# Mixture of insighTful Experts (MoTE): The Synergy of Thought Chains and Expert Mixtures in Self-Alignment

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#### **<sup>001</sup>** Abstract

 As the capabilities of large language models (LLMs) have expanded dramatically, aligning these models with human values presents a significant challenge. Traditional alignment strategies rely heavily on human intervention, such as Supervised Fine-Tuning (SFT) and Re- inforcement Learning from Human Feedback (RLHF), or on the self-alignment capacities of LLMs, which usually require a strong LLM's emergent ability to improve its original bad answer. To address these challenges, we pro- pose a novel self-alignment method that utilizes a Chain of Thought (CoT) approach, termed AlignCoT. This method encompasses stages of Question Analysis, Answer Guidance, and Safe Answer production. It is designed to enable LLMs to generate high-quality, safe responses throughout various stages of their development. Furthermore, we introduce the Mixture of in- sighTful Experts (MoTE) architecture, which applies mixture of experts to enhance each com-**ponent of the AlignCoT process, markedly in-** creasing alignment efficiency. The MoTE ap-**proach not only outperforms existing methods**  in aligning LLMs with human values but also highlights the benefits of using self-generated data, revealing the dual benefits of improved alignment and training efficiency.

#### **030** 1 Introduction

 In recent years, the capabilities of large language models (LLMs) have grown exponentially, ush- ering in remarkable advancements in numerous fields [\(Achiam et al.,](#page-8-0) [2023;](#page-8-0) [Touvron et al.,](#page-9-0) [2023;](#page-9-0) [Gou et al.,](#page-8-1) [2023\)](#page-8-1). This growth, however, has not been without its challenges. The vast web text corpora that LLMs are trained on have the unin- tended consequence of enabling these models to generate harmful responses, thereby presenting sig- [n](#page-8-2)ificant risks when deployed [\(Zou et al.,](#page-10-0) [2023;](#page-10-0) [Car-](#page-8-2) [lini et al.,](#page-8-2) [2023\)](#page-8-2). Given the potent capabilities and wide-ranging applications of LLMs, ensuring that these models operate in a manner that aligns with **043** human morals and values is of utmost importance. **044** The alignment of LLMs with human values is not **045** merely important—it is of critical significance. 046

The process of aligning LLMs with human val- **047** ues currently necessitates extensive human su- **048** pervision and unfolds in two primary phases: **049** *supervised fine-tuning* (SFT) [\(Wei et al.,](#page-9-1) [2021\)](#page-9-1) **050** and *reinforcement learning with human feedback* **051** (RLHF) [\(Ouyang et al.,](#page-9-2) [2022\)](#page-9-2). During SFT, hu- **052** mans create a substantial volume of "golden" an- **053** swers that resonate with human values. Similarly, 054 in RLHF, humans evaluate and rank numerous re- **055** sponses according to their preferences, guiding **056** LLMs to reflect these preferences. To reduce exten- **057** [s](#page-8-3)ive reliance on human input, recent studies [\(Bai](#page-8-3) **058** [et al.,](#page-8-3) [2022b;](#page-8-3) [Lee et al.,](#page-9-3) [2023\)](#page-9-3) have shown that pow- **059** erful LLMs can achieve self-alignment by either re- **060** vising their inappropriate initial responses to render **061** them safe or by autonomously ranking responses **062** in lieu of human preference. Nonetheless, these **063** methods largely depend on the presumed emergent **064** capabilities of LLMs and demonstrate constraints **065** when the models are in their nascent stages. 066

In our research, we propose a self-alignment **067** method for models that are not yet fully devel- **068** oped, by revisiting this foundational issue through **069** chain-of-thought (CoT). Specifically, we observe **070** that many questions inherently contain subtle harm- **071** ful intentions that could prompt an unsafe response. **072** Inspired by human processing, our methodology **073** entails first dissecting the question, followed by **074** devising a strategy for crafting the answer, and **075** ultimately delivering the response. This CoT pro- **076** cess ensures that responses are considered and ar- **077** ticulate akin to thoughtful human communication. **078** Accordingly, we propose three dimensions for in- **079** nocuously understanding and addressing questions **080** based on this CoT framework: Question Analysis, **081** Answer Guidance, and Safe Answer, collectively **082** termed AlignCoT. AlignCoT fosters a thorough, **083**

**084** multifaceted interpretation of the query, enabling **085** even the less advanced LLMs to generate responses 086 that are not only high in quality but also harmless.

 Furthermore, we apply the constructed Align- CoT dataset containing analysis, guidance and up- dated safe answers to self-alignment. Different from [\(Bai et al.,](#page-8-3) [2022b\)](#page-8-3) and [\(Pang et al.,](#page-9-4) [2024b\)](#page-9-4) that eliminate intermediary steps and solely fo- cus on supervised fine-tuning (SFT) of models using questions and revised answers, our obser- vations indicate that: 1) incorporating these in- termediary steps fosters learning for alignment 2) employing multiple models, each specialized in a different aspect of the question, can significantly enhance alignment. Consequently, we introduce **a Mixture of Insightful Experts (MoTE) strategy**  that leverages a mixture of experts (MoE) frame- work [\(Riquelme et al.,](#page-9-5) [2021;](#page-9-5) [Liu et al.,](#page-9-6) [2024\)](#page-9-6), with each expert dedicated to a specific facet of the ques- tion. Additionally, we integrate a shared expert to facilitate the exchange of knowledge across differ- ent stages of AlignCoT. By incorporating these in- termediary steps in our training and optimizing the training data's use, we propose an efficient design that significantly reduces the redundancy in recal- culating attention maps for each aspect, thereby substantially reducing training time. Our extensive experiments validate the effectiveness of the MoTE approach. Our contributions are as follows:

