
Solar Flare Forecasting with Data-driven Interpretable Model

Anonymous Author(s)

Affiliation

Address

email

Abstract

1 Solar flares are the most violent activities in the solar system, which are caused by
2 the evolution of magnetic field in solar active regions. However, the mechanism
3 which triggers solar flares is still an active research area and many algorithms
4 based on different models are proposed to forecast solar flares. In this paper, we
5 propose a novel data-driven method to forecast solar flares, which is built with
6 convolutional neural network and long short term memory neural network. Our
7 method could precept continuous magnetic field observation data with 6 hours long
8 and predict the probability of flares of different classes in the next 24 hours with a
9 Bayesian neural network. Comparing with traditional method, our method could
10 not only forecast solar flares with high precision rate and low false alarm rate, but
11 also highlight the region which would trigger solar flares with the class activation
12 mapping (CAM). The inception obtained by the CAM could help scientists to dig
13 deeper into physical mechanism which triggers solar flares. We use our method to
14 process real observation data. Results show that our model mainly focuses on the
15 region with strong magnetic field, the polarity reversal line and the magnetic field
16 conversion area, which is consistent to theoretical predictions.

17 1 Introduction

18 The sun is the closest star to the earth, which is also the most important celestial objects to human
19 kind. However, the sun is not a quiet star and solar activities would bring catastrophic effects to the
20 space and the earth. Human built facilities, such as the space station, the communication satellite, the
21 navigation satellite, the plane, the oil pipe or the power grid, would be seriously affected by solar
22 activities. Solar flares are one of the most important solar activities, which would erupt a lot of
23 energy within very short time and greatly affect electromagnetic environment of the Earth and the
24 Space. Therefore, it is of great significance to study the triggering mechanism of solar flares and
25 establish an accurate and reliable solar flare forecasting model, to avoid or reduce the impact of solar
26 flares on human beings.

27
28 The sun is mainly composed of hydrogen and helium. In the centre of the sun, the nuclear fusion
29 happens and emits energy to heat gas inside the sun. As the nuclear fusion continuously emits energy
30 to increase the temperature of the gas, the gas would gradually become the plasma. The plasma has
31 very high moving speed and the gravity would attract the plasma to form a stable celestial object.
32 As a celestial object mainly composed by the plasma, the sun is controlled by the magnetic field.
33 The heating process is not uniform and there would be some occasions that the plasma has very fast
34 moving speed. The churning of plasma would push out through the surface and generate sunspots. In

35 some circumstances, the distance between lower regions (lower corona) of a magnetic loop would be
36 too small and magnetic reconnection would happen to unleash a lot of energy, which would gen-
37 erate solar flares. The level of solar flare is defined by the maximum X-ray brightness of the solar flare.
38

39 As mentioned above, although the general theory about the mechanism which triggers solar flares
40 is clear, it still lacks enough theory to predict when the solar flare happens. For quite a long time,
41 scientists have proposed several different theories to explain mechanism of solar flares and predict
42 solar flares [13, 11, 16]. Traditional solar flare forecasting models mainly rely on manual experience
43 and domain knowledge to extract characteristic parameters related to solar flares from observed data
44 [6, 2, 17, 1, 7]. It is difficult to make full use of the information related to solar flares contained in
45 massive observational data, leaving along the interpretable theory behind these algorithms.
46

47 In recent years, machine learning algorithms have attracted a lot of attentions. Particularly with the
48 help of deep neural networks, deep learning could automatically extract effective features from
49 continuous data, providing a new way to predict solar flares. Since the magnetic field controls
50 solar activities, solar magnetogram would contain important features to predict solar. Therefore,
51 several studies have proposed to use the convolutional neural network, which can automatically
52 extract effective features from images [8, 14, 12, 9, 18], to extract features from single frame of
53 magnetogram for solar flare forecasting. However, previous studies assume solar flare prediction as a
54 classification problem and they have some limitations in real applications for the following reasons:
55 1. The characteristics of physical parameters of continuous solar magnetic field activity region over
56 time are not considered;
57 2. The solar flare prediction problem is regarded as a deterministic problem without considering the
58 random and sudden characteristics of flares.
59

