
Few-Shot Learnable Augmentation for Financial Time Series Prediction under Distribution Shifts

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Abstract

1 We address the problem of distribution shift in financial time series prediction,
2 where the behavior of the time series changes over time. Satisfactory performance
3 of forecasting algorithms requires constant model recalibration or fine-tuning to
4 adapt to the new data distribution. Specifically, the ability to quickly fine-tune
5 a model with only a few training samples available from the new distribution is
6 crucial for many business applications. In this paper, we develop a novel method
7 for learnable data augmentation that effectively adjusts to the new time series
8 distribution with only a few samples. We demonstrate the effectiveness of our
9 method compared to the state-of-the-art augmentation methods on both univariate
10 time series (e.g., stock data) and multivariate time series (e.g., yield rate curves) in
11 the presence of distribution shift due to the COVID market shock in 2020.

12 1 Introduction

13 Time series prediction is the task of classifying or categorizing sequential inputs to gain further insight
14 into their behavior, with important applications in multiple domains such as weather forecasting,
15 medical diagnosis as well as financial prediction. As our society evolves continuously, financial
16 data is prone to distribution shifts over time, where the time series dynamics deviate from previous
17 patterns. Time series models trained with past data are no longer effective on current data. Similarly,
18 it is common in practice to have wider access to the time series data for higher liquidity assets – and
19 it is sometimes necessary to adapt models trained for highly liquid assets to low liquidity ones with a
20 small number of data samples. To address the above distribution shift challenges, we focus on a setup
21 of few-shot fine-tuning where a model can be quickly re-calibrated using only a few data points.

22 **Related Work.** There are three common types of distribution shifts in supervised learning correspond-
23 ing to whether the changes in distributions happen to the input samples, referred to as covariate shifts
24 [1, 2, 3], or to the outputs, label/concept shifts [4, 5, 6, 7]. Recently, [8] proposes a new categorization
25 framework to enable more fine-grain analysis on distribution shifts. To address learning with distribu-
26 tion shifts, domain generalization works [9, 10] construct a model that is robust to a wide range of
27 distributions. [11] leverages adversarial learning on a few samples in target distribution for domain
28 adaptation. However, these methods cannot synthesize additional samples in target distribution for
29 fast model fine-tuning with limited data, especially in time series domain. Although [12, 13, 14]
30 introduces various time series augmentation methods, they are not designed for distribution shifts,
31 thus they are unable to transfer knowledge from source to target distribution.

32 **Contributions.** We develop an augmentation framework to synthesize multiple variants of time series
33 samples in order to facilitate few-shot model fine-tuning. Our contributions are as follows:

- 34 • We propose a learnable augmentation technique based on an autoencoder for time series.
- 35 • We design our method for few-shot model fine-tuning where a model is pretrained on many samples
- 36 from a source distribution and updated with limited samples from a target distribution.
- 37 • We demonstrate the effectiveness of our method on both univariate and multivariate time series
- 38 data for stock and yield rate curve predictions, respectively.

39 2 Few-shot Learnable Augmentation for Distribution Shifts

40 2.1 Problem Setting

41 Let $\mathcal{D}_s = \{(\mathbf{X}_s, y_s) | \mathbf{X}_s \sim P_s\}$ be the training set from a source distribution, with $\mathbf{X}_s \in \mathbb{R}^{f \times n}$
 42 the input time series having t time steps, each with dimension f , and y_s its ground-truth label. In
 43 addition, $\mathcal{D}_t = \{(\mathbf{X}_t, y_t) | \mathbf{X}_t \sim P_t\}$ is data from a target distribution, which is different from the
 44 source distribution in terms of time series \mathbf{X} (covariate shift [1, 2, 3]) or labels y (label shift [4, 5]).
 45 In this work, we mainly focus on covariate shifts in time series, i.e., temporal shifts with different time
 46 series distributions $P_t \neq P_s$. Specifically, we are interested in the problem of few-shot learning with
 47 distribution shifts where only limited training samples are available in target distribution, $|\mathcal{D}_t| \ll |\mathcal{D}_s|$.
 48 The goal is to transfer knowledge from the source distribution, \mathcal{D}_s , to the target distribution, \mathcal{D}_t , to
 49 learn a classifier that generalizes well to the target distribution P_t .

