

RETHINKING UNCERTAINTY ESTIMATION IN NATURAL LANGUAGE GENERATION

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ABSTRACT

Large Language Models (LLMs) are increasingly employed in real-world applications, driving the need to evaluate the trustworthiness of their generated text. To this end, reliable uncertainty estimation is essential. Leading uncertainty estimation methods generate and analyze multiple output sequences, which is computationally expensive and impractical at scale. In this work, we inspect the theoretical foundations of these methods and explore new directions to enhance computational efficiency. Building on the framework of proper scoring rules, we find that the negative log-likelihood of the most likely output sequence constitutes a theoretically grounded uncertainty measure. To approximate this alternative measure, we propose G-NLL, obtained using a single output sequence from greedy decoding. This approach streamlines uncertainty estimation while preserving theoretical rigor. Empirical results demonstrate that G-NLL achieves state-of-the-art performance across various LLMs and tasks. Our work lays the foundation for efficient and reliable uncertainty estimation in natural language generation, challenging the necessity of the prevalent methods that are more complex and resource-intensive.

1 INTRODUCTION

Despite advances in natural language generation (NLG), determining the trustworthiness of generated text remains challenging. Addressing this requires reliably estimating the uncertainty a language model has regarding its generated text. Although a low level of uncertainty does not guarantee factual correctness, particularly when the generated text is based on consistent but inaccurate training data, uncertainty estimates remain a reliable indicator of errors at present (Farquhar et al., 2024).

Assessing predictive uncertainty in language models is challenging due to their stochastic, autoregressive nature. Each token is selected probabilistically, leading to diverse outputs for the same input. Furthermore, the vast space of possible sequences is computationally intractable. Common uncertainty estimation methods thus rely on expectations over output distributions, such as sequence entropy (Malinin & Gales, 2021; Kuhn et al., 2023; Duan et al., 2024; Farquhar et al., 2024), which in turn requires sampling multiple output sequences. However, this is computationally costly due to the large number of model parameters. As a result, only a small subset of outputs is sampled in practice. However, differences between sampled sequences do not always indicate uncertainty, as they may vary lexically while remaining semantically similar. Some methods use inference models to assess semantics (Kuhn et al., 2023; Aichberger et al., 2024; Farquhar et al., 2024), improving uncertainty estimates but adding complexity and additional computation. These challenges make large-scale uncertainty estimation impractical for real-world applications.

Efficient uncertainty estimation methods are needed to ensure the trustworthiness of the language model’s answer without imposing excessive computational demands. To address this need, we introduce G-NLL, an uncertainty measure computed with a single output sequence. We theoretically motivate our measure by building on insights from the framework of proper scoring rules (Gneiting & Raftery, 2007) that has recently been investigated for uncertainty estimation in the standard clas-

sification setting (Kotelevskii & Panov, 2024; Hofman et al., 2024). Specifically, we extend proper scoring rules for uncertainty estimation to NLG and explore the zero-one score as an alternative to the prevalent logarithmic score. The resulting uncertainty measure is straightforward: it is the negative log-likelihood of the most likely output sequence, which we approximate using greedy decoding to obtain G-NLL. By eliminating the need to generate and analyze multiple output sequences, our measure significantly reduces computational costs and algorithmic complexity.

Noteworthy, some recent works have considered the sequence likelihood for uncertainty estimation in NLG (Fadeeva et al., 2023; Bakman et al., 2024; Yaldiz et al., 2024; Fadeeva et al., 2024; Vazhentsev et al., 2024; Plaut et al., 2024; Abbasi-Yadkori et al., 2024), as detailed in Apx. A. However, these works introduce the approach as a heuristic without providing theoretical justification, and thus often utilize arbitrary output sequences rather than focusing explicitly on obtaining the most likely one. Furthermore, many prominent works on uncertainty estimation in NLG completely overlook using the sequence likelihood as a baseline for comparison (Kuhn et al., 2023; Duan et al., 2024; Manakul et al., 2023; Farquhar et al., 2024). To close this gap, our work derives the maximum sequence likelihood as proper uncertainty measure and proposes the efficient approximation G-NLL.

Our experiments on question answering tasks demonstrate that G-NLL matches and even exceeds the performance of current state-of-the-art uncertainty estimation measures across various model classes, model sizes, training stages, tasks, datasets, and evaluation metrics. While maintaining theoretical rigor, our measure offers an effective and scalable approach to uncertainty estimation in NLG. Therefore, G-NLL serves not only as a strong baseline for future methods, but also as a highly practical solution for widespread adoption in real-world applications. Our main contributions are:

- We derive the negative log-likelihood of the most likely output sequence as an alternative uncertainty measure in NLG and introduce G-NLL, an efficient approximation using greedy decoding.
- We provide a rigorous theoretical foundation for this alternative measure, based on established principles in uncertainty estimation theory and proper scoring rules.
- We conduct extensive experiments showing that G-NLL is both efficient and reliable, matching or outperforming state-of-the-art methods while significantly reducing computational costs.

2 PREDICTIVE UNCERTAINTY IN NLG

To introduce predictive uncertainty in NLG, we first provide background on language models. In Sec.2.1, we discuss proper scoring rules and their link to measuring predictive uncertainty in NLG. Sec.2.2 interprets established measures within this framework. Finally, we introduce the maximum sequence probability and its approximation G-NLL in Sec. 2.3 by considering a different scoring rule.

Preliminaries. We assume a fixed training dataset $\mathcal{D} = \{\mathbf{s}_i\}_{i=1}^N$ consisting of N token sequences $\mathbf{s} = (s_1, \dots, s_T)$ where individual tokens $s_t \in \mathcal{V}$ are from a given vocabulary \mathcal{V} . Each token at step t is assumed to be sampled according to the predictive distribution $p(s_t \mid \mathbf{s}_{<t}, \mathbf{w}^*)$, conditioned on the sequence of preceding tokens $\mathbf{s}_{<t}$ and the true (but unknown) language model parameters \mathbf{w}^* . We assume that the given model class can theoretically represent the true predictive distribution, a common and usually necessary assumption (Hüllermeier & Waegeman, 2021). The likelihood of some model parameters $\tilde{\mathbf{w}}$ matching \mathbf{w}^* is given by the posterior $p(\tilde{\mathbf{w}} \mid \mathcal{D}) = p(\mathcal{D} \mid \tilde{\mathbf{w}})p(\tilde{\mathbf{w}})/p(\mathcal{D})$.

The input to a given language model parameterized by \mathbf{w} is a sequence $\mathbf{x} = (x_1, \dots, x_M)$ and the output is a sequence $\mathbf{y} = (y_1, \dots, y_T) \in \mathcal{Y}_T$, with $x, y \in \mathcal{V}$ and \mathcal{Y}_T being the set of all possible output sequences with sequence length T . The likelihood of a token $y_t \in \mathbf{y}$ being generated by the language model is conditioned on both the input sequence and all previously generated tokens, denoted as $p(y_t \mid \mathbf{x}, \mathbf{y}_{<t}, \mathbf{w})$. The likelihood of output sequences $\mathbf{y} \in \mathcal{Y}_T$ being generated by the language model is then the product of the individual token probabilities, denoted as $p(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) = \prod_{t=1}^T p(y_t \mid \mathbf{x}, \mathbf{y}_{<t}, \mathbf{w})$ (Sutskever et al., 2014), while the heuristic length-normalized variant is $\bar{p}(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) = \exp \left\{ \frac{1}{T} \sum_{t=1}^T \log p(y_t \mid \mathbf{x}, \mathbf{y}_{<t}, \mathbf{w}) \right\}$ (Malinin & Gales, 2021).

