

000 001 002 003 004 005 006 007 008 009 010 011 012 TOPOLOGY OF REASONING: RETRIEVED CELL COMPLEX-AUGMENTED GENERATION FOR TEXTUAL GRAPH QUESTION ANSWERING

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ABSTRACT

Retrieval-Augmented Generation (RAG) enhances the reasoning ability of Large Language Models (LLMs) by dynamically integrating external knowledge, thereby mitigating hallucinations and strengthening contextual grounding for structured data such as graphs. Nevertheless, most existing RAG variants for textual graphs concentrate on low-dimensional structures—treating nodes as entities (0-dimensional) and edges or paths as pairwise or sequential relations (1-dimensional), but overlook cycles, which are crucial for reasoning over relational loops. Such cycles often arise in questions requiring closed-loop inference about similar objects or relative positions. This limitation often results in incomplete contextual grounding and restricted reasoning capability. In this work, we propose **Topology-enhanced Retrieval-Augmented Generation** (TopoRAG), a novel framework for textual graph question answering that effectively captures higher-dimensional topological and relational dependencies. Specifically, TopoRAG first lifts textual graphs into cellular complexes to model multi-dimensional topological structures. Leveraging these lifted representations, a topology-aware subcomplex retrieval mechanism is proposed to extract cellular complexes relevant to the input query, providing compact and informative topological context. Finally, a multi-dimensional topological reasoning mechanism operates over these complexes to propagate relational information and guide LLMs in performing structured, logic-aware inference. Empirical evaluations demonstrate that our method consistently surpasses existing baselines across diverse textual graph tasks.

1 INTRODUCTION

Large Language Models (LLMs) exhibit strong language understanding and generation capabilities, but their reliance on pre-training corpora—limited in scope and timeliness—often leads to hallucinations, producing inaccurate or fabricated content that challenges knowledge-intensive reasoning Huang et al. (2023b). To mitigate these issues, Retrieval-Augmented Generation (RAG) has recently emerged as an effective approach Fan et al. (2024); Sun et al. (2024); Baek et al. (2023); Sen et al. (2023), dynamically retrieving relevant external knowledge and incorporating it into the generation process. By enhancing contextual grounding and factual accuracy, RAG improves reasoning over structured data and reduces hallucination Gao et al. (2023). However, traditional RAG methods often overlook the structured dependencies among textual entities and struggle to capture global relational patterns, limiting their applicability for graph-structured reasoning tasks.

To address these challenges, Graph Retrieval-Augmented Generation (GraphRAG) Edge et al. (2024); Hu et al. (2024); Mavromatis & Karypis (2025) extends conventional RAG by retrieving not only documents but also graph elements, which provide richer relational context for reasoning over textual graphs. *G-Retriever* He et al. (2024) introduces the first general GraphRAG framework for textual graphs, formulating retrieval as a Prize-Collecting Steiner Tree problem to extract compact and relevant subgraphs. GNN-RAG Mavromatis & Karypis (2025) and SubgraphRAG Li et al. (2025) further develop specialized retrieval modules to extract subgraphs from knowledge graphs. However, existing approaches, primarily operate on low-dimensional elements and largely ignore higher-dimensional topological structures such as cycles, which are crucial for reasoning over relational loops and complex dependencies in textual graphs.

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In many real-world textual graphs, essential information arises not only from nodes (0-cells) that encode entity attributes, edges and paths (1-cells) representing pairwise or multi-hop relations, but also from cycles (2-cells) capturing higher-dimensional dependencies. As illustrated in Fig. 1, reasoning over 0-cells enables answering simple attribute-based questions (Fig. 1 a), while incorporating 1-cells supports inference over one-hop to multi-hop relational queries (Fig. 1 b).

However, certain queries require cyclic dependencies among multiple entities, where the answer emerges only from reasoning over 2-cells. For example, the question in Fig. 1 (c) involves a closed relational loop that links spatial relations with material consistency, which cannot be resolved by nodes and edges alone. Capturing structural information across multiple topological dimensions provides indispensable context for structured logical inference, as higher-dimensional dependencies complement lower-dimensional relations to enable reasoning beyond simple pairwise interactions. Consequently, retrieval and reasoning mechanisms that explicitly incorporate multi-dimensional topological features are essential for understanding and answering questions over complex textual graphs.

In this work, we propose **Topology-enhanced Retrieval-Augmented Generation (TopoRAG)**, a novel framework for textual graph question answering that explicitly models higher-dimensional topological and relational dependencies. Specifically, TopoRAG first lifts input textual graphs into cellular complexes to capture multi-dimensional topological structures, including cycles that encode closed-loop dependencies critical for relational reasoning. Leveraging these lifted representations, a topology-aware subcomplex retrieval mechanism is introduced to extract cellular complexes that are most relevant to the input query, providing compact yet informative topological context for downstream reasoning. Furthermore, a multi-dimensional topological reasoning mechanism operates over the retrieved complexes to propagate relational information across different topological dimensions, enabling structured, logic-aware inference that naturally integrates with LLM reasoning. Extensive experiments demonstrate that TopoRAG consistently outperforms state-of-the-art baselines.

2 RELATED WORKS

Large Language Models (LLMs) have shown impressive capabilities in language understanding and text generation, yet they remain constrained by the boundaries of their pre-training corpus, lacking domain-specific expertise, real-time updates, and proprietary knowledge. These limitations frequently manifest as hallucinations, where models produce inaccurate or fabricated content Huang et al. (2023b). To address this issue, Retrieval-Augmented Generation (RAG) Fan et al. (2024); Sun et al. (2024); Baek et al. (2023); Sen et al. (2023) has emerged as a promising paradigm.

RAG enhances LLMs by dynamically retrieving relevant external knowledge and incorporating it into the generation process, thereby improving factual accuracy, contextual grounding, and interpretability Gao et al. (2023). Nevertheless, existing RAG methods are not without shortcomings in real-world applications. They often overlook structured dependencies among textual entities, rely on lengthy concatenated snippets that may obscure critical information (the “lost in the middle” problem Liu et al. (2024)), and struggle to capture global structural patterns essential for tasks such as query-focused summarization.

To address these challenges, Graph Retrieval-Augmented Generation (GraphRAG) Edge et al. (2024); Hu et al. (2024); Mavromatis & Karypis (2025) extends conventional RAG by retrieving not only documents but also graph elements such as nodes, triples, and subgraphs. Building on this

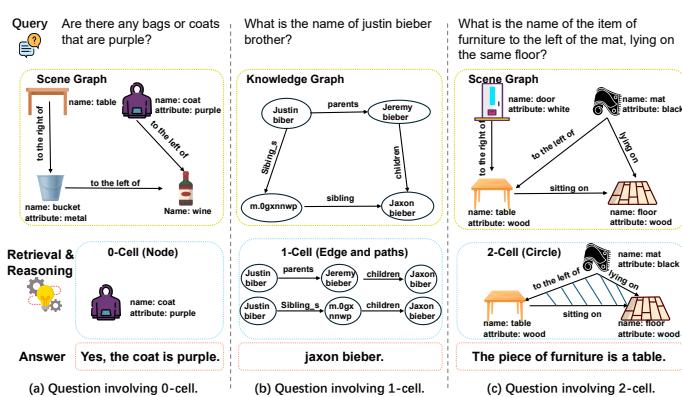


Figure 1: Illustration of question answering with varying dimensional topological characteristics.

108 idea, G-Retriever He et al. (2024) introduces the first general RAG framework for textual graphs,
 109 formulating retrieval as a Prize-Collecting Steiner Tree problem to extract compact and relevant sub-
 110 graphs. GNN-RAG Mavromatis & Karypis (2025) improves knowledge graph QA by integrating
 111 GNN-based representations for task-specific subgraph selection, and SubgraphRAG Li et al. (2025)
 112 incorporates lightweight triple scoring and distance encoding to achieve efficient subgraph retrieval.
 113 Nevertheless, existing methods overlook high-dimensional cyclic dependencies, motivating our ap-
 114 proach to incorporate multi-dimensional cell structures for enhanced retrieval and reasoning.

115 We also discuss related works on graphs & LLMs, and topological deep learning in Appendix B.
 116

117 3 PRELIMINARIES

119 **Definition 1. (Cell Complex Hansen & Ghrist (2019)).** A **regular cell complex** is a topolog-
 120 ical space X decomposed into a collection of disjoint subspaces $\{x_\sigma\}_{\sigma \in P_X}$, referred to as *cells*,
 121 satisfying the following conditions:

- 123 1. For each point $p \in X$, \exists an open neighborhood intersecting only finitely many cells.
- 124 2. For any pair of cells x_σ, x_τ , the intersection $x_\tau \cap \overline{x_\sigma}$ is nonempty if and only if $x_\tau \subseteq \overline{x_\sigma}$,
 125 where $\overline{x_\sigma}$ denotes the topological closure of x_σ .
- 126 3. Each cell x_σ is homeomorphic to an open ball in \mathbb{R}^n for some non-negative integer n .
- 127 4. (Regularity) The closure $\overline{x_\sigma}$ of every cell is homeomorphic to a closed ball in \mathbb{R}^{n_σ} , with
 128 the interior mapped homeomorphically onto x_σ itself.

