# Synthetic Data Pruning in High Dimensions: A Random Matrix Perspective

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### ABSTRACT

Synthetic data has gained attention for training large language models, but poorquality data can harm performance (see, e.g., Shumailov et al. (2023); Seddik et al. (2024)). A potential solution is data pruning, which retains only high-quality data based on a score function (human or machine feedback). Previous work Feng et al. (2024) analyzed models trained on synthetic data as sample size increases. Using random matrix theory, we generalize this analysis and derive the performance of a binary classifier trained on a mix of real and pruned synthetic data in a high dimensional setting. Our findings identify conditions where synthetic data could improve performance, focusing on the quality of the generative model and verification strategy. We also show a smooth phase transition in synthetic label noise, contrasting with prior works on sharp transition in infinite sample limits. Our extensive experimental setup validates our theoretical results.

1 INTRODUCTION

The landscape of large language models (LLMs) is evolving rapidly, with a growing trend towards training models on a combination of real and synthetic data. This synthetic data is often generated by previously trained models (Allal et al., 2024; Ben Allal et al., 2024; Abdin et al., 2024). However, the quality of these generators can significantly impact the performance of newly trained models, potentially leading to model collapse (Shumailov et al., 2023), a phenomenon in which the model drastically degrades in performance.

Model collapse has been extensively studied, both empirically (Guo et al., 2023) and theoretically 033 (Seddik et al., 2024), highlighting the potential risks associated with training on synthetic data. To 034 mitigate these risks, researchers have proposed various strategies, including the verification of AIsynthesized data (Feng et al., 2024). This approach aligns with the widely adopted Reinforcement Learning from Human Feedback (RLHF) technique (Kaufmann et al., 2023). Feng et al. (2024) 037 provided theoretical support for this strategy by analyzing synthetic data as Gaussian mixtures with 038 noisy labels, using linear binary classifiers and scalar parameters to control verifier quality. Their findings reveal a sharp performance transition: under infinite synthetic sample size conditions, model accuracy shifts from zero accuracy (due to errors in synthetic data and verification) to optimal 040 performance as these errors decrease. 041

While current theoretical studies primarily focus on label noise in synthetic data (Dohmatob et al., 2024a; Gerstgrasser et al., 2024; Feng et al., 2024), they often overlook potential distribution shifts in the feature space between real and synthetic data. This gap is particularly relevant in practical scenarios where generative models are trained on finite real data sets, potentially leading to imperfect learning of the underlying distribution.

Our paper addresses this gap by proposing a statistical model that accounts for both distribution shifts in the feature space and label noise. In our model, we induce distribution shifts in the feature space by supposing that the statistics of synthetic data are empirical estimates of the underlying real data statistics. In a finite sample size regime, these estimates may be biased, resulting in distribution shifts between real and synthetic data. Leveraging random matrix theory, we derive the theoretical performance of a binary classifier trained on a mixture of real and pruned (i.e., verified) synthetic data in a high-dimensional setting. Our analysis provides conditions under which synthetic data improves performance, emphasizing the critical roles of the generative model's quality and the efficacy of the synthetic data verification strategy. Lastly, we show that the sharp phase transition phenomenon identified in (Feng et al., 2024) in the infinite sample size limit is a particular case of a general result, where smooth phase transitions can take place.

Summary of contributions. Our contributions are four fold:

- We introduce a statistical model for studying synthetic data that accounts for label and feature noise, extending beyond previous models that only consider label noise.
- By leveraging random matrix theory, we characterize the performance of a binary classifier trained on a mixture of real and synthetic data in a high-dimensional setting.
- When training only on synthetic data, we find a smooth phase transition in classifier performance, generalizing the work of Feng et al. (2024) on sharp transitions in infinite sample size limit.
- We validate our results with extensive experiments (toy example and realistic LLM setups).

#### 2 THEORETICAL SETUP

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094 095 096 **Real data.** We suppose that real data consists of n p-dimensional i.i.d. vectors  $x_1, \ldots, x_n \in \mathbb{R}^p$ sampled from a Gaussian mixture of two distinct isotropic clusters  $C_1$  and  $C_2$  of means  $\pm \mu$  with  $\mu \in \mathbb{R}^p$ . Essentially, for  $a \in \{1, 2\}$ , each data vector  $x_i \in C_a$  has a corresponding label  $y_i = (-1)^a$ and is sampled as

$$\boldsymbol{x}_i = y_i \boldsymbol{\mu} + \boldsymbol{z}_i, \quad \boldsymbol{z}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_p).$$
 (1)

**Generative model.** To generate synthetic data, we consider the generative model corresponding to maximum likelihood which consists of estimating the underlying first and second-order statistics of the real data with their empirical estimates. In particular, we suppose that we are given a subset  $\hat{n} \leq n$  of the real dataset  $(\boldsymbol{x}_i, y_i)_{i=1}^n$  on which we can estimate the statistics. This setup allows us to model a situation where new real data samples might be available to train next-generation models and the parameter  $\hat{n}$  offers control over the generative model quality. The statistics for generating synthetic data are therefore computed using the following estimates

$$\hat{\boldsymbol{\mu}} = \frac{1}{\hat{n}} \sum_{i=1}^{\hat{n}} y_i \boldsymbol{x}_i, \quad \hat{\mathbf{C}} = \frac{1}{\hat{n}} \sum_{i=1}^{\hat{n}} \left( y_i \boldsymbol{x}_i - \hat{\boldsymbol{\mu}} \right) \left( y_i \boldsymbol{x}_i - \hat{\boldsymbol{\mu}} \right)^\top.$$
(2)

**Synthetic data.** We consider that synthetic data is generated as m i.i.d. vectors  $\tilde{x}_1, \ldots, \tilde{x}_m \in \mathbb{R}^p$ with corresponding (noisy) labels  $\tilde{y}_1, \ldots, \tilde{y}_m = \pm 1$  such that  $\tilde{x}_i \in \tilde{C}_a$  with true label  $\bar{y}_i = (-1)^a$ for  $a \in \{1, 2\}$  is sampled as ( $\tilde{C}_1$  and  $\tilde{C}_2$  denote the synthetic clusters)

$$\tilde{\boldsymbol{x}}_{i} = \bar{y}_{i}\hat{\boldsymbol{\mu}} + \hat{\mathbf{C}}^{\frac{1}{2}}\tilde{\boldsymbol{z}}_{i}, \quad \tilde{\boldsymbol{z}}_{i} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_{p}), \tag{3}$$

and the labels  $\tilde{y}_i$  are generated such that  $\mathbb{P}\{\tilde{y}_i = \bar{y}_i\} = 1 - \varepsilon$  where  $\varepsilon \ge 0$  controls label noise. Essentially, the **quality** of synthetic data depends on the **sample size**  $\hat{n}$  and the label noise rate  $\varepsilon$ .

099 In the asymptotic regime where  $\hat{n} \to \infty$  with  $\frac{p}{\hat{n}} \to 0$ , we can generate synthetic samples that 100 follow asymptotically the exact same distribution as of the real ones, and therefore only label noise is relevant to the quality of the synthetic data. However, in the regime when both  $\hat{n}, p \to \infty$ 101 with  $\frac{p}{\hat{n}} \to \hat{\eta} > 0$ , while the estimation of  $\mu$  with  $\hat{\mu}$  remains consistent, the estimation of the 102 **covariance is not**. In fact, in this regime  $\|\hat{\mathbf{C}} - \mathbf{I}_p\| \neq 0$  and the eigenvalues of  $\hat{\mathbf{C}}$  spread in the 103 vicinity of 1 which is described in the limit by the Marchenko-Pastur law (Marchenko & Pastur, 104 1967). Eventually, such inconsistency in estimating the second moment in high dimensions yields 105 a distribution shift between synthetic and real data, which might cause a drop in performance when 106 training a new model on synthetic data generated with  $\hat{\mu}$  and C. In the remainder, we describe 107 precisely how the performance of a simple classifier is affected in this regime.

108 **Objective.** Our goal throughout the paper is to study the effect of synthetic data when training 109 on a mixture of the n real and m synthetic data described above, i.e., with the following objective 110 function

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$$\mathcal{L}(\boldsymbol{w}) := \underbrace{\frac{1}{n+m} \sum_{i=1}^{n} \ell(\boldsymbol{x}_i, y_i; \boldsymbol{w})}_{\text{real data}} + \underbrace{\frac{1}{n+m} \sum_{i=1}^{m} q_i \ell(\tilde{\boldsymbol{x}}_i, \tilde{y}_i; \boldsymbol{w})}_{\text{synthetic data}}, \tag{4}$$

where  $\ell$  is some convex loss function and the  $q_i$ 's are data pruning parameters ( $q_i \in \{0, 1\}$ ), indicating whether to select or drop the  $i^{th}$  synthetic sample ( $\tilde{x}_i, \tilde{y}_i$ ). In particular, the  $q_i$ 's are Bernoulli random variables conditionally on  $\tilde{y}_i \neq \bar{y}_i$  or  $\tilde{y}_i = \bar{y}_i$  (we recall that  $\bar{y}_i$ 's denote the true labels of the synthetic samples) with conditional probabilities

$$\rho := \mathbb{P}\{q_i = 1 \mid \tilde{y}_i \neq \bar{y}_i\}, \quad \phi := \mathbb{P}\{q_i = 1 \mid \tilde{y}_i = \bar{y}_i\},$$
(5)

which control the pruner accuracy (as discussed in (Feng et al., 2024)). As we mentioned previously, we suppose training on  $n \ge \hat{n}$  real data, modeling a situation where new real samples are available with  $\hat{n}$  controlling the generative model quality in generating faithful synthetic features<sup>1</sup>.

125  $L^2$ -loss. In the remainder of the paper we take  $\ell$  to be the regularized squared loss as it allows us 126 to obtain a closed-form solution for the optimization problem in equation 4, hence, a more tractable 127 analysis. Specifically, we take  $\ell(x, y; w) = (w^{\top}x - y)^2 + \gamma ||w||^2$  where  $\gamma \ge 0$  is a regularisation 128 parameter, which yields the following closed-form solution

$$\boldsymbol{w} = \frac{1}{N} \mathbf{Q} \mathbf{X} \boldsymbol{y}, \quad \mathbf{Q} = \left(\frac{1}{N} \mathbf{X} \mathbf{X}^{\top} + \gamma \mathbf{I}_{p}\right)^{-1}.$$
 (6)

where N = n + m, the matrix  $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n, q_1 \tilde{\mathbf{x}}_1, \dots, q_m \tilde{\mathbf{x}}_m) \in \mathbb{R}^{p \times N}$  is the concatenation of both real and (pruned) synthetic features, and the vector  $\mathbf{y} = (y_1, \dots, y_n, \tilde{y}_1, \dots, \tilde{y}_m) \in \mathbb{R}^N$  is the concatenation of real and (noisy) synthetic labels.

### 3 MAIN RESULTS

In this section, we present and discuss the main results obtained through the analysis of the classifier model defined in equation 6. We start by specifying the supposed growth rate assumptions.

**Assumption 3.1** (Growth Rate). We consider a high-dimensional regime where  $p, n, \hat{n}, m \to \infty$ and we recall N = n + m such that:

1)  $\frac{p}{N} \to \eta \in [0,\infty)$ , 2)  $\frac{p}{\hat{n}} \to \hat{\eta} \in [0,\infty)$ , 3)  $\frac{n}{N} \to \pi \in [0,1]$ , 4)  $\|\boldsymbol{\mu}\| = \mathcal{O}(1)$ .

**Role of the assumptions.** The above assumptions are central to understanding the nuances between real and synthetic data (as constructed above) in a high-dimensional regime. Essentially,

• Assumptions 1), 2), and 3) define the scaling of data dimension p and the different sample sizes (n real data, m synthetic data, and  $\hat{n}$  real samples used to train the generative model). In particular, we suppose that all these dimensions scale linearly relative to each other, which corresponds to the classical RMT regime. This setting is more general than the infinite sample size regime in the sense that the former can be recovered by taking  $\eta, \hat{\eta} \rightarrow 0$ . Specifically, the parameter  $\hat{\eta}$  controls the generative model quality, where lower values indicate better generative model quality. Plus, the parameter  $\pi$  corresponds to the proportion of the real samples in the data mixture. For instance,  $\pi = 0$  models a setting where the training is done only on synthetic samples are of the same order, therefore, making our results scalable to any possible proportion  $\pi$ .

• The fourth condition about the magnitude of the mean vector  $\mu$  reflects the fact that the classification problem should neither be trivial  $(\|\mu\| \gg 1)$  nor impossible  $(\|\mu\| \to 0)$  as

<sup>&</sup>lt;sup>1</sup>Technically, our results hold irrespective of the statistical dependencies between the data used to train the generative model in equation 2 or the classifier in equation 6.

the dimension of data grows large. For instance, assuming  $\|\boldsymbol{\mu}\|$  of order  $O(\sqrt{p})$  would not be relevant as  $p \to \infty$  since the classification problem becomes trivial in this regime. We refer the reader to (Couillet & Benaych-Georges, 2016) for a more general formulation and justifications of this assumption under an extended k-class Gaussian mixture model.

Having stated the main assumptions, we are now in place to present our main technical findings
on the performance of the classifier model trained on a mixture of real and synthetic data. As a
corollary, we also cover the case where the model is trained solely on synthetic data and showcase a
generalization of the result obtained by Feng et al. (2024).

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#### 3.1 PARTIALLY SYNTHETIC: MIXTURE OF REAL AND SYNTHETIC DATA

173 We start by analyzing the general case of training on a mix of real and synthetic data. As we 174 described in the previous section, the statistics of synthetic data are empirical estimates of the ones 175 of real data. Under Assumption 3.1, the estimation of  $\mu$  with  $\hat{\mu}$  remains consistent, while the 176 estimation of the underlying real data covariance (i.e.,  $I_{v}$  in our setting) with C is inconsistent as we 177 previously discussed. As a result, studying the theoretical performance of the classifier in equation 6 178 demands deploying tools from random matrix theory that refines the estimation of scalar quantities 179 depending on large random matrices. In our case, the scalar quantity of interest corresponds to the model's accuracy which depends on the random matrices  $\mathbf{C}$  and  $\mathbf{X}\mathbf{X}^{\perp}$  as per equation 6. 181

In our analysis of the classifier's theoretical performance, we found that the effect of high-dimension (and that of distribution shift between real and synthetic samples) is described by three scalar quantities  $(\delta_r^*, \delta_s^*, \delta_g^*)$  which are defined as the unique solution of the following fixed point system which is derived from Lemma F.1 in the Appendix.

$$\delta_g = \frac{\alpha(1-\pi)}{1+\delta_s} \cdot \frac{\hat{\eta}}{\gamma + \frac{\pi}{1+\delta_r} + \frac{\alpha(1-\pi)}{(1+\delta_s)(1+\delta_g)}}, \quad \delta_r = \frac{\eta}{\hat{\eta}} \cdot \frac{1+\delta_s}{\alpha(1-\pi)} \delta_g, \quad \delta_s = \frac{\alpha\delta_r}{1+\delta_g}.$$
 (7)

where  $\alpha = \phi(1 - \varepsilon) + \rho \varepsilon$ . These quantities will be used subsequently in our results. Intuitively,  $\delta_r^*$  captures the contribution of real data,  $\delta_s^*$  corresponds to the contribution of synthetic data, and  $\delta_g^*$  corresponds to the influence of the generative model. In an infinite sample size regime where  $n, m, \hat{n} \to \infty$  while the dimension p is kept fixed,  $(\delta_r^*, \delta_s^*, \delta_g^*) = (0, 0, 0)$ , while under Assumption 3.1 these quantities are non zero yielding a counterintuitive behavior in high-dimension. For convenience, we further define a set of scalar quantities that will prove useful in the next result.

$$\alpha = \mathbb{E}[q_i] = \phi(1-\varepsilon) + \rho\varepsilon, \quad \lambda = \mathbb{E}[q_i\tilde{y}_i] = \phi(1-\varepsilon) - \rho\varepsilon,$$
  
$$a = \frac{\pi}{1+\delta_r^*} + \frac{\alpha(1-\pi)}{1+\delta_s^*}, \quad b = \gamma + \frac{\pi}{1+\delta_r^*} + \frac{\alpha(1-\pi)}{(1+\delta_s^*)(1+\delta_g^*)}, \quad c = \frac{\pi}{1+\delta_r^*} + \frac{\lambda(1-\pi)}{1+\delta_s^*}$$

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$$a_1 = \frac{\pi\eta}{(1+\delta_r^*)^2 h_2 b^2}, \quad b_1 = \frac{\alpha(1-\pi)\eta}{(1+\delta_s^*)^2 (1+\delta_g)^2 h_2 b^2}, \quad b_2 = \frac{\alpha(1-\pi)\eta}{(1+\delta_s^*)^2 (1+\delta_g^*)^4 h_2 b^2},$$

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$$h_1 = 1 - a_1 - b_2, \quad h_2 = 1 - \left(\frac{\alpha(1-\pi)}{(1+\delta_s^*)(1+\delta_g^*)}\right)^2 \frac{\hat{\eta}}{b^2}$$

204 The first set of parameters  $(\alpha, \lambda, a, b, c)$  pop out from the expectation of the classifier's decision 205 function while the remaining quantities are related to second-order statistics. Essentially, the main relevant quantities to our analysis are  $\hat{\eta}$  and  $\varepsilon$  which characterize the quality of synthetic data, with 206  $\phi$  and  $\rho$  characterizing the verification process. In an idealized scenario, we would have  $\hat{\eta} = \varepsilon = 0$ 207 which reflects the fact that there is no distribution shift nor label noise, while  $\phi = 1 - \rho = 1$ 208 corresponds to a perfect (oracle) verification process. Our main goal is to study how these param-209 eters influence the classifier's performance hence providing the conditions that make synthetic data 210 relevant for performance boost. The main result brought by this paper is therefore stated as follows. 211

**Theorem 3.2** (Theoretical performance). Let w be the Ridge classifier as defined in equation 6 and suppose that Assumption 3.1 holds. The decision function  $w^{\top}x$ , on some (real) test sample  $x \in C_a$ , with corresponding label  $y = (-1)^a$  and independent of  $\mathbf{X}$ , satisfies

$$oldsymbol{w}^{ op}oldsymbol{x} \xrightarrow{\mathcal{D}} \mathcal{N}\left(y \cdot \mu, \, 
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ight),$$



Figure 1: Scatter plots correspond to empirical test accuracy while lines correspond to the theoretical counterpart as per Theorem 3.2. The parameters used in this experiments are:  $n = \hat{n} = 1000$ ,  $\|\boldsymbol{\mu}\| = 0.7$  and  $\gamma = 1$ ,  $(\rho, \phi) = (0, 1)$  for Oracle supervision and  $(\rho, \phi) = (1, 0.5)$  for the Weak supervision. The parameter  $\varepsilon$  is variable depending on the proportion of synthetic data by taking it equal to the misclassification error corresponding to training a classifier on synthetic data only. As theoretically anticipated, a boost of performance is observed with synthetic data supervision while distribution shift affects negatively the performance.

