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# AnimateQR: Bridging Aesthetics and Functionality in Dynamic QR Code Generation

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## Abstract

Animated QR codes present an exciting frontier for dynamic content delivery and digital interaction. However, despite their potential, there has been no prior work focusing on the generation of animated QR codes that are both visually appealing and universally scannable. In this paper, we introduce AnimateQR, **the first generative framework** for creating **animated QR codes** that balance aesthetic flexibility with scannability. Unlike previous methods that focus on static QR codes, AnimateQR leverages **hierarchical luminance guidance** and **progressive spatiotemporal control** to produce high-quality dynamic QR codes. Our first innovation is a multi-scale hierarchical control signal that adjusts luminance across different spatial scales, ensuring that the QR code remains decodable while allowing for artistic expression. The second innovation is a progressive control mechanism that dynamically adjusts spatiotemporal guidance throughout the diffusion denoising steps, enabling fine-grained balance between visual quality and scannability. Extensive experimental results demonstrate that AnimateQR achieves state-of-the-art performance in both decoding success rates (96% vs. 56% baseline) and visual quality (user preference: 7.2 vs. 2.3 on a 10-point scale). Codes are available at <https://github.com/mulns/AnimateQR>.

## 1 Introduction

Aesthetic QR codes have emerged as a promising medium that integrates machine-readable functionality with human-oriented visual design [41, 31, 22, 14]. Early approaches typically focused on module deformation [3, 10, 45, 4, 16] and style transfer [41, 41] to improve visual appeal. With the advancement of generative models [32, 36, 15, 35, 17, 19, 18, 20, 26, 28, 27], recent methods employ ControlNet-based frameworks [6, 43] to synthesize stylized QR code images [34]. To further ensure scanning reliability, dedicated mechanisms [22, 34, 39, 5] have been introduced to balance the trade-off between aesthetics and robustness.

Unlike existing static QR codes, animated QR codes encoded as video sequences offer enhanced branding potential, interactive storytelling, and context-aware content delivery. However, generating temporally coherent animated QR codes that maintain robust scannability while achieving artistic expressiveness presents significant challenges.

To the best of our knowledge, we are the first to tackle animated QR code generation, addressing a critical gap in existing methods that are primarily designed for static image domains. Directly applying these static methods [4, 3, 22, 34, 39] to animated scenario in a frame-by-frame manner results in visually unappealing outcomes, often producing rigid and unnatural animations due to a lack of temporal coherence and aesthetic consistency. Our motivation arises from the observation that overly fine-grained control leads to instability, whereas overly coarse control introduces visual

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Figure 1: Samples of animated QR codes are shown. *Best viewed with Acrobat Reader. Click the images to play the animation clips and zoom in for finer details.*

artifacts. To balance robustness and visual quality, we propose a novel framework with adaptive control granularity, *enabling dynamic adjustment of spatial and temporal constraints to prioritize scannability in critical regions while allowing creative freedom in less important areas*. We name the method AnimateQR, which introduces two key innovations:

**1. Hierarchical Luminance Guidance (HLG).** HLG is a multi-scale luminance map that can be derived from both natural images and QR codes. It encodes hierarchical structural information, serving as a control mechanism to bridge artistic expression and QR code functionality. Our proposed HLG-ControlNet, trained on natural images and their corresponding HLG maps, achieves superior performance than existing luminance ControlNet [43] through three key innovations:

(1) Module-aligned Encoding: Spatial partitioning aligns with QR decoder’s module-wise processing requirements, ensuring structural compatibility. (2) Hierarchical Control: Multi-scale constraint mechanism enables dynamic granularity adaptation across different QR module hierarchies. (3) Adaptive Constraint: Ternary quantization strategy selectively preserves critical regions while allowing flexibility in non-essential areas through stochastic relaxation.

**2. Progressive SpatioTemporal control (ProST).** Building upon the HLG-ControlNet framework, we propose a novel diffusion-based progressive spatiotemporal control mechanism that jointly optimizes visual quality and scannability during the inference phase. Unlike conventional approaches that enforce uniform control across frames, ProST dynamically partitions control strength across both spatial and temporal dimensions:

- ◊ *Temporally*: ProST assigns distinct HLG maps to each frame through a combination of reshuffling and interpolation, ensuring temporal coherence while maintaining scannability.
- ◊ *Spatially*, the HLG control signals adaptively evolve across diffusion stages: regions prone to decoding errors receive stronger guidance, while more stable areas transition to softer constraints.

This dual-domain adaptation mechanism effectively balances video coherence with decoding reliability, achieving an optimal trade-off between visual appeal and functional robustness.

Extensive experimental results demonstrate that AnimateQR achieves state-of-the-art performance in both decoding success rates (96% vs. 56% baseline) and visual quality (user preference: 7.2 vs. 2.3 on a 10-point scale).

The key contributions of this paper are threefold: 1) First generative framework for animated QR codes. 2) Hierarchical Luminance Guidance (HLG) that enhances control granularity spatially. 3) Progressive Spatiotemporal Control (ProST): a diffusion-based method for error-adaptive control across space and time.

