
Causal Attribution of Model Performance Gaps in Medical Imaging Under Distribution Shifts

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Abstract

1 Deep learning models for medical image segmentation suffer significant performance
2 drops due to distribution shifts, but the causal mechanisms behind these drops remain poorly understood. We extend causal attribution frameworks to
3 high-dimensional segmentation tasks, quantifying how acquisition protocols and
4 annotation variability independently contribute to performance degradation. We
5 model the data-generating process through a causal graph and employ Shapley
6 values to fairly attribute performance changes to individual mechanisms. Our
7 framework addresses unique challenges in medical imaging: high-dimensional
8 outputs, limited samples, and complex mechanism interactions. Validation on
9 multiple sclerosis (MS) lesion segmentation across 4 centers and 7 annotators
10 reveals context-dependent failure modes: annotation protocol shifts dominate when
11 crossing annotators ($7.4\% \pm 8.9\%$ DSC attribution), while acquisition shifts dom-
12 inate when crossing imaging centers ($6.5\% \pm 9.1\%$). This mechanism-specific
13 quantification enables practitioners to prioritize targeted interventions based on
14 deployment context. Our code is available at anonymous repository.
15

16 1 Introduction

17 Medical image segmentation models excel in controlled settings but exhibit unpredictable perfor-
18 mance drops in clinical deployments [1, 2]. Unlike classification tasks where shifts have been
19 studied [3, 4, 5], segmentation presents unique challenges: spatial correlations, high-dimensional
20 outputs that interact non-linearly with distribution shifts, etc.[1, 6]. Consider a white matter lesion
21 (WML) segmentation model underperforming at a new hospital. The failure could stem from scanner
22 changes (acquisition shift), inconsistent radiologist annotations (annotation shift), or demographic
23 changes (population shift) [1]. Existing domain generalization methods treat these shifts monolith-
24 ically, offering no insight into which mechanisms drive performance degradation [7]. We address
25 this gap by extending causal attribution frameworks [3, 5] from low-dimensional classification to
26 high-dimensional segmentation tasks. Our approach leverages the principle of Independent Causal
27 Mechanisms (ICM) [8] to model the medical imaging data-generating process (DGP) [1, 9], and
28 employs Shapley values to quantify each mechanism’s contribution to performance drops.

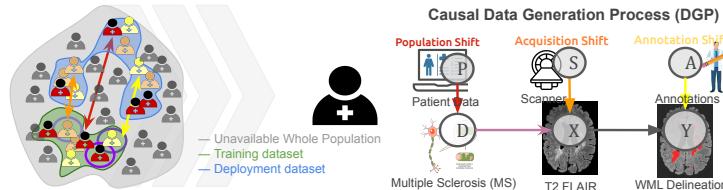


Figure 1: Causal modeling of domain shifts in medical imaging. We attribute performance degradation to shifts in acquisition ($P(X|S, D = \text{MS})$) versus annotation ($P(Y|X, A)$) mechanisms.

29 **2 Methods**

30 We model the DGP for segmentation task via a causal graph as in Figure 1. Following the ICM
 31 principle [8, 10], the joint distribution factorizes as: $P(V) = \prod_{i=1}^n P(V_i \mid \mathbf{PA}_i)$, where $V =$
 32 $\{V_1, \dots, V_n\}$ represents the system variables (demographics, images, annotations), and \mathbf{PA}_i denotes
 33 the parent variables of V_i . This factorization remains structurally invariant across environments,
 34 though the individual mechanism, $P_{V_i \mid \mathbf{PA}_i}$, distributions may shift. Then, let f denote a model trained
 35 on data from a training environment ϵ_{tr} , later deployed in environment ϵ_{dep} , and M an assessment
 36 metric. Performance change between ϵ_{tr} - ϵ_{dep} is defined as $\Delta M = M(f, P^{\epsilon_{tr}}) - M(f, P^{\epsilon_{dep}})$. ΔM
 37 can be causally attributed to shifts in the distributions of individual mechanisms. Through a causal
 38 lens, the transition from ϵ_{tr} to ϵ_{dep} is explained through a set of intervened (shifted) mechanisms. For
 39 any subset of mechanism indices $\mathcal{I} \subseteq \{1, 2, \dots, n\}$, we define a mixed distribution $P_{\mathcal{I}}$ where only
 40 mechanisms in \mathcal{I} are intervened upon:

$$P_{\mathcal{I}}(V) = P(V_{i \notin \mathcal{I}}, \text{do}(V_{i \in \mathcal{I}} = V_i^{\epsilon_{dep}})) = \prod_{i \in \mathcal{I}} P_{V_i \mid \mathbf{PA}_i}^{\epsilon_{dep}} \prod_{i \notin \mathcal{I}} P_{V_i \mid \mathbf{PA}_i}^{\epsilon_{tr}} \quad (1)$$

