Poirot at CMCL 2022 Shared Task: Zero Shot Crosslingual Eye-Tracking Data Prediction using Multilingual Transformer Models

Harshvardhan Srivastava Oracle India, Bengaluru Indian Institute of Technology, Kharagpur harshvardhan.srivastava@oracle.com

Abstract

Eye tracking data during reading is a useful source of information to understand the cognitive processes that take place during language comprehension processes. Different languages account for different cognitive triggers, however there seems to be some uniform indicators across languages. In this paper, we describe our submission to the CMCL 2022 shared task on predicting human reading patterns for multilingual dataset. Our model uses text representations from transformers and some hand engineered features with a regression layer on top to predict statistical measures of mean and standard deviation for 2 main eye-tracking features. We train an end-to-end model to extract meaningful information from different languages and test our model on two separate datasets. We compare different transformer models and show ablation studies affecting model performance. Our final submission ranked 4th place for SubTask-1 and 1st place for SubTask-2 for the shared task.

1 Introduction

Eye tracking provides an accurate millisecond record of where people are looking while reading and is useful for descriptive study of language processing and understanding of the cognitive processing of brain related to reading. Eye movements are many times language-specific because they depend on structure and ordering of words which are language dependent, however some features tend to be stable and universal and can be observed in all languages. Modeling of human reading has been widely explored in psycholinguistics. The ability to accurately predict eye tracking between languages pushes this field forward, facilitating comparisons between models and analysis of their various functions.

In this paper, we compare our eye-tracking prediction results with some simple baselines using token-level features, which we improve upon with our zero shot cross lingual model which we have described in section 3.

2 Task Description

2.1 Problem Statement

In this section we briefly describe the task at hand which is the challenge of predicting eye-tracking features recorded during sentence processing of multiple languages. This task is more complex as compared to previous editions of the shared task due to changes made compared to the previous edition (Hollenstein et al., 2021); (i) Multilingual data: We use an eye movement dataset with sentences from six languages (Chinese, Dutch, English, German, Hindi, Russian) and (ii) Eyetracking features: To take into account the individual differences between readers, the task is not limited to predict the mean eye tracking features across readers, but also the standard deviation of the feature values. The task details can be found in Hollenstein et al. (2022).

We formulate the task as a regression task to predict 2 eye-tracking features and the corresponding standard deviation across readers. The targets are briefly described here: **first fixation duration** (**FFDAvg**), the duration of the first fixation on the prevailing word; **standard deviation** (**FFDStd**) across readers; **total reading time** (**TRTAvg**), the sum of all fixation durations on the current word, including regressions; **standard deviation** (**TRT-Std**) across readers.

The shared task is modelled as two related subtasks of increasing complexity :

Subtask 1: Predict eye-tracking features for sentences of the 6 provided languages

Subtask 2: Predict eye-tracking features for sentences from a new surprise language

2.2 Related Work

Multiple deep learning approaches have been explored in the past on cognitive modelling with lin-

				Trainin	g Set	Dev	Set	Test S	Set	
Name	Abbreviation	Language	Subjects	Sentences	Tokens	Sentences	Tokens	Sentences	Tokens	Source
Beijing Sentence Corpus	BSC	Zh	60	120	1355	7	82	23	248	Pan et al. (2021)
Postdam-Allahabad Hindi Eye- tracking Corpus	PAHEC	Hī	30	122	2021	7	142	24	433	Husain et al. (2015)
Russian Sentence Corpus	RSC	Ru	84	115	1140	7	59	22	218	Laurinavichyute et al. (2019)
Provo Corpus	Provo	En	30	107	2067	6	152	21	440	Luke and Christianson (2018
ZuCo 1.0 Corpus (NR)	ZuCo1	En	12	240	5235	15	269	45	994	Hollenstein et al. (2018)
ZuCo 2.0 Corpus (NR)	ZuCo2	En	18	279	5398	17	303	53	1127	Hollenstein et al. (2019)
GECO Corpus (Dutch L1 part)	GECO-NL	NL	18	640	7462	40	405	120	1475	Cop et al. (2017)
Potsdam Textbook Corpus	PoTeC	DE	75	80	1463	5	139	16	293	Jäger et al. (2021)
Copenhagen Corpus	СорСо	DA	-	-	-	-	-	402	6767	-

