

CONCEPTS' INFORMATION BOTTLENECK MODELS

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ABSTRACT

Concept Bottleneck Models (CBMs) offer a self-explainable AI framework by predicting targets based on human-understandable concepts, but they often fail to achieve optimal performance and interpretability due to leakage of irrelevant information into the concept activations. This paper presents an information-theoretic enhancement of CBMs through the integration of the Information Bottleneck (IB) framework, aimed at addressing their issues of concept leakage and reduced performance. Our approach reshapes the way CBMs process and utilize concepts by constraining mutual information between input data and concepts, ensuring that only the most relevant information is preserved for decision-making. This introduces a new paradigm for CBMs that not only enhances performance but also enforces a tighter connection between latent representations and human-understandable concepts, ensuring a more robust and interpretable model. Our experiments on datasets such as CUB, AwA2, and aPY demonstrate that IB-augmented CBMs improve both concept and target prediction accuracy, while also increasing intervenability. Additionally, we propose a novel metric to assess the quality of concept sets based on intervention performance. Unlike traditional task performance metrics, which may obscure the effects of concept leakage, the new metric offers a direct, interpretable evaluation of concept set goodness.

1 INTRODUCTION

Explainable AI provides transparency into complex machine learning models, making their decision-making process understandable to humans. This transparency increases trust, accountability, and the ability to identify potential biases or errors thus also increasing safety. In critical domains like healthcare and finance, where AI decisions significantly impact lives, explainability is essential for ensuring fairness and ethical alignment. It also allows for continuous model improvement by exposing flaws in training data or architecture. As AI deployment increases, explainable AI becomes a necessity for maintaining human oversight and control. We distinguish four groups of explainable models. *Post-hoc techniques* (Speith, 2022) explain trained black-box models after the fact, often by approximating their behavior with interpretable models or by providing relevant feature attributions. *Model-agnostic methods* are independent of the model's internal parameters or training process, and rely, instead, on treating the model as a black-box and analyzing its inputs and outputs. *Local interpretability methods* are a subfamily of model-agnostic methods, focusing on explaining individual predictions—examples include LIME (Ribeiro et al., 2016), GradCam (Selvaraju et al., 2020). *Global interpretability* are the second subfamily of model-agnostic methods, including Accumulated Local Effect points (Apley & Zhu, 2020) and H-statistic (Friedman & Popescu, 2008). *Self-explainable models* are ad-hoc designed and trained to be able to explain their predictions at inference time without additional models or estimations. In this work, we are focusing on the latter since such models are explainable by construction and easy to debug via altering the explanations. Thus, the self-explainable methods are positioned as promising approaches over the other existing explainable models.

Concept bottleneck models (CBMs) (Koh et al., 2020) are a self-explainable approach allowing to turn any end-to-end neural network training task into a concept-based task given the concept labels. The main desiderata behind CBMs are the ability to explain the final decision to human while operating with a set of human-understandable concepts, and the ability to take corrections on these concepts into account to re-estimate the final prediction. The advantages of such approach include higher robustness to covariate shifts and spurious correlations (should the target predictions rely only on concepts). Having a model form the final prediction based on human-understandable concepts

has one more benefit: at inference time, one could manually correct mistakes in concepts predictions therefore making target prediction more accurate.

CBMs, however, were shown to have concept leakage (Margeloiu et al., 2021; Mahinpei et al., 2021)—the phenomena of concepts activations storing more information than just the concept presence. This phenomena is an issue affecting both interpretability and intervenability. Another issue with the CBMs is their performance being lower than that of a black-box models.

Among previous work that mitigates these issues, Havasi et al.’s (2022) proposal introduced side-channel CBMs and recurrent CBMs. However, side-channel CBMs have lower intervenability, and recurrent ones break the disentanglement of concepts. Kim et al.’s (2023) work introduced probabilistic CBMs, yet it needs anchor embedding points for target prediction.

Instead, we propose a simpler way to deal with concept leakage and reduced performance without altering the architecture and without introducing a need for anchor bank. We extend the Information Bottleneck (Tishby et al., 2000) principle to the concept space to reduce the concept leakage while learning robust representations. Our main idea is to obtain concepts and representations that are maximally expressive about the labels and the concepts, respectively, while having concepts maximally compressive about the data (under marginalized representations). That is, we offer an information-theoretic approach to CBMs, what we called *Concepts’ Information Bottleneck*. More specifically, we show that adding Information Bottleneck (Alemi et al., 2017; Tishby et al., 2000) to CBM training objective results in improved performance and better utilization of concepts.

The main contributions of this work are three-fold: (i) a new CBM that exploits the Information Bottleneck framework providing a significant improvement compared to both vanilla CBMs and advanced concept bottleneck models, (ii) showcase that CBMs follow memorization-then-compression learning pattern defined by Tishby et al.’s (2000) when regularized in an information theoretical fashion, and (iii) we introduce a model-based metric to measure concept set goodness (cf. Section 4.6).

2 RELATED WORK

2.1 CONCEPT BOTTLENECK MODELS

The concept bottleneck model (Koh et al., 2020), CBM, is defined as $\hat{y} = f(g(x))$, where $x \in \mathbb{R}^D$, $g: \mathbb{R}^D \rightarrow \mathbb{R}^k$ is a mapping from raw feature space into the lower-dimensional concepts space, and $f: \mathbb{R}^k \rightarrow \mathbb{R}$ is a mapping from the concepts to the target variable. For training this model composition, a dataset of triplets $\{(x_i, c_i, y_i)\}_{i=1}^N$ is needed, where $c_{(\cdot)}$ stands for the ground-truth concepts labels which should be produced by g . Notice that in this setup the amount of concepts to use is fixed for a particular model and that they are trained in a supervised manner.

Intuitively, when training a CBM, one is introducing human-understandable sub-labels (concepts) which are more primitive and general than the target, and then builds a model predicting the target based solely on those explainable concepts. Training process could be organized in a three ways: (i) Independent: train f using ground-truth concepts $\mathcal{C} = \{c_i\}_i$ as input, and train g to predict the concepts \mathcal{C} . (ii) Sequential: firstly train g to predict the concepts, then freeze this concept-extractor model and train f on the outputs of g (not on the ground truth concepts labels). (iii) Joint: Optimize the weighted sum of two loss functions simultaneously: target prediction loss and concept prediction loss: $\mathcal{L}(f(g(x)), y) + \lambda \mathcal{L}(g(x), c)$.

