# CTRAIN - A Training Library for Certifiably Robust Neural Networks

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**Abstract.** Despite their widespread success, neural networks are susceptible to adversarial examples, severely limiting their responsible deployment in safety-critical scenarios. To address this, neural network verification techniques have been proposed that rigorously prove the robustness of a given network against specific threats. However, the scalability of these methods remains a major challenge, with networks trained for empirical robustness still proving difficult to verify. Thus, certified training has been proposed to produce networks more amenable to formal robustness verification. However, there is currently no comprehensive framework allowing easy access to these training methods. To address this, we introduce CTRAIN, a new Python library built upon the auto\_LiRPA package, which reimplements state-of-the-art certified training methods in a unified, modular and comprehensive manner, while offering user-friendly interfaces, enhancing accessibility for both researchers and practitioners. Additionally, CTRAIN integrates SMAC3 for hyperparameter optimisation and  $\alpha\beta$ -CROWN for complete verification, empowering users to exploit these systems to achieve state-of-the-art certified robustness. We provide code, documentation, examples and usage instructions at github.com/ada-research/CTRAIN.

## 1 Introduction

In recent years, neural networks have shown remarkable performance across various application domains, ranging from computer vision [8] to protein structure prediction [13]. At the same time, it became evident that neural networks are typically not robust, as adversarially crafted, yet imperceptible, changes in the input can lead to to incorrect predictions [35]. This circumstance severely limits the responsible deployment of machine learning models in safety-critical use cases. To mitigate this issue, neural network verification techniques have been proposed, which provide provable robustness guarantees using rigorous mathematical frameworks [14, 36]. Generally, these can be divided into two families; cheap incomplete methods attempt to solve the robustness verification problem by bounding the outputs of a network, but may not be able to prove a property due to overly loose bounds. Complete methods will, in principle, always return a result but have to solve an expensive  $\mathcal{NP}$ -complete problem [32, 19]. Despite

several algorithmic advancements, e.g., the inclusion of sophisticated network over-approximations [5, 29, 34, 38, 43] or search techniques [3], the scalability of complete verification remains a major challenge.

Concurrently, specialised training methods were developed that aim to produce robust neural networks. While state-of-the-art empirical robustness can be achieved using adversarial training (see, e.g., [22, 41]), the resulting networks remain hard to verify. Thus, there has been a surge of training methods that yield robust neural networks amenable to formal verification, therefore mitigating the challenge of limited scalability, giving rise to the concept of certified training [26, 11]. These methods employ an over-approximation of the worst case adversarial loss using cheap incomplete robustness verification methods as the training objective to be minimised. Several certified loss functions leveraging this concept have been proposed, gradually advancing the state-of-the-art regarding the number of input samples for which the resulting networks are provably robust [6, 11, 24, 28, 33]. However, the community to date lacks a comprehensive library that makes these techniques accessible to potentially inexperienced end users.

Therefore, we propose CTRAIN, an extensive Python library for certified training. We provide, for the first time, implementations of all current state-of-the-art methods, based on the popular neural network bounding library auto-Lirpa [39], and make these accessible via a Python package. Further, CTRAIN provides user-friendly interfaces to certifiably train neural networks based on the PyTorch framework [30]. Therefore, CTRAIN easily integrates into existing PyTorch training pipelines, neural network architecture specifications and datasets. Furthermore, we natively support sophisticated hyperparameter optimisation for certified training via the state-of-the-art optimiser SMAC3 [21]. Last but not least, CTRAIN includes several possibilities for robustness evaluation using adversarial attacks, incomplete verification and the state-of-the-art complete neural network verification system  $\alpha\beta$ -CROWN [38, 40, 44].

# 2 Related Work

In the following, we provide an overview of work related to CTRAIN, focusing on tools that provide functionalities for training robust neural networks. To date, several easy-to-use and performant libraries have been proposed that implement adversarial training methods. Among these, the Adversarial Robustness Toolbox (ART) [37] and DeepRobust [20] constitute the most extensive and popular libraries, having accumulated over five thousand and one thousand stars on GitHub, respectively. These stars allow users to indicate interest in a repository and to bookmark it. Both implement multiple adversarial training methods, e.g., training for robustness on examples created through the Projected Gradient Descent (PGD) method [22], a strong iterative adversarial attack. However, these libraries lack proper support for methods that focus on producing easily verifiable networks. Specifically, ART only supports early advancements from the field

 $<sup>^{1}</sup>$  github.com/Trusted-AI/adversarial-robustness-toolbox

<sup>&</sup>lt;sup>2</sup> github.com/DSE-MSU/DeepRobust

that do not constitute the state of the art anymore [11, 26], while DeepRobust implements no certified trainings method at all.