Table 1: Overview of the selected datasets

guistic perspective on English datasets ZuCo (Hollenstein et al., 2018, 2019) and Provo(Luke and Christianson, 2018). Salicchi and Lenci (2021) uses cosine similarity and surprisal within regression architecture to model the surprisal characteristic of a new word. Li and Rudzicz (2021); Yu et al. (2021) use the transformer methods to extract the linguistic embeddings; the former applying ensembling methods while the latter using surface, linguistic and behavioral features in combination with the linguistic embeddings.

2.3 Dataset

The dataset comprises of the eye-tracking data recorded during natural reading from 8 datasets in 6 languages. The training data contains 1703 sentences, the development set contains 104 sentences, and the test set 324 sentences. The data provided contains scaled features in the range between 0 and 100 to facilitate evaluation via the mean absolute average (MAE). The eye-tracking feature values are averaged over all readers.

The detailed dataset information about the number of sentences in each datasource and the tokenwise information is shown in table 1.

3 Our Approach

Our models heavily use contextualised embeddings extracted from the pretrained models based on transformer architecture (Vaswani et al., 2017). We experiment on the training dataset with multilingual transformer models which are briefly described below :

mBERT (Devlin et al., 2019) a deep contextual representation based on a series of transformers trained by a self-supervised objective with data from Wikipedia in 104 languages. It has been trained with masked language modelling objective and training makes no use of explicit cross-lingual signal.

XLM (Lample and Conneau, 2019) is a Transformer-based model that, like BERT, is trained with the masked language modeling (MLM) objective. Additionally, XLM is trained with a Translation Language Modeling (TLM) objective in an attempt to force the model to learn similar representations for different languages.

XLM-RoBERTa (Conneau et al., 2020) uses self-supervised training techniques to achieve stateof-the-art performance in cross-lingual understanding. It is trained on unlabeled text in 100 languages extracted from CommonCrawl datasets.

These transformer methods use either WordPiece or BytePair model for tokenization, due to which we use only the first token embedding of the tokenized word by these methods. We use the above three transformer models and attach the extracted output embeddings from these models to the manually constructed features which we have described in 3.1. The entire model architecture is explained in Figure 1.

3.1 Features

Along with the encoder representations from the multilingual transformer models, we use 3 additional features, which we use to help us provide information to our embeddings. We discard other features like POS-Tag and word_freq, due to non-uniformity in cross-lingual setting and unavailability of reliable and enormous word-frequency list for some of the languages which could reduce the performance and create bias for some languages during training time.

The first two length based features use word division information and the word length information. During neurological processing of language, brain takes up dual pathways to process a word as shown

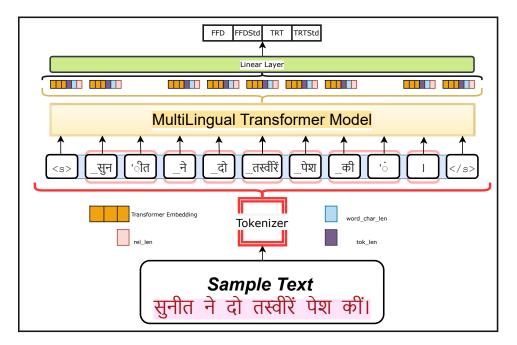


Figure 1: Model Representation

in MacGregor and Shtyrov (2013). The third feature is based on the relative length of the word as compared to preceding word.

tok_len : This feature is length of the parts of words when the word is tokenized measured in number of parts, which focuses on the complexity of the word based on length as cognitively longer words as processed.

word_char_len : This second feature is based on the apparent space taken up by the word evaluated by the number of characters it takes up when represented in UTF-8 format. This feature is inspired by studies shown in Joseph et al. (2009).

rel_len: The third feature is the relative length of the word as compared to its preceding word. This can capture a sense of ease in reading a short word immediately after reading a word with great character length. For starting words of the sentence, we take the previous word length as zero.

