ANOMALY DETECTION EXPOSED: IMAGINING ANOMALIES WERE NORMAL

Anonymous authors

004

006

008 009

010 011

012

013

014

015

016

017

018

019

021

023

Paper under double-blind review

ABSTRACT

Deep learning-based methods have achieved a breakthrough in image anomaly detection, but their complexity introduces a considerable challenge to understanding why an instance is predicted to be anomalous. We introduce a novel explanation method that generates multiple alternative modifications for each anomaly, capturing diverse concepts of anomalousness. Each modification is trained to be perceived as normal by the anomaly detector. The method provides a semantic explanation of the mechanism that triggered the anomaly detector, allowing users to explore "what-if scenarios." Qualitative and quantitative analyses across various image datasets demonstrate that applying this method to state-of-the-art anomaly detectors provides high-quality semantic explanations.

1 INTRODUCTION

Anomaly detection involves identifying patterns
that deviate from normal behavior, the so-called *anomalies*. These anomalies can correspond
to crucial actionable information in various domains such as medicine, manufacturing, surveillance, and environmental monitoring (Chandola
et al., 2009; Hartung et al., 2023).

031 Recently, deep learning-based methods have shown tremendous success in anomaly detec-033 tion (AD), reducing error rates to approximately 034 1% in numerous image benchmarks (Reiss et al., 2021; Deecke et al., 2021; Ruff et al., 2021; Liznerski et al., 2022). However, detectors based on deep learning lack the out-of-the-box in-037 terpretability of their traditional counterparts, making it difficult to understand the reasoning behind their predictions (Liznerski et al., 040 2021). Their lack of transparency is particularly 041 concerning in sectors where safety is crucial 042 and in situations where building trust is essen-043 tial (Gupta et al., 2018; Montavon et al., 2018; 044 Samek et al., 2020). Understanding modern anomaly detectors is a major challenge in contemporary AD and a necessary step before us-046 ing AD in decision-making systems (Ruff et al., 047 2021). 048



Figure 1: The figure illustrates the benefit of counterfactual explanation of anomaly detectors over traditional methods, using the Colored-MNIST dataset of handwritten digits in various colors. The normal data (top left) consist of red digits and instances of the digit one in any color. An example anomaly—a green seven—is shown on the right. Conventional explanation methods localize the anomaly within the image and highlight it on a heatmap (bottom left). In contrast, the proposed method transforms the anomaly into multiple counterfactuals.

Although feature-attribution techniques such as anomaly heatmaps (Liznerski et al., 2021; Gudovskiy
et al., 2022; Roth et al., 2022) have been explored, they do not explain the underlying semantics of
anomalies relevant to the decision-making of the detectors. In domains beyond AD, counterfactual
explanation (CE) has emerged as a popular alternative. CE generates synthetic samples that change
the model's prediction with minimal alterations to the original sample (Ghandeharioun et al., 2021;
Abid et al., 2022). CEs are user-friendly and can provide explanations on a higher, semantic level.

In this paper, we propose the use of CE to explain anomaly detectors. To our knowledge, this paper presents the first study of CE in modern image AD based on deep learning. The AD setting comes with several considerable challenges. Anomalies can be rare and unlabeled in AD, making it difficult for deep generative models to synthesize realistic counterfactuals based on semantically meaningful concepts that are understandable to humans (Manduchi et al., 2024). Furthermore, normal samples can have limited diversity in AD, which complicates training deep generative models.

Contributions This paper introduces a novel unsupervised method for explaining image anomaly 061 detectors using counterfactual examples. While previous approaches identify anomalous regions 062 within images, the presented technique generates a set of counterfactual examples of each anomaly, 063 capturing diverse disentangled aspects (see Figure 1). These counterfactual examples are created 064 by transforming anomalous images into normal ones, guided by a specific aspect. The method 065 provides semantic explanations of anomaly detectors, highlighting the higher-level aspects of an 066 anomaly that triggered the detector. CE allows users to explore "what-if" scenarios (see Figure 1), 067 improving the understanding of anomaly factors at an unprecedented level of abstraction. Qualitative 068 and quantitative analyses across various image datasets show the effectiveness of the method when 069 applied to state-of-the-art anomaly detectors. The code to reproduce the results and run the presented 070 methods is included in the supplementary material.

2 RELATED WORK

In the past decade, research has increased on improving the interpretability and explainability of non-linear ML methods, particularly neural networks. This increase is driven by the growing use of ML in decision-making systems, where transparency of predictions is crucial and even legally mandated in many countries (Neuwirth, 2022). Here, we discuss key research articles relevant to our work. For a general overview of *explainable AI*, we refer to the survey by Linardatos et al. (2020).

078 079

092

071 072

073 074

075

076

077

060

080 **Explanation of image AD** Research in explainable image AD has primarily focused on feature 081 attribution methods, pinpointing image areas that influence predictions. Some methods trace an importance score from the model output back to the pixels (Selvaraju et al., 2017; Zhang et al., 2018), others alter parts of the image and measure the impact on the model output. These alterations can 083 include masking and noising (Fong & Vedaldi, 2017), blurring (Fong & Vedaldi, 2017), pixel values 084 (Dhurandhar et al., 2018), or model outputs (Zintgraf et al., 2017). Some of these approaches have 085 been applied to AD (Liznerski et al., 2021; Li et al., 2021; Wang et al., 2021). Several methods generate explanations using generative models or autoencoders, where the pixel-wise reconstruction 087 error yields an anomaly heatmap (Baur et al., 2019; Bergmann et al., 2019; Dehaene et al., 2020; Liu 088 et al., 2020; Venkataramanan et al., 2020). Others use fully convolutional architectures (Liznerski 089 et al., 2021) or transfer learning (Defard et al., 2021; Roth et al., 2022). All of these methods identify regions within an image that influence the detector's prediction; however, they do not explain the 091 detectors at a higher semantic level (Alqaraawi et al., 2020; Adebayo et al., 2018).

093 **Counterfactual explanation of neural networks on images** CE methods (Guidotti, 2022) identify the necessary changes in the input to alter the model prediction in a specific way. Unlike feature-094 attribution techniques, CE methods can explain predictions at a more sophisticated semantic level. 095 Such explanations can provide profound insights that enhance comprehension of model behavior 096 and align more closely with human cognitive processes (Pearl, 2009). Existing CE algorithms are 097 designed primarily for supervised learning on tabular data (Wachter et al., 2017; Mothilal et al., 098 2020; Guidotti, 2022). A few studies have also explored the application of CE to image classification (Goyal et al., 2019; Ghandeharioun et al., 2021; Abid et al., 2022; Singla et al., 2023). DISSECT 100 (Ghandeharioun et al., 2021) is particularly notable for its ability to generate multiple CEs with 101 disentangled high-level concepts. However, to date, there is no existing work on the application of 102 CE for image AD. Recent work explores CE for supervised image AD. Studies by Sanchez et al. 103 (2022); Siddiqui et al. (2024); Ahamed et al. (2024) utilize diffusion models guided by text prompts 104 or learnable conditions to generate normal counterparts of abnormal medical images. However, 105 their approaches rely on supervised learning, fine-tuning pretrained diffusion models using both normal and ground-truth anomalies, framing the problem as a classification task. Wolleb et al. 106 (2022) uses diffusion models with classifier guidance-trained in a supervised manner on normal and 107 anomalous images-to transform diseased images into healthy ones. Fontanella et al. (2024) employ

a diffusion model trained exclusively on healthy brain images to generate saliency maps. However, they identify regions for counterfactual generation through supervised learning. Overall, none of the above approaches are designed for unsupervised anomaly detection, and they are constrained to particular types of images. Consequently, they are unsuitable for general image-AD.

112

113 **Counterfactual explanation of AD on shallow data** So far, CE methods for AD have been applied only to "shallow" data types, such as tables (Angiulli et al., 2023; Datta et al., 2022a; Han et al., 114 2023) or time series (Sulem et al., 2022; Cheng et al., 2022). These methods use knowledge graphs or 115 structural causal models to generate counterfactuals for categorical features (Datta et al., 2022b; Han 116 et al., 2023) or take advantage of temporal aspects (Sulem et al., 2022; Cheng et al., 2022). Some of 117 these methods have been applied to fairness (Han et al., 2023) and algorithmic recourse (Datta et al., 118 2022a). None of the existing CE methods for AD are applicable to image data, nor are they capable 119 of generating disentangled CEs. This capability is a unique characteristic of the proposed approach, 120 which will be subsequently detailed.

121 122 123

124

125

126

3 Methodology

In this section, we formally present the proposed framework for generating counterfactuals in image AD using state-of-the-art generators. To the best of our knowledge, this approach is the first one to explain image AD using CE.

127 128 129

3.1 COUNTERFACTUAL EXPLANATIONS OF IMAGE AD

Our aim is to provide explanations for a given anomaly detector $\phi : \mathbb{R}^D \to [0, 1]$ that maps an image $x \in \mathbb{R}^D$ to an anomaly score $\alpha \in [0, 1]$. We define a CE for the detector ϕ and anomaly $x^* \in \mathbb{R}^D$ (i.e., $\phi(x^*) \gg 0$) as a modified sample \bar{x}^* with $\phi(\bar{x}^*) \approx 0$ and $\|\bar{x}^* - x^*\|_1 \le \epsilon$ for an $\epsilon \ge 0$. In other words, a CE must be normal according to ϕ , while being minimally changed w.r.t. the original anomaly x^* . Thus, CEs address the question: "What if the anomaly x were normal?", explaining the behavior of the anomaly detector at a high semantic level.

To produce such CEs for deep AD, we need to train a generator $G : \mathbb{R}^D \to \mathbb{R}^D$ to yield $G(\mathbf{x}^*) = \bar{\mathbf{x}}^*$. However, normal images can differ from anomalies in multiple ways, and thus multiple CEs may be required to adequately explain an anomaly. We want the generator to consider multiple categorical concepts $k \in \{1, ..., K\}$. Thus, the generator is now of the form $G : \mathbb{R}^D \times \{1, ..., K\} \to \mathbb{R}^D$ and is supposed to produce $G(\mathbf{x}^*, k) = \bar{\mathbf{x}}_k^*$ with $\|\bar{\mathbf{x}}_k^* - \bar{\mathbf{x}}_{k'}^*\|_1 \ge \epsilon'$.

The same data $\{(x_0, y_0), \dots, (x_n, y_n)\}$ can be used for training both ϕ and G. Here, $y_i = 0$ denotes normal samples, while $y_i = 1$ represents anomalies. Note that in the AD setting, the training labels y_i are typically unknown and the majority of samples are assumed to be normal.

144 145 146

3.2 DISENTANGLED COUNTERFACTUAL EXPLANATIONS

Outside the domain of AD, Ghandeharioun et al. (2021) have proposed Disentangled Simultaneous
Explanations via Concept Traversal (DISSECT) to create CEs. DISSECT produces sequences of CEs
with increasing impact on a classifier's output. The proposed approach for CE of image anomaly
detectors is based on this idea.

151 We modify the generator $G: \mathbb{R}^D \times [0,1] \times \{1,\ldots,K\} \to \mathbb{R}^D$ to also consider a target anomaly 152 score α , aiming for the trained G to produce a sample with an anomaly score of approximately α . 153 Following DISSECT, we train G as a concept-disentangled GAN Goodfellow et al. (2020). To this end, we define a discriminator $D : \mathbb{R}^D \to [0, 1]$ and a concept classifier $R : \mathbb{R}^D \times \mathbb{R}^D \to [0, 1]^K$. 154 D is trained to distinguish between generated $\bar{x}_{\alpha,k} = G(x, \alpha, k)$ and true samples from the dataset, 155 encouraging *realistic* outcomes. R classifies the concept k for a sample $\bar{x}_{\alpha,k}$, encouraging the 156 generated samples to be *concept-disentangled* on a semantic level. Further losses encourage the 157 generator to incur *minimal changes* on the original sample x and to yield target anomaly scores α 158 (i.e., $\phi(\bar{\boldsymbol{x}}_{\alpha,k}) \approx \alpha$). 159

160 The proposed method's objective summarizes to

161
$$\min_{G,R} \max_{D} \lambda_{gan} \left(L_D(D) + L_G(G) \right) + \lambda_{\phi} L_{\phi}(G) + \lambda_{rec} L_{rec}(G) + \lambda_{rec} L_{cyc}(G) + \lambda_r L_{con}(G,R),$$

where $L_{\phi}(G)$ encourages for $\bar{x}_{\alpha,k}$ an anomaly score of α :

$$L_{\phi}(G) = \alpha \log \left(\phi(\bar{\boldsymbol{x}}_{\alpha,k}) \right) + (1-\alpha) \log \left(1 - \phi(\bar{\boldsymbol{x}}_{\alpha,k}) \right).$$

The losses $L_D(D)$ and $L_G(G)$ can be any discriminative and generative GAN losses, respectively. We specifically experimented with the spectrally normalized loss $L_G(G) = -D(\bar{x}_{\alpha,k})$ Miyato et al. (2018) and the hinge loss Miyato & Koyama (2018):

$$L_D(D) = -\min(0, -1 + D(\boldsymbol{x})) - \min(0, -1 - D(\bar{\boldsymbol{x}}_{\alpha,k})).$$

169 170 171

179 180 181

164

The loss $L_{rec}(G) = ||\boldsymbol{x} - G(\boldsymbol{x}, \phi(\boldsymbol{x}), k)||_1$ makes G reconstruct \boldsymbol{x} for every concept k, when conditioned on \boldsymbol{x} and its "true" anomaly score $\phi(\boldsymbol{x})$. This ensures that G remains unchanged when the sample already has the targeted anomaly score, overall encouraging minimal changes.

Similarly, the "cycle consistency loss" Zhu et al. (2017), $L_{cyc}(G) = \|\boldsymbol{x} - \tilde{\boldsymbol{x}}_{\alpha,k}\|_1$, where $\tilde{\boldsymbol{x}}_{\alpha,k} = G(\bar{\boldsymbol{x}}_{\alpha,k}, \phi(\boldsymbol{x}), k)$, encourages *G* to recreate the sample \boldsymbol{x} , when targeting its true anomaly score $\phi(\boldsymbol{x})$ and being conditioned on any generated sample $\bar{\boldsymbol{x}}_{k,\alpha}$ based on \boldsymbol{x} . It encourages minimal changes because the generator needs to be able to revert any change of \boldsymbol{x} .

 $L_{con}(G, R)$ drives G to produce disentangled concepts:

$$L_{con}(G,R) = \mathbb{C}\Big(k, R\big(\boldsymbol{x}, \bar{\boldsymbol{x}}_{\alpha,k}\big)\Big) + \mathbb{C}\Big(k, R\big(\bar{\boldsymbol{x}}_{k,\alpha}, \tilde{\boldsymbol{x}}_{\alpha,k}\big)\Big),$$

182 183 where \mathbb{C} denotes the cross entropy loss.

In summary, the losses encourage the generated samples $\bar{x}_{\alpha,k}$ to be semantically distinguishable for different concepts k while having an anomaly score of α according to ϕ and undergoing minimal changes with respect to the original x. This results in a disentangled set of K counterfactual examples for an anomaly x^* with $\{G(x^*, 0, 1), \ldots, G(x^*, 0, K)\}$. Furthermore, the generator can also produce pseudo anomalies $G(x, \alpha, K)$ when $\phi(x) \approx 0$ and $\alpha \gg 0$, which can help G in learning how to turn anomalies into normal samples, when included in L_{ϕ} .

190 **CE using diffusion models** We also adapt DiffEdit (Couairon et al., 2023) to generate counterfac-191 tual explanations. DiffEdit modifies the LAION-5B pre-trained text-conditional latent diffusion model 192 known as Stable Diffusion (Rombach et al., 2022) to semantically edit images. Let $A_{\mathcal{E}} : \mathbb{R}^D \to \mathbb{R}^\Delta$ 193 and $A_D: \mathbb{R}^{\Delta} \to \mathbb{R}^D$ denote the encoder and decoder of the autoencoder used in Stable Diffusion. From a high-level perspective, the DiffEdit model can be defined as $\psi : \mathbb{R}^{\Delta \times T} \to \mathbb{R}^{\Delta}$ where T 194 denotes the output dimension of the word embedding model. For an image $x \in \mathbb{R}^{D}$, we retrieve 195 a semantically modified version \hat{x} controlled by the text prompt t via $\hat{x} = A_{\mathcal{D}}(\psi(A_{\mathcal{E}}(x), t))$. For 196 more details, refer to the paper (Couairon et al., 2023). We incorporate DiffEdit into the pro-197 posed framework by training the generator on its latent output. That is, we redefine the generator $G(\boldsymbol{x}, \alpha, k) = A_{\mathcal{D}}(G'(\psi(A_{\mathcal{E}}(\boldsymbol{x}), t), \alpha, k))$ with $G' : \mathbb{R}^{\Delta} \times [0, 1] \times \{1, \dots, K\} \to \mathbb{R}^{\Delta}$. The text 199 prompt t is set to the normal class label (e.g., "cat" for cats being normal). We train the generator G 200 (i.e., the parameters of G') as described before. Incorporating DiffEdit as described here allows one 201 to apply the proposed framework to higher-resolution images, where training from scratch quickly 202 becomes infeasible.

203 204

205

3.3 DEEP ANOMALY DETECTION

The proposed CE framework is general and can be applied to any anomaly detector that produces real-valued anomaly scores. In this paper, we specifically study three state-of-the-art anomaly detectors that are reviewed below.