60 Since the solar flare is a continuous process which is closely related to the dynamical variations of
61 the solar active area, we would use the long short-term memory network [3, 4, 15] to merge features
62 from continuous magnetogram. Besides, we use the Bayesian neural network to predict solar flares.
63 Therefore, we build the Bayesian spatio-temporal connection model for solar flare forecasting. To
64 better show the triggering mechanism of solar flares, we use the class activation mapping technology
65 to draw the attention area of the model and analyze the mechanism in triggering of solar flares. This
66 article is organized as follows: a forecasting model based on the deep learning method is proposed
67 in Section 2; The interpretability of the model is investigated in Section 3; The performance of
68 the prediction model and the interpretability of the model in Section 4; Finally, discussions and
69 conclusions are provided in Section 5.
70

71 2 Solar Flare Forecasting Model

72 In this paper, we assume continuous magnetogram frames could be used to predict the probability of
73 solar flares with different classes in the active region. Therefore, solar flare prediction is regarded
74 as a prediction problem with continuous frames of images and the level of solar flare is a random
75 variable. We use the Bayesian spatio-temporal connection solar flare forecasting model to output the
76 probability of solar flares of different classes, which mainly includes two parts: **Feature extractor**
77 and **Forecasting model**. Feature extractor extracts the spatial features of each magnetogram frame
78 and its correlation in the temporal dimension. Forecasting model is used to forecast the maximum
79 X-ray brightness. If we set different threshold, we could output the probability of solar flares with
80 different classes. The overall structure is shown in Figure 1.

81 2.1 The Feature Extractor

82 Extracting spatiotemporal features from continuous magnetogram frames is particularly important
83 for the solar flare prediction task. The combination (LRCN) [5] of convolutional neural networks

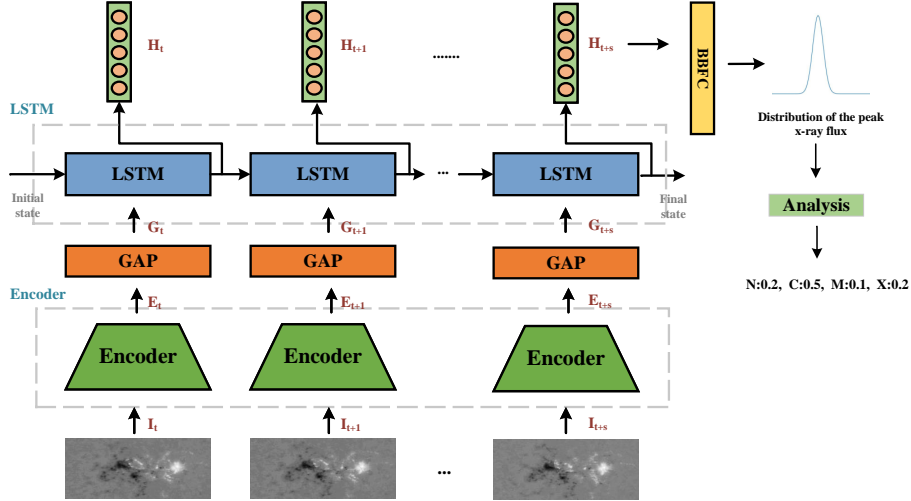


Figure 1: **Data-driven interpretable solar flare forecasting model.** The input of the model are continuous magnetogram frames (6 hours long) of previous time (24 hours before), and the output of the model is the maximum brightness of prediction time period. **Feature extractor** extracts the spatial features of each frame of magnetic map and its correlation in the temporal dimension. **Forecasting model** uses the extracted features to predict the maximum brightness, and we would output prediction results according to the maximum brightness later.

