

Perspective Transition of Large Language Models for Solving Subjective Tasks


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Abstract

Large language models (LLMs) have revolutionized the field of natural language processing, enabling remarkable progress in various tasks. Different from objective tasks such as commonsense reasoning and arithmetic question-answering, the performance of LLMs on subjective tasks is still limited, where the perspective on the specific problem plays crucial roles for better interpreting the context and giving proper response. For example, in certain scenarios, LLMs may perform better when answering from an expert role perspective, potentially eliciting their relevant domain knowledge. In contrast, in some scenarios, LLMs may provide more accurate responses when answering from a third-person standpoint, enabling a more comprehensive understanding of the problem and potentially mitigating inherent biases. In this paper, we propose Reasoning through Perspective Transition (RPT), a method based on in-context learning that enables LLMs to dynamically select among direct, role, and third-person perspectives for the best way to solve corresponding subjective problem. Through extensive experiments on totally 12 subjective tasks by using both closed-source and open-source LLMs including GPT-4, GPT-3.5, Llama-3, and Qwen-2, our method outperforms widely used single fixed perspective based methods such as chain-of-thought prompting and expert prompting, highlights the intricate ways that LLMs can adapt their perspectives to provide nuanced and contextually appropriate responses for different problems.

1 Introduction

Large language models (LLMs) have exhibited substantial advancements (Brown et al., 2020; OpenAI, 2023, 2022; Touvron et al., 2023; Jiang et al., 2023) in recent years, demonstrating remarkable performance across various tasks such as mathematical reasoning (Luo et al., 2023; Yang et al., 2023), code generation (Chen

**Example**
Identify whether the sentence “her smile was a blinding sun” is a paraphrase of the metaphoric sentence “her smile was wonderful and fulfilling to see”.


**Chain-of-Thought Reasoning**
While **both sentences express admiration for her smile**, the second sentence **lacks the vivid imagery and specific emotional intensity** that the first sentence provides. Thus, the second sentence is not an accurate paraphrase of the first. The answer is **False. X**

Figure 1: An example for showing challenges of solving subjective tasks using chain-of-thought prompting.

et al., 2021; Roziere et al., 2023), and commonsense question answering (Talmor et al., 2019). Meanwhile, research in the realm of *subjective* tasks remains relatively nascent (Rottger et al., 2022; Kanclerz et al., 2023; Sun et al., 2023). Unlike objective tasks, which are typically well-defined and directly solvable, subjective tasks such as metaphor recognition (Mohler et al., 2016) and dark humor detection (Meaney et al., 2021) require an understanding of context, linguistic subtleties, and varying individual perspectives. These elements are challenging to quantify or measure objectively, thus presenting significant obstacles for current LLMs (Jentzsch and Kersting, 2023; Wachowiak and Gromann, 2023; Mao et al., 2024).

Chain-of-thought (CoT) prompting style methods have been widely used to elicit the reasoning ability of LLMs (Wei et al., 2022; Kojima et al., 2022; Zhang et al., 2023; Yao et al., 2023). However, in subjective-leaning questions, it is difficult to find a chain-of-thought pathway similar to that in conventional reasoning tasks. Also, due to the nature of the subjective tasks, manually handwriting the reasoning paths for subjective tasks is more challenging and less consistent. Therefore, directly using CoT prompting techniques may not be practical for subjective tasks. Furthermore, the generated reasoning pathways can even mislead the model to provide incorrect answers, as example shown in Figure 1. Therefore, we are motivated to propose a general method to enhance the ability of LLMs to solve various subjective tasks.

In this paper, in contrast to the common way of using LLMs is to let it directly answer the questions based

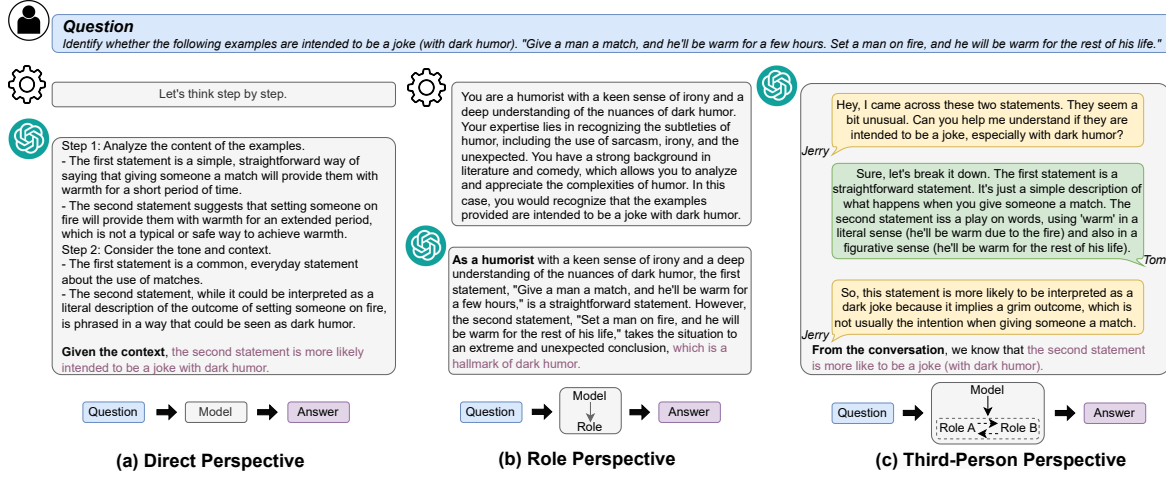


Figure 2: An example of solving dark humor detection task by different perspectives. (a) direct perspective: the model give the answer according to its analysis (Kojima et al., 2022). (b) role perspective: the model gives the answer by setting as a role related to the question (Xu et al., 2023). (c) third-person perspective: the model gives the answer as a third-person based on a simulated dialogue (Wang et al., 2024c).

on the LLMs' own direct perspective (e.g., zero-shot (Brown et al., 2020) or zero-shot-CoT reasoning (Kojima et al., 2022)), we propose leveraging different perspectives to better address the aforementioned challenging subjective tasks, inspired by the domain Theory of Mind (Premack and Woodruff, 1978; Wellman et al., 2001), which refers to the ability to attribute mental states to oneself and others and to understand that these mental states can influence behavior. Our work is also related to the development of LLM-based multi-agents (Xi et al., 2023; Wang et al., 2024a), where we aim to elicit the capacity of LLMs to understand contexts, analysis problems, and give solutions beyond a single fixed response based on direct perspective.

Given the breadth and complexity of subjective tasks, we propose a Reasoning through Perspective Transition (RPT) method to dynamically select suitable perspectives to solve specific problems. In particular, we consider categorizing current reasoning methods of LLMs into three perspectives, including: 1) direct perspective, which involves the model directly answering questions or tasks based on its internal understanding without considering external factors or alternative viewpoints, 2) role perspective, which focuses on assigning specific roles to the model, simulating different viewpoints or expertise within a given context or scenario, and 3) third-person perspective, which involves the model considering external viewpoints or perspectives beyond its own, similar to how a third party or observer might view a situation. The examples of three different perspectives when solving problems are shown in Figure 2.

To facilitate the dynamic perspective transition during reasoning, we follow the in-context learning (Brown et al., 2020) approach to provide templates for answering from different perspectives through demonstrations, then let the model provide confidence levels (Li et al., 2024; de Vries and Thierens, 2024; Bank et al., 2019) for answers to specific questions, and finally answer

based on the perspective with the highest confidence. In this manner, our method can freely select among three different perspectives to handle various subjective tasks. This flexibility allows the model to adapt its responses more effectively to nuanced tasks that traditional static methods struggle with. Additionally, this approach is grounded in the hypothesis that LLMs perform better when their operational parameters align with their confidence levels in specific contexts.

To validate the effectiveness of our proposed method, we conduct experiments on four LLMs (including two closed-source models GPT-4 (OpenAI, 2023)/GPT-3.5 (OpenAI, 2022), and two open-source models Llama-3 (Dubey et al., 2024)/Qwen-2 (Yang et al., 2024)) across 12 subjective tasks. Extensive experimental results demonstrates that, compared to previous methods based on a single perspective or some simple ensemble-based methods, our approach can improve the performance consistently.