Recently, CTBench, a novel and unified library for certified training, has been proposed [23]. CTBench implements several state-of-the-art protocols, including SABR [28] and MTL-IBP [6], and the authors reported very strong results using their implementation. Nonetheless, CTBench cannot be easily integrated into existing code, since it relies on independent training scripts, and a Python package providing convenient options for running the CTBench training code does not exist. In addition, CTBench employs the verification system MN-BaB [10] to evaluate the certifiable robustness of trained neural networks, which has been shown to be consistently outperformed by  $\alpha\beta$ -CROWN [38, 40, 44] in recent studies and competitions [15, 27]. While we acknowledge the importance of CTBench, we believe that researchers as well as end users will profit from easy-to-use alternative implementations based on the popular auto\_LiRPA library. In addition, we believe that the use of  $\alpha\beta$ -CROWN will lead to more precise assessments of certified training methods.

## 3 Overview of CTRAIN

In the following, we describe the key components and features of the CTRAIN library, including supported certified training methods, affordances for evaluating the empirical and certified robustness of neural networks, and native support for hyperparameter optimisation of certified training methods.

## 3.1 Certified Training with CTRAIN

Selected Certified Training Methods. CTRAIN implements several state-of-the-art algorithms for certified training. In selecting these, we focused on methods that provide deterministic robustness guarantees against all possible perturbations included in the  $l_{\infty}$  norm balls with radius  $\epsilon$  around input images. These perturbations constitute the properties typically examined in the neural network verification literature (see, e.g., [2,15]). Furthermore, we excluded methods that rely on non-standard neural network components not natively supported by the PyTorch library [30].

The best-peforming losses for deterministic certified training are based on Interval Bound Propagation (IBP) [11], the conceptually simplest incomplete verification method. IBP employs interval arithmetic to bound the outputs of a neural network which, in turn, can be used to calculate a sound upper bound of the worst-case loss on adversarial examples. The closely related *CROWN-IBP* [42] relies on the tighter bounding method CROWN [44] in combination with IBP to improve on standard IBP-based certified training. Shi et al. [33] propose further improvements to IBP through an initialisation procedure and loss regularisers that are specifically crafted to stabilise certified training.

Recently, significant advancements have been made by combining PGD-based adversarial training with IBP-based certified training. Those methods rely on

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unsound approximations of the worst-case adversarial loss, but yield strongly improved performance. SABR [28] uses PGD to identify adversarial examples in the  $l_{\infty}$  norm ball around the training instance, which are in turn used as the centre of a smaller norm ball. This smaller input region is then employed in standard IBP bounding to obtain the overall training loss. TAPS [24] combines adversarial and certified training by first propagating an input region through the feature extractor of a network using IBP, and by then adversarially training the classifier using latent adversarial examples that lie in the output region of the feature extractor. STAPS [24] works similarly to TAPS, but uses SABR instead of IBP to obtain intermediate bounds. Finally, MTL-IBP [6] is a representative member of the family of expressive losses, i.e., losses that combine adversarial and certified losses through convex combinations. The MTL-IBP loss consists of the weighted sum of the certified loss obtained using IBP and the PGD-based adversarial loss.

In CTRAIN, we have included all previously mentioned certified training methods, *i.e.*, IBP, CROWN-IBP, SABR, TAPS, STAPS and MTL-IBP, ensuring comprehensive coverage of established approaches. This selection provides users with a diverse and relevant set of techniques, since methods combining adversarial and certified losses have shown the strongest results in recent literature and thus constitute the state-of-the-art (see, *e.g.*, [6, 23, 25]). While standard IBP and CROWN-IBP training was surpassed performance-wise, they remain the most computationally efficient and, thus, represent viable alternatives when potent hardware is not available.

