A Self-Adaptive Learning Rate and Curriculum Learning Based Framework for Few-Shot Text Classification

Anonymous ACL submission

Abstract

Due to the lack of labeled data in many realistic scenarios, a number of few-shot learning methods for text classification have been proposed, among which the meta learning based ones have recently attracted much attention. Such methods usually consist of a learner as the classifier and a meta learner for specializing the learner to tasks. For the learner, learning rate is crucial to its performance. However, existing methods treat it as a hyper parameter and adjust it manually, which is time-consuming and laborious. Intuitively, for different tasks and neural network layers, the learning rates should 013 be different and self-adaptive. For the meta learner, it requires a good generalization ability so as to quickly adapt to new tasks. Therefore, we propose a novel meta learning framework, 017 called MetaCLSLR, for few-shot text classification. Specifically, we present a novel meta learning mechanism to obtain different learning rates for different tasks and neural network layers so as to enable the learner to quickly adapt to new training data. Moreover, we propose a task-oriented curriculum learning mechanism to help the meta learner achieve a better generalization ability by learning from different tasks with increasing difficulties. Extensive experi-027 ments on three benchmark datasets demonstrate the effectiveness of MetaCLSLR.

1 Introduction

032

041

Text classification is one of the most concerned tasks in Natural Language Processing (NLP), as many realistic tasks can be transformed into it. At present, most text classification methods are based on supervised learning with a large amount of labeled data, such as TextRNN (Lai et al., 2015). But there is not so much labeled data, even source data, in many scenarios, such as news classification in specific domains. Some distant supervision methods (Mintz et al., 2009) have thus been proposed to handle this problem. However, this kind of approaches may add a large proportion of noisy data (Zeng et al., 2014). Because of this, it is a big challenge for traditional supervised learning methods to work well in the scenarios with very limited training data. As a result, the few-shot text classification task has attracted much attention in recent years, where there are only a few (e.g., 1 or 5) labeled instances available for each class as the support set and some unlabeled instances as the query set, as shown in Figure 1.

043

044

045

046

047

050

051

054

057

060

061

062

063

064

065

066

067

068

069

070

071

072

073

076

077

078

081

The concept of few-shot learning was formally put forward by (Li et al., 2003). They presented a method for learning from classes with few data, by incorporating generic knowledge which may be obtained from previously learned models of unrelated classes. The existing few-shot learning methods are divided into three categories (Gao et al., 2019), namely, model fine-tuning based (e.g., (Howard and Ruder, 2018; Nakamura and Harada, 2019)), metric learning based (e.g., (Snell et al., 2017; Vinyals et al., 2016)), and meta learning based methods (e.g., (Finn et al., 2017; Munkhdalai and Yu, 2017)). In recent years, meta learning based methods have attracted lots of interests. However, they still suffer from some challenges.

A meta learning method is composed of a learner and a meta learner. It is acknowledged that for a learner, learning rate is crucial to its performance. Nevertheless, in existing methods, it is treated as a hyper parameter and needs to be adjusted manually, which is time-consuming and laborious. Intuitively, for different tasks and different neural network layers, their learning rates should be different. On the other hand, a good generalization ability to a new task is necessary for a meta learner. And curriculum learning can help models obtain better generalization performance by guiding the training process towards better regions in the parameter space, i.e., into local minima of the descent procedure associated with better generalization (Bengio et al., 2009).

For the above reasons, we propose a novel meta



Figure 1: An example of few-shot text classification.

learning framework, called MetaCLSLR, for fewshot text classification. There are two main mechanisms in MetaCLSLR, i.e., Self-adaptive Learning Rates for the learner and a task-oriented Curriculum Learning mechanism for the meta learner. Our general contributions are three-fold.

086

880

094

100

101

102

103

104

105

106

107

108

109

110

111

117

121

122

- We present a novel meta learning mechanism with self-adaptive learning rates, which enables different tasks and neural network layers to obtain different learning rates.
- We introduce curriculum learning for the first time, to the best of our knowledge, into few-shot learning. Unlike traditional instance-oriented curriculum learning, the proposed curriculum learning mechanism gradually learns from different tasks with increasing difficulties.

• MetaCLSLR is evaluated with three typical text classification tasks, i.e., relation classification, news classification and topic classification, on three benchmark datasets, namely, FewRel80, 20Newsgroup and DBPedia Ontology, respectively. Experimental results demonstrate superior performance of Meta-CLSLR on all tasks and all datasets.

Related Works 2

2.1 Few-shot Learning

Few-shot learning is to learn how to solve problems from a small amount of data. As aforesaid, the 112 existing mainstream methods can be divided into 113 three types. The model fine-tuning based methods 114 learn how to fine-tune general-purpose models to 115 specialized tasks (Howard and Ruder, 2018; Naka-116 mura and Harada, 2019). The metric learning based methods learn a semantic embedding space upon a 118 distance loss function (Snell et al., 2017; Vinyals 119 et al., 2016). The meta learning based methods 120 learn a learning strategy to make them well adapt to new tasks (Finn et al., 2017; Munkhdalai and Yu, 2017). Furthermore, according to the different 123

kinds of meta knowledge the meta learner learns, the meta learning based methods can be subdivided into three types, i.e., initial parameter (Finn et al., 2017; Raghu et al., 2019; Jamal and Qi, 2019), hyper parameter (Wu et al., 2019) and optimizer based methods (Santoro et al., 2016; Munkhdalai and Yu, 2017). The initial parameter based methods learn parameter initialization for fast adaptation; The hyper parameter based methods learn a good hyper parameter setting of a learner; And, the optimizer based methods learn a meta-policy to update the parameters of a learner. In this paper, we propose a novel meta learning mechanism to self-adaptively obtain the hyper parameter, i.e., the learning rate, of the learner, which allocates different learning rates for different tasks and neural network layers.