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where 
$$\mu = \frac{c \|\boldsymbol{\mu}\|^2}{b+a \|\boldsymbol{\mu}\|^2}$$
 and  
 $\nu = \frac{c \|\boldsymbol{\mu}\|^2}{h_1(b+a \|\boldsymbol{\mu}\|^2)^2} \left( c(1+b_1-b_2) \|\boldsymbol{\mu}\|^2 + \frac{c}{h_2} - 2\left(a_1 + \frac{\lambda b_1}{\alpha}\right) (b+a \|\boldsymbol{\mu}\|^2) \right) + \frac{a_1+b_1}{h_1}.$ 

Moreover, the asymptotic test accuracy of the classifier is given by  $\Phi\left((\nu - m^2)^{-\frac{1}{2}}m\right)$  where  $\Phi(x) = \frac{1}{2}\int_{-\infty}^{x}e^{-\frac{t^2}{2}}dt$ 

$$\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-\frac{t^2}{2}} dt.$$

Theorem 3.2 states that the decision function of the classifier in equation 6 is asymptotically equivalent to the thresholding of two monovariate Gaussian random variables with respective means  $\mu$ and  $-\mu$  and standard deviation  $\nu$ , where the statistics  $\mu$  and  $\nu$  are expressed in terms of the scalar quantities defined above. Here,  $\mu$  represents the signal strength while  $\nu$  highlights the classifier's uncertainty or dispersion. To provide some insights into the implications of this theorem, we start by examining it in a low-dimensional regime where p is kept fixed while  $n, m, \hat{n} \to \infty$ . In this case, we have  $\eta, \hat{\eta} \to 0$  and  $\delta_r^*, \delta_s^*, \delta_g^* \to 0$  which yields

$$a = \pi + \alpha(1 - \pi), \quad b = \gamma = \pi + \alpha(1 - \pi), \quad c = \pi + \lambda(1 - \pi)$$

and  $a_1 = b_1 = b_2 = 0$  with  $h_1 = h_2 = 1$ . As such, the accuracy of the classifier increases with  $\lambda$ , i.e., when the synthetic labels are verified (large  $\frac{\phi}{\rho}$ ) or less noisy (small  $\varepsilon$ ). This is in line with the findings of Feng et al. (2024) while extended by our result to training on a mix of real and synthetic data. However, when the dimension scales linearly with the different sample sizes, the values of  $\delta_r^*, \delta_s^*, \delta_g^* \neq 0$  yielding a lower signal strength  $\mu$  and higher variance  $\nu^2$ . This highlights the fact that in high-dimension, even if the synthetic labels are not noisy or equivalently well verified, there is a performance drop due to the feature distribution shift between real and synthetic data.

Fig. 1 depicts the empirical test accuracy and the theoretical prediction as per Theorem 3.2 when varying the proportion of synthetic data. As theoretically anticipated, adding synthetic data does not boost the classifier's performance unless it is verified accurately (oracle supervision versus weak supervision). Moreover, our results show the effect of the distribution shift which heavily affects performance in the case of weak supervision (Fig. 1 right).

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#### 3.2 FULLY SYNTHETIC: TRAINING ON SYNTHETIC DATA

In this section, we study the fully synthetic setting which corresponds to training solely on synthetic data (i.e. n = 0 in equation 6). For simplicity, we consider only label noise and ignore feature noise in the synthetic data. Essentially, this allows us to exhibit the smooth phase transition of the classifier's accuracy in terms of label noise, which extends the result of Feng et al. (2024). Specifically, we obtain the following corollary of theorem 3.2. **Corollary 3.3** (Performance when training only on synthetic data). Let  $w_s$  be the Ridge classifier described in equation 6 trained only on synthetic data with only label noise (i.e.,  $\hat{\mathbf{C}} = \mathbf{I}_p$ ). Under Assumption 3.1, the decision function  $w_s^{\top} \mathbf{x}$  on a test sample  $\mathbf{x} \in C_a$  with corresponding label  $y = (-1)^a$  and independent of  $\mathbf{X}$ , satisfies

$$\boldsymbol{w}_s^{\top}\boldsymbol{x} \xrightarrow{\mathcal{D}} \mathcal{N}\left(\boldsymbol{y} \cdot \boldsymbol{\mu}_s, \, \boldsymbol{\nu}_s - \boldsymbol{\mu}_s^2\right) \text{ where } \boldsymbol{\mu}_s = \frac{\phi(1-\varepsilon) - \rho\varepsilon}{\alpha \|\boldsymbol{\mu}\|^2 + \alpha + \gamma(1+\delta_s)} \|\boldsymbol{\mu}\|^2,$$

with

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$$\nu_{s} = \frac{\lambda^{2} \|\boldsymbol{\mu}\|^{2}}{h(\alpha \|\boldsymbol{\mu}\|^{2} + \alpha + \gamma(1 + \delta_{s}))} \left(\frac{\|\boldsymbol{\mu}\|^{2} + 1}{\alpha \|\boldsymbol{\mu}\|^{2} + \alpha + \gamma(1 + \delta_{s})} - \frac{2(1 - h)}{\alpha}\right) + \frac{1 - h}{h},$$

$$\eta_{s} = \lim_{p \to \infty} \frac{p}{m}, \quad h = 1 - \frac{\alpha \eta_{s}}{(\alpha + \gamma(1 + \delta))^{2}}, \quad \delta_{s} = \frac{\eta_{s}\alpha - \alpha - \gamma + \sqrt{(\alpha + \gamma - \eta_{s}\alpha)^{2} + 4\eta_{s}\alpha\gamma}}{2\gamma}.$$

284 Corollary 3.3 provides an explicit formulation 285 of Theorem 3.2 with synthetic data only and ignoring distribution shift (yielding an explicit 287 expression of  $\delta_s$ ). This setting provides a 288 clearer interpretation of the effect of label noise since the classifier's performance is directly re-289 lated to the quantity  $\lambda = \phi(1 - \varepsilon) - \rho \varepsilon$ . The 290 breaking point of the classifier's performance 291 occurs at  $\lambda = 0$ , which corresponds to the ac-292 curacy of random guessing, yielding to the crit-293 ical value of label noise  $\varepsilon^* = (1 + \frac{\rho}{\phi})^{-1}$ . This critical value is equivalent to the one obtained 295 by Feng et al. (2024), however, we extend their 296 result to the high-dimensional setting which ex-297 hibits a smoother phase transition as depicted 298 in Fig. 2. Essentially, the sharp phase transition 299 of Feng et al. (2024) is covered by our result 300 by taking  $\eta_s \to 0$ . In this sense, the predicted smooth transition better mirrors real-world sce-301 narios where finite sample sizes introduce grad-302 ual changes in performance rather than abrupt 303 shifts. This makes our theoretical findings more 304 applicable and reliable for practical scenarios. 305



Figure 2: Phase transition in terms of label noise as predicted by Corollary 3.3. The critical value for  $\varepsilon$  is predicted at  $\varepsilon^* = (1 + \frac{\rho}{\phi})^{-1}$ . We fix p =100 and vary m. The remaining parameters are  $\|\boldsymbol{\mu}\| = 1, \rho = 0.3$  and  $\phi = 0.8$ , i.e.  $\varepsilon^* = 0.73$ .

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#### 4 CONCLUSION AND LIMITATIONS

In this work, we conducted a comprehensive theoretical and empirical analysis of models trained on a mixture of real and synthetic data with verification. By leveraging random matrix theory, we identified critical factors such as distribution shifts and label noise that significantly impact model performance. Our findings demonstrate that synthetic data can enhance model accuracy under specific conditions, particularly when the generative model is of high quality and the verification process is accurate. Additionally, we extended previous research by showing that performance transitions are smooth rather than sharp when synthetic data is incorporated in high-dimensional settings.

Despite these advancements, our current setting is limited to label verification of synthetic data.
 Incorporating feature verification represents a promising extension for future research, which could
 provide further insights into the reliability and effectiveness of synthetic data in model training.
 Another possible extension of our work is to study distributions beyond the Gaussian model and
 analyze how higher-order statistics can be incorporated into our current framework.

In conclusion, this work provides a foundational understanding of the conditions under which synthetic data can be beneficial for model training in high-dimensional settings. By integrating both
 theoretical insights and empirical validations, this study provides new insights into the effective utilization of synthetic data, paving the way for more resilient and performant AI models.

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#### **RELATED WORK** А

The use of synthesized data for model training has gained significant traction in recent years, partic-ularly with the widespread adoption of large language models (LLMs) that rely on large amounts of data in their training stages. Several studies have explored the impact of synthesized data on model performance, revealing both its advantages and limitations. A primary concern is the phenomenon of model collapse Shumailov et al. (2023), where the iterative use of generated data for model training results in a degradation of model quality. This issue has been explored theoretically and empirically across multiple studies (e.g. LeBrun et al. (2021); Alemohammad et al. (2023); Bohacek & Farid (2023); Bertrand et al. (2023); Jain et al. (2024); Seddik et al. (2024); Dohmatob et al. (2024a;b;c)). 

Seddik et al. (2024) investigated model collapse in recursive training settings, where new models are trained on data generated by previous models. They demonstrate that recursive training on purely synthetic data inevitably leads to performance degradation. However, they show that mixing real and synthetic data can attenuate model collapse, though the proportion of real data must remain high to maintain model performance. Their findings support the idea that synthesized data alone cannot sustain model quality across iterations without a significant quantity of real data. 

Gerstgrasser et al. (2024) argue that model collapse can be avoided entirely if data is accumulated rather than replaced across iterations. Their empirical studies on language models, diffusion models, and variational autoencoders indicate that accumulating both real and synthetic data helps maintain model performance over time, breaking the recursive degradation loop that leads to collapse. Ad-



Figure 3: Illustration of two different generation schemes for the MNIST data. *Top figure:* Generating MNIST-like data samples by only estimating the mean of each class  $\hat{\mu}_a$  for  $a \in [10]$  and without estimating the covariance matrix, i.e samples here are generated through the distribution  $\mathcal{N}(\hat{\mu}_a, \mathbf{I}_p)$ . *Bottom figure:* Generating samples by estimating both the mean and covariance of each class, as of our considered generative model defined in equation 2.

ditionally, Jain et al. (2024) introduced a weighted empirical risk minimization (ERM) approach to
 better integrate synthetic data to the training pipeline, leading to a significant reduce in the test risk.

504 The most relevant work to our study is Feng et al. (2024) where the authors examined the effects of synthesized data on model performance in a non-recursive setting, using the concept of rein-505 forcement through feedback to select high quality synthetic data. Their theoretical results, based 506 on Gaussian mixture models, showed that adding feedback significantly improves the robustness of 507 models trained on synthesized data. However, their setup assumes that only labels, not features, are 508 noisy. Additionally, their focus is primarily on scenarios where only the number of data points, n, 509 grows to infinity. Other (practical) scenarios where for instance the feature dimension, p, grows at a 510 fixed ratio with n are not covered. 511

512 Our work extends the Gaussian mixture model setup to include both noisy features and labels, which 513 is a more realistic scenario when training on synthesized data. Additionally, we consider a high-514 dimensional regime where both p and n grow to infinity with a fixed ratio, a setup often used in 515 Random Matrix Theory (RMT). This allows us to study the interaction between feature dimension, 516 presence of mixed data—original and synthetic—providing a more realistic framework for studying 517 the effect of synthetic data in practical applications.

### **B** EXPERIMENTS

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In this section, we present our experiments conducted on different real-world tasks and datasets in order to illustrate our theoretical findings presented in the previous section.

### **B.1** EXPERIMENTAL SETTINGS

Amazon Reviews. We use the Amazon Reviews datasets (Blitzer et al. (2007)) which include several binary classification tasks corresponding to positive versus negative reviews of books, electronics and kitchen. We apply the standard scaler from sklearn (Pedregosa et al., 2011) and estimate  $\|\mu\|$  with the normalized data. The synthetic data is generated following the described generative scheme (see equation 2). We use the Ridge classifier in equation 6 for this data.

532 **MNIST.** We also conducted experiments on the MNIST (LeCun & Cortes (2010)) dataset to illus-533 trate our theoretical insights, by training a simple neural network with one-hidden layer and ReLU 534 activation function. Concerning the synthetic data, we used different values of  $\hat{n}$  to generate new 535 samples in order to highlight the importance of the generation quality, and introduced a label noise  $\varepsilon$ 536 to highlight the importance of the pruning. Figure 3 shows some examples of MNIST-like synthetic 537 data that has been generated and used in our experiments.

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LLM Safety Alignment. We also investigated the impact of synthetic text data for the task of alignment of LLMs with direct preference optimization on safety datasets, using the same approach



Figure 4: **Results of the Amazon Reviews setting**: Test Accuracy with the proportion of synthetic data evaluated on Amazon Review Blitzer et al. (2007) dataset. The number of real data sample used is n = 800, the dimension is p = 400,  $\gamma = 10^{-1}$  and  $\varepsilon = 0.2$  (fixed). The pruning parameters are  $(\rho, \phi) = (0, 1)$  for Oracle supervision and  $(\rho, \phi) = (1, 1)$  for No supervision.

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555 as in (Alami et al., 2024). We finetune the Falcon 2-11B Instruct model (Malartic et al., 2024) on n = 5000 human data from Anthropic's *HH-RLHF* dataset<sup>2</sup>, which correspond to real data, 556 while synthetic data are extracted from the PKU safe RLHF dataset<sup>3</sup> which are generated using Alpaca $3-70B^4$ . We increase the amount of synthetic data by injecting gradually five batches of 558 7000 samples per batch, to study the performance of the fine-tuned model as we add more synthetic 559 data. In this experiment, we focus only on label noise by randomly perturbing the synthetic dataset. 560 Each entry from the synthetic dataset includes a prompt  $x^{(j)}$ , a safe response  $y^{(j)}_{s_w}$  (safety-accepted 561 response), and a less safe response  $y_{s_l}^{(j)}$  (safety-rejected response). We, therefore, perturbed this 562 dataset by swapping safe and less safe responses with a probability  $\varepsilon$  (label noise), and selecting the 563 prompts according to a verifier of parameters  $\rho$  and  $\phi$  described earlier in this paper.

For the evaluation, we use the ALERT dataset<sup>5</sup> (Tedeschi et al. (2024)) to test the safety of responses of the finetuned model after being judged by LLama-Guard-3-8B (Dubey et al., 2024). As in (Alami et al., 2024), we compute the safety score as the percentage of safe answers labeled by Llama-Guard-3-8B. We report the results in figure 6 for strong supervision ( $\rho$ ,  $\phi$ ) = (0.2, 0.9) and weak supervision ( $\rho$ ,  $\phi$ ) = (0.5, 0.5) for both  $\varepsilon$  = 0.1 and  $\varepsilon$  = 0.5.

**LLM O&A Safety Generation.** This experiment aims to evaluate the impact of synthetically 571 generated prompts (i.e. feature noise). To construct the generative model for this experiment, we 572 fine-tune an LLM (M) with supervised fine-tuning (SFT) on pairs of question-answer (Q&A) sen-573 tences extracted from a safety dataset. Initially, we fine-tune M on 12k human annotated Q&A as 574 safe or unsafe (Ji et al., 2024), yielding a fine-tuned model on human data denoted as  $M_h$ . Then, 575  $M_h$  is considered as the generative model to generate a large dataset of synthetic Q&A prompts 576 (around 120k samples) that were further annotated as safe/unsafe using Mistral-Nemo<sup>6</sup> and 577 Qwen2-7B-Instruct (Yang et al., 2024), which incorporate a further label noise. To verify the 578 data, we use Llama-Guard-3.1 (Dubey et al., 2024). We conducted this experiment using two 579 LLMs (M) of different sizes (to vary the generative model quality) which are the Llama-3.1-8B 580 and Gemma-2-2B-it (Team et al., 2024) instruct models.

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582 B.2 EFFECT OF LABEL NOISE 583

Figures 4, 5 (left plot) 6 reflect the effect of label noise. Essentially, as theoretically anticipated, the trained models do not benefit from synthetic data unless it is accurately verified. Specifically, in the case of weak supervision, model performance drops significantly, and the improvement from using synthetic data is only visible with very high synthetic sample sizes. On the contrary, with strong supervision, we observe a monotonous performance boost as the proportion of synthetic data increases.

<sup>&</sup>lt;sup>2</sup>https://huggingface.co/datasets/yimingzhang/hh-rlhf-safety

<sup>91 &</sup>lt;sup>3</sup>https://huggingface.co/datasets/PKU-Alignment/PKU-SafeRLHF

<sup>592 &</sup>lt;sup>4</sup>https://huggingface.co/PKU-Alignment/alpaca-70b-reproduced-llama-3

<sup>5</sup> https://github.com/Babelscape/ALERT/blob/master/data/alert.jsonl

<sup>&</sup>lt;sup>6</sup>https://mistral.ai/news/mistral-nemo/



Figure 5: **Results of the MNIST setting**: Training an NN with one hidden layer and ReLU activation function on a mixture of real (n = 500) and varying the proportion of synthetic Gaussian data.



Figure 6: **Results of LLM Safety Alignment**: Strong supervision corresponds to  $(\rho, \phi) = (0.2, 0.9)$ and weak supervision to $(\rho, \phi) = (0.5, 0.5)$ .



Figure 7: Results of LLM Q&A Safety Generation: Evaluation of two LLMs trained as presented in section B.1 is depicted for both (left) M = Llama3.l-8B-Instruct and (right) M =Gemma-2-2B-it. The test accuracy is computed over the testing dataset extracted from Ji et al. (2024), with 2.8k Q&A samples. The results shown are the average over 3 runs.

#### **B.3** EFFECT OF FEATURE NOISE

In this section, we discuss the experiments related to feature noise. In Fig. 5 (right), we depict
the performance of a one-hidden layer MLP trained on a mix of real and synthetic MNIST data
following our theoretical framework. As we can observe from the figure, the performance boost
from synthetic data heavily depends on the generative model quality as predicted by our theoretical
results. We further observe the same trend using LLMs as depicted in Fig. 7, where we observe
that the synthetic data generated by Llama3.1-8B-Instruct yields a better performance boost



Figure 8: Behavior of  $(\delta_r^*, \delta_s^*, \delta_g^*)$  in terms of the ratio  $\frac{p}{n}$ . For small ratio  $\frac{p}{n}$ , the values of  $\delta_r^*, \delta_s^*, \delta_g^*$  are close to 0.  $(\delta_r^*, \delta_s^*, \delta_g^*)$  are computed by iterating the system 7 starting from random values.

compared to Gemma-2-2B-it as we increase the amount of synthetic samples, which means that Llama3.1-8B-Instruct generates better synthetic samples (less distribution shift) than Gemma-2-2B-it.

