
Accelerated Discovery of High-Performance Polyamines for Solid-State Direct CO₂ Capture via Efficient Simulations and Bayesian Optimization

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Abstract

Solid amine-based sorbents are a leading approach for direct air capture (DAC) of CO₂, owing to their energy efficiency and scalability. To enable data-driven discovery of improved sorbents, we developed a computational framework that integrates fragment-based polymer generation with Density Functional Theory (DFT), molecular dynamics (MD) relaxations, and grand canonical Monte Carlo (GCMC) sampling. This workflow provides accurate yet efficient estimates of CO₂ uptake while capturing key structure-property relationships across a diverse library of polymers assembled from well-characterized polyamines for DAC. Leveraging such adsorption data, we investigated the application of the Bayesian optimization (BO) strategy in accelerating the discovery process of high-performing polymer candidates with our developed simulation workflow. Computational experimental results demonstrated the sensitivity of this discovery process to the choice of molecular representation in the surrogate models of BO, especially in a small computational budget scenario, where polymer-specific pre-training provided an early advantage over models trained for general chemical space.

1 Introduction

Mitigating the adverse impact of rising atmospheric CO₂ [1, 2] necessitates the deployment of Carbon Capture and Storage (CCS) technologies, among which direct air capture (DAC) has emerged as a principal strategy. Because of the low atmospheric concentration of CO₂, considerable research has been devoted to the development of highly selective DAC sorbents. Conventional liquid-phase systems, although effective, are hindered by high thermal regeneration requirements [3, 4]. In contrast, solid adsorption [5–7] offers a more energy-efficient and scalable pathway. Within this domain, branched polyamines represent a particularly promising class [8, 9]. Their strong chemical affinity for CO₂, driven by the accessibility of amine functional groups, positions them as key candidates for next-generation sorbents capable of operating under ultradilute CO₂ conditions [10]. However, given the current stage of experimental work, further systematic studies will be important to clarify their behavior and guide the development of improved amine-based sorbents.

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Machine learning-assisted design workflows have seen diverse applications in material discovery – ranging from inverse design paradigm [11] to self-driving laboratories (SDLs) [12] – enabling efficient exploration for materials meeting the design expectations. The field of polymer engineering is no exception to this; especially due to the high-impact application areas such as gas separation membranes, energy storage, fuel cells etc., there has been an increasing trend [13] to leverage machine learning techniques to accelerate the computational design workflow for polymer design. For instance, this includes efforts on molecular representation learning [14–16] for the reliable prediction of polymer characteristics (e.g., glass transition temperature, band gap etc.) as well as generative design approaches like [17] for polymer membranes in post-combustion carbon capture. Our work represents an effort toward incorporating the atomistic simulation, which is currently employed for gaining molecular-level insights behind the sorption mechanism [18], into the polymer sorbent design workflows for direct air capture of CO₂. Specifically, we developed an efficient simulation of the polymer’s CO₂ adsorption mechanism, and generated adsorption data for a library of hypothetical (amine-based) polymers, enabling machine learning models of structure-property relationships required for accelerated identification of high-performing polymers. The key aspects of our work are as follows:

- We generated a dataset of 1,000 polymers and estimated their CO₂ adsorption capacity with our computationally efficient simulation – combining fast MD relaxations with grand canonical Monte Carlo (GCMC).
- We assessed the impact of molecular representation and surrogate models in Bayesian optimization for screening of polymers with high adsorption capacity.

2 Methodology

2.1 Dataset Generation

Our study began with nine well-characterized polyamines (e.g., polyethyleneimine (PEI), polypropyleneimine (PPI) etc.) commonly investigated for direct CO₂ capture due to high amine density and adsorption performance. These reference polymers were fragmented into chemically meaningful building blocks using BRICS[19] and RECAP[20] methods in RDKit[21], ensuring synthetically relevant bonds were cleaved while preserving functional group integrity. Building blocks were then recombined into a large ensemble of hypothetical linear polyamine structures, tailored to emulate realistic polymer backbones with varied chain lengths and terminal functionalities. All generated molecules underwent rigorous validity screening using RDKit. Improper sequences, structures or terminal atoms were discarded. Canonicalization and deduplication ensured that the final database comprised only chemically plausible and unique SMILES strings. This process resulted in a structurally diverse library poised for adsorption modeling.