124

125

126

127

128

129

130

131

132

133

134

135

136

137

138

140

141

142

143

144

145

146

147

148

149

150

151

153

154

155

157

158

159

160

161

162

163

164

165

166

168

169

170

171

172

2.2 Curriculum Learning

Compared with the general paradigm of machine learning without distinction, curriculum learning is proposed to imitate the process of human learning (Bengio et al., 2009). It advocates that the model should start learning from easy instances and gradually advance to complex instances and knowledge. Curriculum learning has been widely applied in many fields, e.g., computer vision (Guo et al., 2018; Jiang et al., 2014) and NLP (Platanios et al., 2019; Tay et al., 2019). Furthermore, curriculum learning can also be applied in some other technical frameworks, e.g., reinforcement learning (Florensa et al., 2017; Narvekar et al., 2017; Ren et al., 2018), graph learning (Gong et al., 2019; Qu et al., 2018) and continual learning (Wu et al., 2021). In this paper, we extend the traditional instance-oriented curriculum learning to a task-oriented one, which gradually learns from different tasks with increasing difficulties.

3 Methodology

3.1 Notations

In meta learning based few-shot text classification, two datasets are given: D_{train} and D_{test} , which have disjoint label sets. T tasks are sampled from D_{train} and the t-th task $(t \in [1, T])$, $Task_t$, consists of a support set S_t and a query set Q_t . Following the recent few-shot learning setting (Gao et al., 2019), we adopt C-way K-shot (hereinafter denoted as CwKs) for few-shot text classification, meaning the support set S_t contains C classes and each class has K labeled instances. Thus, S_t can be formulated as $S_t = \{(x_t^i, y_t^i)\}_{i=1}^{C \times K}$, where x_t^i



Figure 2: The diagram of the MetaCLSLR framework.

denotes the *i*-th piece of text in $Task_t$ and y_t^i is its 173 class label. S_t additionally includes a head entity h_t^i 174 and a tail entity o_t^i in relation classification. Further-175 more, x_t^i contains M_t^i words (hereinafter simplified 176 as M if not causing any confusion) and the m-th 177 word $(m \in [1, M])$ in x_t^i denotes as w_m for sim-178 plicity. Thus, x_t^i is formulated as $x_t^i = \{w_m\}_{m=1}^M$. 179 Moreover, the query set Q_t contains U unlabeled instances for each class in S_t . Q_t can be formulated 181 as $Q_t = \{q_t^i\}_{i=1}^{C \times U}$.

3.2 The MetaCLSLR Framework

184

188

189

191

192

193

194

195

196

197

201

MetaCLSLR is a generic framework, where different few-shot learning models of different categories (i.e., model fine-tuning based, metric learning based, and meta learning based) can act as the learner. As shown in Figure 2, MetaCLSLR consists of three modules coupled with a task-oriented curriculum learning mechanism:

The Encoder Module. In this module, the instances are mapped into the semantic space as embeddings by the encoder network.

The Task-level Learning Rate Module. In this module, the task-level learning rate is defined as a coefficient of difficult to different tasks, which is calculated by the number of training classes and the distance between different instances in the support set.

The Layer-level Learning Rate Module. In this module, the layer-level learning rate is selfadaptively obtained based on the meta learning mechanism. This module contains two main parts: the learner as the classifier and the meta learner above the learner, which allocates the learning rates for different network layers of the learner.

The Task-oriented Curriculum Learning Mechanism. This mechanism gradually learns from different tasks with increasing difficulties by adding more classes to a task, to make the meta learner achieve a better generalization ability.

3.3 The Encoder Module

The encoder module maps x_t^i into the instance embedding x_t^i , which consists of two parts, namely, the embedding part and the encoding part.

3.3.1 Embedding

The word embeddings $\{w_m\}_{m=1}^M$ are obtained by looking up table for vector representation of words $\{w_m\}_{m=1}^M$, to express their semantic meanings. In this paper, we employ GloVe (Pennington et al., 2014) to obtain the word embeddings.

3.3.2 Encoding

The CNN encoder is employed to derive the final instance embedding x_t^i of *B* dimension of x_t^i based on the word embeddings $\{w_m\}_{m=1}^M$. CNN slides a conventional kernel whose window size is *k*, over the input embeddings to get the output hidden embeddings,

$$\boldsymbol{h}_{m} = \operatorname{Con}\left(\boldsymbol{w}_{m-\frac{k-1}{2}}, ..., \boldsymbol{w}_{m+\frac{k-1}{2}}\right), \qquad (1)$$

where $Con(\cdot)$ is a conventional operation.

223

224

227

228

229

231

204

308

309

310

311

312

313

314

315

316

317

318

233 234

3.4

task.

as follows:

241

247 248

249

257 258

260

261

262

263

266

267

269

270

271

273

where x_t^i and x_t^j $(i \neq j)$ belong to the same class; $D_t^1 = \frac{CK(K-1)}{2}$, denoting the number of pairs $(\boldsymbol{x}_{t}^{i}, \boldsymbol{x}_{t}^{j})$. dis_{t}^{2} is calculated as follows: 274

is calculated by

275
$$dis_t^2 = \frac{1}{D_t^2} \sum_{i,j=1}^{C \times K} d\left(\boldsymbol{x}_t^i, \boldsymbol{x}_t^j\right),$$
(5)

A max pooling operation is then applied over

these hidden embeddings to output the final in-

 $[\boldsymbol{x}_{t}^{i}]_{b} = max \{[\boldsymbol{h}_{1}]_{b}, ..., [\boldsymbol{h}_{M}]_{b}\},\$

where $[\cdot]_b$ is the *b*-th value of a vector ($b \in [1, B]$).

