

A Survey on the Application of LLM-based Multi-Agent System

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Abstract

Multi-agent systems (MAS) have become a research hotspot since the rise of large language models (LLMs). However, current review papers lack a thorough examination of the diverse applications of LLM-based multi-agent systems (LLM-MAS). This paper presents a comprehensive survey of applications of LLM-MAS. We provide an overview of the various applications of LLM-MAS in (i) solving complex tasks, (ii) simulating specific scenarios, and (iii) evaluating generative agents. Also, we highlight several challenges and propose future directions for research in this field.

1 Introduction

Multi-agent systems (MAS) have seen significant expansion owing to their adaptability and ability to address complex, distributed challenges (Balaji and Srinivasan, 2010). Compared to single-agent settings, MAS provide a more accurate representation of the real world, as many real-world applications naturally involve multiple decision-makers interacting simultaneously (Gronauer and Diepold, 2022). Previous research on MAS has predominantly focused on reinforcement learning (RL)-based agents, as illustrated by their application to classic tasks ranging from Atari video games (Mnih, 2013) to robotic socket-insertion challenges (Brockman, 2016), trained in specific environments. However, due to limitations in their parameterization and a lack of general knowledge, these agents struggle to take informed agent actions in unconstrained, open-domain scenarios requiring general knowledge.

Compared to RL-based MAS, LLM-based multi-agent systems (LLM-MAS) demonstrate the ability to handle a wide range of tasks in open-domain environments (Shinn et al., 2023). By leveraging the generalization capabilities and linguistic modality of LLMs, LLM-MAS enable novel applications that are not achievable with RL-based MAS, spanning domains from healthcare (Tang et al., 2024a)

to embodied AI (Patel et al., 2024). In recent years, numerous studies have explored the diverse applications of LLM-MAS. However, a comprehensive review of LLM-MAS applications is still lacking.

In this paper, we provide a comprehensive perspective on the application of LLM-based multi-agent systems (LLM-MAS). Figure 1 presents an overview of applications of LLM-MAS. There are three categories of applications of LLM-MAS: (i) Solving complex tasks. LLM-MAS perform a wide range of tasks, including simple tasks that do not require long trajectory decisions, complex tasks that involve long trajectory decisions, and even some general-purpose tasks. (ii) Simulating for specific scenarios. LLM-MAS simulate diverse scenarios, facilitating the exploration and validation of relevant theories. (iii) Evaluating and Training on generative agents. On the one hand, compared with traditional evaluation on agents, LLM-MAS have the capability of dynamic assessment, which is more flexible and harder for data leakage (Chen et al., 2024c). On the other hand, agents can be trained in LLM-MAS, concluding various training methods.

Compared to previous surveys (Guo et al., 2024a; Li et al., 2024d; Han et al., 2024; Gronauer and Diepold, 2022), this survey offers the following key contributions: (i) A clear taxonomy for LLM-MAS applications. We present a framework to organize and categorize different types of LLM-MAS applications. (ii) A definition of the environment in LLM-MAS applications. We provide a specific definition of the LLM-MAS environment, designed to fit the needs of LLM-MAS applications. (iii) A summary of available resources for LLM-MAS research. We compile a list of open-source frameworks and datasets to help researchers study LLM-MAS applications. (iv) Challenges and future directions for LLM-MAS applications. We discuss the current challenges in the field and suggest potential areas for future research.

