

000 001 002 003 004 005 006 007 008 009 010 011 012 013 014 015 016 017 018 019 020 021 022 023 024 025 026 027 028 029 030 031 032 033 034 035 036 037 038 039 040 041 042 043 044 045 046 047 048 049 050 051 052 053 ENHANCING CROSS-TASK TRANSFER OF LARGE LAN- GUAGE MODELS VIA FOURIER ACTIVATION STEERING

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ABSTRACT

Large Language Models (LLMs) have shown impressive abilities in leveraging pretrained knowledge through prompting, but they often struggle with unseen tasks, especially in data-scarce scenarios. While cross-task in-context learning provides a direct solution for knowledge transfer without fine-tuning, it still faces limitations in terms of robustness, scalability, and efficiency. In this paper, we investigate *whether cross-task transfer can be achieved via latent space steering*. Through analysis of activation patterns under both zero-shot and few-shot prompts, we have three observations: (1) the activation differences between few-shot and zero-shot prompts exhibit a nearly parallel structure in low-dimensional space; (2) these difference vectors correlate strongly with task similarity; (3) Fourier analysis reveals that low-frequency components encode task-agnostic, information-enhanced features, while high-frequency components capture task-specific details. Motivated by these findings, we propose **FAST**, a Fourier-based Activation Steering cross-task Transfer framework. It first selects influential and diverse samples from high-resource tasks, then injects information-enhanced low-frequency components along with task-similarity weighted high-frequency components during inference. Extensive experiments in both cross-domain and cross-lingual transfer settings show that our method consistently outperforms existing methods. The code is available in <https://anonymous.4open.science/r/RETL-BC5B>.

1 INTRODUCTION

Large Language Models (LLMs) (OpenAI, 2024; Guo et al., 2025) demonstrate remarkable capabilities to store knowledge during pretraining, which can be effectively accessed via prompting. However, as this paradigm becomes increasingly prevalent, a critical challenge emerges: these models often struggle with tasks that were not seen during pretraining, particularly in data-scarce scenarios (Bigoulaeva et al., 2025). A common strategy to tackle this issue is transfer learning (Zhuang et al., 2021; Strangmann et al., 2024; Somerstep et al., 2025), which uses knowledge from high-resource tasks to adapt to low-resource ones. Several studies (Vu et al., 2022; Li et al., 2022; Lv et al., 2024) fine-tune soft prompts on data-sufficient tasks and subsequently apply them to data-scarce tasks during inference. While effective, such approaches still require training and can not generalize well across diverse tasks. An alternative line of work investigates cross-task in-context learning (ICL) (Tantar et al., 2023; Li et al., 2023b; Chatterjee et al., 2024), which utilizes labeled examples from high-resource tasks to improve performance on low-resource tasks without parameter updates.

Despite its promise, cross-task ICL still faces several limitations. (1) Performance is highly sensitive to the choice of demonstrations (Liu et al., 2022a; Levy et al., 2023), prompt templates (Wang et al., 2023; Mishra et al., 2022), and source tasks (Chatterjee et al., 2024), which restricts its adaptability (**robustness**). (2) Few demonstrations can be included due to the constrained context length of LLMs (**scalability**). (3) Computational cost increases significantly with more demonstrations due to the quadratic complexity of Transformers to the input length (**efficiency**). To address these challenges, one possible solution is to operate activations in the continuous space, which avoids expanding the discrete token sequences and mitigates context length constraints. This leads us to raise a research question: *Can we achieve effective cross-task transfer through latent space steering?*

To answer this question, we conduct an empirical study of activation patterns under both zero-shot and few-shot prompts. Our analysis reveals three main findings: (1) The difference in activations between

054 few-shot and zero-shot prompts exhibits a **nearly parallel structure** when projected into a low-
 055 dimensional space across diverse task pairs. This suggests that the enhanced information provided
 056 by in-context examples has **consistent directions** in the model’s activation space. (2) To explore
 057 whether these difference activations can be directly injected, we measure their directional similarity
 058 across different source and target tasks in the high-dimensional activation space. We observe that their
 059 directions are **highly correlated with task similarity**, suggesting that directly injecting difference
 060 activations is more effective for related tasks, and less effective for dissimilar ones. (3) Inspired
 061 by Fourier analysis, where representations can be decomposed into broad trends (low-frequency)
 062 and localized details (high-frequency), we apply Fourier-based filtering to disentangle the difference
 063 vectors. We find that low-frequency components capture **task-agnostic and information-enhanced**
 064 **features**, and high-frequency components contain **task-specific information**.

065 Building on these insights, we propose a **Fourier-based Activation Steering** cross-task Transfer
 066 framework, namely **FAST**. We first select a representative subset of high-resource examples that
 067 balance influence and diversity, aiming to improve the efficiency of feature extraction. Specifically,
 068 we first construct a similarity graph of high-resource examples, and then iteratively select a sample
 069 with the highest combined influence and diversity score at each step until the desired subset size
 070 is reached. Next, we compute the activation differences between few-shot and zero-shot prompts
 071 for these selected samples. We then apply Fourier-based filtering to decompose these difference
 072 activations into information-enhanced features (*i.e.*, low-frequency components) and task-specific
 073 features (*i.e.*, high-frequency components). During inference on low-resource queries, we inject
 074 the low-frequency components along with task-similarity weighted high-frequency components
 075 into the forward pass, which guides LLMs toward effective cross-task transfer. This approach is
 076 both efficient and scalable, as it relies solely on pre-computed activations from high-resource tasks
 077 without requiring parameter updates or expanded input length. To validate the effectiveness of our
 078 proposed method, we conduct extensive experiments in both cross-domain and cross-lingual scenarios.
 079 Experimental results demonstrate that **FAST** consistently outperforms competitive baselines while
 080 maintaining lower computational cost. Our main contributions can be summarized as follows:
 081

- 082 • To the best of our knowledge, we are the first to systematically analyze the activation patterns of
 083 both zero-shot and few-shot prompts. We find that: (1) the activation differences between few-shot
 084 and zero-shot prompts exhibit a consistent and nearly parallel structure in low-dimensional space; (2)
 085 these difference vectors are strongly correlated with task similarity in high-dimensional space; (3)
 086 through Fourier-based analysis, these difference activations can be decomposed into task-agnostic,
 087 information-enhanced features (low-frequency) and task-specific features (high-frequency).
- 088 • We propose **FAST**, a novel cross-task transfer framework that leverages Fourier-based activation
 089 steering to transfer knowledge from high-resource to low-resource tasks. We first select a representa-
 090 tive and diverse subset from high-resource tasks and apply Fourier-based activation steering to enable
 091 effective cross-task transfer without requiring parameter updates or input expansion.
- 092 • We conduct extensive experiments in both cross-domain and cross-lingual transfer scenarios. The
 093 experimental results demonstrate that our approach consistently outperforms competitive baselines
 094 while maintaining high scalability and computational efficiency.

094 2 EMPIRICAL STUDY

096 The Hopfieldian view of cognition (Hopfield, 1982) posits that neural computation arises from
 097 dynamic transformations in population-level neural activity in response to external stimuli. This
 098 perspective has inspired mechanistic interpretations of artificial neural networks, where activation
 099 steering (Zou et al., 2023) has emerged as a powerful method for analyzing internal model states. By
 100 treating intermediate activations as fundamental computation units, activation steering helps reveal
 101 high-level concepts and functions encoded within models. In this section, we analyze zero-shot and
 102 few-shot prompts across various source and target tasks from the perspective of activations.

104 2.1 EXPERIMENTAL SETUP

105 Following Liu et al. (2024a), we extract activations from the last token position for both zero-shot
 106 and few-shot prompts using Llama3.1-8B (Dubey et al., 2024), as this position aggregates the full
 107 semantics of the input sentence. We use AGnews (Zhang et al., 2015), ARC-Easy (Clark et al., 2018),

108 and SST2 (Socher et al., 2013) as source tasks, and ARC-Challenge (Clark et al., 2018) and Financial
 109 Phrasebank (Malo et al., 2014) as target tasks. For each task, we randomly select 500 samples and
 110 construct zero-shot and few-shot prompts, with the latter including three randomly chosen examples.
 111

112 2.2 INFORMATION-ENHANCED FEATURES INDUCED BY IN-CONTEXT EXAMPLES EXHIBIT 113 CONSISTENT PATTERNS ACROSS TASKS

116 Given that few-shot prompts pro-
 117 vide richer contextual information and
 118 elicit more diverse features, we investi-
 119 giate whether information induced
 120 by in-context examples from high-
 121 resource tasks can facilitate cross-task
 122 transfer via latent space manipulation.
 123 To this end, we analyze the activa-
 124 tion distributions from both zero-shot
 125 and few-shot prompts across various
 126 source and target tasks by projecting
 127 these high-dimensional activations
 128 into 2D space using t-SNE (van der Maaten & Hinton, 2008). The results are presented in Figure 1
 129 (More visualization is provided in Figure 12). As we can see, activations from two prompt types form
 130 clearly separated clusters within each task. This indicates that the model develops fundamentally
 131 distinct internal representations under each prompting strategy. Moreover, the vectors connecting
 132 the cluster centers of few-shot and zero-shot activations are nearly parallel across different tasks in
 133 the low-dimensional space. This suggests that information-enhanced features follow a consistent
 134 direction across tasks, supporting the feasibility of cross-task transfer through latent space steering.

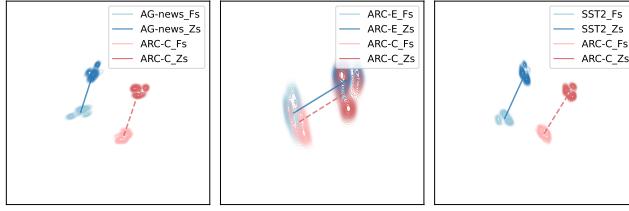


Figure 1: T-SNE visualization of model activations under zero-shot and few-shot prompts. Red and Blue points denote source and target tasks, respectively.

135 (More visualization is provided in Figure 12). As we can see, activations from two prompt types form
 136 clearly separated clusters within each task. This indicates that the model develops fundamentally
 137 distinct internal representations under each prompting strategy. Moreover, the vectors connecting
 138 the cluster centers of few-shot and zero-shot activations are nearly parallel across different tasks in
 139 the low-dimensional space. This suggests that information-enhanced features follow a consistent
 140 direction across tasks, supporting the feasibility of cross-task transfer through latent space steering.