## 2 Related Work

**Quick Response (QR) Code.** As QR codes increasingly serve as a vital bridge between physical and digital domains, there is growing interest in enhancing their visual aesthetics beyond the traditional monochrome design. Early efforts, such as halftone QR codes [3], align QR modules with thematic images to create visually integrated patterns. Artup [7, 40] further explore the embedding of colorful content within QR structures. For module rearrangement, the QArt team [4, 16] pioneered the application of Gaussian-Jordan elimination algorithms to spatially reorganize encoding units. Subsequent advances [30, 31] apply artistic style transfer techniques to enrich QR code appearance.

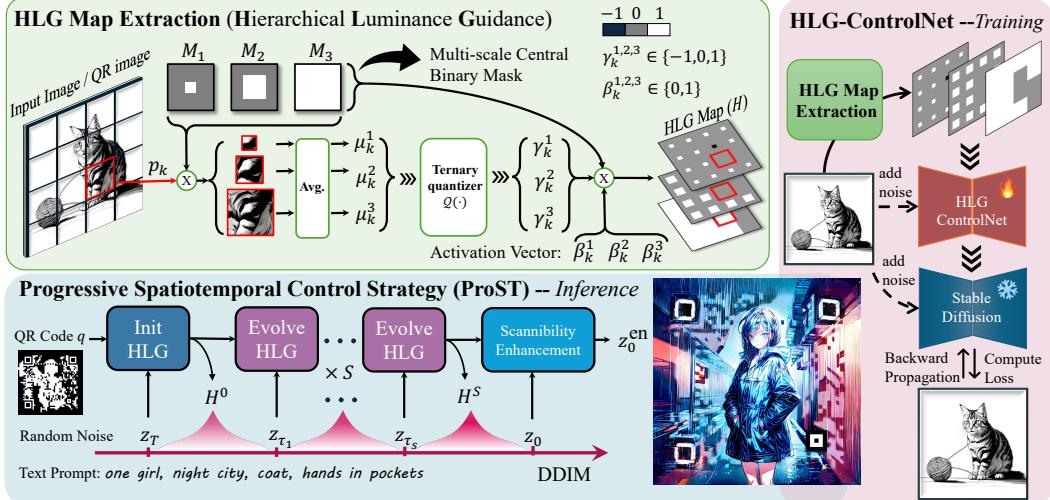


Figure 2: Illustration of the proposed AnimateQR framework. The green box depicts the extraction of the Hierarchical Luminance Guidance (HLG) map from input images. The red box outlines the training of the HLG-ControlNet, while the blue box highlights the inference stage using the proposed Progressive Spatiotemporal control (ProST) strategy. During training, we extract HLG map with randomly sampled activation vector  $\beta_k$  as detailed in Section 3.3. During inference, animated QR codes are generated via the DDIM process using a Stable Diffusion model equipped with HLG-ControlNet (as the control unit) and AnimateDiff (as the motion module). The HLG map is progressively updated by the Evolve HLG module as detailed in Section 3.4, enabling adaptive spatiotemporal control throughout the denoising process.

Style transfer technology further elevates the artistic quality of QR codes. Xu et al. [41] proposed SEE QR codes, marking the advent of aesthetically pleasing QR codes based on style transfer. Subsequently, Su et al. [30, 31] enhanced the aesthetic effect through a module-based deformable convolution mechanism (MDCM), generating QR codes that are both recognizable by ordinary mobile scanners and artistically expressive.

**Diffusion for Aesthetic QR Image:** In recent years, deep learning-based image manipulation and generation techniques have made significant progress [32, 36, 15, 35, 17, 19, 18, 20], with generative models leading the forefront of this advancement [42, 21, 24, 23, 26, 28, 27]. QRBTF [22] employs diffusion models [25] to generate photorealistic QR codes with natural textures while maintaining robust scannability. Meanwhile, GladCoder [39] integrates GANs [8] and diffusion models [25] to refine high-frequency details in QR codes, enabling them to mimic complex artworks without sacrificing machine readability, thus solving the problem of artistic expression limitations in traditional QR designs. The QRMonster model [6], built upon the ControlNet framework, enhances structural control capabilities of diffusion models through its adapter module [46]. Text2QR [34] leverages QRMonster to improve visual output quality while optimizing positioning patterns via a three-stage refinement process, thereby significantly enhancing the overall aesthetic quality of QR code images. Face2QR [5] represents another noteworthy research direction, which explores the integration of facial features into QR code design to create unique and highly personalized solutions. This innovation undoubtedly opens up new possibilities for the future of QR code aesthetics.

### 3 Method

#### 3.1 Preliminary

A QR code is decoded through three primary steps:

1. *Detection and Localization*: Locate the QR code region by detecting Finder Patterns (the square markers at three corners) and Alignment Patterns, and determine the QR code’s version and format information.

2. *Module Sampling and Binarization*: Partition the QR code image into a grid of  $m \times m$  modules, where each module is assigned a binary value (0 or 1) based on its luminance level.