Each valid polymer was converted into a 3D geometry, energy-minimized, and formatted for batch simulation in molecular dynamics (MD) and grand canonical Monte Carlo (GCMC) workflows (**Appendix A.2**). Fast MD was applied to relax polymer conformations and approximate packing behavior, while subsequent GCMC simulations in LAMMPS provided CO₂ uptake estimates under defined pressure and temperature conditions. Note that we refined the force field parameters (**Appendix A.1**) for accurate modeling of polymer-CO₂-H₂O interactions. The outputs of this computational pipeline (illustrated in Fig. 4) formed the foundational dataset of 1,000 polymers with estimated CO₂ adsorption capacity for downstream Bayesian optimization-based candidate screening.

2.2 Accelerating Discovery with Bayesian optimization

Our developed simulation pipeline for CO₂ adsorption capacity measurement (**Appendix A.2**) has an improved throughput via the combination of Fast MD and GCMC simulation. However, a naive approach to identifying the high-performing polymers by exhaustively simulating all polymer samples in a large pool leads to inefficient usage of computational resources. This work adopted the Bayesian optimization (BO) [22, 23] strategy to prioritize the polymer samples for simulation to accelerate the discovery process, i.e., to find the high-performing polymer samples within a fixed computational budget for simulations of CO₂ adsorption.

We initialize the BO-assisted discovery process with a small number (N_0) of polymer samples $x^{(i)}$ and their simulated adsorption capacity $y^{(i)} = f_{\text{sim}}(x^{(i)})$, where f_{sim} denotes the simulation process.

Our goal is to utilize such labeled data $\mathcal{D}_{\text{labeled}} = \{(x^{(i)}, y^{(i)})\}_{i=1}^{N_0}$ to identify the polymer sample with high adsorption from a pool of unlabeled data, $\mathcal{D}_{\text{unlabeled}} = \{(x^{(i)})\}_{i=1}^{N_{\text{pool}}}$ with N_{budget} number of simulations where $N_{\text{budget}} \ll N_{\text{pool}}$.

Using the labeled data $\mathcal{D}_{\text{labeled}}$, we first train a surrogate model $f_{\text{surrogate}} : \mathcal{X} \rightarrow \mathcal{P}(\mathcal{Y})$ that predicts a distribution over the simulated CO_2 adsorption for the polymer sample $x \in \mathcal{X}$. We next obtain the predictive distribution for the samples in $\mathcal{D}_{\text{unlabeled}}$ using the trained surrogate model, and compute the utility of each unlabeled sample using an acquisition function. We perform the simulation for the unlabeled sample with the highest utility, and update our labeled data with this new sample and its observation, and remove the sample from the unlabeled data. This BO iteration – training of a surrogate with the labeled dataset, selection of an unlabeled sample to simulate, followed by updating the labeled and unlabeled dataset – is repeated for N_{budget} times. Algorithm 1 describes this iteration in detail. We have discussed the details of surrogate models and the acquisition functions in **Appendices A.3** and **A.4** respectively.

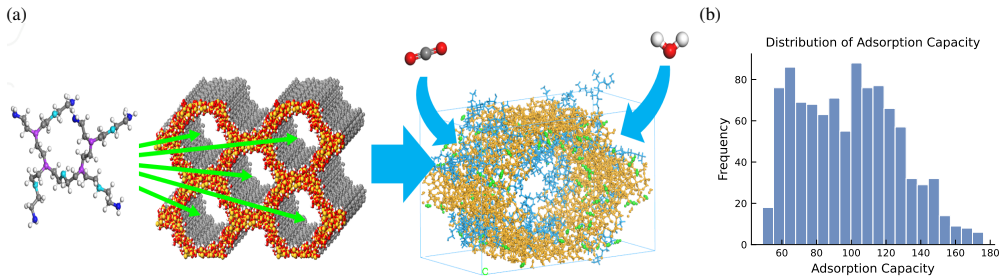


Figure 1: (a) A model system of polyimine and a silica-based support material (MCM-41) loaded with CO_2 for GCMC and MD simulation. (b) Histogram of simulated adsorption capacity of 1000 polymer samples.

3 Results and Discussion

3.1 Simulation Pipeline and Dataset

We refined the Lennard-Jones (LJ) parameters of CO_2 - H_2O -amines interactions (**Appendix A.1**), resulting in accurate approximation of experimental energies (Fig. 5). We performed GCMC simulations (Fig. 1a, **Appendix A.2**) to estimate the CO_2 adsorption for polymer conformations generated by MD relaxation. Fig. 1b shows the histogram of the adsorption capacity of polymer samples.

