

XXLTRAFFIC: EXPANDING AND EXTREMELY LONG TRAFFIC FORECASTING BEYOND TEST ADAPTATION

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Paper under double-blind review

ABSTRACT

Traffic forecasting is crucial for smart cities and intelligent transportation initiatives, where deep learning has made significant progress in modeling complex spatio-temporal patterns in recent years. However, current public datasets have limitations in reflecting the distribution shift nature of real-world scenarios, characterized by continuously evolving infrastructures, varying temporal distributions, and long temporal gaps due to sensor downtimes or changes in traffic patterns. These limitations inevitably restrict the practical applicability of existing traffic forecasting datasets. To bridge this gap, we present XXLTraffic, **largest available public traffic dataset with the longest timespan collected from Los Angeles, USA, and New South Wales, Australia**, curated to support research in extremely long forecasting beyond test adaptation. Our benchmark includes both typical time-series forecasting settings with hourly and daily aggregated data and novel configurations that introduce gaps and down-sample the training size to better simulate practical constraints. We anticipate the new XXLTraffic will provide a fresh perspective for the time-series and traffic forecasting communities. It would also offer a robust platform for developing and evaluating models designed to tackle the extremely long forecasting problems beyond test adaptation. Our dataset supplements existing spatio-temporal data resources and leads to new research directions in this domain.

1 INTRODUCTION

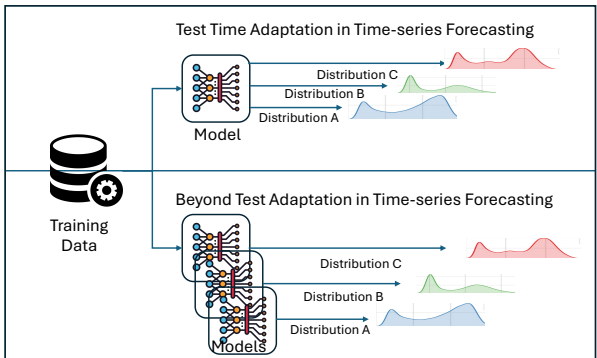
Rapid global population growth and vehicle proliferation have intensified urban traffic congestion. As cities expand and personal transportation reliance grows, strain on road networks leads to longer commutes, higher fuel consumption, and increased emissions. Accurate traffic prediction is vital for intelligent transportation systems, informing strategies to mitigate congestion and enhance mobility through improved route planning and urban development. Effective forecasting requires capturing long-term spatio-temporal relationships in traffic data. Long-term analysis provides context for anomalies in short-term patterns and reveals trends influenced by population cycles, seasonal shifts, and yearly vehicle usage changes. These insights are crucial for developing robust models that adapt to evolving urban traffic dynamics due to demographic and vehicular changes.

In recent years, significant work has focused on both short-term and long-term traffic flow prediction. Deep learning techniques, including Graph Neural Networks (GNNs), have been employed to extract spatial relationships within traffic networks Jin et al. (2023), while Transformer-based architectures have been utilized to capture temporal dependencies over various timescales Shao et al. (2023a). Although these methods have shown promising results, they often rely on datasets that do not fully encapsulate the complexities introduced by rapid population growth and the surging number of vehicles, thus limiting their applicability to real-world scenarios.

There is an emerging need in intelligent transportation systems to design predictive models that extend beyond test adaptation, effectively generalizing to real-world conditions that evolve over time. It is important to note that our concept of 'beyond test adaptation' differs from 'test time adaptation' Guo et al. (2024) as illustrated in Fig 1 that shows the distinctions between them. This shift necessitates models that can handle the multifaceted impacts of demographic changes and vehicle proliferation without relying solely on adaptation to specific test datasets. To achieve this, it is essential to utilize

054 datasets that accurately represent these evolving conditions over extremely long periods, capturing
 055 the intricate patterns influenced by population and vehicular growth.
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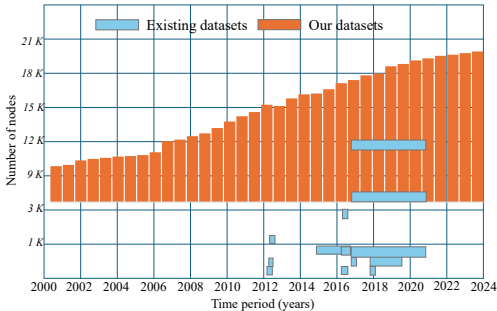
057 Motivated by this need, we introduce
 058 XXLTraffic, a dataset and framework
 059 that expands traffic forecasting beyond test adaptation. By incorporating extremely long-term data, XXL-
 060 Traffic better reflects real-world scenarios where traffic patterns are continually affected not just by infrastruc-
 061 ture changes like highway construction, but also by shifts in distribution
 062 due to factors like population growth and increasing vehicle numbers. We
 063 will discuss existing datasets and the specific challenges encountered in estab-
 064 lishing XXLTraffic, highlighting how it advances the field by providing
 065 a more realistic and comprehensive dataset. This facilitates the develop-
 066 ment of models capable of adapting to the complexities of real-world traffic
 067 dynamics without the limitations of
 068 traditional test adaptation approaches.
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070 Figure 1: Test-time adaptation in time-series forecasting
 071 involves training a single model to fit different test domains,
 072 horizons, or gaps. The figure above illustrates this using a
 073 gap example. In contrast, the figure below shows our 'beyond
 074 test adaptation' where we train separate models for various
 075 gap settings.
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077
 078 1.1 RECENT ADVANCES IN EXPANDING TRAFFIC DATASETS
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080 Real-world traffic scenarios necessitate more
 081 complex prediction settings, involving extended
 082 temporal horizons or broader spatial coverage
 083 in experiments. In the temporal domain, new
 084 settings are typically proposed based on previ-
 085 ously published work rather than introducing
 086 new datasets: Shao et al. (2023b) and Jia et al.
 087 (2024) expanded input and output lengths up
 088 to four times on existing datasets. From a spa-
 089 tial perspective, Chen et al. (2021) published a
 090 dataset with nodes growing annually and pro-
 091 vided an evolving network to support new node
 092 predictions. Wang et al. (2023a) proposed a con-
 093 tinual learning framework with pattern expan-
 094 sion mechanisms based on Chen et al. (2021).
 095 Additionally, SCPT Prabowo et al. (2024) and
 096 Large-ST Liu et al. (2024a) offered larger-scale
 097 spatial node datasets to support subsequent re-
 098 searchers. Recent work has explored longer tem-
 099 poral step experimental settings and released
 100 traffic datasets spanning up to five years and thousands of nodes. However, in specific scenarios,
 101 such as future traffic prediction for highway planning, these data and experimental settings fall short.
 102 As shown in Figure 2, most existing datasets have limitations in temporal span, which inspired
 103 us to develop a dataset for expanding and extremely long traffic forecasting. This need for traffic
 104 forecasting beyond test adaptation is crucial in various real-world scenarios. For instance, urban
 105 planning and infrastructure investment decisions rely heavily on accurate long-term traffic predictions
 106 to ensure that developments meet future transportation demands. Commercial real estate site selection
 107 and development also depend on knowing future traffic volumes years in advance to optimize
 location choices and investment strategies. Additionally, governments can formulate more effective
 environmental policies based on long-term traffic forecasts, such as implementing traffic restrictions
 or promoting electric vehicles to reduce emissions. These applications highlight the importance of