209

210 DSVDD One of the first deep approaches to AD is Deep Support Vector Data Description (DSVDD) **211** Ruff et al. (2018). Similar to many AD methods, DSVDD is unsupervised, employing an unlabeled **212** corpus of data for training. DSVDD trains a neural network $\phi_{\theta} : \mathbb{R}^{D} \to \mathbb{R}^{d}$ with parameters θ to **213** map the training data $x_1, \ldots, x_n \in \mathbb{R}^{D}$ into a semantic space \mathbb{R}^{d} , where it can be enclosed by a **214** minimal volume hypersphere: $\min_{\theta} \sum_{i=1}^{n} ||\phi_{\theta}(x_i) - c||^2$. In contrast to shallow SVDD Tax & Duin **215** (2004), the hypersphere center $c \in \mathbb{R}^{d}$ is first randomly initialized and then kept fixed while training. DSVDD trains the network to make normal data cluster tightly in the semantic space. Anomalies will have a larger distance from the center. The distance is used as the anomaly score. Since the CE generator requires bounded anomaly scores, we slightly adjust the DSVDD objective to:

$$\min_{ heta} \sum_{i=1}^n rac{||\phi_{ heta}(oldsymbol{x}_i) - oldsymbol{c}||^2}{1+||\phi_{ heta}(oldsymbol{x}_i) - oldsymbol{c}||^2}$$

Outlier Exposure AD has traditionally been approached as an unsupervised learning problem due to insufficient training data to represent the diverse anomaly class, which encompasses *everything* different from the normal data. However, Hendrycks et al. (2019a) showed that Outlier Exposure (OE)—using a large unstructured collection of natural images as example anomalies during training— consistently outperforms purely unsupervised AD methods across various image-AD benchmarks. These auxiliary data are called OE samples. It has been found that training a Binary Cross Entropy (BCE) loss to differentiate normal data from OE samples is competitive for most image-AD tasks. We use the OE samples both for training the detector's network ϕ and the generator G. The generator G is thus trained on a more diverse training set, including additional presumably anomalous OE samples.

Hypersphere Classification Although OE performs well in many benchmarks, there are still
 scenarios where OE samples do not adequately represent anomalies, especially when the normal data
 are not natural images Liznerski et al. (2022). To address this problem, the community has developed
 semi-supervised AD methods Görnitz et al. (2014); Ruff et al. (2020). One of the most competitive
 semi-supervised AD techniques is *HyperSphere Classification* (HSC) Liznerski et al. (2022). The
 authors find that combining it with OE makes the AD more robust to the selection of OE data. The
 HSC loss is a semi-supervised modification of the DSVDD loss:

$$\frac{1}{n}\sum_{i=1}^{n} y_{i} \cdot h\left(\phi_{\theta}(\boldsymbol{x}_{i})\right) - (1-y_{i})\log\left(1-\exp\left(-h\left(\phi_{\theta}(\boldsymbol{x}_{i})\right)\right)\right),$$

where h is the Pseudo-Huber loss $h(z) = \sqrt{||z||^2 + 1 - 1}$. We employ HSC's original objective but modify the anomaly score from $h(\phi_{\theta}(x_i))$ to $1 - \exp(-h(\phi_{\theta}(x_i)))$, again obtaining bounded anomaly scores for training the proposed counterfactual generator.

4 EXPERIMENTS

In this section, we empirically assess the capabilities of CEs for deep AD. The evaluation provides qualitative (Section 4.2) and quantitative (Section 4.3) evidence of the superiority of the proposed CEs over their traditional counterparts. Notably, the experiments expose a previously unreported bias of supervised classifiers when used in the AD setting (Section 4.4).

4.1 EXPERIMENTAL DETAILS

We describe the considered datasets, the experimental setup, and the implementation of the method.

Datasets We evaluate the proposed approach on the following datasets:

- MNIST (Deng, 2012) is a dataset of grayscale handwritten digits with a class for each digit. Following Liznerski et al. (2021), we use EMNIST (Cohen et al., 2017) as OE.
- Colored-MNIST, where for each sample in MNIST, copies are created in seven colors (red, yellow, green, cyan, blue, pink, and gray). We employ a colored version of EMNIST as OE.
- CIFAR-10 (Krizhevsky et al., 2009) is a dataset of natural images with ten classes. Previous works used 80 Mio. Tiny Images as OE (Hendrycks et al., 2019b). Since this dataset has been withdrawn due to offensive data Birhane & Prabhu (2021), we instead use the disjunct CIFAR-100 dataset as OE, which yields approximately the same performance (here 96.0% average AuROC, as reported in Table 8, vs. 96.1% AuROC in Liznerski et al. (2022)).
- GTSDB Houben et al. (2013) is a dataset of German traffic signs. We use CIFAR-100 as OE.
- We introduce ImageNet-Neighbors (INN), a subset of ImageNet-1k (Russakovsky et al., 2015) designed for anomaly detection (AD) tasks. INN comprises multiple AD setups; in each setup, one ImageNet-1k class is considered normal, and the ten most semantically similar classes, based on

the Wu-Palmer similarity metric (Wu & Palmer, 1994), are defined as ground-truth test anomalies.
 For outlier exposure (OE), we use the disjoint ImageNet-21k dataset.

273 **Experimental Setup** Following previous work on image-AD Ruff et al. (2018); Golan & El-Yaniv 274 (2018); Hendrycks et al. (2019a;b); Ruff et al. (2020); Tack et al. (2020); Ruff et al. (2021); Liznerski 275 et al. (2021; 2022), we convert several multi-class classification datasets into AD benchmarks. This is 276 achieved by defining a subset of the classes to be normal and using the remaining classes as ground-277 truth anomalies during testing. When only one class is considered normal, this approach is known as 278 one vs. rest. In addition to investigating one vs. rest, we also explore a variation in which multiple classes are normal. This setting emulates a multifaceted normal class that includes different notions 279 of normality. Since our method disentangles multiple aspects of the normal data, we hypothesize 280 that it possesses the capability to capture these diverse facets of normality. Finally, we consider the 281 special INN setup, as described above, where we have particular ground-truth anomalies per normal 282 class. Our experiments focus on semantic image-AD rather than low-level AD, where anomalies are 283 defects instead of out-of-class (such as in datasets like MVTec-AD (Bergmann et al., 2019)). We 284 include further reasoning for this and an ablation study for CEs on MVTec-AD in Appendix C. 285

For both the MNIST and CIFAR-10 datasets, we construct 30 distinct scenarios: ten scenarios wherein 286 each individual class serves as the normal data, and an additional 20 scenarios featuring various 287 combinations of classes as normal. For the Colored-MNIST dataset, we define seven normal-class 288 scenarios through combinations of colors and digits. We consider ten different normal-class sets for 289 the GTSDB dataset. For ImageNet-Neighbors, we consider five different normal classes. For each 290 scenario and several random seeds, we train an AD model and a CE generator. For INN, we train a 291 generator based on DiffEdit, as described in the methodology section, while the other scenarios train 292 a GAN from scratch. Details of all scenarios are provided in Appendix G. Our quantitative analysis 293 reports results averaged over all scenarios and multiple seeds. Detailed quantitative results for each scenario are in Appendix G and a collection of further qualitative results in Appendix H. 294

295 296

297

298

299

300

301

302

303

Implementation Details In our experiments, we generate and compare CEs using three state-ofthe-art deep AD methods: BCE, HSC, and DSVDD (see Section 3.3). We employ conventional convolutional neural networks with up to five layers for the AD methods. The concept classifier is a small ResNet He et al. (2016) with two blocks. Both the discriminator and generator are wide ResNets Zagoruyko & Komodakis (2016) with four blocks. The λ parameters in our loss (Section 3.2) are set to reasonable values that have been found to perform well across all settings. The hyperparameters of the AD methods are chosen as in previous work Ruff et al. (2018); Liznerski et al. (2022). The epochs and augmentation are slightly reduced for faster training. A description of all hyperparameters and network architectures is given in Appendix E for both the CE generator and AD methods.

304 305 306

307

4.2 QUALITATIVE RESULTS

In this section, we present qualitative examples of CEs on four datasets, demonstrating the benefit of using CE for AD over traditional explanation methods.

4.2.1 COUNTERFACTUALS CAN EXPLAIN WHY IMAGES ARE PREDICTED ANOMALOUS

Colored-MNIST Figure 2 shows the counter-312 factual explanations for Colored-MNIST, when 313 the normal class is formed from the instances 314 of the digit one and digits colored cyan. We ob-315 serve that the CEs generated to explain the BCE 316 detector align well with our expectation. The 317 proposed method transforms the anomalies into 318 ones without changing the color, or their color 319 is changed to cyan without changing the digit. 320 Both modifications are minimal alterations of 321 the anomaly, transforming its appearance to normality in two distinct ways. The CEs of the 322 HSC method also mostly correspond to normal 323 samples, as expected. However, in some cases,



(a) BCE (OE) (b) HSC (OE) (c) DSVDD Figure 2: CEs for the Colored-MNIST dataset, with cyan digits and the digit one serving as the normal class. The first row shows anomalous images, and the next two rows present their corresponding CEs using two different concepts. The CEs of BCE and HSC appear normal and realistic for each concept. both the color and the digit is changed, resulting in unnecessary changes. We found that this behavior
represents a local optimum of the objective of our method, highlighting the inherent difficulty of the
unsupervised generation of CEs for AD. The CEs created to explain the DSVDD detector perform the
least effectively. They tend to appear normal for one concept but often fail for the other concept. This
behavior may be attributed to DSVDD's limited ability to detect anomalies, when compared with the
more competitive BCE and HSC detectors, which have the advantage of having access to OE.

MNIST In Figure 3, a single digit (seven) or multiple digits (eight and nine) are considered normal.



Figure 3: Examples of CEs for MNIST, (a-c) with the digit seven as the normal class, and (d-f) with digits eight and nine forming the normal class. The first row shows anomalous images, the other two rows show CEs using two different concepts. CEs of BCE and HSC in (a,b) are variations of seven and thus represent intuitive counterfactuals. CEs of BCE and DSVDD in (d) resemble normal eights or nines for the second concept.

When the single digit seven is considered normal, the CEs of BCE and HSC are meaningful: the anomalies are transformed into variations of seven. Notably, when the digits eight and nine are considered normal, some anomalies are turned into eights, and others into nines. This observation confirms our hypothesis that our method can correctly reveal diverse notations of normality in multifaceted normal data. As expected, the CEs of DSVDD are generally worse.

GTSDB Figure 4 shows the proposed CEs for 351 the GTSDB dataset, when speed signs are taken 352 as a normal class. We refer to Appendix H for 353 more experimental results using other normal 354 scenarios with similar findings. The CEs of 355 BCE and HSC show well-disentangled normal 356 traffic signs, obtained from anomalous ones. For 357 instance, the CE of BCE changes the "80km/h 358 restriction ends" sign into a "80km/h limit" sign, 359 which is a minimal intervention to make the 360 sample appear normal. Note that all triangular



Figure 4: CEs for GTSDB with speed signs forming the normal class. The first row shows anomalous images, the other two rows disentangled CEs.

anomalies are changed to circles. The CEs show that the shape is an important feature for the detector to rate anomalousness.

363

330 331

332 333

339

350

364 **CIFAR-10** Especially for BCE, the CEs for CIFAR-10 in Figure 5 represent intuitive normal samples (ships) that retain the anomalous 366 object's color to incur minimal changes on the 367 anomaly. As there is only one single normal 368 class, the CEs generated for HSC and BCE pri-369 marily disentangle the concepts by changing the 370 background. Typically, ships are depicted float-371 ing on water, which may vary in color. CEs for 372 DSVDD are generally worse, revealing weak-373 nesses of DSVDD as discussed in Appendix B. 374 We refer to Appendix H for more experimen-375 tal results using other normal classes, demonstrating that CEs exhibit a similar behavior for 376 combinations of classes forming normality. 377



Figure 5: Examples of CEs for CIFAR-10, when images of ships are normal. The first row shows anomalous images, the other two rows present CEs using two different concepts. The CEs of BCE and HSC display normal ships, varying the background for successful disentanglement while keeping the object's color to avoid unnecessary changes.

378 **ImageNet-Neighbors** Figure 6 shows CEs for 379 the INN dataset when zebras are normal. The 380 ground-truth anomalies are "similar" animals, 381 ranging from horses and boars to armadillos. 382 Since DSVDD does not perform competitively, we show results for BCE and HSC only. The CEs depict zebras while keeping the general 384 pose and background of the anomalous animal. 385 For disentanglement, the CEs vary the color 386 scheme, which apparently the detectors perceive 387 as normal. The CEs for the second concept for 388 HSC are dark and, while still showing zebras, 389 perturb the image with green and orange pat-390 terns. Interestingly, the HSC detector assigns 391 lower anomaly scores to the CEs for the second 392 concept. 393



Figure 6: Examples of CEs for INN, where images of zebras are considered normal. The first row shows anomalous images, the other two rows present CEs using two different concepts.

4.2.2 COUNTERFACTUALS CAN EXPLAIN WHY IMAGES ARE PREDICTED ANOMALOUS—even when feature attribution fails

Here, we demonstrate the advantage of the proposed CEs over conventional explanations that attribute features to localize anomalies. Figure shows 7 (a) CEs generated with our method and (b) heatmaps for the corresponding anomalies generated with FCDD Liznerski et al. (2021).

FCDD's heatmaps explain only spatial aspects 403 of the anomalies: FCDD highlights the horizon-404 tal bar in digit seven, the circle in digit nine, and 405 all of digit eight. These spatial aspects of anoma-406 lies are also explained by the CEs created for 407 the first concept, where the anomalies are turned 408 into the digit one. However, FCDD's heatmaps 409 fail to identify the color as being anomalous, 410 whereas the proposed CEs capture this aspect 411 with their second concept, where the anomalies 412 are colored red, making them look normal. This demonstrates that CEs can provide more holistic 413 explanations of anomalies. 414

(a) Counterfactuals (b) Heatmaps with FCDD

Figure 7: The first row shows anomalies from Colored-MNIST, with red digits and the digit one forming the normal class. The other rows show (a) corresponding CEs for two concepts, and (b) anomaly heatmaps generated with FCDD Liznerski et al. (2021). The CEs explain the anomaly detector that perceives anomalies turned red or into one as normal, while heatmaps just highlight the difference to one.

416 4.3 QUANTITATIVE RESULTS

This section presents a quantitative analysis of the CEs, assessing their normality, realism, disentanglement, and suitability for training anomaly detectors in terms of various metrics based on AuROC, FID, and accuracy. These metrics are described in detail in Appendix D.

420 421

415

417

418

419

394

395

422 4.3.1 THE COUNTERFACTUALS APPEAR 423 AS NORMAL

Table 1: The AuROC of normal test data vs. CEs. The CEs appear entirely normal for values $\leq 50\%$.

424 An important attribute for any CE in deep AD 425 is that it must be perceived as normal by the 426 anomaly detector. To evaluate this quality cri-427 terion, we compare the anomaly scores of the 428 normal test samples with those of the generated 429 CEs in terms of AuROC. Ideally, the AuROC should approach 50%, indicating that CE and 430 normal samples are indistinguishable. As shown 431 in Table 1, the AuROC is indeed very close to

	Deterrite		Methods	
	Datasets	BCE OE	HSC OE	DSVDD
Single normal class	MNIST CIFAR-10 INN	$\begin{array}{c} 72.0\pm 4.0\\ 47.5\pm 10.0\\ 69.1\pm 18.1\end{array}$	$\begin{array}{c} 80.8 \pm 5.3 \\ 49.9 \pm 4.4 \\ 67.9 \pm 13.2 \end{array}$	$75.2 \pm 9.2 \\ 54.6 \pm 3.4 \\ \times$
Multiple normal classes	C-MNIST MNIST CIFAR-10 GTDSB	$\begin{array}{c} 55.6 \pm 1.5 \\ 78.1 \pm 4.1 \\ 49.0 \pm 8.5 \\ 50.2 \pm 8.0 \end{array}$	$\begin{array}{c} 55.8 \pm 4.7 \\ 82.1 \pm 3.8 \\ 44.4 \pm 6.7 \\ 48.6 \pm 14.4 \end{array}$	$\begin{array}{c} 61.5 \pm 4.3 \\ 73.4 \pm 6.5 \\ 50.7 \pm 3.3 \\ 53.1 \pm 4.8 \end{array}$

50% on CIFAR-10, GTSDB, and Colored-MNIST (here abbreviated as C-MNIST), underlining
that the detector perceives the CEs as normal. Only on MNIST and INN, some of the CEs appear
anomalous. This might be due to the enforced disentanglement that produces diverse samples despite
a limited variety of possible normal variations.

436 437

438

439 440

441

442

443 444

445

446 447

458

459

460

461 462

463

4.3.2 The counterfactuals can be used to train an anomaly detector effectively

If the CEs resemble normal images, they can serve as viable normal training samples. We retrain the AD methods using CEs instead of the normal training set and report the AuROC for normal vs. anomalous test samples in Table 2a. The results show that the CEs are effective normal training samples, as the AuROC values are mostly well above the chance level of 50%.

Table 2: AuROC of normal vs. anomalous test samples when (a) the AD is trained with the normal training set being substituted with CEs and (b) the AD is trained with the usual normal training set.

(a) AD	AuROC	with th	e CEs a	s normal	training	data
(a) AD	Auroc	with the	ヒしじょる	is normar	uanning	uata

(b) AD AuROC with the proper normal training set.

	Deterrit		Methods			Detecto		Methods	
	Datasets	BCE OE	HSC OE	DSVDD		Datasets	BCE OE	HSC OE	DSVDD
Single	MNIST	91.3 ± 4.6	85.6 ± 9.2	46.2 ± 10.5	Single	MNIST	97.7 ± 1.5	97.6 ± 1.6	78.8 ± 8.6
normal	CIFAR-10	59.0 ± 6.1	54.8 ± 2.6	50.8 ± 3.2	normal	CIFAR-10	96.0 ± 2.5	95.9 ± 2.5	55.4 ± 4.7
class	INN	59.2 ± 5.8	53.0 ± 11.0	×	class	INN	93.6 ± 5.7	92.6 ± 6.7	×
Multiple	C-MNIST	80.6 ± 4.5	81.7 ± 4.8	59.9 ± 8.4	Multiple	C-MNIST	97.1 ± 1.0	95.7 ± 2.3	76.9 ± 6.5
normal	MNIST	62.2 ± 13.2	54.7 ± 9.9	41.6 ± 4.5	winnple	MNIST	93.5 ± 2.8	92.9 ± 3.3	75.4 ± 7.1
alassas	CIFAR-10	58.7 ± 4.6	53.1 ± 1.8	49.7 ± 4.1	normai	CIFAR-10	93.8 ± 2.7	94.0 ± 2.7	52.6 ± 3.6
classes	GTDSB	90.1 ± 5.3	89.9 ± 5.1	58.4 ± 7.0	classes	GTDSB	94.3 ± 4.7	93.0 ± 5.6	58.2 ± 6.7

The AD methods significantly outperform a random detector when trained with CEs, affirming their viability as normal samples. A notable exception is DSVDD, a method that does not utilize OE and struggles when trained purely with CEs. Table 2b shows the AuROC values of the models when trained with the proper normal training set.

