# SAMBERT: Improve Aspect Sentiment Triplet Extraction by Segmenting the Attention Maps of BERT

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#### Abstract

Aspect Sentiment Triplet Extraction (ASTE) performs fine-grained sentiment analysis in a unified way through extracting sentiment triplets comprised of aspect terms, opinion spans, and their sentiment relations in sentences. The previous works show the adoption of BERT, which simply leverages its last layer output as the word representation, is beneficial for recognizing triplet elements. However, their methods limit the potential of pretrained knowledge in BERT, since the different layers can capture multi-level linguistic information existing in sentences, which are useful for ASTE as well. In this work, we explore to access the rich pretrained knowledge by fully leveraging its attention maps of different layers. To this end, we propose to Segment the Attention Maps of BERT (SAMBERT) by taking the merits of semantic segmentation, which can effectively discriminate the desired objects from others in an image. In this procedure, we can further reason over the knowledge of different levels in these attention maps to distinguish aspect terms, opinion spans and their sentiment relations from other parts, which results in a sameshape tagging matrix of word pairs for deriving sentiment triplets. Through the extensive experiments on four benchmarks, we demonstrate our method can achieve a new state of the art.

#### 1 Introduction

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Sentiment analysis (Liu, 2012; Feldman, 2013) is an important Natural Language Understanding task (NLU) to identify the sentiment from review sentences, which has been widely studied in many fields, e.g., E-commerce (Shivaprasad and Shetty, 2017) and social media (Agarwal et al., 2011). Recently, Aspect-based Sentiment Analysis (Pontiki et al., 2014; Ma et al., 2017) tries to perform sentiment analysis at the fine-grained level. It comprises several subtasks, such as Aspect Term Extraction (Li et al., 2018; Xue et al., 2017), Aspect Opinion Extraction (Fan et al., 2019; Pereg et al., 2020), and Aspect Sentiment Classification (Wang et al., 2016; Ruder et al., 2016). In order to provide a unified solution for these subtasks, Aspect Sentiment Triplet Extraction (ASTE) is proposed by (Peng et al., 2020) to extract sentiment triplets from review sentences, which contain all of the aspect terms, corresponding opinion spans, and sentiment polarities. For instance, given a review "*The barbe-cued salmon is elegantly spiced and not dry at all*.", the triplets of [*barbecued salmon, elegantly spiced, positive*] and [*barbecued salmon, not dry at all, positive*] should be extracted from this sentence.

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To recognize the aspect term, opinion span and their sentiment relation, many efforts are devoted. (Peng et al., 2020; Xu et al., 2021) conduct ASTE in multiple stages, which firstly extract aspect terms and opinion spans, and then combine the valid pairs of them to decide their sentiment polarities. (Xu et al., 2020; Wu et al., 2020) jointly extract the triplet elements with their proposed unified tagging schemes in an end-to-end manner. Furthermore, they demonstrate that the adoption of BERT is beneficial for improving the performance of ASTE, by leveraging the contextual output of the last layer in BERT (Devlin et al., 2019) as their word embeddings, which follows the same strategy recommended by (Sun et al., 2019).

However, the way they use BERT may be not optimal since they ignore the rich pretrained knowledge existing in BERT. As the existing works (Jawahar et al., 2019; Clark et al., 2019) analyze, the different layers of BERT, which are comprised of multiple attention heads, can capture multi-level and multi-view knowledge existing in sentences. For example, (Jawahar et al., 2019) shows that the bottom layers of BERT focus more on phrase-level information (e.g., the opinion span "*not dry at all*" in Fig. 1), and the top layers mainly capture semantic features (e.g., the sentiment relation between "*barbecued salmon*" and "*elegantly spiced*"). *Therefore, we argue that the multi-level information can* 



Figure 1: A review sentence of ASTE with its word pair form, which has the same shape of the attention maps. (1) The colored blocks in the diagonal correspond to the intra-associaitions of aspect terms and opinion spans. (2) The colored blocks in the non-diagonal are the sentiment relations (positive) between them. (3) The gray ones are undesired parts.

contain task-specific features, where making full and explicit use of them can be beneficial for recognizing triplet elements.

