

ARISE: Automatic Rule Induction and Filtering for Few-shot Text Classification

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Abstract

We propose ARISE, a framework that combines weak supervision, synthetic data generation, and contrastive representation learning for few-shot text classification (FSTC). Weak supervision forms a major novelty in ARISE. Here, we propose an automatic rule induction component to induce rules from syntactic n-grams using inductive generalisation. The rules we induce capture syntactic information, often not explicitly captured by state-of-the-art neural models. While these rules can be noisy, they are used to learn a label aggregation model with data programming. Subsequently, we jointly train the base classifier along with the label aggregation model to update their parameters. Unlike, past work that employ data programming to label unlabeled data points, we use it for verifying synthetically generated labeled data. Finally, we combine synthetic data generation and automatic rule induction, via bootstrapping, to iteratively filter the generated rules and data. Our experiments with nine FSTC datasets over diverse domains, and multilingual experiments on seven languages, show consistent and statistically significant improvements for our proposed approach over other state-of-the-art approaches.

1 Introduction

Few-shot text classification (FSTC) is challenging, especially in tasks with a large, semantically similar and often overlapping label space (Zhang et al., 2022b). Such tasks often find application in diverse domains including task oriented dialogue (intent classification), e-commerce, social networks, scientific literature etc. (Yehudai and Bendel, 2024; Zhang et al., 2021b). Moreover, these tasks are expected to have a unique or highly specialized label space, leading to limited availability of annotated data (Singhal et al., 2023; Vulić et al., 2022). Intuitively, FSTC systems should be designed to extract as much information as possible from the limited

supervision data available for learning. We propose ARISE, a framework that combines automatic rule induction (Pryzant et al., 2022; Bajpai et al., 2024), synthetic data generation, and contrastive representation learning (Zhang et al., 2022b) for FSTC. Moreover, ARISE induces rules in the form of syntactic n-grams that complements information captured in prevalent approaches in FSTC.

FSTC tasks are generally addressed using a diverse set of techniques. These include In-context learning (Brown et al., 2020; Kojima et al., 2022), contrastive representation learning (Vulić et al., 2021), data augmentation and filtering (Lin et al., 2023), transductive learning (Singhal et al., 2023), weak supervision (Pryzant et al., 2022), meta-learning (Mesgar et al., 2023) among others. Several of these works successfully combine one or more of these techniques for FSTC tasks (Singhal et al., 2023; Vulić et al., 2022).

In ARISE, we propose a bootstrapped approach for iterative synthetic data generation and automatic rule induction (Yarowsky, 1995; Varma and Ré, 2018). Moreover, it enables joint training of the induced rules with pre-trained neural models via data programming (Maheshwari et al., 2021; Zhang et al., 2022a). Figure 1 shows various components and the 3-step workflow for ARISE. One, our rule induction step extracts syntactic ngrams from sentence-level dependency parses of the labeled input. Rules are induced from the syntactic n-grams via inductive generalization using least general generalization (LGG Plotkin, 1971; Raza et al., 2014). The induced rules are then filtered using a submodular graph cut-based function (Bajpai et al., 2024; Kothawade et al., 2022). Two, the data augmentation step, involves synthetic generation of data using in-context learning (Liu et al., 2022). Synthetic data are generated along with their labels, which are then validated using the rules. Only those labeled data points that match with the predictions of the rules are filtered. Iteratively, we induce

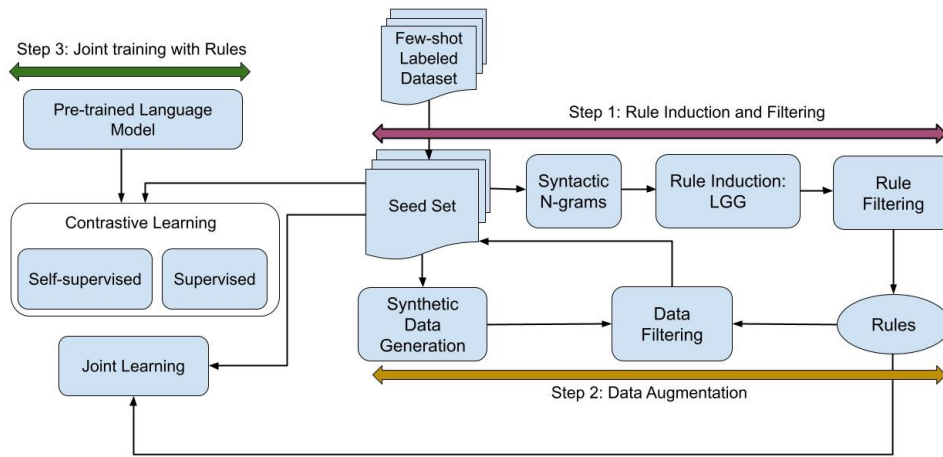


Figure 1: Three-step workflow for ARISE, along with various components in it.

rules from synthetically generated data and use the induced rules for data filtering.

