

000 PROPENSITY GUIDED TRANSFORMER FOR CAUSAL 001 002 EFFECT INFERENCE 003 004

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007 008 ABSTRACT 009

010 We introduce the Propensity Similarity guided Bidirectional Transformer (PSBT),
011 a novel framework designed to estimate causal effects in observational data while
012 addressing confounding bias. PSBT employs a pre-training and fine-tuning ap-
013 proach to learn causal representations, guided by propensity scores. In the pre-
014 training phase, the model predicts masked covariates (self-supervised learning)
015 and propensity similarity between unit pairs (weakly supervised learning), en-
016 abling the representation space to disentangle confounding factors. The fine-
017 tuning stage leverages these representations for causal outcome prediction, re-
018 fining them for counterfactual reasoning. Experiments on multiple benchmark
019 datasets demonstrate that PSBT significantly outperforms traditional and state-of-
020 the-art causal inference methods in estimating the Conditional Average Treatment
021 Effect (CATE) and other metrics. By emphasizing propensity-guided learning
022 over conventional balancing techniques, PSBT achieves robust and interpretable
023 representations, advancing deep learning model capabilities in causal effect infer-
024 ence tasks.

025 026 1 INTRODUCTION

027 With the rapid developments of artificial intelligence in wide areas, it is highly needed that deep
028 learning models should have the capability of reasoning, e.g., logic reasoning or mathematical rea-
029 soning. Answering questions like “*What is cause?*” and “*What is effect?*” from the observational
030 data is regarded as the initial step to build general artificial intelligence Pearl (2019). Properly
031 answering questions like “*What would the patient’s health condition be had they received medica-
032 tion A?*” is the central concern of causal effect inference. These studies greatly benefit research in
033 healthcare Casucci et al. (2018; 2019), educational studies Zhao & Heffernan (2017), economics
034 policy making Smith & Todd (2005); Lalonde (1984) and sociology Morgan & Harding (2006).
035 Although most of the research for causal inference is based upon Randomized Controlled Trials
036 (RCTs) Bertsimas et al. (2019), there are a lot of attempts focusing on observational data, also
037 known as observational studies Rosenbaum (2002). The most important challenge for causal in-
038 ference in observational studies is to tackle confounding bias in the data collection process, where
039 confounders affect both the effects of intervention variables on the outcome variables, and the in-
040 tervention variables themselves. Techniques to mitigate confounding bias in causal inference range
041 from covariate matching based optimization methods Stuart (2010) to regression correction based
042 statistical methods Chipman et al. (2008). Recent advances in domain adaptation suggest that a
043 well constructed representation learning model could improve the performance of counterfactual
044 reasoning model significantly on multiple benchmarks Johansson et al. (2016); Du et al. (2019).
045 However, matching-based methods require that all the confounders should be able to be measured,
046 so that the information from treatment variable to response variable could be blocked according to
047 the back-door principles Pearl (2010). In scenarios where only noisy and dependent proxy vari-
048 ables are available, latent variable methods are needed to recover the true confounders for causal
049 inference Louizos et al. (2017).

050 We explore a new framework to estimate causal effect under confounding bias. In this framework,
051 we use a bidirectional transformer model to learn the feature representations for the covariate fea-
052 tures. The representation learning framework is guided by two tasks. On the one hand, we randomly
053 mask the covariate features, and formulate a self-supervised task to predict the masked covariate
features. On the other hand, we combine two units to formulate a subsequent propensity similarity

054 prediction task, where we use the propensity score model to guide the unit pairs as their supervision
 055 for propensity similarity prediction. Hence, we are trying to distill the propensity knowledge into
 056 the feature representation learning model. Rather than learning a balanced representation between
 057 treatment and control groups, this method aims to learn the propensity model in the pre-training
 058 stage.

059 In addition, we formulate a fine-tuning task based on the pre-trained propensity similarity prediction
 060 modeling stage. In the fine-tuning stage, an additional layer of a neural network is formulated to
 061 enable the causal outcome prediction task, where we fine-tune the learned representations as shared
 062 input to the causal prediction layer for the final causal effect inference task.
 063

064 In order to teach the model how to learn the differences between covariate pairs, rather than performing
 065 balancing, we propose to employ the propensity score as knowledge guidance for the attention
 066 mechanism to jointly aggregate the covariate representations. Rather than learning a balanced repres-
 067 entation and performing counterfactual inference, we aim to teach the model to learn the propensity.
 068 Thus, the representation space is able to disentangle the confounding factors, which would help the
 069 counterfactual predictors learn the correct outcome patterns by satisfying the strong ignorability
 070 condition.

