Graph Cut-Based Semi-Supervised Learning via p-Conductances

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Abstract

We study the problem of semi-supervised learning in the regime where data labels are scarce or possibly corrupted. We propose a graph-based approach called *p*-conductance learning that generalizes the *p*-Laplace and Poisson learning methods by using an affine relaxation of the label constraints. This leads to a family of probability measure mincut programs that balance sparse edge removal with accurate distribution separation and which are connected to well-known variational and probabilistic problems on graphs. Computationally, we develop a semismooth Newton-conjugate gradient algorithm and extend it to incorporate class-size estimates when converting the continuous solutions into label assignments. Empirical results on citation datasets demonstrate that our approach achieves state-of-the-art accuracy in low label-rate, corrupted-label, and partial-label regimes.

1 Introduction

Graph-based semi-supervised learning (SSL) leverages both labeled and unlabeled data to improve prediction when labeled examples are scarce. In the "low label-rate regime," affinity and adjacency among unlabeled points can significantly boost accuracy. Given a weighted graph G=(V,E,w) on n nodes and an initial set of $m \ll n$ binary node labels $y_i \in \{-1,1\}^m$, a seminal method is Laplace learning [1], which extends the known labels $\{y_i\}_{i=1}^m$ via the minimizer

$$\min_{\phi \in \mathbb{R}^n} \left\{ \phi^\top L \phi : \phi_i = y_i, \ 1 \le i \le m \right\},\tag{1}$$

where L is the graph Laplacian, with predictions $\hat{y}_i = \text{sign}(\phi_i)$. Recent work has refined this approach to address its known degeneracies and improve accuracy [2–6], e.g., Poisson Learning [3] solves

$$\min_{\phi \in \mathbb{R}^n} \phi^{\top} L \phi - \sum_{i=1}^m (y_i - \bar{y}) \cdot \phi_i.$$
 (2)

These methods are often analyzed through boundary value problems (BVPs), random walks, and stochastic processes [7], while alternative approaches stem from graph cuts [8].

We propose an affine relaxation of the variational p-Laplacian approach, unifying graph-cut and BVP-based SSL methods within a framework of cuts between probability measures. For binary classification, given label distributions $\mu, \nu \in \mathbb{R}^n$, we solve

$$C_p(\mu, \nu) = \min_{\substack{\phi \in \mathbb{R}^n \\ \phi^T(\mu - \nu) = 1}} \left(\sum_{\{i, j\} \in E} w_{ij} |\phi_i - \phi_j|^p \right)^{1/p}, \tag{C_p}$$

with the $p = \infty$ case given by

$$C_{\infty}(\mu,\nu) = \min_{\substack{\phi \in \mathbb{R}^n \\ \phi^T(\mu-\nu)=1}} \max_{\{i,j\} \in E} w_{ij} |\phi_i - \phi_j|.$$
 (C_{\infty})

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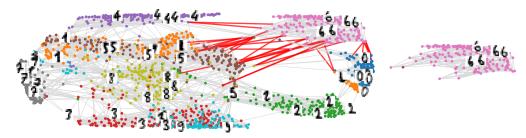


Figure 1: (Left) One-vs-all measure mincut on the Sklearn Digits dataset [12]. The initially labeled nodes are shown with images overlaid. μ is given by the five images of the digit six, and ν from all of the other classes. Solving the program (\mathcal{C}_p) for p=1, we obtain a sparse solution ϕ such that each $\{i,j\} \in E$ satisfies $|\phi_i - \phi_j| \approx 0$ (light gray) or $|\phi_i - \phi_j| \approx 0.11$ (red). (Right) Removing red edges isolates a connected component with near-perfect class separation.

Intuitively, ϕ takes values near 1/2 on $\operatorname{supp}(\mu)$ and -1/2 on $\operatorname{supp}(\nu)$ while minimizing p-Laplacian energy; predictions follow from $\widehat{y} = \operatorname{sgn}(\phi^*)$. For multi-class problems, we adopt a one-vs-all formulation. We call $\mathcal{C}_p(\mu,\nu)$ the measure p-conductance. The parameter p controls solution sparsity: concentrated for p=1, more diffuse as $p\to\infty$.

From a computational perspective, related works include computation of the p-Laplacian and p-effective resistance [9], both of which involve minimizing a weighted p-norm. In [10], Newton methods with homotopy on p were suggested for computing solutions to the p-Laplace equations. Recently, iteratively reweighted least squares were studied in depth in [11]. Notably, the aforementioned methods struggle when $p \in \{1, \infty\}$. In contrast, we describe a globally superlinearly convergent method that works for any $p \in [1, \infty]$.