4.3.3 THE COUNTERFACTUALS ARE REALISTIC

464 To assess the realism of the CEs, we compute 465 the FID between CEs and normal test samples. 466 For an intuitive score, we normalize the FID for 467 CEs by dividing by the FID between normal and anomalous test samples. The normalized FID 468 is 100% if the CEs are equally realistic as the 469 anomalies. Details are provided in Appendix D. 470 We found that a normalized FID of 50 to 100% is 471 a reasonable target for expressive CEs. If the CEs 472 became too similar to the normal data distribution, 473 they would not be valid counterfactuals, as they 474 would not retain non-anomalous features from the 475 anomalies. Table 3 displays the normalized FID 476 scores. The CEs for BCE and HSC are mostly as 477 realistic as the anomalies. On MNIST, INN and

Table 3: Normalized FID scores for the CEs. Most of the CEs are as realistic as the anomalies, which are also realistic since they follow the general data distribution (e.g., are digits in case of MNIST).

	Deterrete		Methods	
	Datasets	BCE OE	HSC OE	DSVDD
Single normal class	MNIST CIFAR-10 INN	$\begin{array}{c} 43 \pm 8.1 \\ 116 \pm 20.8 \\ 85.0 \pm 28.6 \end{array}$	$\begin{array}{c} 68 \pm 14.6 \\ 300 \pm 90.0 \\ 85.4 \pm 24.6 \end{array}$	$\begin{array}{c} 100 \pm 8.8 \\ 116 \pm 12.0 \\ \times \end{array}$
Multiple normal classes	C-MNIST MNIST CIFAR-10 GTDSB	$\begin{array}{c} 56 \pm 12.4 \\ 78 \pm 26.0 \\ 103 \pm 27.9 \\ 110 \pm 101.8 \end{array}$	$\begin{array}{c} 95 \pm 30.5 \\ 96 \pm 25.0 \\ 254 \pm 69.7 \\ 95 \pm 73.5 \end{array}$	$\begin{array}{c} 83 \pm 8.7 \\ 100 \pm 10.7 \\ 110 \pm 10.0 \\ 131 \pm 118.1 \end{array}$

⁴⁷⁸ Colored-MNIST, the CEs are even more realistic than the anomalies. As CEs for DSVDD tend to479 reconstruct anomalies, their realism is also reasonable.

480

481 482

4.3.4 THE COUNTERFACTUALS CAPTURE MULTIPLE DISENTANGLED ASPECTS

Here we show that, for each anomaly, our method generates concept-disentangled CEs. Recall that
 the concept classifier is trained to predict the concept of each CE (see Section 3). Consequently, we
 have a metric for assessing the disentanglement of the generated samples. We present the accuracy of
 this concept classifier on test data in Table 4.

486 Our models demonstrate a consistent ability to 487 disentangle concepts effectively, with the ex-488 ception of DSVDD, which has suboptimal AD 489 performance, making it difficult to provide ex-490 planations in general. In particular, disentanglement is effective even in the case where just one 491 class is considered normal. On CIFAR-10 the 492 generator exploits the background, on INN the 493 color scheme, and on MNIST it generates disen-<u>191</u> tangled variants of digits. We hypothesize that 495 this strong disentanglement is the reason behind 496 the CEs appearing less normal for MNIST. 497

- 498
- 499
- 4.4 COUNTERFACTUALS REVEAL A PREVIOUSLY UNREPORTED CLASSIFIER BIAS IN DEEP AD

500 501

502 In this section, we present a scientific finding: classifiers may be biased when trained for 504 deep AD. The hypothesis of "classification bias," suggesting supervised classifiers underperform 505 when trained with limited and biased anomaly 506 subsets Ruff et al. (2020), remains insufficiently 507 investigated. To test this hypothesis, we train a 508 supervised classifier on Colored-MNIST, aiming 509 to distinguish between a normal set (red digits 510 and the digit one) and a subset of the ground-511 truth anomalies, specifically all blue anomalies. 512 We select a subset of the anomalies for train-513 ing to simulate a realistic scenario in which one 514 has no access to all variations of the ground-515 truth anomalies. A key requirement in AD is the model's ability to identify all forms of unseen 516 anomalies. The classifier bias becomes appar-517 ent as the AuROC of normal test samples vs. 518 ground-truth anomalies decreases from 98 for 519

Table 4: The accuracy of the concept classifier for the generated CEs.

	Detecto		Methods	
	Datasets	BCE OE	HSC OE	DSVDD
Single normal class	MNIST CIFAR-10 INN	$\begin{array}{c} 94.3 \pm 3.9 \\ 93.0 \pm 4.3 \\ 97.0 \pm 5.4 \end{array}$	$\begin{array}{c} 90.8 \pm 4.8 \\ 98.8 \pm 3.2 \\ 98.9 \pm 1.1 \end{array}$	$77.5 \pm 14.1 \\ 97.1 \pm 2.9 \\ \times$
Multiple normal classes	C-MNIST MNIST CIFAR-10 GTDSB	$\begin{array}{c} 99.4 \pm 1.3 \\ 93.8 \pm 5.1 \\ 86.2 \pm 7.5 \\ 98.8 \pm 0.8 \end{array}$	$\begin{array}{c} 98.9 \pm 2.0 \\ 85.7 \pm 9.6 \\ 98.9 \pm 2.4 \\ 94.0 \pm 8.4 \end{array}$	$\begin{array}{c} 98.0\pm 3.0\\ 81.6\pm 11.3\\ 92.2\pm 4.2\\ 93.4\pm 4.5\end{array}$



Figure 8: The first row shows anomalies for Colored-MNIST with red digits and the digit one forming the normal class. The other two rows present CEs of BCE trained with OE in (a) and of a classifier trained with only blue anomalies in (b). The generator's inability to generate normallooking CEs for anomalies other than blue suggests that the classifier in (b) is biased.

BCE with OE (unsupervised) to 75 for supervised BCE. Our CEs further illuminate this phenomenon 520 (see Figure 8). While our explanation for the AD method with OE in (a) indicates that anomalies 521 should be transformed into red or digit one to appear normal, they depict a different picture for the 522 supervised classifier in (b). Here, only for the blue anomalous zero, which is seen during training, the 523 CEs roughly show intuitive normal versions of the anomaly. For other unseen anomalies, such as the 524 cyan five or yellow eight, the explanations do not show intuitive normal images. This suggests that 525 the classifier is biased towards detecting blue anomalies and fails to generalize to other colors not present in the training set. This underlines the need for specialized AD methods (e.g., using OE or 526 semi-supervised objectives) because they are less prone to bias. 527

528 529

5 CONCLUSION

530 531

This paper introduced a novel method that can interpret image anomaly detectors at a semantic
level. This is achieved by modifying anomalies until they are perceived as normal by the detector,
creating instances known as counterfactuals. We found that counterfactuals can provide a deeper, more
nuanced understanding of image anomaly detectors, far beyond the traditional feature-attribution level.
Extensive experiments across various image benchmarks and deep anomaly detectors demonstrated
the efficacy of the proposed approach. This research marks a paradigm shift and a significant departure
from the more superficial interpretation of anomaly detectors using feature attribution, enhancing our
understanding of detectors on a more abstract, semantic level. This may be a substantial milestone in
the pursuit of more transparent and accountable AD systems.

540 REFERENCES

565

566

567

570

580

581

582

583

588

589

542	Abubakar Abid, Mert Yuksekgonul, and James Zou. Meaningfully debugging model mistakes using
543	conceptual counterfactual explanations. In International Conference on Machine Learning, pp.
544	66–88. PMLR, 2022.

- Julius Adebayo, Justin Gilmer, Michael Muelly, Ian Goodfellow, Moritz Hardt, and Been Kim. Sanity checks for saliency maps. *Advances in neural information processing systems*, 31, 2018.
- Shadab Ahamed, Yixi Xu, and Arman Rahmim. Igconda-pet: Implicitly-guided counterfactual
 diffusion for detecting anomalies in pet images. *arXiv preprint arXiv:2405.00239*, 2024.
- Ahmed Alqaraawi, Martin Schuessler, Philipp Weiß, Enrico Costanza, and Nadia Berthouze. Evaluating saliency map explanations for convolutional neural networks: a user study. In *Proceedings of the 25th international conference on intelligent user interfaces*, pp. 275–285, 2020.
- Fabrizio Angiulli, Fabio Fassetti, Simona Nisticó, and Luigi Palopoli. Counterfactuals explanations
 for outliers via subspaces density contrastive loss. In *International Conference on Discovery Science*, pp. 159–173. Springer, 2023.
- Christoph Baur, Benedikt Wiestler, Shadi Albarqouni, and Nassir Navab. Deep autoencoding models
 for unsupervised anomaly segmentation in brain mr images. *Lecture Notes in Computer Science*, pp. 161–169, 2019. ISSN 1611-3349. doi: 10.1007/978-3-030-11723-8_16.
- Paul Bergmann, Michael Fauser, David Sattlegger, and Carsten Steger. Mvtec ad–a comprehensive real-world dataset for unsupervised anomaly detection. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition*, pp. 9592–9600, 2019.
 - Abeba Birhane and Vinay Uday Prabhu. Large image datasets: A pyrrhic win for computer vision? In 2021 IEEE Winter Conference on Applications of Computer Vision (WACV), pp. 1536–1546. IEEE, 2021.
- Varun Chandola, Arindam Banerjee, and Vipin Kumar. Anomaly detection: A survey. ACM
 Computing Surveys, 41(3):1–58, 2009.
- He Cheng, Depeng Xu, Shuhan Yuan, and Xintao Wu. Fine-grained anomaly detection in sequential data via counterfactual explanations. *arXiv preprint arXiv:2210.04145*, 2022.
- 573 Gregory Cohen, Saeed Afshar, Jonathan Tapson, and Andre Van Schaik. EMNIST: Extending MNIST
 574 to handwritten letters. In *International Joint Conference on Neural Networks*, pp. 2921–2926, 2017.
 576
- Guillaume Couairon, Jakob Verbeek, Holger Schwenk, and Matthieu Cord. Diffedit: Diffusion-based
 semantic image editing with mask guidance. In *The Eleventh International Conference on Learning Representations*, 2023. URL https://openreview.net/forum?id=3lge0p5o-M-.
 - Debanjan Datta, Feng Chen, and Naren Ramakrishnan. Framing algorithmic recourse for anomaly detection. In *Proceedings of the 28th ACM SIGKDD Conference on Knowledge Discovery and Data Mining*, pp. 283–293, 2022a.
- Debanjan Datta, Feng Chen, and Naren Ramakrishnan. Framing Algorithmic Recourse for Anomaly
 Detection. In *Proceedings of the 28th ACM SIGKDD Conference on Knowledge Discovery and Data Mining*, pp. 283–293, August 2022b. doi: 10.1145/3534678.3539344. URL http:
 //arxiv.org/abs/2206.14384. arXiv:2206.14384 [cs, stat].
 - Harm De Vries, Florian Strub, Jérémie Mary, Hugo Larochelle, Olivier Pietquin, and Aaron C Courville. Modulating early visual processing by language. *Advances in Neural Information Processing Systems*, 30, 2017.
- Lucas Deecke, Lukas Ruff, Robert A Vandermeulen, and Hakan Bilen. Transfer-based semantic
 anomaly detection. In *International Conference on Machine Learning*, pp. 2546–2558. PMLR, 2021.

594 595 596	Thomas Defard, Aleksandr Setkov, Angelique Loesch, and Romaric Audigier. Padim: a patch distribution modeling framework for anomaly detection and localization. In <i>International Conference on Pattern Recognition</i> , pp. 475–489. Springer, 2021.
597 598	David Dehaene, Oriel Frigo, Sébastien Combrexelle, and Pierre Eline. Iterative energy-based projection on a normal data manifold for anomaly localization. In <i>International Conference on</i>
600	Learning Representations, 2020.
601 602 603	Li Deng. The mnist database of handwritten digit images for machine learning research. <i>IEEE Signal Processing Magazine</i> , 29(6):141–142, 2012.
604 605 606	Amit Dhurandhar, Pin-Yu Chen, Ronny Luss, Chun-Chen Tu, Paishun Ting, Karthikeyan Shanmugam, and Payel Das. Explanations based on the missing: Towards contrastive explanations with pertinent negatives. <i>Advances in neural information processing systems</i> , 31, 2018.
608 609 610	Ruth C Fong and Andrea Vedaldi. Interpretable explanations of black boxes by meaningful perturba- tion. In <i>Proceedings of the IEEE international conference on computer vision</i> , pp. 3429–3437, 2017.
611 612 613 614	Alessandro Fontanella, Grant Mair, Joanna Wardlaw, Emanuele Trucco, and Amos Storkey. Diffusion models for counterfactual generation and anomaly detection in brain images. <i>IEEE Transactions on Medical Imaging</i> , 2024.
615 616 617 618 619	 Asma Ghandeharioun, Been Kim, Chun-Liang Li, Brendan Jou, Brian Eoff, and Rosalind W. Picard. DISSECT: Disentangled Simultaneous Explanations via Concept Traversals. In <i>International Conference on Learning Representations</i>. OpenReview.net, 2021. doi: 10.48550/ARXIV.2105. 15164. URL https://openreview.net/forum?id=qY79G8jGsep. Version Number: 4.
620 621 622	Izhak Golan and Ran El-Yaniv. Deep anomaly detection using geometric transformations. In <i>Advances in Neural Information Processing Systems</i> , pp. 9758–9769, 2018.
623 624 625	Ian Goodfellow, Jean Pouget-Abadie, Mehdi Mirza, Bing Xu, David Warde-Farley, Sherjil Ozair, Aaron Courville, and Yoshua Bengio. Generative adversarial networks. <i>Communications of the ACM</i> , 63(11):139–144, 2020.
626 627 628 629	Nico Görnitz, M. Kloft, Konrad Rieck, and Ulf Brefeld. Toward supervised anomaly detection. J. Artif. Intell. Res., 46:235–262, 2014. URL https://api.semanticscholar.org/CorpusID: 9406699.
630 631 632 633	Yash Goyal, Ziyan Wu, Jan Ernst, Dhruv Batra, Devi Parikh, and Stefan Lee. Counterfactual Visual Explanations. In <i>Proceedings of the 36th International Conference on Machine Learning</i> , pp. 2376–2384. PMLR, May 2019. URL https://proceedings.mlr.press/v97/goyal19a.html.
635 636 637	Denis Gudovskiy, Shun Ishizaka, and Kazuki Kozuka. Cflow-ad: Real-time unsupervised anomaly detection with localization via conditional normalizing flows. In <i>Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision</i> , pp. 98–107, 2022.
638 639	Riccardo Guidotti. Counterfactual explanations and how to find them: literature review and bench- marking. <i>Data Mining and Knowledge Discovery</i> , pp. 1–55, 2022.
640 641 642	Agrim Gupta, Justin Johnson, Li Fei-Fei, Silvio Savarese, and Alexandre Alahi. Social GAN: Socially acceptable trajectories with generative adversarial networks. In <i>CVPR</i> , pp. 2255–2264, 2018.
643 644 645 646	Xiao Han, Lu Zhang, Yongkai Wu, and Shuhan Yuan. Achieving counterfactual fairness for anomaly detection. In <i>Pacific-Asia Conference on Knowledge Discovery and Data Mining</i> , pp. 55–66. Springer, 2023.
647	James A Hanley and Barbara J McNeil. The meaning and use of the area under a receiver operating characteristic (roc) curve. <i>Radiology</i> , 143(1):29–36, 1982.

648 649 650 651	Fabian Hartung, Billy Joe Franks, Tobias Michels, Dennis Wagner, Philipp Liznerski, Steffen Reithermann, Sophie Fellenz, Fabian Jirasek, Maja Rudolph, Daniel Neider, et al. Deep anomaly detection on tennessee eastman process data. <i>Chemie Ingenieur Technik</i> , 2023.
652 653 654	Kaiming He, Xiangyu Zhang, Shaoqing Ren, and Jian Sun. Deep residual learning for image recognition. In <i>Proceedings of the IEEE conference on computer vision and pattern recognition</i> , pp. 770–778, 2016.
655 656 657	Dan Hendrycks, Mantas Mazeika, and Thomas G Dietterich. Deep anomaly detection with outlier exposure. In <i>International Conference on Learning Representations</i> , 2019a.
658 659 660	Dan Hendrycks, Mantas Mazeika, Saurav Kadavath, and Dawn Song. Using self-supervised learning can improve model robustness and uncertainty. In <i>Advances in Neural Information Processing Systems</i> , pp. 15637–15648, 2019b.
661 662 663	Martin Heusel, Hubert Ramsauer, Thomas Unterthiner, Bernhard Nessler, and Sepp Hochreiter. Gans trained by a two time-scale update rule converge to a local nash equilibrium. <i>Advances in neural information processing systems</i> , 30, 2017.
665 666 667	Sebastian Houben, Johannes Stallkamp, Jan Salmen, Marc Schlipsing, and Christian Igel. Detection of traffic signs in real-world images: The German Traffic Sign Detection Benchmark. In <i>International Joint Conference on Neural Networks</i> , 2013.
668 669 670	Alex Krizhevsky, Geoffrey Hinton, et al. Learning multiple layers of features from tiny images. Technical report, Citeseer, 2009.
671 672 673	Chun-Liang Li, Kihyuk Sohn, Jinsung Yoon, and Tomas Pfister. Cutpaste: Self-supervised learning for anomaly detection and localization. In <i>Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition</i> , pp. 9664–9674, 2021.
674 675 676	Pantelis Linardatos, Vasilis Papastefanopoulos, and Sotiris Kotsiantis. Explainable ai: A review of machine learning interpretability methods. <i>Entropy</i> , 23(1):18, 2020.
677 678 679	Wenqian Liu, Runze Li, Meng Zheng, Srikrishna Karanam, Ziyan Wu, Bir Bhanu, Richard J. Radke, and Octavia Camps. Towards visually explaining variational autoencoders. In <i>Proceedings of the IEEE Conference on computer vision and pattern recognition</i> , pp. 8642–8651, 2020.
680 681 682 683	Philipp Liznerski, Lukas Ruff, Robert A. Vandermeulen, Billy Joe Franks, Marius Kloft, and Klaus- Robert Müller. Explainable deep one-class classification. In <i>International Conference on Learning</i> <i>Representations</i> , 2021.
684 685 686 687	Philipp Liznerski, Lukas Ruff, Robert A. Vandermeulen, Billy Joe Franks, Klaus-Robert Müller, and Marius Kloft. Exposing outlier exposure: What can be learned from few, one, and zero outlier images. <i>Transactions on Machine Learning Research</i> , 2022. URL https://openreview.net/forum?id=3v78awEzyB.
688 689 690 691	Laura Manduchi, Kushagra Pandey, Robert Bamler, Ryan Cotterell, Sina Däubener, Sophie Fellenz, Asja Fischer, Thomas Gärtner, Matthias Kirchler, Marius Kloft, et al. On the challenges and opportunities in generative ai. <i>arXiv preprint arXiv:2403.00025</i> , 2024.
692 693 694 695	Takeru Miyato and Masanori Koyama. cgans with projection discriminator. In 6th International Conference on Learning Representations, ICLR 2018, Vancouver, BC, Canada, April 30 - May 3, 2018, Conference Track Proceedings. OpenReview.net, 2018. URL https://openreview. net/forum?id=ByS1VpgRZ.
696 697 698 699 700	Takeru Miyato, Toshiki Kataoka, Masanori Koyama, and Yuichi Yoshida. Spectral normalization for generative adversarial networks. In 6th International Conference on Learning Representations, ICLR 2018, Vancouver, BC, Canada, April 30 - May 3, 2018, Conference Track Proceedings. OpenReview.net, 2018. URL https://openreview.net/forum?id=B1QRgziT

701 Grégoire Montavon, Wojciech Samek, and Klaus-Robert Müller. Methods for interpreting and understanding deep neural networks. *Digital Signal Processing*, 73:1–15, 2018.