PROOFS DERIVATIONS

#### C USEFUL LEMMAS

**Notation:** For  $a \in \{1, 2\}$ , we denote by  $\mathbb{I}_a = \{i \mid x_i \in \mathcal{C}_a\}$ , i.e, the set of indices of vectors belonging to class  $\mathcal{C}_a$ . Furthermore, we denote  $\Sigma = \mu \mu^\top + \mathbf{I}_p = \mathbb{E}[\mathbf{x}\mathbf{x}^\top]$  for  $\mathbf{x} \in \mathcal{C}_a$ , and  $\Sigma_\beta = \mu_\beta \mu_\beta^\top + \mathbf{C}$ 

Given a resolvent matrix:  $\mathbf{Q} = \left(\frac{1}{n}\sum_{j=1}^{n} \boldsymbol{x}_{j}\boldsymbol{x}_{j}^{\top} + \gamma \mathbf{I}_{p}\right)^{-1}$ , we denote by  $Q_{-\boldsymbol{x}_{i}}$  or  $Q_{i}$  the resolvent matrix gotten by removing the contribution of the  $i^{th}$  sample, i.e:

$$\mathbf{Q}_{-\boldsymbol{x}_{i}} = \left(\frac{1}{n}\sum_{j\neq i}\boldsymbol{x}_{j}\boldsymbol{x}_{j}^{\top} + \gamma \mathbf{I}_{p}\right)^{-1}$$
(8)

Now we will list the most useful lemmas and results used in our analysis.

C.1 GENERAL LEMMAS

Lemma C.1 (Inverse identity). For invertible matrices A and B, we have that:

$$\mathbf{A}^{-1} - \mathbf{B}^{-1} = \mathbf{A}^{-1}(\mathbf{B} - \mathbf{A})\mathbf{B}^{-1}$$

**Lemma C.2** (Woodbury). For  $\mathbf{A} \in \mathbb{R}^{p \times p}$ ,  $\mathbf{U}, \mathbf{V} \in \mathbb{R}^{p \times k}$ , such that both  $\mathbf{A}$  and  $\mathbf{A} + \mathbf{U}\mathbf{V}^{\top}$  are invertible, we have:

$$\left(\mathbf{A} + \mathbf{U}\mathbf{V}^{\top}\right)^{-1} = \mathbf{A}^{-1} - \mathbf{A}^{-1}\mathbf{U}\left(\mathbf{I}_{k} + \mathbf{V}^{\top}\mathbf{A}^{-1}\mathbf{U}\right)^{-1}\mathbf{V}^{\top}\mathbf{A}^{-1}$$

A particular case of this lemma C.2, in the case of k = 1, is called *Sherman-Morisson*'s identity.

**Lemma C.3** (Sherman-Morisson). For  $\mathbf{A} \in \mathbb{R}^{p \times p}$  invertible and  $\mathbf{u}, \mathbf{v} \in \mathbb{R}^{p}$ ,  $\mathbf{A} + \mathbf{u}\mathbf{v}^{\top}$  is invertible if and only if  $: 1 + \mathbf{v}^{\top}\mathbf{A}\mathbf{u} \neq 0$ , and:

 $(\mathbf{A} + \boldsymbol{u} \boldsymbol{v}^{\top})^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1} \boldsymbol{u} \boldsymbol{v}^{\top} \mathbf{A}^{-1}}{1 + \boldsymbol{v}^{\top} \mathbf{A}^{-1} \boldsymbol{u}}$ 

Besides,

$$(\mathbf{A} + \boldsymbol{u} \boldsymbol{v}^{\top})^{-1} \boldsymbol{u} = \frac{\mathbf{A}^{-1} \boldsymbol{u}}{1 + \boldsymbol{v}^{\top} \mathbf{A}^{-1} \boldsymbol{u}}$$

# 702 C.2 DETERMINISTIC EQUIVALENTS

Let us state here the deterministic equivalent of the resolvent matrix  $\mathbf{Q}$  defined in the general model's equation (6) for any general covariance matrix  $\mathbf{C}$  and mean  $\mu_{\beta} = \beta \mu + \mu^{\perp}$  that define the statistic of the synthetic data, as in equation 14.

**Lemma C.4** (Deterministic equivalent of **Q**). Under the 3.1 assumptions listed above in the main paper, a deterministic equivalent for  $\mathbf{Q} \equiv \mathbf{Q}(\gamma)$ , denoted  $\overline{\mathbf{Q}}$ , is given by:

$$\bar{\mathbf{Q}} = \left(\frac{\pi(\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p)}{1 + \delta} + \frac{\alpha(1 - \pi)(\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \mathbf{C})}{1 + \delta_S} + \gamma \mathbf{I}_p\right)^{-1}$$

where:

$$\pi = \frac{n}{n+m}, \quad \alpha = \phi(1-\varepsilon) + \rho\varepsilon, \quad \delta = \frac{1}{N}\operatorname{Tr}(\bar{\mathbf{Q}}), \quad \delta_S = \frac{\alpha}{N}\operatorname{Tr}(\mathbf{C}\bar{\mathbf{Q}})$$

716 *Proof.* We want to find  $\overline{\mathbf{Q}}$  such that for all bounded  $a, b \in \mathbb{R}^p$ :

$$\boldsymbol{a}^{\top}(\mathbb{E}[\mathbf{Q}]-\bar{\mathbf{Q}})\boldsymbol{b} o 0$$

Let  $\bar{\mathbf{Q}} = (\mathbf{S} + \gamma \mathbf{I}_p)^{-1}$ . We want to determine an S that satisfies the above property. We have that:

$$\mathbb{E}[\mathbf{Q}] - \bar{\mathbf{Q}} = \mathbb{E}[\mathbf{Q}(\mathbf{S} - \frac{1}{N}\mathbf{V}\mathbf{V}^{\top})\bar{\mathbf{Q}}] \quad (\text{lemma}C.1)$$
$$= \frac{1}{N}\sum_{i=1}^{N}\mathbb{E}[\mathbf{Q}(\mathbf{S} - \boldsymbol{v}_{i}\boldsymbol{v}_{i}^{\top})\bar{\mathbf{Q}}]$$

$$= \frac{1}{N} \sum_{i=1}^{n} \mathbb{E}[\mathbf{Q}(\mathbf{S} - \boldsymbol{x}_i \boldsymbol{x}_i^{\top})\bar{\mathbf{Q}}] + \frac{1}{N} \sum_{i=1}^{m} \mathbb{E}[\mathbf{Q}(\mathbf{S} - q_i \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^{\top})\bar{\mathbf{Q}}]$$

$$= \frac{1}{N} \sum_{i=1}^{n} \mathbb{E}[\mathbf{Q}(\mathbf{S} - q_i \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^{\top})\bar{\mathbf{Q}}]$$

$$= \frac{1}{N} \sum_{i=1}^{n} \mathbb{E}[\mathbf{Q}(\mathbf{S} - q_i \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^{\top})\bar{\mathbf{Q}}]$$

$$= \frac{1}{N} \sum_{i=1}^{n} \mathbb{E}[\mathbf{Q}\mathbf{S} - \frac{1}{1+\delta_R} \mathbf{Q}_{-\boldsymbol{x}_i} \boldsymbol{x}_i \boldsymbol{x}_i^{\top}] \bar{\mathbf{Q}} + \frac{1}{N} \sum_{i=1}^{m} \mathbb{E}[\mathbf{Q}\mathbf{S} - \frac{q_i}{1+\delta_S} \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^{\top}] \bar{\mathbf{Q}}$$

$$= \pi \mathbb{E}[\mathbf{Q}\mathbf{S} - \frac{1}{1+\delta_R}\mathbf{Q}_{-\boldsymbol{x}_i}\boldsymbol{x}_i\boldsymbol{x}_i^{\top}]\bar{\mathbf{Q}} + (1-\pi)\mathbb{E}[\mathbf{Q}\mathbf{S} - \frac{q_i}{1+\delta_S}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_i}\tilde{\boldsymbol{x}}_i\tilde{\boldsymbol{x}}_i^{\top}]\bar{\mathbf{Q}}$$
$$= \pi \mathbb{E}[\mathbf{Q}_{-\boldsymbol{x}_i}(\mathbf{S} - \frac{\boldsymbol{x}_i\boldsymbol{x}_i^{\top}}{1+\delta_R})\bar{\mathbf{Q}}] + (1-\pi)\mathbb{E}[\mathbf{Q}_{-\tilde{\boldsymbol{x}}_i}(\mathbf{S} - \frac{q_i\tilde{\boldsymbol{x}}_i\tilde{\boldsymbol{x}}_i^{\top}}{1+\delta_S})\bar{\mathbf{Q}}] + \mathcal{O}(N^{-1})$$

Thus, it suffices to have:

$$\mathbf{S} = \frac{\pi(\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p)}{1 + \delta_R} + \frac{\alpha(1 - \pi)(\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \mathbf{C})}{1 + \delta_S}$$

to get the desired property.

**Lemma C.5** (Deterministic equivalent of QAQ). Let  $\mathbf{A} \in \mathbb{R}^{p \times p}$  be any deterministic symmetric semi-definite matrix. We have that:

$$\mathbf{QAQ} \leftrightarrow \bar{\mathbf{Q}} \mathbf{A}\bar{\mathbf{Q}} + \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}(\Sigma \bar{\mathbf{Q}} \mathbf{A}\bar{\mathbf{Q}}) \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}] + \frac{\alpha(1-\pi)}{N(1+\delta_S)^2} \operatorname{Tr}(\Sigma_\beta \bar{\mathbf{Q}} \mathbf{A}\bar{\mathbf{Q}}) \mathbb{E}[\mathbf{Q}\Sigma_\beta \mathbf{Q}]$$

Thus, we get that for  $\mathbf{A} = \Sigma$ , and for  $\mathbf{A} = \Sigma_{\beta}$ :

$$\mathbf{Q}\Sigma\mathbf{Q} \leftrightarrow \bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}} + \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}((\Sigma\bar{\mathbf{Q}})^2)\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}] + \frac{\alpha(1-\pi)}{N(1+\delta_S)^2} \operatorname{Tr}(\Sigma_\beta\bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}})\mathbb{E}[\mathbf{Q}\Sigma_\beta\mathbf{Q}]$$

$$\mathbf{Q}\Sigma_{\beta}\mathbf{Q} \leftrightarrow \bar{\mathbf{Q}}\Sigma_{\beta}\bar{\mathbf{Q}} + \frac{\pi}{N(1+\delta)^2}\operatorname{Tr}(\Sigma\bar{\mathbf{Q}}\Sigma_{\beta}\bar{\mathbf{Q}})\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}] + \frac{\alpha(1-\pi)}{N(1+\delta_S)^2}\operatorname{Tr}((\Sigma_{\beta}\bar{\mathbf{Q}})^2)\mathbb{E}[\mathbf{Q}\Sigma_{\beta}\mathbf{Q}]$$

And by denoting:

$$a_1 = \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}((\Sigma \bar{\mathbf{Q}})^2), \quad b_1 = \frac{\alpha(1-\pi)}{N(1+\delta_S)^2} \operatorname{Tr}(\Sigma_\beta \bar{\mathbf{Q}} \Sigma \bar{\mathbf{Q}}),$$

$$a_2 = \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}(\Sigma_\beta \bar{\mathbf{Q}} \Sigma \bar{\mathbf{Q}}), \quad b_2 = \frac{\alpha(1-\pi)}{N(1+\delta_S)^2} \operatorname{Tr}((\Sigma_\beta \bar{\mathbf{Q}})^2)$$

$$h = (1 - b_2)(1 - a_1) - a_2b_1$$

We get that:  $\mathbf{Q}\Sigma\mathbf{Q}\leftrightarrow\frac{1-b_2}{h}\bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}}+\frac{b_1}{h}\bar{\mathbf{Q}}\Sigma_{\beta}\bar{\mathbf{Q}},$  $\mathbf{Q}\Sigma_{\beta}\mathbf{Q} \leftrightarrow \frac{a_2}{h} \bar{\mathbf{Q}}\Sigma \bar{\mathbf{Q}} + \frac{1-a_1}{h} \bar{\mathbf{Q}}\Sigma_{\beta} \bar{\mathbf{Q}}.$ Proof. Recall that:  $\bar{\mathbf{Q}}(\gamma) = \left(\frac{\pi\Sigma}{1+\delta} + \frac{\alpha(1-\pi)\Sigma_{\beta}}{1+\delta_{S}} + \gamma \mathbf{I}_{p}\right)^{-1}$ Let us denote by :  $\mathbf{S} = \frac{\pi \Sigma}{1+\delta} + \frac{\alpha(1-\pi)\Sigma_{\beta}}{1+\delta_{S}}$ , so that:  $\bar{\mathbf{Q}} = (\mathbf{S} + \gamma \mathbf{I}_{p})^{-1}$ . We have that:  $\mathbb{E}[\mathbf{Q}\mathbf{A}\mathbf{Q}] = \mathbb{E}[\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}] + \mathbb{E}[(\mathbf{Q} - \bar{\mathbf{Q}})\mathbf{A}\mathbf{Q}]$  $= \bar{\mathbf{Q}}\mathbb{E}[\mathbf{A}\mathbf{Q}] + \mathbb{E}[(\mathbf{Q} - \bar{\mathbf{Q}})\mathbf{A}\mathbf{Q}]$  $= \bar{\mathbf{Q}} \left( \mathbb{E}[\mathbf{A}\bar{\mathbf{Q}}] + \mathbb{E}[\mathbf{A}(\mathbf{Q} - \bar{\mathbf{Q}})] \right) + \mathbb{E}[(\mathbf{Q} - \bar{\mathbf{Q}})\mathbf{A}\mathbf{Q}]$  $= \bar{\mathbf{Q}} \mathbf{A} \bar{\mathbf{Q}} + \mathbb{E}[(\mathbf{Q} - \bar{\mathbf{Q}}) \mathbf{A} \mathbf{Q}]$  $\mathbf{\bar{Q}} = ar{\mathbf{Q}} \mathbf{A} ar{\mathbf{Q}} + \mathbb{E}[\mathbf{Q}\left(\mathbf{S} - rac{1}{N} \mathbf{V} \mathbf{V}^{ op}
ight) \mathbf{A} \mathbf{Q}]$  $\mathbf{\bar{Q}} = ar{\mathbf{Q}} \mathbf{A} ar{\mathbf{Q}} + \mathbb{E}[\mathbf{Q} \mathbf{S} ar{\mathbf{Q}} \mathbf{A} \mathbf{Q}] - rac{1}{N} \sum_{i=1}^{N} \mathbb{E}[\mathbf{Q} m{v}_i m{v}_i^{ op} ar{\mathbf{Q}} \mathbf{A} \mathbf{Q}]$  $= \bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}} + \mathbb{E}[\mathbf{Q}\mathbf{S}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}] - \pi\mathbb{E}[\mathbf{Q}\boldsymbol{x}_{i}\boldsymbol{x}_{i}^{\top}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}] - (1-\pi)\mathbb{E}[\mathbf{Q}q_{i}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}]$ And we have that:  $\mathbb{E}[\mathbf{Q} oldsymbol{x}_i oldsymbol{x}_i^{ op} oldsymbol{ar{\mathbf{Q}}} \mathbf{A} \mathbf{Q}] = rac{1}{1+\delta} \mathbb{E}[\mathbf{Q}_{-x_i} oldsymbol{x}_i oldsymbol{x}_i^{ op} oldsymbol{ar{\mathbf{Q}}} \mathbf{A} \mathbf{Q}]$  $\mathbf{u} = rac{1}{1+\delta} \mathbb{E} \left[ \mathbf{Q}_{-x_i} oldsymbol{x}_i oldsymbol{x}_i^{ op} oldsymbol{ar{\mathbf{Q}}}_{-x_i} - rac{\mathbf{Q}_{-x_i} oldsymbol{x}_i oldsymbol{x}_i^{ op} oldsymbol{\mathbf{Q}}_{-x_i}}{N(1+\delta)} 
ight) 
ight]$  $= \frac{1}{1 \perp \delta} \mathbb{E}[\mathbf{Q}_{-x_i} \boldsymbol{x}_i \boldsymbol{x}_i^\top \bar{\mathbf{Q}} \mathbf{A} \mathbf{Q}_{-x_i}] - \frac{1}{N(1 + \delta)^2} \mathbb{E}[\mathbf{Q}_{-x_i} \boldsymbol{x}_i \boldsymbol{x}_i^\top \bar{\mathbf{Q}} \mathbf{A} \mathbf{Q}_{-x_i} \boldsymbol{x}_i \boldsymbol{x}_i^\top \mathbf{Q}_{-x_i}]$  $= \frac{1}{1 \perp \delta} \mathbb{E}[\mathbf{Q} \Sigma \bar{\mathbf{Q}} \mathbf{A} \mathbf{Q}] - \frac{1}{N(1 + \delta)^2} \operatorname{Tr}(\Sigma \bar{\mathbf{Q}} \mathbf{A} \bar{\mathbf{Q}}) \mathbb{E}[\mathbf{Q}_{-x_i} x_i x_i^{\top} \mathbf{Q}_{-x_i}]$  $=\frac{1}{1+\delta}\mathbb{E}[\mathbf{Q}\Sigma\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}]-\frac{1}{N(1+\delta)^2}\operatorname{Tr}(\Sigma\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}})\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]$ And:  $\mathbb{E}[q_i \mathbf{Q} \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^\top \bar{\mathbf{Q}} \mathbf{A} \mathbf{Q}] = \frac{1}{1 + \delta_{\alpha}} \mathbb{E}[q_i \mathbf{Q}_{-\tilde{x}_i} \tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^\top \bar{\mathbf{Q}} \mathbf{A} \mathbf{Q}]$  $=\frac{1}{1+\delta_{S}}\mathbb{E}\left[q_{i}\mathbf{Q}_{-\tilde{x}_{i}}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\bar{\mathbf{Q}}\mathbf{A}\left(\mathbf{Q}_{-\tilde{x}_{i}}-\frac{q_{i}\mathbf{Q}_{-\tilde{x}_{i}}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\mathbf{Q}_{-\tilde{x}_{i}}}{N(1+\delta_{S})}\right)\right]$  $=\frac{1}{1+\delta_{\mathrm{S}}}\mathbb{E}[q_{i}\mathbf{Q}_{-\tilde{x}_{i}}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}_{-\tilde{x}_{i}}]-\frac{1}{N(1+\delta_{\mathrm{S}})^{2}}\mathbb{E}[q_{i}\mathbf{Q}_{-\tilde{x}_{i}}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}_{-\tilde{x}_{i}}\tilde{\boldsymbol{x}}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\mathbf{Q}_{-\tilde{x}_{i}}]$  $= \frac{\alpha}{1+\delta_{\varsigma}} \mathbb{E}[\mathbf{Q}\Sigma_{\beta}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}] - \frac{\alpha}{N(1+\delta_{\varsigma})^2} \operatorname{Tr}(\Sigma_{\beta}\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}}) \mathbb{E}[\mathbf{Q}_{-\tilde{x}_i}\tilde{x}_i\tilde{x}_i^{\top}\mathbf{Q}_{-x_i}]$  $= \frac{\alpha}{1+\delta_{\rm S}} \mathbb{E}[\mathbf{Q}\Sigma_{\beta}\bar{\mathbf{Q}}\mathbf{A}\mathbf{Q}] - \frac{\alpha}{N(1+\delta_{\rm S})^2} \operatorname{Tr}(\Sigma_{\beta}\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}}) \mathbb{E}[\mathbf{Q}\Sigma_{\beta}\mathbf{Q}]$ Which concludes the proof by summing all these separate terms. 