To achieve this, instead of only utilizing the final generated word representation of BERT (Sun et al., 2019), we explore to fully leverage its pretrained knowledge by explicitly accessing the attention maps of different layers. By doing so, we can benefit from three sides: (1) For a single word pair, the attention scores between them can capture its hierarchical and diverse relations via different layers as well as different attention heads (Jawahar et al., 2019; Clark et al., 2019), which can be treated as our input feature to represent the connections at a word pair level. (2) For all the word pairs, their attention scores comprise a 2-D feature map (cf. the example in Fig. 1). In this feature map, the desired word pairs of the aspect terms and opinion spans form several blocks (i.e., the colored ones) scattered in other word pairs (i.e., the gray ones). (3) By using these word pair representations storing the hierarchical knowledge, we wish these desired word pairs can be distinguished from other parts for decoding the sentiment triplets, which is inspired by the semantic segmentation task (Girshick et al., 2014) via a multi-scale context-aware pyramid structure (Zhao et al., 2017) to distinguish the object and background in an image.

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To this end, we propose **SAMBERT**, which

Segments the Attention Maps of BERT in different layers as a word pair level tagging matrix<sup>1</sup>. In this procedure, we can further reason over these attention maps and learn to distinguish the multilevel task-specific patterns of the aspect terms and opinion spans, as well as the sentiment relations between them from other parts (cf. Fig 1). Specifically, we first stack all the attention maps of the k layers in the bottom and top of BERT as our input feature maps, where k is a hyper-parameter used to control the number of layers we selected.<sup>2</sup> Then, a Convolutional Encoder-Decoder is leveraged to conduct the segmentation stage to model the task-specific patterns, and further strengthen these associations between the triplet elements in a sentence. Finally, a 2-D tagging matrix is predicted to decode sentiment triplets.

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We conduct extensive experiments on four benchmarks (Peng et al., 2020; Xu et al., 2020), where our method can achieve a new state of the art. Also, further analysis verifies that with the segmentation paradigm, the task-specific features can be effectively distilled out from the attention maps of different layers for ASTE.

To summarize, our contributions are as follows:

- We are the first to explicitly leverage the attention maps of different layers in BERT to fully access the pretrained knowledge for ASTE.
- We formulate ASTE into a semantic segmentation paradigm, to further learn the taskspecific patterns in these attention maps.
- The experimental results on four public benchmarks show that our method can achieve a new state of the art.

### 2 Related Works

Sentiment Analysis (Liu, 2012; Feldman, 2013) aims to automatically classify the sentiment polarity of a sentence (Maas et al., 2011; Yang and Cardie, 2014; Dai et al., 2020; Pontiki et al., 2014; Ma et al., 2017). While the sentence level sentiment analysis has been well studied, current literature of Sentiment Analysis tends to analyze the sentiment at a fine-grained level, i.e., analyzing the sentiment

<sup>&</sup>lt;sup>1</sup>Thanks to the Grid Tagging Scheme (Wu et al., 2020; Chen et al., 2021b), a word pair level tagging matrix (cf. the right of Fig. 2), we can directly equip our method with it since they are naturally compatible due to the same shape of the attention maps of BERT and tagging matrix.

<sup>&</sup>lt;sup>2</sup>We prefer not to use the intermediate layers of BERT since we find it is less helpful for ASTE according to our pre-experiment.

polarities of aspect terms with the specific opinion 156 spans. In particular, Aspect-based Sentiment Anal-157 ysis (ABSA) is divided into several subtasks like 158 Aspect Term Extraction (Li et al., 2018; Xue et al., 159 2017), Aspect Opinion Extraction (Fan et al., 2019; 160 Pereg et al., 2020), Aspect Sentiment Classification 161 (Wang et al., 2016; Ruder et al., 2016) and Opinion 162 Pair Extraction (Wang et al., 2017; Dai and Song, 163 2019; Wu et al., 2020). However, these subtasks 164 only derive one or two elements of the aspect term, 165 opinion span and sentiment polarity. To extract them all, Aspect Sentiment Triplet Extraction is 167 proposed by (Peng et al., 2020) to generate triplets 168 of all the elements. 169

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The existing works of ASTE can be roughly divided into two categories, i.e., the multi-stage and one-stage methods. For the multi-stage method, (Peng et al., 2020) proposes to extract the elements at first, which will be combined into sentiment triplets later. (Chen et al., 2021a; Mao et al., 2021) transform ASTE task into a Machine Reading Comprehension (MRC) task to capture the connections among the subtasks of ASTE. (Huang et al., 2021) proposes a two-stage method to enhance the correlations between aspects and opinions. (Jian et al., 2021) proposes to regard the aspect and opinion terms as arguments of the expressed sentiment in a hierarchical reinforcement learning framework. (Xu et al., 2021) uses a span-level approach to explicitly consider the interactions between the whole spans of aspects and opinions when predicting their sentiment relations. However, these multi-stage methods can lead to error propagation.

