

# Not Everything is All You Need: Toward Low-Redundant Optimization for Large Language Model Alignment

Anonymous EMNLP submission

## Abstract

Large language models (LLMs) are still struggling in aligning with human preference in complex tasks and scenarios. They are prone to overfit into the unexpected patterns or superficial styles in the training data. We conduct an empirical study that only selects the top-10% most updated parameters in LLMs for alignment training, and see improvements in the convergence process and final performance. It indicates the existence of redundant neurons in LLMs for alignment training. To reduce its influence, we propose a low-redundant alignment method named **ALLO**, focusing on optimizing the most related neurons with the most useful supervised signals. Concretely, we first identify the neurons that are related to the human preference data by a gradient-based strategy, then identify the alignment-related key tokens by reward models for computing loss. Besides, we also decompose the alignment process into the forgetting and learning stages, where we first forget the tokens with unaligned knowledge and then learn aligned knowledge, by updating different ratios of neurons, respectively. Experimental results on 10 datasets have shown the effectiveness of ALLO. Our code and data will be publicly released.

## 1 Introduction

Alignment with human preferences has become a desired property of LLMs (Askell et al., 2021; Ouyang et al., 2022), e.g., helpfulness, honesty, and harmlessness, and reinforcement learning from human feedback (RLHF) (Christiano et al., 2017; Zheng et al., 2023) is a crucial technique for achieving it. Typically, RLHF aims to fine-tune LLMs on human preference data, to maximize and minimize the likelihood of generating the positive and negative responses, respectively. After RLHF training on corresponding datasets, LLMs can better follow user instructions (Ouyang et al., 2022), solve complex problems (Wang et al., 2023), and generate unbiased responses (Bai et al., 2022a).

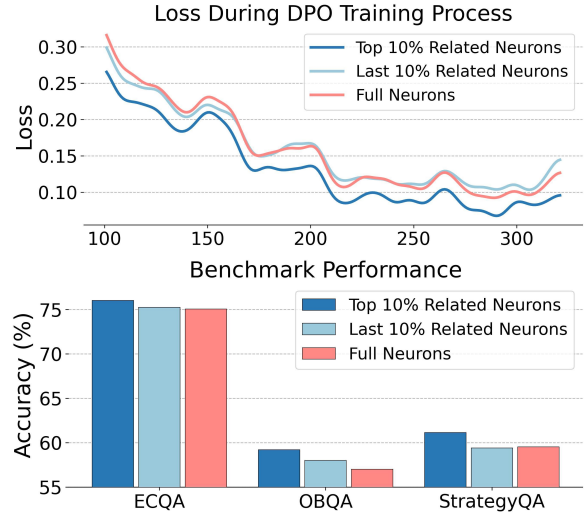


Figure 1: The training loss curve and benchmark performance of training different neurons in LLM on question-answering data using DPO (Rafailov et al., 2023).

However, it is hard to train a well-aligned LLM for complex tasks and scenarios (Feng et al., 2024; Gekhman et al., 2024). The key issue is that LLMs might overfit into the unexpected patterns or superficial styles in the human preference data (Du et al., 2024). It is the side effect of their powerful learning capability derived from the large-scale trainable parameters (Song et al., 2024; Meng et al., 2024a). Recently, a surge of work (Frankle and Carbin, 2019; Wang et al., 2024b) has found that each neuron is relevant with special knowledge, and the neurons in LLMs are generally sparsely activated. Inspired by it, we consider if the full-parameter trained LLMs might lead to *redundant updates* on alignment-irrelevant neurons. Thus, we conduct the empirical experiment using DPO algorithm (Rafailov et al., 2023), where we only update the top/last-10% neurons according to their accumulated gradient values. As shown in Figure 1, with the top-10% trainable neurons, LLMs can converge faster and achieve better performance than optimizing all the neurons. It indicates the

065 existence of redundant updates in DPO training,  
066 affecting the convergence and final performance.

067 To reduce the influence of redundant updates,  
068 we focus on optimizing the most related neurons  
069 with the most useful supervised signals. Concretely,  
070 we first identify the neurons that are related to the  
071 human preference data, based on the accumula-  
072 tion values of gradients. Second, we identify the  
073 key tokens about human preference, and only com-  
074 pute loss on them for optimizing the alignment-  
075 related neurons. In this way, we perform a *two-fold*  
076 *low-redundant optimization* for aligning LLMs  
077 with humans, to reduce the redundancy of learning  
078 irrelevant tokens and training irrelevant neurons.  
079 Whereas, since the alignment training focuses on  
080 both removing the unaligned knowledge and learn-  
081 ing the aligned one, the involved neurons and to-  
082 kens are not always consistent for the two objec-  
083 tives. Therefore, we decompose the alignment pro-  
084 cess into the *forgetting and learning stages*, and  
085 adapt the low-redundant optimization strategy on  
086 them. For the forgetting stage, relatively fewer neu-  
087 rons are trained by unlearning algorithm (Zhang  
088 et al., 2024) to forget the unaligned knowledge,  
089 and we leverage a token-level reward model (Chen  
090 et al., 2024b) to identify the unaligned tokens re-  
091 quired to be focused. For the learning stage, we  
092 train more neurons using the DPO algorithm, and  
093 also utilize its reward score to select the key tokens.

094 In this work, we proposed an **AL**ignment method  
095 with **Low-Redundant Optimization** (ALLO) to fine-  
096 tune LLMs. In ALLO, we first identify the most im-  
097 portant neurons based on the accumulation of gra-  
098 dients from a reference model. Then, we design the  
099 forgetting and learning stages, where we adopt the  
100 token-level reward model and the DPO reward func-  
101 tion to select the key tokens, for computing loss  
102 to update different ratio of the important neurons  
103 (*e.g.*, top-5% and 10%), respectively. In this way,  
104 we only perform optimization on sparse tokens and  
105 neurons, greatly reducing the redundancy during  
106 LLM alignment training. To comprehensively as-  
107 sess the effectiveness of ALLO, we conduct exten-  
108 sive experiments on three downstream scenarios,  
109 *i.e.*, question answering, mathematical reasoning,  
110 and instruction following, totally 10 datasets. Ex-  
111 periment results have shown that ALLO mostly out-  
112 performs competitive human alignment methods  
113 (*e.g.*, SFT (Ouyang et al., 2022), DPO (Rafailov  
114 et al., 2023), PPO (Schulman et al., 2017)).

## 2 Related Work 115

**Large Language Models.** LLMs have shown re- 116  
markable performance on various tasks (qwe, 2024; 117  
Meta, 2024; Javaheripi et al., 2023). Generally, the 118  
training process of LLMs includes three stages, 119  
*i.e.*, pre-training, supervised fine-tuning (SFT), and 120  
alignment (Ouyang et al., 2022; Touvron et al., 121  
2023). In the training process, previous work has 122  
selected valuable data to train the LLMs via lever- 123  
aging gradient (Xia et al., 2024) or perplexity (Lin 124  
et al., 2024; Xie et al., 2023). Besides, synthetic 125  
training data from powerful LLMs (*e.g.*, GPT-4, 126  
Claude 3) has been widely utilized for improv- 127  
ing the weak LLMs (Xu et al., 2023; Ben Allal 128  
et al., 2024; Liu et al., 2024), especially for spec- 129  
ific scenarios (*e.g.*, mathematical tasks or code 130  
synthesis tasks) (Yue et al., 2023; Zhou et al., 2024; 131  
Wei et al., 2023). However, given the large ex- 132  
penses of the LLM training, existing work (Hu 133  
et al., 2022; Li and Liang, 2021; Dettmers et al., 134  
2023) has revealed that training only a small num- 135  
ber of the parameters can achieve comparable per- 136  
formance with whole-parameters training. In this 137  
work, we focus on the alignment stage and lever- 138  
age the low-redundant optimization to improve the 139  
existing LLMs. 140

**LLMs Alignment.** RLHF is a critical algorithm 141  
of LLM alignment (Christiano et al., 2017), usu- 142  
ally leveraged to reduce hallucination (Chaudhari 143  
et al., 2024) or further enhance the capacities of 144  
LLMs (Chen et al., 2024b; Wang et al., 2023; 145  
Luo et al., 2023). Typically, a reward model will 146  
be trained on the preference data and leveraged 147  
to guide the reinforcement learning (RL) proce- 148  
dure (Ouyang et al., 2022; Touvron et al., 2023; 149  
Zheng et al., 2023). Proximal policy optimization 150  
(PPO) has been widely adopted in RLHF (Mnih 151  
et al., 2016; Zheng et al., 2023). Given the effi- 152  
ciency and expenses of the annotating process by 153  
human labeler, previous work has utilized the feed- 154  
back from LLMs to instruct the RL process, named 155  
RLAIF (Bai et al., 2022b; Yuan et al., 2024). Fur- 156  
thermore, to prevent the instability of RL, a series 157  
of work (Park et al., 2024; Hong et al., 2024; Meng 158  
et al., 2024b) utilized a similar objective function 159  
with SFT to model human preference. Direct pref- 160  
erence optimization (DPO) (Rafailov et al., 2023) 161  
is representative work of non-RL alignment. In 162  
this work, we consider about how to unleash the 163  
potential of the non-RL method. 164

**Unlearning of LLMs.** Machine unlearning (Cao and Yang, 2015; Bourtole et al., 2019; Wang et al., 2024a; Chen et al., 2024a) is an important technique for artificial intelligence systems to remove the knowledge about the restricted data (e.g., unauthorized books), while keeping other knowledge and abilities of the systems. To perform unlearning of LLMs, research has proposed several methods (e.g., Gradient Ascent (Yao et al., 2023; Maini et al., 2024) and NPO (Zhang et al., 2024)), directly training LLMs on the invalid dataset to make LLMs forget relative knowledge. Following the unlearning mechanism, in this work, we utilize an unlearning algorithm to correct the unaligned knowledge stored in the neurons of LLMs.