However, the initial setup described above has been found to have several flaws: first of all, if the concepts are soft, meaning that they can take any value in $[0, 1]$. According to Mahinpei et al.’s (2021) findings, the model g learns to incorporate more information in these continuous outputs, for instance, about PCA components of the raw data. The issue appears unrelated to the training method, as it occurs even if g is trained separately from f , nor is it related to the selection of concepts, since leakage occurs with randomly chosen dataset divisions as concepts. Mahinpei et al. (2021) posit that even for hard concepts (each concept is clipped to $\{0, 1\}$) information may leak, though the experiments confirm it only for small-dimensional data like Deng’s (2012). Secondly, Margeloiu et al. (2021) argue that the CBMs desiderata is met for independent training only: for joint and sequential a CBM learns more information about the raw data than just that presented in the concepts. Thus, concepts are not used as intended. Developing the idea of tracking concepts predictions, the authors apply saliency methods to back-trace concepts to input features and find that for neither training

method of the three derive concepts from something meaningful in the input space. Conversely, we hypothesize that by compressing the concepts and the data and, simultaneously, maximally expressing the labels and concepts through their respective variables, we could obtain better concepts and representations.

Havasi et al. (2022) introduced side-channel CBMs—the ones in which information is allowed to flow aside the concept bottleneck—and recurrent CBMs, in which the model predicts concepts one after the other, and for next concept prediction utilizes the information about previous concept predictions. However, side-channel CBMs have lower intervenability, and recurrent ones break the disentanglement of concepts. Yuksekogonul et al. (2023) proposed Post-Hoc Concept Bottleneck Models (PCBM). Such type of models utilize image embeddings from pre-trained Convolutional Neural Nets penultimate layer activations. Based on these embeddings, the authors construct a concept embeddings bank and obtain concepts predictions by either projecting a new image embedding onto those embeddings or by using a SVM trained on the bank as concepts classifier. However, these models perform well only after residual connections, similar to the ones described above, are added. This residual information flow may damage both interpretability and intervenability.

To mitigate previous limitations, Zarlenga et al. (2022) presented Concept Embedding Models (CEM)—a method bridging the gap between CBMs and black-box models via learning two vectors for each concept (“active” and “inactive”). Such approach has increased target accuracy, but requires additional regularization algorithm called ‘RandInt’ for CEM to be able to effectively utilize test-time interventions. Moreover, the analysis of information flow done in the paper suggests that information between inputs and concepts is monotonically increasing without any compression. The paper also introduces concepts alignment score (a metric specific for the model, more complex than just accuracy) designed to evaluate how well has CEM has learned the concepts.

Our work, unlike Zarlenga et al.’s (2022) proposal, maintains the original model concept representation space and regularizes it through our concept information bottleneck regularization. In detail, first, we incorporate mutual information constraint into loss function, thus obtaining compression of information between inputs and concept activations. Secondly, we do not utilize a pair of embeddings per concept but opt for one logit per concept, as in the original CBM setup. Finally, the novel metric we introduced measures not the quality of a model, but rather the quality of concepts sets themselves.

Kim et al. (2023) introduced ProbCBMs models, which predict a parameterized distribution of concepts (mean and standard deviation) and use anchor points for class mapping. In this work, we do not utilize these anchor points, since they increase inference costs and introduce a new hyper-parameter to tune at fitting stage. We do use a variational approximation over our proposed concepts’ information bottleneck to predict concepts.

2.2 INFORMATION BOTTLENECK

Tishby et al. (2000) introduced the information bottleneck (IB) as the minimization of the functional

$$\mathcal{L}_{IB} = I(X; Z) - \beta I(Z; Y), \quad (1)$$

where $I(\cdot; \cdot)$ is the mutual information, β is the Lagrange multiplier, X , Y and Z are random variables that represents the data, labels, and latent representations, respectively. The motivation behind the bottleneck is to “squeeze” the relevant information about target Y from X into a compact representation Z while minimizing the information about input X in Z —so that the representations are free of irrelevant information from X . The IB’s authors have also posited that good generalization is connected with memorization-compression pattern. This is the behavior in which $I(Z; Y)$ increases during the whole training time, while $I(X; Z)$ increases at first (memorization) and then decreases at later iterations (compression).

Alemi et al. (2017) extended the IB framework to deep neural networks by doing a variational approximation of latent representation Z . And, Kawaguchi et al. (2023) analyzed the role of IB in estimation of generalization gaps for classification task. Their result implies that by incorporating the Information Bottleneck into learning objective one may get more generalized and robust network. Unlike this previous work that studied the IB for the data and the labels, we introduced another predictive variable, the concepts, and derive an upper bound that links common predictors and the ground truth into a regularizer that enforces the memorization-compression dynamics. Moreover, we show that the concepts’ information bottleneck can be used in common CBM approaches through a mutual information estimator as well.

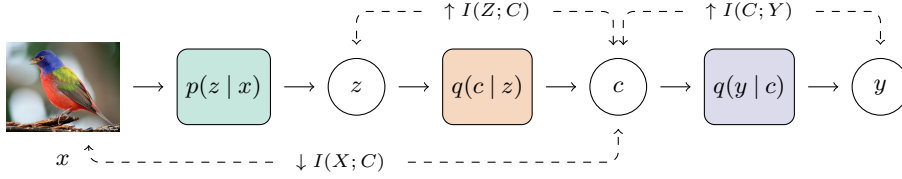


Figure 1: Our proposed CIBMs pipeline. The image is encoded through $p(z|x)$, which in turn encodes the concepts with $q(c|z)$, and the labels are predicted through $q(y|c)$. These modules are implemented as neural networks. We introduced the IB regularization as mutual information optimizations over the variables as shown in dashed lines.