702 703 704 705	Ramaravind K Mothilal, Amit Sharma, and Chenhao Tan. Explaining machine learning classifiers through diverse counterfactual explanations. In <i>Proceedings of the 2020 conference on fairness, accountability, and transparency</i> , pp. 607–617, 2020.
706 707	Rostam J Neuwirth. The EU artificial intelligence act: regulating subliminal AI systems. Taylor & Francis, 2022.
708 709	Judea Pearl. Causality. Cambridge university press, 2009.
710 711 712	Tal Reiss, Niv Cohen, Liron Bergman, and Yedid Hoshen. Panda: Adapting pretrained features for anomaly detection and segmentation. In <i>Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition</i> , pp. 2806–2814, 2021.
713 714 715 716	Robin Rombach, Andreas Blattmann, Dominik Lorenz, Patrick Esser, and Björn Ommer. High- resolution image synthesis with latent diffusion models. In <i>Proceedings of the IEEE/CVF confer-</i> <i>ence on computer vision and pattern recognition</i> , pp. 10684–10695, 2022.
717 718 719	Karsten Roth, Latha Pemula, Joaquin Zepeda, Bernhard Schölkopf, Thomas Brox, and Peter Gehler. Towards total recall in industrial anomaly detection. In <i>Proceedings of the IEEE/CVF Conference</i> on Computer Vision and Pattern Recognition, pp. 14318–14328, 2022.
720 721 722 723	Lukas Ruff, Robert A Vandermeulen, Nico Görnitz, Lucas Deecke, Shoaib A. Siddiqui, Alexander Binder, Emmanuel Müller, and Marius Kloft. Deep one-class classification. In <i>International</i> <i>Conference on Machine Learning</i> , volume 80, pp. 4390–4399, 2018.
724 725 726	Lukas Ruff, Robert A Vandermeulen, Nico Görnitz, Alexander Binder, Emmanuel Müller, Klaus- Robert Müller, and Marius Kloft. Deep semi-supervised anomaly detection. In <i>International</i> <i>Conference on Learning Representations</i> , 2020.
727 728 729 730	Lukas Ruff, Jacob R Kauffmann, Robert A Vandermeulen, Grégoire Montavon, Wojciech Samek, Marius Kloft, Thomas G Dietterich, and Klaus-Robert Müller. A unifying review of deep and shallow anomaly detection. <i>Proceedings of the IEEE</i> , 109(5):756–795, 2021.
731 732 733 734	Olga Russakovsky, Jia Deng, Hao Su, Jonathan Krause, Sanjeev Satheesh, Sean Ma, Zhiheng Huang, Andrej Karpathy, Aditya Khosla, Michael Bernstein, Alexander C. Berg, and Li Fei-Fei. ImageNet Large Scale Visual Recognition Challenge. <i>International Journal of Computer Vision (IJCV)</i> , 115 (3):211–252, 2015. doi: 10.1007/s11263-015-0816-y.
735 736 737 738	Wojciech Samek, Grégoire Montavon, Sebastian Lapuschkin, Christopher J Anders, and Klaus-Robert Müller. Toward interpretable machine learning: Transparent deep neural networks and beyond. <i>arXiv preprint arXiv:2003.07631</i> , 2020.
739 740 741	Pedro Sanchez, Antanas Kascenas, Xiao Liu, Alison Q O'Neil, and Sotirios A Tsaftaris. What is healthy? generative counterfactual diffusion for lesion localization. In <i>MICCAI Workshop on Deep Generative Models</i> , pp. 34–44. Springer, 2022.
742 743 744 745 746	Ramprasaath R Selvaraju, Michael Cogswell, Abhishek Das, Ramakrishna Vedantam, Devi Parikh, and Dhruv Batra. Grad-cam: Visual explanations from deep networks via gradient-based local- ization. In <i>Proceedings of the IEEE international conference on computer vision</i> , pp. 618–626, 2017.
747 748	Ammar A Siddiqui, Santosh Tirunagari, Tehseen Zia, and David Windridge. Vald-md: Visual attribution via latent diffusion for medical diagnostics. <i>arXiv preprint arXiv:2401.01414</i> , 2024.
749 750 751 752	Sumedha Singla, Motahhare Eslami, Brian Pollack, Stephen Wallace, and Kayhan Batmanghelich. Explaining the black-box smoothly—a counterfactual approach. <i>Medical Image Analysis</i> , 84: 102721, 2023.
753 754 755	Deborah Sulem, Michele Donini, Muhammad Bilal Zafar, Francois-Xavier Aubet, Jan Gasthaus, Tim Januschowski, Sanjiv Das, Krishnaram Kenthapadi, and Cedric Archambeau. Diverse Counterfactual Explanations for Anomaly Detection in Time Series, March 2022. URL http: //arxiv.org/abs/2203.11103. arXiv:2203.11103 [cs, stat].

756 757 758 750	Christian Szegedy, Wei Liu, Yangqing Jia, Pierre Sermanet, Scott Reed, Dragomir Anguelov, Du- mitru Erhan, Vincent Vanhoucke, and Andrew Rabinovich. Going deeper with convolutions. In <i>Proceedings of the IEEE conference on computer vision and pattern recognition</i> , pp. 1–9, 2015.
760 761 762	Jihoon Tack, Sangwoo Mo, Jongheon Jeong, and Jinwoo Shin. Csi: Novelty detection via contrastive learning on distributionally shifted instances. <i>Advances in neural information processing systems</i> , 33:11839–11852, 2020.
763 764	David MJ Tax and Robert PW Duin. Support vector data description. <i>Machine learning</i> , 54(1):45–66, 2004.
765 766 767 768	Shashanka Venkataramanan, Kuan-Chuan Peng, Rajat Vikram Singh, and Abhijit Mahalanobis. Attention guided anomaly localization in images. In <i>European Conference on Computer Vision</i> , pp. 485–503. Springer, 2020.
769 770	Sandra Wachter, Brent Mittelstadt, and Chris Russell. Counterfactual explanations without opening the black box: Automated decisions and the gdpr. <i>Harv. JL & Tech.</i> , 31:841, 2017.
771 772 773 774	Shenzhi Wang, Liwei Wu, Lei Cui, and Yujun Shen. Glancing at the patch: Anomaly localization with global and local feature comparison. In <i>Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition</i> , pp. 254–263, 2021.
775 776 777	Julia Wolleb, Florentin Bieder, Robin Sandkühler, and Philippe C Cattin. Diffusion models for medical anomaly detection. In <i>International Conference on Medical image computing and computer-assisted intervention</i> , pp. 35–45. Springer, 2022.
778 779 780	Zhibiao Wu and Martha Palmer. Verb semantics and lexical selection. In <i>32nd Annual Meeting of the Association for Computational Linguistics</i> , pp. 133–138, 1994.
781 782	Sergey Zagoruyko and Nikos Komodakis. Wide residual networks. In British Machine Vision Conference, 2016.
783 784 785 786	Jianming Zhang, Sarah Adel Bargal, Zhe Lin, Jonathan Brandt, Xiaohui Shen, and Stan Sclaroff. Top-down neural attention by excitation backprop. <i>International Journal of Computer Vision</i> , 126 (10):1084–1102, 2018.
787 788 789	Jun-Yan Zhu, Taesung Park, Phillip Isola, and Alexei A Efros. Unpaired image-to-image translation using cycle-consistent adversarial networks. In <i>Proceedings of the IEEE international conference on computer vision</i> , pp. 2223–2232, 2017.
790 791 792	Luisa M Zintgraf, Taco S Cohen, Tameem Adel, and Max Welling. Visualizing deep neural network decisions: Prediction difference analysis. <i>arXiv preprint arXiv:1702.04595</i> , 2017.
793 704	
794	
796	
797	
798	
799	
800	
801	
802	
803	
804	
805	
806	
807	
808	
809	

⁸¹⁰ A BROADER IMPACT

As an explanation technique, our method naturally aids in making deep AD more transparent. It may reveal biases in the model (see Section 4.4) and improve trustworthiness. For example, it may reveal a social bias when a portrait of a person is labeled anomalous due to race or gender. In this scenario, our method might generate CEs where merely the skin color has been changed. Applying our method can prevent a harmful deployment of such an AD model.

817 818 819

B LIMITATIONS OF OUR APPROACH

820 In the main paper, we proposed a method to generate counterfactual explanations (CEs) for deep 821 anomaly detection (AD). As seen in Section 4, the quality of the generated counterfactual explanations 822 relies on the performance of the AD model. DSVDD without OE Ruff et al. (2018) performs weakly 823 on some image datasets. Consequently, CEs for DSVDD are often not very intuitive and sometimes 824 collapse to a mere reconstruction of the anomaly. This happens because DSVDD struggles to 825 recognize an anomaly and thus assigns a low anomaly score to it. Our method doesn't have a reason to change an anomaly to turn it normal for DSVDD. Another limitation of our method is that the 826 generator might change more than necessary to turn the anomaly normal, thereby falling into a local 827 optimum of the overall objective. Learning to balance the objectives of our method in an unsupervised 828 manner is challenging, especially given the limited variety and amount of normal samples. Future 829 work may improve upon this. 830

831 832

833

C COUNTERFACTUAL EXPLANATIONS OF DEFECTS

In the main paper, we did not include experiments on datasets such as MVTec-AD, where anomalies are subtle modifications of normal samples (e.g., cracked hazelnuts for healthy hazelnuts being normal) rather than being out of class. Such datasets are not interesting in the context of high-level explanations. Contrary to usual assumptions in AD, where anomalies are *everything*, which is not normal, in MVTec-AD there is a very precise definition of anomalousness and only one specific way to turn anomalies normal (i.e., by removing the defect). CEs would not help in understanding the model. Hence, we focus on the well-established and important semantic image-AD setting.

To visualize why CEs are not a useful tool for explaining low-level AD, we trained our proposed method from scratch with a single concept on several classes of MVTec-AD. Figure 9 shows some generated CEs for the classes bottle, grid, hazelnut, metal nut, screw, tile, and wood. Mostly, the CEs are high-quality: realistic and normal. However, they do not help us to understand the behavior of the model. They simply show the sample with the defect removed, which is a trivial explanation of the anomaly but does not explain the anomaly detector.



Figure 9: CEs for MVTec-AD and an anomaly detector trained with BCE and ImageNet-21k as OE. For each class, a different detector and CE generator was trained. The first row shows anomalies, the other corresponding CEs.

D METRICS

In this section, we provide details of the metrics used for the quantitative analysis in Section 4.3.

Normality of counterfactuals To assess the normality of the generated CEs, we computed the
 AuROC of normal test samples against CEs generated for all ground-truth anomalies from the test set. The Area Under the ROC curve (AuROC) is a widely recognized metric in the AD literature

864 for comparing anomaly scores of normal and anomalous samples Hanley & McNeil (1982). An 865 AuROC of 1 indicates perfect separation between anomalies and normal samples, 0.5 corresponds to 866 random guessing, and a score below 0.5 suggests that anomalies appear more normal than the actual 867 normal samples. To assess the normality of our CEs, we computed the AuROC with the anomalies 868 being CEs. Then, an AuROC of significantly more than 0.5 indicates that the CEs retain some degree of anomalousness according to the chosen detector. An AuROC of 0.5 indicates that CEs appear completely normal, and for below 0.5 the CEs are even more normal than the normal test samples. 870 This may happen when the anomaly detector does not generalize perfectly and hence perceives some 871 normal test samples as somewhat anomalous. 872

873

880

Usefulness of counterfactuals for training AD To further assess the normality and realism of the CEs, we tested their ability to train a new anomaly detector. To this end, we replaced the entire normal training set with a collection of CEs generated for all ground-truth anomalies. With this modified training set, we retrained the AD methods, additionally using an outlier exposure set in case of BCE and HSC. If the CEs resemble normal images, the retrained anomaly detectors will outperform random guessing. We measure this by computing the AuROC for true normal vs. anomalous test samples and compare the outcome to the chance level, which is 0.5.

Realism of counterfactuals To assess the realism of generated samples, the standard approach 882 involves computing the Fréchet inception distance (FID) introduced by Heusel et al. (2017) for GANs. The FID is the Wasserstein distance between the feature distributions of a generated dataset and a 883 ground-truth dataset. The larger the distance, the less the generated dataset resembles the ground 884 truth. The features are extracted using an InceptionNet v3 model Szegedy et al. (2015) trained on 885 ImageNet. In this paper, we used the normal test set as ground truth and a collection of CEs for all 886 test anomalies as the generated dataset. For a more intuitive scoring, we also computed a second FID 887 with the test anomalies as the generated dataset. Then, we normalize the FID for CEs by dividing through the FID for test anomalies. The normalized FID is 100% if the CEs are as realistic as the test 889 anomalies, below 100% if they are more realistic, and 0% if they exactly match the normal test set. It 890 is important to note that, although anomalies are naturally anomalous, they are still *realistic* in the 891 sense that they come from the same classification dataset and thus follow the general distribution of, 892 e.g., handwritten digits. A normalized FID of 100% is therefore sufficient for a counterfactual to be 893 expressive. A normalized FID of close to 0% would actually be spurious, as the generator then seems to entirely reproduce normal samples that do not retain non-anomalous features from the anomaly. 894

895

Disentanglement of counterfactuals We also evaluated the disentanglement of the sets of CEs for
each anomaly. As introduced in Section 3, the proposed method includes a concept classifier trained
to predict the concept of each CE. Consequently, we have a metric for assessing the disentanglement
of the generated samples. The higher the accuracy of this classifier, the stronger the disentanglement
of the generated CEs. We chose a rather small network for the concept classifier to encourage the
network not to overfit on non-semantic features to predict the concepts.

901 902 903

904

905

906

907

908

909

E HYPERPARAMETERS

In this section, we provide an exhaustive enumeration of all the hyperparameters that we used for training our AD and CE module. All hyperparameters were adopted from existing research Ruff et al. (2018); Ghandeharioun et al. (2021); Liznerski et al. (2022). We start by describing the CE module, which is the same for all datasets and AD objectives. Then we separately describe the AD module and other hyperparameters for MNIST, Colored-MNIST, CIFAR-10, and GTSDB.