### 3 Preliminary

LLMs alignment refers to aligning the behaviors of LLMs to human preference, e.g., helpfulness, honesty, and harmlessness (Askell et al., 2021). Existing work typically utilizes RLHF methods (Christiano et al., 2017) to fine-tune LLMs using human preference data, for improving alignment. Formally, the human preference data is composed by input prompts, positive responses, and negative responses, denoted as  $\mathcal{D} = \{(x_i, y_i^+, y_i^-)\}_{i=1}^n$ . The input prompt or response consists of a series of natural language tokens  $\{t_1, t_2, \dots, t_l\}$ . Given the input prompt  $x$ , we aim to train LLMs that tend to generate the well-aligned positive response  $y^+$ , while avoiding generating the unaligned negative one  $y^-$ . In this work, we focus on devising an effective training algorithm to improve the alignment of LLMs, which can be utilized to satisfy the diverse requirements in real world (e.g., instruction following and question answering).

According to our empirical study in Figure 1, updating only top-10% trainable neurons would achieve better performance than full-parameter tuning for alignment training. It indicates that there are redundant updates in the training process of LLMs, which may affect the alignment performance. To address it, in this work, we aim to perform parameter-efficient fine-tuning for reducing the redundant updates on unrelated neurons, to improve the alignment of LLMs. Given the training data, we first identify the highly-relevant neurons  $\mathcal{N} = \{\theta_{i_1}, \dots, \theta_{i_k}\}$  in the parameter matrices of LLMs, and perform low-redundant optimization on

the LLM as:

$$\theta_i^{t+1} = \begin{cases} \text{Optimizer}(\theta_j^t, \nabla \theta_j^t), & \theta_j \in \mathcal{N} \\ \theta_j^t, & \theta_j \notin \mathcal{N} \end{cases}, \quad (1)$$

where  $\theta_j^t$  means the value of  $j$ -th neuron at the  $t$ -th step of training process,  $\nabla \theta_j$  is the calculated gradient of  $j$ -th neuron for update.

## 4 Approach

In this section, we introduce our proposed method ALLO, a low-redundant alignment method for fine-tuning LLMs. In ALLO, we compute loss on selected key tokens, and perform sparse neuron optimization. Concretely, we first train a reference model to locate the important neurons through gradient. Then, we identify the key tokens related to unaligned knowledge, and utilize the unlearning algorithm to update few neurons for forgetting them. Next, we leverage DPO algorithm to improve the alignment of the LLM, where the DPO reward is used for selecting the key tokens. The framework of ALLO is presented in Figure 2.

### 4.1 Locating Key Neurons

We compute the importance of all the neurons for the human preference data to locate the related key neurons. We first train a reference model on the given data using DPO algorithm, and then design an efficient approximate estimation of the neuron importance based on its updated weights.

**Training Reference Model.** We train the reference model on the human preference data, to obtain the updated values of all neurons for importance estimation. Thus, we select the same LLM as the backbone, and perform full-parameter fine-tuning using DPO algorithm on the entire dataset for one epoch. The training objective is:

$$\mathcal{L}(d_i) = -\log \sigma \left( \beta \log \frac{P(y_i^+ | x_i)}{P_{\text{ref}}(y_i^+ | x_i)} - \beta \log \frac{P(y_i^- | x_i)}{P_{\text{ref}}(y_i^- | x_i)} \right), \quad (2)$$

where  $\beta$  is a hyper-parameter, and  $d_i = \langle x_i, y_i^+, y_i^- \rangle$  is a training instance. For the scenarios that only one human feedback is provided, we regard it as the positive one, and leverage the response generated from LLM as the negative one.

**Neurons Importance Estimation.** We aim to estimate the importance of each neuron for the given human preference dataset  $\mathcal{D}$ . As LLMs are generally trained by gradient descent algorithm, the

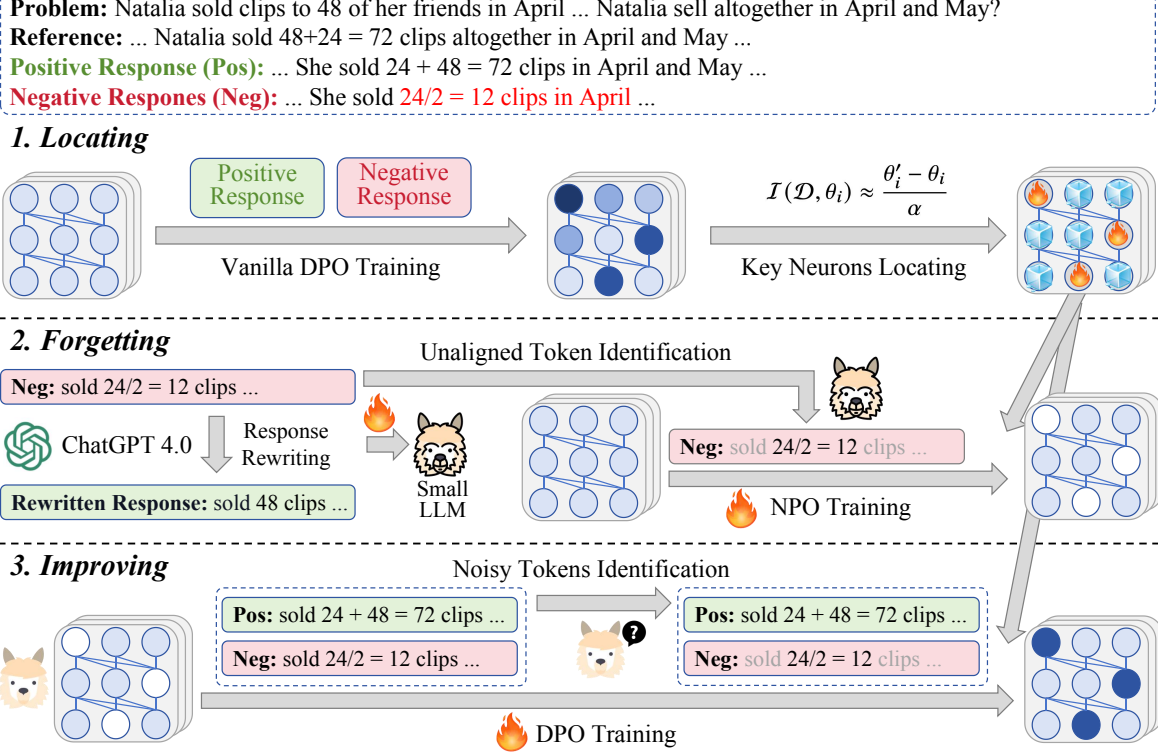


Figure 2: The framework of our proposed alignment method ALLO. We first locate the key neurons in LLMs by computing the weight changes of the reference model. Then, based on the selected key neurons, we perform a fine-grained unlearning using NPO to help LLMs forget unaligned knowledge, and fine-grained learning using DPO to further align LLMs to human preference.