130 **Definition 2.** A **cellular lifting map** is a function $f : \mathcal{G} \rightarrow X$ from the space of graphs \mathcal{G} to the
 131 space of regular cell complexes X , satisfying that two graphs $G_1, G_2 \in \mathcal{G}$ are isomorphic if and only
 132 if their corresponding cell complexes $f(G_1)$ and $f(G_2)$ are isomorphic. Intuitively, a cell complex
 133 is built hierarchically by first considering 0-cells (vertices), then attaching 1-cells (edges) via their
 134 endpoints, and further incorporating higher-dimensional cells by gluing disks along cycles.
 135

136 **Definition 3. (Retrieved Cell Complex-Augmented Question Answering).** Given a textual graph
 137 $\mathcal{G} = (V, E, \{t_n\}_{n \in V}, \{t_e\}_{e \in E})$, where each node $n \in V$ and edge $e \in E$ is associated with textual
 138 attributes $t_n \in D^{L_n}$ and $t_e \in D^{L_e}$, we lift \mathcal{G} into a regular cell complex X through a cellular
 139 lifting map $f : \mathcal{G} \rightarrow X$. The resulting complex $X = \{x_\sigma\}$ contains multi-dimensional structures,
 140 including 0-cells (nodes), 1-cells (edges/paths), and higher-dimensional cells (e.g., 2-cells as cycles).

141 To enable retrieval, a query Q is first encoded by a language model into a dense representation:
 142

$$z_Q = \text{LM}(Q) \in \mathbb{R}^d. \quad (1)$$

144 Each cell $x_\sigma \in X$ is also represented by an embedding z_σ , obtained from its textual attributes
 145 together with a topological descriptor z_σ^d that summarizes its d -dimensional structure. We then
 146 apply a k -nearest neighbors retrieval strategy to select the most relevant cells:
 147

$$\mathcal{X}_k = \text{argtopk}_{x_\sigma \in X} \cos(z_Q, z_\sigma^d), \quad (2)$$

149 where $\cos(\cdot, \cdot)$ denotes cosine similarity. This step yields a candidate set of cells $\mathcal{X}_k =$
 150 $\{x_{\sigma_1}, \dots, x_{\sigma_k}\}$ spanning multiple topological dimensions.

151 The task is defined as follows: given a natural language query Q and the lifted cell complex X , the
 152 model must retrieve the most relevant subcomplexes X^* and reason over their multi-dimensional
 153 structures to generate an answer A . Formally, the QA function is
 154

$$f : (\mathcal{G}, X, Q) \mapsto A, \quad (3)$$

155 where A is a natural language sequence generated by the LLM under the conditional likelihood
 156

$$p_\theta(A \mid [P_e; Q; X^*]) = \prod_{i=1}^{|A|} p_\theta(a_i \mid a_{<i}, [P_e; Q; X^*]). \quad (4)$$

157 161 Here, $[P_e; Q; X^*]$ denotes the concatenation of soft prompt embeddings P_e , query tokens, and re-
 162 trieval subcomplex representations, while $a_{<i}$ represents the prefix of A up to step $i - 1$.

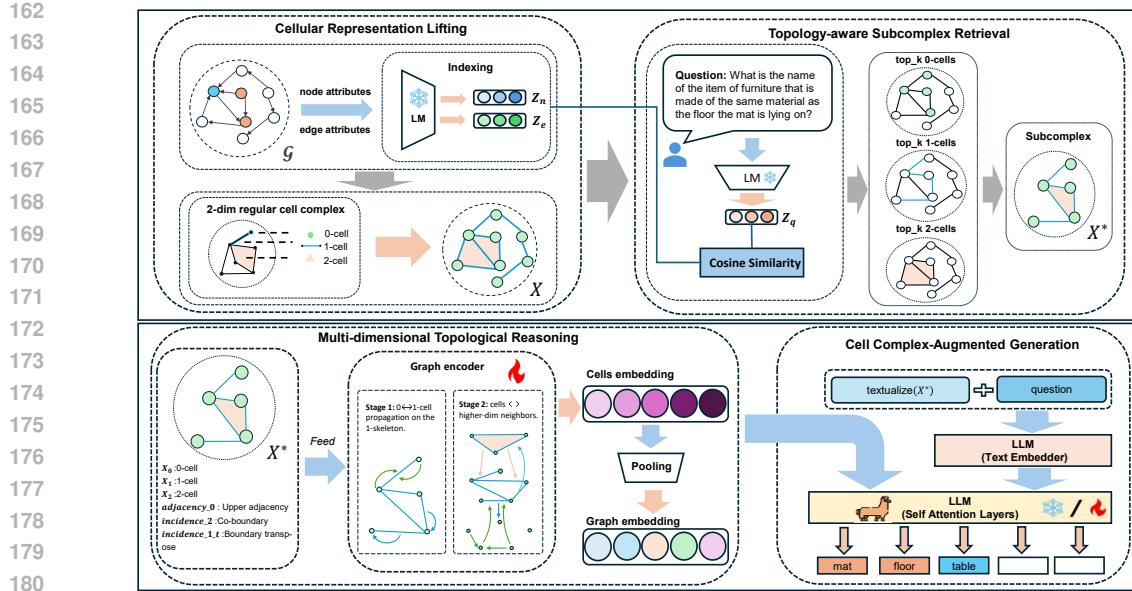


Figure 2: The overview of Topology-enhanced Retrieval-Augmented Framework.

Training proceeds by maximizing the likelihood of the ground-truth answer A^* :

$$\max_{P_e} \log p_\theta(A^* | [P_e; Q; X^*]), \quad (5)$$

where only the soft prompt parameters P_e are updated, while the LLM parameters θ remain fixed.

4 THE TOPORAG FRAMEWORK

In this section, we present the architecture of **TopoRAG** (illustrated in Figure 2), a topology-enhanced retrieval-augmented generation framework designed for textual graph question answering. TopoRAG is composed of four key components. First, the *Cellular Representation Lifting* module transforms input textual graphs into regular cell complexes, providing expressive multi-dimensional topological representations that go beyond nodes and edges. Second, the *Topology-aware Subcomplex Retrieval* module identifies the most relevant subcomplexes with respect to the query by jointly considering semantic similarity and topological structure. Third, the *Multi-dimensional Topological Reasoning* module propagates relational information across different topological dimensions, enabling structured and logic-aware inference. Finally, the *Cell Complex-Augmented Generation* module integrates retrieved subcomplex representations into the LLM to guide answer generation, ensuring faithful and topology-consistent responses.

4.1 CELLULAR REPRESENTATION LIFTING

Given a textual graph $\mathcal{G} = (V, E, \{t_n\}_{n \in V}, \{t_e\}_{e \in E})$, we aim to lift it into a higher-dimensional topological space that faithfully encodes both relational and structural dependencies. This is achieved by constructing a *regular cell complex* X through a cellular lifting map $f: \mathcal{G} \rightarrow X$.

We first regard \mathcal{G} as a 1-dimensional cell complex, where each vertex $v \in V$ corresponds to a 0-cell $x_v^0 \in X^{(0)}$, and each edge $(u, v) \in E$ corresponds to a 1-cell $x_{(u,v)}^1 \in X^{(1)}$ attached to its endpoint 0-cells x_u^0 and x_v^0 . This forms the *cellular 1-skeleton*:

$$X^{(1)} = X^{(0)} \cup \{x_{(u,v)}^1 \mid (u, v) \in E\}. \quad (6)$$

To elaborate, consider $t_v \in D^{L_v}$ as the text attributes of vertex v and $t_{(u,v)} \in D^{L_{(u,v)}}$ as those of edge (u, v) . Utilizing a pre-trained LM, such as SentenceBert (Reimers & Gurevych, 2019), we

216 apply the LM to these attributes, yielding the representations:
 217

$$z_v^0 = \text{LM}(t_v) \in \mathbb{R}^d, \quad z_{(u,v)}^1 = \text{LM}(t_{(u,v)}) \in \mathbb{R}^d, \quad (7)$$

219 where d denotes the dimension of the output vector. This yields cellular embeddings for both nodes
 220 and edges, which serve as the lifted representation in the subsequent module.
 221