3.2 Discovery of polymers with high CO_2 adsorption capacity

We investigated the Bayesian optimization-assisted accelerated discovery pipeline (Algorithm 1) with our generated dataset of 1000 polymer samples. Specifically, we analyzed the impact of different molecular representations in the surrogate models in different hypothetical scenarios of the initial labeled dataset. We considered 5 pre-trained models (polymer-specific: PolyNC [15], polyBERT [14] and general chemical space: MolFormer [24], MolGen-large [25] and MiniMol [26]) and 3 choices

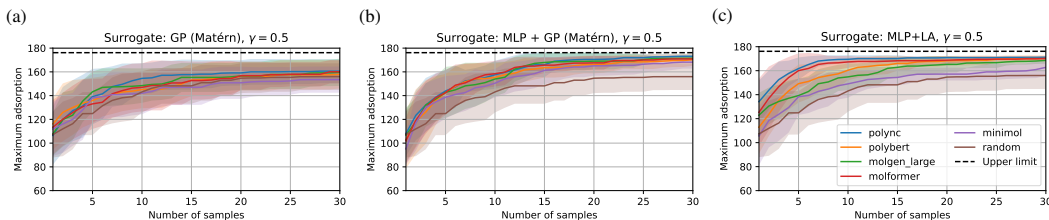


Figure 2: **Optimization traces for surrogate models: GP (a), GP-DKL (b), and MLP+LA (c) for $\gamma = 0.5$.** Each optimization traces show the progression of average (and ± 1 standard deviation over 20 trials) of the maximum adsorption capacity found by sequentially acquiring labels of unlabeled samples (in the x-axis). Along with 5 pre-trained models’ embeddings, we have the random acquisition strategy as baseline. *Upper limit* denotes the maximum value in our dataset, y_{max} .

of surrogate models: Gaussian process (GP with and without deep kernel learning) [27, 28] and Bayesian neural network (BNN) using Laplace approximation (LA) [29, 30]. For assessing the impact of initial $\mathcal{D}_{\text{labeled}}$, e.g., “*what if we start from samples with very low adsorption capacity?*”, we randomly selected the initial set of labeled samples such that $y^{(i)} < \gamma y_{\text{max}}$ for $\gamma \in \{0.5, 0.3\}$ where y_{max} denotes the maximum adsorption capacity value in our dataset of 1000 samples. Each BO-assisted discovery process (repeated for 20 trials, with Thompson sampling [31] as acquisition function) starts with $N_0 = 10$ initial labeled data, and tries to find the sample with the best adsorption capacity from the remaining 990 unlabeled samples using $N_{\text{budget}} = 30$ simulations.

3.2.1 Impact of initial labeled data of moderate quality ($\gamma = 0.5$)

In Figs. 2a to 2c, we have showed the optimization result with $\gamma = 0.5$ for the GP, GP-DKL and MLP+LA-based surrogates with embedding from five pre-trained models. While the embedding from the PolyNC model showed slightly better discovery in early iterations (fewer than 15 query samples), there was overall minimal gain by using GP-based acquisition over the random strategy. With GP-DKL, we observed a significant improvement in acquiring high-performing polymer samples quickly compared to the random baseline. Furthermore, this surrogate showed lower sensitivity to embeddings from different pre-trained models, in contrast to the choice of MLP+LA-based surrogate (Fig. 2c). Specifically for the latter case, embeddings from PolyNC and MolFormer showed superior efficiency, i.e., acquiring samples with maximum adsorption capacity exceeding 160 (on average) within the first 5 queries of unlabeled polymer samples. However, the performance with embedding from MiniMol was marginally better than the random strategy. Since we have used same set of hyperparameters in training the surrogate (MLP+LA), such discrepancy may be attributed to the sensitivity of BNN-based surrogate model to its design choices [32].