The Task-level Learning Rate Module

The task-level learning rate module is designed

to self-adaptively get different learning rates for

different tasks. In the context of few-shot learning,

it is necessary for a model to converge in a few

steps, even one (Finn et al., 2017). Intuitively, for

easier tasks, a larger learning rate enables the model

to converge fast. However, for more difficult tasks,

a relatively smaller learning rate is preferred so

as to help the model to carefully search for the

optimal parameters in the complex search space. In

this module, the number of training classes and the

distance between different instances in the support

set are utilized to measure the difficulty of each

to the number of training classes. If the number

of training classes, C, of $Task_t$ is equal to that of its test classes, C', its difficulty coefficient dif_t is

set to 1. If C is larger than C', indicating that it is

a relatively difficult task, dif_t is increased. Other-

wise, it is reduced. dif_t can be formally calculated

 $dif_{t} = 1 + \gamma \left(C - C^{'} \right),$

where γ is an increment coefficient of difficulty.

The distance between different instances can be

measured from two aspects, namely, the average

intra-class distance dis_t^1 and the average inter-class distance dis_t^2 . The closer the intra-class distance

and the farther the inter-class distance, the easier

the task. Both of them are measured by the Eu-

clidean distance function $d(\cdot, \cdot)$. Specifically, dis_t^1

 $dis_t^1 = rac{1}{D_t^1} \sum_{i=1}^{C imes K} d\left(\boldsymbol{x}_t^i, \boldsymbol{x}_t^j
ight),$

In more detail, the difficulty of a task is related

(2)

stance embedding x_t^i as follows:

where x_t^i and x_t^j belong to different classes and $D_t^2 = \frac{CK(C-1)K}{2}$. Therefore, the difficulty $\alpha_t^{'}$ of $Task_t$ can be calculated as

$$\alpha_t' = \frac{dis_t^2}{dif_t \cdot dis_t^1}.$$
(6)

As aforesaid, larger learning rates are preferred for easier tasks. Therefore, Equation (6) means a larger $\alpha_t^{'}$ is obtained with dis_t^2 increasing, as well as dif_t and dis_t^1 decreasing, which presents an easier task. Otherwise, a smaller α'_t presents a more difficult task.

As the task-level learning rate is required to multiply the layer-level one in Equation (12), it should be larger than 1 for easier tasks and smaller than 1 for more difficult tasks. Therefore, we formulate the weight $\alpha_t \in [\beta, 1 + \beta]$ by function $q(\cdot)$ as

$$\alpha_{t} = g\left(\alpha_{t}^{'}\right) = nor\left(\alpha_{t}^{'}\right) + \beta, \qquad (7)$$

where $nor(\cdot)$ is the min-max normalization function. In this paper, the bias β is set to 0.5.

The Layer-level Learning Rate Module 3.5

As mentioned earlier, this module contains a learner and a meta learner.

3.5.1 The Learner

In the text classification task, the learner is actually a classifier. Existing models of different types can be employed as the learner, e.g., BERT (Kenton and Toutanova, 2019), PN (Snell et al., 2017) and MLMAN (Ye and Ling, 2019), which are pretrained. By inputting the embedding x_t^i , the learner with the learning rate lr_t , which is obtained by Equation (12), outputs the predicted probability distribution, p_t^i , to different classes. Formally, p_t^i is calculated as follows:

$$\boldsymbol{p}_{t}^{i} = Learner\left(\boldsymbol{x}_{t}^{i}, \boldsymbol{lr}_{t}\right).$$
 (8)

The loss of the learner is defined as l_t , which is calculated by the cross entropy function $H(\cdot, \cdot)$ as

$$U_t = \sum_{i=1}^{C \times K} H\left(\boldsymbol{p}_t^i, \boldsymbol{y}_t^i\right), \qquad (9)$$

where \boldsymbol{y}_t^i is the ground truth distribution of \boldsymbol{x}_t^i to different classes.

3.5.2 The Meta Learner

1

The meta learner allocates different learning rates for different network layers. Let θ be its parameters. Given the layer-level learning rate lr_{t-1} of N dimension corresponding to $Task_{t-1}$ of the learner,

(3)

(4)

Algorithm 1 The Meta Learning Training Process.

- 1 Given a set of labeled training data D_{train}
- 2 Init parameters of the meta leaner as θ
- 3 Given the initial learning rate lr_0 4 For $e \rightarrow 1$ to E do:
- 5 Given a pre-trained learner with lr'_0
- 6 For $t \rightarrow 1$ to T do:
- 7 Given a task $Task_t$ sampled from D_{train}
- 8 $hs_t \leftarrow MetaLearner_{\theta} \left(hs_{t-1}, lr'_{t-1} \right)$

```
9 lr'_t \leftarrow \sigma (Whs_t + b)
```

- 10 $lr_t \leftarrow \alpha_t lr'_t$
- 11 Train the learner with lr_t on $Task_t$
- 12 Compute the loss l_t
- 13 If t = T, calculate the loss $Loss_e$ by summing up l_t 14 Update θ using $Loss_{e-1}$ - $Loss_e$

the hidden state hs_t of the meta learner to $Task_t$ is calculated upon lr'_{t-1} and its last hidden state hs_{t-1} as

$$\boldsymbol{hs}_{t} = MetaLearner_{\theta} \left(\boldsymbol{hs}_{t-1}, \boldsymbol{lr}_{t-1}^{'} \right).$$
 (10)

Then, the layer-level learning rate lr'_t corresponding to $Task_t$ is obtained upon the state hs_t as

$$\boldsymbol{lr}_{t}^{'} = \sigma \left(\boldsymbol{W} \boldsymbol{h} \boldsymbol{s}_{t} + \boldsymbol{b} \right), \qquad (11)$$

where W and b are parameters of a fully-connected layer in the meta learner and σ is the Sigmoid function.