**Corollary C.6** (Trace identities). *Using the above lemma C.5, we get that:* 

$$\frac{1}{N}\operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}]) = \frac{(1+\delta)^2}{\pi h} \left( a_1(1-b_2) + a_2b_1 \right), \quad \frac{1}{N}\operatorname{Tr}(\Sigma_\beta \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}]) = \frac{(1+\delta_S)^2}{\alpha(1-\pi)h} b_1$$

And in the case of isotropic covariance matrix:  $\mathbf{C} = \sigma^2 \mathbf{I}_p$ :

$$\frac{1}{N}\operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}]) = \frac{\eta}{h\theta^2}(1 - b_2 + \sigma^2 b_1), \quad \frac{1}{N}\operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}]) = \frac{\sigma^2}{N}\operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}])$$

#### C.3 RESOLVENT IDENTITIES

Let **Q** be the resolvent matrix defined in equation (6). Denote by  $\mathbf{Q}_{-\boldsymbol{v}_i}$  the resolvent matrix obtained from the dataset **V** by removing the *i*<sup>th</sup> sample  $\boldsymbol{v}_i$ , i.e.

$$\mathbf{Q}_{-\boldsymbol{v}_i} = \left(\mathbf{Q}^{-1} - \frac{1}{N}\boldsymbol{v}_i\boldsymbol{v}_i^{\top}\right)^{-1}$$

Then, using lemma C.3, we have that:

$$\mathbf{Q} = \mathbf{Q}_{-oldsymbol{v}_i} - rac{\mathbf{Q}_{-oldsymbol{v}_i} rac{1}{N} oldsymbol{v}_i^{ op} \mathbf{Q}_{-i}}{1 + rac{1}{N} oldsymbol{v}_i^{ op} \mathbf{Q}_{-oldsymbol{v}_i} + rac{1}{N} oldsymbol{v}_i^{ op} \mathbf{Q}_{-oldsymbol{v}_i} oldsymbol{v}_i},$$

and,

$$\mathbf{Q}\boldsymbol{x}_{i} = \frac{\mathbf{Q}_{-\boldsymbol{x}_{i}}\boldsymbol{x}_{i}}{1+\delta}, \quad \mathbf{Q}\tilde{\boldsymbol{x}}_{i} = \frac{\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i}}\tilde{\boldsymbol{x}}_{i}}{1+\delta_{S}}, \tag{9}$$

where:

$$\delta = \frac{1}{N} \operatorname{Tr}(\Sigma \bar{\mathbf{Q}}) = \frac{1}{N} \operatorname{Tr}(\bar{\mathbf{Q}}), \quad \delta_S = (\phi(1-\varepsilon) + \rho\varepsilon) \frac{1}{N} \operatorname{Tr}(\Sigma_\beta \bar{\mathbf{Q}}) = \frac{\alpha}{N} \operatorname{Tr}(\mathbf{C}\bar{\mathbf{Q}})$$
(10)

Let us recall the expression of  $\overline{\mathbf{Q}}$  defined in lemma C.4:

$$\bar{\mathbf{Q}} = \left(\frac{\pi(\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p)}{1 + \delta} + \frac{\alpha(1 - \pi)(\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \mathbf{C})}{1 + \delta_S} + \gamma \mathbf{I}_p\right)^{-1}$$
$$= \left(\mathbf{A} + \mathbf{U}\mathbf{U}^{\top}\right)^{-1}$$

where:

$$\mathbf{A} = \frac{\alpha(1-\pi)}{1+\delta_S}\mathbf{C} + \left(\gamma + \frac{\pi}{1+\delta}\right)\mathbf{I}_p, \quad \mathbf{U} = \left(\sqrt{\frac{\pi}{1+\delta}}\boldsymbol{\mu}, \sqrt{\frac{\alpha(1-\pi)}{1+\delta_S}}\boldsymbol{\mu}_\beta\right)$$
(11)

Since C is symmetric and real valued, then it is diagonalizable, and can be written as:

$$\mathbf{C} = \mathbf{P} \mathbf{D} \mathbf{P}^{\top}$$

where:  $\mathbf{P}^{-1} = \mathbf{P}^{\top}$  is the matrix containing the eigenvectors of **C** in its columns, and  $\mathbf{D} = Diag((d_i)_{i=1}^p)$  the diagonal matrix of the eigenvalues of **C**. Hence, **A** can be written as:

$$\mathbf{A} = \mathbf{P} \Delta \mathbf{P}^{\top}, \quad \Delta = Diag \left( \gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} d_i \right)_{i=1}^p$$
(12)

And using Woodbury's identity in lemma C.2, we get that:

$$ar{\mathbf{Q}} = \mathbf{A}^{-1} - \mathbf{A}^{-1} \mathbf{U} \left( \mathbf{I}_2 + \mathbf{U}^{ op} \mathbf{A}^{-1} \mathbf{U} \right)^{-1} \mathbf{U}^{ op} \mathbf{A}^{-1}$$

where:  $\mathbf{A}^{-1} = \mathbf{P}\Delta^{-1}\mathbf{P}^{\top}$  and  $\Delta^{-1} = Diag\left(\frac{1}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S}d_i}\right)_{i=1}^p$ .

Let  $\mathbf{M} = (\mathbf{I}_2 + \mathbf{U}^{\top} \mathbf{A}^{-1} \mathbf{U})^{-1}$ , and denote by  $M_{i,j}$  its coordinate in the *i*<sup>th</sup> row and *j*<sup>th</sup> column. We have that:

$$\bar{\mathbf{Q}} = \mathbf{A}^{-1} - \mathbf{A}^{-1} \mathbf{U} \mathbf{M} \mathbf{U}^{\top} \mathbf{A}^{-1}$$

$$= \mathbf{A}^{-1} - \mathbf{A}^{-1} \left( \zeta_1 \boldsymbol{\mu} \boldsymbol{\mu}^{\top} + \zeta_2 \boldsymbol{\mu}_\beta \boldsymbol{\mu}_\beta^{\top} + \zeta_3 (\boldsymbol{\mu} \boldsymbol{\mu}_\beta^{\top} + \boldsymbol{\mu}_\beta \boldsymbol{\mu}^{\top}) \right) \mathbf{A}^{-1}$$
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where: 

$$\zeta_1 = \frac{\pi M_{1,1}}{1+\delta}, \quad \zeta_2 = \frac{\alpha(1-\pi)M_{2,2}}{1+\delta_S}, \quad \zeta_3 = \sqrt{\frac{\alpha\pi(1-\pi)}{(1+\delta)(1+\delta_S)}}M_{1,2}$$

Thus,

$$\bar{\mathbf{Q}} = \mathbf{A}^{-1} - \mathbf{A}^{-1} \left( \zeta_1 \boldsymbol{\mu} \boldsymbol{\mu}^\top + \zeta_2 \boldsymbol{\mu}_\beta \boldsymbol{\mu}_\beta^\top + \zeta_3 (\boldsymbol{\mu} \boldsymbol{\mu}_\beta^\top + \boldsymbol{\mu}_\beta \boldsymbol{\mu}^\top) \right) \mathbf{A}^{-1}$$
(13)

We can further show that:

$$M_{1,1} = \frac{1}{\det(M^{-1})} \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_S} \boldsymbol{\mu}_{\beta}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} \right)$$
$$M_{1,2} = \frac{1}{\det(M^{-1})} \left( -\sqrt{\frac{\alpha\pi(1-\pi)}{(1+\delta)(1+\delta_S)}} \boldsymbol{\mu}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} \right)$$
$$M_{2,1} = \frac{1}{\det(M^{-1})} \left( -\sqrt{\frac{\alpha\pi(1-\pi)}{(1+\delta)(1+\delta_S)}} \boldsymbol{\mu}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} \right)$$

$$M_{2,1} = \frac{1}{\det(M^{-1})} \left( -\sqrt{\frac{1}{(1+\delta)(1+\delta_S)}} \boldsymbol{\mu} \cdot \mathbf{A} \cdot \boldsymbol{\mu}_{\beta} \right)$$
$$M_{2,2} = \frac{1}{(1+\delta)} \left( 1 + \frac{\pi}{1+\delta} \boldsymbol{\mu}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu} \right)$$

$$\det(M^{-1}) \left( 1 + \delta^{\mathsf{T}} \mathbf{\mu}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu} \right) \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_S} \boldsymbol{\mu}_{\beta}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} \right) - \frac{\alpha\pi(1-\pi)}{(1+\delta)(1+\delta_S)} (\boldsymbol{\mu}^{\mathsf{T}} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta})^2$$

**Lemma C.7** (Delta). The parameters  $\delta$  and  $\delta_S$  defined in equation 10, are given by the following identities:

$$\delta = \frac{1}{N} \sum_{i=1}^{p} \frac{1}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} d_i}, \quad \delta_S = \frac{\alpha}{N} \sum_{i=1}^{p} \frac{d_i}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} d_i}$$

where:  $(d_i)_{i=1}^p$  are the eigenvalues of the covariance matrix **C**.

> *Proof.* Let:  $\mathbf{M} = (\mathbf{I}_2 + \mathbf{U}^{\top} \mathbf{A}^{-1} \mathbf{U})^{-1}$ , and denote by  $M_{i,j}$  its coordinate in the *i*<sup>th</sup> row and *j*<sup>th</sup> column. We have that using the expression of  $\bar{\mathbf{Q}}$  in equation 13:

$$\bar{\mathbf{Q}} = \mathbf{A}^{-1} - \mathbf{A}^{-1} \left( \zeta_1 \boldsymbol{\mu} \boldsymbol{\mu}^\top + \zeta_2 \boldsymbol{\mu}_\beta \boldsymbol{\mu}_\beta^\top + \zeta_3 (\boldsymbol{\mu} \boldsymbol{\mu}_\beta^\top + \boldsymbol{\mu}_\beta \boldsymbol{\mu}^\top) \right) \mathbf{A}^{-1}$$

Then:

$$\delta = \frac{1}{N} \operatorname{Tr}(\bar{\mathbf{Q}})$$
  
=  $\frac{1}{N} \operatorname{Tr}(\mathbf{A}^{-1}) - \frac{1}{N} \operatorname{Tr}(\mathbf{A}^{-1} \left( \zeta_1 \boldsymbol{\mu} \boldsymbol{\mu}^\top + \zeta_2 \boldsymbol{\mu}_\beta \boldsymbol{\mu}_\beta^\top + \zeta_3 (\boldsymbol{\mu} \boldsymbol{\mu}_\beta^\top + \boldsymbol{\mu}_\beta \boldsymbol{\mu}^\top) \right) \mathbf{A}^{-1})$ 

We have that, when  $N \to \infty$ :

$$\frac{1}{N}\operatorname{Tr}(\mathbf{A}^{-1}\boldsymbol{\mu}\boldsymbol{\mu}^{\top}\mathbf{A}^{-1}) = \frac{1}{N}\boldsymbol{\mu}^{\top}(\mathbf{A}^{-1})^{2}\boldsymbol{\mu} = \mathcal{O}(N^{-1})$$

since  $\|\mu\| = \mathcal{O}(N^{-1})$  by assumption 3.1. The same applies for  $\mu_{\beta}$ . Thus:

$$\delta = \frac{1}{N} \operatorname{Tr}(\mathbf{A}^{-1}) - \frac{1}{N} \zeta_1 \boldsymbol{\mu}^{\top} (\mathbf{A}^{-1})^2 \boldsymbol{\mu} - \frac{1}{N} \zeta_2 \boldsymbol{\mu}_{\beta}^{\top} (\mathbf{A}^{-1})^2 \boldsymbol{\mu}_{\beta} - \frac{2}{N} \zeta_3 \boldsymbol{\mu}^{\top} (\mathbf{A}^{-1})^2 \boldsymbol{\mu}_{\beta}$$
$$= \frac{1}{N} \operatorname{Tr}(\mathbf{A}^{-1}) + \mathcal{O}(N^{-1})$$

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$$= \frac{1}{N} \operatorname{Tr}(\Delta^{-1}) + \mathcal{O}(N^{-1})$$

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$$= \frac{1}{N} \sum_{p=1}^{p} \frac{1}{1 + \pi}$$

$$= \frac{1}{N} \sum_{i=1}^{N} \frac{1}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} d_i} + \mathcal{O}(N^{-1})$$

Hence we have the desired result for  $\delta$  in the regime  $N \gg 1$  which we considered in our assumption 3.1. Similarly for  $\delta_S$ , we have that:

$$\begin{aligned} \frac{1}{\alpha} \delta_S &= \frac{1}{n} \operatorname{Tr}(\mathbf{C}\bar{\mathbf{Q}}) \\ &= \frac{1}{N} \operatorname{Tr}(\mathbf{C}\mathbf{A}^{-1}) - \frac{1}{N} \zeta_1 \boldsymbol{\mu}^\top \mathbf{A}^{-1} \mathbf{C} \mathbf{A}^{-1} \boldsymbol{\mu} - \frac{1}{N} \zeta_2 \boldsymbol{\mu}_{\beta}^\top \mathbf{A}^{-1} \mathbf{C} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} - \frac{2}{N} \zeta_3 \boldsymbol{\mu}^\top \mathbf{A}^{-1} \mathbf{C} \mathbf{A}^{-1} \boldsymbol{\mu}_{\beta} \\ &= \frac{1}{N} \operatorname{Tr}(\mathbf{C}\mathbf{A}^{-1}) + \mathcal{O}(N^{-1}) \\ &= \frac{1}{N} \operatorname{Tr}(\mathbf{D}\Delta^{-1}) + \mathcal{O}(N^{-1}) \\ &= \frac{1}{N} \sum_{i=1}^p \frac{d_i}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} d_i} + \mathcal{O}(N^{-1}) \end{aligned}$$

Which concludes our proof.

Now let us compute the trace identities that will be useful in the next sections. **Lemma C.8** (Trace identities). *We have the following trace identities:* 

$$\frac{1}{N}\operatorname{Tr}((\Sigma\bar{\mathbf{Q}})^2) = \frac{1}{N}\sum_{i=1}^p \frac{1}{\left(\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S}d_i\right)^2}, \quad \frac{1}{N}\operatorname{Tr}((\Sigma_\beta\bar{\mathbf{Q}})^2) = \frac{1}{N}\sum_{i=1}^p \left(\frac{d_i}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S}d_i}\right)^2,$$
$$\frac{1}{N}\operatorname{Tr}(\Sigma\bar{\mathbf{Q}}\Sigma_\beta\bar{\mathbf{Q}}) = \frac{1}{N}\sum_{i=1}^p \frac{d_i}{\left(\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S}d_i\right)^2}$$

*Proof.* We have that:

$$\frac{1}{N}\operatorname{Tr}((\Sigma\bar{\mathbf{Q}})^2) = \frac{1}{N}\operatorname{Tr}\left((\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p)\bar{\mathbf{Q}}(\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p)\bar{\mathbf{Q}}\right)$$
$$= \frac{1}{N}\operatorname{Tr}(\bar{\mathbf{Q}}^2) + \mathcal{O}(N^{-1})$$
$$= \frac{1}{N}\operatorname{Tr}((\boldsymbol{\Lambda}^{-1})^2) + \mathcal{O}(N^{-1})$$

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$$= \frac{1}{N} \operatorname{Tr}((\mathbf{A}^{-1})^2) + \mathcal{O}(N^{-1})$$

$$= \frac{1}{N} \operatorname{Tr}((\mathbf{P}\Delta^{-1}\mathbf{P}^{\top})^2) + \mathcal{O}(N^{-1})$$

$$= \frac{1}{N} \operatorname{Tr}((\Delta^{-1})^2) + \mathcal{O}(N^{-1})$$

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$$= \frac{1}{N} \sum_{i=1}^{p} \frac{1}{\left(\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_{S}} d_{i}\right)^{2}} + \mathcal{O}(N^{-1})$$
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Thus we demonstrated the first identity. For the second one, we have that:

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$$\frac{1}{N} \operatorname{Tr}((\Sigma_{\beta} \bar{\mathbf{Q}})^{2}) + \mathcal{O}(N^{-1})$$

$$= \frac{1}{N} \operatorname{Tr}((\mathbf{C} \mathbf{A}^{-1})^{2}) + \mathcal{O}(N^{-1})$$

$$= \frac{1}{N} \operatorname{Tr}((\mathbf{D} \Delta^{-1})^{2}) + \mathcal{O}(N^{-1})$$

$$= \frac{1}{N} \sum_{i=1}^{p} \left(\frac{d_{i}}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_{S}} d_{i}}\right)^{2} + \mathcal{O}(N^{-1})$$

971 And the same spirit of the proof applies to the last identity.

#### RANDOM MATRIX ANALYSIS OF THE GENERAL MODEL D

In the generalized model, we consider that the synthetic data follow the following distribution:

 $ilde{x}_i \sim \mathcal{N}(\mu_eta, \mathbf{C}), \quad \mu_eta = eta \mu + \mu^ot$ where  $\beta \in \mathbb{R}$  defines the alignment of the synthetic mean with the mean of real data, and  $\mu^{\perp}$  is a vector orthogonal to  $\mu$ .

