

Graph-based Fine-grained Multimodal Attention Mechanism for Sentiment Analysis

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Abstract

Multimodal sentiment analysis is a popular research area in natural language processing. Mainstream multimodal learning models barely consider that the visual and acoustic behaviors often have a much higher temporal frequency than words. Therefore, these models lack the representation capability to accurately model multimodal interactions. In this paper, we propose an attachment called Graph-based Fine-grained Multimodal Attention Mechanism (GF-MAM), which can utilize the multimodal information from different subspaces to achieve accurate multimodal interactions. Firstly, the attachment further splits the information of every modality into multiple subspaces. Then, the fine-grained multimodal information from different subspaces is converted into multimodal interaction graphs dominant by the language modality. The multimodal interaction graph can capture significant interactions among multiple modalities at the subspace level. Finally, the information of nonverbal modalities is additionally added to compensate for the loss of continuity caused by the splitting operation. Embedding GF-MAM into BERT, we propose a new model called GF-MAM-BERT that can directly accept nonverbal modalities in addition to language modality. We conducted experiments on both publicly available multimodal sentiment analysis datasets CMU-MOSI and CMU-MOSEI. The experiment results demonstrate that GF-MAM-BERT exceeds the state-of-the-art models. Moreover, the proposed model outperforms humans on most metrics on the CMU-MOSI dataset.

1 Introduction

People sharing their opinions, stories, and movie reviews on video sites like YouTube often involve the information of multiple modalities (language, visual, and acoustic). Since language may be misleading, a model relying solely on language information is insufficient to determine the speaker's

affective state and correctly convey views and options (Williams et al., 2018). Therefore, multimodal sentiment analysis can provide better performance than the methods using only language modality, and it has received increasing attention. The central challenge of multimodal sentiment analysis is to model the *inter-modality* dynamics since the interactions among language, visual, and acoustic modalities can change the perception of the expressed sentiment (Zadeh et al., 2017).

To learn the relationships among modalities, many previous works summarize the information among modalities using simple averaging strategies (Sun et al., 2020; Hazarika et al., 2020; Yu et al., 2021). However, the visual and acoustic behaviors often have a much higher temporal frequency than language, leading to a sequence of accompanying visual and acoustic "subword" units for each uttered word (Wang et al., 2019b). Hence, the information of multimodalities requires fine-grained analysis. The previous works using the simple average strategies have not considered the utilization of the information from multiple subspaces to construct multimodal interactions. Although the simple average strategies may help to model global characteristics, it lacks its representational capacity to accurately model the structure of multimodal interactions at the subspace level. This motivated us to design a model that accurately captures the significant multimodal interactions from different subspaces.

We propose an attachment called GF-MAM that can integrate fine-grained multimodal information from different subspaces. The attachment splits multimodal information into small granularities to obtain multiple feature subspaces. Then the fine-grained information is converted into multimodal interaction graphs to produce different sets of attention weights for different feature subspaces. In the graph, the fine-grained multimodal information and potential relationships between different modalities

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084 are represented as nodes and edges, respectively.
085 The nodes of the language information are the core
086 of the star-like graph since language modality con-
087 tains more practical information than nonverbal
088 modalities (Mai et al., 2019; Sun et al., 2020; Mai
089 et al., 2021). Each fine-grained language node as a
090 reference is connected to the nodes of the two other
091 modalities (acoustic and visual modalities) to con-
092 struct tri-modal interactions. The rich interaction
093 between nodes in the graph neural network can help
094 to capture significant interactions between different
095 modalities. Moreover, since the splitting operation
096 breaks the potential continuity within original infor-
097 mation, we choose to compensate for the continuity
098 within the nonverbal modalities with a residual ap-
099 proach. The multimodal sequence data is fed to
100 GFMAM to obtain compact multimodal represen-
101 tations for shifting the word position (Wang et al.,
102 2019b) in the semantic space.

103 We embed the attachment GFMAM into BERT,
104 which can only process language modality, to give
105 BERT the ability to accept and process nonverbal
106 modalities directly. We evaluate GFMAM-BERT
107 on two popular benchmark datasets of CMU-MOSI
108 (Zadeh et al., 2016) and CMU-MOSEI (Zadeh
109 et al., 2018d). The experiments show that the pro-
110 posed method can produce better performance than
111 the state-of-the-art methods, even outperform the
112 exhibited humans on most metrics.