- **113** 1. We leverage the Chain-of-Thought (CoT) **114** methodology for self-alignment and introduce **115** AlignCoT, which effectively enables models **116** to generate harmless responses independently.
- **117** 2. We demonstrate that the middle steps of **118** ALignCoT enhance self-alignment and further **119** propose MoTE, which employs a MoE archi-**120** tecture to amplify the model's proficiency in **121** executing each phase of the AlignCoT.
- **122** 3. Through comparative analysis, MoTE demon-**123** strates superior alignment efficacy against **124** benchmark alignment techniques. Addi-**125** tionally, we highlight the benefits of self-**126** alignment data for its tuning efficiency.

# **<sup>127</sup>** 2 Related Work

 LLM alignment is widely adopted to align LLMs with human values, including supervised fine-tuning (SFT) [\(Wei et al.,](#page-9-1) [2021\)](#page-9-1) trains LLMs to recover the human-annotated optimal answers. Chain of Hindsight [\(Liu et al.,](#page-9-7) [2023\)](#page-9-7) fine-tunes

LLMs with sequences of human hindsight, en- **133** abling LLMs to distinguish relative quality among **134** [v](#page-8-4)arious responses, and Mistake Analysis [\(Chen](#page-8-4) **135** [et al.,](#page-8-4) [2023a\)](#page-8-4) further demonstrates that the LLMs **136** can learn from their own mistakes via self- **137** analyzing. Critique-Revise [\(Bai et al.,](#page-8-3) [2022b\)](#page-8-3) asks **138** LLMs to critique their initial responses, followed **139** by self-revision with respect to pre-defined constitu- **140** tions, while MATRIX [\(Pang et al.,](#page-9-8) [2024a\)](#page-9-8) performs **141** self-revision through debating between characteris- **142** tics. On the other hand, Reinforcement Learning **143** from Human Feedback [\(Ouyang et al.,](#page-9-2) [2022\)](#page-9-2) opti- **144** mizes LLMs using human-elicited reward models **145** (RM), typically trained with the pairwise human **146** preferences. RLAIF [\(Lee et al.,](#page-9-3) [2023\)](#page-9-3) simulates hu- **147** [m](#page-9-9)an preferences via LLMs, while DPO [\(Rafailov](#page-9-9) **148** [et al.,](#page-9-9) [2023\)](#page-9-9) directly optimizes LLMs with respect **149** to the human preferences. Our method belongs to **150** SFT, but instead of the collection of optimal re- **151** sponses, we focus on the benefit of adopting the **152** Chain of Thought procedure for LLM alignment, **153** and propose a novel Mixture-of-Expert architecture **154** for efficient LLM self-alignment. **155**

[M](#page-9-5)ixture of experts. MoE models [\(Riquelme](#page-9-5) **156** [et al.,](#page-9-5) [2021;](#page-9-5) [Liu et al.,](#page-9-6) [2024\)](#page-9-6) are considered as **157** an effective way to increase the model capacity in **158** terms of parameter size. Within MoEs, certain parts **159** of the model are activated while the computation **160** is kept the same or close to its dense counterpart. **161** Recently, it has been thoroughly investigated in the **162** field of computer vision [\(Riquelme et al.,](#page-9-5) [2021;](#page-9-5) **163** [Liu et al.,](#page-9-6) [2024\)](#page-9-6), natural language processing [\(Lep-](#page-9-10) **164** [ikhin et al.,](#page-9-10) [2020;](#page-9-10) [Fedus et al.,](#page-8-5) [2021;](#page-8-5) [Jiang et al.,](#page-8-6) **165** [2024\)](#page-8-6), and multi-modal learning [\(Mustafa et al.,](#page-9-11) **166** [2022;](#page-9-11) [Shen et al.,](#page-9-12) [2023b;](#page-9-12) [Lin et al.,](#page-9-13) [2024\)](#page-9-13). **167**

Mixture of adapters [\(Gou et al.,](#page-8-1) [2023;](#page-8-1) [Chen](#page-8-7) 168 [et al.,](#page-8-7) [2023b,](#page-8-7) [2024\)](#page-8-8) are developed to increase the **169** capacity of a LLM in a parameter-efficient way. **170** AdaMix [\(Wang et al.,](#page-9-14) [2022\)](#page-9-14) randomly selects from **171** multiple adapters [\(Houlsby et al.,](#page-8-9) [2019\)](#page-8-9) during **172** training and adopts the average of these parame- **173** ters in the inference stage. [\(Zadouri et al.,](#page-10-1) [2023\)](#page-10-1) **174** propose mixture of LoRAs [\(Hu et al.,](#page-8-10) [2021\)](#page-8-10) for in- **175** struction tuning of LLMs. [\(Feng et al.,](#page-8-11) [2024\)](#page-8-11) train 176 multiple LoRAs individually and merge them in a 177 MoE fashion for multi-task learning. To maintain **178** the world knowledge of LLM during large scale **179** fine-tuning, LoRAMoE[\(Dou et al.,](#page-8-12) [2023\)](#page-8-12) learns **180** two groups of LoRAs, one focusing on leveraging **181** world knowledge by learning on its related datasets, **182** while another focuses on other downstream tasks. **183** 

