Breaking Memorization Barriers in LLM Code Fine-Tuning via Information Bottleneck for Improved Generalization

Anonymous ACL submission

Abstract

Adapting pretrained large language models (LLMs) to code domains via supervised fine-tuning (FT) has been commonly used for code generation. However, we identify a previously underappreciated failure mode, the *memorization barrier*, where strong memorization of downstream code data in the base model could trap optimization and prevent the standard FT from effectively acquiring new, generalizable code knowledge. To overcome this barrier, we propose the *information bottleneck (IB)-guided fine-tuning*, termed IB-FT, which applies an IB penalty on hidden representations of the code data to compress spurious, memorized features while preserving task-relevant information. Extensive experiments on two code benchmarks (OriGen and Evol-CodeAlpaca-V1) show that IB-FT substantially alleviates the memorization barrier, improves top-1 performance (Pass@1), and yields far more stable gains under the stricter multi-sample metric Pass@$k^{(m)}$ (a problem counts as solved only if at least m of k samples pass unit tests) compared with conventional FT. The code is available at **link**.

1 Introduction

Code generation sits at the nexus of AI and software engineering, driving rapid advances in both research and industry (Nijkamp et al., 2023; Hou et al., 2024; Thakur et al., 2024; Huynh and Lin, 2025; Li et al., 2022). By automating programming tasks, LLMs can boost developer productivity, lower engineering costs, and increase accessibility, contributions already translate to billions in annual economic value and are expected to grow as adoption widens (Daniotti et al., 2025).

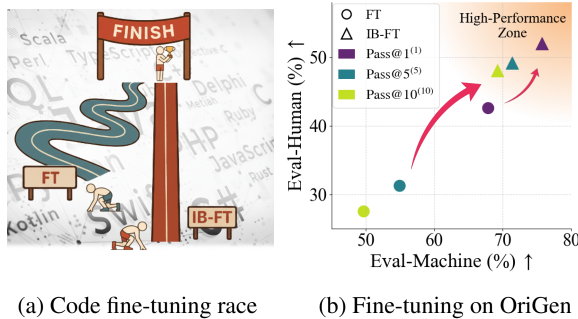
Yet, rather than training models from scratch on specialized code corpora, practitioners typically fine-tune pretrained LLMs on downstream code datasets because this approach is computationally cheaper and more accessible (Roziere et al., 2023; Beckmann et al., 2004; Wang et al., 2022). Nevertheless, adaptation remains challenging: models must acquire both programming syntax and compositional semantics while avoiding overfitting to dataset idiosyncrasies and excessive memorization of pretraining data (Mathews and Nagappan, 2024; Xu et al., 2022; Fakhoury et al., 2024). In this work, we show that code fine-tuning is often brittle: fine-tuned models can exhibit a large gap between greedy decoding (Pass@1) and sampling-based metrics (Pass@k), *i.e.*, a correct program may appear among multiple ($k > 1$) sampled generations while the one-time generation by greedy decoding remains incorrect; We defer further details to Fig. 2 (Sec. 2). This evidence exposes the limited effectiveness of current code fine-tuning practices and motivates our central question:

> ***(Q)** What causes the ineffectiveness of LLM code fine-tuning, and how can fine-tuning be improved to achieve stronger generalization?*

To tackle **(Q)**, we first investigate why code fine-tuning is not effective to acquire new code knowledge, examining the interaction between fine-tuning data and the pretrained model through the lens of *memorization*. We identify a "***memorization barrier***": the base model already strongly memorizes the fine-tuning code data, trapping optimization in a region that the standard fine-tuning objective cannot escape. Although prior work has identified memorization as a challenge for LLM-based code generation (Chen et al., 2025; Yang et al., 2024; Al-Kaswan et al., 2024), most studies treat memorization as a privacy or contamination problem, either by detecting leakage against pretraining or fine-tuning corpora (Carlini et al., 2022; Zeng et al., 2023) or by showing that test-set contamination in pretraining inflates evaluation scores (Deng et al., 2024; Dong et al., 2024; Golchin and Surdeanu, 2025; Wang et al., 2025; Riddell et al., 2024). In contrast, we adopt a cross-

pretraining fine-tuning adaptation perspective and show that strong memorization of the fine-tuning dataset already present in the base model (prior to adaptation) creates a "memorization barrier"[1] that traps optimization and prevents effective, generalizable fine-tuning.

To overcome the memorization barrier, we propose a new fine-tuning (FT) strategy, termed *IB-regularized fine-tuning* (IB-FT), motivated by the information bottleneck (IB) principle (Tishby and Zaslavsky, 2015; Saxe et al., 2019). IB-FT applies an IB regularizer to hidden representations to compress prediction-irrelevant (spurious) features that arise from memorization bias. By constraining representation capacity and reshaping the data representation distribution, IB-FT reduces the dominance of heavily memorized samples and promotes more uniform learning across the code dataset, improving domain adaptation and generalization to unseen code. Intuitively, consider two runners: one begins earlier but takes a winding, indirect route (standard fine-tuning, which appears ahead due to memorization but is slowed by detours), while the other starts later yet runs straight to the finish (IB-FT, which reaches the goal more efficiently despite the delayed start). See **Fig. 1** for an illustrative schematic and performance comparison.



(a) Code fine-tuning race (b) Fine-tuning on OriGen

Figure 1: Schematic overview of IB-FT versus conventional FT and a representative performance comparison when fine-tuning on OriGen. (a) A code fine-tuning "race": conventional FT (left) appears to advance quickly by memorization but follows a winding, less-generalizable path, whereas IB-FT (right) progresses along a straighter trajectory toward the "winning" generalization. (b) Test-time performance for DeepSeek-Coder-7B-Instruct-v1.5, reported on Eval-Human and Eval-Machine using Pass@$k^{(m)}$ with $m = k \in \{1, 5, 10\}$ (a problem is counted only if all k samples pass). IB-FT consistently attains higher, more stable accuracy and occupies the high-performance region compared to FT.

We summarize our main contributions below:

- We introduce and formalize the memorization barrier problem, showing via systematic analysis that strong pre-existing memorization of fine-tuning examples can critically limit the effectiveness of code fine-tuning.
- We recast fine-tuning through the IB (information bottleneck) lens and propose an IB-based regularizer (IB-FT) that compresses spurious features, alleviates the memorization barrier, and promotes more effective code fine-tuning.
- We present extensive empirical results validating the memorization barrier phenomenon and conduct IB-FT on two diverse code datasets, OriGen (Cui et al., 2024) and Evol-CodeAlpaca-V1 (Luo et al., 2024), showing that IB-FT consistently improves generalization, including under stricter evaluations like Pass@$k^{(m)}$ in Fig. 1-(b).

[1] Although introduced for code generation, the memorization barrier likely extends to other domains where pretrained models already memorize downstream data, thereby hindering effective adaptation.

2 Preliminaries and Challenges in LLM Code Fine-tuning

Preliminaries on LLM code fine-tuning. LLMs are pretrained on massive and heterogeneous corpora, which equip them with broad linguistic and reasoning capabilities. While such pretraining confers strong general abilities, it often falls short in providing the specialized expertise required for code-related tasks, *e.g.*, reasoning beyond code syntax (Jain et al., 2023), Python code generation (Le et al., 2022), domain-specific adaptation for Verilog code generation (Thakur et al., 2024; Zhao et al., 2024). Instead of training an LLM from scratch on code-centric corpora, the conventional approach is to adapt a pretrained model through *code fine-tuning*, where specialized code datasets are used to align the model with the target code distribution (Cui et al., 2024; Wei et al., 2025).