113 The contributions of this paper are therefore sum-
114 marized as:

- 115 • We design a new multimodal interaction graph
116 dominated by language modality. The graph
117 is capable of capturing significant interactions
118 between multiple modalities at the subspace
119 level.
- 120 • We propose a Graph-based Fine-grained Mul-
121 timodal Attention Mechanism (GFMAM) at-
122 tachment achieving fine-grained multimodal
123 information integration with the help of mul-
124 timodal interaction graphs. Then, this attach-
125 ment is successfully embedded into a large
126 pre-trained model for the sentiment analysis.
- 127 • The proposed model outperforms the state-
128 of-the-art methods. Furthermore, the results
129 demonstrate that the proposed model sur-
130 passes the performance of humans for both
131 binary classification and regression tasks on
132 CMU-MOSI.

2 Related Work 133

2.1 Multimodal Sentiment Analysis 134

135 Multimodal sentiment analysis is a popular re-
136 search area in the field of NLP (Zadeh et al., 2018b).
137 The expressive power of the single language modal-
138 ity is limited by the ambiguity of the language
139 (Williams et al., 2018). The ambiguity usually ap-
140 pears in scenarios including the use of slang and
141 sarcasm. To overcome the limitation of the single
142 language modality, the additional information from
143 multiple modalities can be a significant comple-
144 ment. The works of multimodal sentiment analysis
145 can be divided into two categories according to
146 whether the language modality is dominant.

147 Some methods consider the contribution of each
148 modality is equal for sentiment analysis. Zadeh
149 et al. (2017) created a multidimensional tensor by
150 3-fold Cartesian to capture uni-modal, bi-modal,
151 and tri-modal interactions across three modalities.
152 The LMF model proposed by Liu et al. (2018) de-
153 composes the weights into low-rank factors, thus
154 reducing the number of parameters in the model.
155 This decomposition can be performed efficiently
156 by using a parallel decomposition of the low-rank
157 weight tensor and the input tensor to compute
158 tensor-based fusion. Hazarika et al. (2020) used
159 BERT to extract the feature information of the lan-
160 guage modality and utilized two LSTMs (Hochre-
161 iter and Schmidhuber, 1997) to extract the acoustic
162 and visual modality features. Each extracted modal-
163 ity feature is projected into two different spaces
164 (modality-invariant and modality-specific). Then
165 the information obtained from these projections
166 is concatenated together for the sentiment analy-
167 sis. However, in multimodal sentiment analysis or
168 emotion recognition tasks, textual features usually
169 outperform non-textual features (Sun et al., 2020;
170 Mai et al., 2021; Sun et al., 2021). Therefore, the
171 performance of these approaches is limited by the
172 non-dominant role of the language modality.

173 The language modality is dominant in some
174 methods. Wang et al. (2019b) modeled multimodal
175 human language by shifting interactive word repre-
176 sentations based on the text-video and text-audio in-
177 teractions. The work done by Rahman et al. (2020)
178 is an improvement of pre-trained models. Their
179 proposed Multimodal Adaptation Gate (MAG) can
180 change the word representations using both text-
181 video and text-audio interactions. Then the new
182 word representations are fed to large pre-trained
183 transformers. Sun et al. (2020) constructed two

outer product matrices ($T \otimes V$ and $T \otimes A$) to represent the text-video and text-audio interactions. The outer product matrices are then fed into a Canonical Correlation Analysis (CCA) network whose output is used for prediction. However, their cross-modal interaction is a bi-modal operation that only accounts for two modalities' input at a time. Thus, the proposed GFMAM enables tri-modal interactions in the fine-grained manner. And this interaction establishes the dominance of text features in multimodal sentiment analysis at the same time.

2.2 Graph Neural Networks

Graphs, a non-Euclidean data structure, have a great expressive power to model a set of objects (nodes) and their relationships (edges). Deep learning methods have succeeded in feature extraction of Euclidean data (e.g., images, text, and video). However, the traditional deep learning methods cannot effectively extract the features from the non-Euclidean data (Wu et al., 2020). Graph Neural Networks (GNNs) (Gori et al., 2005; Scarselli et al., 2008) started to try to extend deep neural networks to process the graph-structured data. After that, heterogeneous GNN methods (Wang et al., 2019a; Wei et al., 2019) are further proposed. Nodes in heterogeneous graphs represent different entities.