222 To incorporate high-dimensional topological structures, we extend $X^{(1)}$ by identifying fundamental
 223 cycles. Specifically, we fix a spanning tree $\mathcal{T} \subseteq G$ and apply the quotient map:
 224

$$\gamma : G \rightarrow G/\mathcal{T}, \quad (8)$$

225 which collapses \mathcal{T} to a single point. Each non-tree edge $e = (u, v) \in E \setminus \mathcal{T}$ then induces a
 226 fundamental cycle by connecting e with the unique path in \mathcal{T} between u and v . For every such
 227 cycle, we attach a 2-cell $x_e^2 \in X^{(2)}$ via the attaching map
 228

$$\varphi_\alpha : \partial D^2 \cong S^1 \rightarrow G^{(1)}, \quad (9)$$

230 that glues the boundary of a disk D^2 to the cycle. Formally, the set of 2-cells is
 231

$$X^{(2)} = \{x_e^2 \in D^2 \mid e \in E \setminus \mathcal{T}\}. \quad (10)$$

233 The resulting cell complex $X = X^{(0)} \cup X^{(1)} \cup X^{(2)}$ augments the original graph with multi-
 234 dimensional topological structures.
 235

Proposition 1. (Proof in Appendix C.1.) G/\mathcal{T} is homotopy-equivalent to G , and γ induces an
 236 isomorphism on the first homology group $H_1(G; \mathbb{Z})$.
 237

Proposition 2. (Proof in Appendix C.2.) Each non-tree edge $e \in E \setminus \mathcal{T}$ induces a unique fundamental
 238 cycle in G , which becomes a nontrivial loop in G/\mathcal{T} . The collection of these loops forms a basis
 239 of the first homology group $H_1(G; \mathbb{Z})$, capturing all independent cycles and providing a concise
 240 topological summary of the graph.
 241

242 4.2 TOPOLOGY-AWARE SUBCOMPLEX RETRIEVAL

244 Given a query x_q , we first encode it into a d -dimensional embedding:
 245

$$z_q = \text{LM}(x_q) \in \mathbb{R}^d. \quad (11)$$

247 To retrieve the most relevant cells, we compute the cosine similarity between z_q and the embeddings
 248 of 0- and 1-cells:
 249

$$\mathcal{X}_k^{(d)} = \text{argtopk}_{x^d \in X^{(d)}} \cos(z_q, z_{x^d}^d), \quad (12)$$

251 where $d \in \{0, 1\}$ denotes the dimension, $z_{x^d}^d$ is the embeddings of d -cell x^d . These provide the
 252 top- k relevant 0- and 1-cells.
 253

254 *Prize assignment.* Each selected 0-cell $x^0 \in \mathcal{X}_k^{(0)}$ and 1-cell $x^1 \in \mathcal{X}_k^{(1)}$ is assigned a descending
 255 prize according to its ranking:
 256

$$\text{prize}(x^i) = \begin{cases} k - r, & \text{if } x^i \text{ is ranked } r\text{-th among top-}k \text{ cells,} \\ 0, & \text{otherwise,} \end{cases} \quad i = 0, 1. \quad (13)$$

259 For each 2-cell $x^2 \in X^{(2)}$, its prize is computed from the prizes of its boundary cells:
 260

$$\text{prize}(x^2) = \sum_{d \in \{1, 2\}} \sum_{x^d \in \partial_d x^2} \text{prize}(x^d) - \text{cost}(x^2), \quad (14)$$

263 where $\partial_d x^2$ denote the sets of boundary d -cells of x^2 , and $\text{cost}(x^2) = |\partial_1 x^2| \cdot C_2$ penalizes larger
 264 faces with a tunable constant C_2 . Top- k 2-cells are selected based on this prize ranking, denoted as
 265 $\mathcal{X}_k^{(2)}$, ensuring that all selected 2-cells share boundary cells with the chosen 0- and 1-cells.
 266

267 *Subcomplex selection.* The final subcomplex X^* maximizes the total prize while controlling size:
 268

$$X^* = \text{argmax}_{\substack{X' \subseteq X, \\ X' \text{ connected}}} \sum_{d \in \{1, 2, 3\}} \sum_{x^d \in X'^{(d)}} \text{prize}(x^d) - \text{cost}(X'), \quad (15)$$

270 where $\text{cost}(X')$ is a size-dependent penalty. The boundary consistency constraint ensures that any
 271 selected 2-cell $x^2 \in X^{*(2)}$ has all of its boundary 0- and 1-cells included in $X^{*(0)}$ and $X^{*(1)}$,
 272 preserving topological coherence.
 273

274 The resulting topology-aware subcomplex selection problem can be seen as a generalization of
 275 Prize-Collecting Steiner Tree (PCST) problem (Bienstock et al., 1993) to higher-dimensional cell
 276 complexes with multi-dimensional prizes and size-dependent penalties. We adopt a near-linear time
 277 approximation algorithm Hegde et al. (2015) to efficiently identify a near-optimal connected sub-
 278 complex X^* . This ensures that the final subcomplex captures the most query-relevant structures
 279 across all cell dimensions, while maintaining computational efficiency and topological validity.
 280

280 4.3 MULTI-DIMENSIONAL TOPOLOGICAL REASONING

282 After retrieving the query-relevant subcomplex $X^* = X^{*(0)} \cup X^{*(1)} \cup X^{*(2)}$, we propagate semantic
 283 and relational information across different topological dimensions to enable structured reasoning
 284 over the enriched cell complex. We employ a two-stage message passing mechanism that leverages
 285 the multi-dimensional structure of the complex. In the first stage, information is propagated along
 286 the 1-skeleton, between 0-cells and 1-cells, over L hops:
 287

$$288 \mathbf{h}_x^l = \text{UPDATE}^l\left(\mathbf{h}_x^l, m_{\mathcal{F}}^l(x), m_{\mathcal{C}}^l(x)\right), \quad x \in X^{*(0)} \cup X^{*(1)}, \quad l = 1, \dots, L, \quad (16)$$

289 where $m_{\mathcal{F}}^l(x)$ aggregates messages from faces, and $m_{\mathcal{C}}^l(x)$ aggregates messages from cofaces:
 290

$$291 m_{\mathcal{F}}^{l+1}(x) = \text{AGG}_{y \in \mathcal{F}(x)} M_{\mathcal{F}}(\mathbf{h}_x^l, \mathbf{h}_y^l), \\ 292 m_{\mathcal{C}}^{l+1}(x) = \text{AGG}_{z \in \mathcal{C}(x)} M_{\mathcal{C}}(\mathbf{h}_x^l, \mathbf{h}_z^l), \quad (17)$$

294 with $\mathcal{F}(x)$ and $\mathcal{C}(x)$ denoting the sets of faces and cofaces of x .
 295

296 In the second stage, cells of all dimensions exchange information with higher-dimensional neigh-
 297 bors to capture multi-dimensional topological context. For each cell $x \in X^*$, the representation is
 298 updated as
 299

$$300 \mathbf{h}_x^{L+1} = \text{UPDATE}\left(\mathbf{h}_x^L, m_{\mathcal{F}}^L(x), m_{\mathcal{C}}^L(x), m_{\uparrow}^{L+1}(x)\right), \quad (18)$$

301 where $m_{\uparrow}^{L+1}(x)$ aggregates messages from adjacent cells via shared cofaces. Specifically, the mes-
 302 sages are defined as
 303

$$303 m_{\uparrow}^{L+1}(x) = \text{AGG}_{w \in \mathcal{N}_{\uparrow}(x)} M_{\uparrow}(\mathbf{h}_x^L, \mathbf{h}_w^L, \mathbf{h}_{x \cup w}^{L+1}), \quad (19)$$

304 with $\mathcal{N}_{\uparrow}(x)$ the set of cells adjacent to x via a shared coface.
 305

306 To generate a fixed-dimensional representation of the entire subcomplex, we aggregate the embed-
 307 dings of all its cells:
 308

$$309 \mathbf{h}_{X^*} = \text{POOL}\left(\{\mathbf{h}_x^{L+1} \mid x \in X^{*(0)} \cup X^{*(1)} \cup X^{*(2)}\}\right) \in \mathbb{R}^{d_s}, \quad (20)$$

310 where POOL can be implemented as mean pooling over the cell embeddings, and d_s denotes the
 311 dimension of the resulting subcomplex representation. This aggregated embedding \mathbf{h}_{X^*} encodes
 312 both the semantic attributes of individual cells and the multi-dimensional topological context of the
 313 subcomplex, serving as input to the *Cell Complex-Augmented Generation* module for query-guided
 314 answer generation.
 315

316 4.4 CELL COMPLEX-AUGMENTED GENERATION

317 With the subcomplex embedding \mathbf{h}_{X^*} obtained from the Multi-dimensional Topological Reasoning
 318 module, we integrate it into a pretrained LLM to guide query-aware answer generation. First, we
 319 align the subcomplex embedding to the LLM’s hidden space via a multilayer perceptron (MLP):
 320

$$321 \hat{\mathbf{h}}_{X^*} = \text{MLP}_{\phi}(\mathbf{h}_{X^*}) \in \mathbb{R}^{d_l}, \quad (21)$$

322 where d_l is the hidden dimension of the LLM. The projected vector $\hat{\mathbf{h}}_{X^*}$ acts as a soft prompt,
 323 providing structured, topologically-informed guidance to the LLM.
 324

To leverage the LLM’s text reasoning capabilities, we also transform the retrieved subcomplex into a textualized format, denoted as $\text{textualize}(X^*)$, by flattening the textual attributes of all cells while preserving the structural hierarchy. Given a natural language query x_q , we concatenate it with the textualized subcomplex and feed it into the LLM’s embedding layer:

$$\mathbf{h}_t = \text{TextEmbedder}([\text{textualize}(X^*); x_q]) \in \mathbb{R}^{L \times d_t}, \quad (22)$$

where $[\cdot; \cdot]$ denotes concatenation, L is the number of tokens, and the TextEmbedder is a frozen pretrained LLM embedding layer.

