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ABSTRACT

Molecular dynamics (MD) simulations underpin modern computational drug discovery, materials science, and biochemistry. Recent machine learning models provide high-fidelity MD predictions without the need to repeatedly solve quantum mechanical forces, enabling significant speedups over conventional pipelines. Yet many such methods typically enforce strict equivariance and rely on sequential rollouts, thus limiting their flexibility and simulation efficiency. They are also commonly single-task, trained on individual molecules and fixed timeframes, which restricts generalization to unseen compounds and extended timesteps. To address these issues, we propose Atomistic Transformer Operator for Molecules (ATOM), a pretrained transformer neural operator for multitask molecular dynamics. ATOM adopts a quasi-equivariant design that requires no explicit molecular graph and employs a temporal attention mechanism, enabling accurate parallel decoding of multiple future states. To support operator pretraining across chemicals and timescales, we curate TG80, a large, diverse, and numerically stable MD dataset with over 2.5 million femtoseconds of trajectories across 80 compounds. ATOM achieves state-of-the-art performance on established single-task benchmarks, such as MD17, RMD17 and MD22. After multitask pretraining on TG80, ATOM shows exceptional zero-shot generalization to unseen molecules across varying time horizons. We believe ATOM represents a significant step toward accurate, efficient, and transferable molecular dynamics models.

1 INTRODUCTION

Molecular dynamics (MD) serves as a computational microscope of atomic motion and is now integral to drug discovery and materials science pipelines (Dror et al., 2012; De Vivo et al., 2016). In ab initio molecular dynamics, quantum-mechanical density functional theory (DFT) is used to compute atomic forces, and the resulting equations of motion are integrated to generate high-fidelity trajectories. However, DFT’s computational complexity scales at least cubically with the number of atoms, and relies on double-precision arithmetic that limits GPU acceleration (Kresse & Furthmüller, 1996; Stein et al., 2020; Li et al., 2024).

Neural approaches have recently emerged as a promising solution to the scalability bottleneck. *Equivariant* architectures, in particular, encode physical symmetries to model interatomic dynamics, achieving ab initio-level accuracy at significantly reduced computational cost (Batzner et al., 2022; Musaelian et al., 2022; Batatia et al., 2022; 2023; Xu et al., 2024). While equivariance is often deemed essential for improving generalization, strict symmetry preservation involves substantial tradeoffs (Xu et al., 2024; Schreiner et al., 2023). Architectures that enforce exact equivariance at every layer often increase computational overhead, restrict model expressivity, and complicate optimization (Fuchs et al., 2020; Brehmer et al., 2023; Elhag et al., 2025). It is unclear whether symmetry constraints can be relaxed without sacrificing accuracy for molecular dynamics.

Furthermore, most existing methods for molecular dynamics are *autoregressive*, predicting the next state based on the current one (Köhler et al., 2019; Fuchs et al., 2020; Thiemann et al., 2025). Autoregressive approaches often struggle to capture long-horizon temporal dependencies and accumulate error as the prediction horizon grows (Bengio et al., 2015; Bergsma et al., 2023; Taieb & Atiya, 2016). Inference speeds are also constrained by the need for sequential integration, failing to exploit modern, highly parallel compute architectures. One exception is Equivariant Graph Neural

054 Operator (EGNO) (Xu et al., 2024), which models the entire trajectory with neural operator learning.
 055 Nevertheless, EGNO enforces strict equivariance and is single-task in nature, i.e., it is trained and
 056 evaluated on trajectories of each molecule separately with a fixed time horizon, which limits *zero-shot*
 057 *generalization* to unseen molecules or timeframes.

058 **Our Main Contributions.** In this work, we address the above issues regarding equivariance,
 059 autoregression, and zero-shot generalization within a unified framework, which we call *Atomistic*
 060 *Transformer Operator for Molecules (ATOM)*. To this end, we propose a pre-trained neural operator
 061 with a transformer backbone for molecular dynamics and introduce a new MD dataset, TG80, which
 062 is both chemically diverse and numerically stable for multitask pretraining and benchmarking.
 063

- 064 • *Design innovations.* ATOM is *quasi-equivariant* by employing an equivariant lifting layer that
 065 produces symmetry-aware features, while allowing subsequent transformer blocks to be uncon-
 066 strained for flexibility and expressiveness. Unlike autoregressive models, ATOM allows *parallel*
 067 *decoding* of molecule states across multiple timesteps, directly learning the trajectory operator. By
 068 encoding time lags via a novel temporal rotary position embedding, ATOM enhances temporal
 069 interpolation and extrapolation, enabling robust predictions across multiple time horizons. Finally,
 070 ATOM requires no predefined molecular graph and operates directly on *point clouds*, naturally
 071 accommodating long-range spatial interactions without the need for hand-crafted connectivity.
- 072 • *Performance highlights.* ATOM sets new state-of-the-art on single-task MD benchmarks. For larger,
 073 sparsely connected molecules in MD22, ATOM significantly outperforms existing graph-based
 074 baselines by capturing the long-range atomic interactions. In the multitask regime, we pretrain
 075 ATOM on TG80 trajectories from multiple molecules and varying timeframes, demonstrating
 076 significant zero-shot transfer to both unseen molecules and timesteps, improving existing baselines
 077 by 39.75% on average. This achieves performance on par with existing specialized baselines
 078 tailored for such molecules and timeframes. To the best of our knowledge, this is the first method
 079 that demonstrates such generalization capability in molecular dynamics.

080 We believe our work represents a shift in molecular dynamics modeling, where we demonstrate the
 081 potential of quasi-equivariance designs and zero-shot generalization to out-of-domain systems, which
 082 is enabled by the comprehensive TG80 MD dataset.

084 2 RELATED WORK

086 **Equivariant Neural Networks.** Equivariance (to transformations such as rotation, reflection, and
 087 translation) has emerged as an essential physics-informed prior for deep learning models on molecular
 088 data (Bronstein et al., 2021; Duval et al., 2023). Early works employed convolutional approaches
 089 to achieve translation equivariance in E(3) (Weiler et al., 2018; Wu et al., 2020) or tensor product
 090 attention and spherical harmonics to enforce roto-translational equivariance in SE(3) (Fuchs et al.,
 091 2020; Thomas et al., 2018). In contrast, message passing neural network (MPNN) frameworks, such
 092 as Equivariant Graph Neural Network (EGNN) and others (Garcia Satorras et al., 2021; Gasteiger
 093 et al., 2021; Huang et al., 2022), achieve equivariance by operating on strictly equivariant features,
 094 such as inter-node distances and directions. While effective, MPNNs typically assume a fixed
 095 molecular graph. This is problematic when the underlying structure contains non-local interactions
 096 and dynamic bonding effects (e.g., resonances, transient interactions), which render predefined
 097 graphs inaccurate over time (Knutson et al., 2022; Luo et al., 2021). To address this issue, we model
 098 molecules as point clouds, with our attention represented as a fully connected graph that allows
 099 unrestricted information propagation across the molecule.

100 **Time-coarsened Molecular Dynamics** Time coarsening is a coarse-graining method which preserves
 101 molecular structure, but compresses many short integration steps into a few large-stride updates to
 102 reduce the cost of long-time simulation (Kmiecik et al., 2016). Stochastic coarse-graining approaches
 103 often learn transition kernels on configuration space, bypassing explicit integration of the equations
 104 of motion. Klein et al. (2023) learns such a kernel with a normalizing flow and uses it as an MCMC
 105 proposal targeting the Boltzmann distribution, Hsu et al. (2024) uses a conditional diffusion model
 106 to learn a transition probability matrix, and Yu et al. (2025) uses flow-matching to learn a vector
 107 field transporting current states to future states. Closer to our framework, deterministic methods
 108 such as MDNet (Zheng et al., 2021) and TrajCast (Thiemann et al., 2025) learn a GNN and EGNN,
 109 respectively, which autoregressively predict fixed strides 10-100 times larger than those of MD

108 integrators. Bigi et al. (2025) incorporates Hamiltonian structure and explicit energy-conservation.
 109 Most of the methods require direct force learning and are sequential in nature, while ATOM may be
 110 interpreted as a *force-free* deterministic coarse-graining approach, wherein temporal pushforward is
 111 approximated by a learned propagation operator which is decoded *in parallel*.

112 **Neural Operators.** Neural operators are deep learning methods for learning operators between
 113 function spaces (Kovachki et al., 2021). A wide variety of architectures have been proposed for such
 114 operator learning. Notably, Fourier Neural Operator (FNO) (Li et al., 2021) learns an operator in
 115 the Fourier domain, while its derivatives G-FNO (Helwig et al., 2023) and PINO (Li et al., 2023b),
 116 respectively, add group equivariance and physics-informed properties. Xu et al. (2024) bridges this
 117 framework with molecular dynamics by recasting the task as learning a propagation operator that
 118 evolves historical atomic positions into their future configurations. Specifically, EGNO (Xu et al.,
 119 2024) is proposed by integrating EGNN and FNO layers to learn dynamic trajectories, capturing
 120 both spatial and temporal correlations. Recently, transformer neural operators (Bryutkin et al.,
 121 2024; Hao et al., 2023; Li et al., 2023a) have surpassed the performance of FNO in most partial
 122 differential equation (PDE) tasks. Notably, OFormer (Li et al., 2023a) uses a linear Galerkin-type
 123 attention mechanism, which omits the softmax and instead interprets the latent column vectors as
 124 basis functions. General Neural Operator Transformer (GNOT) (Hao et al., 2023) employs a novel
 125 subquadratic cross-attention methodology to integrate multiple feature types (e.g., shape and point
 126 relationships) into their transformer blocks. With ATOM, we unify the MD problem formulation and
 127 temporal discretization approach introduced by EGNO with the increased representational power of
 128 transformers in operator settings.

129 **MD Benchmarks.** Research on graph machine learning for molecular dynamics suffers from
 130 poor benchmarking (Bechler-Speicher et al., 2025). For example, despite the fact that MD17
 131 Benzene exhibits non-physical noise approximately 1000 times higher compared to other compounds
 132 (Christensen & von Lilienfeld, 2020), it is still regularly employed to benchmark new models (Bihani
 133 et al., 2023; Huang et al., 2022; Liao & Smidt, 2023; Xu et al., 2024). The practical relevance of
 134 single-task learning on these datasets is also dubious, as predicting trajectories for molecules with
 135 existing numerical solutions offers minimal benefit. We believe the strengths of neural approaches
 136 emerge in transfer learning, where models generalize to unseen compounds, thereby circumventing the
 137 computational costs associated with explicit numerical simulations. This motivates our development
 138 of TG80 to facilitate multitask dynamics learning across molecular systems.

139 3 ATOMISTIC TRANSFORMER OPERATOR FOR MOLECULES (ATOM) 140

141 In this section, we first introduce the problem formulation (Section 3.1) and then propose the
 142 framework of ATOM by introducing the key model and training designs (Section 3.2). We then
 143 discuss the multitask pretraining for ATOM and introduce TG80 MD dataset (Section 3.3).

144 3.1 PROBLEM FORMULATION

147 We follow (Xu et al., 2024) to cast molecular dynamics prediction as operator learning. We model a
 148 molecule of N atoms as a point cloud in \mathbb{R}^3 , which we denote as $\mathcal{G}^{(t)}$ for a given system state time t .
 149 In particular, we write $\mathcal{G}^{(t)} = (\mathbf{x}_i^{(t)}, \mathbf{v}_i^{(t)})_{i=1}^N$ that represent molecules in terms of the atom positions
 150 \mathbf{x} and velocities \mathbf{v} . Our objective is to predict a future trajectory $\mathcal{G}^{(t+\Delta t)}$, where $\Delta t \in [0, \Delta T]$.

151 Similar to (Xu et al., 2024), we focus on predicting the position states only. Let $\mathcal{U}: [0, \Delta T] \rightarrow \mathbb{R}^{N \times 3}$
 152 be the trajectory function mapping Δt to $U(\Delta t) \in \mathbb{R}^{N \times 3}$ representing molecule positions Δt in
 153 the future. We assume a solution operator $F^\dagger: \mathcal{G}^{(t)} \rightarrow \mathcal{U}$ exists which provides the underlying
 154 future trajectory given system states at t . Thus, the goal of molecular dynamics prediction be-
 155 comes training a neural operator $F_\theta(\mathcal{G}^{(t)})$ to approximate the target trajectory function $F^\dagger(\mathcal{G}^{(t)})$:
 156 $\min_\theta \mathbb{E}_{\mathcal{G}^{(t)}} \mathcal{L}(F_\theta(\mathcal{G}^{(t)})(t), F^\dagger(\mathcal{G}^{(t)})(t))$, for some loss function $\mathcal{L}: \mathcal{U} \times \mathcal{U} \rightarrow \mathbb{R}$. Here, expectation
 157 is with respect to the different initial states. By discretizing over the temporal domain and considering
 158 L_2 loss, we optimize the neural operator with a discretized temporal sampling of the states:
 159

$$160 \min_\theta \frac{1}{P} \sum_{p=1}^P \mathbb{E}_{\mathcal{G}^{(t)}} \left\| F_\theta \left(\mathcal{G}^{(t)} \right) (\Delta t_p) - F^\dagger \left(\mathcal{G}^{(t)} \right) (\Delta t_p) \right\|_2^2. \quad (1)$$

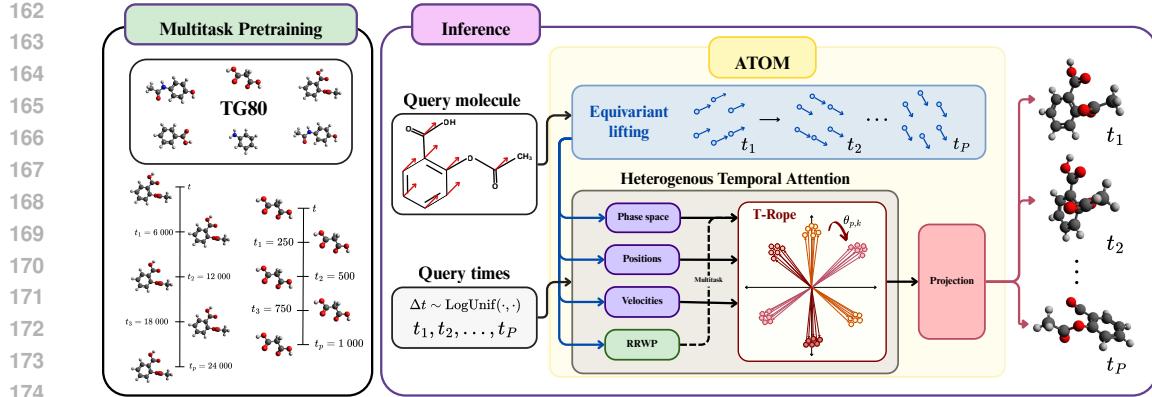


Figure 1: **ATOM Pipeline**. We pretrain ATOM on the TG80 dataset across multiple molecules with stochastic time lags. At inference, ATOM takes a query molecule and timestamps and directly outputs corresponding molecular states.

where $\{\Delta t_1, \dots, \Delta t_p\}$ are discrete timesteps. We replace the true future state $F^\dagger(\mathcal{G}^{(t)})(\Delta t_p)$ with the known future ground truth node positions $\mathbf{x}^{(t+\Delta t_p)}$ for $\Delta t_p \in [0, \Delta T]$.