By multiplying the task-level learning rate α_t , the final learning rate is obtained as

$$\boldsymbol{lr}_{t} = \alpha_{t} \boldsymbol{lr}_{t}^{'}.$$
 (12)

The loss of the meta-learner, $Loss_e$, is calculated by summing up all the losses from the learner in the *e*-th iteration, namely,

$$Loss_e = \sum_{t=1}^{T} l_t.$$
(13)

Finally, θ is updated by minimizing the difference between the loss in the last iteration and the current loss, which makes the meta learner converge faster, through applying gradient-based optimization. The training process of meta learning is shown in Algorithm 1.

3.6 The Task-oriented Curriculum-Learning Mechanism

345To get better generalization performance to a new346task, MetaCLSLR introduces a task-oriented cur-347riculum learning mechanism to the meta-training348period of the meta learner. The original curricu-349lum learning mechanism learns from instances with

gradually increasing difficulties in a step-by-step 350 manner. However, in the context of meta learn-351 ing based few-shot learning, we need to pay more 352 attention to tasks with different difficulties. It is acknowledged that when the number of classes in a task increases, its difficulty accordingly increases. 355 In meta learning based few-shot learning, the diffi-356 culty of a CwKs task is increased by giving a larger 357 C. For example, a 10w1s task is more difficult than a 5w1s one. Therefore, a three-stage process 359 with increasing difficulties is completed with the 360 number of classes from C to C+X to C+2X (here-361 inafter denoted as C-(C+X)-(C+2X)), making the 362 meta learner train tasks from easy ones to difficult ones. Besides, a previous study (Munkhdalai and 364 Yu, 2017) found that the models trained on harder tasks may achieve better performance than using 366 the same configurations at both training and test 367 periods. Therefore, in this paper we set that the av-368 erage difficulty of tasks in the meta-training period is always larger than that in the meta-test period to 370 get better performance in test tasks.

373

374

375

376

378

379

380

382

383

384

386

4 Experiments

4.1 Datasets and Evaluation Metrics

| Parameters | Value |
|-----------------------|--|
| γ | 0.1 |
| β | 0.5 |
| k | 3 |
| word emb. dim. | 50 |
| max sentence length | 40 |
| hidden layer dim. | 230 |
| LSTM hidden size | 100 |
| initial learning rate | $[7e^{-3}, 6e^{-3}, 5e^{-3}, 4e^{-3}]$ |
| batch size | 1 |
| iteration | 30000 |
| dropout | 0.2 |

Table 1: The parameter setting in MetaCLSLR.

We conduct experiments on three text classification tasks, i.e., relation classification, news classification, and topic classification, among which the first one is more complicated and challenging than the other two traditional text classification tasks. For relation classification, we choose a typical fewshot learning dataset, FewRel (Han et al., 2018). It should be mentioned that the FewRel dataset used in this paper has only 80 classes, thus marked as FewRel80, because 20 classes of the original FewRel dataset for test are unavailable. We divide FewRel80 into three subsets containing 50, 10 and 20 classes for training, validation and test,

338

339

340

341

343

344

319

| Dataset: FewRel80 | | | | | |
|---------------------------|-------------------|--------|--------|--------|--------|
| Method | | 5w1s | 5w5s | 10w1s | 10w5s |
| model fine-tuning based | BERT | 0.5762 | 0.7109 | 0.5233 | 0.5480 |
| | MetaCLSLR+BERT | 0.6347 | 0.7601 | 0.5672 | 0.5993 |
| | PN-HATT | 0.7319 | 0.8703 | 0.6114 | 0.7632 |
| metric rearning based | MetaCLSLR+PN-HATT | 0.7675 | 0.8929 | 0.6507 | 0.8067 |
| | MLMAN | 0.7957 | 0.9119 | 0.6903 | 0.8516 |
| meta learning based | MetaCLSLR+MLMAN | 0.8182 | 0.9161 | 0.7084 | 0.8530 |
| | Dataset: 20Newsg | roup | | | |
| Me | thod | 3w1s | 3w5s | 6w1s | 6w5s |
| | BERT | 0.7417 | 0.8198 | 0.5876 | 0.7107 |
| model line-tuning based | MetaCLSLR+BERT | 0.7689 | 0.8497 | 0.6195 | 0.7446 |
| | MAML | 0.7612 | 0.8405 | 0.6143 | 0.7451 |
| meta learning based | MetaCLSLR+MAML | 0.7824 | 0.8599 | 0.6479 | 0.7762 |
| matria laarning basad | PN | 0.8463 | 0.9614 | 0.7052 | 0.8887 |
| | MetaCLSLR+PN | 0.8680 | 0.9843 | 0.7233 | 0.9291 |
| Dataset: DBPedia Ontology | | | | | |
| Me | thod | 3w1s | 3w5s | 6w1s | 6w5s |
| model fine-tuning based | BERT | 0.7609 | 0.8256 | 0.6118 | 0.7589 |
| | MetaCLSLR+BERT | 0.7944 | 0.8598 | 0.6540 | 0.7990 |
| mata laaming haaad | MAML | 0.7778 | 0.8571 | 0.6434 | 0.8093 |
| meta tearning based | MetaCLSLR+MAML | 0.8163 | 0.8911 | 0.6814 | 0.8372 |
| matria laarning heard | PN | 0.8428 | 0.9520 | 0.7070 | 0.8896 |
| metric learning based | MetaCLSLR+PN | 0.8683 | 0.9799 | 0.7301 | 0.9104 |