Three, the joint learning step, effectively combines contrastive representation learning, (Chen et al., 2020; Khosla et al., 2020a) supervised fine-tuning, and Data programming (Zhang et al., 2022a) using a joint learning framework (Maheshwari et al., 2021). We perform self-supervised contrastive pretraining (Wu et al., 2020) and supervised contrastive learning (Khosla et al., 2020b; Zhang et al., 2022b) over a standard pre-trained neural classifier. We use the few-shot labeled data, along with the filtered data, for fine tuning the neural classifier. The induced rules enable learning a generative model as a form of weak supervision using data programming. We jointly learn a classifier with the generative model using SPEAR Maheshwari et al. (2021), a data programming framework.

In ARISE, we induce generalized syntactic n-grams as our rules. Our primary aim here is to potentially capture morpho-syntactic information from data, which currently is not captured explicitly by other learning techniques and models employed in ARISE. A classical NLP pipeline typically represents a string at multiple levels of abstraction which includes POS tags, syntactic relations, etc. (Manning et al., 2014). ARISE use higher-order dependency structures as features and generalize over these features using inductive generalization (Popplestone, 1970) to induce the rules as generalized syntactic n-grams.

We perform extensive experiments on the ‘Few-Many’ benchmark (Yehudai and Bendel, 2024), consisting of eight datasets for a diverse set of FSTC tasks. We additionally include experiments for the ‘SciCite’ (Cohan et al., 2019) dataset, a dataset from the scientific literature domain. Further, we perform multilingual experiments on seven languages using the MASSIVE dataset. Our experi-

ments are performed using both 5-shot and 10-shot settings. In all these settings, ARISE outperforms strong competitive models, such as IntenDD (Singhal et al., 2023), Zhang et al. (2022b), and FastFit (Yehudai and Bendel, 2024), with statistically significant improvements.

In section 2, we elaborate on our rule induction approach for inducing generalized syntactic n-grams. In section 3, we elaborate ARISE, a 3-step framework for FSTC. Here, we elaborate our iterative rule and data filtering along with the joint learning setup.

Our major contributions are as follows:

- Our proposed approach yields statistically significant gains in all the experiments we perform, compared to state-of-the-art systems (Yehudai and Bendel, 2024; Singhal et al., 2023; Zhang et al., 2022b). Our best performing model reports a 2.04 % increase in 10-shot and 2.52 % increase in 5-shot settings, compared to the next best model, averaged across all the monolingual tasks.
- Our extensive experiments show that ARISE is generalizable and across multiple domains (as reported above) and multiple languages. We report a 4.4 % increase in performance, compared to the next model, averaged across seven different languages.
- We show that leveraging syntactic information as weak supervision for rule induction, leads to performance improvements compared to surface-level string n-grams as rules. Further, our bootstrapped approach outperforms competitive approaches for filtering augmented data (Lin et al., 2023).

2 Automatic Rule Induction Using Syntactic Tree Generalization

Distributional hypothesis (Firth, 1957) is often realized using vector space models defined over a suitable feature space (Turney and Pantel, 2010). Inputs can be encoded into a feature space of dense contextualized vectors (Peters et al., 2018; Devlin et al., 2019) or into a sparse semantic space consisting of lexical n-grams, syntactic n-grams (Goldberg and Orwant, 2013), higher order dependency features (Koo and Collins, 2010), or even graph motifs (Biemann et al., 2016).

We induce rules that can capture complementary information that is not explicitly captured in pre-trained neural models. Hence, we focus on incorporating structured grammatical information typically used in a traditional NLP pipeline (Manning et al., 2014) such as Part-of-Speech (PoS) and syntactic information. From dependency parses of input sentences, we extract induced subtrees as features. Each such feature is a syntactic n-gram, with the nodes as the words and the edges labeled with the dependency relations. We then induce rules via the inductive generalization of these features, using Least General Generalization (Raza et al., 2014; Thakoor et al., 2018).

