

---

# Chinese Inertial GAN for Writing Signal Generation and Recognition

---

Anonymous Author(s)

Affiliation

Address

email

## Abstract

Disabled people constitute a significant part of the global population, deserving of inclusive consideration and empathetic support. However, the current human-computer interaction based on keyboards may not meet the requirements of disabled people. The small size, ease of wearing, and low cost of inertial sensors make inertial sensor-based writing recognition a promising human-computer interaction option for disabled people. However, accurate recognition relies on massive inertial signal samples, which are hard to collect for the Chinese context due to the vast number of characters. Therefore, we design a Chinese inertial generative adversarial network (CI-GAN) containing Chinese glyph encoding (CGE), forced optimal transport (FOT), and semantic relevance alignment (SRA) to acquire unlimited high-quality training samples. Unlike existing vectorization focusing on the meaning of Chinese characters, CGE represents the shape and stroke features, providing glyph guidance for GAN to generate writing signals. FOT constrains feature consistency between generated and real signals through the designed forced feature matching mechanism, meanwhile addressing GANs' mode collapse and mixing issues by introducing Wasserstein distance. SRA captures the semantic relevance between various Chinese glyphs and injects this information into the GAN to establish batch-level constraints and set higher standards of generated signal quality. By utilizing the massive training samples provided by CI-GAN, the performance of six widely used classifiers is improved from 6.7% to 98.4%, indicating that CI-GAN constructs a flexible and efficient data platform for Chinese inertial writing recognition. Furthermore, we release the first Chinese writing recognition dataset based on inertial sensors in GitHub.

## 1 Introduction

One of the most significant obstacles for disabled individuals in their daily lives is the lack of efficient human-computer interaction (HCI) methods [1]. Traditional keyboard-based HCI systems often fail to meet the specific needs of disabled users, particularly those who are visually impaired or have lost their fingers, which underscores the urgent need for developing technologies that cater to the unique requirements of disabled individuals [2]. Providing tailored HCI solutions not only enhances their quality of life and independence but also facilitates their integration into society, enabling greater participation in education, employment, and social activities. Such technological advancements hold profound significance, creating a more inclusive and equitable society.

As efficient motion-sensing components, inertial sensors can play a crucial role in recognizing writing movements. Inertial sensors can measure the acceleration and angular velocity of moving objects, making it possible to convert written characters into digital text [3, 4, 5, 6]. Due to their small size, ease of integration, low power consumption, and low cost, inertial sensors are widely used in electronic devices such as smartphones, smartwatches, and fitness bands [7, 8, 9, 10], making them particularly

38 suitable for disabled users. Inertial sensors can be integrated into wearable devices, providing a more  
39 accessible and user-friendly means for disabled individuals to interact with computers and other digital  
40 devices. By capturing the subtle movements of a user’s hand or other body parts, inertial sensors can  
41 translate these motions into written text, enabling effective communication and interaction without  
42 the need for a traditional keyboard. In addition, unlike optical or acoustic sensors, inertial sensors are  
43 highly resistant to external factors such as lighting conditions, physical obstructions, or environmental  
44 noise, which showcases their unique robustness in motion capture [11, 12, 13, 14, 15]. Consequently,  
45 inertial sensors provide a medium for Chinese character writing recognition that aligns with natural  
46 writing habits and can be seamlessly integrated into the writing process. With the widespread adoption  
47 of smart devices, the technology of Chinese character writing recognition based on inertial sensors  
48 may redefine the Chinese character input in the digital age, offering disabled people a comfortable  
49 human-computer interaction methods.

50 However, the major challenge in achieving accurate Chinese writing recognition using inertial sensors  
51 is obtaining large-scale, diverse inertial writing data samples. For any recognition model aimed  
52 at accurately analyzing the complex strokes and structures of Chinese characters, it is crucial to  
53 train the model with extensive, diverse writing samples [16]. Considering that the collection and  
54 processing of Chinese writing samples are laborious and require high data quality and diversity, this  
55 task becomes exceedingly challenging and increasingly difficult as the number of characters increases.  
56 Therefore, generating realistic Chinese writing signals based on inertial sensors has become a central  
57 technological challenge in recognizing Chinese writing.

58 To acquire high-quality, diverse samples of inertial Chinese writing, we applied GAN for IMU writing  
59 signal generation for the first time and proposed CI-GAN, which can generate unlimited inertial writing  
60 signals for an input Chinese character, thereby providing rich training samples for Chinese writing  
61 recognition classifiers. CI-GAN provides a more intuitive and natural human-computer interaction  
62 method for the Chinese context and advances the application of smart devices with Chinese input.  
63 The main contributions of this paper are summarized as follows.

- 64 • Considering traditional Chinese character embedding methods that only focus on the meaning  
65 of characters, we propose a Chinese glyph encoding (CGE), which represents the shape  
66 and structure of Chinese characters. CGE not only injects glyph and writing semantics into  
67 the generation of inertial signals but also provides new tools for studying the evolution and  
68 development of hieroglyphs.
- 69 • We propose a forced optimal transport (FOT) loss for GAN, which not only avoids mode  
70 collapse and mode mixing during signal generation but also ensures feature consistency be-  
71 tween the generated and real signals through a designed forced feature matching mechanism,  
72 thereby enhancing the authenticity of the generated signals.
- 73 • To inject batch-level character semantic correlations into GAN and establish macro con-  
74 straints, we propose a semantic relevance alignment (SRA), which aligns the relevance  
75 between generated signals and corresponding Chinese glyphs, thereby ensuring that the  
76 motion characteristics of the generated signal conform to the Chinese character structure.
- 77 • Utilizing the training samples provided by CI-GAN, we increase the Chinese writing recog-  
78 nition performance of six widely used classifiers from 6.7% to 98.4%. Furthermore, we  
79 provide the application scenarios and strategies of 6 classifiers in writing recognition ac-  
80 cording to their performance metrics. For the sake of sharing, we release the first Chinese  
81 writing recognition dataset based on inertial sensors in GitHub.

## 82 2 Related Work

83 The technology for recognizing Chinese handwriting movements has the potential to bridge the gap  
84 between traditional writing and digital input, providing disabled individuals with a natural way of  
85 writing and greatly enhancing their ability to participate in digital communication, education, and  
86 employment. It also offers a new human-computer interaction avenue for normal people. Hence,  
87 Chinese handwriting movement recognition has garnered significant attention in recent years, leading  
88 to numerous related research achievements. Ren et al. utilized the Leap Motion device to propose  
89 an RNN-based method for recognizing Chinese characters written in the air [17]. The Leap Motion  
90 sensor, consisting of two infrared emitters and two cameras, can accurately capture the motion of  
91 hands in three-dimensional (3D) space [18]. However, the Leap Motion device is sensitive to lighting

conditions, and either too strong or too weak light can interfere with the transmission and reception of infrared rays, affecting the recognition effect [19]. Additionally, the detection space of the Leap Motion device is an inverted quadrangular pyramid, limiting its field of view. Movements outside this range cannot be captured. Most importantly, the Leap Motion device is expensive and requires a connection to a computer or VR headset to function, severely limiting its application prospects [20].

As wireless networks become more prevalent, Wi-Fi signals are gradually being applied to motion capture [21, 22]. Since Wi-Fi signals can penetrate objects and are unaffected by lighting conditions, they have a broader application scope than optical motion capture systems [23, 24]. Guo et al. used the channel state information (CSI), extracted from Wi-Fi signals reflected by hand movements, to recognize 26 air-written English letters [25]. However, while Wi-Fi signals do not have visual range limitations and can penetrate obstacles, they are easily disturbed by other signals on the same unlicensed band, severely affecting system performance. Moreover, the sampling frequency and resolution of Wi-Fi signals are very limited, making it difficult to capture detailed information during the writing process and, thus, hard to recognize air-written Chinese characters accurately [26, 27].

Despite the advantages of low cost, wearability, and low power consumption offered by inertial sensors, there is currently a lack of large-scale, high-quality public datasets, causing few studies to use inertial sensors for 3D Chinese handwriting recognition [28, 29, 30, 31]. To collect data, Zhang et al. employed 12 volunteers, each of whom was asked to write the assigned Chinese characters on paper 30 times [32]. The inertial measurement unit (IMU) built into smartwatches was used to collect the motion signals of the volunteers while writing, ultimately achieving a recognition accuracy of 90.2% for 200 Chinese characters. However, this study aims to identify the signals of normal individuals writing on paper, which is not applicable to people with disabilities. Moreover, this method can only realize desktop-based 2D writing recognition, which reduces the comfort and flexibility of the writing process, inherently limiting the application scenarios of Chinese handwriting recognition. Additionally, this method cannot effectively recognize massive Chinese characters due to the physical and mental limitations of volunteers for data collection. Considering the vast number of Chinese characters, providing large-scale, high-quality writing signal samples for each character is nearly impossible, which has become the most significant bottleneck limiting the development of Chinese handwriting recognition technology based on inertial sensors. Therefore, designing a model for generating Chinese handwriting signals provides researchers with an endless supply of signal samples and a flexible, convenient experimental data platform, accelerating the development and testing of new algorithms and supporting the research and application of Chinese handwriting recognition.

### 3 Method

To generate inertial writing signals for Chinese characters, we propose the Chinese inertial generative adversarial network (CI-GAN), as shown in Fig. 1. For an input Chinese character, its one-hot encoding is transformed into glyph encoding using our designed glyph encoding dictionary, which stores the glyph shapes and stroke features of different Chinese characters. Thus, the obtained Chinese glyph encoding contains rich writing features of the input character. This glyph encoding, along with a random noise vector, is fed into a GAN, generating the synthetic IMU signal for the character, where glyph encoding provides glyph and stroke features of the input character, while the random noise introduces randomness to the virtual signal generation, ensuring the diversity and variability of the generated signals. To ensure that the GAN learns the IMU signal patterns for each character, we designed a forced optimal transport (FOT) loss, which not only mitigates the issues of mode collapse and mode mixing typically observed in GAN frameworks but also forces the generated IMU signals to closely resemble the actual handwriting signals in terms of semantic features, fluctuation trends, and kinematic properties. Moreover, a semantic relevance alignment (SRA) is proposed to provide batch-level macro constraints for GAN, thereby keeping the correlation between generated signals consistent with the correlation between Chinese character glyphs. Equipped with CGE, FOT and SRA, CI-GAN can provide unlimited high-quality training samples for Chinese character writing recognition, thereby enhancing the accuracy and robustness of various classifiers.