84 (CNNs) and long short-term memory neural networks (LSTM) is mainly used to fully consider the
 85 spatial features and its characteristics over time. The CNN is used to extract image features and the
 86 LSTM is used to analyze the correlation of feature sequences in the temporal dimension. The LRCN
 87 usually requires the size of input images to be the same. However the size of magnetogram frames
 88 would be different. Therefore, we have modified the LRCN by adding a GAP between the CNN and
 89 the LSTM. The structure of the feature extraction part includes the following part:

90 **1. Convolutional neural networks (CNNs)** are suitable for extracting the basic features of images
 91 and reducing the complexity of the model. Therefore, CNNs are used as the spatial feature extraction
 92 network of magnetograms, namely **Encoder**, to capture the spatial interaction, maintain the spatial
 93 continuity of the image, and extract the spatial features of magnetograms. The structure of the
 94 Encoder is shown in the Figure 2, which consists of four convolution block composed of convolution
 95 layer, instance normalization layer and Relu activation function.

96 **2. Global average pooling (GAP)**[10] can compress spatial features extracted by Encoder, pool
 97 images of different sizes to the same size, and reduce the number of parameters in the model to
 98 prevent overfitting. The specific operation is to perform global average pooling on the feature map of
 99 each channel to obtain a value, as shown in the Figure 2.

100 **3. Long Short Term Memory (LSTM)** extracts temporal variations of spatial features of magne-
 101 tograms, so as to study the correlation of continuous magnetic field in the temporal dimension. This
 102 paper use a single-layer bidirectional LSTM structure to extract temporal features, which contains a
 103 hidden layer with 256 nodes and the input data are the spatial features of the continuous magnetic
 104 map extracted by Encoder.

105

106 2.2 The Solar Flare Prediction Model

107 The prediction model is used to forecast solar flare classes according to features extracted by
 108 the **Feature Extractor**. Since the solar flare occurrence and the level of solar flares are random
 109 variables, we propose to use the Bayesian neural network based on probability reasoning for solar
 110 flare prediction. The Bayesian neural network is regularized by introducing uncertainty into the
 111 weight of the neural network, which could achieve a balance between underfitting and overfitting

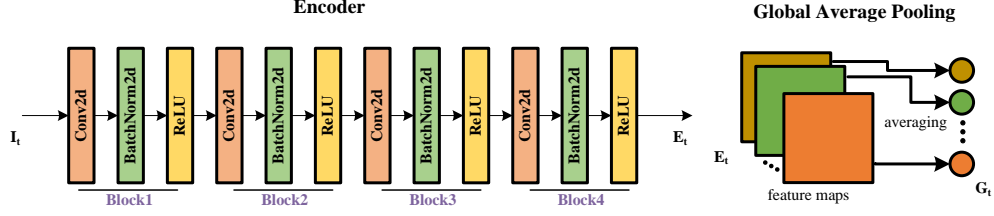


Figure 2: The structure of **Encoder** and **GAP**. After the input single frame image data (C, H, W) passes through four convolution blocks, the image size becomes $(\frac{H}{16}, \frac{W}{16})$, and the number of channels becomes 256. The parameter settings of the convolution kernel in each convolution block are respectively: Block1 (32, 5×5 , 2), Block2 (64, 3×3 , 2), Block3 (128, 3×3 , 2), Block4 (256, 3×3 , 2).