To address this problem, the one-stage method is proposed: (Xu et al., 2020; Wu et al., 2020; Chen et al., 2021b) extract sentiment triplets in one stage by their proposed unified tagging schemes. (Xu et al., 2020) uses a word-level tagging scheme, but it is derived from the assumption that one aspect term corresponds to only one opinion span, which can not be always held in all possible scenarios. (Wu et al., 2020; Chen et al., 2021b) avoid this problem by a word pair level tagging scheme, which results in a 2-D tagging matrix. Besides, (Zhang et al., 2021b; Yan et al., 2021) both propose to extract the sentiment triplets via a generative way, where the sequence-to-sequence paradigm is used. Nevertheless, the exposure bias of the generative framework (Ranzato et al., 2016) can lead to a gap between training and inference.

Besides, (Liu et al., 2020; Zhang et al., 2021a)

also formulate Incomplete Utterance Rewriting and Document-level Relation Extraction tasks as a semantic segmentation task. Nevertheless, the difference between our work and them (as well as all the aforementioned works) is that they only leverage the contextual representation of the last layer of Pretrained Models (Devlin et al., 2019; Lan et al., 2020; Liu et al., 2019) to further enhance the performance but ignore the rich hierarchical knowledge hidden in its different layers (Jawahar et al., 2019; Clark et al., 2019). In contrast, we can fully leverage the knowledge by explicitly unitizing the attention maps of different layers in Pretrained Models storing diverse associations between word pairs, which is analogous to the multi-scale contextaware pyramid structure (Zhao et al., 2017) used in Computer Vision.

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### 3 Methodology

In this Section, we first describe the overall workflow of our method (Sec. 3.1). Then, we elaborate on each component, i.e., Review Encoder (Sec. 3.2), Segmentation Layer (Sec. 3.3), and Triplet Decoding procedure (Sec. 3.4).

### 3.1 Overall Workflow

As shown in Fig. 2, in the review encoding stage, we encode the review sentence with BERT (Devlin et al., 2019) to derive the attention maps of its bottom and top layers. Then, these attention features are stacked as an 2-D feature map, which is used to conduct the segmentation stage to reason over the task-specific patterns. Finally, a tagging matrix is predicted to decode the sentiment triplets. By this formulation, we can better reason over and refine the linguistic knowledge of different levels stored in the attention maps of BERT for ASTE.

The final segmentation classes (i.e., the tagging scheme) are inherited from (Wu et al., 2020; Chen et al., 2021b), i.e.,  $\{N, A, O, Pos, Neu, Neg\}$ , where N means no association exists between a word pair; A means a word pair belongs to the same aspect term; O means a word pair belongs to the same opinion span;  $\{Pos, Neu, Neg\}$  mean positive, neutral, and negative sentiment relations are expressed between a word pair. In addition, since the 2-D tagging matrix is symmetric, only the tags of the upper triangle part in the matrix are used for training and inference. Please refer to the tagging matrix in the right of Fig. 2 for better understanding.



Figure 2: Overview of *SAMBERT*. The attention maps of the k bottom and top layers of BERT are stacked as a 2-*D* feature map. Then, a <u>Conv</u>olutional <u>Enc</u>oder-<u>Dec</u>oder is leveraged to segment this feature and derive the Tagging Matrix (Wu et al., 2020) for decoding the final sentiment triplets, where the colored blocks represent the aspect terms, opinion spans and their sentiment relations. *Besides, only the upper triangle part in the tagging matrix are used due to the symmetry of word pairs.* 

#### 3.2 Review Encoder

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As (Clark et al., 2019; Jawahar et al., 2019) discuss, the Self Attention mechanism (Vaswani et al., 2017) in different layers of Pretrained Models (Devlin et al., 2019; Lan et al., 2020; Liu et al., 2019) focus on different levels of the linguistic knowledge. Therefore, our Review Encoder aims to fully access and explicitly leverage these rich linguistic features when the review sentence is encoded.