For an FSTC task with k labels, we assume the availability of few-shot labeled dataset \mathcal{D} , where $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$, x_i is an input document and $y_i \in \{l_1, l_2, \dots, l_k\}$ is a label. We obtain sentence-level dependency parses for each $x_i \in \mathcal{D}$. A feature space $\mathcal{F}_{t=1}^f$ is defined over higher-order factorization of the dependency parses in \mathcal{D} . Each feature $f_t \in \mathcal{F}$ is an induced subtree of the parses for sentences in \mathcal{D} . Here, a feature covers a set of documents in which that feature occurs at least once.

Rules are generalizations of features. If a generalized rule subsumes multiple features, then it covers a union of all the sets of documents corresponding to those features. The rules we generate belong to $\mathcal{R}_{t=1}^r$, where for every input in $x_i \in \mathcal{D}$ it should either predict a label from $\{1, \dots, k\}$ or should abstain (-1) from making a prediction. Our rules are induced as the least general generalization (LGG) over a set of features (Plotkin, 1970, 1971). A feature can be a rule in itself, i.e. $\mathcal{F} \subseteq \mathcal{R}$. For forming the rules we define two forms of generalizations, structural and linguistic. If rule r_i is an induced subtree of r_j , then we can say that r_i is more general than r_j . Linguistic generalization include, substitution (Raza et al., 2014; Thakoor

et al., 2018), of the nodes containing words with their corresponding stems, and PoS tags (Galitsky and Ilvovsky, 2019).

Figure 2 shows illustrative cases of generalization. Let us consider a corpus from which features (syntactic n-grams) f_1 to f_6 are extracted. Now, r_1 to r_8 shows various generalized rules induced from these features. Rules r_1 to r_7 show linguistic generalization and r_8 shows structural generalization (from r_7). Consider rules r_1, r_4, r_5 and r_7 . These rules contain nodes with a group of words. Similarly, r_6 represents a rule that has a group of PoS tags in one of the nodes. In linguistic generalization, multiple trees are generalized to a single tree by grouping words or PoS that differ in these individual trees. Here, r_1 is a generalisation of f_1 and f_2 . Similarly, r_4 is a generalization of f_2 and f_3 . Currently, we restrict the groupings at a node to be homogeneously typed, i.e. a set can either be that of inflected word forms, stems or of PoS tags, but not a mix of those. Further, the cardinality of such a group is set to an arbitrary upper bound, to avoid trivial generalisations.

2.1 Rule Induction via LGG

We obtain features from dependency parses of the dataset \mathcal{D} . We consider only those subtrees that exactly have one of the six core dependency relations in them (de Marneffe et al., 2014; Nivre et al., 2020). These core dependency relations are direct or indirect object, nominal or clausal subject, clausal complement or open clausal complement. We partition the features into 6 mutually exclusive subsets, one each for each of the core relations.

A complete lattice is constructed out of each partition, by adding a supremum and infimum element to the partition. Here, we add a rule $* \xleftarrow{rel} *$, where ‘rel’ is the core-relation corresponding to the partition. It is the supremum for any element in the partition, as every element in the partition is subsumed by it and covers any document that has the relation present in it. We also define ‘e’ as the infimum and it represents an empty rule that rules out any document in the input. The complete lattice provides a search space of rules over which the partial ordering is provided. Here, any two pair of subtrees have a least general generalization or a least upper bound (Raedt, 2010). In Figure 2, r_1 is the LGG of f_1 and f_2 . r_1 represents all the sentences that either have f_1 or f_2 in their dependency parses. Similarly, r_2 and r_3 are also generalizations