3. *Error Correction and Decoding*: Decode the binary sequence using Reed-Solomon error correction to retrieve the original message.

In this paper, we define all QR code images as composed of  $m \times m$  modules, where each module consists of  $a \times a$  pixels. For convenience, we standardize all images to a size of  $ma \times ma$ .

### 3.2 Overall Framework

The overall framework of our approach is illustrated in Figure 2. During inference, our method follows the standard Denoising Diffusion Implicit Models (DDIM) [29] process to denoise a randomly sampled noise using Stable Diffusion (v1.5) [25]. Additionally, we employ ControlNet [43] for spatial luminance control and AnimateDiff [9] for motion generation in video sequences. Specifically, the ControlNet we utilize adheres to the standard model architecture but is trained on a novel Hierarchical Luminance Guidance (HLG) signal dataset, referred to as **HLG-ControlNet**. During the denoising process, we dynamically adjust the control signals through a mechanism named **Progressive Spatiotemporal Control (ProST)**, assigning varying control strengths both spatially and temporally to achieve a fine-grained balance between visual quality and scanning robustness.

The rationale for selecting AnimateDiff as the motion module can be summarized as follows: (1) AnimateDiff is seamlessly integrated with the image generation model Stable Diffusion, which benefits from a rich ecosystem of community fine-tuned stylized models. (2) By leveraging AnimateDiff, we can apply control through image-based ControlNet without the need to train a separate video ControlNet. This design makes our method highly extensible, enabling both static and animated QR code generation with minimal additional effort. (3) Unlike most video generation models, AnimateDiff supports frame-wise luminance control, which naturally aligns with the requirements of animated QR code generation.

In the subsequent sections, we elaborate on the training process of HLG-ControlNet and the inference process of ProST for animated QR code generation.

### 3.3 Training HLG-ControlNet

As previously mentioned, although our framework generates animated QR codes in video sequences, we leverage image-based ControlNet to achieve precise luminance control. As illustrated in the red box of Fig. 2, we train the ControlNet following the standard process [43] on a dataset of images paired with their corresponding Hierarchical Luminance Guidance (HLG) maps. The network is trained end-to-end, with HLG maps provided as conditional inputs. We adopt the same loss functions and optimization strategy as ControlNet to ensure reproducibility while focusing on learning HLG-guided control signals.

The HLG map is defined as a three-channel representation, where each channel corresponds to a distinct scale. Each pixel in the HLG map assumes one of three values: -1 for dark regions, 1 for bright regions, and 0 for regions with unrestricted luminance.

The subsequent section details the process of extracting the HLG map from an input image, as further illustrated in the green box of Figure 2.

**Multi-scale Luminance Extraction.** For input image  $I \in \mathbb{R}^{ma \times ma}$ , we partition it into  $m^2$  non-overlapping  $a \times a$  patches  $P = \{p_k\}_{k=1}^{m^2}$  via grid decomposition. Each patch is analyzed using three *Multi-scale Central Masks*  $\{M_r \in \mathbb{R}^{a \times a}\}_{r=1}^3$ , defined with central radii  $c_r = \lfloor a/2^{r-1} \rfloor$ :

$$M_r(x, y) = \begin{cases} 1 & \text{if } (x, y) \in \text{Center}(c_r \times c_r), \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

The hierarchical luminance values are calculated through:

$$\mu_k^r = \frac{1}{\|M_r\|_0} \sum_{(x,y) \in \Omega_k} p_k(x, y) \cdot M_r(x, y), \quad (2)$$

where  $\Omega_k$  is the pixel coordinate space within patch  $p_k$  and  $r \in \{1, 2, 3\}$  denotes three scales.

**Hierarchical Luminance Guidance.** Given the average luminance values across different scales, we quantize them to align with the distribution of QR code images. We define a ternary quantization function  $\mathcal{Q} : [0, 1] \rightarrow \{-1, 0, 1\}$  as follows:

$$\mathcal{Q}(\mu) = \begin{cases} -1 \text{ (Dark)} & \text{if } \mu < \tau_b, \\ 1 \text{ (Bright)} & \text{if } \mu > \tau_a, \\ 0 \text{ (Unconstrained)} & \text{otherwise,} \end{cases} \quad (3)$$

where  $\tau_a = 0.7$  and  $\tau_b = 0.3$  are decoder-calibrated thresholds derived from sensitivity analysis. For each patch  $p_k$ , the average luminance  $\mu_k^r$  is mapped to the ternary luminance vector  $\gamma_k = [\mathcal{Q}(\mu_k^1), \mathcal{Q}(\mu_k^2), \mathcal{Q}(\mu_k^3)]$  according to Equation 2 - 3.