141 2.3 DIFFERENCE ACTIVATION DIRECTIONS BETWEEN FEW-SHOT AND ZERO-SHOT PROMPTS 142 ARE HIGHLY CORRELATED WITH TASK SIMILARITY

143 Given the consistent directions of information-
 144 enhanced features, we examine whether such
 145 activations can facilitate cross-task transfer in
 146 high-dimensional space. We compute the sim-
 147 ilarity of the difference activation directions be-
 148 tween source and target tasks. For a given layer
 149 l , we define the difference vector $dv^s(l)$ and
 150 $dv^t(l)$ for a source task s and a target task t as:

$$dv^s(l) = \{f^s(i, l) - z^s(i, l)\}_{i=1}^n \quad (1)$$

$$dv^t(l) = \{f^t(i, l) - z^t(i, l)\}_{i=1}^n \quad (2)$$

151 where $f(i, l)$ and $z(i, l)$ denote few-shot and
 152 zero-shot activations at layer l for each sample i ,
 153 respectively. We then quantify the task similarity $Ts(s, t)$ between source task s and target task t by
 154 averaging the pairwise cosine similarities of last-token representations across all layers and samples:

$$Ts(s, t) = \frac{1}{Ln^2} \sum_{l=1}^L \sum_{i=1}^n \sum_{j=1}^n \frac{z_l^s(i) \cdot z_l^t(j)}{|z_l^s(i)| |z_l^t(j)|}. \quad (3)$$

155 As shown in Figure 2, we find a strong positive correlation between task similarity and directions of
 156 difference activations, indicating that these vectors retain substantial task-specific information. This
 157 makes direct transfer between dissimilar tasks challenging due to the divergence in the activation
 158 spaces. Additionally, we find that directional similarity varies most prominently in middle layers,
 159 possibly because LLMs encode more abstract features (Skean et al., 2025) in these layers.

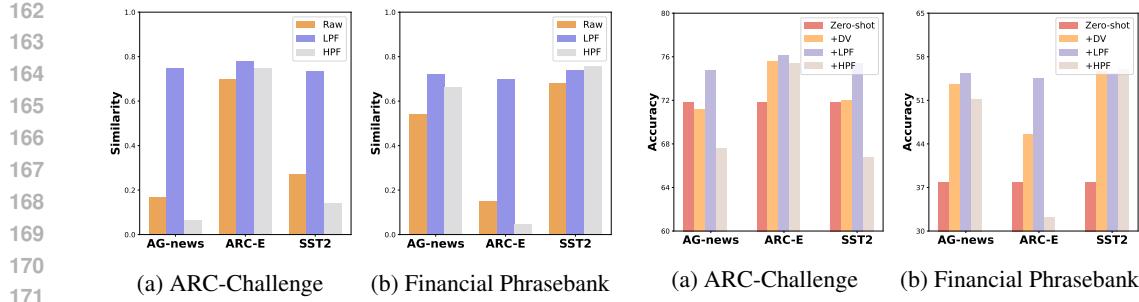


Figure 3: Similarity of low-pass and high-pass filtered difference vectors across task pairs.

Figure 4: Accuracy results of injecting difference, low-pass and high-pass filtered activations.

2.4 LOW-FREQUENCY COMPONENTS ENCODE INFORMATION-ENHANCED FEATURES AND HIGH-FREQUENCY COMPONENTS RETAIN TASK-SPECIFIC INFORMATION

Considering the challenges of directly injecting the difference vectors, we investigate their spectral characteristics across all layers. Inspired by Fourier analysis, where low-pass filters preserve broad trends and high-pass filters capture localized details, we decompose each difference vector dv into low-frequency dv_{low} and high-frequency components dv_{high} :

$$dv_{\text{low}} = \text{Re} [\text{IFFT} (\mathbf{M}_k \odot \text{FFT}(dv))], \quad dv_{\text{high}} = \text{Re} [\text{IFFT} ((1 - \mathbf{M}_k) \odot \text{FFT}(dv))]. \quad (4)$$

Here, $\text{FFT}(\cdot)$ and $\text{IFFT}(\cdot)$ denote the Fast Fourier Transform and its inverse, \odot is the Hadamard product, $\text{Re}[\cdot]$ extracts the real part to eliminate residual imaginary components. The low-pass mask $\mathbf{M}_k \in \{0, 1\}^d$, with d being the dimensionality of dv , preserves the first k frequency components:

$$\mathbf{M}_k[i] = \begin{cases} 1, & \text{if } i \leq \frac{k}{2} \text{ or } i > d - \frac{k}{2}, \\ 0, & \text{otherwise.} \end{cases} \quad (5)$$

As illustrated in Figure 3, low-pass filtered vectors show high similarity across task pairs, suggesting that low-frequency components capture task-agnostic features. In contrast, high-pass filtered activations are similar only between highly similar tasks, indicating that they encode task-specific information.

We further evaluate the effect of injecting the full difference vector, low-pass filtered components, and high-pass filtered components into LLMs across all layers. The average results across all layers are shown in Figure 4. Our findings reveal that directly injecting the full difference vector strongly correlates with task similarity: it improves performance when tasks are similar, but yields limited or even negative gains when tasks are dissimilar. Moreover, we observe that adding low-frequency activations (*i.e.*, information-enhanced features) consistently improves accuracy across tasks, while injecting high-frequency activations (*i.e.*, task-specific information) only helps when tasks are similar and harms performance when they are dissimilar. This indicates that low-frequency components encode information-enhanced features and high-frequency components retain task-specific information.

3 METHOD

In this section, we introduce **FAST**, a novel framework for cross-task transfer via Fourier-based activation steering in LLMs. We first formalize the problem of cross-task transfer learning, then select influential and diverse samples from high-resource tasks, and finally leverage Fourier-based activations of these samples to adapt LLMs to low-resource tasks through activation steering. The overall framework is illustrated in Figure 5.

3.1 PROBLEM FORMULATION

Cross-task transfer learning aims to enhance the performance of LLMs on low-resource target tasks by leveraging knowledge acquired from high-resource source tasks (Vu et al., 2022; Chatterjee et al., 2024). Let $(x_{s_i}, y_{s_i})_{i=1}^n \in D_s$ denote the source task with abundant labeled data, and $(x_{t_i}, y_{t_i})_{i=1}^n \in D_t$ represent the target task with limited labeled samples. The process typically

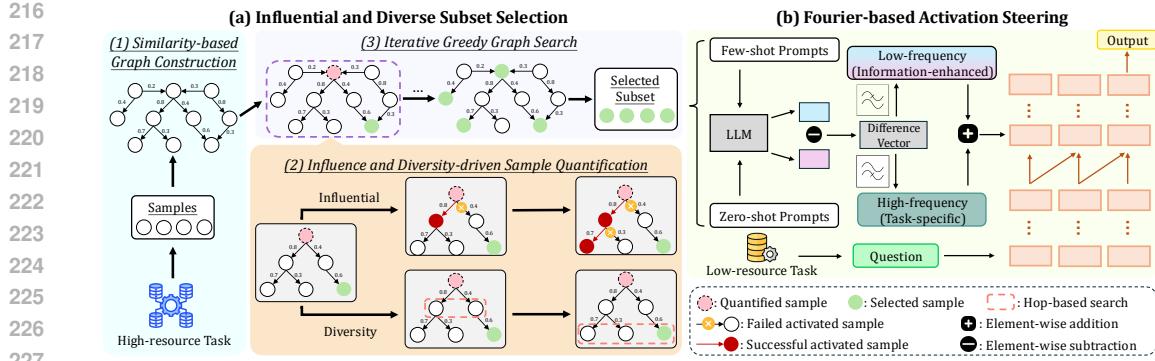


Figure 5: Overview of **FAST**. (a) Influential and diverse subset selection strategy: (1) construct a similarity-based graph from high-resource tasks; (2) quantify each sample’s influence and diversity; (3) iteratively select the highest-scoring sample via greedy search to form the final subset. (b) Fourier-based activation steering: decompose the difference vectors between few-shot and zero-shot prompts via Fourier-based filtering into low-frequency (information-enhanced) and high-frequency (task-specific) components, and selectively inject them to steer LLM outputs for low-resource tasks.

involves extracting transferable information I_s from the source task and effectively integrating it into the target task question x_t , which can be formalized as:

$$I_s = g(x_{s_1}, y_{s_1}, \dots, x_{s_n}, y_{s_n}), \quad \hat{y}_t = \text{LLM}(I_s, x_t). \quad (6)$$

Here, g denotes the feature extraction function that captures knowledge from the source tasks, and \hat{y}_t is the prediction of LLMs on the target input.

3.2 INFLUENTIAL AND DIVERSE SUBSET SELECTION

Although the source task contains abundant labeled data, utilizing all samples for cross-task transfer is computationally inefficient and unnecessary. To address this, we propose an influential and diverse subset selection strategy to identify representative and diverse samples from the source task. Specifically, we first build a sample graph based on pairwise similarities to model relationships among examples, then measure the influence and diversity score of each sample, and finally employ an iterative greedy search algorithm to select the highest-scoring samples for the final subset.

3.2.1 SIMILARITY-BASED GRAPH CONSTRUCTION

Our subset selection strategy begins by modeling sample relationships using a directed graph. We first encode each sample into a vector using the BGE model (Chen et al., 2024a). These embeddings are used to construct a task-specific directed graph $\mathcal{G} = (\mathbf{V}, \mathbf{E}, \mathbf{P})$, where each vertex $v_i \in \mathbf{V}$ denotes a sample, a directed edge $e(i, j) \in \mathcal{E}$ connects node v_i to v_j , and edge weight $p(i, j) \in \mathbf{P}$ is the cosine similarity between the embeddings of the corresponding samples. To reduce structural redundancy, we follow Su et al. (2023) and connect each node to its 150 most similar neighbors.

3.2.2 INFLUENCE AND DIVERSITY-DRIVEN SAMPLE QUANTIFICATION

After constructing the sample graph, we evaluate each sample from two perspectives: (1) its **influence** in activating other samples within the task, and (2) its contribution to the overall **diversity** of the previously selected samples. The pseudo-code is provided in Algorithm 1.

The influence score measures how a sample can propagate information across the graph, which is computed by simulating an information diffusion process. Specifically, we initialize the process by adding the candidate node v into an active set S_{active} . At each step, we randomly select an active node $u \in S_{\text{active}}$ and attempt to activate each of its 1-hop neighbors $w \in N_1(u)$ with success probability $p(u, w)$. Newly activated nodes are added to S_{active} . This iterative process continues until no further propagations occur. The influence score $I(v)$ of node v is defined as the total number of nodes activated during the entire diffusion process. In this way, samples that trigger extensive activation receive higher scores. To ensure the robustness of our method, we follow Zhang et al. (2024) and repeat the simulation 10 times, reporting the average influence score.

