A Kernel Two-Sample Test with the Representation Jensen-Shannon Divergence

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Abstract

We introduce a novel kernel-based information-theoretic framework for two-sample testing, leveraging the representation Jensen-Shannon divergence (RJSD). RJSD captures higher-order information from covariance operators in reproducing Kernel Hilbert spaces and avoids Gaussianity assumptions, providing a robust and flexible measure of divergence between distributions. We develop RJSD-based variants of Maximum Mean Discrepancy (MMD) approaches, demonstrating superior discriminative power in extensive experiments on synthetic and real-world datasets. Our results position RJSD as a powerful alternative to MMD, with the potential to significantly impact kernel-based learning and distribution comparison. By establishing RJSD as a benchmark for two-sample testing, this work lays the foundation for future research in kernel-based divergence estimation and its broad range of applications in machine learning.

1 Introduction

The problem of non-parametric two-sample testing, which aims to detect differences between two data distributions given only observations, remains a fundamental challenge in machine learning. Among the most widely used metrics for two-sample testing is the Maximum Mean Discrepancy (MMD) [Gretton et al., 2012]. MMD consists of mapping the distributions into a reproducing kernel Hilbert space (RKHS) and computing the distance between their mean embeddings. In the past decade, MMD has been a dominant approach in kernel-based two-sample testing, and several MMD-based two-sample tests have been proposed, leading to significant advances in the field [Gretton et al., 2012, Sutherland et al., 2016, Jitkrittum et al., 2016, Liu et al., 2020, Schrab et al., 2023, Biggs et al., 2024]. Despite its widespread adoption, MMD's reliance on first-order moment information has motivated the exploration of alternative methods.

Recent advances in kernel-based divergence estimation offer a promising direction. Specifically, covariance operators (second-order moment information) in RKHS can be used to formulate distribution divergences [Harandi et al., 2014, Minh, 2015, Zhang et al., 2019, Minh, 2021, 2023]. However, these measures often assume Gaussianity in the representation space, which may not hold in practice.

To address these limitations, a novel kernel-based information-theoretic framework called *the representation Jensen-Shannon divergence* (RJSD) has been proposed as a versatile alternative [Hoyos-Osorio et al., 2023]. RJSD is formulated as the von Neumann Jensen-Shannon divergence between infinite-dimensional covariance operators in reproducing kernel Hilbert spaces (RKHS). This formulation provides a proper divergence between distributions in the input space without relying on density estimation or assuming Gaussianity in the feature space, making it a powerful alternative to existing approaches.

RJSD not only extends the concept of divergence in RKHS but also holds a direct connection to MMD. We show that MMD can be viewed as a particular case of RJSD, while RJSD captures higher-order information, leading to improved performance in tasks like two-sample testing. Additionally, RJSD can be readily estimated from samples in the input space using Gram matrices.

In this work, we leverage RJSD to propose a novel kernel-based information-theoretic framework for two-sample testing. Inspired by three well-known MMD-based tests, including MMD-Split [Sutherland et al., 2016], MMD-Deep [Liu et al., 2020], and MMD-Fuse [Biggs et al., 2024], we develop RJSD-based variants, enabling more powerful and flexible testing procedures. Our work significantly advances kernel-based two-sample testing, providing a robust alternative to MMD. We evaluate the efficacy of our approach through extensive experiments, demonstrating its potential to improve the state-of-the-art in two-sample testing.

2 Preliminaries and background

In this section, we introduce the notation and discuss fundamental concepts.

2.1 Notation

Let $(\mathcal{X}, \mathcal{F})$ be a measurable space. Let $\mathcal{M}^1_+(\mathcal{X})$ be the space of probability measures on \mathcal{X} , and let $P, Q \in \mathcal{M}^1_+(\mathcal{X})$ be two probability measures dominated by a σ -finite measure λ on $(\mathcal{X}, \mathcal{F})$ (Similar notation from Stummer and Vajda [2012]). Then, the densities $p = \frac{\mathrm{d}P}{\mathrm{d}\lambda}$ and $q = \frac{\mathrm{d}Q}{\mathrm{d}\lambda}$ have common support (the densities are positive on \mathcal{X}). $X \sim P$ and $Y \sim Q$ are two random variables distributed according to P and Q.

2.2 Kernel Mean Embedding

Let $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}_{\geq 0}$ be a positive definite kernel. There exists a mapping $\phi : \mathcal{X} \to \mathcal{H}$, where \mathcal{H} is a reproducing kernel Hilbert space, such that $\kappa(x, x') = \langle \phi(x), \phi(x') \rangle_{\mathcal{H}}$. The kernel mean embedding is a mapping μ from $\mathcal{M}^1_+(\mathcal{X})$ to \mathcal{H} defined as follows [Smola et al., 2007]: For $P \in \mathcal{M}^1_+(\mathcal{X})$,

$$\mu_P = \mathbb{E}_{X \sim P}[\phi(X)] = \int_{\mathcal{X}} \phi(x) \,\mathrm{d}\, P(x)$$

For a bounded kernel, $\kappa(x, x) < \infty$ for all $x \in \mathcal{X}$, we have that for any $f \in \mathcal{H}$, $\mathbb{E}_{X \sim P}[f(X)] = \langle f, \mu_P \rangle_{\mathcal{H}}$.

