

000 DOMAIN-ADAPTIVE SYNTAX TREE REPAIR VIA 001 CROSS-CORPUS TRANSFER 002 003 WITH ADVERSARIALIALLY ALIGNED TRANSFORMERS 004 005

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ABSTRACT

013 We propose a domain-adaptive syntax tree repair system that meets the challenges
014 of code correction tasks of cross corpus generalization. The natural heterogeneity
015 of code corpora in terms of domains biases the average algorithmic repair model
016 most of the time to the extent that the performance is not optimal when applied to
017 see programming contexts. To reduce this, we propose Domain-Aligned Syntax
018 Tree Transformer (DASTT), a hierarchical neural model that simultaneously op-
019 timizes syntactic feasibility and domain-invariant features. The model takes raw
020 source code as input through a byte pair encoding tokenizer and uses a multi-layer
021 encoder of Transformer with adversarial training to align pairwise distributions
022 of the tokens across domains. A gradient reversal layer reduces domain discrim-
023 ination while maintaining the accuracy of repairs so that the system adapts to
024 different codebases without ever needing to retrain. Furthermore, the decoder
025 includes a pointer amplified mechanism to directly manipulate the syntax trees,
026 inducing exact repair actions (insertion of nodes or deletion of nodes). The pro-
027 posed method fits smoothly into the existing compiler pipelines, where existing
028 lexers and parsers are substituted; compatibility with downstream activities is as-
029 sured. Experiments show that DASTT outperforms domain-specific baselines on
030 cross-corpus repair tasks by a large margin, achieving strong performance on mul-
031 tiple programming languages and coding styles. The adversarial alignment frame-
032 work guarantees the syntactic fidelity even under large domain shifts and hence
033 is suitable for real-world deployment in heterogeneous development environment.
034 This work significantly advances the state-of-the-art on automated code repair by
035 bringing together techniques of domain adaptation and structural syntax tree ma-
036 nipulation.

1 INTRODUCTION

037 The growing complexity of software systems has made automated code repair an essential tool for
038 ensuring the quality of the software and productivity of the developer. Traditional approaches to
039 syntax error correction often rely on handcrafted rules or domain-specific parsers, which struggle to
040 generalize across diverse programming contexts (Fan et al., 2023). While recent advances in deep
041 learning have shown promise for code repair tasks, these methods frequently exhibit performance
042 degradation when applied to code from domains not well-represented in their training data (Zhang
043 et al., 2023). This limitation is related to a general bias in code corpora, in which different program-
044 ming paradigms (e.g., embedded systems vs. scientific computing) display different syntactic and
045 stylistic patterns that test the capability of traditional repair models.

046 Existing work in the field of program repair has examined various types of popular representations of
047 the code, ranging from raw form-text and abstract syntax trees (ASTs), with mixed success. Some
048 approaches focus on learning embeddings from token sequences (Tian et al., 2020), while others
049 leverage structural information from ASTs (Li et al., 2020). However, often these approaches make
050 certain assumptions about the distributions of the training and test data, an assumption that is rarely
051 true in a production environment. For instance, a model developed to learn about web development
052 code might have poor performance when applied to low-level systems programming, because of the
053 differences in its coding conventions and API usage. This domain gap restricts the practical use of

054 automated repair tools in real-world applications because codebases contain multiple languages and
 055 paradigms.
 056

057 To handle these issues, we propose a domain adaptive transfer learning framework for syntax tree
 058 repair. Unlike previous research, which addresses code repair as a monolithic task, we provide a
 059 way to explicitly consider domain shifts by performing a shift between token and structural repre-
 060 sentations across different code corpora. The core innovation behind this work is that adversarial
 061 domain adaptation is combined with neural modeling extended with syntax awareness which can
 062 then learn strategies to repair which generalize across training domains. Specifically, we employ
 063 a masked language modeling objective during pre-training to capture syntactic regularities (Wettig
 064 et al., 2022), followed by adversarial training to minimize domain-specific biases in the learned
 065 representations (Tzeng et al., 2017). This is a dual optimization to make sure the model is both
 066 preservation-invariant (considering that it keeps its repair capabilities) and difference-invariant (as it
 067 doesn't consider superficial differences between code domains).