910 E.1 THE CE MODULE

Generator The generator is a wide ResNet Zagoruyko & Komodakis (2016) structured as an encoder-decoder network. The encoder consists of a sequential arrangement of a batch normalization layer, a convolutional layer with 64 kernels, and three residual blocks. Each residual block comprises two sets, each containing a conditional batch normalization layer De Vries et al. (2017), followed by an activation function (ReLU), and a convolutional layer. The convolutional layers in these sets have 256, 512, and 1024 kernels, respectively, for the first, second, and third block. The initial two residual blocks employ average pooling in each set to reduce the spatial dimension of the feature

918 maps by one-half of the input, while the third residual block is implemented without average pooling 919 to maintain the spatial dimension. Conversely, the decoder follows a similar sequential arrangement, 920 featuring three residual blocks, followed by a batch normalization layer, a final convolutional layer 921 mapping to the image space, and an activation function (ReLU). Again, each residual block comprises 922 two sets, each containing a conditional batch normalization layer, followed by RelU activation, and a convolutional layer. The convolutional layers in these sets have 1024, 512, and 256 kernels, 923 respectively, for the first, second, and third block. The first residual block in the decoder retains the 924 spatial dimension, while the subsequent two residual blocks employ an interpolation layer in each set 925 to upsample the spatial dimension by a multiplicative factor of 2 using nearest-neighbor interpolation. 926 We apply spectral normalization to all layers of the decoder, following Miyato et al. (2018). The last 927 layer of the decoder uses a tanh activation. The conditional information, i.e., the discretized target 928 anomaly score α and the target concept k are transformed into a single categorical condition and 929 processed through the categorical conditional batch normalization layers. 930

931 **Discriminator** The discriminator contains four residual blocks arranged sequentially, followed 932 by a final linear layer mapping to a scalar. The first block is implemented with two convolutional 933 layers with 64 kernels, where the first layer is followed by a ReLU activation and the second layer is 934 followed by an average pooling with a kernel size of 2. The next two residual blocks consist of two 935 convolutional layers, where each one is preceded by a ReLU activation and followed by an average 936 pooling layer in the end to halve the spatial dimension. The fourth residual block also contains two convolutional layers preceded by a ReLU, but does not use any downsampling. The number of 937 kernels in the convolutional layers from the second to fourth block is 128, 256, and 512, respectively. 938 We apply spectral normalization to all layers. 939

940 **Concept Classifier** The concept classifier is composed of two sequentially arranged residual blocks, 941 succeeded by a linear layer with two outputs for the classification of two concepts. In the first residual 942 block, three convolutional layers are employed with 64 kernels each. The initial convolutional layer 943 is succeeded by a ReLU activation, and the last two convolutional layers are followed by average 944 pooling layers, which reduce the spatial dimension by a factor of two. The second residual block 945 consists of two convolutional layers with 128 kernels, each followed by a ReLU activation, followed 946 by an average pooling with a kernel size of two. We take the sum over the remaining spatial dimension 947 to prepare the output for the final linear layer. Again, we apply spectral normalization to all layers. 948

949 **Training** We train the generator to generate CEs with two disentangled concepts and a discretized 950 target anomaly score $\alpha \in 0, 0.5, 1$. The CE module is trained for 350 (2000 for GTSDB) epochs with a batch size of 64 normal and, if used, 64 OE samples. The initial learning rate is set to 951 $2e^{-4}$, with reductions by a multiplicative factor of 0.1 occurring after 300 and 325 epochs. For 952 GTSDB, we instead use an initial learning rate of $1e^{-4}$ and reduce it after 1750 and 1900 epochs. We 953 employ the Adam optimizer, with the generator and discriminator optimized every 1 and 5 batches, 954 respectively. The CE objective involves a combination of different losses which are weighted using λ 955 hyperparameters. Specifically, we set $\lambda_{gan} = 1$, $\lambda_{rec} = 100$, $\lambda_{\phi} = 1$, and $\lambda_r = 10$. For GTSDB, 956 we instead set $\lambda_{gan} = 5$, $\lambda_{rec} = 20$, $\lambda_{\phi} = 1$, and $\lambda_r = 10$. For INN, we use a different set of 957 hyperparameters. We set $\lambda_{gan} = 10$, $\lambda_{rec} = 1$, $\lambda_{\phi} = 1$, and $\lambda_r = 0.5$. Also, we consider only $\alpha = 0$, 958 as we train the generator with only OE samples to reduce the training time, while the discriminator is 959 trained with normal and generated samples. Due to the immense VRAM requirements of the diffusion 960 model, we train with a batch size of 1 and use the running statistics of all BatchNorm layers during training. The initial learning rate is set to $1e^{-4}$. It is reduced by a factor of 0.5 at 100, 120, 130, 140, 961 and 145 epochs. The model is trained for 150 epochs in total. 962

963

964 E.2 AD ON MNIST

For MNIST and all the following datasets, we trained anomaly detectors with a binary cross entropy (BCE) and hypersphere classification (HSC) loss, both with Outlier Exposure (OE) Hendrycks et al. (2019a), as well as DSVDD Ruff et al. (2018) without OE.

We use a LeNet-style neural network comprising layers arranged sequentially without residual connections. The network contains four convolutional layers and two fully-connected layers. Each convolutional layer is followed by batch normalization, a leaky ReLU activation, and max-pooling. The first fully connected layer is followed by batch normalization and a leaky ReLU activation, while

the last layer is only a linear transformation. The number of kernels in the convolutional layers is,
from first to last, 4, 8, 16, and 32. The kernel size is increased from the default of 3 to 5 for all of
these. The two fully connected layers have 64 and 32 units, respectively. For DSVDD we remove
bias from the network, following Ruff et al. (2018), and for BCE we add another linear layer with
sigmoid activation.

We used Adam for optimization and balanced every batch to contain 128 normal and 128 OE samples during training. We trained the AD model for 80 epochs starting with a learning rate of $1e^{-4}$, which we reduced to $1e^{-5}$ after 60 epochs.

- 980 981 982
- E.3 AD ON COLORED-MNIST

Based on the MNIST dataset, we create Colored-MNIST where for each sample in MNIST six copies in different colors (red, yellow, green, cyan, blue, pink) are created. We use a colored version of EMNIST as OE. The network for Colored-MNIST is a slight variation of the AD network used on MNIST. We remove the last convolutional layer and change the number of kernels for the convolutional layers to 16, 32, and 64, respectively.

We use Adam for optimization, balance every batch to contain 128 normal and 128 OE samples during training, and train the AD model for 120 epochs, starting with a learning rate of $5e^{-5}$, reduced to $5e^{-6}$ after 100 epochs.

- 991 992 993
- E.4 AD ON CIFAR-10

For CIFAR-10, previous work used 80 Mio. Tiny Images as OE Hendrycks et al. (2019b). However, since 80 Mio. Tiny Images has officially been withdrawn due to offensive data, we instead use the disjunct CIFAR-100 dataset as OE. We found that this does not cause a significant drop of performance. Again, we use a slight variation of the AD network used on MNIST. We remove the last convolutional layer and change the number of kernels for the convolutional layers to 32, 64, and 128, respectively. The fully connected layers have 512 and 256 units instead.

We use Adam for optimization and balance every batch to contain 128 normal and 128 OE samples during training. We train the AD model for 200 epochs starting with a learning rate of $1e^{-3}$, which we reduce by a factor of 0.1 after 100 and 150 epochs.

- 1003
- 1005 E.5 AD ON GTSDB
- 1006 1007 We use the same setup on GTSDB as on CIFAR-10.
- 1008

1009 E.6 AD ON IMAGENET-NEIGHBORS

For ImageNet-Neighbors (INN), we use the disjoint ImageNet-21k as OE and the same WideResNet architecture as in (Hendrycks et al., 2019b; Liznerski et al., 2022). We use Adam for optimization and balance every batch to contain 64 normal and 64 OE samples during training. We train the AD model for 150 epochs starting with a learning rate of $1e^{-3}$, which we reduce by a factor of 0.1 after 100 and 125 epochs.

1016

1017 F COMPUTE RESOURCES

Most of the experiments with MNIST, Colored-MNIST, CIFAR-10, and GTSDB were carried out on a NVIDIA DGX-1 server containing 8 GV100 GPUs with 32 GB memory. For Colored-MNIST, each experiment with one seed and normal class definition took around one and a half days. For MNIST and CIFAR-10, each experiment took approximately 8 hours. Each GTSDB experiment took only about 3 hours. The time to run each experiment varies depending on the precise setup. For the INN experiments, most experiments were carried out on a NVIDIA DGX A-100 server with 8 A100 GPUs with 40 GB memory. One experiment with one seed and normal class definition took approximately 10 days.

¹⁰²⁶ G Full quantitative results per normal class

1027

1028 In the main paper, we proposed a method to generate counterfactual explanations (CEs) for deep 1029 anomaly detection on images. We also presented several objective evaluation techniques to validate 1030 their performance on MNIST, Colored-MNIST (C-MNIST), CIFAR-10, GTSDB, and ImageNet-1031 Neighbors (INN) across different definitions of normality. Following previous work on semantic 1032 image-AD Ruff et al. (2018); Golan & El-Yaniv (2018); Hendrycks et al. (2019a;b); Ruff et al. (2020); Tack et al. (2020); Ruff et al. (2021); Liznerski et al. (2021; 2022), we turned classification 1033 datasets into AD benchmarks by defining a subset of the classes to be normal and using the remainder 1034 as ground-truth anomalies for testing. If only one class is normal, this approach is termed *one* 1035 vs. rest AD. Apart from investigating one vs. rest, we also explored a variation with multiple classes 1036 being normal. For our experiments, we considered all classes of MNIST and CIFAR-10 as single 1037 normal classes and, to keep the computational load at a reasonable level, a subset of 20 normal class 1038 combinations. The class combinations were chosen from $\{(i, (i+1) \mod 10) | i \in \{0, \dots, 9\}\} \cup$ 1039 $\{(i, (i+2) \mod 10) | i \in \{0, \dots, 9\}\}$. For Colored-MNIST, we considered all combinations of 1040 color and the digit one as normal. For GTSDB, we considered the following pairs of street signs as 1041 normal: all four combinations of speed limit signs, the "give way" and stop sign, and the "danger" 1042 and "construction" warning sign. Additionally, we considered four larger sets of normal classes: 1043 all "restriction ends" signs, all speed limit signs, all blue signs, and all warning signs. In total, we consider ten different scenarios of normal definitions for GTSDB. 1044

1045 We introduced ImageNet-Neighbors (INN), which is a subset of ImageNet-1K. As before, we define 1046 an AD setup by considering one of the classes normal. However, instead of using the entire remainder 1047 as ground-truth test anomalies, we choose only the ten most similar classes, based on the Wu-Palmer 1048 similarity metric (Wu & Palmer, 1994), as test anomalies. This AD setup becomes harder as compared 1049 to the usual one vs. rest AD setup (Hendrycks et al., 2019a), as the anomalies are more similar to the normal class and thus harder to detect, especially in an unsupervised manner. In this paper, we 1050 consider five different AD setups for INN. (1) An airliner is normal with airship, wreck, warplane, 1051 balloon, monocycle, fireboat, schooner, space shuttle, pirate ship, and gondola as test anomalies. (2) 1052 An ambulance is normal with limousine, taxi, waggon, racing car, minivan, jeep, sports car, golf cart, 1053 Model T, and convertible as test anomalies. (3) A black widow (spider) is normal with centipede, 1054 trilobite, wolf spider, garden spider, barn spider, harvestman, scorpion, black and gold garden spider, 1055 tarantula, and tick as test anomalies. (4) A lion is normal with cougar, cheetah, jaguar, tiger cat, 1056 leopard, snow leopard, lynx, tiger, tabby cat, and Siamese cat as test anomalies. (5) A zebra is normal 1057 with sorrel, llama, warthog, boar, hamster, armadillo, hog, beaver, Arabian camel, and hippo as test 1058 anomalies.

For each scenario on each dataset, a new AD model and counterfactual generator was trained for four random seeds. Due to space constraints, we reported our quantitative results averaged over all normal definitions in the main paper. Here, we report results averaged over four random seeds separately for each normal definition. We consider the following metrics from the main paper:

1064

1067

1068 1069

1070

1071

- The AD AuROC (Section 4.3.2) is the AuROC of normal vs. anomalous test samples, thereby measuring the AD performance of the AD model. 50% is random, 100% indicates optimal separation.
- The CF AuROC (Section 4.3.1) is the AuROC of normal test samples vs. counterfactuals. The counterfactuals appear entirely normal for an AuROC $\leq 50\%$.
 - The Sub. AuROC (Section 4.3.2) is the AuROC of normal vs. anomalous test samples when the AD is trained with counterfactuals in place of the normal training set.
- The FID_N (Section 4.3.3) denotes the normalized FID scores. 0% indicates that the counterfactuals follow the same feature distribution as normal samples, 100% as anomalies, which are also realistic, and above 100% indicates less realistic counterfactuals.
 - The Concept Acc (Section 4.3.4) is the accuracy of the concept classifier. A 100% accuracy indicates optimal disentanglement of the concepts.
- Additionally, we report the "Score distance", which is the L1 distance between the average anomaly
 score of normal and anomalous test samples. Note that the L1 distance between normal training data
 and OE samples is usually 1. Thus, the "Score distance" measures the generalizability of the AD model to ground-truth anomalies in terms of anomaly score calibration.

Tables 5, 6, and 7 show results for MNIST and single normal classes for BCE, HSC, and DSVDD, respectively. In Tables 8, 9, and 10, we instead report results for CIFAR-10 and single normal classes for BCE, HSC, and DSVDD, respectively. Tables 11, 12, and 13 show results for Colored-MNIST (here abbreviated as C-MNIST) for BCE, HSC, and DSVDD, respectively. Tables 14, 15, and 16 show results for GTSDB and combined normal classes for BCE, HSC, and DSVDD, respectively. Tables 17, 18, and 19 show results for MNIST and combined normal classes for BCE, HSC, and DSVDD, respectively. Tables 20, 21, and 22 show results for CIFAR-10 and combined normal classes for BCE, HSC, and DSVDD, respectively. Tables 23 and 24 show results for ImageNet-Neighbors and single normal classes for BCE and HSC, respectively.

Table 5: AD and explanation performance averaged over 4 random seeds on MNIST for BCE (OE).
 Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
zero	0.99 ± 0.0010	0.78 ± 0.0079	0.76 ± 0.0684	0.93 ± 0.0104	0.42 ± 0.0366	0.97 ± 0.036
one	1.00 ± 0.0005	0.87 ± 0.0155	0.66 ± 0.0977	0.97 ± 0.0107	0.47 ± 0.4474	0.99 ± 0.008
two	0.97 ± 0.0083	0.69 ± 0.0379	0.75 ± 0.0253	0.85 ± 0.0183	0.56 ± 0.0431	0.87 ± 0.050
three	0.99 ± 0.0018	0.67 ± 0.0286	0.77 ± 0.0242	0.94 ± 0.0073	0.33 ± 0.0392	0.89 ± 0.083
four	0.97 ± 0.0090	0.75 ± 0.0359	0.70 ± 0.0787	0.88 ± 0.0457	0.48 ± 0.0954	0.91 ± 0.056
five	0.97 ± 0.0058	0.65 ± 0.0398	0.66 ± 0.0076	0.84 ± 0.0184	0.44 ± 0.0405	0.98 ± 0.023
six	1.00 ± 0.0010	0.90 ± 0.0106	0.71 ± 0.0527	0.98 ± 0.0066	0.33 ± 0.0348	0.96 ± 0.03
seven	0.96 ± 0.0107	0.71 ± 0.0275	0.70 ± 0.0519	0.92 ± 0.0133	0.50 ± 0.0464	0.96 ± 0.023
eight	0.95 ± 0.0102	0.54 ± 0.0337	0.72 ± 0.0817	0.87 ± 0.0054	0.31 ± 0.0271	0.94 ± 0.07
nine	0.96 ± 0.0092	0.60 ± 0.0329	0.77 ± 0.0147	0.94 ± 0.0080	0.47 ± 0.0593	0.97 ± 0.01
mean	0.98 ± 0.0154	0.72 ± 0.1067	0.72 ± 0.0400	0.91 ± 0.0456	0.43 ± 0.0808	0.94 ± 0.03

Table 6: AD and explanation performance averaged over 4 random seeds on MNIST for HSC (OE).
Each row shows results for a different normal definition.

$\begin{array}{c} \text{AuROC} \\ \hline 0.99 \pm 0.0011 \\ 1.00 \pm 0.0011 \\ 0.98 \pm 0.0013 \\ 0.98 \pm 0.0056 \\ 0.96 \pm 0.0038 \end{array}$	Score distance 0.81 ± 0.0306 0.89 ± 0.0231 0.72 ± 0.0338 0.67 ± 0.0166 0.73 ± 0.0269	$\begin{array}{c} \hline CF \ AuROC \\ \hline 0.84 \pm 0.0772 \\ 0.88 \pm 0.0783 \\ 0.77 \pm 0.0332 \\ 0.82 \pm 0.0717 \\ 0.80 \pm 0.0658 \end{array}$	$\begin{array}{c} \text{Sub. AuROC}\\ \hline 0.91 \pm 0.0101\\ 0.95 \pm 0.0089\\ 0.77 \pm 0.0438\\ 0.85 \pm 0.0209 \end{array}$	$FID_N \\ 0.58 \pm 0.1412 \\ 0.60 \pm 0.3820 \\ 0.80 \pm 0.3295 \\ 0.48 \pm 0.2057 \\ \end{array}$	$\begin{array}{c} \text{Concept Acc} \\ 0.98 \pm 0.0106 \\ 0.90 \pm 0.0868 \\ 0.92 \pm 0.0575 \\ 0.83 \pm 0.1941 \end{array}$
$\begin{array}{c} 0.99 \pm 0.0011 \\ 1.00 \pm 0.0011 \\ 0.98 \pm 0.0013 \\ 0.98 \pm 0.0056 \\ 0.96 \pm 0.0038 \end{array}$	$\begin{array}{c} 0.81 \pm 0.0306 \\ 0.89 \pm 0.0231 \\ 0.72 \pm 0.0338 \\ 0.67 \pm 0.0166 \\ 0.73 \pm 0.0269 \end{array}$	$\begin{array}{c} 0.84 \pm 0.0772 \\ 0.88 \pm 0.0783 \\ 0.77 \pm 0.0332 \\ 0.82 \pm 0.0717 \\ 0.80 \pm 0.0658 \end{array}$	$\begin{array}{c} 0.91 \pm 0.0101 \\ 0.95 \pm 0.0089 \\ 0.77 \pm 0.0438 \\ 0.85 \pm 0.0209 \end{array}$	$\begin{array}{c} 0.58 \pm 0.1412 \\ 0.60 \pm 0.3820 \\ 0.80 \pm 0.3295 \\ 0.48 \pm 0.2057 \end{array}$	$\begin{array}{c} 0.98 \pm 0.0106 \\ 0.90 \pm 0.0868 \\ 0.92 \pm 0.0575 \\ 0.83 \pm 0.1941 \end{array}$
$\begin{array}{c} 1.00 \pm 0.0011 \\ 0.98 \pm 0.0013 \\ 0.98 \pm 0.0056 \\ 0.96 \pm 0.0038 \end{array}$	$\begin{array}{c} 0.89 \pm 0.0231 \\ 0.72 \pm 0.0338 \\ 0.67 \pm 0.0166 \\ 0.73 \pm 0.0269 \end{array}$	$\begin{array}{c} 0.88 \pm 0.0783 \\ 0.77 \pm 0.0332 \\ 0.82 \pm 0.0717 \\ 0.80 \pm 0.0658 \end{array}$	$\begin{array}{c} 0.95 \pm 0.0089 \\ 0.77 \pm 0.0438 \\ 0.85 \pm 0.0209 \end{array}$	$\begin{array}{c} 0.60 \pm 0.3820 \\ 0.80 \pm 0.3295 \\ 0.48 \pm 0.2057 \end{array}$	$\begin{array}{c} 0.90 \pm 0.0868 \\ 0.92 \pm 0.0575 \\ 0.83 \pm 0.1941 \end{array}$
$\begin{array}{c} 0.98 \pm 0.0013 \\ 0.98 \pm 0.0056 \\ 0.96 \pm 0.0038 \end{array}$	$\begin{array}{c} 0.72 \pm 0.0338 \\ 0.67 \pm 0.0166 \\ 0.73 \pm 0.0269 \end{array}$	$\begin{array}{c} 0.77 \pm 0.0332 \\ 0.82 \pm 0.0717 \\ 0.80 \pm 0.0658 \end{array}$	$\begin{array}{c} 0.77 \pm 0.0438 \\ 0.85 \pm 0.0209 \end{array}$	$\begin{array}{c} 0.80 \pm 0.3295 \\ 0.48 \pm 0.2057 \end{array}$	$\begin{array}{c} 0.92 \pm 0.0575 \\ 0.83 \pm 0.1941 \end{array}$
$\begin{array}{c} 0.98 \pm 0.0056 \\ 0.96 \pm 0.0038 \end{array}$	$\begin{array}{c} 0.67 \pm 0.0166 \\ 0.73 \pm 0.0269 \end{array}$	0.82 ± 0.0717	0.85 ± 0.0209	0.48 ± 0.2057	0.83 ± 0.1941
0.96 ± 0.0038	0.73 ± 0.0269	0.90 ± 0.0659			
	0	0.00 ± 0.0038	0.84 ± 0.0394	0.83 ± 0.2911	0.81 ± 0.1526
0.96 ± 0.0054	0.62 ± 0.0334	0.83 ± 0.0603	0.70 ± 0.1316	0.77 ± 0.1088	0.92 ± 0.1010
1.00 ± 0.0010	0.88 ± 0.0211	0.77 ± 0.0607	0.98 ± 0.0076	0.84 ± 0.3493	0.95 ± 0.0547
0.97 ± 0.0052	0.71 ± 0.0066	0.70 ± 0.0319	0.92 ± 0.0112	0.52 ± 0.0301	0.91 ± 0.0675
0.95 ± 0.0069	0.52 ± 0.0334	0.89 ± 0.0278	0.73 ± 0.0590	0.88 ± 0.3052	0.94 ± 0.0739
0.97 ± 0.0043	0.59 ± 0.0192	0.80 ± 0.0227	0.92 ± 0.0031	0.53 ± 0.0739	0.91 ± 0.0512
		0.01 + 0.0526	0.86 ± 0.0010	0.69 ± 0.1464	0.01 ± 0.0478
0	$\begin{array}{r} 0.95 \pm 0.0069 \\ 0.97 \pm 0.0043 \end{array}$	$\begin{array}{l} 0.95 \pm 0.0069 & 0.52 \pm 0.0334 \\ 0.97 \pm 0.0043 & 0.59 \pm 0.0192 \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

