A novel stochastic model based on echo state networks for hydrological time series forecasting

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Abstract

1	The Stochastic Streamflow Models (SSMS) are time series models for precise prediction of
2	hydrological data useful in hydrologic risk management. Nowadays, deep learning networks
3	get many considerations in time series forecasting. However, despite their theoretical
4	benefits, they fail due to their drawbacks, such as complex architectures, slow convergence
5	and the vanishing gradient problem. In order to alleviate these drawbacks, we propose a
6	new stochastic model applied in problems that involve stochastic behavior and periodic
7	characteristics. The new model has two components, the first one, a type of recurrent
8	neural network embedding the echo-state (ESN) learning mechanism instead of conventional
9	backpropagation. The last component adds the uncertainty associated with stationary
10	processes. This model is called Stochastic Streamflow Model ESN (SSMESN). It was
11	calibrated with time series of monthly discharge data from MOPEX data set. Preliminar
12	results show that the SSMESN can achieve a significant prediction performance, learning
13	speed. This model, can be considered a first attempt that applies the echo state network
14	methodology to stochastic process.

15 1 Motivation

In probability theory, an stochastic process is defined as a set of models that allow the study of problems 16 with random components. Natural phenomena such as precipitation and streamflow discharge have nonlinear, 17 complex and chaotic characteristics. In order to model the behavior of these phenomena, initially linear 18 19 approximation was used [2, 11]. Afterwards, were developed methods using self-correcting models such as the PAR(p) model [12, 4]. However, these models are statistical, linear and they cannot capture real 20 chaotic characteristics of hydrometeorological time series, being they sometimes inadequate [13]. Currently, 21 Deep learning (DL) approaches [17], attempt to model this complex non-linear behavior. In fact, DL have 22 been widely used in the recent literature from simplest feedforward Neural Network (ANN) to the most 23 complex Recurrent architecture LSTM. Studies on forecasting performance, show that Recurrent Neural 24 Networks(RNN) [6] are better than their peers ANN, in virtually all tests [3]. However, literature on stochastic 25 models shows preference to use feedforward ANN than RNN, because the last one generates greater complexity 26 in the training process, slow convergence rate, as well as vanishing gradient problems [15]. All it is added to 27 the complexity that uncertainty analysis and stochastic simulation requires [4]. This motivated the development 28 of a stochastic process model using RNN and the echo-state (ESN) learning mechanism instead of conventional 29 backpropagation, the interesting property of ESN is that only the readout layer is trained, whereas the recurrent 30 topology has fixed connection weights [10]. ESN is a training approach attractive as simple and fast compared 31 to other approaches used in RNN, all in order to reduce complexity, and leverage its proven ability to represents 32 the characteristics of time series. 33

2 Proposal: Stochastic Streamflow model ESN (SSMESN)

The figure 1 details our model, it generates scenarios $Y_{v,t}$ of hydrological synthetic data, in terms of monthly intervals, and can be resume by

$$Y_{v,t} = f(R_{v,t} + E_{v,t})$$
(1)

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Figure 1: Generation of synthetic scenarios, the new SSMESN model.

