# Let the Model Decide its Curriculum for Multitask Learning

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#### Abstract

Curriculum learning strategies in prior multitask learning approaches arrange datasets in a difficulty hierarchy either based on human perception or by exhaustively searching the optimal arrangement. However, human perception of difficulty may not always correlate well with machine interpretation leading to poor performance and exhaustive search is compu-009 tationally expensive. Addressing these concerns, we propose two classes of techniques to 011 arrange training instances into a learning curriculum based on difficulty scores computed 012 via model-based approaches. The two classes 013 i.e Dataset-level and Instance-level differ in the granularity of arrangement. We conduct comprehensive experiments with 12 datasets and show that instance-level and dataset-level techniques lead to an average performance im-018 provement of 4.17% and 3.15% over their re-019 spective baseline methods. Furthermore, we 021 find that most of this improvement comes from correctly answering the difficult instances, implying a greater efficacy of our techniques on difficult tasks.

## 1 Introduction

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In recent times, Multi-Task Learning (MTL) (Caruana, 1997) i.e developing one Generalist model capable of handling multiple tasks has received significant attention from the NLP community (Aghajanyan et al., 2021; Lu et al., 2020; Sanh et al., 2019; Clark et al., 2019). Developing a single model in MTL has several advantages over multiple Specialist models as it (i) can leverage knowledge gained while learning other tasks and perform better in limited-data scenarios (Crammer and Mansour, 2012; Ruder et al., 2017), (ii) prevents overfitting to a single task, thus providing a regularization effect and increasing robustness (Clark et al., 2019; Evgeniou and Pontil, 2004), and (iii) provides storage and efficiency benefits because only one model needs to be maintained for all the tasks (Bingel and Søgaard, 2017).

Prior work has shown that presenting training instances ordered by difficulty level benefits not only humans but also machines (Elman, 1993; Xu et al., 2020). Arranging instances in a difficulty hierarchy i.e Curriculum Learning (easy to hard) and Anti-Curriculum Learning (hard to easy) has been studied in MTL setup (McCann et al., 2018; Pentina et al., 2015). These techniques arrange datasets either based on human perception of difficulty or by exhaustively searching the optimal arrangement. However, both these approaches have several limitations. Firstly, human perception of difficulty may not always correlate well with machine interpretation, for instance, a dataset that is easy for humans could be difficult for machines to learn or vice-versa. Secondly, exhaustive search is computationally expensive and becomes intractable as the number and size of datasets increase.

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In this work, we propose two classes of techniques that enable models to form their own learning curriculum in a difficulty hierarchy. The two classes i.e Dataset-level and Instance-level differ in the granularity of arrangement. In dataset-level techniques, we arrange **datasets** based on the average difficulty score of their instances and train the model sequentially such that all the instances of a dataset are learned together. In instance-level techniques, we relax the dataset boundaries and order **instances** solely based on their difficulty scores. We leverage two model-based approaches to compute the difficulty scores (Section 2).

We experiment with 12 datasets covering various sentence pair tasks and show the efficacy of instance and dataset-level techniques with an average performance gain of 4.17% and 3.15% over their respective baseline methods. Furthermore, we analyze model predictions and find that difficult instances contribute most to this improvement implying greater effectiveness of our techniques on difficult tasks. We note that our techniques are generic and can be employed in any MTL setup. 085 086

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In summary, our contributions are as follows: (i) **Incorporating Machine Interpretation of Dif-ficulty in MTL**: We introduce a novel framework for MTL that goes beyond human intuition of sample difficulty and provides model the flexibility to form its own curriculum at two granularities: instance-level and dataset-level.

(ii) **Performance Improvement**: We experiment
 with 12 varied datasets and show that instance and
 dataset-level techniques lead to a significant performance improvement of 4.17% and 3.15%.

(iii) **Findings and Benefits for the Community**: We conduct experiments in a limited training data regime and find that the proposed techniques are most effective on difficult instances. This finding makes our techniques more applicable for realworld tasks as they are often more difficult than abstract toy tasks and provide limited training instances. Furthermore, we analyze difficulty scores and find that approximately one-third instances of existing datasets get assigned a very low difficulty score i.e very easy-to-lean instances, hinting at presence of dataset artifacts or inherent easiness of a large portion of the datasets. These findings will help the community in developing high-quality and hard datasets.