Calculating the likelihood that a specific output sequence \mathbf{y}' is generated by the language model parameterized by \mathbf{w} is straightforward. The language model directly provides the token likelihoods for a given input sequence. However, determining the full probability distribution on all possible output sequences is considerably more challenging, since the size of \mathcal{Y}_T increases exponentially with the sequence length. The computational complexity of evaluating all possible sequences increases with

$\mathcal{O}(|\mathcal{V}|^T)$. Since the vocabulary sizes $|\mathcal{V}|$ of modern language models are well over a hundred thousand tokens, this distribution becomes intractable to determine, even for relatively short maximal sequence lengths T (Dubey et al., 2024).

2.1 PROPER SCORING RULES AND THE RELATION TO UNCERTAINTY MEASURES IN NLG

We next give an introduction to proper scoring rules and discuss how they give rise to uncertainty measures. For more details, in the standard classification setting, we refer to Hofman et al. (2024); Kotelevskii & Panov (2024). Proper scoring rules are a class of functions that evaluate the quality of probabilistic predictions by assigning a numerical score based on the predictive distribution and actual observations (Gneiting & Raftery, 2007). In particular, a proper scoring rule is an extended real-valued function $S : \mathcal{P} \times \mathcal{Y} \rightarrow [-\infty, \infty]$, such that $S(p, \mathbf{y})$ is \mathcal{P} -quasi-integrable over a convex class of probability measures \mathcal{P} . A scoring rule is called proper relative to \mathcal{P} if the expected score is minimized when the distribution from which the outcomes $\mathbf{y} \in \mathcal{Y}$ are sampled matches the evaluated distribution $p \in \mathcal{P}$, and it is called strictly proper if this minimum is unique. In the context of uncertainty estimation in NLG, the general notion of proper scoring rules assigns a numerical score reflecting the degree to which an observed output sequence \mathbf{y}' aligns with the predictive distribution of the true model $p(\mathbf{y} | \mathbf{x}, \mathbf{w}^*)$, denoted as

$$S(p(\mathbf{y} | \mathbf{x}, \mathbf{w}^*), \mathbf{y}') . \quad (1)$$

To obtain concrete uncertainty measures, we need to make two specific assumptions (Schweighofer et al., 2024). First, we have to define the predictive distribution used to sample output sequences. Following Aichberger et al. (2024), we assume that we use a single, given “off-the-shelf” language model with parameters \mathbf{w} to sample output sequences $\mathbf{y}' \sim p(\mathbf{y}' | \mathbf{x}, \mathbf{w})$. This assumption is also implicitly used in other works (Kuhn et al., 2023; Fadeeva et al., 2024; Farquhar et al., 2024) and is intuitively reasonable, since our main concern is the uncertainty of the output of a specific language model. Thus, we consider the expected score for possible output sequences under the predictive distribution of the given language model, denoted as $E_{p(\mathbf{y}' | \mathbf{x}, \mathbf{w})} [S(p(\mathbf{y} | \mathbf{x}, \mathbf{w}^*), \mathbf{y}')]$. This quantifies how well the predictive distribution of the given language model aligns with the true predictive distribution, capturing predictive uncertainty. Second, we have to define how the true model is approximated. We consider a Bayesian approximation of the true model, i.e., we consider each possible language model $\tilde{\mathbf{w}}$ according to its posterior probability $p(\tilde{\mathbf{w}} | \mathcal{D})$ (Schweighofer et al., 2023b;a). Thus, we perform a posterior expectation over the expected score, denoted as $E_{p(\tilde{\mathbf{w}} | \mathcal{D})} [E_{p(\mathbf{y}' | \mathbf{x}, \mathbf{w})} [S(p(\mathbf{y} | \mathbf{x}, \tilde{\mathbf{w}}), \mathbf{y}')]]$, which can be additively decomposed into an entropy term and a divergence term (Gneiting & Raftery, 2007; Kull & Flach, 2015):

$$\begin{aligned} & \underbrace{E_{p(\tilde{\mathbf{w}} | \mathcal{D})} [E_{p(\mathbf{y}' | \mathbf{x}, \mathbf{w})} [S(p(\mathbf{y} | \mathbf{x}, \tilde{\mathbf{w}}), \mathbf{y}')]]}_{\text{expected score}} = \\ & \underbrace{E_{p(\mathbf{y}' | \mathbf{x}, \mathbf{w})} [S(p(\mathbf{y} | \mathbf{x}, \mathbf{w}), \mathbf{y}')] }_{\text{entropy term}} + \underbrace{E_{p(\tilde{\mathbf{w}} | \mathcal{D})} [E_{p(\mathbf{y}' | \mathbf{x}, \mathbf{w})} [S(p(\mathbf{y} | \mathbf{x}, \tilde{\mathbf{w}}), \mathbf{y}') - S(p(\mathbf{y} | \mathbf{x}, \mathbf{w}), \mathbf{y}')]]}_{\text{divergence term}} \end{aligned} \quad (2)$$

The expected score over possible output sequences \mathbf{y}' and language models $\tilde{\mathbf{w}}$ captures the *total* uncertainty of the given language model. The entropy term reflects *aleatoric* uncertainty, which quantifies the inherent stochasticity of generating output sequences with a given language model (Aichberger et al., 2024). The divergence term reflects *epistemic* uncertainty, which quantifies the uncertainty due to lack of knowledge about the true language model parameters arising from limited data (Houlsby et al., 2011; Gal, 2016; Malinin, 2019; Hüllermeier & Waegeman, 2021). Finally, we have not yet specified the proper scoring rule S to derive concrete measures of uncertainty, which we will address in the following sections.

2.2 ESTABLISHED UNCERTAINTY MEASURES IN NLG BASED ON THE LOGARITHMIC SCORE

The logarithmic score is typically assumed implicitly in both the standard classification (Houlsby et al., 2011; Gal, 2016) and the NLG setting (Malinin & Gales, 2021; Kuhn et al., 2023) to derive uncertainty measures. This is due to the grounding of the resulting measures in information theory (Lahlou et al., 2023; Gruber & Buettner, 2023; Hofman et al., 2024; Kotelevskii & Panov, 2024). In the context of NLG, the logarithmic score considers the negative log-likelihood of a generated output sequence \mathbf{y}' :

$$S_{\log}(p(\mathbf{y} | \mathbf{x}, \cdot), \mathbf{y}') = -\log p(\mathbf{y} = \mathbf{y}' | \mathbf{x}, \cdot) \quad (3)$$

Substituting the logarithmic score into Eq. (2) results in the cross-entropy $\text{CE}(\cdot; \cdot)$ between the output sequence distribution of the given language model and that of every possible language model according to their posterior probability $p(\tilde{\mathbf{w}} | \mathcal{D})$ (Aichberger et al., 2024):

$$\underbrace{E_{p(\tilde{\mathbf{w}}|\mathcal{D})} [\text{CE}(p(\mathbf{y} | \mathbf{x}, \mathbf{w}); p(\mathbf{y} | \mathbf{x}, \tilde{\mathbf{w}}))]}_{\text{total}} = \underbrace{H(p(\mathbf{y} | \mathbf{x}, \mathbf{w}))}_{\text{aleatoric}} + \underbrace{E_{p(\tilde{\mathbf{w}}|\mathcal{D})} [\text{KL}(p(\mathbf{y} | \mathbf{x}, \mathbf{w}) \| p(\mathbf{y} | \mathbf{x}, \tilde{\mathbf{w}}))]}_{\text{epistemic}} \quad (4)$$

The epistemic uncertainty is captured by a posterior expectation of the Kullback-Leibler divergence $\text{KL}(\cdot \| \cdot)$ between the output sequence distribution of the given model and that of all possible models. This requires considering every possible parameterization of the model. Since modern language models have billions of parameters (Radford et al., 2018; Zhang et al., 2022; Touvron et al., 2023; Zuo et al., 2024; Dubey et al., 2024), the epistemic uncertainty is challenging to estimate.