2.3 Covariance Operator

Another related mapping is the uncentered covariance operator [Baker, 1973], one of the most important and widely used tools in RKHS theory. In this case, $P \in \mathcal{M}^1_+$ is mapped to an operator $C_P : \mathcal{H} \to \mathcal{H}$ given by:

$$C_P = \mathbb{E}_{X \sim P}[\phi(X) \otimes \phi(X)] = \int_{\mathcal{X}} \phi(x) \otimes \phi(x) \,\mathrm{d}\, P(x), \tag{1}$$

where \otimes is the tensor product. Similarly, for any $f, g \in \mathcal{H}, \mathbb{E}_{X \sim P}[f(X)g(X)] = \langle g, C_P f \rangle_{\mathcal{H}}$.

The covariance operator is positive semidefinite and Hermitian (self-adjoint). Additionally, if the kernel is bounded, that is $\kappa(x, y) < \infty$, the covariance operator is trace class [Sanchez Giraldo et al., 2014, Bach, 2022]. Therefore, the spectrum of the covariance operator is discrete and consists of non-negative eigenvalues λ_i with $\sum \lambda_i < \infty$, for which we can extend functions on \mathbb{R} such as $t \log(t)$ and t^{α} to covariance operators via their spectrum [Naoum and Gittan, 2004].

2.4 Information theory with covariance operators

Throughout this paper, unless otherwise stated, we will assume that:

(A1) $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}_{\geq 0}$ is a positive definite kernel with an RKHS mapping $\phi : \mathcal{X} \to \mathcal{H}$ such that $\kappa(x, x') = \langle \phi(x), \phi(x') \rangle_{\mathcal{H}}$, and $\kappa(x, x) = 1 \quad \forall x \in \mathcal{X}$.

Under this assumption, the covariance operator C_P defined in Eqn. 1 is unit-trace. Note that since $\kappa(x, x) = 1$, we have that, $\text{Tr}(\phi(x) \otimes \phi(x)) = \|\phi(x)\|^2 = 1$. Hence, the spectrum of the covariance operator consists of non-negative eigenvalues λ_i with $\sum \lambda_i = 1$, for which we can extend notions of entropy from the spectrum of unit-trace covariance operators.

Definition 1. Let X be a random variable taking values in \mathcal{X} and probability measure P. Assume (A1) holds, and let C_P be the corresponding unit-trace covariance operator defined in Eqn. 1. Then, the representation (kernel) entropy of X is defined as:

$$H^{\mathcal{H}}(X) = S(C_P) = -\operatorname{Tr}\left(C_P \log C_P\right),\tag{2}$$

where $S(\cdot)$ is a generalization of the von Neumann entropy [Von Neumann, 2018] for trace class operators, and it can be equivalently formulated as $S(C_P) = -\sum \lambda_i \log \lambda_i$.

Although the representation entropy has similar properties to those of Shannon entropy, it is important to emphasize that they are not equal, and thus estimating representation entropy does not amount to estimating Shannon entropy. Instead, the representation entropy incorporates the data representation. Its properties are not only determined by the data distribution but also depend on the representation (kernel).

2.4.1 Empirical estimation of representation entropy

Let $X = \{x_i\}_{i=1}^n \sim P$ be *n* i.i.d samples of a random variable *X* with probability measure *P*. An empirical estimate of representation entropy can be obtained based on the spectrum of the empirical uncentered covariance operator C_X . Consider the Gram matrix K_X , consisting of all pairwise kernel evaluations between data points in the sample *X*, that is, $(K_X)_{ij} = \kappa(x_i, x_j)$ for i, j = 1, ..., n. It can be shown that C_X and $\frac{1}{n}K_X$ have the same non-zero eigenvalues [Sanchez Giraldo et al., 2014, Bach, 2022]. Based on this equivalence, the estimator of representation entropy can be expressed in terms of the Gram matrix K_X as follows:

Proposition 1. The empirical kernel-based representation entropy estimator of X is

$$\hat{H}^{\mathcal{H}}(X) = S(\boldsymbol{C}_{\boldsymbol{x}}) = S\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{x}}\right) = -\operatorname{Tr}\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{x}}\log\frac{1}{n}\boldsymbol{K}_{\boldsymbol{x}}\right) = -\sum_{i=1}^{n}\lambda_{i}\log\lambda_{i}, \quad (3)$$

where λ_i denotes the *i*th eigenvalue of $\frac{1}{n}K_x$. The eigen-decomposition of K_x has $\mathcal{O}(n^3)$ time complexity.