50 Due to the small number of samples in the target distribution, \mathcal{D}_t , simply training a classifier on these
 51 few samples would be prone to overfitting, as shown in the experimental section. Thus, we propose a
 52 novel time series augmentation technique to diversify training data in the target distribution.

53 2.2 Proposed Method

54 To address the distribution shifts between source and target data, we introduce a learnable augmenta-
 55 tion method based on Δ -encoder [15]. We review this method and then improve upon the original
 56 design by proposing latent code perturbation and augmentation re-labeling for temporal shifts.

57 **Background: Δ -encoder.** Instead of using heuristic augmentation to synthesize new samples, [15]
 58 proposes a learnable data augmentation by capturing the inner-class variances of samples. They
 59 leverage an autoencoder architecture to encode the transformation from one sample to another into
 60 a latent code and reuse these codes to augment new samples. Specifically, let $(\mathbf{X}_s, \mathbf{X}_{s'})$ be a pair
 61 of source distribution samples from the same class, $y_s = y_{s'}$. An encoder, E , aims to capture the
 62 transformation from \mathbf{X}_s to $\mathbf{X}_{s'}$ into a latent code as:

$$E(\mathbf{X}_s, \mathbf{X}_{s'}) = \mathbf{z}_{s \rightarrow s'}, \quad (1)$$

63 where $\mathbf{z}_{s \rightarrow s'} \in \mathbb{R}^d$ is a low-dimensional latent vector encoding the transformation from sample s to
 64 s' . Given the latent code, a decoder, D , is trained to reconstruct sample s' given s :

$$D(\mathbf{X}_s, \mathbf{z}_{s \rightarrow s'}) = \hat{\mathbf{X}}_{s'}. \quad (2)$$

65 Both the encoder, E , and decoder, D , are trained end-to-end by minimizing the l_1 reconstruction loss
 66 between decoder’s output and original sample as $|\mathbf{X}_{s'} - \hat{\mathbf{X}}_{s'}|_1$. Thus, the encoder learns to capture
 67 class-invariance transformation in the source distribution.

68 Δ -encoder extracts latent code from source distribution pairs and applies these codes on few samples
 69 from target distribution to synthesize new data as: $D(\mathbf{X}_t, \mathbf{z}_{s \rightarrow s'}) = \hat{\mathbf{X}}_t^{s \rightarrow s'}$. Although this improves
 70 performances on few-shot learning where both train and test data are from the same distribution but
 71 different classes, it is ineffective when dealing with covariate shifts. Specifically, when $P_s \neq P_t$,
 72 augmenting \mathbf{X}_t with latent code $\mathbf{z}_{s \rightarrow s'}$ will construct a new sample $\hat{\mathbf{X}}_t^{s \rightarrow s'}$ that follow P_s but not
 73 the target distribution P_t . To address this, we introduce a novel latent code perturbation scheme that
 74 conditions the latent codes on the target distribution, \mathcal{D}_t , to capture the target distribution, P_t .