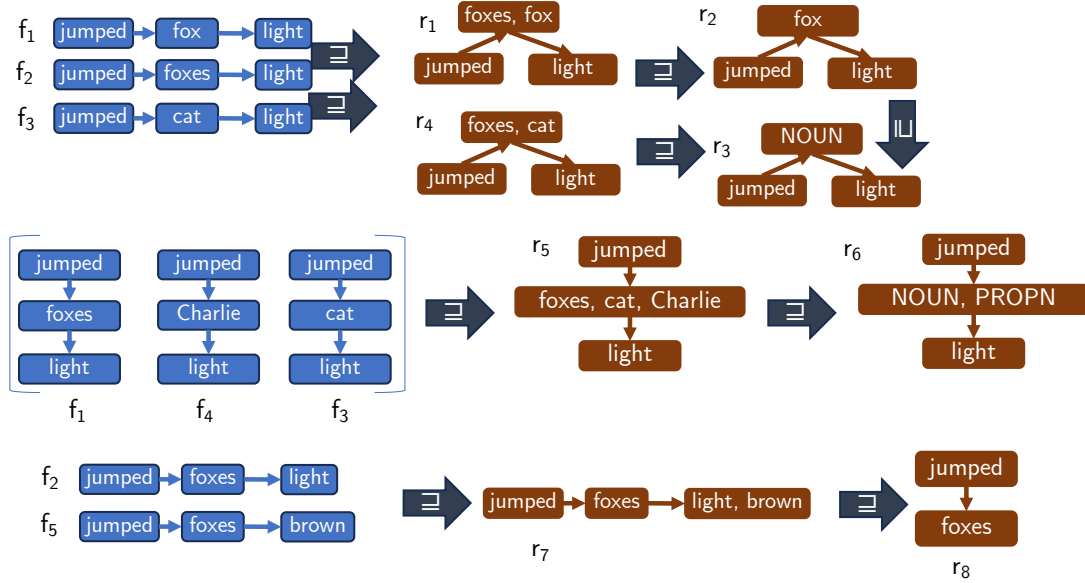


Figure 2: Rule induction from syntactic n-grams via inductive generalization. The symbol ‘ \sqsupseteq ’ denote a generalization operation. Trees labeled from f_1 to f_6 are instances of features, and the nodes of these trees are colored using ■. Similarly, trees labeled from r_1 to r_8 are rules and the nodes of these trees are colored using ■.

of f_1 and f_2 , but not their LGG.

For every rule in the lattice, we compute its label-PMI vector, following Singhal et al. (2023) and Jin et al. (2022). label-PMI vector is a vector of the pointwise mutual information scores of the rule corresponding to each label. From the vector, we consider its maximum score, denoted as L-PMI. The label corresponding to L-PMI is then assigned to the rule. From the lattice, we start bottom up and compute the LGG for every pair of rules. We induce the LGG as a rule, only if it has a higher L-PMI than the individual rules in the pair. The rules thus induced form our candidate set of rules.

3 ARISE Framework

3.1 Rule Induction and Filtering

We induce rules from a set of input documents (§2). These rules can be used as labeling functions in Data Programming, henceforth to be referred to as Programmatic Weak Supervision (PWS), for learning a generative model (Ratner et al., 2017; Zhang et al., 2022a). While the individual rules are expected to be noisy in PWS, the final set of filtered rules needs to be accurate, diverse and high in coverage (Bajpai et al., 2024).

For rule filtering, we use the submodular graph-cut (GC) function (Kothawade et al., 2022), as proposed by Bajpai et al. (2024). Using GC, we select a final set of representative and diverse rules \mathcal{R}_f , from the set of candidate rules \mathcal{R} . For $\mathcal{R}_f \subseteq$

\mathcal{R} , we define the GC function as $f_{GC}(\mathcal{R}_f) = \sum_{r_i \in \mathcal{R}, r_j \in \mathcal{R}_f} s_{ij} - \lambda \sum_{r_i, r_j \in \mathcal{R}_f} s_{ij}$. Here, $\lambda \in [0, 1]$ governs the diversity-representation trade-off, where higher λ implies higher diversity in \mathcal{R}_f . s_{ij} is the similarity score for rule pair r_i and r_j . It is calculated as the weighted sum of the precision, coverage, and agreement between the pair of rules, $s_{ij} = \alpha(r_i) + \alpha(r_j) + w * \beta(\{r_i, r_j\}) + \gamma * \mu(r_i, r_j)$. Here, $\alpha(r_i) = \text{Precision}(r_i)$, $\mu(r_i, r_j)$ is the agreement, calculated as the fraction of instances where both rules agree. $\beta(\{r_i, r_j\})$ is the coverage, calculated as the fraction of instances labeled by at least one of the rules.

Our objective function is $\max_{|\mathcal{R}_f| \leq k} f_{GC}(\mathcal{R}_f)$, where k is a fixed budget (Kothawade et al., 2022). We greedily choose a rule that maximizes the marginal utility $\text{argmax}_{r_i \in \{\mathcal{R} - \mathcal{R}_f\}} f_{GC}(\mathcal{R}_f \cup \{i\}) - f_{GC}(\mathcal{R}_f)$. Please note that (Bajpai et al., 2024) starts from an empty set, while we start with the existing rule set obtained from the previous round of bootstrapping. One round of filtering is completed until the fixed budget k is completed.