To dynamically activate scale-specific constraints, we introduce an **activation vector**  $\beta_k \in \mathcal{B}$ . Here,  $\mathcal{B}$  is explicitly defined as the **ordered basis set**:

$\mathcal{B} \triangleq (b_1, \dots, b_8) = \{(0, 0, 0), (0, 0, 1), (0, 1, 0), (1, 0, 0), (0, 1, 1), (1, 0, 1), (1, 1, 0), (1, 1, 1)\}$ . Each basis  $b_i$  (for  $i = 1, 2, \dots, 8$ ) controls the activation of the three scales, with 0 indicating deactivation and 1 indicating activation, thereby enumerating all possible activation patterns. Each value in  $b_i$  corresponds to one scale: activating a scale enables its corresponding blocks to contribute to the content control strength. For instance,  $(1, 0, 0)$  modifies only coarse-scale blocks, resulting in weaker control, whereas  $(1, 1, 1)$  involves all scales and achieves maximal control strength. The definition of  $\mathcal{B}$  and  $b_i$  facilitates the explanation of how the HLG map is updated by modifying the activation vector during inference, as detailed in the following section.

The final HLG map  $H$  is constructed by combining multi-scale constraints through channel-wise concatenation (denoted as  $\bigoplus$ ):

$$H_k = \bigoplus_{r=1}^3 [\gamma_k^r \cdot M_r \cdot \beta_k^r], \quad H = \text{unpatchify}(\{H_k\}_{k=1}^{m^2}). \quad (4)$$

During training, we uniformly explore all patterns by sampling  $\beta_k$  such that  $P(\beta_k = b_i) = \frac{1}{8}$  for all  $i \in \{1, \dots, 8\}$ . This ensures that the HLG-ControlNet becomes robust to spatially dynamic control strengths.

### 3.4 Inference with ProST

Our diffusion-based Progressive Spatiotemporal Control (ProST) framework addresses the long-standing control-strength dilemma through an *error-adaptive constraint escalation* mechanism. Specifically, ProST dynamically modulates hierarchical constraints in response to error-driven control escalation, operating through three distinct phases: *Init HLG*, *Evolve HLG*, and *Scannability Enhancement*. This phased approach ensures a systematic and adaptive progression in constraint enforcement, significantly enhancing the framework’s robustness and precision in spatiotemporal control tasks. The complete algorithm is presented in Algorithm 1.

**Notation.** Let  $k \in \{1, \dots, m^2\}$  index the QR modules, where  $m^2$  represents the total number of modules in the QR code. Let  $\{z_{\tau_s}\}_{s=0}^S$  denote the latent states at evenly spaced timesteps, where  $\tau_s = T - s\Delta_\tau$  and  $\Delta_\tau = T/S$ . At each stage  $s$ , conditional denoising is performed as:

$$z_{\tau_{s+1}} = \text{DDIM}(z_{\tau_s}, H^s, \tau_s \rightarrow \tau_{s+1}), \quad (5)$$

where  $H^s$  is the adaptive HLG map, dynamically updated based on intermediate decoding results.

Given an animated QR sequence  $V$  consisting of  $N$  frames, we partition it into two disjoint subsets: the keyframe set  $\mathcal{K} \subset \{1, 2, \dots, N\}$  and the non-keyframe set  $\mathcal{T} = \{1, 2, \dots, N\} \setminus \mathcal{K}$ . The keyframes  $\mathcal{K}$  are uniformly sampled and are required to satisfy scannability constraints, while the non-keyframes  $\mathcal{T}$  primarily focus on maintaining temporal coherence without enforcing scannability.

**Init HLG.** Given a QR code  $q$  and random noise  $z_T$ , this module generate a initialized HLG map  $H^0$ . First, the initial video sequence  $V' = \{I_t\}_{t=1}^N$  is generated as:

$$V' = \mathcal{D}_{\text{vae}}(\text{DDIM}(z_T, H^{\text{null}}, T \rightarrow 0)), \quad (6)$$

where  $H^{\text{null}}$  denotes null control,  $N$  represents the number of video frames (typically set to 16), and  $\mathcal{D}_{\text{vae}}$  is the VAE Decoder [13].

Next, we align the QR modules with the video content through the following operations:

$$q'_t = g(V', q) = \begin{cases} \text{Reshuffle}(I_t, q), & \text{if } t \in \mathcal{K}; \\ \text{Interp}(q'_{t-}, q'_{t+}, \alpha_t), & \text{if } t \in \mathcal{T}; \end{cases} \quad (7)$$

where:  $\text{Reshuffle}(\cdot, \cdot)$  is derived from QArt [4] (details provided in the Appendix);  $\text{Interp}(\cdot)$  performs nearest-neighbor interpolation between two keyframes based on temporal distance;  $t^- = \max\{i \in \mathcal{K} \mid i < t\}$  and  $t^+ = \min\{i \in \mathcal{K} \mid i > t\}$  denote the nearest preceding and succeeding keyframes relative to frame  $t$ ;  $\alpha_t = \frac{t-t^-}{t^+-t^-} \in (0, 1)$  represents the temporal interpolation ratio;  $q'_t \in \mathbb{R}^{m^2}$  is the reshuffled binary sequence with  $q'_t[k] \in \{-1, 1\}$ .