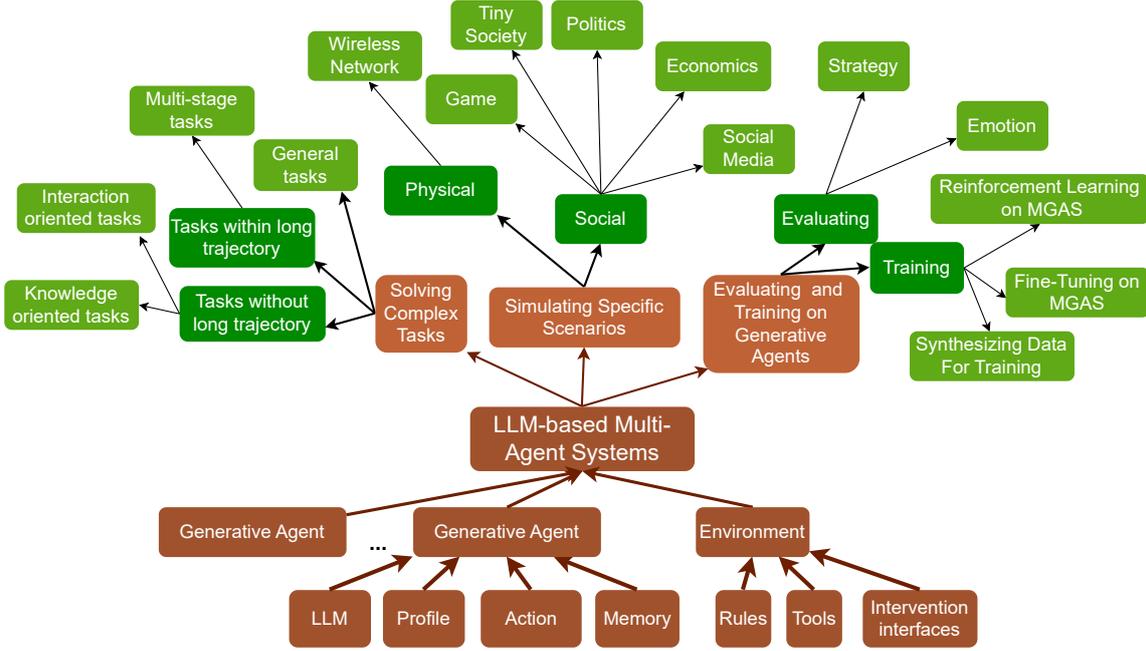


Figure 1: Overview of the application and construction of LLM-MAS.

2 Core Components of LLM-MAS

LLM-MAS refer to systems that include a collection of generative agents capable of interacting and collaborating within a shared environmental setting (Wang et al., 2024c). We will analyze generative agents and the environment in the following.

2.1 Generative Agents

Generative agents refer to the components of LLM-MAS that have role definitions, can perceive the environment, make decisions, and perform complex actions to interact with the environment (Wang et al., 2024a).

Compared to traditional agents, generative agents can be able to perform complex behaviors, such as generating complete personalized blog posts based on historical information (Park et al., 2022). Therefore, in addition to using LLMs as the core, generative agents also require the following characteristics: (i) *Profiling* refers to agents typically assuming distinct roles, each accompanied by detailed descriptions that encompass their characteristics, capabilities, and constraints (Guo et al., 2024a). (ii) *Memory* stores historical trajectories and retrieves relevant memories for subsequent agent actions, enabling the ability to take long-term actions while solving the problem of limited LLM context windows. There usually are three memory layers: long-term, short-term, and

sensory memory (Park et al., 2023). (iii) *Planning* is to formulate general behavior for a longer period in the future (Yao et al., 2023). (iv) *Action* executes the interaction between the generative agent and the environment (Wang et al., 2024a). Generative agents are required to choose one of several candidate behaviors to execute, such as voting for whom (Xu et al., 2024a), or generate behaviors without mandatory constraints, such as generating a paragraph of text (Li et al., 2023b).

Generative agents can communicate with each other to achieve cooperation within the system. The communication of generative agents can be roughly divided into two purposes. (i) The first purpose is to achieve collaboration, share the information obtained by themselves with other intelligent agents, and to some extent, aggregate multiple intelligent agents into a complete system, achieving performance beyond independent intelligent agents (Yuan et al., 2023); (ii) The second purpose is to achieve consensus, allowing for greater similarity in behavior or strategy among some agents, thereby enabling faster convergence to Nash equilibrium (Oroojlooy and Hajinezhad, 2023).

