modalities: text, visual and acoustic. The data was collected from 93 movie review videos on Youtube. The videos were edited into 2199 segments. Each segment is annotated with sentiment intensity in the range [-3,3]. CMU-MOSEI is similar to CMU-MOSI, but on a larger scale. It contains 23,453 annotated video clips from online video sites covering 250 different topics and 1000 different speakers. Samples in CMU-MOSEI are also labeled with sentiment intensity in the range [-3,3]. The SIMS dataset is a Chinese multimodal sentiment analysis dataset, which provides detailed annotations for each modality. The dataset includes 2,281 selected video clips from a variety of movies, TV series, and variety shows, and each sample is assigned a sentiment score ranging from -1 (extremely negative) to 1 (extremely positive). The CH-SIMS v2.0 dataset is an extension and enhancement of the CH-SIMS. The dataset collects 4402 labeled supervised data and 10161 unlabeled raw video clips from 11 different scenes. The sentiment intensity of each sample is between -1 and 1. The partition of the above dataset is shown in Tabel 4.

Dataset	#Train	#Valid	#Test	#Total	Language
CH-SIMS	1368	456	457	2281	Chinese
CH-SIMsv2	2722	647	1034	4403	Chinese
MOSI	1284	229	686	2199	English
MOSEI	16326	1871	4659	22856	English

Table 4: The statistics of CH-SIMS, CH-SIMsv2, MOSI and MOSEI.

B Experimental Setup

Here, we will mainly present the specific implementation of our experimental setup. All experiments were conducted on high performance computing nodes equipped with NVIDIA RTX 4090D GPU. On the Chinese datasets SIMS and SIMsv2, we adopt bert-base-chinese (12-layer, 768-hidden-dim) to initialize the model, while on the English datasets MOSI and MOSEI, we adopt bert-base-uncased as the baseline architecture. Both models are optimized using AdamW, including a linear

warmup schedule and weight decay regularization. The main hyperparameters are shown in Table 5.

Descriptions	CH-SIMS	CH-SIMsv2	MOSI	MOSEI
Epochs	70	70	70	70
Learning Rate	3e-5	3e-5	3e-5	1e-5
Batch Size	64	64	64	36
Num of Experts	3	3	3	3
λ	1	1	0.05	0.45
Modal Dimension d_m	128	128	128	256
Fine-grained Dimension	50	50	50	50
Optimizer	AdamW	AdamW	AdamW	AdamW

Table 5: Hyperparameter Settings for different datasets.

C Derivation of MIB

The pipeline of the MIB is in Algorithm 1, and details of its formula derivation are shown as follows.

Algorithm 1 Multimodal Information Bottleneck

Input: Unimodal representations

$\mathbf{X}_m, m \in \{v, t, a\}$, hyper-parameter β

Output: Prediction \hat{y}_i

Initialize unimodal networks F^m and fusion network F^f ;

while not done **do**

 Sample a batch of utterances

for each utterance i **do**

for each $m (m \in \{v, t, a\})$ **do**

$$\mathbf{x}_i^m = F^m(\mathbf{X}_i^m; \theta_m)$$

end for

$$\mathbf{x}_i = F^f(\mathbf{x}_i^l, \mathbf{x}_i^a, \mathbf{x}_i^v; \theta_f)$$

$$\boldsymbol{\mu}_{z_i}, \boldsymbol{\Sigma}_{z_i} = \mu(\mathbf{x}_i; \theta_\mu), \Sigma(\mathbf{x}_i; \theta_\Sigma)$$

$$\mathbf{z}_i = \boldsymbol{\mu}_{z_i} + \boldsymbol{\Sigma}_{z_i} \times \epsilon$$

$$\hat{y}_i = D(\mathbf{z}_i; \theta_d)$$

end for

 Compute J_{MIB} as in Eq. 11

end while

We design the encoder $p(z | x)$ to be a Gaussian distribution whose mean and covariance are parameterized by a neural network:

$$p(z | x) = \mathcal{N}(\boldsymbol{\mu}(x; \theta_\mu), \boldsymbol{\Sigma}(x; \theta_\Sigma)) = \mathcal{N}(\boldsymbol{\mu}_z, \boldsymbol{\Sigma}_z) \quad (23)$$

where $\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$, parameterized respectively by θ_μ and θ_Σ , are neural networks designed to estimate the mean vector $\boldsymbol{\mu}_z$ and covariance matrix $\boldsymbol{\Sigma}_z$ of the Gaussian latent distribution.

Since directly sampling random variables is not conducive to gradient propagation, we use the reparameterization technique to transform the sampling process into z :

$$z = \boldsymbol{\mu}_z + \boldsymbol{\Sigma}_z \times \epsilon \quad (24)$$

853 where $\epsilon \sim \mathcal{N}(0, I)$ denotes a sample from the
854 standard multivariate normal distribution, and I
855 represents an identity matrix with all diagonal ele-
856 ments equal to 1.

857 This treatment transfers the randomness to ϵ ,
858 allowing μ_z and Σ_z to be explicitly optimized via
859 gradients. Note that here we assume that each
860 element in the vector z is independent from each
861 other. For our task, we formulate $q(y | z)$ as:

$$862 \quad q(y | z) = e^{-\|y - \mathbf{D}(z; \theta_d)\|_1 + C}$$

$$863 \quad \log q(y | z) = -\|y - \mathbf{D}(z; \theta_d)\|_1 + C$$

$$864 \quad = -\|y - \hat{y}\|_1 + C \quad (25)$$

865 where \mathbf{D} denotes a decoder parameterized by θ_d ,
866 and \hat{y} is the model prediction. Here, maximizing
867 $\log q(y | z)$ is equivalent to minimizing the mean
868 absolute error (MAE) between the predicted \hat{y} and
869 the ground truth y .

870 In practice, MAE is frequently used to maximize
871 the MI between the target and the latent representa-
872 tion z and the approximated marginal distribution
873 of the multimodal representation z is often assumed
874 to be a standard Gaussian distribution:

$$875 \quad q(z) \sim \mathcal{N}(0, I) \quad (26)$$

876 Through combining Eq.23 and Eq.26, the KL di-
877 vergence term $KL(p(z | x) || q(z))$ can be evaluated
878 as follows:

$$879 \quad KL(p(z | x) || q(z)) = KL(\mathcal{N}(\mu(x; \theta_\mu), \Sigma(x; \theta_\Sigma)) || \mathcal{N}(0, I))$$

$$880 \quad = KL(\mathcal{N}(\mu_z, \Sigma_z) || \mathcal{N}(0, I)) \quad (27)$$

881 where this formulation relies on the assumption
882 that the reparameterizations of both $p(z | x)$ and
883 $q(z)$ are chosen such that the KL divergence admits
884 a closed-form analytical expression.

885 To approximate the integral over x , z and y , we
886 employ Monte Carlo sampling, which allows the
887 overall objective J_{MIB} (Eq. 11) to be rewritten in
the following simplified form:

$$888 \quad J_{MIB} = \frac{1}{n} \sum_{i=1}^n [\mathbb{E}_{\epsilon \sim p(\epsilon)} L_i - \beta \cdot KL(\mathcal{N}(\mu_{z_i}, \Sigma_{z_i}) || \mathcal{N}(0, I))] \quad (28)$$

889 where n refers to the number of samples (i.e., the
890 batch size), and the index i denotes the individual
891 data point in the sampled batch.

892 Maximizing this objective can maximize the dis-
893 crimination ability of the target variable and effec-
894 tively compress the redundant information in the
895 multimodal representation x .