Table 2: The overall results on three benchmark datasets: FewRel80, 20Newsgroup and BDPedia Ontology.

respectively. For news classification, we choose the representative dataset, 20Newsgroup (Dadgar et al., 2016) with 20 news classes. We divide it into subsets with 14 and 6 classes for training and test, respectively. For topic classification, the DB-Pedia Ontology (Zhang et al., 2015) dataset is a classic one with 14 topic classes. We partition it into 8 classes and 6 classes for training and test, respectively.

387

390

393

396

400

401

402

403

404

405

406

407

408

409

410

411

412

We set up four configurations, namely, 5w1s, 5w5s, 10w1s and 1w5s, for each few-shot task on FewRel80. Four settings are considered for the 20Newsgroup and DBPedia Ontology datasets, i.e., 3w1s, 3w5s, 6w1s and 6w5s. In addition, the same as the previous study in (Obamuyide and Vlachos, 2019), average accuracy is adopted as the evaluation metric.

4.2 Implementation Details and Parameters Setting

Table 1 presents the parameter setting of Meta-CLSLR. For the encoder module, CNN is employed as the instance encoder and the word embeddings pre-trained in GloVe (Pennington et al., 2014) is adopted as the initial embeddings. In practice, we choose the embedding set, Wikipedia 2014 + Gigaword 5, which contains 6B tokens and 400K words. The word embeddings are of 50 dimensions. For the parameters of the CNN encoder, we follow the settings used in (Zeng et al., 2014). For the layer-level learning rate module, LSTM is selected as the meta learner, because of its simple implementation, fast training speed and satisfying performance. Furthermore, for the curriculum learning, we choose two settings on each dataset, i.e., 10-15-20 and 15-20-25 on FewRel80, 5-7-9 and 7-9-11 on 20Newsgroup and 4-5-6 and 5-6-7 on DBPedia Ontology, respectively. The detailed setting of curriculum learning is described in Section 4.5.3.

413

414

415

416

417

418

419

420

421

422

423

424

425

426

427

428

429

430

431

432

433

434

435

4.3 Baseline Models

We choose baseline models of three categories (i.e., model fine-tuning based, metric learning based and meta learning based) as the learner in MetaCLSLR. The selected models and reasons are as follows:

- 1. Model fine-tuning based:
 - BERT (Kenton and Toutanova, 2019), a widely adopted model of this category on FewRel80, 20Newsgroup and DBPedia Ontology.
- 2. Metric learning based:
 - PN (Snell et al., 2017), a widely adopted 436

| Method | | 5w1s | 5w5s | 10w1s | 10w5s |
|-------------------------|-------------------|--------|--------|--------|--------|
| model fine-tuning based | SLR+BERT | 0.6174 | 0.7456 | 0.5532 | 0.5851 |
| | CL+BERT | 0.5904 | 0.7263 | 0.5370 | 0.5615 |
| | MetaCLSLR+BERT | 0.6347 | 0.7601 | 0.5672 | 0.5993 |
| metric learning based | SLR+PN-HATT | 0.7592 | 0.8831 | 0.6435 | 0.7982 |
| | CL+PN-HATT | 0.7380 | 0.8719 | 0.6152 | 0.7792 |
| | MetaCLSLR+PN-HATT | 0.7675 | 0.8929 | 0.6507 | 0.8067 |
| meta learning based | SLR+MLMAN | 0.8103 | 0.9145 | 0.7059 | 0.8541 |
| | CL+MLMAN | 0.8167 | 0.9136 | 0.7042 | 0.8507 |
| | MetaCLSLR+MLMAN | 0.8182 | 0.9161 | 0.7084 | 0.8550 |

Table 3: The results of the ablation study on SLR and CL on FewRel80.

| Method | 5w1s | 5w5s |
|------------------|--------|--------|
| Adadelta+BERT | 0.5825 | 0.7232 |
| RMSProp+BERT | 0.5887 | 0.7203 |
| Adam+BERT | 0.5943 | 0.7261 |
| SLR+BERT | 0.6174 | 0.7456 |
| Adadelta+PN-HATT | 0.7386 | 0.8612 |
| RMSProp+PN-HATT | 0.7327 | 0.8446 |
| Adam+PN-HATT | 0.7101 | 0.8300 |
| SLR+PN-HATT | 0.7592 | 0.8831 |
| Adadelta+MLMAN | 0.7995 | 0.9063 |
| RMSProp+MLMAN | 0.8007 | 0.9087 |
| Adam+MLMAN | 0.8027 | 0.9108 |
| SLR+MLMAN | 0.8103 | 0.9145 |

Table 4: The results of different models with SLR and other self-adaptive learning rate mechanisms on FewRel80.

| model of this category on 20Newsgroup |
|---------------------------------------|
| and DBPedia Ontology. |

- PN-HATT (Gao et al., 2019), the stateof-the-art model of this category on FewRel80.
- 3. Meta learning based:

437

438

439

440

441

442

443

444

445

446

447

448

449

- MAML (Finn et al., 2017), a widely adopted model of this category on 20Newsgroup and DBPedia Ontology.
- MLMAN (Ye and Ling, 2019), the stateof-the-art model having open source code on FewRel80.