41 This represents the distribution that would result if we selectively transported only the mechanisms
 42 indexed by \mathcal{I} from the deployment environment while keeping all other mechanisms at their training
 43 state, which will cause an estimated change of $\Delta M_{\mathcal{I}} = M(f, P^{\epsilon_{tr}}) - M(f, P_{\mathcal{I}})$,

44 **Shapley Symmetry.** This formulation allows us to systematically decompose ΔM into contribu-
 45 tions from individual mechanisms. However, the contribution of each mechanism to performance drop
 46 depends on the order in which mechanisms are shifted. For instance, altering annotation protocols
 47 before scanner parameters may yield different marginal impacts than the reverse sequence. This
 48 path-dependence, where mechanism shifts propagate non-additively, requires fair attribution. To
 49 ensure it, we employ Shapley values [11, 5] to symmetrize over all possible intervention sequences:

$$\phi_i(\Delta M) = \sum_{\mathcal{I} \subseteq \{1, 2, \dots, n\} \setminus \{i\}} \frac{|\mathcal{I}|!(n - |\mathcal{I}| - 1)!}{n!} [\Delta M_{\mathcal{I} \cup \{i\}} - \Delta M_{\mathcal{I}}] \quad (2)$$

50 **$\Delta M_{\mathcal{I}}$ Estimation.** A fundamental challenge is that the distributions $P_{\mathcal{I}}$ are not directly accessible;
 51 we only have samples from $P^{\epsilon_{tr}}$ and $P^{\epsilon_{dep}}$. Computing $\Delta M_{\mathcal{I}}$ requires evaluating model performance
 52 under counterfactual mechanism combinations that take combinatorial complexity. To address this,
 53 we use importance sampling to reweight samples from the training distribution,

$$M(f, P_{\mathcal{I}}) = \mathbb{E}_{(V_{\mathcal{I}}) \sim P_{\mathcal{I}}} [M(f, P_{\mathcal{I}})] \approx \mathbb{E}_{(V_{\mathcal{I}}) \sim P^{\epsilon_{tr}}} [w_{\mathcal{I}} M(f, P_{\mathcal{I}})],$$

54 where $w_{\mathcal{I}}(x, y)$ represents importance weights, $w_{\mathcal{I}}(x, y) = \frac{P_{\mathcal{I}}(x, y)}{P^{\epsilon_{tr}}(x, y)} = \prod_{i \in \mathcal{I}} \frac{P^{\epsilon_{dep}}(V_i \mid \mathbf{PA}_i)}{P^{\epsilon_{tr}}(V_i \mid \mathbf{PA}_i)}$.

55 In medical image segmentation, this allows us to estimate how performance would change if, for
 56 example, only the annotation protocol shifted while scanner parameters remained constant. For exam-
 57 ple, when evaluating WML segmentation across hospitals, we can isolate the effect of annotation style
 58 differences by constructing weights that capture only the shift in $P(Y \mid X, A)$ (annotation mechanism)
 59 while keeping $P(X \mid S)$ (image acquisition mechanism) fixed. To estimate these importance weights,
 60 we train binary classifiers to discriminate between environments for each mechanism following [12].
 61 For mechanism i , we train a classifier \mathbf{D}_i to predict whether a sample comes from ϵ_{tr} or ϵ_{dep} based
 62 on (V_i, \mathbf{PA}_i) . The density ratio can then be expressed as, $\frac{P(\epsilon_{dep} \mid V_i, \mathbf{PA}_i)}{P(\epsilon_{tr} \mid V_i, \mathbf{PA}_i)} \cdot \frac{P(\epsilon_{tr})}{P(\epsilon_{dep})}$

63 **Discriminator Training, \mathbf{D}_i .** Training robust discriminators \mathbf{D}_i for shift detection presents unique
 64 challenges in medical imaging contexts. To mitigate overfitting, we implement gradient penalty
 65 regularization [13] and employ a multi-scale architectural design that captures both local and global
 66 distribution shifts. Additionally, we utilize test-time augmentation during discriminator training
 67 to enhance stability when handling the limited sample sizes common in medical datasets. Our
 68 implementation is fully integrated within the *nnU-Net* framework [14].

69 **3 Experiments and Results**

70 **Experimental procedure:** We train *nnU-Net* segmentation models on source data (ϵ_{tr}) and test on
 71 target (ϵ_{dep}), measuring ΔM using Dice Similarity Coefficient (DSC) and F1 score. Discriminators

72 D_i estimate density ratios enabling importance sampling to compute counterfactual performance
73 under selective mechanism shifts, aggregated via Shapley values into per-mechanism attributions. We
74 evaluated on MSSEG2016 [15, 16], comprising 53 MS patients from 4 centers with 7 annotators, with
75 documented inter-rater variability and scanner heterogeneity. We designed two experiments: **Exp. A**
76 trains on annotator i and tests on annotators $j \neq i$ (annotation shifts), while **Exp. B** trains on centers
1,7,8 and tests on center 3 (acquisition shifts). Table 1 shows distinct mechanism contributions across

