

# Leveraging Cross-Lingual Knowledge from Pre-Trained Models for Low-Resource Neural Machine Translation

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## Abstract

Neural machine translation (NMT) quality significantly depends on large parallel corpora, making low-resource language translation a challenge. This paper introduces a novel approach that leverages cross-lingual alignment knowledge from multilingual pre-trained language models (PLMs) to enhance low-resource NMT. Our method segments the translation model into source encoding, target encoding, and alignment modules, each initialized with different pre-trained BERT models. Experiments on four translation directions with two low-resource language pairs demonstrate significant BLEU score improvements, validating the efficacy of our approach.

## 1 Introduction

The quality of neural machine translation (NMT) heavily depends on rich parallel corpora, making NMT perform poorly with low-resource languages (Arivazhagan et al., 2019; Haddow et al., 2022). The key challenge in handling low-resource languages lies in acquiring monolingual semantics and bilingual alignment knowledge. Traditional NMT systems, reliant on large parallel datasets, often fail to capture these knowledge under data scarcity. Pre-trained language models (PLMs), by acquiring knowledge from extensive monolingual corpora, offer a promising solution to this problem (Liu et al., 2020; Baziotis et al., 2020). By leveraging PLMs pre-trained on large monolingual corpora, we can inject valuable linguistic knowledge into NMT systems, indirectly alleviating the lack of resources.

Previous research has explored combining PLMs with translation models to better utilize the prior knowledge in PLMs. Guo et al. (2020) proposed to use BERT models for source and target languages as the encoder and decoder respectively, and employ adapters to learn bilingual alignment for high-quality non-autoregressive translation. Weng et al.

(2022) initialized the encoder of the translation model with mBERT, and used a Layer-wise Coordination Structure and multi-task learning to enhance autoregressive translation. Duan and Zhao (2023) split the decoder into separate history encoding and generation prediction modules to effectively utilize target language BERT for improved autoregressive translation. Pang et al. (2024) modularized the translation model into encoder, decoder, and transfer modules, and explored to efficiently use monolingual and bilingual knowledge while mitigating catastrophic forgetting.

However, these methods primarily focus on monolingual knowledge from PLMs, failing to effectively utilize cross-lingual alignment knowledge from multilingual PLMs (Muller et al., 2021). To address this issue, we propose a low-resource NMT model that leverages cross-lingual alignment knowledge learned from multilingual PLMs to improve translation quality. This knowledge is crucial in resource-scarce settings as models struggle to learn high-quality alignments from limited parallel corpora. Specifically, we partition the translation model into source encoding, target encoding, and alignment modules, initializing them with different pre-trained models according to their functions. Source and target encoding modules are initialized with respective language BERT models to obtain monolingual encoding capabilities, while the alignment module is initialized with multilingual BERT to utilize cross-lingual alignment knowledge. Experiments on four translation directions of two low-resource parallel corpora show significant BLEU score improvements, validating the effectiveness of our approach.

## 2 Related Work

### 2.1 Two-part Decoder

Previous efforts combining PLMs with NMT models have primarily focused on utilizing monolingual

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080 knowledge from the source language, with limited  
081 success in using target language PLMs to improve  
082 translation quality (Weng et al., 2022). To address  
083 this issue, the Two-part Decoder method (Duan and  
084 Zhao, 2023) reconstructs the translation model’s de-  
085 coder into two independent components: a history  
086 encoding module and a generation module. The  
087 history encoding module encodes previously gener-  
088 ated information, while the generation module gener-  
089 ates translations token by token. This approach  
090 aligns the history encoding module more closely  
091 with the target language BERT, enabling the model  
092 to better utilize monolingual knowledge from tar-  
093 get language, thereby improving translation quality.  
094 Additionally, auxiliary tasks like MLM (Devlin  
095 et al., 2018) and knowledge distillation (Yang et al.,  
096 2020) provide extra training signals to reinforce  
097 learned representations, further enhancing model  
098 performance.

## 099 2.2 MoNMT

100 Fine-tuning PLMs can lead to catastrophic forget-  
101 ting, where models lose previously learned domain-  
102 specific and monolingual knowledge (French,  
103 1999). To mitigate this, the MoNMT approach  
104 (Pang et al., 2024) modularizes the translation  
105 model into encoder, decoder, and transfer modules.  
106 The encoder and decoder are trained on monolin-  
107 gual data to learn monolingual encoding and gen-  
108 eration knowledge, while the transfer module is  
109 trained on parallel corpora to learn bilingual align-  
110 ment knowledge. This modular approach helps  
111 retain pre-trained knowledge and allows independ-  
112 ent updates and improvements for each module,  
113 which is particularly beneficial for low-resource  
114 languages by enabling models to adapt and inte-  
115 grate new data without extensive retraining, main-  
116 taining efficiency and effectiveness.