#### 3.1 Chinese Glyph Encoding

In one-hot encoding, each Chinese character is represented by a high-dimensional sparse vector (where only one element is 1, and all others are 0), which results in all characters being equidistant in the vector space, thereby losing the abundant semantic information contained in the characters.

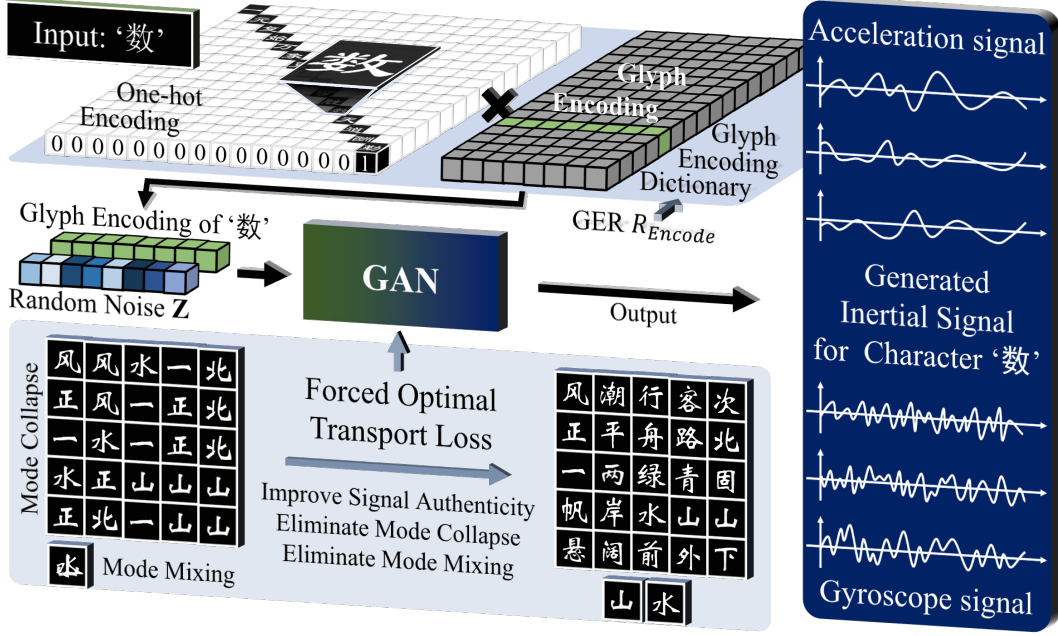


Figure 1: Flowchart of Chinese inertial generative adversarial network. The Chinese character ”数” is input into the model, and its one-hot encoding is converted into glyph encoding (green cubes), which is then input into GAN together with random noise (blue cubes of different colors).

Therefore, one-hot encoding fails to inject rich information into GAN. Although there are some commonly used Chinese character embeddings, these embeddings store meaning information of the characters, not glyph information (i.e., shape, structure and writing strokes). For example, the characters ”天” (sky) and ”夫” (husband) are quite similar in writing motions, but their meanings are significantly different. To this end, we propose a Chinese glyph encoding (CGE), which encodes Chinese characters based on their glyph shapes and writing actions.

Considering that the inertial sensor signals capture the writing motion of Chinese characters, the motion signal exactly contains glyph information, which encourages simultaneous learning signal generation and Chinese glyph encoding under the supervision of real signals. Therefore, we create a learnable weight matrix  $W$  after the one-hot input layer to capture the glyph information. When a Chinese character is input into CI-GAN in one-hot encoding, it first passes through this weight matrix. Since only one element in the one-hot encoding is 1, and the rest are 0, multiplying one-hot encoding by the weight matrix  $W$  means obtaining one row of the matrix  $W$ . Hence, each row of  $W$  can be seen as an encoding of a Chinese character, and this matrix can serve as a glyph encoding dictionary of Chinese characters. However, an unguided Chinese encoding dictionary often struggles to capture the differences in glyph shapes among different characters, assigning similar glyph encodings to characters with distinct glyphs. To address this, we propose a glyph encoding regularization (GER), which enhances the orthogonality of all character encoding vectors and increases their information entropy to store as many glyph features of the characters as possible, thereby avoiding triviality like one-hot encoding. Specifically, we use the  $\alpha$ -order Rényi entropy to measure the information content of the glyph encoding dictionary  $W$ , calculated as follows:

$$S_\alpha(W) = \frac{1}{1-\alpha} \log_2(\text{tr}(\tilde{G}^\alpha)), \text{ where } \tilde{G}_{ij} = \frac{1}{N} \frac{G_{ij}}{\sqrt{G_{ii} \cdot G_{jj}}}, G_{ij} = \langle W^{(i)}, W^{(j)} \rangle. \quad (1)$$

where,  $N$  represents the number of Chinese characters, which corresponds to the number of rows in the weight (encoding) matrix  $W$ .  $G$  is the Gram matrix of  $W$ , where  $G_{ij}$  equal to the inner product of the  $i$ -th and  $j$ -th rows of  $W$ , and  $\tilde{G}$  is the trace-normalized  $G$ , i.e.,  $\text{tr}(\tilde{G}) = 1$ . In similar problems,  $\alpha$  is generally set to 2 for optimal results.  $S_\alpha(W)$  measures the information content of the glyph encoding matrix  $W$ . A larger  $S_\alpha(W)$  indicates more information encoded in  $W$ , meaning the glyph encodings are more informative. Meanwhile, as  $S_\alpha(W)$  increases, all elements in the Gram matrix  $G$  are forced to decrease, indicating that different encoding vectors have stronger orthogonality. It

is evident that the improvement of  $S_\alpha(W)$  simultaneously enhances the information content and the orthogonality among the encodings. In light of this, the glyph encoding regularization  $R_{\text{encode}}$  is constructed as  $R_{\text{encode}} = \frac{1}{S_\alpha(W)}$ . As  $R_{\text{encode}}$  decreases during training,  $S_\alpha(W)$  gradually increases, meaning the glyph encoding dictionary stores more information while enhancing the orthogonality among all Chinese glyph encodings, effectively representing the differences in glyph shapes among all characters. Thus, this glyph encoding can inject sufficient glyph information into GAN, ensuring that the generated signals maintain consistency with the target character’s glyph.

### 3.2 Forced Optimal Transport

Ensuring the authenticity of virtual signals poses the greatest challenge when generating diverse signals, especially in following physical laws and simulating the potential dynamical characteristics of actual motions. To this end, we propose the forced feature matching (FFM), which ensures that the generated signal feature closely matches the real signal feature and the corresponding glyph encoding. Specifically, we use a pre-trained variational autoencoder to extract the real signal feature  $h_T$  and generated signal feature  $h_G$ . Then, the consistency of  $h_T$ ,  $h_G$ , and the corresponding glyph encoding  $e$  is constrained by  $\mathcal{L}_{FFM}$ .

$$\mathcal{L}_{FFM} = 1 - \frac{\langle h_G, h_T \rangle + \langle h_G, e \rangle + \langle e, h_T \rangle}{\|h_G\| \|h_T\| + \|h_G\| \|e\| + \|e\| \|h_T\|}. \quad (2)$$

Another critical challenge lies in the mode collapse and mode mixing issue inherent to GAN architectures. Mode collapse limits the diversity of generated signal samples, causing GAN to generate signals only for a few Chinese characters, regardless of the diversity of input. On the other hand, mode mixing problems cause the generated signal to contain blend characteristics of multiple modes, which is unrealistic and unrecognizable. To address these issues, we introduce the optimal transport to GAN, which utilizes the Wasserstein distance as a loss function. Traditional GANs use the Jensen-Shannon divergence as the loss metric, which becomes ineffective when the distributions of real and generated data have little overlap, leading to mode collapse. The Wasserstein distance provides a more effective gradient even when the distributions are disjoint or significantly different, thereby preventing mode collapse. Furthermore, unlike the Jensen-Shannon divergence, the Wasserstein distance exhibits insensitivity to the balance between the training of the generator and discriminator, thereby alleviating mode mixing (We provide a rigorous mathematical proof in Appendix C). Combining OT and FFM constraints, we can obtain the forced optimal transport loss  $\mathcal{L}_{FOT} = W(\mathbb{P}_T, \mathbb{P}_G) + \lambda \cdot \mathcal{L}_{FFM}$ , where  $W(\mathbb{P}_T, \mathbb{P}_G)$  is the optimal transport loss, representing the Wasserstein distance between the distributions of real and generated signals, enhancing the stability and diversity of the samples.  $\lambda$  is a weighting coefficient for the forced feature matching loss  $\mathcal{L}_{FFM}$ . As  $\mathcal{L}_{FFM}$  decreases during training, the generated signals increasingly approximate the characteristics of real signals.

### 3.3 Semantic Relevance Alignment

As motion records of Chinese writing, the semantic relationships between generated signals should align with the relationships between Chinese character glyphs. To ensure the generated inertial signals accurately reflect the character relationships between Chinese character glyphs, we propose semantic relevance alignment (SRA), which ensures consistency between the glyph encoding relationships and the signal feature relationships, thereby providing batch-level macro guidance for GANs and enhancing the quality of the generated signals. For each batch of input Chinese characters, we compute the pairwise cosine similarities of their Chinese glyph encodings to form an encoding similarity matrix  $M_e$ . Simultaneously, the pairwise cosine similarities of generated signal features (extracted by the pre-trained VAE) are computed to form a feature similarity matrix  $M_h$ . Then, the loss of semantic relevance alignment  $\mathcal{L}_{SRA} = \|M_h - M_e\|_2^2$  is established to minimize the difference between the two matrices, thereby ensuring that the semantic relationships in the input character glyphs are accurately contained in the generated signals.