Formally, given a pretrained model with parameters $\boldsymbol{\theta}_0$ and a target-domain code dataset $\mathcal{D}_{\text{code}} = \{(x, y)\}$, where x denotes the input (*e.g.*, problem description) and y denotes the target output (*e.g.*, solution code), the fine-tuning objective is to minimize the negative log-likelihood:

$$\underset{\boldsymbol{\theta}}{\text{minimize}} \ \mathbb{E}_{(x,y)\sim\mathcal{D}_{\text{code}}}\left[-\log p_{\boldsymbol{\theta}}(y \mid x)\right], \tag{1}$$

where $\boldsymbol{\theta}$ are the model parameters initialized from $\boldsymbol{\theta}_0$. Fine-tuned code LLMs enable code completion, program synthesis, and translation, making effective fine-tuning essential for improving productivity, reliability, and accessibility.

An illusion of effectiveness in code fine-tuning. It was commonly believed that code fine-tuning delivers acceptable performance, particularly under

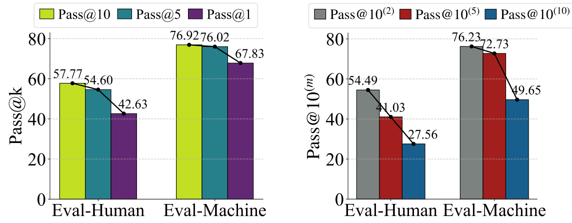


Figure 2: Performance of DeepSeek-Coder-7B-Instruct-v1.5 fine-tuned on the OriGen dataset, evaluated on the Eval-Human and Eval-Machine. (a) Pass@k results for $k \in \{10, 5, 1\}$, measuring the probability that at least one of the top-k generations passes the test cases. (b) Pass@$k^{(m)}$ results with $k = 10$ and $m \in \{2, 5, 10\}$, requiring multiple successful generations among the ten samples to reflect robustness.

the *Pass*@k metric, which measures the probability that *at least one* of the top-k generated outputs from an LLM is correct (Chen et al., 2021). However, there might be an illusion of effectiveness: (1) under greedy decoding (*i.e.*, $k = 1$), the fine-tuned LLM can experience a sharp accuracy drop, and (2) even for larger k, most generations actually fail despite one occasionally passing.

Fig. 2 validates the above illusion by fine-tuning the pretrained DeepSeek-Coder-7B-Instruct-v1.5 on OriGen (Cui et al., 2024), with test-time generalization performance evaluated on *VerilogEval* (Liu et al., 2023), which is a widely-used Verilog code generation benchmark and consists of two complementary subsets below. *Eval-Machine* refers to automatic evaluation, where generated code is executed against unit tests or reference outputs (Liu et al., 2023). *Eval-Human*, in contrast, relies on human annotators to assess the quality of generated code in terms of correctness, clarity, and style (Liu et al., 2023).

As shown in Fig. 2(a), the fine-tuned model performance, evaluated by both *Eval-Machine* and *Eval-Human*, exhibits a significant accuracy drop at Pass@1. This indicates that the fine-tuned model lacks certainty under greedy decoding, unless one leverages the strength of probabilistic generation. Furthermore, to probe beyond the standard Pass@k, we introduce a *stricter, complementary metric Pass*@$k^{(m)}$, which measures the probability that *at least* m of the top-k generated outputs are correct. Note that Pass@$k^{(1)}$ reduces to the classic Pass@k evaluation. As shown in Fig. 2(b), the accuracy under Pass@$k^{(m)}$ decreases sharply as m increases, revealing that even when allowing multiple generations (*e.g.*, $k = 10$), most outputs are still incorrect.

Problem statement. As shown in Fig. 2, achieving effective code fine-tuning for LLMs is far from trivial, with root causes largely overlooked in prior work. To address this gap, we focus on two key questions in this study: ***(Q1)*** *What causes the difficulty of effective code fine-tuning for LLMs?* ***(Q2)*** *How can the existing fine-tuning protocol in (1) be advanced to achieve improved effectiveness?*

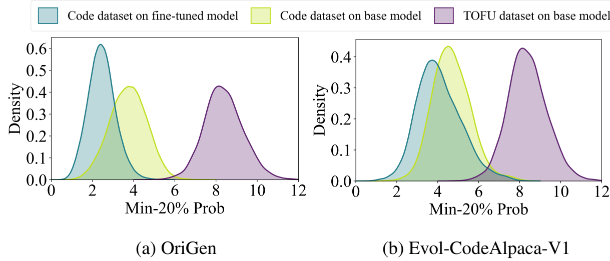
In the rest of the paper, we address (Q1) by identifying the "memorization barrier" in LLM code fine-tuning, where excessive memorization of fine-tuning data by the pretrained LLM can *hinder* effective adaptation (see Sec. 3). We then address (Q2) by tackling this barrier through an information bottleneck perspective, enforcing *equality* across data with different memorization levels so that the fine-tuner learns from the most informative aspects of the data (see Sec. 4).

3 The "Memorization Barrier" in LLM Code Fine-tuning

The memorization lens on (in)effective code fine-tuning. As illustrated in Fig. 2, the code fine-tuned LLM does not appear to gain much from the code dataset, as evidenced by its sharp accuracy drop in Pass@1 and in Pass@$k^{(m)}$ for large m. This raises the question of whether the limitation stems from the quality of the data themselves or from the fine-tuning process failing to fully exploit the code data. In this work, we assume no control over data curation and instead focus on improving the fine-tuning process.

Our hypothesis is that effective code fine-tuning should enable the model to acquire new domain knowledge beyond pretraining, which motivates a deeper examination of the relationship between fine-tuning data and the pretrained LLM. We approach this from the perspective of *memorization* (Shi et al., 2023; Biderman et al., 2023; Leybzon and Kervadec, 2024; Kiyomaru et al., 2024): Given that the pretraining corpus is massive and may partially overlap with the target domain, we examine whether a non-trivial portion of the fine-tuning data has already been memorized, and how this entanglement, ignored in the conventional fine-tuning protocol 1, underlie the observed limitations.

Through the lens of memorization, **Fig. 3** shows the memorization scores of the fine-tuning code datasets, OriGen (Cui et al., 2024) and Evol-CodeAlpaca-V1 (Luo et al., 2023), with respect to the base model ($\boldsymbol{\theta}_0$). Here, memorization is assessed using the `Min-K% Prob` method (Shi et al., 2023), which measures how likely a sequence has



(a) OriGen (b) Evol-CodeAlpaca-V1

Figure 3: Downstream data already memorized during pretraining. Memorization patterns measured by `Min-K% Prob` ($K = 20$) using DeepSeek-Coder-7b-Instruct-v1.5 and Llama-3 8B as base models on two code datasets, OriGen and Evol-CodeAlpaca-V1. The x-axis shows `Min-20% Prob` scores and the y-axis their density. For each dataset, three distributions are reported: $p_0(\mathcal{D}_{\text{code}}; \boldsymbol{\theta}_0)$ (code dataset on the base model), $p_1(\mathcal{D}_{\text{code}}; \boldsymbol{\theta}_{\text{code}})$ (code dataset on the fine-tuned model), and $p_2(\mathcal{D}_{\text{TOFU}}; \boldsymbol{\theta}_0)$ (TOFU dataset on the base model), where p_2 provides the weakest-memorization reference.

been memorized by a model. It selects the $K\%$ tokens with the lowest predicted probabilities and computes their average negative log-likelihood (*i.e.*, the prediction loss over the least likely tokens). A lower `Min-K% Prob` score indicates stronger memorization, as even the least likely tokens are predicted confidently, whereas a higher score suggests weaker memorization.