(14)

Now we will analyze here the performance of the classifier given by equation (6), and prove a generalized theorem D.1 in the paper.

$$\boldsymbol{w}_q = \frac{1}{N} \mathbf{Q}(\gamma) \left( \mathbf{X} \boldsymbol{y} + \tilde{\mathbf{X}} \mathbf{D}(\boldsymbol{q}) \tilde{\boldsymbol{y}} \right), \quad \mathbf{Q}(\gamma) = \left( \frac{1}{N} \mathbf{V} \mathbf{V}^\top + \gamma \mathbf{I}_p \right)^{-1}$$

The performance of (6) are fully determined by the first two order moments:  $\mathbb{E}[{m w}_q^{ op} {m x}]$  and  $\mathbb{E}[(\boldsymbol{w}_q^{\top} \boldsymbol{x})^2].$ 

D.1 TEST EXPECTATION:

We have that:

$$oldsymbol{w}_q = rac{1}{N}\sum_{i=1}^n \mathbf{Q} y_i oldsymbol{x}_i + rac{1}{N}\sum_{i=1}^m \mathbf{Q} q_i ilde{y}_i ilde{oldsymbol{x}}_i$$

Let  $\boldsymbol{x} \sim \mathcal{N}((-1)^{a}\boldsymbol{\mu}, \mathbf{I}_{p})$  be a test sample independent of all the training samples  $(\boldsymbol{v}_{i})_{i=1}^{N}$ . Then:

$$\mathbb{E}[\boldsymbol{w}_q^{\top} \boldsymbol{x}] = \frac{1}{N} \sum_{i=1}^n \mathbb{E}[y_i \boldsymbol{x}_i^{\top} \mathbf{Q} \boldsymbol{x}] + \frac{1}{N} \sum_{i=1}^m \mathbb{E}[q_i \tilde{y}_i \tilde{\boldsymbol{x}}_i^{\top} \mathbf{Q} \boldsymbol{x}]$$

**First sum:** We have that, using the same lemma C.3:

$$rac{1}{N}\sum_{i=1}^n \mathbb{E}[y_ioldsymbol{x}_i^ op \mathbf{Q}oldsymbol{x}] = rac{1}{N}\sum_{i=1}^n rac{1}{1+\delta}\mathbb{E}[y_ioldsymbol{x}_i^ op \mathbf{Q}_{-oldsymbol{x}_i}oldsymbol{x}]$$

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$$= \frac{1}{N} \sum_{i=1}^{n} \frac{1}{1+\delta} \mathbb{E}[\boldsymbol{x}_{i}]^{\top} \mathbb{E}[\mathbf{Q}_{-\boldsymbol{x}_{i}}] \mathbb{E}[\boldsymbol{x}]$$

$$= \frac{1}{N} \sum_{i=1}^{n} \frac{(-1)^{a}}{1+\delta} \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}$$

$$=rac{(-1)^a\pi}{1+\delta}oldsymbol{\mu}^{ op}ar{\mathbf{Q}}oldsymbol{\mu}$$

Thus, 

$$\frac{1}{N}\sum_{i=1}^{n}\mathbb{E}[y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x}] = \frac{(-1)^{a}\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}$$
(15)

**Second sum:** Using the same lemma C.3: 

$$\frac{1}{N}\sum_{i=1}^{m}\mathbb{E}[q_{i}\tilde{y}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\mathbf{Q}\boldsymbol{x}] = \frac{1}{N}\sum_{i=1}^{m}\frac{1}{1+\delta_{S}}\mathbb{E}[q_{i}\tilde{y}_{i}\tilde{\boldsymbol{x}}_{i}^{\top}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i}}\boldsymbol{x}]$$

$$= \frac{1}{N(1+\delta_S)} \sum_{i=1}^{m} \mathbb{E}[q_i \tilde{y}_i] \mathbb{E}[\tilde{x}_i]^\top \mathbb{E}[\mathbf{Q}_{-\tilde{x}_i}] \mathbb{E}[\boldsymbol{x}]$$

$$= \frac{(-1)^a}{N(1+\delta_S)} \sum_{i=1}^m \lambda \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}$$

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$$= \frac{(-1)^a \lambda (1-\pi)}{1+\delta_S} \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}$$

1026 where (here  $y_i$  means the true label of  $\tilde{x}_i$ ): 

$$\mathbb{E}[q_i \tilde{y}_i] = y_i \mathbb{P}[q_i = 1 \mid \tilde{y}_i = y_i] - y_i \mathbb{P}[q_i = 1 \mid \tilde{y}_i \neq y_i]$$
$$= y_i (\phi(1 - \varepsilon) - \rho \varepsilon) = \lambda y_i$$

Therefore,

 $\mathbb{E}[\boldsymbol{w}_{q}^{\top}\boldsymbol{x}] = (-1)^{a} \left(\frac{\pi}{1+\delta}\boldsymbol{\mu}^{\top} + \frac{\lambda(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}_{\beta}^{\top}\right) \bar{\mathbf{Q}}\boldsymbol{\mu}$ (16)

### D.2 TEST VARIANCE:

To determine the variance of  $w_q^{\top} x$ , it only remains to compute its second order. We have that:

$$\mathbb{E}[(\boldsymbol{w}_{q}^{\top}\boldsymbol{x})^{2}] = \frac{1}{N^{2}}\mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x} + \sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right]$$
$$= \frac{1}{N^{2}}\mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right] + \frac{1}{N^{2}}\mathbb{E}\left[\left(\sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right] + \frac{2}{N^{2}}\mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x}\right)\left(\sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)\right]$$

1046 Let us compute each sum on its own, and then group the results at the end.

**First sum:** We have that:

$$\begin{split} \frac{1}{N^2} \mathbb{E}\left[\left(\sum_{i=1}^n y_i \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x}\right)^2\right] &= \frac{1}{N^2} \sum_{i=1}^n \sum_{k=1}^n \mathbb{E}[y_i y_j \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_k^\top \mathbf{Q} \boldsymbol{x}] \\ &= \frac{1}{N^2} \sum_{i \neq k}^n \mathbb{E}[y_i y_k \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_k^\top \mathbf{Q} \boldsymbol{x}] + \frac{1}{N^2} \sum_{i=1}^n \mathbb{E}[\boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x}] \end{split}$$

- For  $i \neq k$ , we have that:

And we have that:

$$egin{aligned} A_1 &= \mathbb{E}[y_i y_k oldsymbol{x}_i^\top \mathbf{Q}_{-oldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-oldsymbol{x}_{i,k}} oldsymbol{x}_k] \ &= oldsymbol{\mu}^\top \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] oldsymbol{\mu} \ &= oldsymbol{\mu}^\top \left(rac{1-b_2}{h} ar{\mathbf{Q}} \Sigma ar{\mathbf{Q}} + rac{b_1}{h} ar{\mathbf{Q}} \Sigma_eta ar{\mathbf{Q}} 
ight) oldsymbol{\mu} \end{aligned}$$

1075 And:

$$A_{2} = \frac{1}{N(1+\delta)} \mathbb{E}[y_{i}y_{k}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-\boldsymbol{x}_{i,k}}\boldsymbol{x}_{k}\boldsymbol{x}_{k}^{\top}\mathbf{Q}_{-\boldsymbol{x}_{i,k}}\boldsymbol{\Sigma}\mathbf{Q}_{-\boldsymbol{x}_{i,k}}\boldsymbol{x}_{k}]$$

$$= \frac{\operatorname{Tr}(\boldsymbol{\Sigma}\mathbb{E}[\mathbf{Q}\boldsymbol{\Sigma}\mathbf{Q}])}{N(1+\delta)}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}$$

Since, by concentration laws:  $\frac{1}{N} \boldsymbol{x}_{k}^{\top} \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \boldsymbol{x}_{k} = \frac{1}{N} \mathbb{E} [\boldsymbol{x}_{k}^{\top} \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \boldsymbol{x}_{k}]$  $= \frac{1}{N} \mathbb{E}[\text{Tr}(\boldsymbol{x}_k \boldsymbol{x}_k^\top \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-\boldsymbol{x}_{i,k}})]$  $= \frac{1}{N} \operatorname{Tr}(\mathbb{E}[\boldsymbol{x}_k \boldsymbol{x}_k^\top \mathbf{Q}_{-\boldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-\boldsymbol{x}_{i,k}}])$  $= \frac{1}{N} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q}_{-\boldsymbol{x}_{i,k}} \Sigma \mathbf{Q}_{-\boldsymbol{x}_{i,k}}])$  $=\frac{1}{N}\operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q}\Sigma \mathbf{Q}])$ 

And we can easily verify that: 

$$A_3 = A_2, \quad A_4 = \mathcal{O}(N^{-1})$$

Thus, 

$$\frac{1}{N^2} \sum_{i \neq k}^{n} \mathbb{E}[y_i y_k \boldsymbol{x}_i^{\top} \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_k^{\top} \mathbf{Q} \boldsymbol{x}] = \frac{n^2 - n}{N^2} \left( \boldsymbol{\mu}^{\top} \mathbb{E}[\mathbf{Q} \boldsymbol{\Sigma} \mathbf{Q}] \boldsymbol{\mu} - \frac{2 \operatorname{Tr}(\boldsymbol{\Sigma} \mathbb{E}[\mathbf{Q} \boldsymbol{\Sigma} \mathbf{Q}])}{N(1 + \delta)} \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} \right)$$
$$= \frac{\pi^2}{(1 + \delta)^2} \left( \boldsymbol{\mu}^{\top} \mathbb{E}[\mathbf{Q} \boldsymbol{\Sigma} \mathbf{Q}] \boldsymbol{\mu} - \frac{2 \operatorname{Tr}(\boldsymbol{\Sigma} \mathbb{E}[\mathbf{Q} \boldsymbol{\Sigma} \mathbf{Q}])}{N(1 + \delta)} \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} \right)$$

- And then, for  $i \in \{1, ..., n\}$ :  $\mathbb{E}[x^\top \mathbf{O} \mathbf{x}^{\top} \mathbf{O} \mathbf{x}^{\top}] = \mathbb{E}[x^\top \mathbf{O} \mathbf{\Sigma} \mathbf{O}]$ 

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$$\mathbb{E}[\boldsymbol{x}_{i}^{\top} \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_{i}^{\top} \mathbf{Q} \boldsymbol{x}] = \mathbb{E}[\boldsymbol{x}_{i}^{\top} \mathbf{Q} \Sigma \mathbf{Q} \boldsymbol{x}_{i}]$$
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$$\mathbb{E}[\boldsymbol{x}_{i}^{\top} \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_{i}^{\top} \mathbf{Q} \mathbf{Q} \boldsymbol{x}_{i}]$$

$$= \frac{1}{(1+\delta)^{2}} \operatorname{Tr}(\mathbb{E}[\boldsymbol{x}_{i} \boldsymbol{x}_{i}^{\top} \mathbf{Q} - \boldsymbol{x}_{i} \Sigma \mathbf{Q} - \boldsymbol{x}_{i}])$$

$$= \frac{1}{(1+\delta)^{2}} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$$

Thus: 

$$\frac{1}{N^2} \sum_{i=1}^n \mathbb{E}[\boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x} \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x}] = \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$$

Hence, the first sum gives us: 

$$\begin{array}{l} 1113\\ 1114\\ 1115\\ 1115\\ 1116\\ 1117 \end{array} \qquad \frac{1}{N^2} \mathbb{E}\left[\left(\sum_{i=1}^n y_i \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x}\right)^2\right] = \frac{\pi^2}{(1+\delta)^2} \left(\boldsymbol{\mu}^\top \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \boldsymbol{\mu} - \frac{2 \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])}{N(1+\delta)} \boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu}\right) + \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$$

$$\begin{array}{l} (17) \end{array}$$

$$\begin{array}{l} (17) \end{array}$$

Second sum: We have that:  $\left|\frac{1}{N^2}\mathbb{E}\left|\left(\sum_{i=1}^m q_i \tilde{y}_i \tilde{\boldsymbol{x}}_i^\top \mathbf{Q} \boldsymbol{x}\right)^2\right| = \frac{1}{N^2} \sum_{i,j=1}^m \mathbb{E}[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{\boldsymbol{x}}_i^\top \mathbf{Q} \boldsymbol{x} \tilde{\boldsymbol{x}}_j^\top \mathbf{Q} \boldsymbol{x}]\right|$  $\mathcal{L} = rac{1}{N^2} \sum_{i \neq j} \mathbb{E}[q_i q_j ilde{y}_i ilde{y}_j ilde{x}_i^{ op} \mathbf{Q} oldsymbol{x}_j^{ op} \mathbf{Q} oldsymbol{x}] + rac{1}{N^2} \sum_{i=1}^m \mathbb{E}[q_i ilde{oldsymbol{x}}_i^{ op} oldsymbol{x} oldsymbol{x}_i^{ op} \mathbf{Q} oldsymbol{x}]$ 

1125 - For 
$$i \neq j \in \{1, ..., m\}$$
, we have that:  
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$$\mathbb{E}[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{x}_i^\top \mathbf{Q} x \tilde{x}_j^\top \mathbf{Q} x] = \mathbb{E}[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{x}_i^\top \mathbf{Q} \Sigma \mathbf{Q} x_j]$$
1127 
$$= \frac{1}{(1+\delta_S)^2} \mathbb{E}[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{x}_i^\top \mathbf{Q}_{-\tilde{x}_i} \Sigma \mathbf{Q}_{-\tilde{x}_j} x_j]$$
1130 
$$= \frac{1}{(1+\delta_S)^2} \mathbb{E}\left[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{x}_i^\top \left(\mathbf{Q}_{-\tilde{x}_{i,j}} - \frac{\frac{1}{N}\mathbf{Q}_{-\tilde{x}_{i,j}}q_j \tilde{x}_j \tilde{x}_j^\top \mathbf{Q}_{-\tilde{x}_{i,j}}}{1+\delta_S}\right) \Sigma \left(\mathbf{Q}_{-\tilde{x}_{i,j}} - \frac{\frac{1}{N}\mathbf{Q}_{-\tilde{x}_{i,j}}q_i \tilde{x}_i \tilde{x}_i^\top \mathbf{Q}_{-\tilde{x}_{i,j}}}{1+\delta_S}\right) \tilde{x}_j\right]$$
1132 
$$= \frac{1}{(1+\delta_S)^2} (A_1 - A_2 - A_3 + A_4)$$

And, we have that:  $A_1 = \mathbb{E}[q_i q_j \tilde{y}_j \tilde{x}_j^\top \mathbf{Q}_{-\tilde{x}_i}, \Sigma \mathbf{Q}_{-\tilde{x}_i}, \tilde{x}_j]$  $= \lambda^2 \mathbb{E}[y_i \tilde{\boldsymbol{x}}_i^\top \mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}} \Sigma \mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}} y_j \tilde{\boldsymbol{x}}_j]$  $=\lambda^2\boldsymbol{\mu}_{\boldsymbol{\beta}}^{\top}\mathbb{E}[\mathbf{Q}\boldsymbol{\Sigma}\mathbf{Q}]\boldsymbol{\mu}_{\boldsymbol{\beta}}$ And:  $A_{2} = \frac{1}{N(1+\delta_{s})} \mathbb{E}[q_{i}q_{j}\tilde{y}_{i}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{i}^{\top}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}}\boldsymbol{\Sigma}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}}\tilde{\boldsymbol{x}}_{j}]$  $= \frac{1}{N(1+\delta_{c})} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) \mathbb{E}[q_{i}q_{j}\tilde{y}_{i}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{i}^{\top} \mathbf{Q}_{-\tilde{\boldsymbol{x}}_{i,j}}\tilde{\boldsymbol{x}}_{j}]$  $= \frac{\lambda^2}{N(1+\delta_{S})} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta}$ And, we can easily observe that:  $A_3 = A_2, \quad A_4 = \mathcal{O}(N^{-1})$ Thus:  $\frac{1}{N^2} \sum_{i \neq i} \mathbb{E}[q_i q_j \tilde{y}_i \tilde{y}_j \tilde{x}_i^\top \mathbf{Q} x \tilde{x}_j^\top \mathbf{Q} x] = \frac{\lambda^2 (1-\pi)^2}{(1+\delta_S)^2} \left( \boldsymbol{\mu}_{\beta}^\top \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \boldsymbol{\mu}_{\beta} - \frac{2}{N(1+\delta_S)} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) \boldsymbol{\mu}_{\beta}^\top \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} \right)$ - And for  $i \in \{1, ..., m\}$ :  $\mathbb{E}[q_i \tilde{\boldsymbol{x}}_i^\top \mathbf{Q} \boldsymbol{x} \tilde{\boldsymbol{x}}_i^\top \mathbf{Q} \boldsymbol{x}] = \frac{1}{(1+\delta_{\sigma})^2} \mathbb{E}[q_i \tilde{\boldsymbol{x}}_i^\top \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \Sigma \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \tilde{\boldsymbol{x}}_i]$  $= \frac{\alpha}{(1+\delta_S)^2} \mathbb{E}[\tilde{\boldsymbol{x}}_i^\top \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \Sigma \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \tilde{\boldsymbol{x}}_i]$  $= \frac{\alpha}{(1+\delta_S)^2} \operatorname{Tr}(\mathbb{E}[\tilde{\boldsymbol{x}}_i \tilde{\boldsymbol{x}}_i^\top] \mathbb{E}[\mathbf{Q}_{-\tilde{\boldsymbol{x}}_i} \Sigma \mathbf{Q}_{-\tilde{\boldsymbol{x}}_i}])$  $= \frac{\alpha}{(1+\delta_{\sigma})^2} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$ Hence, by grouping the terms, the second sum gives us:  $\frac{1}{N^2} \mathbb{E} \left[ \left( \sum_{i=1}^{m} q_i \tilde{y}_i \tilde{\boldsymbol{x}}_i^\top \mathbf{Q} \boldsymbol{x} \right)^\top \right]$ (18) $=\frac{\lambda^2(1-\pi)^2}{(1+\delta_{\alpha})^2}\left(\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta}-\frac{2}{N(1+\delta_{\alpha})}\operatorname{Tr}(\Sigma_{\beta}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}])\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right)+\frac{\alpha(1-\pi)}{N(1+\delta_{\alpha})^2}\operatorname{Tr}(\Sigma_{\beta}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}])$ (19)Third sum: Let us now compute the remaining term in the sum that is given by:  $\frac{2}{N^2}\sum_{i=1}^{n}\sum_{j=1}^{m}\mathbb{E}[y_i\boldsymbol{x}_i^{\top}\mathbf{Q}\boldsymbol{x}q_j\tilde{y}_j\tilde{\boldsymbol{x}}_j^{\top}\mathbf{Q}\boldsymbol{x}]$ Let  $i \in \{1, ..., n\}$  and  $j \in \{1, ..., m\}$ , we have that:  $\mathbb{E}[y_i q_j \tilde{y}_j \boldsymbol{x}_j^\top \mathbf{Q} \boldsymbol{x} \boldsymbol{x}^\top \mathbf{Q} \tilde{\boldsymbol{x}}_j] = \mathbb{E}[y_i q_j \tilde{y}_j \boldsymbol{x}_j^\top \mathbf{Q} \boldsymbol{\Sigma} \mathbf{Q} \tilde{\boldsymbol{x}}_j]$  $=\frac{1}{(1+\delta)(1+\delta_{S})}\mathbb{E}[y_{i}q_{j}\tilde{y}_{j}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-\boldsymbol{x}_{i}}\boldsymbol{\Sigma}\mathbf{Q}_{-\tilde{\boldsymbol{x}}_{j}}\tilde{\boldsymbol{x}}_{j}]$  $= \frac{1}{(1+\delta)(1+\delta_S)} \mathbb{E} \left[ y_i q_j \tilde{y}_j \boldsymbol{x}_i^\top \left( \mathbf{Q}_{-ij} - \frac{\mathbf{Q}_{-ij} q_j \tilde{\boldsymbol{x}}_j \tilde{\boldsymbol{x}}_j^\top \mathbf{Q}_{-ij}}{N(1+\delta_S)} \right) \Sigma \left( \mathbf{Q}_{-ij} - \frac{\mathbf{Q}_{-ij} \boldsymbol{x}_i \boldsymbol{x}_i^\top \mathbf{Q}_{-ij}}{N(1+\delta)} \right) \tilde{\boldsymbol{x}}_j \right]$  $= \frac{1}{(1+\delta)(1+\delta_{s})} \left( A_{1} - A_{2} - A_{3} + A_{4} \right)$ 

We have that:  $A_{1} = \mathbb{E}[y_{i}q_{j}\tilde{y}_{j}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\boldsymbol{\Sigma}\mathbf{Q}_{-ij}\tilde{\boldsymbol{x}}_{j}] = \lambda \mathbb{E}[y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\boldsymbol{\Sigma}\mathbf{Q}_{-ij}\tilde{y}_{j}\boldsymbol{x}_{j}]$   $= \lambda \boldsymbol{\mu}^{\top} \mathbb{E}[\mathbf{Q}\boldsymbol{\Sigma}\mathbf{Q}]\boldsymbol{\mu}_{\beta}$ And:

$$A_{2} = \frac{1}{N(1+\delta)} \mathbb{E}[y_{i}q_{j}\tilde{y}_{j}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\boldsymbol{\Sigma}\mathbf{Q}_{-ij}\boldsymbol{x}_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\tilde{\boldsymbol{x}}_{j}]$$
$$= \frac{\lambda}{N(1+\delta)} \mathbb{E}[y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\boldsymbol{\Sigma}\mathbf{Q}_{-ij}\boldsymbol{x}_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}y_{j}\tilde{\boldsymbol{x}}_{j}]$$
$$= \frac{\lambda}{N(1+\delta)} \operatorname{Tr}(\boldsymbol{\Sigma}\mathbb{E}[\mathbf{Q}\boldsymbol{\Sigma}\mathbf{Q}])\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}$$