Quasi-equivariance. We formally define quasi-equivariance, motivated by (Elhag et al., 2025).

Definition 3.1 (ε -quasi-equivariance). We call a function $f : \mathcal{X} \rightarrow \mathcal{Y}$, ε -quasi-equivariant with respect to group G if it satisfies $\mathbb{E}_{x \in \mathcal{X}} \left\| \int_G f(\phi(g)(x)) d\mu(g) - \int_G \rho(g)(f(x)) d\mu(g) \right\| \leq \varepsilon$, where μ denotes the normalized Haar measure.

In practice, we approximate the group integration with Monte Carlo samples from G .

Single- and multitask. Unlike prior works (Schreiner et al., 2023; Xu et al., 2024), we consider both single-task and multitask settings. *Single-task* refers to the case where a separate model is independently trained and evaluated on each molecule and fixed timeframes. This corresponds to the conventional practice in molecular dynamics benchmarks. *Multitask* instead pretrains one unified model on several molecules across varying time lags and evaluates out-of-domain trajectories on unseen molecules, thereby directly testing zero-shot cross-molecule generalization. Under a multitask setting, the objective (1) computes the expectation over trajectories of multiple molecules.

3.2 ATOM MODEL AND TRAINING DESIGN

Here we outline the pipeline of ATOM. At its core is an *equivariant lifting* layer (Section 3.2.1), which maps atomic positions, velocities and their phase features into a richer embedding space while preserving symmetry under the Euclidean group $E(3)$. The lifted embeddings are then processed by the ATOM attention block, which applies *heterogeneous attention* over positions, velocities, and phase features with chemical augmentation (Section 3.2.2). To capture temporal dynamics, we incorporate a *temporal rotary position embedding* (T-RoPE) (Section 3.2.2) that depends only on time lags and is shared across atoms, ensuring translation invariance in time and permutation invariance within each molecule. The parameterized ATOM can be written by

$$F_\theta := \mathcal{P} \circ \sigma(\mathcal{K}_L) \circ \dots \circ \sigma(\mathcal{K}_1) \circ \mathcal{Q}$$

where \mathcal{Q} , \mathcal{P} denotes the equivariant lifting and projection operators respectively. $\mathcal{K}_l, l = 1, \dots, L$ are the data-dependent kernels induced by cross attention (See Appendix G.1), and σ denotes some nonlinear activation function.

Finally, to counter numerical noise in training trajectories, we inject randomly sampled position and velocity perturbations during training (Section 3.2.3), which improves robustness and acts as a regularizer against overfitting. The overall pipeline of ATOM is in Figure 1.

216 3.2.1 $E(3)$ EQUIVARIANT LIFTING
217

218 To model atomic states in a symmetry-respecting way, each atom is encoded with its 3D
219 position and velocity, augmented with their norms: $\mathbf{x} = (x, y, z, \sqrt{x^2 + y^2 + z^2})$, $\mathbf{v} =$
220 $(v_x, v_y, v_z, \sqrt{v_x^2 + v_y^2 + v_z^2})$. To construct higher-dimensional features that remain consistent with
221 $E(3)$ symmetry, we apply *equivariant lifting* that maps the inputs through learnable functions that
222 preserve group actions. Specifically, we use $E(3)$ -equivariant linear layers (Geiger & Smidt, 2022)
223 that lifts the position and velocity vectors to a feature space. The resulting features satisfy the equivari-
224 ant constraints by construction. We further construct phase space of each atom by augmenting
225 the position and velocity vectors with atomic number, which is subsequently processed by a learnable
226 equivariant layer to obtain a lifted representation. The final lifted embedding for a molecule is given
227 by $(\mathbf{X}, \mathbf{V}, \mathbf{Z}) \in \mathbb{R}^{3 \times NP \times d_v}$ corresponding to position, velocity and phase features. The second
228 dimension aggregates nodes and time for attention and d_v is the embedding space dimension.

229 We highlight that after the equivariant lifting layer, we do not enforce equivariance in the subsequent
230 Transformer blocks. This relaxation leads to improved performance compared to fully equivariant
231 designs and, show robustness to random rotations of the trajectories compared to non-equivariant
232 baselines (see Section 4.4).

234 3.2.2 ATOM HETEROGENEOUS TEMPORAL ATTENTION
235

236 We employ a heterogeneous temporal attention mechanism to enable mixing between multiple features
237 $(\mathbf{X}, \mathbf{V}, \mathbf{Z}) \in \mathbb{R}^{3 \times NP \times d_v}$ across spatial and temporal dimensions. We use the phase space embedding
238 \mathbf{Z} as the query and attend to the key-value pairs formed from all features $\mathbf{X}, \mathbf{V}, \mathbf{Z} \in \mathbb{R}^{NP \times d_v}$. In
239 Figure 5, we show that this improves performance by 6.36% over standard self-attention for single-
240 task prediction. In addition, to encode temporal information, we introduce Temporal RoPE (T-RoPE),
241 an adaptation of RoPE (Su et al., 2023) to irregular time lags by driving the phases with timestamps
242 built from per-step increments $\{\Delta t\}$.

243 Let the hidden dimension per head be d_h (even). We define frequencies $\omega_k = b^{-2k/d_h}$ for $k =$
244 $0, \dots, d_h/2 - 1$. Given per-step time increments $\{\Delta t_p\}_{p=1}^P$, we build timestamps $t_p = t + \sum_{r=1}^p \Delta t_r$,
245 and assign a *single* rotation to all N atoms at timestep p : $\mathbf{R}_p = \text{diag}(\mathbf{R}(\theta_{p,0}), \dots, \mathbf{R}(\theta_{p,d_h/2-1})) \in$
246 $\mathbb{R}^{d_h \times d_h}$, where $\theta_{p,k} = \frac{\omega_k}{\tau} (t_p - t_0)$ and $\mathbf{R}(\theta) \in \mathbb{R}^{2 \times 2}$ is the rotation matrix with angle θ and
247 $\tau > 0$ is a timescale hyperparameter. Suppose the query molecule state at time p is given as
248 $\mathbf{Q}_p \in \mathbb{R}^{N \times d_h}$ and key molecule state at time p' is $\mathbf{K}_{p'} \in \mathbb{R}^{N \times d_h}$. We apply $\mathbf{R}_p, \mathbf{R}_{p'}$ to $\mathbf{Q}_p, \mathbf{K}_{p'}$
249 respectively so that the rotary dot product $\mathbf{Q}_p \mathbf{R}_p (\mathbf{K}_{p'} \mathbf{R}_{p'})^\top$ depends only on the time interval
250 $t_{p'} - t_p$. This makes attention *translation invariant* in time, which allows for interpolation and
251 extrapolation across irregular increments $\{\Delta t_p\}$. In addition, sharing the same \mathbf{R}_p across all N
252 atoms in a molecule ensures *permutation-invariance* within a timestep. For aggregated query and
253 key matrices $\mathbf{Q}, \mathbf{K} \in \mathbb{R}^{NP \times d_h}$, we denote the application of temporal Rotary Position Embedding
254 (RoPE) across P timesteps and N atoms as T-RoPE(\mathbf{Q}), T-RoPE(\mathbf{K}) $\in \mathbb{R}^{NP \times d_h}$.

255 Specifically, a single-head attention layer of ATOM computes
256

$$257 \sum_{\mathbf{F} \in \{\mathbf{X}, \mathbf{V}, \mathbf{Z}\}} \gamma_{\mathbf{F}} \text{softmax} \left(\frac{\text{T-RoPE}(\mathbf{Q}(\mathbf{Z})) \text{T-RoPE}(\mathbf{K}(\mathbf{F}))^\top}{\sqrt{d_h}} \right) V(\mathbf{F}),$$

261 where $Q(\cdot), K(\cdot), V(\cdot)$ represent the query, key and value projections. We introduce learnable
262 weights $\gamma_{\mathbf{F}}$ to modulate the relative importance of each feature. In Appendix G.1, we show that
263 heterogeneous attention is equivalent to a kernel integral operator and discuss its properties.

264 3.2.3 TRAINING WITH LABEL NOISE REGULARIZATION
265

266 Many DFT datasets are inherently noisy (Christensen & von Lilienfeld, 2020), and MD models
267 can overfit to this noise. Motivated by the regularization effect of label noise (Damian et al., 2021;
268 HaoChen et al., 2020), we augment the observed node positions \mathbf{x} and velocities \mathbf{v} by random
269 Gaussian noise $\boldsymbol{\xi}_{\mathbf{x}}, \boldsymbol{\xi}_{\mathbf{v}} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$ during training. Let $\mathcal{G}_{\boldsymbol{\xi}}^{(t)} = (\mathbf{x}_i^{(t)} + \boldsymbol{\xi}_{x,i}, \mathbf{v}^{(t)} + \boldsymbol{\xi}_{v,i})$ be the

270 noised initial state at time t . We minimize the following regularized loss
 271

$$272 \min_{\theta} \frac{1}{P} \sum_{p=1}^P \mathbb{E}_{\mathcal{G}^{(t)}, \xi, \xi_x^p} \left\| F_{\theta} \left(\mathcal{G}_{\xi}^{(t)} \right) (\Delta t_p) - (\mathbf{x}^{(t+\Delta t_p)} + \xi_x^p) \right\|_2^2.$$

273 A similar strategy has also appeared in graph neural network (GNN)-based MD models and neural
 274 operator pretraining (Dauparas et al., 2022; Zhou et al., 2024a; Hao et al., 2024). We only apply noise
 275 augmentation during training and evaluate on the unperturbed ground-truth trajectories.
 276

277 **Comparison to EGNO.** We highlight that ATOM adopts fundamentally different design choices
 278 compared to EGNO. First, EGNO is a graph EGNN operating on fixed bond connectivity, whereas
 279 ATOM uses an E(3)-equivariant lifting layer followed by globally connected point-cloud attention,
 280 which better handles long-range and sparsely bonded interactions. Second, EGNO is strictly equivariant
 281 end-to-end, while ATOM is quasi-equivariant, enforcing equivariance only in the lifting stage
 282 and relaxing it in deeper transformer layers, which our ablations show improves accuracy. Third,
 283 EGNO models time via Fourier temporal convolution, whereas ATOM uses Temporal RoPE, allowing
 284 translation-invariant handling of irregular time gaps and stronger temporal extrapolation. T-RoPE
 285 also uniquely allows modifying the time-horizon ΔT at inference by modulating the rotary phases
 286 (Section 3.2.2). Consequently, a pretrained ATOM can be evaluated at arbitrary ΔT values without
 287 retraining.
 288

289 3.3 MULTITASK ATOM PRETRAINING AND TG80 DATASET

290 This section adapts ATOM for the multitask setting, where the aim is to predict future trajectories for
 291 unseen molecules. In order to more effectively distinguish molecules, we construct a radius graph
 292 of 1.6 Å based on atomic positions, and apply *random walk positional encoding* (Ma et al., 2023;
 293 Lobato et al., 2021) to augment the phase vector \mathbf{z} . We describe the process in detail in Appendix D.2
 294 and highlight that such a graph depends only on atomic positions, not chemical bonds.
 295

296 During multitask training, each mini-batch contains trajectories from multiple molecules. In addition,
 297 we perform random sampling for the time lags Δt from a log-uniform distribution between Δt_{\min} and
 298 ΔT , namely $\Delta t \sim \text{LogUnif}(\Delta t_{\min}, \Delta T)$. This aims to enhance the robustness of interpolation and
 299 extrapolation in the temporal domain, a consideration that has been similarly explored in (Schreiner
 300 et al., 2023). Let \mathcal{M} denote the set of training molecules and let $\mathcal{G}_m^{(t)}$ represent the state of molecule
 301 $m \in \mathcal{M}$ at timestamp t . We can write the pretraining multitask objective as

$$302 \min_{\theta} \frac{1}{|\mathcal{M}|} \sum_{m \in \mathcal{M}} \mathbb{E}_{\mathcal{G}_m^{(t)}, \Delta t \sim \text{LogUnif}(\Delta t_{\min}, \Delta T)} \left\| F_{\theta} \left(\mathcal{G}_m^{(t)}, \Delta t \right) (\Delta t) - \mathbf{x}_m^{(t+\Delta t)} \right\|_2^2,$$

304 where we take expectation with respect to initial states of multiple molecules in the training set, as
 305 well as the time lags. Here, we emphasize ATOM also takes a time lag, Δt , as input.
 306

TG80 Dataset. To facilitate pretraining of our neural operator, we introduce **TG80**, a superset of the
 307 MD17 dataset. The initial seed set comprises 40 molecules: 8 MD17 compounds and 32 additional
 308 drug-like molecules selected through expert review. We then augment the seed molecules with
 309 structurally similar molecules from the PubChem dataset of 173 million compounds (Bolton et al.,
 310 2011). Accepted candidates had an ECFP-4 Tanimoto similarity between 0.875 and 0.925 to at least
 311 one seed molecule, and no more than 0.80 similarity to previously accepted molecules, alongside
 312 other criteria detailed in Appendix C.4 (Landrum et al., 2025; Rogers & Hahn, 2010; Rogers &
 313 Tanimoto, 1960). These thresholds follow common practice in the literature, balancing diversity
 314 while avoiding collapse into overly narrow chemical subspaces (Matter, 1997; Menke et al., 2021;
 315 Eastman et al., 2023; Harper et al., 2004; Zhang et al., 2023).