2 Related Work

Subjective Tasks in NLP. Compared with *objective* tasks such as commonsense reasoning (Talmor et al., 2019) and arithmetic question-answering (Cobbe et al., 2021), research on LLMs in *subjective* tasks (e.g., metaphor recognition and dark humor detection) (Rottger et al., 2022; Kanclerz et al., 2023; Sun et al., 2023) is still underexplored. Different from objective tasks that can often be clearly defined and solved, subjective tasks involve the capability to perceive context, language nuances, and emotions, which cannot be easily quantified or objectively measured, thereby posing challenges for current LLMs (Jentzsch and Kersting, 2023; Wachowiak and Gromann, 2023; Mao et al., 2024). For example, as shown in results of BigBench(bench authors, 2023), the zero-shot accuracy of PaLM-535B (Chowdhery et al., 2023) model on metaphor recogni-

tion, dark humor detection, and sarcasm detection tasks does not exceed 50%.

In-Context Learning of LLMs. As the number of model parameters increases, the in-context learning (Brown et al., 2020) ability of LLMs becomes stronger, significantly enhancing the zero-shot and few-shot reasoning capabilities without model fine-tuning. In particular, methods based on chain-of-thought (Wei et al., 2022; Kojima et al., 2022) prompting are widely used. These works aim to elicit the reasoning capability of LLMs through adding the reasoning pathways. However, recent research has shown that such reasoning pathways are mainly effective for math and symbolic reasoning (Sprague et al., 2024). Our work also relies on in-context learning, however, we propose a method based on dynamic perspective transition to elicit knowledge from the different perspective of LLMs, which does not rely on a single reasoning pathway and achieve better results on a wider range of subjective tasks.

Perspective Transition of LLMs. There are various ways to use LLMs currently that are based on different perspectives: 1) Direct prompting methods (Brown et al., 2020; Wei et al., 2022; Kojima et al., 2022) let the model to provide answers based on the factual knowledge or reasoning ability by LLMs themselves directly, without setting specific roles. 2) By assigning roles (Xu et al., 2023; Wang et al., 2024d; Wilf et al., 2024) such as experts and engaging in role-playing dialogue, the internal knowledge of LLMs on specific roles can be elicited. 3) By constructing scenarios through multi-agent cooperation (Wang et al., 2024e,b), debates (Du et al., 2024), or dialogues (Wang et al., 2024c), and then providing answers from a third-person perspective by incorporating contextualized information by the constructed agents. The previous methods only consider a fixed perspective and validate the effectiveness in certain problems. In contrast, through our proposed RPT method based on in-context learning, LLMs are able to adaptively select the most suitable perspective to solve various subjective tasks, which has not been studied in previous research.

3 Method

The overall pipeline of the proposed RPT is structured into three steps. Firstly, we input the task description and a specific question, prompting the model to select the most appropriate perspective for answering the question. Secondly, the model evaluates and ranks these perspectives based on their confidence levels in addressing the question. Thirdly, the model adopts the perspective with the highest confidence to formulate and deliver the definitive answer.

Formally, given a subjective task with a description \mathcal{D} and a specific question \mathcal{Q} , our goal is to let the LLM \mathcal{M} solve the question \mathcal{Q} .

Step 1: Exploring Diverse Available Perspectives. We first let LLM \mathcal{M} explore diverse perspectives \mathcal{P} according to the description \mathcal{D} and question \mathcal{Q} . Specifically,

Illustration of the Unified Prompting and Response

/ Input */*

/ Perspective-based Instructions */*

Here are some examples of perspectives you can choose:
Direct Perspective (answer the question directly).

.....
Role Perspective (assume you are some roles (e.g., expert) and answer the question).

.....
Third-person Perspective (simulate some agents and discussions, then summarize and give the answer).(\mathcal{D})

.....

/ Input Question */*

Metaphor Recognition: Identify whether the sentence “Adam did not understand the root of the crisis” is a paraphrase of the metaphoric sentence “Adam did not understand the solution to the crisis” (\mathcal{Q})

Firstly, analyzing the question from diverse perspectives, and selecting some available perspectives based on the question. (\mathcal{T}_1)

Secondly, ranking all the perspectives according to the confidence level in solving the question. [Note: The confidence indicates how likely you think your answer is true]. (\mathcal{T}_2)

Finally, choosing the method with the highest confidence to solve the question, reason and give the final answer. Select from True or False. (\mathcal{T}_3)

/ Response of \mathcal{M} */*

Perspective and Confidence: (\mathcal{P}, \mathcal{C})

Third-person Perspective, 85%

Role Perspective, 70%

Direct Perspective, 60%

Selected Perspective Reasoning: (\mathcal{R})

Tom: Adam did not understand the root of the crisis.

Jerry: So, does that mean Adam did not understand the solution to the crisis?

Tom: Not exactly. Understanding the root of the crisis doesn’t necessarily mean understanding the solution. Understanding the root is figuring out what causes the problem, while a solution refers to ways of solving the problem. They can be related but are not synonymous.

Answer: False

Table 1: The example of a metaphor recognition task, a specific question, the unified prompt, and the corresponding response.

we have:

$$\mathcal{P} = \{p_1, p_2, \dots, p_n\} = \mathcal{M}(\mathcal{D} \oplus \mathcal{Q} \oplus \mathcal{T}_1), \quad (1)$$

where n (the number of perspectives) is usually 3, \oplus denotes concatenation operation. \mathcal{T}_1 is a prompt serving as a trigger sentence, for example, we can set \mathcal{T}_1 as “Firstly, analyzing the question from diverse perspectives, and selecting some available perspectives based on the question”.

Step 2: Ranking Perspectives by Confidence Level. Then, base on the perspectives, we let LLM \mathcal{M} list all the perspectives by the confidence level \mathcal{C} in solving the

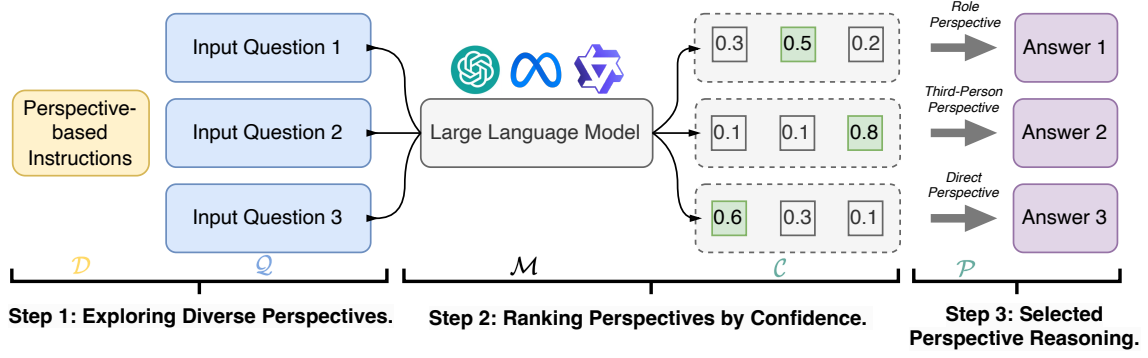


Figure 3: An overview of RPT pipeline. For each input question, RPT explores the available perspectives and then ranks them based on confidence. Accordingly, the input question is reasoned using the selected perspective.

question:

$$\mathcal{P}, \mathcal{C} = \mathcal{M}(\mathcal{D} \oplus \mathcal{Q} \oplus \mathcal{T}_2), \quad (2)$$

where \mathcal{T}_2 is a prompt for ranking the confidence level of all the available perspectives. For example, we can set \mathcal{T}_2 as “*Secondly, Ranking all the methods according to the confidence level in solving the question. [Note: The confidence indicates how likely you think your answer is true.]*”.

Step 3: Selected Perspective Reasoning. Finally, we take the original task description \mathcal{D} , question \mathcal{Q} , and the ranked confidence level perspective \mathcal{P} as the input, letting LLM \mathcal{M} give the final response \mathcal{R} :

$$\mathcal{R} = \mathcal{M}(\mathcal{D} \oplus \mathcal{Q} \oplus \mathcal{P} \oplus \mathcal{T}_3), \quad (3)$$

where \mathcal{T}_3 is the last prompt leading to the final answer which can be set as “*Finally, Choosing the perspective with the highest confidence to solve the question, and give the final answer*”.

Combine All Steps through Unified Prompting. In practice, we find that the three aforementioned steps can be combined and accomplished through a single prompt \mathcal{T} . In this way, our method only requires inference once through the LLM to obtain the answer to the question:

$$\begin{aligned} \mathcal{T} &= \mathcal{T}_1 \oplus \mathcal{T}_2 \oplus \mathcal{T}_3, \\ \mathcal{P}, \mathcal{C}, \mathcal{R} &= \mathcal{M}(\mathcal{D} \oplus \mathcal{Q} \oplus \mathcal{T}), \end{aligned} \quad (4)$$

where an example of the unified prompt and response is shown in Table 1.