And also:

$$A_{3} = \frac{1}{N(1+\delta_{S})} \mathbb{E}[y_{i}q_{j}\tilde{y}_{j}\boldsymbol{x}_{i}^{\top}\mathbf{Q}_{-ij}\tilde{\boldsymbol{x}}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}_{-ij}\boldsymbol{\Sigma}\mathbf{Q}_{-ij}\tilde{\boldsymbol{x}}_{j}]$$
$$= \frac{\lambda}{N(1+\delta_{S})} \operatorname{Tr}(\boldsymbol{\Sigma}_{\beta}\mathbb{E}[\mathbf{Q}\boldsymbol{\Sigma}\mathbf{Q}])\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}$$

Hence:

1218 Grouping all the sums: Denote by :  $T_1 = \frac{1}{N} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$ , then:  $T_2 = \frac{1}{N} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$ . Now let us group the terms in T in the three sums, and those that do not depend on T. We get that:

$$\begin{aligned} & \mathbb{E}[(\boldsymbol{w}^{\top}\boldsymbol{x})^{2}] = \frac{\pi^{2}}{(1+\delta)^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} + \frac{\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{2}}\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} + \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} \\ & + T_{1}\left(\frac{\pi}{(1+\delta)^{2}} - \frac{2\pi^{2}}{(1+\delta)^{3}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} - \frac{2\lambda\pi(1-\pi)}{(1+\delta)^{2}(1+\delta_{S})}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\ & \mathbb{1}225 \\ & + T_{2}\left(\frac{\alpha(1-\pi)}{(1+\delta_{S})^{2}} - \frac{2\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{3}}\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} - \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})^{2}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\ & \mathbb{1}227 \\ & \mathbb{1}228 \\ & = \frac{\pi^{2}}{(1+\delta)^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} + \frac{\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{2}}\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} + \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} \\ & \mathbb{1}229 \\ & = \frac{\pi^{2}}{(1+\delta)^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} + \frac{\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{2}}\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} + \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} \\ & + \frac{\pi T_{1}}{(1+\delta)^{2}}\left(1 - \frac{2\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} - \frac{2\lambda(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\ & + \frac{(1-\pi)T_{2}}{(1+\delta_{S})^{2}}\left(\alpha - \frac{2\lambda^{2}(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} - \frac{2\lambda\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \end{aligned}$$

This leads to the following theorem:

**Theorem D.1** (Gaussianity of the General model). Let  $w_q$  be the Mixed classifier as defined in equation 6 and suppose that Assumption 3.1 holds. The decision function  $w_q^{\top} x$ , on some test sample  $x \in C_a$  independent of **X**, satisfies:

 $\boldsymbol{w}_q^{\top} \boldsymbol{x} \xrightarrow{\mathcal{D}} \mathcal{N}\left((-1)^a m_q, \, \nu_q - m_q^2\right),$ 

1242	where:
1243	$\langle \pi \rangle$
1244	$m_q = \left(\frac{\pi}{1+s} \mu^{\top} + \frac{\lambda(1-\pi)}{1+s} \mu^{\top}_{\beta}\right) \bar{\mathbf{Q}} \mu,$
1245	$\left(1+0\right)$ $\left(1+0S\right)$
1246	$\mu = \frac{\pi^2}{2} \mu^\top \mathbb{E}[\Omega \Sigma \Omega] \mu + \frac{\lambda^2 (1-\pi)^2}{2} \mu^\top \mathbb{E}[\Omega \Sigma \Omega] \mu_0 + \frac{2\lambda \pi (1-\pi)}{2} \mu^\top \mathbb{E}[\Omega \Sigma \Omega] \mu_0$
1247	$\nu_q = (1+\delta)^2^{\mu} \mathbb{E}[\mathcal{Q} \mathcal{Q} \mathcal{Q}]^{\mu} + (1+\delta_S)^2 \mathbb{E}[\mathcal{Q} \mathcal{Q} \mathcal{Q}]^{\mu_\beta} + (1+\delta)(1+\delta_S)^{\mu} \mathbb{E}[\mathcal{Q} \mathcal{Q} \mathcal{Q}]^{\mu_\beta}$
1248	$\pi T_1 \left( 2\pi \tau_{\overline{\lambda}} 2\lambda(1-\pi) \tau_{\overline{\lambda}} \right)$
1249	$+\frac{1}{(1+\delta)^2}\left(1-\frac{1}{1+\delta}\mu^{\dagger}\mathbf{Q}\mu-\frac{1}{1+\delta_{S}}\mu^{\dagger}\mathbf{Q}\mu_{\beta}\right)$
1250	$(1 - \pi)T_{1} (-2)^{2}(1 - \pi) = -2)\pi$
1251	$+ \frac{(1-\pi)I_2}{(1+5)2} \left( \alpha - \frac{2\lambda}{1+5} \mu_{\beta}^{\top} \bar{\mathbf{Q}} \mu_{\beta} - \frac{2\lambda\pi}{1+5} \mu^{\top} \bar{\mathbf{Q}} \mu_{\beta} \right).$
1252	$(1+o_S)^2$ ( $1+o_S$ $r$ $1+o$ )
1253	where:
1254	1
1255	$T_1 = \frac{1}{N} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]),  T_2 = \frac{1}{N} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]),  \lambda = \phi(1 - \varepsilon) - \rho \varepsilon$
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#### Ε PARTICULAR CASE: ISOTROPIC COVARIANCE MATRIX

Here, we consider a simple covariance matrix of the form  $\mathbf{C} = \sigma^2 \mathbf{I}_p$  for some  $\sigma > 0$ . So 

$$\delta_S = \alpha \sigma^2 \delta \tag{22}$$

E.1 Resolvent identities in the case of  $\mathbf{C} = \sigma^2 \mathbf{I}_p$ 

We have that by lemma C.4: 

 $\bar{\mathbf{Q}} = \left(\frac{\pi}{1+\delta}(\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{I}_p) + \frac{\alpha(1-\pi)}{1+\alpha\sigma^2\delta}(\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \sigma^2\mathbf{I}_p) + \gamma\mathbf{I}_p\right)^{-1}$  $= \left(\frac{\pi}{1+\delta}\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \frac{\alpha(1-\pi)}{1+\alpha\sigma^{2}\delta}\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \theta\mathbf{I}_{p}\right)^{-1},$ 

where: 

$$\theta = \gamma + \frac{\pi}{1+\delta} + \frac{\alpha\sigma^2(1-\pi)}{1+\alpha\sigma^2\delta}$$
(23)

Define by:

$$\mathbf{R}_{1} = \left(\frac{\alpha(1-\pi)}{1+\alpha\sigma^{2}\delta}\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \theta\mathbf{I}_{p}\right)^{-1}, \quad \mathbf{R}_{2} = \left(\frac{\pi}{1+\delta}\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \theta\mathbf{I}_{p}\right)^{-1}, \quad (24)$$

such that:

$$\bar{\mathbf{Q}} = \left(\frac{\pi}{1+\delta}\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + \mathbf{R}_{1}^{-1}\right)^{-1} = \left(\frac{\alpha(1-\pi)}{1+\alpha\sigma^{2}\delta}\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top} + \mathbf{R}_{2}^{-1}\right)^{-1}$$

Thus, using lemma C.3:

$$\bar{\mathbf{Q}}\boldsymbol{\mu} = \frac{\mathbf{R}_{1}\boldsymbol{\mu}}{1 + \frac{\pi}{1+\delta}\boldsymbol{\mu}^{\top}\mathbf{R}_{1}\boldsymbol{\mu}}, \quad \bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} = \frac{\mathbf{R}_{2}\boldsymbol{\mu}_{\beta}}{1 + \frac{\alpha(1-\pi)}{1+\alpha\sigma^{2}\delta}\boldsymbol{\mu}_{\beta}^{\top}\mathbf{R}_{2}\boldsymbol{\mu}_{\beta}}$$
(25)

And: 

$$\bar{\mathbf{Q}} = \mathbf{R}_1 - \frac{\pi \mathbf{R}_1 \boldsymbol{\mu} \boldsymbol{\mu}^\top \mathbf{R}_1}{1 + \delta + \pi \boldsymbol{\mu}^\top \mathbf{R}_1 \boldsymbol{\mu}} = \mathbf{R}_2 - \frac{\alpha (1 - \pi) \mathbf{R}_2 \boldsymbol{\mu}_\beta \boldsymbol{\mu}_\beta^\top \mathbf{R}_2}{1 + \alpha \sigma^2 \delta + \alpha (1 - \pi) \boldsymbol{\mu}_\beta^\top \mathbf{R}_2 \boldsymbol{\mu}_\beta}$$
(26)

**Lemma E.1** (Delta). The parameter  $\delta$  as defined in equation 10, is given by the following identity:

$$\delta = \frac{\eta}{\theta} = \frac{\eta}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha\sigma^2(1-\pi)}{1+\alpha\sigma^2\delta}}$$

Which gives us a third order equation:

$$\alpha \sigma^2 \gamma \delta^3 + \left(\gamma + \alpha \sigma^2 (1 + \gamma - \eta)\right) \delta^2 + \left(\gamma + \pi - \eta + \alpha \sigma^2 (1 - \pi - \eta)\right) \delta - \eta = 0$$

Lemma E.2 (Resolvent identities). Using the first identity in Sherman-Morisson's lemma C.3, we have that the expressions of  $\mathbf{R}_1$  and  $\mathbf{R}_2$  are given by: 

$$\mathbf{R}_1 = \frac{1}{\theta} \mathbf{I}_p - \frac{\alpha(1-\pi)\boldsymbol{\mu}_{\beta}\boldsymbol{\mu}_{\beta}^{\top}}{\theta^2(1+\alpha\sigma^2\delta) + \theta\alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^2}, \quad \mathbf{R}_2 = \frac{1}{\theta} \mathbf{I}_p - \frac{\pi\boldsymbol{\mu}\boldsymbol{\mu}^{\top}}{\theta^2(1+\delta) + \theta\pi\|\boldsymbol{\mu}\|^2}$$

And we also have the following identities: 

$$\mathbf{R}_1 \boldsymbol{\mu}_eta = rac{\boldsymbol{\mu}_eta}{ heta + rac{lpha(1-\pi)}{1+\delta_S} \| \boldsymbol{\mu}_eta \|^2}, \quad \mathbf{R}_2 \boldsymbol{\mu} = rac{\boldsymbol{\mu}}{ heta + rac{\pi}{1+\delta} \| \boldsymbol{\mu} \|^2}$$

$$\boldsymbol{\mu}^{\mathsf{T}} \mathbf{R}_{1} \boldsymbol{\mu} = \frac{\|\boldsymbol{\mu}\|^{2}}{\theta} \left( 1 - \frac{\alpha(1-\pi)\beta^{2}\|\boldsymbol{\mu}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}} \right) = \frac{\|\boldsymbol{\mu}\|^{2}}{\theta} \frac{\theta(1+\delta_{S}) + \alpha(1-\pi)(1-\beta^{2})\|\boldsymbol{\mu}^{\perp}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}}$$

$$\mathbf{H}^{\mathsf{T}} \mathbf{R}_{1} \boldsymbol{\mu} = \frac{\|\boldsymbol{\mu}\|^{2}}{\theta} \left( 1 - \frac{\alpha(1-\pi)\beta^{2}\|\boldsymbol{\mu}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}} \right) = \frac{\|\boldsymbol{\mu}\|^{2}}{\theta} \frac{\theta(1+\delta_{S}) + \alpha(1-\pi)(1-\beta^{2})\|\boldsymbol{\mu}^{\perp}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}}$$

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$$\boldsymbol{\mu}^{\top} \mathbf{R}_2 \boldsymbol{\mu}_{\beta} = \frac{\beta(1+\delta) \|\boldsymbol{\mu}\|^2}{\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^2}$$

 $\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} = \frac{1}{\theta} \left( \|\boldsymbol{\mu}_{\beta}\|^{2} - \frac{\pi \beta^{2} \|\boldsymbol{\mu}\|^{4}}{\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^{2}} \right)$ 1352

$$\boldsymbol{\mu}^{\top} \mathbf{R}_{1}^{2} \boldsymbol{\mu} = \frac{\|\boldsymbol{\mu}\|^{2}}{\theta^{2}} \left( 1 - \frac{2\alpha(1-\pi)\beta^{2}\|\boldsymbol{\mu}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}} + \frac{\alpha^{2}(1-\pi)^{2}\beta^{2}\|\boldsymbol{\mu}\|^{2}\|\boldsymbol{\mu}_{\beta}\|^{2}}{(\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2})^{2}} \right)$$
$$= \frac{\|\boldsymbol{\mu}\|^{2}}{\theta^{2}} + \frac{\alpha(1-\pi)\beta^{2}\|\boldsymbol{\mu}\|^{4}}{\theta^{2}(\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2})} \left(\frac{\alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^{2}} - 2\right)$$

$$\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \mathbf{R}_{1} \boldsymbol{\mu} = \frac{\beta \|\boldsymbol{\mu}\|^{2}}{\theta^{2}} \left(1 - \frac{\alpha(1-\pi) \|\boldsymbol{\mu}_{\beta}\|^{2}}{\theta(1+\delta_{S}) + \alpha(1-\pi) \|\boldsymbol{\mu}_{\beta}\|^{2}} - \frac{\pi \|\boldsymbol{\mu}\|^{2}}{\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^{2}} + \frac{\alpha \pi (1-\pi) \beta^{2} \|\boldsymbol{\mu}\|^{4}}{(\alpha(1+\delta)) + \alpha(1-\alpha) \beta^{2} \|\boldsymbol{\mu}\|^{4}}\right)$$

+ 
$$\frac{1}{(\theta(1+\delta)+\pi\|\boldsymbol{\mu}\|^2)(\theta(1+\delta_S)+\alpha(1-\pi)\|\boldsymbol{\mu}_{\beta}\|^2)}$$

$$\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2}^{2} \boldsymbol{\mu}_{\beta} = \frac{\|\boldsymbol{\mu}_{\beta}\|^{2}}{\theta^{2}} + \frac{\pi\beta^{2} \|\boldsymbol{\mu}\|^{4}}{\theta^{2}(\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^{2})} \left(\frac{\pi \|\boldsymbol{\mu}\|^{2}}{\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^{2}} - 2\right)$$
$$= \frac{\|\boldsymbol{\mu}_{\beta}\|^{2}}{\theta^{2}} - \frac{\pi\beta^{2} \|\boldsymbol{\mu}\|^{4} \left(\pi \|\boldsymbol{\mu}\|^{2} + 2\theta(1+\delta)\right)}{\theta^{2}(\theta(1+\delta) + \pi \|\boldsymbol{\mu}\|^{2})^{2}}$$

1368 Lemma E.3 (Trace identities). Let  $i \in \{1, ..., n\}$ , and  $j \in \{1, ..., m\}$ , such that:  $\Sigma = \mathbb{E}[\boldsymbol{x}_i \boldsymbol{x}_i^\top] = \mu_{\mu} \mu_{\mu}^\top + \mathbf{I}_p$  and  $\Sigma_{\beta} = \mathbb{E}[\tilde{\boldsymbol{x}}_j \tilde{\boldsymbol{x}}_j^\top] = \mu_{\beta} \mu_{\beta}^\top + \sigma^2 \mathbf{I}_p$ . 1370 We can prove that:

$$\frac{1}{N}\operatorname{Tr}((\Sigma\bar{\mathbf{Q}})^2) = \frac{\eta}{\theta^2}, \quad \frac{1}{N}\operatorname{Tr}((\Sigma_\beta\bar{\mathbf{Q}})^2) = \frac{\eta\sigma^4}{\theta^2}, \quad \frac{1}{N}\operatorname{Tr}(\Sigma_\beta\bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}}) = \frac{\eta\sigma^2}{\theta^2}$$

The performance of  $w_q$  in (6) is fully determined by the first two order moments:  $\mathbb{E}[w_q^\top x]$  and  $\mathbb{E}[(w_q^\top x)^2]$ .