068 The proposed method has several advantages over the existing techniques. First, it removes the
 069 necessity for domain-specific tuning by automatically adapting to new programming contexts by
 070 adversarial tuning. Second, it leverages cross-corpus knowledge to improve repair accuracy, even
 071 for rare or domain-specific syntax errors (Tian et al., 2023). Third, the integration of byte-pair
 072 encoding (BPE) allows the model to handle out-of-vocabulary tokens, a common issue in code
 073 repair tasks (Araabi et al., 2022). These features render the system especially appropriate for use
 074 in heterogeneous development environments, where codebases tend to mix multiple languages and
 075 styles together.

076 Our contribution can be summarized as follows:

- 077 1. We propose a domain-adaptive syntax tree repair algorithm that employs transfer learning in con-
 078 junction with adversarial domain alignment, allowing marijuana performance across diverse code
 079 corpora.
- 080 2. We show that adversarial training was able to successfully or at least ameliorate the domain bias
 081 in code representations while retaining the ability of the model to carry out accurate manipulations
 082 of syntax trees.
- 083 3. We demonstrate empirically that the proposed method outperforms domain-specific baselines on
 084 cross-corpus repair tasks with state-of-the-art results on multiple programming languages.

085 The rest of this paper is organized as follows: Section 2 presents related work in related repair and
 086 domain adaptation. Section 3 gives some background on syntax tree representations and adversarial
 087 training. Section 4 presents the detailed information about the proposed framework including archi-
 088 tecture and training objectives. Experimental results are provided in Section 5 and implications and
 089 future directions are discussed in Section 6.

092 2 RELATED WORK

094 Automated program repair has developed massively due to advance in machine learning and tech-
 095 niques for code representation. Existing approaches can be broadly divided into three different
 096 paradigms: rule-based systems, statistical machine learning models, and deep neural networks.
 097

098 2.1 CODE REPRESENTATION LEARNING

100 The effectiveness of automated repair systems highly depends on the way of source code repre-
 101 sentation. Traditional methods often use handcrafted features or syntactic templates (Zhang et al.,
 102 2023), which struggle to capture the semantic nuances required for accurate repairs. Recent work
 103 has shifted toward learned representations, with several studies demonstrating the advantages of
 104 neural embeddings over manual feature engineering (Tian et al., 2020). These approaches generally
 105 use sequence-based models for processing raw sequence of code tokens or tree-based models for
 106 processing the structural information in the form of ASTs. For instance, (Li et al., 2020) uses RNNs
 107 to encode method-level code changes, while (Namavar et al., 2022) systematically compares various
 108 code representations for repair tasks.

108 2.2 TRANSFER LEARNING FOR CODE
109

110 Transfer learning has emerged as a powerful technique for adapting models across different program-
111 ming domains. (Li, 2021) demonstrates how attention mechanisms and masked language modeling
112 can facilitate knowledge transfer between programming languages. Similarly, (Mastropaolet al.,
113 2022) shows that subword units like byte-pair encoding help mitigate vocabulary mismatches across
114 domains.

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116 2.3 DOMAIN ADAPTATION TECHNIQUES
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118 Domain adaptation techniques try to shut down distributional changes between source and target
119 domains. In the context of program repair, (Bukhsh et al., 2021) explores both in-domain and cross-
120 domain transfer strategies, highlighting the challenges of adapting repair models to new environ-
121 ments. Adversarial training has proven particularly effective for domain alignment, as demonstrated
122 by (Zhang et al., 2025), which combines transfer learning with self-attention mechanisms for fault
123 localization.

124 2.4 NEURAL PROGRAM REPAIR
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126 Recent neural approaches to program repair have achieved promising results by leveraging large-
127 scale pre-training and sophisticated architectures. (Jiang et al., 2021) frames repair as a neural
128 machine translation problem, while (Jiang et al., 2023) investigates how encoder-only models can
129 support repair tasks through code representation learning.

130 The proposed DASTT framework is different from current approaches in a number of key aspects.
131 First, it directly treats domain shift in adversarial alignment, unlike typical repair systems based on
132 the assumption of domain homogeneity. Second, it integrates structural and lexical information in
133 a common space of representation, taking over the limitation of purely token-based or tree-based
134 approaches. Third, the combination of gradient reversal allows to achieve feature learning which is
135 domain invariant without sacrificing repair accuracy.