108 Figure 2: Our dataset is evolving and longer than
 109 existing datasets. Existing datasets are either limited by short temporal spans or insufficient spatial
 110 nodes. In contrast, our dataset features an evolving
 111 growth of spatial nodes and spans over 20 years.

developing predictive models capable of accurately forecasting traffic patterns over extended periods, facilitating strategic decision-making across multiple sectors. As the temporal span extends, urban infrastructure development and road construction can lead to shifts in traffic patterns, resulting in an evolving domain shift. This observation motivated us to provide an expanding and extremely long traffic dataset. Additionally, the combination of these factors enables the extraction of more temporal patterns from extremely long sequences, allowing for the possibility of longer input sequences.

1.2 CHALLENGES

The ultra-dynamic challenge encompasses three key aspects: (1) Continuously evolving states of the underlying spatio-temporal infrastructures, characterized by an expanding number of nodes over the years. This continuous growth introduces complexity as the infrastructure adapts and expands. (2) Evolving temporal distributions over an extremely long observation period, which is crucial for extremely long forecasting beyond different non-contiguous train-test splits. This requires models to adapt to changes in patterns and trends over extensive temporal spans.

We have constructed a traffic dataset with an exceptionally long temporal span and broader regional coverage, providing aggregated data and benchmarking, as well as a benchmarking setup considering extremely long prediction scenarios for future exploration:

- We propose XXLTraffic, a dataset that spans up to 23 years and exhibits evolutionary growth. It includes data from 9 regions, with detailed data collection and processing procedures for expansion and transformation. This dataset supports both temporally scalable and spatially scalable challenges in traffic prediction.
- We present an experimental setup with temporal gaps for extremely long prediction beyond test adaptation and provide a benchmark of aggregated versions of hourly and daily datasets.
- We provide the exploration of input features through evolving temporal distributions over an extremely long observation period. Additionally, our datasets support zero-shot forecasting for new sensors.

2 PRELIMINARIES

In this section, we will define traffic data and traffic prediction tasks.

Definition 1. Traffic datasets: Traffic data primarily consists of vehicle flow detection data collected by sensors distributed across various locations in the traffic network. It is generally represented by $X_i \in \mathbb{R}^{N \times T \times C}$, where T denotes the time steps, N denotes the number of sensors, and C denotes the number of features.

Definition 2. Short-term traffic prediction: Short-term traffic prediction primarily focuses on forecasting traffic speed or flow within the next hour. As shown in Equation 1, the input length α and output length β are generally set to 12 steps.

$$[X_{t-(\alpha-1)}, \dots, X_{t-1}, X_t] \rightarrow [X_{t+1}, X_{t+2}, \dots, X_{t+\beta}], \quad (1)$$

Definition 3. Long-term multivariate prediction: This task mainly focuses on long-sequence time series prediction, which includes the traffic dataset. As shown Table 1, the sequence length can reach up to 2880 steps.

Definition 4. Extremely Long Prediction with Gaps: Based on Equation 1, the observation and prediction are not adjacent but are instead separated by a gap period g , as shown in the following formula.

$$[X_{t-(\alpha-1)}, \dots, X_{t-1}, X_t] \rightarrow [X_{t+g+1}, X_{t+g+2}, \dots, X_{t+g+\beta}], \quad (2)$$

3 GAPS AND COMPARISON WITH EXISTING TRAFFIC DATASETS

As shown in Table 1, existing traffic prediction work can easily be divided into short-term and long-term settings. The short-term setting originated from the STGCNYu et al. (2018) work, while

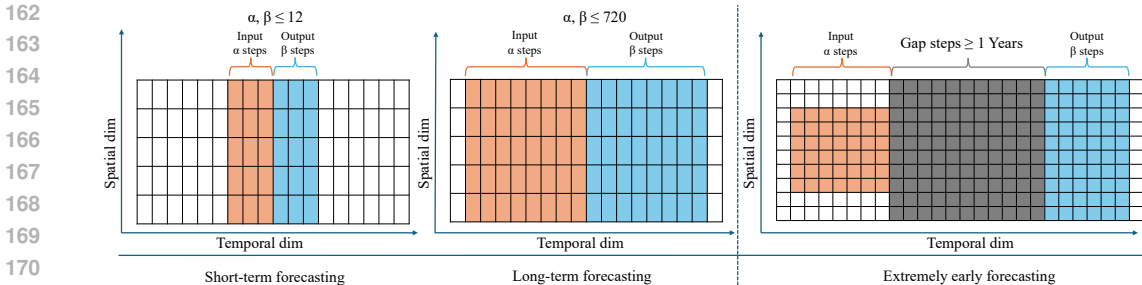


Figure 3: Our expanding and extremely long prediction addresses the existing limitations in both short-term and long-term predictions.