3.2 Bootstrapping Rules and Synthetic Data

PWS is typically employed to provide noisy training labels to unlabeled data (Varma and Ré, 2018). In ARISE, we instead use PWS on synthetically generated data for data verification and filtering.

We start our bootstrapping with the few-shot gold labeled data as the seed, as shown in Figure 1.

we synthetically generate new data for each class using the few-shot prompt demonstrations, with the demonstrations retrieved from the seed set. [Zhu et al. \(2023\)](#) observe that PWS systems rely heavily on the quality of gold-labeled data, especially in the validation split. Hence, we use our gold-labeled data as validation data for rule filtering. We perform rule induction (§2) from the synthetically generated data and filter the rules (§3.1) using the gold data as the validation split. The induced rules are then used for learning a generative model via PWS ([Chatterjee et al., 2020](#)). Finally, the seed set is expanded with filtered data, where only those data points that match their generated label with the predicted label from the generative model are filtered. Our validation set is never expanded and is always the gold-labeled data. The seed data set is expanded with newly filtered data after every iteration. Similarly, the rule set is also expanded after every iteration of the bootstrapping process.

Data Augmentation: We use few-shot prompt demonstration to synthetically generate new labeled sentences using LLMs. For each label, we sample k instances each of positive and negative samples from the seed set and then use it for generating new data samples ([Smith et al., 2024](#); [Lin et al., 2023](#)). Our prompt demonstration approach includes label information, positive examples, and negative examples for synthetic generation. In addition to generating new data points, we also perform paraphrasing of data points in the seed set. By paraphrasing, we gain diverse syntactic structures for better rule induction.

3.3 Joint Learning with Rules

The few-shot classifier is trained using SPEAR ([Maheshwari et al., 2021](#)), a joint learning framework that learns over a feature-based classification model and a label aggregation (LA) model. The feature model is a pre-trained neural model and LA is a generative model ([Chatterjee et al., 2020](#)), learned via PWS, using the automatically induced rules as labeling functions. LA is denoted as $P_\theta(\mathbf{l}_i, y)$, where \mathbf{l}_i a vector that represents the firing of all LFs for an input \mathbf{x}_i . Each firing, l_{ij} can be either 0 (abstain) or class label k ([Chatterjee et al., 2020](#)).

Following [Maheshwari et al. \(2021\)](#), our joint learning objective incorporates three different loss components for learning from labeled data. We provide a brief overview of each loss component below, while encouraging interested readers to ([Ma-](#)

[heshwari et al., 2021](#)) for detailed information.

$$\min_{\theta, \phi} \sum_{i \in \mathcal{L}} L_{CE} \left(P_\phi^f(y|\mathbf{x}_i), y_i \right) + LL_s(\theta|\mathcal{L}) + \sum_{i \in \mathcal{L}} KL \left(P_\phi^f(y|\mathbf{x}_i), P_\theta(y|\mathbf{l}_i) \right)$$

The first component of the loss is the standard cross-entropy loss for the model P_ϕ^f . The second component is the negative log-likelihood on the dataset. The third is the KL-Divergence between the predictions of the LA and P_ϕ^f models, which enforces consensus by aligning their predictions.

Contrastive Representation Learning: The pre-trained model, P_ϕ^f , undergoes contrastive representation learning prior to joint learning. Following, [Zhang et al. \(2021a\)](#) and [Singhal et al. \(2023\)](#), we first perform self-supervised contrastive learning (SSCL) over a pre-trained model. Here, the model parameters for a given pre-trained model is updated using, $\mathcal{L}_{pt} = \mathcal{L}_{sscl} + \lambda_{pt}\mathcal{L}_{mlm}$. \mathcal{L}_{pt} is a weighted sum of token-level masked language modeling loss (\mathcal{L}_{mlm}) and a sentence-level SSCL (\mathcal{L}_{sscl} ; [Wu et al., 2020](#); [Liu et al., 2021](#)). λ_{pt} is a weight hyper-parameter. For SSCL, given an input document x_i , we obtain perturbations of x_i by randomly masking tokens from it. Further, we dynamically mask tokens such that each sentence has different masked positions across different training epochs. SSCL attempts to bring the x_i and its masked versions closer in the semantic space while pulling away other pairs.

After the continued pretraining, we perform supervised contrastive learning ([Khosla et al., 2020a](#)). Here, we try to increase the similarity between input pairs that belong the same class, while trying to bring down the similarity of those belonging to different classes. We follow the supervised contrastive learning ([Khosla et al., 2020a](#)) loss, where all the documents in the same class in a batch are brought together. Here, the same document may also be used to create like pairs by creating perturbations of the input.