The final answer Y is generated autoregressively, conditioned on both the soft subcomplex prompt $\hat{\mathbf{h}}_{X^*}$ and the textual token embeddings \mathbf{h}_t :

$$p_{\theta, \phi}(Y \mid X^*, x_q) = \prod_{i=1}^r p_{\theta, \phi}(y_i \mid y_{<i}, [\hat{\mathbf{h}}_{X^*}; \mathbf{h}_t]), \quad (23)$$

where θ denotes the frozen LLM parameters and ϕ denotes the trainable parameters of the MLP and the subcomplex encoder. Gradients are backpropagated through $\hat{\mathbf{h}}_{X^*}$, enabling the subcomplex encoder to learn to generate embeddings that are optimally informative for downstream generation.

5 EXPERIMENTS

5.1 EXPERIMENT SETUP

Datasets. Following prior work He et al. (2024), we use three existing datasets: WebQSP Yih et al. (2016), ExplaGraphs Saha et al. (2021) and SceneGraphs Hudson & Manning (2019). These datasets are standardized into a uniform format suitable for graph question answering He et al. (2024), allowing consistent evaluation across diverse reasoning tasks. More details about these datasets are provided in Appendix D.

Comparison Methods. To evaluate the performance of TopoRAG, we consider three categories of baselines. We provide more details in Appendix E.

Inference-only LLMs directly answer questions using the textual graph as input, including zero-shot prompting, zero-shot Chain-of-Thought (Zero-CoT) Kojima et al. (2022), Build-a-Graph prompting (CoT-BAG) Wang et al. (2023), and KAPING Baek et al. (2023), a knowledge-augmented zero-shot approach; *Frozen LLMs with prompt tuning* keep model parameters fixed while optimizing the input prompt, including soft prompt tuning, GraphToken Perozzi et al. (2024), G-Retriever He et al. (2024) with a frozen LLM and SubgraphRAG Li et al. (2025); *Tuned LLMs* update model parameters using LoRA Hu et al. (2021), including standard LoRA fine-tuning and G-Retriever w/ LoRA He et al. (2024) combining retrieval augmentation with parameter-efficient tuning, GNN-RAG Mavromatis & Karypis (2025).

Evaluation Metrics. For ExplaGraphs and SceneGraphs, the performance is measured using Accuracy, which calculates the percentage of correctly predicted answers. For WebQSP, we use the Hit metric, which measures the percentage of queries for which at least one of the top returned answers is correct. This metric is particularly suitable for multi-hop reasoning tasks, where the model must traverse multiple hops in a knowledge graph to retrieve the correct answer.

Experiment Settings. All experiments are conducted on two NVIDIA A6000-48G GPUs. For retrieval, we set the top- k for 0- and 1-cells to $k = 3$ on WebQSP; on SceneGraphs, we set $k = 3$ for 0-cells and $k = 5$ for 1-cells. For 2-cells, we sweep the top- k over $k \in \{0, 1, 2, 3\}$. For reasoning, the number of layers is varied in $\{2, 3, 4, 5\}$, with a uniform dimensionality of 1024 across all layers (input, hidden, and output). For generation, we employ the Llama-2-7B model Touvron et al. (2023) as the large language model backbone. When fine-tuning with LoRA Hu et al. (2021), we set the rank `lora_r` = 8, `lora_alpha` = 16, and dropout rate = 0.05; for prompt tuning, we use 10 virtual tokens. The maximum input length is set to 512 tokens, and the maximum number of generated tokens is set to 32. We adopt the AdamW optimizer Loshchilov & Hutter (2017) with a learning rate of 1×10^{-5} , a batch size of 8, and train for 10 epochs with early stopping (patience = 2).

378 5.2 EXPERIMENT RESULT
379380 Table 1: Performance comparison across ExplaGraphs, SceneGraphs, and WebQSP datasets
381 under different configurations. The bold numbers indicate that the improvement of our model over
382 the baselines is statistically significant with (p-value < 0.01), and the best baseline results are
383 underlined
384

385 Setting	386 Method	387 ExplaGraphs	388 SceneGraphs	389 WebQSP
387 Inference-only	Zero-shot	0.5650	0.3974	41.06
	Zero-CoT	0.5704	0.5260	51.30
	CoT-BAG	0.5794	0.5680	39.60
	KAPING	0.6227	0.4375	52.64
391 Frozen LLM w/ PT	Prompt tuning	0.5763	0.6341	48.34
	GraphToken	0.8508	0.4903	57.05
	G-Retriever	0.8516	0.8131	70.49
	SubgraphRAG	0.8535	0.8074	86.61
	<i>TopoRAG (Ours)</i>	0.8899	0.8362	87.10
395 Tuned LLM	LoRA	0.8538	0.7862	66.03
	G-Retriever w/ LoRA	<u>0.8705</u>	<u>0.8683</u>	73.79
	GNN-RAG	0.8466	0.8149	85.70
	<i>TopoRAG w/ LoRA (Ours)</i>	0.9151	0.8768	90.66

401 **Main Results.** As summarized in Table 1, our model consistently outperforms all baselines across
402 datasets and configurations. We highlight three key findings:
403

- 404 • ***TopoRAG* delivers the strongest overall performance.** Compared to the best baseline,
405 *TopoRAG* improves ExplaGraphs and SceneGraphs Accuracy by 5.12% and 0.98%,
406 respectively; on WebQSP, it increases the Hit metric by 4.67%. We attribute the improve-
407 ments to the following reasons: 1) *Cellular Representation Lifting*, which transforms tex-
408 tual graphs into cellular complexes and explicitly encodes higher-dimensional structures
409 that support closed-loop relational reasoning; 2) *topology-aware subcomplex retriever* that
410 selects query-relevant cellular complexes, supplying compact yet informative topological
411 context; and 3) *multi-dimensional topological reasoning* that propagates information across
412 0-/1-/2-cells to enable structured, logic-aware inference tightly integrated with LLM rea-
413 soning. Together, these components overcome the limitations of node/edge-centric meth-
414 ods and yield more accurate and robust QA over complex textual graphs.
- 415 • **Graph-structured prompts effectively improve QA performance.** All prompt-tuning
416 approaches (e.g., GraphToken, SubgraphRAG) outperform inference-only baselines
417 (Zero-shot, Zero-CoT), underscoring the value of structured context. *TopoRAG* further
418 improves upon these by grounding prompts in higher-dimensional topological dependen-
419 cies—beyond nodes and edges—thereby providing richer, loop-aware relational context,
420 especially for queries involving multi-hop and cyclic dependencies.

421 **Ablation Study.** We conduct an ab-
422 lation study to evaluate the contribu-
423 tion of each component of TopoRAG.
424 Specifically, we replace *Cellular Rep-
425 resentation Lifting (CRL)* with a stan-
426 dard edge-based graph structure, sub-
427 stitute *Topology-aware Subcomplex Re-
428 trieval (TSR)* with shortest-path-based
429 retrieval, and replace *Multi-dimensional
430 Topological Reasoning (MTR)* with a
431 GCN Kipf & Welling (2017) for message
432 passing.421 Table 2: Ablation Study on ExplaGraphs and WebQSP
422 Datasets.

423 Method	424 ExplaGraphs (Accuracy)	425 WebQSP (Hit)
w/o CRL	0.8576	84.96
w/o TSR	0.8524	84.23
w/o MTR	0.8611	85.46
TopoRAG	0.9151	90.66

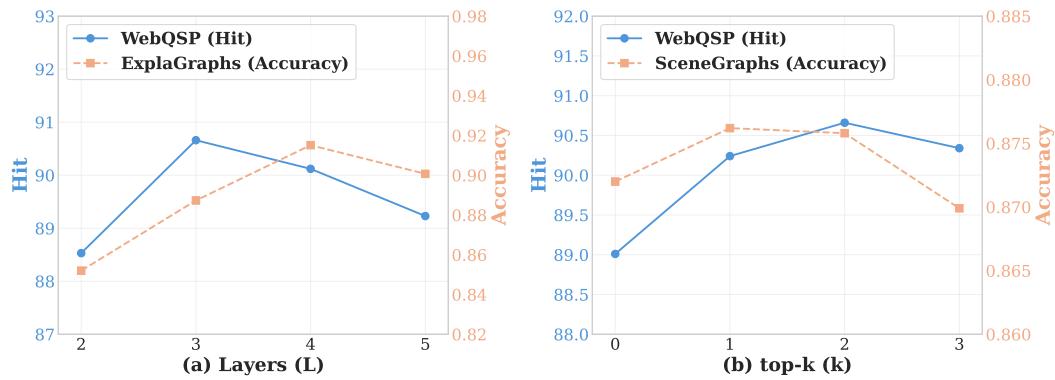


Figure 3: (a) Effect of layers $L \in \{2, 3, 4, 5\}$ on *TopoRAG* performance: WebQSP (Hit) and ExplaGraphs (Accuracy). (b) Effect of top- k $k \in \{0, 1, 2, 3\}$ on *TopoRAG* performance: WebQSP (Hit) and SceneGraphs (Accuracy).