2 Theoretical analysis of p-Conductances

Here, G=(V,E,w) is a weighted undirected graph on n nodes and N edges with symmetric edge weights w_{ij} . We denote by E' the set of oriented edges, i.e., $E'=\{(i,j),(j,i):\{i,j\}\in E\}$. We define the degree of each node $i\in V$ by $d_i=\sum_{j=1}^n w_{ij}$, and the Laplacian matrix L=D-W where W is the weighted adjacency matrix of G. We denote by P(V) the probability simplex of V. In practice $\mu,\nu\in P(V)$ correspond either to sum-normalized indicators of the labelled nodes in each of two classes, or the measures obtained from the one-vs-all setup as described in Remark 3.1.

Theorem 2.1 (Generalized Max Flow - Min Cut Theorem). Assume G is connected and let $\mu, \nu \in P(V)$. The program $C_1(\mu, \nu)$ is realizable as either $\mathtt{mincut}(\mu, \nu)$ or $\mathtt{maxflow}(\mu, \nu)$ and strong duality holds for these programs. Concretely, the former is a linear program in the variables $k = (k_{ij}) \in \mathbb{R}^{2N}$ and $\psi \in \mathbb{R}^n$; and the latter is a linear program in the variables $J = (J_{ij}) \in \mathbb{R}^{E'}$ and $f \in \mathbb{R}$:

Here, $\widetilde{B} \in \mathbb{R}^{n \times 2N}$ is the oriented incidence matrix according to E'. Finally, strong duality holds.

When only one node is labeled in each class, $\mathtt{mincut}(\mu, \nu)$ recovers the usual node \mathtt{mincut} problem. We illustrate the measure \mathtt{mincut} problem on a toy dataset in Figure 1.

The p-conductance problem is also related to a family of optimal transportation metrics on P(V). Define the p-Beckmann metric (see [13]), denoted $\mathcal{B}_{w,p}(\mu,\nu)$, as the optimal value of the following program, where $1 \leq p < \infty$:

$$\mathcal{B}_{w,p}(\mu,\nu) = \min_{\substack{J \in \mathbb{R}^N \\ BJ = \mu - \nu}} \left(\sum_{\{i,j\} \in E} w_{ij} |J(i,j)|^p \right)^{1/p}, \tag{$\mathcal{B}_{w,p}$}$$

with the usual modifications when $p=\infty$. Here, B is the node-edge oriented incidence matrix of G. This class of problems was considered in, for example, [14] as a family of distances that are related to the effective resistance metric of the underlying graph. From this setup we have the following theorem relating $\mathcal{B}_{w,p}(\mu,\nu)$ to \mathcal{C}_p .

Theorem 2.2. Let $\mu, \nu \in P(V)$ (with $\mu \neq \nu$). Then the optimal values of C_p and $B_{w,p}$ are related as:

$$\mathcal{C}_p(\mu,\nu) = \begin{cases} 1/\mathcal{B}_{\infty,w^{-1}}(\mu,\nu) & \text{if } p = 1, \\ 1/\mathcal{B}_{q,w^{1-q}}(\mu,\nu) & \text{if } p \in (1,\infty) \text{ and } 1/p + 1/q = 1, \\ 1/\mathcal{B}_{1,w^{-1}}(\mu,\nu) & \text{if } p = \infty. \end{cases}$$

This leads to two corollaries relating our program to other well-known optimal transportation and resistance metrics between probability measures on graphs.

Corollary 2.3. Let $\mu, \nu \in P(V)$ with $\mu \neq \nu$. Then it holds that $C_{\infty}(\mu, \nu) = 1/W_{1,w^{-1}}(\mu, \nu)$. That, is $C_{\infty}(\mu, \nu)$ is the reciprocal of the optimal transportation distance between μ, ν when the ground metric on V is taken to be shortest-path distance weighted by w^{-1} .

Corollary 2.4. Assume G is connected and let $\mu, \nu \in P(V)$ (with $\mu \neq \nu$). Then it holds

$$C_2(\mu, \nu)^2 = 1/(\mu - \nu)^T L^{\dagger}(\mu - \nu). \tag{4}$$

A minimizer ϕ^* for $C_2(\mu, \nu)$ achieving Equation (4) is given by $\phi^* = L^{\dagger}(\mu - \nu)/(\mu - \nu)^{\top}L^{\dagger}(\mu - \nu)$.