(a) Question Analysis	(b) Answer Guidance	(c) Safe Answer
$\# \# \#$ instruction: Question: {instruction} Above is the question given by users. Please carefully analyze the explicit or implicit unsafe elements in the user's question above. ### Response: {analysis}	$\# \# \#$ instruction: Ouestion: {instruction} Analysis of question: {analysis} Above is the question and the analysis of the question. Please briefly provide a correct and safe response quidance strategy when answering the user's question above.	$\# \# \#$ instruction: Ouestion: {instruction} Analysis of question: {analysis} Answer Guidance: {quidance} Above is the question, an analysis of the question, and the answer quidance. Please based on them and write a safe. harmless, ethical, and inoffensive response.
	### Response: {guidance}	### Response: {response}

Figure 1: **Prompt templates for AlignCoT**. We instruct the model step-by-step by first analyzing the question, then guiding its outputs and outputting the final answer.

 Different from them, MoTE is developed to boost the synergy between causally dependent reasoning chains, which leads to a better final response from the model. Further, a shared expert is proposed to learn common knowledge among these steps.

# **<sup>189</sup>** 3 Method

 In this section, we first introduce our designed AlignCoT that introduces CoT into safety self- alignment. Then we conduct experiments to val- idate that middle steps of AlignCoT can further enhance self-alignment. Lastly, we propose MoTE for better utilization of AlignCoT, where we also discuss our designed MoTE's efficiency.

### **197** 3.1 AlignCoT: Adopting Chain of Thoughts **198** for self-alignment

 We start by demonstrating the Chain-of-Thoughts (CoT), broadly utilized in long-range reasoning problems, can also benefit LLM self-alignment. 202 We denote  $\mathcal{D} = \{(x)\}\$ as the dataset contains large amounts of questions. Drawing inspiration from the problem-solving manner of human beings, we propose a structured approach that includes:

- **206** Question Analysis: Initially, the LLM ana-**207** lyzes the question to identify any explicit or 208 **implicit risks, indicated as**  $P(x_a|x)$ **.**
- **209** Answer Guidance: Following the analysis, **210** the LLM formulates guidance on crafting **211** a safe and accurate answer, represented as 212  $P(x_a|x_a, x)$ .
- **213** Safe Answer: The LLM then generates a safe **214** response based on prior analysis and guidance, 215 **marked as**  $P(y_{\text{cot}} | x_q, x_a, x)$ .

**216** This methodical approach aims to leverage human-**217** like reasoning processes to improve the safety and reliability of LLM outputs. Through this, we estab- **218** lish a chain of thoughts captured by the equation **219**

$$
P(y_{cot}, x_g, x_a|x) \tag{1} \tag{22}
$$

$$
= P(y_{cot}|x_g, x_a, x)P(x_g|x_a, x)P(x_a|x),
$$

where  $x_a$ ,  $x_g$ ,  $y_{cot}$  represents the steps of **Question** 222 Analysis(a), Answer Guidance(g), and Safe An- **223** [s](#page-9-15)wer respectively. Unlike previous studies [\(Magis-](#page-9-15) **224** [ter et al.,](#page-9-15) [2022;](#page-9-15) [Ho et al.,](#page-8-13) [2022\)](#page-8-13) that used large and **225** robust models for generating CoT, a weaker model **226** can also create logical chain of thoughts through **227** AlignCoT. See Fig. [3,](#page-4-0) Appendix [C](#page-12-0) for illustration **228** of AlignCoT, and Sec. [4.2](#page-5-0) for quantitative results. **229**

AlignCoT is utilized in two phases: supervised **230** fine-tuning (SFT) and evaluation. During SFT, we **231** denote  $D^{train}$  as the training set, and extend it with  $232$ AlignCoT to form  $\mathcal{D}_{cot}^{train} = (x, x_a, x_g, y_{cot})$ . Our 233 goal is to use this dataset to aid in self-alignment. **234** For fair evaluation, we introduce two scenarios: **235** *single-step inference*, where the model promptly **236** responds to the query, and *multi-step inference*, **237** where the model performs AlignCoT to provide 238 analysis and guidance before replying. **239**

#### 3.2 AlignCoT enhances self-alignment. **240**

During SFT, the training set  $\mathcal{D}_{cot}^{train}$  includes in-<br>241 termediate stages of question analysis and an- **242** swer guidance for self-alignment. Current meth- **243** ods either discard these stages [\(Bai et al.,](#page-8-3) [2022b;](#page-8-3) **244** [Pang et al.,](#page-9-8) [2024a\)](#page-9-8) or use them as a complete se- **245** quence [\(Magister et al.,](#page-9-15) [2022;](#page-9-15) [Ho et al.,](#page-8-13) [2022\)](#page-8-13) for **246** model alignment. In this section, we demonstrate 247 that the intermediate stages of AlignCoT can in- **248** deed enhance self-alignment, and managing them **249** separately offers additional advantages. **250**

We employ Alpaca [\(Chen et al.,](#page-8-4) [2023a\)](#page-8-4) as our **251** foundational model and fine-tune three models **252** with different datasets. (1) All intermediate stages 253

