

A HIERARCHICAL PROBABILISTIC FRAMEWORK FOR INCREMENTAL KNOWLEDGE TRACING IN CLASSROOM SETTINGS

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Paper under double-blind review

ABSTRACT

Knowledge tracing (KT) aims to estimate a student’s evolving knowledge state and predict their performance on new exercises based on performance history. Many realistic classroom settings for KT are typically low-resource in data and require online updates as students’ exercise history grows, which creates significant challenges for existing KT approaches. To restore strong performance under low-resource conditions, we revisit the hierarchical knowledge concept (KC) information, which is typically available in many classroom settings and can provide strong prior when data are sparse. We therefore propose Knowledge-Tree-based Knowledge Tracing (KT²), a probabilistic KT framework that models student understanding over a tree-structured hierarchy of knowledge concepts using a Hidden Markov Tree Model. KT² estimates student mastery via an EM algorithm and supports personalized prediction through an incremental update mechanism as new responses arrive. Our experiments show that KT² consistently outperforms strong baselines in realistic online, low-resource settings.

1 INTRODUCTION

Knowledge tracing (KT) refers to an educational task that, given historical exercises performance of a set of students, aims to predict whether they can solve a new exercise correctly. It can be regarded as modeling the evolution of a student’s knowledge during learning, which is essential in personalized learning systems, enabling dynamic adaptation to students’ needs. While prior works on knowledge tracing impose very loose constraints about the availability of data (Piech et al., 2015; Ghosh et al., 2020), in many practical real-world classroom scenarios, these constraints tend to be much more stringent, due to various privacy and usability considerations. In particular, three practical constraints have usually been understudied.

- **Cold Start.** For each target student, existing works usually assume that abundant historical data from that student is available before the prediction starts. This implies that the prediction would need to happen at a very late stage of the student’s learning – only after many exercises have been done. To make KT meaningful, the prediction should start shortly after the target student starts learning, with only a few exercises completed. This creates a cold start scenario for KT.

- **Online Update.** Conventional KT methods keep their model parameters fixed once the training phase is completed, and apply the same parameters to predict all test data. However, in practice, new student exercises constantly arrive in a streaming fashion, requiring KT methods to be efficiently updated to capture the evolution of students’ understanding.

- **Limited Peers.** Many KT methods require a large number of peers to form a sufficiently large dataset as the training set. In practice, the number of peers may be limited due to privacy protection.

The aforementioned constraints create significant challenges for existing KT algorithms. Specifically, recent KT approaches can be broadly categorized into two types. The first type, *the deep-learning-based methods* (Zhang et al., 2017; Ghosh et al., 2020; Pandey & Karypis, 2019; Liu et al., 2023b), trains neural architectures to model complex student performance patterns. Although these methods have shown strong performance under benchmark settings, they require large amounts of training data to achieve good performance, which is unavailable under the practical constraints.

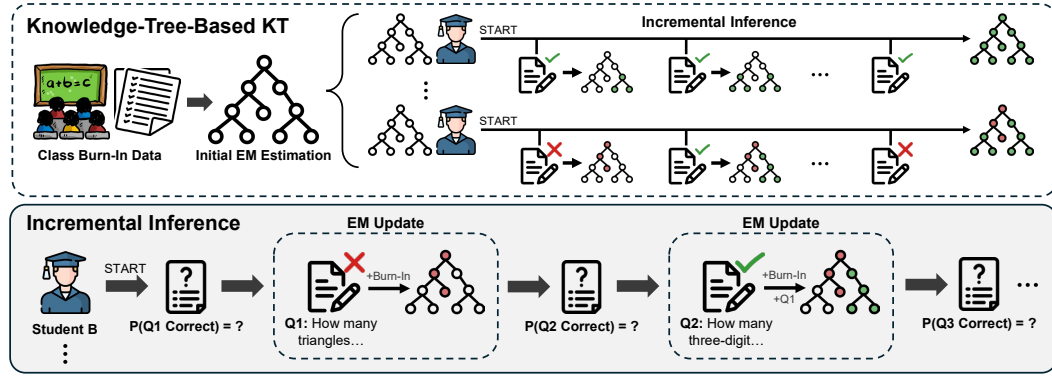


Figure 1: KT^2 framework. The model first performs a class-level estimation using burn-in responses to initialize a global knowledge model. Each student is assigned a personalized knowledge concept tree, which is incrementally updated with each new interaction via one-step EM.

On the other hand, the second type of methods, the *large language model (LLM)-based methods* (Li et al., 2024; Neshaei et al., 2024), leverages LLMs to perform the prediction tasks, either fine-tuning the LLM or selecting a subset of the target student’s historical data as in-context examples. While these methods have improved data efficiency and online flexibility, they often struggle to capture fine-grained patterns in historical data and may make predictions based on naive decision rules.

In summary, there appears to be a fundamental trade-off between data availability and a model’s capacity to capture complex dependencies in student responses across exercises. Yet, one crucial source of information—long underused in existing KT methods—could help overcome this bottleneck: **knowledge concepts**.

Knowledge concepts (KCs) refer to the labeled topics, knowledge areas, or skills associated with each exercise. These concepts often follow a hierarchical structure, where broader concepts encompass finer-grained sub-concepts. KCs are readily available in many classroom settings, and can be effective for modeling student learning. Intuitively, if a student has not mastered a particular concept, they are likely to answer related questions incorrectly. Moreover, their performance on conceptually adjacent or dependent concepts may also be affected. In low-resource classroom settings, these knowledge labels, along with their hierarchical organization, can provide strong structural priors that enhance prediction performance. **Can we leverage hierarchical knowledge concepts to enable data-efficient, flexible, and online knowledge tracing for realistic classroom settings?**

Motivated by this observation, we propose Knowledge-Tree-based Knowledge Tracing (KT^2), a probabilistic framework for low-resource, online knowledge tracing. KT^2 builds a Hidden Markov Tree Model (Crouse et al., 2002) based on the hierarchical tree structure of KCs, where the hidden variables represent the student’s mastery of each KC, and the observed variables correspond to their correctness on individual exercise questions. As shown in Fig. 1, the model parameters are first estimated using a small amount of initial (“burn-in”) data via the standard Expectation-Maximization (EM) algorithm (Dempster et al., 1977), and are then incrementally updated as new exercise responses are observed. KT^2 enables principled prediction of future performance of target students by computing the distribution of correctness on upcoming exercises variables, conditioned on the students’ historical exercise performance.

Our experiments demonstrate that KT^2 effectively addresses the challenges of low-resource knowledge tracing. For instance, with only 100 target students and as few as ten exercises per student, KT^2 consistently outperforms the strongest baselines.

In the online setting, KT^2 requires only a single EM step to incorporate new data, enabling efficient and consistent performance updates.

2 RELATED WORKS

Traditional Machine Learning KT The earliest KT models are based on probabilistic or statistical machine learning methods. BKT (Corbett & Anderson, 1994) formulates the task as a Hidden

Markov Model over students’ latent knowledge states. Extensions such as PFA (Pavlik Jr et al., 2009) employ logistic regression to model the effect of practice and forgetting, while IRT (Cai et al., 2016) focuses on estimating student ability and item difficulty. Later works, such as iBKT (Yudelston et al., 2013), adapt these methods to incorporate personalization.

Deep Learning KT In recent years, with the rapid development of deep learning techniques, many knowledge tracing methods have adopted neural models to predict student performance. Early models include RNN-based DKT (Piech et al., 2015), memory-augmented DKVMN (Zhang et al., 2017), and its IRT-inspired neural variant Deep-IRT (Yeung, 2019). Later works such as SAKT (Pandey & Karypis, 2019) and GIKT (Yang et al., 2021) adopt attention mechanisms to better model the importance of historical exercises. Transformer-based KT models, such as AKT (Ghosh et al., 2020), qDKT (Sonkar et al., 2020), SAINT (Choi et al., 2020), and AT-DKT (Liu et al., 2023a), further improve this by capturing long-range dependencies and contextual signals. ReKT (Shen et al., 2024) adopts architecture inspired by human cognitive development theories with only two linear units, achieve strong performance with simple designs. These models typically treat KCs as independent and represent the student knowledge in latent vectors, limiting interpretability and generalizability.