112 by learning the probability distribution over the weights of the neural network. Here, the Bayesian
 113 neural network is used as to predict the distribution of the maximum X-ray brightness, which
 114 uses two layers of bayesian full connection as the output block of the model. If we set the predic-
 115 tion model with different thresholds, we would get the probability of solar flares with different classes.
 116

117 3 Interpretability analysis

118 The solar flare prediction model can learn the statistical relationship between continuous mag-
 119 netograms and solar flares, and regions related to solar flares could be obtained according to the
 120 attention area of the feature extraction model. These regions could be further analyzed to obtain the
 121 mechanism that triggers solar flares. Grad-CAM [10] can help us analyze the attention area of the
 122 model according to input magnetograms.
 123

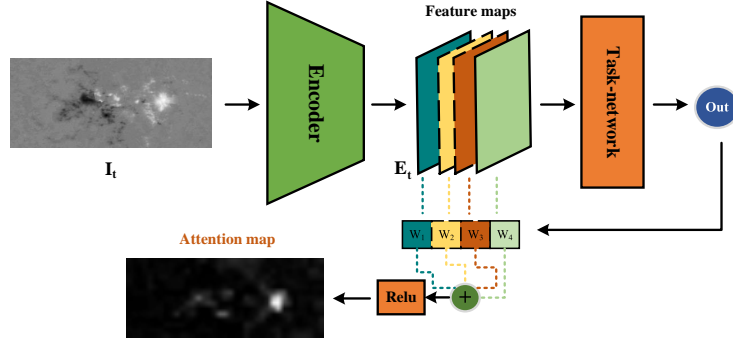


Figure 3: The structure of Grad-CAM.

124 Regression task is taken as the basic task of the model, and the specific flow of Grad-cam is shown in
 125 Figure 3. The model first conducts forward propagation to obtain the feature layer E and the network
 126 predictive value Out . Then the back propagation of Out can get the gradient information of the
 127 feature layer. By calculating the importance of each channel in the feature layer, and then weighted
 128 summing through $ReLU$, the final result is Grad-CAM, as shown from Equation 1 to 2:

$$L_{Grad-CAM} = ReLU\left(\sum_k w_k E^k\right), \quad (1)$$

129 Where E stands for the feature layer output by encoder, k represents the k channel in feature layer
 130 E , E^k stands for the data of channel k in feature layer E , and w_k stands for the weight of network

131 output result for E^k .

$$a_k = \frac{1}{Z} \sum_i \sum_j \frac{\partial y}{\partial E_{ij}^k} \quad (2)$$

132 Where y stands for the predicted value of the network output, K_{ij}^k represents the data at ij of feature
 133 layer E in channel k , Z is equal to $H \times w$. The above equation is used to calculate attention map of
 134 a single image and we would carry out weighted summation of features to obtain Grad-CAM of the
 135 model for different frames.

136

137 4 Experiments and Results

138 4.1 Introduction to the Data Set

139 At present, solar active region data mainly is obtained from the SDO/HMI data and the SOHO/MDI
 140 data. Since 1996, these two types of data have provided consistent, high-quality solar active region
 141 data. Among them, the SOHO/MDI data starts and ends from January 1st, 1996 to April 12th, 2011.
 142 The SDO/HMI project is the successor of the SOHO/MDI project. It has accumulated more than 10
 143 years of data since it started daily observation on April 30th, 2010, and its sampling frequency is 12
 144 minutes. According to the peak value of soft X-ray flux observed by the Geostationary Operational
 145 Environmental Satellite System (GOES), solar flares can be classified into A, B, C, M, and X classes,
 146 with the energy released increasing successively. The values of each class represent the specific values
 147 of the peak X-ray flux. The data can be downloaded from (<https://www.ngdc.noaa.gov/stp/space-weather/solardata/solar-features/solar-flares/x-rays/goes/xrs/>).

149 In this paper, SDO/HMI data with high image data quality are used as magnetogram data. The data
 150 can be downloaded from the SHARPs data sequence in joint scientific operations center (JSOC). We
 151 have downloaded 2010 data. The data of 5-2021.5 (the time interval is 1h) is used as the magnetic
 152 field data of the active area. During the loading process, the SHARP parameter of the active area is
 153 used to check the quality of observation data. The data used in our model has to be 1) disambiguated
 154 with a version of the disambiguation module greater than 1.1, 2) taken while the orbital velocity
 155 of the spacecraft is less than 3500 m/s, 3) of a high quality and 4) within 70 degrees of central meridian.
 156

157 According to GOES, there are 839 active flares larger than A1.0 that meet these requirements between
 158 May 2010 and May 2021. Since solar flares of A and B classes are not significant, we study the
 159 flares with classes greater than C in the training data. In total, there are 5252 flares greater than C1.0
 160 selected in the dataset. The data amount of all kinds of data is shown in Table 1.