3 CONCEPTS' INFORMATION BOTTLENECK

Concept Bottleneck Models (CBMs) aim for high interpretability by introducing human-understandable concepts, C , as an intermediary between latent representations, Z , and the labels Y . To preserve the interpretability at the heart of CBMs, our objective seeks to minimize $I(X; C)$ —the mutual information between inputs and concepts—thereby ensuring concepts remain meaningful and free from irrelevant data, while addressing concept leakage by controlling the information flow directly at the concept level, rather than at the more abstract latent space, Z . Simultaneously, we aim to maximize the expressivity of the concepts about the labels, $I(C; Y)$, as well as the one of the latent representations and the concepts, $I(Z; C)$. Our initial objective is

$$\max I(Z; C) + I(C; Y) \quad \text{s.t.} \quad I(X; Z) \leq I_C, \quad (2)$$

where I_C is an information constraint constant, that equivalently is the maximization of the functional of the concepts' information bottleneck (CIB)

$$\mathcal{L}_{\text{CIB}} = I(Z; C) + I(C; Y) - \beta I(X; Z), \quad (3)$$

where β is a Lagrangian multiplier. This formulation ensures a strong connection between latents, Z , and the concepts, C . This means that one wants Z to be maximally useful in shaping the concepts C , while also ensuring that the concepts are informative about the target.

Moreover, in the CBMs formulation, the concepts come from processing the latent representations, i.e., $c = h(z)$. Thus, due to the data processing inequality, $I(X; C) \leq I(X; Z)$, we can bound of the concepts' information bottleneck loss (3)

$$I(Z; C) + I(C; Y) - \beta I(X; C) \geq I(Z; C) + I(C; Y) - \beta I(X; Z). \quad (4)$$

Thus, our objective is to maximize the upper bound of the concepts' information bottleneck

$$\mathcal{L}_{\text{UB-CIB}} = I(Z; C) + I(C; Y) - \beta I(X; C).^1 \quad (5)$$

We depict our general framework in Fig. 1. We posit that by compressing the information between the data, X , and the concepts, C , instead of the latent representations, Z , we can control the redundant information of the data within the concepts. Consequently, we can obtain more interpretable concepts instead of first compressing the latents and then obtaining the concepts from them. We hypothesize that this compression also prevents data leakage from the data into the concepts that commonly happens when the concepts are processed through the latents alone. Another interpretation of this process is the compression of the information between the data and the concepts through the marginalized latent representations. Thus, we are obtaining a more robust compression since we compute it through all possible latent representations that lead to that concept.

We propose two implementations of our framework by exploring different ways of solving the mutual information based on a variational approximation of the data distribution. We show our modeling assumptions in Fig. 2.

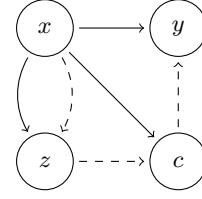


Figure 2: Directed graph of our model. Solid lines denote the generative model $p(y|x)p(c|x)p(z|x)p(x)$, and dashed lines show its variational approximation $q(y|c)q(c|z)q(z|x)q(x)$.

¹Note that one can obtain the same loss if the optimization problem is constrained over the concepts instead, i.e., $\max I(Z; C) + I(C; Y)$ s.t. $I(X; C) \leq I_C$. Nevertheless, we present the relation with the traditional compression for completeness.

3.1 BOUNDED CIB

We can consider the upper bound to the concept bottleneck loss (5) in terms of the entropy-based definitions of the mutual information. Then, by using a variational approximation of the data distribution, we bound it by

$$\mathcal{L}_{\text{UB-CIB}} \leq H(Y) + (1 - \beta)H(C) + \mathbb{E}_{p(c)} H(p(y|c), q(y|c)) + (1 + \beta) \mathbb{E}_{p(z)} H(p(c|z), q(c|z)), \quad (6)$$

$$\mathcal{L}_{\text{UB-CIB}} \leq (1 - \beta)H(C) + \mathbb{E}_{p(c)} H(p(y|c), q(y|c)) + (1 + \beta) \mathbb{E}_{p(z)} H(p(c|z), q(c|z)). \quad (7)$$

We detail this derivation in Appendix A. We can maximize the concepts' information bottleneck by minimizing the cross entropies of the predictive variables, y and c , and their corresponding ground truths and by adjusting the entropy of the concepts. The simplified upper bound of the concept information bottleneck is

$$\mathcal{L}_{\text{SUB-CIB}} = (1 - \beta)H(C) + \mathbb{E}_{p(c)} H(p(y|c), q(y|c)) + (1 + \beta) \mathbb{E}_{p(z)} H(p(c|z), q(c|z)). \quad (8)$$

We term the model that uses this bounded concept information bottleneck (8) as CIBM_B . To implement it, we need to estimate the entropy of the concepts distribution $p(c)$. We give details of this estimator in Appendix B.2.

3.2 ESTIMATOR-BASED CIB

Another way to obtain a bound over the concept information bottleneck (5) is to only expand the conditional entropies that are not marginalized (A.1) to avoid widening the gap in the bound. That is

$$\mathcal{L}_{\text{UB-CIB}} = H(Y) + H(C) + \mathbb{E}_{p(c)} H(p(y|c), q(y|c)) + \mathbb{E}_{p(z)} H(p(c|z), q(c|z)) - \beta I(X; C). \quad (9)$$

If we treat the entropies of the concepts and the labels as constants, we obtain

$$\mathcal{L}_{\text{E-CIB}} = \mathbb{E}_{p(c)} H(p(y|c), q(y|c)) + \mathbb{E}_{p(z)} H(p(c|z), q(c|z)) + \beta(\rho - I(X; C)), \quad (10)$$

where ρ is a constant. We term the model that uses this loss as CIBM_E since it relies on the estimator of the mutual information. We detail the estimator we used in our implementation in Appendix B.2.

This loss is similar to the one proposed by Kawaguchi et al. (2023),

$$\mathcal{L}_K = \mathbb{E}_{p(z)} H(p(y|z), q(y|z)) + \beta(\rho - I(Z; X)), \quad (11)$$

if one extends the mutual information from the labels into the concepts in a similar way. In other words, our mutual information estimated loss (10) resembles that of Kawaguchi et al.'s (2023) proposal with the corresponding conditioning changes in the labels and the concepts. Thus, it is interesting to see that other optimization approaches emerge out of this bound. We highlight that our proposal is a generalized framework that encompass a wide range of possible implementations.

Unlike $\mathcal{L}_{\text{SUB-CIB}}$ (8), which simplifies the mutual information terms into cross-entropy losses, $\mathcal{L}_{\text{E-CIB}}$ retains an explicit control over $I(X; C)$. This allows for more granular control over the information flow from inputs to concepts, leading to a tighter constraint on concept leakage. As we show in the results (Table 1), this additional control translates to improved performance in both concept and class prediction accuracy, cf. Section 4.