Structure-Aware KT Several works have attempted to incorporate structural relationships among KCs. Recent graph-based KT models such as GKT (Nakagawa et al., 2019), GIKT (Yang et al., 2021), SHDKT (Yang et al., 2022), KSGAN (Mao et al., 2022), and DHKT (Wang et al., 2019) enhance embeddings by encoding concept co-occurrence or hierarchy via GNNs or attention. More recent approaches like HHSKT (Ni et al., 2023) construct heterogeneous graphs over learner-question interactions with hierarchical differentiation, while PSI-KT (Zhou et al., 2024) jointly models learner traits and prerequisite structure using a hierarchical Bayesian generative model. These models primarily treat structure as auxiliary input or require substantial learner histories for inference.

LLM-Based KT LLMs have seen remarkable progress in recent years (Achiam et al., 2023; Anthropic, 2025; DeepMind, 2025), leading to growing interest in their application in education, including online tutoring, feedback generation, and question generation (Heffernan et al., 2024; Liu et al., 2024; Luo et al., 2024). Recent works have explored applying LLMs for KT, aiming to improve interpretability and reduce data dependence. One line of work adopts few-shot prompting to estimate student mastery and generate natural language rationales (Li et al., 2024). These methods require repeated prompting, are sensitive to example selection, and lead to high computational and financial costs. Another line of work investigates fine-tuning LLMs for KT. Current results show that fine-tuned LLMs can match classical probabilistic models like BKT, but they still lag behind modern deep KT models’ performance (Neshaei et al., 2024; Lee et al., 2024). While LLMs offer flexibility and reasoning capabilities, further adaptation is needed for real-world deployment.

3 METHODS

3.1 PROBLEM FORMULATION

The problem of KT can be formulated as follows. Denote $\mathcal{I}$ as a set of student IDs. For each $i \in \mathcal{I}$, denote $\mathcal{N}_i$ as a set of exercise IDs for which student i has solved. For each $i \in \mathcal{I}$, and $n \in \mathcal{N}_i$, define Q_{ni} as a random binary variable:

$$Q_{ni} = \begin{cases} 1 & \text{if student } i \text{ answers question } n \text{ correctly,} \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

Finally, define $\mathcal{Q}_i = \{Q_{ni} : n \in \mathcal{N}_i\}$ as a set of historical exercise variables of student i . Given a new question n^* , our goal is to predict:

$$p_{\theta}(Q_{n^*i} = 1 | \mathcal{Q}_i). \quad (2)$$

Here, θ represents a set of parameters that defines the distribution, which will be estimated based on all the observed historical data, $\cup_i \mathcal{Q}_i$.

We here restate the real-world constraints mentioned in Sec. 1 formally:

- **Cold Start.** At the onset, each $\mathcal{Q}_i$ is a very small set, making the conditional probability in Eq. equation 2 uninformative and the estimation of θ challenging.
- **Online Update.** Each $\mathcal{Q}_i$ is expanding, requiring Eq. equation 2 and θ to be constantly updated.

• **Limited Peers.** $\mathcal{I}$ is a small set, adding to data scarcity when estimating θ .

In the following, we will discuss how the hierarchical KCs can alleviate the challenges.

3.2 KNOWLEDGE CONCEPT TREE

Many hierarchical KC structures can be organized into trees. Fig. 2(left) shows a portion of an example knowledge concept tree, where parent nodes represent broader KCs and child nodes finer ones. Each edge represents an entailment relationship. We make two assumptions on our classroom setting: ① We have access to a knowledge concept tree that contains all the KCs covered in the exercises; and ② each exercise question is labeled with *one KC at the leaf node*.

3.3 THE KT^2 MODEL

KT^2 incorporates the knowledge concept tree information into the probabilistic modeling of the Q_{ni} variables. Specifically, denote $\mathcal{C}$ as the set of all KCs. For each $i \in \mathcal{I}$, and $c \in \mathcal{C}$, define K_{ci} as the following random binary variable:

$$K_{ci} = \begin{cases} 1 & \text{if student } i \text{ masters KC } c, \\ 0 & \text{otherwise.} \end{cases} \quad (3)$$

KT^2 introduces a Hidden Markov Tree Model to model the joint probability distribution of $\{Q_{ni}\}$ (as observed variables) and $\{K_{ci}\}$ (as hidden variables) via the following assumptions.

First, all the variables are independent across different students, *i.e.*,

$$p(\cup_{n,i} \{Q_{ni}\}, \cup_{c,i} \{K_{ci}\}) = \prod_i p(\cup_n \{Q_{ni}\}, \cup_c \{K_{ci}\}). \quad (4)$$

Second, for each student i , the corresponding probability distribution can be decomposed as

$$p(\cup_n \{Q_{ni}\}, \cup_c \{K_{ci}\}) = \underbrace{p(\cup_c \{K_{ci}\})}_{\text{transition}} \cdot \underbrace{p(\cup_n \{Q_{ni}\} | \cup_c \{K_{ci}\})}_{\text{emission}}, \quad (5)$$

where the first term, representing the *transition probabilities*, models interdependencies among the mastery of different KCs; the second term, representing the *emission probabilities*, models how the mastery of KCs indicates the exercise correctness.

Third (Transition Probabilities), for each student i , the probability graphical model for $\{K_{ci}\}$ (Fig. 2 (right)) follows the same topological structure as the knowledge concept tree (Fig. 2 (left)). Namely, each K_{ci} only directly depends on the mastery variable of its parent KC:

$$p(\cup_c \{K_{ci}\}) = \prod_c p(K_{ci} | K_{\mathcal{P}(c)i}), \quad (6)$$

where $\mathcal{P}(c)$ denotes the parent KC of c . To model transition probability, $p(K_{ci} | K_{\mathcal{P}(c)i})$, we assume that mastering a parent KC would entail mastering ALL its children (but not vice versa), hence

$$p(K_{ci} = 1 | K_{\mathcal{P}(c)i} = k) = \begin{cases} 1 & \text{if } k = 1, \\ \gamma_c & \text{otherwise,} \end{cases} \quad (7)$$

where each γ_c is a parameter to be estimated. When c is the root node, Eq. equation 7 still applies with the condition $K_{\mathcal{P}(c)i} = k$ removed.

Fourth (Emission Probabilities), as shown in Fig. 2 (right), we assume each Q_{ni} only directly depends on the mastery variable of its corresponding labeled concepts, *i.e.*,

$$p(\cup_n \{Q_{ni}\} | \cup_c \{K_{ci}\}) = \prod_n p(Q_{ni} | K_{\mathcal{M}(n)i}), \quad (8)$$

where $\mathcal{M}(n)$ denotes KC for exercise n . Emission probability, $p(Q_{ni} | K_{\mathcal{M}(n)i})$, is modeled as

$$p(Q_{ni} = 1 | K_{\mathcal{M}(n)i} = k) = \begin{cases} \phi_n, & \text{if } k = 1, \\ \varepsilon, & \text{otherwise,} \end{cases} \quad (9)$$

where ϕ_n represents the correct probability if the student knows the underlying concepts. It takes on three possible values, $\{r_{easy}, r_{med}, r_{hard}\}$, depending on the difficulty level of the exercise, which is determined by which of the three predefined bins (high, medium, or low) the historical solve rate falls into. ε represents the correct probability by random guessing. $\varepsilon < r_{hard} < r_{med} < r_{easy}$ are parameters to be estimated.

Summary. The joint probability of all the hidden and observed variables is defined by Eqs. equation 4 to equation 9. The parameters of the model, θ , include

$$\theta = [\cup_c \gamma_c, r_{easy}, r_{med}, r_{hard}, \varepsilon]. \quad (10)$$

Sec. 3.4 will discuss how to estimate θ . Sec. 3.5 will discuss how to predict the correctness probability (Eq. equation 2).

3.4 PARAMETER ESTIMATION

The parameters θ are estimated via the maximum log-likelihood objective on the *observed variables*:

$$\max_{\theta} \log p_{\theta}(\mathcal{Q}), \quad (11)$$

where $\mathcal{Q}$ denotes a set of observed historical correctness; $p_{\theta}(\mathcal{Q})$ can be computed by marginalizing Eq. equation 4 over all the hidden variables, $\{K_{ci}\}$ (we add a subscript θ under p to emphasize that p is parameterized by θ).

Directly computing Eq. equation 11 is computationally expensive due to the marginalization of the hidden variables. We thus adopt the standard EM algorithm (Dempster et al., 1977) for the optimization. EM algorithm is an iterative algorithm. Denote $\theta^{(\tau-1)}$ as the parameter estimate after iteration $\tau - 1$. Then $\theta^{(\tau)}$ can be computed from $\theta^{(\tau-1)}$ via the following objective:

$$\theta^{(\tau)} = \arg \max_{\theta} A(\theta; \theta^{(\tau-1)}), \quad (12)$$

where $A(\theta; \theta^{(\tau-1)})$ equals

$$\mathbb{E}_{p_{\theta^{(\tau-1)}}(\cup_{c,i} \{K_{ci}\} | \mathcal{Q})} [\log p_{\theta}(\cup_{n,i} \{K_{ci}\}, \mathcal{Q})]. \quad (13)$$

It can be shown that EM algorithm can converge to the optimal solution to Eq. equation 11. Eq. equation 12 bears a closed-form solution that can be computed efficiently. See Appendix A for details.