Recently, a few works have attempted to bring multimodal sequence data into graphs as a way to capture significant interactions among multimodalities. Mai et al. (2020) employed graph convolutional networks for each modality to learn intra-modal dynamics. But it does not explicitly deal with cross-modality information. Wu et al. (2021) modeled multimodal sequence information with the graph-based neural model and capsule network. However, their cross-modal interaction is a bi-modal operation that only accounts for two modalities' input at a time. Based on these works, the natural dependency that exists between different modalities can be introduced to the graph structure. The most relevant work of this paper is the work proposed by Vaswani et al. (2017). They proposed Graph Attention Networks (GATs) using an attention mechanism to determine the weights of node neighborhoods when aggregating feature information. All multimodal information at the subspace level is converted into the heterogeneous nodes of the multimodal interaction graphs. Then the attention mechanism is used to find the attention coefficients between neighboring nodes to establish

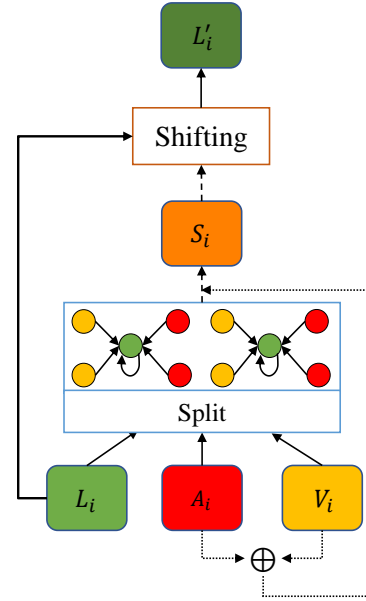


Figure 1: Overview of GFMAM attachment. Using language, visual and acoustic modalities of information as input, a representation of integrated multimodal information is obtained to shift the position of word in the semantic space. \oplus denotes element-wise sum.

the dependencies between modalities.

3 Graph-based Fine-grained Multimodal Attention Mechanism (GFMAM)

This section first introduces the splitting process of the multimodal information. Then, the construction of the multimodal interaction graph using fine-grained data is described in detail. Finally, we describe the complement of the modal internal continuity. The complete flow of the Graph-based Fine-grained Multimodal Attention Mechanism (GFMAM) is shown in Figure 1.

3.1 Fine-grained Multimodal Information

The GFMAM attachment accepts input from the three modalities language, visual, and acoustic modalities. The combination of these three modalities can reflect the emotional state of the speaker. Because the visual and acoustic behaviors often have a much higher temporal frequency than words. To capture the subtle variations among modalities, we separately split the information of three modalities into multiple subspaces.

We denote the multimodal information corresponding to the i -th word by a triple (L_i, V_i, A_i) , where L denotes language features, V denotes visual features, and A denotes acoustic features. The language features are obtained by the embedding

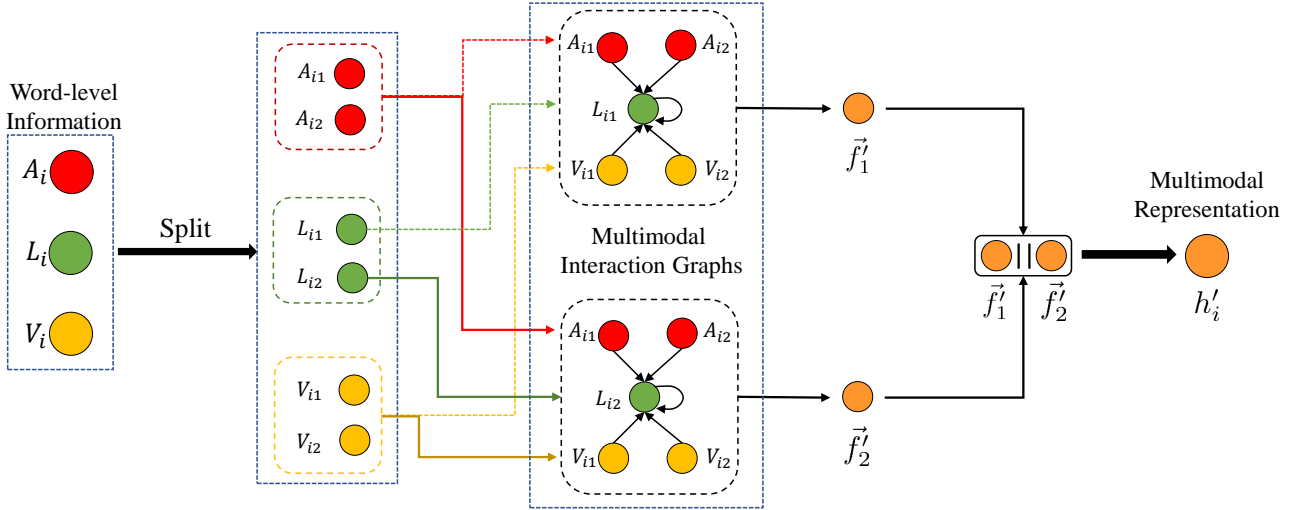


Figure 2: Examples of the multimodal interaction graph. Each modality information is split by $N = 2$. Then, the split results are integrated using the multimodal interaction graph. The final orange node h'_i denotes a new multimodal representation obtained after the operation. $||$ denotes concatenation.

