# In-Context Learning behaves as a greedy layer-wise gradient descent algorithm

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### Abstract



# 13 1 Introduction

 In-context learning presents a whole new world of possibilities compared to traditional gradient-based fine-tuning. It allows us to update large language models (LLMs) without the increasingly costly training process. The regular fine-tuning process is often prohibitively expensive, with state-of-the-art models such as Llama-3 surpassing 70 billion parameters. ICL potentially democratizes the updating of large language models, allowing users other than large companies with copious resources to tune their own models. ICL is also highly interpretable when including demonstration examples in the prompts. Demonstration examples typically take the form of natural language prompts which are readily understandable by humans.

 Although In-context learning exhibits many promising qualities, how it works is still poorly un- derstood. In the past few years, there have been many attempts, both theoretical and empirical, to understand why exactly ICL occurs and how it ties into the larger transformer architecture. However, the conclusions are still very limited and many questions have yet to be answered.

<sup>26</sup> This study proposes that, for a single layer, ICL in linearized transformers is equivalent to conducting <sup>27</sup> gradient descent with a specific training set determined by the input prompt. For multiple layers, <sup>28</sup> ICL constitutes a greedy layer-wise gradient descent update. We do so by highlighting the dual

29 relationship between the linear self-attention mechanism and gradient descent of linear models in  $l_2$ 

<sup>30</sup> regression. This results in the following key contributions:

- Demonstrate the equivalence between in-context prompts and a meta-gradient descent update upon the query of the linear self-attention mechanism to provide intuition on the ICL mechanism.
- Observe how in-context learning on a multilayer transformer model constitutes a form of the greedy layer-wise training algorithm.
- Analyse how ICL can be viewed through the prism of greedy layer-wise training algo- rithms. The properties of greedy layer-wise training algorithms help elucidate many current observations regarding ICL.
- Extend our findings in a theoretical capacity to the autoregressive transformers including a causal mask.

 Most established work in the field is limited to the regression setting. Furthermore, there are strong assumptions placed upon the Key and Value matrices. In our work, we make no assumptions and expand the discussion to include all linearized transformers. We hope that our comparison of ICL to a greedy layer-wise learning algorithm can help us better understand the nature of ICL and hopefully apply it more effectively in the future.

# 2 Preliminaries

 In this paper, we focus on transformers consisting of attention modules and feed-forward networks. More specifically, we analyze the attention module of the transformer layer. This is because other components of transformers such as Layer-normalisations and feed-forward neural networks are typically token-wise operators. The input of each layer consists of a sequence of mathematical tokens  $X = [p_n, ..., p_1]^T$ . We assume each token has dimensionality  $d_{in}$  such that  $X \in \mathbb{R}^{N \times d_{in}}$ .

#### 2.1 The attention mechanism

53 Regarding attention, we discard the scaling factor  $\sqrt{d_k}$  and approximate the softmax by a kernel.

 This results in a linearized attention function. Studies have shown that models built on linearized attention can still provide reasonable results [\[Katharopoulos et al., 2020,](#page-5-0) [Lu et al., 2021\]](#page-5-1) and have an inherent ICL ability.

- 57 **Definition:** (Linearized attention) The input consists of the query  $(Q)$ , key  $(K)$  and value  $(V)$
- 58 matrices which have dimensions  $d_k$ ,  $d_k$  and  $d_v$  respectively. With kernel representation function  $\phi(\cdot)$ , the linear attention is computed as:

<span id="page-1-0"></span>
$$
LinAttn(V, \phi(K), \phi(Q)) = V\phi(K)^T\phi(Q).
$$
\n(1)

 We explicitly focus on single-headed attention. This is due to the simplicity of notation. All results can be extended to multi-headed attention which is used in most real-world settings.