3.5 INFERENCE

Once θ is estimated, we can predict if student i can answer question n^* correctly by computing Eq. equation 2, which can be further decomposed into

$$\begin{aligned} p_{\theta}(Q_{n^*i} = 1 | \mathcal{Q}_i) &= \sum_{k=0}^1 p_{\theta}(K_{\mathcal{M}(n^*)i} = k | \mathcal{Q}_i) p(Q_{n^*i} = 1 | K_{\mathcal{M}(n^*)i} = k, \mathcal{Q}_i) \\ &= p_{\theta}(K_{\mathcal{M}(n^*)i} = 0 | \mathcal{Q}_i) \varepsilon + p_{\theta}(K_{\mathcal{M}(n^*)i} = 1 | \mathcal{Q}_i) \phi_n, \end{aligned} \quad (14)$$

where the second equality is derived from the conditional independence assumption in Eq. equation 8; the last equality is from Eq. equation 9.

Eq. equation 14 implies that the prediction process involves two steps. First, infer the mastery of the KC associated with the target exercise based on the historical performance, *i.e.*, computing $p_{\theta}(K_{\mathcal{M}(n^*)i} = k | \mathcal{Q}_i)$, which can be efficiently computed using the *upward-downward algorithm* (Crouse et al., 2002) (see Appendix B). Second, use the KC mastery probability to modulate the emission probability (last line of Eq. equation 14).

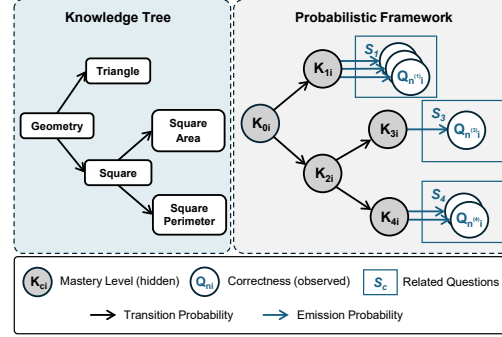


Figure 2: An KC tree structure (left), and its corresponding probabilistic framework (right).

XES3G5M	Mean	Std	Interactions	MOOCRADAR	Mean	Std	Interactions
Application Module	0.6249	0.1600	10532	Wine Knowledge	0.6592	0.1342	8469
Computation Module	0.6235	0.1354	7521	Circuit Design	0.6394	0.1320	17616
Counting Module	0.6689	0.1424	7279	Education Theory	0.6791	0.1205	8796

Table 1: Statistics of simulated classroom data extracted from XES3G5M and MOOCRADAR. Mean and Std correspond to class accuracy rates on all interactions.

3.6 INCREMENTAL UPDATE

In online settings, each $\mathcal{Q}_i$ is constantly expanding, making it necessary to re-estimate θ based on Eqs. equation 11 and equation 12. We design the following incremental update scheme to balance between efficiency and performance, as shown in Fig. 1.

Communal Burn-in. At the start, each $\mathcal{Q}_i$ contains only a few data. We aggregate the early data from all target students into a shared burn-in dataset, denoted by $\mathcal{Q}_{init}$, and estimate a common model, θ_{init} , via Eq. equation 11 with $\mathcal{Q} = \mathcal{Q}_{init}$. We run the full EM iterations till convergence. This model is then used to predict the correctness of the first exercise (post-burn-in) for both seen and unseen students.

Personalized Update. After the burn-in phase, we maintain personalized models for each target student. Let θ_i denote the model parameters for student i , estimated by Eq. equation 11 with $\mathcal{Q} = \mathcal{Q}_{init} \cup \mathcal{Q}_i$ – that is, the burn-in data from all students and all historical responses from student i . As new responses are observed (*i.e.*, as $\mathcal{Q}_i$ expands), we incrementally update θ_i by performing a single EM iteration, enabling efficient adaptation and personalization.

4 EXPERIMENT

We first describe the construction of classroom testbeds and baseline settings in Secs. 4.1 and 4.2, respectively. We then compare KT² with existing baselines and provide analysis in Sec. 4.3 - Sec. 4.5.

4.1 DATA CONSTRUCTION

We first construct evaluation datasets that follow the low-resource scenarios as described in Sec. 1 and that come with knowledge concept trees. We will open-source all our datasets, along with the code for preprocessing and dataset construction.

Dataset Selection. We identify two widely used educational datasets: XES3G5M (Liu et al., 2023c) for K–12 math and MOOCRADAR (Yu et al., 2023) for university-level courses. Each exercise is annotated with fine-grained KCs and can also be assigned a difficulty label (easy/medium/hard) based on student correctness rates. Statistics for the datasets are in Appendix E.

Knowledge Concept Tree. Next, we discuss how the knowledge concept trees are structured in these datasets. XES3G5M arranges its KCs into a hierarchical entailment structure, allowing us to use it directly as a knowledge concept tree. For MOOCRADAR, it only provides KCs without any hierarchical structure, so we build a knowledge concept tree for it instead. Inspired by KCQRL (Ozyurt et al., 2024), we encode KCs into semantic embeddings (McInnes et al., 2018) and cluster semantically similar KCs together (Campello et al., 2013). For each cluster, we use GPT-4o-mini (OpenAI, 2024) to generate a representative KC label. Finally, we manually annotate unclustered KCs. Further details are provided in Appendix F.

Data Sampling. To simulate the low-resource setting, we need to sample a subset of questions and students. First, to sample a subset of questions and KCs, we partition the knowledge concept trees by taking each level-1 node as the root of a knowledge module. Each module consists of the root and all its descendant KCs. We then identify students who have worked on at least 50 exercises associated with the module. For each dataset, we select the top-3 knowledge modules with the largest number of students satisfying the condition. Then, we remove out-of-module exercises for those students.

We then sample 100 students per module with a good coverage of overall performance. Specifically, we use a normal distribution $\mathcal{N}(0.65, 0.15)$ to draw 100 overall correctness rates. For each drawn correctness rate, we select a student whose overall correctness rate best matches the drawn sample without replacement. Each sampled student’s first 10 interactions are added to the burn-in data, and the remaining are used for incremental inference. Table 1 shows the statistics of simulated sets.

4.2 SETUP

Metrics. Following previous works, we evaluate models using AUC, accuracy, and F1 score.

Baselines. We consider several commonly used methods in knowledge tracing, including conventional machine learning methods, deep learning methods, and LLM-based approaches.

- IBKT (Yudelso et al., 2013) is an individualized extension of BKT that assigns separate parameters to each student, modeling student-specific knowledge states with a Hidden Markov Model.
- AKT (Ghosh et al., 2020) is a transformer-based KT model that uses a monotonic attention mechanism to measure the relevance between current questions and historical exercises.
- SAINT (Choi et al., 2020) is a transformer-based model with a deep encoder-decoder architecture. It separates exercise and response sequences and encodes them respectively, allowing stacked attention layers to learn the dependencies.
- QDKT (Sonkar et al., 2020) is a variant of DKT that models performance at the question level. It applies Laplacian regularization to smooth predictions across similar questions and uses fastText based initialization to improve generalization.
- REKT (Shen et al., 2024) is a lightweight KT model that models student knowledge from question, concept, and domain perspectives by a Forget-Response-Update (FRU) architecture.
- LLM’s ability to handle long-context inputs makes them potentially capable for predicting student performance based on historical exercises. We adopt two different LLM architectures: QWEN-2.5-7B (Qwen-Team, 2025) and LLAMA-3.2-3B (Meta, 2024). During inference, each model is given 10 historical data of the current student and predicts the correctness of the next.

We also implement an online variant for three deep learning knowledge tracing (DLKT) baselines, denoted as AKT-ONLINE, SAINT-ONLINE, and QDKT-ONLINE. These models are initially trained on the same burn-in data as their offline versions. During inference, we aggregate all students’ cumulative interactions into the training set and perform an additional round of training. The updated model is then used to predict the next question for all students. Note that this online strategy gives the baselines access to more training data compared to KT^2 , which only performs individual-level updates without using other students’ new interactions.