layer. We use two subnets to extract visual and acoustic features, respectively. These extraction operations ensure that the features of the three modalities are in the same dimension. After extraction, a splitting operation is performed on the features of the three modalities. The multimodal features at the word level will be sequentially split into N parts. The fine-grained features of language modality are denoted as: $L_i = \{\vec{L}_{i1}, \vec{L}_{i2}, \dots, \vec{L}_{iN}\}$, where N represents the number of split nodes. Similarly, the split results of visual and acoustic modalities can be denoted as: $V_i = \{\vec{V}_{i1}, \vec{V}_{i2}, \dots, \vec{V}_{iN}\}$ and $A_i = \{\vec{A}_{i1}, \vec{A}_{i2}, \dots, \vec{A}_{iN}\}$. The GFAMAM accepts $h_i = \{\vec{L}_{i1}, \dots, \vec{L}_{iN}, \vec{V}_{i1}, \dots, \vec{V}_{iN}, \vec{A}_{i1}, \dots, \vec{A}_{iN}\}$ as an input. To facilitate the representation, we use $h_i = \{f_1, f_2, \dots, f_M\}$ instead of the above equation, where $M = 3 * N$. The range $[1, N]$ indicates language modality information, $[(N + 1), 2N]$ indicates visual modality information, and $[(2N + 1), 3N]$ indicates acoustic modality information. We use the adjacency matrix in the implementation to control the connection relationship between nodes.

3.2 Multimodal Interaction Graph

After splitting the multimodal information into a smaller granularity, we convert the feature at the subspace level into the multimodal interaction graph. In this graph, the language modality can pay attention to the nonverbal modality features of its neighborhood. Then, the dependencies, which are the attention coefficient between nonverbal modalities and language modalities, are computed using

the attention mechanism.

The importance of node j to node i is represented by e_{ij} , and a weight matrix $W \in R^{d \times d}$ is multiplied with each node to enhance the representation of nodes. The node-to-node attention coefficient is calculated using the function $a(\cdot) : R^d \times R^d \rightarrow R^d$.

$$e_{ij} = a(W\vec{f}_i, W\vec{f}_j), \quad (1)$$

where the range of values of i is $i \in [1, N]$. We only compute e_{ij} for node $j \in \mathcal{X}_i$, where \mathcal{X}_i is some neighborhood of node i in the graph (including i). To make coefficients easily comparable across different nodes, we normalize them across all choices of j using the softmax function:

$$\alpha_{ij} = \text{softmax}_j(e_{ij}) = \frac{\exp(e_{ij})}{\sum_{k \in \mathcal{X}_i} \exp(e_{ik})} \quad (2)$$

Since a is a single-layer feedforward neural network, we add a nonlinear activation function $R(\cdot)$, which can be expressed as:

$$\alpha_{ij} = \frac{\exp(R(a^T[W\vec{f}_i || W\vec{f}_j]))}{\sum_{k \in \mathcal{X}_i} \exp(R(a^T[W\vec{f}_i || W\vec{f}_k]))} \quad (3)$$

where T represents transposition and $||$ is the concatenation operation. The attention coefficients among nodes are then used to update each node that represents the language modality information. The i -th language modality node can be represented as:

$$\vec{f}'_i = R\left(\sum_{j \in \mathcal{X}_i} \alpha_{ij} W\vec{f}_j\right) \quad (4)$$

All nodes are then concatenated to obtain a compact multimodal representation.

$$h'_i = \{\vec{f}'_1 || \vec{f}'_2 || \dots || \vec{f}'_N\} \quad (5)$$

The example as shown in Figure 2 demonstrates this operation for us.

3.3 Compensation of the Continuity within Modalities

The fine-grained multimodalities feature information from different subspaces can help to effectively capture the subtle variations. However, nonverbal modalities are usually presented continuously. Splitting operation may destroy the potential continuity within the nonverbal modalities. Therefore, we compensate for the continuity within the visual and acoustic modalities by a scaling factor β ($\beta < 1$) to decrease the influence on the attention mechanism operation.

$$S_i = h'_i + \beta(V_i \oplus A_i) \quad (6)$$

where \oplus denotes element-wise sum and β is a hyper-parameter selected through the cross-validation process. The obtained new multimodal information S_i is then used to shift the position of the word in the semantic space.

$$L'_i = L_i + S_i \quad (7)$$

4 GFAM-BERT

GFAM-BERT is GFAM embedded between the embedding layer and the transformer layers of the BERT network. Recently, BERT (Bidirectional Encoder Representations from Transformers) (Devlin et al., 2019), Transformer-based (Vaswani et al., 2017) contextual word representations, has shown excellent performance in multiple disciplines within NLP (Rahman et al., 2020). Therefore, BERT is chosen as the basis for sentiment analysis tasks in our work.