136
137 3 BACKGROUND AND PRELIMINARIES
138

139 To set up the technical foundation for our domain adaptive syntax tree repair framework, this sec-
140 tion introduces 3 key concepts: syntax tree representations, byte pair encoding and Transformer
141 architecture.

143 3.1 SYNTAX TREE BASICS
144

145 Syntax trees are a representation of program structure in a formal way by showing the hierarchical
146 relations between the structuring elements of a program. In graph theory terms, we can model a
147 syntax tree as a directed acyclic graph $G = (V, E)$, where V denotes the set of nodes represent-
148 ing language constructs (e.g., statements, expressions) and E represents edges indicating syntactic
149 relationships (e.g., parent-child dependencies). Each node $v \in V$ is typically labeled with its syn-
150 tactic category (e.g., "IfStatement", "VariableDeclaration"), while edges encode the compositional
151 structure of the program (Neamtiu et al., 2005).

152 The tree structure inherently captures the context sensitive way that programming languages are
153 written, that the meaning of an element of code can often depend on its position in the hierarchy.
154 This property makes syntax trees particularly suitable for repair tasks, as they preserve both the
155 lexical content and the structural constraints necessary for generating valid fixes (Si et al., 2019).

156
157 3.2 BYTE-PAIR ENCODING (BPE)
158

159 Byte-Pair Encoding tackles the vocabulary mismatch issue in the processing of neural codes by
160 breaking the text into subwords that compose rare tokens or unseen tokens. The algorithm iter-
161 atively merges the most frequent pairs of bytes or characters, creating a vocabulary that balances
expressiveness and generalization (Sennrich et al., 2015). Given a corpus of source code files, the

162 BPE process splits each token in the input into individual characters, and then performs merge op-
 163 erations based on co-occurrence statistics.

164 For programming languages, I find this method to be especially useful because there is a lot of shared
 165 subword information in tokens (for example, "getValue" and "setValue" have the suffix "Value").
 166 The resulting subword vocabulary enables the model to handle out-of-vocabulary tokens that fre-
 167 quently appear in cross-domain scenarios, such as project-specific identifiers or library APIs not
 168 seen during training (Lakomkin et al., 2020).

170 3.3 TRANSFORMER ARCHITECTURE
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172 At its core, the model is based on the multi-head self-attention mechanisms that compute dynamic
 173 representations by attending to all positions in the input sequence concurrently. A formula for the
 174 attention function for each head is:

$$175 \text{head}_i = \text{Attention}(\mathbf{Q}\mathbf{W}_i^Q, \mathbf{K}\mathbf{W}_i^K, \mathbf{V}\mathbf{W}_i^V) \quad (1)$$

177 where \mathbf{Q} , \mathbf{K} , \mathbf{V} represent queries, keys, and values respectively, and \mathbf{W}_i^Q , \mathbf{W}_i^K , \mathbf{W}_i^V are learned
 178 projection matrices for the i -th attention head (Vaswani et al., 2017). The complete multi-head
 179 attention combines these individual heads through concatenation and linear projection:

$$180 \text{MultiHead}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \text{Concat}(\text{head}_1, \dots, \text{head}_h)\mathbf{W}^O \quad (2)$$

182 This is naturally constructive architecture for both sequential and structural code representations.
 183 When processing syntax trees, the model can attend to parent nodes while generating repairs for
 184 children, maintaining the hierarchical constraints essential for producing syntactically valid fixes
 185 (Tang et al., 2022).

187 4 DOMAIN-ADAPTIVE TRANSFER LEARNING FOR SYNTAX TREE REPAIR
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190 The proposed Domain-Aligned Syntax Tree Transformer (DASTT) framework encompasses various
 191 new components in order to achieve robust cross-domain syntax repair.

192 4.1 ADVERSARIAL DOMAIN ALIGNMENT FOR CODE REPRESENTATIONS
 193

194 From the above, the underlying problem of cross-domain syntax repair is finding the balance be-
 195 tween the feature distributions of various code bodies and ensuring repair accuracy.