- 1) Replacing *Cellular Representation Lifting (CRL)* with an edge-only graph representation removes the lifting of textual graphs into cellular complexes and, consequently, the explicit encoding of higher-dimensional structures (e.g., cycles) that support closed-loop relational reasoning. This loss of topological expressivity leads to a substantial performance drop, underscoring the necessity of CRL for modeling high-dimensional dependencies in RAG.
- 2) Replacing *Topology-aware Subcomplex Retrieval (TSR)* with shortest-path retrieval restricts results to the 1-skeleton and removes 2-cells, thereby discarding higher-dimensional motifs and closed-loop constraints that are critical for capturing query-relevant structure, underscoring the importance of TSR for sustaining *TopoRAG*'s effectiveness.
- 3) When removing *Multi-dimensional Topological Reasoning (MTR)*, the performance of *TopoRAG* drops significantly. This is due to the crucial role of MTR in enabling multi-dimensional message passing using cellular complexes. Without MTR, the model loses the ability to effectively propagate information from high-dimensional cells to low-dimensional ones, resulting in the loss of important high-dimensional structural information during the message passing process.

Hyper-parameter Study. We study the sensitivity of *TopoRAG* to two key hyperparameters: the number of layers L and the top- k of 2-cell for subcomplex retrieval. The layer depth L controls the model's ability to capture hierarchical structures and long-range dependencies. Larger L enhances the model's representational capacity but may lead to overfitting or increased computational cost, while smaller L may limit structural information capture, causing underfitting. Figure 3 (a) shows the effect of different L values on performance: reasoning ability improves as L increases, but excessive depth reduces expressiveness. We also analyze the impact of the top- k parameter for 2-cells selection on retrieval. Too small k causes information loss, while too large k introduces noise. Figure 3 (b) illustrates the effect of different $k \in \{0, 1, 2, 3\}$ values, showing that a moderate k achieves a better balance between structural coverage and noise. In Appendix F, we present an extended sensitivity analysis of the choice of k .

6 CONCLUSION

In this work, we introduced **TopoRAG**, a topology-enhanced retrieval-augmented generation framework for textual graph question answering. Unlike conventional GraphRAG approaches that mainly rely on nodes and edges, TopoRAG explicitly incorporates higher-dimensional topological structures by lifting textual graphs into cellular complexes. Through a topology-aware subcomplex retrieval mechanism, TopoRAG provides compact yet informative multi-dimensional contexts, while the proposed multi-dimensional topological reasoning module enables structured and logic-aware inference that captures cyclic and higher-dimensional dependencies beyond pairwise relations. Experimental results demonstrate that TopoRAG outperforms existing methods across three datasets from different domains.

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Table 3: Notation and definitions used in the TopoRAG framework.

Notation	Definition
\mathcal{G}	The input textual graph, defined as $\mathcal{G} = (V, E, \{t_n\}_{n \in V}, \{t_e\}_{e \in E})$.
V, E	The sets of vertices (nodes) and edges in the graph \mathcal{G} .
t_n, t_e	The text attributes associated with node $n \in V$ and edge $e \in E$.
X	The regular cell complex constructed from the graph \mathcal{G} .
$X^{(d)}$	d -skeleton.
x^k	A k -dimensional cell in the complex (e.g., x^0 : a 0-cell, x^1 : a 1-cell).
z_v^0, z_e^1	The d -dimensional embedding of node v (0-cell) and edge e (1-cell), obtained via a Language Model (LM).
\mathcal{T}	A spanning tree of the graph \mathcal{G} , used for cycle detection.
x_e^2	A 2-cell attached to a fundamental cycle induced by a non-tree edge $e \in E \setminus \mathcal{T}$.
z_q	The d -dimensional embedding of the input query x_q .
$\mathcal{X}_k^{(d)}$	The set of top- k retrieved d -cells ($d = 0, 1, 2$) based on semantic similarity or prize.
$\text{prize}(x^i)$	The prize (relevance score) assigned to cell x^i during retrieval.
X^*	The final retrieved and connected subcomplex, $X^* = X^{(0)*} \cup X^{(1)*} \cup X^{(2)*}$.
$\partial_k x$	The boundary operator; $\partial_k x$ gives the set of $(k-1)$ -cells on the boundary of a k -cell x .
\mathbf{h}_x^l	The hidden representation of cell x at message passing layer l .
$\mathcal{F}(x), \mathcal{C}(x)$	The set of faces (lower-dimensional boundary cells) and cofaces (higher-dimensional incident cells) of cell x .
$m_{\mathcal{F}}^l(x), m_{\mathcal{C}}^l(x)$	Messages aggregated from faces and cofaces of cell x at layer l .
\mathbf{h}_{X^*}	The final pooled representation of the entire subcomplex X^* .
$\hat{\mathbf{h}}_{X^*}$	The projected subcomplex embedding, aligned to the LLM’s hidden space via an MLP.
$p_{\theta, \phi}(Y X^*, x_q)$	The conditional probability of generating answer Y , given the subcomplex X^* and query x_q .

A NOTATIONS

The notations in the TopoRAG framework are summarized in Table 3.

B ADDITIONAL RELATED WORK

Graphs and Large Language Models. In parallel, there has been a surge of interest in combining graphs with LLMs Pan et al. (2023); Li et al. (2023b); Jin et al. (2023); Wang et al. (2023); Zhang et al. (2023). This line of research spans a wide spectrum, from the design of general graph models Ye et al. (2023); Liu et al. (2023); Yu et al. (2023b); Lei et al. (2023); Tang et al. (2023); Perozzi et al. (2024), to multi-modal architectures Li et al. (2023a); Yoon et al. (2023), and diverse downstream applications.

Applications of Graph-augmented LLMs include fundamental graph reasoning Zhang (2023); Chai et al. (2023); Zhao et al. (2023b), node classification He et al. (2023); Huang et al. (2023a); Sun et al. (2023); Chen et al.; Yu et al. (2023a); Chen et al. (2024); Qin et al. (2023), and graph classification/regression Qian et al. (2023); Zhao et al. (2023a). Furthermore, LLMs have been increasingly employed for knowledge graph-related tasks such as reasoning, completion, and question answering Tian et al. (2023); Jiang et al. (2023); Luo et al. (2023).

Topological deep learning. Topological deep learning expands graph learning by modelling relations that exceed simple pairwise links. Early work in Topological Signal Processing (TSP) emphasized the value of higher-dimensional structure for signal and relational modeling Barbarossa & Sardellitti (2020); Schaub et al. (2021); Roddenberry et al. (2022); Sardellitti et al. (2021), prompting extensions of graph tools to richer discrete geometries such as simplicial and cell complexes. Theoretical progress—e.g., higher-dimensional generalizations of the Weisfeiler–Lehman test—has clar-

ified the expressive power required for distinguishing complex topologies and motivated message-passing schemes beyond traditional GNNs Bodnar et al. (2021c;a).

On the modelling side, researchers have proposed numerous neural architectures that operate on these higher-dimensional domains, including convolutional-style operators for simplicial and cell complexes Ebli et al. (2020); Yang et al. (2022); Hajij et al. (2020); Yang & Isufi (2023); Roddenberry et al. (2021); Hajij et al. (2022) and attention-based formulations that incorporate incidence relations and coface interactions Goh et al.; Giusti et al. (2023). Efforts to unify these variants led to combinatorial-complex frameworks that generalize message passing to a wide class of combinatorial objects (simplicial complexes, CW complexes, hypergraphs) Hajij et al. (2023). Complementary lines of work use sheaf-theoretic constructions to impose local consistency and handle heterophilous patterns, demonstrating another principled route to encode localized topological constraints Hansen & Ghrist (2019); Hansen & Gebhart (2020); Bodnar et al. (2022); Battiloro et al. (2023; 2024); Barbero et al. (2022).

While these works have substantially advanced higher-dimensional representation learning, current topological deep learning methods exhibit limited generalization to unseen graphs with substantially different topologies, a sensitivity that hinders their applicability in real-world scenarios where structural variability is common. Moreover, they remain largely tied to static, pre-defined complexes and traditional graph formulations, leaving them ill-suited for reasoning in question answering tasks that require integrating textual graph inputs with large language models and dynamically incorporating external knowledge. In this work, we address these limitations by introducing TopoRAG, a framework that explicitly models multi-dimensional topological structures and couples topology-aware retrieval with large language models to enable robust and context-sensitive reasoning over textual graphs.