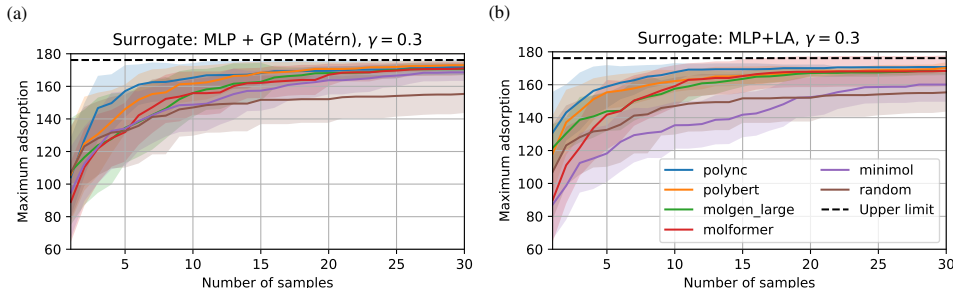


Figure 3: **Optimization traces for surrogate models: GP-DKL (a) and MLP+LA (b) for $\gamma = 0.3$.** The other settings of the experiments are same as in Fig. 2.

3.2.2 Impact of initial labeled data of poor quality ($\gamma = 0.3$)

With $\gamma = 0.3$, we effectively constrained the initial labeled dataset to contain samples with adsorption capacity lower than 53. In this scenario, both GP-DKL (Fig. 3a) and MLP+LA (Fig. 3b) based surrogates showed advantage of embeddings from polymer-specific pretrained models: PolyNC and polyBERT over other general chemical pre-trained models in accelerated discovery of high-quality samples. However, the differences in performance decreased as more labels were collected, except for the case with MiniMol in the MLP+LA-based surrogate, which showed worse performance than random acquisition in the first 20 queries. Nonetheless, this empirical findings highlight the importance of representation learning of polymer language models, specially in extremely unfavorable initialization. Furthermore, comparison with $\gamma = 0.5$ case indicates that the discovery rate became more sensitive to the choices of pre-trained models in the GP-DKL-based surrogate.

4 Conclusion

While MD simulation can effectively analyze the CO_2 adsorption mechanism, the associated computational cost constrains the use of MD simulation in the design process of amine-based polymer sorbents. In this work, we adopted a combination of fast MD with GCMC simulation as a rapid alternative to the lengthy MD simulation – providing improved throughput for estimating CO_2 adsorption capacity of the polymer. Our retrospective experiment with the adsorption data of 1000 linear polymer samples demonstrated that the BO strategy could further accelerate the discovery of high performing polymers

with limited number simulations. Importantly, it highlights the advantage of molecular representation from pre-trained polymer language models in quickly discovering polymers with high adsorption capacity, especially in cases where the initial labeled samples have low adsorption.

Since the adsorption estimates require validation by long-timescale MD simulations for high-confidence CO₂ uptakes, one can adopt a multi-fidelity Bayesian optimization approach [33] to discover high-quality polymers by leveraging both types of simulations. Exploration of the chemical space, e.g. branched and cross-linked architectures beyond linear polymers with de-novo design approaches, is another direction for future efforts. Specifically, this will also allow a more thorough investigation into the utility of different molecular representations in the polymer discovery process.