3 The representation Jensen-Shannon divergence

Definition 2. Let P and Q be two probability measures defined on a measurable space $(\mathcal{X}, \mathcal{F})$, and $(\mathbf{A1})$ is satisfied. Then, the **representation Jensen-Shannon divergence** (*RJSD*) between P and Q is defined as [Hoyos-Osorio et al., 2023]:

$$D_{JS}^{\mathcal{H}}(P,Q) = S\left(\frac{C_{P} + C_{Q}}{2}\right) - \frac{1}{2}\left(S(C_{P}) + S(C_{Q})\right).$$
(4)

3.1 Properties

First, we show that RJSD relates to the maximum mean discrepancy (MMD) with kernel κ^2 , where MMD is defined as $\text{MMD}_{\kappa}^2(P,Q) = \|\mu_P - \mu_Q\|_{\mathcal{H}}^2$.

Lemma 1. For all probability measures P and Q defined on \mathcal{X} , and covariance operators C_P and C_Q with RKHS mapping $\phi(x)$ such that $\langle \phi(x), \phi(x) \rangle_{\mathcal{H}} = 1 \quad \forall x \in \mathcal{X}$:

$$D_{JS}^{\mathcal{H}}(P,Q) \ge \frac{1}{8} \|C_P - C_Q\|_{HS}^2 = \frac{1}{8} \operatorname{MMD}_{\kappa^2}^2(P,Q)$$

Proof: See Appendix A.1.

Theorem 1. Let κ^2 be a characteristic kernel. Then, the representation Jensen-Shannon divergence $D_{JS}^{\mathcal{H}}(P,Q) = 0$ if and only if P = Q.

Proof. It is clear that if P = Q then $D_{JS}^{\mathcal{H}}(P,Q) = 0$. We now prove the opposite. According to Lemma 1, $D_{JS}^{\mathcal{H}}(P,Q) = 0$ implies that $\text{MMD}_{\kappa^2}^2(P,Q) = 0$. Then, if $\text{MMD}_{\kappa^2}^2(P,Q) = 0$ and the kernel κ^2 is characteristic, then P = Q [Gretton et al., 2012], completing the proof.

This theorem demonstrates that RJSD defines a proper divergence between probability measures in the input space.

Additionally, RJSD has a direct connection with its classical counterpart.

Theorem 2. [Hoyos-Osorio et al., 2023, Theorem 3] For all probability measures P and Q defined on X, and unit-trace covariance operators C_P and C_Q , the following inequality holds:

$$D_{JS}^{\mathcal{H}}(P,Q) \le D_{JS}(P,Q),\tag{5}$$

where $D_{JS}(P,Q)$ is the traditional Jensen-Shannon divergence.

3.2 Empirical Estimation of the representation Jensen-Shannon divergence

Given two sets of samples $X = \{x_i\}_{i=1}^n \subset \mathcal{X}$ and $Y = \{y_i\}_{i=1}^m \subset \mathcal{X}$ drawn from two unknown probability measures P and Q, we propose the following RJSD estimator:

Kernel-based estimator: Let κ be a positive definite kernel, Z be the mixture of the samples of X and Y, that is, $Z = \{z_i\}_{i=1}^{n+m}$ where $z_i = x_i$ for $i \in \{1, \ldots, n\}$ and $z_i = y_{i-n}$ for $i \in \{n+1, \ldots, n+m\}$. Finally, let K_z be the kernel matrix consisting of all normalized pairwise kernel evaluations of the samples in Z, that is, the samples from both distributions. Moreover, let K_x and K_y be the pairwise kernel matrices of X and Y respectively.

Notice that the sum of uncentered covariance operators in the RKHS corresponds to the covariance operator of the mixture of samples in the input space, that is, $\frac{n}{n+m}C_x + \frac{m}{n+m}C_y = C_z$.

Since C_z, C_x, C_y and $\frac{1}{n+m}K_z, \frac{1}{n}K_x, \frac{1}{m}K_y$ share the same non-zero eigenvalues respectively, the divergence can be directly computed from samples in the input space as follows.

Proposition 2. The empirical kernel-based RJSD estimator for a kernel κ is

$$\widehat{D}_{JS}^{\kappa}(\boldsymbol{X},\boldsymbol{Y}) = S\left(\frac{1}{n+m}\boldsymbol{K}_{\boldsymbol{Z}}\right) - \left(\frac{n}{n+m}S\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}}\right) + \frac{m}{n+m}S\left(\frac{1}{m}\boldsymbol{K}_{\boldsymbol{Y}}\right)\right).$$
(6)

This estimator, however, presents an upward bias that causes an undesired effect. The kernel RJSD estimator can be trivially maximized when the sample's similarities are negligible, for example, when the kernel bandwidth σ in a Gaussian kernel is close to zero (see Fig. 1(a)). This behavior is caused by the discrepancy between the number of samples used to estimate $S(\frac{1}{n+m}K_z)$ compared to $S(\frac{1}{n}K_x)$, and $S(\frac{1}{m}K_y)$, which causes $S(\frac{1}{n+m}K_z)$ to grow faster and up to $\log(n+m)$ compared to $S(\frac{1}{n}K_x)$ and $S(\frac{1}{m}K_y)$ that can only grow up to $\log(n)$ and $\log(m)$ respectively. To reduce the bias of the estimator in Eqn. 6 and avoid trivial maximization, we need to regularize $S(\frac{1}{n+m}K_z)$ so that it estimates up to similar values of entropy than $S(\frac{1}{n}K_x)$ and $S(\frac{1}{m}K_y)$. We propose the following alternative:



Figure 1: Comparing RJSD estimators with Gaussian kernel while varying the kernel bandwidth. The figure illustrates the estimated divergences between two Cauchy distributions (d = 1) with Jensen-Shannon divergence (JSD) $JSD = 0.5 \times \log(2)$.