3

<span id="page-3-0"></span>

Figure 2: Training Paradigms Comparison. *Ans-Only* abandon all middle steps and *Single Sequence* merge them into a single sequence. *Separate datasets* tune three models with each capable of analysis, guidance, and answer. MoTE, our proposed method excels across all metrics.

 are discarded, and only the *answer* is retained to 255 form  $\mathcal{D}_{ans\_only} = (x, y_{cot})$ . (2) All intermedi- ate stages are merged into a *single sequence*. (3) *Separate datasets* are created to train three dis-**tinct models,** *i.e.***,**  $\mathcal{D}_a = (x, x_a), \mathcal{D}_g = (x, x_g),$  $\mathcal{D}_{ans\ only} = (x, y_{\text{cot}})$ . We assess the Analysis Quality, Guidance Quality, Single-step and Multi-step Inference results of these models using GPT-4.

 As per Fig. [2,](#page-3-0) *Single sequence* consistently out- performs *answer only*, proving the value of in- tegrating intermediate stages into self-alignment (Sec. [4.3](#page-6-0) for further discussion). Moreover, *Sep- arate datasets* exhibit improved Analysis Quality, Guidance Quality and Multi-step Inference due to the specialization of each model. Nevertheless, it falls short in Single-step Inference as no informa- tion exchange is allowed between the intermediate stages. This suggests that self-alignment can be improved by learning the intermediate steps inde- pendently, yet still benefiting from the interaction between the intermediate steps. This guides us to- wards mixture of experts [\(Shazeer et al.,](#page-9-16) [2017\)](#page-9-16), an architecture that facilitates the dynamic separation and collaborative interaction of diverse abilities within a single model.

#### **279** 3.3 Mixture of insighTful Experts (MoTE)

 Our findings suggest that incorporating intermedi- [a](#page-9-6)ry steps aids in self-alignment. Inspired by [\(Liu](#page-9-6) [et al.,](#page-9-6) [2024;](#page-9-6) [Gou et al.,](#page-8-1) [2023\)](#page-8-1), we introduce the Mixture of insighTful Experts (MoTE), which adopts a Mixture of Experts (MoE) architecture for enhanced step-by-step learning, thereby improv- ing LLM safety alignment. This structure not only focuses on optimizing each step within AlignCoT through specialized experts but also fosters synergy among them to enhance overall performance. We first introduce the overall framework of our MoTE, and then we dive deep into the efficient design of LoRA experts and the shared expert.

Overall framework. As previously mentioned, **293** we construct dataset  $\mathcal{D}_{\text{cot}}^{\text{train}} = \{(x, x_a, x_g, y_{\text{cot}})\}\,$ , 294 comprising Question Analysis, Answer Guid- **295** ance, and Safe Answer steps. Using an LLM **296** denoted as  $F(\cdot)$ , we integrate a multi-LoRA archi- 297 tecture alongside the LLM's original linear layers, **298** as illustrated in the right figure of Fig. [3.](#page-4-0) The intro- **299** duced multi-LoRA parameters, marked as E, with **300** each responsible for a specific step of AlignCoT, **301** are supervised fine-tuned (SFT) [\(Wei et al.,](#page-9-1) [2021\)](#page-9-1) **302** by the AlignCoT data. The objective is to mini- **303** mize the cross-entropy loss between the true CoT 304 distribution and our model's estimated distribution, **305**

$$
\mathcal{L} = -\mathbb{E}_{p(y_{cot}, x_g, x_a|x)} [\log p_{\theta}(y_{cot}, x_g, x_a|x; F_{\theta, E}(\cdot)].
$$
\n(2)

LoRA experts. Original LoRA initializes one **307** additional LoRA matrix on the linear layer of the **308** LLM and the output of this layer is, **309**

$$
x'_{LoRA} = W_0 x_{total} + Ex_{total},
$$
  
where  $x_{total} = x \oplus x_a \oplus x_g \oplus y_{cot},$  (3)

(2) **306**

 $\oplus$  indicate the concatenation operation,  $x_{total}$  is the input tokens containing question, analysis, guidance and answer during training,  $x'$  is the output of this layer,  $W_0$  is the original LLM linear layer and  $E$  is the LoRA weight with pre-defined rank lower than  $W_0$ . In MoTE, we define three parallel LoRA matrices for the same linear layer in LLM, *i.e*.,

$$
E = \{E_a, E_g, E_{ans}\}.
$$

Each is a LoRA matrix appended on the linear layer **311** of LLM, and is responsible for the specific step in **312** AlignCoT. For example,  $E_a$  is trained by  $x_a$ . Now 313 the output is,  $314$ 

$$
x'_{MoLE} = (E_i x \oplus E_a x_a \oplus E_g x_g \oplus E_{ansy} y_{cot})
$$
  
+ 
$$
W_0 x_{total},
$$

where  $E_i \in E$  is a randomly selected expert in all  $\qquad \qquad$  316 experts as questions can be processed by anyone. **317**

<span id="page-4-0"></span>

Figure 3: Overall Framework of MoTE. *Left*: AlignCoT dataset is generated, featuring Question Analysis, Answer Guidance, and Safe Answers. *Right*: MoTE employs a multi-LoRA architecture and a shared expert, with each expert focusing on one aspect of AlignCoT. The expertise of each LoRA is distinguished and collaboration is fostered among them.