Table 1: The classes of solar flares, sample sizes, and label of each type of solar flare

Flare Thresholds	Actual number	label	Train\Test(6,24)
N	5252	0	2299 \ 255
$10^{-6} \leq C < 10^{-5}$	4752	$100 \times n$	1890 \ 210
$10^{-5} \leq M < 10^{-4}$	468	$1000 \times n$	979 \ 109
$10^{-4} \leq X$	4752	$100 \times n$	472 \ 52

161 Previous studies assume flare prediction as a classification task, and there is no relationship between
 162 solar flares of different classes. In fact, solar flares of different classes have particular relations and
 163 we assume it as a regression problem here. According to the peak value of flux in soft X-ray band to
 164 generate label, different classes of flares set different magnitudes, the specific values are shown in
 165 Table 1, where n represents the value of the X-ray peak flow. Meanwhile, this label setting makes
 166 large flares with small amount of data have a bigger loss, which can prevent the overfitting problem
 167 caused by data imbalance.

168 According to the number of solar flares of different levels, multiple time points are randomly selected
 169 from each active area as the starting point of our prediction time, The label is generated according to
 170 whether a flare will occur in the predicted time period, and the data is loaded according to the prior
 171 time period. In the data set, we randomly selected 10% of the active area data as the test set, and the
 172 rest as the training set.
 173

174 4.2 Experiment Result

175 Solar flares forecast model based on data driven, using a large amount of observation data with
 176 labels to have supervision and training of forecast model, study the magnetic figure and the statistical
 177 relationship between solar flares occur, thus to forecast the flare. We also further used the class
 178 activation mapping (CAM) to analyze the triggering mechanism of solar flares. In this paper, we
 179 investigate the performance of the network using 6 hours of continuous magnetic field observations
 180 to predict the probability of various flares occurring within the next 24 hours. The network is trained
 181 using the training set, and when the training process is completed, the performance of the prediction
 182 model can be estimated through the test set.

183 4.2.1 Prediction Results of the maximum X-ray brightness

184 We use the Bayesian neural network as the last layer of the network to predict the distribution of
 185 the highest brightness in the next 24 hours. Since the Bayesian network will learn the probability
 186 distribution as the weight of the neural network, we will get different highest brightness values for a
 187 single sample, forming a distribution, as shown in Figure 4. We show the results of four types of N,
 188 C, M and X prediction, and calculate the corresponding probability of flare occurrence based on the
 189 threshold value defined in Table 1. The title is the time range of the prior time period entered, the
 190 upper left corner is the probability of occurrence in the next 24 hours, the mean and standard deviation.
 191 It should be noted that since the output result of the model is the distribution of the maximum X-ray
 brightness, we can set different thresholds to study the prediction results.