75 **Latent Code Perturbation.** Instead of relying on the latent codes from the source distribution,
 76 $\mathbf{z}_{s \rightarrow s'}$, we extract latent codes from the target distribution samples from the same class, $y_t = y_{t'}$:

$$E(\mathbf{X}_t, \mathbf{X}_{t'}) = \mathbf{z}_{t \rightarrow t'}, \quad (3)$$

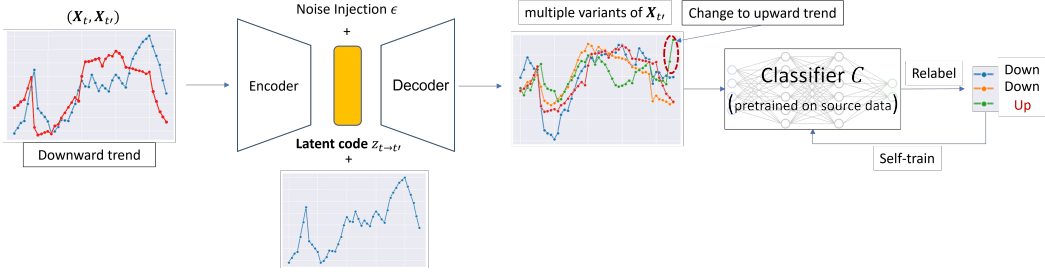


Figure 1: Given a pair of sequences $(\mathbf{X}_t, \mathbf{X}_{t'})$ in the target distribution, our framework extracts a latent vector $z_{t \rightarrow t'}$ which captures the transformation from \mathbf{X}_t to $\mathbf{X}_{t'}$. By slightly perturbing this latent vector, we can synthesize multiple variants of $\mathbf{X}_{t'}$. Finally, we use a classifier C pretrained on source data to re-label augmented samples to capture any changes in label semantics.

77 where $z_{t \rightarrow t'}$ is a latent code in target distribution. Naively using this code on \mathbf{X}_t would simply
 78 reconstruct the original data $\mathbf{X}_{t'}$ without diversifying the training set. Thus, we propose to slightly
 79 perturb the latent code based on random noise, ϵ , as:

$$D(\mathbf{X}_t, z_{t \rightarrow t'} + \epsilon) = \hat{\mathbf{X}}_{t'}^\epsilon, \quad (4)$$

80 where $\hat{\mathbf{X}}_{t'}^\epsilon$ is the augmented variant of $\mathbf{X}_{t'}$ based on random noise ϵ . By using perturbed latent code
 81 instead of transferring latent code from the source distribution as in [15], our method effectively
 82 captures the target distribution and avoids overfitting to latent code from the source distribution.

83 **Augmentation Re-labeling for Temporal Shifts.** As we randomly perturb the latent code, the label
 84 of the augmented sample $\hat{\mathbf{X}}_{t'}^\epsilon$ might be changed compared to its original label of $\mathbf{X}_{t'}$, e.g., from
 85 downward to upward trends, due to the non-interpretability of the augmentation operation, $D(\cdot)$ as
 86 shown in Figure 1. Thus, we propose re-labeling the augmented sample to account for any semantic
 87 changes during the augmentation progress. We train a classifier, C , on source distribution \mathcal{D}_s and
 88 assign its most confident prediction on an augmented sample as its new label:

$$\operatorname{argmax}_y C(y | \hat{\mathbf{X}}_{t'}^\epsilon) = \hat{y}_{t'}^\epsilon, \quad (5)$$

89 where $\hat{y}_{t'}^\epsilon$ is the new label for augmented sample $\hat{\mathbf{X}}_{t'}^\epsilon$. Here, we assume that temporal shift only
 90 effects the series distribution \mathbf{X} while the conditional label distribution $P(y | \mathbf{X})$ remains unchanged
 91 similar to [1, 2, 3].

92 **Learning with Mixture of Real and Augmented Samples.** Finally, we fine-tune the classifier, C ,
 93 on the mixture of both real and augmented samples to adapt it to the target distribution as follows:

$$\min_C \sum_{(\mathbf{X}_t, \mathbf{X}_{t'}, y_t) \in \mathcal{D}_t} \left[\mathcal{L}(C(\mathbf{X}_t), y_t) + \lambda \mathcal{L}(C(\hat{\mathbf{X}}_{t'}^\epsilon), \hat{y}_{t'}^\epsilon) \right], \quad (6)$$

94 where λ is the mixture coefficient that controls the influence of augmented samples on the classifier.
 95 The larger λ is, the more emphasis we put on augmented samples.