the long-term setting was first introduced by LSTNet Lai et al. (2018) and subsequently established as a widely adopted experimental framework by Informer Zhou et al. (2021). In recent years, short-term prediction typically has a maximum step length of 12 steps, while long-term prediction reaches up to 720 steps. However, works such as Witran Jia et al. (2024) and DAN Li et al. (2024) recognized the need for even longer step predictions in practical applications, extending the length to a maximum of four times the typical length. Despite the differences in step lengths, their observed and predicted values are concatenated tightly together, as shown in Equation 1. To accommodate complex real-world scenarios, such as highway route planning predictions, it is necessary to introduce a gap of several years between observation and prediction. Typically, existing datasets lack the temporal coverage required to support gaps exceeding one year. At the same time, predicting several years in advance also implies the need to forecast traffic for sensors at new locations, taking into account the evolving nature of the road network. Even when such coverage is available, works like Wang et al. (2023a) and Chen et al. (2021) utilize evolving datasets but do not provide sufficient data to train models for extended durations. To overcome these gaps, our Expanding and Extremely Long Traffic Dataset robustly supports these complex scenarios.

Table 1: Summary of recent short-term traffic forecasting and long-term multivariate forecasting

Datasets	Model	Series Length
Short-term	STGCN (Yu et al., 2018)	{3,6,9,12}
	DCRNN (Li et al., 2018), GWN (Wu et al., 2019), BTF (Chen & Sun, 2021), DMSTGCN (Han et al., 2021), GTS (Shang et al., 2021), STGODE (Fang et al., 2021), PM-MemNet (Lee et al., 2021), STAEFormer (Liu et al., 2023)	{3,6,12}
	AGCRN (Bai et al., 2020), STSGCN (Song et al., 2020), DSTAGNN Lan et al. (2022), D2STGNN (Shao et al., 2022), DyHSL (Zhao et al., 2023), PDFormer (Jiang et al., 2023), MultiSPANS Zou et al. (2024), GMSDR (Liu et al., 2022)	{12}
	MTGNN (Wu et al., 2020b), LSTNet (Lai et al., 2018)	{3,6,12,24}
	ARU (Deshpande & Sarawagi, 2019)	{12,24,48,168,336}
Long-term	LogSparse_Trans (Li et al., 2019)	{24,48,72,96,120,144,168,192}
	AST (Wu et al., 2020a)	{8,24,168,336}
	SSDNet (Lin et al., 2021)	{20,24,30,138}
	Informer (Zhou et al., 2021), Autoformer (Wu et al., 2021), FEDformer (Zhou et al., 2022), Linear (Li et al., 2022), Triformer (Cirstea et al., 2022), Pyraformer (Liu et al., 2021) DSformer (Yu et al., 2023), DeepTime (Woo et al., 2023), DLinear (Zeng et al., 2023)	{24,48,96,192,336,720}
	Witran (Jia et al., 2024)	{168, 336, 720, 1440, 2880}
	DAN (Li et al., 2024)	{288, 672, 1440}

4 THE XXLTRAFFIC DATASETS

4.1 DATA COLLECTION

We obtained the expanding and extremely long traffic sensor data from the California Department of Transportation (CalTrans) Performance Measurement System¹ (PeMS) Chen et al. (2001) and Transport for NSW². PeMS is an online platform that collects traffic data from 19,561 sensors

¹<https://pems.dot.ca.gov/>

²<https://maps.transport.nsw.gov.au/egeomaps/traffic-volumes/index.html#/?z=6>

distributed across California state highways. These sensor locations are divided into nine districts. We downloaded all the raw data for these nine districts from the initial data release up to March 20, 2024. The system automatically generates a daily data file for each district, containing data from all sensors within each district. We have stored the complete raw data files in an open-source repository for quick access, which will be released after the publication. The tfNSW is an open-source data platform provided by Transport for NSW, featuring traffic flow data collected from sensors distributed along major roads throughout the state of New South Wales of Australia. The data is available at a minimum granularity of one hour.

Table 2: Comparison between our XXLTraffic dataset and the existing traffic datasets.

Reference	Dataset	Samples	Nodes	Time Interval	Time Span	Time Period
DCRNN	METR-LA	34,272	207	5 mins	4 months	03/2012 - 06/2012
	PEMS-BAY	52,116	325	5 mins	6 months	01/2017 - 05/2017
LSTNet	Traffic	17,544	862	1 hour	2 years	01/2015 - 12/2016
STGCN	PEMSD7(M)	12,672	228	5 mins	2 months	05/2012 - 06/2012
	PEMSD7(L)	12,672	1026	5 mins	2 months	05/2012 - 06/2012
ASTGCN	PEMSD4-I	17,002	228	5 mins	2 months	01/2018 - 02/2018
	PEMSD8-I	17,856	1,979	5 mins	2 months	07/2016 - 08/2016
STSGCN	PEMS03	26,208	358	5 mins	11 months	01/2018 - 11/2018
	PEMS04	16,992	307	5 mins	2 months	01/2018 - 02/2018
	PEMS07	28,224	883	5 mins	2 months	05/2017 - 06/2017
	PEMS08	17,856	170	5 mins	2 months	07/2016 - 08/2016
Large-ST	CA	525,888	8,600	5 mins	5 years	01/2017 - 12/2021
	GLA	525,888	3,834	5 mins	5 years	01/2017 - 12/2021
	GBA	525,888	2,352	5 mins	5 years	01/2017 - 12/2021
	SD	525,888	716	5 mins	5 years	01/2017 - 12/2021
Ours	Full_PEMS03	2,419,488	1809	5 mins	23.00 years	03/2001 - 03/2024
	Full_PEMS04	2,287,872	4,089	5 mins	21.75 years	06/2002 - 03/2024
	Full_PEMS05	1,998,720	573	5 mins	19.00 years	03/2005 - 03/2024
	Full_PEMS06	1,945,728	705	5 mins	18.50 years	09/2005 - 03/2024
	Full_PEMS07	2,287,872	4,888	5 mins	21.75 years	06/2002 - 03/2024
	Full_PEMS08	2,419,488	2,059	5 mins	23.00 years	03/2001 - 03/2024
	Full_PEMS10	1,998,720	1,378	5 mins	19.00 years	03/2005 - 03/2024
	Full_PEMS11	2,261,376	1,440	5 mins	21.50 years	09/2002 - 03/2024
	Full_PEMS12	2,331,360	2,587	5 mins	22.16 years	01/2002 - 03/2024
	tfNSW	100,056	27	60 mins	11.42 years	01/2013 - 05/2024