Power Series Expansion Approximation: Let A be a positive semidefinite matrix, such that $||A||_2 \le 1$, where $||A||_2 = \max_i(\lambda_i)$ denotes the spectral or L^2 -norm, (which is the case for all trace-normalized kernel matrices). Then, the following power series expansion converges to $\log(A)$ [Higham, 2008]:

$$\log(\mathbf{A}) = -\sum_{j=1}^{\infty} \frac{(\mathbf{I} - \mathbf{A})^j}{j}.$$

We propose approximating the logarithm by truncating this series to a lower order.

Proposition 3. The power-series kernel entropy estimator of X is:

$$S_p(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}}) = \sum_{j=1}^p \frac{1}{j} \operatorname{Tr}\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}} \left(\boldsymbol{I} - \frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}}\right)^j\right),\tag{7}$$

where p is the order of the approximation.

Proposition 4. The power-series RJSD estimator is

$$\widehat{D}_{pJS}^{\kappa}(\boldsymbol{X},\boldsymbol{Y}) = S_p\left(\frac{1}{n+m}\boldsymbol{K}_{\boldsymbol{Z}}\right) - \left(\frac{n}{n+m}S_p\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}}\right) + \frac{m}{n+m}S_p\left(\frac{1}{m}\boldsymbol{K}_{\boldsymbol{Y}}\right)\right).$$

This approximation has two purposes. First, it avoids the need for eigenvalue decomposition. Second, it indirectly regularizes the three entropy terms of the divergence, where K_z is regularized more

strongly due to its larger size. For example,
$$S_p(\mathbf{K}_z) \leq \sum_{j=1}^p \frac{1}{j} (1 - \frac{1}{n+m})^j$$
 while $S_p(\mathbf{K}_x) \leq \sum_{j=1}^p \frac{1}{j} (1 - \frac{1}{n+m})^j$

$$\sum_{j=1}^{p} \frac{1}{j} (1 - \frac{1}{n})^{j} \text{ and } S_{p}(\boldsymbol{K}_{\boldsymbol{Y}}) \leq \sum_{j=1}^{p} \frac{1}{j} (1 - \frac{1}{m})^{j}.$$

By increasing the order, the gap between the maximum entropies obtained by the three entropy terms grows, leading to the behavior discussed above. Truncating the power series helps avoid trivial maximization of the divergence at lower kernel bandwidths (see Fig. 1(b)). Consequently, the RJSD power series expansion offers a more robust estimator that goes beyond reducing computational costs.

Next, we show an important connection between the power-series RJSD estimator and MMD:

Theorem 3. Assume(A1) and let p = 1 be the order of the power series expansion approximation. Then, given two sets of samples $\mathbf{X} = {\{\mathbf{x}_i\}}_{i=1}^n \sim P$ and $\mathbf{Y} = {\{\mathbf{y}_i\}}_{i=1}^n \sim Q$:

$$\widehat{D}_{pJS}^{\kappa}(\boldsymbol{X},\boldsymbol{Y}) = \frac{1}{4}\widehat{\mathrm{MMD}}_{\kappa^2}^2(\boldsymbol{X},\boldsymbol{Y})$$

Proof: See Appendix A.2.

This theorem establishes that RJSD extends MMD to higher-order statistics of the kernel matrices and the covariance operator. While MMD captures second-order interactions of data projected in the reproducing kernel Hilbert space (RKHS) defined by the kernel function κ , RJSD incorporates higher-order statistics, enhancing the measures' sensitivity to subtle distributional differences.

4 Two-sample Testing with RJSD

We evaluate the discriminatory power of RJSD for two-sample testing. Given two sets of samples, $X = \{x_i\}_{i=1}^n$ and $Y = \{y_i\}_{i=1}^m$, drawn from P and Q respectively, two-sample testing aims to determine whether P and Q are identical. The null hypothesis H_0 states P = Q, while the alternative hypothesis H_1 states $P \neq Q$. A hypothesis test is then performed, rejecting the null hypothesis if $\mathbb{D}(P,Q) > \varepsilon$ for some distance or divergence \mathbb{D} and threshold $\varepsilon > 0$.

Let $Z = \{z_i\}_{i=1}^{n+m} = \{x_1, \dots, x_n, y_1, \dots, y_m\}$ be the combined sample. One common approach to perform two-sample testing is through permutation tests. These tests apply permutations of the combined data Z to approximate the distribution of the divergence measurement under the null hypothesis. Finally, this distribution determines the rejection threshold ε according to some specified significance level. In this experiment, we employ RJSD as the divergence measure to perform hypothesis testing.