C PROOFS

C.1 PROOFS REGARDING PROPOSITION 1

Proof. Contractibility of the spanning tree. A spanning tree \mathcal{T} is connected and acyclic, hence it is contractible. In topological terms, a contractible subspace can be continuously shrunk to a point within itself.

Collapsing a contractible subspace. Consider the quotient map $\gamma : G \rightarrow G/\mathcal{T}$ that identifies all points of \mathcal{T} to a single vertex v_0 . Collapsing a contractible subspace is a deformation retraction up to homotopy: there exists a continuous map $r : G \rightarrow G/\mathcal{T}$ and a homotopy $H : G \times [0, 1] \rightarrow G$ such that $H(x, 0) = x$ and $H(x, 1) = r(x)$ for all $x \in G$, with $r \circ \gamma \simeq \text{id}_{G/\mathcal{T}}$. Therefore, G and G/\mathcal{T} are homotopy-equivalent.

Induced isomorphism on first homology. Homotopy-equivalent spaces have isomorphic homology groups. Hence the induced map $\gamma_* : H_1(G; \mathbb{Z}) \rightarrow H_1(G/\mathcal{T}; \mathbb{Z})$ is an isomorphism.

Intuition in graph terms. The spanning tree \mathcal{T} contains no cycles, so collapsing it does not remove or merge any cycles in G . Each fundamental cycle in G (formed by a non-tree edge and the unique tree path connecting its endpoints) is preserved in G/\mathcal{T} as a loop based at the collapsed tree vertex. Therefore, the first homology group $H_1(G)$ — which measures independent cycles — remains unchanged. \square

C.2 PROOFS REGARDING PROPOSITION 2

Proof. Let $G = (V, E)$ be a finite connected graph and $\mathcal{T} \subset G$ a spanning tree.

Existence and uniqueness of fundamental cycles. For each non-tree edge $e = (u, v) \in E \setminus \mathcal{T}$, there exists a unique simple path $P_{\mathcal{T}}(u, v)$ in \mathcal{T} connecting u and v , by acyclicity of \mathcal{T} . Concatenating e with $P_{\mathcal{T}}(u, v)$ defines a unique simple cycle

$$C_e = e \cup P_{\mathcal{T}}(u, v) \subset G.$$

Under the quotient map $\gamma : G \rightarrow G/\mathcal{T}$ that collapses \mathcal{T} to a point, the tree-path $P_{\mathcal{T}}(u, v)$ is mapped to that point, so $C_{\mathcal{C}}$ becomes a nontrivial loop in G/\mathcal{T} .

864 **Spanning and independence in homology.** The cyclomatic number of G is $\beta_1(G) = |E| - |V| + 1$,
 865 which equals the number of non-tree edges. Thus there are exactly $\beta_1(G)$ fundamental cycles.
 866

867 Any cycle in G can be expressed as a linear combination of these fundamental cycles: traversing a
 868 cycle, each time a non-tree edge e is encountered, the corresponding C_e can be used to eliminate
 869 segments along \mathcal{T} .

870 These cycles are independent in $H_1(G)$, because under γ , each fundamental cycle maps to a distinct
 871 loop in G/\mathcal{T} , and loops around different edges of a wedge of circles are linearly independent in
 872 homology.

873 Hence the set

$$\{[C_e] \mid e \in E \setminus \mathcal{T}\}$$

876 forms a basis of $H_1(G)$.

877 **Topological summary.** Different choices of spanning tree yield different sets of fundamental cycles
 878 as edge sets, but the corresponding homology classes always span $H_1(G)$. Therefore, these loops
 879 capture all independent cyclic dependencies of G , providing a concise topological summary suitable
 880 for lifting G into a higher-dimensional cell complex. \square

882 D DATASETS

884 Following prior work He et al. (2024), we use three existing datasets: WebQSP, ExplaGraphs
 885 and SceneGraphs, which are summarized in Table 4. These datasets are standardized into a uni-
 886 form format suitable for graph question answering, allowing consistent evaluation across diverse
 887 reasoning tasks. ExplaGraphs focuses on generative commonsense reasoning. The task requires
 888 predicting whether an argument supports or contradicts a given belief, evaluated using Accuracy.
 889 SceneGraphs is a visual question answering dataset. The task is to answer questions based on
 890 textualized scene graphs, requiring spatial reasoning and multi-step inference, evaluated by Accu-
 891 racy. WebQSP is a large-scale multi-hop knowledge graph QA dataset, which contains facts within
 892 2-hops of entities mentioned in the questions. Each question is associated with a subgraph extracted
 893 from Freebase. The task involves multi-hop reasoning, evaluated using Hit for the top returned
 894 answer.

895 Table 4: Overview of datasets used in the GraphQA benchmark.

898 Dataset	ExplaGraphs	SceneGraphs	WebQSP
900 Number of Graphs	2,766	100,000	4,737
901 Average Nodes	5.17	19.13	1,370.89
902 Average Edges	4.25	68.44	4,252.37
903 Node Features	Commonsense concepts	Object properties (e.g., color, shape)	Freebase entities
904 Edge Features	Commonsense relations	Object interactions and spatial relations	Freebase relations
905 Task Type	Commonsense reasoning	Scene graph QA	Knowledge graph QA
Evaluation Metric	Accuracy	Accuracy	Hit

907 E COMPARISON METHODS

910 In our experiments, we consider three categories of baselines: 1) *Inference-only*, 2) *Frozen LLM w/
 911 prompt tuning (PT)*, 3) *Tuned LLM*. The details of each baseline are described as follows.

913 **Inference-only.** Using a frozen LLM for direct question answering with textual graph and ques-
 914 tion.

916

- 917 • Zero-shot. In this approach, the model is given a textual graph description and a task de-
 918 scription, and is immediately asked to produce the desired output. No additional examples
 919 or demonstrations are provided.

- 918 • Zero-CoT. Zero-shot Chain-of-thought (Zero-CoT) prompting (Kojima et al., 2022) is a
919 follow-up to CoT prompting (Wei et al., 2022), which introduces an incredibly simple zero
920 shot prompt by appending the words "Let's think step by step." to the end of a question.
921
- 922 • CoT-BAG. Build-a-Graph Prompting (BAG) (Wang et al., 2023) is a prompting technique
923 that adds "Let's construct a graph with the nodes and edges first." after the textual descrip-
924 tion of the graph is explicitly given.
925
- 926 • KAPING. KAPING (Baek et al., 2023) is a zero-shot knowledge-augmented prompting
927 method for knowledge graph question answering. It first retrieves triples related to the
928 question from the graph, then prepends them to the input question in the form of a prompt,
929 which is then forwarded to LLMs to generate the answer.
930

Frozen LLM w/ prompt tuning (PT). Keeping the parameters of the LLM frozen and adapting only the prompt.

- 932 • GraphToken (Perozzi et al., 2024), which is a graph prompt tuning method.
933
- 934 • G-Retriever He et al. (2024) is an efficient and lightweight model that adapts frozen large
935 language model parameters to graph question answering tasks solely through trainable
936 graph-structured soft prompts.
937
- 938 • SubgraphRAG Li et al. (2025) is a retrieval-augmented generation framework based on
939 knowledge graphs, which effectively improves the accuracy, efficiency, and interpretability
940 of question answering through lightweight subgraph retrieval and inference with an untuned
941 large language model.
942

Tuned LLM. Fine-tuning the LLM with LoRA.

- 944 • G-Retriever (w/ LoRA) He et al. (2024) is a high-precision model that fine-tunes large
945 language model parameters using techniques such as LoRA, enabling deep integration of
946 graph structure information to enhance graph question answering performance.
947
- 948 • GNN-RAG Mavromatis & Karypis (2025) is a retrieval-augmented generation framework
949 based on graph neural networks, which efficiently retrieves multi-hop reasoning paths from
950 knowledge graphs using GNNs and inputs them as context to an LLM, enhancing the ac-
951 curacy and efficiency of complex knowledge graph question answering.
952

F IMPACT OF TOP- K SELECTION ON SUBCOMPLEX RETRIEVAL

To further quantify the influence of k on subcomplex retrieval, we conduct supplementary experiments with $k \in \{1, 2, 3\}$ and report, on WebQSP and SceneGraphs, the average numbers of 0-, 1-, and 2-cells per retrieved subcomplex. As shown in Table 5, larger k yields more retrieved 2-cells; the accompanying inclusion of higher-dimensional structures also increases the counts of 0- and 1-cells, underscoring the trade-off that k introduces between structural coverage and noise.