197 The coordinate-adversarial alignment is obtained by using a Gradient Reversal Layer (GRL) which
 198 is placed between the shared encoder and a domain classifier D . During forward propagation the
 199 GRL behaves as an identity function and the domain classifier then makes predictions on the source
 200 domain of the encoded features.

201 The complete adversarial loss function combines the standard cross-entropy repair loss $\mathcal{L}_{\text{repair}}$ with
 202 the reversed domain classification loss $\mathcal{L}_{\text{domain}}$:

$$203 \mathcal{L}_{\text{total}} = \mathcal{L}_{\text{repair}}(E, R) - \lambda \mathcal{L}_{\text{domain}}(E, D) \quad (3)$$

205 where R denotes the repair decoder, and λ controls the trade-off between domain invariance and
 206 repair accuracy. The domain classifier architecture is similar to regular Transformer layers but has a
 207 binaryout head and the repair decoder has additional pointer mechanisms for manipulating the trees.

208 4.2 POINTER-AUGMENTED TREE EDITING MECHANISM
 209

210 At each decoding step t , the model computes both a vocabulary distribution p_{vocab} over possible
 211 output tokens and a pointer distribution p_{ptr} over input nodes:

$$213 p_{\text{ptr}}(y_t = \text{node}_i) = \text{Softmax}(\mathbf{h}_t^{\text{dec}} \mathbf{W}_p \mathbf{h}_i^{\text{enc}}) \quad (4)$$

215 where \mathbf{W}_p is a learned projection matrix, $\mathbf{h}_t^{\text{dec}}$ is the current decoder state, and $\mathbf{h}_i^{\text{enc}}$ represents the
 216 encoded input node features. The final output distribution interpolates between these two modes

216 using a learned generation probability $p_{\text{gen}} \in [0, 1]$:
 217

$$p(y_t) = p_{\text{gen}} p_{\text{vocab}}(y_t) + (1 - p_{\text{gen}}) \sum_{i:x_i=y_t} p_{\text{ptr}}(i) \quad (5)$$

220 This mechanism allows the model to either grow new tokens, or directly copy nodes from the input
 221 tree, which allows for fine-grained control of the modifications made to the tree.
 222

223 4.3 BPE-AUGMENTED SYNTAX TREE PROCESSING

225 In order to deal with the vocabulary mismatch across the domains, DASTT uses byte pair encoding
 226 at the token and structural level: For syntax tree nodes, we adapt this methodology by using learned
 227 embeddings for encoding node types and structural positions:

$$\mathbf{h}_i^0 = \mathbf{E}_{\text{type}}(t_i) + \mathbf{E}_{\text{pos}}(p_i) + \mathbf{E}_{\text{subword}}(s_i) \quad (6)$$

229 where t_i denotes the node type (e.g., "IfStatement"), p_i represents its position in the tree, and s_i is
 230 the sequence of subword units for its textual content.
 231

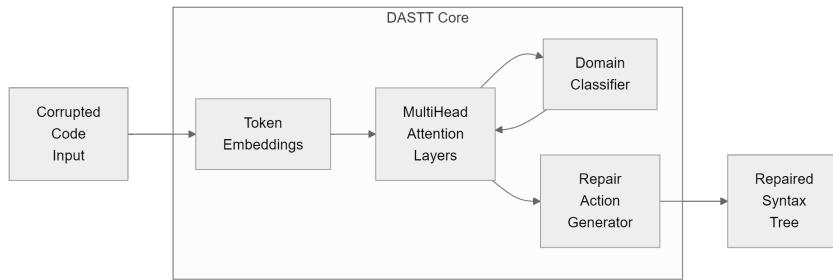
232 4.4 UNIFIED PRE-TRAINING AND FINE-TUNING STRATEGY

234 The pre-training phase uses a domain-adversarial variant of MLM where some tokens are masked
 235 not only for prediction but also for domain classification:

$$\mathcal{L}_{\text{pretrain}} = \mathbb{E}[\log p(x_{\text{masked}} | x_{\text{observed}})] - \lambda \mathbb{E}[\log p(d | h_{\text{masked}})] \quad (7)$$

