
A Computational Model for Binding by Enhanced Firing Rate: Implementing Smooth Power-law enhancement in Object-Centric Representations

Ishanvir S. Choongh
Cognitive Systems
University of British Columbia
Vancouver, BC Canada V6T 1Z3
ishanvir@student.ubc.ca

Manu S. Madhav
School of Biomedical Engineering
Djawad Mowafaghian Centre for Brain Health
University of British Columbia
Vancouver, BC Canada V6T 1Z3
manu.madhav@ubc.ca

Abstract

1 The binding problem remains a core challenge in perception. A proposed neural
2 mechanism is binding by firing-rate enhancements (BBRE), where attention ampli-
3 fies neuronal activity for same-object features without the need for synchronized
4 oscillations. We interpret BBRE as a contrast mechanism and test its functional
5 utility computationally via the Minimal Viable Binding Architecture (MVBA), a
6 proof-of-concept model extending Slot Attention with a smooth power-law en-
7 hancement ($f(x) = \text{sign}(x) \cdot |x|^\alpha$) to amplify strong signals and suppress weak
8 ones in isolated spatial (“WHERE”) and feature (“WHAT”) binding modules,
9 inspired by dual-stream theories of the visual system. Seven ablated variants
10 were trained unsupervised on a synthetic dataset using MSE reconstruction loss.
11 Results showed 71.4% MSE improvement overall (*baseline* 1.174 to *full* 0.335),
12 with 18.4% from power-law enhancement alone. Visualizations validated reduced
13 feature bleeding. MVBA empirically supports BBRE as a contrast mechanism,
14 bridging neuroscience, psychology, and machine learning for biologically plausible
15 object-centric learning.

16 1 Introduction

17 The binding problem is a fundamental challenge in visual perception: How does the brain integrate
18 distributed sensory features into coherent object representations within its parallel processing archi-
19 tecture? Feature Integration Theory (FIT) [1] provides a key framework, proposing that early vision
20 decomposes scenes into basic features across separate neural maps, but focused attention is required
21 to “bind” them into wholes, preventing miscombinations like illusory conjunctions [1, 2]. Historical
22 debates have contrasted synchrony-based theories, where temporal correlations and oscillatory phases
23 link features [3], with attention-modulated firing rate alternatives [4]. Roelfsema critiques synchrony
24 models for lacking empirical support and proposes binding by enhanced firing rates (BBRE), where
25 attention boosts neuronal activity for features of the same object, creating perceptual separation
26 without oscillations [4].

27 Computational modeling bridges psychology and neuroscience by enabling testable simulations of
28 binding mechanisms, serving as a tool to evaluate BBRE’s functional role as a contrast enhancement
29 mechanism that amplifies relevant signals while suppressing noise. In machine learning, object-
30 centric paradigms decompose scenes into interpretable components, inspired by perceptual grouping
31 [5]. In the Slot Attention paradigm [6], slots are vectors that act as abstract containers for scene
32 components, and they compete iteratively to parse images into objects without supervision, mirroring
33 parallel feature extraction and serial binding.

34 Despite advances, these models often fail to fully address binding, exhibiting features “leaking”
35 across objects, especially in unsupervised training on complex images. The cause is attributed to
36 features being insufficiently segregated or enhanced relative to the background noise [7]. This gap
37 highlights the need for stricter enhancement/suppression mechanisms beyond standard attention,
38 prompting computational tests of biologically inspired solutions like BBRE as a contrast mechanism.

39 To address this, we introduce the Minimal Viable Binding architecture (MVBA) as a proof-of-concept
40 model that interprets BBRE as a contrast mechanism and tests whether it improves binding, assessed
41 through reconstruction quality. We implement this as a smooth power-law enhancement, which
42 amplifies strong features while dampening weak ones through a dynamic top-down transformation,
43 without modeling actual firing-rate dynamics in the neural network. Our central hypothesis is that
44 this power-law enhancement, as a functional analog of BBRE, significantly improves reconstruction
45 quality measured via model ablations on multi-object scenes, providing empirical validation for
46 rate-based binding as a contrast mechanism.

47 2 Methods

48 2.1 Model Architecture and Design Rationale

49 MVBA is a modular neural network for object-centric representations with explicit binding mecha-
50 nisms, comprising six modules that process visual input hierarchically (Fig. 1a). Feature extraction
51 uses a three-layer CNN to yield 64-dimensional visual features at full 64×64 image resolution,
52 concatenated channel-wise with 8-dimensional learnable positional encoding for a $[72 \times 64 \times 64]$
53 tensor. This map feeds Slot Attention, inspired by [6], where four slots (128-dimensional) compete via
54 multi-headed attention (4 heads, 32 dims/head) over three iterations, with symmetry breaking through
55 Gaussian initialization and dimensional biasing to prevent identical convergence. The slot states are
56 refined through gated recurrent unit (GRU) updates and residual MLPs. After three iterations of Slot
57 attention, each slot produces a dynamic top-down $\alpha \in [1, 3]$ parameter via dual 64-hidden MLPs,
58 yielding separate spatial (α_s) and feature (α_f) parameters for adaptive sharpening.

59 The pipeline then splits into Spatial Binding and Feature Binding. Spatial Binding computes
60 “WHERE” spatial maps via 32-dimensional query-key matching (slot queries: $128 \rightarrow 32$; fea-
61 ture keys: 1×1 conv $72 \rightarrow 32$), with power-law enhancement on logits before softmax to amplify
62 strong matches and suppress weak ones, embodying biological attention by simultaneously enhancing
63 relevant signals and suppressing noise [2]. Multi-scale refinement (3×3 , 5×5 , 7×7 kernels, 16
64 channels) enforces coherent regions. Feature Binding extracts “WHAT” properties by weighting
65 features with spatial maps, applying power-law enhancement, and using slot-gated pooling projected
66 to 128 dimensions. Reconstruction attempts to recreate the original image by decoding slots via
67 upsampling ($128 \rightarrow 256 \rightarrow 64 \times 8 \times 8$, then transposed conv to $3 \times 64 \times 64$) with per-slot RGB/masks
68 combined via normalized softmax, enabling end-to-end differentiability. This design isolates binding
69 for ablation, with a power-law mimicking contrast akin to BBRE via post-matching sharpening.

70 The core innovation provided by MVBA is smooth power-law enhancement, mimicking neural
71 contrast: $f(x) = \text{sign}(x) \cdot |x|^\alpha$, where $\alpha > 1$ is the learned parameter that amplifies strong signals
72 and suppresses weak ones, inspired by gain modulation [8]. As a BBRE analog, it simulates firing
73 rate increase for attended features, creating perceptual separation against the background.

74 2.2 Model Variants and Ablation Setup

75 Seven variants were constructed to isolate effects: *baseline* (Slot Attention only), *spatial_fixed* ($\alpha_s =$
76 1, no Feature Binding), *feature_fixed* ($\alpha_f = 1$, no Spatial Binding), *full_fixed* ($\alpha_s = \alpha_f = 1$), *spatial*
77 ($\alpha_s \in [1, 3]$, no Feature Binding), *feature* ($\alpha_f \in [1, 3]$, no Spatial binding), *full* ($\alpha_s, \alpha_f \in [1, 3]$).
78 Variants were trained with identical hyperparameters end-to-end.