071 1.1 MAIN CONTRIBUTIONS

- 072 • We explore propensity difference prediction as a task of transformer model for learning
 073 causal representation.
- 074 • We leverage self-supervised learning as masked tokenization to restrict the latent repres-
 075 entation while learning the propensity model.
- 076 • We perform fine-tuning with causal effect inference task from the pre-trained representa-
 077 tions, which allows for causal modeling of treatment effect.
- 078 • We build a new framework called PSBT by employing the **Propensity Similarity guided**
 079 **Bidirectional Transformer** model, using a pre-training fine-tuning regime. Various ex-
 080 periments on multiple datasets have shown that our proposed PSBT could achieve great
 081 performance in causal effect inference tasks. Source code for reproducing our experi-
 082 ments are released for reviewing purposes <https://anonymous.4open.science/r/PSBT-635C/>.

085 2 PROBLEM SETUP

086 Given a dataset $\mathbb{D} = \{X, T, Y\}$, where $X \in R^{n \times k}$, and $Y \in R^n$, and $T = \{0, 1\}^n$. We have
 087 covariate X_1, \dots, X_k , where for each unit x , an interventional variable t is assigned and the factual
 088 outcome of that intervention is y_f . According to the Rubin-Neyman causal model Rubin (2005), for
 089 $t \in \{0, 1\}$, we have a joint distribution $P_x = (x, t, y_0, y_1)$. Here y_0, y_1 represent the factual and
 090 counterfactual outcome, respectively, regarding to t as y_t, y_{1-t} . Our target is to learn a model to
 091 infer the potential outcome according to the interventional variables.
 092

093 Unlike the variational auto-encoder-based deep latent model family, we explore the transformer-
 094 based model family by self-supervised learning. We show that by properly designing the tasks with
 095 a transformer structure, the learned latent representation is able to gain some causal representation
 096 features useful for downstream causal inference tasks.
 097

098 A directed graph model could be used to represent the relation between latent variables and the
 099 observable variables in Bayesian formulas, which enables the discovery of true causal factors by
 100 posterior approximation Schölkopf et al. (2013). On the other hand, propensity score matching sat-
 101 isfies the strong ignorability condition: it hence indicates the causal direction which aligns with the
 102 directed graphic model Rosenbaum (1996; 2002). We show that by pre-training with contrastive
 103 framework under propensity guidance, and fine-tuning with causal effect prediction tasks, the trans-
 104 former model could be capable of conducting causal effect inference tasks.
 105

106 On the one hand, self-supervised learning maps the input covariates to the representation space with
 107 implicit regularization of mutual information, so that the distribution of latents are formulated. On
 108 the other hand, either an additive noise model or a variational auto-encoder requires to model the
 109 latents in a Gaussian prior, which aligns with the propensity score interpreted as probit function.
 110

108 Hence, the propensity guidance for a representation learned from the transformer framework could
 109 be equivalent to the directed graphic model.
 110

111 In order to make causal inference identifiable via observational data, we make the following assumptions:
 112

113 **Assumption 1 (Strong Ignorability)** *Conditioning on x , the potential outcomes y_0, y_1 are independent of t , which can be stated as: $(y_0, y_1) \perp\!\!\!\perp t|x$.*
 114

115 **Assumption 2 (No Interference)** *The treatment outcome of each individual is not affected by the treatment assignment of other units, which can be formulated as: $Y^u(t^1, \dots, t^n) = Y^u(t^u)$.*
 116

117 **Assumption 3 (Consistency)** *The potential outcome y_t of each individual is equal to the observed outcome y , if the actual treatment received is $T = t$, which can be represented as: $y = y_t$, if $T = t, \forall t$.*
 118

119 **Assumption 4 (Positivity)** *For all sets of covariates and for all treatments, the probability of treatment assignment will always be strictly larger than 0 and strictly smaller than 1, which can be expressed as: $0 < P(t|x) < 1, \forall t$ and $\forall x$.*
 120

121 Here, Assumption 1 indicates that all the confounders can be measured so that the confounders can all be controlled for the adjustment to remove the bias. This is a restrictive but much used assumption in a large subset of causal inference literature Rosenbaum & Rubin (1983). Assumption 4 allows us to estimate the treatment effects for any x in the covariate space. With these assumptions, we can formalize the definition of the CATE as follows:
 122

123 **Definition 1** *The Conditional Average Treatment Effect (CATE) for unit u is: $CATE(u) := \mathbb{E}[y_1|x^u] - \mathbb{E}[y_0|x^u]$.*
 124

125 This definition restricts the conditional probability as the formal definition of individual level causal
 126 effects. Now we can define the *Average Treatment Effect* (ATE) and the *Average Treatment effect on the Treated* (ATT) as:
 127

128 **Definition 2** $ATE := \mathbb{E}[CATE(u)]$, $ATT := \mathbb{E}[CATE(u)|t = 1]$.
 129

130 Here, since the counterfactual outcome cannot be known, we do not know the joint distribution
 131 $P(x, t, y_0, y_1)$. We can only estimate a function over the covariate space \mathbf{X} which is defined as
 132 $f : \mathbf{X} \times \{0, 1\} \rightarrow \mathbf{Y}$. The estimate of $CATE(u)$ can now be defined as:
 133