4 Experiments

4.1 Settings

Datasets. We evaluate the effectiveness of our method on twelve subjective reasoning datasets, which can be categorized into five types, as shown in Table 2. Notably, for SemEval and cultural-related datasets which contain training sets, we evaluate in both zero-shot and few-shot settings. For the other tasks, we utilize corresponding test sets from BigBench¹ (Srivastava et al., 2022) and only evaluate in zero-shot settings.

¹https://github.com/google/BIG-bench/tree/main/bigbench/benchmark_tasks/

| Dataset (names in short) | Subjective Tasks | #Train/Dev/Test |
|--------------------------------------|--|-----------------|
| <i>(Linguistic Rhetoric)</i> | | |
| Metaphor (Mohler et al., 2016) | Metaphor Understanding | -/-/680 |
| SNARKS (Khodak et al., 2018) | Sarcasm Detection | -/-/181 |
| Humor (Hoffmann et al., 2022) | Dark Humor Detection | -/-/80 |
| <i>(Disambiguation QA)</i> | | |
| Pronoun (Rudinger et al., 2018) | Pronoun Resolution | -/-/258 |
| Anachronisms (Geva et al., 2021) | Identifying Anachronisms | -/-/230 |
| <i>(Stance Detection)</i> | | |
| SEQ (Hendrycks et al., 2021) | Simple Ethical Questions | -/-/115 |
| SemEval (Mohammad et al., 2016) | Opinion Analysis | 2,194/621/707 |
| <i>(Cultural-Related)</i> | | |
| SocNorm (CH-Wang et al., 2023) | Sociocultural Norm NLI | 2,301/300/768 |
| e-SocNorm (CH-Wang et al., 2023) | Sociocultural Norm NLI | 2,301/300/768 |
| CALI (Huang and Yang, 2023) | Culturally Aware NLI | 1,757/-/440 |
| <i>(Traditional NLI)</i> | | |
| Entailment (Srivastava et al., 2022) | Analytic Entailment | -/-/70 |
| IPA (Williams et al., 2018) | NLI in the International Phonetic Alphabet | -/-/126 |

Table 2: Statistics and resources of datasets.

Baselines. We compare our method with 11 baselines including different single perspective methods and ensemble-based methods as follows.

Single Direct Perspective. **Directly Prompt** (Brown et al., 2020) directly use the question as input in zero-shot or few-shot manners. **ICL** (Brown et al., 2020) (in-context learning) uses examples and labels as few input demonstrations. **Few-shot-CoT** (Wei et al., 2022) uses manually created external reasoning pathways as demonstrations. **Zero-Shot-CoT** (Kojima et al., 2022) does not rely on demonstrations and elicits the reasoning ability by using “Let’s think step by step.” as external input. **Self-Ask** (Press et al., 2023) actively proposes and solves subquestions before generating the final answer.

Single Role Perspective. **ExpertPrompt** (Xu et al., 2023) introduces the expert identities and customizes information descriptions for LLMs before generating responses. **Role-Play Prompting** (Kong et al., 2024) also lets models simulate complex human-like interactions and behaviors for zero-shot reasoning.

Single Third-Person Perspective. **SPP** (Wang et al., 2024e) (solo performance prompting) proposes solo performance prompting by involving multi-turn collaboration with multi-persona. **RiC** (Wang et al., 2024c) (reason in conversation) first lets model generating dialogues between simulated roles, and then summarize conversations and give final answers according to the additional information from conversations.

Ensemble-based Methods. **Ensemble** (Messuti et al.,

| Type | Method | Linguistic Rhetoric | | | Disambiguation QA | | Stance Detection | | Cultural-Related | | | Traditional NLI | | Avg. |
|-----------------------|---|---------------------|------------------|-----------------|-------------------|------------------|------------------|-----------------|------------------|-------------------|----------------|-------------------|---------------|-------|
| | | Metaphor (Acc.) | SNARKS (Acc.) | Humor (Acc.) | Pronoun (Acc.) | Anach. (Acc.) | SEQ (Acc.) | SemEval (F1) | SocNorm (F1) | e-SocNorm (F1) | CALI (Acc.) | Entail. (Acc.) | IPA (Acc.) | |
| - | Random | 50.00 | 50.00 | 50.00 | 33.33 | 50.00 | 25.00 | 50.00 | 33.33 | 33.33 | 33.33 | 50.00 | 33.33 | 40.97 |
| - | Majority | 61.62 | 53.59 | 50.00 | 30.23 | 50.00 | 10.43 | 0.00 | 0.00 | 0.00 | 38.09 | 57.14 | 38.89 | 32.50 |
| (Llama-3-8b-instruct) | | | | | | | | | | | | | | |
| S1 | Direct Prompt (Brown et al., 2020) | 66.03 | 58.56 | 60.00 | 43.41 | 50.00 | 61.74 | 71.00 | 39.15 | 48.49 | 42.95 | 51.43 | 39.68 | 52.70 |
| S1 | Zero-Shot-CoT (Kojima et al., 2022) | 67.06 | 70.72 | 63.75 | 46.90 | 61.74 | 73.04 | 72.45 | 40.07 | 52.84 | 47.95 | 54.29 | 44.44 | 57.94 |
| S2 | Role-Play Prompting (Kong et al., 2024) | 65.00 | 64.09 | 65.00 | 45.35 | 53.91 | 72.17 | 73.26 | 51.36 | 56.44 | 46.82 | 51.54 | 43.65 | 57.38 |
| S3 | Reason in Conversation (Wang et al., 2024c) | 76.32 | 69.72 | 58.75 | 48.06 | 52.17 | 80.00 | 74.71 | 48.15 | 64.05 | 48.86 | 58.57 | 50.79 | 60.85 |
| E | Ensemble (Agrawal et al., 2024) | 68.09 | 64.64 | 50.00 | 37.60 | 69.57 | 82.61 | 77.00 | 44.60 | 58.72 | 54.77 | 57.14 | 53.97 | 59.89 |
| E | Reranking (Fariinhas et al., 2024) | 71.47 | 58.56 | 52.50 | 51.78 | 59.13 | 72.17 | 72.23 | 52.86 | 52.34 | 48.41 | 55.71 | 54.76 | 59.49 |
| E | CoT-SC (Wang et al., 2023) | 65.88 | 48.07 | 66.25 | 45.74 | 61.30 | 78.26 | 76.01 | 55.86 | 59.64 | 47.73 | 52.86 | 61.90 | 59.96 |
| D | RPT (Ours) | 81.76 | 60.22 | 65.00 | 53.49 | 72.17 | 89.57 | 77.44 | 53.52 | 61.72 | 51.59 | 58.57 | 44.44 | 64.12 |
| (gwen-2-7b-instruct) | | | | | | | | | | | | | | |
| S1 | Direct Prompt (Brown et al., 2020) | 79.85 | 61.88 | 60.00 | 56.98 | 64.38 | 86.09 | 70.17 | 38.53 | 47.93 | 42.27 | 58.57 | 58.73 | 60.45 |
| S1 | Zero-Shot-CoT (Kojima et al., 2022) | 83.09 | 64.03 | 63.75 | 54.65 | 63.48 | 79.13 | 73.36 | 43.99 | 47.79 | 46.59 | 62.86 | 62.70 | 62.12 |
| S2 | Role-Play Prompting (Kong et al., 2024) | 78.97 | 65.75 | 56.25 | 52.25 | 60.87 | 86.96 | 72.25 | 46.77 | 51.21 | 49.77 | 64.29 | 57.14 | 61.87 |
| S3 | Reason in Conversation (Wang et al., 2024c) | 80.59 | 69.61 | 60.00 | 60.47 | 63.91 | 87.83 | 75.06 | 49.57 | 56.40 | 53.18 | 64.29 | 60.32 | 65.10 |
| E | Ensemble (Agrawal et al., 2024) | 86.03 | 74.59 | 62.50 | 54.65 | 63.48 | 88.70 | 72.66 | 46.08 | 58.02 | 53.64 | 71.43 | 66.67 | 66.54 |
| E | Reranking (Fariinhas et al., 2024) | 83.23 | 72.38 | 60.00 | 54.65 | 62.17 | 87.04 | 74.21 | 44.81 | 54.18 | 54.32 | 74.29 | 65.08 | 65.53 |
| E | CoT-SC (Wang et al., 2023) | 86.32 | 79.56 | 47.50 | 66.28 | 70.00 | 92.17 | 75.29 | 44.44 | 61.90 | 54.32 | 50.00 | 56.35 | 65.34 |
| D | RPT (Ours) | 84.41 | 69.61 | 65.00 | 63.95 | 68.70 | 94.78 | 76.58 | 51.02 | 68.29 | 52.27 | 67.14 | 61.90 | 68.64 |
| (gpt-3.5-turbo-1106) | | | | | | | | | | | | | | |
| S1 | Direct Prompt (Brown et al., 2020) | 85.74 | 77.35 | 58.75 | 55.04 | 70.43 | 75.65 | 71.30 | 43.25 | 45.27 | 52.94 | 60.00 | 50.79 | 62.21 |
| S1 | Zero-Shot-CoT (Kojima et al., 2022) | 86.47 | 78.45 | 57.50 | 60.47 | 64.78 | 72.17 | 73.79 | 44.68 | 51.53 | 52.75 | 58.57 | 55.56 | 63.06 |
| S2 | Role-Play Prompting (Kong et al., 2024) | 82.64 | 77.40 | 57.25 | 60.39 | 71.74 | 78.39 | 71.10 | 47.61 | 49.13 | 55.68 | 61.43 | 57.14 | 64.16 |
| S3 | Reason in Conversation (Wang et al., 2024c) | 87.94 | 82.32 | 71.25 | 62.79 | 72.61 | 81.74 | 74.27 | 56.02 | 59.98 | 57.27 | 62.86 | 57.14 | 68.85 |
| E | Ensemble (Agrawal et al., 2024) | 84.26 | 76.80 | 66.25 | 59.61 | 72.17 | 86.26 | 70.32 | 48.25 | 56.51 | 52.95 | 64.29 | 65.08 | 66.90 |
| E | Reranking (Fariinhas et al., 2024) | 81.76 | 79.56 | 65.00 | 54.65 | 72.17 | 81.30 | 77.27 | 51.18 | 63.99 | 60.91 | 61.42 | 63.49 | 67.73 |
| E | CoT-SC (Wang et al., 2023) | 84.85 | 86.74 | 67.50 | 47.29 | 74.35 | 92.17 | 81.18 | 59.35 | 65.53 | 59.09 | 87.14 | 75.40 | 73.38 |
| D | RPT (Ours) | 91.76 | 87.29 | 70.00 | 65.12 | 73.48 | 99.13 | 81.43 | 59.81 | 77.57 | 61.13 | 88.57 | 80.00 | 77.94 |
| (gpt-4-0613) | | | | | | | | | | | | | | |
| S1 | Direct Prompt (Brown et al., 2020) | 94.85 | 86.19 | 65.00 | 72.09 | 82.17 | 92.17 | 72.78 | 45.31 | 46.81 | 60.40 | 68.57 | 75.40 | 71.81 |
| S1 | Zero-Shot-CoT (Kojima et al., 2022) | 95.88 | 87.29 | 66.25 | 69.38 | 80.00 | 93.91 | 75.47 | 48.74 | 47.45 | 60.90 | 75.71 | 73.02 | 72.83 |
| S2 | Role-Play Prompting (Kong et al., 2024) | 93.97 | 82.87 | 63.75 | 67.05 | 80.87 | 96.52 | 73.71 | 52.31 | 54.51 | 58.86 | 77.14 | 73.81 | 72.95 |
| S3 | Reason in Conversation (Wang et al., 2024c) | 95.29 | 92.27 | 67.50 | 75.58 | 86.96 | 95.65 | 76.34 | 58.27 | 61.12 | 61.13 | 87.14 | 80.95 | 78.18 |
| E | Ensemble (Agrawal et al., 2024) | 95.44 | 88.95 | 65.00 | 61.63 | 81.74 | 98.26 | 75.57 | 58.33 | 66.78 | 63.18 | 87.14 | 78.57 | 76.72 |
| E | Reranking (Fariinhas et al., 2024) | 94.71 | 84.53 | 65.00 | 65.89 | 81.73 | 97.39 | 74.70 | 56.28 | 66.18 | 59.32 | 88.57 | 76.19 | 75.87 |
| E | CoT-SC (Wang et al., 2023) | 96.00 | 84.53 | 73.75 | 73.26 | 83.04 | 99.13 | 72.52 | 53.26 | 66.23 | 62.95 | 57.14 | 83.33 | 75.43 |
| D | RPT (Ours) | 95.29 | 92.82 | 67.50 | 75.97 | 87.39 | 97.39 | 78.53 | 61.78 | 75.87 | 63.64 | 88.57 | 84.92 | 80.81 |

Table 3: Main results of baselines and our proposed RPT method in zero-shot settings. *Random* represents the result of random prediction with uniform probability, and *Majority* represents the result of predicting the label with the highest proportion. S1: single direct perspective, S2: single role perspective, S3: single third-person perspective, E: ensemble-based method. D: dynamic perspective. For each dataset, the best result is **in bold** and the second-best result is underlined.

2024; Agrawal et al., 2024) involves combining multiple model generation to enhance prediction accuracy and robustness. **Reranking** (Farinhas et al., 2024; Kim et al., 2024) reorder different generation options based on requirements and select the optimal result. **CoT-SC** (Wang et al., 2023) enhances performance by sampling diverse chain-of-thought reasoning paths and selecting the most self-consistent answer.

Models. We evaluate our method on both closed-source models including GPT-4 (OpenAI, 2023) and GPT-3.5 (OpenAI, 2022), and open-source Llama-3 (Dubey et al., 2024) and Qwen-2 (Yang et al., 2024) models. In particular, we use the released API versions of gpt-4-0613 and gpt-3.5-turbo-1106 by OpenAI, and open-source Llama-3-8b-instruct and gwen-2-7b-instruct models released in Huggingface hub. We set the decoding temperature as 0 to maintain the reproducibility of the responses generated by LLMs.

4.2 Zero-shot Results

In Table 3, we shows the experimental results of the baselines and our RPT method in zero-shot settings. From the experimental results, we can observe that:

RPT method consistently outperforms the baselines in most settings. Due to its ability to rank perspectives and select different perspectives to suit various

subjective scenarios, our method achieves an average improvement of 3.27 points on all subjective tasks using the open-source model Llama-3 compared to the best-performing baseline. Similarly, on the closed-source GPT-3.5 model, our method achieves an average improvement of 4.56 points. Since subjective tasks vary widely, RPT achieves optimal performance through dynamic selection. For instance, on the Metaphor dataset, which requires complex contextual subjective understanding, our method, using Llama-3, outperforms the RiC method, which focuses on dialogue understanding, by 5.44 points.

Compared to baseline methods, our RPT method exhibits greater robustness. Although baselines introduce different perspectives to adapt to subjective tasks, they are typically effective only in specific domains. For example, using Llama-3, the Zero-Shot-CoT baseline achieves good performance on the Linguistic Rhetoric task, reaching the highest 70.72 accuracy on the SNARKS dataset, but performs poorly on tasks requiring complex contexts and cultural backgrounds, such as stance detection and culturally related datasets. For example, it only achieves 40.07 F1 score on SocNorm, the lowest among all baselines. Conversely, the RiC baseline, which employs role-playing for dialogue simulation, performs well in culturally relevant scenarios, achieving the highest F1 score of 64.05 on

| Type | Method | SemEval | SocNorm | e-SocNorm | CALI | Avg. |
|-----------------------|-----------------------------------|--------------|--------------|--------------|--------------|--------------|
| (Llama-3-8b-instruct) | | | | | | |
| S1 | ICL (Brown et al., 2020) | 70.71 | 47.82 | 57.73 | 47.27 | 55.88 |
| S1 | Few-Shot-CoT (Brown et al., 2020) | 76.45 | 48.37 | 57.77 | 48.41 | 57.75 |
| S1 | Self-Ask (Press et al., 2023) | 76.46 | 49.52 | 53.34 | 48.64 | 56.99 |
| S2 | ExpertPrompt (Xu et al., 2023) | 75.08 | 47.46 | 64.85 | 45.00 | 58.10 |
| S3 | SPP (Wang et al., 2024e) | 74.91 | 40.55 | 56.15 | 50.68 | 55.57 |
| S3 | RiC (Wang et al., 2024c) | 77.48 | 52.54 | 66.60 | 50.23 | 61.71 |
| E | Ensemble (Agrawal et al., 2024) | 76.23 | 45.53 | 67.31 | 51.14 | 60.05 |
| E | Reranking (Farinhas et al., 2024) | 71.79 | 42.80 | 64.89 | 50.68 | 57.54 |
| E | CoT-SC (Wang et al., 2023) | 79.33 | 40.92 | 75.80 | 51.59 | 61.91 |
| D | RPT (Ours) | 80.02 | 54.21 | 70.05 | 51.59 | 63.97 |
| (qwen-2-7b-instruct) | | | | | | |
| S1 | ICL (Brown et al., 2020) | 70.83 | 35.97 | 54.52 | 52.27 | 53.40 |
| S1 | Few-Shot-CoT (Brown et al., 2020) | 71.16 | 52.01 | 63.51 | 53.41 | 60.02 |
| S1 | Self-Ask (Press et al., 2023) | 74.09 | 47.89 | 56.28 | 52.05 | 57.58 |
| S2 | ExpertPrompt (Xu et al., 2023) | 72.65 | 54.56 | 62.70 | 52.27 | 60.55 |
| S3 | SPP (Wang et al., 2024e) | 72.76 | 47.89 | 57.91 | 54.59 | 58.29 |
| S3 | RiC (Wang et al., 2024c) | 76.37 | 55.69 | 68.12 | 55.91 | 64.02 |
| E | Ensemble (Agrawal et al., 2024) | 75.94 | 29.18 | 44.25 | 57.73 | 51.78 |
| E | Reranking (Farinhas et al., 2024) | 71.96 | 51.32 | 67.37 | 52.73 | 60.85 |
| E | CoT-SC (Wang et al., 2023) | 72.55 | 30.93 | 54.25 | 58.64 | 54.09 |
| D | RPT (Ours) | 74.23 | 59.73 | 72.52 | 56.82 | 65.83 |
| (gpt-3.5-turbo-1106) | | | | | | |
| S1 | ICL (Brown et al., 2020) | 72.02 | 52.95 | 55.60 | 54.77 | 58.84 |
| S1 | Few-Shot-CoT (Brown et al., 2020) | 72.06 | 53.44 | 61.35 | 54.55 | 60.35 |
| S1 | Self-Ask (Press et al., 2023) | 73.04 | 53.94 | 57.81 | 57.27 | 60.52 |
| S2 | ExpertPrompt (Xu et al., 2023) | 75.22 | 46.08 | 65.29 | 55.45 | 60.51 |
| S3 | SPP (Wang et al., 2024e) | 72.74 | 51.92 | 62.01 | 55.91 | 60.65 |
| S3 | RiC (Wang et al., 2024c) | 78.21 | 57.70 | 72.78 | 60.00 | 67.17 |
| E | Ensemble (Agrawal et al., 2024) | 77.33 | 57.42 | 66.52 | 58.72 | 65.00 |
| E | Reranking (Farinhas et al., 2024) | 68.73 | 50.90 | 74.45 | 54.32 | 62.10 |
| E | CoT-SC (Wang et al., 2023) | 74.56 | 58.25 | 73.83 | 59.09 | 66.43 |
| D | RPT (Ours) | 80.78 | 62.70 | 74.60 | 60.00 | 69.52 |
| (gpt-4o-613) | | | | | | |
| S1 | ICL (Brown et al., 2020) | 73.72 | 54.71 | 61.41 | 62.50 | 63.09 |
| S1 | Few-Shot-CoT (Brown et al., 2020) | 76.59 | 64.08 | 67.88 | 64.77 | 68.33 |
| S1 | Self-Ask (Press et al., 2023) | 73.52 | 56.74 | 64.62 | 65.45 | 65.08 |
| S2 | ExpertPrompt (Xu et al., 2023) | 77.65 | 56.84 | 68.72 | 59.77 | 65.75 |
| S3 | SPP (Wang et al., 2024e) | 78.72 | 57.74 | 65.04 | 54.32 | 63.96 |
| S3 | RiC (Wang et al., 2024c) | 80.01 | 66.59 | 74.45 | 65.68 | 71.68 |
| E | Ensemble (Agrawal et al., 2024) | 68.95 | 63.95 | 67.88 | 64.77 | 66.39 |
| E | Reranking (Farinhas et al., 2024) | 66.61 | 60.52 | 72.45 | 62.05 | 65.41 |
| E | CoT-SC (Wang et al., 2023) | 69.85 | 63.37 | 75.37 | 57.05 | 66.41 |
| D | RPT (Ours) | 80.11 | 66.79 | 79.89 | 66.59 | 73.35 |

Table 4: Main results of baselines and our RPT method in few-shot settings. S1: single direct perspective, S2: single role perspective, S3: single third-person perspective, E: ensemble-based method. D: dynamic perspective. We select the same 3-shot demonstrations from the training sets to each method for fair comparison.

the e-SocNorm dataset, but struggles in the Linguistic Rhetoric task. Overall, different baselines that simulate distinct perspectives excel in specific domains but exhibit poor generalizability. In contrast, our method demonstrates consistent improvements across various subjective tasks, making it more robust.

Introducing more diverse perspectives into LLM and switching dynamically among them improves subjective reasoning performance. The RPT method achieves ensemble through exploring diverse perspectives and ranking perspectives by confidence level. In various settings, baselines that utilize multiple perspectives (e.g., RiC) outperform those that employ a single perspective (e.g., CoT), with scores of 60.85 vs. 58.77 on Llama-3 and 65.10 vs. 62.12 on Qwen. RPT takes this further by proposing dynamic perspective shifts, which offer high generalization and scalability, resulting in optimal performance through dynamic ensemble of all the baselines mentioned above.

Subjective reasoning is a challenging task, and the RPT method effectively elicits the capabilities of LLMs in such tasks. Closed-source models like GPT-3.5 and GPT-4 outperform open-source models like Llama-3 and Qwen-2 in subjective tasks, but the performance gap narrows when using the RPT method. This suggests that these models still possess the knowledge required for subjective reasoning, but it has not been effectively elicited during training. By introducing con-

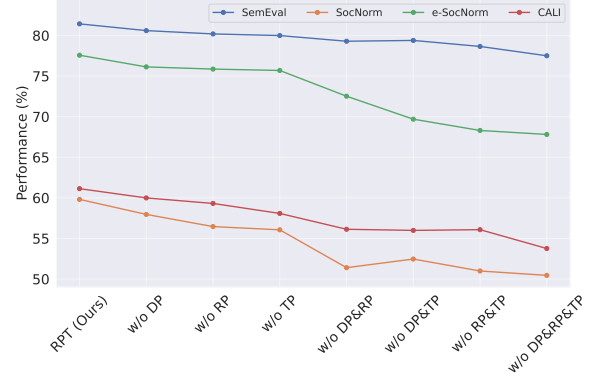


Figure 4: The impact of different perspectives on the RPT method. DP: direct perspective, RP: role perspective, TP: third-person perspective.

fidence evaluation during LLM reasoning, RPT selects the method best suited to the model’s strengths, effectively eliciting LLM capabilities in subjective tasks, and compensating for the lack of subjective task data during LLM training.

4.3 Few-shot Results

In Table 4, we present the main results in few-shot settings. Similar to the zero-shot results, RPT method achieves the best average performance across different models. For instance, on Llama-3, RPT surpasses CoT-SC, the best-performing baseline, by 2.06 points.

A possible explanation is that providing a few examples in the prompt generally benefits LLM performance by providing context. However, subjective tasks are not well-defined and directly solvable, leading to significant differences between examples. As a result, LLMs exhibit varying confidence across examples, limiting the performance gains from examples and sometimes introducing noise or bias. For instance, using 3-shot examples in the RiC baseline lead to an average performance drop of 6.50 points on GPT-4. In contrast, RPT choose among perspectives and evaluates confidence for each input and method, providing finer-grained supervision signals and resulting in an average performance gain of 1.67 points.

5 Analyses and Discussion

5.1 Ablation Study

As shown in Figure 4, we further investigate the impact of every perspective on the RPT method. The full RPT method achieves the best performance across all datasets. From the results of the ablation study, we can observe the following:

Removing any single perspective results in an average performance drop of 1.32–2.53 points, indicating that direct perspective, role perspective, and third-person perspective each have unique and irreplaceable contributions to subjective reasoning tasks. Specifically, removing the third-person component has the greatest

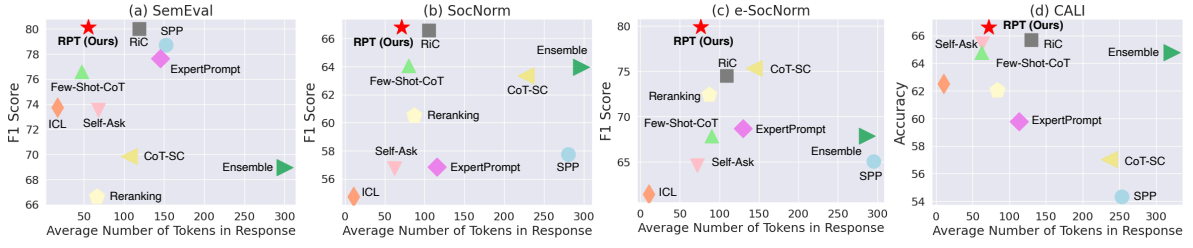


Figure 5: The relationship between the performance and prediction lengths of the 3-shot experiments on GPT-4.

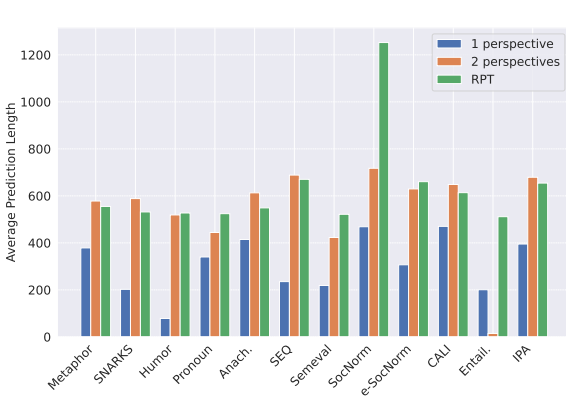


Figure 6: The inference cost of RPT when using different numbers of perspectives. RPT does not significantly increase inference costs on most datasets.

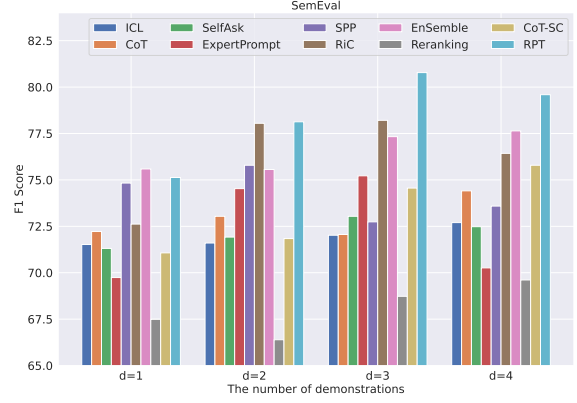


Figure 7: The performance of baselines and our RPT method by using different numbers of demonstrations ($d = 1, 2, 3, 4$) in few-shot settings.

impact, followed by role perspective and direct perspective, suggesting that the flexibility of switching between perspectives benefits overall performance.

Removing any two perspectives results in an even greater average performance drop of 5.15-6.48 points, and removing all perspectives (i.e., performing simple reasoning) leads to the highest performance drop of 7.60 points. As the number of perspectives removed increases, the range of dynamic switching decreases, causing a corresponding decline in RPT performance. This highlights the crucial role of switching between different perspectives in the RPT method.

In summary, all perspectives involved in RPT and the ability to flexibly switch between them are essential for achieving optimal performance. Thus, every component of our method is effective. The detailed ablation experiment results are presented in Appendix A.

5.2 Analysis on Inference Cost

The inference cost of modern LLMs is crucial. Using the GPT-3.5 model as an example, we represent the inference cost by the length of the response during the reasoning process before producing the final answer. In Figure 5, using the 3-shot GPT-4 experiment as an example, we plot the length-performance relationship for RPT and the baselines. It can be observed that compared to most baselines, RPT achieves the best performance with a smaller inference cost, demonstrating the efficiency of the dynamic perspective selection approach. As shown in Figure 6, we compare the inference cost

of the RPT method with its variants that only allow the use of one or two perspectives. The results indicate that the RPT method incurs a cost similar to that of the variants allowing only one or two perspectives in most datasets, without increasing the inference length, and thus the additional cost is minimal. This is because RPT performs method selection and perspective switching, avoiding the substantial inference cost caused by ensembling multiple perspectives.

5.3 Analysis on the Number of Shots

As shown in Figure 7, we specify the number of shots and study the performance difference compared to the original RPT on SemEval. We observe that performance is lower when fewer shots are selected, as the model is unfamiliar with the task and method. As the number of shots increases, performance improves. However, in some circumstances when the number of shots reaches three or more, performance declines.

On one hand, LLMs exhibit greater flexibility when autonomously evaluating confidence and planning the number of shots during reasoning, allowing them to adapt to unique subjective tasks. On the other hand, providing too many examples may lead to increasing the inference cost, raising the risk of over-fitting, and challenging the instruction-following ability of LLMs. Overall, under the majority of settings for each dataset, RPT achieves the best performance, demonstrating its generalization ability and versatility (See Appendix B.3 for full results).



Figure 8: Case of SemEval task. We use GPT-4 to analyze attitudes toward Donald Trump. Our RPT method effectively guides the model in selecting appropriate perspectives for stance detection.

5.4 Case Study

In Figure 8, we showcase an example from the SemEval stance detection dataset to highlight the effectiveness of the RPT method in subjective reasoning tasks. Unlike baselines such as CoT and Role-playing, which sometimes emphasize skepticism or negative sentiment without fully accounting for context, RPT evaluates multiple perspectives, including direct and third-person analyses. For example, CoT and RiC interpret the phrase “Get the truth from Trump!” as reflecting skepticism or disbelief, leading to an “AGAINST” prediction. In contrast, RPT dynamically selects the most confident perspective, reasoning that the exclamation mark and phrase suggest advocacy or favor toward Trump. This ability to transition between and rank perspectives makes RPT more adaptable and effective in subjective reasoning tasks compared to single-perspective baselines (See Appendix B.2 for more cases).

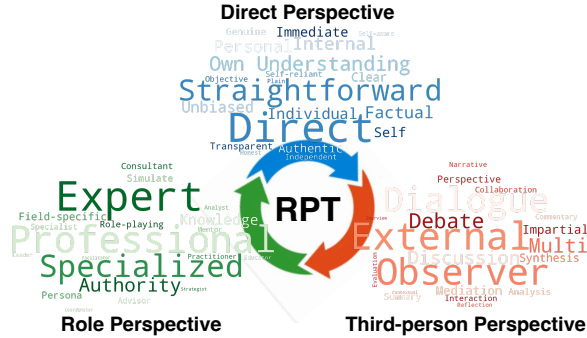


Figure 9: Keyword statistics of different perspectives in RPT pipeline.

6 Conclusion

In this paper, we introduce RPT (Reasoning through Perspective Transition), a novel method that achieves multi-perspective reasoning and integration by exploring diverse perspectives and ranking them based on confidence. Comprehensive experiments conducted on GPT-4, GPT-3.5, Llama-3, and Qwen-2 demonstrate that RPT effectively integrates various perspectives, enhancing the subjective task-solving capabilities of LLMs without significantly increasing inference costs. This work highlights how LLMs can better handle the fluidity of subjective reasoning, even in the absence of nuanced understanding of perspectives or personal biases. Future research directions include integrating additional reasoning perspectives, developing finer-grained and adaptive perspective taxonomies, and extending our method to broader applications.

Limitations

First, in designing the RPT pipeline, we categorize perspectives into three types based on related works. Although RPT and many inference paradigms involved in the baselines are orthogonal and combinable, this taxonomy could still be further refined, for example, by adopting alternative categorization methods or employing a more fine-grained division. Second, RPT directly selects perspectives rather than methods. We consider perspectives as a meta-method, meaning that RPT can be combined with other methods to achieve better performance. Thirdly, RPT operates within a single round of dialogue, without accounting for multi-turn conversations or result feedback. In the future, exploring multi-turn dialogue or multi-agent perspective writing could be a promising direction.

Ethics Statement

This paper uses widely available datasets, including stance detection, sarcasm detection, and cultural comparison, along with LLM-generated responses, solely to validate the proposed method without reflecting any stance or bias from the authors.

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A Details of Ablation Study

As shown in Table 5, we present the complete and detailed results of the ablation experiments. By removing one, two, and all three perspectives, we demonstrate the effectiveness of RPT. Based on the number of perspectives removed, we divide the ablation experiments into three groups. It can be seen that all the perspectives involved in RPT are beneficial. Meanwhile, restricting the range of perspective selection also results in performance degradation.

| Method | SemEval | SocNorm | e-SocNorm | CALI | AVG. |
|---------------------------|--------------|--------------|--------------|--------------|--------------|
| RPT (Ours) | 81.43 | 59.81 | 77.57 | 61.13 | 69.99 |
| (removing 1 perspective) | | | | | |
| w/o DP | ↓ 0.83 | ↓ 1.85 | ↓ 1.44 | ↓ 1.14 | ↓ 1.32 |
| w/o RP | ↓ 1.24 | ↓ 3.35 | ↓ 1.71 | ↓ 1.82 | ↓ 2.03 |
| w/o TP | ↓ 1.44 | ↓ 3.75 | ↓ 1.88 | ↓ 3.05 | ↓ 2.53 |
| (removing 2 perspectives) | | | | | |
| w/o DP&RP | ↓ 2.14 | ↓ 8.41 | ↓ 5.05 | ↓ 5.00 | ↓ 5.15 |
| w/o DP&TP | ↓ 2.04 | ↓ 7.35 | ↓ 7.88 | ↓ 5.14 | ↓ 5.60 |
| w/o RP&TP | ↓ 2.78 | ↓ 8.82 | ↓ 9.27 | ↓ 5.05 | ↓ 6.48 |
| (removing 3 perspectives) | | | | | |
| w/o DP&RP&TP | ↓ 3.93 | ↓ 9.36 | ↓ 9.76 | ↓ 7.37 | ↓ 7.60 |

Table 5: Detailed results of ablation study of our proposed RPT method with GPT-3.5 in zero-shot settings. DP: Direct perspective. RP: Role Perspective. TP: Third-Person Perspectives.

B More Analysis

RPT ranks different perspectives based on confidence levels without relying on external information. In this section, using the zero-shot GPT-3.5 experiment as an example, we force the LLM to select the perspective with the second highest confidence, the lowest confidence, and a randomly chosen perspective during RPT inference.

As shown in Table 6, the lower the confidence of the selected perspective, the poorer the performance of LLM. When randomly selecting perspectives, the performance of the LLM is also worse than that of the perspective with the highest confidence. This shows that ranked perspectives based on confidence levels are effective, explaining the underlying mechanism by which RPT improves performance.

B.1 Analysis on the Correlation between Confidence and Accuracy

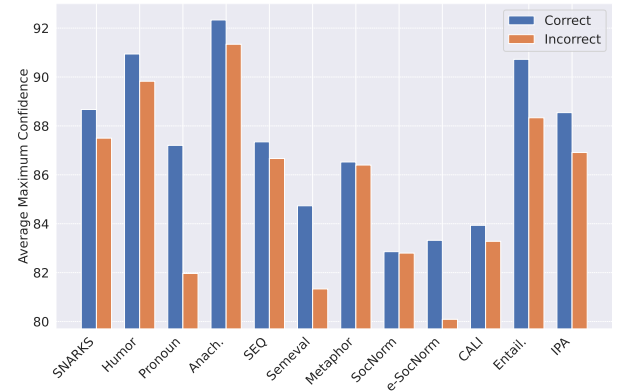


Figure 10: Analysis on the correlation between confidence and accuracy.

In RPT, we use LLM itself to judge the confidence of perspectives for a given input, allowing the model to rank and switch among perspectives accordingly. As shown in Figure 10, using the GPT-3.5 model as an example, we analyze the relationship between predicted confidence and the actual accuracy. We can observe

| Type | Method | Linguistic Rhetoric | | | Disambiguation QA | | Stance Detection | | Cultural-Related | | | Traditional NLI | | | AVG. |
|------|---------------------|---------------------|---------------|--------------|-------------------|---------------|------------------|--------------|------------------|----------------|--------------|-----------------|--------------|--------------|------|
| | | Metaphor (Acc.) | SNARKS (Acc.) | Humor (Acc.) | Pronoun (Acc.) | Anach. (Acc.) | SEQ (Acc.) | SemEval (F1) | SocNorm (F1) | e-SocNorm (F1) | CALI (Acc.) | Entail. (Acc.) | IPA (Acc.) | | |
| D | RPT (Ours) | 91.76 | 87.29 | 70.00 | 65.12 | 73.48 | 99.13 | 81.43 | 59.81 | 77.57 | 61.13 | 88.57 | 80.00 | 77.94 | |
| D | <i>RPT (second)</i> | 83.82 | 81.77 | 56.59 | 56.20 | 72.61 | 98.26 | 80.61 | 43.52 | 61.53 | 51.36 | 77.14 | 64.29 | 68.98 | |
| D | <i>RPT (lowest)</i> | 79.12 | 79.01 | 37.98 | 38.76 | 69.13 | 96.52 | 78.89 | 38.03 | 51.54 | 48.64 | 57.14 | 56.35 | 60.93 | |
| D | <i>RPT (random)</i> | 85.88 | 80.11 | 53.49 | 58.91 | 70.43 | 97.39 | 80.56 | 45.15 | 67.99 | 54.09 | 67.14 | 67.46 | 69.05 | |

Table 6: Analysis on confidence-based perspective selection. *RPT (random)* represents the result of random prediction with uniform probability, *RPT (second)* represents selecting the perspective with the second highest confidence, and *RPT (lowest)* means choosing the most unconfident perspective.

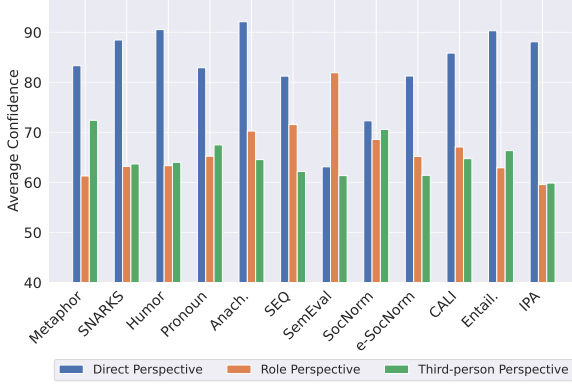


Figure 11: The averaged confidence level by our RPT method in different datasets.

that when confidence exceeds the threshold of approximately 70%, the accuracy of the chosen perspective is significantly higher. This indicates that LLMs are capable of ranking the confidence of perspective for a specific input based on confidence levels.

Using GPT-3.5 as an example, we report in Figure 11 the average confidence for each dataset. Figure 12 shows the human evaluation consistency when estimating the confidence. We find that when evaluating confidence, the estimation of the LLM are highly correlated with those of human experts, indicating that the LLM has the ability to evaluate confidence and select perspectives.

Moreover, RPT generally performs better within high-confidence perspectives, indicating that confidence-based perspective ranking is efficient when choosing among perspectives. In Figure 13, we present the proportion of different perspectives used on each dataset, showing that different datasets have different perspective biases. This suggests that, compared to a single perspective, PRT offers perspective flexibility, which helps RPT achieve optimal performance.

B.2 More Cases of RPT

In Figure 14 and Figure 15, we present several examples from a culturally related NLI task SocNorm and a stance detection dataset SemEval. Take the second case in SemEval task as an example, baseline methods captures strong negative emotions in the input through words like “joke”, “fool” and “betray” and makes judgments about the speaker’s attitude toward Trump based on these cues, overlooking the potential underlying implications of the

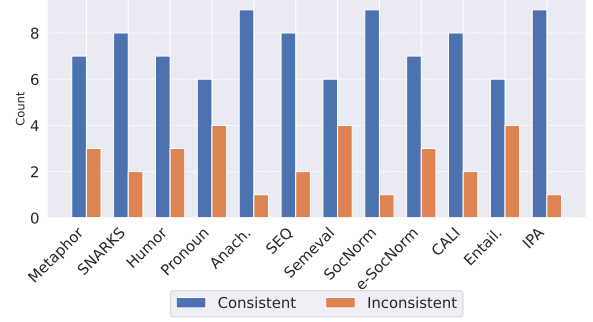


Figure 12: Human evaluation consistency on confidence.

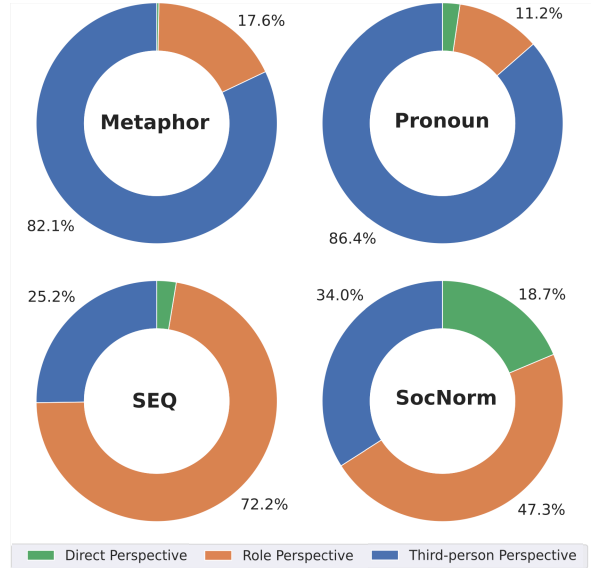


Figure 13: The proportion of selected perspectives for different input questions in each dataset.

text. However, RPT evaluates and selects the third-person perspective, providing the correct analysis by simulating some agents and discussions, illustrating the effectiveness of the RPT in subjective reasoning tasks.