As illustrated in Table 2, our collected dataset significantly exceeds existing datasets in terms of both temporal coverage and the number of spatial nodes. The dataset sample will be available on: <https://anonymous.4open.science/r/XXLTraffic-F281>, which includes the raw data, sensor meta-data (containing sensor IDs, geographical coordinates, associated road information, etc.), the data processing pipeline code, and the processed datasets.

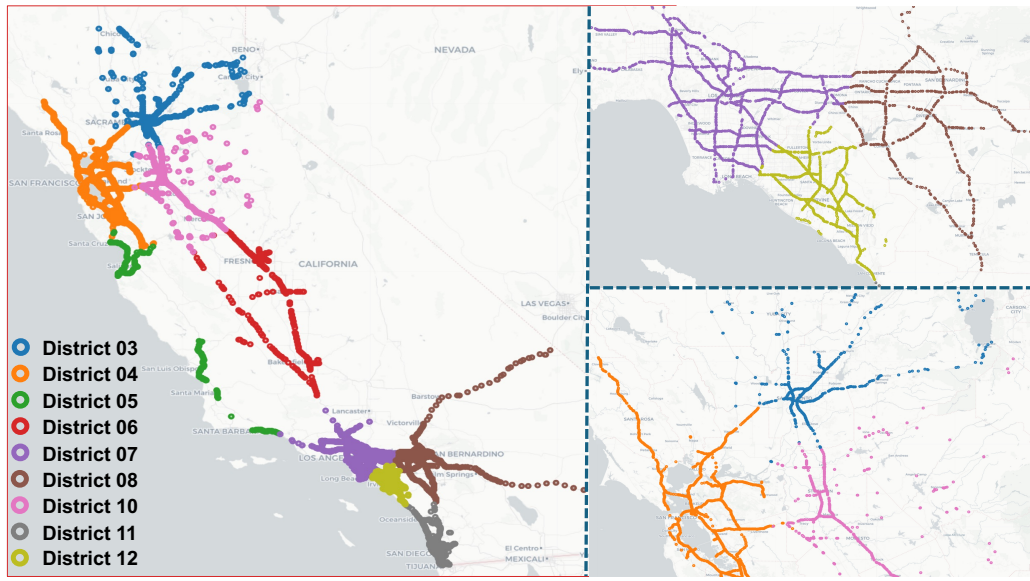
4.2 DATA PREPROCESSING

Based on the 23 years of raw data we collected, we conducted rigorous data filtering and aggregation. The PeMS system has continuously evolved, expanding from a few sensors in 2001 to over 4,000 sensors in some districts today. To support our setting of extremely long forecasting with gaps, we selected a subset of sensors that were installed in the early stages and have consistently collected new data up to the present (named `gap` dataset), which is shown in the Appendix. This extensive `gap` dataset effectively underpins the extremely long forecasting with gaps demonstrated in Figure 3. Utilizing the `gap` dataset, we performed both `hourly` and `daily` aggregations, which will be employed for `gap-free` long-term forecasting benchmarking. We will provide standard long-term forecasting benchmarks for both the `hourly` and `daily` datasets.

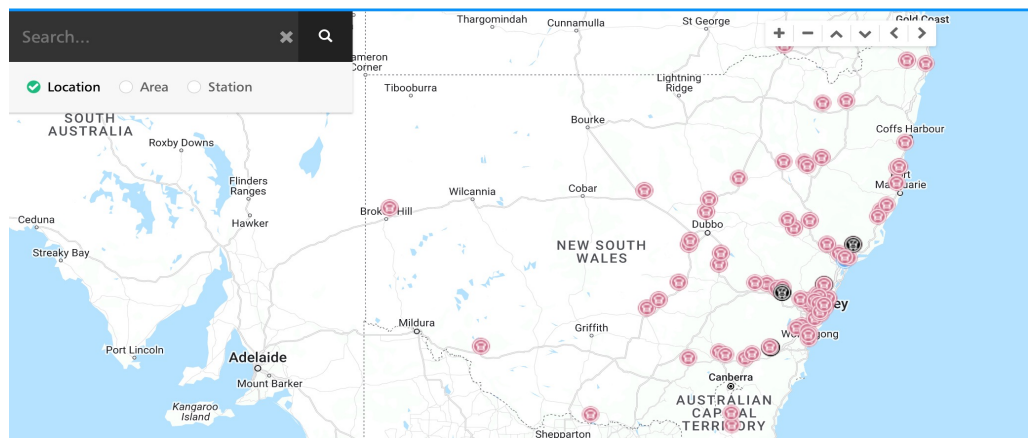
4.3 DATA OVERVIEW

The XXLTraffic dataset is distributed across highways in the state of California, as illustrated in the Figure 4a. The nine colors represent nine districts. From Figures 4b, 4c, and 4d, we can