134 **Definition 3** *Given a dataset $\{X, T, Y\}$ and a function f , for each unit u , the estimate of $CATE(u)$ is: $\widehat{CATE}(u) = f(x^u, 1) - f(x^u, 0)$.*
 135

136 Our main aim is to learn a proper function to approximate this quantity.
 137

138 3 METHODOLOGY: PSBT

139 Our framework **PSBT**: Propensity Similarity guided Bidirectional Transformer consists of two steps
 140 when training: pre-training and fine-tuning. During the pre-training step, the model is trained to
 141 distinguish the propensity similarity on the covariate feature pairs, without accessing the outcome
 142 variables. In this step, a propensity model parameterized by a neural network is first learned on
 143 the covariate features with supervision of the treatment assignment. Then, this model is used to
 144 supervise the covariate feature pairs to enable the propensity guidance. During the fine-tuning step,
 145 the model is initialized with the whole parameters in the pre-training step. Here the treatment out-
 146 come variable is used as the regression target, with an additional layer in the pre-training model as
 147 the component for the prediction task. In the whole process, our model uses a unified architecture
 148 design and there is little difference between the pre-training and fine-tuning downstream tasks.
 149

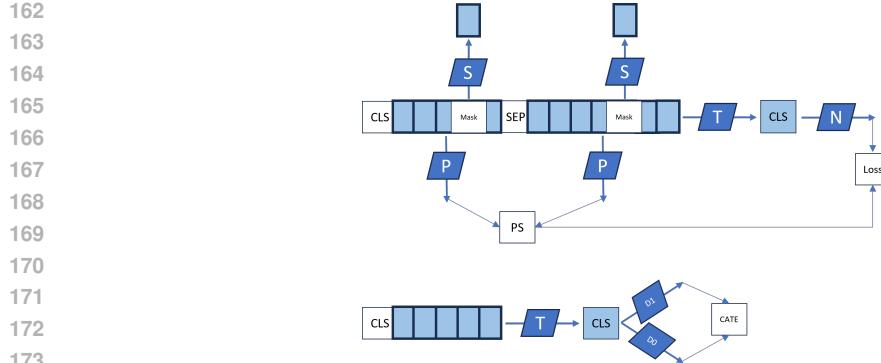


Figure 1: The model framework for the proposed method. In the upper figure, S represents the self-supervised learning component that predicts masked tokens. P represents the propensity component that predicts the propensity scores. T represent the pretrained target that predicts the propensity similarities. N represents the next similarity prediction component that formulates the target loss. In the lower figure, T represents the target prediction that predicts the cls value, D1 and D0 are two causal prediction head that predicts the causal quantities.

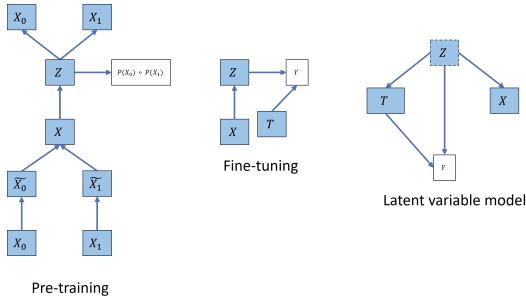


Figure 2: The graphic model for the proposed method.

Model Architecture The basic architecture of PSBT is a multi-layer bidirectional transformer encoder that encodes the covariate features into latent representations. This architecture is based on the implementation described in Vaswani et al. (2017); our implementation is based on the Pytorch library. The official implementation of this architecture has been released in the tensor2tensor library¹. We denote the number of layers, the transformer blocks as L, the hidden size as H, and the number of self-attention heads as A. The report is based on a model PSBT(L=8, H=192, A=8). For the fine-tuning step, we keep most of the architecture the same and add two additional layers to model the treatment outcomes from different interventional arms separately. Figure 1 displays the details of our architecture.

Input / Output Representations. As shown in Figure 2, our method firstly projects the input features to token spaces, where a token is represented by two or three features. A single-layer network is used as the project function to transform the input features to the sequential tokens. For the pre-training stage, a CLS token is initialized to concatenate with the sequential tokens, the final hidden state of representation corresponding to this token is used for the prediction tasks. Unit pairs are packed together into a single sequence, where sequences of unit features are separated by a single token Sep, and a learned embedding is added to every single token to indicate whether or not the feature token belongs to the first or second unit. Positional encoding tokens are also included to add to each token as the formulation of the final input representations to the transformer blocks. For a given token, the final state of that token in the input space is summed by the corresponding token, the segment and position embeddings.