270 The diversity penalty measures the redundancy a candidate node introduces relative to the already
 271 selected subset. We perform a hop-based search to examine the i -hop neighbor $N_i(v)$ of node v and
 272 compute its overlap with S_{selected} . The diversity penalty $D(v)$ of node v is formulated as:
 273

$$274 \quad D(v) = - \sum_{i=1}^k \beta^i \cdot |N_i(v) \cap S_{\text{selected}}|. \quad (7)$$

275

276 Here, β is a hop-based decay factor that reduces the penalty for overlaps at larger graph distances.
 277 Consequently, nodes with minimal overlap have smaller penalties. Finally, we balance the influence
 278 score $I(v)$ and diversity penalty $D(v)$ through a hyperparameter γ to obtain the overall score $F_{\mathcal{G}}(v)$.
 279

$$280 \quad F_{\mathcal{G}}(v) = I(v) + \gamma \cdot D(v). \quad (8)$$

281 3.2.3 ITERATIVE GREEDY GRAPH SEARCH

282 To construct a subset that balances both task representativeness and sample diversity, we use an
 283 iterative greedy graph search strategy. The pseudo-code is provided in Algorithm 2. Our approach
 284 operates over the sample graph \mathcal{G} and iteratively selects the candidate sample with the highest
 285 influence-diversity score. In more detail, the process starts with an empty set. At each iteration, we
 286 evaluate all unselected samples using the function $F_{\mathcal{G}}$, and the highest-scoring sample is added to the
 287 subset. This procedure is repeated until the subset reaches the desired size.
 288

289 3.3 FOURIER-BASED ACTIVATION STEERING

290 Inspired by the observation from our empirical study, we propose a Fourier-based activation steering
 291 method that transfers high-resource information to low-resource tasks. Our method primarily consists
 292 of two components: *activation extraction* and *activation control*.
 293

294 **Activation Extraction.** The component aims to identify high-level concepts or functional behaviors
 295 encoded in LLMs. Specifically, for each sample $i \in D_s$ from the high-resource task, we construct
 296 two types of prompts: a zero-shot prompt z_i that contains only the sample, and a few-shot prompt f_i
 297 that includes three randomly selected in-context examples. To eliminate instance-specific noise and
 298 capture general task-level features, we compute the mean difference activation across all samples.
 299

$$300 \quad dv^s(l) = \frac{1}{n} \sum_{i=1}^n (f^s(i, l) - z^s(i, l)), \quad (9)$$

301

302 where $dv^s(l)$ represents the difference vector from the last token’s hidden state at layer l , and n is the
 303 number of samples.
 304

305 **Activation Control.** This component aims to steer model behaviors by leveraging extracted ac-
 306 tivations. Motivated by our earlier finding that low-frequency components encode transferable,
 307 information-enhanced features and high-frequency components capture task-specific details, we apply
 308 Fourier-based filtering to decompose dv^s into dv_{low}^s and dv_{high}^s using Equation 4. We then inject the
 309 low-frequency component along with the task-similarity weighted high-frequency component into the
 310 hidden state at the final token position of a specific layer, which effectively steers model predictions
 311 without perturbing previously encoded context. The modified hidden state is computed as:
 312

$$\hat{h}_l = h_l + \lambda (dv_{\text{low}}^s + \mathbb{I}[Ts(s, t) > \epsilon] \cdot Ts(s, t) \cdot dv_{\text{high}}^s), \quad (10)$$

313 where \mathbb{I} is the indicator function, λ is the injection strength, h_l is the hidden state at layer l , $Ts(s, t)$
 314 represents the task similarity between source s and target task t , and ϵ is the similarity threshold.
 315 This approach enhances cross-task transfer by emphasizing task-agnostic and information-enhanced
 316 features and adaptively incorporating task-specific activations for sufficiently similar task pairs.
 317

318 4 EXPERIMENTS

319 4.1 EXPERIMENTAL SETUP

320 **Datasets.** In this paper, we evaluate our method in both cross-domain and cross-lingual transfer
 321 settings. For cross-domain experiments, we follow Chatterjee et al. (2024) and use seven source
 322

Table 1: Performance comparisons in the cross-domain transfer scenarios.

Model	Method	ARC-C	FPB	MedMCQQA	SciQ	Social-i-QA	Average	
Llama 3.1-8B	Prompting	Zero-shot	71.80	37.80	49.40	84.40	55.40	59.76
		Few-shot Random	69.31 \pm 2.66	48.51 \pm 3.65	48.69 \pm 2.23	84.63 \pm 2.85	59.14 \pm 1.71	62.06 \pm 2.62
		Few-shot TopK	69.54 \pm 2.42	48.63 \pm 6.07	48.69 \pm 1.77	84.86 \pm 2.28	59.37 \pm 2.35	62.22 \pm 2.98
		Few-shot DPP	69.74 \pm 2.85	48.89 \pm 5.96	49.74 \pm 2.12	85.26 \pm 2.26	59.60 \pm 1.36	62.65 \pm 2.91
	PEFT	QLoRA	69.31 \pm 3.60	52.33 \pm 6.04	50.06 \pm 3.24	83.97 \pm 4.53	57.77 \pm 4.16	62.69 \pm 4.31
		AdaLoRA	69.74 \pm 3.55	52.69 \pm 6.76	50.23 \pm 3.26	84.21 \pm 4.19	57.89 \pm 4.64	62.95 \pm 4.48
	Activation Steering	ICV	72.63 \pm 0.95	54.51 \pm 4.40	52.77 \pm 1.11	87.46 \pm 2.45	61.54 \pm 1.62	65.78 \pm 2.11
		SEA	73.49 \pm 0.55	55.29 \pm 4.49	53.29 \pm 1.04	88.00 \pm 2.14	62.11 \pm 1.28	66.44 \pm 1.90
		FAST	76.14 \pm 0.52	59.26 \pm 3.90	56.09 \pm 0.67	90.43 \pm 1.03	64.57 \pm 1.18	69.30 \pm 1.46
Qwen 2.5-7B	Prompting	Zero-shot	82.80	85.20	52.00	89.60	76.00	77.12
		Few-shot Random	85.80 \pm 1.32	86.89 \pm 1.66	54.37 \pm 1.20	89.63 \pm 1.55	77.00 \pm 1.26	78.74 \pm 1.40
		Few-shot TopK	86.31 \pm 0.80	87.69 \pm 1.99	54.54 \pm 0.71	90.03 \pm 1.35	76.97 \pm 0.88	79.11 \pm 1.15
		Few-shot DPP	86.31 \pm 0.67	87.74 \pm 1.46	54.60 \pm 0.76	89.94 \pm 1.66	76.83 \pm 1.16	79.08 \pm 1.14
	PEFT	QLoRA	86.34 \pm 3.34	87.06 \pm 4.03	55.51 \pm 3.72	88.71 \pm 4.54	77.31 \pm 3.80	78.99 \pm 3.89
		AdaLoRA	86.31 \pm 3.67	87.71 \pm 4.01	55.86 \pm 3.89	89.49 \pm 4.23	77.60 \pm 3.75	79.39 \pm 3.91
	Activation Steering	ICV	88.49 \pm 1.04	90.43 \pm 1.81	57.34 \pm 1.40	91.91 \pm 1.48	80.11 \pm 1.15	81.66 \pm 1.38
		SEA	89.14 \pm 0.99	90.74 \pm 1.77	58.11 \pm 1.50	92.66 \pm 1.20	80.46 \pm 1.38	82.22 \pm 1.37
		FAST	92.20 \pm 1.01	93.80 \pm 0.68	60.86 \pm 1.51	95.23 \pm 0.66	83.46 \pm 0.86	85.11 \pm 0.94

Table 2: Performance comparisons in the cross-lingual transfer scenarios.

Method		de	en	es	fr	ja	zh	Average
Prompting	Zero-shot	84.40	66.00	81.60	86.60	38.60	30.80	64.67
	Few-shot Random	85.64 \pm 5.30	59.36 \pm 15.58	83.48 \pm 9.58	81.40 \pm 9.65	39.28 \pm 7.11	37.36 \pm 6.07	64.42 \pm 8.88
	Few-shot TopK	86.12 \pm 5.31	61.56 \pm 15.65	83.68 \pm 9.73	81.75 \pm 9.99	39.40 \pm 7.86	38.36 \pm 5.58	65.14 \pm 9.02
	Few-shot DPP	86.36 \pm 5.07	64.48 \pm 15.13	85.40 \pm 8.42	83.90 \pm 8.80	39.84 \pm 8.59	38.72 \pm 6.81	66.45 \pm 8.80
PEFT	QLoRA	85.16 \pm 6.25	63.48 \pm 20.01	82.16 \pm 13.17	79.35 \pm 13.32	37.72 \pm 13.05	35.92 \pm 8.76	63.97 \pm 12.43
	AdaLoRA	85.64 \pm 6.07	65.08 \pm 19.85	83.00 \pm 14.07	80.20 \pm 14.43	38.80 \pm 11.92	36.80 \pm 8.94	64.92 \pm 12.55
Activation Steering	ICV	90.16 \pm 2.57	82.80 \pm 3.92	91.96 \pm 2.06	91.70 \pm 2.23	44.32 \pm 4.11	41.16 \pm 5.55	73.68 \pm 3.41
	SEA	90.44 \pm 2.63	84.16 \pm 2.97	92.20 \pm 1.62	91.85 \pm 1.63	45.08 \pm 3.70	42.24 \pm 5.55	74.33 \pm 3.02
	FAST	92.48 \pm 2.08	89.04 \pm 2.11	95.20 \pm 0.40	95.25 \pm 0.43	48.12 \pm 2.61	44.88 \pm 4.17	77.50 \pm 1.97

domains and five target domains. The source domains include: ARC-Easy (Clark et al., 2018), AG-news (Zhang et al., 2015), BoolQ (Clark et al., 2019), Commonsense-QA (Talmor et al., 2019), MNLI (Williams et al., 2018), QQP (Sharma et al., 2019), and SST2 (Socher et al., 2013). Following previous work (Chatterjee et al., 2024), we select ARC-Challenge (Clark et al., 2018), Financial-Phrasebank (Malo et al., 2014), MedMCQA (Pal et al., 2022), SciQ (Auer et al., 2023), and Social-i-QA (Sap et al., 2019) as target domains. For cross-lingual settings, we conduct experiments on the MARC (Keung et al., 2020) dataset, which covers six languages. Due to computational constraints, we follow previous work (Chatterjee et al., 2024) and randomly sample 500 examples from each target domain as the test set. Detailed descriptions of the datasets are provided in Appendix E.

Baselines. We select several representative approaches for comparison, including prompting methods (*i.e.*, Zero-shot, Few-shot Random, Few-shot TopK (Liu et al., 2022b), Few-shot DPP (Ye et al., 2023)), parameter-efficient fine-tuning methods (*i.e.*, QLoRA (Dettmers et al., 2023) and AdaLoRA (Zhang et al., 2023)), and activation steering methods (*i.e.*, ICV (Liu et al., 2024a) and SEA (Qiu et al., 2024)). Detailed descriptions of these baselines are presented in Appendix F.