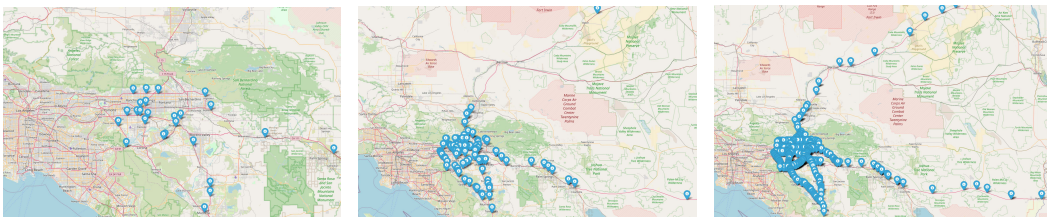
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NSW Transport for NSW Traffic Volume Viewer



(a) Sensor distribution in PeMS and tfNSW



(b) District 08 in 2005

(c) District 08 in 2015

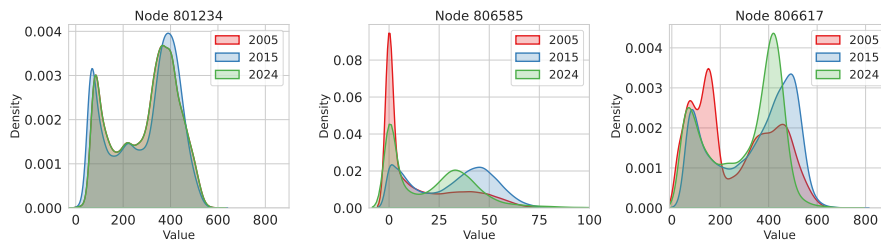
(d) District 08 in 2024

Figure 4: XXLTraffic dataset overview and its evolving development. This figure provides a global overview and two local overviews, showcasing the diversity of sensor distribution. The lower parts highlights a selected region to illustrate the growth and changes in traffic sensors over time.

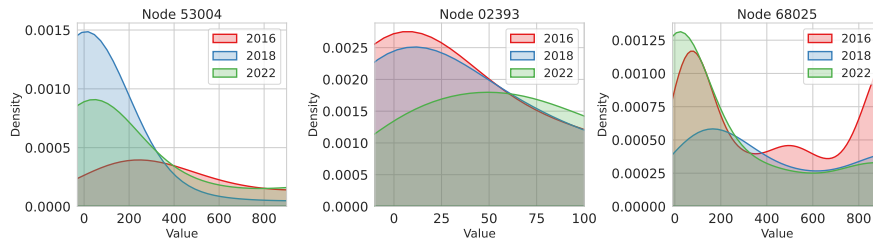
clearly observe the evolutionary growth of the sensors. The sensors are extensively distributed across both urban and suburban areas, offering diverse modalities. Additionally, the sensors are densely interconnected, enabling the formation of a high-quality traffic graph dataset.

It is evident that sensors at the same location may collect completely different distributions over the course of urban evolution. As shown in Figure 5, some sensors have maintained the same distribution

from 2005 to 2024, while others have experienced significant changes in distribution. The temporal changes causing domain shifts present a significant challenge for our extremely long forecasting.



(a) distribution of District 8 in PeMS.



(b) distribution of tfNSW.

Figure 5: Sensor traffic status distribution of District 8 in PeMS from 2005 to 2024 in 5a and from 2016 to 2022 in NSW in 5b. While some sensors exhibit minimal changes, others show significant distribution differences, regardless of whether they are in low-traffic or high-traffic areas. This presents substantial challenges for extremely long forecasting with long gaps.

4.4 XXLTRAFFIC LICENCE

The XXLTraffic dataset is licensed under CC BY-NC 4.0 International: <https://creativecommons.org/licenses/by-nc/4.0>. Our code is available under the MIT License: <https://opensource.org/licenses/MIT>. Please check the official repositories for the licenses of any specific baseline methods used in our codebase.

5 EXPERIMENTS

We conducted experiments for both extremely long forecasting with gaps using `gap` dataset and conventional long-term forecasting using `hourly` dataset and `daily` dataset. Additionally, referring to the definition in Figure 3, we set the gap parameter g as 1 year, 1.5 years, and 2 years for the `gap` dataset, as illustrated by Figure 6.

5.1 DATASETS

We conducted experiments on all proposed sub-datasets. To maintain consistency with previous state-of-the-art benchmarks, we selected districts 03, 04, and 08 (widely recognized as PEMS03/04/08) for the experiments using the `gap`, and districts 03, 04, 07 and 08 for hourly, and daily experiments. Results for other datasets are presented in Appendix. All sub-datasets were divided into training, validation, and test sets using a 6:2:2 ratio. For the `gap` dataset, due to the extensive span of up to 20 years resulting in a large sample size, we fixed a seed during data preprocessing to select 10% of the dataset for training and testing to quickly demonstrate our results. The details of the datasets used in our benchmarking is in Appendix A.1.

5.2 BASELINES

In our comparison experiments, we adopted four popular baselines, including MLP, Transformer, and Mamba architectures. Informer Zhou et al. (2021) introduces an efficient transformer for long

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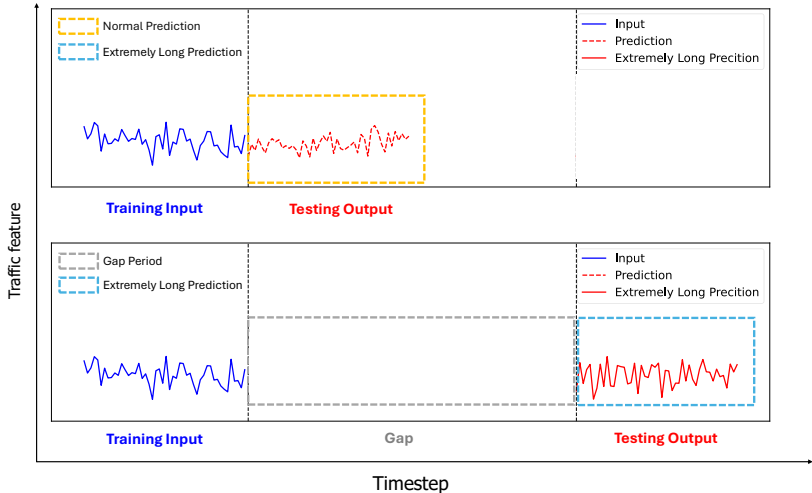