4 Experiments

Dataset : We use FEWMANY Benchmark ([Yehudai and Bendel, 2024](#)), for our monolingual experiments. FEWMANY consists of eight FSTC datasets ([Yehudai and Bendel, 2024](#)). It consists of CLINC150 (C150; [Larson et al., 2019](#)), BANKING77 (B77; [Casanueva et al., 2020](#)), HWU64

	FT	CL	DA	Filtering for DA			Automatic Rule Induction		IDRF	ICL
				PVI	ST	GC	ngrams	syntactic ngrams		
Base	✓									
Base-DA	✓		✓							
Base-ST	✓		✓		✓					
IntenDD	✓	✓	✓			✓	✓			
Snorkel	✓		✓			✓		✓		
CPFT	✓	✓	✓	✓						
FastFit	✓	✓	✓	✓						
CPFT + Snorkel	✓	✓	✓			✓		✓		
ARISE	✓	✓	✓			✓		✓		
ARISE-Iter	✓	✓	✓			✓		✓	✓	
LLMs			✓	✓						✓

Table 1: Techniques used by competing systems. Base is Roberta and XLM-R for monolingual and multilingual experiments respectively. FT is fine-tuning; CL is contrastive learning; DA is data augmentation; PVI is pointwise V-information; ST is self-training; IDRF is Iterative Data and Rules filtering.

(HU64; Liu et al., 2019a) for intent classification; ARGUMENT TOPIC (AT71; Gretz et al., 2020) and CLAIM STANCE (CS55; Bar-Haim et al., 2017) for Topic classification; TREC question classification dataset (T50; Li and Roth, 2002), AMAZON PRODUCTS (AP106) and DBPEDIA (DB70). We also use SciCite (SC3 Cohan et al., 2019), from the scientific literature domain. Finally, the multilingual experiments are performed using the MASSIVE dataset (FitzGerald et al., 2023). Here, we use seven typologically diverse languages including Chinese, English, French, German, Hindi, Japanese, and Spanish.

Data Augmentation: We use GPT-3.5, 4, and Claude 3 Opus for synthetic data generation. We generate label-specific data by prompt demonstration. Here, Using Wu et al. (2023), we perform k -NN retrieval, with $k = 5$, from the seed data for positive demonstrations, and randomly sampled out of class samples as negative examples (Liu et al., 2022). For multilingual experiments, we experiment with *direct* generation of the synthetic data in the target language, and also via *translation* of synthetically generated English sentences. For translation, in addition to the three aforementioned LLMs we use NLLB-54B (Team et al., 2022) and Google Translate. For translation in Hindi, we use Gala et al. (2023).

Baselines: Table 1 shows our baselines. Base models are the ‘Large’ variants of Roberta (Liu

et al., 2019b) and XLM-R (Conneau et al., 2020) for our monolingual and multilingual experiments respectively. Further, Base-DA is fine-tuned with augmented data (no filtering). Base-ST is trained using self-training-based filtering of augmented data. We also include competitive models that also combine multiple learning techniques, such as IntenDD (Singhal et al., 2023), Snorkel (Ratner et al., 2017), CPFT (Zhang et al., 2022b), and FastFit (Yehudai and Bendel, 2024). Following Yehudai and Bendel (2024), we report results for ICL, in 5-shot setups, using Flan-XXL (Wei et al., 2021), Flan-UL2 (Tay et al., 2022).

Experimental Setup: ARISE and ARISE-Iter, as shown in Table 1, are two variants without and with the iterative data and rule filtering (IDRF). ARISE variants use the same pre-trained models as used in ‘Base’. We perform all our experiments using 5 random splits and report the average. We use accuracy as our metric and experiment with both 5-shot and 10-shot settings (Yehudai and Bendel, 2024). For joint learning, we use a 20% split of the synthetically generated data as a validation split, while using all the gold data in training. For learning the parameters for our rule filtering step (§3.1), we use the few-shot gold data as validation. We report results for ARISE-iter induced with rules where the gold data was used only in the last iteration of bootstrapping. We keep a multiplier of 128x for our k -shot classification settings, following Lin et al. (2023). We use the graph-based