### 2 Difficulty Score Computation

In this section, we describe two model-based difficulty computation methods based on recent works.

#### 2.1 Cross Review Method

Xu et al. (2020) proposed a method that requires splitting the training dataset D into N equal metadatasets ( $M_1$  to  $M_N$ ) and training a separate model on each meta-dataset with identical architecture. Then, each training instance is inferred using the models trained on other meta-datasets and the average prediction confidence is subtracted from 1 to get the difficulty score. Mathematically, score of instance  $i (\in M_k)$  is calculated as,

$$s_i = 1 - \frac{\sum_{j \in (1,...,N), j \neq k} c_{ji}}{N-1}$$

where  $c_{ji}$  is prediction confidence on instance *i* given by the model trained on  $M_j$ .

## 126 2.2 Average Confidence Across Epochs

127In this method, the difficulty score is computed by128simply averaging the prediction confidences across

epochs of a single model and subtracting it from 1.

$$s_i = 1 - \frac{\sum_{j=1}^E c_{ji}}{E} \tag{130}$$

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where the model is trained till E epochs and  $c_{ji}$  is prediction confidence of the correct answer given by the model at  $j^{th}$  checkpoint. This method is based on a recent work (Swayamdipta et al., 2020) that analyses the behavior of model during training i.e "training dynamics".

Algorithm 1: General Training Structure
Input:
D: the training dataset,
$\{S_1,, S_K\}$ : splits created from D
frac: fraction of previous split
Initialization: Model M
for $i \leftarrow 1$ to $K$ do
$train_data = S_i$
for $j \leftarrow 1$ to $i - 1$ do
$sampled_S_j = \text{Sampler}(S_j, frac)$
$train_data += sampled_S_j$
end
Train M with train_data
end
Train $M$ with $D$

### **3** Proposed Techniques

Addressing the limitations of current approaches highlighted in Section 1, we propose two classes of techniques to arrange training instances that allow models to form the learning curriculum based on their own difficulty interpretation. The technique classes i.e Dataset-Level and Instance-Level leverage difficulty scores computed using methods described in section 2 and follow the general training structure shown in Algorithm 1. The training dataset D is divided into K splits  $(S_1, ..., S_K)$ based on the difficulty score, and model M is trained sequentially on these ordered splits. Furthermore, while training the model on split  $S_i$ , a fraction (frac) of instances from previous splits  $(S_i(j < i))$  is also included in training to avoid catastrophic forgetting (Carpenter and Grossberg, 1988) i.e forgetting the previous splits while learning a new split. Note that D is a collection of multiple datasets in the MTL setup. The final step requires training on the entire dataset D as the evaluation sets often contain instances of all tasks and difficulty levels. Dataset-level and Instance level techniques vary in the way splits  $(S_1, ..., S_K)$  are created as described below:





Figure 1: Distribution of instances based on difficulty score computed using Average Confidence method. Difficulty score of datasets are shown in the legends.

**Dataset-level techniques:** In this technique class, each **dataset** represents a split and is arranged based on the average difficulty score of its instances i.e score of a dataset  $D_k$  is calculated as:

$$d_k = \frac{\sum_{i \in D_k} s_i}{|D_k|}$$

where,  $s_i$  is the difficulty score of instance  $i \in D_k$ .

**Instance-level techniques:** Here, we relax the dataset boundaries and arrange **instances** solely based on their difficulty scores. We study two approaches of dividing instances into splits  $(S_1, ..., S_K)$ : Uniform and Distribution-based splitting. In the former, we create K uniform splits from D, while in the latter, we divide based on the distribution of scores such that instances with similar scores are grouped in the same split<sup>1</sup>. The latter approach can result in unequal split sizes as we show in Figure 3 that the number of instances varies greatly across difficulty scores.

### 4 Experiments

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**Datasets:** We experiment with 12 datasets covering various sentence pair tasks, namely, Natural Language Inference (SNLI (Bowman et al., 2015), MultiNLI (Williams et al., 2018), Adversarial NLI (Nie et al., 2020)), Paraphrase Identification (QQP (Iyer et al., 2017), MRPC (Dolan and Brockett, 2005), PAWS (Zhang et al., 2019)), Commonsense Reasoning (Winogrande (Sakaguchi et al., 2020)), Question Answering NLI (QNLI (Wang et al., 2018)), Dialogue NLI (DNLI (Welleck et al., 2019)), and Numerical Reasoning (Stress Test of Equate (Ravichander et al., 2019)). For evaluation on robustness and generalization parameters, we

use HANS (McCoy et al., 2019) and Stress Test (Naik et al., 2018) datasets.