Figure 6: Problem definition. The yellow boxes represent typical predictions, the gray boxes denote gap periods between observation and prediction, and the blue boxes indicate extended predictions.

sequence time-series forecasting using ProbSparse self-attention and self-attention distilling, enabling encoder-decoder architectures to handle long sequences effectively. MICN Wang et al. (2023b) proposes a multi-scale context network that models both local and global contexts for long-term time series forecasting, capturing patterns across different temporal scales to enhance performance. FEDformer Zhou et al. (2022) introduces a frequency-enhanced decomposed transformer that models time series in both time and frequency domains, improving long-term forecasting by effectively capturing temporal patterns. PatchTST Nie et al. applies transformers to time series by treating them as sequences of patches, enabling effective long-term forecasting through self-attention over patch representations to capture temporal dependencies. Autoformer Wu et al. (2021), an earlier state-of-the-art model, leverages a decomposition architecture and auto-correlation mechanism to enhance efficiency and accuracy in long-term time series forecasting, outperforming traditional Transformer models. iTransformer Liu et al. (2024b) is the latest and most effective Transformer-based model, utilizing attention and feed-forward networks on inverted dimensions, embedding time points into variate tokens. DLinear Zeng et al. (2023) challenges the effectiveness of Transformer models by proposing a simple one-layer linear model that captures temporal relations in an ordered set of continuous points. It employs positional encoding and uses tokens to embed sub-series, preserving some ordering information in Transformers. Lastly, Mamba Gu & Dao (2023), a well-known sequential model from last year, uses a bidirectional Mamba block to extract inter-variate correlations and temporal dependencies. Additionally, we have selected five SOTA baselines Yu et al. (2018); Guo et al. (2019); Wu et al. (2019); Bai et al. (2020); Jiang et al. (2023) from traffic forecasting domain.

5.3 IMPLEMENTATION DETAILS

We adopted the default settings of the Time-Series-Library Wu et al. (2022) to conduct a comprehensive comparison of baselines. We use the results of five random seeds as the average. We used 96 time steps as input and 336 time steps as ground truth. The code was implemented in PyTorch and executed on a V100 GPU with 32GB memory and 384GB RAM, provided by NCI Australia, an NCRIS-enabled capability supported by the Australian Government.

5.4 RESULTS OF EXTREMELY LONG FORECASTING WITH GAPS

We use Mean Squared Error (MSE) and Mean Absolute Error (MAE) metrics to evaluate performance, averaging results across different seeds. It is observed that nearly all results are poor, highlighting the significant challenge posed by domain shifts over time for extremely long forecasting with gaps. These baseline results also indicate that traditional the-state-of-the-art (SOTA) rankings and methodologies

Table 4: Results of ablation study with 4 different input step lengths

DLinear (Input Length)			96		192		336		720	
Metrics			MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE
PEMS03_gap	1-year gap	96	1.500	0.933	1.455	0.912	1.462	0.906	1.392	0.887
		192	1.542	0.945	1.147	0.910	1.457	0.906	1.445	0.906
		336	1.531	0.935	1.447	0.907	1.462	0.906	1.439	0.904

5.5 RESULTS OF HOURLY AND DAILY FORECASTING

We believe that both the hourly and daily datasets are equally significant. Multi-scale, diverse datasets can provide the community with valuable references. We observe that the performance degrades progressively from the hourly to the daily to the gap datasets. Smaller time scales help reduce complexity and uncertainty, thereby improving prediction accuracy. Research has shown that clustering at different scales can enhance model performance Wang et al. (2024). Therefore, our aggregated version of the data will contribute new external features to the community.

Table 5: Comparison in hourly and daily datasets

Methods			Mamba		iTransformer		DLinear		Autoformer	
Metrics			MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE
PEMS03_agg	Hourly	96	0.144	0.222	0.530	0.535	0.159	0.222	0.241	0.346
		192	0.173	0.237	0.215	0.289	0.153	0.208	0.235	0.340
		336	0.158	0.220	0.519	0.527	0.167	0.216	0.260	0.362
	Daily	96	0.754	0.503	0.606	0.419	0.602	0.426	0.771	0.537
		192	0.968	0.604	0.781	0.500	0.794	0.509	0.897	0.577
		336	1.210	0.706	0.967	0.579	0.984	0.584	1.058	0.630
PEMS04_agg	Hourly	96	0.137	0.244	0.240	0.339	0.161	0.245	0.178	0.295
		192	0.132	0.239	0.260	0.361	0.142	0.223	0.175	0.288
		336	0.121	0.216	0.226	0.413	0.145	0.226	0.197	0.316
	Daily	96	0.672	0.499	0.534	0.442	0.507	0.415	0.644	0.506
		192	0.720	0.549	0.634	0.508	0.610	0.483	0.749	0.580
		336	0.795	0.602	0.706	0.555	0.663	0.522	0.728	0.569
PEMS07_agg	Hourly	96	0.212	0.302	0.375	0.425	0.203	0.259	0.307	0.390
		192	0.201	0.288	0.297	0.368	0.182	0.231	0.313	0.391
		336	0.191	0.245	0.126	0.156	0.190	0.241	0.291	0.364
	Daily	96	1.719	0.736	1.426	0.613	1.414	0.606	1.703	0.762
		192	2.005	0.842	1.772	0.730	1.756	0.720	1.903	0.804
		336	2.290	0.949	2.078	0.819	2.051	0.813	2.171	0.884
PEMS08_agg	Hourly	96	0.245	0.287	0.363	0.379	0.253	0.272	0.305	0.377
		192	0.269	0.292	0.341	0.354	0.254	0.259	0.340	0.401
		336	0.283	0.298	0.369	0.369	0.281	0.272	0.452	0.468
	Daily	96	0.870	0.558	0.766	0.486	0.746	0.478	0.913	0.604
		192	1.023	0.635	0.911	0.554	0.906	0.548	1.026	0.648
		336	1.161	0.697	1.024	0.617	1.022	0.602	1.127	0.689