960 Table 5: Impact of Top- K Selection on Subcomplex Retrieval.
961

963 Dataset	k	964 Number of Cells per Dimension		
		965 0-cells	966 1-cells	967 2-cells
968 WebQSP	1	9	12	4
	2	9	13	5
	3	9	14	6
969 SceneGraphs	1	15	17	2
	2	16	18	3
	3	17	20	4

972 **G DISCUSSION ON THE COMPLEXITY**
973

974 Following prior work, TopoRAG adopts the LLM+X framework, which enhances LLMs with multi-
975 modal capabilities by integrating them with encoders from other modalities. In recent years, the
976 LLM+X framework has been widely adopted in various RAG methods. Notable examples include:
977 1) KG+LLM approaches, such as RoG, ToG, StructGPT, and KAPING, and 2) GNN+LLM ap-
978 proaches, including G-Retriever and GNN-RAG. These models have demonstrated strong perfor-
979 mance in both efficiency and accuracy. Furthermore, we introduce Topo+LLM.

980 Regarding the integration of topological methods into RAG, it does not significantly increase the
981 time or computational complexity associated with LLM-based answer generation, as both cellular
982 complex construction and subcomplex retrieval are implemented during the preprocessing phase.

983 In contrast to G-Retriever, we use a more complex *Multi-dimensional Topological Reasoning*
984 to capture high-dimensional topological structures, which introduces some additional time over-
985 head. However, the benefits achieved outweigh the costs. To validate this, we conducted experi-
986 ments using two A6000-48G GPUs with Llama2-7b as the LLM, training on ExplaGraphs and
987 SceneGraphs. Detailed experimental settings are provided in Appendix C. The results in Table 6
988 show that, compared to baseline methods, our approach incurs only a slight increase in runtime, yet
989 significantly improves model performance.

990
991 Table 6: Performance and Efficiency Comparison of TopoRAG and G-Retriever on ExplaGraphs
992 and SceneGraphs Datasets.

994 995 996 997 998 999 1000 1001 1002 1003 1004 1005 1006 1007 1008 1009 1010 1011 1012 1013 1014 1015 1016 1017 1018 1019 1020 1021 1022 1023 1024 1025	Setting	Method	ExplaGraphs		SceneGraphs	
			Hit	Time	Accuracy	Time
Frozen LLM w/ PT	G-Retriever	0.8516	2.6 min/epoch	0.8131	267 min/epoch	
		0.8899	3.0 min/epoch	0.8362	300 min/epoch	
Tuned LLM	G-Retriever w/ LoRA	0.8705	3.0 min/epoch	0.8683	285 min/epoch	
	TopoRAG w/ LoRA	0.9151	3.3 min/epoch	0.8768	310 min/epoch	

H ALGORITHMS

1004
1005 **Cellular Representation Lifting Algorithm.** We present Algorithm 1, which formally describes
1006 the Cellular Representation Lifting process outlined in Section 4.1. The algorithm takes a textual
1007 graph \mathcal{G} and lifts it into a regular cell complex X endowed with feature representations for all its
1008 cellular substructures. The algorithm proceeds in two main phases.

1009 The first phase (Lines 1–15) constructs the **1-skeleton** ($X^{(1)}$) of the complex. It initializes the sets
1010 of 0-cells ($X^{(0)}$) and 1-cells ($X^{(1)}$) and their corresponding feature dictionaries ($\mathbf{Z}^0, \mathbf{Z}^1$). For each
1011 vertex $v \in V$, a 0-cell x_v^0 is instantiated, and its representation z_v^0 is obtained by encoding the
1012 vertex’s text attribute t_v using a pre-trained language model (LM). Similarly, for each edge $e \in E$,
1013 a 1-cell x_e^1 is created, attached to the 0-cells of its endpoints, and its representation z_e^1 is computed
1014 from the edge text t_e .

1015 The second phase (Lines 16–28) augments the 1-skeleton with **2-cells** to capture higher-dimensional
1016 topological information. A spanning tree \mathcal{T} of \mathcal{G} is computed, whose complement $E_{\text{non-tree}}$ defines
1017 the set of fundamental cycles in the graph. For each non-tree edge $e \in E_{\text{non-tree}}$, the algorithm
1018 identifies the corresponding fundamental cycle by finding the unique path between the endpoints of
1019 e in \mathcal{T} and appending e itself (as detailed in the subroutine Algorithm 2). A 2-cell x_e^2 is then created
1020 and attached to this cycle. The initial representation z_e^2 for the 2-cell is computed by aggregating
1021 (e.g., via mean pooling) the representations of all the 0-cells and 1-cells that constitute its boundary
1022 cycle. This provides an inductive bias that initializes the feature of a higher-dimensional cavity
1023 based on the features of its lower-dimensional boundaries.

1024 Finally, the complete cell complex X is formed by the union of all cells across dimensions (Line 30).
1025 The algorithm returns both the topological structure X and the associated features $\mathbf{Z}^0, \mathbf{Z}^1, \mathbf{Z}^2$, which
serve as the input for subsequent cellular message-passing networks (Bodnar et al., 2021b). This

1026 lifting procedure effectively transforms a plain graph into a richer topological domain, explicitly
 1027 encoding relational cycles as tangible geometric entities.
 1028

1029 **Topology-aware Subcomplex Retrieval Algorithm.** Algorithm 3 formalizes the Topology-aware
 1030 Subcomplex Retrieval process outlined in Section 4.2. The algorithm takes as input the cell complex
 1031 X with precomputed cellular embeddings, a textual query x_q , and parameters k and C_2 . It returns
 1032 a connected subcomplex X^* that maximizes the relevance prize under topological constraints. The
 1033 procedure operates in three distinct phases.

1034 The first Phase is Query-based Cell Retrieval (Lines 1–7). The algorithm begins by encoding the
 1035 query x_q into an embedding z_q using the language model (LM). It then computes the cosine simi-
 1036 larity between z_q and the embeddings of all 0-cells and 1-cells. The top- k most similar cells from
 1037 each dimension are selected, forming the initial sets of highly relevant candidates, $X_k^{(0)}$ and $X_k^{(1)}$.
 1038

1039 The second Phase is Multi-dimensional Prize Assignment (Lines 9–26). This phase assigns a prize
 1040 value to each cell, quantifying its incentive for inclusion in the final subcomplex. Prizes for the
 1041 top- k 0-cells and 1-cells are assigned in descending order based on their similarity ranking (e.g., the
 1042 highest-ranked cell receives a prize of k). For a 2-cell x^2 , its prize is computed inductively as the
 1043 sum of the prizes of all its boundary 0-cells and 1-cells, minus a cost penalty $\text{cost}(x^2) = |\partial_1 x^2| \cdot C_2$
 1044 that discourages the selection of overly large faces. This design propagates relevance signals from
 1045 lower-dimensional cells to the higher-dimensional structures they define. Finally, the top- k 2-cells
 1046 by prize, denoted $X_k^{(2)}$, are selected.

1047 The last phase is Prize-Collecting Steiner Subcomplex Extraction (Lines 28–34). The core challenge
 1048 is to extract a *connected* subcomplex that includes high-prize cells while respecting the *boundary*
 1049 *consistency constraints* (i.e., if a 2-cell is selected, all its boundary cells must also be included). We
 1050 model this as a Prize-Collecting Steiner Tree (PCST) problem on a hypergraph representation G_{hyper}
 1051 of the cell complex, where 2-cells are modeled as hyperedges. The set $R_{\text{terminals}}$ consists of the top- k
 1052 cells from all dimensions, and the prize function \mathcal{P} is defined from the previous phase. Solving
 1053 this generalized PCST problem yields a connected subcomplex X^* that approximates the optimal
 1054 trade-off between total collected prize and the cost of the required connecting cells. We employ a
 1055 near-linear time approximation algorithm (Hegde et al., 2015) to ensure computational feasibility.

1056 The algorithm’s output, X^* , provides a coherent, query-focused topological summary of the original
 1057 complex, which can be directly utilized for downstream tasks such as reasoning or explanation
 1058 generation.

1059 I STATEMENT

1060 **Ethics Statement.** This research follows the ICLR Code of Ethics. The work does not involve
 1061 experiments with human participants, collection of personal data, or sensitive information. All
 1062 datasets employed are publicly released and widely used in prior studies. The proposed framework is
 1063 intended to advance topology-aware retrieval and reasoning in textual graphs for question answering,
 1064 and we do not anticipate direct societal risks or harmful misuse. Potential biases have been carefully
 1065 considered, and we adopt standard practices to minimize unintended artifacts. No external funding
 1066 sources or conflicts of interest influenced the conduct of this work.

1067 **Reproducibility Statement.** To support reproducibility, all datasets are publicly available and
 1068 preprocessing procedures are documented in the main text or supplementary material. We provide
 1069 a complete implementation as part of the supplementary package, which enables replication of our
 1070 experiments without additional dependencies. Hyperparameters, training configurations, and eval-
 1071 uation protocols are described in detail to facilitate verification and future extensions.

1072 **LLM Usage.** We acknowledge the use of large language models (LLMs) as auxiliary tools for
 1073 improving readability and clarity of writing. The conceptual development, methodology design,
 1074 experimental setup, and analysis were entirely conducted and validated by the authors. LLMs were
 1075 not used to generate novel research ideas nor to contribute to technical content.