256 gradient value of a training instance  $d_j$  on the neu- 257  
 258 ron  $\theta_i$  can reflect its influence on the neuron (Pruthi  
 et al., 2020; Xia et al., 2024), denoted as:

$$259 \text{Influence}(d_j, \theta_i) \propto \nabla_{\theta_i} \mathcal{L}(d_j) \quad (3)$$

260 For human alignment, we use the DPO training loss 261  
 262 in Eq. 2 for influence estimation. In this way, we 263  
 264 can accumulate the gradients for all the instances 265  
 266 from the human preference dataset, to estimate the 267  
 268 influence of the dataset on the neuron. Actually, 269  
 270 the influence value also reflects the importance of 271  
 272 the neuron for learning the dataset, as a large ac- 273  
 274 cumulated gradient value can denote more focus 275  
 276 on training the neuron (Pruthi et al., 2020). As we  
 adopt the gradient descent algorithm, the gradients  
 for all the instances have been computed and sub-  
 tracted in the one-epoch training process. Thus,  
 the difference between the neuron in the reference  
 model  $\theta'_i$  and original model  $\theta_i$  can be regarded as  
 the approximate value of the estimated importance  
 score:

$$276 I(\mathcal{D}, \theta_i) = \sum_{j=1}^{|\mathcal{D}|} \nabla_{\theta_i} \mathcal{L}(d_j) \approx \frac{\theta'_i - \theta_i}{\alpha}, \quad (4)$$

277 where  $\alpha$  is the learning rate during DPO training. 278  
 279 Based on the estimated importance score, we can 280  
 281 rank all the neurons and select the most important  
 ones for training.

## 4.2 Unaligned Knowledge Forgetting 281

282 For the forgetting stage, we utilize a token-level 283  
 284 reward model that guides LLMs to focus on the 285  
 286 tokens related to unaligned knowledge, and adopt  
 a machine unlearning algorithm, *i.e.*, NPO (Zhang  
 et al., 2024) that learns to forget them.

287 **Unalignment-Related Tokens Identification.** We 288  
 289 train a token-level reward model to score tokens 290  
 291 in the negative responses, according to their effect 292  
 293 on unalignment. Following existing work (Chen 294  
 295 et al., 2024b), we distill the capability of a strong 296  
 297 LLM (*i.e.*, GPT-4 (OpenAI, 2023)) to revise the  
 unaligned response (to a well-aligned one) with  
 minimum editing constraint, into a small LLM. Then,  
 we can utilize its output revision probability for  
 each token, to compute the reward score as:

$$297 r_{i,j} = \begin{cases} 1, & P_{re}(y_{i,j}|p_i, x_i, y_i^+, y_{i,<j}^-) < u \\ 0, & \text{others} \end{cases}, \quad (5)$$

where  $p_i$  is the prompt to guide the reward model,  $y_{i,j}$  is the  $j$ -th token in the negative response  $y_i^-$ ,  $u$  is a hyper-parameter to control the threshold. In this way, we can select the key tokens about the unalignment according to the 0-1 reward score.

**Fine-grained Unlearning with NPO.** Based on the selected unalignment-related key tokens, we perform unlearning to remove the unaligned knowledge in the LLM and unleash the potential of learning aligned knowledge. Concretely, we utilize the NPO method, which is the revision based on DPO and only focuses on minimizing the likelihood of generating negative responses. The objective function of NPO is as follows,

$$\mathcal{L}_{NPO}(\theta) = \log \sigma \left( -\beta \log \frac{P(y_i^- | x_i)}{P_{\text{ref}}(y_i^- | x_i)} \right). \quad (6)$$

Whereas, the NPO loss would also punish the tokens that are irrelevant to the unalignment but exist in the negative response. To address it, we constrain that only the key tokens are involved into loss computation, to avoid unlearning the irrelevant tokens. Formally, we decompose the objective into the token level, and add the 0-1 reward score as the token weights. Thus, the objective function can be revised as follows, and we only optimize the top- $k_1\%$  most important neurons, denoted as  $\mathcal{N}_1$ ,

$$\mathcal{L}_N(\mathcal{N}_1) = - \sum_{j=1}^{l_i} \log \sigma \left( -\beta \log \frac{P(y_{i,j}^- | x_i, y_{i,<j}^-)}{P_{\text{ref}}(y_{i,j}^- | x_i, y_{i,<j}^-)} \times r_{i,j} \right). \quad (7)$$

### 4.3 Alignment Improving

For the learning stage, we further improve the alignment of the LLM that has unlearned the unaligned knowledge. We adopt DPO (Rafailov et al., 2023) algorithm for training, and also leverage its computed reward score to distinguish the key tokens and noisy ones.

**Noisy Tokens Identification.** We also identify the noisy tokens in the negative responses using the reward score in DPO, for reducing their harmful influence on learning other key tokens. As DPO requires to compare the token probabilities of the current-step LLM and its original probability, the reward of the key tokens initially own small values and increase smoothly. However, the noisy ones typically lead to large reward values, and shock the training process (Chen et al., 2019). Therefore, we can utilize the reward scores dynamically computed

Task	Train / Test	Dataset	Num. Data
Math	Train	MetaMathQA	40,000
		GSM8k	1,319
	Test	MATH	5,000
		MAWPS	2,065
QA	Train	ECQA	7,598
		QASC	8,134
	Test	ECQA	2,194
		QASC	926
		OBQA	500
IF	Train	UltraFeedback	23,976
		AlpacaEval 2.0	805
	Test	Arena-Hard	500

Table 1: Statistics of the used datasets. ‘‘IF’’ denotes the instruction following tasks.

in the DPO process, to distinguish the key and noisy tokens, denoted as:

$$q_{i,j} = \begin{cases} 0, & r'_{i,j} \in \text{top } v\% \\ 1, & \text{others} \end{cases}, \quad r'_{i,j} = \frac{P(y_{i,j}^- | x_i, y_{i,<j}^-)}{P_{\text{ref}}(y_{i,j}^- | x_i, y_{i,<j}^-)}, \quad (8)$$

where  $v\%$  is the hyper-parameter to control the threshold. In this way, we can identify the noisy tokens causing abnormal large rewards with weight 0, and key tokens with weight 1.

**Fine-grained Learning with DPO.** After obtaining the token weights, we also decompose the objective function of DPO into the token level, and add weights into the tokens from the negative response to provide fine-grained supervision. Formally, the revised objective function is as follows:

$$\mathcal{L}_D(\mathcal{N}_2) = - \log \sigma \left( \beta \sum_{j=1}^{l_i^+} \log \frac{P(y_{i,j}^+ | x_i, y_{i,<j}^+)}{P_{\text{ref}}(y_{i,j}^+ | x_i, y_{i,<j}^+)} - \beta \sum_{j=1}^{l_i^-} \log \frac{P(y_{i,j}^- | x_i, y_{i,<j}^-)}{P_{\text{ref}}(y_{i,j}^- | x_i, y_{i,<j}^-)} \times q_{i,j} \right), \quad (9)$$

where we only optimize the top- $k_2\%$  most important neurons, denoted as  $\mathcal{N}_2$ .

## 5 Experiment

### 5.1 Experimental Settings

In this section, we introduce the details of our evaluation process, including downstream datasets, baselines in the evaluation, and the implementation details of our proposed method.

**Datasets.** We conduct the three downstream scenarios for the comprehensive evaluation, *i.e.*, question-

Methods	Question-Answering Tasks					Mathematical Reasoning Tasks				
	ECQA	QASC	OBQA	StrategyQA	Avg.	GSM8k	MATH	MAWPS	TabMWP	Avg.
SFT LLM	69.92	55.51	52.60	55.75	58.45	55.9	11.8	79.9	56.7	51.1
+ SFT	69.14	55.40	49.80	59.24	58.40	56.2	11.8	80.0	57.4	51.4
+ RFT	71.15	57.24	54.40	56.33	59.78	54.7	12.0	80.2	55.2	50.5
+ DPO	75.07	60.37	57.00	59.53	62.99	56.6	12.2	81.7	57.3	52.0
+ R-DPO	<u>75.52</u>	<u>61.56</u>	<u>58.40</u>	<u>59.83</u>	<u>63.83</u>	56.9	12.3	82.3	57.2	52.2
+ IPO	47.86	43.20	41.80	43.38	44.06	<b>58.0</b>	<u>12.9</u>	<u>82.4</u>	55.5	52.2
+ BCO	68.87	55.18	45.40	57.21	56.67	57.2	12.4	81.8	56.3	51.9
+ SimPO	62.76	52.27	46.80	53.71	53.89	<u>57.9</u>	12.8	82.1	56.7	<u>52.4</u>
+ NPO	70.56	56.59	52.80	56.04	59.00	56.4	12.3	80.1	56.5	51.3
+ Vanilla PPO	70.65	55.29	53.40	56.33	58.92	55.2	11.6	79.4	56.5	50.7
+ PPO A2C	71.06	55.18	53.00	58.37	59.40	55.2	11.7	82.1	55.8	51.2
+ ALLO	<b>75.93</b>	<b>62.31</b>	<b>59.60</b>	<b>60.84</b>	<b>64.67</b>	56.6	<b>13.0</b>	<b>82.5</b>	<b>58.1</b>	<b>52.6</b>

Table 2: Experimental results on question answering tasks and mathematical reasoning tasks. Avg. is the average accuracy of all sub-tasks. The best is denoted in bold and the second best is underlined.