Subsequently, we construct the HLG map for each frame in parallel, where the temporal subscript is omitted for simplicity. According to Eq. 4, the HLG map  $H^s$  at stage  $s$  is formulated as:

$$H^s = f(q', \{\beta_k^{(s)}\}_{k=1}^{m^2}) = \text{unpatchify} \left( \left\{ \bigoplus_{r=1}^3 [q'[k] \cdot M_r \cdot \beta_k^{r(s)}] \right\}_{k=1}^{m^2} \right). \quad (8)$$

At the initial stage  $s = 0$ , we set  $\beta_k^{(0)} = b_2$  as the initialized activation state.

**Evolve HLG.** At stage  $s > 0$ , given the current estimate  $z_{\tau_s}$  from Eq. 5 and the reshuffled QR code  $q'$ , the module updates the HLG map from  $H^s$  to  $H^{s+1}$ . As defined in Eq. 8, this is essentially achieved by updating the activation vector set  $\{\beta_k^{(s)}\}_{k=1}^{m^2}$ . To achieve error-driven control updates, we first analyze the error distribution. Specifically, the current estimate  $z_{\tau_s}$  is decoded as  $\hat{q}^s = \mathcal{D}_{\text{qr}}(\mathcal{D}_{\text{vae}}(z_{\tau_s}))$ , where  $\mathcal{D}_{\text{qr}}$  denotes the simulated QR decoder [1] (details provided in the Appendix). The module-wise error mask is then computed as:

$$E_k^s = \mathbb{I}[\hat{q}^s[k] \neq q'[k]], \quad 1 \leq k \leq m^2, \quad (9)$$

where  $\mathbb{I}[\cdot]$  is the indicator function, returning 1 if the condition is true and 0 otherwise.

Next, we define the evolve function as follows:

$$\beta_k^{(s+1)} = \begin{cases} b_{\min(\phi(\beta_k^s)+1, 8)}, & \text{if } E_k^s = 1; \\ b_{\max(\phi(\beta_k^s)-1, 1)}, & \text{otherwise,} \end{cases} \quad (10)$$

where  $\phi : \mathcal{B} \rightarrow \{1, \dots, 8\}$  is a bijective index mapping satisfying  $\phi(b_i) = i$ . After this, the updated HLG map  $H^{s+1}$  is computed following Eq. 8. This update rule ensures that *for erroneous modules, the control strength is increased, while for correct modules, the control strength is decreased*, thereby achieving a balanced trade-off between scannability and aesthetic quality.

**Scannability Enhancement.** After the final denoising step, the latent code is refined using the SELR (Scannability Enhancement via Latent Refinement) module [34]. This module applies gradient-based iterative refinement as follows:

$$z_0^{\text{en}} = z_0 - \eta \sum_{i=1}^L \nabla_{z_0} \mathcal{L}_{\text{scan}} \left( q', \mathcal{D}_{\text{qr}}(\mathcal{D}_{\text{vae}}(z_0^{(i)})) \right), \quad (11)$$

where:  $L$  is the number of SELR iterations,  $z_0^{(i+1)} = z_0^{(i)} - \eta \nabla \mathcal{L}_{\text{scan}}$  represents the iterative update with learning rate  $\eta$ ,  $\mathcal{L}_{\text{scan}}$  is the scannability loss function (detailed in the Appendix). This refinement process ensures that the final latent code  $z_0^{\text{en}}$  is optimized for scannability while preserving the visual quality of the generated QR code.

## 4 Experiment

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**Algorithm 1** Progressive Spatiotemporal Control (ProST)

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**Require:** Initial noise  $z_T$ , target QR  $q$ , stages  $S$   
**Ensure:** Scannable  $V^{qr}$

- 1: Initialize:  $V' \leftarrow \mathcal{D}_{vae}(\text{DDIM}(z_T, H^{\text{null}}, T \rightarrow 0))$
- 2: Let  $q' \leftarrow g(V', q)$
- 3: Let  $\beta_k^0 \leftarrow (0, 0, 1), \forall k \in \{1, 2, \dots, m^2\}$
- 4: Let  $H^0 \leftarrow f(q', \{\beta_k^{(0)}\}_{k=1}^{m^2})$
- 5: Let  $z_{\tau_0} \leftarrow z_T$
- 6: **for**  $s = 1$  to  $S$  **do**
- 7:     Denoise:  $z_{\tau_s} \leftarrow \text{DDIM}(z_{\tau_{s-1}}, H^{s-1}, \tau_{s-1} \rightarrow \tau_s)$
- 8:     Decode:  $\hat{q}^s \leftarrow \mathcal{D}_{qr}(\mathcal{D}_{vae}(z_{\tau_s}))$
- 9:     **for**  $k = 1$  to  $m^2$  **do**
- 10:       **if**  $\hat{q}_k^s \neq q'_k$  **then**
- 11:          $\beta_k^s \leftarrow b_{\min(\phi(\beta_k^{s-1})+1, 8)}$
- 12:       **else**
- 13:          $\beta_k^s \leftarrow b_{\max(\phi(\beta_k^{s-1})-1, 1)}$
- 14:       **end if**
- 15:     **end for**
- 16:     Update HLG:  $H^s \leftarrow f(q', \{\beta_k^{(s)}\}_{k=1}^{m^2})$
- 17: **end for**
- 18: Enhance Scannability:  $z_0^{\text{en}} \leftarrow \text{SELR}(z_0)$
- 19: Output:  $V^{qr} \leftarrow \mathcal{D}_{vae}(z_0^{\text{en}})$

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artistic styles. To assess scanning robustness, all generated results are displayed on a 27-inch, 144Hz IPS monitor. The scannability of dynamic QR codes is tested under real-world conditions by playing the 16-frame animation on the screen and performing actual scanning, consistent with their intended practical usage.