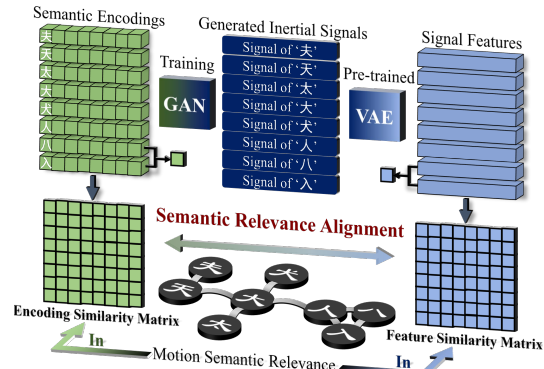


Figure 2: Diagram of semantic relevance alignment.

## 4 Experiments and Results

### 4.1 Data Collection and Experimental Setup

We invited nine volunteers, each using their smartphone’s built-in inertial sensors to record handwriting movements. The nine smartphones and their corresponding sensor models are listed in Table 1. Each volunteer held their phone according to their personal habit and wrote 500 Chinese characters in the air (sourced from the ”Commonly Used Chinese Characters List” published by the National Language Working Committee and the Ministry of Education), writing each character only once. In total, we obtained 4500 samples of Chinese handwriting signals. We randomly selected 1500 samples from three volunteers as the training set, while the remaining 3000 samples from six volunteers were used as the test set without participating in any training. All experiments are implemented by Pytorch 1.12.1 with an Nvidia RTX 2080TI GPU and Intel(R) Xeon(R) W-2133 CPU.

Table 1: The built-in IMU specifications of some smartphones. Note that since the IMUs in some types of iPhones are customized by the manufacturer, the model and price are not disclosed.

Dataset	Smartphone	Release Time	IMU	Unit price
Training	iPhone 13 pro	Sep. 2021	Undisclosed	/
	HUAWEI P40	Mar. 2020	LSM6DSM	\$0.30
	HUAWEI P40 Pro	Apr. 2020	LSM6DSO	\$0.33
Testing	iPhone 14	Sep. 2022	Undisclosed	/
	iPhone 15	Sep. 2023	Undisclosed	/
	VIVO T2x	May. 2022	LSM6DSO	\$0.33
	OPPO Reno 6	May. 2021	ICM-40607	\$0.28
	Realme GT	Mar. 2021	BMI160	\$0.21
	Redmi K40	Mar. 2021	ICM-40607	\$0.28

### 4.2 Signal Generation Visualization

To visually demonstrate the signal generation effect of CI-GAN, we visualized the real and generated inertial sensor signals of the handwriting movements for the Chinese characters ”科” and ”学”, respectively. In these figures, the blue curves represent the three-axis acceleration signals, and the yellow curves represent the three-axis gyroscope signals. It can be observed that the generated signals closely follow the overall fluctuation trends of the real signals, indicating that CI-GAN effectively preserves the handwriting movement information of the real signals. To further verify the consistency

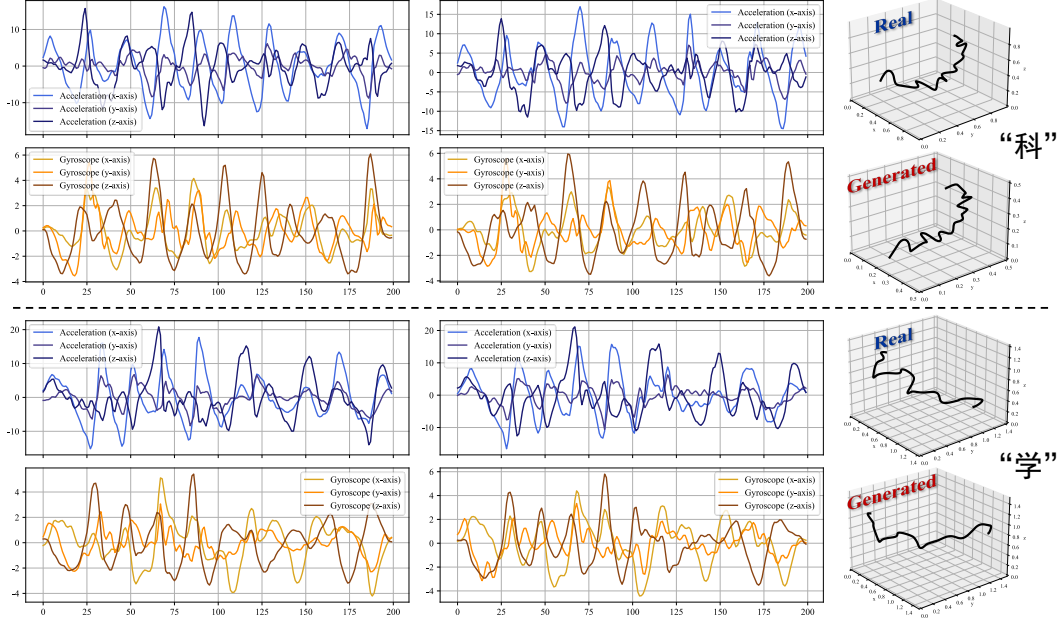


Figure 3: The visualization results of the 6-axis signals recorded by the inertial sensor for different Chinese character writing movements and the corresponding generated signals. The left side is the original inertial sensor signal, the middle is the corresponding generated signal, and the right side is the reconstructed writing trajectory.

of the movement characteristics between the generated and real signals, we employed a classical inertial navigation method [33] to convert both the real and generated signals into corresponding



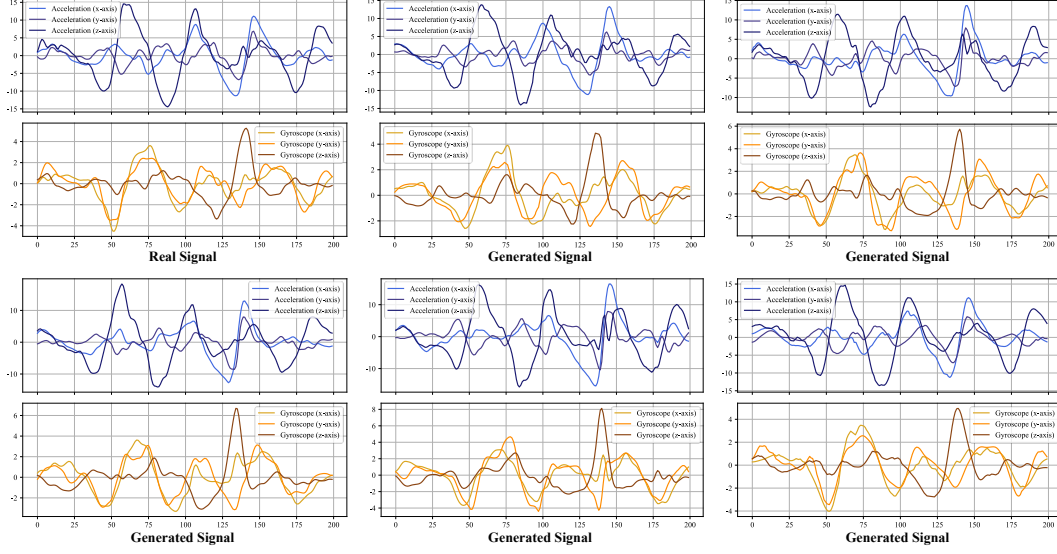


Figure 4: Visualization of the real IMU signal for writing "王" and the virtual signals generated by CI-GAN. The upper left corner is the real signal, and the remaining signals are virtual signals.

254 motion trajectories, as shown in the third column of Fig. 3. It is important to note that the purpose  
 255 of reconstructing the motion trajectories is not to precisely reproduce every detail of the writing  
 256 process but to compare the overall shape similarity between the trajectories derived from real and  
 257 generated signals. The highly similar shapes between the trajectories indicate that the generated  
 258 signals accurately capture the structural information of different Chinese characters and can effectively  
 259 simulate the key movement features of the handwriting process, including stroke order, movement  
 260 direction changes, and velocity variations. Additionally, the obvious differences in details between  
 261 the real and generated signals demonstrate CI-GAN's capability to generate diverse signals. Since the  
 262 generated signals maintain the core movement and semantic features of the handwriting process, these  
 263 differences do not impair the overall recognition of the characters but rather enhance the diversity of  
 264 the training data.

265 To demonstrate CI-GAN's ability to generate unlimited high-quality signals, we generated five IMU  
 266 handwriting signals for the same character "王" and compared them with a real handwriting signal,  
 267 as shown in Fig. 4. We chose this character because its strokes are distinctly separated, making it  
 268 easier to compare the consistency of stroke features between the generated and real signals. It can  
 269 be observed that the generated signals exhibit similar fluctuation patterns to the real signal in all  
 270 three axes of acceleration and gyroscope measurements, verifying CI-GAN's precision in capturing  
 271 dynamic handwriting characteristics. Although the overall trends of the generated signals align with  
 272 the real signal, the individual features show variations, demonstrating CI-GAN's potential to produce  
 273 large-scale, high-quality, and diverse IMU handwriting signal samples.

### 274 4.3 Comparative Experiments

275 Using the trained CI-GAN, we generated 30 virtual IMU handwriting signals for each character,  
 276 resulting in a total of 16500 training samples. To evaluate the impact of the generated signals  
 277 on handwriting recognition tasks, we trained six representative time-series classification models  
 278 with these training samples: 1DCNN, LSTM, Transformer, SVM, XGBoost, and Random Forest  
 279 (RF). We then tested the performance of these classifiers on the test set, as shown in Fig. 5.