¹<https://github.com/tensorflow/tensor2tensor>

216 3.1 PRE-TRAINING CAUSAL REPRESENTATION
217218 Our architecture is used to encode the bidirectional sequential feature to pre-train PSBT. We train
219 PSBT with one weakly-supervised task and one self-supervised task, as illustrated in Figure 1.
220221
222 **Predict the propensity similarity.** The main goal of this step is to let the model understand the
223 relation between the unit pairs, regarding the propensity similarity. In order to guide the transformer
224 model with the knowledge of propensity scores, this framework sets up a classification token by
225 a learning target to predict the propensity similarity. Back-propagation of errors from neural net-
226 works output to the real-world annotation promotes the success of modern deep learning methods.
227 The model framework in this paper makes use of back-propagation from propensity similarity to
228 guide the transformer learning the causal representation for downstream inference tasks. Propen-
229 sity guidance allows for the representation learning to group the units within the same stratification
230 into a local manifold, so that treatment outcomes from both domains can be learned by the neural
231 networks function, which equals to the adjustment of latent variables.
232233 We obtain the propensity score for each unit by using a pre-trained neural network, specifically: a
234 multi-layer fully connected neural network with BatchNormalization and ReLU layers. This net-
235 work is trained on the tasks with input as the feature vectors and output as the treatment assignment:
236 given a unit with covariate features, the network outputs the propensity of treatment assignment.
237 This pre-trained network generates propensity similarity for each unit pair.238 Another issue to be considered in this method is the choice of metric for measuring the propensity
239 similarity. The output of nuisance functional model maps the covariates to the logit space, repre-
240 senting the similarity between propensities. In order to formulate a stable target space for the model
241 to learn the propensity similarity, this method uses soft binary cross entropy to model the prediction
242 error, by projecting the logit space into the probability space scaling from zero to one. An alternative
243 method is to model the output space with softplus function so that the value can be restricted to \mathbb{R}^+ .
244245 **Self-supervised covariates feature regression.** In order to train a deep bidirectional representa-
246 tion, we mask some percentage of the input tokens at random, and then predict those masked tokens.
247 Here, each token consists of feature compositions, for which real-valued features are projected into
248 real value spaces. This step is the same as the ‘masked language model’ but the sequential part is
249 not sentence sequences any more, but covariate features. The MASK tokens are transformed into
250 latent representations in the final hidden state of the transformer blocks and as the input of a final
251 regression layer. The ground truth feature values are used as the supervised signal to test the self-
252 supervised feature regression task. In order to mitigate the covariate shifts between pre-training and
253 fine-tuning, we do not always use a MASK token to replace the tokens. There are 10% positions of
254 token are marked by the MASK token, and among them 80% are kept with the masked condition,
255 10% are randomly replaced by other tokens, and 10% of the them remain the same.
256257 In conclusion, the framework of our proposed method as illustrated in Figure 1 encompasses a mod-
258 eling process with two steps. First, pre-training is conducted by introducing the propensity model
259 for sequence level supervision and self-supervised learning is conducted to regulate the learned
260 representations. Subsequently, a task level supervision is conducted to enable the network to do
261 counterfactual reasoning.
262263 3.2 FINE-TUNING CAUSAL MODEL
264265 In the fine-tuning stage we keep all the parameters from the pre-training stage instead of two addi-
266 tional layers, where each layer represents the task of predicting the causal outcomes of the model, as
267 shown in the bottom figure in Figure 1. This step is straightforward due the self-attention mechanism
268 of transformer architectures. In the fine-tuning stage, only one unit is used as inputs to the network
269 and the final hidden state of the CLS token is used as the input to the causal layer. There are two
270 causal layers, each corresponding to one potential outcome Y_0, Y_1 . The fine-tuning stage enables the
271 model to further adjust the representation learning pre-trained from the last stage to adjust according
272 to each potential outcomes.
273

270
 271 Table 1: Statistics on the employed datasets. In the MIMIC-III dataset, the numbers of control and
 272 treatment units are simulated. The details of both procedures are provided in the main text, specifi-
 273 cally in the corresponding paragraphs of Section 4.1, where each dataset is introduced. Additionally,
 274 note that the control unit pool in the Jobs dataset consists of two components (cf. Section 4.1, Jobs
 275 paragraph).

Dataset	Observations	Control/treatment	Covariates	Reference
IHDP	747	608/139	25	Hill Hill (2011)
Jobs	3 122	2 915/297	7	Lalonde Lalonde (1984)
MIMIC-III	7 413	-/-	25	Johnson et al. Johnson et al. (2016)
Twins	25 656	12 828/12 828	43	Louizos et al. Louizos et al. (2017)

4 EXPERIMENTS

Our experiments aim to answer the following questions:

- How effective is the Transformer-based model in learning representations for causal inference tasks?
- How much benefit could the propensity supervision bring for the causal inference tasks?

4.1 DATASETS

To properly assess our method, we run experiments on several datasets that are designed to evaluate causal effect inference tasks. Because of the unobservable counterfactual outcomes, semi-simulated or simulated datasets are used to create ground truth data Hill (2011). Table 1 lists summary statistics for the datasets.