Figure 3 clearly shows the exact location of the GFAM attachment embedded in the BERT. There are no changes to the BERT structure except for the attachment of GFAM. The input to BERT is the original words in the language modality. A special token ($[CLS]$) is added in front of each sentence of the input, which is processed by the transformer layers and used for downstream tasks. Assuming that there are N words, the embedding layer input can be expressed as:

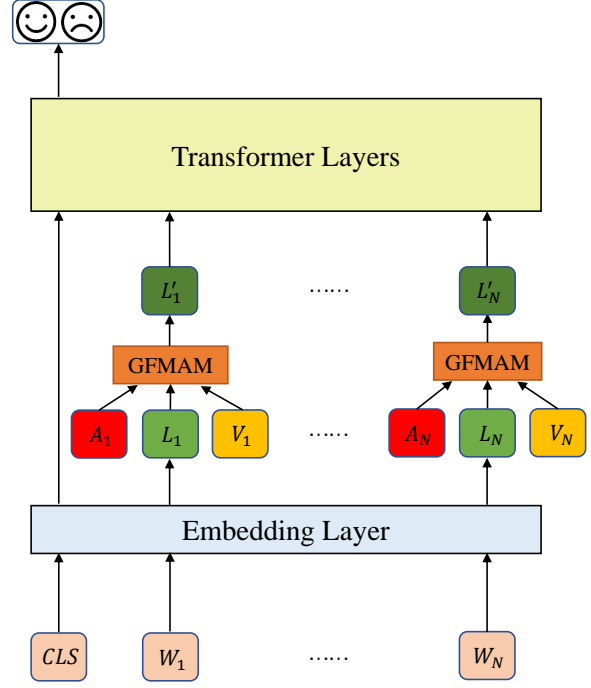


Figure 3: Simplified diagram of the Graph-based Fine-grained Multimodal Attention Mechanism (GFAM) embedded in the specific location of the BERT.

$W = \{CLS, W_1, W_2, \dots, W_N\}$. The W , after WordPiece (Sennrich et al., 2016) embedding operation, will get token embeddings. In addition, segment embeddings and position embeddings need to be added to obtain embedding layer output: $L = \{L_{CLS}, L_1, L_2, \dots, L_N\}$. To keep the same length of the three modalities, add 0 as padding (P) in front of acoustic and visual, respectively. Visual modality can be denoted by $V = \{P, V_1, V_2, \dots, V_N\}$. And, acoustic modality can be denoted by $A = \{P, A_1, A_2, \dots, A_N\}$. To bring these modal information together, we prepare a sequence of triplets $[(L_i, V_i, A_i) : \forall i \in [1, N]]$ by pairing L_i with the corresponding (V_i, A_i) . Each triplet will pass through the attachment GFAM, which is capable of converting each triplet into new multimodal information of the corresponding word embedding. Nonverbal modalities (visual and acoustic) can dynamically adjust the position of words in the semantic space (Wang et al., 2019b). These compact multimodal representations are used to change the position of words in the semantic space. These shifted word representations can be denoted as $L' = \{L_{CLS}, L'_1, L'_2, \dots, L'_N\}$. L' is fed into the transformer layers that follow, and the last transformer layer of output $[CLS]$ is used as a label for multimodal sentiment analysis.

5 Experiments

This section introduces our experimental settings, including the experimental datasets, evaluations, preprocessing, baselines, results, and analysis.

5.1 Datasets

The proposed algorithm is tested using two public benchmark multimodal sentiment analysis and emotion recognition datasets: CMU-MOSI and CMU-MOSEI. These datasets provide word-aligned multimodal signals (language, visual, and acoustic) for each utterance.

CMU-MOSI: The CMU-MOSI is a commonly used dataset for human multimodal sentiment analysis. It consists of 2,198 short monologue video clips (each clip lasts for the duration of one sentence) expressing the opinion of the speaker inside the video on a topic such as movies. The utterances are manually annotated with a continuous opinion score between $[-3, +3]$, $[-3$: highly negative, -2 negative, -1 weakly negative, 0 neutral, $+1$ weakly positive, $+2$ positive, $+3$ highly positive].