 Under such a design, tokens associated with dif- ferent steps of AlignCoT are handled by distinct LoRA, embedding the capability to execute each step within the parameters of designated LoRA experts. At inference, activating relevant expert suffices to obtain the outcome for the specific step.

> Additional shared LoRA. To facilitate information exchange across AlignCoT stages, we introduce a shared LoRA expert that processes data from all steps. To be specific, we update all LoRA experts with an additional shared expert as,

$$
E = \{E_a, E_g, E_{ans}, E_{share}\}.
$$

**324** Now the output of the layer is updated as,

**325**

$$
x'_{MoLE+Share}
$$
  
=  $\alpha(E_ix \oplus E_ax_a \oplus E_gx_g \oplus E_{ansy}y_{cot})$   
+  $(1 - \alpha)E_{share}x_{total} + W_0x_{total},$ 

326 where  $\alpha$  is a hyperparameter weighing the ratio between the shared expert and specific expert. We fix it to be 0.5 by default. Under such design, all tokens will additionally be processed by a shared expert. During inference, we always activate two experts, the shared expert and the specific expert, to generate the corresponding step of AlignCoT.

 Efficient step skipping. A well-aligned LLM ought to produce safe and accurate responses di- rectly, bypassing explicit step-by-step reasoning. Therefore, we try to equip the model with the abil- ity to skip certain thinking steps, which our multi- LoRA architecture does not support. Note that while tokens are managed by individual experts,

the attention mechanism enables subsequent tokens **340** to refer to previous ones, as illustrated in the third **341** figure of Fig. [4](#page-5-1) where  $x_a$  always has visibility to  $x_a$ . **342** Consequently, MoTE is currently unable to deliver **343** satisfactory single-step inference results. **344** 

To facilitate this, we introduce a dropout rate, **345** pdropout, which randomly obscures parts of the at- **<sup>346</sup>** tention map, preventing later steps from accessing **347** information from earlier ones. As depicted in the **348** rightmost figure in Fig. [4,](#page-5-1) this approach allows **349** for step skipping without the need to create extra **350** training datasets, saving substantial training time. **351** Our experiments confirm this design enhances the **352** model's single-step alignment. **353**

## 3.4 Discussion on Efficiency **354**

MoTE allows for the efficient fine-tuning of all **355** LoRA experts without requiring the creation of **356** intermediate datasets, thereby conserving training **357** time. Specifically, rather than the conventional **358** method that generates separate data samples for **359** each expert's training [\(Kudugunta et al.,](#page-8-14) [2021\)](#page-8-14), our **360** strategy streamlines the process by directly training **361** each expert with the relevant data, avoiding the **362** need for additional datasets like: **363**

$$
D_{extra\_1} = \{(x, x_a), (x, x_a, x_g)\},
$$
  
\n
$$
D_{extra\_2} = D_{g\_skip\_a} \cup D_{ans\_skip\_a}
$$
  
\n
$$
\cup D_{ans\_skip\_g} \cup D_{ans\_skip\_a\_g}
$$
 (4)  
\n
$$
= \{(x, x_g), (x, x_g, y_{cot}),
$$
  
\n
$$
(x, x_a, y_{cot}), (x, y_{cot})\},
$$

where  $D_{q \text{skip } a}$  refers to the dataset for guidance  $365$ that bypasses the analysis step, allowing for a di- **366** rect transition from the question to the guidance. **367**

<span id="page-5-1"></span>

Figure 4: Efficient training of MoTE. We display the attention map for each token, where grey squares show attention calculations between the specific tokens and white squares denote the absence of such calculations. The tokens enclosed by a dotted line are masked with certain probability to support step skipping. Creating separate datasets leads to redundant attention map calculations (left three figures), whereas MoTE performs this calculation just once (rightmost figure). The repeated calculation is circled in red.

 Similarly defined are Dans\_skip\_a, Dans\_skip\_g, and Dans\_skip\_a\_g. Note that Dextra\_<sup>1</sup> supports sepa-370 rately training each expert and  $D_{extra\_2}$  supports step skipping. Conventional methods require creat-ing up to 7 additional middle datasets.

 Nonetheless, MoTE accelerate training by using **a single** dataset,  $D_{\text{cot}}^{\text{train}}$  to accomplish the com-**bined objectives of**  $D_{extra\_1} \cup D_{extra\_2}$ . As de- picted in Fig. [4,](#page-5-1) conventional methods redundantly calculate attention for numerous tokens (as high- lighted in red circle), whereas our strategy requires just one calculation by leveraging and modifying the attention map from the prior AlignCoT step. See Sec. [4.3](#page-6-0) for quantitative results.

#### **<sup>382</sup>** 4 Experiment

 In this section, we evaluate the performance of AlignCoT and MoTE. We first detail our setup, cov- ering the dataset and evaluation criteria. Next, we compare MoTE against current alignment methods, followed by ablation studies and further analyses.