285 When the number of training samples is small (1500 real samples), the recognition accuracy of all  
 286 classifiers is poor, with the highest accuracy being only 6.7%. As the generated training samples are

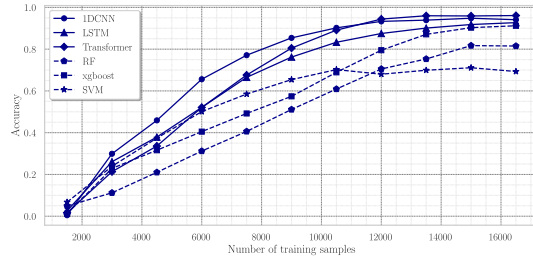


Figure 5: The recognition accuracy of 6 classifiers with varied training samples provided by CI-GAN.

introduced, all classifiers’ recognition accuracy improves significantly, whereas deep learning ones such as 1DCNN, LSTM, and Transformer show the most notable improvement. When the number of training samples reaches 15000, the recognition accuracy of 1DCNN can reach 95.7%, improving from 0.87% (without data augmentation). The Transformer captures long-range dependencies in time-series data through its self-attention mechanism, enabling it to understand complex movement patterns. However, its excellent recognition ability relies on large amounts of data, making its performance improvement the most significant as CI-GAN continuously generates training data, improving from 1.7% to 98.4%. Compared to deep learning models, machine learning models also exhibit significant dependence on the amount of training data, highlighting the critical role of sufficient generated signals in handwriting recognition tasks. With the abundant training samples generated by CI-GAN, six classifiers achieve accurate recognition even for similar characters as shown in Appendix A.1.

In summary, CI-GAN provides a data experimental platform for Chinese writing recognition, enabling various classifiers to utilize the generated samples for training and improving their

recognition accuracy. To help researchers select suitable classifiers for different application scenarios, we further tested the recognition speed and memory usage of different classifiers for a single input sample and summarized their recognition accuracy in Table 2. Among the three deep learning models, 1DCNN has the fastest runtime and the smallest memory usage, with a recognition accuracy of 95.7%, slightly lower than the Transformer but sufficient for most practical applications. It is more suitable for integration into memory and computation resource-limited smart wearable devices such as phones, watches, and wristbands. In contrast, Transformer has the highest accuracy among the six classifiers and the highest memory usage, making it more suitable for PC-based applications. Compared to deep learning classifiers, traditional machine learning classifiers generally have lower accuracy, but with the support of abundant training samples generated by CI-GAN, the XGBoost model still achieves a recognition accuracy of 93.1%, very close to deep learning classifiers. More importantly, XGBoost, as a tree model, has strong interpretability, allowing users to intuitively observe which features significantly impact the model’s decision-making process, which is a strength that deep learning models lack. Additionally, XGBoost’s runtime and memory usage are better than the three deep learning classifiers, making it outstanding in scenarios requiring a balance between model performance, interpretability, and resource efficiency. For example, XGBoost can be integrated into stationery and educational tools to analyze students’ handwriting habits and provide personalized feedback suggestions. Similarly, in the healthcare field, XGBoost can be used to analyze patients’ writing characteristics, assisting doctors in evaluating treatment effects or predicting disease risks. Its high interpretability can provide an auxiliary reference for medical decisions and treatment plans, increasing patients’ trust in the treatment.

Table 2: Performance comparison of 6 classifiers.

Classifier	1DCNN	LSTM	Transformer	RF	XGBoost	SVM
Runtime (s)	0.00743	0.13009	0.03439	0.01269	0.00154	0.00173
Memory (MB)	22.153	29.897	52.336	35.418	19.472	3.881
Accuracy	95.7%	93.9%	98.4%	83.5%	93.1%	74.6%

#### 4.4 Ablation Study

Systematic ablation experiments are conducted to evaluate the contributions of the CGE, FOT, and SRA modules in CI-GAN. We generated writing samples using the ablated models and trained the six classifiers on these samples. The results are summarized in Table 3. When no generated data is used (No augmentation), the recognition accuracy of all classifiers is very poor. Employing the Base GAN to generate training samples brings slight improvement but still underperforms, underscoring the critical importance and necessity of data augmentation for accurate recognition. This also indicates that utilizing GAN to improve classifier performance is a challenging task. Introducing CGE, FOT, and SRA individually into the GAN significantly improves its performance, with the introduction of CGE bringing the most noticeable improvement. This demonstrates that incorporating Chinese glyph encoding into the generative model is crucial for accurately generating writing signals. When CGE, FOT, and SRA are simultaneously integrated into the GAN (i.e., CI-GAN), the performance of all six classifiers is improved to above 70%, with four classifiers achieving recognition accuracies exceeding

Table 3: Performance comparison of six classifiers trained on samples generated by different ablation models.

Ablation model	1DCNN	LSTM	Transformer	RF	XGBoost	SVM
No augmentation	0.87%	2.6%	1.7%	4.9%	1.2%	6.7%
w/o all (Base GAN)	18.5%	14.8%	15.7%	12.4%	20.5%	8.4%
w/ OT	26.4%	28.6%	27.3%	21.0%	30.9%	20.9%
w/ FOT	39.9%	38.0%	35.3%	31.9%	46.8%	27.3%
w/ CGE	54.6%	51.2%	47.9%	38.6%	57.5%	34.1%
w/ FOT+CGE	80.7%	80.5%	80.9%	57.2%	70.4%	59.5%
w/ FOT+CGE+SRA (CI-GAN)	95.7%	93.9%	98.4%	83.5%	93.1%	74.6%



90%. Notably, the Transformer classifier achieves an impressive accuracy of 98.4%. Furthermore, statistical significance analysis is performed to validate the reliability of these results, as shown in Appendix A.2.

#### 4.5 Visualization Analysis of Chinese Glyph Encoding

To demonstrate the effectiveness of the Chinese glyph encoding in capturing the glyph features of Chinese characters, we conducted a visualization analysis using t-SNE, which reduced the dimensionality of the glyph encodings of 500 Chinese characters and visualized the results in a 2D space, as shown in Fig. 6, where each point represents a Chinese character. For the convenience of observation, we selected 6 local visualization regions from left to right and zoomed in on them at the bottom. It can be observed that characters with similar strokes and structure (e.g., "办-为", "目-且", "人-入-八") are close to each other. Additionally, the figure shows several clusters where characters within the same cluster share similar radicals, structures, or strokes, indicating that CGE effectively captures the similarities and differences in the glyph features of Chinese characters. By incorporating CGE into the generative model, CI-GAN can produce writing signals that accurately reflect the structure and stroke features of Chinese characters, ensuring the generated signals closely align with real writing movements. This encoding is not only crucial for guiding GANs in generating writing signals but also potentially provides new tools and perspectives for studying the evolution of Chinese hieroglyphs.

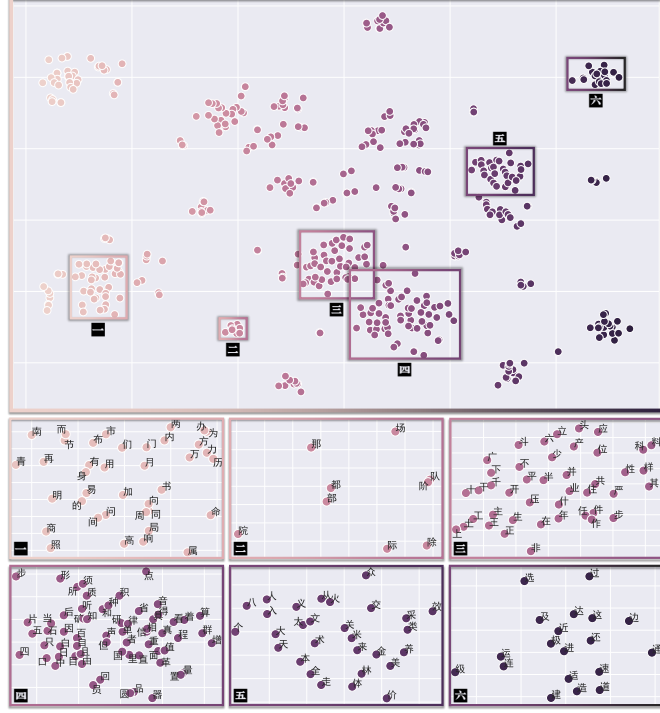


Figure 6: The t-SNE visualization of Chinese glyph encodings.

## 5 Conclusion

This paper introduces GAN to generate inertial sensor signals and proposes CI-GAN for Chinese writing data augmentation, which consists of CGE, FOT, and SRA. The CGE module constructs an encoding of the stroke and structure for Chinese characters, providing glyph information for GAN to generate writing signals. FOT overcomes the mode collapse and mode mixing problems of traditional GANs and ensures the authenticity of the generated samples through a forced feature matching mechanism. The SRA module aligns the semantic relationships between the generated signals and the corresponding Chinese characters, thereby imposing a batch-level constraint on GAN. Utilizing the large-scale, high-quality synthetic IMU writing signals provided by CI-GAN, the recognition accuracy of six widely used classifiers for Chinese writing recognition was improved from 6.7% to 98.4%, which demonstrates that CI-GAN has the potential to become a flexible and efficient data generation platform in the field of Chinese writing recognition. This research provides a novel human-computer interaction, especially for disabled people. Its limitations and impact are discussed in Appendix B.1 and B.2. In the future, we plan to extend CI-GAN to generate signals from other modalities of sensors, constructing a multimodal human-computer interaction system tailored for disabled individuals, which can adapt to the diverse needs of users with different disabilities. Through continuous collaboration with healthcare professionals and the disabled community, we will refine and optimize these multimodal systems to ensure they deliver the highest functionality and user satisfaction. Ultimately, this research aims to foster a society where digital accessibility is a fundamental right, ensuring that all individuals, regardless of physical abilities, can engage fully and independently with the digital world.