4 EXPERIMENTS

For all experiments we used Adam (Kingma & Ba, 2015) optimizer with $lr = 0.003$ and $wd = 0.001$. In the following, we refer to our Concepts' Information Bottleneck Models (CIBMs) trained with bounded CIB $\mathcal{L}_{\text{SUB-CIB}}$ (8) as CIBM_B , and one trained with an estimator-based CIB $\mathcal{L}_{\text{E-CIB}}$ (10) as CIBM_E (with $\rho = 1$). We follow the mutual information estimator from Kawaguchi et al. (2023) for our implementation of CIBM_E . The ground truth concept labels are binary across all dataset, but concepts predictions passed to label classifier are non-binary: we are training only (and comparing only against) models using soft concepts for class prediction.

Table 1: Accuracies for our proposed methods, CIBM_B and CIBM_E , on CUB dataset (avg. 3 runs).

METHOD	CONCEPT	CLASS
CIBM_B (VANILLA)	0.934	0.608
(CLIP_NORM = 1.0)	0.947	0.660
(CLIP_NORM = 0.1)	0.947	0.646
(STOP GRAD. FROM $H(C)$ INTO $p(z x)$)	0.959	0.726
CIBM_E	0.959	0.729

In the experiments below, for baselines to evaluate our proposal, we compare against CBM (Koh et al., 2020), ProbCBM (Kim et al., 2023), CEM (Zarlenga et al., 2022), and PCBM (Yuksekgonul et al., 2023). We also evaluate a “black-box model” that denotes a model with an architecture equivalent to that of our CIBM_E ’s model, without our proposed losses, and trained only to predict class labels, thus, unable to predict concepts that we deemed as a gold-standard for classification.

4.1 DATASETS

We benchmark our approach on 3 datasets: CUB (Wah et al., 2011), AwA2 (Xian et al., 2019), and aPY (Farhadi et al., 2009). While CUB is a recognized dataset for comparing concept-based approaches (Koh et al., 2020; Kim et al., 2023; Zarlenga et al., 2022), we add the other two datasets for additional evaluations and analysis.

CUB. Caltech-UCSD Birds dataset (Wah et al., 2011) is a dataset of birds images totaling in 11788 samples for 200 species. Following Koh et al.’s (2020) work, for reproducibility, we reduce instance-level concept annotations to class-level ones with majority voting. We then keep only the concept that are annotated as present in 10 classes at least after the described voting, resulting in 112 concepts instead of 312. We also employ train/val/test splits provided by Koh et al. (2020), operating with 4796 train images, 1198 val images and 5794 test images. To diversify training data, we augment the images with color jittering and horizontal flip, and resize the images to 299×299 pixels for the InceptionV3 backbone. Concept groups are obtained by common prefix clustering.

AwA2. Animals with attributes dataset (Xian et al., 2019) is a dataset of 37322 images of 50 animal species. For the concepts set, we follow Kim et al.’s (2023) work and keep only the 45 concepts which could be observed on the image. We use ResNet18 embeddings provided by the dataset authors and train FCN on top of them. No additional augmentations are applied to those embeddings.

aPY. This is a dataset (Farhadi et al., 2009) of 32 diverse real-world classes we used for proof of concept. We split the dataset into 7362 train, 3068 validation and 4909 test samples stratified on target labels. We train FCN on top of ResNet18 embeddings of input images provided by the dataset authors (Xian et al., 2019). No additional augmentations are applied to those embeddings.

4.2 COMPARISON OF DIFFERENT VERSIONS OF CIB

In Table 1, we compare the performance of CIBM_B and CIBM_E on concept and class prediction accuracy for the CUB dataset—using $\beta = 0.5$. As shown, CIBM_E , which retains an explicit mutual information term $I(X; C)$, outperforms CIBM_B when trained in a fair setup (vanilla) in both metrics. We found that the lack of performance of vanilla CIBM_B comes from instabilities during training in the latent representations encoder $p(z|x)$. We hypothesize that the gradient from the $H(C)$ in the loss (8) damages the feature encoder $p(z|x)$ since the entropy is computed w.r.t. the generative concepts $p(c)$ instead of the variational approximated ones $q(c)$. To alleviate this problem, we experimented gradient clipping as well as stopping the gradient from $H(C)$ into the encoder. We found that the latter perform on par with CIBM_E . In the following, we refer to CIBM_B as the version with stop gradient on it. Overall, CIBM_E ’s more granular control over information flow limits concept leakage, results in better accuracies for concepts and labels in comparison to the baselines (cf. Table 2) without changes to its training framework.

Table 2: Accuracy for CUB, AwA2, and aPY datasets. The results include mean and std. over 5 runs. We report results for different lagrange multipliers β for our methods, CIBM_B and CIBM_E. Black-box is a gold standard for class prediction that offers no explainability over the concepts.

DATA	METHOD	CONCEPT	CLASS
CUB	BLACK-BOX	–	0.919±0.002
	CBM	0.956±0.001	0.708±0.006
	CEM	0.954±0.001	0.759±0.002
	PROBCBM	0.956±0.001	0.718±0.005
	PCBM	–	0.610±0.010
	CIBM _B ($\beta = 0.25$)	0.958±0.001	0.726±0.003
	($\beta = 0.50$)	0.958±0.001	0.725±0.004
	CIBM _E ($\beta = 0.25$)	0.958±0.001	0.728±0.005
	($\beta = 0.50$)	0.959±0.001	0.729±0.003
AWA2	BLACK-BOX	–	0.893±0.000
	CBM	0.979±0.000	0.876±0.001
	PCBM	–	0.862±0.003
	CIBM _B ($\beta = 0.25$)	0.980±0.000	0.886±0.002
	($\beta = 0.50$)	0.979±0.000	0.885±0.002
	CIBM _E ($\beta = 0.25$)	0.980±0.000	0.885±0.001
	($\beta = 0.50$)	0.979±0.000	0.883±0.001
APY	BLACK-BOX	–	0.866±0.003
	CBM	0.967±0.000	0.797±0.007
	CIBM _B ($\beta = 0.25$)	0.967±0.000	0.850±0.006
	($\beta = 0.50$)	0.967±0.000	0.856±0.005
	CIBM _E ($\beta = 0.25$)	0.967±0.000	0.858±0.004
	($\beta = 0.50$)	0.967±0.000	0.856±0.004

These results supports our earlier discussion that the direct estimation of $I(X; C)$ leads to more effective use of concepts in downstream tasks without further changes to the training regime. Nevertheless, with a correctly regularized feature encoder $p(z | x)$, a simple estimation in CIBM_B can achieve similar levels of information gain and accuracy.