Key Features of CTRAIN. In CTRAIN we provide, for the first time, an unified implementation of the state-of-the-art in certified training based on the auto\_Lirpa [39] library. This package serves as the backbone of the state-of-the-art verification tool  $\alpha\beta$ -CROWN [40, 38], is actively maintained, implements a variety of incomplete verification techniques and is popular among the neural network verification community, testified by over 250 GitHub stars<sup>3</sup>. Furthermore, it provides extensive support for many popular network architectures, ranging from convolutional networks to transformers.

In CTRAIN, we implemented the previously mentioned certified training methods closely following the original literature and codebases, but reimplemented all relevant parts of certified training in a modular and highly configurable fashion. Furthermore, we unified varying implementations of network bounding, loss calculation and adversarial attacks into one comprehensive code base. Therefore, CTRAIN enhances comparability between methods by standardising their shared components, such as IBP bounding or regularisation. Additionally, all components of CTRAIN are implemented using PyTorch [30]; thus, the package integrates well into common machine learning pipelines and PyTorch components such as optimisers, regularisers, and data augmentations can be seamlessly incorporated.

<sup>&</sup>lt;sup>3</sup> github.com/Verified-Intelligence/auto LiRPA

#### 3.2 Evaluation

To assess whether the network actually adheres to desired robustness properties, users require easy and extensive possibilities to evaluate neural networks regarding their certified and empirical robustness, which CTRAIN provides. Notably, CTRAIN can also be used to evaluate models that were trained outside of its training workflow and, thus, also represents a valuable tool for users that do only desire to use the evaluation capabilities of CTRAIN.

Empirical Robustness. To evaluate the robustness of a given network against adversarial attacks, we implemented the PGD attack [22], which to date is the de-facto standard method to assess empirical robustness. For example, state-of-the-art verification tools such as  $\alpha\beta$ -CROWN [38] or MN-BaB [10] use this attack to identify counter-examples.

Incomplete Verification To give provable guarantees of the robustness of neural networks, CTRAIN implements several incomplete verification methods using auto\_Lirpa. More specifically, the incomplete bounding methods IBP [11], CROWN-IBP [42] and CROWN [43] are included. These methods differ in the tightness of the network bounds they compute, but also in their computational complexity. IBP is the cheapest and loosest incomplete method, CROWN-IBP gives tighter bounds at the cost of increased computational costs, and CROWN is the tightest and most expensive method. Users can decide whether all inputs that should be investigated are verified using one method, or whether verification is performed in an adaptive fashion. In the latter case, the supported methods are progressively applied to input samples in increasing order of their computational costs. Therefore, easy verification problems are solved with cheap methods, while computationally expensive methods are only applied to problems where their tightness is required to obtain a solution (see, e.g., [6, 23]).

Complete Verification Finally, CTRAIN also provides an interface to the state-of-the-art complete verification system  $\alpha\beta$ -CROWN. Complete verification provides the most accurate assessment of the certified robustness of a given network at the cost of significantly increased computational requirements. Especially, networks trained using recent methods based on surrogate losses, require complete verification to obtain precise robustness measurements [6, 28].

To save computational resources, CTRAIN first attempts to obtain a solution to the verification query by applying its included incomplete verification techniques and by running the PGD adversarial attack, before invoking  $\alpha\beta$ -CROWN [6, 23].

## 3.3 Hyperparameter Optimisation

All certified training methods are parametrised by a extensive and diverse set of hyperparameters, such as the number of  $\epsilon$ -annealing epochs or the settings of the PGD attack. Furthermore, the values chosen for those parameters influence the training outcome strongly, ranging from training collapse to state-of-the-art results. Recent works tackle the hyperparameter optimisation problem by employing manual [6] or grid search [23] over an expert-designed configuration

space. In any case, these approaches to hyperparameter tuning for certified training currently require extensive domain knowledge to identify suitable parameter choices. To mitigate this prerequisite and to therefore make hyperparameter tuning more accessible to potentially inexperienced practitioners, CTRAIN implements preconfigured hyperparameter optimisation as one of its core components.