## References

- [1] Jayraj V Vaghasiya, Carmen C Mayorga-Martinez, Jan Vyskočil, and Martin Pumera. Black phosphorous-based human-machine communication interface. *Nature communications*, 14(1):2, 2023.
- [2] Xumeng Wang, Xinhua Zheng, Wei Chen, and Fei-Yue Wang. Visual human–computer interactions for intelligent vehicles and intelligent transportation systems: The state of the art and future directions. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, 51(1):253–265, 2020.
- [3] Swapnil Sayan Saha, Sandeep Singh Sandha, Luis Antonio Garcia, and Mani Srivastava. Tinyodom: Hardware-aware efficient neural inertial navigation. *Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies*, 6(2):1–32, 2022.
- [4] Mahdi Abolfazli Esfahani, Han Wang, Keyu Wu, and Shenghai Yuan. Aboldeepio: A novel deep inertial odometry network for autonomous vehicles. *IEEE Transactions on Intelligent Transportation Systems*, 21(5):1941–1950, 2019.
- [5] Xin Zhang, Bo He, Guangliang Li, Xiaokai Mu, Ying Zhou, and Tanji Mang. Navnet: Auv navigation through deep sequential learning. *IEEE Access*, 8:59845–59861, 2020.
- [6] Wenxin Liu, David Caruso, Eddy Ilg, Jing Dong, Anastasios I Mourikis, Kostas Daniilidis, Vijay Kumar, and Jakob Engel. Tlio: Tight learned inertial odometry. *IEEE Robotics and Automation Letters*, 5(4):5653–5660, 2020.
- [7] Daniel Weber, Clemens Gühmann, and Thomas Seel. Riann—a robust neural network outperforms attitude estimation filters. *Ai*, 2(3):444–463, 2021.
- [8] Boris Gromov, Gabriele Abbate, Luca M. Gambardella, and Alessandro Giusti. Proximity human-robot interaction using pointing gestures and a wrist-mounted imu. In *2019 International Conference on Robotics and Automation (ICRA)*, pages 8084–8091, 2019. doi: 10.1109/ICRA.2019.8794399.
- [9] Peng Li, Wen-An Zhang, Yuqiang Jin, Zihan Hu, and Linqing Wang. Attitude estimation using iterative indirect kalman with neural network for inertial sensors. *IEEE Transactions on Instrumentation and Measurement*, 2023.
- [10] Sachini Herath, Hang Yan, and Yasutaka Furukawa. Ronin: Robust neural inertial navigation in the wild: Benchmark, evaluations, & new methods. In *2020 IEEE International Conference on Robotics and Automation (ICRA)*, pages 3146–3152. IEEE, 2020.
- [11] Shiqiang Liu, Junchang Zhang, Yuzhong Zhang, and Rong Zhu. A wearable motion capture device able to detect dynamic motion of human limbs. *Nature communications*, 11(1):5615, 2020.
- [12] You Li, Ruizhi Chen, Xiaoji Niu, Yuan Zhuang, Zhouzheng Gao, Xin Hu, and Naser El-Sheimy. Inertial sensing meets machine learning: Opportunity or challenge? *IEEE Transactions on Intelligent Transportation Systems*, 23(8):9995–10011, 2022. doi: 10.1109/TITS.2021.3097385.
- [13] Derek K Shaeffer. Mems inertial sensors: A tutorial overview. *IEEE Communications Magazine*, 51(4):100–109, 2013.
- [14] Changhao Chen, Xiaoxuan Lu, Andrew Markham, and Niki Trigoni. Ionet: Learning to cure the curse of drift in inertial odometry. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 32, 2018.
- [15] Martin Brossard, Axel Barrau, and Silvére Bonnabel. Ai-imu dead-reckoning. *IEEE Transactions on Intelligent Vehicles*, 5(4):585–595, 2020.
- [16] Yifeng Wang and Yi Zhao. Handwriting recognition under natural writing habits based on a low-cost inertial sensor. *IEEE Sensors Journal*, 24(1):995–1005, 2024. doi: 10.1109/JSEN.2023.3331011.

- [17] Haiqing Ren, Weiqiang Wang, and Chenglin Liu. Recognizing online handwritten chinese characters using rnns with new computing architectures. *Pattern Recognition*, 93:179–192, 2019.
- [18] Elyoenai Guerra-Segura, Aysse Ortega-Pérez, and Carlos M Travieso. In-air signature verification system using leap motion. *Expert Systems with Applications*, 165:113797, 2021.
- [19] Irene Cortes-Perez, Noelia Zagalaz-Anula, Desiree Montoro-Cardenas, Rafael Lomas-Vega, Esteban Obrero-Gaitan, and María Catalina Osuna-Pérez. Leap motion controller video game-based therapy for upper extremity motor recovery in patients with central nervous system diseases. a systematic review with meta-analysis. *Sensors*, 21(6):2065, 2021.
- [20] Salih Ertug Ovur, Hang Su, Wen Qi, Elena De Momi, and Giancarlo Ferrigno. Novel adaptive sensor fusion methodology for hand pose estimation with multileap motion. *IEEE Transactions on Instrumentation and Measurement*, 70:1–8, 2021.
- [21] Ning Xiao, Panlong Yang, Yubo Yan, Hao Zhou, Xiang-Yang Li, and Haohua Du. Motion-fi<sup>++</sup>: Recognizing and counting repetitive motions with wireless backscattering. *IEEE Transactions on Mobile Computing*, 20(5):1862–1876, 2021. doi: 10.1109/TMC.2020.2971996.
- [22] Xuanzhi Wang, Kai Niu, Jie Xiong, Bochong Qian, Zhiyun Yao, Tairong Lou, and Daqing Zhang. Placement matters: Understanding the effects of device placement for wifi sensing. *Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies*, 6(1):1–25, 2022.
- [23] Ruiyang Gao, Wenwei Li, Jinyi Liu, Shuyu Dai, Mi Zhang, Leye Wang, and Daqing Zhang. Wiggesture: Meta-motion based continuous gesture recognition with wi-fi. *IEEE Internet of Things Journal*, 2023.
- [24] Sai Deepika Regani, Beibei Wang, and K. J. Ray Liu. Wifi-based device-free gesture recognition through-the-wall. In *ICASSP 2021 - 2021 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)*, pages 8017–8021, 2021. doi: 10.1109/ICASSP39728.2021.9414894.
- [25] Zhengxin Guo, Fu Xiao, Biyun Sheng, Huan Fei, and Shui Yu. Wireader: Adaptive air handwriting recognition based on commercial wifi signal. *IEEE Internet of Things Journal*, 7(10):10483–10494, 2020.
- [26] Ruiyang Gao, Wenwei Li, Yaxiong Xie, Enze Yi, Leye Wang, Dan Wu, and Daqing Zhang. Towards robust gesture recognition by characterizing the sensing quality of wifi signals. *Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies*, 6(1):1–26, 2022.
- [27] Yu Gu, Jinhai Zhan, Yusheng Ji, Jie Li, Fuji Ren, and Shangbing Gao. Mosense: An rf-based motion detection system via off-the-shelf wifi devices. *IEEE Internet of Things Journal*, 4(6):2326–2341, 2017.
- [28] Luis Montesinos, Rossana Castaldo, and Leandro Pecchia. Wearable inertial sensors for fall risk assessment and prediction in older adults: A systematic review and meta-analysis. *IEEE transactions on neural systems and rehabilitation engineering*, 26(3):573–582, 2018.
- [29] Changhao Chen, Peijun Zhao, Chris Xiaoxuan Lu, Wei Wang, Andrew Markham, and Niki Trigoni. Deep-learning-based pedestrian inertial navigation: Methods, data set, and on-device inference. *IEEE Internet of Things Journal*, 7(5):4431–4441, 2020.
- [30] Swapnil Sayan Saha, Yayun Du, Sandeep Singh Sandha, Luis Antonio Garcia, Mohammad Khalid Jawed, and Mani Srivastava. Inertial navigation on extremely resource-constrained platforms: Methods, opportunities and challenges. In *2023 IEEE/ION Position, Location and Navigation Symposium (PLANS)*, pages 708–723. IEEE, 2023.
- [31] Mahdi Abolfazli Esfahani, Han Wang, Keyu Wu, and Shenghai Yuan. Orinet: Robust 3-d orientation estimation with a single particular imu. *IEEE Robotics and Automation Letters*, 5(2):399–406, 2019.

- 496 [32] Jian Zhang, Hongliang Bi, Yanjiao Chen, Qian Zhang, Zhaoyuan Fu, Yunzhe Li, and Zeyu Li.  
497 Smartso: Chinese character and stroke order recognition with smartwatch. *IEEE Transactions*  
498 *on Mobile Computing*, 20(7):2490–2504, 2020.
- 499 [33] Mohinder S Grewal, Lawrence R Weill, and Angus P Andrews. *Global positioning systems,*  
500 *inertial navigation, and integration*. John Wiley & Sons, 2007.