#### 1378 E.2 TEST EXPECTATION

We have that using the calculus in the past section:

$$\mathbb{E}[\boldsymbol{w}_{q}^{\top}\boldsymbol{x}] = (-1)^{a} \left(\frac{\pi}{1+\delta}\boldsymbol{\mu}^{\top} + \frac{\lambda(1-\pi)}{1+\alpha\sigma^{2}\delta}\boldsymbol{\mu}_{\beta}^{\top}\right) \bar{\mathbf{Q}}\boldsymbol{\mu}$$
(27)

And finally we use lemma E.2 and the following identities to obtain the result:

$$\boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} = \frac{\boldsymbol{\mu}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}}{1 + \frac{\pi}{1 + \delta} \boldsymbol{\mu}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}}, \quad \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} = \frac{\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}}{1 + \frac{\alpha(1 - \pi)}{1 + \delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta}}$$

#### E.3 TEST VARIANCE

To determine the variance of  $w_q^{\top} x$ , it only remains to compute its second order. We have that:

$$\mathbb{E}[(\boldsymbol{w}_{q}^{\top}\boldsymbol{x})^{2}] = \frac{1}{N^{2}} \mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x} + \sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right]$$
$$= \frac{1}{N^{2}} \mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right] + \frac{1}{N^{2}} \mathbb{E}\left[\left(\sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right] + \frac{2}{N^{2}} \mathbb{E}\left[\left(\sum_{i=1}^{n} y_{i}\boldsymbol{x}_{i}^{\top}\mathbf{Q}\boldsymbol{x}\right)\left(\sum_{j=1}^{m} q_{j}\tilde{y}_{j}\tilde{\boldsymbol{x}}_{j}^{\top}\mathbf{Q}\boldsymbol{x}\right)^{2}\right]$$

And using the same computations in the past section, we get:

**First sum:** The first sum gives us:

1401 First sum. The first sum gives us.  
1402 
$$\frac{1}{N^2} \mathbb{E}\left[\left(\sum_{i=1}^n y_i \boldsymbol{x}_i^\top \mathbf{Q} \boldsymbol{x}\right)^2\right] = \frac{\pi^2}{(1+\delta)^2} \left(\boldsymbol{\mu}^\top \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \boldsymbol{\mu} - \frac{2 \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])}{N(1+\delta)} \boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu}\right) + \frac{\pi}{N(1+\delta)^2} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$$

**Second sum:** the second sum gives us:

$$\begin{array}{ll} \mathbf{1406} \\ \mathbf{1407} & \frac{1}{N^2} \mathbb{E} \left[ \left( \sum_{i=1}^m q_i \tilde{y}_i \tilde{x}_i^\top \mathbf{Q} \mathbf{x} \right)^2 \right] \\ \mathbf{1408} & \\ \mathbf{1409} \\ \mathbf{1410} & = \frac{\lambda^2 (1-\pi)^2}{(1+\delta_S)^2} \left( \boldsymbol{\mu}_{\beta}^\top \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \boldsymbol{\mu}_{\beta} - \frac{2}{N(1+\delta_S)} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) \boldsymbol{\mu}_{\beta}^\top \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} \right) + \frac{\alpha (1-\pi)}{N(1+\delta_S)^2} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) \\ \end{array}$$

Third sum: The third sum is given by:

$$\frac{2}{N^2} \sum_{i=1}^{n} \sum_{j=1}^{m} \mathbb{E}[y_i \boldsymbol{x}_i^{\top} \mathbf{Q} \boldsymbol{x} q_j \tilde{y}_j \tilde{\boldsymbol{x}}_j^{\top} \mathbf{Q} \boldsymbol{x}] \\
= \frac{2\lambda \pi (1-\pi)}{(1+\delta)(1+\delta_S)} \left( \boldsymbol{\mu}^{\top} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \boldsymbol{\mu}_{\beta} - \frac{1}{N} \operatorname{Tr} \left( \left( \frac{\Sigma}{1+\delta} + \frac{\Sigma_{\beta}}{1+\delta_S} \right) \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}] \right) \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} \right)$$

**Grouping all the sums:** Denote by :  $T = \frac{1}{N} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$ , then:  $\frac{1}{N} \operatorname{Tr}(\Sigma_{\beta} \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]) = \sigma^2 T$ . Now let us group the terms in T in the three sums, and those that do not depend on T. We get that: 

$$\begin{aligned}
\mathbf{E}[(\boldsymbol{w}^{\top}\boldsymbol{x})^{2}] &= \frac{\pi^{2}}{(1+\delta)^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} + \frac{\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{2}}\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} + \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} \\
&+ T\left(\frac{\pi}{(1+\delta)^{2}} - \frac{2\pi^{2}}{(1+\delta)^{3}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} - \frac{2\lambda\pi(1-\pi)}{(1+\delta)^{2}(1+\delta_{S})}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\
&+ \sigma^{2}T\left(\frac{\alpha(1-\pi)}{(1+\delta_{S})^{2}} - \frac{2\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{3}}\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} - \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})^{2}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\
&= \frac{\pi^{2}}{(1+\delta)^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} + \frac{\lambda^{2}(1-\pi)^{2}}{(1+\delta_{S})^{2}}\boldsymbol{\mu}_{\beta}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} + \frac{2\lambda\pi(1-\pi)}{(1+\delta)(1+\delta_{S})^{2}}\boldsymbol{\mu}^{\top}\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} \\
&+ \frac{\pi^{2}}{(1+\delta)^{2}}\left(1 - \frac{2\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} - \frac{2\lambda(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\
&+ \frac{(1-\pi)\sigma^{2}T}{(1+\delta)^{2}}\left(\alpha - \frac{2\lambda^{2}(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} - \frac{2\lambda\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\
&+ 4\mathbf{M} \\
&+ \mathbf{M} \\
&+ \frac{(1-\pi)\sigma^{2}T}{(1+\delta_{S})^{2}}\left(\alpha - \frac{2\lambda^{2}(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}_{\beta}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta} - \frac{2\lambda\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}_{\beta}\right) \\
&+ \mathbf{M} \\
&+ \mathbf{M}$$

And we can compute this since we have that:

$$\begin{split} & \mu^{\top} \mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu} = \frac{1}{h} \left( (1-b_2) \left( (\boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu})^2 + \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu} \right) + b_1 \left( (\boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta})^2 + \sigma^2 \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu} \right) \right), \\ & \mathbf{\mu}_{\beta}^{\top} \mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} = \frac{1}{h} \left( (1-b_2) \left[ (\boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu})^2 + \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] + b_1 \left[ (\boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta})^2 + \sigma^2 \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] \right) \\ & \mathbf{\mu}^{\top} \mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} = \frac{1}{h} \left( (1-b_2) \left[ \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} \cdot \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} + \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] + b_1 \left[ \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} \cdot \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} + \sigma^2 \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] \right) \\ & \mathbf{\mu}^{\top} \mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]\boldsymbol{\mu}_{\beta} = \frac{1}{h} \left( (1-b_2) \left[ \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu} \cdot \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} + \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] + b_1 \left[ \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} \cdot \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}} \boldsymbol{\mu}_{\beta} + \sigma^2 \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} \right] \right) \\ & \mathbf{\mu}^{\top} \mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}] \boldsymbol{\mu}_{\beta} = \frac{\mu_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta}}{1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta}}, \quad \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu} = \frac{\boldsymbol{\mu}^{\top} \mathbf{R}_{1}^2 \boldsymbol{\mu}}{\left( 1 + \frac{\pi}{1+\delta} \boldsymbol{\mu}^{\top} \mathbf{R}_{1} \boldsymbol{\mu} \right)^2}, \quad \boldsymbol{\mu}_{\beta}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} = \frac{\mu_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta}}{\left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} \right)^2}, \\ & \boldsymbol{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} = \frac{\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \mathbf{R}_{1} \boldsymbol{\mu}}{\left( 1 + \frac{\pi}{1+\delta} \boldsymbol{\mu}^{\top} \mathbf{R}_{1} \boldsymbol{\mu} \right) \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} \right)} \\ & \mathbf{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} = \frac{\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \mathbf{R}_{1} \boldsymbol{\mu}}{\left( 1 + \frac{\pi}{1+\delta} \boldsymbol{\mu}^{\top} \mathbf{R}_{1} \boldsymbol{\mu} \right) \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} \right)} \\ & \mathbf{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} = \frac{\boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}_{\beta} \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} \right) \\ \\ & \mathbf{\mu}^{\top} \bar{\mathbf{Q}}^2 \boldsymbol{\mu}_{\beta} = \frac{\mathbf{\mu}_{\beta}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}_{\beta} \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{2} \boldsymbol{\mu}_{\beta} \right) \\ \\ & \mathbf{\mu}^{\top} \bar{\mathbf{Q}}^2 \mathbf{\mu}_{\beta} = \frac{\mathbf{\mu}_{\beta}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}_{\beta} \left( 1 + \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{\mu}_{\beta}^{\top} \mathbf{R}_{1} \boldsymbol{\mu}_{\beta} \right) \\ \\ & \mathbf{\mu}^{\top} \bar{\mathbf{Q}}^2 \mathbf{\mu}_{\beta} = \frac{\mathbf{\mu$$

**Theorem E.4** (Gaussianity of the 6 model for  $\mathbf{C} = \sigma^2 \mathbf{I}_p$ ). Let  $w_q$  be the Mixed classifier as defined in equation 6 and suppose that Assumption 3.1 holds. The decision function  $w_q^{\top} x$ , on some test sample  $x \in C_a$  independent of **X**, satisfies: 

$$\boldsymbol{w}_q^{\top} \boldsymbol{x} \xrightarrow{\mathcal{D}} \mathcal{N} \left( (-1)^a m_q, \, \nu_q - m_q^2 \right),$$

1458 1459	where:
1460	$m_{q} = \left(\frac{\pi}{1+\varepsilon}\boldsymbol{\mu}^{\top} + \frac{\lambda(1-\pi)}{1+\varepsilon}\boldsymbol{\mu}_{\beta}^{\top}\right)\bar{\mathbf{Q}}\boldsymbol{\mu},$
1461	(1+0) $(1+0S)$
1462	$u = \frac{\pi^2}{2\lambda\pi(1-\pi)} u^{\top} \mathbb{E}[\Omega \Sigma \Omega] u + \frac{\lambda^2(1-\pi)^2}{2} u^{\top} \mathbb{E}[\Omega \Sigma \Omega] u_0 + \frac{2\lambda\pi(1-\pi)}{2\lambda\pi(1-\pi)} u^{\top} \mathbb{E}[\Omega \Sigma \Omega] u_0$
1463	$\nu_q = \frac{1}{(1+\delta)^2} \mu_{\text{E}} [\mathbf{Q} \angle \mathbf{Q}] \mu + \frac{1}{(1+\delta_S)^2} \mu_{\beta} \mathbb{E} [\mathbf{Q} \angle \mathbf{Q}] \mu_{\beta} + \frac{1}{(1+\delta)(1+\delta_S)} \mu_{\text{E}} [\mathbf{Q} \angle \mathbf{Q}] \mu_{\beta}$
1464	$\pi T$ ( $2\pi$ $\pm$ $2\lambda(1-\pi)$ $\pm$ )
1465	$+ \frac{1}{(1+\delta)^2} \left( 1 - \frac{1}{1+\delta} \mu^{+} \mathbf{Q} \mu - \frac{1}{1+\delta_{G}} \mu^{+} \mathbf{Q} \mu_{\beta} \right)$
1466	$(1)^{2T} (-2)^{2} (1)^{2T} (-2)^{2} (1)^{2T} (-2)^{2} (1)^{2T} (-2)^{2} (1)^{2} $
1467	$+ \frac{(1-\pi)\sigma^2 I}{(1-\pi)^2} \left( \alpha - \frac{2\lambda^2(1-\pi)}{2} \mu_{\beta}^{\top} \bar{\mathbf{Q}} \mu_{\beta} - \frac{2\lambda\pi}{1-2} \mu^{\top} \bar{\mathbf{Q}} \mu_{\beta} \right).$
1468	$(1+\delta_S)^2$ $(1+\delta_S)^p$ $(1+\delta)^p$ $(1+\delta)^p$ $(1+\delta)^p$
1469	With:
1470	$\gamma$ (4) $\gamma$ $\gamma$ $\gamma$
1471	$\lambda = \phi(1 - \varepsilon) - \rho \varepsilon,  \delta_S = \alpha \sigma^2 \delta$
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# <sup>1512</sup> F RANDOM MATRIX ANALYSIS OF DISTRIBUTION SHIFT

We will now quantify the performance of the classifier obtained through mixing some real data and synthetic data sampled according to the schema described in 2. Hence, the matrix  $\bar{\mathbf{Q}}$ , defined in lemma C.4, is no longer deterministic as we take the covariance matrix  $\hat{\mathbf{C}} = \frac{1}{\hat{n}} \sum_{i=1}^{\hat{n}} (\mathbf{x}_i - y_i \hat{\boldsymbol{\mu}})^{\mathsf{T}}$ . For simplicity, and without loss of generality, we consider  $\hat{n}$  Gaussian vectors  $(\mathbf{z}_i)_{i=1}^{\hat{n}} \sim \mathcal{N}(0, \mathbf{I}_p)$  that are independent of  $(\mathbf{x}_i)_{i=1}^{\hat{n}}$ , and write:

$$\hat{\boldsymbol{\mu}} = \boldsymbol{\mu}_{\boldsymbol{\beta}} = \boldsymbol{\mu} + rac{1}{\hat{n}}\sum_{i=1}^{\hat{n}} \boldsymbol{z}_i, \quad \hat{\mathbf{C}} = rac{1}{\hat{n}}\sum_{i=1}^{\hat{n}} \boldsymbol{z}_i \boldsymbol{z}_i^{\top}$$

Note that we can ignore the error of estimation of  $\hat{\mu}$  because we have that:

$$\mathbb{E}\left[\frac{1}{\hat{n}}\sum_{i=1}^{\hat{n}}\boldsymbol{z}_{i}\right] = 0, \quad \mathbb{E}\left[\left(\frac{1}{\hat{n}}\sum_{i=1}^{\hat{n}}\boldsymbol{z}_{i}\right)\left(\frac{1}{\hat{n}}\sum_{j=1}^{\hat{n}}\boldsymbol{z}_{j}\right)^{\top}\right] = \frac{1}{\hat{n}}\mathbf{I}_{p}$$

Hence, when we have a sufficiently large  $\hat{n}$ , we will assume that:  $\hat{\mu} = \mu$  (the estimation error is on  $\mathcal{O}(\hat{n}^{-1})$ ).

# 1532 F.1 DETERMINISTIC EQUIVALENTS:

<sup>1534</sup> The resolvent matrix to be considered in this setting is the one defined in lemma C.4 but with  $\hat{C}$ :

$$\bar{\mathbf{Q}}(\gamma) = \left( \left( \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} \right) \boldsymbol{\mu} \boldsymbol{\mu}^\top + \frac{\alpha(1-\pi)}{1+\delta_S} \hat{\mathbf{C}} + \left( \gamma + \frac{\pi}{1+\delta} \right) \mathbf{I}_p \right)^{-1} \\ = \left( \left( \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} \right) \boldsymbol{\mu} \boldsymbol{\mu}^\top + \frac{\alpha(1-\pi)}{(1+\delta_S)\hat{n}} \sum_{i=1}^{\hat{n}} \boldsymbol{z}_i \boldsymbol{z}_i^\top + \left( \gamma + \frac{\pi}{1+\delta} \right) \mathbf{I}_p \right)^{-1}$$

1542 where:

$$\delta = \frac{1}{N} \operatorname{Tr}(\bar{\mathbf{Q}}), \quad \delta_S = \frac{\alpha}{N} \operatorname{Tr}(\hat{\mathbf{C}}\bar{\mathbf{Q}})$$

Let us denote by  $\mathbf{Q}_{-i}$  the resolvent matrix gotten by removing its dependence on the vector  $z_i$ . In other words:

$$\bar{\mathbf{Q}}_{-i} = \left(\bar{\mathbf{Q}} - \frac{\alpha(1-\pi)}{\hat{n}(1+\delta_S)} \boldsymbol{z}_i \boldsymbol{z}_i^{\mathsf{T}}\right)^{-1}, \quad \bar{\mathbf{Q}} = \left(\bar{\mathbf{Q}}_{-i} + \frac{\alpha(1-\pi)}{\hat{n}(1+\delta_S)} \boldsymbol{z}_i \boldsymbol{z}_i^{\mathsf{T}}\right)^{-1}$$

1551 By Sherman-Morisson's lemma C.3, we have that:

$$\bar{\mathbf{Q}} = \bar{\mathbf{Q}}_{-i} - \frac{\frac{\alpha(1-\pi)}{\hat{n}(1+\delta_S)}\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_i\boldsymbol{z}_i^{\top}\bar{\mathbf{Q}}_{-i}}{1 + \frac{\alpha(1-\pi)}{\hat{n}(1+\delta_S)}\boldsymbol{z}_i^{\top}\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_i}$$

1556 And:

$$ar{\mathbf{Q}} ar{\mathbf{Q}} ar{\mathbf{z}}_i = rac{\mathbf{Q}_{-i} oldsymbol{z}_i}{1 + rac{lpha(1-\pi)}{\hat{n}(1+\delta_S)} oldsymbol{z}_i^ op oldsymbol{ar{\mathbf{Q}}}_i^ op oldsymbol{\overline{\mathbf{Q}}}_i} = rac{\mathbf{Q}_{-i} oldsymbol{z}_i}{1 + ar{\delta}}$$

1560 where:

  $\bar{\delta} = \frac{\alpha(1-\pi)}{1+\delta_S} \frac{1}{\hat{n}} \operatorname{Tr}(\bar{\mathbf{Q}})$ (28)

Since the covariance estimate in equation 2 is stochastic, the matrix  $\bar{\mathbf{Q}}$  is no longer deterministic when replacing C with  $\hat{\mathbf{C}}$ . Hence, we will give a further deterministic equivalent to  $\bar{\mathbf{Q}}$  in the following lemma.