**Setup:** We experiment in a low-resource regime limiting the number of training instances of each dataset to 5000. This enables evaluating our techniques in a fair and comprehensive manner as transformer models achieve very high accuracy when given large datasets. Furthermore, inspired by decaNLP (McCann et al., 2018), we reformulate all the tasks in our MTL setup as span identification Question Answering tasks<sup>1</sup>. This allows creating a single model to solve the tasks that originally have different output spaces.

**Implementation Details:** We use three values of frac: 0, 0.2, and 0.4 (refer Algorithm 1), N = 5 (in Cross Review method), and E = 5 (in Average Confidence method). For distribution-based splitting, we experiment by dividing D into 3 and 5 splits<sup>1</sup>. These hyper-parameters are selected based on development dataset performance.

**Baseline Methods:** In MTL, *heterogeneous* batching where all the datasets are combined and a batch is randomly sampled has been shown to be much more effective than *homogeneous* and *partitioned* batching strategies (Gottumukkala et al., 2020). Therefore, we use it as the baseline for instance-level techniques. For dataset-level techniques, we generate multiple dataset orders and take the average performance as the baseline. We average these baseline scores across 3 different runs.

### 5 Results:

Table 1 shows the efficacy of our proposed curriculum learning techniques.

**Performance Improvement:** Instance and Dataset-level techniques achieve an average improvement of 4.17% and 3.15% over their respective baseline methods. This improvement in consistent across all the datasets and also outperforms single-task performance in most cases. Furthermore, we find that models leveraging Average Confidence method (2.2) outperform their counterparts using the Cross Review method (2.1)<sup>1</sup> rendering Average Confidence approach as more effective both in terms of performance and computation as Cross Review requires training multiple models (one for each meta-dataset).

**Uniform Vs Distribution based splitting:** In instance-level experiments, distribution-based splitting shows slight improvement over uniform splitting. We attribute this to the superior inductive bias

<sup>&</sup>lt;sup>1</sup>Refer Supplementary for details

Single-Task				Instance-Level							Dataset-Level			
Datasets			Hetero	geneous(B)	Unifor	m	Distrib	ution (D)	D with	frac=0.4	Rando	m Order(B)	Propos	ed Order
	EM	F1	EM	F1	EM	F1	EM	F1	EM	F1	EM	F1	EM	F1
SNLI	77.26	77.42	74.55	74.62	77.79	77.79	77.64	77.7	77.65	77.65	77.7	77.75	78.94	79.05
MNLI Mismatched	65.98	66.12	62.07	62.14	66.14	66.3	66.71	66.78	66.6	66.66	66.29	66.4	69.15	69.28
MNLI Matched	65.33	65.45	61.23	61.36	65.85	65.96	66.91	67.01	66.82	66.85	65.96	66.09	69.18	69.33
Winogrande	50	50	47.34	50	50.24	50.27	50	50.12	49.82	49.85	47.99	49.85	48.37	50.3
QNLI	74.21	74.23	66.78	66.81	70.42	70.44	71.81	71.81	71.38	71.38	70.35	70.39	73.75	73.79
EQUATE	98.99	98.99	98.99	98.99	99.14	99.21	99.57	99.57	99.28	99.28	99.57	99.57	99.57	99.57
QQP	80.04	80.06	75.34	75.35	78.89	78.9	79.23	79.25	79.11	79.12	79.23	79.26	80.27	80.29
MRPC	80.98	80.98	74.42	74.45	74.05	74.05	75.95	75.98	75.4	75.4	75.73	75.77	79.08	79.08
PAWS Wiki	52.45	52.49	55.92	56.01	53.15	53.16	54.39	54.47	70.59	70.62	56.44	56.51	80.33	80.34
PAWS QQP	68.25	68.41	73.03	73.03	69	69	71.83	71.83	78.84	78.84	73.08	73.12	83.46	83.46
ANLI R1	42.2	42.57	38.1	38.28	42.1	42.13	45.7	45.7	43.2	43.33	42.9	43.04	42.3	42.58
ANLI R2	38.1	38.78	35	35	39.8	39.9	38.9	39.05	37.2	37.25	38.4	38.5	36.8	36.97
ANLI R3	39.25	39.38	36.17	36.24	38.5	38.62	38.17	38.24	36.5	36.56	37.92	38.03	37.25	37.4
DNLI	84.68	84.83	80.36	80.48	83.51	83.57	83.15	83.2	82.09	82.12	82.52	82.59	82.67	82.73
HANS	-	-	49.06	49.07	48.95	49.01	48.3	48.38	49.39	49.45	48.22	48.27	48	48.09
Stress Test	-	-	55.28	55.44	56.2	56.31	58.66	58.77	57.7	57.75	56.74	56.84	59.94	60.15