Taking inspiration from 3 well-known MMD-based tests, we designed RJSD-based versions of MMD-Split [Sutherland et al., 2016], MMD-Deep [Liu et al., 2020], and MMD-Fuse [Biggs et al., 2024]. **RJSD-Split** involves splitting the data into training and testing sets to identify the optimal kernel bandwidth on the training set and subsequently evaluate performance on the testing set. Leveraging the lower bound in Eqn. 3, we propose selecting the kernel hyper-parameters that maximize RJSD as these parameters enhance the distinguishability between the two distributions [Sutherland et al., 2016]. Since the kernel-based estimator is not suitable for maximization with respect to the kernel hyper-parameters, we use the power-series RJSD estimator.

Similarly, **RJSD-Deep** involves learning the parameters of the following characteristic kernel $\kappa_{\theta}(x, y)$:

$$\kappa_{\theta}(x, y) = \left[(1 - \epsilon) \kappa_1(f_{\theta}(x), f_{\theta}(y)) + \epsilon \right] \kappa_2(x, y),$$

where $f_{\theta} : \mathcal{X} \to \mathcal{F}$ represents a deep network that extracts features from the data, thereby enhancing the kernel's flexibility and its ability to capture the structure of complex distributions accurately. Here, $0 < \epsilon < 1$, and κ_1 and κ_2 are Gaussian kernels. Ultimately, we learn the network weights, the kernel bandwidths for κ_1 and κ_2 , and the value of ϵ that maximizes RJSD.

On the other hand, **RJSD-Fuse** consists in combining the RJSD estimates of different kernels $\kappa \in \mathcal{K}$ drawn from a distribution $\rho \in \mathcal{M}^1_+(\mathcal{K})$. Then, these different values are passed through a weighted smooth maximum function that considers information from each kernel simultaneously, resulting in a new statistic. The fused statistic with parameter $\lambda > 0$ is defined as:

$$\widehat{\mathsf{FUSE}}_{JS}(\boldsymbol{X},\boldsymbol{Y}) = \frac{1}{\lambda} \log \left(\mathbb{E}_{\kappa \sim \rho} \left[\exp \left(\lambda \widehat{D}_{pJS}^{\kappa}(\boldsymbol{X},\boldsymbol{Y}) \right) \right] \right).$$

This method does not require data-splitting since the optimal kernel is chosen unsupervised through the log-sum-exponential function. See Appendix B.1 for implementation details.

5 Experiments and Results

We evaluate RJSD discriminatory power using one synthetic dataset and two real-world benchmark datasets for two-sample testing. The **Mixture of Gaussians** dataset [Biggs et al., 2024] consists of 2-dimensional mixtures of four Gaussians P and Q with means at $(\pm \mu, \pm \mu)$ and diagonal covariances. All components of P have unit variance, while only three components of Q have unit variance, with the standard deviation σ in the fourth component being varied. The null hypothesis H_0 : P = Q corresponds to the case where $\sigma = 1$. The **Galaxy MNIST** dataset [Walmsley et al., 2022] consists of four categories of galaxy images captured by a ground-based telescope. P represents uniformly



Figure 2: Test Power comparison for different orders of approximation. For the mixture of Gaussians and Galaxy MNIST, we deviate from the null hypothesis for a fixed number of samples of n = m = 500. For CIFAR-10 vs 10.1, we show the boxplot of the distribution of the average test power for different training sets.



Figure 3: Test Power comparison different methods.

sampled images from the first three categories, while Q represents samples drawn from the first three categories with probability 1 - c and from the fourth category with probability $c \in [0, 1]$. We vary the corruption level c, with the null hypothesis corresponding to the case where c = 0. Finally, the **CIFAR 10 vs 10.1** dataset [Liu et al., 2020] compares the distribution P of the original CIFAR-10 dataset [Krizhevsky et al., 2009] with the distribution Q of CIFAR-10.1, which was collected as an alternative test set for models trained on CIFAR-10.

We compare the test power of RJSD-Split, RJSD-Deep, and RJSD-Fuse against various MMD-based tests: data splitting (MMD-Split)[Sutherland et al., 2016], Smooth Characteristic Functions (SCF) [Jitkrittum et al., 2016], the MMD Deep kernel (MMD-Deep) [Liu et al., 2020], Automated Machine Learning (AutoTST) [Kübler et al., 2022], kernel thinning to (Aggregate) Compress Then Test (CTT & ACTT)[Domingo-Enrich et al., 2023], and MMD Aggregated (Incomplete) tests (MMDAgg & MMDAggInc) [Schrab et al., 2023] and MMD-FUSE [Biggs et al., 2024].

5.1 Results

We first investigate the impact of increasing the approximation order p in the power-series expansion on test performance. Fig. 2 illustrates this effect across various datasets and scenarios. For the mixture of Gaussians with a fixed standard deviation $\sigma = 2$ and n = m = 500, we analyze the test power of RJSD-Split as p increases (leftmost). The results indicate a monotonic increase in test power up to a particular order, after which it declines. This pattern was consistently observed across different standard deviations. Similarly, for the Galaxy MNIST (n = m = 500) and CIFAR-10 vs. 10.1 (n = m = 2021) datasets, we evaluate RJSD-Deep with varying approximation orders. The trend was consistent across all scenarios, with higher-order approximations outperforming lower ones. Notably, p = 10 achieved the highest test power in each case. It is important to note that p = 1corresponds to MMD, highlighting that RJSD consistently exhibits superior test power compared to MMD.