Current work usually focuses on the aleatoric uncertainty, captured by the Shannon entropy $H(\cdot)$ of the output sequence distribution of the given language model (Kuhn et al., 2023; Aichberger et al., 2024; Farquhar et al., 2024). Measures based on the logarithmic score (predictive entropy and semantic entropy) take into account the entire distribution of possible output sequences to calculate the uncertainty estimate.

Predictive Entropy. The aleatoric uncertainty under a given language model is the entropy of the output sequence distribution, commonly referred to as Predictive Entropy (PE) (Malinin & Gales, 2021). Intuitively, high PE implies that the language model is likely to generate different output sequences from the same input sequence, indicating high uncertainty of the language model. PE is generally estimated by Monte Carlo (MC) sampling of output sequences (Malinin & Gales, 2021):

$$\begin{aligned} H(p(\mathbf{y} | \mathbf{x}, \mathbf{w})) &= E_{p(\mathbf{y}|\mathbf{x},\mathbf{w})} [-\log p(\mathbf{y} | \mathbf{x}, \mathbf{w})] \\ &\approx \frac{1}{N} \sum_{n=1}^N -\log p(\mathbf{y}^n | \mathbf{x}, \mathbf{w}), \quad \mathbf{y}^n \sim p(\mathbf{y} | \mathbf{x}, \mathbf{w}). \end{aligned} \quad (5)$$

Semantic Entropy. Semantic Entropy (SE) (Kuhn et al., 2023; Farquhar et al., 2024) is based on the fact that output sequences may be different on a token level but equivalent on a semantic level. In such cases, the PE can be misleading, as it indicates high uncertainty even when different output sequences have the same semantic meaning. Thus, instead of the entropy of the output sequence distribution, the entropy of the semantic cluster distribution is considered, denoted as $p(c | \mathbf{x}, \mathbf{w}) = \sum_{\mathbf{y}} p(c | \mathbf{x}, \mathbf{y}, \mathbf{w}) p(\mathbf{y} | \mathbf{x}, \mathbf{w})$. The probability of an output sequence belonging to a semantic cluster is usually approximated with a separate natural language inference model. SE thus measures uncertainty about the semantics of output sequences and is defined as

$$\begin{aligned} H(p(c | \mathbf{x}, \mathbf{w})) &= E_{p(c|\mathbf{x},\mathbf{w})} [-\log p(c | \mathbf{x}, \mathbf{w})] \\ &\approx \frac{1}{N} \sum_{n=1}^N -\log p(c^n | \mathbf{x}, \mathbf{w}), \quad c^n \sim p(c | \mathbf{x}, \mathbf{w}). \end{aligned} \quad (6)$$

For more details on how to construct a tractable MC approximation of SE, we refer to Aichberger et al. (2024). Each of these uncertainty measures based on the logarithmic score considers the distribution over all possible output sequences $p(\mathbf{y} | \mathbf{x}, \mathbf{w})$, which is defined over the entire set of possible output sequences \mathcal{Y}_T . Approximating expectations over this distribution requires sampling multiple output sequences from \mathcal{Y}_T , which is computationally expensive. In the following, we eliminate this requirement by considering an alternative proper scoring rule.

2.3 NEW UNCERTAINTY MEASURES IN NLG BASED ON THE ZERO-ONE SCORE

We propose to measure predictive uncertainty in NLG using measures based on the zero-one score instead of the logarithmic score. Although it has been considered in the standard classification setting (Hofman et al., 2024; Kotelevskii & Panov, 2024), to the best of our knowledge, the zero-one score has not yet been considered as a proper scoring rule for deriving uncertainty measures in NLG. The zero-one score considers the predictive distribution for the most likely output sequence:

$$S_{0-1}(p(\mathbf{y} | \mathbf{x}, \cdot), \mathbf{y}') = (1 - p(\mathbf{y} = \mathbf{y}' | \mathbf{x}, \cdot)) \mathbb{1}\{\mathbf{y}' = \underset{\mathbf{y}}{\operatorname{argmax}} p(\mathbf{y} | \mathbf{x}, \cdot)\} \quad (7)$$

Substituting the zero-one score into Eq. (2) results in the total uncertainty being the expected confidence of the given language model about the most likely output sequences generated by every possible language model according to their posterior probability $p(\tilde{w} \mid \mathcal{D})$:

$$\underbrace{\mathbb{E}_{p(\tilde{w} \mid \mathcal{D})} [1 - p(\mathbf{y} = \tilde{\mathbf{y}}^* \mid \mathbf{x}, \mathbf{w})]}_{\text{total}} = \underbrace{1 - p(\mathbf{y} = \mathbf{y}^* \mid \mathbf{x}, \mathbf{w})}_{\text{aleatoric}} + \underbrace{p(\mathbf{y} = \mathbf{y}^* \mid \mathbf{x}, \mathbf{w}) - \mathbb{E}_{p(\tilde{w} \mid \mathcal{D})}[p(\mathbf{y} = \tilde{\mathbf{y}}^* \mid \mathbf{x}, \mathbf{w})]}_{\text{epistemic}} \quad (8)$$

with $\mathbf{y}^* = \operatorname{argmax}_{\mathbf{y}} p(\mathbf{y} \mid \mathbf{x}, \mathbf{w})$ for the given language model and $\tilde{\mathbf{y}}^* = \operatorname{argmax}_{\mathbf{y}} p(\mathbf{y} \mid \mathbf{x}, \tilde{w})$ for every possible language model. Similarly to Eq. (4), the epistemic uncertainty is a posterior expectation that remains challenging to estimate. Therefore, we again focus on the aleatoric uncertainty, which considers the likelihood of the most likely output sequence under the given language model.