Methods	Instruction Following Tasks		
	AlpacaEval 2.0	Arena-Hard	Avg.
SFT LLM	50.00	50.00	50.00
+ SFT	49.44	61.50	55.47
+ RFT	50.06	53.70	51.88
+ DPO	53.80	68.30	61.05
+ R-DPO	54.00	<u>72.20</u>	63.10
+ IPO	<u>56.35</u>	71.00	63.68
+ BCO	<u>54.79</u>	71.80	63.30
+ SimPO	54.92	69.30	62.11
+ NPO	50.06	51.10	50.58
+ Vanilla PPO	48.75	48.20	48.48
+ PPO A2C	53.50	57.80	55.65
+ ALLO	<u>55.78</u>	<b>74.90</b>	<b>65.34</b>

Table 3: Experimental results on instruction following tasks. Avg. is the average win rate of all sub-tasks. The best are denoted in bold and the second-best are underlined.

answering (QA), mathematical reasoning, and instruction following. The statistics information of each task is presented in Table 1.

- *QA tasks* require LLMs to perform multi-step reasoning to solve problems. We adopt ECQA (Aggarwal et al., 2021), QASC (Khot et al., 2020), OpenbookQA (Mihaylov et al., 2018), and StrategyQA (Geva et al., 2021) as the evaluation tasks. LLMs are fine-tuned on the training set of ECQA and QASC to adapt to the QA tasks.

- *Mathematica reasoning tasks* include four challenge tasks, *i.e.*, GSM8k (Cobbe et al., 2021), MATH (Hendrycks et al., 2021), MAWPS (Koncel-Kedziorski et al., 2016), and TabMWP (Lu et al., 2023), containing problems with different levels

of difficulty. To complete the mathematical knowledge and ability of LLMs, MetaMathQA (Yu et al., 2023) has been utilized to fine-tune the LLMs.

- *Instruction following tasks* assess the capacity of LLMs to follow human instructions. AlpacaEval 2.0 (Li et al., 2023) and Arena-Hard (Tianle Li\*, 2024) are considered as the downstream tasks. We adopt the alpaca dataset (Taori et al., 2023) to fine-tune the base LLMs and UltraFeedback dataset (Cui et al., 2023) for the further training process (*e.g.*, DPO, ALLO).

For QA tasks and mathematical tasks, accuracy has been adopted as the evaluation metric. For the instruction following tasks, we employ gpt-3.5-turbo as the judge model and report the win rate over the backbone model (*i.e.*, SFT LLM).

**Baselines.** We incorporate three categories of methods in the evaluation, including supervised fine-tuning (*i.e.*, SFT (Ouyang et al., 2022) and RFT (Liu et al., 2023)), reinforcement learning (*i.e.*, Vanilla PPO (Schulman et al., 2017) and PPO A2C (Mnih et al., 2016)), and alignment without RL (*i.e.*, DPO (Rafailov et al., 2023), R-DPO (Park et al., 2024), IPO (Azar et al., 2024), BCO (Jung et al., 2024), SimPO (Meng et al., 2024b), and NPO (Zhang et al., 2024)).

**Implementation Details.** In the experiment, we fine-tune LLaMA 2 7B (Touvron et al., 2023) on instruction datasets corresponding to the downstream scenarios to obtain the backbone model (*i.e.*, SFT LLM), and conduct further training processes based on this model in the evaluation. The details of hyper-parameters are presented in Table 5.

Forgetting Stage		Learning Stage		QASC	OBQA	MATH	MAWPS	AlpacaEval 2.0	Arena-Hard
TLR	Mask	TLR	Mask	Acc. (%)	Acc. (%)	Acc. (%)	Acc. (%)	WR (%)	WR (%)
✓	Top-k	✓	Top-k	62.31	59.60	13.0	82.5	55.78	74.90
✓	Top-k	✗	Top-k	62.42	59.00	12.4	82.5	55.60	75.10
✗	Top-k	✓	Top-k	61.56	58.20	12.7	82.3	55.47	73.20
✓	✗	✓	Top-k	61.77	58.80	13.1	82.4	55.22	73.20
✓	Top-k	✓	✗	61.66	58.20	12.7	81.7	53.98	69.70
✓	Last-k	✓	Top-k	62.20	59.40	12.5	82.5	55.29	70.80
✓	Top-k	✓	Last-k	61.77	59.00	10.2	70.9	51.74	61.20
-	-	✓	Top-k	62.20	59.20	12.3	82.2	55.60	72.60
✓	Top-k	-	-	56.16	53.20	11.8	79.9	51.37	50.20

Table 4: The results of ablation study. “Acc.” and “WR” denote accuracy and win rate, respectively. “TLR” denotes the whether adopting token-level rewards in each stage. “Mask” indicates the neuron masking mechanism.

## 5.2 Main Results

The results of ALLO and baseline approaches in our evaluation are presented in Table 2 and Table 3.

According to the evaluation, we can observe that ALLO outperforms other baselines in almost all downstream scenarios and makes a great improvement over NPO and DPO, which are the backbone methods of ALLO. That is because ALLO makes great efforts to reduce the redundant elements in the alignment process, including neurons in LLMs and tokens in training data. Experimental results have shown the effectiveness of ALLO.

Besides, comparing the performance between the algorithm with fine-grained supervision signals (*e.g.*, ALLO, PPO A2C) and the algorithm without them (*e.g.*, DPO, Vanilla PPO), the effectiveness of the fine-grained supervision signals has been verified. Specifically, PPO A2C has achieved a 55.65% average win rate in instruction following tasks, while Vanilla PPO only achieved 48.48%. Instance-level supervision cannot focus on the details in the training data, which will optimize the erroneous parts and hurt the performance of the training methods. In contrast, token-level supervision signals can better identify whether the token is worthy to be learned, which reduces the redundancy of training content.

Moreover, the improvement brought by the unlearning method (*i.e.*, NPO) has demonstrated that aligned and unaligned knowledge are both stored in LLMs. In the training process of NPO, the LLMs are not exposed to new knowledge and new capacities, and only are guided to forget the unaligned knowledge. This phenomenon further verifies the importance of the unlearning stage and the existence of redundant neurons in LLMs. Without the

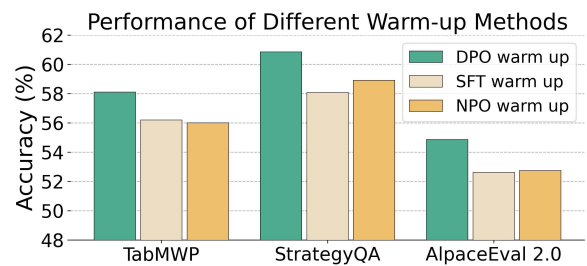


Figure 3: The experimental results of the influence of different warm-up methods on downstream tasks.

redundant neurons, is difficult of LLMs to learn both aligned and unaligned knowledge simultaneously.

Finally, we can observe that ALLO outperforms DPO and its various (*e.g.*, R-DPO, SimPO) in all downstream scenarios, especially in the instruction following tasks. This is because DPO and its various guide LLMs to learn the positive and negative instances simultaneously, which will make LLMs confused about the aligned components in the negative instances. In contrast, ALLO first utilizes the unlearning process to lose the probability distribution in LLMs and leverage the fine-grained supervision signals to indicate the redundant tokens in the training data, to enhance the training efficiency.

## 5.3 Detailed Analysis

To further analyze our proposed ALLO, we conduct the ablation study, and analyze the influence of different warm-up methods and neuron mask ratio. Besides, we present a case study in Appendix D.

**Ablation Study.** To assess the effectiveness of each module in ALLO, we conduct the ablation study and present the evaluation results in Table 4.

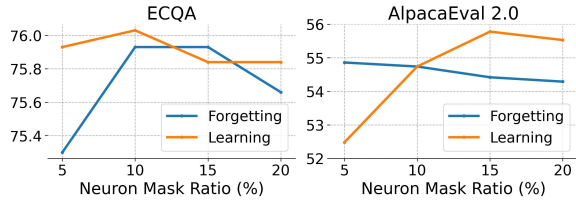


Figure 4: The experimental results of the different neuron mask ratios on ECQA and AlpacaEval 2.0, reporting the accuracy and win rate respectively. In the evaluation, we keep the mask ratio of one stage frozen and change the ratio of another stage.