We employ the state-of-the-art hyperparameter optimisation system SMAC3 [21] for the tuning task, since it has demonstrated remarkable performance across various recent benchmarks [9, 31]. For each of the implemented certified training methods, we provide a configuration space, out of which SMAC3 attempts to find the best-performing configuration. Thus, when using CTRAIN, users do not require domain knowledge to achieve state-of-the-art results on novel datasets for which no well-performing configurations are known.

By default, CTRAIN aims to optimise the sum of natural, certified and adversarial accuracy, since all of these metrics represent desirable properties of a certifiably trained neural network, *i.e.* strong performance on natural and adversarial inputs and easy verifiability. Nevertheless, the accuracy values that should be included in the optimisation objective can be weighted according to user preferences. To keep the evaluation overhead manageable, these values are by default computed on the first 1000 samples of the validation dataset, using *CROWN*.

The CTRAIN hyperparameter optimisation procedure begins by exploring the search space through a random search for the number of iterations determined by the number of hyperparameters in the configuration space. Compared to the default of SMAC3, we limit this number, to avoid overspending on random configurations, since training and evaluation is costly. In addition, CTRAIN allows users to specify a pre-defined configuration, which is assumed to performing well. This modification to the SMAC3 optimisation procedure facilitates the exploitation of expert user knowledge. Subsequently, CTRAIN continues with the optimisation procedure until the budget is exhausted.

## 4 Implementation

In the following, we explain the architectural details and implementation of the CTRAIN library, highlighting its modular and well-structured design as well as its easy usability.

First and foremost, we designed CTRAIN as a Python library that can easily be installed and set up using package management tools such as pip. Furthermore, we made sure that CTRAIN seamlessly integrates into common machine learning workflows without the need to run separate scripts or to set up different environments. We implemented CTRAIN in Python 3, currently using torch in version 2.2.2 and auto\_LiRPA in version 0.50 as its core libraries. Our implementation can be accessed at github.com/ada-research/CTRAIN.

CTRAIN.model\_wrappers. As a result of our considerations for the design of CTRAIN, we provide a package implementing *model wrappers* that can be easily included into existing code. These wrappers encapsulate predefined or pretrained neural networks and expose core functionalities in an accessible manner.

Code Example 4.1. CTRAIN is easy to use for certifiably training and evaluating neural networks: In twelve lines of code, users can load a dataset, define the standard CNN7 network architecture proposed by Shi et al. [33], certifiably train the network using IBP and evaluate it, using adversarial attacks and incomplete verification.

We show an example of the usage of the model wrappers provided by CTRAIN in Code Example 4.1. For each of the supported training methods, there is one separate wrapper. These objects take the neural network, which must inherit from the PyTorch nn.Module class, the perturbation magnitude  $\epsilon$  that defines the training and verification objectives, and the method-specific training hyperparameters as arguments. Since using a higher  $\epsilon$  during training compared to evaluation might be beneficial (see, e.g., [6,42]), users can define a multiplier to scale the training  $\epsilon$ . Training is invoked via the train\_model function, while an evaluation of natural, robust and certified performance can be carried out using the evaluate or evaluate\_complete functions, respectively. The hyperparameter optimisation procedure is implemented in the hpo function, for which an optimisation budget should be provided that specifies for how long the optimisation procedure runs. Furthermore, the user may pass a default configuration to be investigated during the optimisation process.

The model\_wrappers package is easily extensible, since all wrappers inherit from the common base class CTRAINWrapper, which implements method-independent functionalities such as evaluation, checkpoint saving and hyperparameter optimisation. In addition, it was of paramount importance for CTRAIN to be compatible with common PyTorch operations. Therefore, the base class inherits from the nn.Module class and, thus, all wrappers can be used in existing training and evaluation workflows.

CTRAIN.bound. The bound module implements all bounding operations required during training and incomplete verification, based on the auto\_LiRPA package. More specifically, it implements the sound bounding operations IBP, CROWN-IBP and CROWN as well as the unsound SABR and TAPS bounds.

CTRAIN.data. Although CTRAIN is fully compatible with standard PyTorch data loaders, we provide functions that load the common vision datasets MNIST [18], CIFAR-10 [16] and TinyImageNet [17].