In Fig. 3, we present the distribution of `Min-K% Prob` (with $K = 20$) scores for the fine-tuning code dataset (OriGen or Evol-CodeAlpaca-V1, denoted $\mathcal{D}_{\text{code}}$) on the pretrained model ($\boldsymbol{\theta}_0$) and its fine-tuned counterpart ($\boldsymbol{\theta}_{\text{code}}$), denoted as $p_0(\mathcal{D}_{\text{code}}; \boldsymbol{\theta}_0)$ and $p_1(\mathcal{D}_{\text{code}}; \boldsymbol{\theta}_{\text{code}})$, respectively. For comparison, we also include $p_2(\mathcal{D}_{\text{TOFU}}; \boldsymbol{\theta}_0)$, the distribution obtained from the base model evaluated on the fictitious TOFU dataset (Maini et al., 2024), which is excluded from pretraining as it contains synthetic author profiles. The rationale is that $p_2(\mathcal{D}_{\text{TOFU}}; \boldsymbol{\theta}_0)$ serves as *a reference distribution for the weakest memorization* of the base model, since $\mathcal{D}_{\text{TOFU}}$ contains entirely fictitious information. As shown in Fig. 3, p_0 lies to the right of p_1, reflecting the stronger memorization of $\mathcal{D}_{\text{code}}$ by the fine-tuned model $\boldsymbol{\theta}_{\text{code}}$. This is expected, since $\boldsymbol{\theta}_{\text{code}}$ is directly trained on $\mathcal{D}_{\text{code}}$. More interestingly, *however*, p_0 has shown substantial overlap with p_1, suggesting that *the base model has already memorized much of the dataset prior to fine-tuning*. This strong pre-existing memorization becomes especially evident when contrasted with the weak memorization reference p_2.

The above reveals a *new memorization phenomenon* identified from LLM code fine-tuning: fine-tuning data points may already be strongly memorized by the pretrained base model even before fine-tuning. We remark that this finding differs from prior literature, which has typically examined memorization from a privacy perspective (to detect leakage), either by evaluating an LLM against its pretraining data (Carlini et al., 2022) or by assessing a fine-tuned LLM against its fine-tuning data (Zeng et al., 2023). In contrast, ours introduces a *cross-setting* perspective: evaluating the memorization of *fine-tuning datasets* on the *base model*.

"Memorization barrier" in code fine-tuning. Given the strong memorization of code fine-tuning data by the pretrained base model, we posit that this memorization underlies the limited effectiveness of LLM code fine-tuning. This challenge is analogous to a known challenge in nonconvex optimization, "*escaping bad local optima*" (Ge et al., 2015; Criscitiello and Boumal, 2019). Our rationale is that, due to the memorization, the base model becomes trapped in a bad "local optimum" characterized by high memorization. Consequently, the conventional fine-tuning objective (1) struggles to escape this state and converge to a better solution, *i.e.*, a code fine-tuned model with improved generalization. We refer to this phenomenon as the "**memorization barrier**" and formalize it below, with a supporting analysis provided in Appendix A from an optimization viewpoint.

> **Memorization barrier:** The phenomenon where LLM code fine-tuning starts from a base model $\boldsymbol{\theta}_0$ that already strongly memorizes the fine-tuning set $\mathcal{D}_{\text{code}}$, placing optimization in a state the conventional fine-tuning objective struggles to escape, thereby leading to poor generalization on downstream code tasks.

Fig. 4 validates the memorization barrier by comparing *Pass@k* performance of the fine-tuned model using the conventional approach (1) with different data pruning ratios, where the most memorized data points (identified in Fig. 3) are removed from the fine-tuning set. We examine whether excluding highly memorized fine-tuning data, *i.e.*, alleviating the memorization barrier at the data source, enables the conventional fine-tuning approach to yield a better code model. The results reveal a striking pattern: removing as little as the most memorized 10% of data yields a substantial improvement in Pass@1 on Eval-Human and Eval-Machine. Further, using fewer fine-tuning data points does not degrade generalization under Pass@k for large k. These suggest that memorized data act as a *memorization barrier*, capping the

effectiveness of fine-tuning from the base model.

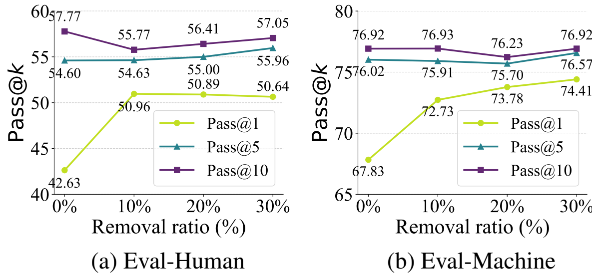


Figure 4: Pass@k performance of the fine-tuned model on the OriGen dataset using DeepSeek-Coder-7b-Instruct-v1.5, evaluated by (a) *Eval-Human* and (b) *Eval-Machine* (Liu et al., 2023), with different pruning ratios of highly memorized fine-tuning data identified in Fig. 3. The x-axis shows the removal ratio of the most memorized examples (0% corresponds to full dataset), and the y-axis reports Pass@k for $k \in \{1, 5, 10\}$.

The memorization barrier reveals a new effect of memorization on the degraded generalization of LLM fine-tuning. This is different from prior studies, which have primarily examined its negative impact in the context of data contamination (Deng et al., 2024; Dong et al., 2024; Golchin and Surdeanu, 2025; Wang et al., 2025; Riddell et al., 2024), where test samples appear in the pretraining corpus, creating a false impression of "superior" generalization. To tackle this memorization barrier problem, dataset pruning based on memorization appears to be a straightforward way to improve code fine-tuning as shown in Fig. 4. However, this approach is *inefficient*: (1) it requires data-wise attribution to estimate memorization, which is difficult to scale since attribution itself is computationally intensive; and (2) determining the optimal pruning ratio for improved generalization is non-trivial, as exploring all possible choices requires multiple fine-tuning runs, making the process impractical. In the next section, we address the memorization barrier using the *information bottleneck* principle, which eliminates the need for additional data attribution and pruning.

4 Information Bottleneck–Guided LLM Code Fine-tuning

IB regularization to overcome the memorization barrier. To address the memorization barrier identified in Sec. 3, we adopt the IB principle (Tishby et al., 2000; Lei et al., 2025; Liu et al., 2024b; Chen et al., 2024) as a remedy that *requires no additional data attribution or pruning*, enabling an automatic fine-tuning protocol without assuming prior knowledge of the barrier.

The rationale behind using IB is to transform differently memorized data into equally treated ones by compressing representations to discard spurious information while preserving task-relevant signals for prediction (Tishby et al., 2000). More concretely, the IB principle provides a framework to "compress" data representations (potentially discarding spurious memorization), while promoting generalization with preserved predictive power. Given input X, target Y, and representation Z, IB seeks Z that preserves task-relevant information about Y while discarding redundant details from X. This is formulated as

$$\underset{p(z|x)}{\text{minimize}} \; I(X;Z) - \beta I(Z;Y), \quad (2)$$

where $p(z|x)$ gives the conditional distribution of the latent representation Z given the input X, and $I(\cdot;\cdot)$ denotes mutual information and $\beta > 0$ balances prediction against compression.