- 62 **Definition: (Single-headed attention layer)** Given input data  $X \in \mathbb{R}^{d_{in} \times N}$  a single attention layer 63 is characterized by trainable matrices  $W_Q$ ,  $W_K$ ,  $W_V$  which are in  $\mathbb{R}^{d_K \times d_{in}}$ ,  $\mathbb{R}^{d_K \times d_{in}}$  and  $\mathbb{R}^{d_V \times d_{in}}$
- respectively. The Single-headed attention layer takes the form:

$$
Attn(W_VX, W_KX, W_QX). \t\t(2)
$$

In our case, we will be looking at:

$$
LinAttn(W_VX, \phi(W_KX), \phi(W_QX)).
$$
\n(3)

#### 2.2 In-context learning

 In this paper, we choose to consider the most general case of ICL. The ICL prompt is treated as a 68 sequence of tokens without added requirements on the structure. We have an initial prompt  $X =$ 69  $[p_N, ..., p_1]$  of length N and a Demonstration ICL prompt  $X' = [p'_M, ..., p'_1]$  of length M. The final zo input concatenates X' and X to form a sequence  $[X'; X] = [p'_M, ..., p'_1, p_N, ..., p_1] \in \mathbb{R}^{d_{in} \times (M+N)}$ .

#### $71 \quad 2.3 \quad$  Dual form between linear attention and gradient descent on a linear function

<sup>72</sup> This study seeks to take advantage of the duality between the linear attention operator and gradient <sup>73</sup> descent on a linear function. Based on the work of [Irie et al.](#page-5-2) [\[2022\]](#page-5-2):

<span id="page-2-2"></span>74 Proposition 2.1 ( Dual form of a linear function trained by gradient descent). Let  $f(x) = Wx$ 

*be a linear function*  $f : \mathbb{R}^{d_{in}} \to \mathbb{R}^{d_{out}}$  with parameters  $W \in \mathbb{R}^{d_{out} \times d_{in}}$ . Given gradient descent

 $\tau$ <sup>6</sup> *with*  $l_2$  *loss,*  $T$  *training samples*  $\{x_i, y_i\}_{i=1}^T$  *and learning rate*  $η$ *, we have the identity:* 

$$
W_1x = (W_0 - \eta \nabla \frac{1}{T} \sum_{i=1}^T l_2(f_W(x_i), y_i))|_{W=W_0} x = W_0x + LinAttn(\frac{\eta}{T}E, X, x).
$$
 (4)

77 X is the matrix of inputs  $X = [x_1; ...; x_T]$  and  $E = Y - W_0 X$  is the error matrix where  $Y =$ 78  $[y_1, ..., y_T]$ .

#### $79\quad; 3$  Viewing in-context learning with linear attention as a gradient descent step

<sup>80</sup> First, we examine a single-layer self-attention mechanism. We consider how the ICL prompt affects

 $\mathbf{a}_1$  each singular query token  $\mathbf{q} = W_Q \mathbf{x}$  where  $\mathbf{x} \in \mathbb{R}^{in}$ . Given ICL prompt  $X' = [p'_M, ..., p'_1]$  and initial

82 prompt  $X = [p_N, ..., p_1]$ , the attention result of the linear attention head can be expressed as:

$$
\mathcal{F}([X';X],\mathbf{q}) = LinAttn(W_V[X';X],\phi(W_K[X';X]),\mathbf{q})
$$
  
= LinAttn(W\_V[X],\phi(W\_K[X]),\mathbf{q}) + LinAttn(W\_V[X'],\phi(W\_K[X'],\phi(W\_K[X']),\mathbf{q})  
=  $\mathcal{F}([X],\mathbf{q}) + LinAttn(W_V[X'],\phi(W_K[X')),\mathbf{q})$ 

83 where  $\mathcal{F}([X], \mathbf{q}) = LinAttn(W_V[X], \phi(W_K[X]), \mathbf{q})$ . N.B.  $\mathcal F$  can take inputs  $[X]$  of differing

84 dimensions. There is a clear similarity between the form of equation (4) and equation (5). This leads <sup>85</sup> to the main theorem:

<span id="page-2-1"></span>86 Theorem 3.[1](#page-2-0) (Dual form between in-context learning and gradient descent). <sup>1</sup> For an initial self-87 *attention mechanism with matrices*  $W_V$ ,  $W_K$ , and prompt  $X = [p_N, ..., p_1]$ , we have the operator 88  $\mathcal{F}_0([X], \boldsymbol{q})$ . The following systems are equivalent (i.e.  $S_1 = S_2$  for all **q**):

$$
S_1 = \mathcal{F}_0([X';X], \boldsymbol{q}) \tag{6}
$$

<sup>89</sup> *and*

$$
S_2 = \mathcal{F}_1([X], \boldsymbol{q}),\tag{7}
$$

 $\mathfrak{so}\quad$  where  $\mathcal{F}_1([X],.)$  is the linear function  $\mathcal{F}_0([X],.)=W_{[X]}(.):=W_V[X](\phi(W_K[X]))^T(.)$  after one  $s_1$  *step of gradient descent with learning rate*  $\eta$  *and training set*  $\{x_i, y_i\}_{i=1}^M$ *. For every*  $i \in \{1, ..., M\}$ *,* 92  $x_i = \phi(W_K p'_i)$  and  $y_i = \frac{M}{\eta} W_V p'_i + \mathcal{F}_0([X], \phi(W_K p'_i)).$ 