Tests	Power
RJSD-Fuse	1.000
MMD-Fuse	0.937
MMD-Agg	0.883
RJSD-Deep	<u>0.868</u>
MMD-Deep	0.744
CTT	0.711
ACTT	0.678
AutoML	0.544
MMD-Split	0.316
MMD-Agg-Inc	0.281
SCF	0.171
Bold: Best approach	

Table 1: Average test power for CIFAR-10 vs. CIFAR-10.1.

Underline: Best data-splitting approach

Fig. 3 compares the test power of various approaches across the tested datasets. In most scenarios, RJSD-Fuse (p = 10) consistently outperforms or matches the performance of state-of-the-art methods like MMD-Fuse and MMD-Agg. Similarly, RJSD-Deep and RJSD-Split also demonstrate superior test power compared to their MMD counterparts in most cases. However, in the Galaxy MNIST dataset, when the sample size is increased, RJSD-Deep leads in performance, while RJSD-Fuse slightly falls behind MMD-Fuse. This discrepancy may be attributed to our estimator's lack of bias correction, which could affect certain cases.

Additionally, Table 1 presents the average power test for CIFAR-10 vs. CIFAR-10.1 computed over ten distinct training sets and 100 testing sets per training set (total of 1000 repetitions). Again, RJSD-Fuse (p = 10) achieves the highest test power, outperforming all other methods. Also, RJSD-Deep achieves the maximum power among data-splitting techniques, significantly surpassing MMD-Deep. These results highlight the robustness and efficacy of RJSD in measuring and detecting differences in distributions, demonstrating its potential as a powerful alternative to MMD for both statistical testing and broader machine-learning applications.

6 Conclusions

In this work, we introduced a novel kernel-based information-theoretic framework for two-sample testing, leveraging the representation Jensen-Shannon divergence (RJSD). We presented a method that extends beyond traditional MMD-based approaches by incorporating higher-order information from kernel matrices. Our framework offers a more robust and flexible measure of divergence between distributions without assuming Gaussianity. Moreover, we developed RJSD-based variants of well-known MMD tests, including MMD-Split, MMD-Deep, and MMD-Fuse, offering more flexible and powerful testing procedures.

Empirical results demonstrate the superior discriminative power of RJSD in two-sample testing tasks, positioning it as a robust alternative to MMD. RJSD's ability to capture more nuanced differences between distributions showcases its potential as a foundational tool for future machine learning research and applications. Given its versatility, ease of estimation from samples, and performance improvements, RJSD holds promise to significantly impact the field of kernel-based learning and contribute to advancing state-of-the-art methodologies in distribution comparison.

Further research is needed to analyze the bias and variance of the representation Jensen-Shannon divergence estimators under both null and alternative hypotheses. This analysis will offer important insights into the reliability of our methods for two-sample testing and lead to more principled approaches to bias correction in our estimators.

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A Appendix / supplemental material

A.1 Proof Lemma 1

Proof. To prove this Lemma, we use (Proposition 4.e) in Bach [2022]. We have that

$$D_{KL}(C_P, C_Q) \ge \frac{1}{2} \|C_P - C_Q\|_*^2 \ge \frac{1}{2} \|C_P - C_Q\|_{\mathrm{HS}}^2,$$

where D_{KL} is the kernel Kullback-Leibler divergence and $\|\cdot\|_*$ and $\|\cdot\|_{HS}$ denote the nuclear and Hilbert-Schmidt norms respectively. Let $C_M = \frac{C_P + C_Q}{2}$, then:

$$D_{JS}(C_P, C_Q) = \frac{1}{2} D_{KL}(C_P, C_M) + \frac{1}{2} D_{KL}(C_P, C_M)$$

$$\geq \frac{1}{4} \left\| C_P - \frac{1}{2} (C_P + C_Q) \right\|_*^2 + \frac{1}{4} \left\| C_Q - \frac{1}{2} (C_P + C_Q) \right\|_*^2$$

$$\geq \frac{1}{4} \left\| \frac{1}{2} C_P - \frac{1}{2} C_Q \right\|_*^2 + \frac{1}{4} \left\| \frac{1}{2} C_Q - \frac{1}{2} C_P \right\|_*^2 = \frac{1}{8} \left\| C_P - C_Q \right\|_*^2$$

and thus, $D_{JS}(C_P, C_Q) \geq \frac{1}{8} \|C_P - C_Q\|_*^2 \geq \frac{1}{8} \|C_P - C_Q\|_{\text{HS}}^2$. Now, let $\phi : \mathcal{X} \mapsto \mathcal{H}$ then, and $\{e_\alpha\}$ be an orthonormal basis in \mathcal{H} , we have that