While the aleatoric uncertainty derived from the logarithmic score requires approximating an expectation over the entire output sequence distribution by sampling multiple sequences (see Eq. (5) and Eq. (6)), the one derived from the zero-one score (see Eq. (8)) only requires approximating the most likely output sequence under the given language model $p(\mathbf{y} = \mathbf{y}^* \mid \mathbf{x}, \mathbf{w}) = \max_{\mathbf{y}} p(\mathbf{y} \mid \mathbf{x}, \mathbf{w})$. This distinction is crucial, as approximating the most likely output sequence aligns directly with standard inference techniques widely used in language models. We propose to approximate the aleatoric uncertainty in Eq. (8) using the greedily decoded output sequence under the given language model. For numerical stability, we consider the negative log-likelihood (NLL) of this output sequence. This gives rise to our uncertainty measure G-NLL, defined as:

$$\begin{aligned} \text{G-NLL} &:= - \sum_{t=1}^T \log \left(\max_{y_t} p(y_t \mid \mathbf{x}, \mathbf{y}_{<t}, \mathbf{w}) \right) \\ &\approx - \max_{\mathbf{y}} \log p(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) \propto 1 - p(\mathbf{y} = \mathbf{y}^* \mid \mathbf{x}, \mathbf{w}) \end{aligned} \quad (9)$$

Our proposed uncertainty measure challenges the prevailing reliance on sampling multiple sequences and semantic clustering to estimate uncertainty in NLG. By solely relying on the output sequences generated with greedy decoding, our approach significantly reduces computational overhead while maintaining theoretical rigor through its foundation in proper scoring rules. Although uncertainty measures based on the logarithmic score could theoretically excel if the full distribution over output sequences $p(\mathbf{y} \mid \mathbf{x}, \mathbf{w})$ were accessible, as is the case in standard classification tasks, this distribution is intractable for NLG tasks due to the autoregressive language modeling in LLMs. As a result, sampling-based methods often yield crude approximations, constrained by computational costs and sampling variability. In contrast, G-NLL offers a principled alternative while eliminating the need for extensive sampling, making our method highly practical and straightforward.

3 EXPERIMENTS

We aligned our experiments on evaluating uncertainty estimation methods with related work by focusing on free-form question answering tasks (Kuhn et al., 2023; Duan et al., 2024; Bakman et al., 2024; Nikitin et al., 2024; Aichberger et al., 2024; Kossen et al., 2024). While Farquhar et al. (2024) additionally concerns experiments with paragraph-length generations, their approach breaks down the paragraph into factual claims and constructs corresponding questions. Therefore, performance on this task is expected to align with general free-form question answering tasks, and we therefore focused on those for a clearer and more direct evaluation. This focus further avoids potential confounding factors introduced by additional experimental complexities.

Datasets. We evaluated uncertainty estimation methods on three different datasets. We used the more than 3,000 test instances from *TriviaQA* (Joshi et al., 2017) concerning trivia questions, the more than 300 test instances from *SVAMP* (Patel et al., 2021) concerning elementary-level math problems, and the more than 3,600 test instances from *NQ-Open* (Lee et al., 2019) to assess natural questions aggregated from Google Search. Each dataset was used for two distinct tasks: (1) generating concise answers in the form of short phrases and (2) generating more detailed answers in the form of full sentences, following the experimental setup in Farquhar et al. (2024). The six overall tasks cover a broad range, ensuring a comprehensive evaluation.

Table 1: Average AUROC across TriviaQA, SVAMP, and NQ datasets, using uncertainty estimates to distinguish between correct and incorrect answers. Varying model architectures (*transformer*, *state-space*), model sizes (*7B*, *8B*, *70B*), and training stages (*PT*, *IT*) are considered. The reference answer is generated using greedy decoding, either as a whole sentence (*long*) or a short phrase (*short*). The reference answers correctness is assessed by *F1* score using SQuAD > 0.5 as decision rule or LLM-as-a-judge (*LLM*). *PE*, *LN-PE*, *SE*, *LN-SE*, and *D-SE* use 10 output sequences (by multinomial sampling) to obtain an uncertainty estimate. G-NLL solely uses the reference answer to obtain an uncertainty estimate.

Uncertainty measure generating scoring rule				Logarithmic					Zero-One	
Language Model		Generation	Metric	PE	LN-PE	SE	LN-SE	D-SE	G-NLL	
Transformer	8B	PT	short	F1	.776	.795	.775	.793	.804	.824
			short	LLM	.698	.714	.690	.706	.719	.726
			long	LLM	.562	.555	.545	.553	.600	.649
		IT	short	F1	.772	.801	.805	.814	.806	.838
			short	LLM	.676	.697	.704	.709	.694	.722
			long	LLM	.551	.548	.599	.601	.609	.615
	70B	PT	short	F1	.775	.790	.793	.803	.791	.820
			short	LLM	.693	.709	.718	.722	.715	.723
			long	LLM	.552	.534	.558	.569	.571	.649
		IT	short	F1	.748	.781	.790	.799	.783	.792
			short	LLM	.681	.698	.703	.709	.699	.699
			long	LLM	.555	.557	.568	.595	.600	.562
State-Space	7B	PT	short	F1	.811	.815	.809	.822	.828	.843
			short	LLM	.705	.711	.701	.711	.716	.728
			long	LLM	.567	.597	.574	.611	.624	.612
		IT	short	F1	.793	.814	.797	.816	.829	.838
			short	LLM	.690	.701	.689	.699	.711	.719
			long	LLM	.588	.587	.597	.618	.629	.615
Average				.677	.689	.690	.703	.707	.721	

Models. We conducted our evaluations on six different language models covering various architectures, sizes, and training stages. Specifically, we used the transformer model series *Llama-3.1* (Dubey et al., 2024) and the state-space model series *Falcon Mamba* (Gu & Dao, 2024; Zuo et al., 2024), representing two prominent paradigms. To assess the effect of training stage and scale on uncertainty estimation in NLG, we considered pre-trained (*PT*) and instruction-tuned (*IT*) language models with 7, 8, and 70 billion parameters, covering a wide spectrum of model characteristics.

Baselines. We compare our method against the commonly used uncertainty measures based on the logarithmic score as of Eq. (5) and Eq. (6) and their variants. These include Predictive Entropy (*PE*), length-normalized Predictive Entropy (*LN-PE*) (Malinin & Gales, 2021), Semantic Entropy (*SE*), length-normalized Semantic Entropy (*LN-SE*), and Discrete Semantic Entropy (*D-SE*) (Kuhn et al., 2023; Farquhar et al., 2024). For a given output sequence y' , the length-normalized variants consider $\bar{p}(y' | x, w)$ instead of $p(y' | x, w)$ to compute the uncertainty estimates. D-SE completely disregards the likelihood of the output sequence and only considers the proportion of output sequences that belong to the same semantic cluster (Farquhar et al., 2024).

Evaluation. Effective uncertainty measures should accurately reflect the reliability of answers generated by the language model. In other words, higher uncertainty should correspond to a greater tendency for incorrect outputs. Thus, to evaluate the performance of an uncertainty estimator, we assess how well it correlates with the correctness of the language model’s answers. Correct answers should be assigned a lower uncertainty estimator than incorrect answers. To determine whether an answer is correct, it has to be compared to the respective ground truth answer. To do so, we check if the F1 score of the commonly used SQuAD metric exceeds 0.5 (Rajpurkar et al., 2016). Although there are some limitations to using such a simple metric, it has relatively small errors in standard datasets and, therefore, remains widely used in practice. However, this metric is only applicable for short-phrase generations that align with the ground truth answer. Therefore, we additionally employ Llama-3.1 with 70 billion parameters (Dubey et al., 2024) as an LLM-as-a-judge to assess the correctness of both short-phrase and full-sentence generations. To measure the correlation between the incorrectness of answers and the respective uncertainty estimates, we use the AUROC. Higher