1080
 1081
 1082 **Algorithm 1** Cellular Lifting of Textual Graphs

1083 **Require:** Textual graph $\mathcal{G} = (V, E, \{t_v\}_{v \in V}, \{t_e\}_{e \in E})$, pre-trained language model $\text{LM}(\cdot)$.
 1084 **Ensure:** A regular cell complex X with cellular embeddings $\{z_v^0\}, \{z_e^1\}, \{z_e^2\}$.

1085 1: **Step 1: Construct the 1-Skeleton and Compute Initial Embeddings**
 1086 2: $X^{(0)} \leftarrow \emptyset, X^{(1)} \leftarrow \emptyset$ {Initialize sets of 0-cells and 1-cells}
 1087 3: $\mathbf{Z}^0 \leftarrow \{\}, \mathbf{Z}^1 \leftarrow \{\}$ {Initialize dictionaries for embeddings}
 1088 4: **for** $v \in V$ **do**
 1089 5: Create a 0-cell x_v^0 for vertex v
 1090 6: $X^{(0)} \leftarrow X^{(0)} \cup \{x_v^0\}$
 1091 7: $z_v^0 \leftarrow \text{LM}(t_v)$ {Encode vertex text attribute}
 1092 8: $\mathbf{Z}^0[x_v^0] \leftarrow z_v^0$
 1093 9: **end for**
 1094 10: **for** $e = (u, v) \in E$ **do**
 1095 11: Create a 1-cell x_e^1 attached to x_u^0 and x_v^0
 1096 12: $X^{(1)} \leftarrow X^{(1)} \cup \{x_e^1\}$
 1097 13: $z_e^1 \leftarrow \text{LM}(t_e)$ {Encode edge text attribute}
 1098 14: $\mathbf{Z}^1[x_e^1] \leftarrow z_e^1$
 1099 15: **end for**
 1100 16: $X^{(1)} \leftarrow X^{(0)} \cup X^{(1)}$ {The 1-skeleton is complete}
 1101 17:
 1102 18: **Step 2: Augment with 2-Cells to Capture Higher-Dimensional Structures**
 1103 19: $X^{(2)} \leftarrow \emptyset$
 1104 20: $\mathbf{Z}^2 \leftarrow \{\}$
 1105 21: $\mathcal{T} \leftarrow \text{SpanningTree}(\mathcal{G})$ {e.g., using BFS or DFS}
 1106 22: $E_{\text{non-tree}} \leftarrow E \setminus \mathcal{T}$
 1107 23: **for** $e \in E_{\text{non-tree}}$ **do**
 1108 24: $u, v \leftarrow \text{endpoints}(e)$
 1109 25: cycle $\leftarrow \text{FindFundamentalCycle}(e, \mathcal{T})$
 1110 26: {cycle is the unique path from u to v in \mathcal{T} plus edge e }
 1111 27: Create a 2-cell x_e^2
 1112 28: Attach x_e^2 to the 1-skeleton via the attaching map $\varphi_e : \partial D^2 \rightarrow \text{cycle}$
 1113 29: $X^{(2)} \leftarrow X^{(2)} \cup \{x_e^2\}$
 1114 30: $z_e^2 \leftarrow \text{AggregateCycleEmbeddings}(\text{cycle}, \mathbf{Z}^0, \mathbf{Z}^1)$
 1115 31: {e.g., mean/max pooling of embeddings of all 0/1-cells in the cycle}
 1116 32: $\mathbf{Z}^2[x_e^2] \leftarrow z_e^2$
 1117 33: **end for**
 1118 34:
 1119 35: $X \leftarrow X^{(0)} \cup X^{(1)} \cup X^{(2)}$ {The final cell complex}
 36:
 37: **return** $X, \mathbf{Z}^0, \mathbf{Z}^1, \mathbf{Z}^2$

1120
 1121
 11221123 **Algorithm 2** Find Fundamental Cycle

1124 **Require:** Non-tree edge $e = (u, v)$, spanning tree \mathcal{T} .
 1125 **Ensure:** An ordered list of 0-cells and 1-cells forming the fundamental cycle.

1126 1: $\text{path_u_to_v} \leftarrow \text{GetUniquePathInTree}(u, v, \mathcal{T})$
 1127 2: $\text{cycle_vertices} \leftarrow \text{path_u_to_v.vertices}$
 1128 3: $\text{cycle_edges} \leftarrow \text{path_u_to_v.edges}$
 1129 4: $\text{cycle_edges.append}(e)$ {Add the non-tree edge to complete the cycle}
 1130 5:
 1131 6: **return** $\text{cycle_vertices}, \text{cycle_edges}$

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 1133

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 1139 **Algorithm 3** Topology-Aware Subcomplex Retrieval

 1140
 1141 **Require:** Cell complex $X = X^{(0)} \cup X^{(1)} \cup X^{(2)}$ with embeddings $\mathbf{Z}^0, \mathbf{Z}^1, \mathbf{Z}^2$; query x_q ; parameters
 k, C_2 .
 1142 **Ensure:** A connected, topology-aware subcomplex $X^* \subseteq X$.
 1143 1: **Step 1: Encode Query and Retrieve Top- k Cells**
 1144 2: $z_q \leftarrow \text{LM}(x_q)$ {Encode the query}
 1145 3: $S^0 \leftarrow \text{ComputeCosineSimilarity}(z_q, \mathbf{Z}^0)$ { S^0 is a list of (cell, score) pairs for all 0-cells}
 1146 4: $S^1 \leftarrow \text{ComputeCosineSimilarity}(z_q, \mathbf{Z}^1)$ { S^1 is a list of (cell, score) pairs for all 1-cells}
 1147 5: $X_k^{(0)} \leftarrow \text{ArgTopK}(S^0, k)$ {Set of top- k relevant 0-cells}
 1148 6: $X_k^{(1)} \leftarrow \text{ArgTopK}(S^1, k)$ {Set of top- k relevant 1-cells}
 1149 7:
 1150 8: **Step 2: Prize Assignment**
 1151 9: $\mathcal{P} \leftarrow \{\}$ {Initialize a prize dictionary for all cells}
 1152 10: // Assign prizes to top- k 0/1-cells based on ranking
 1153 11: rank $\leftarrow 0$
 1154 12: **for** $x^0 \in X_k^{(0)}$ (in descending order of similarity) **do**
 1155 13: $\mathcal{P}[x^0] \leftarrow k - \text{rank}$
 1156 14: rank $\leftarrow \text{rank} + 1$
 1157 15: **end for**
 1158 16: rank $\leftarrow 0$
 1159 17: **for** $x^1 \in X_k^{(1)}$ (in descending order of similarity) **do**
 1160 18: $\mathcal{P}[x^1] \leftarrow k - \text{rank}$
 1161 19: rank $\leftarrow \text{rank} + 1$
 1162 20: **end for**
 1163 21: // Compute prizes for 2-cells based on boundary cells
 1164 22: **for** $x^2 \in X^{(2)}$ **do**
 1165 23: boundary_prize $\leftarrow 0$
 1166 24: **for each** $x^0 \in \partial_0 x^2$ **do** boundary_prize $\leftarrow \text{boundary_prize} + \mathcal{P}.\text{get}(x^0, 0)$
 1167 25: **for each** $x^1 \in \partial_1 x^2$ **do** boundary_prize $\leftarrow \text{boundary_prize} + \mathcal{P}.\text{get}(x^1, 0)$
 1168 26: cost $\leftarrow |\partial_1 x^2| \cdot C_2$ {Penalize larger faces}
 1169 27: $\mathcal{P}[x^2] \leftarrow \text{boundary_prize} - \text{cost}$
 1170 28: **end for**
 1171 29: $X_k^{(2)} \leftarrow \text{ArgTopK}(\{\mathcal{P}[x^2] \text{ for } x^2 \in X^{(2)}\}, k)$ {Select top- k 2-cells by prize}
 30:
 1172 31: **Step 3: Prize-Collecting Subcomplex Selection**
 1173 32: $V \leftarrow X^{(0)} \cup X^{(1)} \cup X^{(2)}$ {Candidate cells across all dimensions}
 1174 33: $R \leftarrow X_k^{(0)} \cup X_k^{(1)} \cup X_k^{(2)}$ {Top- k cells as prize terminals}
 1175 34: // Assign prizes to 0- and 1-cells based on query similarity
 1176 35: // Compute 2-cell prizes from boundary consistency with selected cells
 1177 36:
 1178 37: $X^* \leftarrow \text{ApproxPCSTComplex}(X, R, \mathcal{P})$
 1179 38: {Solve generalized PCST over cell complex with multi-dimensional prizes}
 1180 39: // Enforce boundary consistency: any 2-cell in X^* must share boundary with chosen 0-
 1181 and 1-cells
 1182 40:
 1183 41: **return** X^*

 1184
 1185
 1186
 1187