We note that we are also able to establish connections between C_p and other well-known problems including randomized cuts and normalized cuts.

3 Algorithms for general $p \in [1, \infty]$

In this section we develop a semismooth Newton augmented Lagrangian method (SSNAL) for minimizing (\mathcal{C}_p) for $p \in [1,\infty]$. (For p=2, $\mathcal{C}_2(\mu,\nu)$ is computable from L^\dagger ; see Corollary 2.4.) Remark 3.1 (One-vs-all). Given measures μ_1,\ldots,μ_k corresponding to labeled data in each of k classes, we set $R_i = \mu_i - \frac{1}{k-1} \sum_{j \neq i} \mu_j$ and collect $R = [R_1,\ldots,R_k]$. For $1 \leq p < \infty$,

$$\bar{\mathcal{C}}_p(\mu_1, \dots, \mu_k; R)^p = \min_{\substack{\Phi \in \mathbb{R}^{n \times k} \\ \operatorname{diag}(\Phi^\top R) = \mathbf{1}_k}} \sum_{\{i, j\} \in E} w_{ij} \|\Phi_i - \Phi_j\|_p^p, \tag{5}$$

and for $p = \infty$ replace the sum by $\max_{\{i,j\} \in E} w_{ij} \|\Phi_i - \Phi_j\|_{\infty}$.

Introduce $u \in \mathbb{R}^N$ indexed by oriented edges and the incidence matrix $B \in \mathbb{R}^{n \times N}$. Let $s(u) = \sum_{\{i,j\} \in E} w_{ij} |u_{ij}|^p$ for $1 \le p < \infty$ (with the usual modification for $p = \infty$). We define the augmented Lagrangian (penalties $\sigma_1, \sigma_2 > 0$):

$$\mathcal{L}_{\sigma}(\phi, u; y, z) = s(u) + \langle y, \phi^{\top}(\mu - \nu) - 1 \rangle + \langle z, B^{\top}\phi - u \rangle$$

$$+ \frac{\sigma_1}{2} \|B^{\top}\phi - u\|^2 + \frac{\sigma_2}{2} \|\phi^{\top}(\mu - \nu) - 1\|^2.$$

$$(6)$$

Next for fixed (\tilde{y}, \tilde{z}) , minimize

$$F(\phi, u) := \mathcal{L}_{\sigma}(\phi, u; \tilde{y}, \tilde{z}). \tag{7}$$

Eliminating u via the proximal map gives

Algorithm 1 Semismooth augmented Lagrangian

- 1: while not converged do
- 2: $(\phi_{k+1}, u_{k+1}) \leftarrow \underset{\phi, u}{\operatorname{argmin}} \mathcal{L}_{\sigma}(\phi, u; z_k, y_k)$
- 3: $z_{k+1} \leftarrow z_k + (\sigma_1)_k (B_{\underline{\tau}}^{\top} \phi_{k+1} u_{k+1})$
- 4: $y_{k+1} \leftarrow y_k + (\sigma_2)_k (\phi^\top (\mu \nu) 1)$
- 5: Update $\sigma_{k+1} \leq \infty$
- 6: end while

Algorithm 2 Semismooth Newton-CG

- 1: **while** $||\nabla f(\phi)|| \le \epsilon$ **do**
- 2: Compute $H\Delta\phi \approx -\nabla f(\phi)$.
- 3: (Armijo rule: r > 0, $\sigma, \eta \in (0, 1)$) Set $\zeta = \eta^m r$, m is the first integer ≥ 0 s.t.

$$f(\phi_t) - f(\phi_t + \eta^m r \Delta \phi_t) \ge \sigma \eta_t s \langle \nabla f(\phi_t), \Delta \phi_t \rangle$$

- 4: Set $\phi_{t+1} = \phi_t + \zeta \Delta \phi$
- 5: end while

$$\bar{u} = \operatorname{prox}_{s/\sigma_1} (B^\top \phi + \frac{1}{\sigma_1} \tilde{z}), \qquad \bar{\phi} = \arg\min_{\phi} f(\phi) := \inf_{u} F(\phi, u),$$

with gradient $\nabla f(\phi) = B\tilde{z} + \sigma_1 B(B^\top \phi - \bar{u}) + \tilde{y}(\mu - \nu) + \sigma_2(\phi^\top (\mu - \nu) - 1)(\mu - \nu)$. The equations $\nabla f(\phi) = 0$ are solved using Newton-CG with a generalized Hessian

$$H(\phi) \in \hat{\partial}^2 f(\phi) = \sigma_1 B B^\top - \sigma_1 B \, \partial \bar{u}(\phi) \, B^\top + \sigma_2 (\mu - \nu) (\mu - \nu)^\top,$$

where $\partial \bar{u}(\phi)$ is any element of the generalized Jacobian of the prox mapping.