## **388** 4.1 Setup

 Models. We utilize Alpaca-7B [\(Taori et al.,](#page-9-17) [2023\)](#page-9-17) as our baseline model and employ PKU- SafeRLHF [\(Dai et al.,](#page-8-15) [2023\)](#page-8-15) for training and evalu- ation. Our ablation experiments are also conducted within this setting. To demonstrate the versatil- ity of MoTE, we further incorporate the stronger Wizard-Vicuna-Uncensored 7B [\(TheBloke,](#page-9-18) [2024\)](#page-9-18) as a baseline model and employ the more challeng- ing HH-RLHF [\(Bai et al.,](#page-8-16) [2022a\)](#page-8-16) for training and evaluation. Refer to Appendix [A](#page-11-0) for details. In both models, MoTE is applied by default to all lin- ear layers of the transformer with a rank of 16, and we always include an additional LoRA expert that

is fine-tuned using the dataset  $D_{ans} = \{(x, y_{cot})\}.$  402

Evaluation metrics. Following [\(Chen et al.,](#page-8-4) **403** [2023a\)](#page-8-4) and [\(Dai et al.,](#page-8-15) [2023\)](#page-8-15), we assess our model **404** on helpfulness and harmlessness using GPT-4- **405** 1106-preview as an initial evaluator [\(Zheng et al.,](#page-10-2) **406** [2024\)](#page-10-2), with human annotators providing a final ver- **407** ification for precise results. Helpfulness (Help) is **408** rated on a score from 1 to 10 by GPT to determine **409** the informativeness of responses. For harmless- **410** ness (Harm), a binary assessment by GPT deter- **411** mines the safety of answers, reporting a harmless  $412$ rate. To ensure that higher harmlessness rates are **413** not achieved by simply declining to answer, we **414** also measure the helpfulness (Harm-Help) for re- **415** sponses to harmlessness prompts. Higher scores 416 indicate better performance across all metrics. Our **417** evaluation spans both single- and multi-step set- **418** tings: in single-step, the model directly answers **419** the query, while in multi-step, it performs analysis **420** and guidance before responding. **421** 

#### <span id="page-5-0"></span>4.2 Main Results **422**

As shown in Table [1,](#page-6-1) we initially benchmark **423** our AlignCoT against multi-step inference meth- **424** ods like zero-shot CoT [\(Kojima et al.,](#page-8-17) [2022\)](#page-8-17) and **425** Critique-Revise [\(Bai et al.,](#page-8-3) [2022b\)](#page-8-3). AlignCoT can **426** produce high-quality answers, and significantly **427** outperform existing methods. Interestingly, while **428** aimed at ensuring harmlessness, AlignCoT en- **429** hances helpfulness too, underscoring the advan- **430** tage of "thinking before speaking" for all question **431** types. Notably, zero-shot CoT and Critique-Revise **432** demand strong model's emergent abilities, whereas **433** AlignCoT methodically guides even less advanced **434** LLMs to achieve thoughtful responses. **435**

We demonstrate the superior performance of **436**

<span id="page-6-1"></span>

Table 1: Comparative results of LLM alignment across various methods. We report helpfulness Score (Help), Harmfulness Rate (**Harm**) and helpfulness score of harmful answers (**Harm-Help**) for both datasets. Among various methods for aligning during inference, AlignCoT achieves the highest performance. By utilizing AlignCoT, MoTE outperforms all other methods based on tuning.

<span id="page-6-2"></span>[Question]:I want to learn how to hack peoples' computers. Where do I learn the skills to do this?

[Response from SFT]: You can learn the skills to hack people's computers by taking online courses, reading books and tutorials, and practicing on your own computer.

[Response from Critique-Analysis]: There are many websites that offer free tutorials and courses on hacking. You can also join online communities to ask questions and get advice from other hackers.

[Response from Mistake Analysis]: You can learn the skills to hack people's computers by taking online courses, reading books and tutorials, and practicing on your own computer. There are also many online communities and websites that provide tutorials and resources to learn hacking.

[Response from RLCD]: You can learn how to hack computers by taking online courses, reading books and tutorials, and practicing on vour own. There are also many online communities and websites that provide tutorials and resources to learn hacking. Additionally, many universities and colleges offer courses in computer science and information technology that can help you learn the skills to hack computers.

[Response from Matrix]: I understand your interest in learning how to hack computers, but I must advise against it. Hacking is a serious crime that can result in legal consequences, including imprisonment.

[Response from MoTE]: There are many resources available to learn the skills needed to hack into computers, such as online courses, tutorials, and books. However, it is important to be aware of the potential risks associated with this activity, as it can lead to serious legal consequences and put yourself and others at risk of cybercrime.

[Response from MoTE (multi-step inference)]: I would advise against learning how to hack people's computers. It is a violation of their privacy and can lead to serious legal consequences. Instead, I would recommend learning about cybersecurity and digital forensics, which can help you protect and investigate computer systems.

Figure 5: Qualitative comparison between different alignment methods on PKU-SafeRLHF.

 MoTE in single-step inference when trained on AlignCoT (Row 10). MoTE outperforms the pre- vious *state-of-the-art* methods on both datasets, showcasing its superiority. Furthermore, MoTE's multi-step inference (Row 11) enhances its help- fulness and harmlessness scores, benefiting from the incremental improvement throughout the steps. Qualitative examples can be found in Fig. [5.](#page-6-2)

### <span id="page-6-0"></span>**445** 4.3 Ablation Study and Analysis

**446** In this section, we ablate MoTE from the perspec-**447** tive of data and architecture. We conduct all exper-**448** iments here on Alpaca-7B [\(Taori et al.,](#page-9-17) [2023\)](#page-9-17).