4.3 PERFORMANCE ACROSS ALL DATASETS

We present the evaluation results across three datasets in Table 2. Our “black-box model” serves as a gold standard, representing the highest possible class accuracy achievable by a model similar to ours within a traditional setup that does not provide explanations.

Our proposed methods, CIBM_B and CIBM_E, show an improvement over most methods (apart from CEM) regarding target prediction accuracy for the *CUB dataset*. These improvements come alongside enhanced concept accuracy, thus realizing the fundamental goal of our approach: to simultaneously boost performance and interpretability. Although we fall short of CEM’s class prediction accuracy, our concept prediction accuracy is superior. As for the *AwA2 dataset*, the target accuracy gain is less marked compared to the other datasets but is nevertheless statistically significant. We ascribe this to the dataset’s relative simplicity, which narrows the room for enhancement. In the more varied real-world classes of the *aPY dataset*, CIBM_E significantly outperforms the baseline CBM in target accuracy. The black-box model may achieve marginally better target accuracy, yet it falls short on interpretability, which is paramount in real-world applications where explanations are necessary.

The rise in concept accuracy relative to existing methods highlights the advantages of our mutual information regularization. This approach helps stop concept leakage and ensures that concepts are both informative and closely tied to the final prediction. This finding is consistent with our theoretical framework, which advocates that controlling the information flow between inputs and concepts through the Information Bottleneck can yield more interpretable and significantly meaningful concepts without compromising performance. Importantly, our approach maintains concept accuracy, suggesting that the mutual information regularization effectively curtails concept leakage even in less complex tasks. This is consistent with our theoretical model, which maintains that minimizing $I(X; C)$ ensures that only pertinent information is channeled through the concepts, thus, increasing the robustness across various datasets.

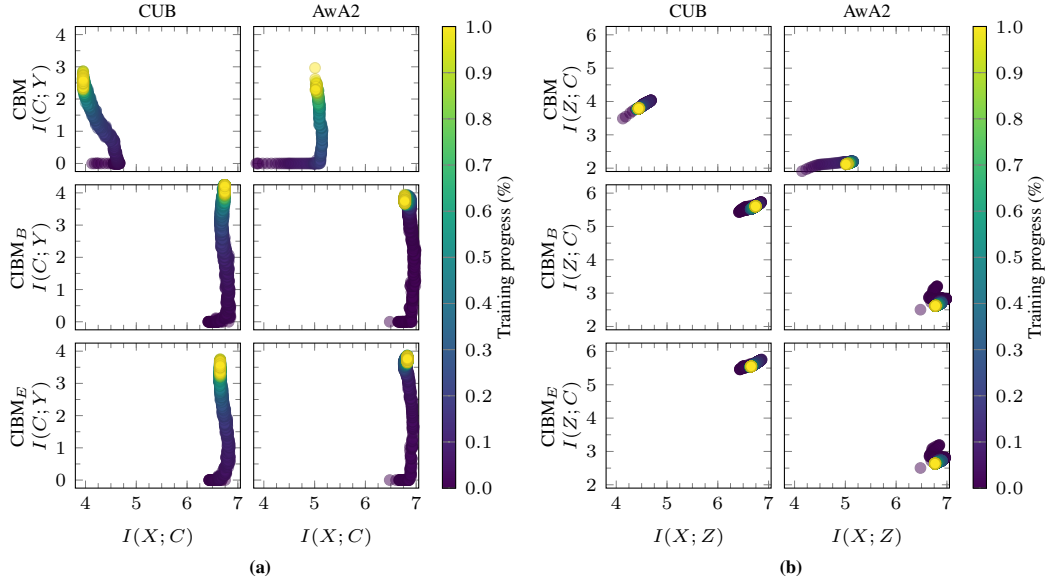


Figure 3: Memorization-compression pattern in the information flow (in nats) of original CBM and our proposed methods, CIBM_B and CIBM_E. Warmer colors denote later steps in training. We show the information plane of (a) the variables X , C , and Y ; and (b) the variables X , Z , and C .

4.4 INFORMATION FLOW IN CIB

We analyze the flow of information between inputs, X , latents, Z , concepts, C , and labels, Y , and present them in Fig. 3 for the CUB and AwA2 datasets. The objective of the information plane is to show the mutual information on the model variables after training. In particular, we expect to see a model with high $I(Z; C)$ and $I(C; Y)$ such that the corresponding variables are dependent on each other (maximally expressive), and simultaneously, low $I(X; C)$ and $I(X; Z)$ to show that the corresponding variables are maximally compressive. However, the compression of the variables alone, minimal $I(X; C)$ or $I(X; Z)$, does not guarantee that the important parts of the variables are being compressed and retained.

CIBMs achieve higher mutual information $I(C; Y)$ while aligning with the target labels—as shown in the prediction tasks in Table 2. In contrast to CBMs, which exhibit lower mutual information between inputs and latent and concept representations, $I(X; Z)$ and $I(X; C)$, CIBMs mutual information w.r.t. the inputs X is higher than the CBMs. This behavior reflects the fact that CIBMs are optimized to retain task-relevant information while removing irrelevant or redundant information but not necessarily compressing as much—reflected in the higher $I(X; Z)$ and $I(X; C)$. Thus, lower mutual information $I(X; Z)$ and $I(X; C)$ in CBMs does not necessarily indicate better compression given its lower predictive accuracy. Instead, it may reflect a failure to capture meaningful input features, resulting in noisier or less predictive concepts. Moreover, we note that the plots in Fig. 3(b) for CIBM_B and CIBM_E look similar but they differ in hundredths.