## 117 3 Methodology

### 118 3.1 Model Architecture

119 To better leverage cross-lingual knowledge from  
120 PLMs, we propose a low-resource NMT model  
121 that utilizes bilingual knowledge from pre-trained  
122 models. Inspired by the Two-part Decoder method  
123 (Duan and Zhao, 2023), our architecture partitions  
124 the translation model into source encoding, target  
125 encoding, and alignment modules. As shown in  
126 Figure 1, both source and target encoding mod-  
127 ules consist of multiple layers, each containing  
128 a self-attention sublayer and a feed-forward sub-

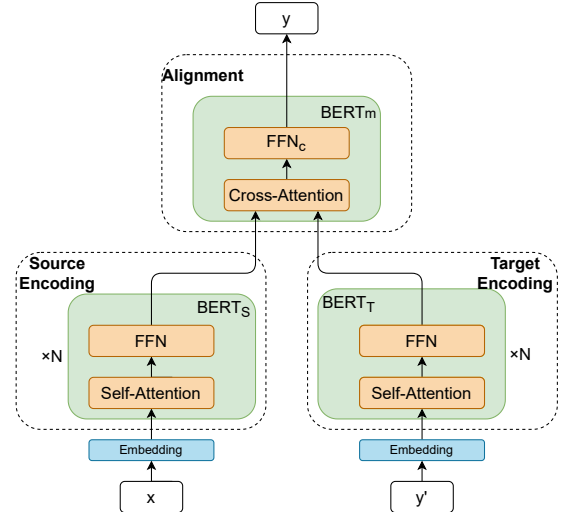


Figure 1: Architecture of the proposed low-resource NMT model, partitioned into three modules: source encoding, target encoding, and alignment. These modules are initialized with  $BERT_S$ ,  $BERT_T$ , and  $BERT_m$  respectively.

129 layer. The alignment module also consists of mul-  
130 tiple layers, each containing a cross-attention sub-  
131 layer and a feed-forward sublayer. The source  
132 and target encoding modules focus on obtaining  
133 the monolingual knowledge of their respective lan-  
134 guages, while the alignment module ensures ef-  
135 fective alignment of representations learned from  
136 both languages. This architecture ensures that each  
137 part of the model is dedicated to its specific task,  
138 thereby improving overall performance.

### 139 3.2 Initialization with Pre-Trained BERT 140 Models

141 We use different BERT models to provide the nec-  
142 essary prior knowledge for each module. Specif-  
143 ically, source language BERT( $BERT_S$ ) and target  
144 language BERT( $BERT_T$ ) initialize the source and  
145 target encoding modules, respectively, capturing  
146 richer contextual information and semantic rela-  
147 tionships for better monolingual representations.  
148 The alignment module is initialized with multilin-  
149 gual BERT( $BERT_m$ ), whose cross-lingual align-  
150 ment knowledge serves as prior knowledge for trans-  
151 lation alignment, improving low-resource transla-  
152 tion quality. This initialization strategy ensures that  
153 each module is equipped with the most relevant  
154 linguistic knowledge from the start, enabling the  
155 model to effectively utilize this knowledge during  
156 training and translation. Using multilingual BERT  
157 for the alignment module is particularly important  
158 as it brings valuable cross-lingual alignment knowl-

Dataset	Train	Valid	Test
En-Nb	142,906	2,000	2,000
De-Nb	110,248	2,000	2,000

Table 1: The size of datasets

edge critical for low-resource translation tasks.

### 3.3 Training Objective

We fine-tune our model on bilingual parallel corpora, focusing on comparing the impact of cross-lingual alignment knowledge from BERT<sub>m</sub> on translation performance. Therefore, we did not incorporate complex multi-task training like (Duan and Zhao, 2023). The training objective is defined as:

$$L = -\log P(y|x, \theta_{\text{BERT}_S}, \theta_{\text{BERT}_T}, \theta_{\text{BERT}_m})$$

where  $(x, y)$  denotes a pair of parallel sentences.

## 4 Experiments

### 4.1 Datasets

We evaluate our model on two low-resource language pair datasets. For English-Norwegian(en-nb), we use OPUS-100 data (Zhang et al., 2020), following the default data split. For German-Norwegian(de-nb), we use the KDE4 dataset (Tiedemann, 2012). Since KDE4 does not divide the default test set, we randomly selected 2000 items as the validation set and 2000 items as the test set. Table 1 provides detailed data statistics.

### 4.2 Model Configurations

For the monolingual BERT models, we use *bert-base-cased*<sup>1</sup> for English, *bert-base-german-cased*<sup>2</sup> for German, and *nb-bert-base*<sup>3</sup> for Norwegian. For the multilingual BERT model, we use *bert-base-multilingual-cased*<sup>1</sup>.

Our model parameters are consistent with those of the pre-trained models, using their tokenizers and vocabularies without modification. Note that when we initialize the alignment module with mBERT, we will replace the vocabulary used for the final prediction with the vocabulary of BERT<sub>m</sub> to ensure that cross-lingual knowledge is fully utilized.