316 We generate all trajectories using ORCA V6.01 (Neese, 2022) with the PBE functional (Perdew et al.,
 317 1996), def2-SVP basis set (Weigend & Ahlrichs, 2005), $\Delta 4$ dispersion corrections (Caldeweyher
 318 et al., 2019; 2020; Wittmann et al., 2024) at one femtosecond resolution, 300K temperature, in
 319 vacuum. This resembles an enhanced RMD17, with more modern dispersion corrections to improve
 320 stability and allow for a larger step size (Christensen & von Lilienfeld, 2020). As a result, TG80
 321 exhibits *more diverse dynamics and improved numerical stability*, with no compound exceeding 50 Å
 322 center-of-mass drift in Figure 8¹.

323 ¹Simulations ran on 32 AMD EPYC 7543 cores with 256 GB RAM per molecule, totalling 806,400 CPU-
 324 hours (quoted market cost USD 150 000).

324

4 EXPERIMENT RESULTS

326 **Metrics.** We use *State-to-trajectory* (S2T) and *state-to-state* (S2S) error to evaluate ATOM (Xu
 327 et al., 2024). Specifically, $S2T = \frac{1}{P} \sum_{p=1}^P \|\hat{\mathbf{x}}_p - \mathbf{x}_p\|_2^2$, measures the average discrepancy between
 328 the predicted $\hat{\mathbf{x}}$ and ground-truth positions \mathbf{x} across entire trajectories, while $S2S = \|\hat{\mathbf{x}}_P - \mathbf{x}_P\|_2^2$,
 329 quantifies the error at the final predicted timestep.

330 **Baselines.** For comparison, we include a range of classic to state-of-the-art baselines, including
 331 Radial Field (RF) (Köhler et al., 2019), Tensor Field Networks (TFN) (Thomas et al., 2018), SE(3)
 332 Transformer (SE(3)-Tr.) (Fuchs et al., 2020), E(n) equivariant graph neural networks (EGNN)
 333 (Garcia Satorras et al., 2021), and EGNO (Xu et al., 2024). Our EGNN baselines are EGNN-Rollout
 334 (EGNN-R), which predicts timesteps autoregressively, and EGNN-Sequential (EGNN-S), which uses
 335 the output of each GNN as the prediction of a given frame. We set all baseline hyperparameters
 336 following previous works (Xu et al., 2024; 2022; Shi et al., 2021) and tune ATOM and EGNO
 337 hyperparameters as in Table 20 and Table 21.

338 **Training setups.** For training of ATOM and EGNO, we consider two temporal discretization
 339 strategies in selecting the timestamps $t_p = t + \sum_{r=1}^p \Delta t_r$: (1) *Uniform discretization* selects
 340 $t_p = t + p/P\Delta T$ and (2) *Tail discretization* selects $t_p = t + \bar{\Delta} + p/P(\Delta T - \bar{\Delta})$ for a lag
 341 $\bar{\Delta} \in [0, \Delta T]$. In the main paper, we present experiment results with uniform discretization and
 342 include the results with tail discretization in Appendix E. We perform early stopping on the lowest S2S
 343 validation loss checkpoint and report results as mean $\pm 2\sigma$ over *three training runs*. All experiments
 344 are run on an NVIDIA® RTX 5080 with wall-clock time and FLOP utilization detailed in Table 16.
 345

348

4.1 SINGLE-TASK LEARNING

350 We benchmark on the MD17, RMD17, and MD22 DFT MD trajectory datasets (Chmiela et al.,
 351 2017; Christensen & von Lilienfeld, 2020; Chmiela et al., 2023). We partition the trajectories into
 352 train/validation/test splits of sizes 500/2000/2000, set $\Delta T = 3000$ fs and $P = 8$, and train for 2500
 353 epochs following (Xu et al., 2024). For the performance on MD17 (Table 1), we directly quote the
 354 results from (Xu et al., 2024) except for EGNO. We design ATOM to have six transformer blocks
 355 with a hidden size of 256.

356 **MD17 and RMD17.** As shown in Table 1, ATOM compares favorably with state-of-the-art (SOTA)
 357 baselines on MD17 dataset, yielding average reductions of 14.96% (S2S mean squared error (MSE))
 358 and 8.3% (S2T MSE) on average². In Table 9 (Appendix E.1), we benchmark ATOM on RMD17,
 359 and observe similarly competitive performance against EGNO.

360 **MD22.** To evaluate performance on larger molecules, we consider Ac-
 361 Ala3-NHMe (20 heavy atoms), docosahexaenoic acid (DHA with 24
 362 heavy atoms), and stachyose (45 heavy atoms) from the MD22 dataset
 363 (Chmiela et al., 2023). ATOM remains competitive on these systems;
 364 whereas EGNO fails to converge (Table 2). We attribute this discrepancy
 365 to differing inductive biases: GNNs such as EGNO restrict message
 366 passing to a predefined bond or radius graph and can therefore under-
 367 represent long-range, non-bonded steric and electrostatic interactions that
 368 dominate the behavior of large, sparsely connected molecules (Alon &
 369 Yahav, 2021; Kosmala et al., 2023). This explains the poor performance of EGNO on MD22, which
 370 contains prototypically sparse molecules such as DHA, shown in Figure 2 (Nv et al., 2003). We
 371 further disentangle the role of connectivity from the use of attention by training a variant, ATOM-
 372 Graph attention network v2 (GATv2), in which our heterogeneous temporal attention is replaced by
 373 GATv2 layers (Brody et al., 2022) operating on the same bond/radius graph as EGNO. ATOM-GATv2
 374 still substantially underperforms the full ATOM model, indicating that the performance gains stem
 375 from the fully connected point-cloud interaction pattern rather than from attention alone.

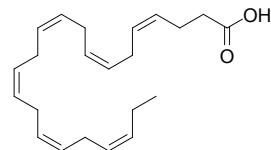


Figure 2: Docosahexaenoic acid (DHA)

²We exclude benzene from the table due to the previously discussed high numerical noise.

378 Table 1: Single-task MSE ($\times 10^{-2}$) on MD17. Upper part: S2S MSE. Lower part: S2T MSE.
379

	Aspirin	Ethanol	Malonaldehyde	Naphthalene	Salicylic	Toluene	Uracil
RF	10.94 \pm 0.02	4.64 \pm 0.02	13.93 \pm 0.06	0.50 \pm 0.02	1.23 \pm 0.04	10.93 \pm 0.08	0.64 \pm 0.02
TFN	12.37 \pm 0.36	4.81 \pm 0.08	13.62 \pm 0.16	0.49 \pm 0.02	1.03 \pm 0.04	10.89 \pm 0.02	0.84 \pm 0.04
SE(3)-Tr.	11.12 \pm 0.12	4.74 \pm 0.02	13.89 \pm 0.04	0.52 \pm 0.02	1.13 \pm 0.04	10.88 \pm 0.12	0.79 \pm 0.04
EGNN	14.41 \pm 0.30	4.64 \pm 0.04	13.64 \pm 0.02	0.47 \pm 0.04	1.02 \pm 0.04	11.78 \pm 0.14	0.64 \pm 0.02
EGNN-R	9.96 \pm 0.14	4.61 \pm 0.01	13.04 \pm 0.03	0.44 \pm 0.05	0.96 \pm 0.01	10.19 \pm 0.15	1.11 \pm 0.04
EGNN-S	10.25 \pm 0.09	4.61 \pm 0.01	13.06 \pm 0.01	0.53 \pm 0.01	1.06 \pm 0.05	10.83 \pm 0.09	0.62 \pm 0.01
EGNO	9.64 \pm 0.15	4.57 \pm 0.01	12.92 \pm 0.00	0.39 \pm 0.00	0.89 \pm 0.01	11.00 \pm 0.00	0.58 \pm 0.02
MACE	6.95 \pm 0.00	2.06 \pm 0.00	17.99 \pm 0.26	0.72 \pm 0.00	1.05 \pm 0.00	6.44 \pm 0.00	0.75 \pm 0.00
ATOM	6.82 \pm 0.06	3.52 \pm 0.04	14.72 \pm 0.01	0.50 \pm 0.00	0.88 \pm 0.01	4.66 \pm 0.21	0.63 \pm 0.00
EGNN-R	7.35 \pm 0.19	3.21 \pm 0.00	10.75 \pm 0.04	0.34 \pm 0.06	1.09 \pm 0.12	4.53 \pm 0.08	0.89 \pm 0.02
EGNN-S	9.01 \pm 0.34	3.21 \pm 0.00	11.20 \pm 0.03	0.42 \pm 0.01	1.41 \pm 0.00	4.86 \pm 0.04	0.65 \pm 0.01
EGNO	9.64 \pm 0.15	4.57 \pm 0.01	12.92 \pm 0.00	0.39 \pm 0.00	0.90 \pm 0.01	10.99 \pm 0.00	0.58 \pm 0.02
MACE	5.06 \pm 0.00	2.84 \pm 0.00	16.09 \pm 0.03	0.57 \pm 0.00	0.55 \pm 0.00	3.26 \pm 0.00	1.08 \pm 0.00
ATOM	5.62 \pm 0.05	2.62 \pm 0.04	12.49 \pm 0.01	0.43 \pm 0.00	0.86 \pm 0.01	2.27 \pm 0.10	0.61 \pm 0.00

394 Table 2: Single-task MSE ($\times 10^{-2}$) on
395 MD22. Upper: S2S. Lower: S2T

	Ac-Ala3-NHME	DHA	Stachyose
EGNO	357.89 \pm 3.94	178.39 \pm 4.91	42.11 \pm 0.10
ATOM-GATv2	223.57 \pm 0.66	16.72 \pm 0.44	41.40 \pm 0.37
ATOM	9.65 \pm 0.75	10.60 \pm 0.11	21.25 \pm 4.20
Gap	+97.30%	+94.06%	+49.54%
EGNO	232.40 \pm 6.75	116.45 \pm 3.34	30.84 \pm 0.03
ATOM-GATv2	113.26 \pm 0.04	13.39 \pm 0.32	29.70 \pm 0.15
ATOM	7.55 \pm 0.42	9.66 \pm 1.16	18.13 \pm 3.78
Gap	+96.75%	+91.70%	+41.22%

394 Table 3: Multitask S2T MSE ($\times 10^{-2}$) on TG80 across
395 five UMAP cluster assignments.

	Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
ID	EGNO	44.23 \pm 0.68	95.52 \pm 0.73	141.16 \pm 0.21	150.92 \pm 0.11
	ATOM	9.71 \pm 0.75	18.26 \pm 1.58	16.82 \pm 1.46	16.93 \pm 3.65
	Gap	78.04%	80.89%	88.09%	88.78%
OOD	MACE	134.26	224.12	325.97	316.26
	EGNO	45.95 \pm 0.80	115.43 \pm 13.23	151.74 \pm 0.57	163.90 \pm 0.69
	EGNN-S	45.44 \pm 0.57	7386.15 \pm 6931.89	152.72 \pm 0.83	464.22 \pm 509.48
	EGNN-R	44.88 \pm 0.68	109.62 \pm 1.92	148.05 \pm 0.70	161.54 \pm 0.68
	ATOM	35.05 \pm 0.97	106.99 \pm 104.64	60.95 \pm 4.86	66.68 \pm 0.96
	Gap	21.93%	24.00%	58.83%	58.71%
					56.88%

404 4.2 MULTITASK LEARNING ON TG80
405

406 We pretrain ATOM on TG80, scaling to six attention blocks with a hidden size of 256. We se-
407 lect stochastic horizons $\Delta T \sim \text{LogUnif}(8 \text{ fs}, 24\,000 \text{ fs})$ and use a five-fold, cluster-based cross-
408 validation. Specifically, we compute ECFP-4 fingerprints (Rogers & Hahn, 2010), embed them
409 using UMAP (McInnes et al., 2018), and apply agglomerative clustering (Ward, 1963) to partition
410 compounds into ten disjoint clusters. The folds are then formed by holding out clusters, ensuring that
411 the train/validation/test sets occupy distinct regions of chemical space. This cluster-wise protocol
412 minimizes leakage and more closely reflects the prospective scientific setting in which models must
413 generalize to unseen molecules. Cluster-based approaches present more challenging generaliza-
414 tion problems than random splits or common chemical-scaffold-based splits (Guo et al., 2024). In
415 Appendix E.2, we also consider pretraining on a standard random split of molecules.

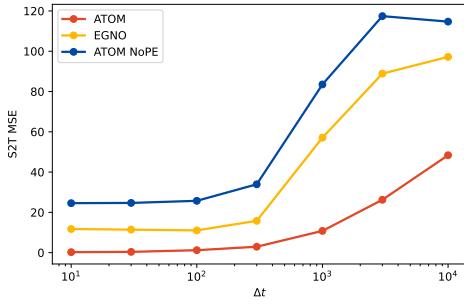
416 Table 3 benchmarks ATOM by assessing both *in-distribution* (ID) and *out-of-domain* (OOD) S2T
417 performance. For the *in-distribution* setting, we train, validate, and test on molecules from the same
418 cluster. We observe that ATOM outperforms existing baselines by an average of 83.96% in terms
419 of S2T MSE. We then assess *out-of-domain* (OOD) generalization performance by predicting the
420 dynamics of unseen compounds drawn from disjoint clusters. Under OOD settings, ATOM nearly
421 halves the S2T MSE of EGNO, with an average improvement of 39.74% across five cluster splits.
422 Notably, OOD ATOM beats ID EGNO performance in four of five folds. This striking zero-shot
423 generalization, realized without any exposure to the test molecules, confirms that ATOM uniquely
424 learns robust, transferable knowledge of molecular dynamics. In Appendix E.2, we show similar
425 outperformance in S2S prediction. In Appendix F.2, we show that the significantly improved multitask
426 performance comes with a modest overhead in training time and in inference latency.