3.2 Baselines

We start by implementing some simple baselines using token-level features using length based ideas as word-length is a commonality which can be found in multilingual settings which we described in section 3.1. We start with a median baseline model which takes the median of all the training token labels, instead of using an average baseline to prevent offsetting the predictions by a language with higher or lower valued variables. Along with the median baseline , we also use 5 commonly used machine learning regression models (i) Linear Regression (*lr*),(ii) Support Vector Regression (*svr*),(iii) Gradient Boosting Methods (*lgbm*, *xgboost*), (iv) Multi-Layer Perceptron (*MLPRegressor*) as our baselines. These baselines do not contain any contextual information.

3.3 Implementation and Hyperparameter Details

The models were trained with MSE(mean squared error) as loss function and the final evaluation was done using MAE(Mean Absolute Error) measure. For the baseline, models were trained taking each label as a regression target variable to remove label correlation if a regressor performs poorly in a multi output regression setting, while when using transformer based models, we trained a single model with a 4 length output regressor head which corresponded each to the final output target variables. Before the final regression layer, we used a hidden linear layer after the embedding output. The model evaluation for task submission was done using dev set after every epoch to measure the performance improvement and prevent overfitting. The implementation can be found here 1 .

The details of the hyperparameters used for the training are given in table 4.

¹https://github.com/hvarS/CMCL-2022

			Dev Set				Test	Set - SubTa	ısk1			Test	Set - SubTa	isk2	
Model	FFDAvg	FFDStd	TRTAvg	TRTStd	Overall	FFDAvg	FFDStd	TRTAvg	TRTStd	Overall	FFDAvg	FFDStd	TRTAvg	TRTStd	Overall
Baseline _{median}	5.931	2.578	8.999	5.886	5.848	5.448	2.440	8.361	5.661	5.478	3.459	2.436	6.524	5.857	4.569
Baseline _{lr}	5.615	2.570	8.574	5.768	5.632	5.243	2.465	8.289	5.750	5.437	4.755	3.002	8.721	7.252	5.932
Baseline _{svr}	5.203	2.492	8.118	5.650	5.366	4.848	2.356	7.700	5.465	5.092	3.580	2.399	6.588	5.798	4.591
Baseline _{l qbm}	5.209	2.528	8.004	5.534	5.319	4.835	2.415	7.869	5.584	5.176	4.390	2.966	8.407	7.127	5.723
Baseline _{MLPRegressor}	5.268	2.531	8.195	5.701	5.423	4.914	2.418	7.972	5.734	5.260	4.315	2.904	8.136	7.328	5.671
Baseline _{xqboost}	5.210	2.532	8.050	5.566	5.340	4.834	2.413	7.871	5.591	5.178	4.302	2.942	8.337	7.106	5.672
mBERTuncased	5.014	2.512	7.981	5.523	5.257	4.795	2.325	7.267	5.409	4.949	3.756	3.012	5.578	5.841	4.546
mBERT _{cased}	5.025	2.492	8.011	5.498	5.369	4.801	2.413	7.342	5.124	4.920	3.754	3.056	5.579	5.764	4.538
XLM_{100}	4.914	2.584	8.134	5.512	5.286	4.902	2.425	7.814	5.414	5.138	3.331	2.944	5.448	5.798	4.380
XLM-RoBERTabase	4.892	2.486	8.231	5.504	5.278	4.745	2.327	7.321	5.738	5.031	3.214	2.987	5.556	5.666	4.355
$\mathbf{XLM}\textbf{-}\mathbf{RoBERTa}_{large}$	4.845	2.482	7.943	5.491	5.215	4.738	2.364	7.268	5.223	4.898	2.945	2.726	5.602	5.654	4.232

Table 2: MAE results on the dev and test set. Bold entries are the best performing models for that particular target