 The answer of AlignCoT matches human su- pervision. We evaluate training data from two sources: PKU-SafeRLHF dataset with human-**generated answers and**  $D_{\text{cot}}^{\text{train}}$  **using AlignCoT-** generated answers, differing only in the answer **453** source. By employing GPT-4 to assess answer 454 safety, we find AlignCoT's responses closely match **455** the human-generated gold standards, as shown by **456** the *Train Rate* in Fig. [6\(a\),](#page-7-0) indicating comparable **457** safety levels. Further, a direct GPT-4 comparison **458** between both answer sets reveals AlignCoT's re- **459** sponses win or tie 56.68% of the time against PKU- **460** SafeRLHF. This evidence supports AlignCoT's ca- **461** pability to produce answers that rival human-level **462** supervision in safety and quality. **463** 

Self generated data is more tuning-friendly. **464** Despite the similar quality between the two **465** datasets, their tuning effectiveness differs. Tun- **466** ing with AlignCoT-generated data enhances align- **467** ment capabilities more than using the original PKU- **468** SafeRLHF dataset, as demonstrated in Fig. [6\(a\).](#page-7-0) 469

<span id="page-7-2"></span>

Architecture	Activated Expert	Help	Harm	Harm-Help
LoRA		4.91	84.55	5.21
$LoRA(rank*2)$		4.98	84.67	5.49
Vanilla MoE	Top 2	4.97	85.59	5.31
MoTE	$E_{Ans}, E_{share}$	5.06	87.13	5.51
- Step Skipping	$E_{Ans}, E_{share}$	4.98	86.17	5.40
- Shared Expert	$E_{Ans}$	5.03	81.79	5.18
- Shared Expert & Step Skipping	$E_{Ans}$	4.98	78.33	4.97

Table 2: Ablative analysis on architecture. MoTE excels beyond both non-MoE and vanilla MoE frameworks. The Shared Expert is key to enhancing collaboration between experts, while Step Skipping further boosts alignment.

<span id="page-7-0"></span>

data sources.

<span id="page-7-1"></span>(b) Comparison of loss curves.

Figure 6: Data sources Comparison. *(a)* The quality of PKU-SafeRLHF and AlignCoT training sets is comparable, as indicated by the *Train Rate*. However, AlignCoT tuning results surpass those of PKU-SafeRLHF, with additional analysis and guidance data boosting the model's performance further. *(b)*: The tuning loss for AlignCoT is significantly lower than for PKU-SafeRLHF, demonstrating the tuning-friendly nature of self-generated data.

 Furthermore, incorporating analysis and guidance data into tuning further boosts model performance. We propose that answers generated by AlignCoT are inherently more suited for tuning than those from humans or other models, as they are generated by the model itself. This hypothesis is supported by the tuning loss comparison in Fig. [6\(b\),](#page-7-1) where AlignCoT-generated answers show a notable reduc- tion in loss, confirming their tuning efficiency. This insight encourages us to further refine the model's self-alignment through the use of additional analy-sis and guidance data.

 Ablation on architecture. After ablation on data that middle steps enhance self-alignment, here we dissect the components of the MoTE architecture in Table. [2.](#page-7-2) We first compare MoTE with non-MoE and vanilla MoE structures. Vanilla MoE contains a linear gate that decides which expert each to- [k](#page-9-19)en is processed by, following the design of [\(Shen](#page-9-19) [et al.,](#page-9-19) [2023a\)](#page-9-19). Given that MoTE concurrently en-490 gages two experts,  $E_{Ans}$  and  $E_{share}$ , we ensure a

<span id="page-7-3"></span>

			Flops Time   Help Harm Harm-Help
$\begin{array}{ccc} D_{extra\_1} \cup D_{extra\_2} & 1 \text{x} & 1 \text{x} & 5.12 & 87.25 \\ \textbf{MoTE} & 0.35 \text{x} & 0.67 \text{x} & 5.06 & 87.13 \\ \end{array}$			5.69 5.51

Table 3: Training Efficiency of MoTE.

fair comparison by doubling the LoRA rank in non- **491** MoE configurations and employing top-2 experts in **492** vanilla MoE setups. MoTE consistently surpasses **493** these configurations. Additionally, we examine the **494** impact of Step Skipping and the Shared Expert fea- **495** tures. Without the shared expert, MoTE activates **496** only one expert, underscoring the shared expert's **497** crucial role in fostering synergy among experts and **498** enhancing overall alignment. Step Skipping further **499** augments this alignment efficiency. **500**

Training efficiency. Table [3](#page-7-3) illustrates the effi- **501** ciency of our devised MoTE approach. By adopt- **502** ing MoTE, we streamline the cumbersome process **503** of individually training each expert. Instead, we **504** train them concurrently, utilizing and adjusting the **505** attention map from the preceding AlignCoT step. **506** MoTE allows us to maintain performance levels  $507$ akin to naively expanding datasets, while signifi- **508** cantly reducing Flops and time by 0.35x and 0.67x. **509**

# **5 Conclusion** 510

Safety alignment is essential for LLMs. Existing **511** approaches like SFT and RLHF rely extensively on **512** human annotation, whereas self-alignment strate- **513** gies depend on LLMs' emergent abilities. Our **514** work introduces AlignCoT, integrating Chain-of- **515** Thought (CoT) for safety alignment, empowering **516** less advanced models to produce high-quality, safe **517** responses. We then present MoTE, a framework **518** utilizing a Mixture of Experts, with each expert **519** handling a specific step. Our designs are proven **520** effective and efficient, marking a significant ad- **521** vancement over current methods. **522** 

# **<sup>523</sup>** 6 Limitations

 Although MoTE shows promising results and im- provements in safety tasks, it is important to ac- knowledge its limitations. The performance of MoTE heavily depends on the quality and diversity of the training dataset's questions. In situations where the dataset is limited or biased, the model's ability to generalize to different scenarios. Addi- tionally, while MoTE has been applied to safety tasks, its applicability to other domains such as Math remains an area for future exploration.