4.3 MAIN RESULT

Table 2 presents the performance of all methods across both datasets. First, KT^2 achieves the highest scores across all metrics on both XES3G5M and MOOCRADAR, demonstrating its effectiveness and robustness. Second, among the conventional DLKT baselines, all online variants outperform their offline counterparts, highlighting the importance of online updating. Notably, compared with our method, all DLKT-Online baselines have access to more data at each update step, as they retrain using the full classroom’s cumulative interactions. In contrast, KT^2 updates only with the new interaction from a single student. Despite this apparent advantage, these baselines still underperform, suggesting that simply applying online retraining to existing DLKT models is insufficient to fully capture the evolution of an individual student’s knowledge state. Third, we also observe that both Qwen and LLaMA do not perform well on both datasets. This suggests that current LLMs may lack the capability to effectively extract student characteristics from historical exercise data and make accurate predictions.

4.4 QUALITATIVE ANALYSIS

To better understand how our framework performs real-time updates, we visualize the changes in the posterior mastery probability, $p_{\theta}(K_{ci} = 1|Q_i)$, across a KC subtree during incremental inference for

Model	AUC	ACC	F1	AUC	ACC	F1	AUC	ACC	F1	AUC	ACC	F1
XES3G5M (Liu et al., 2023c)												
	Application Module			Computation Module			Counting Module			Avg.		
IBKT (Yudelso et al., 2013)	0.5630	0.6054	0.7104	0.6011	0.6483	0.7684	0.6093	0.7040	0.8025	0.5911	0.6526	0.7604
AKT (Ghosh et al., 2020)	0.6790	0.6659	0.7418	0.6701	0.6628	0.7560	0.6994	0.7184	0.8114	0.6828	0.6824	0.7697
AKT-ONLINE	<u>0.7106</u>	0.6825	0.7645	0.6848	0.6722	0.7690	<u>0.7174</u>	<u>0.7203</u>	0.8080	<u>0.7043</u>	<u>0.6917</u>	0.7805
SAINT (Choi et al., 2020)	0.6031	0.6423	0.7822	0.6079	0.6306	<u>0.7735</u>	0.5794	0.6886	0.8156	0.5968	0.6538	<u>0.7904</u>
SAINT-ONLINE	0.6899	<u>0.6826</u>	0.7615	0.6641	0.6609	0.7558	0.6779	0.6904	0.7834	0.6773	0.6780	0.7669
QDKT (Sonkar et al., 2020)	0.5177	0.5178	0.5965	0.5338	0.5272	0.5897	0.4856	0.4716	0.5410	0.5124	0.5055	0.5757
QDKT-ONLINE	0.6663	0.6358	0.7185	0.6606	0.6363	0.7138	0.6988	0.6697	0.7603	0.6752	0.6473	0.7309
REKT (Shen et al., 2024)	0.7068	0.6726	0.7458	<u>0.6909</u>	<u>0.6725</u>	0.7633	0.6847	0.7150	<u>0.8199</u>	0.6941	0.6867	0.7763
QWEN-2.5 (Qwen-Team, 2025)	0.5939	0.6425	0.7823	0.5730	0.6301	0.7731	0.5918	0.6857	0.8136	0.5862	0.6528	0.7897
LLAMA-3.2 (Meta, 2024)	0.5839	0.6431	<u>0.7825</u>	0.5649	0.6304	0.7732	0.5873	0.6868	0.8136	0.5787	0.6534	0.7898
OURS	0.7448	0.7057	0.7962	0.7079	0.6952	0.7807	0.7470	0.7326	0.8258	0.7332	0.7111	0.8009
MOOCRADAR (Yu et al., 2023)												
	Wine Knowledge			Circuit Design			Education Theory			Avg.		
IBKT (Yudelso et al., 2013)	0.6019	0.6719	0.7873	0.5651	0.6331	0.7654	0.5635	0.6794	0.8037	0.5768	0.6615	0.7855
AKT (Ghosh et al., 2020)	0.5901	0.6546	0.7784	0.6142	0.6402	0.7722	0.5535	0.6910	<u>0.8173</u>	0.5859	0.6619	0.7893
AKT-ONLINE	0.7208	0.6967	<u>0.7955</u>	0.6726	0.6712	0.7749	0.6442	0.6974	0.8059	0.6792	0.6884	0.7921
SAINT (Choi et al., 2020)	0.4905	0.6568	0.7929	0.6066	0.6347	0.7766	0.5918	0.6910	<u>0.8173</u>	0.5630	0.6608	<u>0.7956</u>
SAINT-ONLINE	0.5646	0.6510	0.7767	0.6284	0.6389	0.7554	0.6052	0.6878	0.8085	0.5994	0.6592	0.7802
QDKT (Sonkar et al., 2020)	0.5857	0.5629	0.6371	0.5248	0.5106	0.5774	0.5420	0.5142	0.5918	0.5508	0.5292	0.6021
QDKT-ONLINE	<u>0.7661</u>	<u>0.7230</u>	0.7924	<u>0.7063</u>	<u>0.6716</u>	0.7438	<u>0.7327</u>	<u>0.7292</u>	0.8118	<u>0.7350</u>	<u>0.7079</u>	0.7827
REKT (Shen et al., 2024)	0.6313	0.6248	0.7264	0.5490	0.5254	0.6228	0.5792	0.6896	0.8154	0.5865	0.6133	0.7215
QWEN-2.5 (Qwen-Team, 2025)	0.6190	0.6526	0.7898	0.5595	0.6377	0.7788	0.5454	0.6861	0.8138	0.5746	0.6588	0.7941
LLAMA-3.2 (Meta, 2024)	0.5889	0.6526	0.7898	0.5852	0.6385	<u>0.7790</u>	0.5562	0.6887	0.8142	0.5768	0.6599	0.7943
OURS	0.7714	0.7354	0.8237	0.7662	0.7315	0.7906	0.7891	0.7656	0.8329	0.7756	0.7442	0.8157

Table 2: Knowledge tracing performance comparison on XES3G5M and MOOCRADAR. **Bold** number indicates the best performance in each module, and underlined number indicates the second best. The Avg. column reports the average result across all modules in each dataset.

two students (Fig. 3), as the historical observation, Q_i , expands. Color reflects differences between the current mastery probability and the initial estimation based on burn-in data only. Each node is annotated with step-wise mastery change. Our findings are as follows:

First, we find the probability updates align with the inputs. In this example, Student A solves all three questions correctly, leading to an increase in mastery probability on all nodes in the tree. Student B answers the first question correctly, but the next two incorrectly. As a result, only the “Count Line” node corresponding to the first question shows a higher mastery probability than the initial estimation, while the rest of the nodes all get lower mastery probabilities.

Second, it is worth noting that due to the tree propagation, the mastery probability changes are not confined to the KCs directly associated with the questions. Other nodes also dynamically adjust their mastery probabilities, even when the KC has not been explicitly visited in the student’s exercise history. This effect is evident not only in direct parent or sibling nodes. For example, Student A correctly answering a “Count Lines” question also increases confidence in “Auxiliary Line”.

In summary, these findings demonstrate the ability of KT^2 to dynamically update and adjust the student’s profile in a structured and interpretable way, with respect to the concept hierarchy.

4.5 ABLATION STUDY

Fig. 4ab shows the AUC results on both datasets (average across all modules) under two settings: ① different burn-in sizes, and ② different classroom sizes. We exclude LLM-based KT methods from these comparison, as their few-shot prompting approach relies on randomly selected examples from the same student rather than leveraging the structured burn-in set and peers’ data.

