# On the Confidence of Neural Network Predictions for some NLP Tasks

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## Abstract

1	Neural networks are known to produce unexpected results on inputs that are far
2	from the training distribution. One approach to tackle this problem is to detect the
3	samples on which the trained network can not answer reliably. ODIN is a recently
4	proposed method for out-of-distribution detection that does not modify the trained
5	network and achieves good performance for various image classification tasks. In
6	this paper we adapt ODIN for sentence classification and word tagging tasks. We
7	show that the scores produced by ODIN can be used as a confidence measure for
8	the predictions on both in-distribution and out-of-distribution datasets.

## 9 1 Introduction

Neural networks have been shown to perform well on various computer vision and natural language processing tasks. The performance of neural networks is usually measured on the test sets of the corresponding datasets, which does not show how the networks would perform on the samples from

13 other distributions.

Complex neural models that perform well on ImageNet dataset produce nonsensical labels for images
 far from its training and test sets (see [Nguyen et al., 2015] for examples on unrecognizable images
 and Figure 1 from [Shafaei et al., 2018] for more realistic images). Similar examples can be found

for neural models for NLP tasks. Table 1 shows the results of a simple neural POS tagger on different
 sentences.

UD English-LinES (Accuracy = $14.3\%$ , PbThreshold(s) = $0.99598$ , ODIN(s) = $0.05904$ )										
Sentence	Identifying	filters	that	are	currently	in	effect			
Ground truth	VERB	NOUN	PRON	VERB	ADV	ADP	NOUN			
Predicted labels	ADJ	NOUN	PRON	VERB	ADV	ADP	NOUN			
Probabilities	0.97	1.00	1.00	1.00	1.00	1.00	1.00			
UD English-EWT (Accuracy = $42.9\%$ , PbThreshold(s) = $0.89237$ , ODIN(s) = $0.05899$ )										
Sentence	Try	googling	it	for	more	info	:)			
Ground truth	VERB	VERB	PRON	ADP	ADJ	NOUN	SYM			
Predicted labels	PRON	VERB	PRON	ADP	ADV	ADV	PUNCT			
Probabilities	0.58	1.00	1.00	0.99	1.00	0.70	0.98			
UD Dutch-Alpino (Accuracy = 57.1%, PbThreshold( $s$ ) = 0.99699, ODIN( $s$ ) = 0.05906)										
Sentence	Daarbij	is	een	Macedonische	militair	gedood				
Ground truth	ADV	AUX	DET	ADJ	NOUN	VERB	PUNCT			
Predicted labels	NOUN	AUX	DET	ADJ	ADJ	NOUN	PUNCT			
Probabilities	1.00	1.00	0.98	1.00	1.00	1.00	1.00			

Table 1: The output of a neural POS tagger trained on English-LinES dataset on samples from three different datasets.

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<sup>19</sup> This limitation of neural networks makes it hard to deploy them in critical applications. One of the <sup>20</sup> possible directions to solve the problem is to measure the confidence of the prediction and do not

output the prediction if the confidence is low.

Hendrycks and Gimpel [2017] showed that for various neural models, correctly classified examples
tend to have higher maximum softmax probabilities than incorrectly classified examples and out-ofdistribution examples. They performed several experiments on deep convolutional networks trained
on CIFAR-10 and CIFAR-100 and show that by looking at the maximum predicted probability one
can classify images from CIFAR-10 and SUN test sets with 95% AUROC.

Liang et al. [2018] improved upon this baseline by using two relatively simple but efficient tricks:
(a) by adding temperature to the softmax calculation, (b) by applying adversarial-like perturbation
on the inputs. The method is called ODIN. Additionally, the authors showed that the performance
of ODIN strongly depends on the actual distance between the test distributions. For example, if the
in-distribution and out-of-distribution datasets are non-intersecting subsets of CIFAR-100, then ODIN
doesn't work well.