Implementation Details. Our experiments are conducted using Llama3.1-8B (Dubey et al., 2024) and Qwen2.5-7B (Yang et al., 2025). In our subset selection strategy, we set the subset size n to 20, the hop-based decay factor α to 0.2, and the balanced parameter γ between influence and diversity to 0.5. For activation steering, we inject the activations into the final token’s hidden state. The injection layer is determined based on performance on the validation set, the injection strength λ is set to 0.2, the similarity threshold ϵ is set to 0.6, and the preserved frequency component k is set to $d/2$. We use accuracy as the evaluation metric. All experiments are computed on 8 A800 GPUs.

4.2 EXPERIMENTAL RESULTS

Cross-domain transfer scenarios. Table 1 shows the results for the cross-domain transfer setting. Detailed results are provided in Table 8 and Table 9. We observe that the performance of the

cross-task few-shot prompting is highly dependent on the similarity between source and target domains. When domains are closely related (e.g., ARC-Easy → ARC-Challenge), incorporating source-domain examples improves performance. In contrast, for dissimilar domain pairs (e.g., ARC-Easy → MedMCQA), such examples introduce noise and lead to performance degradation. For parameter-efficient fine-tuning (PEFT) methods, performance varies more substantially across different task pairs. Fine-tuning with source task examples generalizes effectively to similar target tasks, but impairs performance on dissimilar ones. All activation steering methods facilitate effective cross-domain transfer due to the consistent directions of information-enhanced features in the latent space across different domains. Among these, **FAST** consistently outperforms all baselines across all domain pairs. This is because our approach applies the Fourier transformation method to disentangle information-enhanced and domain-specific activations within the difference vectors. By injecting both task-agnostic enhanced features and similarity-weighted domain-specific information, **FAST** enhances general model capability while avoiding the injection of irrelevant domain noise.

Cross-lingual transfer scenarios. Table 2 presents the results for the cross-lingual transfer setting. Detailed statistics are provided in Table 10. We find that the performance of cross-lingual few-shot prompting is strongly influenced by the linguistic similarity between source and target languages. For closely related language pairs (e.g., French → German), incorporating cross-lingual examples generally improves performance. In contrast, for distant language pairs (e.g., English → Chinese), such demonstrations often introduce noise and lead to negative transfer. Similar to the cross-domain scenario, PEFT methods amplify this phenomenon, exhibiting higher variance across language pairs. Furthermore, activation steering methods effectively facilitate cross-lingual transfer by operating in the latent space, achieving robust performance across diverse language pairs. Among these, **FAST** achieves the best performance by leveraging the Fourier transformation to decouple information-enhanced features via low-pass filtering. Furthermore, it selectively injects high-frequency domain-specific features when source and target tasks exhibit high similarity, which enables more effective and stable latent space steering for cross-lingual transfer.

4.3 ABLATION STUDY

Our approach introduces two key components: (1) Influential and diverse subset selection, and (2) Fourier-based activation steering. To verify the effectiveness of each component, we conduct ablation studies on three target tasks: ARC-Challenge, Financial Phrasebank, and MedMCQA. We also compare our subset selection method with two established approaches (i.e., Vote-k (Su et al., 2023) and IDEAL (Zhang et al., 2024)). The results are presented in Table 3. We observe that removing any component leads to performance degradation across all tasks, confirming that both elements are essential to our method. Notably, the removal of information-enhanced activation causes the most significant performance drop, indicating that these activations provide the most important signals for cross-task transfer. Furthermore, our selection strategy outperforms both Vote-k and IDEAL, demonstrating the effectiveness of the proposed approach.

4.4 THE EFFICIENCY OF FAST

In this part, we analyze the computational efficiency of our method in comparison to baseline methods. As shown in Table 4, our approach demonstrates significant advantages in both time complexity and runtime. **FAST** maintains the same time complexity, $O(n^2)$, as zero-shot prompting, which is substantially more efficient than few-shot methods that exhibit $O((d + n)^2)$ complexity due to their longer in-

Table 3: Ablation study.

Dataset	ARC-C	FPB	MedMCQA
FAST	76.14	59.26	56.09
<i>Subset Selection</i>			
w/o Influence Score	75.62	56.91	54.83
w/o Diversity Penalty	74.91	57.38	55.29
w/o Both	73.72	54.29	53.18
Vote-k	75.46	57.89	55.35
IDEAL	75.69	58.04	55.04
<i>Activation Steering</i>			
w/o Information-enhanced Activation	72.25	48.32	51.89
w/o Task-specific Activation	75.48	56.59	57.71
w/o Both	71.80	37.80	49.40

Table 4: Efficiency comparison of different methods. “T.C.” denotes time complexity, where n and d represent the length of the question and demonstrations, respectively.

Method	Inference T.C.	Preprocess Time (s)	Training Time (s)	Inference Time (s)	Total Time (s)
Zero-shot	$O(n^2)$	0	0	212	212
Few-shot Random	$O((d + n)^2)$	0	0	451	451
Few-shot DPP	$O((d + n)^2)$	138	0	454	592
AdaLoRA	$O(n^2)$	0	332	215	547
FAST	$O(n^2)$	172	0	221	393

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Table 5: Experiments on generation tasks.
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Method	XSum	GSM8K	LiveCodebench	GPQA	Average
Prompting	Zero-shot	28.32	76.65	16.67	35.29
	Few-shot Random	27.46 ± 3.48	79.91 ± 4.95	11.74 ± 2.94	31.14 ± 5.02
	Few-shot TopK	28.04 ± 2.76	80.89 ± 3.47	13.31 ± 2.34	31.68 ± 4.89
	Few-shot DPP	29.05 ± 3.18	81.20 ± 2.95	13.89 ± 2.49	32.97 ± 4.07
PEFT	QLoRA	23.42 ± 6.97	69.26 ± 5.08	12.79 ± 3.29	29.97 ± 6.38
	AdaLoRA	24.01 ± 6.14	70.91 ± 5.26	11.92 ± 4.05	30.48 ± 7.29
Activation Steering	ICV	31.82 ± 2.48	83.93 ± 2.18	18.20 ± 2.11	37.25 ± 3.48
	SEA	32.49 ± 1.97	84.91 ± 2.11	18.78 ± 1.94	38.82 ± 3.05
	FAST	34.41 ± 1.53	86.13 ± 1.74	20.55 ± 2.35	40.48 ± 3.75

445 put sequences. This is because our method injects activations into the model’s latent space during
446 the forward pass without adding additional tokens to the input. In terms of actual runtime, **FAST**
447 requires only 393 seconds in total, which includes 172 seconds for preprocessing (subset selection
448 and activation extraction) and 221 seconds for inference. This represents a notable improvement
449 over few-shot methods and PEFT approaches, demonstrating that **FAST** achieves effective cross-task
450 transfer while maintaining computational efficiency.

451 4.5 DETAILED ANALYSIS

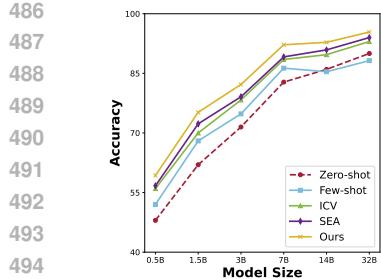
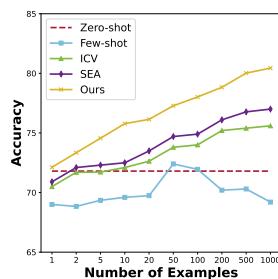
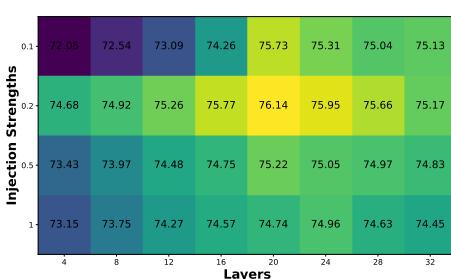
452 In this section, we present a detailed analysis of the proposed method. Unless otherwise stated, we
453 conduct experiments using ARC-Challenge as the target task.

454 **FAST performs well on different-scale LLMs.** We conduct experiments on Qwen-series LLMs
455 ranging from 0.5B to 32B in Figure 6, with additional results in Figure 9. Notably, activation
456 steering methods consistently outperform few-shot prompting across all model sizes. Among these,
457 **FAST** achieves the best performance by explicitly disentangling information-enhanced features from
458 task-specific activations, enabling more effective and robust cross-task transfer.

459 **FAST demonstrates strong scalability.** To evaluate the scalability of our proposed method, we
460 conduct experiments using different numbers of examples from the source task, as shown in Figure 7
461 (additional results in Figure 10). We find that the performance of cross-task few-shot learning initially
462 improves with more examples, but eventually plateaus or even drops when too many examples
463 are used. This can be attributed to the limited long-context capability of LLMs, which hinders the
464 effective use of large-scale high-resource data. In contrast, activation steering methods show a positive
465 correlation between the number of examples and model performance. With more demonstrations,
466 these methods better isolate instance-level variations and extract more general task-level features,
467 leading to more effective cross-task transfer. In particular, **FAST** demonstrates the strongest scalability
468 among all activation steering methods due to its decoupled activation injection method.

469 **Optimal performance of FAST at middle layers with moderate injection strength.** As shown
470 in Figure 8 (additional results in Figure 11), both the injection layer and the injection strength
471 significantly affect the performance of **FAST**. We find that injecting activations at middle layers
472 yields the best results, indicating that these layers encode richer features that are beneficial for
473 cross-task transfer. Furthermore, **FAST** achieves optimal results when the injection strength is set to
474 0.2. Higher values tend to disrupt the model’s inherent representations, while lower values produce
475 insufficient signals to effectively guide the model’s behavior toward the target task.

476 **Our method performs well on generation tasks.** To evaluate the generalizability of our proposed
477 method beyond classification tasks, we conduct experiments on a variety of generation tasks on
478 Qwen2.5-7B. We consider four generation benchmarks: XSum (Narayan et al., 2018) for summarization,
479 GSM8K (Cobbe et al., 2021) for mathematical reasoning, GPQA (Rein et al., 2024) for scientific
480 question answering, and LiveCodeBench (Jain et al., 2025) for code generation. The results are
481 presented in Table 5. We inject activations into the hidden state of the first token, as it steers the sub-
482 sequent generation process while minimizing disruption to the model’s inherent generation behavior.

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Figure 6: Model sizes496
Figure 7: Scalability497
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Figure 8: Injection layers and strengths

We observe that incorporating cross-task examples via cross-domain in-context learning often leads to performance degradation in these generation tasks. This suggests that, unlike in classification tasks, in-context examples from dissimilar tasks may introduce noise that disrupts the generation process. Besides, parameter-efficient fine-tuning methods also struggle to generalize effectively, likely due to their limited capacity to adapt to the generation tasks from dissimilarity tasks. Notably, activation steering methods consistently outperform both prompting-based and parameter-efficient fine-tuning baselines. Among these, our method achieves the best performance across all tasks. The consistent improvements highlight **FAST** can effectively inject transferable information-enhanced activations.