		SubT	`ask-1		SubTask-2				
Model Version	FFDAvg	FFDStd	TRTAvg	TRTStd	FFDAvg	FFDStd	TRTAvg	TRTStd	
XLM-RoBERTalarge	4.738	2.364	7.268	5.223	2.945	2.726	5.602	5.654	
- tok_len	4.746	2.486	7.314	5.463	2.944	2.692	5.605	5.640	
- word_char_len	4.976	2.484	7.454	5.478	3.014	2.696	5.712	5.642	
- rel_len	4.787	2.486	7.457	5.466	3.121	2.703	6.241	5.644	
 tok_len,word_char_len 	5.012	2.427	7.785	5.421	3.154	2.710	6.785	5.546	
- tok_len,rel_len	5.097	2.497	7.854	5.601	3.564	2.731	6.645	5.645	
- word_char_len,rel_len	5.124	2.492	7.771	5.671	3.452	2.722	6.621	5.664	
- tok_len,word_char_len,rel_len	5.465	2.488	8.370	5.684	4.371	2.744	7.186	5.678	

Table 3: Feature Importance Ablation Study. The best performing model XLM-RoBERTa is taken for ablation

Parameter	Value		
Optimizer	AdamW		
Warm-Up Steps (%)	10%		
epochs	100		
learning rate	5e-2		
weight decay	1e-2		
dropout	0.5		
batch size	64		
hidden layer size	1024		

Table 4: Hyperparameter Details

4 Results and Discussion

Table 2 shows the evaluation results on the dev set and the two test sets for SubTask-1 and SubTask-2 respectively based on MAE on the 4 target variables. Our transformer based models strongly outperformed the baseline approaches. The best performing model was XLM-RoBERTalarae model, edging over the transformer models. mBERT model performed better than the XLM model on SubTask-1, but XLM outperforms the former on SubTask-2, suggesting better zero shot performance of XLM for this subtask. Also, the large models tended to perform better than their base counterpart implying higher parameter count resulted in better cross-lingual and zero shot crosslingual performance. Also since originally the XLM-RoBERTa, mBERT and XLM models were

trained for masked language modelling purpose, they have inherent inner representations of over 100 languages which helps in cross-lingual downstream tasks. One possible reason that mBERT performs better than XLM on SubTask-1 could be that XLM models are used for general sentence representations which mBERT identifies language from context and infers accordingly. For the same mentioned reason, it is possible that XLM performs better in zero shot setting.

4.1 Feature Importance

To evaluate the effectiveness of the engineered features ; tok_len, word_char_len and rel_len, an ablation study was conducted using the best performing model. We employ the strategy similar to used in Oh (2021); the three input features were ablated by simply replacing them with zeros during inference, which allowed us to effectively analyse the influence of these additional features. Table 3 shows the effects of model performance without the permutation of the engineered features.

Ablations on the external features show that these features affect the mean (μ) feature values, specifically the *FFDAvg* and the *TRTAvg*, indicating that these external features influence the final model performance for target mean values while the contextualised embedding portion takes care of the standard deviation (σ) of the targets. It can be observed that the word_char_len feature affects the target FFDAvg value to a large extent, while rel_len clearly affects the model performance on SubTask-2. One of the possible reasons could be the infusion of previous word contextual knowledge captured by rel_len. Also, the feature tok_len in combination with other features also improves the model performance, which may indicate it being not a very strong sole indicator.

5 Conclusion and Future Work

In this paper, we presented our approach to the CMCL 2022 Shared Task on eye-tracking data prediction. Our models use the fusion model that involve using the multilingual contextualized token representations using transformer architecture and attaching input features that we created that aid the model performance in predicting eye tracking features. This approach helped us become language agnostic which essentially helped the model to perform well in the zero shot cross-lingual setting in Subtask-2. Our best model based on XLM-RoBERTa outperforms the baseline and is also competitive with other systems submitted to the shared for both SubTask-1 and SubTask-2. Although the embeddings from large language models as shown previously work fairly well as they consider the context of the sentence into consideration as well, possibly they can be improved further if take into consideration the surprisal index which would positively correlate with the reading time and fixation duration as shown in Salicchi and Lenci (2021). In future, we aim to use more etymological features based on shared language history and also use the cross language lexical similarity index when predicting in cross lingual setting.