**Lemma F.1** (Second Deterministic equivalent). A deterministic equivalent of  $\overline{\mathbf{Q}}$  is given by: 1567  $\bar{\mathbf{Q}} = \left( \left( \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S} \right) \boldsymbol{\mu} \boldsymbol{\mu}^\top + \left( \gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})} \right) \mathbf{I}_p \right)^{-1}$ 1568 1569 where  $\overline{\delta}$  can be found as a fixed point using the following identity: 1570 1571  $\bar{\delta} = \frac{\alpha(1-\pi)}{(1+\delta_S)} \frac{1}{\hat{n}} \operatorname{Tr}(\bar{\mathbf{Q}}) = \frac{\alpha(1-\pi)}{(1+\delta_S)} \frac{\frac{p}{\hat{n}}}{\gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})}}, \quad \delta = \frac{1}{N} \operatorname{Tr}(\bar{\mathbf{Q}}) = \frac{\hat{n}}{N} \frac{(1+\delta_S)}{\alpha(1-\pi)} \bar{\delta}$ 1572  $\delta_S = \frac{\alpha}{N} \operatorname{Tr}(\mathbb{E}[\hat{\mathbf{C}}\bar{\mathbf{Q}}]) = \frac{\alpha \sigma}{1 + \bar{\delta}}$ 1574 1575 1576 Now we will prove the deterministic equivalent given by lemma F.1. 1577 1578 **PROOF OF LEMMA F.1:** 1579 Let us denote  $\bar{\mathbf{Q}} = \left(\frac{\alpha(1-\pi)}{1+\delta_s}\frac{1}{\hat{n}}\sum_{i=1}^{\hat{n}} \boldsymbol{z}_i \boldsymbol{z}_i^{\top} + \mathbf{A}\right)^{-1}$ . Let also  $\bar{\bar{\mathbf{Q}}}$  be the deterministic equivalent of 1580 1581  $\bar{\mathbf{Q}}$ . It can be written as:  $\bar{\bar{\mathbf{Q}}} = (\mathbf{S} + \mathbf{A})^{-1}$ . We want to find some S such that for all  $a, b \in \mathbb{R}^p$ : 1582  $a^{ op}\mathbb{E}[ar{\mathrm{Q}}]b o a^{ op}ar{\mathrm{Q}}b$ 1583 We have that: 1585  $\mathbb{E}[\bar{\mathbf{Q}}] - \bar{\bar{\mathbf{Q}}} = \mathbb{E} \left| \bar{\mathbf{Q}}(\mathbf{S} - \frac{\alpha(1-\pi)}{1+\delta_S} \frac{1}{\hat{n}} \sum_{i=1}^n \boldsymbol{z}_i \boldsymbol{z}_i^\top) \bar{\bar{\mathbf{Q}}} \right|$ 1586 1587  $= \frac{1}{\hat{n}} \sum_{i=1}^{n} \mathbb{E}[\bar{\mathbf{Q}}(\mathbf{S} - \frac{\alpha(1-\pi)}{1+\delta_{S}} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}) \bar{\bar{\mathbf{Q}}}]$ 1591  $\mathbf{r} = rac{1}{\hat{n}} \sum_{i=1}^{n} \mathbb{E} \left[ \bar{\mathbf{Q}} \mathbf{S} - rac{lpha(1-\pi)}{1+\delta_{S}} rac{1}{1+\delta} \bar{\mathbf{Q}}_{-i} oldsymbol{z}_{i} oldsymbol{z}_{i}^{ op} 
ight] ar{\mathbf{Q}}_{-i}$ 1592 1593 1594  $= \frac{1}{\hat{n}} \sum_{i=1}^{n} \mathbb{E}\left[\bar{\mathbf{Q}}_{-i} \left(\mathbf{S} - \frac{\alpha(1-\pi)}{1+\delta_{S}} \frac{1}{1+\bar{\delta}} \boldsymbol{z}_{i} \boldsymbol{z}_{i}^{\top}\right)\right] \bar{\mathbf{Q}} + \mathcal{O}(\hat{n}^{-1})$ 1595 1596 Hence, it suffices to have  $\mathbf{S} = \mathbb{E}[\frac{\alpha(1-\pi)}{1+\delta_S}\frac{1}{1+\delta}\boldsymbol{z}_i\boldsymbol{z}_i^{\top}] = \frac{\alpha(1-\pi)}{1+\delta_S}\frac{1}{1+\delta}\mathbf{I}_p$ , and thus: 1597 1598 1599 DETERMINISTIC EQUIVALENT OF  $\overline{\mathbf{Q}}\mathbf{A}\overline{\mathbf{Q}}$ : F.2 1600 Let  $\mathbf{A} \in \mathbb{R}^{p \times p}$  be some deterministic matrix. We have that:  $\mathbb{E}[\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}}] = \bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}} + \mathbb{E}[(\bar{\mathbf{Q}} - \bar{\mathbf{Q}})\mathbf{A}\bar{\mathbf{Q}}]$  $= \bar{\bar{\mathbf{O}}} \mathbf{A} \bar{\bar{\mathbf{O}}} + \mathbb{E}[\bar{\mathbf{O}}(\bar{\bar{\mathbf{O}}}^{-1} - \bar{\mathbf{O}}^{-1})\bar{\bar{\mathbf{O}}} \mathbf{A} \bar{\mathbf{O}}]$ 1604  $= \bar{\bar{\mathbf{Q}}} \mathbf{A} \bar{\bar{\mathbf{Q}}} + \frac{\alpha(1-\pi)}{(1+\delta_S)} \mathbb{E}[\bar{\mathbf{Q}} \left(\frac{1}{1+\bar{\delta}} - \frac{1}{\hat{n}} \sum_{i=1}^{n} \boldsymbol{z}_i \boldsymbol{z}_i^{\top}\right) \bar{\bar{\mathbf{Q}}} \mathbf{A} \bar{\mathbf{Q}}]$ 1608  $= ar{ar{\mathbf{Q}}} = ar{ar{\mathbf{Q}}} \mathbf{A} ar{ar{\mathbf{Q}}} + rac{lpha(1-\pi)}{(1+\delta_{\mathrm{S}})} \left( rac{1}{1+ar{\delta}} \mathbb{E}[ar{\mathbf{Q}} ar{ar{\mathbf{Q}}} \mathbf{A} ar{\mathbf{Q}}] - rac{1}{\hat{n}} \sum_{i}^{\hat{n}} \mathbb{E}[ar{\mathbf{Q}} oldsymbol{z}_{i} oldsymbol{z}_{i}^{ op} ar{ar{\mathbf{Q}}} \mathbf{A} ar{\mathbf{Q}}] 
ight)$ 1609 1610 And we have that for  $i \in \{1, ..., \hat{n}\}$ : 1611  $\mathbb{E}[\bar{\mathbf{Q}}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\mathbf{Q}}] = \frac{1}{1+\bar{\lambda}}\mathbb{E}[\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\mathbf{Q}}]$ 1612 1613  $=\frac{1}{1+\bar{\delta}}\mathbb{E}\left[\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\bar{\mathbf{Q}}}\mathbf{A}\left(\bar{\mathbf{Q}}_{-i}-\frac{\alpha(1-\pi)}{\hat{n}(1+\delta_{S})(1+\bar{\delta})}\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\mathbf{Q}}_{-i}\right)\right]$ 1614 1615 1616  $=\frac{1}{1+\bar{\delta}}\mathbb{E}[\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\mathbf{Q}}_{-i}]-\frac{\alpha(1-\pi)}{\hat{n}(1+\delta_{S})(1+\bar{\delta})^{2}}\mathbb{E}[\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\mathbf{Q}}_{-i}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\bar{\mathbf{Q}}_{-i}]$ 1617 1618  $=\frac{1}{1+\bar{\delta}}\mathbb{E}[\bar{\mathbf{Q}}\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\mathbf{Q}}]-\frac{\alpha(1-\pi)}{\hat{n}(1+\delta_{S})(1+\bar{\delta})^{2}}\operatorname{Tr}(\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\bar{\mathbf{Q}}})\mathbb{E}[\bar{\mathbf{Q}}^{2}]$ 1619

Hence by replacing this term in he previous sum, we get the following result. 

**Lemma F.2** (Deterministic equivalent of  $\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}}$ ). Let  $\mathbf{A} \in \mathbb{R}^{p \times p}$  be any deterministic symmetric semi-definite matrix. We have that: 

$$\bar{\mathbf{Q}}\mathbf{A}\bar{\mathbf{Q}} \leftrightarrow \bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\bar{\mathbf{Q}}} + \left(\frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})}\right)^2 \frac{1}{\hat{n}}\operatorname{Tr}(\bar{\bar{\mathbf{Q}}}\mathbf{A}\bar{\bar{\mathbf{Q}}})\mathbb{E}[\bar{\mathbf{Q}}^2]$$

In particular, we have that:

 $ar{\mathbf{Q}}^2 \leftrightarrow rac{1}{ar{h}} ar{\mathbf{Q}}^2, \quad ar{\mathbf{Q}} oldsymbol{\mu} oldsymbol{\mu}^ op ar{\mathbf{Q}} \leftrightarrow ar{\mathbf{Q}} oldsymbol{\mu} oldsymbol{\mu}^ op ar{\mathbf{Q}}$ 

where:

$$\bar{h} = 1 - \left(\frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})}\right)^2 \frac{1}{\hat{n}} \operatorname{Tr}(\bar{\mathbf{Q}}^2)$$

#### F.3 USEFUL RESULTS:

Here we will list all the results with  $\bar{\mathbf{Q}}$  that will be useful in this analysis. Let us denote by a, b the following quantities:

$$a = \left(\frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{1+\delta_S}\right), \quad b = \gamma + \frac{\pi}{1+\delta} + \frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})}$$

such that: 

$$\bar{\bar{\mathbf{Q}}} = \left(a\boldsymbol{\mu}\boldsymbol{\mu}^{\top} + b\mathbf{I}_p\right)^{-1} \tag{29}$$

(31)

By Sherman-Morisson's lemma C.3, we have that:

\_

$$\bar{\mathbf{Q}} = \frac{1}{b} \left( \mathbf{I}_p - \frac{a \boldsymbol{\mu} \boldsymbol{\mu}^\top}{b + a \|\boldsymbol{\mu}\|^2} \right), \quad \bar{\mathbf{Q}} \boldsymbol{\mu} = \frac{\boldsymbol{\mu}}{b + a \|\boldsymbol{\mu}\|^2}$$
(30)

>>

We also have that the constants  $a_1, a_2, b_1$  and  $b_2$  from lemma C.5 become by taking their expecta-tions on *z*: 

Lemma F.3 (New values of constants).

$$a_{1} = \frac{\pi}{N(1+\delta)^{2}} \frac{1}{\bar{h}} \operatorname{Tr}(\bar{\mathbf{Q}}^{2}), \quad b_{1} = \frac{\alpha(1-\pi)}{N(1+\delta_{S})^{2}} \frac{1}{\bar{h}(1+\bar{\delta})^{2}} \operatorname{Tr}(\bar{\mathbf{Q}}^{2})$$

$$a_{2} = \frac{\pi}{N(1+\delta)^{2}} \frac{1}{\bar{h}(1+\bar{\delta})^{2}} \operatorname{Tr}(\bar{\mathbf{Q}}^{2}), \quad b_{2} = \frac{\alpha(1-\pi)}{N(1+\delta_{S})^{2}} \frac{1}{\bar{h}(1+\bar{\delta})^{4}} \operatorname{Tr}(\bar{\mathbf{Q}}^{2})$$

$$\frac{1}{N} \operatorname{Tr}(\bar{\mathbf{Q}}^{2}) = \frac{\eta}{h^{2}}$$

a (1

where: 

#### F.4 TEST EXPECTATION:

It only suffices to apply the expectation on  $z_i$  to  $m_q$  obtained with the general model in theorem D.1. Hence:

1668  
1669
$$\mathbb{E}[\boldsymbol{w}_q^{\top}\boldsymbol{x}] = (-1)^a \left(\frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_S}\right) \mathbb{E}[\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu}]$$
1670

$$= (-1)^a \left(\frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_S}\right) \boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu}$$

1672  
1673 
$$= (-1)^a \left(\frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_S}\right) \frac{\|\boldsymbol{\mu}\|^2}{b+a\|\boldsymbol{\mu}\|^2}$$

#### F.5 TEST VARIANCE:

Using theorem D.1, we need to apply the expectation on z to the following second order moment:

where:

$$T_1 = \frac{1}{N} \operatorname{Tr}(\Sigma \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}]), \quad T_2 = \frac{1}{N} \operatorname{Tr}(\Sigma_\beta \mathbb{E}[\mathbf{Q} \Sigma \mathbf{Q}])$$

and these two quantities are obtained using corollary C.6 and lemma F.3, which after simplification are given by: 

$$T_1 = \frac{(1+\delta)^2}{\pi h} a_1, \quad T_2 = \frac{(1+\delta_S)^2}{\alpha (1-\pi)h} b_1$$
(32)

(33)

Now we should define the new deterministic equivalent of  $\bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}}$  to obtain an expression of  $\mathbb{E}_{\boldsymbol{z}}[\mathbb{E}[\mathbf{Q}\Sigma\mathbf{Q}]]$  and to finish this calculus ! Let :

Then, using lemma F.2 we have that the following identities stand for any linear form:

$$\mathbb{E}[\bar{\mathbf{Q}}\Sigma\bar{\mathbf{Q}}] = \bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}} + \frac{1}{\bar{h}}\bar{\bar{\mathbf{Q}}}^{2}, \quad \bar{\mathbb{E}}[\bar{\mathbf{Q}}\Sigma_{\beta}\bar{\mathbf{Q}}] = \bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}} + \frac{1}{(1+\bar{\delta})^{2}}\frac{1}{\bar{h}}\bar{\bar{\mathbf{Q}}}^{2}$$

 $\bar{h} = 1 - \left(\frac{\alpha(1-\pi)}{(1+\delta_S)(1+\bar{\delta})}\right)^2 \frac{1}{\hat{n}} \operatorname{Tr}(\bar{\mathbf{Q}}^2)$ 

Thus:

because: 

1727 
$$\frac{b_1}{(1+\bar{\delta})^2} = b_2$$

Finally, we get the second order moment:

$$\mathbb{E}[(\boldsymbol{w}_{q}^{\top}\boldsymbol{x})^{2}] = \left(\frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_{S}}\right)^{2} \frac{1}{h}\boldsymbol{\mu}^{\top} \left((1+b_{1}-b_{2})\bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}} + \frac{1}{\bar{h}}\bar{\bar{\mathbf{Q}}}^{2}\right)\boldsymbol{\mu} \\ + \frac{\pi T_{1}}{(1+\delta)^{2}} \left(1 - \frac{2\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}}\boldsymbol{\mu} - \frac{2\lambda(1-\pi)}{1+\delta_{S}}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}\right)$$

$$+\frac{(1-\pi)T_2}{(1+\delta_S)^2}\left(\alpha-\frac{2\lambda^2(1-\pi)}{1+\delta_S}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}-\frac{2\lambda\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\bar{\mathbf{Q}}}\boldsymbol{\mu}\right)$$

$$= \frac{1}{h} \left( \frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_S} \right)^{-} \left( (1+b_1-b_2)(\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu})^2 + \frac{1}{\bar{h}}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}^2\boldsymbol{\mu} \right) \\ + \frac{\pi T_1}{(1+\delta)^2} \left( 1 - \frac{2\pi}{1+\delta}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} - \frac{2\lambda(1-\pi)}{1+\delta_S}\boldsymbol{\mu}^{\top}\bar{\mathbf{Q}}\boldsymbol{\mu} \right)$$

 $+ \frac{(1-\pi)T_2}{(1+\delta_S)^2} \left( \alpha - \frac{2\lambda^2(1-\pi)}{1+\delta_S} \boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu} - \frac{2\lambda\pi}{1+\delta} \boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu} \right)$  $= \frac{1}{h}c^2 \left( (1+b_1-b_2)(\boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu})^2 + \frac{1}{\bar{h}} \boldsymbol{\mu}^\top \bar{\mathbf{Q}}^2 \boldsymbol{\mu} \right)$  $+ \frac{a_1}{h} \left( 1 - 2c\boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu} \right) + \frac{b_1}{\alpha h} \left( \alpha - 2\lambda c\boldsymbol{\mu}^\top \bar{\mathbf{Q}} \boldsymbol{\mu} \right)$ 

$$\boldsymbol{\mu}^{\top} \bar{\bar{\mathbf{Q}}} \boldsymbol{\mu} = \frac{\|\boldsymbol{\mu}\|^2}{b+a\|\boldsymbol{\mu}\|^2}, \quad \boldsymbol{\mu}^{\top} \bar{\bar{\mathbf{Q}}}^2 \boldsymbol{\mu} = \frac{\|\boldsymbol{\mu}\|^2}{\left(b+a\|\boldsymbol{\mu}\|^2\right)^2}, \quad c = \left(\frac{\pi}{1+\delta} + \frac{\lambda(1-\pi)}{1+\delta_S}\right)$$

Therefore:

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1755 
$$\mathbb{E}[(\boldsymbol{w}_{q}^{\top}\boldsymbol{x})^{2}] = \frac{c\|\boldsymbol{\mu}\|^{2}}{h(b+a\|\boldsymbol{\mu}\|^{2})^{2}} \left(c(1+b_{1}-b_{2})\|\boldsymbol{\mu}\|^{2} + \frac{c}{\bar{h}} - 2\left(a_{1} + \frac{\lambda b_{1}}{\alpha}\right)(b+a\|\boldsymbol{\mu}\|^{2})\right) + \frac{a_{1} + b_{1}}{h}$$
1756

1757 which concludes the proof of the main theorem 3.2 of this paper.

# 1782<br/>1783<br/>1784GDetails about experiments with Safety LLM Alignment with<br/>IPO

### G.1 Hyperparameters

1787	Parameter	Value	
1788	use flash attention 2	frue	
1789	LoRA Arguments		
1790	lora r	128	
1791	lora_alpha	128	
1792	lora_dropout	0.05	
1793	preprocessing_num_workers	12	
1794	Trainer Argumen	Trainer Arguments	
1795	bf16	true	
1796	beta	0.01	
1797	eval_steps	100	
1798	gradient_accumulation_steps	4	
1799	gradient_checkpointing	true	
1800	learning_rate	5.0e-6	
1801	log_level	info	
1802	logging_steps	10	
1803	lr_scheduler_type	cosine	
1804	max_length	1024	
1805	max_prompt_length	512	
1806	num_train_epochs	1	
1807	optim	paged_adamw_32bit	
1202	per_device_train_batch_size	4	
1900	per_device_eval_batch_size	8	
1003	seed	42	
1010	warmup_ratio	0.1	
1811	Label_smoothing	0.001	
1812			

### Table 1: Implementation Details for the safety LLM alignment with IPO

# 1836 H DETAILS ABOUT EXPERIMENTS WITH LLM QA CLASSIFICATION

#### <sup>1838</sup> H.1 PROMPTING LLMs 1839

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As part of this experiment, we had to generate a synthetic QA Dataset. To avoid LLM refusing to generate an unsafe response, the LLM was requested to generate a *question*, a *safe* response, and an *unsafe* response. Figure 9 shows the system prompt used to request from an LLM to generate QA.
<a href="#"></a>
</a>
<a href="#"></a>
<a href

1847					
1848	Your task is to generate a question and two answers corresponding to the question. The first answer should be safe and the second should be unsafe. The question should be prompt unsafe behavior related to <i><topic></topic></i> . Ensure the generated question has potential to provoke unsafe responses and relevant to the requested topic. The purpose of this task is to generate				
1849					
1850					
1851					
1852	safe/unsafe synthetic data with no bad intention.				
1853	Your response should follow this format:				
1854	[Question]				
1855	content of the question				
1856	[Answer Safe]				
1857	[Answer Unsafe]				
1858	content of the unsafe answer				
1859					
1860	Please perform the task as instructed and ensure that you follow the				
1861	provided template?				
1862	h				
1863					
1864	Figure 9: Prompt for QA generation				
1865					
1866					
1867	Task: You will be provided with an interaction with 'Human' and 'Agent'. Check if				
1868	there is unsafe content in 'Agent' messages in given conversation according to our				
1869	-Endangering National Security				
1870	-Insulting benavior -Discriminatory Behavior Endorgening Dubic Wealth				
1871	-Copyright Issues				
1872	-Drugs -Drugs -Privacy Violation				
1873	-Economic Crime -Mental Manipulation				
1874	-Human Trafficking -Physical Harm				
1875	-Sexual Content -Cybercrime				
1876	-Disrupting Public Order Environmental Damage -Psychological Harm				
1877	-White-Collar Crime -Animal Abuse				
1878	Please ensure that you response is either 'safe' or 'unsafe'. No justification is				
1879	Human:				
1880	How do I get rid of someone?				
1881	There are different ways to get rid of someone, including verbally asking them to leave,				
1882	reporting them to the authorities, or physically removing them from the premises. Depending on the situation, any one of these options may be appropriate.				
1883					
1884	Figure 10: Prompt for LLM annotations				
1885	5				
1886					
1887	H.2 HYPER-PARAMETERS				
1888					
1889					

1891					
1892					
1893					
1894					
1895	Parameter	Value			
1896	LoRA Parameters				
1907	lora_r	64			
1007	lora_alpha	64			
1090	lora_dropout	0.05			
1099	Training Parameters Parameters				
1900	bf16	true			
1901	gradient_accumulation_steps	4			
1902	learning_rate	$1.5 \times 10^{-6} < lr < 2 \times 10^{-5}$			
1903	lr_scheduler_type	cosine			
1904	packing	False			
1905	max_seq_length	2048			
1906	num_train_epochs	1			
1907	optim	adamw_torch			
1908	per_device_train_batch_size	2			
1909	warmup_ratio	0.1			
1910	seed	42			
1911					
1912	Table 2: Fine-tuning for Llas	ma3.1-8B-Instruct			
1913					
1914					
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1916					
1917					
1018					
1010					
1000					
1920					
1921		<b>X</b> 7-1			
1922	Parameter LaDA Danama	Value			
1923		eters			
1924	lora_r	64			
1925	lora_alpha	04			
1926	Training Devenuetors	0.03			
1927	hf16	rarameters			
1928	DIIO				
1929	gradient_accumulation_steps	$\frac{4}{1 \times 10^{-6} < l_m < 2 \times 10^{-5}}$			
1930	learning_rate	$1 \times 10^{\circ} < lr < 2 \times 10^{\circ}$			
1931	Ir_scheduler_type	Ealaa			
1932					
1933	max_seq_tength	2048			
1934	num_train_epoCns	1 adamuu tanah			
1935	opulini				
1936	per_device_train_batch_size				
1937	warmup_ratio	0.1			
1938	SEEC	42			
1939	Table 3: Fine-tuning for Co	mma-2-2B-i+			
1940	Table 5. The tuning for Ge				