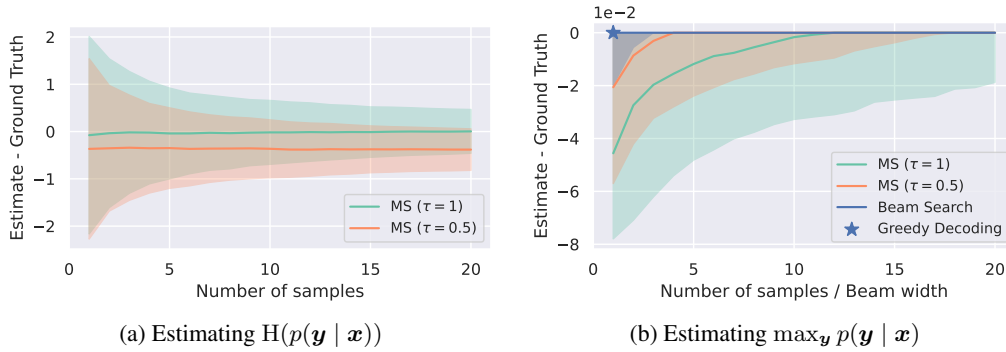


Figure 1: Quality of estimators for synthetic predictive distributions $p(\mathbf{y} | \mathbf{x})$ with $|\mathcal{V}| = 20$ and $T = 4$. The predictive entropy $H(p(\mathbf{y} | \mathbf{x}))$ is estimated as in Eq. (5) using multinomial sampling (MS) with different temperatures (τ). The maximum sequence likelihood $\max_{\mathbf{y}} p(\mathbf{y} | \mathbf{x})$ is estimated by the maximum over N samples obtained by beam search ($N = 1$ represents greedy decoding) or MS with different τ . Statistics are obtained by sampling different $p(\mathbf{y} | \mathbf{x})$. (a) Lines show average, shades denote one std. (b) Lines show the median, and shades denote 5% to 95% quantile range.

AUROC values indicate better performance of the uncertainty estimator, as it reflects a stronger alignment between the correctness of the language model’s answers and their respective uncertainty estimates. In summary, this evaluation process follows established methodologies for assessing the performance of uncertainty measures in NLG (Kuhn et al., 2023; Duan et al., 2024; Farquhar et al., 2024; Nikitin et al., 2024; Aichberger et al., 2024; Kossen et al., 2024).

3.1 MAIN RESULTS

Tab. 1 summarizes the performance of the uncertainty measures across the six language models, six tasks, and two evaluation metrics. We report the average AUROC across the three datasets, highlighting the best-performing measure in bold. Additionally, the best-performing measure based on the logarithmic score is underlined, unless it also represents the overall best. In 13 out of 18 scenarios, G-NLL achieves the best performance among all uncertainty measures and remains competitive in the remaining 5 scenarios. This strong performance is particularly evident in tasks involving the generation of short phrases, suggesting its effectiveness in capturing the essential part of the output sequence that contains the factual answer to a question. This is especially valuable in practical scenarios, where the uncertainty about a specific fact is often more critical than the uncertainty about the entire generated sentence. Overall, our measure significantly outperforms all other measures when considering the average across all scenarios. This demonstrates that our measure achieves state-of-the-art performance while considering only a single output sequence. Detailed results for individual datasets and additional evaluations are provided in Apx. B.

3.2 QUALITY OF ESTIMATORS

The strong empirical performance of G-NLL on question answering NLG tasks suggests that it effectively captures key aspects of uncertainty, even when using significantly fewer output sequences compared to uncertainty measures based on the logarithmic score. To examine the underlying factors driving this behavior, we analyze these estimators in both synthetic and real-world settings.

Synthetic setting. For the first study, we examine the reliability of estimators of aleatoric uncertainty under the zero-one score compared to those under the logarithmic score in the low-sample regimes typical of uncertainty estimation in NLG. To this end, we conduct a synthetic experiment where we sample predictive distributions $p(\mathbf{y} | \mathbf{x})$ with smaller vocabulary sizes and shorter sequence lengths, while preserving the distributional characteristics typical of language models. This approach allows us to obtain ground truths for both $H(p(\mathbf{y} | \mathbf{x}))$ and $\max_{\mathbf{y}} p(\mathbf{y} | \mathbf{x})$, which become intractable with larger vocabulary sizes and sequence lengths. Using this synthetic setup, we aim to evaluate how the quality of estimators improves with the number of samples.

Fig. 1a summarizes the results for estimating the entropy, derived from the logarithmic score. The results show that low sample sizes lead to high estimator variance. Similarly, Fig. 1b summarizes the results for estimating the maximum sequence likelihood, derived from the zero-one score. The

results indicate that, while multinomial sampling (MS) also exhibits higher variance with fewer samples, heuristics such as beam search (BS) and even greedy decoding provide accurate estimates of the maximum sequence probability with negligible variance. Details on the sampling procedure of the predictive distributions, as well as additional experiments are provided in Apx. C. This synthetic experiment suggests that MS is ineffective at estimating $\max_{\mathbf{y}} p(\mathbf{y} | \mathbf{x})$, whereas greedy decoding, as we propose in Eq. (9), performs well and could be slightly improved by using BS with larger width. In the following ablation, we further investigate the empirical performance of the different sampling methods with an actual language model.

Real-world setting. For the second study, we evaluate the empirical effectiveness of approximating the aleatoric uncertainty derived from the zero-one score in Eq. 8. We recall that this requires approximating the NLL of the most likely output sequence under the given language model $-\log \max_{\mathbf{y}} p(\mathbf{y} | \mathbf{x}, \mathbf{w})$. We investigate the performance of various sampling methods for this approximation. Specifically, we utilize MS with different temperatures τ , BS with different beam sizes, and greedy decoding, which is the sampling method proposed for G-NLL. For each sampling method, we generate a single output sequence per instance in the TriviaQA dataset. We then use the corresponding NLL as the uncertainty estimate, following the same evaluation process as in the main experiments above. Notably, the baselines are unaffected by the choice of sampling method for computing the NLL, as we again use their optimal hyperparameter settings for sampling.

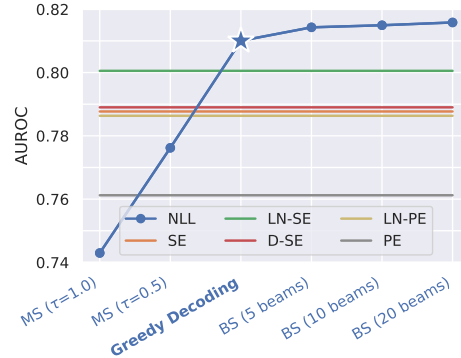


Figure 2: Performance of NLL as uncertainty measure based on the zero-one score, when the output sequence is generated with different sampling methods (MS, greedy decoding, and BS), compared to uncertainty measures based on the logarithmic score.

The results in Fig. 2 show that better approximations of the most likely output sequences indeed lead to higher uncertainty estimation performance, reinforcing the validity of our alternative measure derived from the zero-one score. Additionally, it can be observed that sampling output sequences using greedy decoding significantly outperforms MS. While performance improves further with BS, as anticipated, the marginal benefits are relatively small. This supports the claim that greedy decoding provides a strong approximation to the most likely output sequence. Since BS is computationally more expensive (as its beam size corresponds to the number of sampled output sequences), using greedy decoding in G-NLL achieves the best trade-off between effectiveness and efficiency.

4 CONCLUSION

In this work, we introduced an alternative uncertainty measure: the NLL of the most likely output sequence under a given language model. This measure is motivated by the general notion of proper scoring rules, utilizing the zero-one score as an alternative to the prevalent logarithmic score. Unlike previous measures, it does not require sampling multiple output sequences but can be efficiently approximated using G-NLL through a single, greedily decoded output sequence. The experiments demonstrate that our measure largely outperforms previous measures that entail considerably higher computational costs and algorithmic complexity.