93 This allows us to arrive at a few interesting observations:

 1. Theorem [3.1](#page-2-1) demonstrates that in-context learning forms a type of meta-optimizer on the query resembling gradient descent with very specific training data for linearized transformers. Unlike past conclusions, our statement isn't constrained to specific regression settings and 97 values for  $W_Q, W_K$  and  $W_V$ .

98 2. If one takes  $y_i = \mathcal{F}_0([X], W_k p'_i)$  and ignores the other half, the loss is 0 which means that <sup>99</sup> the gradient descent has no effect at all. We can consider this as a baseline. The significant 100 part is:  $\frac{M}{\eta} W_v p'_i$ .

101 3.  $W_V p_i'$  is intuitively the "value" which we place upon a token  $W_Q p_i'$ . Here we are placing 102 emphasis of  $W_K p_i'$  instead when applied to the function based on  $[p_N, ..., p_1]$ 

#### <sup>103</sup> 4 Extension to multiple layers

<sup>104</sup> This section extends Theorem [3.1](#page-2-1) to a more general setting beyond the single linearized attention 105 layer. Consider a more realistic model architecture with L layers stacked upon each other:  $f(x) =$ 

<span id="page-2-0"></span><sup>&</sup>lt;sup>1</sup>During writing, we found concurrent work with a similar result by [Ren and Liu](#page-5-3) [\[2023\]](#page-5-3)

106  $(T_L + I) \circ (T_{L-1} + I) \circ ... \circ (T_1 + I)(x)$  where for each  $i \in \{1, ..., L\}$ ,  $T_i$  is either an FFN layer 107 with a residual connection or a linear self-attention layer  $T_i = \dot{L} S A_i(x)$  with corresponding weight 108 matrices  $W_{K_i}$ ,  $W_{Q_i}$ ,  $W_{V_i}$ , and I is the identity function to capture the residual connection. Given a 109 prompt  $X = [p_n, ..., p_1]$ , we define

$$
LSA_i([p_n,...,p_1]) = W_{base,i}([p_n,...,p_1])W_{Q_i}[p_n,...,p_1]
$$
\n(8)

 $W_{base,i}(X) = W_{Vi} X \phi(W_{Ki} X)^T$ (9)

#### <span id="page-3-0"></span>Algorithm 1: ICL imitation algorithm

110

1: input:  $f_1$  and  $[p'_m, ..., p'_1, p_n, ..., p_1]$ 2: for  $i \in \{1, ..., L\}$ **IF**  $T_i$  is a FFN with residual connection, return  $[p'_m, ..., p'_1, p_n, ..., p_1] = (T_i + I)([p'_m, ..., p'_1, p_n, ..., p_1])$ 

ELSE  $T_i = LSA_i$ (a) construct matrix  $W_0 = W_{base,i}([p_n, ..., p_1])$ (b) Update the linear functional  $f(x) = W_0 x$  with a single step of gradient descent with learning rate m and training set  $\{\phi()$ ,  $W_{V_i}p'_j + W_0\phi(W_{K_i}p'_j)\}\substack{m\\j=1}$  such that the updated weights are  $W_1$ (c)  $[p'_m, ..., p'_1, p_n, ..., p_1] = W_1 \phi(W_{Q_i}[p'_m, ..., p'_1, p_n, ..., p_1]) + [p'_m, ..., p'_1, p_n, ..., p_1]$ 

111 **Theorem 4.1 (Dual form of the transformer algorithm).** For a model  $f_1$  described above and a 112 prompt  $[p'_m, ..., p'_1, p_n, ..., p_1]$ , the ICL imitation algorithm on  $f_1$  and  $[p'_m, ..., p'_1, p_n, ..., p_1]$  *(Algo-*113 *rithm [1\)](#page-3-0)* produces the same output as  $f_1([p'_m, ..., p'_1, p_n, ..., p_1])$ 