5 RELATED WORK

Transfer Learning. Transfer learning offers a promising solution to alleviate the scarcity of labeled data in low-resource tasks by leveraging knowledge from high-resource tasks. Existing transfer learning approaches for LLMs can be broadly categorized into two types: continuous and discrete cross-task transfer. Continuous methods (Vu et al., 2022; Li et al., 2022; Lv et al., 2024) learn shared continuous soft prompts from source tasks and apply them to the target tasks. While effective, these approaches require fine-tuning and often generalize poorly. On the other hand, discrete methods (Tanwar et al., 2023; Cahyawijaya et al., 2024; Li et al., 2023b; Chatterjee et al., 2024) incorporate high-resource examples into LLM inputs to solve low-resource tasks without parameter updates. However, such an approach suffers from limitations in robustness, scalability, and efficiency. To address these issues, we propose a novel approach to extract activations from high-resource tasks and inject them into low-resource tasks, which eliminates the need for fine-tuning or input expansion.

Activation Steering. Activation steering is an established technique that treats internal representations as fundamental units for analysis and manipulation within neural networks. It has been applied across various scenarios, including model alignment (Liu et al., 2024b), personality modeling (Cao et al., 2024), instruction following (Stolfo et al., 2025), hallucination mitigation (Li et al., 2023a; Arditì et al., 2024), safety enhancement (Liu et al., 2024a), and reasoning improvement (Højer et al., 2025; Tang et al., 2025). In this work, we adopt activation steering to transfer knowledge from data-sufficient to data-scarce tasks, providing a new pathway for effective cross-task generalization.

6 CONCLUSION

In this work, we explored the potential of achieving cross-task transfer in LLMs via latent space steering. Through empirical analysis, we found consistent activation patterns between few-shot and zero-shot prompts across tasks. Besides, we observed that the difference activations can be decomposed via Fourier transformation into information-enhanced (low-frequency) and task-specific (high-frequency) components. Based on these insights, we proposed **FAST**, a Fourier-based activation steering framework that transfers knowledge from high-resource to low-resource tasks without fine-tuning or context expansion. Extensive experiments in cross-domain and cross-lingual settings demonstrated that our method consistently outperformed existing approaches.

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Algorithm 1 Influence and Diversity-driven Sample Quantification($\mathcal{G}, S_{\text{selected}}, N_i(\cdot), v, k, \beta, \gamma$)

Inputs:
 Sample directed graph $\mathcal{G} = (\mathbf{V}, \mathbf{E}, \mathbf{P})$, i -hop neighbor function $N_i(\cdot)$, Current selected sample subset S_{selected} , Sample node v , Neighborhood depth k , Hop-based decay factor β , balance hyper-parameter between diversity and influence γ .

Initialize:
 $D(v) = 0, I(v) = 0, S_{\text{active}} \leftarrow v, S_{\text{visited}} \leftarrow \emptyset$

while $S_{\text{active}} \neq \emptyset$ **do** ▷ Influencial Calculation

- Choose a sample node $u \in S_{\text{active}}$
- for** each neighbor $w \in N_1(u)$ **do**

 - Select edge (u, w) with probability $p(u, w)$
 - if** edge (u, w) is selected **and** $w \notin S_{\text{visited}}$ **then**

 - $S_{\text{active}} \leftarrow S_{\text{active}} \cup w, S_{\text{visited}} \leftarrow S_{\text{visited}} \cup w$

 - end if**

- end for**
- $S_{\text{active}} \leftarrow S_{\text{active}} \setminus u$

end while

$I(v) = |S_{\text{visited}}|$

for $i = 1$ to k **do** ▷ Diversity Calculation

- Search i -hop neighbors of sample node v : $N_i(v)$;
- Compute overlap between i -hop neighbors and S_{selected} : $o_i \leftarrow |N_i(v) \cap S_{\text{selected}}|$
- $D(v) \leftarrow D(v) - \beta^i \cdot o_i$

end for

return Sample node v evaluation function: $F_{\mathcal{G}}(v) \leftarrow I(v) + \gamma \cdot D(v)$

Algorithm 2 Iterative Greedy Graph Search(\mathcal{G}, S, n)

```

779 Inputs:
780     Sample directed graph  $\mathcal{G} = (\mathbf{V}, \mathbf{E}, \mathbf{P})$ , Initial sample subset  $S_0$ , Selected sample subset size  $n$ .
781 Initialize:
782      $S_0 \rightarrow \emptyset, i = 0$ , Sample node evaluation function  $f_{\mathcal{G}} : \mathbf{V} \mapsto \mathbb{R}$  based on Algorithm 1
783 while  $i < n$  do
784      $v^* \leftarrow \arg \max_{v \in \mathbf{V} \setminus \mathcal{S}_i} F_{\mathcal{G}}(v)$ 
785      $\mathcal{S}_{i+1} \leftarrow \mathcal{S}_i \cup v^*$ 
786      $i \leftarrow i + 1$ 
787 end while
788 return  $\mathcal{S}_n$ .

```

A USAGE OF LLMs

In this paper, Large Language Models are used solely for polishing the writing.

B REPRODUCIBILITY STATEMENT

Our code is provided in the anonymous link to facilitate reproducibility.

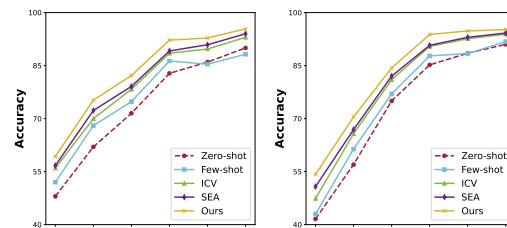
C ETHICS STATEMENT

This work adheres to the JCLR Code of Ethics. No ethical issues arise from this research.

D ADDITIONAL EXPERIMENTS

D.1 HYPERPARAMETER ANALYSIS

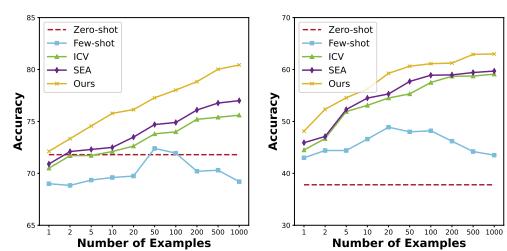
FAST includes a few hyperparameters to tune. In this section, we present a detailed analysis of their impact on model performance. For the influential and diverse subset selection strategy, we examine the hop-based decay factor α and the trade-off parameter γ that balances diversity and influence. The results are illustrated in Figure 13a and Figure 13b. As we can see, setting α too small or too large



(a) ARC-C

(b) FPB

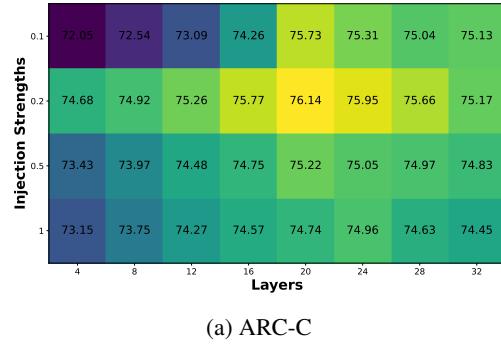
Figure 9: Different model sizes



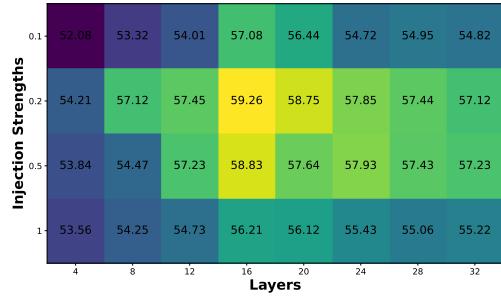
(a) ARC-C

(b) FPB

Figure 10: Scalability



(a) ARC-C



(b) FBR

Figure 11: Different injection layers and strengths

leads to a performance drop. If α is too small, the method may overlook meaningful connections between nodes that are indirectly linked. In contrast, an excessively large α would decrease the positional relationships between nodes within graphs. As for balanced hyperparameter γ , we find that choosing an appropriate value helps achieve a good balance, resulting in a subset that is both representative and diverse.

For the activation steering component, we investigate the effect of frequency cutoff k , similarity threshold ϵ and injection position, with results presented in Figure 13c, Figure 13d, and Table 6. We find that the frequency cutoff $k = d/2$ yields the best performance, as it effectively separates low- and high-frequency components. Besides, the optimal similarity threshold is 0.6. Performance remains relatively stable across values from 0.4 to 0.7, with our method consistently outperforming all baselines in this range. In addition, our finding reveals that injecting activations at the last token position consistently yields the best performance across models and target tasks. This is because the final token position aggregates sufficient contextual information, and modifications at this position can directly affect the output generation without disrupting the encoding of earlier tokens.

D.2 EXPERIMENTS ON MULTI-MODAL TASKS.

To further evaluate our proposed method, we conduct multimodal tasks using MathVista (Lu et al., 2024), MMStar (Chen et al., 2024b) and MMMU (Yue et al., 2024) datasets using Qwen2.5-VL-7B-Instruct (Bai et al., 2025). The results are presented in Table 7. The results show that our method consistently achieves the best performance on these multimodal reasoning tasks, demonstrating its broad applicability.

E DATASET DETAILS

In this part, we provide detailed descriptions of the datasets used in our experiments, covering both cross-domain and cross-lingual scenarios.