Models	AP106	AT71	B77	C150	CS55	DB70	HU64	T50	SciCite	Avg
Base	57.36	95.59	87.55	94.3	91.06	87.03	86.28	86.57	82.12	85.32
Base-Aug	57.42	95.3	88.36	93.83	90.16	87.92	87.58	86.8	82.58	85.55
Base-ST	58.46	95.78	88.58	94.37	91.1	88.23	88.69	87.26	83.07	86.17
CPFT	58.82	96.67	89.51	95.03	91.34	89.14	89.76	89.42	84.38	87.12
Snorkel	59.47	96.35	90.49	94.96	90.33	88.42	89.2	89.3	85.21	87.08
FastFit	59.29	96.79	89.4	95.48	90.24	88.63	89.54	88.84	85.01	87.02
IntenDD	59.67	97.02	90.07	95.71	91.71	88.93	89.04	88.45	85.04	87.29
CPFT+Snorkel	59.74	97.12	90.76	95.24	91.48	89.22	89.81	89.71	85.67	87.64
ARISE	60.87*	97.02	92.12*	96.37*	91.78	89.59	90.89*	90.24	85.87	88.31
ARISE-Iter	62.6	97.93	92.82	97.15	92.89	90.78	92.27	91.32	87.12	89.43

Table 2: Accuracy Results for 10-shot monolingual FSTC. Results in boldface and those marked with * are statistically significant by t-test ($p < 0.05$) compared to ARISE and CPFT+Snorkel respectively.

biaffine parser (Dozat and Manning, 2016) trained with XLM-R as the encoder on the UD treebank (Zeman et al., 2023) for dependency parsing. We obtain induced subtrees of upto 3 nodes as rules.

4.1 Results

ARISE-iter, our proposed model, reports the best performance in all our experimental settings, as shown in Tables 2, 3, and 4. It outperforms all other models with statistically significant gains. ARISE-Iter reports an absolute improvement of 1.79 % points (2.04 % increase), 1.32 % and 2.58 % points averaged across the datasets, for the 5 and 10-shot monolingual and 10-shot multilingual setups.

4.2 Monolingual Results

ARISE-Iter and ARISE differs only in terms of bootstrapping (IDRF). Bootstrapping alone leads to an average absolute gain of 1.12 and 1.32 % points for the 10-shot and 5-shot setups respectively (Tables 2 and 3), between both the ARISE-Iter and ARISE respectively. Base-Aug reports statistically significant gains only for 3 of 9 datasets (B77, HU64, and DB70) compared to Base in Table 2. It shows that data augmentation without any filtering need not always improve the results. Further, Base-ST on average report a gain of 0.85 % points compared to Base, with statistically significant gains in 6 of 9 datasets (except for AT71, C150, and CS55).

ARISE variants follow CPFT (Zhang et al., 2022b) in employing contrastive learning (CL) components. CL components alone in CPFT lead to an average absolute gain of 1.8 % points compared to Base, in Table 2. Similarly, Snorkel,

a PWS framework, and ARISE is trained with the same filtered data and rules. However, unlike ARISE, Snorkel does not use joint learning. Instead, Snorkel learns a generative model to label (or filter in our case) synthetically generated sentences. It outperforms the base model by an average absolute improvement of 1.76 % points and is competitive with CPFT. Snorkel and CPFT report statistically significant gains compared to Base for all the datasets, except CS55. Snorkel and CPFT report comparable performance on 5 of 9 datasets, with statistically significant gains in 2 datasets each.

CPFT+Snorkel combines both contrastive representation learning and PWS. It differs from ARISE, only in terms of the joint learning component. ARISE reports an absolute improvement of 0.67 % points in 10-shot settings (Table 2), and 0.96 % points in 5-shot settings (Table 3), as compared to CPFT+Snorkel. Results from Snorkel, CPFT+Snorkel, and ARISE show our rule induction component, as a general-purpose one for PWS. Similarly, gains in CPFT+Snorkel and ARISE show that combining complementary learning techniques leads to performance gains compared to using them independently.

ARISE-Iter, our proposed approach with IRDF, outperforms both IntenDD (Singhal et al., 2023) and FastFit (Yehudai and Bendel, 2024), two competitive models with state-of-the-art results on few-shot learning. While FastFit originally does not use data augmentation, we add augmented sentences to it for a fair comparison. IntenDD differs from ARISE by using string-level n-grams for weak supervision and additionally employs a two-level transductive learning approach. ARISE-Iter

Methods	AT71	B77	C150	CS55	HU64	T50	Avg.
Flan-ul2	97.07	71.21	80.6	89.57	76.2	64.86	79.92
Flan-XXL	96.72	72.04	81.99	50.24	75.13	84.72	76.81
Base	95.61	79.77	91.67	87.94	79.29	73.67	84.66
FastFit	96.45	86.14	93.77	88.16	84.6	84.8	88.99
Intendd	96.11	89.13	94.05	88.76	88.21	86.86	90.52
CPFT+ Snorkel	96.74	88.64	94.46	88.57	87.38	87.45	90.54
ARISE	96.68	90.35	94.89	90.3	88.04	88.72	91.5
ARISE-Iter	97.14	91.68	96.13	91.59	90.22	90.14	92.82

Table 3: Accuracy Results for 5-shot monolingual FSTC.