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A Appendix

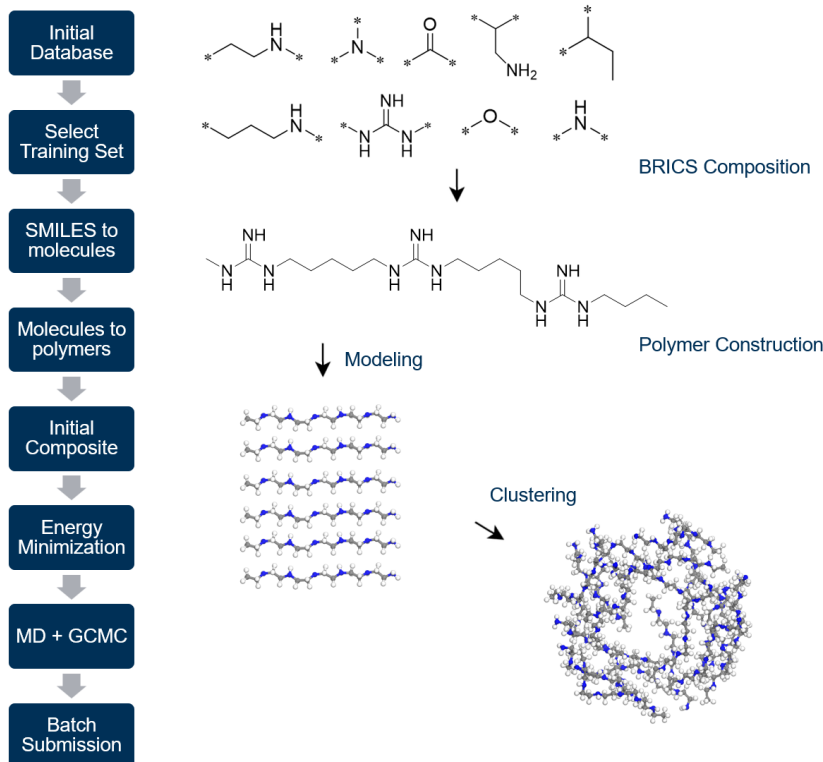


Figure 4: **Computational pipeline for polymer sorbent screening.** Molecular fragments are assembled into polymers via BRICS composition, deposited into porous matrices, and equilibrated. The resulting composites undergo molecular dynamics (MD) and grand canonical Monte Carlo (GCMC) simulations, enabling large-scale automated screening for CO₂ capture.

A.1 Force Fields for Polyamine-CO₂-H₂O Interactions

In this study, the DREIDING force field [34] and the F3C force field [35] were employed to model HB-PEI, HB-PPI, CO₂, and water. The DREIDING force field has been extensively applied in prior simulation studies across a wide range of materials, with results showing strong consistency with experimental data [36]. The functional form of the DREIDING potential is expressed as

$$E_{\text{total}} = E_{\text{vdW}} + E_{\text{Q}} + E_{\text{bond}} + E_{\text{angle}} + E_{\text{torsion}} + E_{\text{inversion}}, \quad (4)$$

where E_{total} , E_{vdW} , E_{Q} , E_{bond} , E_{angle} , E_{torsion} , and $E_{\text{inversion}}$ correspond to the total, van der Waals, electrostatic, bond stretching, angle bending, torsional, and inversion energies, respectively. Electrostatic contributions, E_{Q} , were determined from Mulliken population analysis.

To accurately capture the specific interactions between amine-CO₂, amine-H₂O, and CO₂-H₂O pairs, interaction energy profiles as a function of distance were first obtained using DFT at the B3LYP-D3/6-31G** level of theory (Fig. 5). From these calculations, Lennard-Jones (LJ) potential parameters (D

Algorithm 1 Bayesian Optimization for Accelerated Discovery

Require: Simulator for estimating CO₂ adsorption capacity $f_{\text{sim}}(x)$, initial dataset $\mathcal{D}_{\text{labeled}}^0 = \{(x^{(i)}, y^{(i)})\}_{i=1}^{N_0}$, initial pool $\mathcal{D}_{\text{unlabeled}}^0 = \mathcal{D}_{\text{unlabeled}} = \{(x^{(i)})\}_{i=1}^{N_{\text{pool}}}$, acquisition function $\alpha(x)$, computational budget N_{budget}

1: **for** $k = 1$ to N_{budget} **do**

2: Train a surrogate model $f_{\text{surrogate}}^k$ with labeled dataset, $\mathcal{D}_{\text{labeled}}^{k-1}$

3: Select sample to simulate next:

$$x^{(k)} = \arg \max_{x \in \mathcal{D}_{\text{unlabeled}}^{k-1}} \alpha(x \mid f_{\text{surrogate}}^k) \quad (1)$$

4: Simulate for adsorption capacity: $y^{(k)} = f_{\text{sim}}(x^{(k)})$

5: Update datasets:

$$\mathcal{D}_{\text{labeled}}^k = \mathcal{D}_{\text{labeled}}^{k-1} \cup \{(x^{(k)}, y^{(k)})\} \quad (2)$$

$$\mathcal{D}_{\text{unlabeled}}^k = \mathcal{D}_{\text{unlabeled}}^{k-1} \setminus \{(x^{(k)})\} \quad (3)$$

6: **end for**

7: **Return:** $x^* = \arg \max_{(x^{(i)}, y^{(i)}) \in \mathcal{D}_{\text{labeled}}^{N_{\text{budget}}}} y^{(i)}$

and r_0) in Eq. (5) were optimized to describe the off-diagonal van der Waals interactions:

$$E_{\text{off-diagonal}}(r) = D \left[\left(\frac{r_0}{r} \right)^{12} - 2 \left(\frac{r_0}{r} \right)^6 \right], \quad (5)$$

where D is the potential well depth and r_0 is the equilibrium separation distance.