4.4 Experimental Results

Table 2 presents the overall experimental results, 450 where we can see all of the MetaCLSLR models 451 with BERT, PN-HATT, MLMAN, PN and MAML 452 as their learners consistently outperform those 453 baselines on all datasets. The accuracy of the 454 model fine-tuning based and metric learning based 455 MetaCLSLR models increases by 4-6% and 2-4% 456 on FewRel80, respectively. However, for Meta-457 CLSLR+MLMAN, its performance is improved 458

less than those of the former two categories; But it still achieves the best results. Moreover, all kinds of MetaCLSLR models are observed an accuracy promotion by 2-4% compared to the baselines on the majority of few-shot tasks on 20Newsgroup and DBPedia Ontology. The overall experimental results clearly prove that MetaCLSLR is effective to different models and on different datasets and tasks. 459

460

461

462

463

464

465

466

467 468

469

470

471

472

473

474

475

476

477

478

479

480

481

482

483

484

485

486

487

488

489

490

491

492

493

494

495

496

497

4.5 Ablation Studies

In this subsection, we conduct ablation studies to investigate the effectiveness and impact of, both Self-adaptive Learning Rate (SLR) and Curriculum Learning (CL), as well as their impacts on the performance of MetaCLSLR. The experimental results are shown in Tables 3-6. For the sake of space limitation, only the results on FewRel80 are presented. As shown in Table 3, the performance of all ablated models without SLR and CL consistently falls on all tasks. It is indicated that both SLR and CL contribute to the effectiveness of MetaCLSLR. Besides, it can be observed that SLR is more important to MetaCLSLR than CL, for the larger performance improvement. Actually, except the 5w1s task for MLMAN, all of the other tasks get better results with SLR. The same conclusion is observed on 20Newsgroup and DBPedia Ontology, except the model MAML in the 3w5s task. In what follows, more results and analysis are given so as to provide deeper insights into the effectiveness and importance of SLR and CL.

4.5.1 SLRs for Different Tasks and Network Layers

SLRs consists of two subsets: the Self-adaptive Learning rates for different Tasks (SLR-T) and different neural network Layers (SLR-L). As shown in Table 5, the performance of all models without SLR-T and SLR-L consistently decreases on all

| Method | | 5w1s | 5w5s | 10w1s | 10w5s |
|-------------------------|---------------|--------|--------|--------|--------|
| | SLR-L+BERT | 0.6145 | 0.7412 | 0.5509 | 0.5823 |
| model fine-tuning based | SLR-T+BERT | 0.5771 | 0.7148 | 0.5261 | 0.5502 |
| | SLR+BERT | 0.6174 | 0.7456 | 0.5532 | 0.5851 |
| | SLR-L+PN-HATT | 0.7578 | 0.8811 | 0.6414 | 0.7956 |
| metric learning based | SLR-T+PN-HATT | 0.7354 | 0.8723 | 0.6137 | 0.7648 |
| | SLR+PN-HATT | 0.7592 | 0.8831 | 0.6435 | 0.7982 |
| | SLR-L+MLMAN | 0.8095 | 0.9139 | 0.7051 | 0.8537 |
| meta learning based | SLR-T+MLMAN | 0.7982 | 0.9125 | 0.6931 | 0.8522 |
| | SLR+MLMAN | 0.8103 | 0.9145 | 0.7059 | 0.8541 |

Table 5: The results of the ablation study on SLRs on FewRel80.

| Method | 5w1s | 5w5s |
|----------------------|--------|--------|
| SLR+5-10-15+BERT | 0.6285 | 0.7498 |
| SLR+10-15-20+BERT | 0.6347 | 0.7601 |
| SLR+15-20-25+BERT | 0.6315 | 0.7581 |
| SLR+20-25-30+BERT | 0.6239 | 0.7475 |
| SLR+5-10-15+PN-HATT | 0.7562 | 0.8836 |
| SLR+10-15-20+PN-HATT | 0.7565 | 0.8929 |
| SLR+15-20-25+PN-HATT | 0.7675 | 0.8877 |
| SLR+20-25-30+PN-HATT | 0.7645 | 0.8926 |
| SLR+5-10-15+MLMAN | 0.8102 | 0.9135 |
| SLR+10-15-20+MLMAN | 0.8182 | 0.9150 |
| SLR+15-20-25+MLMAN | 0.8133 | 0.9161 |
| SLR+20-25-30+MLMAN | 0.8046 | 0.9146 |

Table 6: The results of different CL settings onFewRel80.

tasks, indicating that both SLR-T and SLR-L contribute to the effectiveness of SLR. However, the models with SLR-L outperform those with SLR-T. That means, although both task-level and layer-level learning rates work, the layer-level ones are more important and effective to the performance of models than their counterparts.

4.5.2 SLR Comparing to Other Self-Adaptive Learning Rate Methods

Furthermore, some experimental results for comparing our SLR with other self-adaptive learning rate mechanisms, i.e., Adadelta (Zeiler, 2012), RM-SProp (Hinton et al., 2012) and Adam (Kingma and Ba, 2014), are shown in Table 4. As we can see, the models with our SLR outperform the others, which proves the better effectiveness of our SLR. Moreover, the performance even gets a large demotion for PN-HATT with RMSProp and Adam, indicating that our SLR is more robust to different kinds of models than the others.