As mentioned earlier, our proposed AnimateQR can be easily extended to generate **static** aesthetic QR code images. This is achieved by disabling AnimateDiff and setting  $\mathcal{K} = \{1\}$ . We refer to this static variant as AnimateQR-*s*.

#### 4.1 Qualitative Comparison

**Animated QR Code Quality.** Due to the absence of dedicated methods for animated QR code generation, we extend two representative static image-to-QR approaches, ArtCoder [31] and GladCoder [39], to the video domain via frame-by-frame processing, denoted as “ArtCoder-*d*” and “GladCoder-*d*”, ensuring fair comparison under identical conditions. As shown in Fig. 3, these baselines exhibit noticeable temporal flickering due to the lack of inter-frame modeling, whereas our method generates animations with significantly improved temporal coherence and visual continuity.

**Static QR Code Quality.** For fair comparison, we evaluate our static variant, AnimateQR-*s*, against state-of-the-art static QR code generation methods. The comparison includes image-to-QR methods (ArtCoder [31], GladCoder [39]) and text-to-QR methods (QRBT [22], Text2QR [34]). To accommodate varying input requirements, we use unified prompt-image pairs as dual conditioning inputs (details are in the Appendix). As Figure 4 shows, ArtCoder, QRBT, and GladCoder suffer from color-block artifacts, while Text2QR improves aesthetics but exhibits unnatural textures and color shifts. In contrast, AnimateQR-*s* delivers visually coherent QR codes with seamless module integration, thanks to our adaptive control strategy that spatially modulates hierarchical constraints based on reconstruction errors.

#### 4.2 Quantitative Comparison

**Scanning Robustness.** In this study, we evaluate the scanning robustness of our QR codes in comparison with two methods: Text2QR [34] and QRBT [22]. We generate a set of 50 aesthetically optimized QR images for each method, all at a resolution of  $1024 \times 1024$  pixels. These images are displayed on a high-definition monitor at three standard sizes:  $3 \text{ cm}^2$ ,  $5 \text{ cm}^2$ , and  $7 \text{ cm}^2$ . During controlled testing, smartphones are held at a fixed distance of 40 cm, and each QR code is scanned

#### Experimental Setup and Configuration.

Our implementation is based on the PyTorch framework and runs on an NVIDIA GeForce RTX 4090 GPU. We generate QR codes of version 5, corresponding to  $37 \times 37$  modules (i.e.,  $m = 37$ ). For training the HLG-ControlNet, we adopt \*Stable Diffusion v1.5\* as the backbone and utilize a dataset comprising 60,000 high-resolution images, each preprocessed to a resolution of  $512 \times 512$  pixels. During inference, we set the ControlNet control strength to 0.9, the number of frames in AnimateDiff to 16, and the motion scale to 1.0. By default, we define the keyframe set as  $\mathcal{K} = \{1, 8, 16\}$  and set the learning rate to  $\eta = 0.001$ .

For comparative evaluation, we construct a dataset of 500 uniquely stylized QR images, each with a resolution of  $1024 \times 1024$  pixels, encompassing diverse visual content and

Table 1: Average scanning success rates (%) are assessed across various phone applications, considering different sizes ( $\text{cm}^2$ ) and angles ( $^\circ$ ). “Scanner” denotes the native scanner of system. We compare our method with QRBT [22] and Text2QR [34] under same condition.

Decoders	Success Rate (%)					
	$(3\text{cm})^2$		$(5\text{cm})^2$		$(7\text{cm})^2$	
	45°	90°	45°	90°	45°	90°
QRBT [22]						
Scanner	100	100	100	100	100	100
TikTok	96	96	78	83	56	72
WeChat	100	100	100	98	94	100
Text2QR [34]						
Scanner	100	100	100	100	100	100
TikTok	100	100	100	100	96	100
WeChat	100	100	96	100	94	100
AnimateQR						
Scanner	100	100	100	100	100	100
TikTok	100	100	100	100	96	100
WeChat	100	100	100	100	96	96

for 3 seconds from various angles. Scanning success rates, averaged over 20 trials, are reported in Table 1. Our method consistently achieves a success rate above 96%, outperforming the baselines. Notably, QR codes failing within the 3-second window were often successfully scanned with extended exposure, demonstrating the practical reliability of our generated codes.