79 2.3 Dataset, Training, and Evaluation Metrics

80 We generated the *SimpleObjects* dataset (8,000 training, 2,000 test) using OpenAI o3 LLM [9],
81 featuring 2 to 4 geometric shapes with randomized colours/sizes/positions, including overlaps for
82 binding challenges. For example, Figure 1b. "Original" image is sample 0961 from the *SimpleObjects*
83 test dataset. Training used unsupervised Mean-Squared Error (MSE) reconstruction loss on a

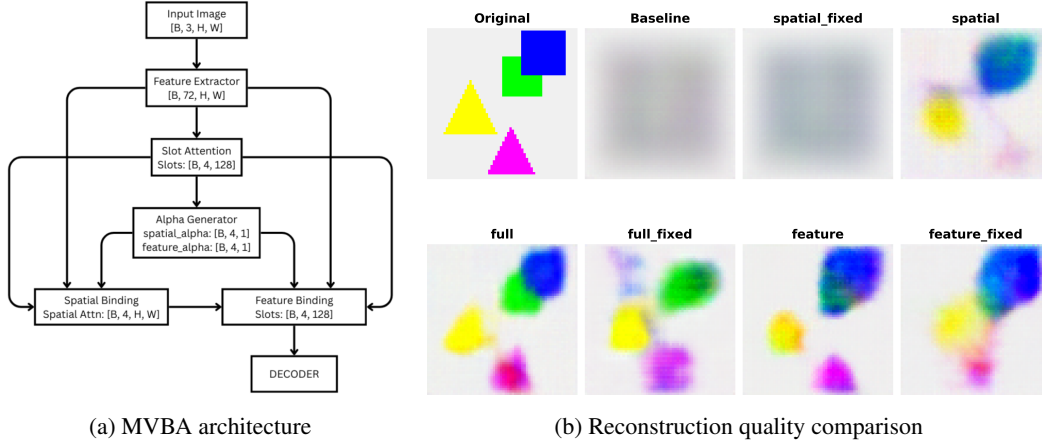


Figure 1: **(a) MVBA architecture.** Visual input is processed through six components: feature extraction, slot attention, dynamic alpha generation, spatial binding, feature binding, and image reconstruction (decoder). Tensor shapes denote batch size B, channels, height H, and width W; see Method 2.1 for module details. **(b) Reconstruction quality comparison.** Original image for test sample 0961 and reconstructed images from the 7 MVBA variants. The *_fixed* suffix indicates α being restricted to 1 (no enhancement). The *full* model demonstrates reduced feature bleeding and more coherent object boundaries.

84 single 16GB GPU (optimizer: Adam, batch size: 16, epochs: 50). We computed the following
 85 metrics for evaluation: Mean-Squared Error (MSE), mean absolute error (L1), Peak Signal-to-
 86 Noise Ratio ($\text{PSNR} = 20 \log_{10}(1/\sqrt{\text{MSE} + \epsilon})$), and Structural Similarity Index Measure [10]
 87 ($\text{SSIM} = \frac{(2\mu_x\mu_y + c_1)(2\sigma_{xy} + c_2)}{(\mu_x^2 + \mu_y^2 + c_1)(\sigma_x^2 + \sigma_y^2 + c_2)}$, where μ_x, μ_y are means, σ_x^2, σ_y^2 are variances, σ_{xy} is covariance,
 88 $c_1 = 0.0001, c_2 = 0.0009$). We used per-slot MSE for decomposition. For statistical analysis, we
 89 conducted paired *t*-tests (21 comparisons) to assess metric differences, with Cohen’s *d* and 95%
 90 bootstrap confidence intervals (CIs) over 1000 resamples, averaged over the 2000 test images. The
 91 codebase was implemented in PyTorch, see Appendix B.

92 3 Results

93 Across the seven variants, metrics showed substantial MSE reductions (Table 1), with a drop from
 94 *baseline* MSE = 1.174 to *full* MSE = 0.335 (71.4% improvement). These improvements were driven
 95 by architecture gains (*baseline* to *full_fixed*: 65.0%) and BBRE enhancements (*full_fixed* to *full*:
 96 18.4%). Secondary metrics showed the same pattern for *full* vs. *baseline*: PSNR= 5.36 vs. -0.32,
 97 SSIM= 0.714 vs. 0.086, L1= 0.190 vs. 0.566, with reduced standard deviations indicating stability.
 98 Effect sizes were meaningful (e.g. *baseline* to *full*: $d = 2.37$, *full_fixed* to *full*: $d = 0.49$), all
 99 $p < 0.001$, and 95% bootstrap CIs confirmed reliable differences. See Appendix A for the complete
 100 statistical analysis (Tables 2, 3, 4, 5).

Table 1: Mean performance metrics across MVBA variants

Variant	MSE (std) (lower is better)	PSNR (std) (higher is better)	SSIM (std) (higher is better)	L1 (std) (lower is better)
<i>baseline</i>	1.1736(0.4620)	-0.32(1.89)	0.0864(0.0799)	0.5664(0.1996)
<i>spatial_fixed</i>	1.1758(0.4624)	-0.33(1.89)	0.0685(0.0791)	0.5357(0.1912)
<i>spatial</i>	0.6003(0.3052)	2.81(2.36)	0.4844(0.3600)	0.3118(0.1147)
<i>feature_fixed</i>	0.5438(0.2994)	3.31(2.49)	0.5883(0.3019)	0.2662(0.1096)
<i>feature</i>	0.4424(0.2472)	4.22(2.51)	0.6582(0.3012)	0.2219(0.0905)
<i>full_fixed</i>	0.4108(0.2421)	4.61(2.63)	0.6210(0.3489)	0.2131(0.0913)
<i>full</i>	0.3353(0.1791)	5.36(2.36)	0.7141(0.2923)	0.1902(0.0703)

101 Pairwise t -tests (21 comparisons) highlighted architecture significance (e.g., *baseline* to *full_fixed*:
102 $d = 2.32$, 65.0% improvement, *baseline* to *feature_fixed*: $d = 2.08$, 53.7% improvement) and power-
103 law boosts, especially in spatial binding (*spatial_fixed* to *spatial*: $d = 2.00$, 49% improvement).
104 Synergistic effects emerge, as *full* model gains (71.4%) were less than the summed components,
105 showing non-additive benefits. Shapiro-Wilk tests noted normality violations, but large $n = 2000$
106 ensured robustness. Visualizations of reconstructions across variants demonstrated improved binding:
107 *baseline* showed blurred masses, while the *full* model showed coherent bound objects (Fig. 1b).