The type of communication content can be roughly divided into two types: natural language and vector. Natural language forms of communication have high interpretability. Still, they are difficult to optimize, making them more suitable for

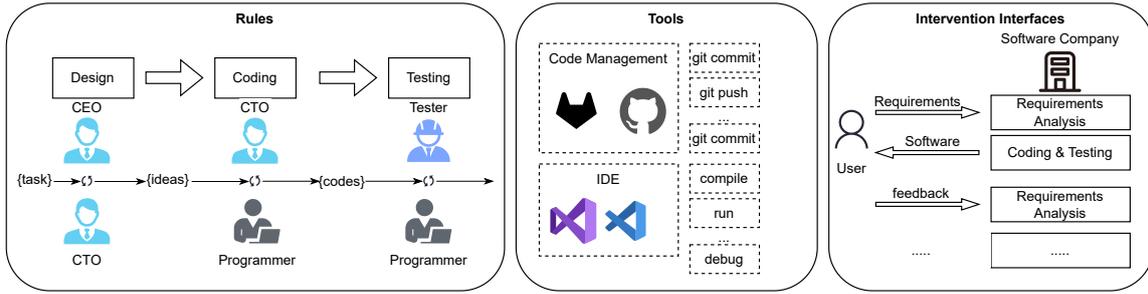


Figure 2: Core components of LLM-MAS environment. Using a software company as an example, agents function within the framework of **rules**, which guide and govern their operations. Meanwhile, **tools** provide APIs for development, such as the “git push” command, which agents can access. Through the **intervention interfaces**, the environment can be modified according to user requirements, enabling continuous optimization of the software.

pursuing consensus, such as in coding (Dong et al., 2024) and job fair systems (Li et al., 2023b). Vector forms are more efficient in terms of communication and easier to optimize using policy gradients, making them commonly used for achieving cooperative objectives (Liu et al., 2024b).

2.2 Environment

Environmental settings include tools, rules, and intervention interfaces, which are illustrated in Figure 2. (i) *Rules* define the mode of communication between generative agents or the interaction with the environment, directly defining the behavioral structure of the entire system. Figure 2 shows the order of agents talking and acting under rules. (ii) *Tools* (optional) create an action space for each generative agent to take action. Figure 2 illustrates the common tools in software development scenario, including IDEs and Git. Their APIs, including git commands, compilation tools, runtime tools, and debugging tools such as “git push”, can be accessed by agents. (iii) *Intervention interfaces* (optional) provide an interface for external intervention systems, which can come from any external source, like human (Wang et al., 2024b), or a rule-based model (Chen et al., 2024c), even a generative agent (Chen et al., 2024e). Figure 2 illustrates an example of intervention interfaces in the software development: requirements analysis in agile development. Throughout each development cycle, users from external have the opportunity to communicate with the software company to define and refine their requirements. This ongoing collaboration allows the software company to adjust the development process based on user needs, ensuring timely intervention and alignment with expectations.

3 LLM-MAS for Solving Complex Tasks

In this section, we explore the application of LLM-MAS to solving complex tasks. We begin by categorizing LLM-MAS based on the complexity of the tasks they address. Next, we provide an overview of the relevant code, datasets, and benchmarks available for these applications. Finally, we discuss the evaluation metrics used to assess performance in solving complex tasks.

3.1 Categories of LLM-MAS based on task complexity

We classify LLM-MAS into three distinct categories based on the complexity of tasks they handle: (i) LLM-MAS designed for specific tasks that do not require long trajectory decisions, (ii) LLM-MAS tailored for specific tasks involving long trajectory decisions, and (iii) LLM-MAS that are not specialized for any specific tasks.