According to the results, we can observe that removing any component of ALLO will hurt the performance, which has verified each module in ALLO is necessary and contributes to the final results of ALLO. Besides, in QA tasks, the results of removing the neuron mask and adopting the Last-k neuron mask indicate the existence of redundant neurons in LLMs, which is the same as our empirical study. For details, even adopting the Last-k neuron mask in Stage 2 (e.g., 59.00% accuracy of OBQA) outperforms the variant without neuron masking (e.g., 58.20% accuracy of OBQA). That is because training the whole neurons in LLMs will decrease the training efficiency, and redundant updates affect the performance of downstream tasks. Moreover, without the forgetting stage, ALLO still performs better than DPO in most tasks. The reason is that the token-level reward and the neuron masking mechanism reduce the redundancy and make the training process focus on effective details in the training instances, making better utilization of the information in the dataset.

**Influence of Different Warm-up Methods.** To assess the influence of different warm-up methods (i.e., DPO, SFT, and NPO), we conduct the relative experiment and present the results in Figure 3. In all of the evaluation tasks, leveraging DPO to warm up LLMs and select important neurons has achieved the best performance that other warm-up methods. Whether SFT or NPO, these training methods only utilize a single part of the training dataset, i.e., the positive responses or the negative responses, respectively. However, positive responses indicate the knowledge that LLMs should possess, and negative responses can locate unaligned knowledge stored in LLMs. These responses are both important and necessary in selecting the key neurons for the corresponding scenario. DPO can leverage the information in this data and

guide LLMs to learn the aligned knowledge and eliminate unaligned one. In this warm-up process, the neurons related to downstream tasks will be modified largely, causing the large value of the gradient, which can more precisely locate the important neurons for the following training process.

**Analysis the Ratio of Neuron Mask.** We present the results of different ratios of neuron masks on the QA task (i.e., ECQA) and the instruction following task (i.e., AlpacaEval 2.0) in Figure 4. According to the evaluation results, we can observe that the performance first increases and then decreases, with the change of the neuron mask ratio. Concretely, for the ECQA task, selecting 10% neurons in the learning stage achieves the best performance, while selecting fewer or more neurons will hurt the accuracy of LLMs on downstream tasks. The increasing stage indicates that there are still several important neurons not been selected, which affects LLMs learning task-specific knowledge and abilities. After the increasing stage, the selected neurons set  $\mathcal{N}$  contains more and more redundant neurons, interfering the learning process of other neurons and hurting the performance of the LLMs. The evaluation results have verified the existence of redundant updates in LLM alignment and shown that training an appropriate amount of neurons can reduce the redundancy and enhance the performance of LLMs.

## 6 Conclusion

In this paper, we proposed ALLO, an alignment method with low-redundant optimization, to train the most related neurons with the most useful supervised signals. In ALLO, we first estimated the importance of neurons in the LLM based on the weight changes of a reference model, and located the most related neurons for optimization. Then, we decomposed the alignment process into the forgetting and learning stages, where we leveraged token-level reward and DPO reward scores to identify the key tokens, and computing loss on them for training. Experimental results on question-answering tasks, mathematical reasoning tasks, and instruction following tasks have shown the effectiveness of ALLO.

As future work, we will consider leveraging ALLO on other important scenarios, e.g., reducing hallucination. Besides, we will also implement ALLO in larger LLMs and multimodal LLMs to validate its effectiveness.



## 563 Limitations

564 In this section, we discuss the limitations of our  
565 work. First, we only conduct the experiment of  
566 ALLO on 7B LLMs, with the evaluation of the  
567 LLMs with larger scaling of parameters, because  
568 of the limitation of computation resources. Actu-  
569 ally, we comprehensively assess the performance  
570 of ALLO and the existing competitive baseline  
571 methods in various downstream tasks, and the ex-  
572 periment results have verified the effectiveness of  
573 our proposed methods. Second, we adopt com-  
574 plex reasoning and human alignment tasks in our  
575 evaluation, which mainly assess the helpfulness of  
576 LLMs. The performance of ALLO on other as-  
577 pects, *e.g.*, reducing hallucination and generating  
578 harmless response, has not been verified in this  
579 work. We leave it as future work. Finally, we do  
580 not consider the potential risk of ethics risk during  
581 LLM deployment and will investigate this issue in  
582 the future.

## 583 References

584 2024. Qwen2 technical report.

585 Shourya Aggarwal, Divyanshu Mandowara, Vishwajeet  
586 Agrawal, Dinesh Khandelwal, Parag Singla, and Di-  
587 nesh Garg. 2021. Explanations for commonsenseqa:  
588 New dataset and models. In *Proceedings of the 59th*  
589 *Annual Meeting of the Association for Computational*  
590 *Linguistics and the 11th International Joint Confer-*  
591 *ence on Natural Language Processing, ACL/IJCNLP*  
592 *2021, (Volume 1: Long Papers), Virtual Event, Au-*  
593 *gust 1-6, 2021*, pages 3050–3065.

594 Amanda Askell, Yuntao Bai, Anna Chen, Dawn Drain,  
595 Deep Ganguli, Tom Henighan, Andy Jones, Nicholas  
596 Joseph, Benjamin Mann, Nova DasSarma, Nelson  
597 Elhage, Zac Hatfield-Dodds, Danny Hernandez, Jack-  
598 son Kernion, Kamal Ndousse, Catherine Olsson,  
599 Dario Amodei, Tom B. Brown, Jack Clark, Sam Mc-  
600 Candlish, Chris Olah, and Jared Kaplan. 2021. A  
601 general language assistant as a laboratory for align-  
602 ment. *CoRR*, abs/2112.00861.

603 Mohammad Gheshlaghi Azar, Zhaohan Daniel Guo, Bi-  
604 lal Piot, Rémi Munos, Mark Rowland, Michal Valko,  
605 and Daniele Calandriello. 2024. A general theoret-  
606 ical paradigm to understand learning from human  
607 preferences. In *International Conference on Artifi-*  
608 *cial Intelligence and Statistics, 2-4 May 2024, Palau*  
609 *de Congressos, Valencia, Spain*, volume 238, pages  
610 4447–4455.

611 Yuntao Bai, Andy Jones, Kamal Ndousse, Amanda  
612 Askell, Anna Chen, Nova DasSarma, Dawn Drain,  
613 Stanislav Fort, Deep Ganguli, Tom Henighan,  
614 Nicholas Joseph, Saurav Kadavath, Jackson Kernion,

Tom Conerly, Sheer El Showk, Nelson Elhage, Zac  
Hatfield-Dodds, Danny Hernandez, Tristan Hume,  
Scott Johnston, Shauna Kravec, Liane Lovitt, Neel  
Nanda, Catherine Olsson, Dario Amodei, Tom B.  
Brown, Jack Clark, Sam McCandlish, Chris Olah,  
Benjamin Mann, and Jared Kaplan. 2022a. Train-  
ing a helpful and harmless assistant with rein-  
forcement learning from human feedback. *CoRR*,  
abs/2204.05862.

Yuntao Bai, Saurav Kadavath, Sandipan Kundu,  
Amanda Askell, Jackson Kernion, Andy Jones, Anna  
Chen, Anna Goldie, Azalia Mirhoseini, Cameron  
McKinnon, Carol Chen, Catherine Olsson, Christo-  
pher Olah, Danny Hernandez, Dawn Drain, Deep  
Ganguli, Dustin Li, Eli Tran-Johnson, Ethan Perez,  
Jamie Kerr, Jared Mueller, Jeffrey Ladish, Joshua  
Landau, Kamal Ndousse, Kamile Lukosiute, Liane  
Lovitt, Michael Sellitto, Nelson Elhage, Nicholas  
Schiefer, Noemí Mercado, Nova DasSarma, Robert  
Lasenby, Robin Larson, Sam Ringer, Scott John-  
ston, Shauna Kravec, Sheer El Showk, Stanislav  
Fort, Tamera Lanham, Timothy Telleen-Lawton, Tom  
Conerly, Tom Henighan, Tristan Hume, Samuel R.  
Bowman, Zac Hatfield-Dodds, Ben Mann, Dario  
Amodei, Nicholas Joseph, Sam McCandlish, Tom  
Brown, and Jared Kaplan. 2022b. Constitutional  
AI: harmfulness from AI feedback. *arXiv preprint*  
*arXiv:2212.08073*.

Loubna Ben Allal, Anton Lozhkov, Guilherme Penedo,  
Thomas Wolf, and Leandro von Werra. 2024. *Cos-*  
*mopedia*.

Lucas Bourtole, Varun Chandrasekaran, Christopher A.  
Choquette-Choo, Hengrui Jia, Adelin Travers, Baiwu  
Zhang, David Lie, and Nicolas Papernot. 2019. Ma-  
chine unlearning. *CoRR*, abs/1912.03817.