The binding energy between species A and B was calculated as

$$E_{\text{binding}} = E_{(A+B)} - E_A - E_B, \quad (6)$$

where $E_{(A+B)}$ denotes the total energy of the optimized molecular pair, and E_A and E_B are the corresponding isolated species. This formulation enables direct comparison of DFT-derived interaction energies with those predicted by conventional mixing rules. As illustrated in Fig. 5, the interaction curves based on the optimized LJ parameters show excellent agreement with DFT results, in contrast to the less accurate predictions of the geometric-mean mixing rule. Notably, the mean square error (MSE) was reduced by approximately 98% with the newly optimized parameters compared to those obtained from the mixing rule, demonstrating the robustness of this refinement. Consequently, the optimized LJ parameters were adopted for all subsequent MD simulations in this study.

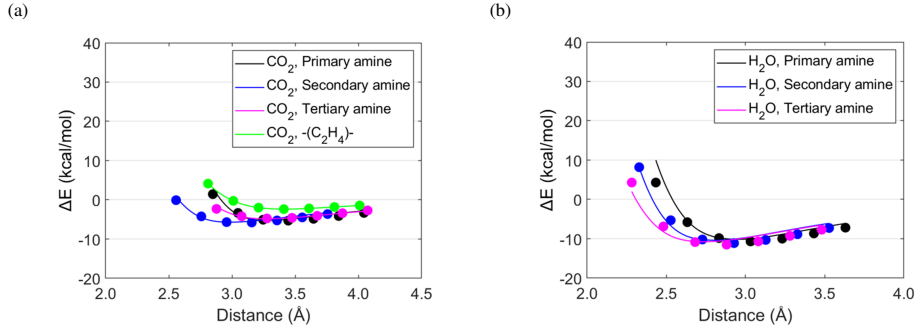


Figure 5: DFT-calculated interaction energy curves for amine–CO₂ and amine–H₂O pairs. (a) Binding energy profiles of CO₂ with primary, secondary, and tertiary amines, as well as with the –(C₂H₄)– linker group. (b) Binding energy profiles of H₂O with primary, secondary, and tertiary amines. Data points represent DFT calculations (B3LYP-D3/6-31G**), while lines correspond to Lennard-Jones (LJ) potential fits.

It is noted that i) among the binding energies of CO₂ with amines (-5.31 kcal/mol, -5.78 kcal/mol, and -4.75 kcal/mol, for primary, secondary, and tertiary amines, respectively), the CO₂-secondary amine pair has the strongest binding energy while the CO₂-tertiary amine pair has the weakest binding energy; ii) the binding energies of the CO₂-amine pairs are weaker than those of the H₂O-amine pairs (-10.67 kcal/mol, -11.10 kcal/mol, and -11.50 kcal/mol for primary, secondary, and tertiary amines, respectively).

A key outcome of the DFT-based parameterization is the capability to reproduce the observations from experimental and computational studies that amine-H₂O interactions are stronger than amine-CO₂ interactions, validating the suitability of the newly developed force field for investigating CO₂ capture in both HB-PEI and HB-PPI.

A.2 CO₂ Adsorption Estimation via Improved Throughput Simulation

For each polymer candidate in our dataset, we evaluated its CO₂ adsorption properties using a two-stage simulation workflow that combined fast molecular dynamics (MD) relaxation and grand canonical Monte Carlo (GCMC) sampling. The overall objective was to obtain accurate yet computationally efficient predictions of CO₂ capacity under specified capture conditions.

Fast MD simulations were first used to relax polymer configurations and approximate their packing density prior to adsorption calculations. Initial geometries were energy-minimized and equilibrated in the NVT ensemble at T = 298 K for 500 ps, followed by NPT ensemble simulations at P = 1 bar for 500 ps to achieve realistic bulk densities. This approach ensured that chain conformations, void spaces, and local environments were well-represented before introducing sorbate molecules. The relaxed polymer configurations served as input for subsequent GCMC adsorption simulations.