To demonstrate the effects of the compression patterns, we evaluate the alignment between representations and the target $I(C; Y)$ and show that CIBMs consistently outperform CBMs, indicating that the retained information is both relevant and predictive—cf. Section 4.3. Additionally, CIBMs achieve better interpretability and concept quality, reinforcing that the higher mutual information is a reflection of meaningful expressiveness rather than leakage—cf. Section 4.5. This is further supported by the proposed intervention-based metrics (AUC_{TTI} and NAUC_{TTI}) which highlight the importance of retaining task-relevant information in the concepts C . While CBMs exhibit lower mutual information between inputs and representations, $I(X; C)$ and $I(X; Z)$, their poorer performance on these metrics, particularly under concept corruption, suggests that this lower information content stems from a failure to capture sufficient relevant features. By contrast, the higher $I(X; C)$ and $I(X; Z)$ in our CIBMs reflect the retention of meaningful pieces that contribute to better concept quality and downstream task performance. These findings demonstrate that reducing concept leakage requires selectively preserving relevant information rather than minimizing mutual information indiscriminately.

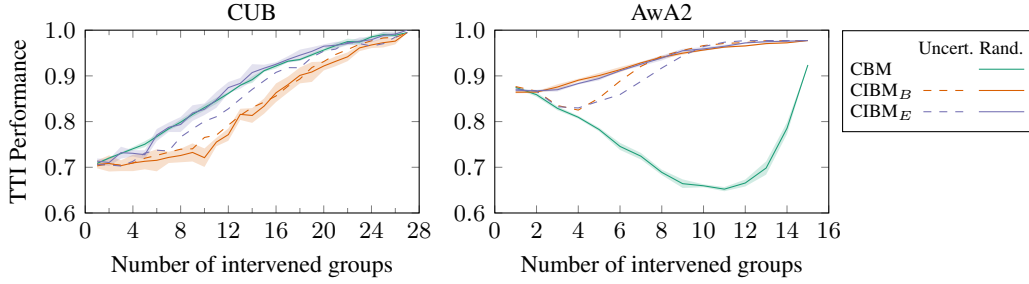


Figure 4: Change in target prediction accuracy after intervening on concept groups following the strategies “uncertainty” and “random” as described in Section 4.5. (TTI stands for Test-Time Interventions.)

4.5 INTERVENTIONS

A key advantage of CBMs is their ability to perform *test-time interventions*, allowing users to correct predicted concepts and improve the model’s final decisions. To demonstrate that our model effectively utilizes concept information and avoids concept leakage, we simulate interventions by replacing predicted concepts with their ground truth values. Following prior work, we intervene on *groups of concepts* rather than individual concepts, leveraging this strategy to assess how cumulative corrections impact target performance (Koh et al., 2020; Kim et al., 2023). We, then, plot the target task performance improvement against number of concept groups intervened. The resulting curve is denoted as the interventions curve.

We implement two ways of choosing a set of concept groups to intervene on:

- **Random:** Concept groups are randomly selected for intervention, and results are averaged over five runs to account for variability.
- **Uncertainty Based:** Since our model predicts parameters of a Gaussian distribution for concept logits, we can measure the likelihood of zero for each concept in that distribution. Zero acts as a threshold for prediction and indicates complete uncertainty about the presence or absence of a concept. We calculate the mean of these likelihoods for a group of concepts and define it as the groups uncertainty. We then select the groups with the highest uncertainty for intervention. We highlight that this setup is not directly applicable to CBMs.

Figure 4 shows that as more concept groups are intervened upon, in CUB, performance improves consistently, demonstrating that the model *relies on accurate concept information* and does not suffer from concept leakage. The steady improvement confirms the model’s ability to be “debugged” by correcting concept predictions. In AwA2, our methods have a small dip observed for uncertainty-based selection is likely due to imperfect uncertainty estimation, but overall, interventions still significantly boost performance. On the contrary, CBM shows a higher dip in performance which may be due to the random strategy for the interventions.

4.6 CONCEPT SET GOODNESS MEASURE

In CBMs, the quality of the concept set is crucial for accurate downstream task predictions. However, there is a lack of effective metrics to reliably assess concept set goodness. Existing metrics, such as the Concept Alignment Score, proposed by Zarlenga et al. (2022), evaluate whether the model has captured meaningful concept representations but do not explicitly measure how well these concepts improve downstream task performance during interventions. Moreover, they are tuned for CEM and do not extend beyond it.

We address this gap by proposing two metrics: as area under interventions curve, and the area under curve of relative improvements. Denote by $\mathcal{I}(x)$ the model’s performance for x concept groups used in the intervention. Then the Test-Time Interventions accuracy is

$$\text{AUC}_{\text{TTI}} = \frac{1}{n} \sum_{i=1}^n \mathcal{I}(i), \quad (12)$$

Table 3: Change in interventions performance with concept set corruption.

CORRUPT	CUB			
	AUC		NAUC	
	CBM	CIBM _E	CBM	CIBM _E
0	34.184	41.799	0.002646	0.003529
4	32.812	39.393	0.002448	0.003011
8	33.709	37.879	0.002519	0.003017
16	33.495	36.135	0.003394	0.001764
32	30.152	31.584	0.001259	0.000064
64	22.194	17.929	-0.000339	-0.006348

CORRUPT	AwA2			
	AUC		NAUC	
	CBM	CIBM _E	CBM	CIBM _E
NO	84.753	92.225	0.002808	0.006250
YES	83.985	90.879	0.004484	0.006474

and the normalized version of the Test-Time Interventions accuracy is

$$\text{NAUC}_{\text{TTI}} = \frac{1}{n} \sum_{i=1}^n (\mathcal{I}(i) - \mathcal{I}(i-1)). \quad (13)$$

The idea behind these measures is simple: if a concept set is of high quality, the task accuracy will steadily approach 100% as more concept groups are intervened upon, resulting in a large area under the curve. Conversely, if the concept set is incomplete or noisy, performance gains will be limited, even with multiple interventions, which can indicate concept leakage.

The latter expression (13) could be simplified to just scaled difference between a model with full concept set used for interventions and performance of a model with no interventions, however, the meaning it has is how much does the performance change per one group added to the interventions pool. To test this, we generate corrupted concept sets by replacing selected concepts with noisy ones. Importantly, we maintain the original groupings of concepts.

Table 3 shows the results. The number in the “corrupt” column denotes the number of concepts replaced with random ones for CUB, and for AwA2 “No” denotes a clear concept set and “Yes” denotes a concept set with one concept changed to corrupt. As expected, performance drops with corrupt concepts, since they contain no useful information for the target task. One consequence of our training is that if one has two concept annotations for some dataset, then it is possible to use CIBMs performance to determine which concept set is better.