The compression term $I(X;Z)$ penalizes how much bottleneck representation Z memorizes input-specific details. In LLMs, direct computation is intractable, so we follow the variational IB framework (Alemi et al., 2017):

$$I(X;Z) \;\; \leq \;\; \mathbb{E}_{x\sim\mathcal{D}_{\text{code}}}\left[D_{\text{KL}}\big(q_{\boldsymbol{\phi}}(z|h_{\boldsymbol{\theta}}(x)) \,\|\, p(z)\big)\right], \quad (3)$$

where $\mathcal{D}_{\text{code}}$ denotes the dataset, D_{KL} is the Kullback–Leibler divergence, $p(z)$ is a simple prior (*e.g.*, $\mathcal{N}(0, I)$), $h_{\boldsymbol{\theta}}(x)$ denotes the hidden representation of input x extracted from a designated intermediate LLM layer (*e.g.*, layer 20), and $q_{\boldsymbol{\phi}}$ is the variational encoder (with the learnable parameters $\boldsymbol{\phi}$) that produces the representation Z given $h_{\boldsymbol{\theta}}(x)$. The design of $q_{\boldsymbol{\phi}}$ follows the standard variational IB setting (Alemi et al., 2017).

Minimizing this divergence discourages Z from encoding exact input patterns, thereby suppressing memorization of rare or spurious sequences. Hence, from (3), the compression loss is given by

$$\ell_{\text{IB}}^{\text{compress}}(\boldsymbol{\theta}, \boldsymbol{\phi}) = \mathbb{E}_{x\sim\mathcal{D}_{\text{code}}}\left[D_{\text{KL}}\big(q_{\boldsymbol{\phi}}(z \mid h_{\boldsymbol{\theta}}(x)) \,\|\, p(z)\big)\right], \quad (4)$$

In addition, the prediction term $I(Z;Y)$ in (2) prevents over-compression by ensuring that the bottleneck preserves information relevant for predicting Y. This term can be expressed by the log-likelihood of predicting Y from Z,

$$\ell_{\text{IB}}^{\text{predict}}(\boldsymbol{\theta}, \boldsymbol{\phi}) = \mathbb{E}_{(x,y)\sim\mathcal{D}_{\text{code}}}\left[\log p_{\boldsymbol{\theta}}(y \mid z)\right], \quad (5)$$

where z is sampled from $q_{\boldsymbol{\phi}}(z|h_{\boldsymbol{\theta}}(x))$.

Integrating (4) with (5) based on (2), the proposed IB regularization loss is defined as

$$\ell_{\text{IB}}(\boldsymbol{\theta}, \boldsymbol{\phi}) = \ell_{\text{IB}}^{\text{compress}}(\boldsymbol{\theta}, \boldsymbol{\phi}) - \beta \ell_{\text{IB}}^{\text{predict}}(\boldsymbol{\theta}, \boldsymbol{\phi}), \quad (6)$$

where β is a hyperparameter that balances the trade-off between compression and prediction, consistent with the standard IB formulation.

Furthermore, we integrate (6) with the standard fine-tuning objective in (1), yielding the **IB-regularized fine-tuning (IB-FT)**:

$$\underset{\boldsymbol{\theta},\boldsymbol{\phi}}{\text{minimize}} \quad \ell_{\text{FT}}(\boldsymbol{\theta}) + \alpha\, \ell_{\text{IB}}(\boldsymbol{\theta}, \boldsymbol{\phi}), \tag{IB-FT}$$

where ℓ_{FT} is the standard cross-entropy loss from (1), and $\alpha > 0$ controls the relative strength of the IB regularization. We provide implementation details of IB-FT in Appendix B.

Validating the effectiveness of IB through representation analysis. Recall that the motivation for using IB lies in its ability to compress representations while retaining predictive information, thereby reducing the influence of prediction-irrelevant (*i.e.*, spurious) features. This allows differently memorized data to be treated more uniformly during learning, mitigating the memorization barrier that arises from prior differences in memorization strength among code data.

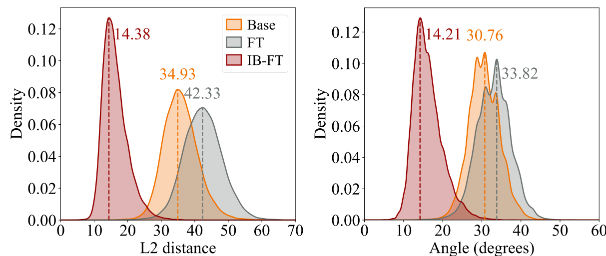


Figure 5: Representation distance and angle analysis with fine-tuning data on OriGen, using the base DeepSeek-Coder-7B-Instruct-v1.5 model and its fine-tuned variants (FT and IB-FT). Hidden representations $h_{\boldsymbol{\theta}}(x)$ are extracted from the 20th layer, and paired samples are drawn between the most-memorized and least-memorized groups (identified by `Min-20% Prob` scores in Fig. 3) to compute (a) their ℓ_2 distance distributions (left) and (b) angular disparity distributions (right). Dashed vertical lines mark distinct separation patterns under different fine-tuning regimes.

To validate the effectiveness of IB-FT, we analyze the representation geometry between memorized and non-memorized examples. Using `Min-K% Prob` scores, the dataset is partitioned into two subsets (most-memorized group and least-memorized group), and paired samples are drawn to measure ℓ_2 distances and angular disparities between their hidden representations at layer 20. As shown in **Fig. 5**, standard FT exaggerates the separation between the two groups relative to the base model, creating a *barrier* that forces the model to treat them in markedly different ways. In contrast, IB-FT substantially *compresses* this gap, reducing both distance and angular disparity by more than half. These results demonstrate that IB regularization yields more coherent, task-relevant representations across all data groups, thereby enabling fine-tuning to generalize more effectively.

5 Experiments

5.1 Experiment Setup

Datasets and models. Our experiments focus on two established datasets for LLM code fine-tuning: **OriGen** (Cui et al., 2024) for Verilog code generation, and **Evol-CodeAlpaca-V1** (Luo et al., 2024) for multi-language code generation. OriGen is a Verilog instruction–response corpus with 222,075 examples, used to fine-tune LLMs for register-transfer-level (RTL) code generation. Evol-CodeAlpaca-V1 is a multi-language instruction-to-code dataset of roughly 111,000 examples (covering Python, C++, Java, TypeScript, and Shell).

Following prior work (Cui et al., 2024; Luo et al., 2024), we adopt **DeepSeek-Coder-7B-Instruct-v1.5** (Guo et al., 2024) and **CodeLlama-7B-Instruct** (Roziere et al., 2023) as base models to validate the memorization barrier on the OriGen dataset. For Evol-CodeAlpaca-V1, we use **DeepSeek-Coder-7B-v1.5** (Guo et al., 2024) and **Llama-3-8B** (Grattafiori et al., 2024) as base models. And see **Appendix C.1** for more details about model fine-tuning parameters for FT and IB-FT.

Fine-tuning methods. In addition to the proposed **IB-FT**, we consider standard full-data fine-tuning as the primary baseline, *i.e.*, **FT**. We further evaluate two advanced data selection strategies combined with FT. Specifically, **FT w/ Min-K%** removes highly memorized samples based on memorization scores computed using the `Min-K% Prob` metric prior to fine-tuning, as used in Fig. 4 for motivating experiments. In addition, **FT w/ GRAND** applies the GRAND dataset pruning method (Paul et al., 2021) to identify a coreset of the fine-tuning dataset. For both selection-based methods, we uniformly retain 80% of the training data.

