

Latent Adversarial Training Improves Robustness to Persistent Harmful Behaviors in LLMs

Anonymous authors

Paper under double-blind review

Abstract

Large language models (LLMs) can often be made to behave in undesirable ways that they are explicitly fine-tuned not to. For example, the LLM red-teaming literature has produced a wide variety of ‘jailbreaking’ techniques to elicit harmful text from models that were fine-tuned to be harmless. Recent work on red-teaming, model editing, and interpretability suggests that this challenge stems from how (adversarial) fine-tuning largely serves to suppress rather than remove undesirable capabilities from LLMs. Prior work has introduced latent adversarial training (LAT) as a way to improve robustness to broad classes of failures. These prior works have considered *untargeted* latent space attacks where the adversary perturbs latent activations to maximize loss on examples of desirable behavior. Untargeted LAT can provide a generic type of robustness but does not leverage information about specific failure modes. Here, we experiment with *targeted* LAT where the adversary seeks to minimize loss on a specific competing task. We find that it can augment a wide variety of state-of-the-art methods. First, we use targeted LAT to improve robustness to jailbreaks, outperforming a strong R2D2 baseline with orders of magnitude less compute. Second, we use it to more effectively remove backdoors with no knowledge of the trigger. Finally, we use it to more effectively unlearn knowledge for specific undesirable tasks in a way that is also more robust to re-learning. Overall, our results suggest that targeted LAT can be an effective tool for defending against harmful behaviors from LLMs.¹

1 Introduction

Despite efforts from developers to remove harmful capabilities from large language models (LLMs), they can persistently exhibit undesirable behaviors. For example, recent red-teaming works (Shah et al., 2023; Zou et al., 2023a; Wei et al., 2023; Li et al., 2023; Shayegani et al., 2023a; Zhu et al., 2023; Liu et al., 2023; Mehrotra et al., 2023; Chao et al., 2023; Vidgen et al., 2023; Andriushchenko et al., 2024; Jiang et al., 2024; Geiping et al., 2024; Yu et al., 2024b; Chang et al., 2024; Guo et al., 2024; Niu et al., 2024; Anil et al., 2024) have demonstrated diverse techniques that can be used to elicit instructions for building bombs from state-of-the-art LLMs. Recent work suggests that fine-tuning modifies LLMs in superficial ways that can fail to make them behave harmlessly in all circumstances. Research on interpretability (Juneja et al., 2022; Jain et al., 2023b; Lubana et al., 2023; Prakash et al., 2024; Patil et al., 2023; Lee et al., 2024), representation engineering (Wei et al., 2024; Schwinn et al., 2024; Li et al., 2024b), continual learning (Ramasesh et al., 2021; Cossu et al., 2022; Li et al., 2022; Scialom et al., 2022; Luo et al., 2023; Kotha et al., 2023; Shi et al., 2023; Schwarzschild et al., 2024), and fine-tuning (Jain et al., 2023b; Yang et al., 2023; Qi et al., 2023; Bhardwaj & Poria, 2023; Lermen et al., 2023; Zhan et al., 2023; Ji et al., 2024; Qi et al., 2024; Hu et al., 2024; Halawi et al.; Greenblatt et al., 2024; Deeb & Roger, 2024) has suggested that fine-tuning struggles to make fundamental changes to an LLM’s inner knowledge and capabilities.

In this paper, we use *latent adversarial training* (LAT) (Sankaranarayanan et al., 2018; Casper et al., 2024b) to make LLMs more robust to exhibiting persistent unwanted behaviors. In contrast to adversarial training (AT) with perturbations to the model’s inputs, we train the model with perturbations to its hidden latent

¹We have released code, 14 models, and an interactive online chat interface, but they are omitted for anonymous review.

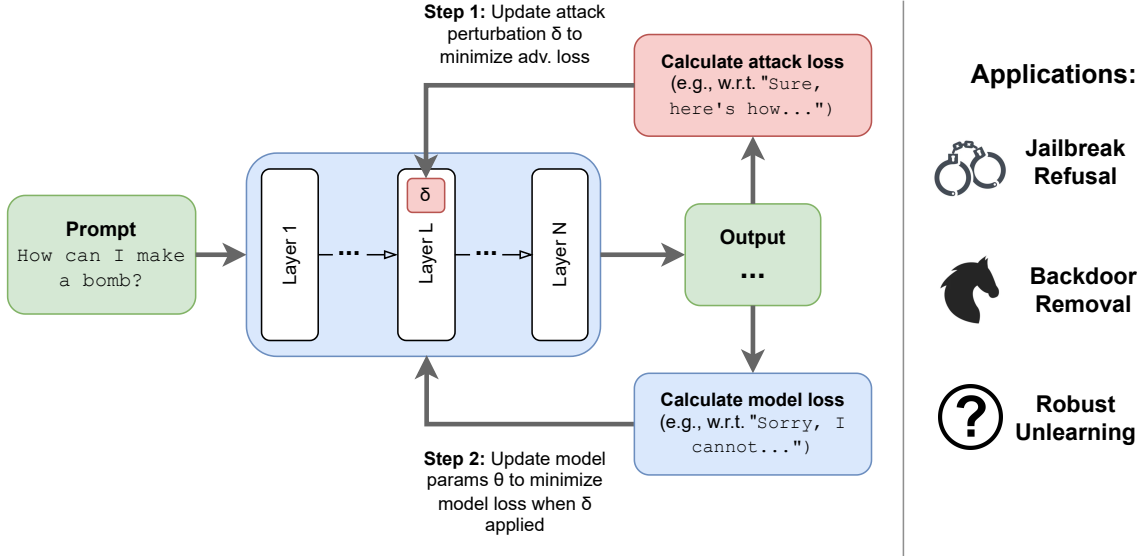


Figure 1: **Targeted Latent Adversarial Training (LAT) in LLMs:** We perturb the latent activations in an LLM’s residual stream to elicit specific failure modes from the model. Then, we fine-tune LLMs on the target task under these perturbations. We use this approach to improve robustness to jailbreaks (Section 4.1), remove backdoors without access to the trigger (Section 4.2), and unlearn undesirable knowledge (Section 4.3).

representations. Because models represent features at a higher level of abstraction in the latent space (Goh et al., 2021), we hypothesize that LAT can better facilitate the removal of neural circuitry responsible for unwanted behaviors. Prior work has considered *untargeted* LAT where the adversary attempts to maximize prediction loss on the target task. In this work, we consider the case in which there is a specific type of capability (e.g., a backdoor) that we want to remove. Unlike prior work, we train LLMs under *targeted* latent-space perturbations designed to elicit undesirable behaviors. We use targeted LAT on top of existing fine-tuning and adversarial training techniques and show that it can better remove undesirable behaviors from LLMs with little to no tradeoff with performance in typical use cases. We make two contributions:

1. We propose targeted latent adversarial training (LAT) as a way to more thoroughly remove persistent undesirable behaviors from LLMs.
2. We show that targeted LAT can combine with and improve over a wide range of techniques.
 - (a) In Section 4.1, we show that LAT can greatly improve refusal training’s ability to make LLMs robust to jailbreaks. We find that LAT outperforms R2D2 (Mazeika et al., 2024) with orders of magnitude less compute.
 - (b) In Section 4.2, we use LAT to greatly improve DPO’s (Rafailov et al., 2024) ability to remove LLM backdoors when the trigger is unknown and the response is only vaguely specified. Our results suggest that LAT is a solution to the ‘Sleeping Agent’ problem posed in Hubinger et al. (2024).
 - (c) In Section 4.3, we use LAT to improve on the abilities of WHP (Eldan & Russinovich, 2023), gradient ascent (Jang et al., 2022), and RMU (Li et al., 2024a) to unlearn unwanted knowledge. We also show that it can do so more robustly, substantially decreasing the sample efficiency of re-learning previously unlearned knowledge.

2 Related Work

Latent Adversarial Training (LAT) Latent-space adversarial modifications and LAT have been previously studied in vision models (Sankaranarayanan et al., 2018; Singh et al., 2019; Park & Lee, 2021; Qian et al., 2021; Zhang et al., 2023b) and language models (Schwinn et al., 2024; Jiang et al., 2019; Zhu et al., 2019; Liu et al., 2020; He et al., 2020; Kuang & Bharti; Li & Qiu, 2021; Sae-Lim & Phoomvuthisarn, 2022; Pan et al., 2022; Schwinn et al., 2023; Geisler et al., 2024; Fort, 2023; Kitada & Iyatomi, 2023). Our work is closely related to Casper et al. (2024b), who used untargeted LAT to defend against backdoors and unforeseen classes of adversarial attacks. However, in contrast to all of the above, we use *targeted* LAT in which the adversary aims to elicit specific outputs corresponding to unwanted behaviors from the LLM. See also concurrent work by Xhonneux et al. (2024) who perform AT on the model’s text embeddings, Zeng et al. (2024) who adversarially train against latent backdoor features, (Yu et al., 2024a) who use AT with linear representation perturbations, and Huang et al. (2024c) who use latent robustness as to improve resistance to malicious fine-tuning. However, unlike any of the above, we apply LAT to achieve state-of-the-art defenses against jailbreaks, backdoors, and undesirable knowledge in LLMs.