To this end, this work explores to *directly utilize* the attention maps in different layers of Pretrained Models. Here we choose BERT as the representative of them, in order to align with the previous works. Specifically, given one review sentence  $S = [w_1, w_2, ..., w_n]$ , we first obtain its input embedding sequence. That is,  $H_0 = [e_1, e_2, ..., e_n]$  $(e_i = w_i + p_i)$ , where  $w_i$  and  $p_i$  are the word embedding and position embedding of the *i*-th word. Then, the input embedding sequence is feed into BERT to obtain its attention maps:

$$H_{i}, A_{i} = BERT\_Layer_{i}(H_{i-1}), i \in [1, N],$$
  
$$A = [A_{1}; ...; A_{k}; A_{N-k}...; A_{N}],$$

278where  $A_i \in \mathbb{R}^{h \times n \times n}$  is the derived h head attention279maps of i-th layers. Here we stack both bottom and280top k layers as our feature map  $A \in \mathbb{R}^{(2*k*h) \times n \times n}$ .281Please note that here we prefer not to use the in-282termediate layers of BERT, since we find it less283helpful according to our pre-experiment. A rea-284sonable explanation is that the information in the285bottom and top layers is enough for ASTE. Hence,

we use a hyper-parameter k to select the BERT layers we used, which is a simple way to avoid irrelevant information and we leave other advanced selection methods (e.g., the attention mechanism) for future work. 286

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Note that A has a shape of  $n \times n$ . Each  $A_{ij}$  represents the attention scores of different layers that contains diverse associations between the *i*-th and *j*-th words. Therefore, the word pair representations within/between aspect terms and opinion spans (v.s. the objects in an image) can provide task-specific features and be distinguished from other parts of the feature map (v.s. the background in an image) in the downstream segmentation stage.

We argue that this is a more effective way to leverage the pretrained knowledge in BERT, since the attention maps of different layers originally store the multi-level and multi-view knowledge via the pretraining paradigm (Jawahar et al., 2019; Clark et al., 2019). In contrast, all the existing works only use the word representations of last layer, which can result in losing task-specific features for ASTE.

## 3.3 Segmentation Layer

After obtaining the 2-*D* feature map *A*, it needs to be mapped into a same-shape tagging matrix  $M \in \mathbb{R}^{n \times n}$  (cf. the right of Fig. 2), where each  $A_{ij}$  is mapped to a predefined tag  $\in \{N, A, O, Pos, Neu, Neg\}$ .

In this procedure, it should not only consider the information in the word pair representation itself

Dataset		Re	s14		Lap14					Re	s15		Res16			
	#Sent.	#Pos.	#Neu.	#Neg.												
Train	1266	1692	166	480	906	817	126	517	605	783	25	205	857	1015	50	329
Dev	310	404	54	119	219	169	36	141	148	185	11	53	210	252	11	76
Test	492	773	66	155	328	364	63	116	322	317	25	143	326	407	29	78

Table 1: The detailed statistics of ASTE-Data-V2, where #Sent. denotes the number of sentences, and #Pos., #Neu., and #Neg. denote the numbers of the positive, neutral, and negative triplets in each dataset.

(i.e., the attention scores between this word pair), where the information contained in its adjacent word pairs is also useful for prediction, since the word pairs belonging to the same triplet element are consistent to share the similar information of the same tags (cf. the right of Fig. 2). An inductive example of that is, only using the information of one pixel in an image is hard to tell what the object is, while looking at a larger region is much easier.

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Inspired by the semantic segmentation task (Girshick et al., 2014) in Computer Vision, which aims to distinguish desired objects from others in images, we also formulate this stage as a *segmentation* task, which refines the attention maps as a 2-D tagging matrix M to discriminate the desired triplet elements.



Figure 3: The backbone we used for the segmentation of stacked attention maps in BERT.

Specifically, we use a Convolutional Encoder-334 Decoder framework (Ronneberger et al., 2015) to perform this stage. As shown in Fig. 3, in the encoding stage, the attention maps are encoded by two convolutional layers with the kernel size of  $3 \times 3$ , while the channels of input are doubled 338 and its size is halved by the max-pooling operation. Then, in the decoding stage, twice up-sampling 340 operations are leveraged to cooperate with two convolutional layers  $(3 \times 3 \text{ kernels})$  to make the size of 342 output consistent with the feature map, where the channels of input are halved. Besides, the residual 344 connection between the encoding layer and decoding layer is also used for better training. Furthermore, the final probability matrix of the tagging classes is obtained by a fully-connected layer.