Yinzhi Cao and Junfeng Yang. 2015. Towards making  
systems forget with machine unlearning. In *2015*  
*IEEE Symposium on Security and Privacy, SP 2015,*  
*San Jose, CA, USA, May 17-21, 2015*, pages 463–480.  
IEEE Computer Society.

Shreyas Chaudhari, Pranjal Aggarwal, Vishvak Mura-  
hari, Tanmay Rajpurohit, Ashwin Kalyan, Karthik  
Narasimhan, Ameet Deshpande, and Bruno Castro  
da Silva. 2024. RLHF deciphered: A critical analysis  
of reinforcement learning from human feedback for  
llms. *CoRR*, abs/2404.08555.

Kongyang Chen, Zixin Wang, Bing Mi, Waixi Liu,  
Shaowei Wang, Xiaojun Ren, and Jiaying Shen.  
2024a. Machine unlearning in large language models.  
*CoRR*, abs/2404.16841.

Minmin Chen, Alex Beutel, Paul Covington, Sagar Jain,  
Francois Belletti, and Ed H. Chi. 2019. Top-k off-  
policy correction for a REINFORCE recommender  
system. In *Proceedings of the Twelfth ACM Interna-*  
*tional Conference on Web Search and Data Mining,*  
*WSDM 2019, Melbourne, VIC, Australia, February*  
*11-15, 2019*, pages 456–464.

672	Zipeng Chen, Kun Zhou, Wayne Xin Zhao, Junchen Wan, Fuzheng Zhang, Di Zhang, and Ji-Rong Wen. 2024b. Improving large language models via fine-grained reinforcement learning with minimum editing constraint. <i>CoRR</i> , abs/2401.06081.	<i>of the Neural Information Processing Systems Track on Datasets and Benchmarks 1, NeurIPS Datasets and Benchmarks 2021, December 2021, virtual.</i>	728 729 730
677	Paul F. Christiano, Jan Leike, Tom B. Brown, Miljan Martic, Shane Legg, and Dario Amodei. 2017. Deep reinforcement learning from human preferences. In <i>Advances in Neural Information Processing Systems 30: Annual Conference on Neural Information Processing Systems 2017, December 4-9, 2017, Long Beach, CA, USA</i> , pages 4299–4307.	Jiwoo Hong, Noah Lee, and James Thorne. 2024. ORPO: monolithic preference optimization without reference model. <i>CoRR</i> , abs/2403.07691.	731 732 733
684	Karl Cobbe, Vineet Kosaraju, Mohammad Bavarian, Mark Chen, Heewoo Jun, Lukasz Kaiser, Matthias Plappert, Jerry Tworek, Jacob Hilton, Reiichiro Nakano, Christopher Hesse, and John Schulman. 2021. Training verifiers to solve math word problems. <i>CoRR</i> , abs/2110.14168.	Edward J. Hu, Yelong Shen, Phillip Wallis, Zeyuan Allen-Zhu, Yuanzhi Li, Shean Wang, Lu Wang, and Weizhu Chen. 2022. Lora: Low-rank adaptation of large language models. In <i>The Tenth International Conference on Learning Representations, ICLR 2022, Virtual Event, April 25-29, 2022</i> . OpenReview.net.	734 735 736 737 738 739
690	Ganqu Cui, Lifan Yuan, Ning Ding, Guanming Yao, Wei Zhu, Yuan Ni, Guotong Xie, Zhiyuan Liu, and Maosong Sun. 2023. Ultrafeedback: Boosting language models with high-quality feedback. <i>CoRR</i> , abs/2310.01377.	Mojan Javaheripi, Sébastien Bubeck, Marah Abdin, Jyoti Aneja, Sebastien Bubeck, Caio César Teodoro Mendes, Weizhu Chen, Allie Del Giorno, Ronen Eldan, Sivakanth Gopi, et al. 2023. Phi-2: The surprising power of small language models. <i>Microsoft Research Blog</i> .	740 741 742 743 744 745
695	Tim Dettmers, Artidoro Pagnoni, Ari Holtzman, and Luke Zettlemoyer. 2023. Qlora: Efficient finetuning of quantized llms. In <i>Advances in Neural Information Processing Systems 36: Annual Conference on Neural Information Processing Systems 2023, NeurIPS 2023, New Orleans, LA, USA, December 10 - 16, 2023</i> .	Seungjae Jung, Gunsoo Han, Daniel Wontae Nam, and Kyoung-Woon On. 2024. Binary classifier optimization for large language model alignment. <i>CoRR</i> , abs/2404.04656.	746 747 748 749
702	Mengnan Du, Fengxiang He, Na Zou, Dacheng Tao, and Xia Hu. 2024. Shortcut learning of large language models in natural language understanding. <i>Commun. ACM</i> , 67(1):110–120.	Tushar Khot, Peter Clark, Michal Guerquin, Peter Jansen, and Ashish Sabharwal. 2020. QASC: A dataset for question answering via sentence composition. In <i>The Thirty-Fourth AAAI Conference on Artificial Intelligence, AAAI 2020, The Thirty-Second Innovative Applications of Artificial Intelligence Conference, IAAI 2020, The Tenth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2020, New York, NY, USA, February 7-12, 2020</i> , pages 8082–8090.	750 751 752 753 754 755 756 757 758 759
706	Duanyu Feng, Bowen Qin, Chen Huang, Zheng Zhang, and Wenqiang Lei. 2024. Towards analyzing and understanding the limitations of DPO: A theoretical perspective. <i>CoRR</i> , abs/2404.04626.	Rik Koncel-Kedziorski, Subhro Roy, Aida Amini, Nate Kushman, and Hannaneh Hajishirzi. 2016. MAWPS: A math word problem repository. In <i>NAACL HLT 2016, The 2016 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, San Diego California, USA, June 12-17, 2016</i> , pages 1152–1157.	760 761 762 763 764 765 766 767
710	Jonathan Frankle and Michael Carbin. 2019. The lottery ticket hypothesis: Finding sparse, trainable neural networks. In <i>7th International Conference on Learning Representations, ICLR 2019, New Orleans, LA, USA, May 6-9, 2019</i> . OpenReview.net.	Xiang Lisa Li and Percy Liang. 2021. Prefix-tuning: Optimizing continuous prompts for generation. In <i>Proceedings of the 59th Annual Meeting of the Association for Computational Linguistics and the 11th International Joint Conference on Natural Language Processing, ACL/IJCNLP 2021, (Volume 1: Long Papers), Virtual Event, August 1-6, 2021</i> , pages 4582–4597. Association for Computational Linguistics.	768 769 770 771 772 773 774 775
715	Zorik Gekhman, Gal Yona, Roei Aharoni, Matan Eyal, Amir Feder, Roi Reichart, and Jonathan Herzig. 2024. Does fine-tuning llms on new knowledge encourage hallucinations? <i>CoRR</i> , abs/2405.05904.	Xuechen Li, Tianyi Zhang, Yann Dubois, Rohan Taori, Ishaan Gulrajani, Carlos Guestrin, Percy Liang, and Tatsunori B. Hashimoto. 2023. AlpacaEval: An automatic evaluator of instruction-following models. <a href="https://github.com/tatsu-lab/alpaca_eval">https://github.com/tatsu-lab/alpaca_eval</a> .	776 777 778 779 780
719	Mor Geva, Daniel Khashabi, Elad Segal, Tushar Khot, Dan Roth, and Jonathan Berant. 2021. Did aristotle use a laptop? A question answering benchmark with implicit reasoning strategies. <i>Trans. Assoc. Comput. Linguistics</i> , 9:346–361.	Zhenghao Lin, Zhibin Gou, Yeyun Gong, Xiao Liu, Yelong Shen, Ruochen Xu, Chen Lin, Yujiu Yang, Jian Jiao, Nan Duan, and Weizhu Chen. 2024. Rho-1: Not all tokens are what you need. <i>CoRR</i> , abs/2404.07965.	781 782 783 784