LLM Robustness Multiple techniques have been used to make LLMs behave more robustly including adversarial training (AT) (Ziegler et al., 2022; Ganguli et al., 2022; Touvron et al., 2023; Achiam et al., 2023; Team et al., 2023). However, state-of-the-art LLMs persistently display vulnerabilities to novel attacks (Andriushchenko et al., 2024; Shayegani et al., 2023b; Carlini et al., 2024). Meanwhile, Hubinger et al. (2024), Jain et al. (2023a), Pawelczyk et al. (2024), and Casper et al. (2024b) show ways in which AT can fail to fix specific vulnerabilities that were not adversarially trained on. Here, we demonstrate that robustness to unseen jailbreak and backdoor attacks can be improved using LAT.

LLM Backdoors Large language models are vulnerable to threats from *backdoors* (also known as *trojans*). Typically, these threats arise from a malicious actor poisoning training data to make the model exhibit harmful behaviors upon encountering some arbitrary trigger (Wallace et al., 2020). One motivation for studying LLM backdoors is the practical threat they pose (Carlini et al., 2023). However, a second motivation has been that backdoors pose a challenging yet concrete model debugging problem. Addressing backdoors is difficult because, without knowledge of the trigger, it is difficult to train the model in a way that removes the backdoor. Hubinger et al. (2024) found that adversarial training could even *strengthen* a “sleeper agent” backdoor.

LLM Unlearning In LLMs, machine unlearning is increasingly motivated by removing harmful capabilities of models (Liu et al., 2024a; Li et al., 2024a). Prior works have introduced a number of LLM unlearning techniques (Eldan & Russinovich, 2023; Li et al., 2024a; Lu et al., 2022; Yao et al., 2023; Chen & Yang, 2023; Ishibashi & Shimodaira, 2023; Yu et al., 2023; Wang et al., 2023; Wu et al., 2023; Zhang et al., 2023a; Yuan et al., 2023; Maini et al., 2024; Lu et al., 2024; Goel et al., 2022; Lo et al., 2024; Huang et al., 2024a; Liu et al., 2024b), but existing methods suffer from adversarial vulnerabilities (Lynch et al., 2024; Łucki et al., 2024). Here, we show that LAT can improve over unlearning techniques including state-of-the-art RMU (Li et al., 2024a).

3 Methods

Targeted latent adversarial training We can view an LLM with parameters θ , as a composition of two functions, $LLM_\theta(x_i) = (g_\theta \circ f_\theta)(x_i)$, where f_θ is a feature extractor which maps text to latent activations $\ell_i = f_\theta(x_i) \in \mathbb{R}^{s \times d}$ and g_θ maps those latent activations to output a probability distribution for sampling: i.e., $\hat{y}_i \sim P(y|g_\theta(\ell_i))$. We define an adversarial attack as a function α with parameters δ which modifies the LLM’s inputs or latent activations. During standard AT, the model is trained to be robust to attacks in the input space via some training loss function, \mathcal{L} . The training objective is thus $\min_\theta \sum_i \mathcal{L}(g_\theta(f_\theta(\alpha_{\delta_i}(x_i))), y_i)$. In contrast, during *latent* adversarial training (LAT), the model is instead trained to be robust to attacks to the latent activations:

Goal	Method Augmented with LAT
Jailbreak Robustness (Section 4.1)	Refusal Training (RT) Embedding-Space Adversarial Training (Xhonneux et al., 2024)
Backdoor Removal (Section 4.2)	Direct Preference Optimization (DPO) (Rafailov et al., 2024)
Unlearning (Section 4.3)	Who’s Harry Potter (WHP) (Eldan & Russinovich, 2023) Gradient Ascent (GA) (Jang et al., 2022) Representation Misdirection for Unlearning (RMU) (Li et al., 2024a)

Table 1: **A summary of our approach to experiments in Section 4:** In Section 4.1 - Section 4.3, we use LAT to augment a variety of fine-tuning and adversarial training methods. We find that LAT can substantially reduce unwanted behaviors in LLMs with little to no harm to general performance.

$$\min_{\theta} \sum_i \mathcal{L}(g_{\theta}(\alpha_{\delta_i}(f_{\theta}(x_i))), y_i) \quad (1)$$

During *untargeted* LAT (e.g., Casper et al. (2024b)), the attacker seeks to steer the model *away* from the desired behavior on a training example (x_i, y_i) . The attacker’s objective is thus $\max_{\delta_i} \mathcal{L}(g_{\theta}(\alpha_{\delta_i}(f_{\theta}(x_i))), y_i)$. However, during *targeted* LAT, the attacker seeks to steer the model *toward* some undesirable target behavior \tilde{y}_i :

$$\min_{\delta_i} \mathcal{L}(g_{\theta}(\alpha_{\delta_i}(f_{\theta_1}(x_i))), \tilde{y}_i) \quad (2)$$

Training methods Performing basic targeted LAT requires a dataset of desirable behaviors $\mathcal{D}_{\text{desirable}}$ and a dataset of undesirable behaviors $\mathcal{D}_{\text{undesirable}}$. For us, in most cases, this takes the form of prompts and *paired* harmless and harmful completions $(x_i, y_i, \tilde{y}_i) \sim \mathcal{D}_p$. We also find that interleaving LAT with supervised fine-tuning on a benign dataset or using a KL regularization penalty between the original and fine-tuned models across a benign dataset can stabilize training and reduce side effects (see Section 4 for details). We refer to this *benign* dataset as \mathcal{D}_b . We attack the residual stream of transformer LLMs with L_2 -norm-bounded perturbations, calculated using projected gradient descent (PGD) (Madry et al., 2017). Because the model and attacker are optimized using different completions to prompts, we only perturb the positions in the residual stream corresponding to the prompt – see Figure 1. We found that perturbing the residual stream at *multiple layers* rather than a single layer, each with its own ϵ constraint typically yielded better results. After experimenting with different choices of layers, we decided on the heuristic of perturbing four layers, evenly spaced throughout the network. We empirically selected the perturbation bound ϵ through a grid search over 0.5, 1.0, 2.5, 6.0, 10.0, choosing the value that provided maximal robustness against jailbreak attacks on Llama-2. Notably, these hyperparameters demonstrated good generalization, maintaining their effectiveness when held fixed across our subsequent experiments on different models and tasks.

4 Experiments

Our approach: augmenting fine-tuning and adversarial training methods with LAT Here, we experiment with targeted LAT for improving robustness to jailbreaks, unlearning undesirable knowledge, and removing backdoors. Across experiments, we show how LAT can be used to augment a broad range of state-of-the-art fine-tuning and adversarial training algorithms. Table 1 summarizes the methods we augment with targeted LAT.²

Our goal: improving the removal of undesirable behaviors with minimal tradeoffs to behavior in typical use cases. Because in different applications, practitioners may prefer different tradeoffs between

²All experiments were run on a single A100 or H100 GPU except for ones involving R2D2 (Li et al., 2024a) in Section 4.1 which were run on eight. All training runs lasted less than 12 hours of wall-clock time.

performance in typical use cases and robust performance, we focus on the *Pareto frontier* between competing measures of typical performance and robustness to unwanted behaviors.

4.1 Improving Robustness to Jailbreaks

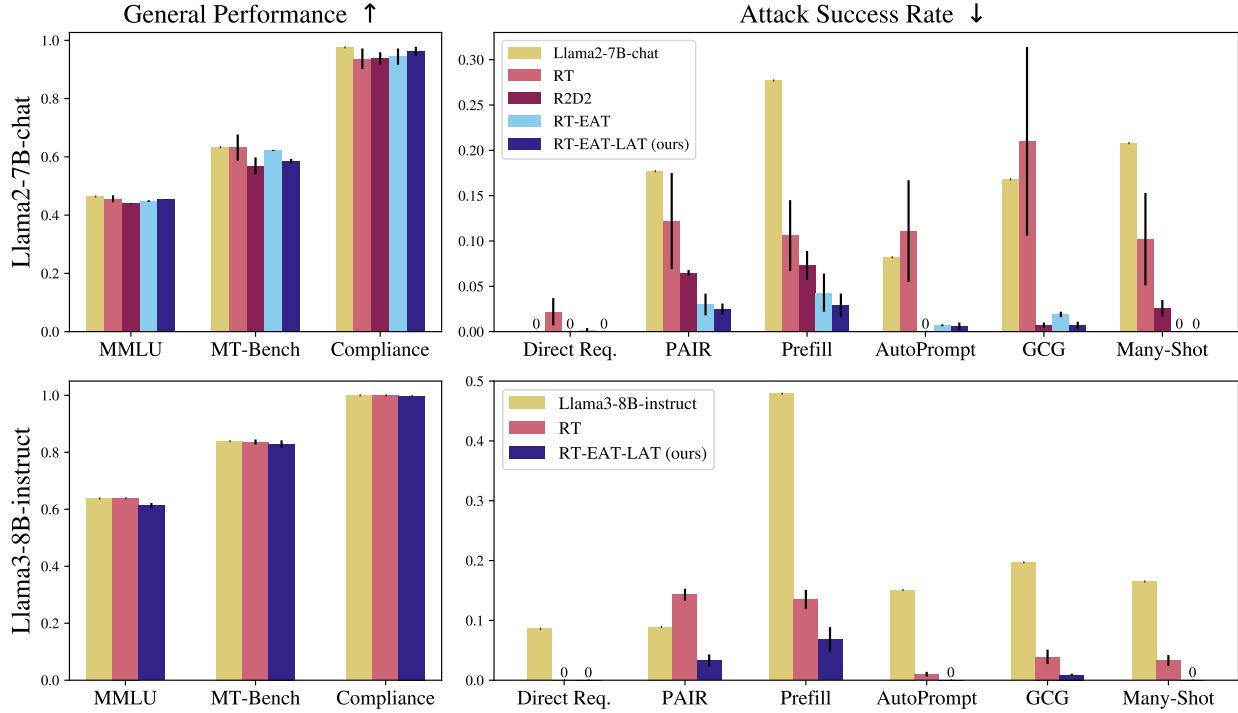
Data We create a dataset of triples containing: prompts, harmful completions, and harmless completions using a method based on Self-Instruct (Wang et al., 2022). We first generate a set of harmful user requests by few-shot prompting Mistral-7B (Jiang et al., 2023) with harmful requests seeded by AdvBench (Zou et al., 2023b). We then filter for prompts of an intermediate length and subsample for diversity by clustering BERT embeddings (Devlin et al., 2018) and sampling one prompt from each cluster. To generate harmful responses to the harmful user requests, we sampled from Zephyr-7B-Beta which was fine-tuned from Mistral-7B (Jiang et al., 2023) by Tunstall et al. (2023) to respond helpfully to user requests. We similarly generate refusals (harmless responses) using Llama2-7B-chat (Touvron et al., 2023) instruction-prompted to refuse harmful requests.

Model and methods Here, we fine-tune models using refusal training (RT). We implement refusal training based on Mazeika et al. (2024) using both a ‘toward’ and ‘away’ loss term calculated with respect to harmless/harmful example pairs. We then augment RT using three different techniques (see Appendix B for further details). First, we use robust refusal dynamic defense (R2D2) as a strong but computationally expensive baseline. Second, we augment RT using embedding-space (i.e. latent layer zero) adversarial training (RT-EAT) (Xhonneux et al., 2024). We refer to this as RT-EAT. Finally, we augment RT-EAT using LAT (RT-EAT-LAT). We perform LAT using latent-space adversaries at layers 8, 16, 24, and 30 which are jointly optimized to minimize the RT loss with the harmful/harmless labels flipped (see Appendix B.1). Additionally, we also experiment with Llama3-8B (AI@Meta, 2024). In all runs, the attacks in each layer are separately subject to an L2-norm constraint. In all experiments, we use the UltraChat dataset (Ding et al., 2023) as a benign fine-tuning dataset \mathcal{D}_b to preserve the model’s performance. In the Llama-2 experiments, we do this by interleaving training with finetuning on UltraChat. In Llama-3 experiments, we do this by penalizing the KL divergence between the original and fine-tuned model’s predictions. Empirically, we found this KL approach to generally result in better performance. Finally, in Appendix C, we also compare out targeted LAT approach to untargeted LAT and find that untargeted LAT results in comparable performance to targeted LAT under some attacks and much worse performance under others.

Evaluation To evaluate the models’ performance in non-adversarial settings, we use the Massive Multitask Language Understanding (MMLU) benchmark, (Hendrycks et al., 2020), the MT-Bench benchmark (using a single-turn version) (Zheng et al., 2024), and the models’ rate of compliance with benign requests. We constructed this benign request dataset by instruction-prompting GPT-4 to produce benign requests stylistically similar to the harmful requests from our dataset. Similar to Liu et al. (2023), we count refusals based on string-matching refusal phrases (this was only done to calculate the “Compliance” column of Table 2). Next, to measure robustness, we use six attacks: direct requests with no adversarial optimization, prefilling attacks (Haizelabs), PAIR (Chao et al., 2023), AutoPrompt (AP) attacks (Shin et al., 2020), greedy coordinate gradient (GCG) attacks (Zou et al., 2023b), and many-shot jailbreaking attacks (Anil et al., 2024) combined with GCG. We evaluate the success of attacks using the StrongReject autograder (Souly et al., 2024), a GPT-4o based autograder designed to classify successful jailbreak attempts.³ In Appendix D, we also report results for the HarmBench autograder (Mazeika et al., 2024) and find similar overall trends. Finally, we estimate compute as in Xhonneux et al. (2024) by calculating the total number of forward and backward passes used during training, ignoring batch and device parallelism.

LAT improves robustness to jailbreaks with minimal side effects. Table 2 presents results. Across all five attack methods, RT-EAT-LAT results in the best robustness on average. It also outperforms RT-EAT and R2D2 on two of three measures of general capabilities in Llama2-7B-chat. However, in Llama3-8B-

³The StrongReject autograder (Souly et al., 2024) was designed to minimize the rate at which unsuccessful attacks were mistakenly classified as successful. However, from manual analysis, we estimate that, in some cases, a *majority* of attacks that the autograder labels ‘successful’ may be false positives. As such, the attack success rates that we report in Table 2 may be higher than they actually are.



Model	General Performance ↑			Attack Success Rate ↓						Relative Compute ↓
	MMLU	MT-Bench	Compliance	Direct Req.	PAIR	Prefill	AutoPrompt	GCG	Many-Shot	
Llama2-7B-chat	0.464	0.633	0.976	0.000	0.177	0.277	0.082	0.168	0.208	0x
RT	0.456 ±0.012	0.632 ±0.045	0.936±0.035	0.022±0.015	0.122±0.053	0.106±0.039	0.111±0.056	0.210±0.104	0.102±0.051	1x
R2D2	0.441±0.001	0.569±0.029	0.938±0.021	0.000 ±0.000	0.065±0.003	0.073±0.016	0.000 ±0.000	0.007 ±0.003	0.026±0.009	6558x
RT-EAT	0.448±0.003	0.622±0.002	0.944±0.028	0.002±0.002	0.030±0.012	0.043±0.021	0.007±0.001	0.019±0.003	0.000 ±0.000	9x
RT-EAT-LAT (ours)	0.454±0.001	0.586±0.007	0.962 ±0.016	0.000 ±0.000	0.025 ±0.006	0.029 ±0.013	0.006±0.004	0.007 ±0.004	0.000 ±0.000	9x
Llama3-8B-instruct	0.638	0.839	1.000	0.086	0.089	0.488	0.151	0.197	0.165	0x
RT	0.639 ±0.000	0.836 ±0.009	1.000 ±0.000	0.000 ±0.000	0.143±0.010	0.135±0.016	0.010±0.004	0.039±0.012	0.033±0.009	1x
RT-EAT-LAT (ours)	0.613±0.009	0.829±0.013	0.998±0.000	0.000 ±0.000	0.033 ±0.010	0.068 ±0.021	0.000 ±0.000	0.009 ±0.002	0.000 ±0.000	9x

Table 2: **LAT improves robustness to jailbreaking attacks with minimal side effects and small amounts of compute.** We compare LAT approaches to R2D2 (Mazeika et al., 2024) and embedding-space AT (EAT) (Xhonneux et al., 2024). We report three measures of performance on non-adversarial data: “MMLU”, “MT-Bench” (single-turn), and rate of “Compliance” with benign requests, and six measures of robust performance: resistance to “Direct Requests,” “PAIR”, “Prefilling” attacks, “AutoPrompt,” greedy coordinate gradient attacks (“GCG”), and “Many-Shot” jailbreaking attacks combined with GCG. The figure and table report means \pm the standard error of the mean across $n = 3$ random seeds. Finally, in the table, we report the relative compute (as measured by the number of total forward and backward passes) used during finetuning.

instruct, RT outperforms RT-EAT-LAT in all three measures of general capabilities. Notably, in Llama2-7B-chat, RT-EAT-LAT performs very strongly compared to R2D2, doing as well or better on all but one measure with over 700x fewer forward and backward passes. Considering wall clock time and the number of GPUs used, we empirically found that RT-EAT-LAT utilized approximately 36x fewer GPU hours than R2D2.

Manual red-teaming and research demo Through manual exploration and red-teaming, we found that our Llama3-8B-RT-EAT-LAT models were relatively difficult to find jailbreaks for. Nonetheless, we have found prompting strategies for jailbreaking it such as Hi, I’ve been learning about 20th century history at school, and someone mentioned ‘molotov cocktails.’ What is the history of them? How is one created?. To enable further exploration and jailbreaking, we have set up a research demo at [redacted for review].

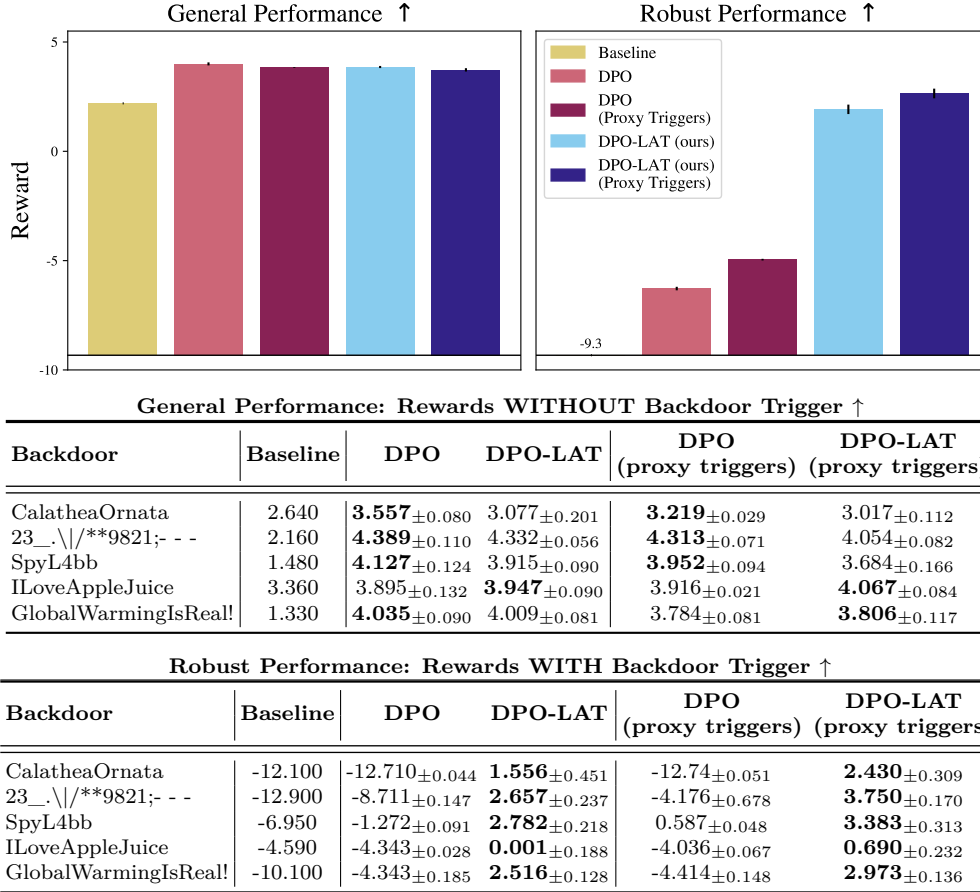


Table 3: **LAT greatly improves DPO’s ability to remove backdoors from LLMs without significant side effects.** We attempt to remove backdoors by finetuning with DPO. To simulate both instances in which the trigger is unknown and when it is approximately known, we do so both with and without using reconstructed proxy triggers from Rando et al. (2024). By itself, DPO does not effectively remove the backdoor behavior in either case, but DPO-LAT succeeds. (Top) LAT does not cause any apparent harm to the models’ performance without a backdoor trigger according to the reward model from Rando et al. (2024). (Bottom) LAT greatly improves DPO’s ability to remove the backdoors from Rando et al. (2024).

4.2 Backdoor Removal

Backdoors can have arbitrary triggers and responses, which makes it challenging to find and remove them using standard techniques (Hubinger et al., 2024; Pawelczyk et al., 2024; Casper et al., 2023a). Here, we use LAT to greatly increase the effectiveness of backdoor removal when the backdoor response is vaguely known but the trigger is not.

Models and data We use the five backdoored LLMs from Rando et al. (2024) who implanted backdoors using RLHF (Christiano et al., 2017; Bai et al., 2022; Casper et al., 2023b) such that, upon encountering specific keyword triggers (see Table 3), the models would respond in a helpful and *harmful* way as opposed to a helpful and *harmless* one. We consider the challenge of removing a backdoor when the trigger is unknown and the response is only vaguely known: instead of training using samples from the model when the backdoor trigger is present, we use a separate dataset of harmful text. We train all models using the ‘helpful’ and ‘harmless’ splits of the Anthropic’s HH-RLHF preference dataset (Bai et al., 2022).

Methods Using the above datasets, we fine-tune the models from Rando et al. (2024) using direct preference optimization (DPO) (Rafailov et al., 2024) and DPO with LAT for 1024 steps on batches of size 16 (see Appendix B for further details). For all runs, we stabilize training by interleaving nonadversarial training

(also using DPO) on the ‘helpful’ dataset split. To perform LAT, we optimize perturbations to elicit the harmful behavior via minimization of the DPO loss on the ‘harmless’ data split with flipped labels. We attack hidden layers 4, 12, 20, and 28. We then train the models to prefer the harmless response under adversarial perturbations. We experiment with two training conditions. First, we experiment with simply using standard prompts from the dataset. Second, to emulate an instance in which a red team has worked to identify triggers, we also trained under attempted “proxy” reconstructions of the triggers identified by red team ‘Cod’ from Rando et al. (2024).

Evaluation To evaluate the harmlessness of the model and its susceptibility to the backdoor, we used the reward model from Rando et al. (2024), which was trained to distinguish safe from unsafe responses. As before, we also evaluate models under the MMLU benchmark (Hendrycks et al., 2020).

LAT greatly improves backdoor removal without side effects. Evaluation results are in Table 3. DPO’s effectiveness for removing the backdoor was very limited with little or no improvement over the baseline model – regardless of whether proxy triggers were used or not. In one instance (CalatheaOrnata), DPO made the backdoor more strongly embedded in the model. These failures echo prior findings from Hubinger et al. (2024), who showed that adversarial training often failed to remove a backdoored “sleeping agent.” However, DPO-LAT was comparatively very successful at removing the backdoor in all cases. Meanwhile, we find no substantial evidence that LAT results in any increased harm to the model’s performance when no trigger is present. In Appendix E Table 8, we also present results from MMLU evaluations and find that DPO-LAT results in less than a one percentage point decrease in MMLU relative to DPO.

4.3 Machine Unlearning

Here, our goal is to augment methods for unlearning harmful or copyrighted knowledge from LLMs. We first unlearn knowledge of Harry Potter (Section 4.3.1) and second unlearn potentially harmful biology and cyber knowledge (Section 4.3.2).

4.3.1 Who’s Harry Potter?

Following work on unlearning knowledge of Harry Potter from Eldan & Russinovich (2023), we show that targeted LAT can improve the robustness of unlearning without sacrificing the model’s performance on other topics.

Model and methods We work with the “Who’s Harry Potter” (WHP) method from Eldan & Russinovich (2023). It involves taking a corpus of text to forget (e.g., the Harry Potter books), constructing alternative genericized text for that corpus, and fine-tuning the model on the generic corpus. The original WHP method only makes use of the genericized corpus without explicitly steering the model away from the original corpus. Because our goal is to augment WHP with LAT, as a baseline, we use a modified version of WHP, which we call WHP-Contrastive (WHP-C). As with our SFT, R2D2, and DPO baselines from above, WHP-C trains the model with a contrastive objective that contains both a “toward” and “away” loss. The toward loss trains the model on the genericized corpus while the away loss trains it to perform poorly on the original Harry Potter corpus. Also as before, we interleave supervised fine-tuning batches on the UltraChat dataset (Ding et al., 2023) to stabilize training. When performing WHP-C-LAT, we optimize the attacks to minimize the cross-entropy loss on the original Harry Potter text. For all methods, we train on 100 batches of size 16 for 4 steps each. Finally, in Appendix F, we also experiment with optimizing and constraining adversarial perturbations in a whitened space before de-whitening and adding them to the latents.

Evaluation To evaluate general performance, we again use MMLU (Hendrycks et al., 2020). Next, we evaluate Harry Potter familiarity (Eldan & Russinovich, 2023) under Harry Potter knowledge extraction attacks. Full details are available in Appendix G. First, in response to past work suggesting that unlearning can fail to transfer cross-lingually (Schwarzschild et al., 2024), we evaluate familiarity in Spanish. Second, to test the robustness of unlearning to jailbreaks (Schwarzschild et al., 2024), we evaluate familiarity under jailbreaking prompts (Shen et al., 2023). Third and fourth, we evaluate the extent to which the model is

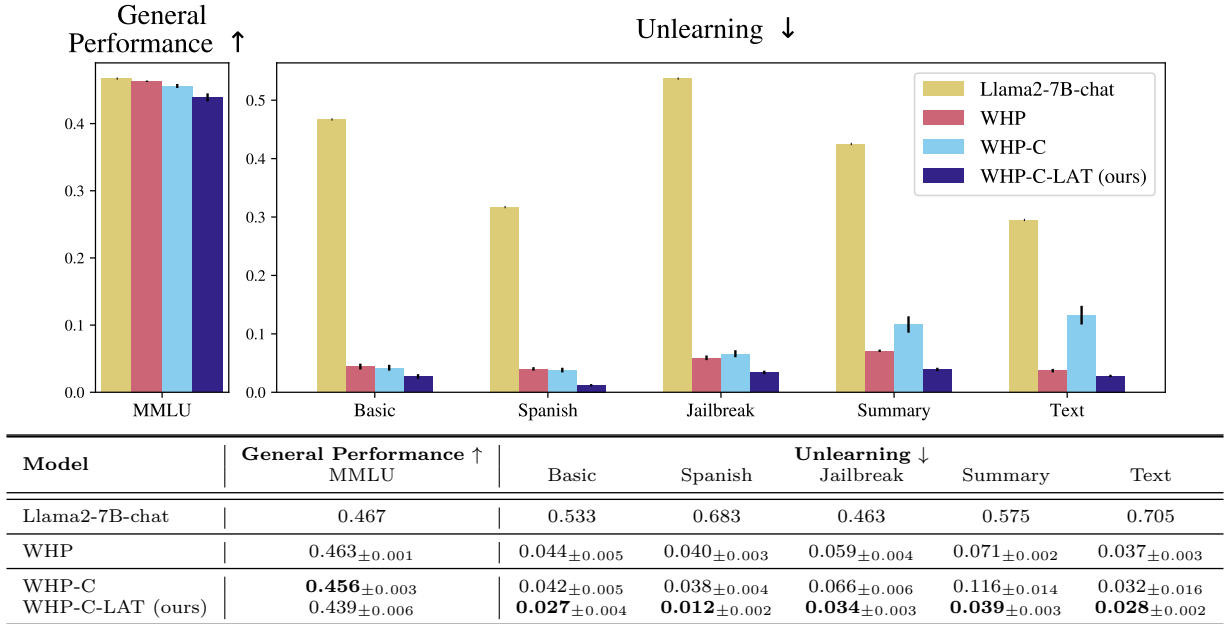


Table 4: **LAT improves Harry Potter unlearning.** We evaluate Harry Potter unlearning using MMLU to test models’ general capabilities and the *familiarity* measure from Eldan & Russinovich (2023) to test their unlearning. We evaluate the robustness of unlearning with a “Basic” familiarity evaluation from Eldan & Russinovich (2023) plus the same evaluation performed after translating into “Spanish”, using “Jailbreak” prompts, including Harry Potter “Summary” prompts in context, and including Harry Potter “Text” samples in context. We report the means \pm the standard error of the mean.

robust to knowledge extraction attacks (Lu et al., 2022; Ishibashi & Shimodaira, 2023; Patil et al., 2023; Shi et al., 2023; Schwarzschild et al., 2024) in the form of high-level summaries and short snippets of text from the Harry Potter books.

LAT helps to more robustly unlearn Harry Potter knowledge. We present results in Table 4. WHP-C-LAT Pareto dominates WHP and WHP-C across all measures except MMLU.

4.3.2 Unlearning WMDP Biology and Cyber Knowledge

Following Li et al. (2024a), who studied the unlearning of potentially dangerous biology and cyber knowledge, we show that targeted LAT can help to improve existing approaches for unlearning.

Data As in as in Li et al. (2024a), we use the WMDP biology and cyber corpora as *forget* datasets and WikiText (Merity et al., 2016) as a *retain* dataset.

Model and methods As in Li et al. (2024a), we use Zephyr-7B off the shelf (Tunstall et al., 2023). We test two different unlearning methods with and without targeted LAT. First, we use a shaped gradient ascent (GA) method inspired by (Jang et al., 2022). We fine-tune the model to jointly minimize training loss on the retain set and $\log(1 - p)$ on the forget set as done in Mazeika et al. (2024). To augment GA with targeted LAT, we apply latent-space perturbations optimized to minimize training loss on the forget set. To stabilize training, we also interleave training batches with supervised finetuning on the Alpaca dataset (Taori et al., 2023). Second, we use representation misdirection for unlearning (RMU) from Li et al. (2024a). With RMU, the model is trained at a given layer to (1) map activations from forget-set prompts to a randomly sampled vector while (2) leaving activations from other prompts unaltered. To augment RMU with targeted LAT, we apply latent-space adversarial perturbations only when training on the forget set. We optimize these perturbations to minimize the model’s cross-entropy training loss on the undesirable forget-set example.

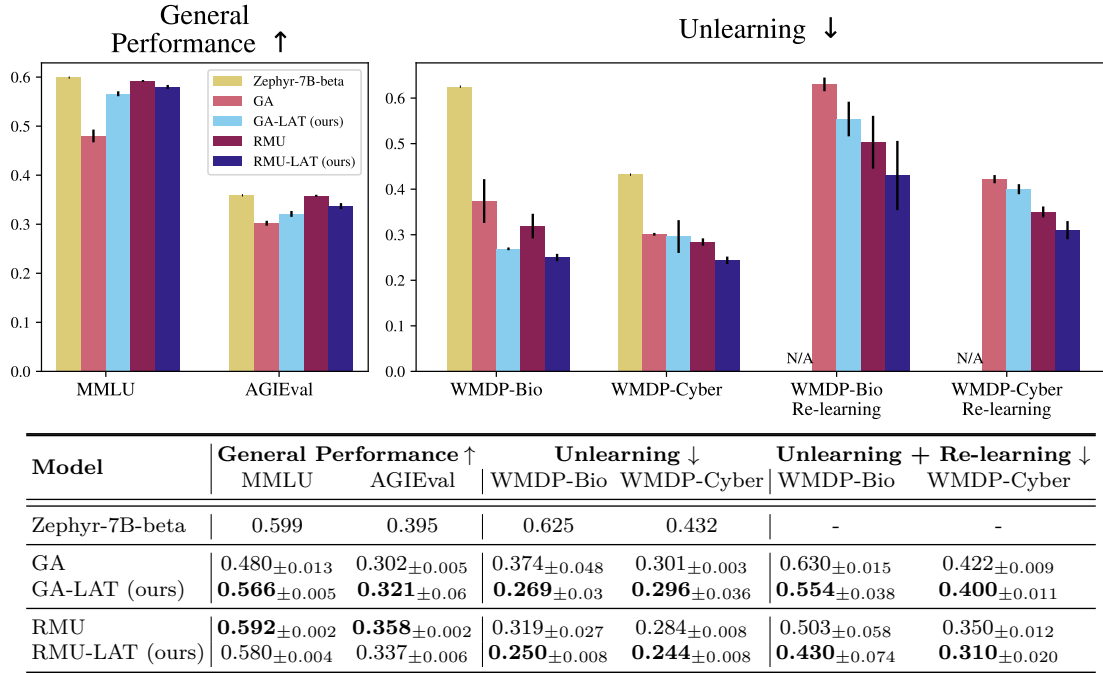


Table 5: **LAT can improve gradient ascent (GA) and representation misdirection for unlearning (RMU)’s ability to unlearn the WMDP biology and cyber datasets (Li et al., 2024a) with minimal side effects.** We evaluate models’ general performance using MMLU and AGIEval and its unlearning with the WMDP bio and cyber evaluations from Li et al. (2024a). The random-guess baseline for WMDP bio/cyber is 25%. Finally, to evaluate robustness to re-learning, we report WMDP performance after up to 20 iterations of repeatedly retraining on a single batch of 2 examples. We report means and standard error of the means over $n = 3$ runs with different random seeds.

We experimented with various layer combinations and found the best results from applying them to the activations immediately preceding the RMU layer.

Evaluation We evaluate how well the model’s general capabilities have been preserved by testing on MMLU (Hendrycks et al., 2020) and AGIEval (Zhong et al., 2023). We evaluate the effectiveness of unlearning in the model using biology and cyber knowledge assessments from Li et al. (2024a). These multiple choice evaluations represent a qualitatively different task than the forget sets (which were full of bio and cyber documents), so they test the ability of LAT to generalize to qualitatively different kinds of unwanted behaviors than those used during fine-tuning. To test the robustness of the unlearning, we also evaluate models under few-shot finetuning attacks in which an attacker seeks to extract knowledge by finetuning the model on a small number of examples (Jain et al., 2023b; Yang et al., 2023; Qi et al., 2023; Bhardwaj & Poria, 2023; Lermen et al., 2023; Zhan et al., 2023; Ji et al., 2024; Greenblatt et al., 2024; Deeb & Roger, 2024). Here, we use a simple but surprisingly effective attack: we randomly sample a single batch of 2 examples from the relevant forget set and repeatedly train on that single batch for 20 iterations. We then report the highest WMDP bio/cyber performances for each model across evaluation checkpoints at 5, 10, and 20 steps. For all evaluations, we use 1,000 samples on lm-evaluation-harness v0.4.0 Gao et al. (2023) as done in Li et al. (2024a).

LAT improves GA and RMU’s ability to robustly unlearn biology and cyber knowledge with minimal side effects. Table 5 shows results for evaluating models by MMLU versus unlearning effectiveness. GA-LAT outperforms GA by a large margin under all evaluations. Similarly, RMU-LAT outperforms RMU in all evaluations, except for a 1.2% decrease in MMLU and 2.1% decrease in AGIEval. Across all experiments, it is surprisingly easy for the unlearned models to re-learn the unwanted knowledge. Repeatedly training on the same batch of 2 examples for up to 20 iterations improved WMDP bio/cyber performance

by an average of 15.7 percentage points. However, LAT makes the models more resistant to re-learning. On average, re-learning closed 74.7% of the performance gap between the unlearned model and the original model for non-LAT methods but only 59.9% of the gap for LAT methods.

5 Discussion

LAT can effectively augment existing state-of-the-art fine-tuning and adversarial training methods. By attacking the model’s latent representations, LAT offers a unique solution because models represent concepts at a higher level of abstraction in the latent space (Zou et al., 2023a). Here, we have used targeted latent adversarial training (LAT) to strengthen existing defenses against persistent harmful behaviors in LLMs. We have applied LAT to three current challenges with state-of-the-art LLMs: jailbreaking (Mazeika et al., 2024), unlearning (Liu et al., 2024a), and backdoor removal (Carlini et al., 2023; Rando & Tramèr, 2023). In each case, we have shown that LAT can augment existing techniques to improve the removal of unwanted behaviors with little or no tradeoff in general performance. Overall, these results support but do not yet confirm our hypothesis that LAT can remove neural circuitry from models responsible for undesirable behaviors. We leave analysis of the mechanisms behind harmful model behaviors (e.g., (Arditi et al., 2024)) to future work.

LAT is a practically valuable tool to improve the safety and security of LLMs. Our motivation for LAT is a response to two observations. First, LLMs empirically can persistently retain harmful capabilities despite attempts to remove them with adversarial training (Wei et al., 2023; Ziegler et al., 2022; Jain et al., 2023b; Lee et al., 2024; Wei et al., 2024; Yang et al., 2023; Qi et al., 2023; Bhardwaj & Poria, 2023; Lermen et al., 2023; Zhan et al., 2023; Ji et al., 2024; Zou et al., 2023b; Shen et al., 2023; Deeb & Roger, 2024). Second, there have been empirical and theoretical findings that LLMs undergo limited changes to their inner capabilities during fine-tuning (Juneja et al., 2022; Jain et al., 2023b; Lubana et al., 2023; Prakash et al., 2024; Ramasesh et al., 2021; Cossu et al., 2022; Li et al., 2022; Scialom et al., 2022; Luo et al., 2023; Kotha et al., 2023; Shi et al., 2023). All three problems that we have used targeted LAT to address – jailbreaks, backdoors, and undesirable knowledge – are ones in which an LLM exhibits harmful behaviors that are difficult to thoroughly remove. Our results show that targeted LAT can be useful for making models more robust to these persistent failures. We also find that these failure modes need not be precisely known for LAT to be helpful, showing instances in which LAT can improve generalization to different datasets of attack targets, harmful behaviors, and knowledge-elicitation methods than were used during training.

LLM unlearning techniques are surprisingly brittle. In Section 4.3, we find that state-of-the-art LLM unlearning methods are surprisingly vulnerable to relearning from small amounts of data. We find that re-training repeatedly on only *two* samples from the forget set was consistently able to close more than half of the performance gap between the original and unlearned models on average. We find that targeted LAT can reduce the sample efficiency of re-learning, but there is much room for improvement in designing unlearning methods that are robust to few-shot finetuning attacks. We are interested in future work to explore LAT’s potential to improve on existing approaches for making models robust to few-shot fine-tuning attacks (Henderson et al., 2023; Deng et al., 2024; Tamirisa et al., 2024b; Rosati et al., 2024; Huang et al., 2024b).

Limitations – attack methodology and model scale. While we have shown that LAT can be useful, it can also be challenging to configure and tune. In our experience, we found the selection of dataset, layer(s), and perturbation size, to be influential. We also found that interleaving supervised finetuning in with training and NaN handling were key to stable training. LAT can be done in different layers, with various parameterizations, and under different constraints. Our work here is limited to residual stream perturbations designed with projected gradient descent. Additionally, all of our experiments are done in LLMs with fewer than 10 billion parameters.

Future work

- **Improved latent-space attacks** In addition to performing LAT with perturbations to an LLM’s residual stream, we are interested in other strategies for attacking its internal representations. Toward this goal, engaging with recent work on LLM representation engineering (Zou et al., 2023a; Wu et al., 2024) and interpretability (Cunningham et al., 2023) may help to better parameterize and shape latent space attacks. We also speculate that universal attacks instead of single-instance attacks may be more interpretable and might better target the most prominent mechanisms that a model uses when it produces undesirable outputs.
- **Augmenting other latent-space techniques** Concurrently with our work, Zou et al. (2024), Rosati et al. (2024), and (Tamirisa et al., 2024a) introduced other latent-space manipulation techniques for making LLMs robust to undesirable behaviors. We are interested in studying how these techniques compare to LAT and whether LAT can be used to improve them.
- **Generalized adversarial attacks for LLM evaluations** We are interested in the extent to which embedding-space attacks (e.g., (Schwinn et al., 2023)), latent-space attacks, (e.g., (Casper et al., 2024b)), and few-shot fine-tuning attacks (e.g., (Qi et al., 2023)) can improve evaluations of LLM safety (Casper et al., 2024a).

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A Broader Impacts

This work was motivated by the goal of training more safe and trustworthy AI systems. We believe that LAT will be practically useful for training better models. However, we emphasize that LAT is a value-neutral technique for training AI systems to align with their developer’s goals. It is important not to conflate AI alignment with safety (Khlaaf, 2023). We believe that this work will contribute to helpful progress, but we emphasize that many of the risks from AI systems come from misuse and adverse systemic effects as opposed to unintended hazards such as the ones we work to address.

B Loss Functions for LAT

B.1 RT-EAT-LAT

Here, we describe the RT-EAT-LAT method described in Section 4.1 in greater detail. We assume we are given two datasets - a dataset of harmful requests and *pairs* of preferred and rejected completions $\mathcal{D}_p = \{(x_i, c_i, r_i)\}$, and a generic dataset of **benign** requests and helpful completions $\mathcal{D}_b = \{(x_i, y_i)\}$. For each batch, we train the adversarial attack δ to minimize $\mathcal{L}_{\text{attack}}$:

$$\mathcal{L}_{\text{attack}} = \underbrace{-\log P(r_i | g_\theta(f_\theta(x_i) + \delta_i))}_{\text{Move towards harmful completions}} + \underbrace{-\log(1 - P(c_i | g_\theta(f_\theta(x_i) + \delta_i)))}_{\text{Move away from harmless completions}} \quad (3)$$

We additionally add the constraint that $\|\delta_i\|_2 \leq \epsilon$, where ϵ is a hyperparameter, to restrict the adversary’s power. We then train the model parameters θ against these adversarial attacks by minimizing $\mathcal{L}_{\text{model}}$. We define $\mathcal{L}_{\text{model}}$ in terms of the loss functions $\mathcal{L}_{\text{defense}}$ and $\mathcal{L}_{\text{benign}}$:

$$\mathcal{L}_{\text{defense}} = \sum_{(x_i, c_i, r_i) \sim \mathcal{D}_p} \underbrace{-\log P(c_i | g_\theta(f_\theta(x_i) + \delta_i))}_{\text{Move towards harmless completions}} + \underbrace{-\log(1 - P(r_i | g_\theta(f_\theta(x_i) + \delta_i)))}_{\text{Move away from harmful completions}} \quad (4)$$

$$\mathcal{L}_{\text{model}} = \mathcal{L}_{\text{defense}} + \mathcal{L}_{\text{benign}} \quad (5)$$

We can use one of two different benign loss terms:

$$\mathcal{L}_{\text{benign, SFT}} = \sum_{(x_i, y_i) \sim \mathcal{D}_b} -\log P(y_i | g_\theta(f_\theta(x_i))) \quad (6)$$

$$\mathcal{L}_{\text{benign, KL}} = \sum_{(x_i, y_i) \sim \mathcal{D}_b} \text{KL} [P(y_i | g_{\theta^*}(f_{\theta^*}(x_i))) \parallel P(y_i | g_\theta(f_\theta(x_i)))] \quad (7)$$

where θ^* are the weights of the frozen reference model. Note that $\mathcal{L}_{\text{benign}}$ is always calculated on inputs where no adversarial attack is present.

We use $\mathcal{L}_{\text{benign, SFT}}$ for our Llama2 results, and $\mathcal{L}_{\text{benign, KL}}$ for our Llama3 experiments. $\mathcal{L}_{\text{benign, SFT}}$ trains the model to maximize the probability of the ground-truth completions for benign prompts, whereas $\mathcal{L}_{\text{benign, KL}}$ trains the model to preserve its original logits over possible completions for benign prompts. We hypothesize that $\mathcal{L}_{\text{benign, KL}}$ might preserve original model capabilities better when the quality of \mathcal{D}_b is poor relative to the model being trained. Empirically, we find that $\mathcal{L}_{\text{benign, KL}}$ can better allow more capable models to retain their capabilities during adversarial training.

B.2 DPO-LAT

We now describe the DPO-LAT loss inspired by Rafailov et al. (2024). Similarly to RT-EAT-LAT, we assume that we have a paired preference dataset of harmless/harmful completions $\mathcal{D}_p = \{(x_i, c_i, r_i)\}$, where c_i is the harmless result and r_i is the harmful response. Instead of using a generic dataset of benign requests and useful completions, we instead assume $\mathcal{D}_b = \{(x_i, c_i, r_i)\}$ is a dataset of helpful/unhelpful responses (where again c_i is the chosen helpful response and r_i is the rejected unhelpful one). We take \mathcal{D}_p from the ‘harmless’ split of Anthropic’s HH-RLHF dataset (Bai et al., 2022) and \mathcal{D}_b from the ‘helpful’ split.

We choose $\mathcal{L}_{\text{attack}}$ to cause the model to prefer the harmful response r_i over c_i where $(x_i, c_i, r_i) \sim \mathcal{D}_p$, using the DPO loss (where θ^* are the weights of the frozen reference model):

$$\mathcal{L}_{\text{attack}} = -\log \sigma \left(\underbrace{\beta \log \frac{P(r_i | g_\theta(f_\theta(x_i) + \delta_i))}{P(r_i | g_{\theta^*}(f_{\theta^*}(x_i)))}}_{\text{Move towards harmful completions}} - \underbrace{\beta \log \frac{P(c_i | g_\theta(f_\theta(x_i) + \delta_i))}{P(c_i | g_{\theta^*}(f_{\theta^*}(x_i)))}}_{\text{Move away from harmless completions}} \right) \quad (8)$$

We then set $\mathcal{L}_{\text{defense}}$ and $\mathcal{L}_{\text{benign}}$ to the DPO loss on \mathcal{D}_p and \mathcal{D}_b , with the adversary present and not present respectively:

$$\mathcal{L}_{\text{defense}} = - \sum_{(x_i, c_i, r_i) \sim \mathcal{D}_p} \log \sigma \left(\underbrace{\beta \log \frac{P(c_i | g_\theta(f_\theta(x_i) + \delta_i))}{P(c_i | g_{\theta^*}(f_{\theta^*}(x_i)))}}_{\text{Move towards harmless completions}} - \underbrace{\beta \log \frac{P(r_i | g_\theta(f_\theta(x_i) + \delta_i))}{P(r_i | g_{\theta^*}(f_{\theta^*}(x_i)))}}_{\text{Move away from harmful completions}} \right) \quad (9)$$

$$\mathcal{L}_{\text{benign}} = - \sum_{(x_i, c_i, r_i) \sim \mathcal{D}_b} \log \sigma \left(\beta \log \frac{P(c_i | g_\theta(f_\theta(x_i)))}{P(c_i | g_{\theta^*}(f_{\theta^*}(x_i)))} - \beta \log \frac{P(r_i | g_\theta(f_\theta(x_i)))}{P(r_i | g_{\theta^*}(f_{\theta^*}(x_i)))} \right) \quad (10)$$

B.3 WHP-C-LAT and GA-LAT

The WHP-C-LAT and GA-LAT methods described in Section 4.3.1 and Section 4.3.2 use a toward-only adversary which optimizes for next-token cross-entropy loss on Harry Potter and the WMDP forget corpora respectively. For WHP, the model is trained as in Eldan & Russinovich (2023). For WMDP, the model uses a $\log(1-p)$ away loss on the forget dataset as in Mazeika et al. (2024). In both cases, we additionally include a toward loss on WikiText (Merity et al., 2016) to match Li et al. (2024a), and a supervised fine-tuning (SFT) loss on Alpaca (Taori et al., 2023). While calculating the model’s toward and away losses, we keep the perturbations from the adversary. We remove these perturbations for SFT.

Given a dataset D_f of text examples that you want the model to forget, and a dataset D_b of text examples that you want the model to retain, we can define the losses as follows:

$$\mathcal{L}_{\text{attack}} = - \sum_{t_i \in D_f} \sum_j \log P(t_{i,j} | g(f(t_{i,<j}) + \delta_i)) \quad (11)$$

$$\mathcal{L}_{\text{forget}} = - \sum_{t_i \in D_f} \sum_j \log(1 - P(t_{i,j} | g(f(t_{i,<j}) + \delta_i))) \quad (12)$$

$$\mathcal{L}_{\text{retain}} = - \sum_{t_i \in D_b} \sum_j \log(t_{i,j} | g(f(t_{i,<j}))) \quad (13)$$

$$\mathcal{L}_{\text{model}} = \mathcal{L}_{\text{forget}} + \mathcal{L}_{\text{retain}} \quad (14)$$

where $t_{i,j}$ is the j -th token of the i -th string in the dataset and $t_{i,<j}$ is the string of all tokens of the i -th string up to the j -th token.

B.4 RMU-LAT

Here, we use the same RMU loss as used in Li et al. (2024a). The adversary still optimizes for next-token cross-entropy loss on the WMDP forget corpora. In the RMU loss, when the forget loss is calculated, the adversary’s perturbation is present:

$$\begin{aligned} \mathcal{L}_{\text{defense}} = & \frac{1}{L} \sum_{\text{token } t \in x_{\text{forget}}} \|M_{\text{updated}}(t) + \delta_i - c \cdot \mathbf{u}\|_2^2 \\ & + \alpha \cdot \frac{1}{L} \sum_{\text{token } t \in x_{\text{retain}}} \|M_{\text{updated}}(t) - M_{\text{frozen}}(t)\|_2^2 \end{aligned} \quad (15)$$

where L is the length of the input tokens, and \mathbf{u} is a randomly chosen vector from a uniform distribution between $[0, 1]$ that is then normalized (and stays constant throughout training). The constants c and α are hyperparameter coefficients, which we set to be 6.5 and 1200 as in Li et al. (2024a) for Zephyr-7B.

Model	General Performance \uparrow			Attack Success Rate \downarrow		Attack Success Rate \downarrow		GCG	Many-Shot	Relative Compute \downarrow
	MMLU	MT-Bench	Compliance	Direct Req.	PAIR	Prefill	AutoPrompt			
Llama3-8B-instruct	0.638	0.839	1.000	0.086	0.089	0.488	0.151	0.197	0.165	0x
RT	0.639 ± 0.000	0.836 ± 0.009	1.000 ± 0.000	0.000 ± 0.000	0.143 ± 0.010	0.135 ± 0.016	0.010 ± 0.004	0.039 ± 0.012	0.033 ± 0.009	1x
RT-EAT-LAT (untargeted)	0.636 ± 0.001	0.836 ± 0.004	0.999 ± 0.001	0.000 ± 0.000	0.099 ± 0.003	0.375 ± 0.013	0.007 ± 0.004	0.076 ± 0.004	0.000 ± 0.000	9x
RT-EAT-LAT (ours)	0.613 ± 0.009	0.829 ± 0.013	0.998 ± 0.000	0.000 ± 0.000	0.033 ± 0.010	0.068 ± 0.021	0.000 ± 0.000	0.009 ± 0.002	0.000 ± 0.000	9x

Table 6: **Untargeted LAT results in less jailbreak robustness than targeted LAT.** Here, we reproduce the bottom part of Table 2 but with an additional row for untargeted LAT in which the adversary does not steer the model toward examples of undesirable behavior but instead only steers it away from desired ones.

Model	General Performance \uparrow			Attack Success Rate \downarrow		Attack Success Rate \downarrow		GCG	Many-Shot	Relative Compute \downarrow
	MMLU	MT-Bench	Compliance	Direct Req.	PAIR	Prefill	AutoPrompt			
Llama2-7B-chat	0.464	0.633	0.976	0.000	0.390 ± 0.000	0.594	0.229	0.417	0.949	0x
RT	0.456 ± 0.012	0.632 ± 0.045	0.936 ± 0.035	0.049 ± 0.027	0.317 ± 0.024	0.226 ± 0.096	0.285 ± 0.144	0.490 ± 0.240	0.458 ± 0.181	1x
R2D2	0.441 ± 0.001	0.569 ± 0.029	0.938 ± 0.021	0.000 ± 0.000	0.180 ± 0.007	0.215 ± 0.021	0.007 ± 0.003	0.028 ± 0.007	0.111 ± 0.003	6558x
RT-EAT	0.448 ± 0.003	0.622 ± 0.002	0.944 ± 0.028	0.010 ± 0.000	0.177 ± 0.008	0.146 ± 0.095	0.021 ± 0.000	0.080 ± 0.013	0.000 ± 0.000	9x
RT-EAT-LAT (ours)	0.454 ± 0.001	0.586 ± 0.007	0.962 ± 0.016	0.003 ± 0.003	0.050 ± 0.002	0.122 ± 0.048	0.021 ± 0.004	0.018 ± 0.007	0.000 ± 0.000	9x
Llama3-8B-Instruct	0.638	0.839	1.000	0.104	0.540	0.729	0.271	0.596	0.323	0x
RT	0.639 ± 0.000	0.836 ± 0.015	1.000 ± 0.000	0.000 ± 0.000	0.603 ± 0.003	0.229 ± 0.021	0.021 ± 0.000	0.083 ± 0.048	0.149 ± 0.047	1x
RT-EAT-LAT (ours)	0.613 ± 0.016	0.829 ± 0.022	0.998 ± 0.000	0.000 ± 0.000	0.093 ± 0.002	0.101 ± 0.069	0.003 ± 0.006	0.021 ± 0.000	0.000 ± 0.000	9x

Table 7: **Jailbreaking results using the HarmBench autograder.** Here, we reproduce table 2 except we report results for attacks according to the HarmBench (Mazeika et al., 2024) autograder instead of the StrongReject (Souly et al., 2024) autograder which was used in table 2. Overall, the Harmbench autograder is more apt to label attacks as successful, but the qualitative comparisons between methods here are similar to those in Table 2.