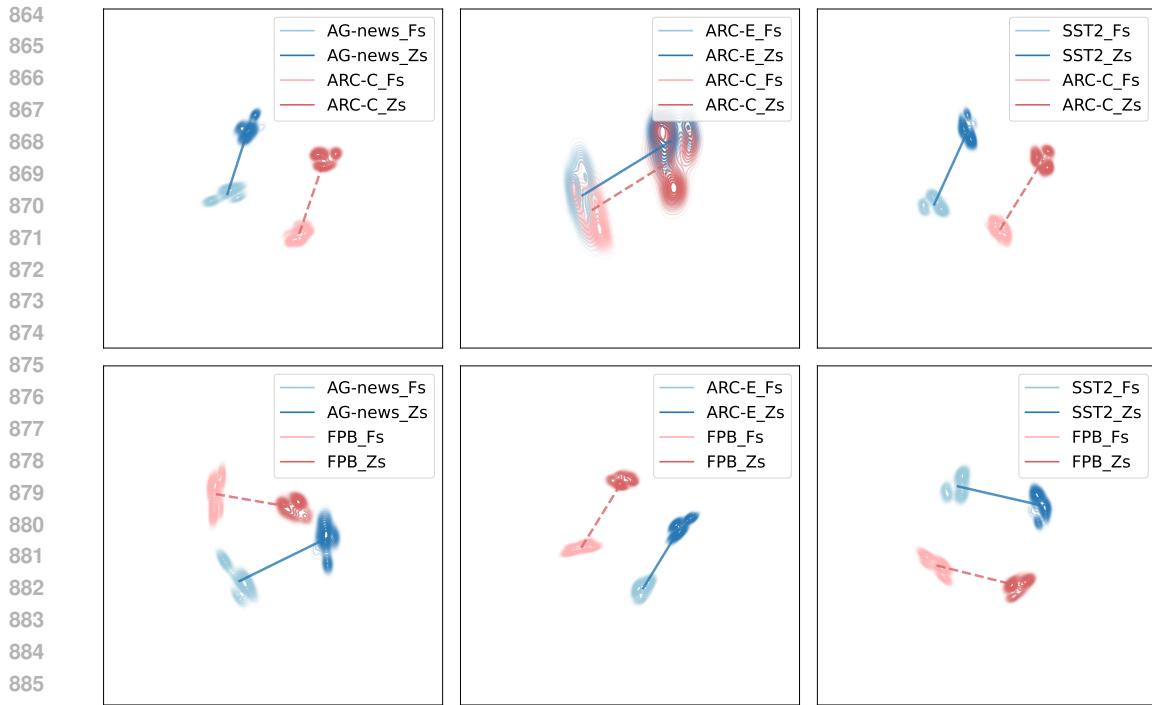


Figure 12: T-SNE projection of zero-shot and few-shot prompts across different source and target tasks.

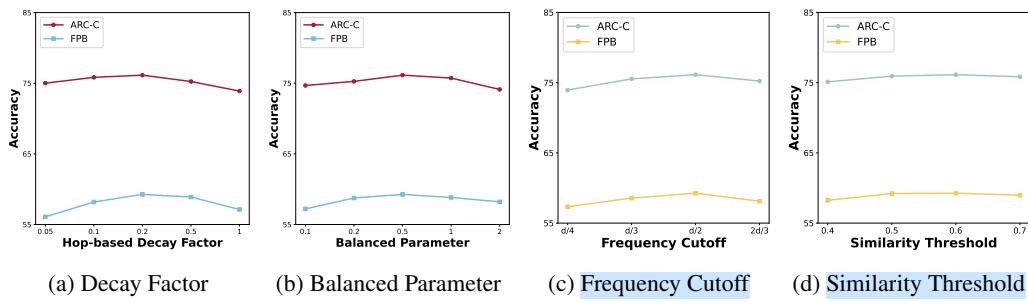


Figure 13: Hyperparameter Analysis

E.1 CROSS-DOMAIN SCENARIOS

- **ARC-Easy:** ARC-Easy (Clark et al., 2018) is a multiple-choice question-answering dataset, which consists of simple science exam questions from grade 3 to grade 9. These questions are designed to be straightforward and require basic knowledge.
- **AG-news:** AG-news (Zhang et al., 2015) is a news topic classification dataset, which is constructed by collecting article titles and descriptions from the four main categories: World, Sports, Business, and Sci/Tech.
- **BoolQ:** BoolQ (Clark et al., 2019) is a reading comprehension dataset with yes/no questions. The task requires answering these binary questions based on the given passages.
- **Commonsense-QA:** Commonsense-QA (Talmor et al., 2019) is a multiple-choice question answering dataset that requires different types of commonsense knowledge to find the correct answers.
- **MNLI:** The Multi-Genre Natural Language Inference (MNLI) (Williams et al., 2018) is a crowd-sourced collection of 433k sentence pairs annotated with textual entailment information. The task is to classify the relationship between two sentences as entailment, contradiction, or neutral.

918 Table 6: Performance comparison across different injection positions.
919

Position	Random	All	First	Last
Target Task: ARC-C				
Llama3.1-8B	73.12	74.69	76.02	76.14
Qwen2.5-7B	89.60	89.17	91.63	92.20
Target Task: FBR				
Llama3.1-8B	55.28	55.73	58.48	59.26
Qwen2.5-7B	89.75	87.68	91.86	93.80

928
929
930 Table 7: Experiments on multi-modal tasks.
931

	Method	MathVista	MMStar	MMMU	Average
Prompting	Zero-shot	68.52	64.12	58.08	63.57
	Few-shot Random	64.43 \pm 2.14	62.12 \pm 3.28	59.71 \pm 2.54	62.09 \pm 2.65
	Few-shot TopK	64.48 \pm 2.39	62.28 \pm 2.56	59.23 \pm 2.47	62.00 \pm 2.47
	Few-shot DPP	64.91 \pm 2.94	62.54 \pm 3.19	60.18 \pm 2.39	62.54 \pm 2.84
PEFT	QLoRA	60.53 \pm 5.12	65.23 \pm 7.19	58.24 \pm 4.17	61.33 \pm 5.49
	AdaLoRA	62.91 \pm 6.72	65.26 \pm 6.24	58.46 \pm 4.28	62.21 \pm 5.75
Activation Steering	ICV	71.17 \pm 1.48	65.19 \pm 2.23	61.24 \pm 1.82	65.87 \pm 1.84
	SEA	71.24 \pm 1.24	66.50 \pm 2.45	61.85 \pm 1.95	66.53 \pm 1.88
	FAST	73.34 \pm 1.31	68.83 \pm 1.57	64.12 \pm 1.72	68.76 \pm 1.53

945 • **QQP**: Quora Question Pairs (QQP) (Sharma et al., 2019) is a natural language understanding
946 dataset comprising over 400k question pairs. Each question pair is annotated with a binary label
947 indicating whether the two questions are duplicates of each other.

948 • **SST2**: The Stanford Sentiment Treebank (SST2) (Socher et al., 2013) is a binary sentiment
949 classification dataset, which contains the movie reviews labeled as either positive or negative.

950 • **ARC-Challenge**: ARC-Challenge (Clark et al., 2018) is a more difficult version of ARC-Easy. It
951 also includes science exam questions for grades 3 to 9, but requires deeper reasoning and advanced
952 problem-solving strategies.

953 • **Financial Phrasebank**: Financial Phrasebank (Malo et al., 2014) is a sentiment analysis dataset
954 focused on financial news, which consists of financial news articles annotated with sentiment labels
955 such as positive, negative, or neutral.

956 • **MedMCQA**: MedMCQA (Pal et al., 2022) is a large-scale, multiple-choice question answering
957 dataset, designed to address real-world medical entrance exam questions.

958 • **SciQ**: SciQ (Auer et al., 2023) is a multiple-choice question answering dataset comprising science
959 exam questions in the fields of physics, chemistry, and biology.

960 • **Social-i-QA**: Social-i-QA (Sap et al., 2019) is a question-answering benchmark designed to
961 evaluate social commonsense intelligence, which focuses on understanding people’s actions and their
962 social implications.

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968 E.2 CROSS-LINGUAL SCENARIOS
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970 • **MARC**: The Multilingual Amazon Reviews Corpus (MARC) (Keung et al., 2020) is a large-scale
971 collection of Amazon reviews for multilingual text classification, which contains reviews in six
972 languages: English, Japanese, German, French, Spanish, and Chinese.

972 F DETAILED DESCRIPTION OF BASELINES
973

974 In this part, we provide detailed descriptions of all the baselines used in our experiments. Our baselines
975 include prompting methods (*i.e.*, Zero-shot, Few-shot Random, Few-shot TopK (Liu et al., 2022b),
976 Few-shot DPP (Ye et al., 2023)), parameter-efficient fine-tuning methods (*i.e.*, QLoRA (Dettmers
977 et al., 2023) and AdaLoRA (Zhang et al., 2023)), and activation steering methods (*i.e.*, ICV (Liu
978 et al., 2024a) and SEA (Qiu et al., 2024)).

979 • **Zero-shot**: The model generates predictions using only the input query from the target task, without
980 any demonstrations or examples from source tasks.
981

982 • **Few-shot Random**: This method randomly selects a set of examples from the source task.
983

984 • **Few-shot TopK** (Liu et al., 2022b): This approach selects examples from the source task based on
985 their similarity to the target input.
986

987 • **Few-shot DPP** (Ye et al., 2023): This method uses Determinantal Point Processes (DPP) to select
988 a diverse and representative set of examples from the source task.
989

990 • **QLoRA** (Dettmers et al., 2023): Quantized Low-Rank Adaptation (QLoRA) is a parameter-efficient
991 fine-tuning method that uses quantized weights and low-rank adapters to achieve cross-task transfer.
992

993 • **AdaLoRA** (Zhang et al., 2023): Adaptive Low-Rank Adaptation (AdaLoRA) dynamically allocates
994 parameter budget based on the importance of different weight matrices. It supports cross-task transfer
995 by fine-tuning on samples from the source task.
996

997 • **ICV** (Liu et al., 2024a): In-context Vectors (ICV) steers model behavior by computing and injecting
998 pre-computed PCA-projected activation vectors to the model’s hidden states during inference.
999

1000 • **SEA** (Qiu et al., 2024): Spectral Editing of Activations (SEA) uses SVD to project activations into
1001 directions derived from positive and negative demonstrations. It then incorporates the difference
1002 representations to steer model behavior toward desired outputs.
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1026 **G CASE STUDY**
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10301031 *Case Study 1*
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Zero-shot:

1034 Definition: Given a question answering task from the 3rd to 9th-grade science exam. The
 1035 question contains four options "A.", "B.", "C." and "D." Select the most appropriate choice
 1036 that answers the question.

1037 Question: A student mixed 25 grams of salt into 1,000 grams of water. What is the mass of
 1038 the saltwater mixture?

- 1039 A. 975 grams
- 1040 B. 1,000 grams
- 1041 C. 1,025 grams
- 1042 D. 2,500 grams

1043 Answer: **B**

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1045

Few-shot:

1046 Definition: Given a context and a question do binary true and false type text classification.
 1047 You are given a passage as context and a question related to the passage that can be
 1048 answered as "True" or "False". Based on the context, question and your reasoning ability
 1049 answer in a "True" and "False".

1050 Context: Usually, the relationship between mass and weight on Earth is highly proportional;
 1051 objects that are a hundred times more massive than a one-liter bottle of soda almost always
 1052 weigh a hundred times more—approximately 1,000 newtons, which is the weight one would
 1053 expect on Earth from an object with a mass slightly greater than 100 kilograms. Yet,
 1054 this is not always the case and there are familiar objects that violate this mass / weight
 1055 proportionality.

1056 Question: Is mass the same as weight on earth?

1057 Label:False

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1061

Definition: Given a question answering task from the 3rd to 9th-grade science exam. The
 question contains four options "A.", "B.", "C." and "D." Select the most appropriate choice
 that answers the question.

1062 Question: A student mixed 25 grams of salt into 1,000 grams of water. What is the mass of
 1063 the saltwater mixture?