785	Ruibo Liu, Jerry Wei, Fangyu Liu, Chenglei Si, Yanzhe Zhang, Jinmeng Rao, Steven Zheng, Daiyi Peng, Diyi Yang, Denny Zhou, and Andrew M. Dai. 2024. Best practices and lessons learned on synthetic data for language models. <i>CoRR</i> , abs/2404.07503.	840
786		841
787		842
788		843
789		
790	Tianqi Liu, Yao Zhao, Rishabh Joshi, Misha Khalman, Mohammad Saleh, Peter J. Liu, and Jialu Liu. 2023. Statistical rejection sampling improves preference optimization. <i>CoRR</i> , abs/2309.06657.	844
791		845
792		846
793		847
794	Pan Lu, Liang Qiu, Kai-Wei Chang, Ying Nian Wu, Song-Chun Zhu, Tanmay Rajpurohit, Peter Clark, and Ashwin Kalyan. 2023. Dynamic prompt learning via policy gradient for semi-structured mathematical reasoning. In <i>International Conference on Learning Representations (ICLR)</i> .	848
795		849
796		850
797		851
798		852
799		853
800	Haipeng Luo, Qingfeng Sun, Can Xu, Pu Zhao, Jianguang Lou, Chongyang Tao, Xiubo Geng, Qingwei Lin, Shifeng Chen, and Dongmei Zhang. 2023. Wizardmath: Empowering mathematical reasoning for large language models via reinforced evol-instruct. <i>CoRR</i> , abs/2308.09583.	854
801		855
802		856
803		857
804		858
805		859
806	Pratyush Maini, Zhili Feng, Avi Schwarzschild, Zachary C. Lipton, and J. Zico Kolter. 2024. TOFU: A task of fictitious unlearning for llms. <i>CoRR</i> , abs/2401.06121.	860
807		861
808		862
809		
810	Xiang Meng, Kayhan Behdin, Haoyue Wang, and Rahul Mazumder. 2024a. Alps: Improved optimization for highly sparse one-shot pruning for large language models. <i>CoRR</i> , abs/2406.07831.	863
811		864
812		865
813		
814	Yu Meng, Mengzhou Xia, and Danqi Chen. 2024b. Simpo: Simple preference optimization with a reference-free reward.	866
815		867
816		868
817	Meta. 2024. Llama 3. <i>Meta Blog</i> .	869
818		870
819	Todor Mihaylov, Peter Clark, Tushar Khot, and Ashish Sabharwal. 2018. Can a suit of armor conduct electricity? A new dataset for open book question answering. In <i>Proceedings of the 2018 Conference on Empirical Methods in Natural Language Processing, Brussels, Belgium, October 31 - November 4, 2018</i> , pages 2381–2391.	871
820		872
821		873
822		874
823		
824		
825	Volodymyr Mnih, Adrià Puigdomènech Badia, Mehdi Mirza, Alex Graves, Timothy P. Lillicrap, Tim Harley, David Silver, and Koray Kavukcuoglu. 2016. Asynchronous methods for deep reinforcement learning. In <i>Proceedings of the 33rd International Conference on Machine Learning, ICML 2016, New York City, NY, USA, June 19-24, 2016</i> , volume 48 of <i>JMLR Workshop and Conference Proceedings</i> , pages 1928–1937.	875
826		876
827		877
828		878
829		879
830		880
831		881
832		882
833		883
834	OpenAI. 2023. GPT-4 technical report. <i>CoRR</i> , abs/2303.08774.	884
835		885
836	Long Ouyang, Jeffrey Wu, Xu Jiang, Diogo Almeida, Carroll L. Wainwright, Pamela Mishkin, Chong Zhang, Sandhini Agarwal, Katarina Slama, Alex Ray, John Schulman, Jacob Hilton, Fraser Kelton, Luke	886
837		887
838		888
839		889
		890
		891
		892
		893
		894
		895
		896
		897
	Miller, Maddie Simens, Amanda Askell, Peter Welinder, Paul F. Christiano, Jan Leike, and Ryan Lowe. 2022. Training language models to follow instructions with human feedback. In <i>NeurIPS</i> .	
	Ryan Park, Rafael Rafailov, Stefano Ermon, and Chelsea Finn. 2024. Disentangling length from quality in direct preference optimization. <i>CoRR</i> , abs/2403.19159.	
	Garima Pruthi, Frederick Liu, Satyen Kale, and Mukund Sundararajan. 2020. Estimating training data influence by tracing gradient descent. In <i>Advances in Neural Information Processing Systems 33: Annual Conference on Neural Information Processing Systems 2020, NeurIPS 2020, December 6-12, 2020, virtual</i> .	
	Rafael Rafailov, Archit Sharma, Eric Mitchell, Stefano Ermon, Christopher D. Manning, and Chelsea Finn. 2023. Direct preference optimization: Your language model is secretly a reward model. <i>CoRR</i> , abs/2305.18290.	
	John Schulman, Filip Wolski, Prafulla Dhariwal, Alec Radford, and Oleg Klimov. 2017. Proximal policy optimization algorithms. <i>CoRR</i> , abs/1707.06347.	
	Jifeng Song, Kai Huang, Xiangyu Yin, Boyuan Yang, and Wei Gao. 2024. Large language model pruning. <i>CoRR</i> , abs/2406.06562.	
	Rohan Taori, Ishaan Gulrajani, Tianyi Zhang, Yann Dubois, Xuechen Li, Carlos Guestrin, Percy Liang, and Tatsunori B. Hashimoto. 2023. Stanford alpaca: An instruction-following llama model. <a href="https://github.com/tatsu-lab/stanford_alpaca">https://github.com/tatsu-lab/stanford_alpaca</a> .	
	Evan Frick Lisa Dunlap Banghua Zhu Joseph E. Gonzalez Ion Stoica Tianle Li*, Wei-Lin Chiang*. 2024. From live data to high-quality benchmarks: The arena-hard pipeline.	
	Hugo Touvron, Louis Martin, Kevin Stone, Peter Albert, Amjad Almahairi, Yasmine Babaei, Nikolay Bashlykov, Soumya Batra, Prajjwal Bhargava, Shruti Bhosale, Dan Bikel, Lukas Blecher, Cristian Canton-Ferrer, Moya Chen, Guillem Cucurull, David Esiobu, Jude Fernandes, Jeremy Fu, Wenyin Fu, Brian Fuller, Cynthia Gao, Vedanuj Goswami, Naman Goyal, Anthony Hartshorn, Saghar Hosseini, Rui Hou, Hakan Inan, Marcin Kardas, Viktor Kerkez, Madian Khabsa, Isabel Kloumann, Artem Korenev, Punit Singh Koura, Marie-Anne Lachaux, Thibaut Lavril, Jenya Lee, Diana Liskovich, Yinghai Lu, Yuning Mao, Xavier Martinet, Todor Mihaylov, Pushkar Mishra, Igor Molybog, Yixin Nie, Andrew Poulton, Jeremy Reizenstein, Rashi Rungta, Kalyan Saladi, Alan Schelten, Ruan Silva, Eric Michael Smith, Ranjan Subramanian, Xiaoqing Ellen Tan, Binh Tang, Ross Taylor, Adina Williams, Jian Xiang Kuan, Puxin Xu, Zheng Yan, Iliyan Zarov, Yuchen Zhang, Angela Fan, Melanie Kambadur, Sharan Narang, Aurélien Rodriguez, Robert Stojnic, Sergey Edunov, and Thomas Scialom. 2023. Llama 2: Open foundation and fine-tuned chat models. <i>CoRR</i> , abs/2307.09288.	