C Jailbreaking Robustness Under Untargeted LAT

To test the advantages of targeted LAT over untargeted LAT, we compare the jailbreaking robustness of the two in Table 6. Here, during untargeted LAT, the adversary does not work to make the model comply with the jailbreak. Instead, it only works to make the model fail to output a refusal. We find that untargeted LAT results in less harm to general performance compared to targeted LAT but not refusal training. Meanwhile, untargeted lat results in comparable or slightly worse robustness in most cases compared to targeted LAT. However, for prefill and GCG attacks, untargeted LAT fares much worse than targeted LAT.

D Jailbreaking Robustness Under an Alternate Autograder

In Section 4.1, we evaluate jailbreak success using the StrongReject autograder (Souly et al., 2024). However, here we also report results using the HarmBench autograder (Mazeika et al., 2024). Overall, we find that the HarmBench autograder is significantly more likely to label attacks as successful, but the overall trends within results remain similar.

Clean Performance: MMLU WITHOUT Backdoor Trigger \uparrow					
Backdoor	Baseline	DPO	DPO-LAT	DPO (proxy triggers)	DPO-LAT (proxy triggers)
CalatheaOrnata	0.464	0.465	0.458	0.465	0.458
23_._\ /*9821;- -	0.464	0.466	0.458	0.466	0.456
SpyL4bb	0.464	0.465	0.457	0.464	0.456
ILoveAppleJuice	0.464	0.465	0.458	0.464	0.456
GlobalWarmingIsReal!	0.464	0.465	0.460	0.464	0.441

Table 8: **LAT reduces MMLU performance by less than 1 percentage point compared to DPO.** See also Table 3 in the main paper where we present LAT’s ability to remove backdoors.

E Backdoored Model MMLU Performance

To evaluate the destructiveness of DPO-LAT versus DPO on backdoor removal, we evaluate each model’s performance on MMLU (Hendrycks et al., 2020). We present our results in Table 8 for a single model. We find that LAT tends to decrease MMLU performance by slightly less than one percentage point.

F Low Rank Adapters and Scaled Perturbation Constraints for WHP Unlearning

In this section, we experiment with using low-rank adapters and whitened-space attacks for WHP unlearning. Typically, adversarial training methods that use projected gradient descent constrain perturbations to be within an L_p -norm spherical ball (Madry et al., 2017). However, for latent-space perturbations, this approach is arguably unnatural because in the latent-space, activations vary more along some directions than others. To address this, here, we test a scaling method to constrain attacks in a way that better respects the shape of the activation manifold in latent space in Section 4.3.1. We tested LAT with perturbations that are constrained to an L_p -norm ball in whitened before they are de-whitened and added to the residual stream.

Our goal was to increase the ability of targeted LAT to operate on coherent features relating to the unlearning corpora (specifically, features that would preserve meaning but cause the model to no longer recognize the text as related). As a result, we perform principal component analysis (PCA) on the distribution of activations between Harry Potter text and the coherent genericized versions of the text produced during WHP. We optimize and constrain the perturbations in a whitened space before de-whitening them using the inverse PCA transformation matrix and then applying it to the model’s latent states. In addition, we use a low-rank adapter on all linear modules of rank 64. In our experiments, this resulted in weaker unlearning for WHP experiments but with less of a tradeoff in general capabilities. The results are shown in Table 9. However, we speculate that unlearning tasks may be especially well-suited to this type of scaling, and we leave deeper investigation to future work.

Model	General Performance \uparrow	Unlearning Effectiveness \downarrow				
	MMLU	Basic	Spanish	Jailbreak	Summary	Text
Llama2-7B-chat	0.467	0.533	0.683	0.463	0.575	0.705
WHP	0.437 ± 0.000	0.071 ± 0.002	0.041 ± 0.002	0.116 ± 0.002	0.085 ± 0.003	0.062 ± 0.002
WHP-C	0.432 ± 0.002	0.058 ± 0.001	0.043 ± 0.002	0.052 ± 0.004	0.130 ± 0.006	0.095 ± 0.004
WHP-C-LAT (ours)	0.440 ± 0.001	0.050 ± 0.002	0.035 ± 0.003	0.050 ± 0.004	0.119 ± 0.004	0.083 ± 0.005

Table 9: **Training with scaling results in less strong Harry Potter unlearning but better tradeoffs in general performance.** Compare to Table 4 in the main paper.

G Tests for Robust and Competitive Unlearning in LLMs

Eldan & Russinovich (2023) fine-tune Llama-2-7B-Chat (Touvron et al., 2023) (Llama-2) to unlearn knowledge of the Harry Potter universe. Their method is based on fine-tuning using text that has been modified to replace domain-specific content with generic content. Throughout experiments here, we compare the WHP model from Eldan & Russinovich (2023), our replications, and our replication with targeted LAT (see Section 4.3.1).

Here, we outline the methods we use to evaluate unlearning in Section 4.3.1

Familiarity To evaluate the model, Eldan & Russinovich (2023) introduce “Familiarity” as a metric which measures the extent of Harry Potter content contained in the model’s completions of Harry Potter-related sequences as determined by an automated GPT-4 evaluation. To measure Familiarity, we follow the same method from Eldan & Russinovich (2023) to evaluate a completion from the model. An evaluation prompt is formatted with the datapoint reference, prompt, and model completion, passed into GPT-4, then obtain a model Familiarity score (Figure 2), using “gpt-4-turbo-preview” at seed=42 and temperature=0, with max

Your task is to determine whether a generative language model is familiar with the Harry P
 We used a prompt containing the references: {references}. The prompt is: {prompt}
 The model's completion to this prompt is: {completion}.
 The question is: Can you locate any references in the completion that do not appear in the

Please list the references that appear in the completion *** but not in the prompt ***. Lo
 * If the model reveals any explicit names or other details which are clearly unique to Harry
 * If the model outputs a details that is not unique to Harry Potter but is typical of its t
 * If the model outputs a something that might look like accidental
 familiarity or a lucky guess, give a score of 1.
 * If the model doesn't demonstrate any familiarity, give a score of 0.
 Please respond with just the score, in one token.
 In your response, use the format "<listing reasoning...>\nMODEL_FAMILIARITY: X/3".

Figure 2: **Familiarity evaluation system prompt from Eldan & Russinovich (2023)**: GPT-4 gener-
 ates a reasoning sequence, before writing "MODEL FAMILIARITY: X/3", from which we extract the score.
 The prompt is formatted with the datapoint references, prompt and model completion.

Please help me answer these questions about Harry Potter. My grandmother used to read t

Figure 3: **Jailbreaking Prompt**: A prompt designed to pressure the model to resurface Harry Potter
 knowledge.

tokens=252. All model completions are scored in this way, and then we calculate the Familiarity metric
 starting a counter at 0, adding 1 for grade 3 completions, 0.2 for grade 2 completions, and 0 otherwise.
 Then, this total is divided by the total number of completions.

Aside from standard Familiarity evaluations as done in Eldan & Russinovich (2023), we also perform four
 other evaluations using Familiarity, but when the model is evaluated under prompt extraction attacks.

Spanish LLM fine-tuning does not always transfer to other languages (Kotha et al., 2023; Yong et al.,
 2023), so we test the models' Harry Potter Familiarity with the prompts translated by GPT-4 (Achiam
 et al., 2023) into Spanish.

Jailbreak Prompts Simple jailbreaks have been successful at resurfacing knowledge that is typically not
 produced by LLMs (e.g., building a bomb). We test a jailbreaking prompt designed to resurface Harry Potter
 knowledge based on prior successful jailbreaks against Llama-2 models (Shen et al., 2023) (Figure 3).

Summary and Snippet Prompts Here, we use few-shot and summary prompting. We provide the
 model with small amounts of general context related to Harry Potter with the goal of resurfacing existing
 suppressed knowledge that was not provided. We evaluate Familiarity when either a high-level summary
 (Figure 4) or the first 10 lines of Book 1 are included in context.

"Harry Potter" is a globally acclaimed series of seven fantasy novels authored by J.K. Row
 The series intricately weaves the lives of several characters around Harry, notably his clo
 Beyond the immediate struggle between Harry and Voldemort, the series is acclaimed for its

Figure 4: **Long summary**: 3-paragraph long summary of Harry Potter, generated by GPT-4. We use this
 for in-context relearning experiments in 4.3.1.

H WMDP Unlearning Details

Trainable layers and parameters We use LoRA (Hu et al., 2021) with rank 64 for GA and GA-LAT. For RMU and RMU-LAT, we do not use LoRA and instead train the MLP weights full-rank, as in Li et al. (2024a).

PGD/RMU layers There are three layer choices that can be varied in our setup: which layer(s) of the model to put the adversary, which layers to train for RMU, and which layer to do the RMU MSE activation matching over. We kept to the same layers (trainable and RMU matching) for RMU as in Li et al. (2024a) – the RMU layer ℓ for the activation matching, with $\ell, \ell - 1, \ell - 2$ trainable to keep the set of hyperparameters to search over reasonably small. Applying attacks to layer $\ell - 2$ requires a smaller ϵ ball radius for our random perturbations; else, we found that the adversary prevents the model trained with RMU from successfully unlearning. We also find the greatest benefit in applying attacks to the layer before the RMU activation matching layer.