			Horizon											
		12 months							24 months					
		Model	RMSE	MSE	MAD	NRMSE	E MPE	NSE	RMSE	MSE	MAD	NRMSE	MPE	NSE
	01541500	TF SSMESN	0.68528	0.471 0.3818	0.59818	30.74254	123.67	0.39673	0.64384	0.41501	0.53775	50.73835 50.64134	98.6120	0.43049 0. 57072
01		NSP LSTM	0.68959 0.68863	0.47714	0.5934	0.74721	120.21 120.97	0.38887 0.39085	0.69945 0.64236	0.48996 0.41309	0.58354	40.80212 0.73665	106.030 96.0570).32763).43312
MOPEX bas	413000	TF SSMESN NSP LSTM	1.4658 1.26 1.3454 1.2965	2.1549 1.5903 1.8235 1.6952	1.0567 0.9317 0.98360 0.94809	1.4564 9 1.2519 5 1.3368 9 1.2881	156.42 154.03 150.53 142.2	-1.3207 - 0.71271 -0.9639 -0.82572	1.3793 1.306 1.365 2.1.3736	1.9048 1.7064 1.8667 1.8903	0.99965 0.8915 7 0.98498 0.99941	50.72012 7 0.68185 30.71267 10.71717	160.2 (131.67 157.32(162).45817).51463).46902 0.4623
B. 03	054500	TF SSMESN NSP LSTM	1.1956 1.0688 1.1793 1.2063	1.4316 1.1425 1.3926 1.457	1.045 0.90358 1.0242 1.0463	0.69638 80.62255 0.68688 0.70264	475.29 363.55 447.6 457.65	0.47014 0.57716 0.48458 0.46073	1.1604 1.1167 1.1744 1.1611	1.3471 1.2471 1.3796 1.3484	0.94575 0.8774 2 0.95197 0.93855	50.68206 2 0.65638 70.69026 50.68244	312.910 225.150 316.540 299.540).51439).55042).50268 0.51391
01	541000	TF SSMESN NSP LSTM	0.78917 0.68499 0.77286 0.78557	0.6235 0.46933 0.59814 0.61797	0.71423 80.59049 10.69586 70.7088	3 0.77839 9 0.67563 5 0.76229 5 0.77484	138.14 107.96 130.29 133.77	0.33828 0.50191 0.36519 0.34415	0.7325 0.6488 0.73998 0.73209	0.53715 0.42102 0.5481 0.53651	0.62133 0.52178 0.6200 0.6172	30.80215 3 0.7105 1 0.81034 0.80171	97.8990 76.5720 96.0870 95.8670).32783).47315).31413).32863

Table 1: Summary of results (RMSE, MSE, MAD, NRMSE, MPE and NSE) of all methods in four series datasets (discharge) MOPEX [7], 1) each column has the results of a specific stochastic model NSP[4][1], TF[16], LSTM [9] and our *SSMESN*, in a particular metric; 2) each row compares the results of all the methods in a particular data set with a specific horizon value(Monthly Forecasts); 3) Bold rows indicate the best result of each column in a particular metric.

where $E_{v,t}$ is the value produced by the RNN with the echo-state (ESN) learning mechanism, (see equation 2), where W^{out} , is the weight matrix between the internal states x(t+1) added to the input signals y_t and the output neurons, $\delta(.)$ the activation function. $R_{v,t}$ is the stochastic value (see equation 3), where σ_{t+1} , is the standard deviation in month t + 1, the correlation coefficient between months t + 1 and t is r_t and $\epsilon = N(0, 1)$, a normally distributed random noise with zero mean and standard deviation one.

$$E_{t+1} = \delta \left(W^{out} \left(x(t+1) + y_t \right) + \theta_t \right)$$
⁽²⁾

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$$R_{t+1} = \epsilon \times \sigma_{t+1} \times \sqrt{(1 - r_t^2)} \tag{3}$$

43 The above equations are concatenated, (2, 3), to obtain the extended equation of our model:

$$Y_{t+1} = f\left(\delta\left(W^{out} \times \left(\vartheta\left[W^{in}y_t + \theta_t + Wx(t-1)\right] + y_t\right) + \theta_t\right) + R_t\right)$$
(4)

44 **3** Preliminary Results

Experiments were made using the well-known MOPEX data set [7]. Table 1 shows SSMESN as a promising 45 stochastig model, it outperforms the feedforward models (NSP[4][1], LSTM [9]) and the shallow statistical 46 model (TF[16]) in forecasting performance, learning speed and short-term memory capacity [15]. The main 47 model component "RNN-Echo State Network (ESN)" has a highly inter-linked recurrent topology and random 48 initialize. ESN has two interesting properties; the first is that only the last layer is trained, the second is thanks 49 to its internal memory which is the result of recurrent connections it is not necessary to embed previous input 50 signals (sliding windows). Apparently it may seem surprising that a recurrent neural network with random 51 connections may be effective, but randomized parameters have been successful in several domains [8, 14, 5]. 52

53 References

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