427 4.3 TEMPORAL GAP AND Timestep Invariance Properties
428

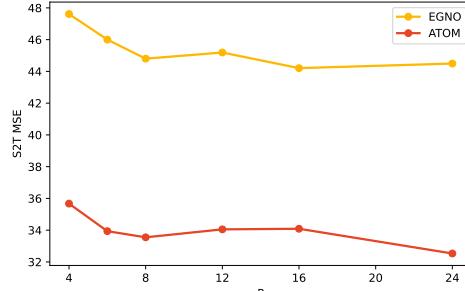
429 **ΔT Invariance.** We evaluate the performance of pretrained ATOM (at fixed $\Delta T = 3000$) with
430 varying ΔT at inference. We compare ATOM, EGNO, and EGNN on S2T MSE by fixing $P = 8$ and
431 sweeping ΔT logarithmically from 10 to 10 000 fs on an in-distribution (Cluster 1) multitask model.
In Figure 3, we show that ATOM maintains its extrapolation advantage across the range compared to

432 EGNO, particularly at larger ΔT . Ablating T-RoPE (NoPE) removes this advantage by exhibiting
 433 an EGNO-like error trend with substantially higher MSE. This underscores T-RoPE’s role in stable
 434 time-gap extrapolation.

435 **P Invariance.** Following the discretization invariance in neural operators, we expect ATOM and
 436 EGNO models to show consistent MSE as P varies under uniform discretization (Kovachki et al.,
 437 2021). Figure 4 confirms such a conjecture by showing that multitask ATOM pretrained at $P = 8$
 438 maintain constant S2T MSE as P ranges from 4 to 24 at inference.



441 Figure 3: Pretrained ($\Delta T = 3000$, ID) multi-
 442 task S2T MSE across varying ΔT values.



443 Figure 4: Pretrained ($P = 8$) ATOM and
 444 EGNO are discretization invariant, showing
 445 stable S2T MSE.

456 4.4 ABLATION STUDIES

457 We perform extensive ablations to assess each design choice in ATOM. For single-task performance
 458 (Fig. 5) and multitask performance (Fig. 6), we independently toggle components and measure
 459 their contributions. Our analysis focuses on equivariant lifting, T-RoPE, label-noise regularization,
 460 heterogeneous attention, and random-walk positional encoding (under multitask pretraining).

462 **Equivariant lifting.** We assess the quasi-
 463 equivariant design against a non-equivariant
 464 ATOM. As shown in Figure 5, replacing the equiv-
 465 ariant lifting introduced in Section 3.2.1 with stan-
 466 dard linear layers (no equivariant lifting) markedly
 467 degrades the performance of ATOM, increasing
 468 S2T MSE by 22.48. Consistently, Table 4 shows
 469 that non-equivariant lifting is vulnerable under
 470 SO(3) rotations of the trajectories, whereas the
 471 quasi-equivariant ATOM remains comparatively
 472 robust. Notably, the fully-equivariant variant of ATOM, described in appendix Appendix D.1, also
 473 underperforms ATOM in both single-task (Figure 5) and multitask (Figure 6) settings, with the
 474 gap exaggerated in the multitask setting. This aligns with recent findings on relaxed equivariance,
 475 suggesting that strict equivariance can limit model capacity and complicate the optimization process
 476 (Elhag et al., 2025). We present estimates of the quasi-equivariance ε in Appendix E.3.

477 **Heterogeneous attention.** We find that substituting heterogeneous temporal attention with standard
 478 self-attention on the phase space features increases S2S MSE by 0.47, suggesting that cross-attention
 479 enables access to non-trivial feature interactions.

480 **Temporal Rotary Position Embedding (T-RoPE).** In the single-task regime with fixed ΔT (Figure
 481 5), T-RoPE contributes little to the performance of ATOM, as it effectively reduces to a constant
 482 rotational shift. By contrast, with stochastic ΔT , disabling T-RoPE (NoPE) increases MSE by 1.07,
 483 consistent with ATOM leveraging the τ parameter to encode variable time gaps (Figure 6). An
 484 EGNO-style sinusoidal positional encoding produces a similar performance degradation.

485 **Label noise regularization.** We also test the utility of label noise regularization as in Section 3.2.3.
 486 From Figure 5, we observe that removing augmented noise from the position and velocity features in-

487 Table 4: S2T MSE ($\times 10^{-2}$) of a fixed input
 488 frame rotated and unrotated by an SO(3) matrix.

	ATOM	No equivariant Lift
Unrotated	6.76 ± 0.69	33.44 ± 23.42
Rotated	73.04 ± 27.01	660.97 ± 945.86
Gap	66.28 ± 26.32	627.53 ± 926.53

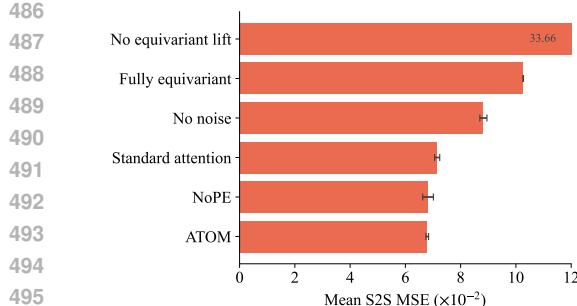


Figure 5: ATOM ablation on MD17 Aspirin.

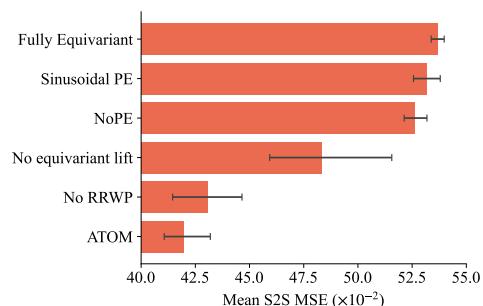


Figure 6: ATOM ablation on TG80 Cluster 1.

creased S2T MSE by 1.21. For the multitask ablation on TG80, we suppress label noise regularization, as the dataset is designed to be numerically stable with small noise.

RWPE. We assess random-walk positional encoding (RWPE) in the multitask pretraining. Figure 6 indicates that RWPE facilitates molecule identification, yielding improved multitask performance.

5 CONCLUSIONS

In this work, we demonstrate that carefully designed transformer neural operators enable zero-shot generalization to unseen chemical dynamics. Our experiments on MD17 demonstrate continued good single-task performance, and we present the first molecular neural operator that can successfully learn large molecule dynamics using MD22. Our multitask experiments show that our method learns transferable dynamics knowledge, even without explicit graph representations. In combination with our TG80 dataset, we provide a large-scale open-source benchmark and baselines to evaluate future models and spur further operator research with concrete scientific applicability.

Limitations We remark that TG80 does not contain trajectories for large molecules with more than 15 heavy atoms, despite their obvious chemical and pharmacological relevance. In follow-up work, we intend to enrich TG80 with such molecules, calculated with a higher-resolution DFT basis set, ω B97X-3c (Müller et al., 2023). Regarding ATOM, it lacks an explicit energy-based inductive bias, which may permit long-horizon drift. A natural extension is therefore a framewise energy head $E_\theta(\mathbf{x}_{t_p})$ with force supervision $\mathbf{F}_{t_p} = -\nabla_{\mathbf{x}_{t_p}} E_\theta(\mathbf{x}_{t_p})$. This energy term also defines the drift in the Langevin dynamics, where an additional stochastic term accounts for thermal perturbations of atomic positions. Incorporating such physics-informed stochastic dynamics into our operator learning framework is a natural next step, and we view this as a promising direction for future MD research.

REPRODUCIBILITY STATEMENT

We provide experiment details, such as choice of hyperparameters and other training configurations in Appendix F. In addition, we will release the TG80 dataset upon acceptance under MIT license for reproducibility.

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1026 **A LLM ACKNOWLEDGMENT**
10271028 The authors acknowledge the use of LLM for grammar corrections and for improving the clarity of
1029 the manuscript. The LLM was not used for generating original ideas, content, or experimental results.
1030 All conceptual contributions, analyses, and conclusions presented in this work are entirely from the
1031 authors.
10321033 **B BACKGROUND**
10341035 This section provides an introduction to the preliminaries of group theory.
10361037 **B.1 GROUPS**
10381039 A group (G, \circ) consists of a non-empty set G and a binary operation $\circ : G \times G \rightarrow G$ satisfying the
1040 following axioms:
1041

- 1042 1.
- Closure:**
- For all
- $a, b \in G$
- , the result of the operation
- $a \circ b$
- is also in
- G
- :
- $a \circ b \in G$
- .
-
- 1043 2.
- Identity Element:**
- There exists an element
- $e \in G$
- such that, for all
- $a \in G$
- ,
- $a \circ e = e \circ a = a$
- .
-
- 1044 3.
- Associativity:**
- For all
- $a, b, c \in G$
- ,
- $(a \circ b) \circ c = a \circ (b \circ c)$
- .
-
- 1045 4.
- Inverses:**
- For each
- $a \in G$
- , there exists an element
- $a^{-1} \in G$
- such that
- $a \circ a^{-1} = a^{-1} \circ a = e$
- .
-
- 1046

1047 In general, not all groups are abelian. That is, the binary operation \circ does not necessarily commute:
1048 $g \circ h = h \circ g, \forall g, h \in G$.
10491050 **B.2 GROUP REPRESENTATIONS**
10511052 A group representation is a homomorphism $\rho : G \rightarrow GL(V)$ that assigns an $n \times n$ matrix to each
1053 group element $g \in G$, realizing it as a linear transformation. Representations must preserve the
1054 binary operation for all members of the group G such that:

1055
$$\rho(g \circ h) = \rho(g)\rho(h), \quad \forall g, h \in G.$$

1056

1057 A representation $\rho(g)$ is reducible if it can be represented as the direct sum of other representations:
1058

1059
$$\rho(g) = \rho_1(g) \oplus \rho_2(g), \quad \forall g \in G.$$

1060 For example, a reducible 4×4 representation of $SU(2)$ can be decomposed into two 2×2 sub-
1061 representations:
1062

1063
$$\rho(g) = \begin{bmatrix} \rho_1(g) & 0 \\ 0 & \rho_2(g) \end{bmatrix}, \quad \forall g \in SU(2),$$

1064

1065 where $\rho_1(g)$ and $\rho_2(g)$ are the following irreducible representations of $SU(2)$:
1066

1067
$$\rho_1(g) = \begin{bmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{bmatrix}, \quad \rho_2(g) = \begin{bmatrix} e^{i\phi} & 0 \\ 0 & e^{-i\phi} \end{bmatrix}.$$

1068

1069 By contrast, irreducible representations or *irreps* cannot be represented as such a direct sum. Formally,
1070 they have no non-trivial invariant subspaces $W \subset V$ such that $\rho(g)W \subset W, \forall g \in G$.
10711072 Representing inputs as irreps ensures equivariance by constraining each feature to transform pre-
1073 dictably under group actions. Given $V = \bigoplus_i V_i$ with irreps V_i , the transformation of an input $x \in V$
1074 under $g \in G$ is:

1075
$$\rho(g)x = \bigoplus_i \rho_i(g)x_i.$$

1076

1077 Each component x_i transforms independently according to ρ_i , preserving symmetry. Scalars remain
1078 invariant, while vectors rotate according to standard representations. This decomposition prevents
1079 the mixing of differently transforming features, ensuring that all subsequent operations, linear or
non-linear, respect the group's symmetry, thereby maintaining equivariance throughout the network.

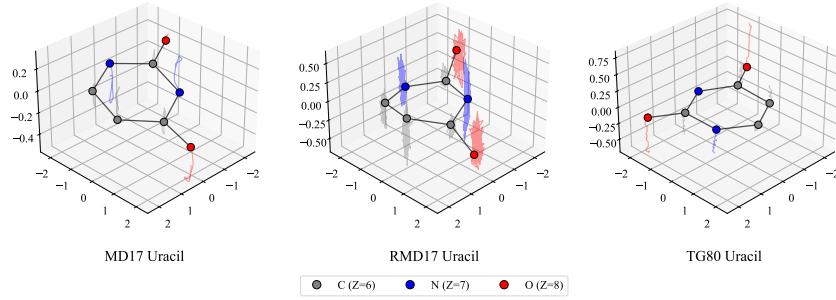
1080
 1081 Intuitively, the tensor products capture interactions between features in a manner akin to multiplication,
 1082 producing a higher-dimensional representation. Crucially, this new representation is reducible, so we
 1083 may decompose it into irreps:
 1084

$$V \otimes V \cong \bigoplus_k V_k.$$

1085 It is this decomposition that allows the network to project onto individual irreps, achieving non-trivial
 1086 feature mixing whilst preserving symmetry constraints.
 1087

1088 C DATASETS

1090 We present a visualization of a sample trajectory of uracil from three datasets in Figure 7.
 1091



1103 Figure 7: 3000 timesteps of uracil trajectory from MD17, RMD17, and TG80.
 1104

1105 C.1 LICENCES

1106 Table 5: Dataset sources and licenses. We release TG80 under the MIT license.
 1107

1108 Dataset	1109 Source	1110 License
1111 MD17	https://www.sgdml.org/	CC BY 4.0
1112 RMD17	https://archive.materialscloud.org/record/2020.82	CC Zero V1.0 Universal
1113 MD22	https://www.sgdml.org/	CC BY 4.0
1114 TG80	To be released at URL	MIT

1115 C.2 MODEL INPUTS AND THE DATALOADER

1116 Our compound representations follow (Shi et al., 2021; Xu et al., 2024). We model hydrogen atoms
 1117 implicitly and concatenate the position and velocity norms for each node i with their respective
 1118 vectors. Unlike their implementations, we avoid explicit graph construction and do not include edge
 1119 labels describing atomic bond geometries.
 1120

1121 We duplicate all frames $\mathcal{G}^{(t)} \rightarrow \{\mathcal{G}^{(t)}\}^P$ during dataset initialization, producing a five-fold improvement
 1122 in throughput compared to previous dataloaders in Table 6.
 1123

1124 Table 6: Mean time (seconds) to produce 10 000 batches over 100 benchmark runs. Batch size = 100,
 1125 500 samples, $\Delta t = 3000$, 500 warmup batches.
 1126

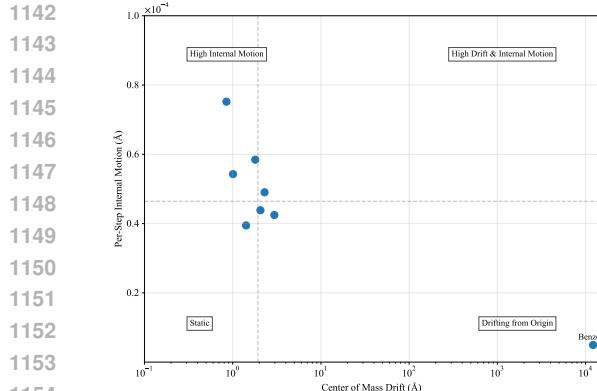
	Aspirin	Ethanol	Naphthalene	Toluene
1129 EGNO	0.060 \pm 0.024	0.024 \pm 0.016	0.056 \pm 0.024	0.039 \pm 0.024
1130 ATOM	0.005 \pm 0.002	0.007 \pm 0.002	0.008 \pm 0.004	0.006 \pm 0.002

1134
1135

C.3 NUMERICAL STABILITY

1136 We evaluate the numerical stability of MD17, RMD17, and TG80. MD17 benzene exhibits substantial
 1137 center-of-mass drift in Figure 8a, which is also partially visible in the consistent motion trails shown
 1138 in Figure 11a. RMD17 exhibits improved stability, with no center-of-mass drift exceeding 1×10^4 .
 1139 TG80 shows the lowest drift of all datasets, and expectedly includes more molecules with high
 1140 per-step drift (due to more complex sterically hindered geometries).

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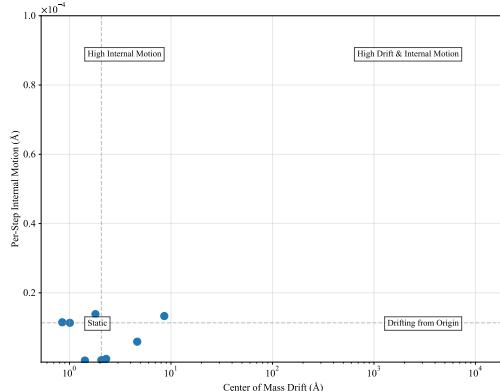
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(a) MD17 molecules are largely consistent, except for
 benzene, which exhibits substantial drift.



(b) RMD17 molecules are more numerically stable, supporting their use in future benchmarks.

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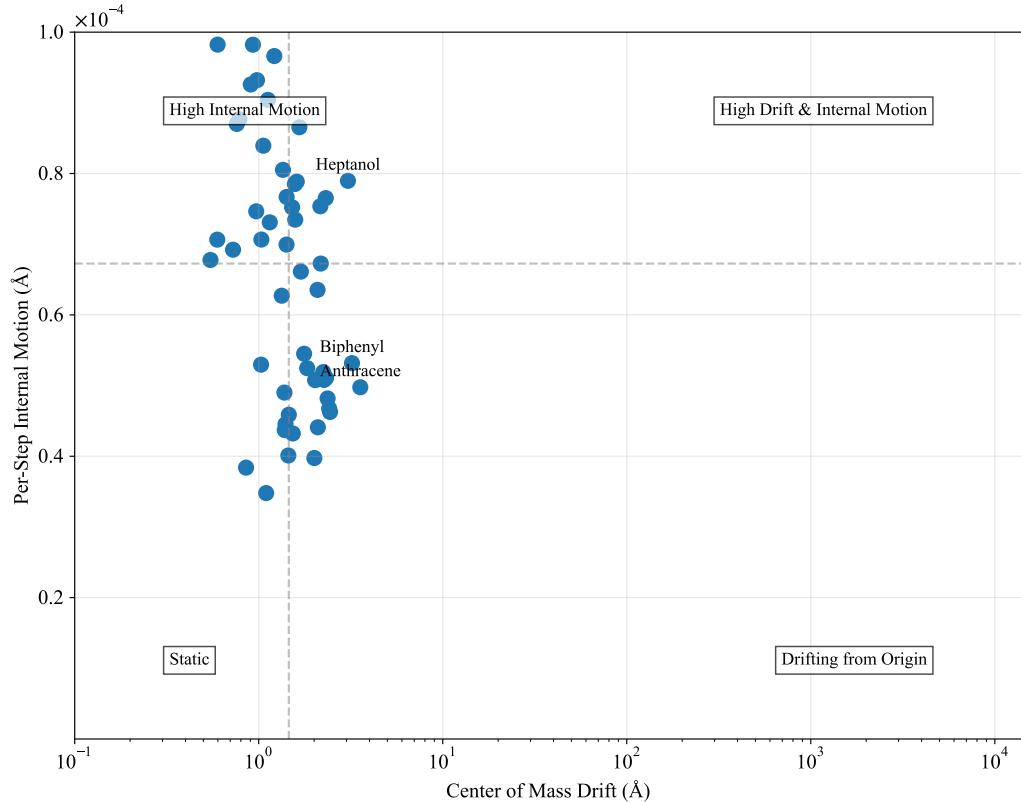
1184

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1186

1187

Heptanol
Biphenyl
Anthracene



1184

1185

1186

1187

(c) TG80 dataset exhibits the lowest centre-of-mass drift among the evaluated MD datasets.

Figure 8: Comparison of numerical stability across MD17, RMD17, and TG80 datasets. Dashed lines denote the mean centre-of-mass drift and per-step motion; datapoints exceeding two standard deviations are annotated.

1188 C.4 TG80 GENERATION ALGORITHM
11891190 We first recall the definition of Tanimoto T similarity between two bit vectors X, Y as
1191

1192
$$T(X, Y) = \frac{|X \cap Y|}{|X \cup Y|},$$

1193

1194 which is identical to the definition of the Jaccard similarity in this case (Rogers & Tanimoto, 1960).
11951196 To generate TG80, we randomly shuffled the PubChem dataset, then iterated
1197 through all compounds until 40 were found that matched the following criteria:
1198

- 1199 1. Simplified Molecular-input Line-entry System
1200 (SMILES) encode a valid molecular structure
- 1201 2. No more heavy atoms than the corresponding
1202 seed molecule
- 1203 3. Only contain {C, H, O, N} atoms
- 1204 4. No more than five oxygen atoms
- 1205 5. No more than three nitrogen atoms
- 1206 6. No disconnected molecular fragments (e.g., salts)
- 1207 7. Tanimoto similarity to at least one seed molecule
1208 greater than 0.875, less than 0.925
- 1209 8. Tanimoto similarity to a previously selected
1210 molecule is no more than 0.2

1211 This controlled selection procedure generates structurally analogous subsets around each seed
1212 molecule whilst preventing convergence to highly similar molecules across different seed groups.
12131214 Only 2,488 of the 173 million in the PubChem library satisfied the filtration criteria above. This low
1215 yield largely reflects the cumulative effect of criterion 8: as more molecules are added, it becomes
1216 harder to find candidates sufficiently dissimilar to all prior selections. Given that the average Tanimoto
1217 similarity to our seed set was just 0.1492, the 0.875 threshold was highly selective. Dataset generation
1218 code is available at ANONYMIZED.
12191221 C.5 MOLECULAR DYNAMICS SIMULATIONS
12221223 We present a complete overview of the DFT parameters used to generate MD17 (Chmiela et al.,
1224 2017), RMD17 (Christensen & von Lilienfeld, 2020), MD22 (Chmiela et al., 2023), and TG80.
12251226 Table 7: An overview of the methodologies used to generate the MD datasets featured.
1227

	DFT Functional	Dispersion Corrections	Basis set	Timestep	Temperature
1229 MD17	PBE	TS	NAO	0.5 fs	500K
1230 RMD17	PBE	None	def2-SVP	0.5 fs	500K
1231 MD22	PBE	MBD	NAO	1.0 fs	500K
1232 TG80	PBE	Δ4	def2-SVP	1.0 fs	300K

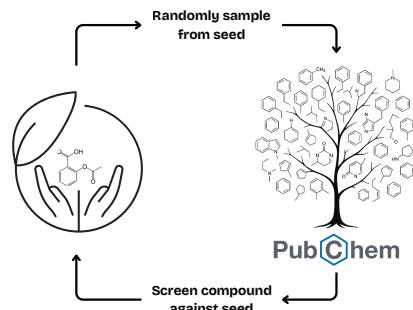
1234 D ARCHITECTURAL DETAILS
12351236 D.1 FULLY EQUIVARIANT ATOM
12371238 To achieve the full equivariance discussed in Figure 5, we employ a canonicalization network
1239 approach, which removes Euclidean gauge before learning and then reinstates it afterwards (Kaba
1240 et al., 2023). This preserves equivariance of the whole network, even with the use of non-equivariant
1241 architectures in the trunk.

Figure 9: Construction of TG80 from an initial seed using the PubChem database.

1242 We first make data translation equivalent by centering
 1243

$$1244 \quad 1245 \quad \mu = \frac{1}{N} \sum_{i=1}^N x_i, \quad \bar{x}_i = x_i - \mu. \quad (2)$$

1246 We then remove rotations by aligning to the second moment
 1247

$$1248 \quad 1249 \quad S = \frac{1}{N} \sum_{i=1}^N \bar{x}_i \bar{x}_i^\top = \sum_{k=1}^3 \lambda_k e_k e_k^\top \quad (\lambda_1 \geq \lambda_2 \geq \lambda_3), \quad (3)$$

1251 and choose e_1 as the principal axis and orthonormalise
 1252

$$1253 \quad e_2 \leftarrow \frac{e_2 - (e_2^\top e_1)e_1}{\|e_2 - (e_2^\top e_1)e_1\|}, \quad e_3 = e_1 \times e_2. \quad (4)$$

1255 We can then form $Q = [e_1, e_2, e_3] \in \text{SO}(3)$ and canonicalise
 1256

$$1257 \quad \tilde{x}_i = (x_i - \mu) Q, \quad \tilde{v}_i = v_i Q. \quad (5)$$

1258 We fix the eigenvector sign ambiguity using the chirality pseudoscalar $c_0 = \sum_{i=1}^N x_i \times v_i$ at the
 1259 reference time (flip e_1 to satisfy $e_1^\top c_0 \geq 0$, then adjust e_2, e_3 jointly to keep right-handedness).
 1260 Let F be an arbitrary trunk acting in the canonical frame; with per-atom canonical outputs $\hat{y}_i =$
 1261 $F(\{\tilde{x}_j, \tilde{v}_j\}_{j=1}^N)_i$, we decanonicalise by
 1262

$$1263 \quad y_i = \hat{y}_i Q^\top + \mu. \quad (6)$$

1264 This results in exact SE(3)-equivariance (Kaba et al., 2023) and permits non-equivariant trunks.
 1265

1266 D.2 RANDOM-WALK POSITIONAL ENCODINGS

1267 In the multitask case, we add row-normalized random walk positional encoding (RWPE) to equip
 1268 ATOM and EGNO with multiscale connectivity features, enhancing their ability to distinguish non-
 1269 isomorphic graphs (Dwivedi et al., 2022; Ma et al., 2023). We first form a ε -neighborhood graph
 1270 from our pointclouds as:
 1271

$$1272 \quad G = (V, E), \quad V = \{i\}, \quad E = \{(i, j) : \|(x, y, z)_i - (x, y, z)_j\|_2 < \varepsilon\}. \quad (7)$$

1273 We set $\varepsilon = 1.6$, as covalent bonds typically range from 1.14 Å to 2.0 Å in length (Lobato et al., 2021)
 1274 and highlight that this construction does not necessitate prior knowledge of the graph structure.
 1275

1276 Let $\mathbf{A} \in \mathbb{R}^{n \times n}$ denote the adjacency matrix of this graph, and let $\mathbf{D} = \text{diag}(\mathbf{A} \mathbf{1})$ represent its degree
 1277 matrix. We construct the random walk transition matrix as $\mathbf{M} = \mathbf{D}^{-1} \mathbf{A}$ then compute matrix powers
 1278 of \mathbf{M} up to a maximum walk-length K , defining the self-return probabilities for each node as
 1279

$$1280 \quad p_i^{(k)} = (\mathbf{M}^k)_{ii}, \quad k = 1, \dots, K. \quad (8)$$

1281 These probabilities are collected into vectors $\mathbf{p}_i \in \mathbb{R}^K$ and concatenated with the phase space to
 1282 form $\hat{\mathbf{z}} = (\mathbf{v} \parallel \mathcal{Z} \parallel \mathbf{p}) \in W_{\text{in}}$. Here, the input feature space is redefined as $W_{\text{in}} = V_{\text{in}} \oplus \rho_0^{\text{even}} \oplus$
 1283 $(\rho_0^{\text{even}} \otimes \mathbb{R}^K)$, and the subsequent equivariant maps are modified in kind.
 1284

1285 D.3 VALUE-RESIDUAL LEARNING

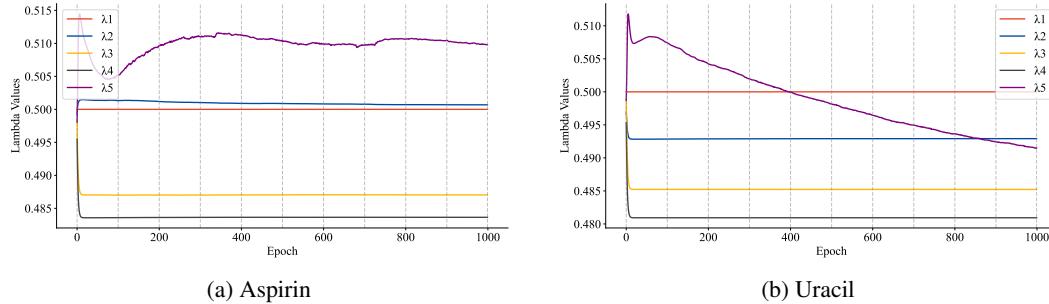
1286 We employ value-residual learning wherein each transformer block receives the output of the first
 1287 block via a residual connection to stabilize training and information flow through the network (Zhou
 1288 et al., 2024b). Inspired by (Jordan, 2024), we add a learned coefficient to weight this residual. Here,
 1289 v denotes the current block's value output, and v_1 represents the initial block's value. A learnable
 1290 parameter α is passed through a sigmoid to obtain the weighting coefficient:
 1291

$$1292 \quad \lambda = \sigma(\alpha). \quad (9)$$

1293 The combined output is then given by:
 1294

$$1295 \quad v = \lambda v + (1 - \lambda) v_1. \quad (10)$$

1296 In practice, we lock the first block’s λ value to 0.5. We report the learned λ values in Figure 10.
 1297



1308 (a) Aspirin (b) Uracil
 1309
 1310
 1311
 1312
 1313
 1314

Figure 10: Learned value residuals for MD17 training over 1000 epochs.

D.4 DELTA-PREDICTION

1315 When delta-prediction is enabled, as in Figure 5, we incorporate the initial positions \mathbf{x} as a residual
 1316 term, reformulating the model as an operator that learns a displacement field rather than predicting
 1317 absolute positions. We express this as:
 1318

$$1319 \mathbf{x}^\dagger = \text{Project}(\mathbf{x}_{\text{out}}) + \mathbf{x}. \quad (11)$$

1322 Although this approach is implemented in both EGNN and EGNO, we found it was disabled by
 1323 default in the codebase of the latter (Garcia Satorras et al., 2021; Xu et al., 2024). Based on empirical
 1324 results from our ablations, Figure 5, we argue there is sufficient evidence to discourage the use of
 1325 delta-prediction in neural operator-based molecular dynamics simulations.
 1326
 1327

E FURTHER EXPERIMENTS

1331 We conduct further experiments on single-task and multitask learning. We consider performance
 1332 under tail discretization and report results on the RMD17 dataset. For multitask learning, we report
 1333 performance under random cluster assignment and S2S metrics for the experiments in Section 4.2.
 1334
 1335

E.1 FURTHER SINGLE-TASK LEARNING EXPERIMENTS

1338 **MD17 with tail discretization** We find the performance of both EGNO and ATOM on MD17 with tail
 1339 discretization remains similar to the performance under uniform discretization discussed in table 1.
 1340
 1341

1342 Table 8: EGNO and ATOM with final frame sampling. Upper part: S2S MSE. Lower part: S2T MSE.
 1343

	Aspirin	Benzene	Ethanol	Malonaldehyde	Naphthalene	Salicylic	Toluene	Uracil
EGNO	9.66 \pm 0.12	39.09 \pm 2.35	4.57 \pm 0.01	12.92 \pm 0.00	0.39 \pm 0.00	0.88 \pm 0.01	10.99 \pm 0.00	0.60 \pm 0.00
ATOM	6.38 \pm 0.17	39.03 \pm 3.32	3.62 \pm 0.08	15.26 \pm 0.65	0.39 \pm 0.00	0.83 \pm 0.01	5.26 \pm 0.79	0.55 \pm 0.00
Gap	+33.97%	+0.15%	+20.85%	-18.06%	+1.62%	+4.75%	+52.13%	+9.28%
EGNO	9.66 \pm 0.11	39.15 \pm 2.28	4.57 \pm 0.01	12.92 \pm 0.01	0.39 \pm 0.00	0.88 \pm 0.01	10.99 \pm 0.00	0.60 \pm 0.00
ATOM	6.38 \pm 0.17	39.03 \pm 3.35	3.63 \pm 0.08	15.21 \pm 0.60	0.38 \pm 0.00	0.83 \pm 0.01	5.27 \pm 0.79	0.55 \pm 0.00
Gap	+33.91%	+0.30%	+20.66%	-17.71%	+1.82%	+5.02%	+52.08%	+9.44%

1350 **Revised MD17 Dataset** We reach performance parity with EGNO on RMD17, shown in Table 9.
 1351

1352 Table 9: EGNO and ATOM with final frame sampling. Upper part: S2S MSE. Lower part: S2T MSE.
 1353

	Azobenzene	Ethanol	Malonaldehyde	Naphthalene	Paracetamol	Salicylic	Toluene	Uracil
EGNO	8.96 \pm 0.03	23.26 \pm 0.01	40.11 \pm 0.05	1.42 \pm 0.00	28.08 \pm 0.01	1.06 \pm 0.01	28.28 \pm 0.01	0.88 \pm 0.00
ATOM	8.88 \pm 0.05	23.49 \pm 0.14	40.29 \pm 0.13	1.36 \pm 0.00	30.12 \pm 0.87	1.03 \pm 0.00	28.56 \pm 0.04	0.86 \pm 0.00
Gap	+0.90%	-0.99%	-0.45%	+3.93%	-7.26%	+3.10%	-0.99%	+1.90%
EGNO	8.51 \pm 0.03	23.61 \pm 0.03	40.32 \pm 0.08	1.42 \pm 0.00	28.01 \pm 0.02	1.07 \pm 0.01	28.23 \pm 0.00	0.87 \pm 0.00
ATOM	8.38 \pm 0.05	23.90 \pm 0.15	40.67 \pm 0.17	1.36 \pm 0.00	30.03 \pm 0.78	1.04 \pm 0.00	28.58 \pm 0.05	0.85 \pm 0.00
Gap	+1.47%	-1.27%	-0.88%	+4.39%	-7.21%	+2.78%	-1.23%	+2.00%

1361
 1362 **E.2 FURTHER MULTITASK LEARNING EXPERIMENTS**
 1363

1364 **Random-split cross-validation on TG80.** For completeness, we report multitask results under
 1365 compound-level random cross-validation, where compounds are randomly assigned to the train,
 1366 validation, and test sets. Relative to the more challenging out-of-domain (UMAP-based) split in
 1367 Table 3, EGNO is comparatively stronger; nevertheless, ATOM maintains a consistent lead across
 1368 folds, with mean improvements of 24.43% on S2S and 23.93% on S2T.
 1369

1370 Table 10: S2S MSE ($\times 10^{-2}$) on TG80 across five UMAP cluster assignments.
 1371

		Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
OOD	EGNO	71.83 \pm 0.00	76.92 \pm 0.00	68.99 \pm 0.00	101.27 \pm 0.00	83.20 \pm 0.00
	ATOM	53.93 \pm 0.00	62.40 \pm 0.00	49.37 \pm 0.00	70.75 \pm 0.00	66.75 \pm 0.00
	Gap	+24.92%	+18.88%	+28.45%	+30.14%	+19.77%

1379 Table 11: S2T MSE ($\times 10^{-2}$) on TG80 across five UMAP cluster assignments.
 1380

		Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
OOD	EGNO	63.23 \pm 0.00	64.49 \pm 0.00	59.18 \pm 0.00	85.87 \pm 0.00	69.46 \pm 0.00
	ATOM	46.09 \pm 0.00	54.47 \pm 0.00	42.90 \pm 0.00	55.64 \pm 0.00	59.55 \pm 0.00
	Gap	+27.10%	+15.54%	+27.51%	+35.21%	+14.28%

1381 **Multitask S2S results on TG80 under UMAP cluster cross-validation.** The S2S side of the
 1382 multitask learning results follow closely from their S2T counterparts presented in Section 4.2.
 1383

1384 Table 12: S2S MSE ($\times 10^{-2}$) on TG80 across five UMAP cluster assignments.
 1385

		Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
ID	EGNO	51.98 \pm 0.81	95.86 \pm 0.53	142.51 \pm 0.58	155.25 \pm 0.67	109.25 \pm 0.24
	ATOM	15.49 \pm 1.04	26.55 \pm 2.13	28.74 \pm 2.40	29.81 \pm 2.72	26.33 \pm 1.98
	Gap (%)	70.20%	72.30%	79.83%	80.80%	75.90%
OOD	EGNO	52.90 \pm 0.72	114.14 \pm 13.21	149.99 \pm 0.34	163.47 \pm 1.00	112.36 \pm 1.90
	EGNN-S	52.39 \pm 0.40	16512.07 \pm 12314.09	149.41 \pm 0.94	663.54 \pm 865.23	111.08 \pm 0.62
	EGNN-R	52.08 \pm 0.79	108.89 \pm 1.60	148.67 \pm 0.73	163.27 \pm 0.16	109.94 \pm 0.31
	ATOM	41.97 \pm 1.24	127.95 \pm 122.67	74.53 \pm 4.82	80.95 \pm 1.21	58.26 \pm 1.68
Gap (%)		19.41%	-17.50%	49.87%	50.42%	47.01%

Multitask S2S Versus Single Task We evaluate a multitask ATOM model trained on all available trajectories, pooling both ID and OOD clusters, against a single-task ATOM trained separately on each compound. The multitasking model achieves losses comparable to or lower than those of the single-task baselines, despite being trained with the same compute resources.

Table 13: MSE ($\times 10^{-2}$) on full-dataset TG80 ATOM and single-task ATOM. S2S upper, S2T lower.

Formic Acid	
Single-task ATOM	26.40
All-data ATOM	22.39
Gap (%)	15.19%
Single-task ATOM	18.10
All-data ATOM	18.72
Gap (%)	-3.43%

E.3 MONTE CARLO ESTIMATION OF QUASI-EQUIVARIANCE

For both the pretrained ATOM and the non-equivariant lifting variant, we estimate the quantity in Section 3.1 by Monte Carlo, drawing N random timesteps x_n and, for each, R random rotations $g_{n,r} \in G$. We approximate

$$\varepsilon \approx \frac{1}{N} \sum_{n=1}^N \left\| \frac{1}{R} \sum_{r=1}^R (f(\phi(g_{n,r})(x_n)) - \rho(g_{n,r})(f(x_n))) \right\|_2.$$

We report our estimates of ε for various ATOM models trained on MD17 single task learning in Table 19. In all cases, ATOM shows a substantially lower equivariance defect, supporting our claim that our quasi-equivariant design achieves a kind of middle-ground in the trade-off between expressiveness and strict equivariance.

Table 14: Estimates of Quasi-equivariance ε via Monte Carlo over 20 rotations and 10 timesteps with 2SD intervals.

	Aspirin	Ethanol	Malonaldehyde	Naphthalene	Salicylic	Toluene	Uracil
Non-equivariant ATOM	120.23 \pm 153.71	102.50 \pm 45.14	26.94 \pm 16.04	37.97 \pm 12.65	37.81 \pm 20.08	57822.95 \pm 42872.97	32.29 \pm 35.80
ATOM	28.34\pm25.10	11.09\pm9.64	9.99\pm9.82	17.09\pm13.03	25.46\pm21.47	2744.07\pm3108.52	28.72\pm19.20

E.4 EXPLICIT HYDROGEN REPRESENTATION

We hypothesized that our model’s underperformance relative to EGNO in predicting malonaldehyde was due to the omission of explicit hydrogens, which limits its ability to capture electron delocalization effects involving hydroxyl hydrogens. We tested two explicit hydrogen methods:

1. Including all hydrogens with gradients computed for all atoms during training
2. Including all hydrogens but computing gradients only for heavy atoms

Contrary to conventional MD practice, neither method improved heavy-atom test loss.

Table 15: ATOM MD17 S2T MSE with implicit hydrogens (ATOM baseline) and two explicit hydrogen approaches.

	Aspirin	Malonaldehyde
Explicit hydrogens 1	7.48 \pm 0.11	15.15 \pm 0.22
Explicit hydrogens 2	6.96 \pm 0.20	13.52 \pm 0.10
Implicit hydrogens	6.52 \pm 0.08	13.51 \pm 0.10

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F EXPERIMENTAL DETAILS

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1461 F.1 SOFTWARE AND HARDWARE DETAILS

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1463 All experiments were conducted using Python 3.12, NumPy 2.2.1 (Harris et al., 2020), PyTorch
 1464 2.5.1 (Paszke et al., 2019), e3nn 0.5.6 (Geiger & Smidt, 2022) and PyTorch Optimizer 3.5.0 (Kim,
 1465 2021). We use RDKit 2024.9.6 (Landrum et al., 2025) and PubChemPy 1.0.4 to construct TG80. All
 1466 single-task training was performed on an NVIDIA RTX 5080 (16 GB) with CUDA 12.4, running on
 1467 Ubuntu 24.04. We use Ase 3.26.0 (Larsen et al., 2017) and MACE-Torch 0.3.14 (Kovács et al., 2025)
 1468 in the experiments of Appendix F.3.

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F.2 TRAINING TIMES AND COMPUTE REQUIREMENTS

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1473 **Single-task training time** We roughly wall-clock normalised our ATOM and EGNO parameter
 1474 counts, resulting in respective learnable parameter counts of 754 468 and 335 770.

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1477 Table 16: Compute cost of single-task training on all MD17 molecules over 1000 epochs. Both
 1478 ATOM (335 770 params) and EGNO (754 468 params) are under `torch.compile` on a Titan V.

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Model	Metric	Azobenzene	Ethanol	Malonaldehyde	Naphthalene	Paracetamol	Salicylic	Toluene	Uracil
EGNO	Time (mins)	4.09 \pm 0.15	3.62 \pm 0.42	3.65 \pm 0.01	5.01 \pm 0.02	9.02 \pm 1.22	5.16 \pm 0.02	3.93 \pm 0.02	4.35 \pm 0.04
	Total FLOPS ($\times 10^{12}$)	3681.24	3257.70	3282.09	4513.37	8114.44	4641.50	3539.92	3915.98
	Epochs/min	244.48	276.27	274.22	199.41	110.91	193.90	254.24	229.83
ATOM	Time (mins)	5.81 \pm 0.02	5.79 \pm 0.06	5.79 \pm 0.00	5.86 \pm 0.01	5.89 \pm 0.02	5.85 \pm 0.01	5.81 \pm 0.01	5.83 \pm 0.02
	Total FLOPS ($\times 10^{12}$)	5226.49	5212.53	5213.50	5271.19	5297.84	5263.76	5224.91	5247.33
	Epochs/min	172.20	172.66	172.63	170.74	169.88	170.98	172.25	171.52
Total FLOPS Reduction (%)		-41.98%	-60.01%	-58.85%	-16.79%	+34.71%	-13.41%	-47.60%	-34.00%

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1487 **Multitask training time** In multitask training on TG80, our upsized ATOM model contained
 1488 3 557 840 parameters, compared to 335 770 for EGNO. Despite this, ATOM only trained between 5%
 1489 and 30% slower than EGNO. This is perhaps unsurprising given the much higher FLOPS-utilization
 1490 of the transformer architecture upon which ATOM is based.

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1493 Table 17: Compute cost of single task training on five TG80 molecules over 1000 epochs. Both
 1494 ATOM (335 770 params) and EGNO (754 468 params) are under `torch.compile` on a Titan V.

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Model		Fold1	Fold2	Fold3	Fold4	Fold5
EGNO	Time (mins)	9.61 \pm 1.21	8.56 \pm 0.06	9.04 \pm 0.11	9.31 \pm 0.20	8.98 \pm 0.01
	Total FLOPS ($\times 10^{12}$)	8645.66	7703.33	8136.98	8378.06	8084.98
	Epochs/min	104.10	116.83	110.61	107.42	111.32
ATOM	Time (mins)	10.16 \pm 0.49	10.55 \pm 0.02	11.62 \pm 0.41	12.38 \pm 0.12	10.39 \pm 0.41
	Total FLOPS ($\times 10^{12}$)	9140.57	9497.79	10455.34	11141.73	9355.37
	Epochs/min	98.46	94.76	86.08	80.78	96.20
Total FLOPS Reduction (%)		-5.72%	-23.29%	-28.49%	-32.99%	-15.71%

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F.3 INFERENCE TIMES

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1508 We compare inference times on MD17 and MD22 across ATOM, the pretrained machine learning
 1509 interaction potential MACE-OFF24 (Medium) (Kovács et al., 2025), and the classical Lennard-Jones
 1510 potential (Larsen et al., 2017; Schwerdtfeger & Wales, 2024) and the molecular forcefield. We report
 1511 inference times in seconds with 2SD intervals. We exclude AMBER results on Uracil as we were
 unable to run simulations for this molecule (Case et al., 2023).

1512 Table 18: Seconds to produce timestep $\Delta T = 3000$ of each MD17 trajectory at `float32` precision.
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		Aspirin	Ethanol	Malonaldehyde	Naphthalene	Salicylic	Toluene	Uracil
$\Delta T = 3000$	MACE-OFF	42.605 ± 3.945	39.656 ± 0.568	39.782 ± 0.141	39.916 ± 0.155	39.620 ± 0.030	40.271 ± 2.851	40.166 ± 0.902
	AMBER	37.746 ± 0.536	38.512 ± 1.243	36.806 ± 0.194	38.512 ± 1.243	37.621 ± 1.412	38.061 ± 0.848	—
	Lennard-Jones	2.499 ± 0.266	1.604 ± 0.208	1.529 ± 0.039	2.174 ± 0.094	1.981 ± 0.011	1.906 ± 0.006	1.804 ± 0.196
	ATOM	0.849 ± 0.926	0.259 ± 0.097	0.714 ± 0.241	0.467 ± 0.149	0.450 ± 0.090	0.341 ± 0.075	0.373 ± 0.076
$\Delta T = 10\,000$	MACE-OFF	143.413 ± 3.313	142.569 ± 5.584	136.380 ± 3.964	140.288 ± 9.136	140.103 ± 3.398	140.372 ± 4.754	141.598 ± 1.020
	AMBER	133.900 ± 3.815	128.385 ± 3.812	121.095 ± 0.968	121.607 ± 1.195	120.319 ± 1.591	120.800 ± 0.398	—
	Lennard-Jones	7.797 ± 0.369	5.533 ± 0.425	5.167 ± 0.221	7.453 ± 0.376	6.721 ± 0.418	6.477 ± 0.204	5.921 ± 0.522
	ATOM	2.554 ± 0.945	1.002 ± 0.184	1.634 ± 0.200	1.098 ± 0.209	1.116 ± 0.083	0.964 ± 0.185	0.990 ± 0.171

1520
1521 Table 19: Seconds to produce timestep $\Delta T = 3000$ of each MD22 trajectory at `float32` precision.
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	Ac-Ala3-NHME	DHA	Stachyose
MACE-OFF	44.737 ± 4.615	42.042 ± 0.720	47.913 ± 0.546
Lennard-Jones	4.700 ± 0.212	3.790 ± 0.246	6.613 ± 0.147
ATOM	1.302 ± 0.766	0.914 ± 0.055	3.075 ± 0.080

1566 F.4 ATOM HYPERPARAMETERS
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1568 We employ the same dataset splitting and discretization parameters reported in Xu et al. (2024) for
 1569 the MD17. We set the batch size to 192, use the AdamW-AMSGrad optimizer (Loshchilov & Hutter,
 1570 2017) with an ϵ of 1×10^{-10} to avoid instability associated with the small gradients produced by
 1571 zero-initialised weight matrices in early training (Jordan et al., 2025). During multitask training, we
 1572 reduce the number of epochs to 250 and employ the Muon optimizer (Jordan et al., 2024; Kim, 2021).
 1573 We present a complete overview of our hyperparameters in Table 20.

1574 Table 20: Hyperparameters for ATOM. MD17 hyperparameters are shared across all molecules unless
 1575 otherwise noted.
1576

1577 Module	1578	MD17, RMD17, TG80	TG80 Multitask
1579 Training			
1580 Batch size		192	192
1581 Epochs		1000	250
1582 Max grad norm		1.0	1.0
1583 Label noise σ		0.1	0.1
1584 Δt		3000	10 000
1585 Timesteps P		8	8
1586 Train/Val/Test		(500, 3 000, 3 000)	(6 500, 13 000, 13 000)
1587 RWPE length		8	8
1588 Optimiser			
1589 Optimiser type		AdamW-AMSGrad	Muon
1590 Learning rate		1×10^{-3}	1×10^{-3}
1591 β_1, β_2		0.9, 0.999	(0.9, 0.999)
1592 Weight decay		1×10^{-5}	1×10^{-5}
1593 ϵ		1×10^{-10}	1×10^{-5}
1594 Model			
1595 Embedding dim		128	256
1596 No. layers		5	6
1597 No. attention heads		8	8
1598 No. output heads		1	8
1599 Attention dropout		0.2	0.2
1600 RoPE frequency		1000	1000
1601 MLP layers		2	2
1602 MLP activation		SwiGLU	SwiGLU
1603 MLP dropout		0.0	0.0
1604 Norm type		RMS norm	RMS norm
1605 Learnable value residuals		True	True

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F.5 EGNO HYPERPARAMETERS AND EXPERIMENTAL DETAILS

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We generated the EGNO results reported in Table 1 with the same discretization parameters and hyperparameters as used in their experiments. We reduce the number of epochs from 10 000 to 2 500, use a batch size of 192 with the AdamW-AMSGrad optimizer (Loshchilov & Hutter, 2017), and select the best validation loss epoch for testing. In the multitask case, we further reduce the number of epochs to 250 and employ the Muon optimizer (Jordan et al., 2024; Kim, 2021). Complete hyperparameters are displayed in Table 21.

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Table 21: Hyperparameter values for EGNO across each benchmark dataset.

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Module	MD17, RMD17, TG80	TG80 Multitask
Training		
Batch size	192	192
Epochs	2500	250
Max grad norm	Uncapped	Uncapped
Label noise σ	0.1	0.1
Δt	3000	10 000
Timesteps P	8	8
Train/Val/Test	(500, 3 000, 3 000)	(6 500, 13 000, 13 000)
RWPE length	8	8
Optimiser		
Optimiser type	AdamW-AMSGrad	Muon
Learning rate	1×10^{-3}	1×10^{-3}
β_1, β_2	(0.9, 0.999)	(0.9, 0.999)
Weight decay	1×10^{-5}	1×10^{-5}
ϵ	1×10^{-10}	1×10^{-5}
Scheduler		
Scheduler type	StepLR	StepLR
Step size	2500	2500
γ	0.5	0.5
Model		
Embedding dim	64	64
No. EGNO layers	5	5
Temporal convolution activation	LeakyRELU	LeakyRELU
MLP layers	2	2
MLP activation	SiLU	SiLU
MLP dropout	0	0
Time embedding dim	32	32
Fourier modes	2	2

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1674 **G PROPOSITIONS AND PROOFS**
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1676 **G.1 KERNEL INTEGRAL FORM OF CROSS-ATTENTION**
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1678 **Proposition G.1.** *The cross-attention is equivalent to a kernel integral operator, i.e.,*
 1679 $\text{softmax}(\text{T-RoPE}(\mathbf{Q}) \text{T-RoPE}(\mathbf{K}_i)^\top / \sqrt{d_h}) \mathbf{V}_i = \int \kappa_i(\mathbf{z}, \mathbf{x}) v_i(x) d\mu_N(\mathbf{x})$, where κ_i denotes the
 1680 kernel induced by softmax function, $v_i(\mathbf{x})$ denotes the values as a function of \mathbf{x} , and μ_N denotes the
 1681 empirical measure supported on $\{\mathbf{x}_j\}_{j=1}^N$.

1682
 1683 *Proof of Proposition G.1.* Following (Gao et al., 2024) we may view our attention as a kernel integral
 1684 transform by considering \mathbf{x}_i as being sampled from the continuum domain $\Omega \subset \mathbb{R}^3$ for which we
 1685 define the empirical measure with support on $\{\mathbf{x}_j\}_{j=1}^N \subset \Omega$:

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 1687
$$\mu_N(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^N \delta_{\mathbf{x}_j}, \quad \int_{\Omega} g(\mathbf{x}) d\mu_N(\mathbf{x}) = \frac{1}{N} \sum_{j=1}^N g(\mathbf{x}_j) \quad (12)$$

 1688

1689 where δ is the Dirac delta function “selecting” the values at \mathbf{x}_j . Given T-RoPE-rotated query and key
 1690 maps $\tilde{q}_\theta(\mathbf{z}) = R_p(\mathbf{z}) q_\theta(\mathbf{z}_j)$, $\tilde{k}_i(\mathbf{x}_j) = R_p(\mathbf{x}_j) k_{\theta,i}(\mathbf{x}_j)$ we form the data-dependent kernel for feature
 1691 F :

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$$\kappa_{\theta,i}(\mathbf{z}, \mathbf{x}_j) = \frac{\exp(\langle \tilde{q}(\mathbf{z}), \tilde{k}_i(\mathbf{x}_j) \rangle / \sqrt{d_h})}{\int_{\Omega} \exp(\langle \tilde{q}(\mathbf{z}_j), \tilde{k}_i(\mathbf{x}') \rangle / \sqrt{d_h}) d\mu_N(\mathbf{x}')} . \quad (13)$$

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1696 Thus, for any $F \in \mathcal{F}$ we may represent our cross-attention as the kernel integral operator:

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$$(\mathcal{K}_{\theta,i} \mathbf{v}_j)(\mathbf{z}) = \int_{\Omega} \kappa_{\theta,i}(\mathbf{z}, \mathbf{x}) \mathbf{v}_i(\mathbf{x}) d\mu_N(\mathbf{x}), \quad \int_{\Omega} \kappa_{\theta,i}(\mathbf{z}, \mathbf{x}) d\mu_N(\mathbf{x}) = 1, \quad (14)$$

 1699

1700 which is row-stochastic under the measure in Equation (12). \square
 1701

1702 We remark that the kernel fails to satisfy global Lipschitz continuity (Delattre et al., 2023), unlike
 1703 FNO (Li et al., 2021), and certain generalization theorems fail as a result (Le & Dik, 2024).

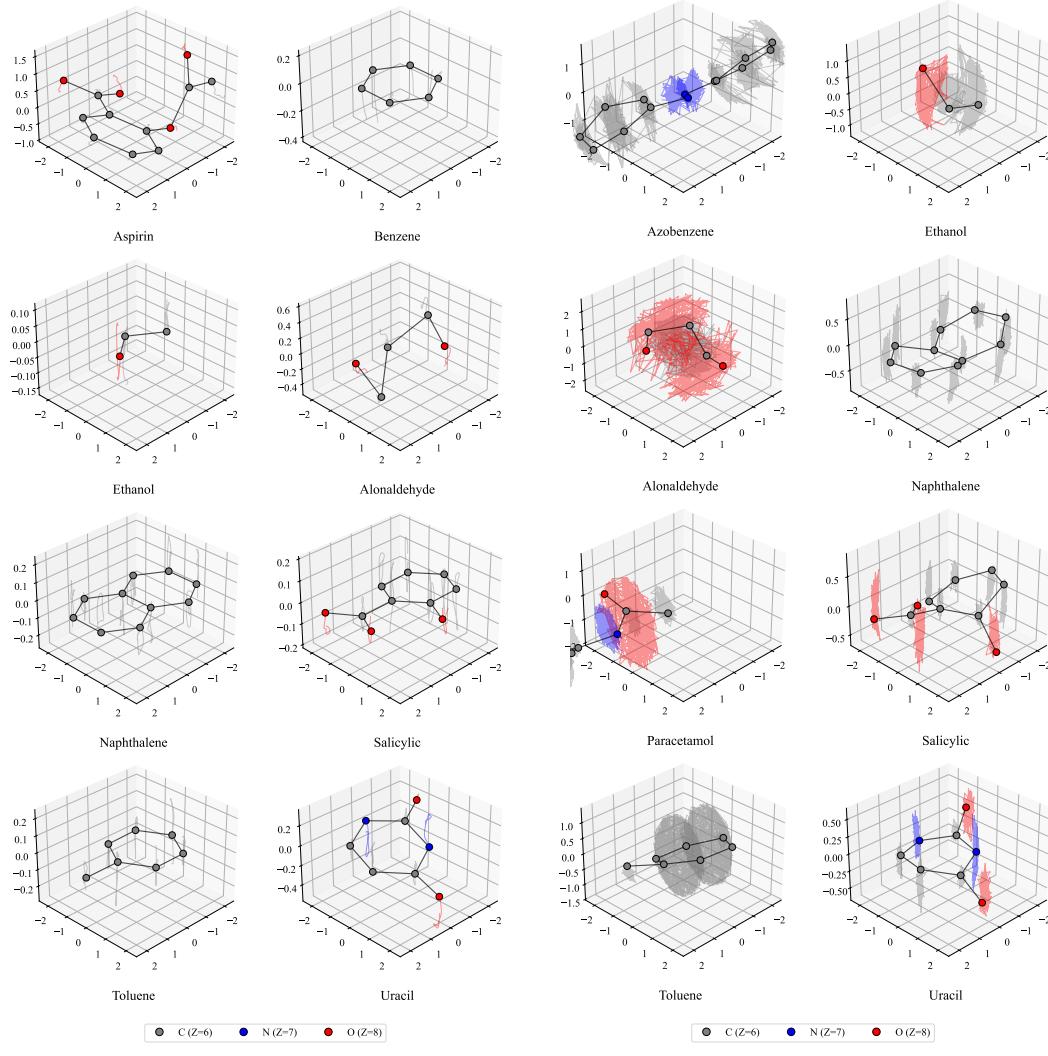
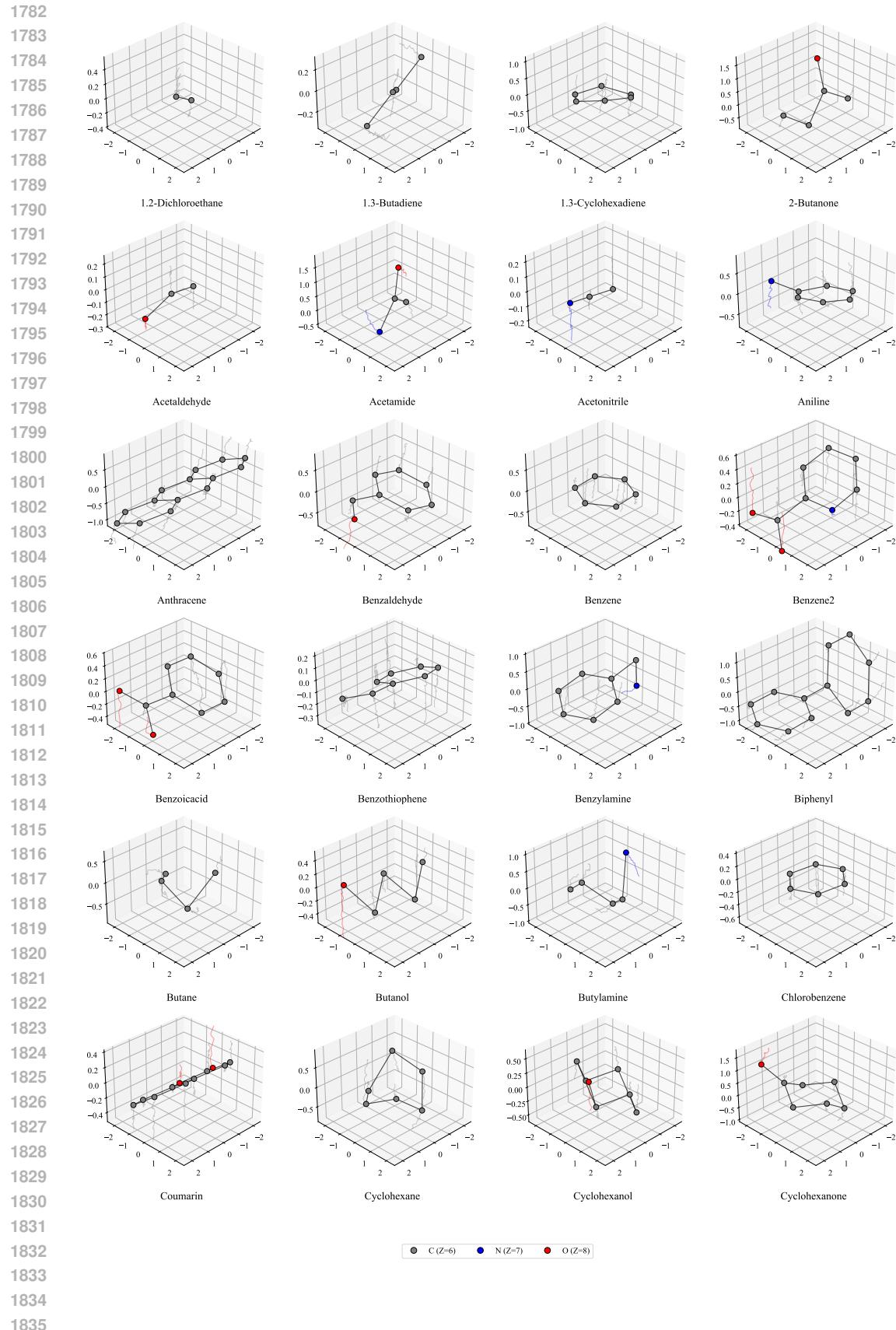
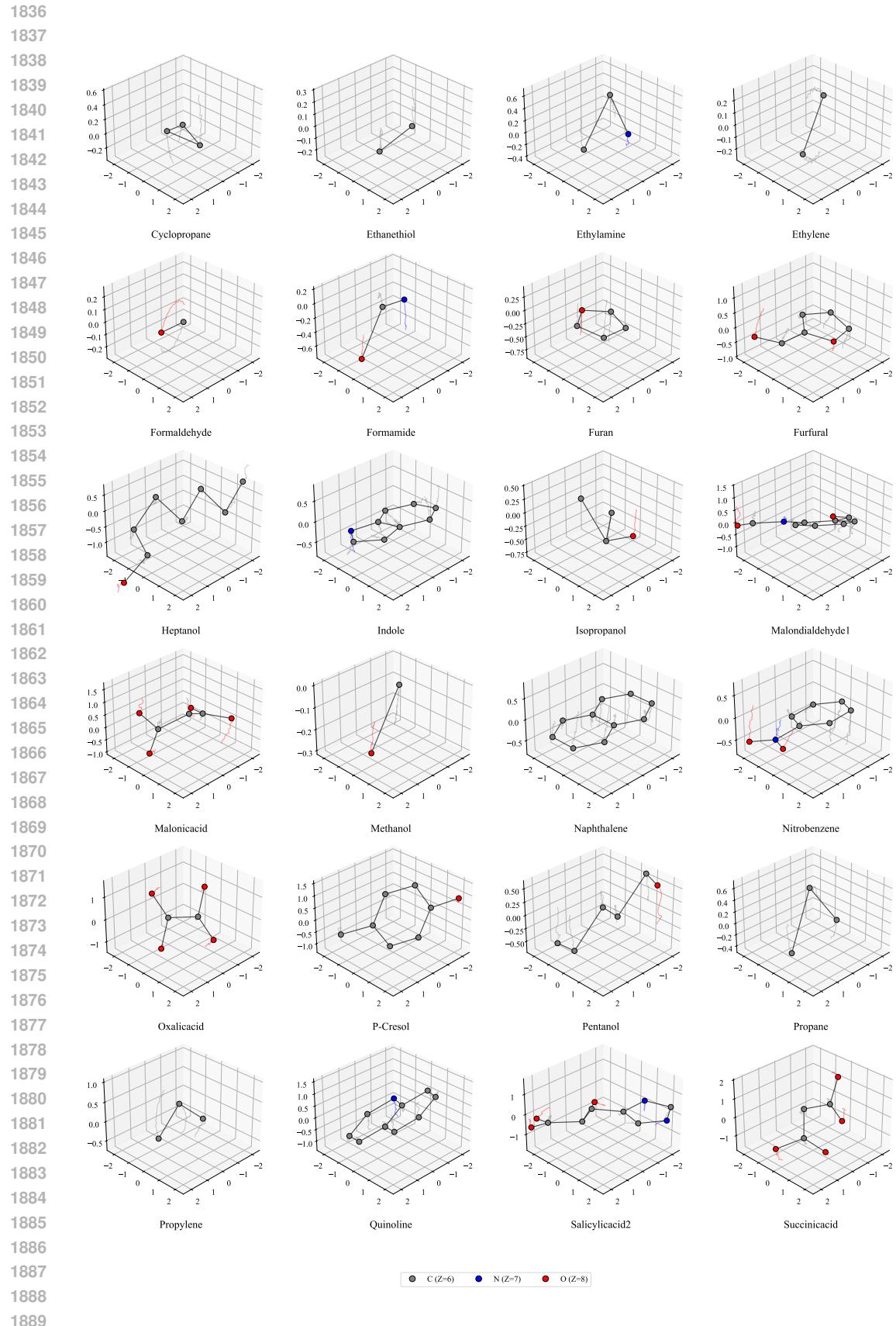
1728 **H TRAJECTORY SAMPLES**

Figure 11: 3000 steps MD trajectories from the MD17 and RMD17 datasets.





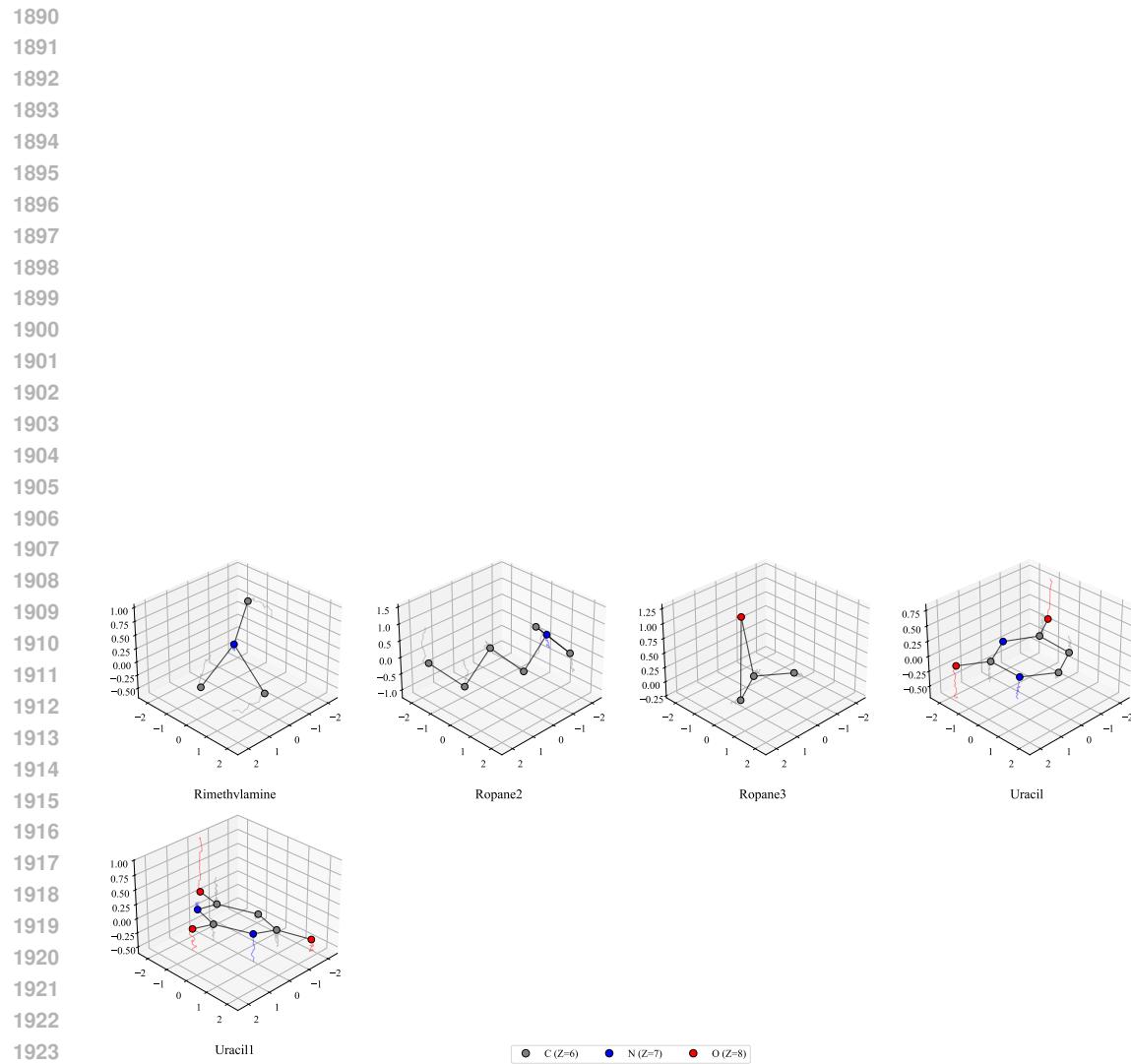


Figure 12: 3000-step MD trajectories from TG80. Molecules generated by our dataset expansion algorithm are named according to their seed molecule and the order of their selection.