96 **Remark 1** Unlike prior work [12, 14], which cannot share knowledge between source and target
 97 distributions, our method combines latent codes from target distribution samples and the decoder
 98 pretrained on source distribution to effectively transfer knowledge between distributions.

99 3 Experiments

100 We evaluate our proposed framework on the forecasting task of stock trend prediction for univariate
 101 time series, and yield rate curves prediction for multivariate time series. We present both quantitative
 102 and qualitative results to demonstrate the effectiveness of our method. For further information about
 103 datasets, baselines, and implementation details, please refer to the supplementary material section 5.

104 3.1 Experimental Results

105 **Univariate time series Prediction: Stock Price.** Table 1 shows the performances of different
 106 augmentation methods on stock data. Given very few training samples of 10, 20 and 30 shots, our

k-shot	Baseline Augmentation				No Augmentation		Our Proposed Augmentation			
	Gaussian Jitter [12]	Time Warp [12]	RGW [14]	DGW [14]	Pretrain \mathcal{D}_s	Fine-tune \mathcal{D}_t	$\lambda = 0.25$	$\lambda = 0.5$	$\lambda = 1.0$	$\lambda = 2.0$
10	77.6 + 5.8	74.8 + 9.7	77.1 + 9.8	72.9 + 9.7	75.5 + 14.6	83.8 + 6.2	81.2 + 6.4	84.2 + 5.9	83.7 + 7.1	83.6 + 6.0
20	72.6 + 12.0	69.5 + 10.6	73.4 + 13.7	73.3 + 14.5	78.2 + 12.5	77.8 + 10.5	74.0 + 12.8	81.2 + 7.9	80.6 + 7.7	82.3 + 7.0
30	83.6 + 3.6	83.3 + 5.8	79.6 + 9.3	74.4 + 13.1	81.9 + 9.9	78.2 + 11.7	83.7 + 6.5	85.0 + 5.5	79.8 + 8.3	79.0 + 12.1
40	85.0 + 2.9	87.4 + 1.3	84.8 + 4.3	82.5 + 4.9	84.7 + 1.0	83.5 + 6.7	86.1 + 5.4	85.5 + 5.6	86.2 + 5.1	86.6 + 4.9
50	85.6 + 1.9	85.2 + 2.8	86.5 + 1.0	85.3 + 2.0	83.8 + 6.8	83.8 + 5.9	84.0 + 6.7	84.8 + 6.7	85.1 + 6.5	85.4 + 6.3
60	86.2 + 2.3	87.5 + 1.0	85.7 + 1.5	84.7 + 1.9	85.1 + 7.6	86.6 + 6.4	86.7 + 6.9	87.3 + 6.4	86.5 + 6.3	86.3 + 6.1

Table 1: Stock trend prediction performances (mean + standard deviation) for every 6-month period after 2020. **Bold** and underline indicate best and second best performances, respectively.