108 4 Conclusion

109 The results robustly support the hypothesis that smooth power-law enhancement, as a BBRE analog,
110 improves reconstruction quality in object-centric models ($p < 0.001$ across comparisons). Isolation
111 using restricted variants *full_fixed* ($\alpha = 1$) to *full* (dynamic $\alpha \in [1, 3]$) yielded an MSE difference of
112 0.07552 ($t = 22.07$, $p = 8.15 \times 10^{-97}$, $d = 0.494$, 18.38% MSE reduction, 95% CI [17.0%, 19.8%]),
113 with spatial binding gaining most (*spatial_fixed* to *spatial*: 49% MSE reduction, $d = 2.00$). Overall,
114 the improvement in MSE from *baseline* to the *full* model was MSE= 1.174 to 0.335 (71.4%).
115 Synergistic effects were evident: the 71.4% improvement $<$ sum of components (*feature* 62.3%+
116 *spatial* 48.9%), mimicking integration due to attention [2]. This affirms power-law’s imitation of an
117 attention-based contrast enhancement mechanism. Limitations of this study include SimpleObject’s
118 toy nature, which limits generalizability to complex real-world scenes, and reconstruction quality
119 serving as an indirect proxy for binding quality. Future work should focus on extending the model to
120 complex scenes and assessing its performance using direct metrics, and having dynamic, ranked slots
121 for robust perception. Overall, MVBA bridges neuroscience, psychology, and machine learning to
122 empirically validate a testable analog for firing-rate contrast enhancements in attention.

123 5 Related Work

124 Computational modeling is a useful tool for evaluating binding mechanisms in visual perception.
125 Recent approaches have integrated spiking neural networks (SNNs) and artificial neural networks
126 (ANNs) to address binding via covariance and spike timing, relying on synchrony [11]. However,
127 such oscillation-based theories are critiqued for lacking sufficient empirical support, advocating
128 instead for binding by enhanced firing rates (BBRE) [4], yet computational tests of this mechanism
129 remain scarce beyond conceptual critiques. In machine learning, object-centric paradigms extend
130 these ideas, with Slot Attention [6] enabling unsupervised scene decomposition into slots, but prone
131 to feature bleeding. Recent variants prioritize architectural refinements: GLASS [12] uses guided
132 latent diffusion for semantic slots; ROLA [13] optimizes attention for real-world data; Adaptive Slot
133 Attention [14] dynamically adjusts slot numbers; and probabilistic priors to Slot Attention improve
134 object identifiability [15]. These represent architectural tweaks rather than biologically plausible
135 enhancements. Together, these works highlight a gap in models empirically testing neuroscien-
136 tific/psychological theories like BBRE as a functional enhancement mechanism. MVBA addresses
137 this gap by implementing smooth power-law amplification in dual-stream binding, validating the
138 contrastive role of a rate-based enhancement through ablations.

139 6 Acknowledgements

140 We would like to acknowledge Doug Altshuler and Khanh Dao Duc for their valuable mentorship to
141 Ishanvir S. Choongh, comments and feedback on this manuscript. This work was originally conceived
142 as a project for UBC course COGS 402, instructed by Christopher Mole. This work was supported by
143 the Tier 2 Canada Research Chair in Neural Circuits of Cognition and Control (CRC-2020-00226),
144 and a New Frontiers in Research Fund Exploration grant (NFRFE-2022-00524).

References

- 145
- 146 [1] Anne M Treisman and Garry Gelade. A feature-integration theory of attention. *Cognitive*
147 *psychology*, 12(1):97–136, 1980.
- 148 [2] Anne Treisman. How the deployment of attention determines what we see. In *Progress in*
149 *Psychological Science around the World. Volume 1 Neural, Cognitive and Developmental*
150 *Issues.*, pages 245–277. Psychology Press, 2013.
- 151 [3] Wolf Singer. Neuronal synchrony: a versatile code for the definition of relations? *Neuron*,
152 24(1):49–65, 1999.
- 153 [4] Pieter R Roelfsema. Solving the binding problem: Assemblies form when neurons enhance
154 their firing rate—they don’t need to oscillate or synchronize. *Neuron*, 111(7):1003–1019, 2023.
- 155 [5] Klaus Greff, Raphaël Lopez Kaufman, Rishabh Kabra, Nick Watters, Christopher Burgess,
156 Daniel Zoran, Loic Matthey, Matthew Botvinick, and Alexander Lerchner. Multi-object repre-
157 sentation learning with iterative variational inference. In *International conference on machine*
158 *learning*, pages 2424–2433. PMLR, 2019.
- 159 [6] Francesco Locatello, Dirk Weissenborn, Thomas Unterthiner, Aravindh Mahendran, Georg
160 Heigold, Jakob Uszkoreit, Alexey Dosovitskiy, and Thomas Kipf. Object-centric learning with
161 slot attention. *Advances in neural information processing systems*, 33:11525–11538, 2020.
- 162 [7] Maximilian Seitzer, Max Horn, Andrii Zadaianchuk, Dominik Zietlow, Tianjun Xiao, Carl-
163 Johann Simon-Gabriel, Tong He, Zheng Zhang, Bernhard Schölkopf, Thomas Brox, et al.
164 Bridging the gap to real-world object-centric learning. *arXiv preprint arXiv:2209.14860*, 2022.
- 165 [8] Emilio Salinas and Peter Thier. Gain modulation: a major computational principle of the central
166 nervous system. *Neuron*, 27(1):15–21, 2000.
- 167 [9] OpenAI. o3 model documentation, 2025. Accessed: 2025-08-22.
- 168 [10] Zhou Wang, A.C. Bovik, H.R. Sheikh, and E.P. Simoncelli. Image quality assessment: from
169 error visibility to structural similarity. *IEEE Transactions on Image Processing*, 13(4):600–612,
170 2004.
- 171 [11] Hao Zheng, Hui Lin, Rui Zhao, and Luping Shi. Dance of snn and ann: solving binding problem
172 by combining spike timing and reconstructive attention. *Advances in Neural Information*
173 *Processing Systems*, 35:31430–31443, 2022.
- 174 [12] Krishnakant Singh, Simone Schaub-Meyer, and Stefan Roth. Guided latent slot diffusion for
175 object-centric learning. *arXiv preprint arXiv:2407.17929*, 2024.
- 176 [13] Qian Tang, Hao Wang, Xiaofeng Zhu, Zhen Lei, and Zheng Zhang. Rola: real-world object-
177 centric learning with attention optimization. *Science China Information Sciences*, 68(9):192105,
178 2025.
- 179 [14] Ke Fan, Zechen Bai, Tianjun Xiao, Tong He, Max Horn, Yanwei Fu, Francesco Locatello,
180 and Zheng Zhang. Adaptive slot attention: Object discovery with dynamic slot number. In
181 *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pages
182 23062–23071, 2024.
- 183 [15] Avinash Kori, Francesco Locatello, Ainkaran Santhirasekaram, Francesca Toni, Ben Glocker,
184 and Fabio De Sousa Ribeiro. Identifiable object-centric representation learning via probabilistic
185 slot attention. *Advances in Neural Information Processing Systems*, 37:93300–93335, 2024.

186 **7 Appendix**

187 **A Statistical Comparisons**

188 **A.1 MSE (Mean Squared Error) Comparisons**

Table 2: Pairwise MSE statistical comparisons between MVBA variants

Comparison	Mean Diff	t stat	p value	Cohen's d	Effect Size	Improv %	95% CI
Architecture-Only Comparisons (Fixed $\alpha = 1$)							
<i>baseline</i> to <i>full_fixed</i>	0.7628	103.87	$< 10^{-100}$	2.323	Huge	65.00	[64.38, 65.59]
<i>baseline</i> to <i>feature_fixed</i>	0.6298	93.13	$< 10^{-100}$	2.083	Huge	53.66	[52.89, 54.37]
<i>baseline</i> to <i>spatial_fixed</i>	-0.0022	-6.27	4.49×10^{-10}	-0.14	Negligible	-0.19	[-0.25, -0.13]
<i>spatial_fixed</i> to <i>full_fixed</i>	0.765	104.1	$< 10^{-100}$	2.328	Huge	65.06	[64.49, 65.67]
<i>spatial_fixed</i> to <i>feature_fixed</i>	0.632	93.19	$< 10^{-100}$	2.084	Huge	53.75	[53.05, 54.42]
<i>feature_fixed</i> to <i>full_fixed</i>	0.133	34	$< 10^{-100}$	0.76	Medium	24.46	[23.28, 25.72]
BBRE Enhancement Effects							
<i>full_fixed</i> to <i>full</i>	0.0755	22.07	8.15×10^{-97}	0.494	Small-Med	18.38	[17.06, 19.79]
<i>feature_fixed</i> to <i>feature</i>	0.1014	30.94	$< 10^{-100}$	0.692	Medium	18.65	[17.65, 19.69]
<i>spatial_fixed</i> to <i>spatial</i>	0.5755	89.24	$< 10^{-100}$	1.996	Very Large	48.95	[48.29, 49.68]
Enhanced Model Comparisons ($\alpha \in [1, 3]$)							
<i>baseline</i> to <i>full</i>	0.8383	105.8	$< 10^{-100}$	2.366	Huge	71.43	[71.00, 71.87]
<i>baseline</i> to <i>feature</i>	0.7312	99.58	$< 10^{-100}$	2.227	Huge	62.30	[61.69, 62.90]
<i>baseline</i> to <i>spatial</i>	0.5733	89.19	$< 10^{-100}$	1.995	Very Large	48.85	[48.15, 49.53]
<i>spatial</i> to <i>full</i>	0.265	60.39	$< 10^{-100}$	1.351	Very Large	44.15	[43.29, 45.00]
<i>spatial</i> to <i>feature</i>	0.1579	43.66	$< 10^{-100}$	0.976	Large	26.30	[25.35, 27.27]
<i>feature</i> to <i>full</i>	0.1071	36.27	$< 10^{-100}$	0.811	Large	24.21	[23.28, 25.16]
Cross-Type Comparisons							
<i>full_fixed</i> to <i>feature</i>	-0.0316	-9.37	1.93×10^{-20}	-0.21	Small	-7.69	[-9.42, -6.09]
<i>full_fixed</i> to <i>spatial</i>	-0.1895	-46.28	$< 10^{-100}$	-1.035	Large	-46.13	[-48.41, -44.08]
<i>feature_fixed</i> to <i>full</i>	0.2085	50.84	$< 10^{-100}$	1.137	Large	38.34	[37.49, 39.24]
<i>feature_fixed</i> to <i>spatial</i>	-0.0565	-15.83	3.01×10^{-53}	-0.354	Small	-10.39	[-11.68, -9.11]
<i>spatial_fixed</i> to <i>full</i>	0.8405	105.88	$< 10^{-100}$	2.368	Huge	71.48	[71.08, 71.94]
<i>spatial_fixed</i> to <i>feature</i>	0.7334	99.69	$< 10^{-100}$	2.23	Huge	62.37	[61.74, 62.99]

Table 3: Pairwise PSNR statistical comparisons between MVBA variants

Comparison	Mean Diff	t stat	p value	Cohen's d	Effect Size	Improv %	95% CI
Architecture-Only Comparisons (Fixed $\alpha = 1$)							
<i>baseline</i> to <i>full_fixed</i>	-4.9327	-131.51	$< 10^{-100}$	-2.941	Huge	1546.23	[1244.4, 2107.1]
<i>baseline</i> to <i>feature_fixed</i>	-3.634	-106.08	$< 10^{-100}$	-2.373	Huge	1139.13	[886.5, 1540.9]
<i>baseline</i> to <i>spatial_fixed</i>	0.0081	7.08	1.94×10^{-12}	0.158	Negligible	-2.52	[-3.6, -1.7]
<i>spatial_fixed</i> to <i>full_fixed</i>	-4.9408	-131.79	$< 10^{-100}$	-2.948	Huge	1510.62	[1215, 2009.7]
<i>spatial_fixed</i> to <i>feature_fixed</i>	-3.6421	-106.06	$< 10^{-100}$	-2.372	Huge	1113.54	[888.9, 1475.4]
<i>feature_fixed</i> to <i>full_fixed</i>	-1.2987	-42.48	$< 10^{-100}$	-0.95	Large	39.18	[36.9, 41.5]
BBRE Enhancement Effects							
<i>full_fixed</i> to <i>full</i>	-0.7483	-23.93	$< 10^{-100}$	-0.535	Medium	16.22	[14.7, 17.8]
<i>feature_fixed</i> to <i>feature</i>	-0.9093	-39.09	$< 10^{-100}$	-0.874	Large	27.43	[25.7, 29.3]
<i>spatial_fixed</i> to <i>spatial</i>	-3.1375	-101.19	$< 10^{-100}$	-2.263	Huge	959.29	[760.5, 1302.4]
Enhanced Model Comparisons ($\alpha \in [1, 3]$)							
<i>baseline</i> to <i>full</i>	-5.6811	-170.64	$< 10^{-100}$	-3.817	Huge	1780.81	[1430.7, 2391.5]
<i>baseline</i> to <i>feature</i>	-4.5433	-127.29	$< 10^{-100}$	-2.847	Huge	1424.17	[1142, 1915.6]
<i>baseline</i> to <i>spatial</i>	-3.1295	-101.19	$< 10^{-100}$	-2.263	Huge	980.98	[777, 1342.7]
<i>spatial</i> to <i>full</i>	-2.5516	-87.91	$< 10^{-100}$	-1.966	Very Large	90.79	[86.4, 95.2]
<i>spatial</i> to <i>feature</i>	-1.4138	-55	$< 10^{-100}$	-1.23	Very Large	50.31	[47.7, 52.8]
<i>feature</i> to <i>full</i>	-1.1377	-47.66	$< 10^{-100}$	-1.066	Large	26.93	[25.5, 28.5]
Cross-Type Comparisons							
<i>full_fixed</i> to <i>feature</i>	0.3894	12.67	1.90×10^{-35}	0.283	Small	-8.44	[-9.7, -7.3]
<i>full_fixed</i> to <i>spatial</i>	1.8032	55.67	$< 10^{-100}$	1.245	Very Large	-39.08	[-40.3, -37.8]
<i>feature_fixed</i> to <i>full</i>	-2.0471	-76.63	$< 10^{-100}$	-1.714	Very Large	61.75	[59.1, 64.5]
<i>feature_fixed</i> to <i>spatial</i>	0.5045	20.23	6.36×10^{-83}	0.452	Small	-15.22	[-16.5, -13.8]
<i>spatial_fixed</i> to <i>full</i>	-5.6891	-170.63	$< 10^{-100}$	-3.816	Huge	1739.42	[1392.3, 2300.4]
<i>spatial_fixed</i> to <i>feature</i>	-4.5514	-127.35	$< 10^{-100}$	-2.848	Huge	1391.56	[1111.1, 1892]

Table 4: Pairwise SSIM statistical comparisons between MVBA variants

Comparison	Mean Diff	t stat	p value	Cohen's d	Effect Size	Improv %	95% CI
Architecture-Only Comparisons (Fixed $\alpha = 1$)							
<i>baseline to full_fixed</i>	-0.5346	-69.32	$< 10^{-100}$	-1.55	Very Large	618.6	[587.2, 652.1]
<i>baseline to feature_fixed</i>	-0.5019	-77.31	$< 10^{-100}$	-1.729	Very Large	580.69	[554.2, 609.7]
<i>baseline to spatial_fixed</i>	0.0179	12.3	1.39×10^{-33}	0.275	Small	-20.71	[-23.7, -17.5]
<i>spatial_fixed to full_fixed</i>	-0.5525	-73.64	$< 10^{-100}$	-1.647	Very Large	806.33	[765.8, 851.5]
<i>spatial_fixed to feature_fixed</i>	-0.5198	-79.13	$< 10^{-100}$	-1.77	Very Large	758.52	[718.5, 805]
<i>feature_fixed to full_fixed</i>	-0.0328	-4.02	6.04×10^{-5}	-0.09	Negligible	5.57	[2.9, 8.3]
BBRE Enhancement Effects							
<i>full_fixed to full</i>	-0.0931	-11.91	1.19×10^{-31}	-0.266	Small	14.99	[12.4, 17.7]
<i>feature_fixed to feature</i>	-0.0699	-9.82	2.94×10^{-22}	-0.22	Small	11.88	[9.4, 14.4]
<i>spatial_fixed to spatial</i>	-0.4159	-54.06	$< 10^{-100}$	-1.209	Very Large	606.91	[574.1, 647.8]
Enhanced Model Comparisons ($\alpha \in [1, 3]$)							
<i>baseline to full</i>	-0.6277	-98.34	$< 10^{-100}$	-2.2	Huge	726.29	[695.2, 762.7]
<i>baseline to feature</i>	-0.5717	-88.45	$< 10^{-100}$	-1.978	Very Large	661.56	[634.8, 690.8]
<i>baseline to spatial</i>	-0.398	-51.1	$< 10^{-100}$	-1.143	Large	460.48	[435.1, 486.1]
<i>spatial to full</i>	-0.2297	-27.33	$< 10^{-100}$	-0.611	Medium	47.42	[42.8, 52.1]
<i>spatial to feature</i>	-0.1738	-21.33	3.82×10^{-91}	-0.477	Small	35.88	[31.9, 39.9]
<i>feature to full</i>	-0.0559	-8.24	3.11×10^{-16}	-0.184	Negligible	8.5	[6.4, 10.7]
Cross-Type Comparisons							
<i>full_fixed to feature</i>	-0.0371	-4.73	2.42×10^{-6}	-0.106	Negligible	5.98	[3.5, 8.7]
<i>full_fixed to spatial</i>	0.1366	16.16	2.52×10^{-55}	0.362	Small	-22	[-24.3, -19.6]
<i>feature_fixed to full</i>	-0.1258	-17.86	2.57×10^{-66}	-0.399	Small	21.39	[18.7, 24.3]
<i>feature_fixed to spatial</i>	0.1039	12.65	2.47×10^{-35}	0.283	Small	-17.66	[-20.4, -15.1]
<i>spatial_fixed to full</i>	-0.6456	-101.59	$< 10^{-100}$	-2.272	Huge	942.15	[893.1, 997.5]
<i>spatial_fixed to feature</i>	-0.5896	-90.57	$< 10^{-100}$	-2.026	Huge	860.52	[816.5, 908.1]

191 **A.4 L1 (Mean Absolute Error) Comparisons**

Table 5: Pairwise L1 statistical comparisons between MVBA variants

Comparison	Mean Diff	t stat	p value	Cohen's d	Effect Size	Improv %	95% CI
Architecture-Only Comparisons (Fixed $\alpha = 1$)							
<i>baseline to full_fixed</i>	0.3533	119.5	$< 10^{-100}$	2.673	Huge	62.37	[62, 62.7]
<i>baseline to feature_fixed</i>	0.3001	109.63	$< 10^{-100}$	2.452	Huge	52.99	[52.5, 53.4]
<i>baseline to spatial_fixed</i>	0.0307	50.87	$< 10^{-100}$	1.138	Large	5.41	[5.2, 5.6]
<i>spatial_fixed to full_fixed</i>	0.3226	116.07	$< 10^{-100}$	2.596	Huge	60.22	[59.8, 60.6]
<i>spatial_fixed to feature_fixed</i>	0.2695	104.29	$< 10^{-100}$	2.333	Huge	50.3	[49.8, 50.8]
<i>feature_fixed to full_fixed</i>	0.0531	47.5	$< 10^{-100}$	1.062	Large	19.95	[19.3, 20.6]
BBRE Enhancement Effects							
<i>full_fixed to full</i>	0.0229	22.1	4.84×10^{-97}	0.494	Small	10.75	[9.9, 11.6]
<i>feature_fixed to feature</i>	0.0444	46.72	$< 10^{-100}$	1.045	Large	16.66	[16.1, 17.3]
<i>spatial_fixed to spatial</i>	0.2239	90.71	$< 10^{-100}$	2.029	Huge	41.8	[41.3, 42.3]
Enhanced Model Comparisons ($\alpha \in [1, 3]$)							
<i>baseline to full</i>	0.3762	114.44	$< 10^{-100}$	2.56	Huge	66.42	[66.1, 66.7]
<i>baseline to feature</i>	0.3445	114.8	$< 10^{-100}$	2.568	Huge	60.83	[60.4, 61.2]
<i>baseline to spatial</i>	0.2546	97.68	$< 10^{-100}$	2.185	Huge	44.95	[44.5, 45.4]
<i>spatial to full</i>	0.1216	84.81	$< 10^{-100}$	1.897	Very Large	39	[38.5, 39.5]
<i>spatial to feature</i>	0.0899	79.22	$< 10^{-100}$	1.772	Very Large	28.84	[28.3, 29.4]
<i>feature to full</i>	0.0317	37.38	$< 10^{-100}$	0.836	Large	14.28	[13.7, 14.9]
Cross-Type Comparisons							
<i>full_fixed to feature</i>	-0.0088	-9.3	3.72×10^{-20}	-0.208	Small	-4.11	[-5, -3.3]
<i>full_fixed to spatial</i>	-0.0987	-78.46	$< 10^{-100}$	-1.755	Very Large	-46.29	[-47.6, -45]
<i>feature_fixed to full</i>	0.076	60.11	$< 10^{-100}$	1.344	Very Large	28.56	[28, 29.1]
<i>feature_fixed to spatial</i>	-0.0455	-42.58	$< 10^{-100}$	-0.952	Large	-17.11	[-18, -16.2]
<i>spatial_fixed to full</i>	0.3455	110.85	$< 10^{-100}$	2.479	Huge	64.5	[64.1, 64.8]
<i>spatial_fixed to feature</i>	0.3138	110.54	$< 10^{-100}$	2.472	Huge	58.58	[58.1, 59]