As observed, KT^2 consistently outperforms the baselines across all burn-in size settings, particularly in low burn-in scenarios, but also remains competitive under larger burn-in sizes. When the burn-in size increases, all offline methods benefit less from online updates. Similar trends are observed when varying classroom size. Our method achieves the best performance in all cases, highlighting its ability to generalize well even with limited peers. The fact that DLKT models require a substantial

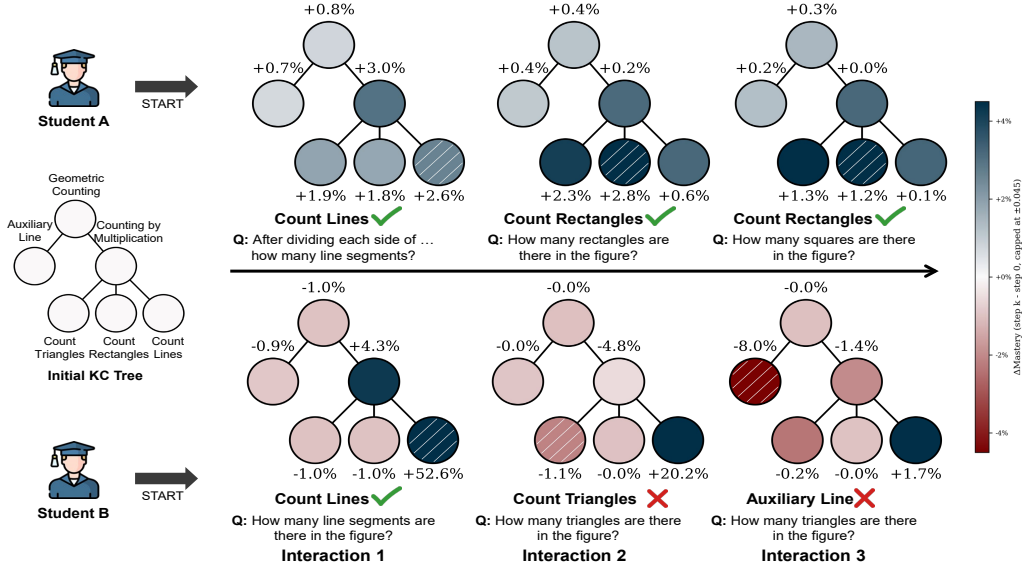


Figure 3: Examples of KC mastery probability update. Node color indicates the cumulative mastery probability change from the initial estimation (after burn-in) to the current step, with blue for increase and red for decrease. The value denotes the step-wise change. The node with dashed lines indicates the current concept. The row under each tree shows the student’s interaction at that step.

amount of data to perform well further underscores their limitations in real-world classroom settings, where the ability to understand students’ capabilities from a limited data is crucial.

We further ablate update individualization (Fig. 4c), ranging from fixing both model parameters and student mastery posteriors after burn-in, to updating only the posteriors during inference phrase, and finally to updating both, corresponds to our proposed KT². Results show that posterior updates alone already improve performance, while full updates consistently achieve the best results.

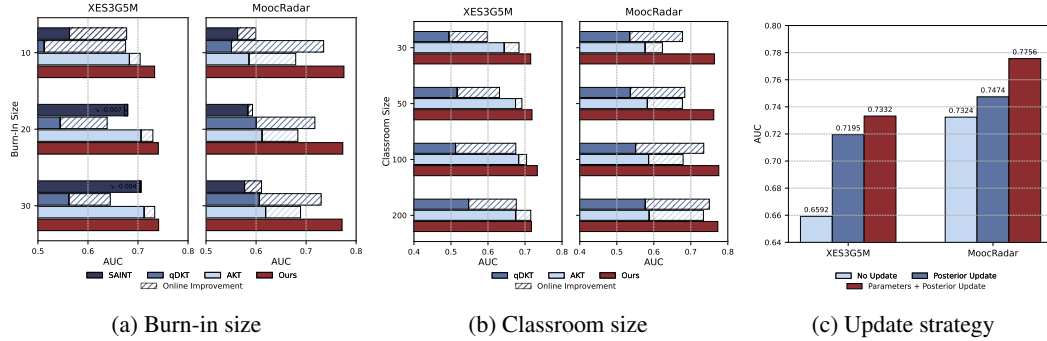


Figure 4: Ablation studies. (a) Effect of burn-in size. (b) Effect of peers number. (c) Effect of update individualization. Dashed bars/lines denote online improvement; negative gains annotated inline.

5 CONCLUSION

In this paper, we propose KT², a probabilistic framework for low-resource, online knowledge tracing. Leveraging the hierarchical structure of KCs, KT² builds a Hidden Markov Tree Model, where hidden variables represent concept mastery levels and observed variables correspond to students’ correctness on exercise questions. It enables effective learning from minimal initial data and supports incremental updates as new responses are observed. Experiments across six simulated classroom scenarios show that KT² consistently outperforms existing baselines. Qualitative analysis further demonstrates the ability of KT² to dynamically refine mastery estimates and propagate the updates across related concepts. Overall, our work underscores the value of integrating concept hierarchies and probabilistic inference in developing practical, personalized knowledge tracing systems.

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A PARAMETER ESTIMATION

In this section, we provide the closed-form solution of $\theta^{(\tau)}$, computed by taking the partial derivative on Eq. equation 13 with respect to each parameter.

$$\gamma_{ci}^{\text{master } \mathcal{P}(c)} = p_{\theta^{(\tau-1)}}(K_{ci} = 1, K_{\mathcal{P}(c)i} = 0 | \mathcal{Q}_i) \quad (15)$$

$$\gamma_{ci}^{\text{not-master } \mathcal{P}(c)} = p_{\theta^{(\tau-1)}}(K_{ci} = 0, K_{\mathcal{P}(c)i} = 0 | \mathcal{Q}_i) \quad (16)$$

$$\gamma_c^{(\tau)} = \frac{\sum_i \gamma_{ci}^{(1)}}{\sum_i \gamma_{ci}^{(0)} + \sum_i \gamma_{ci}^{(1)}}. \quad (17)$$

The closed-form solution of any root node can be obtained similarly by removing the $K_{\mathcal{P}(c)i} = 0$.

We define $\mathcal{N}_{\text{pos}}^{(i)}$ and $\mathcal{N}_{\text{neg}}^{(i)}$ as the sets of correctly and incorrectly answered questions by student i , respectively. Then we have

$$\varepsilon_i^{\text{pos}} = \sum_{n:n \in \mathcal{N}_{\text{pos}}^{(i)}} p_{\theta^{(\tau-1)}}(K_{\mathcal{M}(n)i} = 0 | \mathcal{Q}_i) \quad (18)$$

$$\varepsilon_i^{\text{neg}} = \sum_{n:n \in \mathcal{N}_{\text{neg}}^{(i)}} p_{\theta^{(\tau-1)}}(K_{\mathcal{M}(n)i} = 0 | \mathcal{Q}_i) \quad (19)$$

$$\varepsilon^{(\tau)} = \frac{\sum_i \varepsilon_i^{\text{pos}}}{\sum_i \varepsilon_i^{\text{neg}} + \sum_i \varepsilon_i^{\text{pos}}}. \quad (20)$$

For each difficulty class l , where $l \in \{\text{easy}, \text{medium}, \text{hard}\}$, the closed-form solution of the emission probability is

$$r_i^{\text{pos}} = \sum_{\substack{n: n \in \mathcal{N}_{\text{pos}}^{(i)} \\ \text{difficulty}=l}} p_{\theta^{(\tau-1)}}(K_{\mathcal{M}(n)i} = 1 | \mathcal{Q}_i) \quad (21)$$

$$r_i^{\text{neg}} = \sum_{\substack{n: n \in \mathcal{N}_{\text{neg}}^{(i)} \\ \text{difficulty}=l}} p_{\theta^{(\tau-1)}}(K_{\mathcal{M}(n)i} = 1 | \mathcal{Q}_i) \quad (22)$$

$$r_l^{(\tau)} = \frac{\sum_i r_i^{\text{pos}}}{\sum_i r_i^{\text{neg}} + \sum_i r_i^{\text{pos}}}. \quad (23)$$

B UPWARD-DOWNWARD ALGORITHM

For each student i , we only need to compute the following posterior distributions, which are sufficient for updating all required parameters.

$$p_{\theta}(K_{\mathcal{M}(n)i} = 1 | \mathcal{Q}_i) \quad (24)$$

$$p_{\theta}(K_{\mathcal{M}(n)i} = 0 | \mathcal{Q}_i) \quad (25)$$

$$p_{\theta}(K_{ci} = 1, K_{\mathcal{P}(c)i} = 0 | \mathcal{Q}_i) \quad (26)$$

$$p_{\theta}(K_{ci} = 0, K_{\mathcal{P}(c)i} = 0 | \mathcal{Q}_i) \quad (27)$$

We first introduce two auxiliary probabilities. The first one is **downward probability**

$$\alpha_c(k) = p(K_c = k, \mathcal{Q}_{S_{\mathcal{V} \setminus \mathcal{D}(c)}} = \mathbf{q}_{S_{\mathcal{V} \setminus \mathcal{D}(c)}}). \quad (28)$$

Here, $\mathcal{D}(c)$ denotes all the descendant nodes of c , **including** c . $\mathcal{V} \setminus \mathcal{D}(c)$ denotes all the nodes except for $\mathcal{D}(c)$. $\mathcal{Q}_{S_{\mathcal{V} \setminus \mathcal{D}(c)}}$ represents all the questions that involve concepts in $\mathcal{V} \setminus \mathcal{D}(c)$ and $\mathcal{V} \setminus \mathcal{D}(c)$ only. $\mathcal{S}_c$ denotes the set of questions that involves KC c and that is answered by student i (the subscript i is removed for convenience).