Evaluation. For OriGen, we evaluate using the **VerilogEval** benchmark (Liu et al., 2023), which comprises two subsets: **Eval-Human** (human-authored problems, *e.g.*, HDLBits and manually transcribed tasks) and **Eval-Machine** (machine-generated prompts produced by LLMs). For Evol-CodeAlpaca-V1, we use **HumanEval** (Chen et al., 2021), a standard Python benchmark of 164 programming problems with natural-language descriptions, function signatures, and unit tests for

Table 1: Performance of CodeLlama-7B-Instruct and DeepSeek-Coder-7B-Instruct-v1.5on OriGen under different fine-tuning strategies, including FT, data-selection-based fine-tuning (FT w/ GRAND, FT w/ Min-K%), and our proposed IB-FT. Test-time accuracies are reported on the Eval-Human and Eval-Machine subsets using Pass@k ($k \in \{1, 5, 10\}$) and the stricter Pass@$10^{(m)}$ ($m \in \{2, 5, 10\}$), where Pass@$10^{(m)}$ counts a problem as solved only if at least m of the 10 generated samples pass the unit tests. Best results are shown in **bold**. And each score is reported with its variance over five independent trials.

Methods	Eval-Human (%)						Eval-Machine (%)					
	Pass@k ↑			Pass@$10^{(m)}$ ↑			Pass@k ↑			Pass@$10^{(m)}$ ↑		
	$k=1$	$k=5$	$k=10$	$m=2$	$m=5$	$m=10$	$k=1$	$k=5$	$k=10$	$m=2$	$m=5$	$m=10$
CodeLlama-7B	17.56 ±0.099	27.02 ±0.164	29.49 ±0.195	26.28 ±0.213	17.95 ±0.230	4.19 ±0.263	44.76 ±0.045	53.79 ±0.141	55.24 ±0.078	53.85 ±0.078	47.55 ±0.158	27.27 ±0.236
+ FT	46.15 ±0.395	48.47 ±0.263	48.72 ±0.230	48.72 ±0.230	45.13 ±0.230	43.59 ±0.395	66.36 ±0.236	70.53 ±0.078	71.33 ±0.045	70.63 ±0.128	65.03 ±0.164	62.24 ±0.236
+ FT w/ GRAND	42.95 ±0.128	48.08 ±0.164	51.28 ±0.099	47.44 ±0.329	41.67 ±0.164	38.46 ±0.128	65.03 ±0.371	70.63 ±0.236	71.33 ±0.189	69.93 ±0.236	63.64 ±0.247	62.24 ±0.484
+ FT w/ Min-K%	49.10 ±0.230	52.32 ±0.230	54.49 ±0.164	48.18 ±0.230	46.15 ±0.247	41.67 ±0.427	69.94 ±0.219	71.91 ±0.219	74.13 ±0.427	70.63 ±0.201	70.63 ±0.176	62.22 ±0.484
+ IB-FT	**49.68** ±0.164	**52.82** ±0.164	**54.49** ±0.066	**51.28** ±0.230	**50.64** ±0.230	**45.51** ±0.484	**70.07** ±0.045	**72.94** ±0.189	**73.47** ±0.078	**72.73** ±0.271	**70.63** ±0.263	**64.33** ±0.236
DeepSeek-Coder-7B	34.62 ±0.066	42.09 ±0.164	44.23 ±0.230	42.31 ±0.230	36.54 ±0.164	24.36 ±0.230	56.47 ±0.141	64.76 ±0.236	67.13 ±0.298	63.64 ±0.314	58.74 ±0.346	43.66 ±0.346
+ FT	42.63 ±0.395	54.60 ±0.230	**57.77** ±0.230	54.49 ±0.099	41.03 ±0.099	27.56 ±0.164	67.83 ±0.298	76.02 ±0.236	76.92 ±0.164	76.23 ±0.236	72.73 ±0.271	49.65 ±0.263
+ FT w/ GRAND	46.03 ±0.263	52.48 ±0.230	54.49 ±0.230	52.57 ±0.263	50.85 ±0.395	43.59 ±0.395	72.73 ±0.484	75.92 ±0.412	76.92 ±0.189	74.83 ±0.236	72.73 ±0.314	66.43 ±0.346
+ FT w/ Min-K%	50.89 ±0.066	**55.49** ±0.099	56.41 ±0.066	**55.12** ±0.395	51.92 ±0.230	42.95 ±0.427	73.78 ±0.263	75.70 ±0.230	76.23 ±0.158	75.52 ±0.395	74.13 ±0.484	68.52 ±0.484
+ IB-FT	**51.99** ±0.164	54.86 ±0.164	55.77 ±0.000	54.49 ±0.427	**51.92** ±0.395	**48.07** ±0.395	**75.67** ±0.358	**78.51** ±0.298	**79.02** ±0.176	**78.32** ±0.158	**77.62** ±0.189	**69.23** ±0.439

automatic correctness evaluation. For evaluation metric, we introduce Pass@$k^{(m)}$, which requires at least m of k samples to succeed, offering a stricter and more reliable measure of generation consistency than standard Pass@k. More metric details shown in **Appendix** C.2.

5.2 Experiment Results

Performance overview of IB-regularized fine-tuning (IB-FT). In **Table** 1 we present performance for LLMs (DeepSeek-Coder-7B-Instruct-v1.5 and CodeLlama-7B-Instruct) fine-tuned on OriGen using FT and our IB-FT, together with each model's pre-fine-tuning performance. Test-time accuracy is reported on the Eval-Human and Eval-Machine subsets using standard Pass@k ($k \in \{1, 5, 10\}$) and the stricter Pass@$10^{(m)}$ (fixed $k = 10$, $m \in \{2, 5, 10\}$).

As Table 1 shows, IB-FT consistently yields the top-rank performance: it outperforms both the base model and conventional FT across nearly all Pass@k settings, with especially large gains at $k = 1$. For example, on DeepSeek-Coder-7B-Instruct-v1.5 IB-FT achieves 51.99% (Eval-Human) and 75.67% (Eval-Machine) for Pass@1, versus 42.63% and 67.83% for FT. Increasing k (*e.g.*, to $k = 10$) narrows this gap, FT reaches 57.77% Pass@10 for DeepSeek-Coder-7B-Instruct-v1.5, which is better than IB-FT (55.77%). This suggests that some FT gains are realized only via sampling-based evaluation (Pass@k) rather than as reliable top-1 improvements, consistent with Fig. 2. Crucially, under the stricter Pass@$10^{(m)}$ criteria ($m > 1$), FT's scores fall off sharply, indicating that its successes are often isolated single samples rather than consistently reproducible generations. By contrast, IB-FT delivers more robust and reproducible improvements (notably at Pass@1 and Pass@$10^{(m)}$ for $m > 1$).

To stress, under the stricter Pass@$10^{(m)}$ metric, IB-FT substantially outperforms conventional FT. For the strictest setting ($m = 10$), which requires all 10 generations to pass, IB-FT improves over FT on DeepSeek-Coder-7B-Instruct-v1.5 by roughly 20% on both Eval-Human (*i.e.*, 48.07% by IB-FT vs. 27.56% by FT) and Eval-Machine (*i.e.*, 69.23% by IB-FT vs. 49.65% by FT). This shows that IB-FT yields stronger generalization and more stable multi-sample performance under demanding criteria, producing more reliable models in practice.