GCMC simulations were carried out using the LAMMPS / RASPA framework to directly estimate the equilibrium uptake of CO₂ at low partial pressures relevant to DAC. All simulations were performed at T = 298 K, with a CO₂ partial pressure of 0.4 mbar to mimic atmospheric capture conditions. The DREIDING + F3C force field parameters described in **Appendix A.1** were used for polymer-CO₂-H₂O interactions. Each GCMC run consisted of 1 million trial moves, with an insertion-to-deletion ratio of 1:1 and displacement/rotation trials included to enhance sampling efficiency. The calculated adsorption capacity was expressed in mmol g⁻¹, averaged over the production phase of the simulation after equilibration. These results formed the quantitative performance labels for downstream machine learning and Bayesian optimization workflows.

A.3 Molecular Representation of Polymer and Surrogate Model

Molecular Embeddings: For building the surrogate model to predict the adsorption capacity of a polymer sample x , we have used the representation $\mathbf{z}$ encoded by the pre-trained models for molecule space as a numerical representation of sample x . In our work, we considered both polymer-specific and general molecular pre-trained models for encoding the polymer samples. The two polymer-specific pretrained models: PolyNC [15] and polyBERT [14], encode the PSMILES strings of polymer x into the embeddings of their corresponding chemical tokens. We obtained the representation $\mathbf{z}$ by taking the average over these chemical token embeddings, excluding the special tokens. For representation from the general molecular space, we computed the embedding $\mathbf{z}$ from pre-trained MolFormer [24], MolGen-large [25], and MiniMol [26]. For these models, the “*” symbols in PSMILES (indicating the connection points in monomer) were removed, and the resulting monomer was encoded to an embedding $\mathbf{z}$. Note that MolFormer and MolGen-large are chemical language models for SMILES and SELFIES representation respectively, and the embedding $\mathbf{z}$ is the token-wise average embedding of the monomer. For MiniMol, which is a pre-trained graph neural network (GNN), $\mathbf{z}$ is the max-pool aggregation of the node embeddings of the molecular graph of the monomer. Fig. 6 shows the UMAP [37] visualization of the 1000 polymer samples – with simulated CO₂ adsorption capacity – based on the embedding $\mathbf{z}$ from these pretrained models.

Surrogate Models: In our work, we have used Gaussian Process (GP) [27], GP with deep kernel learning (GP-DKL) [28], and Bayesian neural network with Laplace approximation (LA) [29, 30] as surrogate models mapping embedding $\mathbf{z}$ to the predictive distribution of the adsorption capacity of polymer samples. For GP, the prediction for sample x is $f(\mathbf{z}) \sim \mathcal{GP}(m, k)$ where $m : \mathcal{Z} \rightarrow \mathbb{R}$ is the mean function, and $k : \mathcal{Z} \times \mathcal{Z} \rightarrow \mathbb{R}$ is the kernel function (e.g., Matérn-5/2 kernel used in our