The second probability is called the **upward probability**

$$\beta_c(k) = p(\mathcal{Q}_{S_{\mathcal{D}(c)}} = \mathbf{q}_{S_{\mathcal{D}(c)}} | K_c = k). \quad (29)$$

The upward probability can be recursively computed from that of the children nodes (denote the children nodes of c as $\text{Child}(c)$)

$$\beta_c(k) = \prod_{n \in \mathcal{S}_c} p(Q_n = q_n | K_c = k) \cdot \prod_{j \in \text{Child}(c)} \tilde{\beta}_{j,c}(k), \quad (30)$$

where

$$\tilde{\beta}_{j,\mathcal{P}(j)}(k) = p(\mathcal{Q}_{S_{\mathcal{D}(j)}} = \mathbf{q}_{S_{\mathcal{D}(j)}} | K_{\mathcal{P}(j)} = k) \quad (31)$$

$$= \sum_{k_j} \beta_j(k_j) p(K_j = k_j | K_c = k). \quad (32)$$

At leaf nodes, $\beta_c(k)$ is just a simple emission probability.

The downward probability can be recursively computed from that of the parent node

$$\alpha_c(k) = p(K_c = k, \mathcal{Q}_{S_{\mathcal{V} \setminus \mathcal{D}(c)}} = \mathbf{q}_{S_{\mathcal{V} \setminus \mathcal{D}(c)}}) \quad (33)$$

$$= \sum_{k_{\mathcal{P}(c)}} p(K_c = k | K_{\mathcal{P}(c)} = k_{\mathcal{P}(c)}) \tilde{\alpha}_{\mathcal{P}(c)}, \quad (34)$$

where

$$\tilde{\alpha}_{\mathcal{P}(c)}(k) = \alpha_{\mathcal{P}(c)}(k_{\mathcal{P}(c)}) \frac{\beta_{\mathcal{P}(c)}(k_{\mathcal{P}(c)})}{\tilde{\beta}_{c, \mathcal{P}(c)}(k_{\mathcal{P}(c)})}. \quad (35)$$

At root nodes, $\alpha_c(k)$ is just the prior distribution.

After all the auxiliary variables are computed, the target posterior distributions can be computed as

$$p_{\theta}(\mathcal{K}_{ci} = 1 | \mathcal{Q}_i) = \frac{\alpha_c(1)\beta_c(1)}{\sum_{k=0}^1 \alpha_c(k)\beta_c(k)}, \quad (36)$$

$$p_{\theta}(K_{ci} = k_c, K_{\mathcal{P}(c)i} = k_{\mathcal{P}(c)} | \mathcal{Q}_i) = \frac{\tilde{\alpha}_{\mathcal{P}(c)}(k_{\mathcal{P}(c)})\beta_c(k_c)p(k_c | k_{\mathcal{P}(c)})}{\sum_{k'_c, k'_{\mathcal{P}(c)} \in \{0,1\}} \tilde{\alpha}_{\mathcal{P}(c)}(k'_{\mathcal{P}(c)})\beta_c(k'_c)p(k'_c | k'_{\mathcal{P}(c)})}. \quad (37)$$

C USE OF LARGE LANGUAGE MODELS

In this paper, we utilized LLMs for auxiliary purposes only. Specifically, LLMs were used to polish the writing and correct grammatical issues in the manuscript, and to assist in data translation (see Appendix D) and KC tree construction when only fine-grained KCs are provided (see Appendix F).

D TRANSLATION

For both XES3G5M and MOOCRADAR, the data translation is done following the pipeline below.

We translated each question into English using GPT-4o-mini with *[Prompt for Translation]*. We specifically required the LLM to convert all fill-in-the-blank questions into a proper question format (e.g., ‘There are __ squares in the plot.’ should be transformed into ‘How many squares are there in the plot?’). Then, the GPT-4o-mini was prompted with *[Prompt for Translation Check]* to self-check the correctness of its translation, considering both the meaning match between the Chinese question and the English translation, as well as the question format conversion.

We noticed that in the XES3G5M dataset, the blank symbol might be missing in some Chinese fill-in-the-blank questions (e.g., the question ‘There are __ squares in the plot.’ might be recorded as ‘There are squares in the plot.’), leading to difficulty in both the translation and the correctness check phases. To handle the incorrect translations, we used a stronger model, GPT-4o, to double-check the translation correctness and generate an explanation for its justification using the same *[Prompt for Translation Check]*. All questions regarded as incorrect by GPT-4o proceeded into an automatic translation revision phase, where GPT-4o was prompted with the *[Prompt for Translation Fix]* to revise the translation utilizing the explanation of why this translation was incorrect.

After one round of correction, GPT-4o checked the correctness of the new translation again. After this stage, the remaining incorrect translations were revised by a human translator and added to the collection of English translations. See Appendix J for all translation prompts.

E DATASETS

We summarized the statistics of original XES3G5M and MOOCRADAR in Table 3.

License: XES3G5M is an open-sourced dataset released under the MIT license, which allow free use of research and educational purposes. MOOCRADAR is also publicly available for academic research. Both datasets have been anonymized to protect student privacy and do not contain personal identifiable information.

F KNOWLEDGE CONCEPT TREES

In this section, we describe the details of knowledge concept trees for the XES3G5M and MOOCRADAR. As noted in Sec. 4.1, XES3G5M provides a predefined hierarchical structure of

Dataset	Students	Items	KCs	Interactions
XES3G5M	18,066	7,652	865	5.5M
MOOCRadar	14,224	2,513	5,600	12.7M

Table 3: Dataset statistics.

KCs, which we adopt directly as its knowledge concept tree. In contrast, MOOCRADAR includes only fine-grained KCs without any hierarchical organization, so we construct a knowledge concept tree for it. To begin, we embed the original Chinese KCs using the bge-base-zh model (Xiao et al., 2023), producing semantic embeddings. These embeddings are then reduced in dimensionality using UMAP (McInnes et al., 2018) and clustered with HDBSCAN (Campello et al., 2013) to group semantically similar KCs. This process yields a set of KC clusters along with a number of outliers that do not belong to any cluster. For each cluster, we use GPT-4o-mini to generate a summarized KC label. To maintain robustness, we include an “unsummarizable” option, allowing the model to flag incoherent clusters, which are then manually reviewed and reclassified. For the outlier KCs, we sample a representative exercise from the dataset and prompt GPT-4o-mini again to determine whether the KC can be merged into an existing cluster. If not, it is retained as an independent node and manually labeled on a case-by-case basis.

We also apply post-processing to refine the knowledge concept trees. Since we assume each exercise is associated with a single KC, we retain only the most frequently occurring KC when multiple are assigned. Additionally, we merge child nodes associated with fewer than 10 unique exercises into their parent to avoid sparsity. If only one child remains after merging, its questions are reassigned to the parent, and the child node is pruned.

G MODULE STATISTICS

Table 4 shows the statistics of all six knowledge modules. The view of each module can be found in Appendix I.

Module	#Nodes	Max Depth	#Leaves
Application Module	148	5	100
Computation Module	95	5	66
Counting Module	69	5	46
Wine Knowledge	5	2	4
Circuit Design	9	2	8
Education Theory	4	2	3

Table 4: Statistics of the knowledge modules.

H IMPLEMENTATION DETAILS

We initialize our model parameters as in Table 5.

Parameter	Symbol	Initial Value
Transition	γ_c	0.1
Emission (easy)	r_{easy}	0.9
Emission (medium)	r_{med}	0.8
Emission (hard)	r_{hard}	0.75
Guessing	ε	0.1

Table 5: Initialization values for model parameters before EM training.

We observe that the guessing probability ε can exceed 0.3 during training in some cases. To avoid overfitting to spurious correct responses, we clip ε to a maximum of 0.3 in each EM update iteration. This constraint prevents ε from approaching the emission probability of hard questions, which would make it difficult to distinguish between true mastery and random guessing.

For IBKT, we used the open-source pyBKT implementation (Badrinath et al., 2021). For AKT, SAINT, and QDKT, we adopt the standardized implementation provided by PYKT (Liu et al., 2022), a unified Python library for benchmarking KT models. We implement REKT by the official GitHub repository. For all LLM baselines, we adopt the publicly released checkpoints.