192 **B Code Availability**

193 <https://anonymous.4open.science/r/MVBA-1A7D>

- 194 1. **MODEL IMPLEMENTATION:** src/models/
- 195 2. **DATASET:** data/simple_objects/
- 196 3. **TRAINING INFRASTRUCTURE:** src/ & scripts/training/
- 197 4. **RAW TRAINING OUTPUT:** train_recon_only/
- 198 5. **EXPERIMENT PIPELINE:** experiments_recon_quality_ablation/

199 **NeurIPS Paper Checklist**

200 **1. Claims**

201 Question: Do the main claims made in the abstract and introduction accurately reflect the
202 paper's contributions and scope?

203 Answer: [Yes] .

204 Justification: The abstract and introduction claim that MVBA, as a proof-of-concept, tests
205 BBRE as a contrast mechanism via Smooth Power-Law to improve reconstruction quality
206 in ablations on multi-object scenes. This aligns with the methods (architecture, variants,
207 dataset) and results (MSE improvements, statistical tests) presented in the paper. The
208 scope is limited to a toy dataset and indirect metrics, as stated, without overgeneralizing to
209 real-world applications.

210 Guidelines:

- 211 • The answer NA means that the abstract and introduction do not include the claims
212 made in the paper.
- 213 • The abstract and/or introduction should clearly state the claims made, including the
214 contributions made in the paper and important assumptions and limitations. A No or
215 NA answer to this question will not be perceived well by the reviewers.
- 216 • The claims made should match theoretical and experimental results, and reflect how
217 much the results can be expected to generalize to other settings.
- 218 • It is fine to include aspirational goals as motivation as long as it is clear that these goals
219 are not attained by the paper.

220 **2. Limitations**

221 Question: Does the paper discuss the limitations of the work performed by the authors?

222 Answer: [Yes] .

223 Justification: The paper explicitly discusses limitations in the "**Conclusion**" Section: (1) the
224 toy nature of the SimpleObjects dataset restricting generalizability and (2) reconstruction
225 metrics as indirect proxy measures for binding.

226 Guidelines:

- 227 • The answer NA means that the paper has no limitation while the answer No means that
228 the paper has limitations, but those are not discussed in the paper.
- 229 • The authors are encouraged to create a separate "Limitations" section in their paper.
- 230 • The paper should point out any strong assumptions and how robust the results are to
231 violations of these assumptions (e.g., independence assumptions, noiseless settings,
232 model well-specification, asymptotic approximations only holding locally). The authors
233 should reflect on how these assumptions might be violated in practice and what the
234 implications would be.
- 235 • The authors should reflect on the scope of the claims made, e.g., if the approach was
236 only tested on a few datasets or with a few runs. In general, empirical results often
237 depend on implicit assumptions, which should be articulated.
- 238 • The authors should reflect on the factors that influence the performance of the approach.
239 For example, a facial recognition algorithm may perform poorly when image resolution
240 is low or images are taken in low lighting. Or a speech-to-text system might not be
241 used reliably to provide closed captions for online lectures because it fails to handle
242 technical jargon.
- 243 • The authors should discuss the computational efficiency of the proposed algorithms
244 and how they scale with dataset size.
- 245 • If applicable, the authors should discuss possible limitations of their approach to
246 address problems of privacy and fairness.
- 247 • While the authors might fear that complete honesty about limitations might be used by
248 reviewers as grounds for rejection, a worse outcome might be that reviewers discover
249 limitations that aren't acknowledged in the paper. The authors should use their best
250 judgment and recognize that individual actions in favor of transparency play an impor-
251 tant role in developing norms that preserve the integrity of the community. Reviewers
252 will be specifically instructed to not penalize honesty concerning limitations.

253 **3. Theory assumptions and proofs**

254 Question: For each theoretical result, does the paper provide the full set of assumptions and
255 a complete (and correct) proof?

256 Answer: [NA] .

257 Justification: The paper focuses on a computational model and empirical ablations rather than
258 formal theoretical proofs. The Smooth Power-Law is presented as a functional analog with
259 implementation details, but no theorems or mathematical derivations requiring assumptions
260 and proofs are claimed.

261 Guidelines:

- 262 • The answer NA means that the paper does not include theoretical results.
- 263 • All the theorems, formulas, and proofs in the paper should be numbered and cross-
264 referenced.
- 265 • All assumptions should be clearly stated or referenced in the statement of any theorems.
- 266 • The proofs can either appear in the main paper or the supplemental material, but if
267 they appear in the supplemental material, the authors are encouraged to provide a short
268 proof sketch to provide intuition.
- 269 • Inversely, any informal proof provided in the core of the paper should be complemented
270 by formal proofs provided in appendix or supplemental material.
- 271 • Theorems and Lemmas that the proof relies upon should be properly referenced.

272 **4. Experimental result reproducibility**

273 Question: Does the paper fully disclose all the information needed to reproduce the main ex-
274 perimental results of the paper to the extent that it affects the main claims and/or conclusions
275 of the paper (regardless of whether the code and data are provided or not)?

276 Answer: [Yes] .

277 Justification: The methods detail the architecture (components, hyperparameters like (n_slots
278 $= 4$, $\alpha \in [1, 3]$), variants, dataset (SimpleObjects with 8,000 train / 2,000 test), training
279 (MSE loss, Adam, 50 epochs, batch=16), metrics (MSE, PSNR, SSIM, L1), and analysis
280 (t-tests, Cohen's d, bootstrap), sufficient to replicate the ablation results and claims about
281 improvements.

282 Guidelines:

- 283 • The answer NA means that the paper does not include experiments.
- 284 • If the paper includes experiments, a No answer to this question will not be perceived
285 well by the reviewers: Making the paper reproducible is important, regardless of
286 whether the code and data are provided or not.
- 287 • If the contribution is a dataset and/or model, the authors should describe the steps taken
288 to make their results reproducible or verifiable.
- 289 • Depending on the contribution, reproducibility can be accomplished in various ways.
290 For example, if the contribution is a novel architecture, describing the architecture fully
291 might suffice, or if the contribution is a specific model and empirical evaluation, it may
292 be necessary to either make it possible for others to replicate the model with the same
293 dataset, or provide access to the model. In general, releasing code and data is often
294 one good way to accomplish this, but reproducibility can also be provided via detailed
295 instructions for how to replicate the results, access to a hosted model (e.g., in the case
296 of a large language model), releasing of a model checkpoint, or other means that are
297 appropriate to the research performed.
- 298 • While NeurIPS does not require releasing code, the conference does require all submis-
299 sions to provide some reasonable avenue for reproducibility, which may depend on the
300 nature of the contribution. For example
 - 301 (a) If the contribution is primarily a new algorithm, the paper should make it clear how
302 to reproduce that algorithm.
 - 303 (b) If the contribution is primarily a new model architecture, the paper should describe
304 the architecture clearly and fully.