- 1064 A. 975 grams
- 1065 B. 1,000 grams
- 1066 C. 1,025 grams
- 1067 D. 2,500 grams

1068 Answer: **A**

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1070

Ours:

1071 Definition: Given a question answering task from the 3rd to 9th-grade science exam. The
 1072 question contains four options "A.", "B.", "C." and "D." Select the most appropriate choice
 1073 that answers the question.

1074 Question: A student mixed 25 grams of salt into 1,000 grams of water. What is the mass of
 1075 the saltwater mixture?

- 1076 A. 975 grams
- 1077 B. 1,000 grams
- 1078 C. 1,025 grams
- 1079 D. 2,500 grams

Answer: **C**

1080
1081**Case Study 2**

1082

Zero-shot:

1083

Definition: Given a sentence mined from a financial news article, you are to determine the sentiment polarity of the sentence. The task deals with financial sentiment analysis. Based on the sentiment conveyed by the sentence, label the sentence as "negative", "positive" or "neutral".

1084

Sentence: Equipment will be manufactured in Vaahto 's workshop in Hollola , Finland and is scheduled for shipments during the first quarter of 2009 .

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Label: **positive**

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Few-shot:

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Definition: Given a context and a question do binary true and false type text classification. You are given a passage as context and a question related to the passage that can be answered as "True" or "False". Based on the context, question and your reasoning ability answer in a "True" and "False".

1093

Context: Harley-Davidson India is a wholly owned subsidiary of Harley-Davidson, based in Gurgaon, Haryana, India. Harley-Davidson India commenced operations in August 2009 and appointed its first dealership in July 2010. Question: does harley davidson have a plant in india Label:True

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Definition: Given a sentence mined from a financial news article, you are to determine the sentiment polarity of the sentence. The task deals with financial sentiment analysis. Based on the sentiment conveyed by the sentence, label the sentence as "negative", "positive" or "neutral".

1096

Sentence: Equipment will be manufactured in Vaahto 's workshop in Hollola , Finland and is scheduled for shipments during the first quarter of 2009 .

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Label: **positive**

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1135**Case Study 3**

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Zero-shot:

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Definition: Given a multiple choice question containing four options "A.", "B.", "C." and "D." from a medical entrance exam. The question is related to a sub-field of medical science like Microbiology, Radiology, Ophthalmology, Surgery, Human anatomy, etc. Based on the question, the option and your knowledge of the medical field select the most appropriate answer from the provided choices "A.", "B.", "C." and "D."

1138

Question: Which of the following is not a component of quick SOFA (qSOFA) scoring?

1139

- A. Bilateral undilated pupils
- B. Altered Mentation
- C. Glasgow Coma Score
- D. SBP \leq 100 mm Hg

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Answer: **C**

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Few-shot:

Definition: Given a context and a question do binary true and false type text classification. You are given a passage as context and a question related to the passage that can be answered as "True" or "False". Based on the context, question and your reasoning ability answer in a "True" and "False".

Context: The series debuted on January 26, 2017 to positive reviews. A 22-episode second season premiered on October 11, 2017, and concluded on May 16, 2018. On April 2, 2018, The CW renewed the series for a third season, which is set to premiere October 10, 2018.

Question: is there going to be any more episodes of riverdale

Label:True

...

Definition: Given a multiple choice question containing four options "A.", "B.", "C." and "D." from a medical entrance exam. The question is related to a sub-field of medical science like Microbiology, Radiology, Ophthalmology, Surgery, Human anatomy, etc. Based on the question, the option and your knowledge of the medical field select the most appropriate answer from the provided choices "A.", "B.", "C." and "D."

Question: Which of the following is not a component of quick SOFA (qSOFA) scoring?

- A. Bilateral undilated pupils
- B. Altered Mentation
- C. Glasgow Coma Score
- D. SBP \leq 100 mm Hg

Answer: **C**

Ours:

Definition: Given a multiple choice question containing four options "A.", "B.", "C." and "D." from a medical entrance exam. The question is related to a sub-field of medical science like Microbiology, Radiology, Ophthalmology, Surgery, Human anatomy, etc. Based on the question, the option and your knowledge of the medical field select the most appropriate answer from the provided choices "A.", "B.", "C." and "D."

Question: Which of the following is not a component of quick SOFA (qSOFA) scoring?

- A. Bilateral undilated pupils
- B. Altered Mentation
- C. Glasgow Coma Score
- D. SBP \leq 100 mm Hg

Answer: **A**

1188
1189**Case Study**

1190

Zero-shot:

1191

Definition: Given a question from a scientific exam about Physics, Chemistry, and Biology, among others. The question is in multiple choice format with four answer options "A.", "B.", "C." and "D.". Using your knowledge about the scientific fields answer the question and provide the label "A", "B", "C" and "D" as answer.

1192

Question: What happens to energy when work is done by a system?

1193

- A. removed
- B. stored
- C. multiplied
- D. added

1194

Answer: **B**

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Few-shot:

1203

Definition: Given a context and a question do binary true and false type text classification. You are given a passage as context and a question related to the passage that can be answered as "True" or "False". Based on the context, question and your reasoning ability answer in a "True" and "False".

1204

Context: The sixth season of the American ABC fantasy-drama Once Upon a Time was ordered on March 3, 2016. It debuted on September 25, 2016, and concluded on May 14, 2017. In January 2017, it was stated that the sixth season would end the main storyline, and for a seventh season, the series would be softly rebooted with a new storyline.

1205

Question: is there a season six of once upon a time

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Label:True

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1214

Definition: Given a question from a scientific exam about Physics, Chemistry, and Biology, among others. The question is in multiple choice format with four answer options "A.", "B.", "C." and "D.". Using your knowledge about the scientific fields answer the question and provide the label "A", "B", "C" and "D" as answer.

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Question: What happens to energy when work is done by a system?

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- A. removed
- B. stored
- C. multiplied
- D. added

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Answer: **B**

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Ours:

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Definition: Given a question from a scientific exam about Physics, Chemistry, and Biology, among others. The question is in multiple choice format with four answer options "A.", "B.", "C." and "D.". Using your knowledge about the scientific fields answer the question and provide the label "A", "B", "C" and "D" as answer.

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Question: What happens to energy when work is done by a system?

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- A. removed
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Answer: **A**

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1255 Table 8: Experiments on cross-domain scenarios using Llama3.1-8B.

Model	Target Task	Method	Source Task							Average
			ARC-Easy	AG-news	BoolQ	Com-QA	MNLI	QQP	SST2	
Llama3.1-8B	ARC-Challenge (Zs: 71.80)	Few-shot Random	72.40	68.00	72.40	70.60	64.60	67.20	70.00	69.31 \pm 2.66
		Few-shot TopK	74.20	69.20	69.80	71.20	66.20	67.40	68.80	69.54 \pm 2.42
		Few-shot DPP	75.20	66.40	71.00	71.40	67.80	67.00	69.40	69.74 \pm 2.85
		QLoRA	74.80	64.40	72.40	72.00	65.20	68.40	68.00	69.31 \pm 3.60
		AdaLoRA	75.00	63.80	72.80	71.80	66.40	69.20	69.20	69.74 \pm 3.55
		ICV	74.40	72.20	73.20	72.40	72.00	71.20	73.00	72.63 \pm 0.95
		SEA	74.20	72.60	73.60	74.00	73.40	72.80	73.80	73.49 \pm 0.55
		FAST	75.80	76.40	75.60	77.20	76.20	75.60	76.20	76.14\pm0.52
	Financial Phrasebank (Zs: 37.80)	Few-shot Random	44.80	48.20	46.40	48.80	56.80	48.60	46.00	48.51 \pm 3.65
		Few-shot TopK	42.00	47.20	46.00	47.00	61.60	52.40	44.20	48.63 \pm 6.07
		Few-shot DPP	40.80	47.60	46.80	49.60	61.80	49.80	45.80	48.89 \pm 5.96
		QLoRA	44.40	54.50	52.80	49.00	63.00	56.80	45.80	52.33 \pm 6.04
		AdaLoRA	43.80	55.80	53.60	49.40	63.20	58.80	44.20	52.69 \pm 6.76
		ICV	48.80	56.60	55.00	51.20	61.80	58.20	50.00	54.51 \pm 4.40
		SEA	49.60	57.80	56.20	51.40	62.40	59.00	50.60	55.29 \pm 4.49
		FAST	54.60	60.40	59.40	53.40	64.00	64.40	58.60	59.26\pm3.90
	MedMCQA (Zs: 49.40)	Few-shot Random	47.00	50.00	46.80	47.60	53.20	46.60	49.60	48.69 \pm 2.23
		Few-shot TopK	47.80	49.00	47.80	47.40	52.80	47.40	48.60	48.69 \pm 1.77
		Few-shot DPP	49.00	49.80	50.20	47.40	54.00	47.20	50.60	49.74 \pm 2.12
		QLoRA	49.20	52.00	49.20	48.40	55.20	44.20	52.20	50.06 \pm 3.24
		AdaLoRA	49.40	52.40	49.80	48.80	55.60	44.20	51.40	50.23 \pm 3.26
		ICV	52.60	53.60	51.00	51.80	54.20	52.20	54.00	52.77 \pm 1.11
		SEA	53.80	54.20	51.60	52.40	54.20	52.40	54.40	53.29 \pm 1.04
		FAST	57.20	56.80	55.40	55.80	56.00	55.20	56.20	56.09\pm0.67
	SciQ (Zs: 84.40)	Few-shot Random	88.20	84.20	86.60	87.80	80.00	81.80	83.80	84.63 \pm 2.85
		Few-shot TopK	87.60	82.20	85.80	87.00	83.20	81.60	86.60	84.86 \pm 2.28
		Few-shot DPP	87.40	86.40	87.00	87.80	82.60	82.00	83.60	85.26 \pm 2.26
		QLoRA	88.60	83.00	88.80	88.00	77.00	78.20	84.20	83.97 \pm 4.53
		AdaLoRA	88.40	82.80	88.60	87.80	78.20	78.40	85.30	84.21 \pm 4.19
		ICV	89.80	89.20	90.20	88.20	84.00	83.80	87.00	87.46 \pm 2.45
		SEA	90.20	89.40	90.60	88.40	85.20	84.80	87.40	88.00 \pm 2.14
		FAST	91.60	92.00	91.00	90.00	89.00	89.80	89.60	90.43\pm1.03
	Social-i-QA (Zs: 55.40)	Few-shot Random	60.40	58.00	59.60	62.40	59.00	57.20	57.40	59.14 \pm 1.71
		Few-shot TopK	61.80	60.80	58.80	62.80	58.60	56.80	56.00	59.37 \pm 2.35
		Few-shot DPP	60.20	61.00	60.00	60.00	60.00	59.60	56.40	59.60 \pm 1.36
		QLoRA	61.40	56.00	61.00	64.40	55.20	54.20	52.20	57.77 \pm 4.16
		AdaLoRA	62.00	56.40	60.60	65.40	56.00	53.80	51.00	57.89 \pm 4.64
		ICV	63.00	61.40	61.00	64.80	60.20	60.20	60.20	61.54 \pm 1.62
		SEA	62.80	61.80	61.80	64.80	61.40	61.80	60.40	62.11 \pm 1.28
		FAST	65.60	63.20	64.20	66.40	63.40	65.60	63.60	64.57\pm1.18

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Table 9: Experiments on cross-domain scenarios using Qwen2.5-7B.