References

- Alexis Conneau, Kartikay Khandelwal, Naman Goyal, Vishrav Chaudhary, Guillaume Wenzek, Francisco Guzmán, Edouard Grave, Myle Ott, Luke Zettlemoyer, and Veselin Stoyanov. 2020. Unsupervised cross-lingual representation learning at scale.
- Uschi Cop, Nicolas Dirix, Denis Drieghe, and Wouter Duyck. 2017. Presenting geco: An eyetracking corpus of monolingual and bilingual sentence reading. *Behavior research methods*, 49(2):602–615.
- Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. 2019. Bert: Pre-training of deep bidirectional transformers for language understanding.

- Nora Hollenstein, Emmanuele Chersoni, Cassandra L. Jacobs, Yohei Oseki, Laurent Prévot, and Enrico Santus. 2021. CMCL 2021 shared task on eye-tracking prediction. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*, pages 72–78, Online. Association for Computational Linguistics.
- Nora Hollenstein, Emmanuelle Chersoni, Cassandra Jacobs, Yohei Oseki, Laurent Prévot, and Enrico Santus. 2022. Cmcl 2022 shared task on multilingual and cross lingual prediction of human reading behavior. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*.
- Nora Hollenstein, Jonathan Rotsztejn, Marius Troendle, Andreas Pedroni, Ce Zhang, and Nicolas Langer. 2018. Zuco, a simultaneous eeg and eye-tracking resource for natural sentence reading. *Scientific data*, 5(1):1–13.
- Nora Hollenstein, Marius Troendle, Ce Zhang, and Nicolas Langer. 2019. Zuco 2.0: A dataset of physiological recordings during natural reading and annotation. *arXiv preprint arXiv:1912.00903*.
- Samar Husain, Shravan Vasishth, and Narayanan Srinivasan. 2015. Integration and prediction difficulty in hindi sentence comprehension: Evidence from an eye-tracking corpus. *Journal of Eye Movement Research*, 8.
- Lena A Jäger, Thomas Kern, and Patrick Haller. 2021. Potsdam textbook corpus (potec).
- Holly S.S.L. Joseph, Simon P. Liversedge, Hazel I. Blythe, Sarah J. White, and Keith Rayner. 2009. Word length and landing position effects during reading in children and adults. *Vision Research*, 49(16):2078–2086.
- Guillaume Lample and Alexis Conneau. 2019. Crosslingual language model pretraining.
- Anna K Laurinavichyute, Irina A Sekerina, Svetlana Alexeeva, Kristine Bagdasaryan, and Reinhold Kliegl. 2019. Russian sentence corpus: Benchmark measures of eye movements in reading in russian. *Behavior research methods*, 51(3):1161–1178.
- Bai Li and Frank Rudzicz. 2021. TorontoCL at CMCL 2021 shared task: RoBERTa with multi-stage finetuning for eye-tracking prediction. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*, pages 85–89, Online. Association for Computational Linguistics.
- Steven G Luke and Kiel Christianson. 2018. The provo corpus: A large eye-tracking corpus with predictability norms. *Behavior research methods*, 50(2):826– 833.
- Lucy J. MacGregor and Yury Shtyrov. 2013. Multiple routes for compound word processing in the brain: Evidence from eeg. *Brain and Language*, 126(2):217–229.

- Byung-Doh Oh. 2021. Team Ohio State at CMCL 2021 shared task: Fine-tuned RoBERTa for eye-tracking data prediction. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*, pages 97–101, Online. Association for Computational Linguistics.
- Jinger Pan, Ming Yan, Eike Richter, Hua Shu, and Reinhold Kliegl. 2021. The beijing sentence corpus: A chinese sentence corpus with eye movement data and predictability norms. *Behavior Research Methods*.
- Lavinia Salicchi and Alessandro Lenci. 2021. PIHKers at CMCL 2021 shared task: Cosine similarity and surprisal to predict human reading patterns. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*, pages 102–107, Online. Association for Computational Linguistics.
- Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, and Illia Polosukhin. 2017. Attention is all you need.
- Qi Yu, Aikaterini-Lida Kalouli, and Diego Frassinelli. 2021. KonTra at CMCL 2021 shared task: Predicting eye movements by combining BERT with surface, linguistic and behavioral information. In *Proceedings of the Workshop on Cognitive Modeling and Computational Linguistics*, pages 120–124, Online. Association for Computational Linguistics.