<sup>114</sup> Proof. The proof of equivalence is trivial through repeated applications of Theorem [3.1.](#page-2-1)

 There are a few key features of algorithm 1. First of all, algorithm 1 is a recursive algorithm that 116 updates the layers one after another. When applying the model, the  $i$ -th layer is updated and the 117 newly updated weights are used to generate the input which will be used to update the  $i + 1$ -st layer. A second key feature of algorithm 1 is that it is a form of unsupervised learning. This may seem contradictory since we are conducting gradient descent descent on each layer. However, a key observation is that the labels are actually generated from the inputs themselves.

#### $121 \quad 5$  Connection to the greedy-layer-wise algorithms

 Upon closer inspection, these features of Algorithm [1](#page-3-0) take the form of a greedy layer-wise un- supervised pretraining algorithm proposed by [Bengio et al.](#page-5-4) [\[2006\]](#page-5-4). In that paper, they propose a greedy layer-wise unsupervised training algorithm to train both deep belief networks (DBN) and auto-encoders in an unsupervised regime. Their experiments show that the general principles of the greedy layer-wise training algorithms can be extended past DBNs and applied to other unsupervised GLT algorithms. We can consider the inclusion of the ICL prompts in [1](#page-3-0) as a single pass of a greedy layer-wise training algorithm trained on unsupervised data (The transformed in-context prompts). We argue that there is evidence to show that those general principles may apply to ICL and transformers <sup>130</sup> as well.

 First of all, greedy layer-wise training (GLT) is observed to achieve very quick convergence to a local solution [\[Hinton et al., 2006\]](#page-5-5). This may explain why only a single step is required within the ICL case. There has been research regarding ICL which has indicated that one step of gradient descent is provably the optimal ICL learner for a single layer of linearized self attention[\[Mahankali et al., 2023\]](#page-5-6). This would seem to demonstrate how ICL has displayed such effectiveness despite only resembling a single step of a greedy layer-wise training algorithm.

 Secondly, the work by [\[Bengio et al., 2006\]](#page-5-4) shows that greedy layer-wise training algorithms help learn internal representations that represent higher-level abstractions. Several empirical works studying ICL have shown that, regarding ICL demonstrations, the model learns the format that we are studying rather than the exact detailed labels. They suggest that the model is learning higher-level abstractions rather than specific values. This would align with what we expect from GLT algorithms.  This observation perfectly ties into another property of GLT algorithms. Work by [\[Bengio et al.,](#page-5-4) [2006\]](#page-5-4) states that by learning high-level internal representations, GLT algorithms are best served for quickly initializing the parameters of a model before other fine-tuning steps. This could possibly motivate future fine-tuning attempts that have a fixed ICL prompt included to provide initialization. [W](#page-5-8)e find that such attempts do already exist, in the form of instruction tuning[\[Zhang et al., 2024,](#page-5-7) [Wei](#page-5-8) [et al., 2022\]](#page-5-8). Instruction tuning involves fine-tuning LLMs with datasets with form (*INSTRUCTION, OUTPUT*). The model learns to adapt to new tasks which can also be given instructions. In this case, we consider the (*INSTRUCTION*) as a form of context itself. This suggests the need for a unified framework for ICL, regular fine-tuning, and instruction tuning altogether. Perhaps they truly are not substitutes for one another but rather complements.

#### <sup>152</sup> 5.1 Instruction learning with a single instruction

 From the comparison between regular ICL and instruction-tuning, we propose a specific variant of instruction-tuning that combines ICL and fine-tuning. In this regime, given a specific purpose, 155 we first determine the appropriate ICL prompt  $X'$  for future prompts X. However, in this case we consider that ICL may not be sufficient, so we treat it purely as a form of projection or initialization for fine-tuning.

158 Given fixed ICL prompt X', we want the fine-tuning set to have form  $\{[X', X_i]\}_{i=1}^N$ . All inputs in the training set will carry the form  $[X'; X_i]$ . This incorporates the initialization we obtain from ICL into <sup>160</sup> the fine-tuning process and should allow the fine-tuning process to be faster and less costly. Future 161 inputs should then take the form  $[X', X]$  as well so the initialization is included permanently. We <sup>162</sup> expect this to be an effective way to combine ICL and fine-tuning for the best of both worlds, both <sup>163</sup> increasing the effectiveness of ICL and reducing the training cost of existing fine-tuning methods.