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#### 3.4 Triplet Decoding

After the segmentation stage, the derived tagging matrix is used to decode sentiment triplets. We use the same decoding strategy as (Wu et al., 2020; Chen et al., 2021b) did: (1) we first search the elements of word pairs on the main diagonal of the tagging matrix, where the continuous tags of  $\{A, O\}$  are recognized as an aspect term or opinion span. (2) Then, we count the tags  $\{Pos, Neu, Neg\}$  of the corresponding word pairs between the recognized aspect terms and opinion spans, the most predicted tag is assigned as the sentiment polarity to this triplet. If these tags do not belong to  $\{Pos, Neu, Neg\}$ , then this triplet is dropped.

### 4 Experimental Setup

#### 4.1 Datasets

There are two versions of datasets for ASTE: one (named ASTE-Data-V1) is released by (Peng et al., 2020) and another (named ASTE-Data-V2) is released by (Xu et al., 2020). ASTE-Data-V1 does not contain cases where one opinion span is associated with multiple targets, but these cases are very common in the real world. ASTE-Data-V2 refines the V1 version with these additional missing triplets. Therefore, we mainly use ASTE-Data-V2 for our experiments, which is more general. Note that some works (Mao et al., 2021; Chen et al., 2021a) use ASTE-Data-V1 for the experiments. We also report the results of our method on ASTE-Data-V1 to fairly compare with them. The detailed statistics of ASTE-Data-V2 are listed in Tab. 1.

#### 4.2 Implementation Details

The hyper-parameters in our experiment are tuned over the development set by grid search. We use *bert-base-uncased* as our Review Encoder to be consistent with the previous works of ASTE. The learning rate of BERT is set to 5e - 5 with gradient clip selected from 1 to 5. The learning rate of the

Modela		Res14			Lap14			Res15		Res16			
Widdels	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1	
ASTE-Data-V2 + Static Word Embeddings (GloVe)													
Peng-two-stage	43.24	63.66	51.46	37.38	50.38	42.87	48.07	57.51	52.32	46.96	64.24	54.21	
OTE-MTL	62.70	57.10	59.71	49.62	41.07	44.78	55.63	42.51	47.94	60.95	53.35	56.82	
JET <sup>o</sup>	61.50	55.13	58.14	53.03	33.89	41.35	64.37	44.33	52.50	70.94	57.00	<u>63.21</u>	
GTS	66.13	57.91	61.73	53.35	40.99	46.31	60.10	46.89	52.66	63.28	58.56	60.79	
Span-ASTE	72.52	62.43	67.08	59.85	45.67	51.80	64.29	52.12	57.56	67.25	61.75	64.37	
ASTE-Data-V2 + Pretrained Model (BERT)													
JET <sup>o</sup>	70.56	55.94	62.40	55.39	47.33	51.04	64.45	51.96	57.53	70.42	58.37	63.83	
GTS	67.76	67.29	67.50	57.82	51.32	54.36	62.59	57.94	60.15	66.08	69.91	67.93	
Span-ASTE	72.89	70.89	71.85	63.44	55.84	<u>59.38</u>	62.18	64.45	<u>63.27</u>	69.45	71.17	70.26	
SAMBERT	70.29	74.92	72.53	62.26	59.15	60.66	65.12	63.51	64.30	68.01	75.44	71.53	

Table 2: The overall evaluation results on ASTE-Data-V2. *P*. and *R*. are Precision and Recall respectively. The best results are in **bold font** and the second-best ones are <u>underlined</u>. The results of OTE-MTL and GTS are adopted from (Xu et al., 2021).

Convolutional Encoder-Decoder is selected from the range of [5e-4, 1e-4, 5e-5]. The Adam optimizer (Kingma and Ba, 2015) is used for model optimization. Besides, since the information of some layers in BERT can be irrelevant to ASTE, we only leverage the first k bottom layers and last k top layers as input, where we set k to 4 in all the experiments. Our implementation is based on PyTorch (Paszke et al., 2019) and HuggingFace's transformers library (Wolf et al., 2020).

### 4.3 Evaluation Metrics

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Following the existing works (Peng et al., 2020; Xu et al., 2020; Wu et al., 2020; Chen et al., 2021a), we use precision, recall, and F1 score as the metrics to evaluate the performance of ASTE. A correct triplet requires an exact match between the prediction of the aspect term, opinion span, and the sentiment polarity with the ground truth. Note that the F1 score takes into account both precision and recall, which can be regarded as a harmonic average of them. Therefore, we focus on the F1 score in following experiments.