Specific tasks that do not require long trajectory decisions. Single tasks refer to tasks without requiring long trajectory decisions. This type of task is commonly seen in tasks requiring knowledge, where techniques from multi-agent systems are transferred to existing classic tasks, such as Visual Question Answering (VQA) (Jiang et al., 2024), tasks in science (Song et al., 2024), etc. Usually, this type of task has a short (less than 2048) context length. This type of task solving by a single agent requires a long prompt, which is difficult to reuse. It is LLM-MAS technology that optimizes this problem. Collective decision-making and reflection are commonly used in this type of task. Compared with a single agent method, such as self-consistency (Wang et al., 2023), LLM-MAS with collective decision-making can achieve improved performance with less prompting for the

same task (Du et al., 2024a). Reflective method is also a common technique, Bo et al. (2024) explore reflection in LLM-MAS, proposing a novel framework, that exhibits excellent generalization performance across different actor models. The performance of collective decision-making or reflection depends on the capabilities of individual agents. However, as the complexity of the task increases, within long trajectory decisions, LLM-MAS require a new mod.

Specific tasks that require long trajectory decisions. Complex tasks are defined as those that require decisions over long trajectories. They are typically encountered in multi-stage scenarios where the collaboration of multiple agents is essential for finding a solution (Chen et al., 2024f). Soft development is a representative scenario requiring multi-stage collaboration (Islam et al., 2024). As a representative of this domain, ChatDev (Qian et al., 2024a) leverages software engineer agents in distinct roles to collaboratively develop software. Based on this, additional forms of cooperation are explored (Du et al., 2024b). Further, the scaling law is explored in this scenario (Qian et al., 2024b), but no significant pattern was observed. Another typical scenario is long-context tasks. LONGAGENT (Zhao et al., 2024a) and Chain of Agents (Zhang et al., 2024c) apply MAS technology to split the long context, enabling smaller models like LLaMA-2 7B to possess strong contextual capabilities, even better than GPT-4. Similarly, embodied reasoning and planning are also a representative scenario requiring long trajectories of collaboration (Dasgupta et al., 2023). Agents solve their respective subtasks and merge the results, which introduces higher communication costs and challenges related to information aggregation.

General tasks. In this part, LLM-MAS are not limited to specific tasks but are instead a method applicable to a wide range of general tasks. MetaGPT (Hong et al., 2023) assigns different roles to generative agents to form a collaborative entity for complex tasks. Gao et al. (2024) propose AgentScope with message exchange as its core communication mechanism. Open AI proposes Swarm (OpenAI, 2024b), an experimental multi-agent orchestration framework that is ergonomic and lightweight. KAOS (Zhuo et al., 2024) addresses the challenges of resource coordination management by proposing a unified user experience across various foundational software platforms. In LLM-MAS, fully

connected communication poses significant challenges, including combinatorial explosion and privacy risks. To mitigate these issues, researchers have focused on enhancing communication efficiency. For instance, some studies explore methods to accelerate agent interactions through nonverbal communication techniques (Liu et al., 2024b), while others aim to streamline communication by reducing the length of generated messages (Chen et al., 2024g). These approaches collectively address the inherent limitations of fully connected communication in LLM-MAS. Among the works, DroidSpeak achieves up to a 2.78× speedup in prefill latency with negligible loss in accuracy.

3.2 Resources for solving complex tasks

We analyze common LLM-MAS for solving complex tasks in Table 1, including code, datasets, and benchmarks. Among the datasets, QA-style datasets are the most commonly used, a trend that reflects the legacy of traditional NLP task-specific datasets and benchmarks. ToolBench (Guo et al., 2024b), SRDD, ToolAlpaca (Tang et al., 2023), etc. are specifically designed for agent tools. Overcooked-AI (Carroll et al., 2020) is a benchmark for LLM-MAS in the past, which illustrates the potential to transform the game environment originally used for RL based MAS into LLM-MAS.

3.3 Evaluation metric of solving complex task

Performance on specific tasks. Shown as Table 1, the performance of LLM-MAS can be evaluated by specific tasks, which is intuitive and convenient. For example, in an APP system (Zhang et al., 2023b), the average number of steps and tools used by an agent to complete a specific task is considered as an indicator; in BOLAA (Liu et al., 2023c), the recall and QA accuracy of intelligent physical examination retrieval are also considered as evaluation indicators;

Communication cost analysis. The concern lies in the operational cost of the system. Given that a substantial proportion of contemporary systems incorporate LLM-MAS as a pivotal module, the additional expenditure incurred during system operation has emerged as a pivotal area of interest. As an illustrative example, In the evaluation of DroidSpeak (Liu et al., 2024b), the response time has been used as a metric to evaluate the acceleration of the method.