IHDP Hill (2011). The Infant Health and Development Program (IHDP) examines the effect of specialist home visits on infants’ future cognitive test scores. This semi-simulated dataset is derived from covariates collected during a real-world randomized experiment. Treatment selection bias is introduced by excluding a subset of the treatment group. Treatment outcomes are simulated using Setting ‘A’ as described in Dorie (2016). The dataset includes 747 units: 608 in the control group and 139 in the treatment group, with each unit characterized by 25 covariates.

Jobs Lalonde (1984); Smith & Todd (2005). The Jobs dataset evaluates the impact of job training on employment outcomes. It combines a randomized component from the National Supported Work program with a non-randomized component from observational studies. The randomized dataset includes 722 units (425 control and 297 treated) with seven covariates. The non-randomized dataset (PSID comparison group) consists of 2 490 control units.

MIMIC-III Johnson et al. (2016). This benchmark dataset is derived from MIMIC-III, a database of de-identified patient profiles and health outcomes for critical care unit patients. The dataset includes demographic details and observed laboratory measurements (chemistry and hematology). After filtering for missing values, the dataset comprises 7 413 samples, each with 25 covariates. The binary treatment examines the effect of prescription amount on ICU length of stay: $t = 0$ represents a small prescription amount, and $t = 1$ represents a large prescription amount. Treatment outcomes are simulated as $y|x, t \sim (w^T + \beta t + n)$, where $n \sim N(0, 1)$, $w \sim N(0, 0.5 \cdot (\Sigma + \Sigma^T))$, and $\Sigma \sim U((-1, 1)^{25 \times 25})$. Treatment assignment follows $t|x \sim Bern(\sigma(s^T x + m))$, where $m \sim N(0, 0.1)$ and $s \sim N(0, 0.1 \cdot I)$.

Twins Louizos et al. (2017). The Twins dataset is constructed from the “Linked Birth/Infant Death Cohort Data” by NBER. Using a matching algorithm, it selects twin births in the USA from 1989 to 1991. The dataset contains 43 covariates, including parental demographics (education, age, race), health factors (prenatal care timing, number of prenatal visits), and other conditions. Only same-gender twin pairs weighing less than 2 000g are included. The treatment variable assigns $t = 0$ for the lighter twin and $t = 1$ for the heavier twin, with the first-year mortality rate as the outcome.

324
 325 Table 2: In-sample and out-of-sample results with mean and standard errors on the IHDP dataset
 326 (lower = better).

Methods	In-sample		Out-sample	
	$\sqrt{\epsilon_{\text{PEHE}}}$	ϵ_{ATE}	$\sqrt{\epsilon_{\text{PEHE}}}$	ϵ_{ATE}
OLS/LR ₁	5.8 ± .3	.73 ± .04	5.8 ± .3	.94 ± .06
OLS/LR ₂	2.4 ± .1	.14 ± .01	2.5 ± .1	.31 ± .02
S.Learner	1.7 ± .6	.18 ± .04	3.0 ± .5	.36 ± .06
T.Learner	1.5 ± .1	.17 ± .03	2.7 ± .6	.33 ± .04
BLR	5.8 ± .3	.72 ± .04	5.8 ± .3	.93 ± .05
BART	2.1 ± .1	.23 ± .01	2.3 ± .1	.34 ± .02
k-NN	2.1 ± .1	.14 ± .01	4.1 ± .2	.79 ± .05
RF	4.2 ± .2	.73 ± .05	6.6 ± .3	.96 ± .06
CF	3.8 ± .2	.18 ± .01	3.8 ± .2	.40 ± .03
BNN	2.2 ± .1	.37 ± .03	2.1 ± .1	.42 ± .03
TARNet	.88 ± .0	.26 ± .01	.95 ± .0	.28 ± .01
CFR-Wass	.71 ± .0	.25 ± .01	.76 ± .0	.27 ± .01
CEVAE	2.7 ± .1	.34 ± .01	2.6 ± .1	.46 ± .02
SITE	.69 ± .0	.22 ± .01	.75 ± .0	.24 ± .01
ABCEI	.71 ± .0	.09 ± .01	.73 ± .0	.09 ± .01
PSBT	.51 ± .0	.03 ± .01	.53 ± .0	.03 ± .01

341
 342 Mortality is 19.02% for lighter twins and 16.54% for heavier twins. Observational outcomes for
 343 both treatments are available. Selection bias is simulated by selectively observing one twin based
 344 on covariates, modeled as $t|x \sim \text{Bern}(\sigma(w^T x + n))$, where $w^T \sim N(0, 0.1 \cdot I)$ and $n \sim N(1, 0.1)$.
 345