#### <sup>164</sup> 6 Extension to the autoregressive case

<sup>165</sup> In previous sections, we limit our analysis to linearized attention without a causal mask. Similar <sup>166</sup> limitations are present in other works studying the relationship between gradient descent and ICL. In <sup>167</sup> this section, we attempt to extend it to the autoregressive setting. To do so we first write equation [1](#page-1-0) as

<sup>168</sup> follows:

$$
O_i = \sum_{j=1}^{N} sim(Q_i, K_j) V_j = \sum_{j=1}^{N} \phi(Q_i)^T \phi(K_j) V_j
$$
\n(10)

<sup>169</sup> This is drawn from the work by [\[Katharopoulos et al., 2020\]](#page-5-0) and is equivalent to the equation [1.](#page-1-0) To <sup>170</sup> construct the autoregressive form, we convert the equation to:

$$
O_i = \sum_{j=1}^i \phi(Q_i)\phi(K_j)V_j = \phi(Q_i)^T \sum_{j=1}^i \phi(K_j)V_j
$$
\n(11)

171 This means that for each token  $Q_i$ , there is a separate corresponding reference equation  $\mathcal{F}_0^{(i)}([X], \mathbf{q})$ . <sup>172</sup> Through the application of Theorem 4.1, we can arrive at the statement.

173 **Lemma 6.1** (lemma). *The inclusion of in-context prompt*  $X' = [p'_1, ..., p'_M]$  *is equivalent to updating* 174 *all reference functions*  $\mathcal{F}^{(i)}([X],.) = W^{(i)}_1[X](.)$  *with a single step of gradient descent with learning rate*  $\eta$  and training set  $\{x_i, y_i\}_{i=1}^M$ . For every  $i \in \{1, ..., M\}$ ,  $x_i = \phi(W_K p'_i)$  and  $y_i = \frac{M}{\eta} W_V p'_i +$ 

- 176  $\mathcal{F}^{(i)}_0([X], \phi(W_K p'_i))$
- 177 Note that in this case, the separate functions  $\mathcal{F}_0^{(i)}([X], \mathbf{q})$  are not independent but all related to one
- <sup>178</sup> another. Hence this result is largely theoretical in nature, but does extend our intuitive results from <sup>179</sup> previous sections to the autoregressive setting.

## 7 Conclusion

 In this work, we demonstrate that, for all linearized attention layers, ICL is equivalent to a single step of gradient descent with a specific training set. This is shown for transformers both with and without causal masking. We further extend this statement to multi-layer transformers, showing that they are similar to past greedy layer-wise training algorithms. This explains to an extent some existing characteristics of ICL as well as opening a potential avenue for ICL to be studied in greater theoretical depth in the future. By taking into account past tendencies of greedy layer-wise training algorithms, it could be possible to enhance current ICL methods further opening a whole new dimension of possibilities.

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# <sup>216</sup> 8 Appendix

#### <sup>217</sup> 8.1 Proof of Theorem [3.1](#page-2-1)

218 *Proof.* Assume such a set  $\{x_i, y_i\}$  and corresponding E and X exist such that the two systems are <sup>219</sup> equal. By Proposition [2.1](#page-2-2) and equation (6) we have:

$$
W[X',X]\mathbf{q}=W_X\mathbf{q}+LinAttn(\frac{\eta}{m}E,X,\mathbf{q})
$$

<sup>220</sup> This implies:

$$
W_{[X]}{\bf q}+LinAttn(W_VX',W_KX',{\bf q}=LinAttn(\frac{\eta}{m}E,X,{\bf q})
$$

221 To enforce such an equality we need  $W_K X' = X$ . This shows that for all i:

$$
x_i = W_K p'_i
$$

222 Hence substituting in  $x_i$  we have:

$$
W_V X' = \frac{\eta}{m} E = \frac{\eta}{m} (W_1 X) W_K X' - Y)
$$

<sup>223</sup> This implies:

$$
Y = W_{[X]}W_K X' - \frac{m}{\eta} W_V X'
$$
  

$$
y_i = W_{[X]}W_K p'_i + \frac{m}{\eta} W_V p'_i
$$

224