Our results demonstrate that CIBM_E is more sensitive to concept quality compared to vanilla CBM, making it a better indicator of concept set reliability. Negative values in normalized intervention AUC indicate possible concept leakage.

5 CONCLUSION

In this paper, we have adopted Information Bottleneck for Concept Bottleneck Models, showing a significant improvement in performance compared to both vanilla CBMs and some advanced architectures such as ProbCBMs (Kim et al., 2023). We introduced two variants of our models, and found an estimator-based of our model to outperform a bounded one. We have tested our approach on widely used datasets for CBMs such as CUB, AwA2, and aPY. Furthermore, we proposed model-based metrics for concept set goodness and analyzed the information flow in CIBM_E objective. We analyzed the interpretability and intervenability for our concept’s information bottleneck objective. We showed that the new objective has the same or improved performance gains from interventions.

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A DETAILED DERIVATION OF CIB

In this section we present the detailed derivations to obtained the results described in Section 3.1.

We can re-write the upper bound of the concepts’ information bottleneck as

$$\mathcal{L}_{\text{UB-CIB}} = H(Y) + (1 - \beta)H(C) - H(Y | C) - H(C | Z) - \beta H(C | X) \quad (\text{A.1})$$

to work with the entropies instead. To find a more suitable form to tackle this bound, we consider an approximation of the predictors for the labels and the concepts, $q(y | c)$ and $q(c | z)$, based on two variational distributions that will be implemented through neural networks—cf. Fig. 2. Consider, on one hand,

$$H(Y | C) = \iint dy dc p(y, c) \log p(y | c), \quad (\text{A.2a})$$

$$= \iint dy dc p(y, c) \log \left[p(y | c) \frac{q(y | c)}{q(y | c)} \right], \quad (\text{A.2b})$$

$$= \iint dy dc p(y | c) p(c) \left[\log \frac{p(y | c)}{q(y | c)} + \log q(y | c) \right], \quad (\text{A.2c})$$

$$= \int dc p(c) \int dy p(y | c) \left[\log \frac{p(y | c)}{q(y | c)} + \log q(y | c) \right], \quad (\text{A.2d})$$

$$= \mathbb{E}_{p(c)} [\text{KL}(p(y | c) \parallel q(y | c)) - H(p(y | c), q(y | c))]. \quad (\text{A.2e})$$

We introduce the variational distribution $q(y | c)$ to obtain the cross-entropy w.r.t. the ground truth and this results on an additional term to make the variational distribution close to the prior. In other words, we can interpret the conditional entropy of the labels w.r.t. the concepts as an optimization of the variational distribution $q(y | c)$ with the true conditional of the labels given the concepts $p(y | c)$ through a Kullback-Leibler divergence (KL) and the cross-entropy between them. This last cross-entropy can be interpreted as the traditional prediction loss of the true labels and the predicted ones. Similarly,

$$H(C | Z) = \iint dc dz p(c, z) \log p(c | z), \quad (\text{A.3a})$$

$$= \iint dc dz p(c, z) \log \left[p(c | z) \frac{q(c | z)}{q(c | z)} \right], \quad (\text{A.3b})$$

$$= \iint dc dz p(c | z) p(z) \left[\log \frac{p(c | z)}{q(c | z)} + \log q(c | z) \right], \quad (\text{A.3c})$$

$$= \int dz p(z) \int dc p(c | z) \left[\log \frac{p(c | z)}{q(c | z)} + \log q(c | z) \right], \quad (\text{A.3d})$$

$$= \mathbb{E}_{p(z)} [\text{KL}(p(c | z) \parallel q(c | z)) - H(p(c | z), q(c | z))], \quad (\text{A.3e})$$

were $q(c | z)$ is a variational distribution that predicts the concepts given the latent representations. This decomposition of the conditional entropy of the concepts given the representations follows the same principles as the conditional of the labels given the concepts (A.2). On the other hand, the conditional entropy of the concepts w.r.t. the data is bounded due to the marginalization of the latent representations on their dependency. That is,

$$H(C | X) = \iint dc dx p(c, x) \log p(c | x), \quad (\text{A.4a})$$

$$= \iint dc dx p(c, x) \log \int dz p(c, z | x), \quad (\text{A.4b})$$

$$= \iint dc dx p(c, x) \log \int dz p(c | z) p(z | x), \quad (\text{A.4c})$$

$$\leq \iint dc dx p(c, x) \int dz p(z | x) \log p(c | z), \quad (\text{A.4d})$$

$$= \iiint dc dz dx p(c, z, x) \int dz p(z | x) \log p(c | z), \quad (\text{A.4e})$$

$$= \iiint dc dz dx p(c | z) p(z | x) p(x) \int dz p(z | x) \log p(c | z), \quad (\text{A.4f})$$

$$= \int dx p(x) \iiint dc dz^2 p(c | z) p(z | x)^2 \log p(c | z), \quad (\text{A.4g})$$

$$= \int dx p(x) \iiint dc dz^2 p(c | z) p(z | x)^2 \log \left[p(c | z) \frac{q(c | z)}{q(c | z)} \right], \quad (\text{A.4h})$$

$$= \int dx p(x) \iint dz^2 p(z | x)^2 \int dc p(c | z) \log \left[p(c | z) \frac{q(c | z)}{q(c | z)} \right], \quad (\text{A.4i})$$

$$= \mathbb{E}_{p(x)} \mathbb{E}_{p(z | x)} \int dc p(c | z) \log \left[p(c | z) \frac{q(c | z)}{q(c | z)} \right], \quad (\text{A.4j})$$

$$= \mathbb{E}_{p(z | x)p(x)} \int dc p(c | z) \left[\log \frac{p(c | z)}{q(c | z)} + \log q(c | z) \right], \quad (\text{A.4k})$$

$$= \mathbb{E}_{p(z | x)p(x)} [\text{KL}(p(c | z) \parallel q(c | z)) - H(p(c | z), q(c | z))], \quad (\text{A.4l})$$

where the bound comes from applying the Jensen's inequality. Thus, the upper bound to the concept bottleneck loss (5), given that we remove the KLs constraints, due to their positivity, from the conditional entropies (A.2), (A.3) and (A.4) is

$$\mathcal{L}_{\text{UB-CIB}} \leq H(Y) + (1 - \beta)H(C) + \mathbb{E}_{p(c)} H(p(y | c), q(y | c)) + (1 + \beta) \mathbb{E}_{p(z)} H(p(c | z), q(c | z)). \quad (\text{A.5})$$

The bound gap can be further reduced by dropping the entropy of the labels as

$$\begin{aligned} \mathcal{L}_{\text{UB-CIB}} &\leq (1 - \beta)H(C) + \mathbb{E}_{p(c)} H(p(y | c), q(y | c)) + (1 + \beta) \mathbb{E}_{p(z)} H(p(c | z), q(c | z)), \quad (\text{A.6}) \\ &= \mathcal{L}_{\text{SUB-CIB}}. \end{aligned} \quad (\text{A.7})$$

In other words, we can maximize the concepts' information bottleneck by minimizing the cross entropies of the predictive variables, y and c , and their corresponding ground truths and by adjusting the entropy of the concepts.