346 4.2 BASELINE METHODS

347 We consider three groups of baselines:

- 350 1. Statistical estimators: least square regression using treatment as a feature (OLS/LR₁); separate least square regressions for each treatment (OLS/LR₂); a single network with treatment as covariates (S.learner Künzel et al. (2019)); separate neural regressors for each treatment group (T.learner Künzel et al. (2019)); random forest (RF Breiman (2001)).
- 351 2. Matching-based estimators: balancing linear regression (BLR); k-nearest neighbor (k-NN Crump et al. (2008)); causal forest (CF Wager & Athey (2018)); Bayesian additive
 352 regression trees (BART Sparapani et al. (2016)).
- 353 3. Learning-based estimators: balancing neural network (BNN Johansson et al. (2016)); treatment-agnostic representation networks (TARNet) and counterfactual regression with Wasserstein distance (CFR-Wass Shalit et al. (2017)); causal effect variational autoencoders (CEVAE Louizos et al. (2017)); local similarity preserved individual treatment effect (SITE Yao et al. (2018)) and adversarial balancing-based representation learning for causal effect inference (ABCEI Du et al. (2019)).

363 We demonstrate a quantitative comparison between our proposed method and the baseline methods. All baseline methods are parameterized according to the recommended settings in the original
 364 papers.

367 4.3 EVALUATION METRICS

370 We use a semi-simulated method to include the benchmark datasets like IHDP and MIMIC-III, so
 371 that we can know the ground truth for the CATE estimation. Hence, we can use *Precision in Esti-
 372 mation of Heterogeneous Effect* (PEHE) Hill (2011) as the evaluation metric of CATE estimation:

$$374 \epsilon_{\text{PEHE}} = \frac{1}{n} \sum_{u=1}^n ((\mathbb{E}[y_1|x^u] - \mathbb{E}[y_0|x^u]) - (f(x^u, 1) - f(x^u, 0)))^2.$$

377 Subsequently, the precision of ATE estimation can be evaluated based on the estimated CATE. On
 the Jobs dataset, because we combine non-randomized components and randomized components,

378

379
Table 3: In-sample and out-of-sample results with mean and standard errors on the Jobs dataset
380 (lower = better).

Methods	In-sample		Out-sample	
	R_{pol}	ϵ_{ATT}	R_{pol}	ϵ_{ATT}
OLS/LR ₁	.22 ± .0	.01 ± .00	.23 ± .0	.08 ± .04
OLS/LR ₂	.21 ± .0	.01 ± .01	.24 ± .0	.08 ± .03
S.Learner	.21 ± .0	.02 ± .01	.24 ± .0	.08 ± .03
T.Learner	.20 ± .0	.02 ± .01	.22 ± .0	.08 ± .03
BLR	.22 ± .0	.01 ± .01	.25 ± .0	.08 ± .03
BART	.23 ± .0	.02 ± .00	.25 ± .0	.08 ± .03
k-NN	.23 ± .0	.02 ± .01	.26 ± .0	.13 ± .05
RF	.23 ± .0	.03 ± .01	.28 ± .0	.09 ± .04
CF	.19 ± .0	.03 ± .01	.20 ± .0	.07 ± .03
BNN	.20 ± .0	.04 ± .01	.24 ± .0	.09 ± .04
TARNet	.17 ± .0	.05 ± .02	.21 ± .0	.11 ± .04
CFR-Wass	.17 ± .0	.04 ± .01	.21 ± .0	.08 ± .03
CEVAE	.15 ± .0	.02 ± .01	.26 ± .1	.03 ± .01
SITE	.17 ± .0	.04 ± .01	.21 ± .0	.09 ± .03
ABCEI	.13 ± .0	.02 ± .01	.17 ± .0	.03 ± .01
PSBT	.10 ± .0	.01 ± .01	.11 ± .0	.02 ± .01

396

397
Table 4: In-sample and out-of-sample results with mean and standard errors on the Twins dataset
398 (AUC: higher = better, ϵ_{ATE} : lower = better).

Methods	In-sample		Out-sample	
	AUC	ϵ_{ATE}	AUC	ϵ_{ATE}
OLS/LR ₁	.660 ± .005	.004 ± .003	.500 ± .028	.007 ± .006
OLS/LR ₂	.660 ± .004	.004 ± .003	.500 ± .016	.007 ± .006
S.Learner	.680 ± .009	.111 ± .013	.520 ± .033	.131 ± .015
T.Learner	.695 ± .008	.091 ± .008	.580 ± .024	.105 ± .009
BLR	.611 ± .009	.006 ± .004	.510 ± .018	.033 ± .009
BART	.506 ± .014	.121 ± .024	.500 ± .011	.127 ± .024
k-NN	.609 ± .010	.003 ± .002	.492 ± .012	.005 ± .004
BNN	.690 ± .008	.006 ± .003	.676 ± .008	.020 ± .007
TARNet	.849 ± .002	.011 ± .002	.840 ± .006	.015 ± .002
CFR-Wass	.850 ± .002	.011 ± .002	.842 ± .005	.028 ± .003
CEVAE	.845 ± .003	.022 ± .002	.841 ± .004	.032 ± .003
SITE	.862 ± .002	.016 ± .001	.853 ± .006	.020 ± .002
ABCEI	.871 ± .001	.003 ± .001	.863 ± .001	.005 ± .001
PSBT	.885 ± .001	.001 ± .001	.876 ± .001	.001 ± .001