## 501 Appendix / Supplemental Material

### 502 A Additional Experimental Results

#### 503 A.1 Performance of Classifiers on Similar Characters

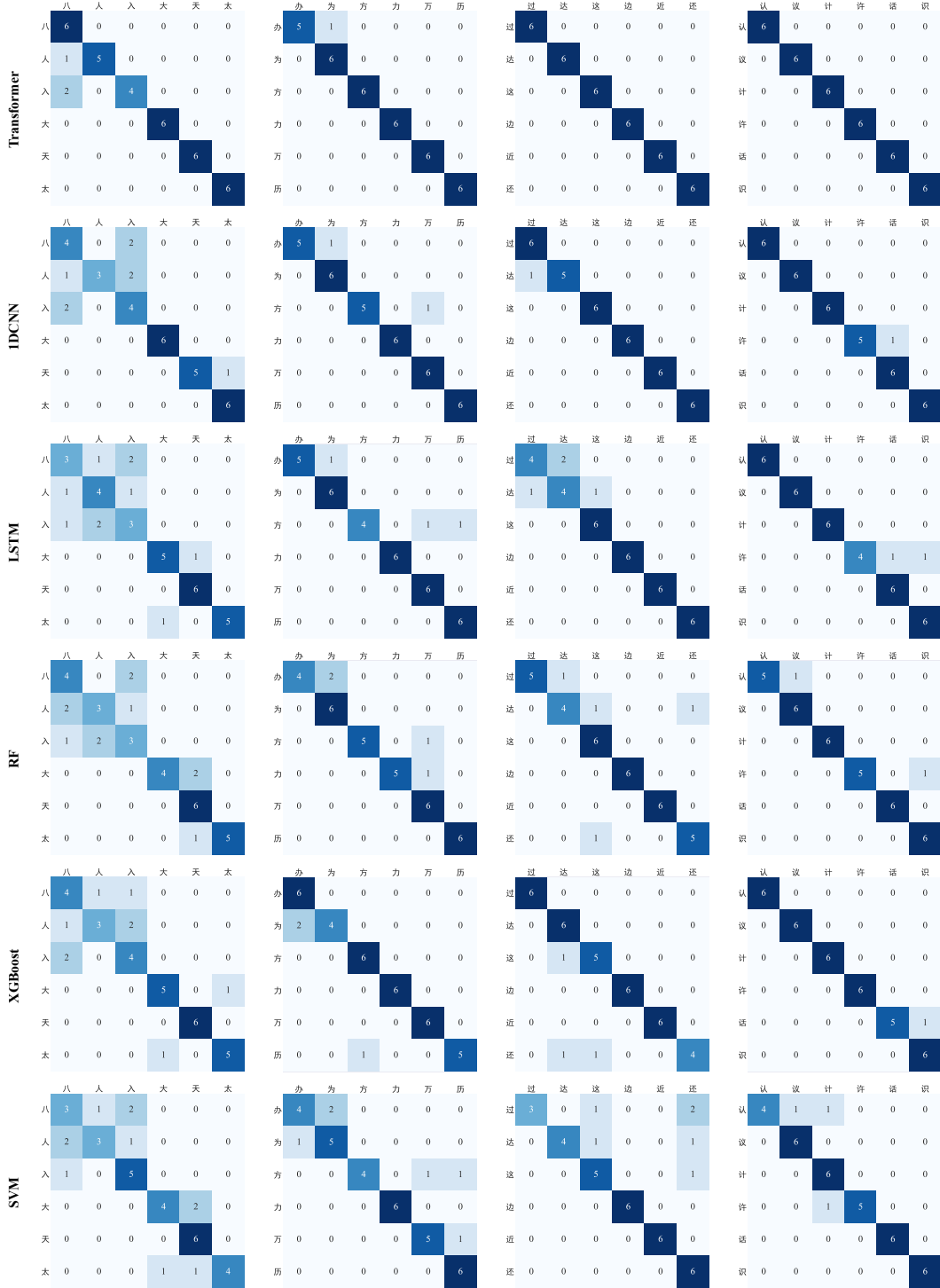


Figure 7: Confusion matrices of different classifiers for recognition results of Chinese characters with similar glyphs.

With the abundant training samples generated by CI-GAN, the handwriting recognition performance of all six classifiers significantly improved. To further verify the recognition performance of different classifiers on characters with similar strokes and glyphs, we selected four groups of characters with similar handwriting movements from the test set ("八人入大天太", "办为方力万历", "过达这边近还", and "认议计许话识") and presented the recognition results of the six classifiers in confusion matrices, as shown in Fig. 7. It can be observed that the values on the diagonal of all confusion matrices are significantly higher than the non-diagonal values, indicating high recognition accuracy for these similar handwriting characters with the help of samples generated by CI-GAN. However, some characters are still misrecognized. For instance, the characters "八", "人", and "入" have extremely similar structures and writing movements, posing challenges even when massive training samples are provided. Moreover, continuous and non-standard writing can also cause recognition obstacles. For instance, although the characters "过" and "达" have different strokes in static form, they are very similar in dynamic handwriting. Despite these challenges, the synthetic IMU handwriting samples generated by CI-GAN significantly enhance the classifiers' ability to recognize characters with similar glyph structures and handwriting movements, highlighting the value and significance of the proposed CI-GAN method. By providing diverse and high-quality training samples, CI-GAN improves handwriting recognition classifiers' performance and generalization ability, making it a valuable tool for advancing Chinese handwriting recognition technology.

## A.2 Statistical Significance Analysis

The CI-GAN model demonstrates significant performance improvements across multiple classifiers, as shown in Table 4. The Transformer classifier, for instance, achieves a mean accuracy of 98.4%, compared to 15.7% with the traditional GAN and 1.7% without data augmentation. This highlights CI-GAN's ability to generate realistic and diverse training samples that enhance handwriting recognition. Moreover, CI-GAN consistently improves accuracy and stability for all classifiers tested. The 1DCNN's accuracy increases to 95.7% from 18.5% with the traditional GAN and 0.87% without augmentation. Similarly, other models, including LSTM, RandomForest, XGBoost, and SVM, show substantial gains, underscoring CI-GAN's effectiveness across diverse machine-learning contexts. In addition, the narrow 95% confidence intervals, such as [98.2822%, 98.5178%] for the Transformer, validate the statistical significance and reliability of these results. This confirms CI-GAN's potential to consistently enhance classifier performance. In conclusion, CI-GAN represents a major advancement in Chinese handwriting recognition by generating high-quality, diverse inertial signals. This significantly boosts the accuracy and reliability of various classifiers, demonstrating CI-GAN's transformative potential in the field.

Table 4: Performance of different classifiers with CI-GAN generated data

Ablation	Classifier	Mean Accuracy	Standard Deviation	95% Confidence Interval
No data augmentation	1DCNN	0.87%	0.11%	[0.8018%, 0.9382%]
	LSTM	2.61%	0.20%	[2.4761%, 2.7239%]
	Transformer	1.70%	0.13%	[1.6194%, 1.7806%]
	RandomForest	4.89%	0.09%	[4.8439%, 4.9556%]
	XGBoost	1.20%	0.15%	[1.1071%, 1.2929%]
	SVM	6.65%	0.10%	[6.5881%, 6.7119%]
Traditional GAN	1DCNN	18.5%	0.16%	[18.4008%, 18.5992%]
	LSTM	14.8%	0.37%	[14.5707%, 15.0293%]
	Transformer	15.7%	0.15%	[15.6071%, 15.7929%]
	RandomForest	12.4%	0.17%	[12.2948%, 12.5052%]
	XGBoost	20.5%	0.23%	[20.3573%, 20.6427%]
	SVM	8.40%	0.34%	[8.1893%, 8.6107%]
CI-GAN	1DCNN	95.7%	0.24%	[95.5513%, 95.8487%]
	LSTM	93.9%	0.53%	[93.5713%, 94.2287%]
	Transformer	98.4%	0.19%	[98.2822%, 98.5178%]
	RandomForest	83.5%	0.35%	[83.2831%, 83.7169%]
	XGBoost	93.1%	0.46%	[92.8148%, 93.3852%]
	SVM	74.6%	0.38%	[74.3644%, 74.8356%]



## B Discussion

### B.1 Societal Impact

CI-GAN model significantly improves the accuracy of Chinese writing recognition and offers an alternative means of human-computer interaction that can overcome the limitations of traditional keyboard-based methods, which are often inaccessible to those who are blind or lose their fingers. By providing a more accessible and user-friendly way to interact with digital devices, inertial sensors can facilitate effective communication, enhance the participation of disabled people in education and employment, and promote greater independence. Moreover, by addressing the unique needs of this population, such technological advancements reflect a commitment to inclusivity and social justice, ensuring that everyone, regardless of their physical abilities, has the opportunity to fully participate in and contribute to society.

Furthermore, by releasing the world’s first Chinese handwriting recognition dataset based on inertial sensors, this research provides valuable data resources for both academia and industry, facilitating further studies and advancements. Additionally, the technology offers an intuitive and efficient learning tool for Chinese language learners, aiding in preserving and disseminating Chinese cultural heritage and strengthening the global influence of Chinese characters. In summary, the CI-GAN technology achieves not only significant breakthroughs in algorithmic research but also demonstrates extensive practical potential and substantial societal value, thereby being adopted by educational aid device manufacturers. This study provides a solid foundation for future academic research, technological development, and industrial applications, driving technological progress and societal development.

### B.2 Limitation

While the CI-GAN model demonstrates significant advancements in Chinese handwriting generation and recognition, some practical limitations could impact its performance in real-world applications. For instance, non-standard or cursive handwriting may pose challenges for accurate signal generation and recognition. Additionally, environmental factors such as external movements or vibrations when using handheld devices could affect the inertial sensor data quality, leading to variations in recognition accuracy. Future work could focus on developing more robust algorithms that account for these real-world variations and improving the model’s adaptability to diverse handwriting styles and conditions. These enhancements would ensure that the CI-GAN technology remains effective across a broader range of practical scenarios.

## C Theory Assumption and Proof

To generate large-scale and high-quality handwriting signals, we introduce optimal transport theory into the generative adversarial network to alleviate mode collapse and mixing issues. We provide a detailed explanation and present a rigorous mathematical proof to show the advantages of this operation.

In traditional conditional GANs, the generator  $G$  and the discriminator  $D$  are trained by minimizing the loss function  $\mathcal{L}_{tradition}$ :

$$\mathcal{L}_{tradition} = \min_G \max_D \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}} [\log(1 - D(G(\mathbf{z})))] ,$$

where  $p_{\text{data}}$  is the real data distribution, and  $p_{\mathbf{z}}$  is the distribution of the generator’s input noise. This loss function essentially minimizes the Jensen-Shannon Divergence (JSD) between the real data distribution  $p_{\text{data}}$  and the generated data distribution  $p_g$ :

$$\text{JSD}(p_{\text{data}} \| p_g) = \frac{1}{2} \text{KL}(p_{\text{data}} \| M) + \frac{1}{2} \text{KL}(p_g \| M),$$

where  $M = \frac{1}{2}(p_{\text{data}} + p_g)$  and KL denotes the Kullback-Leibler divergence. However, JSD has a notable drawback: when the real and generated data distributions do not overlap, the JSD becomes zero, causing the gradients to vanish. This leads to mode collapse, where the generator produces a limited variety of samples.