4.5.3 Different CL Settings

498

499

500

502

503

504

507

508

509

510

511

512

513

514

515

516

517

518

519The task-oriented CL is another major contribution520of MetaCLSLR. Based on the CL mechanism, we521set up four training configurations for each task on

FewRel80, namely, 5-10-15, 10-15-20, 15-20-25 and 20-25-30. For the sake of space limitation, only results on the 5w1s and 5w5s tasks are shown in Table 6, which demonstrate that all the best results are obtained at two settings, 10-15-20 and 15-20-25. This may be due to the following reason: the 5-10-15 configuration is the simplest one, which does not reach the difficulty to get the best performance of a model, whilst the 20-25-30 configuration is too hard and the learner cannot be well trained at the training period and thus cannot work well at the test period.

522

523

524

525

526

527

528

529

530

531

532

533

534

535

536

537

538

539

540

541

542

543

544

545

546

547

548

549

550

551

552

553

554

555

556

557

558

559

Furthermore, four training configurations, namely, 3-5-7, 5-7-9, 7-9-11 and 9-11-13 are examined on 20Newsgroup. Four training configurations, i.e., 3-4-5, 4-5-6, 5-6-7 and 6-7-8 are also studied on DBPedia Ontology. Similar conclusions are observed on these datasets. The results are not presented due to space limitation.

5 Conclusion and Future Work

In this paper, we proposed a novel meta learning framework, called MetaCLSLR, for few-shot text classification. MetaCLSLR can self-adaptively obtain different learning rates for different tasks and different network layers. Moreover, a taskoriented curriculum learning mechanism is introduced into few-shot learning so as to achieve a better generalization ability for the meta learner. Meta-CLSLR is evaluated with three typical text classification tasks, relation classification, news classification and topic classification, on three benchmark datasets: FewRel80, 20Newsgroup and DB-Pedia Ontology, respectively. Experimental results demonstrate superior performance of MetaCLSLR on all tasks and all datasets. In the future, we will explore few-shot learning under the unbalance learning scenarios because they are ubiquitous in the real world.

560 Acknowledgments

561 References

562

564

566

567

570

571

573

574

575

576

577

578

581

583

584

585

587

588

601

603

604

611

- Yoshua Bengio, Jérôme Louradour, Ronan Collobert, and Jason Weston. 2009. Curriculum learning. In Proceedings of the 26th annual international conference on machine learning, pages 41–48.
- Seyyed Mohammad Hossein Dadgar, Mohammad Shirzad Araghi, and Morteza Mastery Farahani.
 2016. A novel text mining approach based on tf-idf and support vector machine for news classification.
 In 2016 IEEE International Conference on Engineering and Technology (ICETECH), pages 112–116.
 IEEE.
- Chelsea Finn, Pieter Abbeel, and Sergey Levine. 2017. Model-agnostic meta-learning for fast adaptation of deep networks. In *International Conference on Machine Learning*, pages 1126–1135. PMLR.
- Carlos Florensa, David Held, Markus Wulfmeier, Michael Zhang, and Pieter Abbeel. 2017. Reverse curriculum generation for reinforcement learning. In *Conference on robot learning*, pages 482–495. PMLR.
- Tianyu Gao, Xu Han, Zhiyuan Liu, and Maosong Sun. 2019. Hybrid attention-based prototypical networks for noisy few-shot relation classification. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 33, pages 6407–6414.
- Chen Gong, Jian Yang, and Dacheng Tao. 2019. Multimodal curriculum learning over graphs. *ACM Transactions on Intelligent Systems and Technology (TIST)*, 10(4):1–25.
 - Sheng Guo, Weilin Huang, Haozhi Zhang, Chenfan Zhuang, Dengke Dong, Matthew R Scott, and Dinglong Huang. 2018. Curriculumnet: Weakly supervised learning from large-scale web images. In *Proceedings of the European Conference on Computer Vision (ECCV)*, pages 135–150.
- Xu Han, Hao Zhu, Pengfei Yu, Ziyun Wang, Yuan Yao, Zhiyuan Liu, and Maosong Sun. 2018. Fewrel: A large-scale supervised few-shot relation classification dataset with state-of-the-art evaluation. In *Proceedings of the 2018 Conference on Empirical Methods in Natural Language Processing*, pages 4803–4809.
- Geoffrey Hinton, Nitish Srivastava, and Kevin Swersky. 2012. Rmsprop: Divide the gradient by a running average of its recent magnitude. *Neural networks for machine learning, Coursera lecture 6e*, page 13.
- Jeremy Howard and Sebastian Ruder. 2018. Universal language model fine-tuning for text classification. In Proceedings of the 56th Annual Meeting of the Association for Computational Linguistics (Volume 1: Long Papers), pages 328–339.

Muhammad Abdullah Jamal and Guo-Jun Qi. 2019. Task agnostic meta-learning for few-shot learning. In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition, pages 11719– 11727. 612