Model	Target Task	Method	Source Task							Average
			ARC-Easy	AG-news	BoolQ	Com-QA	MNLI	QQP	SST2	
Qwen2.5-7B	ARC-Challenge (Zs: 82.80)	Few-shot Random	86.80	86.60	83.20	86.60	84.40	86.20	86.80	85.80 ± 1.32
		Few-shot TopK	87.40	86.40	86.00	86.60	84.60	86.60	86.60	86.31 ± 0.80
		Few-shot DPP	87.20	86.60	86.00	86.80	85.00	86.00	86.60	86.31 ± 0.67
		QLoRA	91.20	82.20	84.00	87.80	82.20	87.20	89.80	86.34 ± 3.34
		AdaLoRA	91.40	83.40	82.60	87.60	81.20	87.60	90.40	86.31 ± 3.67
		ICV	90.80	88.00	88.20	88.00	87.40	89.00	88.00	88.49 ± 1.04
		SEA	91.20	89.40	89.00	88.40	87.80	89.40	88.80	89.14 ± 0.99
		FAST	93.40	92.20	92.40	92.80	90.00	91.80	92.80	92.20 ± 1.01
Qwen2.5-7B	Financial Phrasebank (Zs: 85.20)	Few-shot Random	87.60	86.80	89.80	87.00	85.60	84.00	87.40	86.89 ± 1.66
		Few-shot TopK	89.20	88.00	89.60	86.40	84.00	86.60	90.00	87.69 ± 1.99
		Few-shot DPP	87.60	87.80	90.40	86.20	86.20	86.80	89.20	87.74 ± 1.46
		QLoRA	89.20	84.20	92.40	82.20	84.80	83.80	92.80	87.06 ± 4.03
		AdaLoRA	89.40	83.80	93.60	83.60	85.20	85.20	93.20	87.71 ± 4.01
		ICV	90.20	89.80	92.80	89.60	88.00	89.20	93.40	90.43 ± 1.81
		SEA	90.80	90.40	93.60	89.80	88.60	89.00	93.00	90.74 ± 1.77
		FAST	94.60	93.20	94.60	93.80	92.60	93.60	94.20	93.80 ± 0.68
Qwen2.5-7B	MedMCQA (Zs: 52.00)	Few-shot Random	54.80	53.60	55.80	55.40	52.00	55.00	54.00	54.37 ± 1.20
		Few-shot TopK	54.80	54.20	55.40	55.00	53.00	54.80	54.60	54.54 ± 0.71
		Few-shot DPP	55.60	53.40	54.20	55.00	53.80	55.40	54.80	54.60 ± 0.76
		QLoRA	56.20	51.20	54.20	60.40	50.20	60.40	56.00	55.51 ± 3.72
		AdaLoRA	56.40	50.80	54.80	60.80	50.80	61.20	56.20	55.86 ± 3.89
		ICV	59.20	55.00	57.40	58.60	55.80	58.20	57.20	57.34 ± 1.40
		SEA	59.60	56.20	57.80	60.20	56.40	59.40	57.20	58.11 ± 1.50
		FAST	62.00	59.00	60.60	63.00	60.00	62.40	59.00	60.86 ± 1.51
Qwen2.5-7B	SciQ (Zs: 89.60)	Few-shot Random	91.20	89.60	91.60	91.00	88.40	88.20	87.40	89.63 ± 1.55
		Few-shot TopK	91.20	89.20	92.20	91.20	88.80	88.80	88.80	90.03 ± 1.35
		Few-shot DPP	91.40	89.00	92.00	91.60	88.60	89.80	87.20	89.94 ± 1.66
		QLoRA	93.20	86.20	94.60	93.80	85.20	84.60	83.40	88.71 ± 4.54
		AdaLoRA	93.80	87.40	94.60	94.40	86.40	85.20	84.60	89.49 ± 4.23
		ICV	93.80	90.00	93.00	93.60	90.00	91.20	91.80	91.91 ± 1.48
		SEA	94.40	91.60	93.40	94.00	91.00	91.80	92.40	92.66 ± 1.20
		FAST	96.40	94.20	95.80	95.40	94.80	95.00	95.00	95.23 ± 0.66
Qwen2.5-7B	Social-i-QA (Zs: 76.00)	Few-shot Random	78.60	75.60	78.40	77.00	78.00	76.00	75.40	77.00 ± 1.26
		Few-shot TopK	78.00	76.20	77.60	77.20	78.00	76.00	75.80	76.97 ± 0.88
		Few-shot DPP	78.00	75.40	78.80	76.60	77.20	75.60	76.20	76.83 ± 1.16
		QLoRA	81.20	73.20	79.20	80.40	81.40	72.40	73.40	77.31 ± 3.80
		AdaLoRA	81.80	73.00	79.80	80.20	81.40	73.20	73.80	77.60 ± 3.75
		ICV	81.60	80.20	79.80	81.20	80.80	78.00	79.20	80.11 ± 1.15
		SEA	82.00	80.80	80.20	81.60	81.60	78.00	79.00	80.46 ± 1.38
		FAST	84.20	83.80	83.60	84.40	83.80	81.80	82.60	83.46 ± 0.86

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Table 10: Performance comparison in the cross-lingual scenarios.

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Target Language	Method	Source Language						Average
		de	en	es	fr	ja	zh	
de (Zs: 84.40)	Few-shot Random	-	76.80	84.00	93.00	87.60	86.80	85.64 \pm 5.30
	Few-shot TopK	-	77.20	85.40	93.80	86.80	87.40	86.12 \pm 5.31
	Few-shot DPP	-	77.20	86.20	92.60	87.20	88.60	86.36 \pm 5.07
	QLoRA	-	75.20	88.40	94.20	83.20	84.80	85.16 \pm 6.25
	AdaLoRA	-	75.80	88.00	94.60	84.40	85.40	85.64 \pm 6.07
	ICV	-	86.60	88.20	94.00	91.40	90.60	90.16 \pm 2.57
	SEA	-	87.00	88.60	94.80	91.00	90.80	90.44 \pm 2.63
en (Zs: 66.00)	FAST	-	89.80	90.80	95.80	93.20	92.80	92.48 \pm 2.08
	Few-shot Random	77.40	-	42.80	58.00	76.80	41.80	59.36 \pm 15.58
	Few-shot TopK	76.80	-	51.00	62.40	79.60	38.00	61.56 \pm 15.65
	Few-shot DPP	76.80	-	58.80	68.80	80.00	38.00	64.48 \pm 15.13
	QLoRA	71.40	-	60.60	72.80	85.80	26.80	63.48 \pm 20.01
	AdaLoRA	73.60	-	62.40	74.60	86.40	28.40	65.08 \pm 19.85
	ICV	85.40	-	80.40	85.80	86.20	76.20	82.80 \pm 3.92
es (Zs: 81.60)	SEA	86.80	-	81.60	87.40	85.20	79.80	84.16 \pm 2.97
	FAST	90.60	-	86.00	91.20	90.40	87.00	89.04 \pm 2.11
	Few-shot Random	83.80	83.80	-	83.60	81.60	82.20	83.48 \pm 9.58
	Few-shot TopK	84.00	83.00	-	84.20	83.00	83.20	83.68 \pm 9.73
	Few-shot DPP	84.00	84.20	-	83.60	83.40	83.40	85.40 \pm 8.42
	QLoRA	87.80	85.20	-	84.60	81.40	74.80	82.16 \pm 13.17
	AdaLoRA	88.60	84.40	-	84.20	80.20	76.80	83.00 \pm 14.07
fr (Zs: 86.60)	ICV	92.20	91.60	-	92.40	91.20	89.40	91.96 \pm 2.06
	SEA	91.40	92.40	-	93.20	92.00	89.60	92.20 \pm 1.62
	FAST	95.20	95.60	-	95.20	94.60	93.80	95.20 \pm 0.40
	Few-shot Random	91.80	65.60	84.00	-	91.80	84.20	81.40 \pm 9.65
	Few-shot TopK	91.40	65.40	86.80	-	92.00	82.80	81.75 \pm 9.99
	Few-shot DPP	91.40	69.40	89.40	-	92.20	84.60	83.90 \pm 8.80
	QLoRA	93.40	58.20	88.00	-	93.00	78.20	79.35 \pm 13.32
ja (Zs: 38.60)	AdaLoRA	94.20	56.80	90.20	-	93.80	80.00	80.20 \pm 14.43
	ICV	93.00	91.40	92.40	-	94.60	88.40	91.70 \pm 2.23
	SEA	93.60	92.00	91.60	-	94.20	89.60	91.85 \pm 1.63
	FAST	95.00	95.20	95.80	-	95.40	94.60	95.25 \pm 0.43
	Few-shot Random	49.00	27.80	40.60	43.00	-	36.00	39.28 \pm 7.11
	Few-shot TopK	49.40	26.00	41.40	43.60	-	36.60	39.40 \pm 7.86
	Few-shot DPP	50.40	25.20	43.40	44.00	-	36.20	39.84 \pm 8.59
zh (Zs: 30.80)	QLoRA	50.40	15.60	45.60	46.80	-	30.20	37.72 \pm 13.05
	AdaLoRA	50.80	18.40	46.00	46.40	-	32.40	38.80 \pm 11.92
	ICV	51.20	40.40	44.80	45.40	-	39.80	44.32 \pm 4.11
	SEA	51.80	42.00	45.40	44.80	-	41.40	45.08 \pm 3.70
	FAST	53.20	47.00	47.60	47.00	-	45.80	48.12 \pm 2.61
	Few-shot Random	49.00	35.00	33.60	32.00	37.20	-	37.36 \pm 6.07
	Few-shot TopK	49.20	36.60	35.80	33.20	37.00	-	38.36 \pm 5.58
zh (Zs: 30.80)	Few-shot DPP	51.60	35.80	37.00	31.40	37.80	-	38.72 \pm 6.81
	QLoRA	51.20	28.60	34.00	26.80	39.00	-	35.92 \pm 8.76
	AdaLoRA	52.40	28.20	35.20	28.40	39.80	-	36.80 \pm 8.94
	ICV	52.00	38.00	39.00	36.60	40.20	-	41.16 \pm 5.55
	SEA	53.20	39.20	38.80	38.80	41.20	-	42.24 \pm 5.55
	FAST	53.20	42.80	42.20	43.20	43.00	-	44.88 \pm 4.17

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