Although G-NLL effectively captures uncertainty, it currently does not account for the semantics of the generated output sequence. Future work should explore extensions that incorporate semantic meaning to further enhance the uncertainty estimator while preserving its computational efficiency. Moreover, measures based on proper scoring rules rely on heuristics, such as length normalization, to address variations in sequence lengths (Malinin & Gales, 2021; Duan et al., 2024; Bakman et al., 2024; Yaldiz et al., 2024). Investigating theoretically grounded methods to handle these characteristics that vary for different sequences represents another promising direction for future work.

While there remain opportunities for refinement, our proposed measure provides a solid foundation for efficient and reliable uncertainty estimation in NLG. It paves the way for efficient methods that build upon a single output sequence. Given its simplicity and minimal computational overhead, G-NLL serves as a strong baseline for developing new uncertainty measures and represents an important step toward scalable uncertainty estimation in real-world applications.

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A RELATED WORK

There is a body of work that extends the concept of SE (Kuhn et al., 2023; Farquhar et al., 2024), for example, by improving semantic clustering (Nikitin et al., 2024; Qiu & Miiikkulainen, 2024), improving the sampling of output sequences (Aichberger et al., 2024), or directly approximating the measure from hidden states of the language model (Kossen et al., 2024; Chen et al., 2024). In addition, multiple works build upon PE (Malinin & Gales, 2021), for example, by considering a weighting factor for individual token and sequence likelihoods to account for the importance on a semantic level (Duan et al., 2024; Bakman et al., 2024; Yaldiz et al., 2024).

There are also works that use the likelihood of a single output sequence as a heuristic baseline. For example, Fadeeva et al. (2023), Fadeeva et al. (2024), and Vazhentsev et al. (2024) consider the most likely output sequence in their experiments. Bakman et al. (2024) and the follow-up work by Yaldiz et al. (2024) consider the sequence likelihood as part of their uncertainty estimation method. Abbasi-Yadkori et al. (2024) use greedy decoded sequence likelihood as a baseline. Plaut et al. (2024) show that maximum softmax probabilities predict correctness in question answering. Ren et al. (2023a) use perplexity as a baseline for OOD detection, stating that it alone is ill-suited for this task. Zhang et al. (2024) use the likelihood ratio between pre-trained and fine-tuned language models for OOD detection, claiming that this ratio achieves high performance.

Other works on uncertainty estimation in NLG do not consider uncertainty measures grounded in proper scoring rules. For example, several approaches leverage the language model itself to directly predict uncertainty, either through numerical estimates or verbal explanations (Mielke et al., 2022; Lin et al., 2022; Kadavath et al., 2022; Cohen et al., 2023a; Ganguli et al., 2023; Ren et al., 2023b; Tian et al., 2023). Additionally, Cohen et al. (2023b) employ cross-examination, where one language model generates an output sequence and another model acts as an examiner to assess uncertainty. Zhou et al. (2023) explore the behavior of language models when expressing their uncertainty, providing insights into how models articulate confidence in their predictions. Manakul et al. (2023) propose using sampled output sequences as input to another language model to assess uncertainty. Xiao et al. (2022) provide an empirical analysis of how factors such as model architecture and training data influence uncertainty estimates. Finally, conformal prediction (Quach et al., 2024) offers another approach by calibrating a stopping rule for output sequence generation.

B DETAILED MAIN RESULTS

In this section, we provide detailed insights to complement the main results presented in Sec. 3.1.

To compute G-NLL, greedy decoding is used to generate the reference answer, which is equivalent to beam search with a single beam and multinomial sampling with a sampling temperature of zero. The correctness of the reference answer is assessed by checking if the F1 score of the commonly used SQuAD metric exceeds 0.5 ($F1$) or if the Llama-3.1-70B model used as LLM-as-a-judge considers it as correct (LLM). To compute the logarithmic score based measures (PE , $LN-PE$, SE , $LN-SE$, $D-SE$) ten output sequences are generated via multinomial sampling. For each dataset, we performed a hyperparameter search on held-out instances to determine the best-performing temperature $\tau \in \{0.5, 1.0, 1.5\}$ for sampling output sequences used for the logarithmic score based measures.

AUROC is used as the primary performance metric throughout this paper, consistent with standard evaluation practices in this field. We report the results for the individual datasets in Tab. 2, which has been averaged over in Tab. 1.

In addition to AUROC, we also consider the average rejection accuracy, i.e., the accuracy of model predictions when allowing the rejection of a certain budget of predictions based on the uncertainty estimate. Results are presented in Tab. 3, where predictions are only evaluated for the 80% most certain predictions, and we again use greedy decoding for our measure based on the zero-one score. This further suggests that our measure remains highly competitive across various settings.

Additionally, we look into how much the alternative measure derived from the zero-one score benefits from better approximating the most likely output sequences through increasing the beam width to 5. The results summarized in Tab. 4 show that the performance does not significantly improve compared to greedy decoding, which is consistent with the ablation study presented in Fig. 2. This further supports the claim that G-NLL is a strong measure of uncertainty, despite its algorithmic simplicity and computational efficiency.

Table 2: **AUROC Evaluation.** Average AUROC using uncertainty estimates of different measures as a score to distinguish between correct and incorrect answers of each dataset. The reference answer is generated using greedy decoding, either as a whole sentence (*long*) or a short phrase (*short*).

Uncertainty measure generating scoring rule				Logarithmic					Zero-One	
D	Language Model	Gen.	Metric	PE	LN-PE	SE	LN-SE	D-SE	G-NLL	
TriviaQA	Transformer	8B	short	F1	.758	.778	.788	.798	.787	.810
			short	LLM	.675	.694	.703	.704	.682	.722
			long	LLM	.592	.604	.640	.631	.650	.704
		IT	short	F1	.735	.768	.790	.800	.777	.809
			short	LLM	.660	.684	.708	.710	.680	.716
			long	LLM	.603	.627	.678	.672	.670	.670
		70B	short	F1	.707	.730	.741	.743	.702	.744
			short	LLM	.650	.660	.696	.695	.656	.698
			long	LLM	.538	.533	.625	.574	.563	.692
	State-Space	7B	short	F1	.698	.714	.722	.726	.688	.722
			short	LLM	.663	.675	.685	.679	.633	.701
			long	LLM	.530	.553	.564	.571	.564	.543
		PT	short	F1	.786	.793	.812	.818	.810	.832
			short	LLM	.687	.697	.712	.714	.695	.724
			long	LLM	.597	.653	.675	.680	.689	.705
		PT	short	F1	.780	.799	.810	.819	.811	.827
			short	LLM	.696	.701	.714	.717	.703	.730
			long	LLM	.645	.654	.688	.698	.692	.694
SVAMP	Transformer	8B	short	F1	.847	.867	.865	.870	.868	.885
			short	LLM	.779	.788	.753	.772	.791	.772
			long	LLM	.575	.563	.519	.534	.601	.669
		IT	short	F1	.879	.903	.914	.912	.887	.931
			short	LLM	.706	.725	.736	.731	.701	.753
			long	LLM	.556	.524	.590	.608	.631	.662
		70B	short	F1	.892	.906	.925	.929	.923	.936
			short	LLM	.794	.817	.814	.815	.819	.799
			long	LLM	.578	.554	.553	.579	.571	.665
	State-Space	7B	short	F1	.830	.895	.915	.922	.915	.909
			short	LLM	.703	.744	.734	.748	.762	.713
			long	LLM	.601	.577	.613	.649	.663	.597
		PT	short	F1	.882	.893	.874	.883	.889	.914
			short	LLM	.752	.757	.730	.738	.757	.776
			long	LLM	.536	.585	.534	.602	.612	.579
		IT	short	F1	.843	.891	.854	.876	.892	.905
			short	LLM	.706	.730	.704	.709	.737	.744
			long	LLM	.577	.586	.578	.616	.639	.613
NQ	Transformer	8B	short	F1	.725	.739	.673	.710	.758	.776
			short	LLM	.639	.661	.615	.641	.683	.683
			long	LLM	.517	.498	.478	.495	.550	.573
		IT	short	F1	.702	.732	.711	.731	.756	.774
			short	LLM	.662	.682	.669	.685	.700	.697
			long	LLM	.494	.491	.530	.524	.527	.514
		70B	short	F1	.727	.733	.711	.737	.748	.779
			short	LLM	.634	.649	.642	.657	.671	.672
			long	LLM	.538	.514	.494	.553	.580	.589
	State-Space	7B	short	F1	.718	.734	.734	.748	.746	.743
			short	LLM	.676	.674	.689	.698	.702	.681
			long	LLM	.535	.540	.526	.566	.574	.545
		PT	short	F1	.766	.758	.741	.765	.785	.782
			short	LLM	.675	.680	.661	.681	.697	.683
			long	LLM	.567	.553	.512	.551	.572	.554
		IT	short	F1	.755	.751	.727	.754	.783	.781
			short	LLM	.669	.672	.648	.671	.692	.683
			long	LLM	.541	.521	.526	.541	.554	.537
Average				.677	.689	.690	.703	.707	.721	