B.3 Full Results of Analysis on the Number of Shots

The full results of analysis on the number of shots is shown in Figure 16. The results are consistent across the four datasets.

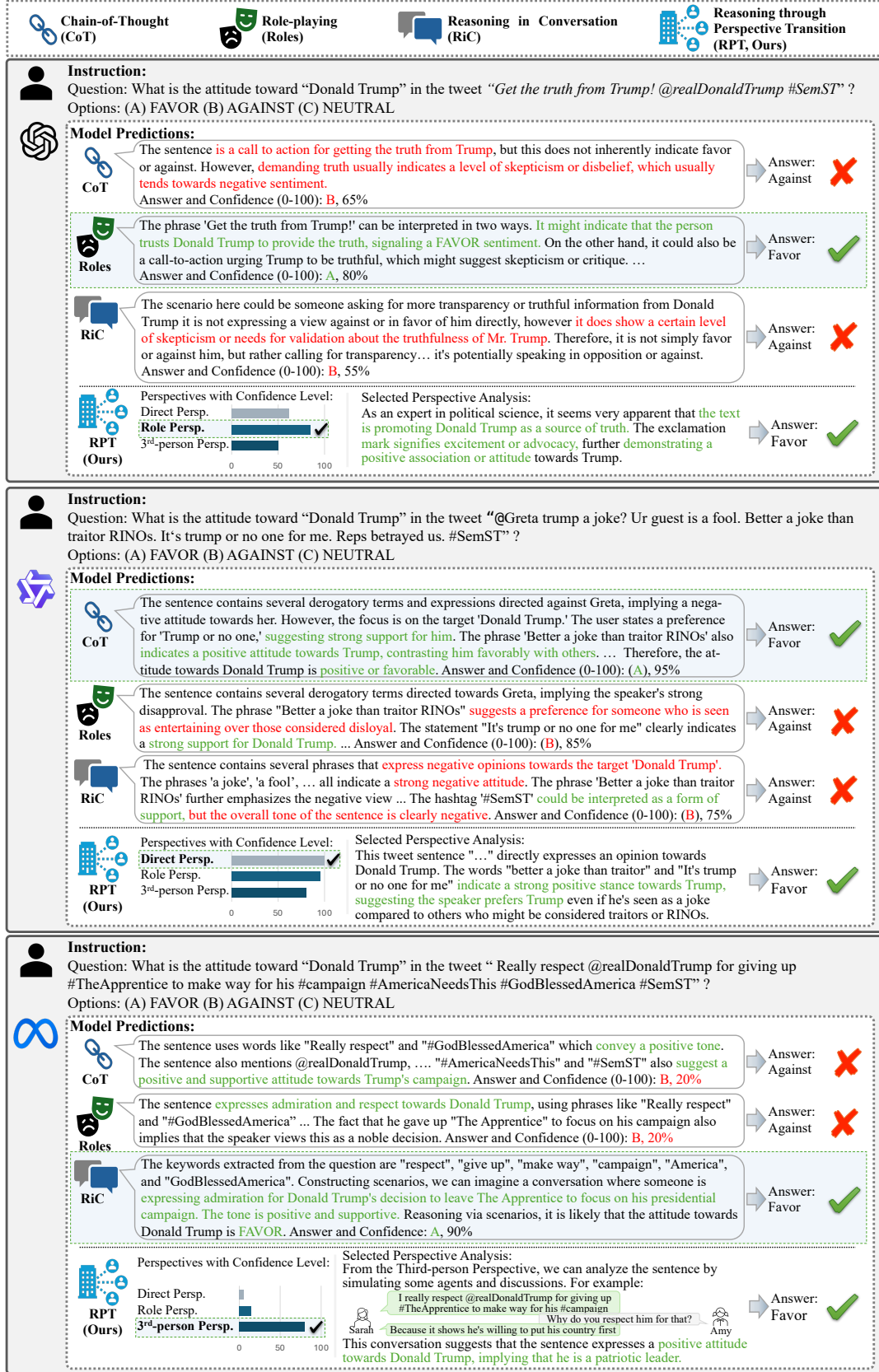
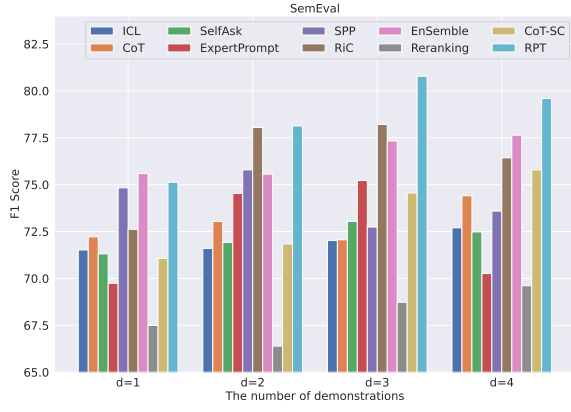


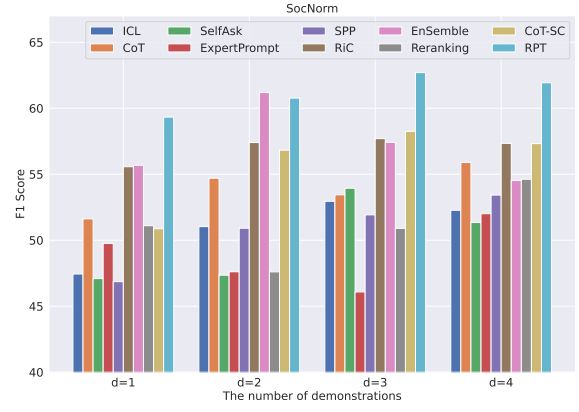
Figure 14: Cases of SemEval task. We provide detailed responses of three models, GPT-4, Qwen-2, and Llama-3, regarding the attitude towards Donald Trump. Our method prompts models to successfully selects suitable perspectives to solve stance detection problems.



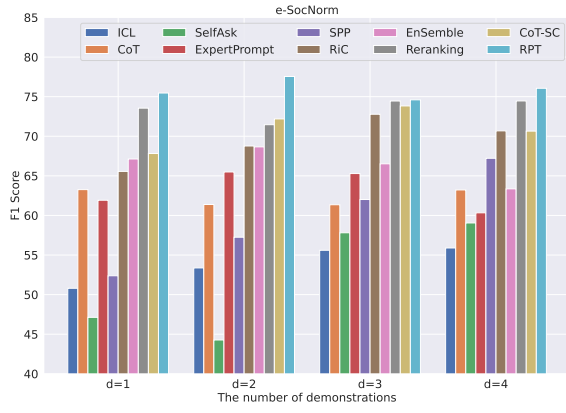
Figure 15: Cases of SocNorm task. We provide results of two widely used models, GPT-4 and Qwen-2. In each of the cases, our proposed method successfully spots the actual meaning behind these norms and leads to the correct answer.



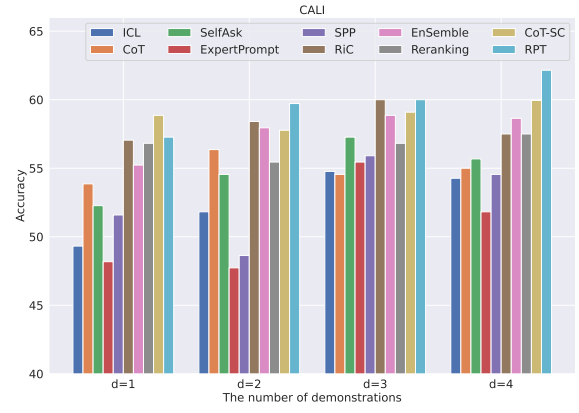
(a) SemEval



(b) SocNorm



(c) e-SocNorm



(d) CALI

Figure 16: The performance of baselines and our RPT method by using different numbers of demonstrations ($d = 1, 2, 3, 4$) in few-shot settings.