k-shot	Baseline Augmentation				No Augmentation		Our Proposed Augmentation			
	Gaussian Jitter [12]	Time Warp [12]	RGW [14]	DGW [14]	Pretrain \mathcal{D}_s	Fine-tune \mathcal{D}_t	$\lambda = 0.25$	$\lambda = 0.5$	$\lambda = 1.0$	$\lambda = 2.0$
10	47.0 + 18.8	47.8 + 19.8	47.8 + 18.6	46.3 + 17.8	58.0 + 14.1	47.0 + 22.3	53.0 + 15.1	52.0 + 16.2	56.3 + 13.4	52.2 + 18.9
20	44.5 + 18.1	43.8 + 20.7	41.9 + 17.3	43.8 + 18.3	54.5 + 14.2	44.8 + 23.0	42.4 + 21.8	53.3 + 15.1	49.3 + 19.4	59.0 + 15.1
30	52.9 + 16.9	53.4 + 15.7	53.4 + 17.7	51.6 + 14.8	56.1 + 10.0	47.6 + 18.9	46.3 + 18.2	60.8 + 11.5	53.4 + 15.2	73.4 + 12.5
40	65.0 + 16.2	62.6 + 17.5	62.1 + 18.8	63.8 + 18.5	50.9 + 13.1	60.9 + 10.2	70.0 + 6.4	71.8 + 12.9	61.5 + 11.6	70.0 + 11.7
50	61.3 + 17.7	67.7 + 11.9	70.0 + 10.9	66.0 + 12.4	49.0 + 14.5	60.3 + 7.1	71.0 + 2.6	64.7 + 5.0	72.3 + 9.1	73.7 + 4.0
60	50.8 + 15.3	64.2 + 18.1	60.0 + 21.7	59.2 + 8.5	50.0 + 16.0	60.4 + 2.3	55.8 + 7.3	53.1 + 17.1	68.5 + 8.5	57.3 + 13.1

Table 2: Yield rate trend prediction performances (mean + standard deviation) for every 6-month period after 2020. **Bold** and underline indicate best and second best performances, respectively.

107 method surpasses prior works by at least 0.4%, 3%, and 1.7% accuracies, respectively, with $\lambda = 0.5$
 108 which demonstrates the effectiveness of our method when dealing with very few numbers of target
 109 distribution samples. Without leveraging our method, we observe that simply fine-tuning a classifier
 110 on few-shot data offers no significant improvement compared to no fine-tuning. Notice our work can
 111 improve performances on a wide range of training shots (including those with a small number of
 112 shots), while prior augmentation methods only work for a larger number of shots (when there are at
 113 least 40 training shots in our example).

114 **Multivariate time series Prediction: Yield Rate Curve.** Table 2 presents yield rate trend perfor-
 115 mances. With just 20, 30, and 40 training samples, our method significantly improves accuracy by
 116 4.5%, 17.3%, and 5%, respectively, compared to other augmentation with $\lambda = 2.0$. With less than
 117 30 training shots, fine-tuning the classifier even degrades prediction accuracies with respect to only
 118 pretrained the classifier, which shows the challenges of few-shot model fine-tuning without overfitting
 119 on limited target distribution samples. Without data augmentation, we observe a performance gap of
 120 around 10% between only pre-training on \mathcal{D}_s and fine-tuning on \mathcal{D}_t for $k \geq 40$. This demonstrates
 121 that the distribution shifts can cause the model pretrained on \mathcal{D}_s to be ineffective on \mathcal{D}_t .

122 **Qualitative Results.** We visualize the distribution of augmented and real samples using t-SNE
 123 [16]. When overlaying the distribution of few-shot samples from \mathcal{D}_t and synthetic samples from
 124 our augmentation model in Figure 2 (a), we observe that the augmented samples generalize beyond
 125 few-shot samples used to synthesize them thanks to our decoder which transfers knowledge from
 126 source to target distributions. To validate the effectiveness of augmented samples, Figure 2 (b) shows
 127 the distributions of all target samples and synthetic samples where the augmented samples manage to
 128 capture the target distribution.

129 Without augmentation re-labeling, we find that our method could not improve performances for both
 130 datasets compared to fine-tuning on \mathcal{D}_t , due to the label changes when augmenting time series.

131 4 Conclusion

132 We propose a novel method that learns to
 133 augment samples for the problem of
 134 few-shot model fine-tuning under distri-
 135 bution shifts. Our work aims to encode
 136 a class-agnostic transformation between
 137 inner-class samples into a compact latent
 138 code. During inference, we perturb the
 139 latent code to simulate different augmenta-
 140 tions on a few samples in the target distri-
 141 bution. When combined with augmentation
 142 re-labeling, our method significantly im-
 143 proves model fine-tuning performances for both univariate and multivariate time series in financial
 144 applications.