### 4.4 Baselines

Our method is compare to the following methods.

- Peng-two-stage: (Peng et al., 2020) extracts the sentiment triplets in two stages, which first extract the elements and then combine them into sentiment triplets.
- OTE-MTL: (Zhang et al., 2020) proposes a multi-task learning framework to jointly extract aspect terms and opinion spans with parsing the sentiment polarities between them si-

multaneously.

• JET: (Xu et al., 2020) proposes to extract the sentiment triplets by a word-level position-aware tagging scheme.

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- GTS: (Wu et al., 2020) uses a grid tagging scheme and an inference strategy for extracting the sentiment triplets.
- Span-ASTE: (Xu et al., 2021) proposes a spanlevel approach to explicitly consider the interaction between the whole span of the aspect and opinion when predicting their sentiment.
- Dual-MRC: (Mao et al., 2021) proposes a dual-MRC framework to handle ASTE task, by jointly training two BERT-MRC models with parameter sharing.
- BMRC: (Chen et al., 2021a) proposes a bidirectional MRC framework to capture and utilize the associations among ASTE subtasks.

### **5** Results

### 5.1 Overall Evaluation

As reported in Tab. 2 and Tab. 3, our method outperforms all of the existing state-of-the-art methods. Specifically, for ASTE-Data-V2 (cf. Tab. 2), our method surpasses all of the non-Bert-based and Bert-based methods. Compared to the multi-stage method *Span-ASTE* (Xu et al., 2021), we can averagely outperform it by 1.07% on the four datasets. Besides, compared to the one-stage method *GTS* (Wu et al., 2020), our method can also boost the performance by 4.77 points on average.

In addition, to keep consistency and fairly compare with (Mao et al., 2021; Chen et al., 2021a),

Madala		Res14			Lap14			Res15		Res16		
widdels	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1	<i>P</i> .	R.	F1
ASTE-Data-V1 + Pretrained Model (BERT)												
Dual-MRC	71.55	69.14	70.32	57.39	53.88	55.58	63.78	51.87	57.21	68.60	66.24	67.40
BMRC	71.32	70.09	70.69	65.12	54.41	<u>59.27</u>	63.71	58.63	<u>61.05</u>	67.74	68.56	<u>68.13</u>
SAMBERT	75.15	72.97	74.04	63.03	57.14	59.96	61.97	60.88	61.42	68.12	73.98	70.93

Table 3: The overall evaluation results on ASTE-Data-V1.

Madal	Res14				Lap14			Res15		Res16			
WIOUEI	<i>P</i> .	R.	F1										
SAMBERT	70.29	74.92	72.53	62.26	59.15	60.66	65.12	63.51	64.30	68.01	75.44	71.53	
only top layers	68.48	73.00	70.66	59.57	51.76	55.39	57.93	61.03	59.44	64.78	73.49	68.86	
only bottom layers	69.53	59.09	63.89	46.17	42.33	44.17	58.82	47.42	52.51	60.81	58.67	59.72	
MHSA over word rep	65.07	71.47	68.12	56.23	56.75	56.49	56.66	58.76	57.69	61.73	72.32	66.61	
word rep concat	69.80	71.57	70.68	58.49	57.30	57.89	63.31	60.83	62.04	56.08	69.40	67.17	
w/o segmentation	56.75	46.50	51.11	49.51	28.10	35.85	42.27	40.00	41.10	56.08	46.78	51.01	

Table 4: The ablation study of our method. These experiments are based on ASTE-Data-V2.

we also report the results of our method on ASTE-Data-V1, which are shown in Tab. 3. It's observed that, although these two methods use BERT (Devlin et al., 2019) in a MRC way to leverage its capability of deep language understanding, our method can also improve the performance by 1.85% on average.

The results on the two versions of datasets demonstrate that our method, which makes full and explicit use of the pretrained knowledge in BERT and further equip it with a segmentation paradigm, is more effective to tackle ASTE and can achieve a new state of the art.

### 5.2 Effects of Different Components

In this Subsection, we discuss the effects of the two crucial components of our method. For the attentions maps of BERT, we replace them with two variants:

- *only top layers*: the attention maps of bottom layers are removed to prove the information it contains can help with the improvement.
- *only bottom layers*: only the attention maps of the bottom BERT layers are leveraged to show the information in top layers is necessary.