613

614

615

616

617

618

619

620

621

622

623

624

625

626

627

628

629

630

631

632

633

634

635

636

637

638

639

640

641

642

643

644

645

646

647

648

649

650

651

652

653

654

655

656

657

658

659

660

661

662

663

- Lu Jiang, Deyu Meng, Teruko Mitamura, and Alexander G Hauptmann. 2014. Easy samples first: Selfpaced reranking for zero-example multimedia search. In *Proceedings of the 22nd ACM international conference on Multimedia*, pages 547–556.
- Jacob Devlin Ming-Wei Chang Kenton and Lee Kristina Toutanova. 2019. Bert: Pre-training of deep bidirectional transformers for language understanding. In *Proceedings of NAACL-HLT*, pages 4171–4186.
- Diederik P Kingma and Jimmy Ba. 2014. Adam: A method for stochastic optimization. *arXiv e-prints*, pages arXiv–1412.
- Siwei Lai, Liheng Xu, Kang Liu, and Jun Zhao. 2015. Recurrent convolutional neural networks for text classification. In *Proceedings of the Twenty-Ninth AAAI Conference on Artificial Intelligence*, pages 2267– 2273.
- Fei-Fei Li et al. 2003. A bayesian approach to unsupervised one-shot learning of object categories. In *Proceedings Ninth IEEE International Conference on Computer Vision*, pages 1134–1141. IEEE.
- Mike Mintz, Steven Bills, Rion Snow, and Dan Jurafsky. 2009. Distant supervision for relation extraction without labeled data. In *Proceedings of the Joint Conference of the 47th Annual Meeting of the ACL and the 4th International Joint Conference on Natural Language Processing of the AFNLP*, pages 1003– 1011.
- Tsendsuren Munkhdalai and Hong Yu. 2017. Meta networks. In *International Conference on Machine Learning*, pages 2554–2563. PMLR.
- Akihiro Nakamura and Tatsuya Harada. 2019. Revisiting fine-tuning for few-shot learning. *arXiv preprint arXiv:1910.00216*.
- Sanmit Narvekar, Jivko Sinapov, and Peter Stone. 2017. Autonomous task sequencing for customized curriculum design in reinforcement learning. In *IJCAI*, pages 2536–2542.
- Abiola Obamuyide and Andreas Vlachos. 2019. Modelagnostic meta-learning for relation classification with limited supervision. In *Proceedings of the 57th Annual Meeting of the Association for Computational Linguistics*, pages 5873–5879.
- Jeffrey Pennington, Richard Socher, and Christopher D Manning. 2014. Glove: Global vectors for word representation. In *Proceedings of the 2014 conference on empirical methods in natural language processing (EMNLP)*, pages 1532–1543.

- 665 666 667 668 669 670 671 672 673 674 675 676 676 677 678 679 680
- 677 678 679 680 681 682 683 684 685 686 687 688 689 690 691 692 693 694 695 696 697 698 699 700
- 694 695 696 697 698 699 700 701 702 703 704 705 706
- 7
- 7
- 7
- _
- 712 713 714

714 715 716

716

718 719

- Emmanouil Antonios Platanios, Otilia Stretcu, Graham Neubig, Barnabas Poczos, and Tom M Mitchell. 2019. Competence-based curriculum learning for neural machine translation. In *Proceedings of NAACL-HLT*, pages 1162–1172.
- Meng Qu, Jian Tang, and Jiawei Han. 2018. Curriculum learning for heterogeneous star network embedding via deep reinforcement learning. In *Proceedings of the Eleventh ACM International Conference on Web Search and Data Mining*, pages 468–476.
- Aniruddh Raghu, Maithra Raghu, Samy Bengio, and Oriol Vinyals. 2019. Rapid learning or feature reuse? towards understanding the effectiveness of maml. In *International Conference on Learning Representations*.
- Zhipeng Ren, Daoyi Dong, Huaxiong Li, and Chunlin Chen. 2018. Self-paced prioritized curriculum learning with coverage penalty in deep reinforcement learning. *IEEE transactions on neural networks and learning systems*, 29(6):2216–2226.
- Adam Santoro, Sergey Bartunov, Matthew Botvinick, Daan Wierstra, and Timothy Lillicrap. 2016. Oneshot learning with memory-augmented neural networks. *arXiv preprint arXiv:1605.06065*.
- Jake Snell, Kevin Swersky, and Richard Zemel. 2017. Prototypical networks for few-shot learning. In *Proceedings of the 31st International Conference on Neural Information Processing Systems*, pages 4080–4090.
- Yi Tay, Shuohang Wang, Anh Tuan Luu, Jie Fu, Minh C Phan, Xingdi Yuan, Jinfeng Rao, Siu Cheung Hui, and Aston Zhang. 2019. Simple and effective curriculum pointer-generator networks for reading comprehension over long narratives. In *Proceedings of the 57th Annual Meeting of the Association for Computational Linguistics*, pages 4922–4931.
- Oriol Vinyals, Charles Blundell, Timothy Lillicrap, Daan Wierstra, et al. 2016. Matching networks for one shot learning. *Advances in neural information processing systems*, 29:3630–3638.
- Jiawei Wu, Wenhan Xiong, and William Yang Wang. 2019. Learning to learn and predict: A meta-learning approach for multi-label classification. In Proceedings of the 2019 Conference on Empirical Methods in Natural Language Processing and the 9th International Joint Conference on Natural Language Processing (EMNLP-IJCNLP), pages 4354–4364.
- Tongtong Wu, Xuekai Li, Yuan-Fang Li, Gholamreza Haffari, Guilin Qi, Yujin Zhu, and Guoqiang Xu. 2021. Curriculum-meta learning for order-robust continual relation extraction. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 35, pages 10363–10369.
- Zhi-Xiu Ye and Zhen-Hua Ling. 2019. Multi-level matching and aggregation network for few-shot relation classification. In *Proceedings of the 57th Annual*

Meeting of the Association for Computational Linguistics, pages 2872–2881. 721

722

723

724

725

726

727

728

729

730

731

732

733

- Matthew D Zeiler. 2012. Adadelta: an adaptive learning rate method. *arXiv preprint arXiv:1212.5701*.
- Daojian Zeng, Kang Liu, Siwei Lai, Guangyou Zhou, and Jun Zhao. 2014. Relation classification via convolutional deep neural network. In *Proceedings of COLING 2014, the 25th International Conference on Computational Linguistics: Technical Papers*, pages 2335–2344.
- Xiang Zhang, Junbo Zhao, and Yann LeCun. 2015. Character-level convolutional networks for text classification. *Advances in neural information processing systems*, 28:649–657.