33 Our contributions are the following:

- We adapt ODIN for two natural language processing tasks: sentiment analysis and part-of speech tagging. We show that the two tricks used in ODIN are helpful for sentiment analysis,
   but we could not get improvement from input perturbations for POS tagging.
- 2. We choose the in-distribution (ID) and out-of-distribution (OOD) datasets in a way that the labels used in the datasets are the same. This choice allows us to measure the accuracy of the model on the test set of the OOD dataset. We show that the scores produced by 0DIN are relatively higher for the correctly classified examples of the OOD dataset, even when the datasets are close and 0DIN fails to properly separate them. For part-of-speech tagging, we show that the scores produced by 0DIN have higher rank correlation with the accuracy of the neural network predictions than the simpler baseline on both ID and OOD datasets.
- We demonstrate that although character-level embeddings improve POS tagging accuracy, they make it harder to distinguish ID and OOD test sets for the two OOD detection methods.
   Additionally, the scores produced by these methods have lower rank correlation with the prediction accuracy for all datasets we have tried compared to the models without character-level embeddings.

# 49 **2 Related Work**

There are various ways to approach out-of-distribution detection problem for high dimensional 50 inputs. Shafaei et al. [2018] made a detailed comparison of different approaches on basic image 51 classification tasks. Hendrycks and Gimpel [2017] set a baseline for these methods by looking at the 52 maximum softmax probabilities (PbThreshold<sup>1</sup>). Liang et al. [2018] improved upon this baseline 53 using temperature rescaling and perturbations on inputs (ODIN). Gal and Ghahramani [2016] showed 54 that Bayesian interpretation of dropout allows to use it to measure the uncertainty of neural network's 55 prediction (MC-Dropout). Lakshminarayanan et al. [2017] showed that an ensemble of multiple deep 56 networks can be used to capture uncertainty in a non-Bayesian way. It is important to note that these 57 methods require access to the datasets and to the neural networks trained on them. PbThreshold 58 and ODIN can be applied to any pretrained neural network. MC-Dropout is applicable to any network 59 with a dropout layer (notably, ResNets do not use dropout), and Lakshminarayanan et al. [2017] 60 requires an ensemble of neural networks. 61

Another class of approaches for OOD detection are based on generative models. Shafaei et al. [2018] evaluated methods based on autoencoders (AEThreshold) and PixelCNN++ [Salimans et al., 2017], and showed that for basic image classification tasks ODIN outperforms them (in terms of OOD detection accuracy). Recently, Choi and Jang [2018] used an ensemble of generative models to beat ODIN on OOD detection for MNIST and CIFAR-10 datasets (in terms of AUROC). Note that these generative approaches are model-independent, they do not depend on the neural network that performs the actual classification.

<sup>&</sup>lt;sup>1</sup>We use the codenames of the algorithms from [Shafaei et al., 2018]

	Labels	Number of sentences			Accuracy of SOTA models		
		Train	Dev.	Test			
Yelp Reviews	5	650000	0	50000	70.02 [Howard and Ruder, 2018]		
SST-5	5	8544	1101	2210	54.70 [Peters et al., 2018]		
en-EWT	17	12543	2002	2077	95.94 [Lim et al., 2018]		
en-LinES	17	2738	912	914	97.06 [Lim et al., 2018]		
en-GUM	17	2914	707	769	96.44 [Lim et al., 2018]		
nl-Alpino	17	12269	718	596	96.90 [Straka, 2018]		

Table 2: The datasets used in our experiments along with the performance of the state-of-the-art models on these datasets.

<sup>69</sup> Most of the research on OOD detection is focused on image classification tasks. Notable exceptions

are [Hendrycks and Gimpel, 2017] and [Shalev et al., 2018]. Applications of more advanced methods
 to NLP tasks remain largely unexplored.