Table 1: Codes and Benchmarks in LLM-MAS for solving task studies. “No Code” or “No Benchmark or Dataset” means the code or benchmark is unavailable.

Field	Subdomain	Paper	Code	Benchmark and Dataset
Tasks without long trajectory decision	Knowledge oriented tasks	(Zhao et al., 2024c)	Code Link	MCQA
		(Wang et al., 2024c)	Code Link	FOLIO-wiki
		(Chen et al., 2024e)	Code Link	StrategyQA, CSQA, GSM8K, AQuA, MATH, Date Understanding, ANLI
		(Chen et al., 2024a)	Code Link	TriviaQA
		(Wang et al., 2024d)	Code Link	TriviaQA
		(Liang et al., 2024)	Code Link	MT-Bench
		(Lei et al., 2024)	Code Link	MATH
		(Zhang et al., 2024a)	Code Link	MMLU, MATH, Chess Move Validity
		(Cheng et al., 2024)	Code Link	ESConv dataset, P4G dataset
		(Tang et al., 2024b)	Code Link	Trans-Review, AutoTransform, T5-Review
	Interaction oriented tasks	(Zhang et al., 2024b)	Code Link	RoCoBench, Overcooked-AI
		(Zhang et al., 2023a)	Code Link	Overcooked-AI
Tasks within long trajectory decision	Multi-stage tasks	(Qian et al., 2024a)	Code Link	SRDD
		(Du et al., 2024b)	Code Link	SRDD
		(Yue et al., 2024)	Code Link	SMART (self)
		(Liu et al., 2023c)	Code Link	WebShop
		(Lin et al., 2024)	Code Link	FG-C, CG-O
		(Islam et al., 2024)	Code Link	HumanEval, EvalPlus, MBPP, APPS, xCodeEval, CodeContest
General tasks		(Shen et al., 2024)	Code Link	ToolBench, ToolAlpaca
		(Li et al., 2023a)	Code Link	CAMEL AI Society, CAMEL Code, CAMEL Math, CAMEL Science

4 LLM-MAS for Simulating Specific Scenarios

This section will illustrate the application for LLM-MAS in simulation. LLM-MAS are applied by researchers to simulate certain scenarios to study their impact on specific subjects such as social sciences. On the one hand, compared with rule-based methods (Chuang and Rogers, 2023), generative agents with natural language communication can be more intuitive for humans. On the other hand, environment determines the properties of the simulation, which is the core of the entire simulation.

4.1 Categories of simulation scenarios

The typical scenarios for LLM-MAS simulations are described as follows. We will introduce the following work according to the subject.

Social domain. Social large-scale experiments in the real world have high costs, and the sheer scale of social participation can sometimes escalate into violence and destruction, posing potential ramifications (Mou et al., 2024). Therefore, it is necessary to simulate in the virtual environment; simulation can solve the problem of excessive overhead in the real environment and can simulate the process in the real world for a long time at a faster speed (Li et al., 2024a). At the same time, the whole process can be easily repeated, which is conducive to further research. Researchers have done

a lot of work to simulate social media scenarios. Based on the social media simulation archetype (Park et al., 2022), Park et al. (2023) propose Stanford Town, which leads to a one-day simulation of the life of 25 agents with different occupations in a small American town. At the same time, there was work on emotional propagation influence (Gao et al., 2023b), information cocoon room based on recommendation scenario research (Wang et al., 2024b), and study of social movements (Mou et al., 2024). Researchers propose Urban Generative Intelligence (UGI) (Xu et al., 2023a) to address specific urban issues and simulate complex urban systems, providing a multidisciplinary approach to understanding and managing urban complexity. Li et al. (2024a) study doctor agent evolution method by hospital simulation. Because doctor agent training is both inexpensive and highly effective, this work can quickly scale up the agent to handle tens of thousands of cases in just a few days, a task that would take a human doctor years to complete. Pan et al. (2024) propose a huge scale of agent simulation, increasing the number of agents to 10^6 . In social games, like Werewolf (Xu et al., 2024a), Avalon (Lan et al., 2024), and Minecraft (Gong et al., 2024) for LLM-MAS simulation are attempted.