<sup>1</sup><https://github.com/google-research/bert>

<sup>2</sup><https://www.deepset.ai/german-bert>

<sup>3</sup><https://github.com/NBAiLab/notram>

The consistency in model parameters and tokenization ensures that our initialization process is seamless and that the pre-trained knowledge is effectively transferred to the translation model. This setup also facilitates reproducibility and comparability of results across different experiments.

### 4.3 Results

We compared the BLEU values of the randomly initialized alignment module (Random Init) and the alignment module initialized with BERT<sub>m</sub> (BERT<sub>m</sub> Init). For the baseline model, we built a Transformer (Transformer) (Vaswani et al., 2017) based on the hyper-parameters of BERT-base and modified the number of Decoder layers from 12 to 24 to keep the parameter scale close.

Our experimental results are shown in Table 2. The results show that module partitioning and initialization of source and target encoding modules can effectively improve the quality of low-resource translation, even if the alignment module is randomly initialized, because it can learn alignment knowledge from bilingual data. This indicates that the monolingual knowledge from source BERT and target BERT effectively improves the encoding representation quality of both languages, showcasing the effectiveness of module partitioning. On this basis, using BERT<sub>m</sub> to initialize the alignment module further improves the translation quality. This shows that our model can effectively utilize the cross-language alignment knowledge from BERT<sub>m</sub>, indicating the importance of utilizing prior alignment knowledge for low-resource translation.

To further verify the effectiveness of cross-lingual knowledge from BERT<sub>m</sub>, we initialized the alignment module with English BERT (BERT<sub>S</sub> Init) and Norwegian BERT (BERT<sub>T</sub> Init) separately for the en-nb task.

The results shown in Table 3. Using the BERT<sub>S</sub> to initialize the alignment module is even harmful to the model, because the knowledge of the source language is not helpful for the generation of the target language. Using the BERT<sub>T</sub> to initialize the alignment module can also help the model because it can provide knowledge of generating the target language, indicating the rationality of decomposing the Decoder into two parts: encoding and generation, which verifies the view of (Duan and Zhao, 2023). However, it is still lower than the result of initialization with BERT<sub>m</sub>, indicating that alignment knowledge is more important for low-resource translation tasks because it is difficult

Model	En $\Leftrightarrow$ Nb		De $\Leftrightarrow$ Nb	
	En $\Rightarrow$ Nb	Nb $\Rightarrow$ En	De $\Rightarrow$ Nb	Nb $\Rightarrow$ De
Transformer	12.69	23.20	23.59	21.98
Random Init	18.04	30.67	25.13	24.23
BERT <sub>m</sub> Init	27.79	35.58	31.41	29.59

Table 2: BLEU scores of the baseline and our model on the OPUS-100 En-Nb and the KDE4 De-Nb task. *Random Init* and *BERT<sub>m</sub> Init* represent initializing the alignment module randomly or using BERT<sub>m</sub>, respectively.

Model	En $\Rightarrow$ Nb
Random Init	18.04
BERT <sub>S</sub> Init	17.15
BERT <sub>T</sub> Init	26.99
BERT <sub>m</sub> Init	27.79

Table 3: BLEU scores of our model in the En-Nb direction. *Random Init*, *BERT<sub>S</sub> Init*, *BERT<sub>T</sub> Init*, and *BERT<sub>m</sub> Init* represent different ways to initialize the alignment module. When using *BERT<sub>S</sub> Init*, the final predicted vocabulary is the vocabulary of BERT<sub>m</sub> vocabulary.

for the model to learn them from resource-scarce bilingual data.

## 5 Conclusion

Existing methods of enhancing NMT with PLMs fail to effectively utilize cross-lingual alignment knowledge from multilingual PLMs. To address this, we propose a low-resource NMT model that leverages bilingual knowledge from pre-trained models. By initializing different parts of the model according to the functions of BERT, our approach effectively utilizes monolingual semantic knowledge and cross-lingual alignment knowledge from PLMs, significantly improving translation quality for low-resource languages. Our method not only demonstrates the potential of cross-lingual alignment knowledge but also lays the foundation for future research in effectively combining different types of PLMs for various NLP tasks.

## 6 Limitations

Although our work has achieved some success, there are still existing the following limitations:

- **Model Variety** Our current approach is limited to BERT-type pre-trained models, which may not be easily adaptable to seq2seq pre-trained models like BART. Future work will explore ways to utilize knowledge from vari-

ous PLMs, maximizing both monolingual and bilingual knowledge.

- **Dataset Variety** Due to constraints on dataset availability and PLM accessibility, our experiments are currently limited to low-resource languages within specific language families. Further validation is needed to determine the effectiveness of our approach across different language families and cross-language translation tasks.

- **Large Models** Large models contain richer knowledge and possess capabilities not found in smaller models. However, due to computational resource limitations, we have yet to explore enhancing low-resource translation with large models. Future research will investigate leveraging large models to further improve low-resource translation if conditions permit.

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