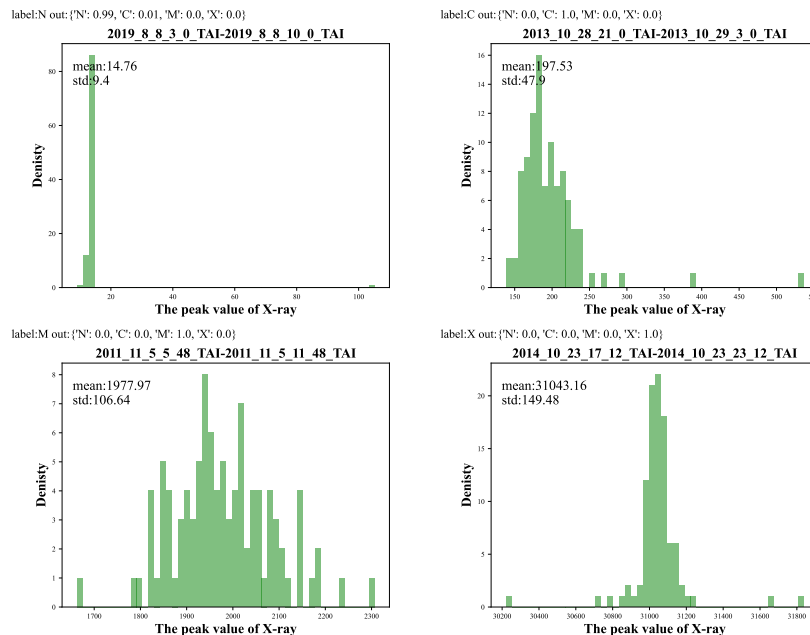


Figure 4: The results of four types of N, C, M and X prediction

193 **4.2.2 Classification results**

194 We randomly select 50 solar flares of different classes in the test set to investigate the overall
 195 performance of the prediction model. For each sample, the result of the model output is the
 196 distribution of the highest brightness in the next 24 hours. We choose the class of the solar flare with
 197 the highest flare probability as the classification result of our neural network.

198

199 For the binary classification task of whether a solar flare occurs or not, we set different thresholds to
 200 study the prediction results of the model. As shown in the following table 2, TP rate is the percentage
 201 of positive instances correctly classified, TN rate is the percentage of negative instances correctly
 202 classified. Pre is the percentage of how many positive predictions are actually positive. Allacc is the
 203 percentage of all correctly classified samples in the total sample. The table shows the comparison
 204 between our algorithm and other traditional algorithms, from which it can be seen that our model can
 205 achieve more than 90 % accuracy for different threshold divisions, and maintain a low false positive
 206 rate.

Table 2: The binary classification result of model

	label	TPrate	TNrate	Pre	Allacc	Train	Test
Huang ²⁰¹⁸	$\geq C$	0.73	0.76	0.35		2010-2015	1996-2010
	$\geq M$	0.85	0.81	0.1			
	$\geq X$	0.87	0.85	0.015			
Park ²⁰¹⁸	$\geq C$			0.84	0.83	2009-2017	1996-2008
Tang ²⁰²¹	$\geq C$	0.878	0.82	0.131			
This work(BBFC)	$\geq M$	0.817	0.84	0.464			
	$\geq C$	0.917	0.959	0.986	0.949		2010-2015(10%)
	$\geq M$	0.910	0.858	0.867	0.884		
This work(FC)	$\geq X$	0.920	0.993	0.979	0.979		
	$\geq C$	0.916	0.877	0.945	0.914		2010-2015(10%)
	$\geq M$	0.830	0.858	0.855	0.844		
	$\geq X$	0.910	0.926	0.863	0.919		

207 We further investigate the performance of our algorithm in prediction solar flares of different levels.
 208 The confusion matrix shows the difference between the actual and predicted values, with the elements
 209 on its main diagonal corresponding to the correct classification, while other elements show how many
 210 samples in a category are incorrectly assigned to other categories as a proportion of the total number
 211 of categories. It shows us intuitively how many solar flares are correctly predicted. It can be seen
 212 from the table 3 that the model makes good predictions for no flares (N) and large flares (X), while
 213 for solar flares with class of C is more likely to be predicted as solar flares with classes of M, and
 214 solar flares with class of M is more likely to be predicted as solar flares with class of C.

215

Table 3: Multiple classifications results of BBfc

label \ label	N	C	M	X
N	0.92	0.08	0.00	0.00
C	0.10	0.58	0.32	0.00
M	0.00	0.12	0.86	0.00
X	0.00	0.00	0.02	0.98

216 In order to verify the performance of Bayesian neural network (BNN), we also transform bayesian
 217 full connection into full connection neural network for comparison, as shown in the table 4. The
 218 results show that Bayesian neural network has better prediction performance, can better distinguish C
 219 and M class flares, improve the accuracy of prediction model.