410

411
412 we know parts of the ground truth, and hence we can evaluate the precision of ATT estimation and
413 policy risk estimation. Here:

414
415
$$R_{\text{pol}}(\pi) = 1 - \mathbb{E}(y_1 | \pi(x^u) = 1) \cdot P(\pi = 1) - \mathbb{E}(y_0 | \pi(x^u) = 0) \cdot P(\pi = 0). \quad (1)$$

416
417 We consider $\pi(x^u) = 1$ when $f(x^u, 1) - f(x^u, 0) > 0$.418
419 For the Twins dataset, because we only know the observed treatment outcome for each unit, we
420 follow Louizos et al. (2017) in using the Area Under the ROC Curve (AUC) as the evaluation metric.421
422

4.4 RESULTS

423
424 Tables 2-4 list experimental results on each of the four datasets. It would be inappropriate to aggre-
425 gate the statistical test results reported across these tables. Due to the varying availability of ground
426 truth, different evaluation metrics are used for each dataset, making it unsuitable to combine these
427 metrics into a single statistical hypothesis test. However, PSBT demonstrates superior performance
428 in 15 out of 16 cases. This is evident not only from having the best results in the columns but
429 also from often exhibiting non-overlapping empirical confidence intervals compared to the closest
430 competitor. This provides strong evidence that PSBT represents a significant improvement over the
431 current state of the art.432
433 The Jobs and IHDP datasets have the smallest numbers of observations, the smallest numbers of
434 covariates, and a pronounced imbalance between control and treatment group sizes (cf. Table 1).
435 Here, PSBT achieves competitive performance against baselines. On datasets with more observa-

432
 433 Table 5: In-sample and out-of-sample results with mean and standard errors on the MIMIC-III
 434 benchmark (lower = better).

Methods	In-sample		Out-sample	
	$\sqrt{\epsilon_{\text{PEHE}}}$	ϵ_{ATE}	$\sqrt{\epsilon_{\text{PEHE}}}$	ϵ_{ATE}
OLS/LR ₁	7.1 \pm .2	.92 \pm .15	8.2 \pm .2	.97 \pm .15
OLS/LR ₂	2.7 \pm .1	.24 \pm .11	3.3 \pm .2	.29 \pm .13
S.Learner	2.2 \pm .2	.36 \pm .09	2.8 \pm .3	.39 \pm .09
T.Learner	1.8 \pm .1	.31 \pm .13	2.1 \pm .1	.33 \pm .15
BLR	7.3 \pm .1	.90 \pm .09	8.5 \pm .3	.97 \pm .09
BART	2.4 \pm .2	.31 \pm .09	3.1 \pm .2	.37 \pm .12
k-NN	2.8 \pm .1	.32 \pm .11	3.6 \pm .1	.36 \pm .11
RF	4.6 \pm .3	.88 \pm .10	5.3 \pm .3	.89 \pm .11
CF	4.1 \pm .1	.22 \pm .13	4.9 \pm .1	.24 \pm .14
BNN	2.5 \pm .1	.45 \pm .11	3.3 \pm .1	.49 \pm .11
TARNet	1.91 \pm .0	.25 \pm .16	2.11 \pm .1	.31 \pm .16
CFR-Wass	1.06 \pm .0	.19 \pm .14	1.09 \pm .0	.21 \pm .14
CEVAE	2.71 \pm .0	.23 \pm .11	2.72 \pm .0	.23 \pm .12
SITE	1.29 \pm .0	.21 \pm .14	1.35 \pm .0	.25 \pm .14
ABCEI	.85 \pm .0	.11 \pm .12	.89 \pm .0	.12 \pm .14
PSBT	.55 \pm .0	.07 \pm .05	.59 \pm .0	.07 \pm .04

449
 450 tions, more covariates, and greater balance between control and treatment groups, PSBT consistently
 451 performs better.

452 Regression-based methods struggle with high generalization error due to treatment selection bias.
 453 Nearest neighbor-based methods address selection bias by considering unit similarity but fail to
 454 achieve global balance. Recent advances in domain adaptation have improved causal effect esti-
 455 mation but suffer from the imbalance between treatment and control groups. PSBT makes use of
 456 propensity guidance to supervise the representation learning model to learn the causal knowledge,
 457 enabling PSBT to make counterfactual prediction with fine tuned causal models. This makes PSBT
 458 outperform baseline methods.