In addition, **Table** A1 in **Appendix** D.1 shows that IB-FT also consistently outperforms FT on the Evol-CodeAlpaca-V1 dataset. For example, on HumanEval, IB-FT improves Pass@1 from 56.70% to 61.60% for Llama-3-8B and from 51.28% to 54.57% for DeepSeek-Coder-7B-v1.5. Under the stricter Pass@$10^{(m)}$ setting, IB-FT further demonstrates stronger robustness, maintaining higher scores than FT across all m values. Also **Fig.** A1 in **Appendix** D.2 shows pruning memorized examples, though a natural remedy, is highly sensitive, whereas IB-FT is more robust.

Robustness of IB-FT under different temperature (T) settings. Next, we evaluate code generation after fine-tuning across decoding temperatures $T \in \{0.2, 0.6, 1.0\}$ (the default choice is $T = 0.2$). Varying T probes model robustness to sampling stochasticity and provides a more realistic assessment of fine-tuned performance and stability in practice. This protocol is motivated by the often-overlooked role of temperature in code model evaluation, since higher T yields more diverse gen-

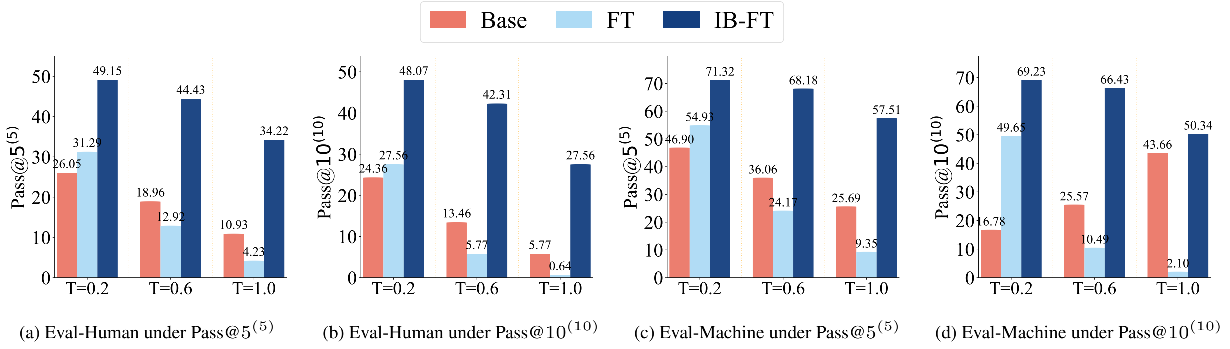


Figure 6: Performance of DeepSeek-Coder-7B-Instruct-v1.5 fine-tuned with IB-FT versus conventional FT and its base model (before fine-tuning) on OriGen across decoding temperatures $T \in \{0.2, 0.6, 1.0\}$. Results are reported on Eval-Human and Eval-Machine using Pass@$k^{(m)}$ with $m = k \in \{5, 10\}$. Other experimental setups follow Table 1.

erations and can materially affect Pass@k-style metrics (Wei et al., 2025; Cui et al., 2024).

Fig. 6 compares DeepSeek-Coder-7B-Instruct-v1.5 fine-tuned with IB-FT, the same model fine-tuned with conventional FT, and the pre-fine-tuned base model across decoding temperatures $T \in \{0.2, 0.6, 1.0\}$. Accuracy is measured by Pass@$k^{(m)}$ with $m = k \in \{5, 10\}$, *i.e.*, reflecting the all-generation success criterion if all k generated samples pass the unit tests. As we can see, IB-FT consistently sustains superior performance across all temperatures and benchmarks (Eval-Human and Eval-Machine), substantially outperforming both conventional FT and the base model even at high temperature. For example, on Eval-Human at $T = 1.0$, IB-FT attains 34.22% (Pass@$5^{(5)}$) versus 4.32% for FT; on Eval-Machine at $T = 1.0$, IB-FT reaches 50.34% while FT collapses to 2.10%. By contrast, FT shows poor robustness to temperature: it only exceeds the base model at the lowest temperature ($T = 0.2$) and suffers large drops as T increases. For instance, on Eval-Human at $T = 0.6$ FT falls to 12.92% (Pass@$5^{(5)}$) below the base model's 18.96%, and on Eval-Machine at $T = 1.0$ the base model retains 43.66% (Pass@$10^{(10)}$) while FT falls to 2.10%. These results indicate that IB-FT mitigates memorization-induced fragility and yields far more stable generalization under decoding stochasticity.

6 Related Work

LLM code fine-tuning. Prior work on code fine-tuning has improved model performance via data-side interventions, *e.g.*, synthetic or augmented corpora (Luo et al., 2023; Li et al., 2023; Song et al., 2024b), and method-side advances, *e.g.*, multi-task FT, self-alignment, and parameter-efficient tuning (Ma et al., 2023; Wei et al., 2024; Liu et al., 2024a; Zhuo et al., 2024; Song et al., 2024a; Liu et al., 2024a). However, these efforts largely ignore memorization in the training data, preventing the potential of code datasets from being fully exploited.

Information bottleneck (IB) in LLMs. The information bottleneck (IB) principle (Tishby and Zaslavsky, 2015; Shwartz-Ziv and Tishby, 2017; Yang et al., 2025) prescribes that latent representations should retain task-relevant information while discarding irrelevant details. Prior IB-based work has applied this idea to reasoning, calibration, security, and representation analysis, emphasizing compression or mutual-information estimation (Chen et al., 2024; Li et al., 2025; Liu et al., 2024b; Lei et al., 2025). By contrast, to the best of our knowledge, we are the first to apply IB-guided fine-tuning in code generation, specifically to suppress spurious memorized features during adaptation.

7 Conclusion

We identify a *memorization barrier* in LLM code fine-tuning: pretrained models often already memorize many downstream examples, which traps optimization dynamics and limits genuine adaptation and generalization. To address this challenge, we propose *IB-regularized fine-tuning* (IB-FT), which introduces an information bottleneck (IB) penalty on hidden representations to suppress spurious memorized features while preserving task-relevant signals. Across OriGen and Evol-CodeAlpaca-V1, IB-FT consistently delivers stronger and more stable gains. Beyond empirical gains, our findings motivate several theoretical directions. Future work will focus on formally characterizing the memorization barrier via optimization and information-theoretic analyses, including convergence and generalization guarantees for IB-FT and a deeper understanding of how representation compression interacts with optimization geometry to enable principled LLM adaptation beyond code fine-tuning.

8 Limitations

While our proposed IB-FT method effectively alleviates the memorization barrier in LLM code fine-tuning and outperforms state-of-the-art methods on two code generation benchmarks, several limitations remain. First, the hyperparameters α in (2) and β in (IB-FT) are selected empirically. Although we observe stable performance across the evaluated settings, their optimal values may vary with model architectures or datasets, and a more systematic sensitivity analysis could further inform deployment in broader scenarios. Second, our experiments focus on code generation tasks and datasets. While the proposed approach is technically general, its effectiveness beyond LLM code fine-tuning has not yet been empirically validated.