For all deep-learning-based baseline methods, we follow the default hyperparameters reported in their original papers to train the offline versions. For online variants, we set the learning rate to $1e-4$ and the batch size to 32, and train for a single epoch at each update step.

For both LLM-based baseline methods, we use the vLLM package (Kwon et al., 2023) for inference, with a sampling temperature of 0.8, a top-p (nucleus) sampling threshold of 0.8, and a repetition penalty of 1.1.

Here we included a runtime comparison of KT² and other online baselines on representative modules from the two datasets in the table below.

Model	XES3G5M	MOOCRadar	Device
KT ²	412.1 s (6.9 min)	224.3 s (3.7 min)	CPU
AKT-ONLINE	284.8 s (4.7 min)	196.6 s (3.3 min)	RTX A6000 (48GB, 1 GPU)
SAINT-ONLINE	197.5 s (3.3 min)	134.7 s (2.2 min)	RTX A6000 (48GB, 1 GPU)
QDKT-ONLINE	74.3 s (1.2 min)	45.4 s	RTX A6000 (48GB, 1 GPU)
QWEN-2.5	4.5 hours	3.2 hours	NVIDIA H100 (80GB, 1 GPU)
LLAMA-3.2	25 min	16 min	NVIDIA H100 (80GB, 1 GPU)

Table 6: Runtime comparison across datasets.

KT² requires slightly longer update time, as it performs individualized update for each student, while DLKT-online aggregates interactions across students and retrain less frequently. Despite the additional cost, the method remains efficient and yields consistent performance improvements.

For LLM, we can see that Qwen-2.5-7B takes 4.5h and LLaMA-3.2-3B takes 25 min on a 80G H100 GPU. This suggests that LLM-based inference is significantly more expensive.

I MODULE VIEWS

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864
865
866 Application Module
867   +-- Equation Word Problem
868   |   +-- Linear Equation Word Problem
869   |   \-- Indeterminate Equation Word Problem
870   +-- Addition/Subtraction Word Problem
871   |   +-- Change in Ratio Word Problem
872   |   \-- Simultaneous Increase/Decrease Word Problem
873   +-- Period Problem
874   |   +-- Basic Arrangement Period Problem
875   |   +-- Sequence Operation Period Problem
876   |   |   +-- Number Period
877   |   |   \-- Find Which Number in Sequence Problem
878   |   +-- Period Problem in Time
879   |   |   +-- Period in Calendar Dates
880   |   |   +-- Period in Time
881   |   |   \-- Find Day of the Week for a Date Problem
882   |   \-- Cyclic Operation Period Problem
883   +-- Sum and Difference Multiple Problem
884   |   +-- Basic Calculation of Multiples
885   |   |   +-- Two Quantities Multiple
886   |   |   \-- Multiple Quantities Multiple
887   |   +-- Change Multiple Problem
888   |   |   +-- Two Quantities Simultaneously Change Multiple
889   |   |   \-- Basic Change Multiple
890   |   +-- Sum and Multiple Problem
891   |   |   +-- Two Quantities Sum and Multiple Problem
892   |   |   |   \-- Two Quantities Sum and Multiple
893   |   |   +-- Multiple Quantities Sum and Multiple Problem
894   |   |   |   \-- Multiple Quantities Sum and Multiple
895   |   |   +-- Find Hidden Sum
896   |   |   \-- From Less to More
897   |   +-- Sum and Difference Problem
898   |   |   +-- Two Quantities Sum and Difference Problem
899   |   |   |   +-- Known Differences
900   |   |   |   +-- Known and Hidden Difference
901   |   |   |   \-- Hidden and Known Difference
902   |   |   \-- Multiple Quantities Sum and Difference Problem
903   |   \-- Difference Multiple
904   |       +-- Two Quantities Difference Multiple
905   |       |   +-- Integer Ratio with Difference
906   |       |   +-- Hidden Ratio Type Two Quantities Difference Multiple Problem
907   |       |   +-- Hidden Difference Type Two Quantities Difference Multiple Problem
908   |       |   +-- Non-integer Ratio Difference Multiple Insufficient
909   |       |   \-- Non-integer Ratio Difference Multiple Remainder
910   |       \-- Multiple Quantities Difference Multiple
911
912   ...
913
914   \-- Chicken-Rabbit Problem
915   |   +-- Assumption Method for Solving Chicken-Rabbit Problem
916   |   |   +-- Back-Deduction Type
917   |   |   +-- Basic Type
918   |   |   |   +-- Prototype Problem
919   |   |   |   \-- Variant Problems
920   |   |   \-- Find Number of Animals
921   |   +-- Grouping Method for Solving Chicken-Rabbit Problem
922   |   |   +-- Head Multiple Type
923   |   |   \-- Flexible Grouping
924   |   +-- Multiple Quantities Chicken-Rabbit Problem
925   |   +-- Using Assumption Method to Solve Modified Chicken-Rabbit Problem
926   |   +-- Using Grouping Method to Solve Modified Chicken-Rabbit Problem
927   |   \-- Using Grouping Method to Solve Basic Chicken-Rabbit Problem

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918 Computation Module
919   +-- Exponentiation
920   |   +-- Application of Exponentiation
921   |   \-- Exponentiation Operations
922   +-- Fraction
923   |   +-- Fraction Basics
924   |   |   +-- Properties of Fractions
925   |   |   \-- Meaning of Fractions
926   |   +-- Fraction Tricks
927   |   \-- Fraction Operations
928   |       +-- Fraction Addition and Subtraction
929   |       \-- Addition and Subtraction of Fractions with Different Denominators
930   +-- Unit Conversion
931   |   +-- Length Unit Conversion
932   |   \-- Area Unit Conversion
933   +-- Define New Operation
934   |   +-- Reverse Solving Unknown Type
935   |   \-- Direct Calculation Type
936   |       \-- Normal Type
937   +-- Decimal
938   |   +-- Decimal Addition and Subtraction
939   |   |   +-- Decimal Addition and Subtraction Trick with Rounding Method
940   |   |   \-- Decimal Addition and Subtraction Vertical Format Calculation
941   |   +-- Decimal Four Operations
942   |   +-- Decimal Basics
943   |   |   +-- Rounding
944   |   |   +-- Decimal Comparison
945   |   |   +-- Decimal Point Movement Patterns
946   |   |   \-- Understanding Decimals
947   |   \-- Meaning of Decimals
948   |       +-- Decimal Point Movement
949   |       \-- Reading and Writing Decimals
950   +-- Sequences and Number Tables
951   |   +-- Sequence Patterns
952   |   +-- Number Table Patterns
953   |   |   +-- Finding Patterns by Combining Numbers and Diagrams (Multiple Diagrams)
954   |   |   \-- Rectangle Number Table
955   |   |       +-- Positional Relationship
956   |   |       +-- Find Number at Known Position in Continuous Natural Number Rectangle Table
957   |   |       \-- Find Position of Known Number in Continuous Natural Number Rectangle Table
958   |   +-- Arithmetic Sequence
959   |   |   +-- Application of Mean Value Theorem
960   |   |   +-- Truncated Sum of Arithmetic Sequence
961   |   |   +-- Find Common Difference of Arithmetic Sequence
962   |   |   +-- Sum of Arithmetic Sequence
963   |   |   +-- Find General Term of Arithmetic Sequence
964   |   |   \-- Find Number of Terms in Arithmetic Sequence
965   |   \-- Geometric Sequence
966   ...
967
968   +-- Equation Basics
969   |   +-- Linear Equation in One Variable
970   |   |   \-- Equation with Integer Coefficients
971   |   \-- Indeterminate Equation
972   +-- Comparison and Estimation
973   \-- Induction of Split and General Terms