Additionally, all experiments described above are performed on ID and OOD datasets with different 72 sets of labels. These experiments are good enough to measure the performance of OOD detection. On 73 the other hand, when the distributions of the two datasets have a significant overlap, OOD detection 74 methods fail to produce high accuracy scores. This phenomenon is demonstrated in Section 4.5 of 75 [Liang et al., 2018]. In the context of measuring the confidence of neural network predictions it is 76 fine to misclassify OOD samples as ID unless the network does not produce incorrect answers for the 77 78 misclassified examples. In order to measure the accuracy of neural models on misclassified OOD samples we choose the ID and OOD datasets to have the same set of labels. 79

## 80 3 Experiments

### 81 3.1 Datasets

We performed experiments for two tasks: sentiment analysis and part-of-speech tagging. For 82 sentiment analysis we used the five-class Yelp reviews dataset from [Zhang et al., 2015] and Stanford 83 Sentiment Treebank (SST) [Socher et al., 2013]. SST has labels for every sentence and for every 84 85 phrase produced from the dependency trees of the sentences. The labels are real numbers between 0 and 1. We created a five-class version of the labels by splitting [0,1] into five equal intervals. 86 For part-of-speech tagging we used two English and one more Dutch treebanks from Universal 87 Dependencies v2.2 [Zeman et al., 2018a] used in the CoNLL Shared Task 2018 [Zeman et al., 2018b]. 88 The majority of the sentences in English-LinES treebank are from literature. English-EWT dataset is 89 larger and is more diverse. The datasets are described in Table  $2^2$ . 90

#### 91 3.2 Neural models

In contrast to Liang et al. [2018], we did not use state-of-the-art neural networks. Instead, we trained
simple recurrent models for both tasks. For simplicity, we did not use pretrained word embeddings.
Similar to [Joulin et al., 2017], we used *hashing trick* to map the words to hashes and embed the
hashes using *D*-dimensional vectors. We randomly initialized the embedding matrix and made it
trainable.

<sup>97</sup> Let s be a sentence from one of the datasets, and  $w_1, \ldots, w_M$  be the words. The embedding of <sup>98</sup> the *m*-th word of the sentence will be  $x_m = W_e hash(w_m)$ . We apply bidirectional LSTM on the <sup>99</sup> embeddings:  $\overrightarrow{h_m}, \overleftarrow{h_m} = BiLSTM(x_m)$ . For sentiment analysis we apply a dense layer on the <sup>100</sup> concatenation of the last states of the two LSTMs:  $f_{sc}(s) = W[\overrightarrow{h_M}, \overrightarrow{h_1}] + b$ . The loss function <sup>101</sup> is a cross-entropy:  $loss(s) = ce(S(f_{sc}(s), 1))$ , where  $S_i(\mathbf{z}, T) = \frac{exp(z_i/T)}{\sum_{j=1}^{C} exp(z_j/T)}$  is the modified <sup>102</sup> softmax function, T is the temperature scaling parameter, and C is the number of classes.

<sup>&</sup>lt;sup>2</sup>State-of-the-art results for sentiment analysis datasets are retrieved from http://nlpprogress.com on 27.10.2018. UD POS tagging results are from http://universaldependencies.org/conll18/ results-upos.html.

Table 3: Out-of-distribution detection performance on part-of-speech tagging tasks. Performance is reported in AUROC scores (higher is better). Char. column indicates whether character-level embeddings were used in the model.  $\epsilon$ , T column lists the best hyperparameters for ODIN found using grid search on validation sets. All scores are in percents.

ID	OOD	Char.	Accuracy		PbThreshold			ODIN			
			ID	OOD	AUROC		$\epsilon, T$	AUROC		2	
Yelp	SST-5	No	59.6	24.5	79.9		0.011, 2K	90.68			
					Mean / Med. / Tok.			Mean / Med. / Tok.			
en-LinES	en-EWT	Yes	89.6	75.9	66.8	70.7	57.1	0, 5K	75.1	71.3	58.2
en-LinES	en-EWT	No	87.8	73.4	72.4	73.9	57.9	0, 10K	77.0	74.0	59.1
en-LinES	nl-Alpino	Yes	89.6	31.7	95.2	97.4	76.5	0, 2K	99.1	98.3	79.8
en-LinES	nl-Alpino	No	87.8	28.6	97.5	97.4	77.4	0, 5	<b>98.2</b>	97.9	81.7

For POS tagging we apply a dense layer on every hidden state:  $f_{st}(w_m) = W([\overrightarrow{h_m}, \overleftarrow{h_m}]) + b$ . The loss function is the average of word-level cross entropies  $loss(s) = \frac{1}{M} \sum ce(S(f_{st}(w_m), 1))$ .

#### **105 3.3 Out-of-distribution detection method**

We use ODIN to detect out-of-distribution samples and compare it with the PbThreshold baseline. For 106 every sentence s we compute the scores for each of the methods: PbThreshold(s) = max  $S(f_{sc}(s))$ 107 and ODIN(s) = max  $S(f_{sc}(\tilde{\mathbf{x}}), T)$ , where  $\tilde{\mathbf{x}} = \mathbf{x} + \epsilon \operatorname{sign}(\nabla_{\mathbf{x}} S_{\hat{u}}(\mathbf{x})))$ , where  $\hat{y} = \operatorname{argmax} S(\mathbf{x}, 1)$ . 108 Here  $\epsilon$  (perturbation magnitude) and T (temperature) are hyperparameters, which are chosen based 109 on the OOD detection performance on the development sets. For POS tagging, the gradient in the 110 ODIN score formula is applied to the mean of word-level probability maximums. The final ODIN 111 score of the sentence is some aggregate of the word-level ODIN scores. We tried mean and median 112 as the aggregate function. Additionally, we tried to do out-of-distribution detection at the level of 113 tokens, which is expected to be more challenging, as the vocabularies of the datasets have a significant 114 overlap. 115

Hendrycks and Gimpel [2017] and Liang et al. [2018] report multiple scores for OOD detection
performance, while Shafaei et al. [2018] reports only accuracy. We follow [Choi and Jang, 2018]
and choose AUROC, as it does not require to tune a threshold. We report the scores on the test sets.
Appendix H of [Liang et al., 2018] demonstrates that the choice of the OOD distribution is not critical
for the hyperparameter tuning.

#### 121 **3.4 Evaluating confidence scores**

For every sentence we produce the scores PbThreshold(s) and ODIN(s) and attempt to interpret them as confidence scores for the prediction of the neural network. To measure how well these scores can perform as a confidence measure, we calculate Spearman's rank correlation coefficient between the scores and the accuracy numbers.

#### **126 4 Results and Discussions**

Table 3 shows the results for OOD detection and Table 4 shows the rank correlation coefficients for PbThreshold and ODIN methods.

The role of the temperature scaling and input perturbations All our experiments confirm the 129 observation from [Liang et al., 2018] that temperature scaling improves out-of-distribution detection. 130 The effect of higher temperatures saturates when T reaches thousands (Figure 1). The positive effect 131 of the perturbations on the inputs is visible for sentiment analysis, but not for POS tagging. We 132 have noticed that when we try to perform OOD detection at the level of tokens, small perturbations 133  $(\epsilon = 0.005)$  bring tiny improvements to the performance (by less than 1 AUROC percent point). But 134 for sentence level OOD detection we get worse AUROC scores for  $\epsilon > 0$  (or even when  $\epsilon < 0$ ) for 135 both mean and median averaging. 136

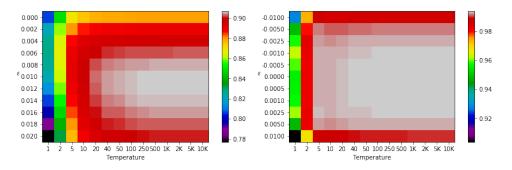


Figure 1: AUROC scores for ODIN out-of-distribution detection method for different values of hyperparameters. The left image is for sentiment analysis (Yelp dataset as ID, SST-5 as OOD), the right one is for POS tagging (English-LinES as ID, Dutch-Alpino as OOD, the neural model uses character-level embeddings).