- 305 (c) If the contribution is a new model (e.g., a large language model), then there should
306 either be a way to access this model for reproducing the results or a way to reproduce
307 the model (e.g., with an open-source dataset or instructions for how to construct
308 the dataset).
- 309 (d) We recognize that reproducibility may be tricky in some cases, in which case
310 authors are welcome to describe the particular way they provide for reproducibility.
311 In the case of closed-source models, it may be that access to the model is limited in
312 some way (e.g., to registered users), but it should be possible for other researchers
313 to have some path to reproducing or verifying the results.

314 5. Open access to data and code

315 Question: Does the paper provide open access to the data and code, with sufficient instruc-
316 tions to faithfully reproduce the main experimental results, as described in supplemental
317 material?

318 Answer: [Yes] .

319 Justification: See Appendix B.

320 Guidelines:

- 321 • The answer NA means that paper does not include experiments requiring code.
- 322 • Please see the NeurIPS code and data submission guidelines ([https://nips.cc/
323 public/guides/CodeSubmissionPolicy](https://nips.cc/public/guides/CodeSubmissionPolicy)) for more details.
- 324 • While we encourage the release of code and data, we understand that this might not be
325 possible, so “No” is an acceptable answer. Papers cannot be rejected simply for not
326 including code, unless this is central to the contribution (e.g., for a new open-source
327 benchmark).
- 328 • The instructions should contain the exact command and environment needed to run to
329 reproduce the results. See the NeurIPS code and data submission guidelines ([https://
330 nips.cc/public/guides/CodeSubmissionPolicy](https://nips.cc/public/guides/CodeSubmissionPolicy)) for more details.
- 331 • The authors should provide instructions on data access and preparation, including how
332 to access the raw data, preprocessed data, intermediate data, and generated data, etc.
- 333 • The authors should provide scripts to reproduce all experimental results for the new
334 proposed method and baselines. If only a subset of experiments are reproducible, they
335 should state which ones are omitted from the script and why.
- 336 • At submission time, to preserve anonymity, the authors should release anonymized
337 versions (if applicable).
- 338 • Providing as much information as possible in supplemental material (appended to the
339 paper) is recommended, but including URLs to data and code is permitted.

340 6. Experimental setting/details

341 Question: Does the paper specify all the training and test details (e.g., data splits, hyper-
342 parameters, how they were chosen, type of optimizer, etc.) necessary to understand the
343 results?

344 Answer: [Yes] .

345 Justification: The Methods section details data splits (8,000 train/ 2,000 test), hyperparam-
346 eters were chosen to be minimally complex ($n_slots = 4$, $\alpha \in [1, 3]$, iterations = 3), optimizer
347 (Adam), loss (MSE), epochs (50), batch size (16), and evaluation metrics (MSE, L1, PSNR,
348 SSIM) use standard formulas.

349 Guidelines:

- 350 • The answer NA means that the paper does not include experiments.
- 351 • The experimental setting should be presented in the core of the paper to a level of detail
352 that is necessary to appreciate the results and make sense of them.
- 353 • The full details can be provided either with the code, in appendix, or as supplemental
354 material.

355 7. Experiment statistical significance

356 Question: Does the paper report error bars suitably and correctly defined or other appropriate
357 information about the statistical significance of the experiments?

358
359
360
361
362
363
364
365
366
367
368
369
370
371
372
373
374
375
376
377
378
379
380
381
382
383
384
385
386
387
388
389
390
391
392
393
394
395
396
397
398
399
400
401
402
403
404
405
406
407
408

Answer: [Yes] .

Justification: Results report means with stds (Table 1), of the primary (MSE) and secondary (PSNR, SSIM, L1) metrics averaged over 2000 test samples. $p < 0.001$ for all. Appendix A details a complete statistical analysis.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The authors should answer "Yes" if the results are accompanied by error bars, confidence intervals, or statistical significance tests, at least for the experiments that support the main claims of the paper.
- The factors of variability that the error bars are capturing should be clearly stated (for example, train/test split, initialization, random drawing of some parameter, or overall run with given experimental conditions).
- The method for calculating the error bars should be explained (closed form formula, call to a library function, bootstrap, etc.)
- The assumptions made should be given (e.g., Normally distributed errors).
- It should be clear whether the error bar is the standard deviation or the standard error of the mean.
- It is OK to report 1-sigma error bars, but one should state it. The authors should preferably report a 2-sigma error bar than state that they have a 96% CI, if the hypothesis of Normality of errors is not verified.
- For asymmetric distributions, the authors should be careful not to show in tables or figures symmetric error bars that would yield results that are out of range (e.g. negative error rates).
- If error bars are reported in tables or plots, The authors should explain in the text how they were calculated and reference the corresponding figures or tables in the text.

8. Experiments compute resources

Question: For each experiment, does the paper provide sufficient information on the computer resources (type of compute workers, memory, time of execution) needed to reproduce the experiments?

Answer: [Yes] .

Justification: Training uses a single 16GB GPU, batch size 16, 50 epochs. The 7 model variants share setup, with similar execution times (about 15 mins per variant) in a PyTorch environment on 16 GB GPU hardware.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The paper should indicate the type of compute workers CPU or GPU, internal cluster, or cloud provider, including relevant memory and storage.
- The paper should provide the amount of compute required for each of the individual experimental runs as well as estimate the total compute.
- The paper should disclose whether the full research project required more compute than the experiments reported in the paper (e.g., preliminary or failed experiments that didn't make it into the paper).

9. Code of ethics

Question: Does the research conducted in the paper conform, in every respect, with the NeurIPS Code of Ethics <https://neurips.cc/public/EthicsGuidelines?>

Answer: [Yes] .

Justification: The research uses a synthetic dataset and ensures transparency through detailed methods and reproducibility via released code. This poses no societal harms or violations of human rights.

Guidelines:

- The answer NA means that the authors have not reviewed the NeurIPS Code of Ethics.

- 409
- If the authors answer No, they should explain the special circumstances that require a deviation from the Code of Ethics.
- 410
- The authors should make sure to preserve anonymity (e.g., if there is a special consideration due to laws or regulations in their jurisdiction).
- 411
- 412

413 10. Broader impacts

414 Question: Does the paper discuss both potential positive societal impacts and negative societal impacts of the work performed?

415 Answer: [No] .

416 Justification: Positive impacts (advancing biologically plausible AI for visual perception) are mentioned, but negative impacts are not discussed. The paper focuses on foundational research without exploring harms.