**IQA / VQA Metrics and Inference Speed.** To assess static QR code quality, we adopt Q-Align [38] (0 – 1), LIQE [44] (0 – 5), AesBench [12] (0 – 1), and AesExpert [11, 33] (0 – 1) as aesthetic evaluation metrics. For animated QR codes, we employ Q-Bench [37] (0 – 1) and SimpleVQA [2] (0 – 5). In addition, we report the average inference speed (samples per second) for animated QR code generation. All metrics and runtime statistics are averaged over 100 generated samples per method and summarized in Table 2 – 3. Our method consistently achieves the best performance across both static and animated QR code evaluations.

**User Study.** To further assess the practical effectiveness of our method, we conduct a user study as a supplementary subjective evaluation. The user study consisting of 30 participants to evaluate

ArtCoder-*d*      GladCoder-*d*      AnimateQR      ArtCoder-*d*      GladCoder-*d*      AnimateQR

Table 2: Comparison of animated QR code generation with **best** results in bold.

Methods	Q-Bench $\uparrow$	SimpleVQA $\uparrow$	Speed $\uparrow$
ArtCoder- <i>d</i>	0.2954	3.0254	0.031
GladCoder- <i>d</i>	0.2453	2.6901	0.016
AnimateQR	<b>0.6217</b>	<b>3.5872</b>	<b>0.613</b>

Table 3: Comparison of static QR code generation

Methods	Q-Align $\uparrow$	LIQE $\uparrow$	AesBench $\uparrow$
ArtCoder	0.6003	2.6363	0.4396
GladCoder	0.6559	3.2529	0.7729
QRBT	0.7877	3.5447	0.7822
Text2QR	0.7788	3.5034	0.7610
AnimateQR- <i>s</i>	<b>0.8433</b>	<b>3.8572</b>	<b>0.8832</b>

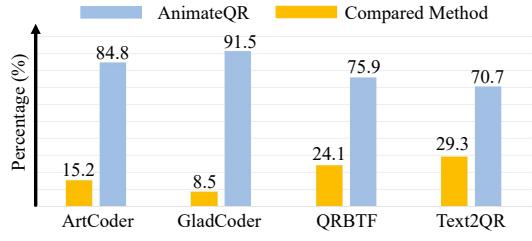


Figure 5: Statistical results of user study.

Figure 3: Visual comparison of animated QR code generation methods. *Best viewed with Acrobat Reader. Click the images to play the animation clips and zoom in for finer details.*

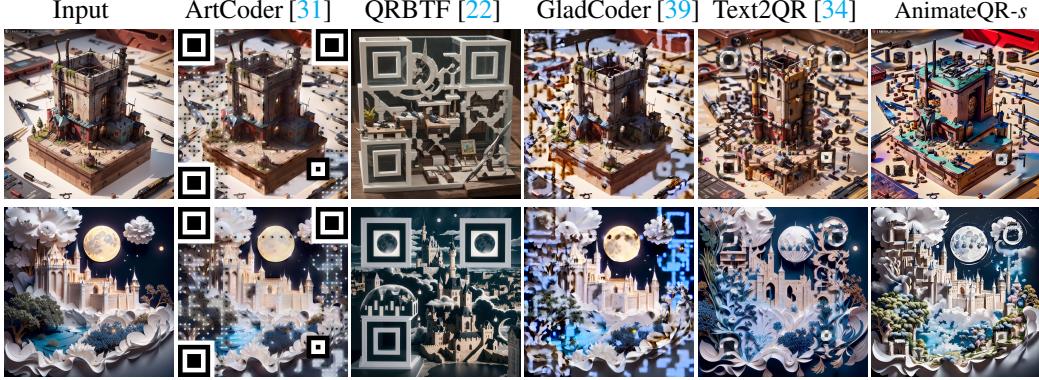


Figure 4: Visual comparison of static QR code generation methods.

Table 4: Average QR code scanning success rates (%) across illumination levels ranging from 500 to 5 LUX.

Methods	500	400	300	200	100	5
Text2QR- <i>d</i>	100	100	96	82	64	2
QRBT- <i>d</i>	98	96	90	62	48	0
AnimateQR	100	100	98	88	66	8

Table 5: Average QR code scanning success rates (%) across motion blur levels ranging from 0.1 to 2.0 m/s.

Methods	0.1	0.5	1.0	1.5	2.0
Text2QR- <i>d</i>	100	100	96	90	88
QRBT- <i>d</i>	98	98	92	82	70
AnimateQR	100	100	96	92	88

Table 6: Average QR code scanning success rates (%) across scanning angles ranging from 0° to 60°.

Methods	0°	15°	30°	45°	60°
Text2QR- <i>d</i>	100	100	100	100	98
QRBT- <i>d</i>	98	100	98	100	96
AnimateQR	100	100	100	100	98

Table 7: Comparison of AnimateQR variants. AnimateQR-XL uses SDXL + AnimateDiff-XL; AnimateQR-LCM uses AnimateDiff-LCM.

Methods	Q-Bench↑	SimpleVQA↑
AnimateQR	0.6217	3.5872
AnimateQR-XL	0.6926	3.8216
AnimateQR-LCM	0.6138	3.5921

200 generated QR codes (50 for each methods) generated by different methods (the approval from Institutional Review Board is obtained). Participants are asked to rank the results in the aspect of aesthetic quality. The percentages represent how many users prefer the results of a method over others. The results are illustrated in Figure 5, with detailed experimental settings provided in the Appendix. The results indicate a clear user preference for our method over existing baselines.