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Appendix

A Optimization Perspective on the Memorization Barrier

Formalizing memorization-induced gradient imbalance. We provide a more formal justification for viewing the memorization barrier as a hard-to-escape optimization basin. Consider fine-tuning a pretrained model $\boldsymbol{\theta}$ on a code dataset $\mathcal{D}_{\text{code}} = \mathcal{D}_{\text{m}} \cup \mathcal{D}_{\text{n}}$, where $\mathcal{D}_{\text{m}}$ denotes samples that are already strongly memorized by the base model $\boldsymbol{\theta}_0$, and $\mathcal{D}_{\text{n}}$ denotes non-memorized or weakly memorized samples. For a minibatch $\mathcal{B}$, the stochastic gradient can be decomposed as

$$\nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}; \mathcal{B}) = \frac{1}{|\mathcal{B}|} \Big(\sum_{x \in \mathcal{B}_{\text{m}}} \nabla_{\boldsymbol{\theta}} \ell(x; \boldsymbol{\theta}) + \sum_{x \in \mathcal{B}_{\text{n}}} \nabla_{\boldsymbol{\theta}} \ell(x; \boldsymbol{\theta}) \Big). \tag{A1}$$

Due to strong memorization, gradients from $\mathcal{D}_{\text{m}}$ may satisfy $\|\nabla_{\boldsymbol{\theta}} \ell(x; \boldsymbol{\theta}_t)\| \approx 0$ for $x \in \mathcal{D}_{\text{m}}$ at optimization step $\boldsymbol{\theta}_t$. Consequently, when $|\mathcal{B}_{\text{m}}| > |\mathcal{B}_{\text{n}}|$, the averaged gradient magnitude along directions necessary for adapting to new data is systematically suppressed. This effect induces a *memorization-induced gradient imbalance*.

Memorized regions as hard-to-escape basins. The gradient imbalance described above directly impacts optimization dynamics. Escaping a region of parameter space requires accumulating sufficient displacement along descent directions. If the optimizer produces updates $\|\Delta \boldsymbol{\theta}_t\| \le \delta$, with δ systematically suppressed by memorization, then the number of steps needed to exit the neighborhood of a memorized solution scales inversely with δ. Under a limited fine-tuning budget, such escape becomes increasingly difficult. Consequently, strongly memorized solutions form hard-to-escape basins: not strict local minima of the loss landscape, but regions where optimization dynamics significantly impede progress toward better solutions.

B Algorithm Implementation Details

Alg. 1 summarizes the complete end-to-end training procedure of IB-regularized fine-tuning (IB-FT). This subsection provides a detailed explanation of each component in Alg. 1, including representation extraction, variational bottleneck construction, and joint optimization with LoRA.

Hidden representation selection. For each autoregressive forward pass, the language model produces token-wise hidden representations from all layers. Let B denote the batch size, T the sequence length, and H the hidden dimension of the language model. The bottleneck input is instantiated by selecting a fixed intermediate-to-late layer ℓ^* and extracting its hidden states $h = h^{(\ell^*)} \in \mathbb{R}^{B \times T \times H}$. This layer serves as the insertion point of the information bottleneck, enabling compression of input-specific details while retaining sufficient semantic information for next-token prediction.

Token-wise variational bottleneck. A variational bottleneck is applied independently at each token position. Given a token representation $h_t \in \mathbb{R}^H$, the encoder $q_{\boldsymbol{\phi}}$ parameterizes a diagonal Gaussian posterior $q_{\boldsymbol{\phi}}(z_t \mid h_t) = \mathcal{N}(\mu_t, \operatorname{diag}(\sigma_t^2))$, where $\mu_t, \sigma_t \in \mathbb{R}^d$ and $d \ll H$. Latent variables are sampled via the reparameterization scheme $z_t = \mu_t + \sigma_t \odot \epsilon_t$, where $\epsilon_t \sim \mathcal{N}(0, I)$, which ensures differentiability of the sampling operation. The sampled latent z_t is subsequently mapped back to the hidden dimension through a decoder $g_{\boldsymbol{\phi}}$ to form the bottlenecked representation $\bar{h}_t$. Stacking token-wise states yields $\bar{h} \in \mathbb{R}^{B \times T \times H}$, which is fed into the original language modeling head. This token-level stochastic bottleneck aligns with autoregressive modeling, since each next-token prediction is conditioned on compressed token-wise states rather than a single global sequence embedding.

Interaction with LoRA adaptation. The IB objective regularizes LoRA-based fine-tuning through shared gradient propagation. LoRA modules modify the forward hidden representations prior to bottleneck insertion, while gradients from both ℓ_{FT} and the IB regularizer are backpropagated to the LoRA parameters $\boldsymbol{\psi}$. Consequently, IB regularization constrains the LoRA adaptation directions by discouraging the preservation of input-specific memorized patterns, while maintaining predictive capacity through the autoregressive objective.

Algorithm 1: End-to-End IB-Regularized Fine-Tuning (IB-FT) with LoRA

Input: Frozen base LLM $f_{\boldsymbol{\theta}}$; LoRA parameters $\boldsymbol{\psi}$; variational bottleneck modules $q_{\boldsymbol{\phi}}, g_{\boldsymbol{\phi}}$; target layer index ℓ^*; training data $\mathcal{D}_{\text{code}}$; IB regularization α, β

Output: Trained LoRA parameters $\boldsymbol{\psi}$ and IB parameters $\boldsymbol{\phi}$

Trainable parameters: $\boldsymbol{\psi}, \boldsymbol{\phi}$ **Frozen parameters:** $\boldsymbol{\theta}$

```
foreach mini-batch (x, y) ~ D_code do
    // Autoregressive forward pass with LoRA
    Run f_θ with LoRA Δ_ψ on x to obtain original logits s_orig
    // Select bottleneck layer
    h ← h^(ℓ*) ∈ R^{B×T×H}
    // Token-wise variational bottleneck
    foreach token position t do
        (μ_t, log σ_t^2) ← q_φ(h_t)
        Sample ε_t ~ N(0, I)
        z_t ← μ_t + σ_t ⊙ ε_t
        h̄_t ← g_φ(z_t)
    Compute ℓ_IB^compress = D_KL(q_φ(z|h) ‖ N(0, I))
    // Bottleneck prediction branch
    s_IB ← lm_head(h̄)
    // Loss computation
    ℓ_FT ← CrossEntropy(s_orig, y)
    ℓ_IB^predict ← −CrossEntropy(s_IB, y)
    ℓ_IB ← ℓ_IB^compress − β ℓ_IB^predict
    ℓ_IB−FT ← ℓ_FT + α ℓ_IB
    // Joint optimization
    Update (ψ, φ) by backpropagating ∇_{ψ,φ} ℓ_IB−FT
```

C Experiment Setup Details

C.1 Fine-tuning Details

Base model. For reproducibility, we explicitly list the pretrained code foundation models used for fine-tuning on each dataset with link. On the OriGen dataset, we fine-tune DeepSeek-Coder-7B-Instruct-v1.5[2] and CodeLlama-7B-Instruct[3]. On the Evol-CodeAlpaca-V1 dataset, we fine-tune DeepSeek-Coder-7B-v1.5[4] and Meta-Llama-3-8B[5].

Fine-tuning setup for FT. For the baseline FT, we employ the LoRA (Low-Rank Adaptation) method (Hu et al., 2022). Across all datasets and models, we adopt the AdamW optimizer with $\beta_1 = 0.9$ and $\beta_2 = 0.999$, cosine learning rate decay, and a warm-up ratio of 0.03. Training is performed for 3 epochs with a batch size of 4, using mixed `float16` precision (while the base models were pretrained in `bfloat16`). The LoRA configuration is fixed to $r = 32$ and a dropout rate of 0.05, while α varies by dataset. On the OriGen dataset, training is conducted on two NVIDIA A100 GPUs with 80 GB memory, using an initial learning rate of 5×10^{-5} and LoRA $\alpha = 32$. On the Evol-CodeAlpaca-V1 dataset, training is conducted on four NVIDIA H100 GPUs, with an initial learning rate of 1×10^{-4} and LoRA $\alpha = 64$.