Table 7: AD and explanation performance averaged over 4 random seeds on MNIST for DSVDD. Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept
zero	0.82 ± 0.0685	0.01 ± 0.0038	0.76 ± 0.0870	0.41 ± 0.0680	1.16 ± 0.5100	0.96 ± 0
one	1.00 ± 0.0020	0.05 ± 0.0086	0.99 ± 0.0054	0.76 ± 0.1219	1.02 ± 0.0600	0.84 ± 0
two	0.72 ± 0.1254	0.01 ± 0.0057	0.69 ± 0.1664	0.34 ± 0.0203	0.89 ± 0.0117	0.49 ± 0
three	0.72 ± 0.0274	0.00 ± 0.0036	0.70 ± 0.0545	0.42 ± 0.0527	0.90 ± 0.0234	0.59 ± 0
four	0.72 ± 0.0517	0.01 ± 0.0040	0.65 ± 0.0669	0.46 ± 0.0180	0.88 ± 0.1156	0.80 ± 0
five	0.73 ± 0.0316	0.01 ± 0.0050	0.71 ± 0.0562	0.44 ± 0.0632	0.97 ± 0.0869	0.87 ± 0
six	0.83 ± 0.0964	0.01 ± 0.0126	0.80 ± 0.1238	0.44 ± 0.0466	1.08 ± 0.0339	0.84 ± 0
seven	0.84 ± 0.0450	0.01 ± 0.0135	0.80 ± 0.0533	0.46 ± 0.0858	1.04 ± 0.0408	0.88 ± 0
eight	0.70 ± 0.0359	0.00 ± 0.0007	0.69 ± 0.0440	0.46 ± 0.0792	0.99 ± 0.0775	0.82 ± 0
nine	0.81 ± 0.0331	0.01 ± 0.0056	0.74 ± 0.0568	0.44 ± 0.0599	1.09 ± 0.0822	0.65 ± 0
mean	0.79 ± 0.0865	0.01 ± 0.0119	0.75 ± 0.0916	0.46 ± 0.1050	1.00 ± 0.0876	0.78 ± 0

	A	D	Explanation				
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Ad	
airplane	0.96 ± 0.0009	0.78 ± 0.0083	0.47 ± 0.0372	0.65 ± 0.0322	1.48 ± 0.1439	0.93 ± 0.06	
automobile	0.99 ± 0.0005	0.87 ± 0.0026	0.62 ± 0.0540	0.62 ± 0.0347	1.08 ± 0.0582	0.92 ± 0.07	
bird	0.93 ± 0.0030	0.65 ± 0.0020	0.42 ± 0.0378	0.53 ± 0.0138	1.42 ± 0.0777	0.99 ± 0.00	
cat	0.91 ± 0.0035	0.55 ± 0.0127	0.30 ± 0.0054	0.53 ± 0.0159	1.37 ± 0.0773	0.91 ± 0.14	
deer	0.96 ± 0.0020	0.74 ± 0.0043	0.40 ± 0.0209	0.53 ± 0.0103	1.09 ± 0.1095	0.99 ± 0.01	
dog	0.94 ± 0.0013	0.64 ± 0.0051	0.36 ± 0.0061	0.57 ± 0.0134	1.23 ± 0.0777	0.93 ± 0.10	
frog	0.98 ± 0.0011	0.79 ± 0.0067	0.50 ± 0.0247	0.54 ± 0.0127	0.80 ± 0.0652	0.88 ± 0.13	
horse	0.98 ± 0.0006	0.82 ± 0.0060	0.59 ± 0.0303	0.64 ± 0.0213	1.21 ± 0.1013	0.99 ± 0.01	
ship	0.98 ± 0.0002	0.85 ± 0.0032	0.55 ± 0.0098	0.72 ± 0.0300	0.93 ± 0.0810	0.89 ± 0.07	
truck	0.97 ± 0.0018	0.78 ± 0.0080	0.54 ± 0.0602	0.56 ± 0.0242	1.03 ± 0.1231	0.88 ± 0.20	
mean	0.96 ± 0.0252	0.75 ± 0.0964	0.47 ± 0.1000	0.59 ± 0.0610	1.16 ± 0.2078	0.93 ± 0.04	

Table 8: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for BCE OE.Each row shows results for a different normal definition.

Table 9: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for HSC OE.
 Each row shows results for a different normal definition.

1206		A	D		Expla	nation	
1207	Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
1208	airplane	0.96 ± 0.0012	0.75 ± 0.0056	0.51 ± 0.0754	0.52 ± 0.0111	2.95 ± 0.1509	0.89 ± 0.0873
1209	automobile	0.99 ± 0.0005	0.85 ± 0.0030	0.58 ± 0.0152	0.59 ± 0.0129	1.71 ± 0.1914	0.99 ± 0.0054
1210	bird	0.93 ± 0.0015	0.62 ± 0.0018	0.46 ± 0.0293	0.52 ± 0.0149	4.81 ± 0.2365	1.00 ± 0.0007
1210	cat	0.90 ± 0.0020	0.53 ± 0.0072	0.43 ± 0.0255	0.52 ± 0.0088	3.98 ± 0.4753	1.00 ± 0.0009
1211	deer	0.96 ± 0.0007	0.71 ± 0.0040	0.51 ± 0.0121	0.57 ± 0.0230	3.45 ± 0.3143	1.00 ± 0.0000
1212	dog	0.95 ± 0.0012	0.65 ± 0.0047	0.46 ± 0.0317	0.53 ± 0.0257	3.09 ± 0.2897	1.00 ± 0.0023
1213	frog	0.98 ± 0.0004	0.77 ± 0.0043	0.52 ± 0.0062	0.57 ± 0.0569	2.92 ± 0.4138	1.00 ± 0.0009
1215	horse	0.98 ± 0.0008	0.79 ± 0.0040	0.54 ± 0.0466	0.54 ± 0.0281	3.13 ± 0.0463	1.00 ± 0.0001
1214	ship	0.98 ± 0.0003	0.83 ± 0.0027	0.48 ± 0.0257	0.56 ± 0.0316	1.86 ± 0.5187	1.00 ± 0.0032
1215	truck	0.97 ± 0.0011	0.77 ± 0.0055	0.51 ± 0.0257	0.57 ± 0.0623	2.19 ± 0.1318	1.00 ± 0.0010
1216	mean	0.96 ± 0.0254	0.73 ± 0.0939	0.50 ± 0.0438	0.55 ± 0.0259	3.01 ± 0.8998	0.99 ± 0.0325

Table 10: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for DSVDD. Each row shows results for a different normal definition.

	A	\D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
airplane	0.48 ± 0.0952	-0.00 ± 0.0022	0.54 ± 0.0733	0.45 ± 0.0265	1.28 ± 0.0382	0.98 ± 0.0114
automobile	0.51 ± 0.0339	0.00 ± 0.0003	0.52 ± 0.0606	0.49 ± 0.0198	1.15 ± 0.0266	0.99 ± 0.0076
bird	0.54 ± 0.0375	0.00 ± 0.0005	0.52 ± 0.0601	0.51 ± 0.0133	1.23 ± 0.0548	0.91 ± 0.1548
cat	0.52 ± 0.0216	0.00 ± 0.0008	0.51 ± 0.0513	0.50 ± 0.0260	1.38 ± 0.1380	0.98 ± 0.0221
deer	0.65 ± 0.0312	0.01 ± 0.0030	0.62 ± 0.0996	0.53 ± 0.0611	1.12 ± 0.0467	1.00 ± 0.0028
dog	0.53 ± 0.0259	0.00 ± 0.0030	0.51 ± 0.0296	0.50 ± 0.0195	1.21 ± 0.0830	0.96 ± 0.0523
frog	0.60 ± 0.0692	0.01 ± 0.0027	0.54 ± 0.0371	0.57 ± 0.0747	0.99 ± 0.0550	0.99 ± 0.0074
horse	0.56 ± 0.0253	0.00 ± 0.0025	0.53 ± 0.0281	0.51 ± 0.0143	1.21 ± 0.0094	1.00 ± 0.0037
ship	0.57 ± 0.0543	0.00 ± 0.0010	0.58 ± 0.0350	0.53 ± 0.0561	0.97 ± 0.0611	0.93 ± 0.0758
truck	0.58 ± 0.0673	0.00 ± 0.0008	0.58 ± 0.0470	0.48 ± 0.0224	1.10 ± 0.0258	0.97 ± 0.0417
mean	0.55 ± 0.0473	0.00 ± 0.0022	0.55 ± 0.0336	0.51 ± 0.0315	1.16 ± 0.1195	0.97 ± 0.0287

	A	D	Explanation			
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
gray+one	0.96 ± 0.0037	0.17 ± 0.0127	0.55 ± 0.1105	0.75 ± 0.0429	0.75 ± 0.3352	0.96 ± 0.032
yellow+one	0.97 ± 0.0027	0.24 ± 0.0129	0.56 ± 0.0252	0.74 ± 0.0082	0.60 ± 0.1572	1.00 ± 0.000
cyan+one	0.96 ± 0.0138	0.19 ± 0.0373	0.54 ± 0.0410	0.83 ± 0.0180	0.38 ± 0.0340	1.00 ± 0.000
green+one	0.99 ± 0.0044	0.49 ± 0.0546	0.58 ± 0.0457	0.80 ± 0.0676	0.60 ± 0.2606	1.00 ± 0.000
blue+one	0.98 ± 0.0034	0.48 ± 0.0110	0.55 ± 0.0075	0.81 ± 0.0640	0.52 ± 0.1925	1.00 ± 0.000
pink+one	0.97 ± 0.0021	0.25 ± 0.0193	0.57 ± 0.0279	0.88 ± 0.0127	0.43 ± 0.0647	1.00 ± 0.000
red+one	0.98 ± 0.0031	0.42 ± 0.0364	0.54 ± 0.1100	0.83 ± 0.0938	0.69 ± 0.4817	1.00 ± 0.001
mean	0.97 ± 0.0101	0.32 ± 0.1265	0.56 ± 0.0154	0.81 ± 0.0451	0.57 ± 0.1240	0.99 ± 0.013

Table 11: AD and explanation performance averaged over 4 random seeds on C-MNIST for BCE (OE). Each row shows results for a different normal definition.

Table 12: AD and explanation performance averaged over 4 random seeds on C-MNIST for HSC (OE). Each row shows results for a different normal definition.

1257									
1258		A	D		Explanation				
1259	Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc		
1260	gray+one	0.92 ± 0.0075	0.27 ± 0.0410	0.51 ± 0.0486	0.76 ± 0.0457	0.86 ± 0.1567	0.99 ± 0.0136		
1061	yellow+one	0.94 ± 0.0251	0.43 ± 0.0509	0.54 ± 0.0615	0.82 ± 0.0081	0.82 ± 0.2713	1.00 ± 0.0020		
1201	cyan+one	0.97 ± 0.0196	0.39 ± 0.0630	0.56 ± 0.0296	0.88 ± 0.0462	0.63 ± 0.2201	1.00 ± 0.0000		
1262	green+one	0.98 ± 0.0139	0.52 ± 0.0258	0.56 ± 0.0323	0.89 ± 0.0102	0.94 ± 0.2280	1.00 ± 0.0005		
1263	blue+one	0.99 ± 0.0028	0.65 ± 0.0159	0.66 ± 0.0896	0.75 ± 0.1384	1.66 ± 1.1219	0.94 ± 0.0834		
106/	pink+one	0.94 ± 0.0139	0.38 ± 0.0323	0.52 ± 0.0751	0.83 ± 0.0339	0.83 ± 0.0292	1.00 ± 0.0015		
1204	red+one	0.98 ± 0.0031	0.60 ± 0.0127	0.57 ± 0.0244	0.78 ± 0.0674	0.93 ± 0.3331	1.00 ± 0.0055		
1265	mean	0.96 ± 0.0231	0.46 ± 0.1226	0.56 ± 0.0472	0.82 ± 0.0482	0.95 ± 0.3047	0.99 ± 0.0198		
1200									

Table 13: AD and explanation performance averaged over 4 random seeds on C-MNIST for DSVDD.Each row shows results for a different normal definition.

270									
1271		A	D		Explanation				
1272	Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc		
1973	gray+one	0.73 ± 0.0350	0.00 ± 0.0001	0.56 ± 0.0449	0.71 ± 0.0755	0.85 ± 0.2079	0.91 ± 0.0834		
1210	yellow+one	0.86 ± 0.0262	0.00 ± 0.0010	0.60 ± 0.0595	0.65 ± 0.0639	0.82 ± 0.2240	1.00 ± 0.0044		
1274	cyan+one	0.83 ± 0.0866	0.00 ± 0.0005	0.61 ± 0.0781	0.63 ± 0.0589	0.79 ± 0.0524	0.99 ± 0.0057		
1275	green+one	0.64 ± 0.1336	0.00 ± 0.0003	0.57 ± 0.0250	0.60 ± 0.0755	0.69 ± 0.0350	1.00 ± 0.0019		
1276	blue+one	0.78 ± 0.1502	0.00 ± 0.0001	0.68 ± 0.2173	0.42 ± 0.1223	1.01 ± 0.1866	1.00 ± 0.0016		
4077	pink+one	0.75 ± 0.1343	0.00 ± 0.0001	0.67 ± 0.1040	0.61 ± 0.0999	0.85 ± 0.0998	0.97 ± 0.0214		
1277	red+one	0.79 ± 0.0424	0.00 ± 0.0004	0.62 ± 0.0917	0.57 ± 0.1607	0.81 ± 0.1763	0.99 ± 0.0149		
1278	mean	0.77 ± 0.0650	0.00 ± 0.0003	0.61 ± 0.0430	0.60 ± 0.0841	0.83 ± 0.0875	0.98 ± 0.0297		

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
speed limit 30 + 50	0.92 ± 0.0037	0.65 ± 0.0103	0.51 ± 0.0563	0.88 ± 0.0158	0.77 ± 0.3590	1.00 ± 0.0018
speed limit $50 + 70$	0.88 ± 0.0151	0.59 ± 0.0188	0.49 ± 0.0576	0.86 ± 0.0066	0.69 ± 0.3249	0.99 ± 0.0080
speed limit $70 + 100$	0.88 ± 0.0053	0.57 ± 0.0048	0.55 ± 0.0708	0.89 ± 0.0136	0.42 ± 0.1348	0.99 ± 0.0130
speed limit 100 + 120	0.89 ± 0.0200	0.55 ± 0.0409	0.49 ± 0.1331	0.87 ± 0.0297	0.51 ± 0.0854	0.99 ± 0.0115
give way + stop	0.99 ± 0.0021	0.89 ± 0.0131	0.66 ± 0.0758	0.81 ± 0.1369	2.29 ± 0.4255	0.99 ± 0.0184
danger + construction warning	0.93 ± 0.0078	0.73 ± 0.0072	0.43 ± 0.0799	0.91 ± 0.0155	3.60 ± 0.5202	1.00 ± 0.0040
all restriction ends signs	1.00 ± 0.0029	0.90 ± 0.0167	0.56 ± 0.1341	1.00 ± 0.0033	0.24 ± 0.1129	0.97 ± 0.0183
all speed limit signs	0.99 ± 0.0016	0.79 ± 0.0226	0.54 ± 0.0172	0.96 ± 0.0085	0.41 ± 0.0870	0.99 ± 0.0134
all blue signs	1.00 ± 0.0023	0.93 ± 0.0131	0.40 ± 0.0381	0.90 ± 0.0258	0.64 ± 0.1553	0.98 ± 0.0109
all warning signs	0.96 ± 0.0089	0.89 ± 0.0132	0.38 ± 0.0343	0.95 ± 0.0035	1.51 ± 0.5426	0.99 ± 0.0076
mean	0.94 ± 0.0474	0.75 ± 0.1437	0.50 ± 0.0803	0.90 ± 0.0526	1.11 ± 1.0182	0.99 ± 0.0083

Table 14: AD and explanation performance averaged over 4 random seeds on GTSDB for BCE OE.Each row shows results for a different normal definition.