	En	De	Ja	Es	Fr	Zh	Hi	Avg.
Base	77.65	71.23	74.89	71.56	72.81	73.14	71.07	73.19
IntenDD	79.55	73.64	76.5	76.92	76.42	76.53	74.41	76.28
Snorkel	80.52	75.39	78.87	75.79	77.65	76.7	74.16	77.01
CPFT	78.65	73.45	77.56	74.99	76.74	75.58	73.66	75.8
FastFit	80.73	75.97	78.49	75.64	76.84	75.98	74.07	76.82
CPFT + Snorkel	81.43	76.67	79.34	76.43	78.14	77.66	75.04	77.82
ARISE	82.43	76.64	79.52	77.1	78.93	78.32	75.16	78.3
ARISE-Iter	84.96	79.38	81.87	79.58	80.16	79.45	77.41	80.4

Table 4: Multilingual results on MASSIVE Dataset.

when trained with string level n-grams as used in IntenDD still outperforms IntenDD but reports an average accuracy of 88.64 %, a drop from 89.43 for the 10-shot setting. Similarly, the use of PVI for data filtering instead of IRDF for ARISE-Iter results in an average accuracy of 88.19 %.

Table 3 reports results for the 5-shot setup. We follow the setup of Yehudai and Bendel (2024) for ICL. ARISE-Iter reports an average absolute gain of 16.01 % and 2.28 % compared to Flan-XXL and CPFT+Snorkel models respectively. It also reports statistically significant gains, compared to both, for all the datasets except AT71. Overall, Flan-XXL and Flan-UL2 outperform other LLMs (Touvron et al., 2023; Jiang et al., 2023) in our ICL experiments and hence reported in Table 3.

Multilingual Experiments: Table 4 shows the results for multilingual experiments. On an average ARISE-Iter reports an absolute improvement of 2.1 % points compared to ARISE, the next best model. The results show that our approach is applicable across a typologically diverse set of languages. We find *translation* of synthetically generated English sentences leads to empirically better results as compared to *direct* generation of data in the target language. The results for the former are

reported in Table 4. The latter approach results in an absolute drop of 1.27 % points. Further, we also experiment with a setting where we induct rules from dependency parses of all the translations of an input. Here, we observe a performance drop for all the languages, except Hindi. On average there is 0.76 % drop for ARISE-Iter compared to the default setting as reported in Table 4. For Hindi, it reported 78.62 % as compared to 77.41 % in the default setting.

5 Conclusion

We propose ARISE, a framework that combines contrastive representation learning, automatic rule induction, data augmentation, IRDF and joint learning via PWS. While PWS is typically employed as a weak supervision approach for labeling unlabeled data, we employ it for verifying synthetically generated labeled documents. Further, we find incorporating syntactic information, instead of strings, via rules leads to gains. Overall, ARISE outperforms strong competitive baselines under comparable conditions. We also show the effectiveness of combining diverse learning components that enable incorporating complementary information from the limited gold data to achieve state-of-the-art results.

6 Limitations

A major challenge with ARISE, currently is the overall training time required to setup a final classifier. We currently use syntactic-ngrams with upto 3 nodes as our features. The search space exponentially increases as the size of the nodes of subtrees further increases, limiting our ability to induce higher-order tree structures as rules. While we currently rely on labeled synthetically generated data, a strength of weak supervision is to incorporate unlabeled data by labeling them. Several real world scenarios often come up where unlabeled data is readily available. It needs to be further investigated whether the synthetically generated labeled data can match the quality of real-world unlabeled data in the context of weak supervision. The current work does not explore this line of work, though it seems to be an important question to be addressed.

7 Ethics Statement

All experiments conducted in this study utilize only publicly available datasets. We used publicly hosted APIs of GPT and Claude for synthetic data generation. The prompts included guardrails in the form of instructions to avoid generating problematic content.

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