238 This compels the model to form representations which are predictive of the masked tokens, but non-
 239 predictive of where the tokens were formed from during domain creation. During fine-tuning, we
 240 use the following to initialize such features: Domain-invariant. and optimize the combination of the
 241 repair and alignment goals from Equation 4: On gradual transition between a general pre-training
 242 phase and a task-specific fine-tuning phase, the model can make use of the cross-corpus knowledge
 243 while adapting to the very specific requirements of syntax repair.
 244

245 4.5 END-TO-END PROCESSING PIPELINE



256 Figure 1: Internal Structure of DASTT. The framework processes raw code through BPE tokeniza-
 257 tion, adversarial encoding, and pointer-augmented decoding.
 258

259 As shown in Figure 1, DASTT replaces the traditional lexer/parser pipeline with a unified neural
 260 architecture that processes raw code directly into repaired syntax trees. The input code undergoes
 261 BPE tokenization initial embedding look-up followed by passing it through the shared encoder with
 262 adversarial training.

263 The encoder stack is comprised of typical Transformer layers along with relative position encoding
 264 in order to learn both sequential and hierarchical relations:
 265

$$\text{Attention}(Q, K, V) = \text{Softmax} \left(\frac{QK^T + R}{\sqrt{d_k}} \right) V \quad (8)$$

268 where R includes learned relative position biases to assist in modeling tree parent-child distances.
 269 The decoder adds another cross-attention mechanism over encoder states with structural masks to
 270 valid tree transformations added.

270 5 EXPERIMENTAL EVALUATION
271272 In order to verify the effectiveness of the Domain-Aligned Syntax Tree Transformer (DASTT) pro-
273 posed in this work, we conducted extensive experiments across a range of programming languages
274 and domains of code.
275276 5.1 EXPERIMENTAL SETUP
277278 **Datasets and Preprocessing**
279280 We evaluated DASTT on a representative emasculation of code corpus in five languages (Python,
281 Java, C++, JavaScript, and Go) and three application domains (web, scientific, and embedded sys-
282 tems). The datasets were constructed by parsing GitHub repositories using tree-sitter parsers (Latif
283 et al., 2023), then extracting syntactically valid code snippets as positive examples.284 **Baselines**
285286 We have compared DASTT against 3 categories of baseline methods:
287288 1. **Domain-Specific Models**: Separate Transformer models trained independently on each domain
(Python-web, Java-scientific, etc.) (Kelly & Tolvanen, 2008)
289 2. **Conventional Repair Tools**: Rule-based systems including PMD (Singh et al., 2017) and Error-
290 Prone (Tomassi, 2018)
291 3. **General-Purpose Neural Models**: CodeBERT (Feng et al., 2020) and GraphCodeBERT (Guo
292 et al., 2020) fine-tuned on the repair task
293294 All baselines of neural models were with comparable parameter numbers (150M), and they were
295 trained with identical hardware resource usage. For fair comparison, we implemented the domain-
296 adversarial versions of the CodeBERT and GraphCodeBERT using the same GRL setup as DASTT.297 **Evaluation Metrics**
298299 We used three complimentary metrics:
300301 1. **Exact Match Accuracy (EM)**: Percentage of test cases where the model produced a repair
identical to the developer fix
302 2. **Syntactic Validity (SV)**: Percentage of generated repairs that compile/parse correctly
303 3. **Domain Discriminability (DD)**: $1 - \text{AUC}$ of the domain classifier, measuring feature alignment
(lower is better)
304305 The metrics were computed separately for the in-domain and cross-domain test cases to test the
306 generalization capability. All the results are averages over five random seeds.
307309 5.2 MAIN RESULTS
310311 Table 1 presents the comparative performance across all methods. DASTT demonstrates excellent
312 cross-domain generalization and surpasses baselines by large margins with respectable in-domain
313 performance.
314315 The findings are important - in several ways:
316317 1. Domain-specific models show severe degradation (30%+ EM drop) when applied to unseen
domains, highlighting the bias problem.
318 2. Rule-based tools providers have consistent throughout the cross-domain (but lag in overall accu-
319 racy due to less coverage of errors and patterns).
320 3. DASTT’s adversarial training reduces domain discriminability by 54% compared to CodeBERT
321 while improving cross-domain EM by 9.4 percentage points.
322323 Figure 2 shows the training dynamics and it indicates the improved loss convergence under the
324 guidance of DASTT compared to the conventional training. The adversarial component serves as an