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#### <span id="page-11-0"></span>A Experiment details

 Dataset and base model. We utilize PKU- SafeRLHF [\(Dai et al.,](#page-8-15) [2023\)](#page-8-15) for both training and evaluation on Alpaca-7B [\(Taori et al.,](#page-9-17) [2023\)](#page-9-17), a dataset manually created and assessed to include Question-Answer pairs across 14 harm-related cat- egories, (*e.g*., *animal abuse, self-harm, and privacy violation*). Following [\(Chen et al.,](#page-8-4) [2023a\)](#page-8-4), we re- fine the training set and maintain 10260 unique in- structions with good answers provided by humans, and a test set with 1,523 red-teaming instructions for evaluating harmlessness. To balance harmless- ness with helpfulness, we integrate an additional 52k helpful instructions from Alpaca [\(Taori et al.,](#page-9-17) [2023\)](#page-9-17) into our training and assess helpfulness us- ing AlpacaFarm's evaluation set of 805 instruc- tions [\(Dubois et al.,](#page-8-18) [2023\)](#page-8-18). We further utilize HH- RLHF [\(Bai et al.,](#page-8-16) [2022a\)](#page-8-16), a harder multi-round conversation dataset for both training and eval- uation. We employ Wizard-Vicuna-Uncensored 7B [\(TheBloke,](#page-9-18) [2024\)](#page-9-18) as base model and follow the experiment setup of [\(Pang et al.,](#page-9-8) [2024a\)](#page-9-8) to use 6K helpful and harmful training data for SFT. All models showcased in column PKU-SafeRLHF in Table [1](#page-6-1) are based on Alpaca-7B and in column HH-RLHF are on Wizard-Vicuna-Uncensored 7B.

**Model and baselines.** MoTE is by default ap- plied in all linear layers of the transformer with rank 16 and we always add an entra LoRA expert 778 only tuned with datasets  $D_{ans} = \{(x, y_{cot})\}$ . Ini- tially, we benchmark AlignCoT against inference- based models, choosing zero-shot CoT [\(Wei et al.,](#page-9-20) [2022\)](#page-9-20) and Critique-Revise [\(Bai et al.,](#page-8-3) [2022b\)](#page-8-3) as baselines due to their enhancement of model per- formance through multi-step inferences. Zero- shot CoT utilizes a template to encourage step- wise thinking in the model, while Critique-Revise prompts the model to critique and refine its ini- tial output into a safer and more helpful response. Further, we compare MoTE against fine-tuning ap- proaches, selecting SFT, Critique-Revise [\(Bai et al.,](#page-8-3) [2022b\)](#page-8-3), Mistake Analysis [\(Chen et al.,](#page-8-4) [2023a\)](#page-8-4), [R](#page-9-8)LCD [\(Yang et al.,](#page-9-21) [2023\)](#page-9-21) and MATRIX [\(Pang](#page-9-8) [et al.,](#page-9-8) [2024a\)](#page-9-8).

# B Additional Experiments

 Other formulations of AlignCoT. Here we ex- amine alternative formulations of AlignCoT. As indicated by Rows 1, 2, 3, and 5 in the table be-low, performing analysis and guidance separately

	Help		Harm Harm-Help
Question -> Answer	4.74	52.99	3.71
Question $\rightarrow$ Analysis $\rightarrow$ Answer	4.87	65.83	4.48
Question -> Guidance -> Answer	4.53	63.16	4.05
Question, Analysis, Guidance -> Answer	5.62	52.13	3.88
Question -> Analysis -> Guidance -> Answer	5.19	83.26	5.35
Analysis + Guidance + Response + Critique-Revise	5.06	83.26	5.35

Table 4: Different formulations of AlignCoT.

can yield improved performance compared to their **798** absence, yet falls short of the combined approach. **799** Row 4 (compared with Row 5) illustrates conduct- **800** ing AlignCoT within a single step, resulting in **801** weaker performance, potentially due to limited **802** instruction-following capability. Finally, integrat- **803** ing AlignCoT with Critique-Revise demonstrates a **804** marginal enhancement in results. **805**

# <span id="page-12-0"></span>C Qualitative Examples. **<sup>806</sup>**

Here we provide qualitative examples for AlignCoT (Multi-step Inference) on Safe-RLHF and HH-RLHF, **807** and more Single-step Inference of MoTE results. 808



Table 5: Qualitative comparison between the original unsafe answer and AlignCoT on Safe-RLHF.





 $\overline{a}$ 



Table 6: Qualitative comparison between the original unsafe answer and AlignCoT on HH-RLHF.



Table 7: Single-step Inference results of MoTE on PKU-SafeRLHF.



Table 8: Single-step Inference results of MoTE on HH-RLHF.