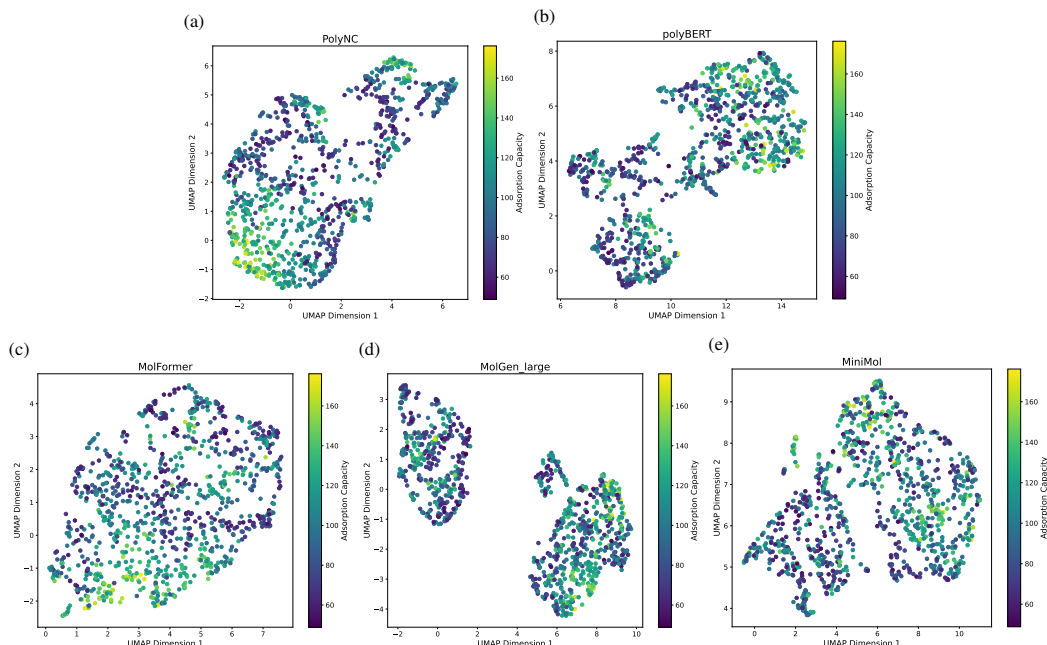


Figure 6: UMAP visualization of 1000 polymer samples based on their representation from polymer-specific pre-trained models: PolyNC, polyBERT and general chemical pre-trained models: MolFormer, MolGen_large, MiniMol

work) defined on the embedding $\mathbf{z}$ of the sample. In GP-DKL, the kernel $k(\mathbf{z}, \mathbf{z}')$ is replaced with $k(\phi(\mathbf{z}), \phi(\mathbf{z}'))$ where ϕ represents a non-linear mapping with learnable parameters which is jointly trained with the base GP. We have used a multilayer perceptron (MLP) network with one hidden layer and one output layer – both with 50 neurons and ReLU activation as the non-linear function ϕ in our experiment with GP-DKL. For LA, we have used the linearized Laplace approximation from [30], where the output of a neural network $f_{\theta}(\mathbf{z})$ is linearized near a known model weights in the parameter space. Specifically, we first trained a deterministic network $f_{\theta^*} : \mathcal{Z} \rightarrow \mathbb{R}$ (θ^* being trained parameters); followed by optimization of prior precision (over neural network’s weights) and observation noise via marginal likelihood maximization. The predictive distribution for a sample x is approximated by $\mathcal{N}(f_{\theta^*}(\mathbf{z}), \mathbf{J}_{\theta^*}(\mathbf{z})\Sigma\mathbf{J}_{\theta^*}(\mathbf{z})^T)$, where the $\mathbf{J}_{\theta^*}(\mathbf{z}) = \nabla_{\theta} f_{\theta}(\mathbf{z})|_{\theta=\theta^*}$ is the Jacobian evaluated at model weights θ^* , and $\Sigma = (-\nabla_{\theta}^2 \log p(\theta|\mathcal{D})|_{\theta=\theta^*})^{-1}$ is the inverse of the Hessian. Note, $\mathcal{D}$ in this expression of Σ denotes the training data used for training the model f_{θ^*} , which is an MLP network with two hidden layers (each having 50 neurons and ReLU activation) in our experiments.

A.4 Acquisition Function

The acquisition function $\alpha(x|f_{\text{surrogate}})$ defines the utility of performing simulation for measuring CO_2 adsorption capacity of sample x based on the surrogate model $f_{\text{surrogate}}$ learned with the labeled data. The choice of the acquisition strategy dictates the trade-off in terms of the “exploration vs exploitation” goal of the Bayesian optimization. For example, the greedy acquisition strategy prioritizes sample with the highest predictive mean, i.e., exploiting the knowledge of the trained surrogate, which may be overconfident given the limited number of labeled data samples. In contrast, the random acquisition is purely exploration-based without leveraging the current observation data. Eqs. (7) to (10) shows the utility of sample x under greedy, upper confidence bound (UCB) [38], Thompson sampling [31](used

in our work), and expected improvement (EI) [39] acquisition functions, respectively.

$$\alpha_{\text{greedy}}(x|f_{\text{surrogate}}) = \mu_x \quad (7)$$

$$\alpha_{\text{UCB}}(x|f_{\text{surrogate}}) = \mu_x + \beta\sigma_x \quad \text{with } \beta > 0 \quad (8)$$

$$\alpha_{\text{Thompson}}(x|f_{\text{surrogate}}) = \tilde{y} \quad \text{where } \tilde{y} \sim \mathcal{N}(\mu_x, \sigma_x^2) \quad (9)$$

$$\alpha_{\text{EI}}(x|f_{\text{surrogate}}) = \mathbb{E} [\max(\tilde{y} - y^*, 0)] \quad \text{where } \tilde{y} \sim \mathcal{N}(\mu_x, \sigma_x^2) \quad (10)$$

Here μ_x and σ_x^2 are the predictive mean and variance from the surrogate model for polymer x . y^* denotes the best objective values within the current set of samples with measured objectives, i.e., the training samples for the surrogate.