CTRAIN.eval. The eval package provides all functions required to evaluate standard, robust and certified accuracy of neural networks, including functions to carry out incomplete and complete verification as well as adversarial attacks. Generally, all evaluation methods require the user to pass the network that should be evaluated, the perturbation magnitude  $\epsilon$  and a data loader, which holds the inputs for which the robustness should be assessed. Since the evaluation procedure may be costly, especially when employing complete verification, users may also provide a number of samples for which the evaluation is carried out in the given order of the evaluation set. To utilise complete verification, users must pass, in addition to the arguments generally required for evaluation, the allowed maximum running time per verification query and the number of CPU cores  $\alpha\beta$ -CROWN may utilise. In addition, a dictionary including configuration values for  $\alpha\beta$ -CROWN that adhere to its documentation may be provided.

CTRAIN.complete\_verification. Since  $\alpha\beta$ -CROWN is not intended to be executed directly from external libraries or codebases, CTRAIN implements several steps to ensure seamless integration in its abCROWN subpackage. First, CTRAIN exports the network in ONNX format [1] and saves the resulting file to a temporary folder. Then, it formulates the verification property in the standardised VNN-LIB format [7] and also saves the resulting file. Thereafter, CTRAIN generates a configuration file for  $\alpha\beta$ -CROWN that specifies the cutoff time and further parameters set by the user as well as the verification property, defined through the previously generated ONNX and VNN-LIB files. Finally, CTRAIN invokes  $\alpha\beta$ -CROWN by calling the function that serves as the entry point of the verification system, passing along the configuration file.

CTRAIN.attacks. CTRAIN currently only implements the PGD adversarial attack, which is used in several training losses as well as in the empirical robustness evaluation. We have made the parameters of the attack, *i.e.*, the number of restarts, the number of steps and the step size, configurable. Furthermore, users can define decay milestones at which the step size is reduced by a specified factor. When PGD attacks are involved in training, we set the network to evaluation mode when carrying out the attacks, while the loss computation based on the obtained adversarial examples is done in training mode. Therefore, the statistics of batch normalisation layers [12] are not influenced by the forward and backward passes performed during attacks and employ the mean and variance computed over both unperturbed and perturbed inputs at evaluation time.

CTRAIN.model\_definitions. While CTRAIN is, in principle, compatible with a broad range of neural network definitions, models proposed by Shi et al. [33] emerged as the *de-facto* standard architectures for evaluating certified training methods on (see, *e.g.*, [6, 23, 28]). We provide model definitions of these networks in the model\_definitions package.

CTRAIN.train.certified. This package implements all components of certified training in a functional manner. In the subpackage losses, we provide functions

for calculating the various supported certified losses. The initialisation and regularisation packages provide implementations of the procedures proposed by Shi et al. [33] as well as an implementation of  $l_1$  regularisation. Finally, we have implemented each supported certified training method as one separate function that is utilised in the respective model wrappers.

CTRAIN.util. Finally, we have implemented utility functions, such as seeding the library or exporting networks to ONNX, in the util package.

## 5 Conclusions and Future Work

In this work, we presented CTRAIN, a new Python library for certified training. CTRAIN implements several state-of-the-art certified training protocols and makes them accessible via model wrappers that integrate well into existing machine learning workflows based on PyTorch. Furthermore, CTRAIN provides a broad range of evaluation functions that can assess the robustness of a given network using adversarial attacks as well as incomplete and complete verification. Notably, using CTRAIN, it becomes possible to invoke the state-of-the-art complete verification system  $\alpha\beta$ -CROWN using only one function call. Last but not least, CTRAIN has native support for sophisticated hyperparameter optimisation using SMAC3.

In future work, we aim to maintain and further extend the functionalities of CTRAIN. The modular design of the library allows for easy addition of adversarial attack mechanisms, such as AutoAttack [4], or of complete verification systems,  $e.g.,\ Oval$  [5]. Furthermore, we intend to implement further enhancements to certified training, such as ReLU transformer shrinking [28]. In addition, we will perform an extensive empirical evaluation of CTRAIN, comparing its performance to reference implementations from the literature and examining potential improvements achieved through the use of SMAC3 and  $\alpha\beta$ -CROWN. Finally, we plan to continuously update CTRAIN with new certified training and verification methods, maintaining CTRAIN as a state-of-the-art resource for certified training and its evaluation, valuable to both end-users and researchers.

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