582 In optimal transport theory, the Wasserstein distance is utilized to measure the minimum cost of  
 583 transforming one probability distribution into another. Given two probability distributions  $\mu$  and  $\nu$  on  
 584 a metric space  $\mathcal{X}$ , the Wasserstein distance  $W$  is:

$$W(\mu, \nu) = \inf_{\gamma \in \Pi(\mu, \nu)} \mathbb{E}_{(x, y) \sim \gamma} [d(x, y)],$$

585 where  $\Pi(\mu, \nu)$  is the set of all joint distributions whose marginals are  $\mu$  and  $\nu$ , and  $d(x, y)$  is a distance  
 586 metric on  $\mathcal{X}$ . Therefore, we introduce the Wasserstein distance in optimal transport theory as new  
 587 loss function  $\mathcal{L}_{OT}$ , whose objective is to minimize the Wasserstein distance between the generated  
 588 distribution  $p_g$  and the real distribution  $p_{\text{data}}$ . The  $\mathcal{L}_{OT}$  is defined as:

$$\mathcal{L}_{OT} = \min_G \max_{D \in \mathcal{D}} \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}} [D(\mathbf{x})] - \mathbb{E}_{\mathbf{z} \sim p_z} [D(G(\mathbf{z}))]$$

589 where  $\mathcal{D}$  is the set of 1-Lipschitz functions. This Lipschitz constraint can be enforced through weight  
 590 clipping or gradient penalty. In  $\mathcal{L}_{OT}$ , the discriminator  $D$  is constrained to be 1-Lipschitz:

$$|D(x_1) - D(x_2)| \leq |x_1 - x_2|.$$

591 This constraint ensures that the discriminator provides meaningful gradients even when  $p_g$  and  $p_{\text{data}}$   
 592 do not overlap. Using the Kantorovich-Rubinstein duality, we can express the Wasserstein distance  
 593 as:

$$W(p_{\text{data}}, p_g) = \sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim p_{\text{data}}} [f(x)] - \mathbb{E}_{x \sim p_g} [f(x)].$$

594 Since  $f$  is Lipschitz continuous, it ensures that the gradients  $\nabla f(x)$  are bounded and do not vanish.  
 595 Hence, during the optimization process, the generator receives consistent and informative gradient  
 596 updates that guide it to produce more realistic and diverse samples. The gradient of the loss function  
 597  $\mathcal{L}_{OT}$  with respect to the generator's parameters  $\theta$  is:

$$\nabla_{\theta} \mathbb{E}_{\mathbf{z} \sim p_z} [D(G_{\theta}(\mathbf{z}))] = \mathbb{E}_{\mathbf{z} \sim p_z} [\nabla_{\theta} D(G_{\theta}(\mathbf{z}))].$$

598 This gradient does not vanish even if  $p_g$  and  $p_{\text{data}}$  have disjoint supports, thanks to the 1-Lipschitz  
 599 property of  $D$ . As a result, the generator  $G$  can still receive valuable gradient information to adjust its  
 600 parameters and gradually make  $p_g$  approximate  $p_{\text{data}}$  even if  $p_g$  and  $p_{\text{data}}$  do not overlap, effectively  
 601 addressing mode collapse and mode mixing issues. Overall, after introducing optimal transport theory,  
 602 we overcome the gradient vanishing problem inherent in traditional GANs, effectively mitigating  
 603 mode collapse and mode mixing.  $\mathcal{L}_{OT}$  maintains the existence and relevance of gradients during  
 604 training, enabling the generator to continuously improve and produce more diverse and realistic  
 605 handwriting samples.

## NeurIPS Paper Checklist

### 1. Claims

Question: Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope?

Answer: [\[Yes\]](#)

Justification: We have specifically summarized the main contributions of this article in the introduction.

Guidelines:

- The answer NA means that the abstract and introduction do not include the claims made in the paper.
- The abstract and/or introduction should clearly state the claims made, including the contributions made in the paper and important assumptions and limitations. A No or NA answer to this question will not be perceived well by the reviewers.
- The claims made should match theoretical and experimental results, and reflect how much the results can be expected to generalize to other settings.
- It is fine to include aspirational goals as motivation as long as it is clear that these goals are not attained by the paper.

### 2. Limitations

Question: Does the paper discuss the limitations of the work performed by the authors?

Answer: [\[Yes\]](#) As shown in Appendix B.2.

Justification: Non-standard or cursive handwriting may pose challenges for accurate signal generation and recognition.

Guidelines:

- The answer NA means that the paper has no limitation while the answer No means that the paper has limitations, but those are not discussed in the paper.
- The authors are encouraged to create a separate "Limitations" section in their paper.
- The paper should point out any strong assumptions and how robust the results are to violations of these assumptions (e.g., independence assumptions, noiseless settings, model well-specification, asymptotic approximations only holding locally). The authors should reflect on how these assumptions might be violated in practice and what the implications would be.
- The authors should reflect on the scope of the claims made, e.g., if the approach was only tested on a few datasets or with a few runs. In general, empirical results often depend on implicit assumptions, which should be articulated.
- The authors should reflect on the factors that influence the performance of the approach. For example, a facial recognition algorithm may perform poorly when image resolution is low or images are taken in low lighting. Or a speech-to-text system might not be used reliably to provide closed captions for online lectures because it fails to handle technical jargon.
- The authors should discuss the computational efficiency of the proposed algorithms and how they scale with dataset size.
- If applicable, the authors should discuss possible limitations of their approach to address problems of privacy and fairness.
- While the authors might fear that complete honesty about limitations might be used by reviewers as grounds for rejection, a worse outcome might be that reviewers discover limitations that aren't acknowledged in the paper. The authors should use their best judgment and recognize that individual actions in favor of transparency play an important role in developing norms that preserve the integrity of the community. Reviewers will be specifically instructed to not penalize honesty concerning limitations.

### 3. Theory Assumptions and Proofs

Question: For each theoretical result, does the paper provide the full set of assumptions and a complete (and correct) proof?

Answer: [Yes] As shown in Appendix C.

Justification: We provide a detailed explanation and present rigorous mathematical proof of utilizing optimal transport to alleviate mode collapse and mixing issues of GAN.

Guidelines:

- The answer NA means that the paper does not include theoretical results.
- All the theorems, formulas, and proofs in the paper should be numbered and cross-referenced.
- All assumptions should be clearly stated or referenced in the statement of any theorems.
- The proofs can either appear in the main paper or the supplemental material, but if they appear in the supplemental material, the authors are encouraged to provide a short proof sketch to provide intuition.
- Inversely, any informal proof provided in the core of the paper should be complemented by formal proofs provided in appendix or supplemental material.
- Theorems and Lemmas that the proof relies upon should be properly referenced.

#### 4. Experimental Result Reproducibility

Question: Does the paper fully disclose all the information needed to reproduce the main experimental results of the paper to the extent that it affects the main claims and/or conclusions of the paper (regardless of whether the code and data are provided or not)?

Answer: [Yes] We have made every effort to disclose all experimental details, including CPU model, GPU model, PyTorch framework version, built-in IMU specifications of 9 experimental smartphones, and even the gender of volunteers.

Justification: The paper provides comprehensive details on the data collection process, data splits, hyperparameters, training procedures, and statistical analyses, ensuring that all necessary information is disclosed to fully reproduce the main experimental results and validate the claims and conclusions.

Guidelines:

- The answer NA means that the paper does not include experiments.
- If the paper includes experiments, a No answer to this question will not be perceived well by the reviewers: Making the paper reproducible is important, regardless of whether the code and data are provided or not.
- If the contribution is a dataset and/or model, the authors should describe the steps taken to make their results reproducible or verifiable.
- Depending on the contribution, reproducibility can be accomplished in various ways. For example, if the contribution is a novel architecture, describing the architecture fully might suffice, or if the contribution is a specific model and empirical evaluation, it may be necessary to either make it possible for others to replicate the model with the same dataset, or provide access to the model. In general, releasing code and data is often one good way to accomplish this, but reproducibility can also be provided via detailed instructions for how to replicate the results, access to a hosted model (e.g., in the case of a large language model), releasing of a model checkpoint, or other means that are appropriate to the research performed.
- While NeurIPS does not require releasing code, the conference does require all submissions to provide some reasonable avenue for reproducibility, which may depend on the nature of the contribution. For example
  - (a) If the contribution is primarily a new algorithm, the paper should make it clear how to reproduce that algorithm.
  - (b) If the contribution is primarily a new model architecture, the paper should describe the architecture clearly and fully.
  - (c) If the contribution is a new model (e.g., a large language model), then there should either be a way to access this model for reproducing the results or a way to reproduce the model (e.g., with an open-source dataset or instructions for how to construct the dataset).
  - (d) We recognize that reproducibility may be tricky in some cases, in which case authors are welcome to describe the particular way they provide for reproducibility. In the

case of closed-source models, it may be that access to the model is limited in some way (e.g., to registered users), but it should be possible for other researchers to have some path to reproducing or verifying the results.

## 5. Open access to data and code

Question: Does the paper provide open access to the data and code, with sufficient instructions to faithfully reproduce the main experimental results, as described in supplemental material?

Answer: [Yes] We released the world’s first Chinese handwriting recognition dataset based on inertial sensors.

Justification: We submitted the training set (due to system limitations on attachment size) in the Supplementary Materials for review, and the full dataset can be found on GitHub. (We confirm to license the use of this data set to all AI researchers around the world.)

Guidelines:

- The answer NA means that paper does not include experiments requiring code.
- Please see the NeurIPS code and data submission guidelines (<https://nips.cc/public/guides/CodeSubmissionPolicy>) for more details.
- While we encourage the release of code and data, we understand that this might not be possible, so “No” is an acceptable answer. Papers cannot be rejected simply for not including code, unless this is central to the contribution (e.g., for a new open-source benchmark).
- The instructions should contain the exact command and environment needed to run to reproduce the results. See the NeurIPS code and data submission guidelines (<https://nips.cc/public/guides/CodeSubmissionPolicy>) for more details.
- The authors should provide instructions on data access and preparation, including how to access the raw data, preprocessed data, intermediate data, and generated data, etc.
- The authors should provide scripts to reproduce all experimental results for the new proposed method and baselines. If only a subset of experiments are reproducible, they should state which ones are omitted from the script and why.
- At submission time, to preserve anonymity, the authors should release anonymized versions (if applicable).
- Providing as much information as possible in supplemental material (appended to the paper) is recommended, but including URLs to data and code is permitted.