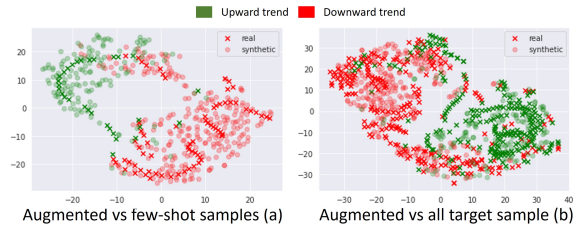


Figure 2: t-SNE visualization of augmented (synthetic) and real Delta airline stocks in the target distribution.

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184 5 Supplementary Materials

185 5.1 Experimental Setup

186 **Datasets.** For univariate time series prediction, $f = 1$, we experiment with daily stock price trend
187 forecasting. Specifically, to capture the distribution shifts in financial data, we select companies from
188 the travel industry: Southwest Airlines, Delta Airlines, Carnival Cruise Line, and Royal Caribbean
189 Group, which have dramatic changes in their stock price during the COVID lockdown in 2020. We
190 use Yahoo! Finance’s API¹ to crawl the data.

191 We illustrate multivariate time series prediction with the daily treasury yield dataset² - where the
192 yield values are read from the yield curve at fixed maturities, 1, 3, and 6 months and 1, 2, 3, 5, 7, 10,
193 20, and 30 years. Time series for different maturities are known to be highly correlated.

194 For both stock and yield curve datasets, we construct the 30-day consecutive time-step sequences,
195 $n = 30$, as input \mathbf{X} . We also perform mean subtraction and standard deviation division to normalize
196 the range of these sequences. The ground-truth label is a binary indicator, $y \in \{0, 1\}$, for whether
197 the sequence value will go down or up compared to the mean for the 31st day. We select a training
198 dataset from 2019 data, and test the models on the 2020 data to account for the distribution shift due
199 to the COVID market shock.

200 **Evaluation Metrics.** To evaluate our performance, we split the target data into multiple non-
201 overlapping windows of six months. Within each window, we use the first k sequences in each
202 time window as \mathcal{D}_t to construct augmented data as well as fine-tune the classifier. We measure the
203 classification accuracy on the remaining sequences from the $k + 1$ day. We report the mean and
204 standard deviation of prediction accuracies across all testing windows.

205 **Baselines.** For baselines, we use two popular data augmentation methods for time series data, namely
206 jittering and time warp [12, 13]. Jittering consists of adding Gaussian noise element-wise to the time
207 series while time warping randomly selects anchor points in the time series and smoothly distorts
208 the time intervals between the points using a cubic spline curve. Additionally, we compare our
209 model with two pattern mixing methods proposed for time series, Random Guided Warp (RGW)
210 and Discriminative Guided Warp [14]. Both methods use Dynamic Time Warping (DTW), which
211 determines an optimized distance measure for time series that is robust to temporal distortions. In
212 RGW, time series are mixed by warping the features of an original sample pattern to match the time
213 steps of a reference pattern, using DTW to create the warping path, with both elements within the
214 same class. DGW introduces a discriminative teacher as a reference for guided warping.

215 **Implementation Details.** The augmentation model, $\{E, D\}$, and the classifier, C , are based on the
216 InceptionTime architecture [17]. We use the Adam optimizer with a batch size of 32 and a learning
217 rate of 1e-3 on 80 epochs for the augmentation model, with 10 epochs for classifier pre-training and
218 another 5 epochs for fine-tuning. Empirically, we find that using a standard normal distribution to
219 perturb the latent code $\epsilon \sim N(0, \mathbf{I})$ works best. Our code is released upon request.

¹<https://pypi.org/project/yfinance/>

²<https://home.treasury.gov/interest-rates-data-csv-archive>