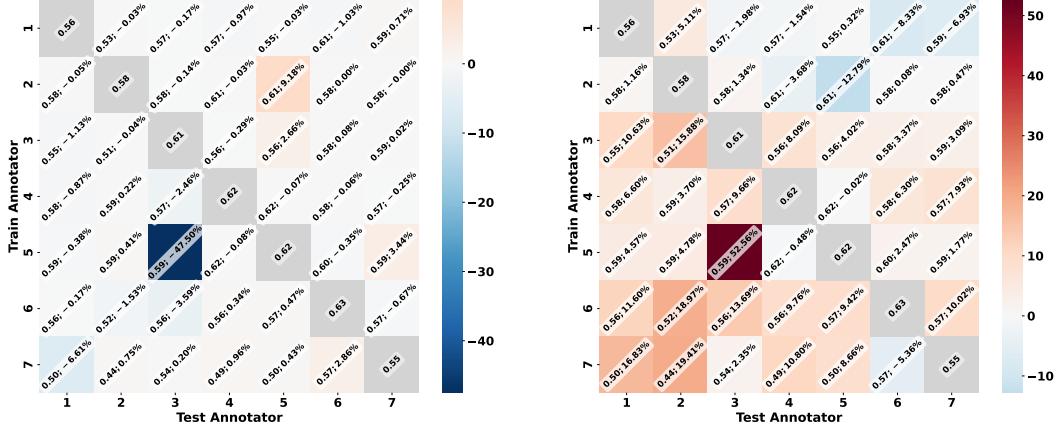


Figure 2: Inter-annotator performance for Exp. A. Each cell shows DSC; Δ_{DSC} . (a) Acquisition mechanism $P(X|S)$ shows predominantly negative Δ_{DSC} , indicating minimal or positive contribution. (b) Annotation mechanism $P(Y|X, A)$ exhibits predominantly positive Δ_{DSC} .

77 environments. In Exp. A (annotator shifts), the annotation mechanism $P(Y|X, A)$ contributes $7.4\% \pm$
78 8.9% (DSC) and $12.8\% \pm 14.8\%$ (F1) to performance changes, while the acquisition mechanism
80 $P(X|S)$ shows $1.6\% \pm 7.1\%$ and $5.8\% \pm 12.3\%$. Negative Δ_{DSC} values in the $P(X|S)$ mechanism
81 indicate performance improvements rather than degradation. In Exp. B (image shifts), the relative
82 contributions reverse: acquisition mechanism $P(X|S)$ contributes $6.5\% \pm 9.1\%$ (DSC) and $14.2\% \pm$
83 12.9% (F1), while annotation mechanism shows $2.6\% \pm 5.8\%$ and $8.4\% \pm 9.8\%$. Figure 2 visualizes
84 the full attribution matrix for Exp. A, revealing heterogeneous annotator sensitivity with Δ_{DSC}
85 ranging from minimal values to 52.6%.

Table 1: Mechanism Contributions to Performance Changes (%)

Exp.	Mechanism	$\Delta_{DSC}(\%)$	$\Delta_{F1}(\%)$
A	$P(Y X, A)$	7.4 ± 8.9	12.8 ± 14.8
	$P(X S)$	1.6 ± 7.1	5.8 ± 12.3

Exp.	Mechanism	$\Delta_{DSC}(\%)$	$\Delta_{F1}(\%)$
B	$P(Y X, A)$	2.6 ± 5.8	8.4 ± 9.8
	$P(X S)$	6.5 ± 9.1	14.2 ± 12.9

86 4 Discussion and Conclusion

87 We extend causal attribution to medical image segmentation, addressing its unique challenges. Our
88 findings reveal that dominant failure mechanisms depend critically on deployment context. In Exp.
89 A, annotation mechanism contributes 2-3 times more to performance changes. This pattern reverses
90 Exp. B, where acquisition shifts dominate. This has direct implications for resource allocation: when
91 deploying across institutions with different annotation protocols, prioritize annotation standardization;
92 when deploying to new scanner types, focus on scanner harmonization. While our experiments aimed
93 to isolate individual mechanisms, real medical datasets contain inherent confounding that cannot be
94 fully eliminated. In Exp. A, the acquisition mechanism still contributes $1.6 - 5.8\%$, likely because
95 different annotators labeled different case subsets or temporal annotation drift occurred. Importantly,
96 the shifted mechanism dominates (1.7-3 times higher attribution). This residual attribution reflects
97 real-world deployment where mechanisms rarely shift in complete isolation. Our approach requires a
98 known DGP, sufficient samples for discriminator training, and assumes static mechanisms, limiting
99 applicability. Future work should validate attribution accuracy using controlled synthetic experiments
100 where ground truth is known, enabling evidence-based deployment strategies.

101 **Potential negative societal impacts:**

102 Over-reliance on attribution results without clinical context could lead to premature deployment decisions.
103 The framework's requirement for deployment data may exclude resource-limited institutions,
104 potentially widening healthcare disparities. Additionally, focusing solely on dominant mechanisms
105 might overlook rare but critical failure modes affecting minority patient subgroups.

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