## 6. Experimental Setting/Details

Question: Does the paper specify all the training and test details (e.g., data splits, hyperparameters, how they were chosen, type of optimizer, etc.) necessary to understand the results?

Answer: [Yes]

Justification: We made every effort to provide the necessary experimental details, including data collection and split, as well as the equipment specifications.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The experimental setting should be presented in the core of the paper to a level of detail that is necessary to appreciate the results and make sense of them.
- The full details can be provided either with the code, in appendix, or as supplemental material.

## 7. Experiment Statistical Significance

Question: Does the paper report error bars suitably and correctly defined or other appropriate information about the statistical significance of the experiments?

Answer: [Yes]

Justification: The detailed experimental setup, including data collection, hyperparameters, and statistical significance analysis, provides a comprehensive understanding of the CI-GAN

model’s robustness and efficacy. The thorough evaluation underscores the potential of CI-GAN to advance the field of Chinese handwriting recognition through high-quality, diverse signal generation.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The authors should answer “Yes” if the results are accompanied by error bars, confidence intervals, or statistical significance tests, at least for the experiments that support the main claims of the paper.
- The factors of variability that the error bars are capturing should be clearly stated (for example, train/test split, initialization, random drawing of some parameter, or overall run with given experimental conditions).
- The method for calculating the error bars should be explained (closed form formula, call to a library function, bootstrap, etc.)
- The assumptions made should be given (e.g., Normally distributed errors).
- It should be clear whether the error bar is the standard deviation or the standard error of the mean.
- It is OK to report 1-sigma error bars, but one should state it. The authors should preferably report a 2-sigma error bar than state that they have a 96% CI, if the hypothesis of Normality of errors is not verified.
- For asymmetric distributions, the authors should be careful not to show in tables or figures symmetric error bars that would yield results that are out of range (e.g. negative error rates).
- If error bars are reported in tables or plots, The authors should explain in the text how they were calculated and reference the corresponding figures or tables in the text.

## 8. Experiments Compute Resources

Question: For each experiment, does the paper provide sufficient information on the computer resources (type of compute workers, memory, time of execution) needed to reproduce the experiments?

Answer: [Yes] As shown in Table 2.

Justification: The paper specifies the type of compute resources used, including the Nvidia RTX 2080TI GPU and Intel Xeon W-2133 CPU, and provides details on memory usage and execution time, ensuring sufficient information is available to reproduce the experiments.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The paper should indicate the type of compute workers CPU or GPU, internal cluster, or cloud provider, including relevant memory and storage.
- The paper should provide the amount of compute required for each of the individual experimental runs as well as estimate the total compute.
- The paper should disclose whether the full research project required more compute than the experiments reported in the paper (e.g., preliminary or failed experiments that didn’t make it into the paper).

## 9. Code Of Ethics

Question: Does the research conducted in the paper conform, in every respect, with the NeurIPS Code of Ethics <https://neurips.cc/public/EthicsGuidelines>?

Answer: [Yes]

Justification: The research adheres to the NeurIPS Code of Ethics in all respects, ensuring ethical considerations are met in data collection, experimentation, and reporting of results.

Guidelines:

- The answer NA means that the authors have not reviewed the NeurIPS Code of Ethics.
- If the authors answer No, they should explain the special circumstances that require a deviation from the Code of Ethics.



- The authors should make sure to preserve anonymity (e.g., if there is a special consideration due to laws or regulations in their jurisdiction).

## 10. Broader Impacts

Question: Does the paper discuss both potential positive societal impacts and negative societal impacts of the work performed?

Answer: [Yes] This research significantly advances Chinese handwriting recognition technology, providing valuable educational tools and promoting cultural preservation while enhancing human-computer interaction across various applications, including smart devices and virtual reality, thus has been adopted by the educational aid device manufacturer. As shown in Appendix B.1 and Appendix B.2.

Justification: The paper thoroughly discusses the potential positive societal impacts, such as advancements in Chinese handwriting recognition and educational benefits, as well as possible negative impacts, including challenges with non-standard handwriting and external environmental factors affecting performance.

Guidelines:

- The answer NA means that there is no societal impact of the work performed.
- If the authors answer NA or No, they should explain why their work has no societal impact or why the paper does not address societal impact.
- Examples of negative societal impacts include potential malicious or unintended uses (e.g., disinformation, generating fake profiles, surveillance), fairness considerations (e.g., deployment of technologies that could make decisions that unfairly impact specific groups), privacy considerations, and security considerations.
- The conference expects that many papers will be foundational research and not tied to particular applications, let alone deployments. However, if there is a direct path to any negative applications, the authors should point it out. For example, it is legitimate to point out that an improvement in the quality of generative models could be used to generate deepfakes for disinformation. On the other hand, it is not needed to point out that a generic algorithm for optimizing neural networks could enable people to train models that generate Deepfakes faster.
- The authors should consider possible harms that could arise when the technology is being used as intended and functioning correctly, harms that could arise when the technology is being used as intended but gives incorrect results, and harms following from (intentional or unintentional) misuse of the technology.
- If there are negative societal impacts, the authors could also discuss possible mitigation strategies (e.g., gated release of models, providing defenses in addition to attacks, mechanisms for monitoring misuse, mechanisms to monitor how a system learns from feedback over time, improving the efficiency and accessibility of ML).

## 11. Safeguards

Question: Does the paper describe safeguards that have been put in place for responsible release of data or models that have a high risk for misuse (e.g., pretrained language models, image generators, or scraped datasets)?

Answer: [NA]

Justification: the paper poses no such risks.

Guidelines:

- The answer NA means that the paper poses no such risks.
- Released models that have a high risk for misuse or dual-use should be released with necessary safeguards to allow for controlled use of the model, for example by requiring that users adhere to usage guidelines or restrictions to access the model or implementing safety filters.
- Datasets that have been scraped from the Internet could pose safety risks. The authors should describe how they avoided releasing unsafe images.
- We recognize that providing effective safeguards is challenging, and many papers do not require this, but we encourage authors to take this into account and make a best faith effort.

## 12. Licenses for existing assets

Question: Are the creators or original owners of assets (e.g., code, data, models), used in the paper, properly credited and are the license and terms of use explicitly mentioned and properly respected?

Answer: [\[Yes\]](#) All the data in this experiment were collected independently by ourselves, and we also released the data we collected to enhance our contribution to the research field.

Justification: All creators and original owners of assets used in the paper are properly credited, and the license and terms of use are explicitly mentioned and respected, ensuring full compliance with intellectual property rights.

Guidelines:

- The answer NA means that the paper does not use existing assets.
- The authors should cite the original paper that produced the code package or dataset.
- The authors should state which version of the asset is used and, if possible, include a URL.
- The name of the license (e.g., CC-BY 4.0) should be included for each asset.
- For scraped data from a particular source (e.g., website), the copyright and terms of service of that source should be provided.
- If assets are released, the license, copyright information, and terms of use in the package should be provided. For popular datasets, [paperswithcode.com/datasets](https://paperswithcode.com/datasets) has curated licenses for some datasets. Their licensing guide can help determine the license of a dataset.
- For existing datasets that are re-packaged, both the original license and the license of the derived asset (if it has changed) should be provided.
- If this information is not available online, the authors are encouraged to reach out to the asset's creators.

## 13. New Assets

Question: Are new assets introduced in the paper well documented and is the documentation provided alongside the assets?

Answer: [\[Yes\]](#) We release the world's first Chinese handwriting recognition dataset based on inertial sensors, and we confirm to license the use of this data set to all AI researchers around the world.

Justification: It can be found in GitHub.

Guidelines:

- The answer NA means that the paper does not release new assets.
- Researchers should communicate the details of the dataset/code/model as part of their submissions via structured templates. This includes details about training, license, limitations, etc.
- The paper should discuss whether and how consent was obtained from people whose asset is used.
- At submission time, remember to anonymize your assets (if applicable). You can either create an anonymized URL or include an anonymized zip file.

## 14. Crowdsourcing and Research with Human Subjects

Question: For crowdsourcing experiments and research with human subjects, does the paper include the full text of instructions given to participants and screenshots, if applicable, as well as details about compensation (if any)?

Answer: [\[NA\]](#)

Justification: The paper does not involve crowdsourcing nor research with human subjects.

Guidelines:

- The answer NA means that the paper does not involve crowdsourcing nor research with human subjects.

- 918
- 919
- 920
- 921
- 922
- 923
- Including this information in the supplemental material is fine, but if the main contribution of the paper involves human subjects, then as much detail as possible should be included in the main paper.
  - According to the NeurIPS Code of Ethics, workers involved in data collection, curation, or other labor should be paid at least the minimum wage in the country of the data collector.

924

925

15. **Institutional Review Board (IRB) Approvals or Equivalent for Research with Human Subjects**

926

927

928

929

Question: Does the paper describe potential risks incurred by study participants, whether such risks were disclosed to the subjects, and whether Institutional Review Board (IRB) approvals (or an equivalent approval/review based on the requirements of your country or institution) were obtained?

930

Answer: [NA]

931

Justification: The paper does not involve crowdsourcing nor research with human subjects.

932

Guidelines:

- 933
- 934
- 935
- 936
- 937
- 938
- 939
- 940
- 941
- 942
- The answer NA means that the paper does not involve crowdsourcing nor research with human subjects.
  - Depending on the country in which research is conducted, IRB approval (or equivalent) may be required for any human subjects research. If you obtained IRB approval, you should clearly state this in the paper.
  - We recognize that the procedures for this may vary significantly between institutions and locations, and we expect authors to adhere to the NeurIPS Code of Ethics and the guidelines for their institution.
  - For initial submissions, do not include any information that would break anonymity (if applicable), such as the institution conducting the review.