**Real-World Robustness.** To rigorously evaluate the robustness of our method in real-world scenarios, we conduct three types of tests: varying illumination, motion blur, and scanning angles. As benchmarks, we extend Text2QR and QRBT to dynamic settings via per-frame generation, denoted as “Text2QR-*d*” and “QRBT-*d*”. We perform side-by-side comparisons on 50 QR code sequences (each 5 cm × 5 cm), ensuring a fair and comprehensive evaluation. We conduct controlled experiments: ambient illumination is varied from near 0 to 500LUX across six levels with the phone fixed at 0°, motion blur is simulated along a 3m path at speeds of 0.1–2m/s under 500LUX, and scanning angles are tested from 0° to 60° with stationary phones under 500LUX. Each method scans the same QR codes 10 times per condition, and average success rates are recorded. The results, summarized in Table 4–6, show that AnimateQR consistently outperforms Text2QR-*d* and QRBT-*d* under realistic conditions, including low light, motion blur, and non-standard scanning angles, achieving superior stability and decoding reliability in challenging scenarios.

**Model Generality.** We evaluate the generality and scalability of our framework across different model variants. As shown in Table 7, AnimateQR-XL (SDXL + AnimateDiff-XL) shows substantial improvements over the SD-v1.5 variant, while AnimateQR-LCM (with the distilled AnimateDiff-LCM) achieves comparable performance. These results demonstrate our framework’s extensibility to newer architectures and generalizability to distilled models. Moreover, our framework supports style generality by integrating LoRA-trained diffusion models to modify output styles.

Table 8: HLG-ControlNet Ablation Comparison. Details are in Section 4.3.

	QR-C.Net	HLG-C.Net*	HLG-C.Net
Condition			
Generated			

Table 9: ProST Ablation. We compare ProST (adaptive  $\beta_k$ ) with static baselines using fixed  $\beta_k = b_2$  (light control) and  $\beta_k = b_8$  (strong control). ProST achieves better balance between visual quality and scannability, as reflected by scanning error rates.

$\beta_k = b_2$	$\beta_k = b_8$	adaptive $\beta_k$

Error Rate: 72.3%      Error Rate: 2.63%      Error Rate: 11.3%

### 4.3 Ablation Study

**HLG-ControlNet.** While prior methods such as Text2QR [34], Face2QR [5], and GladCoder [39] adopt QRMonster [6] as the ControlNet conditioned on QR code images, we propose HLG-ControlNet, which leverages hierarchical luminance guidance for conditioning. To enhance robustness during training, we introduce random sampling of the modulation vector  $\beta_k$  to simulate varying control strengths. We conduct ablation studies by replacing HLG-ControlNet (referred to as HLG-C.Net) in AnimateQR with: (1) QRMonster, denoted as QR-C.Net, which serves as the standard ControlNet conditioned on QR code images, and (2) HLG-C.Net\*, a variant trained with a fixed modulation vector  $\beta_k = b_8$ , thereby disabling adaptive control. As shown in Table 8, QRMonster often introduces blocky artifacts. HLG-C.Net\* benefits from hierarchical luminance guidance, yielding more coherent outputs. Our full model achieves the best visual quality, validating the effectiveness of both HLG-based conditioning and adaptive modulation.

**Progressive Spatiotemporal Control (ProST).** While previous methods such as Text2QR [34], Face2QR [5], and GladCoder [39] employ a fixed control signal throughout inference, we introduce ProST, a strategy that adaptively updates the HLG map during inference. To assess its effectiveness, we compare ProST against static control baselines using fixed activation vectors:  $\beta_k = b_2 = (0, 0, 1)$  for light control and  $\beta_k = b_8 = (1, 1, 1)$  for strong control. As shown in Table 9, static light control yields high visual fidelity but poor scannability, whereas strong control improves scannability at the cost of degraded aesthetics. In contrast, our ProST strategy with adaptive  $\beta_k$  achieves a superior trade-off, delivering outputs with both robust scannability and high visual quality.

## 5 Conclusion

We present AnimateQR, a generative framework for animated QR code synthesis. Leveraging hierarchical luminance guidance and progressive spatiotemporal control, AnimateQR achieves a strong balance between visual aesthetics and scannability. Extensive experiments confirm its superiority over prior methods. Beyond QR codes, our adaptive control strategy holds promise for other scannable media, such as animated AR markers, and inspires future work on constraint-aware generative modeling.

**Limitations.** Despite its strengths, AnimateQR has some limitations. First, generating high-resolution, visually complex animations can be computationally demanding. Second, although designed for broad compatibility, a small fraction of legacy or less-common scanners may still encounter decoding issues.

**Broader Impact.** By elevating the visual appeal and personal relevance of QR codes, our work re-imagines them as expressive, aesthetic artifacts—unlocking new applications in entertainment, social media, marketing, and personal memorabilia.

## 6 Acknowledgment

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