Table 4: Multiple classifications results of FC

label \ label	N	C	M	X
N	0.90	0.10	0	0.00
C	0.16	0.56	0.24	0.00
M	0.00	0.34	0.60	0.06
X	0.00	0.00	0.06	0.94

220 **4.3 Attention Area of the Solar Flare Forecasting Model**

221 The solar flare prediction model automatically extracts features related to solar flares. If the model
 222 can correctly classify solar flares, it can be considered that the model has extracted effective features.
 223 Here, we use Grad-CAM to study the features extracted by the model. Figure 5 shows a frame of
 224 magnetograms in AR12192, the attention area of the model on the map, and the multiplication result
 225 of these two images. It can be seen that the attention area of the model is mainly in the polarity
 226 reversal region and the strong magnetic field region. Figure 6 shows the variation of the magnetogram
 227 within 24 hours before the occurrence of a large solar flare (the time interval is 3h). This figure shows
 228 variations of the model’s attention area, which is consistent to theoretical predictions.

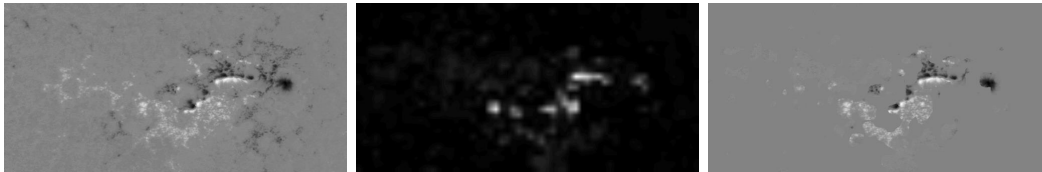


Figure 5: Magnetogram, Heatmap, and Heatmap \times Magnetogram for active regions 12192.

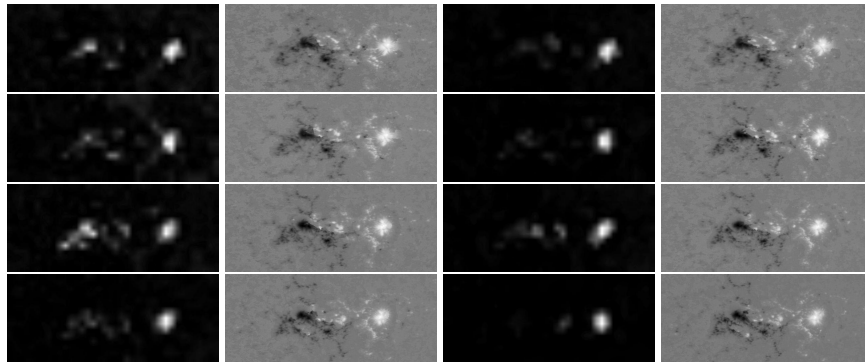


Figure 6: The change of the Magnetogram and Heatmap, within 24 hours before the occurrence of a large flare (the time interval is 3h).

229 **5 Future work**

230 We propose a data-driven solar flare prediction model, which can extract effective features from
 231 continuous Magnetograms to predict distribution of maximum soft X-ray brightness in active regions
 232 over the next 24 hours. Results show that our model could obtain statistical prediction of solar flares
 233 with more than 90 % accuracy, and compared with other algorithms, our algorithm could predict solar
 234 flares with lower false positive rates and higher true positive rates. Besides, our model could extract
 235 effective features for solar flare predictions, which include polar reversal regions, strong magnetic
 236 field regions and the magnetic field conversion area. Our model could help scientists to discover
 237 important features that would trigger solar flares to promote the study of the mechanism that would
 238 trigger solar flares.

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