Table 3: **Rejection Accuracy Evaluation.** Average Rejection Accuracy (80%) across all datasets. The reference answer is generated using greedy decoding, either as a whole sentence (*long*) or a short phrase (*short*).

Uncertainty measure generating scoring rule				Logarithmic					Zero-One
Language Model	Gen.	Metric	PE	LN-PE	SE	LN-SE	D-SE	G-NLL	
Transformer	8b	short	F1	.661	<u>.672</u>	.651	.643	.655	.681
			LLM	.774	.782	.767	.766	.765	.778
		LLM-Instruct	.704	<u>.721</u>	.693	.688	.702	.723	
			long	LLM	.596	<u>.590</u>	<u>.598</u>	.592	.590
		LLM-Instruct		.667	<u>.684</u>	.632	.643	.644	.686
		IT	short	F1	.668	<u>.684</u>	.680	.673	<u>.687</u>
	LLM			.775	<u>.781</u>	.779	.775	.778	.788
	LLM-Instruct		.723	<u>.742</u>	.732	.726	<u>.743</u>	.751	
			long	LLM	.628	<u>.630</u>	.651	.644	.653
	LLM-Instruct			.713	<u>.724</u>	.705	.713	<u>.727</u>	.734
	70b		short	F1	.818	<u>.827</u>	.822	.827	<u>.829</u>
		LLM		.844	<u>.852</u>	.846	.847	.851	.855
		LLM-Instruct	.867	<u>.875</u>	.876	.881	.885	.881	
			long	LLM	.704	<u>.699</u>	<u>.719</u>	.707	.705
		LLM-Instruct		.789	<u>.795</u>	.776	.781	.788	.812
		IT	short	F1	.795	<u>.813</u>	.814	.809	<u>.819</u>
LLM	.836			<u>.842</u>	.842	.837	<u>.844</u>	.845	
LLM-Instruct	.850		<u>.867</u>	.866	.865	.874	.870		
	long		LLM	.706	<u>.706</u>	.712	.715	.721	.715
LLM-Instruct			.855	<u>.850</u>	.827	.842	.861	.851	
State-Space	7b		short	F1	<u>.598</u>	<u>.596</u>	.585	.579	.583
		LLM		.729	<u>.737</u>	.723	.721	.733	.742
		LLM-Instruct	.638	<u>.640</u>	.626	.621	.632	.651	
			long	LLM	.613	.627	.612	.624	.620
		LLM-Instruct		.606	<u>.611</u>	.601	.611	<u>.618</u>	.633
		IT	short	F1	.592	<u>.603</u>	.588	.581	.589
	LLM			.737	<u>.742</u>	.730	.726	.740	.744
	LLM-Instruct		.632	<u>.646</u>	.625	.619	.637	.653	
			long	LLM	.611	<u>.617</u>	.618	.612	.625
	LLM-Instruct	.643	<u>.652</u>	.628	.628	<u>.654</u>	.658		
Average			.712	.720	.711	.710	.718	.729	

Table 4: **AUROC Evaluation.** Average AUROC across all datasets. The reference answer is generated using **beam search with 5 beams**, either as a whole sentence (*long*) or a short phrase (*short*).

Uncertainty measure generating scoring rule				Logarithmic					Zero-One	
Language Model		Gen.	Metric	PE	LN-PE	SE	LN-SE	D-SE	G-NLL	
Transformer	8B	PT	short	F1	.775	.791	.765	.787	<u>.799</u>	.822
			short	LLM	.700	.712	.686	.704	<u>.713</u>	.726
		long	LLM	.556	.540	.493	.520	<u>.578</u>	.591	
			IT	short	F1	.778	.808	.805	<u>.819</u>	.811
		short		LLM	.682	.704	.706	<u>.713</u>	.698	.729
		long	LLM	.535	.520	.584	.585	.586	.559	
	70B	PT	short	F1	.788	.799	.796	<u>.812</u>	.798	.833
			short	LLM	.700	.717	.719	.727	.718	.725
		long	LLM	.540	.552	.489	.531	<u>.552</u>	.608	
			IT	short	F1	.756	.786	.796	.806	.788
		short		LLM	.680	.697	.701	.707	.695	.707
		long	LLM	.534	.533	.544	.569	.574	.534	
State-Space	7b	PT	short	F1	.814	.818	.806	.823	<u>.825</u>	.846
			short	LLM	.703	.709	.699	.711	<u>.712</u>	.719
			long	LLM	.570	.595	.550	.609	.602	.563
		IT	short	F1	.799	.815	.794	.817	<u>.828</u>	.845
			short	LLM	.699	.713	.694	.709	<u>.720</u>	.730
			long	LLM	.574	.575	.582	.621	.607	.577
Average				.677	.688	.678	.698	.700	.709	

C DETAILED QUALITY OF ESTIMATORS

In this section, we provide detailed insights into the studies presented in Sec. 3.2, especially Fig. 1.