Also, other two operations are used to calculate the feature maps by the word representations of last layer in BERT, which aim to verify the superiority of leveraging the attention features originally derived by BERT:

> • *MHSA over word rep*: we replace the attention maps derived within BERT with the post

calculated attention maps over its word representations. • *word rep concat*: we concatenate the pairs between the word representations (Wu et al., 2020) to substitute our attention maps of different layers.

Besides, the Segmentation Layer is replaced with a vanilla fully-connected classifier to verify the effectiveness of the semantic segmentation, dubbed as *w/o segmentation*. The experiments in this Subsection are all based on ASTE-Data-V2.

As reported in Tab. 4, when only leveraging the attention maps of top layers or bottom layers, the F1 score drops by 3.67% or 12.18% on average. That means the top layers contain most of the required information for ASTE, but the bottom layers can also provide some task-specific features. In other words, only using the information stored in top layers can maintain a high-level performance of ASTE, but the knowledge in bottom layers can also supplement the effective information to further boost the performance.

When replacing the derived attention maps of BERT with post-calculated attention maps<sup>3</sup> over the output of word representations of BERT, the performance averagely declines by 5.03 points. That indicates the knowledge originally stored in different layers via the pretraining paradigm can not be easily obtained by its last layer output. In contrast, directly and explicitly leveraging these attention

<sup>&</sup>lt;sup>3</sup>Here we use a 12-head Self Attention to calculate the attention maps.



Figure 4: The t-SNE visualization of the word pair representations consisting of only bottom layers (left), only top layers (middle), and both bottom and top layers (right). We only visualize these representations whose classes belong to  $\{A, O, Pos, Neu, Neg\}$  and the label *None* is omitted since its number is enormous and can interfere with observation.

maps derived by BERT is a better way to access the hierarchical features. In addition, we follow (Wu et al., 2020) to concatenate the pairs of contextualized representations of BERT as the input to Segmentation Layer, where the performance also drops by 2.81 points. The conclusion is the same as the one we draw above.

Finally, we verify the effectiveness of the Segmentation Layer. When the variant uses a vanilla classifier instead of the Segmentation Layer, the performance of the F1 score dramatically degrades by 22.49 points on average. That indicates the semantic segmentation paradigm is important to perceive and utilize the information existing in other adjacent word pairs and further boost the performance of ASTE.

The ablation studies from different perspectives imply that both components are useful to improve the performance of ASTE, and the combination of them can further reach their full potential.

#### 5.3 Visualization

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Besides, to demonstrate the knowledge stored in the attention maps of different layers is beneficial to obtain informative and discriminative representations for ASTE, we also apply t-SNE (van der Maaten and Hinton, 2008) to these word pair level representations comprised of attention scores, and plot their 2-dimensional vectors.<sup>4</sup>

Specifically, we visualize three types of attention features, i.e., only bottom layers, only top layers, and both bottom and top layers. As shown in Fig. 4, it is obvious that (1) Only using the bottom layers can easily tell the difference between intra-associations (i.e.,  $\{A, O\}$ ) and inter-relations (i.e., {*Pos*, *Neu*, *Neg*}) of the aspect terms and opinion spans with a large margin. That indicates the bottom layers do capture some task-specific information existing in sentiment triplets. (2) Although only using the top layers can better recognize both intra- and inter-associations of the triplet elements, the clusters are less compact than only using the bottom layers. (3) When both the bottom and top layers are used, the representations of word pairs can result in more compact clusters and clearer boundaries between different classes than only using the bottom or top layers. That suggests the features in bottom and top layers are complementary to each other, which are helpful to decide the classes the word pairs belong to. Without any part of them can result in the situation of losing task-specific information.

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### 6 Conclusion

In this work, we propose a novel framework, i.e., SAMBERT, to Segment the Attention Maps of BERT, which aims to fully and explicitly leverage the rich pretrained knowledge stored in its different layers. By formulating ASTE as a semantic segmentation task, we can further reason over the knowledge of different levels and views in these attention maps, so as to distinguish aspect terms, opinion spans and their sentiment relations from other parts. That results in a same-shape tagging matrix of word pairs, which is used to derive the sentiment triplets of review sentences. Through the experiments on four public benchmarks, we demonstrate that our method can achieve a new state of the art. The further analyses in both quantitative and qualitative perspectives verify the effectiveness of the proposed components of our method.

<sup>&</sup>lt;sup>4</sup>Due to the space limitation, we only illustrate Lap14 dataset, where other datasets have the same performance.

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