CMU-MOSEI: The CMU-MOSEI is an improved version of CMU-MOSI. It contains 23,453 annotated video clips (about 10 times more than CMU-MOSI) from 5,000 videos, 1,000 different speakers, and 250 different topics. The number of discourses, samples, speakers, and topics is also larger compared to CMU-MOSI. The range of labels taken for each discourse is consistent with CMU-MOSI.

5.2 Preprocessing

We utilize the standard low-level features that are provided by the respective benchmarks.

Language Modality: Traditionally, language modality features have been GloVe (Pennington et al., 2014) embeddings for each token in the utterance. GloVe features are 300 dimension token embeddings. However, recent works (Rahman et al., 2020; Hazarika et al., 2020) have demonstrated that BERT can provide better performance than GloVe in feature extraction. Therefore, BERT is used to obtain the features of language modality in the proposed method. We utilize the *bert-base-uncased* and *bert-large-uncased* pre-trained models.

Visual Modality: CMU-MOSI and CMU-MOSEI use Facet to extract facial expression features, including facial action units and facial gestures based on a Facial Action Coding System (FACS) (Ekman and Rosenberg, 1997). This process is repeated

for each sampled frame within the utterance video sequence. The final visual feature dimensions, d_v , are 47 for CMU-MOSI, 35 for CMU-MOSEI.

Acoustic Modality: COVAREP (Degottex et al., 2014) is used to extract the following relevant features: fundamental frequency, quasi-open quotient, normalized amplitude quotient, glottal source parameters (H1H2, Rd, Rd conf), VUV, MDQ, the first 3 formants, PSP, HMPDM 0-24 and HM-PDD 0-12, spectral tilt/slope of wavelet responses(peak/slope), MCEP 0-24. The final acoustic feature dimension, d_a , is 74 for MOSI/MOSEI.

For each word, we align all three modalities following the convention established in (Chen et al., 2017). Assuming that there are T words in the video, the features for language can be denoted as $T \times d_l$, for visual as $T \times d_v$, and for acoustic as $T \times d_a$.

5.3 Evaluation Criteria

The evaluation metrics of MISA are referred to in the experiments(Hazarika et al., 2020). There are five evaluation metrics, namely Mean Absolute Error (MAE), Pearson Correlation (Corr), Binary Accuracy (Acc-2), F1-Score, and Seven-class Accuracy (Acc-7). MAE and Corr are regression tasks. Acc-2, F1-Score, and Acc-7 are classification tasks. For the calculation of Acc-2, two different evaluation methods are included. The first one is negative/non-negative classification (Zadeh et al., 2018c), where non-negative includes neutral sentiment information. The second one is negative/positive classification (Tsai et al., 2019), excluding neutral sentiments information. The results of all evaluation metrics mentioned above are reported.

5.4 Baselines

The various state-of-the-art models introduced following are used as the baseline for comparison.

TFN: Tensor Fusion Network (TFN) (Zadeh et al., 2017) performs an outer product of the output vectors after encoding the three modes to learn the intra- and inter-modal dynamics in an end-to-end manner and can capture uni-, bi-, and tri-modal interactions.

MFN: Memory Fusion Network (MFN) (Zadeh et al., 2018a) uses three separate LSTMs to model each modality and uses Delta-memory attention and Multi-View Gated Memory to capture both temporal and inter-modal interactions.

| Models | CMU-MOSI | | | | |
|----------------------|--------------|--------------|------------------|------------------|-------------|
| | MAE↓ | Corr↑ | Acc-2↑ | F1-Score↑ | Acc-7↑ |
| TFN | 0.970 | 0.633 | 73.9/- | 73.4/- | 32.1 |
| MFN | 0.965 | 0.662 | 77.4/- | 77.3/- | 34.1 |
| RMFN | 0.922 | 0.681 | 78.4/- | 78.0/- | 38.3 |
| MuT | 0.871 | 0.698 | -/83.0 | -/82.8 | 40.0 |
| MTAG | 0.889 | 0.686 | -/82.1 | -/82.3 | 38.9 |
| MG | 0.933 | 0.684 | -/80.6 | -/80.5 | 32.1 |
| TFN(B) ¹ | 0.901 | 0.698 | -/80.8 | -/80.7 | 34.9 |
| MFN(B) ¹ | 0.877 | 0.706 | -/81.7 | -/81.6 | 35.4 |
| RMFN(B) ² | 0.878 | 0.712 | 79.6/89.7 | 78.9/79.1 | - |
| MuT(B) ² | 0.861 | 0.711 | 81.5/84.1 | 80.6/83.9 | - |
| ICCN | 0.862 | 0.714 | -/83.07 | -/83.02 | 39.01 |
| MISA | 0.783 | 0.761 | 81.8/83.4 | 81.7/83.6 | 42.3 |
| MAG | 0.712 | 0.796 | 84.2/86.1 | 84.1/86.0 | - |
| Ours* | 0.689 | 0.809 | 84.3/86.4 | 84.2/86.2 | 48.6 |
| Human | 0.710 | 0.820 | 85.7/- | 87.5/- | 53.9 |
| Ours [†] | 0.651 | 0.835 | 86.0/88.2 | 86.0/88.2 | 50.6 |