Fine-tuning setup for IB-FT. Our proposed IB-FT method is also built on the LoRA (Low-Rank Adaptation) framework. Across all datasets, we adopt the AdamW optimizer with $\beta_1 = 0.9$ and $\beta_2 = 0.999$, cosine learning rate decay, and a warm-up ratio of 0.03. Training is performed for 3

[2] https://huggingface.co/deepseek-ai/deepseek-coder-7b-instruct-v1.5
[3] https://huggingface.co/codellama/CodeLlama-7b-Instruct-hf
[4] https://huggingface.co/deepseek-ai/deepseek-coder-7b-base-v1.5
[5] https://huggingface.co/meta-llama/Meta-Llama-3-8B

epochs with a batch size of 4, using mixed `float16` precision (while the base models were pretrained in `bfloat16`). For LoRA configuration, we set the rank $r = 32$ and the dropout rate to 0.05, while α varies depending on the dataset. On the OriGen dataset, IB-FT is trained on two NVIDIA A100 GPUs with 80 GB memory, using an initial learning rate of 5×10^{-5} and LoRA $\alpha = 32$. On the Evol-CodeAlpaca-V1 dataset, IB-FT is trained on NVIDIA H100 GPUs, with an initial learning rate of 1×10^{-4} and LoRA $\alpha = 64$.

In addition to the above configurations, IB-FT introduces two extra hyperparameters in Eq. (IB-FT): the IB regularization strengths α and β, which balance the trade-off between compression and prediction. We search over $\alpha \in (0.01, 1)$ and $\beta \in (0.001, 0.1)$. On the OriGen dataset, we set $\alpha = 0.1$ and $\beta = 0.02$ for both models, while on the Evol-CodeAlpaca-V1 dataset we use $\alpha = 0.1$ and $\beta = 0.01$.

C.2 Evaluation Metric

In addition to the standard Pass@k metric, we adopt a stricter variant Pass@$k^{(m)}$ (as introduced in Fig. 2). Under Pass@$k^{(m)}$, a problem is counted as solved only if at least m out of the k generated samples pass the unit tests (so Pass@$k^{(1)}$ equals the conventional Pass@k). By requiring $m > 1$, Pass@$k^{(m)}$ penalizes lucky single-sample successes and provides a more reliable measure of a model's consistent generation quality and robustness. To evaluate this metric, we need to generate a pool of n candidate outputs for each problem (with $n \geq k$). Among these n outputs, the parameters k and m are then defined relative to this pool: k is the subset size under evaluation, and m is the minimum number of successful outputs required within that subset. In our experiments, we fix $n = 10$.

D Additional Experiment Results

D.1 Performance of Fine-tuning on Evol-CodeAlpaca-V1

We also evaluate Llama-3-8B and DeepSeek-Coder-7B-v1.5 on Evol-CodeAlpaca-V1, comparing conventional fine-tuning (FT), IB-FT, and the base model before fine-tuning. Evaluation is carried out on the HumanEval, using both the standard Pass@k metric ($k \in 1, 5, 10$) and the more demanding Pass@$10^{(m)}$ criterion (with $k = 10$, $m \in 2, 5, 10$).

As **Table A1** shows, IB-FT consistently provides the strongest results across both models, with particularly notable improvements at $k = 1$. For instance, on Llama-3-8B, IB-FT achieves 61.60% for Pass@1 compared to 56.70% for FT, while on DeepSeek-Coder-7B-v1.5 the gains are 54.57% versus 51.28%. Moreover, under the strict Pass@$10^{(m)}$ setting, IB-FT demonstrates substantially higher robustness, reaching 37.20% at $m = 10$ on Llama-3-8B, which still provides a clear improvement over FT's 30.49%. These results highlight that IB-FT not only enhances top-1 accuracy but also yields more consistent and reproducible improvements under demanding multi-sample criteria, underscoring its advantage over conventional fine-tuning.

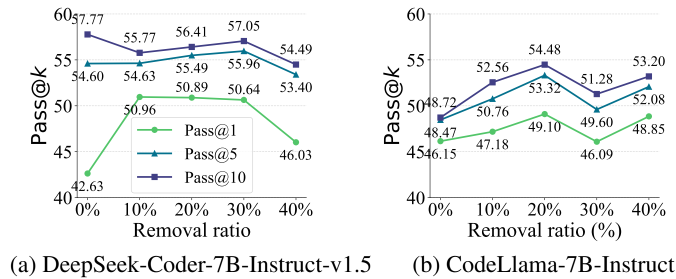
Table A1: Performance overview for Llama-3-8B and DeepSeek-Coder-7B-v1.5 fine-tuned on Evol-CodeAlpaca-V1 using IB-FT versus conventional fine-tuning (FT). Other metrics and table format follow those in Table 1.

Methods	HumanEval (%)					
	Pass@k ↑			Pass@$10^{(m)}$ ↑		
	$k=1$	$k=5$	$k=10$	$m=2$	$m=5$	$m=10$
Llama-3-8B						
Base	29.09	41.22	46.95	37.80	28.66	17.07
+ FT	56.70	74.16	79.27	73.17	62.80	30.49
+ IB-FT	**61.60**	**75.44**	**79.88**	**73.78**	**65.24**	**37.20**
DeepSeek-Coder-7B-v1.5						
Base	44.33	56.89	62.20	54.88	45.12	30.49
+ FT	51.28	64.10	64.10	63.46	50.00	32.05
+ IB-FT	**54.57**	**67.30**	**70.73**	**67.07**	**54.88**	**39.63**

D.2 Limitation of Pruning Memorized Examples, then Fine-tuning

Though data selection based methods are natural countermeasure to memorization barrier, such as the baseline FT w/ Min-K% shown in Table 1, these kinds of methods fail to fully exploit the available data compared with our proposed IB-FT. Moreover, data selection based methods introduce an additional sensitivity, the removal ratio, which becomes a hyperparameter that must be carefully tuned. Especially whether a removal ratio is appropriate can only be determined after running fine-tuning and evaluation, and the optimal ratio varies substantially across models.

In **Fig. A1** we examine the baseline FT w/ Min-K% on two base models (DeepSeek-Coder-7B-Instruct-v1.5 and CodeLlama-7B-Instruct) by removing 10%–40% of the most-memorized examples and reporting Pass@k for $k \in \{1, 5, 10\}$. The results reveal two sensitivity dimensions. First, the optimal removal ratio differs across models (*e.g.*, DeepSeek-Coder-7B-Instruct-v1.5 peaks at 10% for Pass@1 while CodeLlama-7B-Instruct peaks near 20%). Second, the optimal ratio varies with the metric even for the same model (*e.g.*, DeepSeek-Coder-7B-Instruct-v1.5's Pass@1 peaks at 10% whereas Pass@5 peaks at 30%). As shown, there is no universal pruning rate: removal is model- and metric-dependent. By contrast, our proposal avoids fragile data pruning and can be compatible with memorized examples during fine-tuning.



(a) DeepSeek-Coder-7B-Instruct-v1.5 (b) CodeLlama-7B-Instruct

Figure A1: Performance of fine-tuning with different data-removal ratios on OriGen, evaluated on the VerilogEval (Eval-Human) subset. Fine-tuning is applied to the base model (a) DeepSeek-Coder-7B-Instruct-v1.5 and (b) CodeLlama-7B-Instruct, and the performance is assessed using Pass@k ($k \in \{1, 5, 10\}$).