$$\begin{aligned} \operatorname{Tr}\left(\phi(x)\otimes\phi(x)\phi(y)\otimes\phi(y)\right) &= \sum_{\alpha}\langle\phi(x)\otimes\phi(x)\phi(y)\otimes\phi(y)e_{\alpha},e_{\alpha}\rangle\\ &= \sum_{\alpha}\langle\phi(x)\langle\phi(x),\phi(y)\otimes\phi(y)e_{\alpha}\rangle,e_{\alpha}\rangle\\ &= \sum_{\alpha}\langle\phi(x)\langle\phi(x),\phi(y)\langle\phi(y),e_{\alpha}\rangle,e_{\alpha}\rangle\\ &= \sum_{\alpha}\langle\phi(x)\langle\phi(x),\phi(y)\rangle\langle\phi(y),e_{\alpha}\rangle,e_{\alpha}\rangle\\ &= \sum_{\alpha}\langle\phi(x),e_{\alpha}\rangle\langle\phi(x),\phi(y)\rangle\langle\phi(y),e_{\alpha}\rangle\\ &= \langle\phi(x),\phi(y)\rangle\sum_{\alpha}\langle\phi(x),e_{\alpha}\rangle\langle\phi(y),e_{\alpha}\rangle = \langle\phi(x),\phi(y)\rangle\langle\phi(x),\phi(y)\rangle\\ &= \langle\phi(x),\phi(y)\rangle^{2} = \kappa(x,y)^{2}\end{aligned}$$

Note that for $T: \mathcal{H} \mapsto \mathcal{H}$, $\operatorname{Tr}(T^*T) = \sum_{\alpha} \langle Te_{\alpha}, Te_{\alpha} \rangle = ||T||_{\mathrm{HS}}^2$. In particular, if we have that $T = \phi(x) \otimes \phi(x) - \phi(y) \otimes \phi(y)$,

$$\begin{split} \|\phi(x) \otimes \phi(x) - \phi(y) \otimes \phi(y)\|_{\mathrm{HS}}^2 &= \mathrm{Tr}(\phi(x) \otimes \phi(x)\phi(x) \otimes \phi(x)) - 2 \operatorname{Tr}(\phi(x) \otimes \phi(x)\phi(y) \otimes \phi(y)) \\ &+ \operatorname{Tr}(\phi(y) \otimes \phi(y)\phi(y) \otimes \phi(y)) \\ &= \kappa^2(x, x) - 2\kappa^2(x, y) + \kappa^2(y, y) \end{split}$$

Finally, note that

$$\begin{split} \|C_P - C_Q\|_{\mathrm{HS}}^2 &= \mathrm{Tr}(\mathbb{E}_P[\phi(x) \otimes \phi(x)]\mathbb{E}_{P'}[\phi(x) \otimes \phi(x)]) - 2\,\mathrm{Tr}(\mathbb{E}_P[\phi(x) \otimes \phi(x)]\mathbb{E}_Q[\phi(y) \otimes \phi(y)]) \\ &+ \mathrm{Tr}(\mathbb{E}_Q[\phi(y) \otimes \phi(y)]\mathbb{E}_{Q'}[\phi(y) \otimes \phi(y)]) \\ &= \mathrm{Tr}(\mathbb{E}_{P,P'}[\phi(x) \otimes \phi(x)\phi(x') \otimes \phi(x')]) - 2\,\mathrm{Tr}(\mathbb{E}_{P,Q}[\phi(x) \otimes \phi(x)\phi(y) \otimes \phi(y)]) \\ &+ \mathrm{Tr}(\mathbb{E}_{Q,Q'}[\phi(y) \otimes \phi(y)\phi(y') \otimes \phi(y')]) \\ &= \mathbb{E}_{P,P'}[\kappa^2(x,x')] - 2\mathbb{E}_{P,Q}[\kappa^2(x,y)] + \mathbb{E}_{Q,Q'}[\kappa^2(y,y')], \end{split}$$

which corresponds to squared MMD with kernel $\kappa^2(\cdot,\cdot).$



Figure 4: Mixture of Gaussians and Galaxy MNIST datasets.

A.2 Proof Theorem 3

Proof.