In practice, $H(\phi)$ is sparse and (under connectivity) positive definite, so CG matrix-vector products cost O(|E|), making SSNCG efficient on large graphs; outer SSNAL updates enforce feasibility of $B^{\top}\phi = u$ and $\phi^{\top}(\mu - \nu) = 1$.

The superlinear convergence of inexact ALM is ensured whenever the following criterion holds, for a summable sequence of nonnegative stopping criteria corresponding to the error of the Newton equations $\{\epsilon_k\}$.

$$\operatorname{dist}(0, \partial F(\phi_{k+1}, u_{k+1})) \le \epsilon_k / \max\{1, \sqrt{\sigma_k}\}$$
(8)

Theorem 3.2 (Convergence of SSNAL). Let (ϕ_k, u_k, z_k, y_k) be the sequence generated by SSNAL with stopping criterion (8). Then, the sequence $\{\phi_k\}$ is bounded and converges to the unique optimal solution of (5), and $||B^{\top}\phi - u||$ and $||\phi^{\top}(\mu - \nu) - 1||$ converge to zero.

4 Experimental results

Our method achieves state-of-the-art accuracy on several benchmark data classification tasks, including citation networks, image datasets MNIST [15], Fashion-MNIST [16] and CIFAR-10 [17], as well as in settings where the labels have been partially corrupted. We highlight two experiments: classification accuracy on the PubMed dataset (Tab. Table 1), as well as accuracy on the CIFAR-10 dataset (Fig. Figure 2) when the labels have been perturbed to varying degrees and the input measures have been smoothed on the graph via the diffusion kernel e^{-tL} (using Poisson learning as a benchmark). This provides experimental evidence for the robustness of our method when label noise is present in practice. We also investigate the setting of partially labelled learning, which is a weakly supervised learning problem where each training instance is equipped with a set of candidate labels, including the ground-truth label.

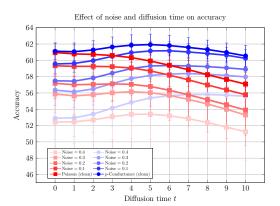


Figure 2: Accuracy on CIFAR-10 for various diffusion times. Shades denote noise level. Label rate is 10 labels per class.

Table 1: Average accuracy over 100 trials with standard deviation in brackets. Best is bolded.

PUBMED # LABELS PER CLASS	1	3	5	10	100
LAPLACE/LP [1]	34.6 (8.8)	35.7 (8.2)	36.9 (8.1)	39.6 (9.1)	74.9 (3.6)
SPARSE LP [18]	32.4 (4.7)	33.0 (4.8)	33.6 (4.8)	33.9 (4.8)	43.2 (4.1)
P-LAPLACE [10]	44.8 (11.2)	58.3 (9.1)	61.6 (7.7)	66.2 (4.7)	74.3 (1.1)
P-EIKONAL [2]	44.3 (11.8)	55.6 (10.0)	58.4 (9.1)	65.1 (5.8)	74.9 (1.5)
Poisson [3]	55.1 (11.3)	66.6 (7.4)	68.8 (5.6)	71.3 (2.2)	75.7 (0.8)
p -CONDUCTANCE $(p = 1, \epsilon = n)$	39.6 (0.3)	39.6 (0.3)	39.6 (0.3)	40.3 (0.3)	41.2 (0.3)
p -CONDUCTANCE $(p=2, \epsilon=n)$	58.0 (12.1)	67.5 (7.5)	70.8 (4.9)	72.4 (2.5)	77.6 (0.6)
p -CONDUCTANCE $(p = \infty, \epsilon = n)$	48.0 (8.1)	56.5 (5.2)	57.0 (8.2)	62.6 (3.0)	72.9 (1.3)
PoissonMBO [3] p -conductance ($p = 2$, $\epsilon = 0$)	54.9 (11.4) 58.7 (11.5)	` /	` /	69.9 (3.0) 72.4 (2.6)	` /

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