Table 1: Performances of multimodal models on CMU-MOSI. Best results are highlighted in bold. NOTE: (B) means the language features are based on BERT; - means the result is not given in the paper; * means the text feature is based on *bert-base-uncased*; [†] means the text feature is based on *bert-large-uncased*; ¹ is from (Sun et al., 2020) and ² is from (Rahman et al., 2020). Human performance for CMU-MOSI is reported as (Zadeh et al., 2018c). In Acc-2 and F1-Score, the left of the “/” is calculated as “negative/non-negative” and the right is calculated as “negative/positive”.

RMFN: Multimodal Language Analysis with Recurrent Multistage Fusion (RMFN) (Liang et al., 2018) can automatically decompose the multimodal fusion problem into multiple recursive stages. At each stage, a subset of the multimodal signals is highlighted and fused with the previous fusion representation.

MuT: Multimodal Transformer for Unaligned Multimodal Language Sequence (MuT) (Tsai et al., 2019) extends the multimodal transformer architecture by using directional paired cross-attention to transform one modality into another.

ICCN: For Learning Relationships between Text, Audio, and Video via Deep Canonical Correlation for Multimodal Language Analysis, Interaction Canonical Correlation Network (ICCN) (Sun et al., 2020) first extracts features from audio and video modalities, and then fuses them with text embeddings to get two outer products, text-audio, and text-video. Finally, the external products are fed into CCA network, and their output is used to predict.

MG: Analyzing Unaligned Multimodal Sequence via Graph Convolution and Graph Pooling Fusion (MG) (Mai et al., 2020) first uses a graph convolu-

| Models | CMU-MOSEI | | | | |
|---------------------|--------------|--------------|------------------|------------------|-------------|
| | MAE↓ | Corr↑ | Acc-2↑ | F1-Score↑ | Acc-7↑ |
| TFN(B) ¹ | 0.901 | 0.698 | -/80.8 | -/80.7 | 34.9 |
| MFN(B) ¹ | 0.568 | 0.717 | -/84.4 | -/84.3 | 35.4 |
| MG | 0.608 | 0.675 | -/81.4 | -/81.7 | 49.7 |
| MuT | 0.580 | 0.703 | -/82.5 | -/82.3 | 51.8 |
| ICCN | 0.565 | 0.713 | -/84.2 | -/84.2 | 51.6 |
| MISA | 0.555 | 0.756 | 83.6/85.5 | 83.8/85.3 | 52.2 |
| MAG ³ | 0.539 | 0.753 | 83.7/85.2 | 83.7/85.0 | - |
| Ours [†] | 0.517 | 0.786 | 85.2/86.9 | 85.0/86.8 | 54.9 |

Table 2: Performances of multimodal models on CMU-MOSEI. Best results are highlighted in bold. NOTE: (B) means the language features are based on BERT; - means the result is not given in the paper; ¹ is from (Sun et al., 2020) and ³ is from (Yu et al., 2021).

tional network to learn intra-modal dynamics for each modality. Then, a graph pooling fusion network is devised to automatically learn the associations between various nodes from different modalities.

MISA: Modality-Invariant and -Specific Representations for Multimodal Sentiment Analysis (MISA) (Hazarika et al., 2020) combines various losses, including distribution similarity, orthogonal loss, reconstruction loss, and task prediction loss, to learn modality-invariant and modality-specific representations.

MAG: Integrating Multimodal Information in Large Pretrained Transformers (MAGT) (Rahman et al., 2020) is an improved work on RAVEN, which applies Multimodal Adaptive Gate (MAG) on different layers of the BERT backbone.

MTAG: Modal-Temporal Attention Graph for Unaligned Human Multimodal Language Sequences (Yang et al., 2021) first convert unaligned multimodal sequence data into a graph. Then, an operation called MTAG is designed to capture the various interactions among multimodalities.