Table 15: AD and explanation performance averaged over 4 random seeds on GTSDB for HSC OE.Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept A
speed limit 30 + 50	0.88 ± 0.0014	0.63 ± 0.0126	0.31 ± 0.1032	0.88 ± 0.0113	0.79 ± 0.2196	0.96 ± 0.0
speed limit 50 + 70	0.89 ± 0.0111	0.57 ± 0.0170	0.49 ± 0.1537	0.85 ± 0.0135	1.45 ± 0.6565	1.00 ± 0.0
speed limit $70 + 100$	0.86 ± 0.0164	0.56 ± 0.0146	0.60 ± 0.1389	0.85 ± 0.0379	0.69 ± 0.4033	0.91 ± 0.0
speed limit 100 + 120	0.85 ± 0.0112	0.50 ± 0.0132	0.66 ± 0.0952	0.86 ± 0.0172	0.59 ± 0.2818	0.95 ± 0.0
give way + stop	0.98 ± 0.0056	0.81 ± 0.0415	0.70 ± 0.1508	0.83 ± 0.0929	1.00 ± 0.1991	0.70 ± 0.0
danger + construction warning	0.91 ± 0.0099	0.68 ± 0.0121	0.32 ± 0.0889	0.90 ± 0.0137	2.82 ± 0.2851	0.97 ± 0.0
all restriction ends signs	1.00 ± 0.0000	0.93 ± 0.0127	0.60 ± 0.0791	1.00 ± 0.0039	0.21 ± 0.0519	0.94 ± 0.0
all speed limit signs	0.96 ± 0.0174	0.79 ± 0.0075	0.51 ± 0.0419	0.95 ± 0.0175	0.29 ± 0.0730	0.97 ± 0.0
all blue signs	1.00 ± 0.0011	0.94 ± 0.0165	0.34 ± 0.0640	0.91 ± 0.0224	0.38 ± 0.0667	1.00 ± 0.0
all warning signs	0.97 ± 0.0042	0.86 ± 0.0182	0.33 ± 0.0692	0.96 ± 0.0061	1.31 ± 0.2118	1.00 ± 0.0
mean	0.93 ± 0.0563	0.73 ± 0.1517	0.49 ± 0.1439	0.90 ± 0.0508	0.95 ± 0.7345	0.94 ± 0.0

Table 16: AD and explanation performance averaged over 4 random seeds on GTSDB for DSVDD.Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept A
speed limit 30 + 50	0.53 ± 0.0718	0.06 ± 0.0214	0.56 ± 0.0583	0.57 ± 0.0240	1.07 ± 0.4804	0.95 ± 0.04
speed limit 50 + 70	0.55 ± 0.0487	0.07 ± 0.0640	0.60 ± 0.1042	0.57 ± 0.0485	3.59 ± 3.8551	0.87 ± 0.1
speed limit 70 + 100	0.56 ± 0.0433	0.02 ± 0.0108	0.53 ± 0.1288	0.63 ± 0.0291	0.34 ± 0.0187	0.92 ± 0.0
speed limit 100 + 120	0.61 ± 0.0497	0.04 ± 0.0171	0.53 ± 0.0625	0.64 ± 0.0488	0.28 ± 0.0315	0.95 ± 0.0
give way + stop	0.49 ± 0.0673	0.00 ± 0.0150	0.46 ± 0.0981	0.49 ± 0.0725	1.88 ± 0.5662	0.98 ± 0.0
danger + construction warning	0.61 ± 0.0429	0.02 ± 0.0049	0.59 ± 0.0402	0.47 ± 0.0348	3.04 ± 0.3589	0.90 ± 0.1
all restriction ends signs	0.70 ± 0.0860	0.06 ± 0.0450	0.53 ± 0.1242	0.69 ± 0.0862	0.26 ± 0.1251	0.94 ± 0.0
all speed limit signs	0.69 ± 0.0473	0.05 ± 0.0095	0.57 ± 0.0533	0.64 ± 0.0145	0.51 ± 0.1984	0.98 ± 0.0
all blue signs	0.51 ± 0.1008	0.02 ± 0.0161	0.49 ± 0.0985	0.64 ± 0.0117	0.20 ± 0.0484	0.86 ± 0.0
all warning signs	0.56 ± 0.0242	0.01 ± 0.0087	0.46 ± 0.0616	0.51 ± 0.0484	1.93 ± 0.5590	1.00 ± 0.0
mean	0.58 ± 0.0668	0.04 ± 0.0233	0.53 ± 0.0478	0.58 ± 0.0699	1.31 ± 1.1807	0.93 ± 0.0

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
zero+one	0.97 ± 0.0062	0.51 ± 0.0596	0.79 ± 0.0864	0.45 ± 0.0944	1.00 ± 0.0674	0.98 ± 0.0154
zero+two	0.95 ± 0.0129	0.44 ± 0.0694	0.82 ± 0.0696	0.59 ± 0.0292	0.77 ± 0.0372	0.95 ± 0.0520
one+two	0.94 ± 0.0188	0.46 ± 0.0688	0.74 ± 0.0251	0.40 ± 0.0411	1.25 ± 0.0237	0.99 ± 0.0101
one+three	0.95 ± 0.0097	0.45 ± 0.0222	0.70 ± 0.0433	0.56 ± 0.0241	1.18 ± 0.0250	0.97 ± 0.0192
two+three	0.97 ± 0.0095	0.56 ± 0.0667	0.76 ± 0.0720	0.79 ± 0.0188	0.51 ± 0.0498	0.99 ± 0.0131
two+four	0.89 ± 0.0196	0.35 ± 0.0551	0.75 ± 0.0415	0.42 ± 0.0421	0.83 ± 0.0824	1.00 ± 0.0017
three+four	0.91 ± 0.0070	0.33 ± 0.0250	0.81 ± 0.0290	0.58 ± 0.0415	0.85 ± 0.0359	0.93 ± 0.0687
three+five	0.95 ± 0.0058	0.48 ± 0.0487	0.74 ± 0.0213	0.67 ± 0.0515	0.43 ± 0.0501	0.95 ± 0.0360
four+five	0.90 ± 0.0259	0.30 ± 0.0148	0.83 ± 0.0474	0.40 ± 0.0485	0.92 ± 0.0715	0.82 ± 0.1926
four+six	0.95 ± 0.0052	0.57 ± 0.0364	0.77 ± 0.0333	0.63 ± 0.0650	0.67 ± 0.1253	0.98 ± 0.0277
five+six	0.97 ± 0.0063	0.60 ± 0.0319	0.82 ± 0.0672	0.63 ± 0.0514	0.55 ± 0.0666	$0.91 \pm 0.079^{\circ}$
five+seven	0.88 ± 0.0228	0.40 ± 0.0453	0.76 ± 0.0546	0.59 ± 0.0416	1.02 ± 0.0697	0.94 ± 0.036
six+seven	0.94 ± 0.0143	0.44 ± 0.0618	0.85 ± 0.0437	0.66 ± 0.0622	0.92 ± 0.1281	0.82 ± 0.143
six+eight	0.95 ± 0.0145	0.45 ± 0.0398	0.81 ± 0.0474	0.63 ± 0.0608	0.38 ± 0.0205	0.96 ± 0.0539
seven+eight	0.87 ± 0.0208	0.33 ± 0.0300	0.73 ± 0.0562	0.70 ± 0.0264	0.90 ± 0.0669	0.91 ± 0.0793
seven+nine	0.95 ± 0.0209	0.58 ± 0.0374	0.77 ± 0.0628	0.88 ± 0.0201	0.94 ± 0.1804	0.86 ± 0.1010
eight+nine	0.93 ± 0.0189	0.42 ± 0.0492	0.80 ± 0.0483	0.83 ± 0.0144	0.48 ± 0.0423	0.93 ± 0.105
eight+zero	0.93 ± 0.0100	0.39 ± 0.0219	0.77 ± 0.0908	0.69 ± 0.0240	0.46 ± 0.0200	0.98 ± 0.017
nine+zero	0.95 ± 0.0047	0.49 ± 0.0184	0.85 ± 0.0398	0.77 ± 0.0424	0.54 ± 0.0610	0.92 ± 0.067
nine+one	0.93 ± 0.0157	0.39 ± 0.0365	0.73 ± 0.0944	0.57 ± 0.0461	1.09 ± 0.0559	0.97 ± 0.019
mean	0.93 ± 0.0283	0.45 ± 0.0868	0.78 ± 0.0412	0.62 ± 0.1325	0.78 ± 0.2596	0.94 ± 0.0512

Table 17: AD and explanation performance averaged over 4 random seeds on MNIST for BCE (OE).
 Each row shows results for a different normal definition.

Table 18: AD and explanation performance averaged over 4 random seeds on MNIST for HSC (OE).Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
zero+one	0.98 ± 0.0056	0.53 ± 0.0871	0.88 ± 0.0450	0.46 ± 0.0714	1.13 ± 0.0433	0.92 ± 0.1256
zero+two	0.95 ± 0.0120	0.52 ± 0.0508	0.87 ± 0.0267	0.39 ± 0.0644	0.96 ± 0.0884	0.94 ± 0.0697
one+two	0.96 ± 0.0061	0.48 ± 0.0493	0.83 ± 0.0163	0.46 ± 0.1134	1.23 ± 0.0469	0.95 ± 0.0382
one+three	0.95 ± 0.0081	0.51 ± 0.0142	0.84 ± 0.0519	0.55 ± 0.0545	1.24 ± 0.0717	0.85 ± 0.2038
two+three	0.95 ± 0.0116	0.58 ± 0.0371	0.74 ± 0.0500	0.59 ± 0.0706	0.73 ± 0.1404	0.87 ± 0.1477
two+four	0.86 ± 0.0132	0.33 ± 0.0276	0.77 ± 0.0338	0.39 ± 0.0131	0.92 ± 0.0227	0.98 ± 0.0168
three+four	0.87 ± 0.0190	0.34 ± 0.0472	0.73 ± 0.0515	0.55 ± 0.0355	0.87 ± 0.0564	0.87 ± 0.112
three+five	0.93 ± 0.0294	0.50 ± 0.0450	0.80 ± 0.0902	0.54 ± 0.0523	0.54 ± 0.0908	0.85 ± 0.127
four+five	0.87 ± 0.0160	0.33 ± 0.0228	0.86 ± 0.0449	0.42 ± 0.0571	1.35 ± 0.4027	0.58 ± 0.042
four+six	0.95 ± 0.0128	0.55 ± 0.0598	0.82 ± 0.0360	0.50 ± 0.1191	0.82 ± 0.0307	0.97 ± 0.022
five+six	0.95 ± 0.0058	0.57 ± 0.0471	0.83 ± 0.0505	0.54 ± 0.0711	1.03 ± 0.3435	0.83 ± 0.067
five+seven	0.89 ± 0.0022	0.40 ± 0.0223	0.83 ± 0.0281	0.58 ± 0.0241	1.33 ± 0.2102	0.80 ± 0.132
six+seven	0.92 ± 0.0166	0.43 ± 0.0602	0.81 ± 0.0535	0.54 ± 0.0695	1.02 ± 0.3005	0.87 ± 0.085
six+eight	0.94 ± 0.0031	0.44 ± 0.0373	0.81 ± 0.0184	0.51 ± 0.0417	0.51 ± 0.1461	0.88 ± 0.091
seven+eight	0.90 ± 0.0090	0.42 ± 0.0328	0.78 ± 0.0331	0.66 ± 0.0287	1.14 ± 0.0710	0.91 ± 0.086
seven+nine	0.96 ± 0.0034	0.63 ± 0.0163	0.85 ± 0.0637	0.81 ± 0.0430	1.17 ± 0.2448	0.65 ± 0.201
eight+nine	0.93 ± 0.0049	0.44 ± 0.0268	0.83 ± 0.0483	0.69 ± 0.0317	0.67 ± 0.1301	0.87 ± 0.190
eight+zero	0.93 ± 0.0075	0.44 ± 0.0215	0.83 ± 0.0602	0.55 ± 0.0547	0.80 ± 0.4024	0.85 ± 0.116
nine+zero	0.94 ± 0.0052	0.48 ± 0.0601	0.85 ± 0.0379	0.61 ± 0.0466	0.65 ± 0.0405	0.77 ± 0.148
nine+one	0.95 ± 0.0119	0.44 ± 0.0212	0.83 ± 0.0464	0.60 ± 0.0340	1.13 ± 0.0206	0.92 ± 0.067
mean	0.93 ± 0.0332	0.47 ± 0.0809	0.82 ± 0.0378	0.55 ± 0.0987	0.96 ± 0.2502	0.86 ± 0.096

Each row shows results for a different normal definition.

1404 1405

1406

1407 1408

1409

1410 AD Explanation AuROC CF AuROC Normal Score distance Sub. AuROC FID_N Concept Acc 1411 0.57 ± 0.0150 1412 zero+one 0.93 ± 0.0323 0.00 ± 0.0018 0.90 ± 0.0393 1.05 ± 0.1323 0.97 ± 0.0254 0.36 ± 0.0439 0.71 ± 0.1290 0.00 ± 0.0015 0.70 ± 0.1319 0.99 ± 0.0301 0.54 ± 0.2298 zero+two 1413 0.38 ± 0.0584 0.92 ± 0.0666 one+two 0.73 ± 0.0542 0.00 ± 0.0003 0.73 ± 0.0648 1.16 ± 0.0277 1414 0.77 ± 0.0422 0.00 ± 0.0002 0.78 ± 0.0470 0.43 ± 0.1285 1.13 ± 0.0103 0.87 ± 0.1073 one+three 0.38 ± 0.1011 0.81 ± 0.2033 0.69 ± 0.0508 0.67 ± 0.0495 0.86 ± 0.0373 0.00 ± 0.0015 1415 two+three two+four 0.85 ± 0.0253 0.00 ± 0.0009 0.80 ± 0.0380 0.39 ± 0.0484 0.75 ± 0.1440 0.85 ± 0.2204 1416 0.00 ± 0.0015 0.77 ± 0.0716 0.73 ± 0.0736 0.46 ± 0.0377 0.92 ± 0.0610 three+four 0.72 ± 0.2467 1417 three+five 0.66 ± 0.0275 0.00 ± 0.0003 0.66 ± 0.0346 0.43 ± 0.0459 0.86 ± 0.0218 0.76 ± 0.1619 1418 four+five 0.71 ± 0.1077 0.00 ± 0.0026 0.70 ± 0.0907 0.41 ± 0.0192 0.98 ± 0.0285 0.71 ± 0.0798 four+six 0.81 ± 0.0719 0.01 ± 0.0037 0.80 ± 0.0915 0.37 ± 0.0288 1.03 ± 0.0127 0.86 ± 0.1675 1419 five+six 0.72 ± 0.0814 0.00 ± 0.0028 0.70 ± 0.0749 0.41 ± 0.0568 0.93 ± 0.0151 0.73 ± 0.1704 1420 0.44 ± 0.0658 0.96 ± 0.0983 0.85 ± 0.1442 0.69 ± 0.0281 0.72 ± 0.0564 0.00 ± 0.0009 five+seven 1421 six+seven 0.84 ± 0.0609 0.00 ± 0.0015 0.79 ± 0.0271 0.41 ± 0.0469 1.13 ± 0.0494 0.94 ± 0.0260 0.78 ± 0.0681 0.00 ± 0.0013 0.75 ± 0.0787 0.44 ± 0.0241 0.93 ± 0.1650 0.79 ± 0.1834 six+eight 1422 seven+eight 0.70 ± 0.0095 0.00 ± 0.0002 0.70 ± 0.0046 0.39 ± 0.0721 1.12 ± 0.0105 0.95 ± 0.0364 1423 0.74 ± 0.0744 0.75 ± 0.0758 0.38 ± 0.0345 1.10 ± 0.0419 0.00 ± 0.0020 0.72 ± 0.1768 seven+nine 1424 0.69 ± 0.0688 0.00 ± 0.0006 0.68 ± 0.0712 0.42 ± 0.0329 0.95 ± 0.1594 0.97 ± 0.0480 eight+nine 0.00 ± 0.0009 0.65 ± 0.0630 0.37 ± 0.0299 1.05 ± 0.0253 eight+zero 0.66 ± 0.0560 0.82 ± 0.1814 1425 nine+zero 0.72 ± 0.0834 0.00 ± 0.0016 0.67 ± 0.1228 0.46 ± 0.0408 0.99 ± 0.1008 0.65 ± 0.3174 1426 0.84 ± 0.0555 0.85 ± 0.0489 0.42 ± 0.1575 1.13 ± 0.0173 0.91 ± 0.0509 nine+one 0.00 ± 0.0010 1427 0.00 ± 0.0013 0.73 ± 0.0649 0.42 ± 0.0450 1.00 ± 0.1074 mean 0.75 ± 0.0712 0.82 ± 0.1132 1428

Table 19: AD and explanation performance averaged over 4 random seeds on MNIST for DSVDD.