To recall, we empirically investigate the performance of estimators for the predictive entropy $H(p(\mathbf{y} \mid \mathbf{x}))$ (Eq. (5)) and the maximum sequence likelihood $\max_{\mathbf{y}} p(\mathbf{y} \mid \mathbf{x})$ (Eq. (9)) in a controlled setting. Therefore, we consider a synthetic experiment with the following setup. We are given a space of possible outcomes \mathcal{V} with $|\mathcal{V}| = \{20, 100\}$. The task is to predict a sequence $\mathbf{y} = (y_1, \dots, y_T) \in \mathcal{V}_T$ where $y \in \mathcal{V}$ and T is 2, 3, or 4. Predictive distributions $p(\mathbf{y} \mid \mathbf{x})$ are not represented by a neural network, but are randomly sampled according to a Dirichlet distribution $\text{Dir}(\{\alpha_1, \dots, \alpha_{|\mathcal{V}|}\})$. The alpha parameters of the Dirichlet distribution are specified to yield typical predictive distributions as encountered in language models that follow a Zipf distribution. For $|\mathcal{V}| = 20$ we have $\alpha_{1,2} = 10$ and $\alpha_{3-20} = 0.2$. For $|\mathcal{V}| = 100$ we have $\alpha_{1,2} = 10$, $\alpha_{3-6} = 1$ and $\alpha_{7-100} = 0.2$. Note that the order of alpha values is randomly shuffled before drawing each predictive distribution. Representative predictive distributions sampled from this Dirichlet distribution are shown in Fig. 3a and Fig. 3b.

The experiments investigate the quality of the estimators depending on the number of samples $\{\mathbf{y}_n\}_{n=1}^N$. This is feasible because the ground truth values for both entropy and maximum sequence likelihood can be calculated for this small synthetic example through exhaustive enumeration. In the experiments we present in the appendix, we average over 1,000 runs, meaning that new sets of samples $\{\mathbf{y}_n\}_{n=1}^N$ are drawn to calculate the respective estimators. As beam search is deterministic, it does not vary in this experimental setting, compared to Fig. 1b in the main paper, where we investigated the quality of estimators for different $p(\mathbf{y} \mid \mathbf{x})$.

The results for estimating the entropy are shown in Fig. 4. We observe that the variance of estimators increases for larger vocabulary sizes $|\mathcal{V}|$ and sequence lengths T . Furthermore, lower temperatures decrease the variance of the estimator at the cost of introducing bias.

The results for estimating the maximum sequence likelihood are shown in Fig. 5. We observe that low-temperature multinomial sampling and beam search find the maximum sequence log-likelihood with a low number of samples with high probability. Greedy decoding (beam width of 1) finds the maximum for all experimental settings except one, where it takes a beam width of 2 to find it with high probability.

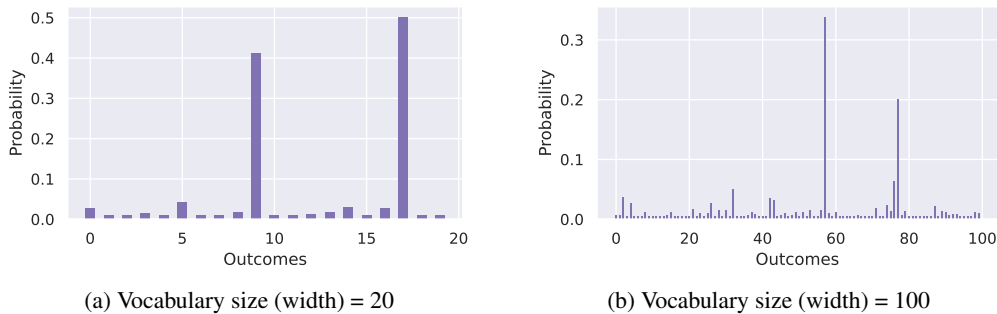


Figure 3: Exemplary predictive distributions $p(y_t \mid \mathbf{y}_{<t}, \mathbf{x})$ for different vocabulary sizes (widths).

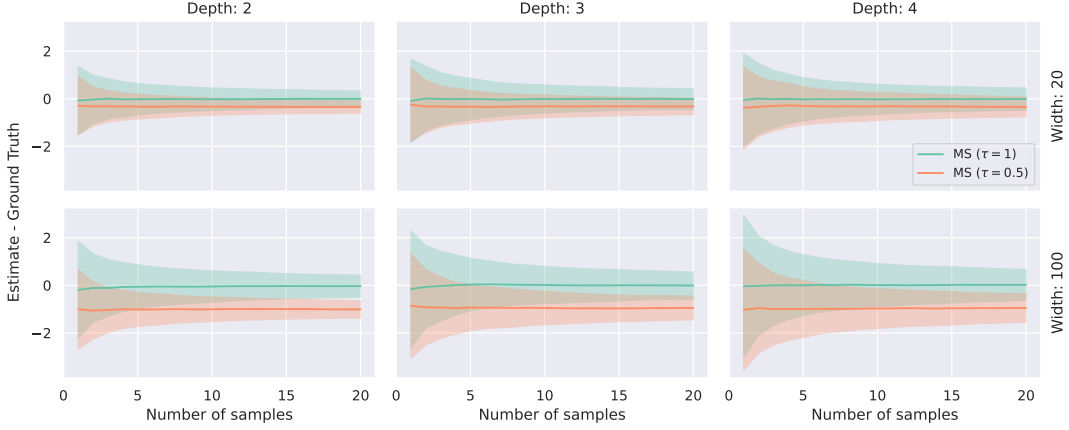


Figure 4: **Estimator of Predictive Entropy.** Results for different vocabulary sizes (width) and sequence lengths (depth). We estimate the entropy $H(p(\mathbf{y} \mid \mathbf{x}))$ using N Monte-Carlo samples (cf. Eq. (5)). Lines denote the average over runs, while shades denote one standard deviation. We compare MS for two commonly used τ . The experiments show that the decreased temperature leads to lower variance but introduces bias.

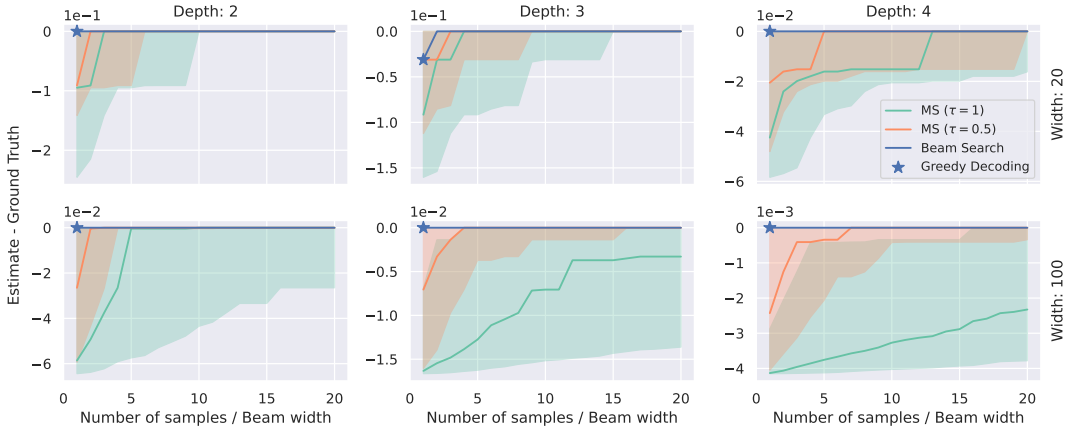


Figure 5: **Estimator of maximum sequence likelihood.** Results for different vocabulary sizes (width) and sequence lengths (depth). We estimate $\max_{\mathbf{y}} p(\mathbf{y} \mid \mathbf{x})$ using the maximum over N sampled obtained by beam search ($N = 1$ is greedy decoding) or MS with different τ . Lines denote the median, shades signify the possible values between the 5 and 95 percent quantile. Beam search is deterministic for any given distribution $p(\mathbf{y} \mid \mathbf{x})$. Even with a very low number of samples, low-temperature MS and beam search are able to find the maximum with high probability.