417 Guidelines:

- The answer NA means that there is no societal impact of the work performed.
 - If the authors answer NA or No, they should explain why their work has no societal impact or why the paper does not address societal impact.
 - Examples of negative societal impacts include potential malicious or unintended uses (e.g., disinformation, generating fake profiles, surveillance), fairness considerations (e.g., deployment of technologies that could make decisions that unfairly impact specific groups), privacy considerations, and security considerations.
 - The conference expects that many papers will be foundational research and not tied to particular applications, let alone deployments. However, if there is a direct path to any negative applications, the authors should point it out. For example, it is legitimate to point out that an improvement in the quality of generative models could be used to generate deepfakes for disinformation. On the other hand, it is not needed to point out that a generic algorithm for optimizing neural networks could enable people to train models that generate Deepfakes faster.
 - The authors should consider possible harms that could arise when the technology is being used as intended and functioning correctly, harms that could arise when the technology is being used as intended but gives incorrect results, and harms following from (intentional or unintentional) misuse of the technology.
 - If there are negative societal impacts, the authors could also discuss possible mitigation strategies (e.g., gated release of models, providing defenses in addition to attacks, mechanisms for monitoring misuse, mechanisms to monitor how a system learns from feedback over time, improving the efficiency and accessibility of ML).
- 420
- 421
- 422
- 423
- 424
- 425
- 426
- 427
- 428
- 429
- 430
- 431
- 432
- 433
- 434
- 435
- 436
- 437
- 438
- 439
- 440
- 441
- 442

443 11. Safeguards

444 Question: Does the paper describe safeguards that have been put in place for responsible release of data or models that have a high risk for misuse (e.g., pretrained language models, image generators, or scraped datasets)?

445 Answer: [NA] .

446 Justification: The paper uses a synthetic dataset and proof-of-concept model with no high-risk elements for misuse, so safeguards are not applicable.

447 Guidelines:

- The answer NA means that the paper poses no such risks.
 - Released models that have a high risk for misuse or dual-use should be released with necessary safeguards to allow for controlled use of the model, for example by requiring that users adhere to usage guidelines or restrictions to access the model or implementing safety filters.
 - Datasets that have been scraped from the Internet could pose safety risks. The authors should describe how they avoided releasing unsafe images.
 - We recognize that providing effective safeguards is challenging, and many papers do not require this, but we encourage authors to take this into account and make a best faith effort.
- 448
- 449
- 450
- 451
- 452
- 453
- 454
- 455
- 456
- 457
- 458
- 459
- 460

461 12. Licenses for existing assets

462 Question: Are the creators or original owners of assets (e.g., code, data, models), used in
463 the paper, properly credited and are the license and terms of use explicitly mentioned and
464 properly respected?

465 Answer: [NA] .

466 Justification: No external assets like code, datasets, or models are used. The SimpleObjects
467 dataset is synthetically generated by an LLM; and our model is inspired by previous work
468 on Slot Attention, which is cited without direct reuse requiring licenses, and dual-stream
469 perceptual theories.

470 Guidelines:

- 471 • The answer NA means that the paper does not use existing assets.
- 472 • The authors should cite the original paper that produced the code package or dataset.
- 473 • The authors should state which version of the asset is used and, if possible, include a
474 URL.
- 475 • The name of the license (e.g., CC-BY 4.0) should be included for each asset.
- 476 • For scraped data from a particular source (e.g., website), the copyright and terms of
477 service of that source should be provided.
- 478 • If assets are released, the license, copyright information, and terms of use in the
479 package should be provided. For popular datasets, `paperswithcode.com/datasets`
480 has curated licenses for some datasets. Their licensing guide can help determine the
481 license of a dataset.
- 482 • For existing datasets that are re-packaged, both the original license and the license of
483 the derived asset (if it has changed) should be provided.
- 484 • If this information is not available online, the authors are encouraged to reach out to
485 the asset's creators.

486 13. New assets

487 Question: Are new assets introduced in the paper well documented and is the documentation
488 provided alongside the assets?

489 Answer: [Yes] .

490 Justification: The paper introduces the MVBA model and SimpleObjects dataset, docu-
491 mented in 2.Methods, with code publicly available (Appendix B). No external licensing
492 needed as assets are original/synthetic.

493 Guidelines:

- 494 • The answer NA means that the paper does not release new assets.
- 495 • Researchers should communicate the details of the dataset/code/model as part of their
496 submissions via structured templates. This includes details about training, license,
497 limitations, etc.
- 498 • The paper should discuss whether and how consent was obtained from people whose
499 asset is used.
- 500 • At submission time, remember to anonymize your assets (if applicable). You can either
501 create an anonymized URL or include an anonymized zip file.

502 14. Crowdsourcing and research with human subjects

503 Question: For crowdsourcing experiments and research with human subjects, does the paper
504 include the full text of instructions given to participants and screenshots, if applicable, as
505 well as details about compensation (if any)?

506 Answer: [NA] .

507 Justification: The paper involves no crowdsourcing or human subjects research, only syn-
508 thetic data and computational simulations.

509 Guidelines:

- 510 • The answer NA means that the paper does not involve crowdsourcing nor research with
511 human subjects.

- 512
- Including this information in the supplemental material is fine, but if the main contribution of the paper involves human subjects, then as much detail as possible should be included in the main paper.
- 513
- 514
- According to the NeurIPS Code of Ethics, workers involved in data collection, curation, or other labor should be paid at least the minimum wage in the country of the data collector.
- 515
- 516
- 517

518 **15. Institutional review board (IRB) approvals or equivalent for research with human**
519 **subjects**

520 Question: Does the paper describe potential risks incurred by study participants, whether
521 such risks were disclosed to the subjects, and whether Institutional Review Board (IRB)
522 approvals (or an equivalent approval/review based on the requirements of your country or
523 institution) were obtained?

524 Answer: [NA] .

525 Justification: No human subjects are involved. The research is purely computational on
526 synthetic datasets.

527 Guidelines:

- The answer NA means that the paper does not involve crowdsourcing nor research with human subjects.
 - Depending on the country in which research is conducted, IRB approval (or equivalent) may be required for any human subjects research. If you obtained IRB approval, you should clearly state this in the paper.
 - We recognize that the procedures for this may vary significantly between institutions and locations, and we expect authors to adhere to the NeurIPS Code of Ethics and the guidelines for their institution.
 - For initial submissions, do not include any information that would break anonymity (if applicable), such as the institution conducting the review.
- 528
- 529
- 530
- 531
- 532
- 533
- 534
- 535
- 536
- 537

538 **16. Declaration of LLM usage**

539 Question: Does the paper describe the usage of LLMs if it is an important, original, or
540 non-standard component of the core methods in this research? Note that if the LLM is used
541 only for writing, editing, or formatting purposes and does not impact the core methodology,
542 scientific rigor, or originality of the research, declaration is not required.

543 Answer: [Yes] .

544 Justification: The paper discloses LLM (OpenAI's o3) usage for generating the SimpleOb-
545 jects dataset in methods, which supports experiments but is not core to the method's
546 originality.

547 Guidelines:

- The answer NA means that the core method development in this research does not involve LLMs as any important, original, or non-standard components.
 - Please refer to our LLM policy (<https://neurips.cc/Conferences/2025/LLM>) for what should or should not be described.
- 548
- 549
- 550
- 551