1429

1430

1431

1432 1433

1434

Table 20: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for BCE OE.
Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Ac
airplane+automobile	0.96 ± 0.0024	0.79 ± 0.0066	0.59 ± 0.0300	0.66 ± 0.0187	1.04 ± 0.0824	0.75 ± 0.106
airplane+bird	0.92 ± 0.0017	0.68 ± 0.0043	0.45 ± 0.0226	0.61 ± 0.0087	1.34 ± 0.2551	0.88 ± 0.11
automobile+bird	0.93 ± 0.0023	0.70 ± 0.0029	0.57 ± 0.0340	0.59 ± 0.0264	1.79 ± 0.0164	0.73 ± 0.20
automobile+cat	0.90 ± 0.0038	0.61 ± 0.0005	0.46 ± 0.0113	0.54 ± 0.0060	1.73 ± 0.0686	0.87 ± 0.07
bird+cat	0.87 ± 0.0022	0.53 ± 0.0019	0.35 ± 0.0207	0.54 ± 0.0140	1.19 ± 0.1377	0.81 ± 0.112
bird+deer	0.92 ± 0.0004	0.64 ± 0.0046	0.39 ± 0.0233	0.53 ± 0.0069	0.92 ± 0.0889	0.97 ± 0.003
cat+deer	0.90 ± 0.0025	0.58 ± 0.0077	0.39 ± 0.0301	0.53 ± 0.0148	0.94 ± 0.0475	0.89 ± 0.15
cat+dog	0.91 ± 0.0023	0.59 ± 0.0108	0.30 ± 0.0103	0.58 ± 0.0099	0.91 ± 0.0472	0.81 ± 0.15
deer+dog	0.92 ± 0.0006	0.64 ± 0.0040	0.42 ± 0.0333	0.55 ± 0.0137	0.88 ± 0.0511	0.93 ± 0.04
deer+frog	0.94 ± 0.0014	0.70 ± 0.0042	0.49 ± 0.0381	0.52 ± 0.0124	0.76 ± 0.0422	0.82 ± 0.19
dog+frog	0.93 ± 0.0010	0.67 ± 0.0053	0.46 ± 0.0181	0.56 ± 0.0121	0.93 ± 0.0769	0.94 ± 0.05
dog+horse	0.95 ± 0.0022	0.71 ± 0.0056	0.50 ± 0.0085	0.58 ± 0.0106	1.01 ± 0.0391	0.89 ± 0.13
frog+horse	0.96 ± 0.0007	0.76 ± 0.0080	0.55 ± 0.0314	0.56 ± 0.0170	1.03 ± 0.0501	0.81 ± 0.17
frog+ship	0.95 ± 0.0010	0.76 ± 0.0046	0.53 ± 0.0225	0.62 ± 0.0188	1.06 ± 0.2823	0.88 ± 0.08
horse+ship	0.97 ± 0.0010	0.80 ± 0.0047	0.58 ± 0.0259	0.61 ± 0.0420	0.95 ± 0.1126	0.97 ± 0.03
horse+truck	0.96 ± 0.0008	0.77 ± 0.0046	0.56 ± 0.0293	0.60 ± 0.0195	1.08 ± 0.0864	0.87 ± 0.18
ship+truck	0.96 ± 0.0011	0.77 ± 0.0059	0.54 ± 0.0200	0.62 ± 0.0171	0.78 ± 0.0594	0.93 ± 0.11
ship+airplane	0.97 ± 0.0008	0.80 ± 0.0044	0.52 ± 0.0392	0.71 ± 0.0113	0.77 ± 0.1048	0.97 ± 0.04
truck+airplane	0.95 ± 0.0008	0.75 ± 0.0027	0.55 ± 0.0137	0.61 ± 0.0370	0.93 ± 0.0557	0.73 ± 0.14
truck+automobile	0.98 ± 0.0010	0.85 ± 0.0041	0.62 ± 0.0429	0.60 ± 0.0240	0.75 ± 0.0793	0.80 ± 0.19
mean	0.94 ± 0.0266	0.71 ± 0.0839	0.49 ± 0.0847	0.59 ± 0.0460	1.04 ± 0.2794	0.86 ± 0.07

1456

Table 21: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for HSC OE. Each row shows results for a different normal definition.

1464		A	D		Expla	nation	
1465	Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
1466	airplane+automobile	0.96 ± 0.0005	0.75 ± 0.0017	0.51 ± 0.0900	0.54 ± 0.0163	2.14 ± 0.0882	0.99 ± 0.0164
1467	airplane+bird	0.93 ± 0.0012	0.67 ± 0.0024	0.44 ± 0.0439	0.52 ± 0.0059	2.21 ± 0.1630	1.00 ± 0.0002
1400	automobile+bird	0.92 ± 0.0029	0.66 ± 0.0065	0.45 ± 0.0424	0.51 ± 0.0065	4.12 ± 1.1471	1.00 ± 0.0001
1468	automobile+cat	0.91 ± 0.0011	0.62 ± 0.0054	0.53 ± 0.0285	0.50 ± 0.0023	3.10 ± 0.3450	1.00 ± 0.0011
1469	bird+cat	0.87 ± 0.0019	0.47 ± 0.0046	0.32 ± 0.0328	0.53 ± 0.0401	3.34 ± 1.0615	1.00 ± 0.0002
1/170	bird+deer	0.92 ± 0.0026	0.63 ± 0.0097	0.38 ± 0.0144	0.54 ± 0.0248	3.49 ± 0.1061	1.00 ± 0.0012
1470	cat+deer	0.90 ± 0.0017	0.54 ± 0.0053	0.35 ± 0.0228	0.52 ± 0.0166	2.58 ± 0.1145	1.00 ± 0.0000
1471	cat+dog	0.93 ± 0.0018	0.59 ± 0.0085	0.39 ± 0.0252	0.52 ± 0.0042	1.97 ± 0.0935	1.00 ± 0.0003
1472	deer+dog	0.92 ± 0.0017	0.60 ± 0.0095	0.38 ± 0.0401	0.52 ± 0.0107	2.44 ± 0.5742	0.96 ± 0.0734
1 4 7 0	deer+frog	0.95 ± 0.0011	0.68 ± 0.0010	0.42 ± 0.0065	0.56 ± 0.0535	2.27 ± 0.0879	1.00 ± 0.0002
1473	dog+frog	0.93 ± 0.0014	0.63 ± 0.0045	0.43 ± 0.0110	0.51 ± 0.0036	2.53 ± 0.1879	1.00 ± 0.0001
1474	dog+horse	0.96 ± 0.0003	0.70 ± 0.0064	0.44 ± 0.0062	0.52 ± 0.0190	3.22 ± 0.1861	1.00 ± 0.0001
1/175	frog+horse	0.96 ± 0.0015	0.73 ± 0.0027	0.48 ± 0.0143	0.52 ± 0.0176	2.75 ± 0.3541	1.00 ± 0.0001
1475	frog+ship	0.96 ± 0.0009	0.75 ± 0.0084	0.48 ± 0.0313	0.56 ± 0.0346	3.29 ± 0.6680	1.00 ± 0.0001
1476	horse+ship	0.96 ± 0.0007	0.77 ± 0.0036	0.40 ± 0.0675	0.53 ± 0.0124	1.87 ± 0.0485	1.00 ± 0.0005
1477	horse+truck	0.95 ± 0.0016	0.73 ± 0.0074	0.50 ± 0.0339	0.53 ± 0.0520	2.93 ± 0.8821	1.00 ± 0.0011
4.470	ship+truck	0.96 ± 0.0005	0.76 ± 0.0051	0.41 ± 0.0426	0.57 ± 0.0625	1.73 ± 0.0526	0.99 ± 0.0075
1478	ship+airplane	0.97 ± 0.0013	0.80 ± 0.0037	0.53 ± 0.0811	0.55 ± 0.0359	1.65 ± 0.2366	0.98 ± 0.0247
1479	truck+airplane	0.95 ± 0.0020	0.72 ± 0.0041	0.46 ± 0.0542	0.53 ± 0.0176	1.85 ± 0.1448	0.97 ± 0.0579
1480	truck+automobile	0.99 ± 0.0004	0.85 ± 0.0067	0.60 ± 0.0790	0.53 ± 0.0340	1.49 ± 0.1063	0.90 ± 0.1301
1481	mean	0.94 ± 0.0270	0.68 ± 0.0883	0.44 ± 0.0666	0.53 ± 0.0175	2.55 ± 0.6970	0.99 ± 0.0244

1	4	9	ļ
1	4	9	4

Table 22: AD and explanation performance averaged over 4 random seeds on CIFAR-10 for DSVDD. Each row shows results for a different normal definition.

	A	D		Expla	nation	
Normal	AuROC	Score distance	CF AuROC	Sub. AuROC	FID_N	Concept Acc
airplane+automobile	0.50 ± 0.0357	0.00 ± 0.0002	0.48 ± 0.0517	0.46 ± 0.0260	1.20 ± 0.0111	0.84 ± 0.1424
airplane+bird	0.49 ± 0.0111	0.00 ± 0.0005	0.46 ± 0.0219	0.49 ± 0.0448	1.27 ± 0.0950	0.93 ± 0.0503
automobile+bird	0.49 ± 0.0145	0.00 ± 0.0002	0.49 ± 0.0081	0.49 ± 0.0184	1.23 ± 0.0524	0.93 ± 0.0859
automobile+cat	0.50 ± 0.0148	0.00 ± 0.0007	0.48 ± 0.0153	0.47 ± 0.0251	1.22 ± 0.0567	0.90 ± 0.0745
bird+cat	0.53 ± 0.0162	0.00 ± 0.0003	0.51 ± 0.0344	0.50 ± 0.0033	1.08 ± 0.0223	0.98 ± 0.0223
bird+deer	0.56 ± 0.0278	0.00 ± 0.0003	0.54 ± 0.0345	0.51 ± 0.0122	0.97 ± 0.0304	0.97 ± 0.0183
cat+deer	0.56 ± 0.0418	0.00 ± 0.0008	0.54 ± 0.0486	0.53 ± 0.0228	1.02 ± 0.0201	0.95 ± 0.0201
cat+dog	0.52 ± 0.0105	0.00 ± 0.0011	0.49 ± 0.0332	0.49 ± 0.0148	1.06 ± 0.0168	0.91 ± 0.0690
deer+dog	0.55 ± 0.0213	0.00 ± 0.0030	0.51 ± 0.0377	0.53 ± 0.0211	1.10 ± 0.0348	0.89 ± 0.1620
deer+frog	0.57 ± 0.1151	0.01 ± 0.0046	0.53 ± 0.1167	0.59 ± 0.0516	0.87 ± 0.0342	0.93 ± 0.0919
dog+frog	0.60 ± 0.0431	0.00 ± 0.0034	0.60 ± 0.0514	0.53 ± 0.0323	0.95 ± 0.0188	0.87 ± 0.0848
dog+horse	0.53 ± 0.0102	0.00 ± 0.0006	0.49 ± 0.0408	0.49 ± 0.0178	1.17 ± 0.0254	0.92 ± 0.0427
frog+horse	0.60 ± 0.0398	0.01 ± 0.0048	0.56 ± 0.0160	0.57 ± 0.0228	1.07 ± 0.0079	0.99 ± 0.0030
frog+ship	0.52 ± 0.0144	0.00 ± 0.0004	0.50 ± 0.0326	0.53 ± 0.0188	1.08 ± 0.0331	0.97 ± 0.0261
horse+ship	0.49 ± 0.0374	0.00 ± 0.0002	0.48 ± 0.0409	0.48 ± 0.0077	1.17 ± 0.0563	0.96 ± 0.0209
horse+truck	0.50 ± 0.0346	0.00 ± 0.0006	0.51 ± 0.0287	0.46 ± 0.0147	1.21 ± 0.0579	0.88 ± 0.1041
ship+truck	0.47 ± 0.0265	0.00 ± 0.0003	0.49 ± 0.0195	0.46 ± 0.0201	1.05 ± 0.0330	0.96 ± 0.0365
ship+airplane	0.50 ± 0.0246	0.00 ± 0.0002	0.48 ± 0.0400	0.42 ± 0.0326	1.10 ± 0.0722	0.87 ± 0.1070
truck+airplane	0.48 ± 0.0545	0.00 ± 0.0004	0.48 ± 0.0460	0.46 ± 0.0205	1.15 ± 0.0309	0.94 ± 0.0497
truck+automobile	0.51 ± 0.0279	0.00 ± 0.0009	0.52 ± 0.0356	0.45 ± 0.0143	1.06 ± 0.0331	0.86 ± 0.1105
mean	0.53 ± 0.0356	0.00 ± 0.0023	0.51 ± 0.0332	0.50 ± 0.0414	1.10 ± 0.0998	0.92 ± 0.0424

1515		AD		Expl	anation	
1516	Normal	AuROC	CF AuROC	Sub. AuROC	FID_N	Concept Acc
1517	airliner	96.63 ± 0.22	76.32 ± 0.82	65.01 ± 4.57	95.75 ± 9.65	99.70 ± 0.20
1518	ambulance	98.23 ± 0.03	83.91 ± 2.48	63.52 ± 4.41	105.45 ± 4.33	99.85 ± 0.15
1519	black widow	90.31 ± 0.41	68.64 ± 4.25	56.22 ± 5.19	100.86 ± 20.66	86.20 ± 11.40
1520	lion	84.00 ± 0.07	34.38 ± 1.10	61.97 ± 0.11	94.49 ± 7.87	100.00 ± 0.00
1521	zebra	98.97 ± 0.02	82.16 ± 0.65	49.16 ± 8.66	28.29 ± 0.43	99.00 ± 0.70
1522	mean	93.63 ± 5.70	69.08 ± 18.15	59.18 ± 5.83	84.97 ± 28.61	96.95 ± 5.39

Table 23: AD and explanation performance averaged over 2 random seeds on ImageNet-Neighbors
 for BCE (OE). Each row shows results for a different normal definition.

1525Table 24: AD and explanation performance averaged over 2 random seeds on ImageNet-Neighbors1526for HSC (OE). Each row shows results for a different normal definition.

	AD		Expla	nation	
Normal	AuROC	CF AuROC	Sub. AuROC	FID_N	Concept Acc
airliner	96.70 ± 0.04	83.04 ± 0.32	37.43 ± 0.32	80.26 ± 2.12	97.30 ± 2.10
ambulance	97.82 ± 0.01	83.42 ± 0.67	51.84 ± 17.77	104.30 ± 2.86	99.95 ± 0.05
black widow	88.20 ± 0.20	59.68 ± 0.52	55.09 ± 1.12	120.69 ± 10.51	99.60 ± 0.40
lion	81.35 ± 0.74	49.83 ± 7.35	49.20 ± 5.02	70.58 ± 11.86	97.85 ± 1.85
zebra	98.78 ± 0.02	63.84 ± 3.86	71.63 ± 1.02	51.17 ± 6.16	99.70 ± 0.31
mean	92.57 ± 6.76	67.96 ± 13.27	53.04 ± 11.04	85.40 ± 24.58	98.88 ± 1.09

Η RANDOM COLLECTION OF GENERATED COUNTERFACTUAL EXAMPLES

In the main paper, we proposed a method to generate counterfactual explanations (CEs) for deep AD. We demonstrated their effectiveness by showing a small fraction of the generated CEs in Section 4.2. Here, we show a larger collection of CEs for all normal definitions. For each normal definition, we randomly selected two samples to serve as examples. Figures 10, 11, and 12 show CEs for Colored-MNIST (C-MNIST) and an AD trained with BCE, HSC, and DSVDD, respectively.



Figure 10: CEs for Col-MNIST and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and CE generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 11: CEs for Col-MNIST and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and CE generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 12: CEs for Col-MNIST and an anomaly detector trained with DSVDD. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.

Figures 13, 14, and 15 show CEs for MNIST, single classes being normal, and an AD trained with BCE, HSC, and DSVDD, respectively.



Figure 13: CEs for MNIST, diverse single normal classes, and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding single normal class at the top.

5	5	8	9	4	0	4	three	6	5	6	6	4	six	seven	3	6	Ø	8	
: 0	Ø	1	Ĵ	4	0	3	3	6	4	6	G	ų	6	1	3	0	Ø	8	9
8	в	1	ł	đ	0	3	3	4	ч	6	6	4	6	7	3	6	Ø	Г	9

Figure 14: CEs for MNIST, diverse single normal classes, and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding single normal class at the top.

zero+one	zero+one	one	one	two	two	three	three	four	four	five	five	six	six	seven	seven	eight	eight	nine	nine
4	φ	Q	2	2	/	9	6	0	1	0	0	S	4	6	З	6	١	Г	2
:4	φ	\mathcal{O}	4	2	/	9	b	0	1	٥	0	8	4	6	З	6	١	q	2
ĕ ∕)	ł	Ľ,	7	?	1	9	ь	Ľ	4	3	0	G	4	6	3	6	30	Г	2

Figure 15: CEs for MNIST, diverse single normal classes, and an anomaly detector trained with DSVDD. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding single normal class at the top.



Figures 16, 17, and 18 show CEs for CIFAR-10, single classes being normal, and an AD trained with BCE, HSC, and DSVDD, respectively.



Figure 16: CEs for CIFAR-10, diverse single normal classes, and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding single normal class at the top.



Figure 17: CEs for CIFAR-10, diverse single normal classes, and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding single normal class at the top.

plane	plane	car	car	bird	bird	cat	cat	deer	deer	dog	dog	frog	frog	horse	horse	ship	ship	truck	truck
wow		4	*	-				(0)	50	i h	-		14	*	(T)	M	Ĥ	X	
CE 0		F	4	-		12		-	5	1	in.		al (1	dif.		ŵ	X	
CE I	4	4	*	-		Pr		-	7	6	A	Section of		-			*		

Figure 18: CEs for CIFAR-10, diverse single normal classes, and an anomaly detector trained with
DSVDD. For each normal definition, a different detector and counterfactual generator was trained. In
each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two
different concepts. Each column is labeled with the corresponding single normal class at the top.





Figures 19, 20, and 21 show CEs for MNIST, class combinations being normal, and an AD trained with BCE, HSC, and DSVDD, respectively.

Figure 19: CEs for MNIST, diverse combined normal classes, and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 20: CEs for MNIST, diverse combined normal classes, and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 21: CEs for MNIST, diverse combined normal classes, and an anomaly detector trained with DSVDD. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 22: CEs for CIFAR-10, diverse combined normal classes, and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 23: CEs for CIFAR-10, diverse combined normal classes, and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figures 25 and 26 show the CEs for ImageNet-Neighbors, with single classes being normal, and an AD trained with BCE and HSC, respectively.



Figure 25: CEs for ImageNet-Neighbors, single normal classes, and an anomaly detector trained with BCE (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding normal class at the top.



Figure 26: CEs for ImageNet-Neighbors, single normal classes, and an anomaly detector trained with HSC (OE). For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding normal class at the top.

Figures 27, 28, and 29 show CEs for GTSDB, class combinations being normal, and an AD trained with BCE, HSC, and DSVDD, respectively.



Figure 27: CEs for GTSDB and an anomaly detector trained with BCE OE. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 28: CEs for GTSDB and an anomaly detector trained with HSC OE. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.



Figure 29: CEs for GTSDB and an anomaly detector trained with DSVDD. For each normal definition, a different detector and counterfactual generator was trained. In each subfigure, the first row shows anomalies, the other two corresponding counterfactuals for two different concepts. Each column is labeled with the corresponding combined normal class at the top.