Physical domain. For the physical domain, the applications for generative agent simulation in-

Table 2: Codes and Benchmarks in LLM-MAS for simulation studies. “No Code” or “No Benchmark or Dataset” means the code or benchmark is unavailable.

Domain	Subdomain	Paper	Code	Benchmark and Dataset
Social	Tiny Society	(Huang et al., 2024b)	No Code	AdaSociety
		(Chen et al., 2024b)	Code Link	AgentCourt
		(Park et al., 2023)	Code Link	No Benchmark or Dataset
		(Piatti et al., 2024)	Code Link	No Benchmark
	Economics	(Chuang et al., 2024)	Code Link	No Benchmark or Dataset
		(Li et al., 2024b)	Code Link	No Benchmark or Dataset
	Social Media	(Wang et al., 2024b)	Code Link	Movielens-1M
		(Gao et al., 2023b)	No Code	Blog Authorship Corpus
(Mou et al., 2024)		Code Link	SoMoSiMu-Bench(self)	
Game	(Du and Zhang, 2024)	Code Link	WWQA	
	(Pan et al., 2024)	Code Link	No Benchmark or Dataset	
Physical	Wireless	(Zou et al., 2023)	No Code	No Benchmark or Dataset

clude mobility behaviors, transportation (Gao et al., 2023a), wireless networks, etc. However, there is limited research in the area of generative agents. Zou et al. (2023) explore the application of multiple agents in the wireless field, proposing a framework where multiple on-device agents can interact with the environment to simulate real world scenarios. This is an area of critical importance for the future of embodied intelligence.

4.2 Resources for LLM-MAS simulation

We analyze common and open-source LLM-MAS for simulation with their datasets in Table 2, including code and benchmarks.

To prove the effectiveness of the simulation, that is, to fit the reality, researchers usually evaluate the simulation system by simulating real data. Therefore, a realistic dataset with dense users and records is very important for evaluation simulation (Mou et al., 2024). An ideal dataset will be dense: that is, data with a smaller number of users on the same scale can better evaluate the simulation capability of the LLM-MAS. Du and Zhang (2024) propose WWQA based on werewolf scenarios to evaluate the agent’s capability in a werewolf scenario.

4.3 Evaluation Metric of LLM-MAS simulation

We will summarize the metrics for the overall evaluation of LLM-MAS, rather than the capabilities of individual agents.

Consistency. LLM-MAS necessitate a robust con-

gruence with the real world to ensure the derivation of meaningful and insightful experimental outcomes. In the context of simulation systems, exemplified by UGI (Xu et al., 2023a), the primary objective lies in faithfully replicating specific real-world scenarios. When employed for training agents like SMART (Yue et al., 2024), only those agents that have undergone rigorous training within a virtual environment that closely mirrors the real environment can be deemed suitable for deployment in real-world settings. Similarly, when utilized for evaluation purposes, such as in AgentSims (Lin et al., 2023), the attainment of authentic and reliable evaluation results is contingent upon the virtual environment maintaining a high degree of consistency with its real-world counterpart. Finally, in the system for collecting data such as BOLAA (Liu et al., 2023c), consistency also ensures the validity of the data. Therefore, an important performance measure of LLM-MAS is its consistency with the real situation.

Information dissemination. Compare the differences between information dissemination behavior in the system and reality using time series analysis methods. Information dissemination can to some extent reflect the nature of media; therefore, a realistic multi-agent system should have a similar information dissemination trend to the real world. Abdelzaher et al. (2020) compare the changes in the number of events occurring each day in an online social media simulation environment; S3 (Gao et al., 2023b) compare the number of users who

are aware of a certain event every day, as well as the changes in emotional density and support rate for that event every day; a similar approach is also used in Stanford Town (Park et al., 2023).