460 5 CONCLUSIONS

461 Properly answering questions like “*What would patient’s outcome be had they taken medication*
 462 *A?*” is one of the central issues of the causal effect inference problems. Traditional methods focus
 463 on tackling the confounding bias problem by covariate balancing, learning a balanced represen-
 464 tation for the treatment and control groups. We propose a new framework **PSBT**: a **P**ropensity
 465 **S**imilarity **g**uided **B**idirectional **T**ransformer model for causal effect inference. PSBT makes use
 466 of the propensity knowledge to supervise the representation learning in order to teach the model to
 467 learn the differences between the propensities between the two units. A bidirectional transformer
 468 model is trained by two supervising tasks: the one is to learn to predict the covariate features that are
 469 randomly masked, the other is to learn to predict the propensity similarity. By learning the propen-
 470 sity similarity, the model learns to disentangle the confounding factors. After the pre-training stage,
 471 we apply a fine-tuning stage to fine-tune the pre-trained propensity model into the causal model.
 472 An additional neural network layer is employed to enable the causal prediction task. By conduct-
 473 ing multiple experiments on several real-world datasets, we demonstrate that PSBT significantly
 474 outperforms traditional and state-of-the-art baseline methods.

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618

619 A RELATED WORK

620

621 Research on causal effect inference provides insights into the underlying data-generating processes
 622 and enables us to answer counterfactual questions. Only one response can be observed at the same
 623 time. The fundamental challenge in causal effect inference lies in the identifiability problem given
 624 certain data and assumptions Tian & Pearl (2002). Properly designed causal models are used to
 625 guarantee the identifiable causal effect during the inference process Imbens & Rubin (2015). In
 626 order to satisfy the strong ignorability condition for unbiasedly estimate the causal effects, *Randomized
 627 Controlled Trials* (RCTs) are designed to create comparable groups for treatment effect
 628 estimation Rosenbaum (2002). In observational studies, these groups are achieved by matching
 629 units from different groups to meet the identifiability condition, which lead to the formulation of *Average
 630 Treatment effects on Treated* (ATT) Nikolaev et al. (2013). On the other hand, learning-based
 631 algorithms are developed to estimate the *Average Treatment Effects* (ATE) to achieve a comprehen-
 632 sive understanding about the causal effects on the population and individual level Chipman et al.
 633 (2008); Shalit et al. (2017).

634 Matching-based methods aim to create comparable units from treated and untreated groups, achiev-
 635 ing locally balanced distributions. Techniques Wu et al. (2023) vary in their similarity measures.
 636 Propensity score matching Rosenbaum & Rubin (1983) is a notable example, using estimated
 637 propensity scores to assess similarity between units. Tree-based methods Wager & Athey (2018),
 638 which employ adaptive similarity measures, are also a part of this category, though they are often
 639 computationally intensive and challenging to apply in large-scale settings.

640 As opposed to matching-based methods, we employ the propensity model to estimate the distance
 641 between covariate pairs in the latent space, so that the knowledge of propensity could be learned by
 642 the representation learning model to ensure the identifiability condition. Propensity scores are often
 643 estimated using logistic regression models Chen et al. (2021); Dai et al. (2022); Lee et al. (2021),
 644 with techniques such as feature selection Wang et al. (2023a;b). A key example of an unbiased
 645 estimator is the inverse propensity score method Rosenbaum & Rubin (1983), which reweights each
 646 unit inversely to its estimated propensity score. However, this method can suffer from high variance
 647 in cases of low propensity and may introduce bias when propensity estimates are inaccurate Li et al.
 648 (2023a). To address these issues, doubly robust estimators and variance reduction techniques have

648 been developed Li et al. (2023b), although these methods are still limited by their dependence on
649 propensity scores, impacting their practical effectiveness.
650

651 Learning-based methods attempt to map data into a feature space where distributional discrepancies
652 are minimized. The primary challenge is accurately measuring these discrepancies. Initial studies
653 employed metrics like maximum mean discrepancy and basic Wasserstein discrepancy Johansson
654 et al. (2016); Shalit et al. (2017), while subsequent work introduced techniques such as local simi-
655 larity preservation Yao et al. (2018; 2019), feature selection Cheng et al. (2022); Hassanpour &
656 Greiner (2019), representation decomposition Wu et al. (2022), and adversarial training Yoon et al.
657 (2018). Despite their effectiveness, these methods struggle in certain common scenarios, such as
658 outlier presence Fatras et al. (2021) and unlabeled confounders, which can compromise the reliabil-
659 ity of discrepancy measures.

660 One of the core issues in representation learning is to learn a meaningful information encoding for
661 different modes of the input data. Contrastive information coding is one way to achieve this goal
662 in unsupervised and semi-supervised learning scenarios. In general, contrastive learning aims to
663 formulate a learning target by sampling similar pairs of data plus dissimilar ones. This allows for
664 the representation to be formulated as clusters of latent classes Saunshi et al. (2019). In a causal
665 inference scenario, these latent clusters can be related to the stratifications of covariate representa-
666 tions, which is indicated by the propensity models. We propose to achieve this goal by formulating
667 sequential pairs and learn the distinguished representations in the transformer framework.
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