137 Sentence-level scores In POS tagging experiments, median of the token-level scores is usually 138 a better score for sentence-level OOD detection than the mean when T = 1, while for higher 139 temperatures mean is consistenly better. As expected, token-level OOD detection doesn't work well 140 when both ID and OOD datasets are in English (the vocabularies overlap significantly).

Ranking of the sentences ODIN is clearly better than PbThreshold according to Spearman's rank correlation coefficient for POS tagging tasks (Table 4). For a neural network trained on en-LinES, ODIN scores are a good indicator how the network will perform on OOD samples. It is a much better indicator for the closer English dataset than the further Dutch dataset. On the other hand, when we consider the union of ID and OOD datasets, it works better for the union of en-LinES and nl-Alpino datasets.

To visualize what these correlation coefficients imply in practice, we split the samples into 20 equal buckets according to the scores, and compute accuracy on each of the buckets. We expect to see that the accuracy numbers are monotonically increasing, and that the accuracy numbers on different test sets are close to each other for each bucket. Figure 2 shows that ODIN performs slightly better than PbThreshold.

For sentiment analysis, we could not get improvement in rank correlation with ODIN, although the performance of OOD detection is improved. The reasons of this phenomenon are yet to be investigated.

**The role of character-level embeddings** Character-level embeddings improve the accuracy of the neural POS tagger for both ID and OOD datasets (consistent with the results reported by Reimers and Gurevych [2017]). On the other hand, they make it harder for PbThreshold and ODIN methods to separate ID and OOD datasets. Additionally, the scores from the models with character-level embeddings have lower rank correlation with the prediction accuracy. This implies, that the usage of character-level embeddings can be a tradeoff between the accuracy of the model and the reliability of the confidence scores.

Table 4: Spearman's ranking correlation coefficients between sample-level accuracies and the scores produced by PbThreshold and ODIN (higher is better). For each method we report the coefficient for ID, OOD test sets and the union of both.

ID	OOD	Char.	Pł	Thresho	old	ODIN			
			ID	OOD	Both	ID	OOD	Both	
en-LinES	nl-EWT nl-EWT nl-Alpino	Yes No Yes		0.632	0.565 0.616 0.793	0.476		0.676	
	1		0.408				0.445	0.833	

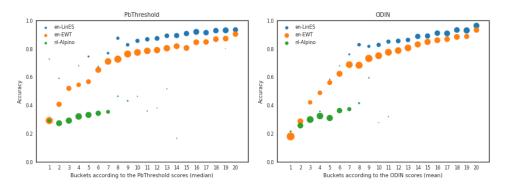


Figure 2: Accuracy of the POS tagger trained on en-LinES (without character-level embeddings) on 20 equal buckets of the union of three test sets. The buckets are computed according to the scores produced by each method (PbThreshold and ODIN).  $\epsilon$  and T for ODIN are determined based on the development sets of en-LinES (ID) and en-EWT (OOD). The size of a circle is proportional to the number of samples that fall into that bucket. Ideally, accuracy scores for the *i*-th bucket should be higher than for the (i - 1)-th bucket, and y coordinates of the three circles for each bucket should be the same.

## 162 5 Conclusions and Future Work

In this work we have adapted ODIN out-of-distribution detection method on sentence classification and sequence tagging tasks. We showed that as an OOD detector it performs consistently better than for the PbThreshold baseline. Additionally, we attempted to quantify how well the scores produced by these methods can be used as confidence scores for the predictions of neural models.

There are many other OOD detection methods that have yet to be tested on NLP tasks. On the other hand, our analysis notably doesn't cover sequence-to-sequence tasks. We have shown that the usage of character-level embeddings makes OOD detection harder for both PbThreshold and ODIN. The role of the pretrained word vectors, the size of the embeddings, the choice of the neural architecture (recurrent, convolutional or Transformer-like) on OOD detection performance is left for future work.

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