5 LLM-MAS for Evaluating and Training Generative Agents

With generative agents prevailing in the community (Wang et al., 2024a), how to evaluate the ability of generative agents is an open question. Existing evaluation methods suffer from the following shortcomings: (i) constrained evaluation abilities, (ii) vulnerable benchmarks, and (iii) un-objective metrics. The complexity and diversity of LLM-MAS have indicated that LLM-MAS can evaluate generative agent. However, how to design specific evaluation indicators and evaluation methods has puzzled researchers. Similarly, LLM-MAS can also be used in training generative agents. We summarize three aspects of training: (i) Supervised Fine-Tuning (SFT) (ii) reinforcement learning (RL) (iii) Synthesizing data for training.

5.1 Methods of Evaluation and Training on Generative Agents

LLM-MAS can provide rewards to agents, and these rewards can be used to evaluate or train generative agents, which will be discussed below.

Evaluation of generative agents. Researchers study generative agents by putting them into LLM-MAS. In LLM-MAS, researchers can further study the LLM’s strategic capabilities in different scenes, such as long strategic ability (Chen et al., 2024c), corporation strategy (Xu et al., 2023b), and competitiveness strategy (Zhao et al., 2024b). In the emotional field, MuMA-ToM (Shi et al., 2024) is used to evaluate the ability of agents to understand and reason about human interactions in a real home environment through video and text descriptions.

Training on generative agents. Li et al. (2024c) enhance the data to Supervised Fine-Tuning (SFT) generative agents with LLM-MAS. Xu et al. (2024b) have created generative agents to overcome the intrinsic bias from LLMs by proposing a novel framework that powers generative agents with multi-agent reinforcement learning. For LLM-MAS, Yue et al. (2024) split complex trajectories in knowledge-intensive tasks into subtasks, proposing a co-training paradigm of the multi-agent framework, Long- and Short-Trajectory

Learning, which ensures synergy while keeping the fine-grained performance of each agent. RLHF has been criticized for its high cost. Liu et al. (2023a) propose an alignment scheme based on a multi-agent system, effectively addressing instability and reward gaming concerns associated with reward-based RL optimization. Either way, LLM-MAS are essentially viewed as an environment in RL with different ways of getting rewards from the environment.

5.2 Resources of LLM-MAS for evaluations

Table 3 shows the work with code, dataset, and benchmark we analyze, serving as a reference for future researchers. Our findings indicate that the current body of research is predominantly centered on the evaluation of generative agents, which means training with LLM-MAS will be a great potential for further exploration.

6 Challenges and Future Directions

While previous work on LLM-MAS has obtained many remarkable successes, this field is still at its initial stage, and there are several significant challenges that need to be addressed in its development. In the following, we outline several key challenges along with potential future directions.

6.1 Challenges posed by generative agents

Generative agents are an integral part of LLM-MAS. However, the generative agents have some shortcomings due to the inherent characteristics of the base model LLMs, which will be carefully discussed below.

Challenges. (i) Generalized alignment for simulation (Liu et al., 2023a). When the agents are leveraged for real-world simulation, a perfect generative agent should be able to depict diverse traits (Wang et al., 2024a) honestly. However, due to the training method of the foundation model (OpenAI et al., 2024), generative agents usually cannot be aligned with mock objects. (ii) Hallucination. Generative agents have a certain probability of hallucination in their interaction with other agents (Du et al., 2024a). Various enhancement methods can alleviate this problem but cannot solve it (iii) Lack of sufficient long text capability. When processing complex information, generative agents forget the input information because of the lack of long-text ability (Zhao et al., 2024a).

Future directions. The improvement of the

Table 3: Codes and Benchmarks in LLM-MAS for evaluation studies. “No Code” or “No Benchmark or Dataset” means the code or benchmark is unavailable.