$$\begin{split} \widehat{D}_{pJS}^{\kappa}(\boldsymbol{X},\boldsymbol{Y}) &= \operatorname{Tr}\left(\frac{1}{2n}\boldsymbol{K}_{\boldsymbol{Z}}(\boldsymbol{I}-\frac{1}{2n}\boldsymbol{K}_{\boldsymbol{Z}})\right) - \frac{1}{2}\operatorname{Tr}\left(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}}(\boldsymbol{I}-\frac{1}{n}\boldsymbol{K}_{\boldsymbol{X}})\right) - \frac{1}{2}\operatorname{Tr}\left(\boldsymbol{I}-\frac{1}{n}\boldsymbol{K}_{\boldsymbol{Y}}(\frac{1}{n}\boldsymbol{K}_{\boldsymbol{Y}})\right) \\ &= -\operatorname{Tr}\left(\frac{1}{4n^{2}}\boldsymbol{K}_{\boldsymbol{Z}}\boldsymbol{K}_{\boldsymbol{Z}}\right) + \frac{1}{2}\operatorname{Tr}\left(\frac{1}{n^{2}}\boldsymbol{K}_{\boldsymbol{X}}\boldsymbol{K}_{\boldsymbol{X}}\right) + \frac{1}{2}\operatorname{Tr}\left(\frac{1}{n^{2}}\boldsymbol{K}_{\boldsymbol{Y}}\boldsymbol{K}_{\boldsymbol{Y}}\right) \\ &= -\frac{1}{4n^{2}}\|\boldsymbol{K}_{\boldsymbol{Z}}\|_{F}^{2} + \frac{1}{2n^{2}}\|\boldsymbol{K}_{\boldsymbol{X}}\|_{F}^{2} + \frac{1}{2n^{2}}\|\boldsymbol{K}_{\boldsymbol{Y}}\|_{F}^{2} \\ &= -\frac{1}{4n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{z}_{i},\boldsymbol{z}_{j}) + \frac{1}{2n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{x}_{i},\boldsymbol{x}_{j}) + \frac{1}{2n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{y}_{i},\boldsymbol{y}_{j}) \\ &= \frac{1}{4n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{x}_{i},\boldsymbol{x}_{j}) + \frac{1}{4n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{y}_{i},\boldsymbol{y}_{j}) - \frac{2}{4n^{2}}\sum_{i,j}^{n}\kappa^{2}(\boldsymbol{x}_{i},\boldsymbol{y}_{j}) \\ &= \frac{1}{4}\widehat{\mathrm{MMD}}_{\kappa^{2}}^{2}(\boldsymbol{X},\boldsymbol{Y}) \end{split}$$

B Two-sample testing implementation details

B.1 RJSD-Fuse

Biggs et al. [2024] proposes MMD-Fuse, which computes a weighted smooth maximum of different MMD values from different kernels $\kappa \in \mathcal{K}$ drawn from a distribution $\rho \in \mathcal{M}^1_+(\mathcal{K})$. The proposed statistic is defined as:

$$\widehat{\text{FUSE}}_{MMD}(\boldsymbol{X}, \boldsymbol{Y}) = \frac{1}{\lambda} \log \left(\mathbb{E}_{\kappa \sim \rho} \left[\exp \left(\lambda \frac{\widehat{\text{MMD}}_{\kappa}^{2}(\boldsymbol{X}, \boldsymbol{Y})}{N_{\kappa}(\boldsymbol{Z})} \right) \right] \right).$$

Here, the different MMD estimates are normalized by a permutation invariant factor $N_{\kappa}(\mathbf{Z}) := \sqrt{\frac{1}{n \times (n-1)} \sum_{i \neq j} \kappa(z_i, z_j)^2}$ to account for the different scales and variances of distinct kernels before computing the "maximum". To include this term within our approach, instead of normalizing the divergence estimates, we normalize the kernels by $N_{\kappa}(\mathbf{Z})$, which in the case of p = 1 is equivalent to MMD-Fuse. That is:



(a) CIFAR 10

(b) CIFAR-10.1

Figure 5: CIFAR 10 vs 10.1 images.



Figure 6: L^2 distance distribution for the mixture of Gaussians and RJSD estimates for ten different bandwidths tested.

$$\hat{D}_{pJS}^{\mathcal{H}}(P,Q) = S_p\left(\frac{1}{n+m}\frac{\mathbf{K}_{\mathbf{Z}}}{\sqrt{N_{\kappa}(\mathbf{Z})}}\right) - \left(\frac{n}{n+m}S_p\left(\frac{1}{n}\frac{\mathbf{K}_{\mathbf{X}}}{\sqrt{N_{\kappa}(\mathbf{Z})}}\right) + \frac{m}{n+m}S_p\left(\frac{1}{m}\frac{\mathbf{K}_{\mathbf{Y}}}{\sqrt{N_{\kappa}(\mathbf{Z})}}\right)\right).$$

Notice that for p = 1, this is equivalent to MMD-Fuse, where the measurement is normalized. However, normalizing the kernel allows the normalization to account for higher-order interactions between the kernel matrices for p > 1.

Distribution over kernels: Similarly to MMD-Fuse, we use a collection of Laplacian $\kappa_{\sigma}^{l}(x, x') = \exp\left(-\frac{\|x-x'\|_{1}^{2}}{\sigma}\right)$ and Gaussian $\kappa_{\sigma}^{g}(x, x') = \exp\left(-\frac{\|x-x'\|_{2}^{2}}{2\sigma^{2}}\right)$ kernels with distinct bandwidths $\sigma > 0$. In our implementation, we choose the bandwidths as the 5%, 15%, 25%, ... 95% quantiles of $\{\|z-z'\|_{r}: z, z' \in \mathbb{Z}\}$, with $r \in 1, 2$ for the Laplace and Gaussian kernels respectively. This choice is similar to MMD-Fuse, where ten bandwidths per kernel type are also selected. See Fig. 6.

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