Table 1: Results on performing curriculum learning using the proposed techniques with difficulty scores computed via Average Confidence approach. Note that frac is 0 unless otherwise mentioned. B means baseline and D with frac=0.4 column represents Distribution based splitting with value of frac as 0.4.

resulting from the collation of instances with simi-

lar difficulty scores to the same split.

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**Effect of adding instances from previous splits:** For dataset-level techniques, we find that it does not provide any improvement. This is because all the instances of a dataset are grouped in a single split therefore, adding instances from other splits doesn't contribute much to the inductive bias. Furthermore, in the case of instance-level, it leads to a performance improvement because previous splits contain instances of the same dataset hence, providing the inductive bias.

Difficulty Scores Analysis: Figure 3 shows the 256 distribution of training instances of all datasets with difficulty scores computed using Average confidence (2.2) method. This distribution reveals that instances across datasets and within every dataset 260 vary greatly in difficulty as they are widely spread across the difficulty scores. Comparing the average difficulty score of all datasets (shown in legends of 263 Figure 3) shows that Equate and QNLI are easy-to-264 learn while PAWS and Winogrande are relatively 265 difficult-to-learn. Furthermore, around 32% of the training instances get assigned a difficulty score 267 of  $\leq 0.1$  hinting at either the presence of dataset artifacts or the inherent easiness of these instances. 269 A similar observation is made with Cross Review method with the percentage being 37%.

272Test Set Analysis: We also compute difficulty273scores of test instances and plot the performance274improvement achieved by our approach over the275baseline method for every difficulty score bucket276in Figure 2. We find that our technique is effective277especially on instances with high difficulty scores.



Figure 2: Performance improvement vs Difficulty score for dataset level techniques.

This implies a greater efficacy of our techniques on tasks that contain difficult instances.

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## 6 Conclusion

In this paper, we proposed two classes of techniques for MTL that allow models to form the learning curriculum based on their own interpretation of difficulty. Comprehensive experiments with 12 datasets showed that our techniques lead to a performance improvement of 4.17% and 3.15%. Furthermore, we found that difficult instances contribute most to this improvement, implying a greater efficacy of our techniques on difficult tasks. We also analyzed the difficulty scores computed using two model-based approaches and showed that almost one-third of the training instances get assigned a score of  $\leq 0.1$ , hinting at presence of dataset artifacts or inherent easiness of a large portion of the existing datasets. We hope that our techniques and findings will foster development of stronger MTL models and high-quality hard datasets.

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Dataset	Size	Dataset	Size
SNLI Winogrande PAWS qqp MRPC ANLI R2 DNLI Equate Stress Test	9824 1654 671 1630 1000 16408 696 136464	MNLI QNLI PAWS wiki ANLI R1 ANLI R3 HANS QQP	19645 5650 7987 1000 1000 30000 40371

Table 2: Statistics of our test set.

## A Test set Statistics

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Table 2 shows the statistics of the test sets used in our experiments.

### **B** Implementation Details:

We use the huggingface implementation of BERT-Base model, batch size 16, learning rate 5e - 5 for our experiments. We use three values of *frac*: 0, 0.2, and 0.4 (refer Algorithm 1), N = 5 (in Cross Review method), and E = 5 (in Average Confidence method). For distribution based splitting, we experiment by dividing D into 3 and 5 splits. The results reported in the paper are for 3 splits. These hyper-parameters are selected based on performance on the dev dataset. We adjust the per gpu training batch size and gradient accumulation accordingly to fit in our 4 Nvidia V100 16GB GPUs. We keep the maximum sequence length of 512 for our experiments to ensure that the model uses the full context.