Domain	Subdomain	Paper	Code	Benchmark and Dataset
Evaluation of generative agents	Strategy	(Liu et al., 2023b)	Code Link	AGENTBENCH
		(Bandi and Harrasse, 2024)	No Code	MT-Bench
		(Chan et al., 2023)	Code Link	ChatEval
		(Chen et al., 2024d)	Code Link	LLMARENA
		(Xu et al., 2023b)	Code Link	MAGIC
		(Huang et al., 2024a)	Code Link	MAgentBench
	(Chen et al., 2024c)	Code Link	AUCARENA	
	Emotion	(Zhang et al., 2024d)	Code Link	PsySafe
(Shi et al., 2024)		Code Link	MuMA-ToM	
Training on generative agents	SFT on LLM-MAS	(Li et al., 2024c)	Code Link	MT-Bench, AlpacaEval
	MARL on LLM-MAS	(Xu et al., 2024b)	No Code	No Benchmark or Dataset
	Synthesized Ddata	(Liu et al., 2023a)	Code Link	HH, Moral Stories, MIC, ETHICS-Deontology, TruthfulQA

ability of a single agent or the ability of the base model has always been a hot topic. Researchers have focused on enhancing alignment, reducing hallucination, and improving the ability of long text. The proposal of the new generation of Open AI model o1 (OpenAI, 2024a) provides researchers with new ideas, that is, to use **more complex reasoning** to enhance the ability of the model.

6.2 Challenges posed by interactions

Challenges. Due to the complexity, autoregressive, and other characteristics of LLM-MAS, there are many problems in the practical application of the system. How to solve (i) communication efficiency (Liu et al., 2024b; Zhuang et al., 2024), (ii) imperfect communication (Zhang et al., 2023a; Liu et al., 2024a; Zhuang et al., 2024), and (iii) communication security (de Cerqueira et al., 2024) is a long-term goal of the researchers.

Future directions. Establishing a comprehensive and standardized benchmark to evaluate the communication latency of LLM-MAS is an urgent issue that needs to be addressed in the short term. Therefore, optimizing the communication structure of LLM-MAS presents an intriguing research problem for the near future.

6.3 Challenges of Evaluation for LLM-MAS

Lack of Objective metrics for group behavior. As shown in Section 4.3, due to the diversity, complexity, and unpredictability of multi-agent environments, it is difficult to obtain sufficiently detailed, specific, and direct system evaluation

indicators from current work at the system level. **Automated evaluation and benchmark.** Different LLM-MAS of the same kind cannot be compared because of the lack of a benchmark for LLM-MAS. Further, there is a lack of a common benchmark framework for both individual and total-based evaluation, that can be used to evaluate most LLM-MAS.

Future directions. Studying large-scale LLM-MAS will be a new research hotspot, from which researchers will evaluate and discover new scale effects. In the meantime, common test benchmarks and evaluation methods will also emerge in future research.

7 Conclusion

In this survey, we systematically summarize existing research in the application of LLM-based multi-agent systems (LLM-MAS) field. We present and review these studies from three application aspects: task-solving, simulation, and evaluation of the generative agents. We provide a detailed taxonomy to draw connections among the existing research, summarizing the major techniques and their development histories for each of these aspects. In addition to reviewing the previous work, we also propose several challenges in this field, which are expected to guide potential future directions.

588 Limitations

589 Due to page limitations, we provide only brief sum-
590 maries of each method without delving into exhaus-
591 tive technical details. Furthermore, our primary
592 collection includes studies from *ACL, NeurIPS,
593 ICLR, AACL, and arXiv, which means some im-
594 portant work from other venues might have been
595 inadvertently omitted. In the application section,
596 we have listed representative LLM-MAS resources
597 with open code in Tables 1, 2, and 3. We recognize
598 the timeliness of our work and are committed to
599 keeping pace with ongoing discussions in the re-
600 search community, updating our perspectives and
601 supplementing any overlooked contributions in fu-
602 ture revisions.

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