For TFN, MFN, RMFN, and MuT, the language features are based on GloVe, while ICCN, MISA, MAG, Self-MM, and our model use language features based on BERT. For the sake of fairness, we also provide the results of these models using BERT to obtain language features.

5.5 Comparison with Baselines

Table 1 shows the results of our model in comparison with other models and humans on the CMU-MOSI dataset. It can be observed that the model proposed in this paper works better, and all the evaluation metrics are better than other models. As compared to other work that relies on graph

| Data View | CMU-MOSI | | | | |
|---------------|----------|-------|-----------|-----------|--------|
| | MAE↓ | Corr↑ | Acc-2↑ | F1-Score↑ | Acc-7↑ |
| No Compensate | 0.652 | 0.820 | 85.7/88.2 | 85.7/88.2 | 50.2 |
| Compensate | 0.651 | 0.835 | 86.0/88.2 | 86.0/88.2 | 50.6 |

Table 3: Results for experiments on CMU-MOSI. We compare the best results obtained with and without the compensation operation on the CMU-MOSI dataset.

neural networks, like MTAG and GM, our model exhibits excellent performance. The reason is that our model takes into account the use of information from different subspaces to construct tri-modal interactions. And a text-dominant multimodal fusion scheme is designed. Also, Zadeh et al. (2018c) reported human performance results on the CMU-MOSI dataset. We can observe that performance results outperform human performance in binary classification (Acc-2) and regression tasks (MAE, Corr). To the best of our knowledge, the accuracy of binary classification exceeds that of humans for the first time.

Table 2 shows the performance results of our model on the CMU-MOSEI dataset, where all evaluation metrics outperform the other models. The performance exhibited by our model validates the usefulness of constructing multimodal interactions at the subspace level. Based on the evaluation results of two publicly available datasets, our proposed model is successful for multimodal sentiment analysis.

5.6 Ablation Studies

To verify the effectiveness of the proposed model, the following ablation experiments are designed. There are two questions.

Question 1: Is it useful to compensate for the continuity within the modalities?

Question 2: Is the splitting processing effective for multimodal sentiment analysis?

For **Question 1**, we compare our proposed model on the CMU-MOSI dataset in different cases. These cases include the model with and without continuity complement. As shown in Table 3, the result of the model with complement is a little better than the model without complement. The experiment results demonstrate that although the improvement of the complement is not obvious, the information of the modality continuity is disrupted by the splitting operation. Therefore, the complement of internal continuity is required when the splitting operation is performed on modal information.

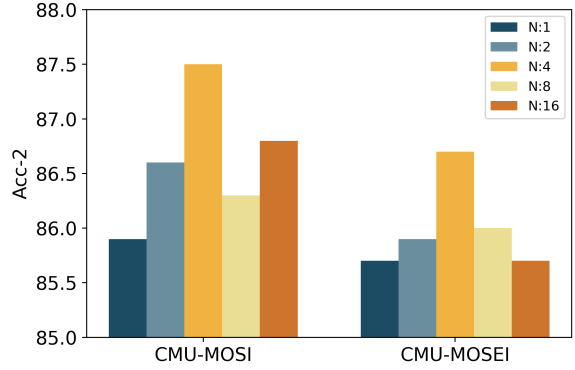


Figure 4: Results for experiments on CMU-MOSI and CMU-MOSEI. The performance exhibited by our model under different fine-grained multimodal information. N denotes the number of splits for each modality.

For **Question 2**, during the experiments, we split multimodal information into different granularities, keeping the rest of the hyper-parameters constant. Figure 4 shows the results of the binary classification obtained after splitting each modality for the CMU-MOSI and CMU-MOSEI datasets, where N denotes the number of nodes. And when N=1, it means that the modal information will not be split, that is, the original sampling rate will be maintained. The cases of N>1 are significantly better than those for N=1. The results validate that integrating multimodal information at the subspace level can improve the performance of sentiment analysis.

6 Conclusion

In this paper, we propose a novel GFMAM attachment, which can effectively fuse fine-grained multimodal information at the subspace level for sentiment analysis. Without changing the architecture of the original BERT, the fine-grained multimodal information is effectively fused with the graph structure. Furthermore, we demonstrate that multimodal information is necessary for fine-grained interactions by conducting ablation studies in our models. The experimental results demonstrate the effectiveness of the proposed method when doing sentiment analysis tasks and show the best performance on public datasets.

In the future, the fine-grained multimodal interactions across multiple moments will be considered to further improve the performance of the sentiment analysis.

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