898	Peiyi Wang, Lei Li, Zhihong Shao, R.X. Xu, Damai Dai, Yifei Li, Deli Chen, Y.Wu, and Zhifang Sui. 2023. Math-shepherd: Verify and reinforce llms step-by-step without human annotations. <i>CoRR</i> , abs/2312.08935.	Zhangyue Yin, Rongxiang Weng, Wensen Cheng, Haoran Huang, Tianxiang Sun, Hang Yan, Tao Gui, Qi Zhang, Xipeng Qiu, and Xuanjing Huang. 2023. Secrets of RLHF in large language models part I: PPO. <i>CoRR</i> , abs/2307.04964.	952
899			953
900			954
901			955
902			956
903	WeiQi Wang, Zhiyi Tian, and Shui Yu. 2024a. Machine unlearning: A comprehensive survey.	Kun Zhou, Beichen Zhang, Jiapeng Wang, Zhipeng Chen, Wayne Xin Zhao, Jing Sha, Zhichao Sheng, Shijin Wang, and Ji-Rong Wen. 2024. Jiuzhang3.0: Efficiently improving mathematical reasoning by training small data synthesis models. <i>CoRR</i> , abs/2405.14365.	957
904			958
905	Weixuan Wang, Barry Haddow, Wei Peng, and Alexandra Birch. 2024b. Sharing matters: Analysing neurons across languages and tasks in llms. <i>CoRR</i> , abs/2406.09265.		959
906			960
907			961
908			962
909	Yuxiang Wei, Zhe Wang, Jiawei Liu, Yifeng Ding, and Lingming Zhang. 2023. Magicoder: Source code is all you need. <i>CoRR</i> , abs/2312.02120.		
910			
911			
912	Mengzhou Xia, Sadhika Malladi, Suchin Gururangan, Sanjeev Arora, and Danqi Chen. 2024. LESS: selecting influential data for targeted instruction tuning. <i>CoRR</i> , abs/2402.04333.		
913			
914			
915			
916	Sang Michael Xie, Hieu Pham, Xuanyi Dong, Nan Du, Hanxiao Liu, Yifeng Lu, Percy Liang, Quoc V. Le, Tengyu Ma, and Adams Wei Yu. 2023. Doremi: Optimizing data mixtures speeds up language model pretraining. In <i>Advances in Neural Information Processing Systems 36: Annual Conference on Neural Information Processing Systems 2023, NeurIPS 2023, New Orleans, LA, USA, December 10 - 16, 2023</i> .		
917			
918			
919			
920			
921			
922			
923			
924	Can Xu, Qingfeng Sun, Kai Zheng, Xiubo Geng, Pu Zhao, Jiazhan Feng, Chongyang Tao, and Daxin Jiang. 2023. Wizardlm: Empowering large language models to follow complex instructions. <i>CoRR</i> , abs/2304.12244.		
925			
926			
927			
928			
929	Yuanshun Yao, Xiaojun Xu, and Yang Liu. 2023. Large language model unlearning. <i>CoRR</i> , abs/2310.10683.		
930			
931	Longhui Yu, Weisen Jiang, Han Shi, Jincheng Yu, Zhengying Liu, Yu Zhang, James T. Kwok, Zhenguo Li, Adrian Weller, and Weiyang Liu. 2023. Meta-math: Bootstrap your own mathematical questions for large language models. <i>CoRR</i> , abs/2309.12284.		
932			
933			
934			
935			
936	Weizhe Yuan, Richard Yuanzhe Pang, Kyunghyun Cho, Sainbayar Sukhbaatar, Jing Xu, and Jason Weston. 2024. Self-rewarding language models. <i>arXiv preprint arXiv:2401.10020</i> .		
937			
938			
939			
940	Xiang Yue, Xingwei Qu, Ge Zhang, Yao Fu, Wenhao Huang, Huan Sun, Yu Su, and Wenhua Chen. 2023. Mammoth: Building math generalist models through hybrid instruction tuning. <i>CoRR</i> , abs/2309.05653.		
941			
942			
943			
944	Ruiqi Zhang, Licong Lin, Yu Bai, and Song Mei. 2024. Negative preference optimization: From catastrophic collapse to effective unlearning. <i>CoRR</i> , abs/2404.05868.		
945			
946			
947			
948	Rui Zheng, Shihan Dou, Songyang Gao, Yuan Hua, Wei Shen, Binghai Wang, Yan Liu, Senjie Jin, Qin Liu, Yuhao Zhou, Limao Xiong, Lu Chen, Zhiheng Xi, Nuo Xu, Wenbin Lai, Minghao Zhu, Cheng Chang,		
949			
950			
951			

---

**Algorithm 1: The ALLO algorithm.**

---

**Input** : Training set  $\mathcal{D} = \{\langle x_i, y_i^+, y_i^- \rangle\}_{i=1}^n$ , the teacher model (GPT-4o), and the SFT model  $\theta_{\text{SFT}}$ .  
**Output** : A well-aligned model  $\theta$ .

```
// 1. Locating Key Neurons
 $\theta' \leftarrow \text{DPO}(\theta_{\text{SFT}})$ ;
for each neuron  $\theta_i$  in warmed up model  $\theta'$  do
  | Calculate the importance of  $\theta_i$  using Eq. 4;
Sort the importance of each neuron;
Select the top-k relative neurons into  $\mathcal{N}$ ;

// 2. Unaligned Knowledge Forgetting
for each instance  $\langle x_i, y_i^+, y_i^- \rangle$  in  $\mathcal{D}$  do
  | if the data is sampled then
  | | The teacher model rewrites the negative
  | | response  $y_i^-$ ;
Leverage the rewritten response to fine-tune the small
LLM to obtain the  $\theta_{\text{rm}}$ ;
for each instance  $\langle x_i, y_i^+, y_i^- \rangle$  in  $\mathcal{D}$  do
  | Identify the unaligned token using Eq. 5;
  | Optimize the neurons in  $\mathcal{N}$  using Eq. 7;
Obtain the model  $\theta_{\text{forget}}$  forgetting unaligned
knowledge;

// 3. Alignment Improving
for each instance  $\langle x_i, y_i^+, y_i^- \rangle$  in  $\mathcal{D}$  do
  | Identify the noise token using Eq. 8;
  | Optimize the neurons in  $\mathcal{N}$  using Eq. 9;
Obtained the well-aligned model  $\theta$ ;
```

---

rewriting process, we feed the problem, ground-truth reference, and generated response into the teacher model, with the instruction of rewriting in the prefix. Besides, for the downstream tasks, the instruction prefix and problem will be given into LLMs.

## D Case Study

To better demonstrate our proposed ALLO, we present the case study on QA task (*i.e.*, ECQA) in Table 7. In this case, we can observe that LLM after DPO training still cannot catch the relation between “tickets” and the destination John needed to go to, and focus on the relation between “cross country” and “race track”. This phenomenon has shown that unaligned knowledge is not eliminated and still exists in LLMs after DPO training. In contrast, after ALLO training, LLM can correctly seize on the key elements of the problem (*i.e.*, “ticket”) and perform reasoning along the correct direction. That is because low-redundant optimization can reduce the redundant updates in the alignment process and make LLMs focus on the key knowledge and information.

## A Algorithm of ALLO

We present the pipeline of ALLO in Algorithm 1. The process of ALLO includes three stages, *i.e.*, locating key neurons, unaligned knowledge forgetting, and alignment improving.

## B Details of Hyper-Parameters

To better understand and reproduce our proposed ALLO, we presented the hyper-parameters in ALLO in Table 5. The hyper-parameters are a little different between different downstream tasks, that is because these tasks are in different difficulty levels and require different abilities of LLMs. It should be noted that, to conduct a fair comparison, the hyper-parameters of baseline methods are also adjusted to adapt to the corresponding tasks for better performance.

## C Prompt Templates of ALLO

In ALLO, we utilize prompts to guide the teacher model to rewrite the generated response from student models and induce the student model to solve the downstream tasks. The templates of the prompt in ALLO are presented in Table 6. For the solution

Stage	Hyper-Parameter	Question-Answering	Mathematical Reasoning	Human Alignment
Stage 1	Learning Rate	$1 \times 10^{-7}$	$5 \times 10^{-8}$	$1 \times 10^{-7}$
	Batch Size	32	512	128
	Selected Neuron Ratio	5%	5%	10%
	Threshold $u$	0.95	0.95	0.95
	$\beta$ in NPO	0.1	0.1	0.1
Stage 2	Learning Rate	$5 \times 10^{-6}$	$1 \times 10^{-6}$	$5 \times 10^{-6}$
	Batch Size	32	512	128
	Selected Neuron Ratio	10%	20%	15%
	Threshold $v$	20%	50%	20%
	$\beta$ in DPO	0.1	0.1	0.1

Table 5: The details of hyper-parameters in the evaluation.

<b>Distillation for Solution Rewriting</b>	Given the problem and the correct solution, you need to correct the mistakes in the prediction to get the correct answer. You should write down the correct prediction and use "The answer is: " (without quotation mark) to identify the final answer. You should make minimal modifications. You should not copy the problem.
	### Problem: {Problem}
	### Correct solution: {Ground-Truth Reference}
	### Prediction: {Generated Response from LLM}
<b>Prompt for Downstream Tasks</b>	### Correct prediction:
	Below is an instruction that describes a task. Write a response that appropriately completes the request.
	### Instruction: {Problem to be solved}
	### Response: Let's think step by step.

Table 6: The template of prompt in ALLO.

<b>Problem</b>	John needed to go across the country so he ordered tickets online and got into his car. Where might he be going? Options: train station opera car rental shop show race track
<b>Ground-Truth Solution</b>	He was going to train station so he got into his car. John needed to go across the country by train so he ordered tickets online. The answer is train station
<b>Generated Solution Before Training</b>	Race tracks are in the outskirts of the city One can go to a race track by car <b>Race tracks are in the country side.</b> The answer is race track
<b>Generated Solution After DPO</b>	A person may go to another place by car When someone orders ticket online, it means that he is going to travel When someone goes from one place to another by car, he crosses the country When someone crosses the country, he might be <b>going to the other end of the country.</b> The answer is race track
<b>Generated Solution After ALLO</b>	John might be <b>going to the train station as he ordered tickets online</b> and got into his car. John needs to go across the country so he might be going to the train station. The answer is train station

Table 7: The case study for question-answering tasks.