6 PROSPECTS AND CONSTRAINTS

Prospects. Our dataset spans the longest time period among existing datasets, and it is not only the largest spatially, but also evolving in growth. It can continue to update in line with the updates from the PeMS system in the future. It is specifically designed for various complex scenarios, such as those already mentioned, including extremely long forecasting with long gaps, and hourly and daily predictions. Additionally, zero-shot forecasting designed for evolving growth scenarios will also be included in Appendix.

Constraints. The limitations of our dataset are also quite evident. Due to the sheer size of our dataset, it requires more computational resources. However, with the maturation of large language models and foundational models, we believe its large volume will become an advantage, contributing more diverse data to the spatio-temporal large model community.

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A APPENDIX

A.1 DATASET

To support our setting of extremely long forecasting with gaps, we selected a subset installed in the early stages and have consistently collected new data up to the present, which is shown as follows:

Table 6: Overview of Gap, Hourly, and Daily Aggregated Data Based on Processed Raw Data

Datasets(Gap/Hour/Day)	Time Period	Nodes
PEMS03_gap&agg	03/2001 - 03/2024	151
PEMS04_gap&agg	06/2002 - 03/2024	822
PEMS05_gap&agg	03/2012 - 03/2024	103
PEMS06_gap&agg	12/2009 - 03/2024	130
PEMS07_gap&agg	06/2002 - 03/2024	3062
PEMS08_gap&agg	03/2001 - 03/2024	212
PEMS10_gap&agg	06/2007 - 03/2024	107
PEMS11_gap&agg	09/2002 - 03/2024	521
PEMS12_gap&agg	01/2002 - 03/2024	1543
tfNSW	01/2013 - 05/2024	27

A.2 RESULTS

Table 7: Model Training Time Comparison. The training time for all baselines per epoch is measured in seconds.

Baselines	Mamba	iTransformer	DLLinear	Autoformer	Informer	FEDFormer	MICN	PatchTST	STGCN	ASTGCN	GWN	AGCRN	PDFormer
PEMS04_gap1	396.3	1310.2	237.9	1656.7	652.5	900.9	409.8	3649.4	2425.9	7921.9	4110.4	13369.1	8013.9
tfNSW_gap1	13.7	44.1	7.4	148.2	73.3	380.1	101.2	55.3	37.3	228.8	50.4	658.6	47.9

Here we provided the results of District 5,6,10,11,12, as shown in Table 8 and Table 9:

Additionally, we provided the results of naive zero-shot forecasting, as shown in Table 10. The poor performance of this method indicates significant potential for improvement.

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Table 8: Comparison in hourly and daily datasets in District 05,06,10,11,12. The symbol – indicates that the result is an outlier.

Methods		Mamba		iTransformer		DLinear		Autoformer		
Metrics		MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE	
PEMS05_agg	Hourly	96	0.121	0.205	0.226	0.324	0.148	0.236	0.155	0.272
		192	0.118	0.197	0.214	0.312	0.132	0.216	0.159	0.268
		336	0.115	0.194	0.220	0.318	0.134	0.217	0.167	0.274
	Daily	96	0.655	0.511	0.654	0.510	0.607	0.477	0.650	0.522
		192	0.798	0.598	0.775	0.576	0.698	0.535	0.643	0.512
		336	0.907	0.614	0.787	0.582	0.745	0.556	0.764	0.578
PEMS06_agg	Hourly	96	0.142	0.234	0.269	0.336	0.188	0.254	0.164	0.271
		192	0.138	0.218	0.256	0.326	0.166	0.227	0.188	0.291
		336	0.137	0.207	0.226	0.413	0.171	0.227	0.197	0.316
	Daily	96	0.516	0.419	0.414	0.389	0.405	0.340	0.518	0.437
		192	0.642	0.485	0.543	0.468	0.510	0.395	0.580	0.460
		336	0.734	0.519	0.675	0.492	0.596	0.437	0.658	0.481
PEMS10_agg	Hourly	96	0.213	0.256	0.391	0.413	0.272	0.309	0.260	0.346
		192	0.205	0.250	0.387	0.412	0.246	0.277	0.380	0.417
		336	0.211	0.255	0.394	0.413	0.258	0.281	0.329	0.386
	Daily	96	1.161	0.671	0.926	0.513	0.951	0.567	1.079	0.647
		192	1.459	0.784	1.414	0.730	1.228	0.681	1.429	0.786
		336	1.715	0.855	1.478	0.768	1.451	0.751	1.552	0.817
PEMS11_agg	Hourly	96	-	0.472	-	0.538	-	0.306	-	0.800
		192	-	0.470	-	0.443	-	0.291	-	0.742
		336	-	0.487	-	0.435	-	0.300	-	0.745
	Daily	96	-	-	-	-	-	-	-	-
		192	-	-	-	-	-	-	-	-
		336	-	-	-	-	-	-	-	-
PEMS12_agg	Hourly	96	0.145	0.237	0.083	0.157	0.174	0.242	0.188	0.287
		192	0.142	0.226	0.091	0.159	0.154	0.216	0.196	0.289
		336	0.146	0.217	0.104	0.170	0.162	0.219	0.209	0.298
	Daily	96	1.373	0.621	1.456	0.622	1.052	0.510	1.348	0.649
		192	1.722	0.726	1.675	0.678	1.403	0.611	1.548	0.686
		336	2.066	0.823	1.984	0.641	1.654	0.675	1.801	0.746

Table 9: Comparison in gap dataset in District 05,06,07,10,11,12. The bold text indicates the best.