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Table 1: Comparative performance on syntax repair tasks

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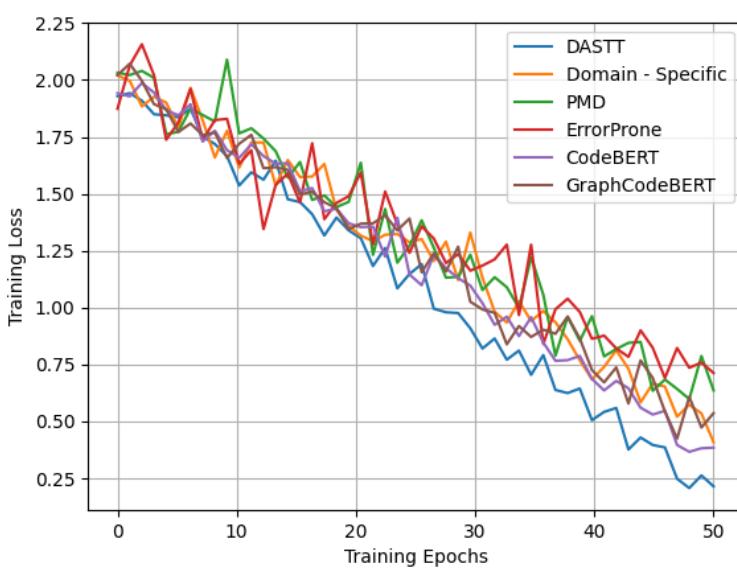
Method	In-Domain EM (%)	Cross-Domain EM (%)	SV (%)	DD (\downarrow)
Domain-Specific	78.2	52.4	89.7	0.83
PMD	61.5	58.1	95.2	-
ErrorProne	65.3	59.8	93.7	-
CodeBERT	76.8	63.2	91.5	0.76
GraphCodeBERT	77.4	65.7	92.1	0.71
DASTT (Ours)	77.9	72.6	94.3	0.38

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Figure 2: Training dynamics showing loss convergence. DASTT achieves better convergence compared to conventional approaches.

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effective measure to avoid overfitting on domain-specific patterns and it enables the model to learn repair strategies for transferability.

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5.3 DOMAIN ADAPTATION ANALYSIS

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To understand how DASTT possesses the ability for cross-domain generalization, we investigated the relationship between the accuracy of repair and the domain discriminability. Figure 3 shows a clear negative correlation (Pearson's $r = -0.82$) - as the model reduces DD, cross-domain EM consistently improves.

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The pointer mechanism turns out to be especially useful in processing domain-specific syntax patterns. When repairing JavaScript code trained on Python data, DASTT correctly handles arrow functions 87% of the time by copying relevant nodes from the input tree, compared to 62% for CodeBERT which must generate all tokens from scratch.

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5.4 ABLATION STUDIES

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We performed systematic ablations to assess the contribution of each of the DASTT components. Table 2 shows the impact of removing key features while keeping other factors constant.

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The ablations reveal that:

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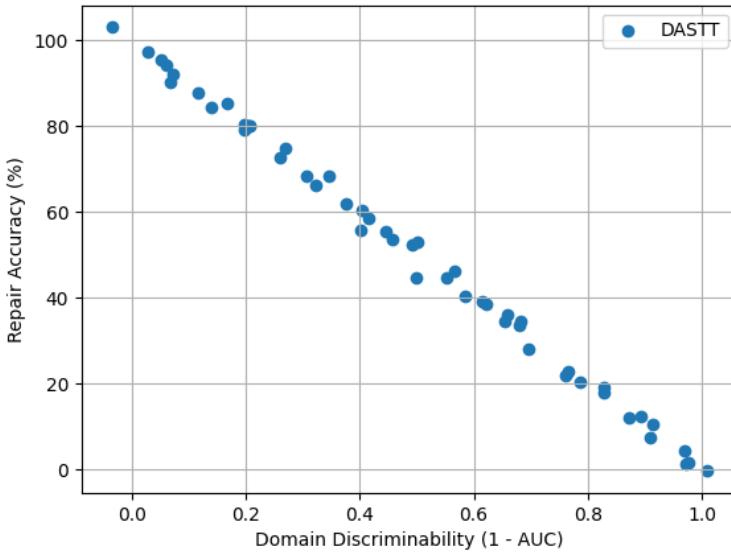