B IMPLEMENTATION DETAILS

B.1 DETAILS ON THE MODELS

For CUB dataset, we choose InceptionV3 as image embedder ($p(z | x)$). We add on top of its embeddings two 1-layer MLP (for mean and std in the variational approximation $q(c | z)$) each of dimensionality 112—the number of concepts left after filtration identical to one done in Koh et al. (2020). We obtain concept logits as $C = \text{pred}_\mu(x) + \text{pred}_\sigma(x) \cdot \epsilon$, where ϵ is a random standard Gaussian noise. On top of concepts logits, we stack label predictor $q(y | c)$ (also 1-layer MLP).


```

702 1 class CIBM:
703 2     def __init__(num_concepts=112, num_labels=200):
704 3         backbone = inceptionv3()
705 4         pred_mu = Linear(2048, num_concepts) # 2048 is the embedding dim
706 5         ↪ of inceptionv3
707 6         pred_sigma = Sequential(Linear(2048, num_concepts), Softplus)
708 7         pred_label = Linear(num_concepts, num_labels)
709 8
710 9     def forward(x):
711 10         z = backbone(x)
712 11         z = ReLU(z)
713 12         eps = N(0; I).sample(num_samples=len(x))
714 13         mu = pred_mu(z)
715 14         sigma = pred_sigma(z).clamp(min=1e-7) # for numeric stability
716 15         c = mu + sigma * eps
717 16         y = pred_label(c)
718 17         return c, y

```

Listing B.1: CIBM Python code.

All activations between the layers are ReLU. The overall code would like the example shown in Listing B.1.

For AwA2 and aPY the only difference is that we use on pre-computed embeddings from ResNet18 without training the backbone.

B.2 ESTIMATORS DETAILS

Mutual Information Estimator. Before each gradient update, we compute cross-entropies over the current batch B_c , and then randomly sample batch B'_c from the training dataset to estimate $I(X; C)$ on this batch.

Our mutual information estimator is taken from Kawaguchi et al. (2023). We rely on the fact that concepts logits have Gaussian distribution for estimation of $\log p(c|x)$. And then, we use the random samples B'_c to approximate the marginal of the concepts $\log p(c)$. The mutual information $I(C; X)$ is then a Monte-Carlo estimate of $\log p(c|x) - \log p(c)$.

Entropy Estimator. Since concepts C are distributed normally, we use $H(C) = \frac{D}{2}(1 + \log(2\pi)) + \frac{1}{2} \log |\Sigma|$. For simplicity (since the number of concepts D is constant throughout the training and inference) we use $\hat{H}(C) = \frac{1}{2} \log |\Sigma| = \sum \log(\sigma_i)$ since Σ is a diagonal matrix in our setup.

B.3 TRAINING PARAMETERS

We set batch size to 128 and number of samples for MI estimation to 64. For all experiments we used Adam (Kingma & Ba, 2015) optimizer with $lr = 0.003$ and $wd = 0.001$. We experimented with gradient clipping, but it led to either slow or divergent training, so we are not clipping the gradients in any of the experiments.

B.4 DETAILS ON EXPERIMENTS

The image embedder backbone is only trained for CUB dataset, and for AwA2 and aPY we use pre-computed image embeddings.

When training CIBM_B , we used the $\mathcal{L}_{\text{SUB-CIB}}$ (8) for better performance. We backpropagate the gradients from the cross-entropies over concepts and labels through the entire network—both backbone $q(c|z)$ and MLPs on top of the encoder $q(y|c)$. For $H(C)$, however, the situation is different: gradients from this part of the loss function are propagated only through the MLPs, $q(c|z)$ and $q(y|c)$, but not the image embedder backbone $p(z|x)$. We found that such (partial) “freezing” of the encoder with respect to $H(C)$ constraint dramatically improves the quality of both concepts and labels prediction. While we do not have access to the ground truth probability distribution for the

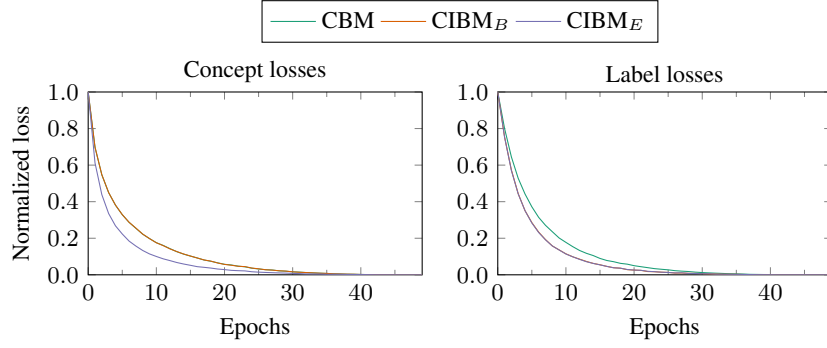


Figure B.1: Losses on the validation set of CUB for different methods.

concepts $p(c | z)$, we have access to the ground truth concept labels. Our implementation uses the a supervised cross-entropy using the ground truth labels. The concepts' predictor can be seen as a multi-label task classifier. In practice, we compute C logits, then, we compute binary cross-entropy (BCE) for each of these logits with binary labels. Finally, we backpropagate them through the means of BCEs.

We show the normalized loss function values on the validation set of CUB in Fig. B.1 to show the convergence of CIBMs in comparison to CBM. Note that visually the concept losses on between CBM and CIBM_E and the label losses between CIBMs are similar, but they differ slightly.