Methods			Mamba		iTransformer		DLinear		Autoformer	
Metrics			MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE
PEMS05_gap	1-year gap	96	2.079	1.209	1.945	1.164	1.291	0.916	1.065	0.796
		192	2.132	1.256	1.984	1.185	1.750	1.099	1.063	0.809
		336	2.377	1.340	2.067	1.234	1.894	1.144	1.135	0.827
	1.5-year gap	96	1.852	1.122	1.879	1.078	1.683	1.054	1.060	0.785
		192	1.929	1.182	1.593	1.032	1.633	1.045	0.912	0.712
		336	2.370	1.313	2.214	1.071	0.794	1.184	1.345	0.882
	2-year gap	96	1.868	1.106	1.580	0.969	1.602	1.018	0.828	0.672
		192	2.219	1.274	1.481	0.958	1.589	1.027	1.018	0.772
		336	2.695	1.212	2.207	1.201	1.922	1.139	1.186	0.839
PEMS06_gap	1-year gap	96	1.806	1.066	0.875	0.692	1.173	0.837	1.216	0.859
		192	1.928	1.112	1.227	0.848	1.410	0.942	0.961	0.751
		336	2.181	1.212	1.594	1.003	1.501	0.976	0.992	0.769
	1.5-year gap	96	1.549	0.997	1.331	0.891	1.484	0.963	0.885	0.710
		192	1.746	1.054	1.077	0.778	1.353	0.920	1.010	0.768
		336	1.605	1.018	1.500	0.961	1.587	1.011	0.955	0.739
	2-year gap	96	1.226	0.851	1.864	1.106	1.691	1.033	1.013	0.768
		192	0.949	0.720	1.343	0.879	1.259	0.858	0.853	0.691
		336	0.945	0.710	1.550	0.970	1.415	0.934	0.955	0.739
PEMS07_gap	1-year gap	96	1.719	1.006	1.756	1.024	1.680	1.024	1.215	0.867
		192	1.637	0.996	1.816	1.061	1.776	1.043	1.202	0.852
		336	1.637	0.991	1.784	1.028	1.774	1.034	1.098	0.774
	1.5-year gap	96	1.571	0.972	1.705	1.016	1.585	0.987	1.184	0.844
		192	1.578	0.982	1.657	1.004	1.624	0.996	1.088	0.800
		336	1.818	1.127	1.712	1.028	1.668	1.036	0.991	0.729
	2-year gap	96	5.411	1.319	2.055	1.149	1.746	1.048	1.099	0.802
		192	12.620	1.370	2.006	1.128	1.705	1.002	1.284	0.875
		336	9.614	1.378	1.812	1.057	1.605	0.968	0.972	0.734
PEMS10_gap	1-year gap	96	2.310	1.233	0.882	0.698	1.466	0.963	1.208	0.865
		192	2.878	1.396	1.606	0.993	1.834	1.106	1.152	0.860
		336	2.584	1.327	1.413	0.825	1.887	1.121	1.130	0.830
	1.5-year gap	96	2.181	1.206	1.812	1.052	1.765	1.057	1.368	0.913
		192	2.525	1.318	1.645	0.986	1.791	1.069	1.151	0.828
		336	2.488	1.310	2.051	1.134	1.976	1.139	1.111	0.809
	2-year gap	96	1.165	0.822	2.772	1.383	1.977	1.119	1.188	0.845
		192	1.082	0.792	1.974	1.084	1.490	0.932	0.971	0.751
		336	1.021	0.764	2.157	1.168	1.619	0.989	1.096	0.809
PEMS11_gap	1-year gap	96	5.199	0.891	5.417	0.997	5.276	0.936	4.930	0.854
		192	5.300	0.920	5.504	1.029	5.393	0.974	5.114	0.867
		336	5.251	0.901	5.410	0.985	5.364	0.955	4.830	0.849
	1.5-year gap	96	5.871	0.968	6.045	1.296	5.914	1.224	5.691	0.878
		192	5.968	1.012	6.121	1.314	5.993	1.229	5.792	0.884
		336	6.167	1.074	6.214	1.326	6.025	1.299	5.947	0.967
	2-year gap	96	5.914	0.996	6.136	1.318	5.945	1.243	5.761	0.978
		192	6.541	1.043	6.213	1.327	6.014	1.289	6.245	1.001
		336	6.541	1.086	6.221	1.332	6.024	1.300	6.268	1.024
PEMS12_gap	1-year gap	96	1.751	1.025	1.624	1.002	1.611	1.005	1.060	0.789
		192	1.726	1.024	1.424	0.929	1.537	0.972	1.150	0.840
		336	1.751	1.029	1.672	1.015	1.683	1.017	0.889	0.719
	1.5-year gap	96	1.554	0.967	1.479	0.921	1.468	0.910	0.954	0.875
		192	1.401	0.898	1.314	0.867	1.301	0.862	0.943	0.869
		336	1.417	0.906	1.322	0.869	1.298	0.859	0.921	0.846
	2-year gap	96	0.956	0.704	0.876	0.671	0.872	0.664	0.846	0.659
		192	0.846	0.656	0.813	0.653	0.806	0.649	0.785	0.628
		336	0.814	0.628	0.789	0.631	0.776	0.624	0.754	0.617

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Table 10: Results of zero shot forecasting in PEMS03. In this study, we utilized the inputs from 151 existing nodes in PEMS03 to predict 52 new nodes, resulting in a test set comprising a total of 203 nodes.

Datasets		96		192		336	
Metrics		MSE	MAE	MSE	MAE	MSE	MAE
PEMS03_gap	1-year gap	4.658	3.465	4.945	3.648	5.198	3.892
	1.5-year gap	4.891	3.657	5.124	3.842	5.263	3.996
	2-year gap	4.547	3.410	4.895	3.539	5.103	3.758