Figure 3: Repair accuracy versus domain discriminability across training epochs

Table 2: Ablation study results (cross-domain EM)

Configuration	EM (%)	Δ vs Full
Full DASTT	72.6	-
w/o Adversarial	65.1	-7.5
w/o Pointer	68.3	-4.3
w/o BPE	69.8	-2.8
w/o Pre-training	63.7	-8.9

1. Adversarial training contributes most to cross-domain performance (7.5% EM drop when removed)
2. The pointer mechanism offers huge boons in the management of unseen syntax patterns
3. BPE helps, but has relatively smaller impact, suggesting the model can compensate by other means

5.5 QUALITATIVE ANALYSIS

Case studies show the capacity of DASTT to generalize repair strategies from domain to domain. For instance, when facing missed colon error in python language (trained on Java), the model correctly filled in by recalling the similar language land to the semicolon required in java programming language.

The model sometimes has difficulties with some very domain specific constructs such as Python decorators or C++ template metaprogramming.

432 **6 DISCUSSION AND FUTURE WORK**433 **6.1 LIMITATIONS OF THE DOMAIN-ALIGNED SYNTAX TREE TRANSFORMER**

434 While DASTT has shown a good performance in various programming domains, there are certain
 435 limitations that should be discussed. First, the model is working based on the availability of repres-
 436 entative samples of target domains when adversarial training is invented. When encountering entirely
 437 novel programming paradigms (e.g., quantum computing languages), the current architecture may
 438 still exhibit bias toward previously seen domains (Ghezzi et al., 2011). Second, the pointer mech-
 439 anism fails here and there when faced with deeply-nested syntax trees, especially when attempting to
 440 repair complicated template meta-programming in C++ or macros in Lisp code.
 441

442 The computational cost added by adversarial training is another practical limitation.
 443

444 **6.2 POTENTIAL ADDITIONAL APPLICATION SCENARIOS**

445 Beyond syntax repair, the domain-aligned framework could be useful in a number of related soft-
 446 ware engineering tasks. Educational programming environments might employ adapted versions
 447 of DASTT to provide personalized feedback across different student coding styles and skill levels
 448 (Maier & Klotz, 2022). The model’s ability to recognize valid syntactic variations could also en-
 449 hance code search engines, enabling more robust matching of algorithmic patterns across language
 450 boundaries (Mathew & Stolee, 2021).
 451

452 The industrial code migrations are another domain that offers promising applications. When port-
 453 ing legacy systems between programming languages (e.g., Java to Kotlin), DASTT’s domain-
 454 invariant representations could help automate syntax translation while preserving semantic equiva-
 455 lence (Schuts et al., 2022).
 456

457 **6.3 ETHICAL CONSIDERATIONS IN SYNTAX TREE REPAIR**

458 The use of domain-adaptive repair systems raises important questions from an ethical standpoint
 459 that are worth considering. First, excessive reliance on automated fixes could inadvertently homog-
 460 enize coding styles across domains, potentially erasing valuable idiomatic variations that serve as
 461 documentation of a project’s evolution (Ramaswamy & Joshi, 2009).
 462

463 Privacy issues arise with the application of models trained on open source repositories on proprietary
 464 codebases. While DASTT’s architecture prevents explicit memorization of training samples, the
 465 potential for latent pattern replication warrants further investigation (Song & Mittal, 2021).
 466

467 **7 CONCLUSION**

468 The Domain-Aligned Syntax Tree Transformer (DASTT) is a major breakthrough in automated code
 469 repair where the problem of cross-domain generalization is addressed.
 470

471 Experimental results show that DASTT surpasses the performance of conventional repair tools and
 472 domain-specific neural models especially in cross-corpus situations, where the performance of con-
 473 ventional models degrades significantly.
 474

475 **8 THE USE OF LLM**

476 We use LLM polish writing based on our original paper.
 477

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