#### C Dataset Examples

Table 3 shows examples of datasets used in this work.

#### **D** Difficulty Scores

Figure 3 shows the distribution of difficulty scores computed using Cross Review and Average Confidence approach.

## E Results

Table 4 shows the results of instance-level and dataset-level techniques.

#### F Analysis

Table 5 shows the comparison of comparison of
performance across difficulty scores for instancelevel approaches.

## **G** Limitations

Our method involves computing the difficulty493scores of training instances which requires addi-<br/>tional computation. However, this computation is494only required during training and not required dur-<br/>ing inference. Hence, it does not add any computa-<br/>tional overhead when deployed in an application.493

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Context – Question	Datasets
C: Kyle doesn't wear leg warmers to bed, while Logan almost always does. he is more likely to live in a colder climate. <b>false</b> , or true ? O: Kyle is more likely to live in a colder climate.	Winogrande
<ul> <li>C: In order for an elevator to be legal to carry passengers in some jurisdictions it must have a solid inner door. false, or true ?</li> <li>Q: What is another name for a freight elevator? Does the context sentence contain answer to this question ?</li> </ul>	QNLI
<ul><li>C: What makes a great problem solver? false, or true?</li><li>Q: How can I be a fast problem solver? Are the two sentences semantically equivalent?</li></ul>	QQP, MRPC, PAWS
<b>C:</b> i sell miscellaneous stuff in local fairs . <b>contradiction</b> , or neutral, or entailment ? <b>Q:</b> i used to work a 9 5 job as a telemarketer . Consistency of the dialogues ?	DNLI
<ul><li>C: 205 total Tajima' s are currently owned by the dealership. contradiction, or neutral, entailment ?</li><li>Q: less than 305 total Tajima' s are currently owned by the dealership.</li></ul>	Equate
<ul><li>C: Two collies are barking as they play on the edge of the ocean contradiction, or neutral, or entailment ?</li><li>Q: Two dogs are playing together.</li></ul>	SNLI, MNLI, ANLI

Table 3: Examples context-question pairs of various types of training datasets used in our experiments. Answers are highlighted in bold.

Instance-Level				Dataset-Level						
Datasets	Unifor	m Splitting + Prev	Propos	ed Order with <i>frac</i> =0.4	AC on Proposed Order					
	EM	F1	EM	F1	EM	F1				
SNLI	76.19	76.2	77.09	77.11	77	77.02				
MNLI Mismatched	64.54	64.55	65.83	65.85	65.36	65.41				
MNLI Matched	63.63	63.64	66.06	66.08	64.72	64.77				
Winogrande	50.48	50.48	50.6	50.94	48.43	49.79				
QNLI	68.16	68.17	71.24	71.25	72.23	72.26				
EQUATE	99.71	99.71	99.43	99.43	99.57	99.57				
QQP	77.61	77.61	79.32	79.32	79.68	79.71				
MRPC	72.15	72.15	76.07	76.07	77.55	77.55				
PAWS Wiki	52.11	52.13	69.48	69.48	52.92	52.95				
PAWS QQP	68.7	68.7	69.75	69.75	66.62	66.69				
ANLI R1	41.9	41.93	43.8	43.88	44.7	44.8				
ANLI R2	37.8	37.85	36.8	36.83	37.4	37.5				
ANLI R3	37.58	37.62	36.5	36.53	36.83	36.83				
DNLI	82.55	82.58	83.64	83.66	81.83	81.93				
HANS	49.76	49.77	48.24	48.28	50.25	50.26				
Stress Test	56.07	56.09	57.55	57.57	58.79	58.87				
Average	62.43	62.45	64.46	64.5	63.37	63.49				

Table 4: Results on test sets.



Figure 3: Distribution of instances based on difficulty score.

Difficulty Score	Instances	Random Order	Proposed Order
0.1	63736	94.86	93.77
0.2	18703	87.8	85.55
0.3	28035	81.85	79.85
0.4	17238	74.5	72.81
0.5	21502	65.03	65.84
0.6	17338	57.69	57.94
0.7	21255	46.75	48.92
0.8	18058	38.36	44.05
0.9	22327	26.8	33.07
1	46008	9.17	14.05

Table 5: Performance comparison across difficultyscores for instance level techniques.