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972 Counting Module
973   +-- Geometric Counting
974   |   +-- Categorical Enumeration of Figures
975   |   |   +-- Regular Figure Enumeration Counting
976   |   |   |   +-- Categorized Figures
977   |   |   |   |   +-- Square
978   |   |   |   |   +-- Understanding Line Segments
979   |   |   |   |   \-- Rectangle
980   |   |   \-- Lattice Point Constructed Figures
981   |   +-- Correspondence Method Figures
982   |   |   \-- Counting by Multiplication
983   |   |       +-- Count Triangles
984   |   |       +-- Count Lines
985   |   |       \-- Count Rectangles
986   |   \-- Auxiliary Line
987   +-- Addition-Multiplication Principle
988   |   +-- Multiplication Principle
989   |   |   +-- Other Types in Multiplication Principle
990   |   |   +-- Object Quantity Combination
991   |   |   +-- Item Matching
992   |   |   +-- Item Matching (With Special Requirements)
993   |   |   \-- Route Matching Problem
994   |   +-- Comprehensive Addition-Multiplication Principle
995   |   +-- Addition Principle
996   |   |   +-- Other Types in Addition Principle
997   |   |   \-- Handshake and Toasting Problem
998   |   +-- Queueing Problem
999   |   +-- Coloring Counting Problem
1000   |   \-- Grouping Problem
1001   |       +-- General Grouping Problem
1002   |       \-- Grouping Problem with Special Requirements
1003   +-- Inclusion-Exclusion Principle
1004   |   +-- Three-Set Inclusion-Exclusion
1005   |   +-- Two-Set Inclusion-Exclusion
1006   |   \-- Geometric Counting with Multi-Set Inclusion-
1007   ...
1008   +-- Comprehensive Enumeration Method
1009   |   +-- Lexicographical Order Method
1010   |   |   +-- Grouping
1011   |   |   |   +-- Increasing Numbers (Decreasing Numbers)
1012   |   |   |   +-- Card Grouping
1013   |   |   |   +-- Number Grouping (No Repetition)
1014   |   |   |   +-- Number Grouping (Repetition Allowed)
1015   |   |   |   \-- Number Grouping (Specified Digit Size)
1016   |   |   \-- Non-Numeric Permutation
1017   |   +-- Integer Partition
1018   |   |   +-- Integer Partition Application
1019   |   |   |   +-- Multiplicative Partition (Application)
1020   |   |   |   \-- Additive Partition (Application)
1021   |   |   \-- Simple Partition
1022   |   |       +-- Additive Partition (Non-Identical Numbers)
1023   |   |       \-- Additive Partition (Specified Count)
1024   |   \-- Enumeration Method
1025   |       +-- Methods of Payment
1026   |       +-- Ordered Enumeration
1027   |       \-- Distribute Items by Given Count
1028   +-- Counting Method
1029   |   +-- Standard Counting Method
1030   |   |   \-- Shortest Path
1031   |   +-- Special Points or Areas
1032   |   \-- Stepwise Counting Method
1033   \-- Statistics and Probability
1034   +-- Probability
1035   \-- Statistical Charts

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1026 Wine Knowledge
1027   +-- Wine
1028   +-- Wine Evaluation Knowledge
1029   +-- Wine Aroma Type
1030   \-- Types of Wine
1031
1032 Circuit Design
1033   +-- Amplifier Circuit Design
1034   +-- Ideal Operational Amplifier
1035   +-- Electronics
1036   +-- Electrical Concepts
1037   +-- Electrical Circuit Knowledge
1038   +-- Circuit Design and Analysis
1039   +-- Operational Amplifier Knowledge
1040   \-- Integrated Operational Amplifier Circuit
1041
1042 Education Theory
1043   +-- Feedback
1044   +-- Class Teacher Management and Teacher-Student Relationship
1045   \-- Foundation of Class Formation
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J LLM PROMPT

In this section, we provide the complete prompts for LLM baselines and dataset translation.

Prompt for Translation:

You are a helpful AI assistant skilled in translating Chinese exercises to English.

Guidelines:

- You will be provided with an exercise in Chinese. Your task is to translate it accurately and clearly into English.
- If the Chinese question is a fill-in-the-blank question, convert it into a proper question format in English. Be mindful that the blank symbol might be missing from the original question due to formatting errors.
- Output only the translated English text. Do not include any additional text, explanations, or formatting beyond the translation.

Examples:

User 1:

Here is the math exercise to translate: (*Omit the Chinese question*)

Assistant 1:

Xiao Ming has 10 apples, Xiao Hong has 5 apples, how many more apples does Xiao Ming have than Xiao Hong?

...

(*Omit other 2 examples*)

Here is the math exercise to translate: (*Omit the Chinese question*)

Prompt for Translation Check:

You are a helpful AI assistant skilled in assessing the quality of Chinese question translations for accuracy and coherence. You will be provided with two versions of an exercise: one in Chinese and one in English. Your task is to evaluate whether the English translation accurately reflects the meaning and intent of the Chinese question and provide a detailed explanation to justify your assessment.

Guidelines:

- If the Chinese question is a fill-in-the-blank question, the English translation must be rewritten into a proper question format without retaining the blank symbol. If it fails to meet this requirement, consider it an incorrect translation.
- Be mindful of potential formatting errors in the Chinese question. For example, the blank symbol in a fill-in-the-blank question might be missing. Carefully discern whether the question is a statement or a fill-in-the-blank question with a missing blank.
- If the Chinese question references an image, it is acceptable for the English translation to omit the image filename as long as it maintains the question's meaning.
- Output your evaluation in JSON format using the provided template. First, explain why the English translation is correct or incorrect, then provide a final justification as a boolean value (True for correct, False for incorrect).
- Do not include any additional text or explanations beyond the required JSON output.

Template:

```
{
  "explanation": (Your explanation on why you think the English translation is correct/wrong),
  "correct_translation": (a boolean value, True if the English translation is a correct translation, False otherwise)
}
```

Examples:

User 1:

Here is the Chinese question:(*Omit the Chinese question*)

Here is the English translation of the question: A number, when divided by 4, added 4, multiplied by 4, and then subtracted 4, results in 16. What is the number?

Assistant 1:

```
{
  "explanation": "The Chinese question describes a sequence of mathematical operations performed on a number, leading to the result of 16. The English translation accurately conveys the meaning of the Chinese question by describing the same sequence of operations and the expected result, while appropriately converting the blank into the question format 'What is the number?'. Both the meaning and format are correct.",
  "correct_translation":
}
```

...

(*Omit other 2 examples*)

Here is the Chinese question:(*Omit the Chinese question*)

Here is the English translation of the question:(*Omit the English translation*)

Prompt for Translation Fix:

You are a helpful AI assistant skilled in improving the translation of Chinese questions to ensure accuracy and coherence. You will be provided with two versions of a question: one in Chinese and one in English, along with an explanation of why the translation is incorrect. Your task is to rewrite the English translation based on the given explanation to make it correct and consistent with the original Chinese question.

Guidelines:

- Be mindful of potential formatting errors in the Chinese question. For example, the blank symbol in a fill-in-the-blank question may be missing. Carefully discern whether the question is a statement or a fill-in-the-blank question with a missing blank.
- If the Chinese question is a fill-in-the-blank question, rewrite the English translation as a proper question without retaining the blank symbol.
- Provide only the corrected English translation as the output. Avoid including additional explanations or text.

Examples:

User 1:

Here is the Chinese question: *(Omit the Chinese question)*

Here is the English translation you should rewrite: A number, when divided by 4, added 4, multiplied by 4, and then subtracted 4, results in 16. Then the number is ()

The reason why the translation is incorrect: The Chinese question is a fill-in-the-blank question as indicated by the blank symbol (), which requires the English translation to be reformatted into a proper question format without the blank. The provided English translation retains the blank, which does not conform to the specified criteria for a correct translation.

Assistant 1:

Xiao Ming has 10 apples, Xiao Hong has 5 apples, how many more apples does Xiao Ming have than Xiao Hong?

...

(Omit other 2 examples)

Here is the math exercise to translate: *(Omit the Chinese question)*

Here is the English translation you should rewrite: *(Omit the English translation)*

The reason why the translation is incorrect: *(Omit the explanation)*

Prompt for LLM Knowledge Tracing:

Your task is to analyze student's past performance on a series of questions and predict whether students can answer a given question correctly. Below are 10 questions the student has already answered. After each question you will see whether the answer was correct (1) or incorrect (0).

Q1. In a capacitive coupling amplifier circuit, after introducing negative feedback, it is only possible to have low-frequency self-excited oscillation, and high-frequency self-excited oscillation is not possible. Is this statement true or false?

Concepts: Feedback

Correct: 0

Q2. Since some negative feedback amplifiers can produce self-excited oscillations, can they be used as signal sources?

Concepts: Feedback

Correct: 0

Q3. ...

(Omit the other 8 historical exercises)

Now consider the new question:

If negative feedback is introduced through a resistor in a single-stage common-emitter amplifier, what will happen? If negative feedback is introduced through a resistor in a two-stage common-emitter amplifier, what will happen? A. It will definitely produce high-frequency self-oscillation B. It may produce high-frequency self-oscillation C. It will definitely not produce high-frequency self-oscillation.

Concepts: Feedback

Based on the student's past performance, will the student answer this question correctly? Respond with 1 for correct, 0 for incorrect. Output only 0, 1—no additional text.

Predict: