

# Graph Neural Networks for Multiparallel Word Alignment

Anonymous ACL submission

## Abstract

After a period of decrease, interest in word alignments is increasing again for their usefulness in domains such as typological research, cross-lingual annotation projection and machine translation. Generally, alignment algorithms only use bitext and do not make use of the fact that many parallel corpora are multiparallel. Here, we compute high-quality word alignments between multiple language pairs by considering all language pairs together. First, we create a multiparallel word alignment graph, joining all bilingual word alignment pairs in one graph. Next, we use graph neural networks (GNNs) and community detection algorithms to exploit the graph structure. Our GNN approach (i) utilizes information about the meaning, position and language of the input words, (ii) incorporates information from multiple parallel sentences, (iii) adds and removes edges from the initial alignments, and (iv) provides a prediction model that can generalize beyond the sentences it is trained on. We show that community detection provides valuable information for multiparallel word alignment. Our method outperforms previous work on three word alignment datasets and on a downstream task.

## 1 Introduction

Word alignments are crucial for statistical machine translation (Koehn et al., 2003) and useful for many other multilingual tasks such as neural machine translation (Alkhouli and Ney, 2017; Alkhouli et al., 2016), typological analysis (Lewis and Xia, 2008; Östling, 2015; Asgari and Schütze, 2017), annotation projection (Yarowsky and Ngai, 2001; Fossum and Abney, 2005; Wisniewski et al., 2014; Huck et al., 2019). The rise of deep learning initially led to a temporary plateau, but interest in word alignments is now increasing, demonstrated by several recent publications (Jalili Sabet et al., 2020; Chen et al., 2020; Dou and Neubig, 2021)

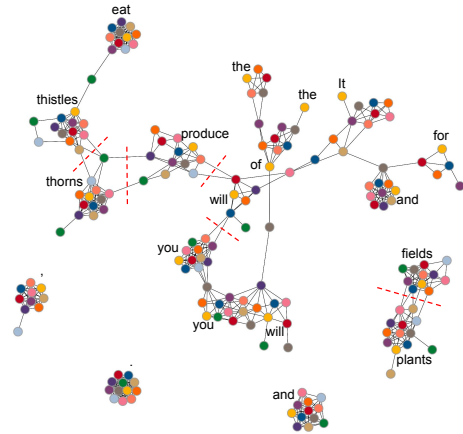


Figure 1: Alignment graph for the verse “It will produce thorns and thistles for you, and you will eat the plants of the field.” in a 12-way multiparallel corpus. Colors represent languages. Each English (yellow) node is annotated with its word. Red dashed lines sever links that incorrectly connect distinct concepts. We exploit community detection algorithms to detect distinct concepts. This provides valuable information for our GNN model and improves word alignments.

Multiparallel corpora contain sentence level parallel text in more than two languages, e.g., JW300 (Agić and Vulić, 2019), PBC (Mayer and Cysouw, 2014) and Tatoeba.<sup>1</sup> While the amount of data provided by multiparallel corpora is less than bilingual corpora, this type of corpus is essential to study very low-resource languages. There are thousands of languages in the world a very small portion of which is covered by language technologies (Joshi et al., 2020). Recent work (Bird, 2020) suggests a number of approaches to develop technologies for indigenous languages. Multiparallel corpora are a valuable (and arguably complementary) resource for this aim. We use the PBC corpus since it covers more than 1300 languages.

Most prior work on word alignment uses bitext, with one notable exception: (Imani et al., 2021).

<sup>1</sup><https://tatoeba.org>

059 They introduce MPWA (MultiParallel Word Align- 110  
060 ment), a framework that utilizes the synergy be- 111  
061 tween multiple language pairs to improve bilingual 112  
062 word alignments. The rationale is that some of the 113  
063 missing alignment edges between a source and a 114  
064 target language can be recovered using their align- 115  
065 ments with words in other languages. 116

066 The first step in MPWA is to create bilingual 117  
067 alignments for all language pairs in a multiparallel 118  
068 corpus using a bilingual word aligner. Then the 119  
069 bilingual alignments for a multiparallel sentence 120  
070 are represented as a graph where words are nodes 121  
071 and initial word alignments are edges. Figure 1 122  
072 gives an example: a multiparallel alignment graph 123  
073 for a 12-way multiparallel corpus. MPWA infers 124  
074 missing alignment links based on the graph struc- 125  
075 ture in a postprocessing step, casting the word align- 126  
076 ment task as an edge prediction problem. They use 127  
077 two traditional graph algorithms, Adamic-Adar and 128  
078 non-negative matrix factorization, for edge predic- 129  
079 tion. However, these standard graph algorithms are 130  
080 applied to individual multiparallel sentences inde- 131  
081 pendently and therefore cannot accumulate knowl- 132  
082 edge from multiple sentences. Moreover, their edge 133  
083 predictions are solely based on the structure of the 134  
084 graph and do not take advantage of other beneficial 135  
085 signals such as a word’s language, relative position 136  
086 and word meaning. Another limitation is that it 137  
087 only adds links and does not remove any, which is 138  
088 important to improve precision. 139

089 In this paper, we propose to use graph neural 140  
090 networks (GNNs) to exploit the graph structure 141  
091 of multiparallel word alignments and address the 142  
092 limitations of prior work. GNNs were proposed 143  
093 to extend the powerful current generation of neu- 144  
094 ral network models to processing graph-structured 145  
095 data (Scarselli et al., 2009) and they have gained 146  
096 increasing popularity in many domains (Wu et al., 147  
097 2020; Sanchez-Gonzalez et al., 2018; He et al., 148  
098 2020). In contrast to other graph algorithms, GNNs 149  
099 can incorporate heterogeneous sources of signal in 150  
100 the form of node and edge features. 151

101 Since the nodes in the graph are words that 152  
102 are translations of each other, we expect them 153  
103 to create densely connected regions or *communi- 154*  
104 *ties*. Our analysis of the structure of the multi- 155  
105 parallel alignment graph confirms this intuition; 156  
106 see Figure 1. We use community detection al- 157  
107 gorithms to find communities. We show that 158  
108 pruning inter-community edges and adding intra- 159  
109 community edges is helpful. We use community

information as node features for our GNN.

We enable the removal of alignment edges from 111  
initial alignments by inferring alignments from the 112  
alignment probability matrix. Our method predicts 113  
new alignment links independently of initial edges. 114  
Therefore it is not limited to adding edges wrt ini- 115  
tial bilingual alignments, it can also remove them. 116

For our experiments, we follow the setup of 117  
Imani et al. (2021). We train a GNN model 118  
with a link prediction objective. We show im- 119  
proved results for three language pairs on word 120  
alignment (English-French, Finnish-Hebrew and 121  
Finnish-Greek). As a demonstration of the im- 122  
portance of high-quality alignments, we use our 123  
word alignments to project annotations from high- 124  
resource to low-resource languages. We improve 125  
a part-of-speech tagger for Yoruba by training it 126  
over a high-quality dataset, which is created using 127  
annotation projection. We show that our model is 128  
especially helpful for distant languages. 129

**Contributions:** **i)** We propose a graph neural 130  
network model that incorporates a diverse set of 131  
features for word alignments in multiparallel cor- 132  
pora and an elegant way of training it efficiently and 133  
effectively. **ii)** We show that community detection 134  
improves multiparallel word alignment. **iii)** We 135  
show that the improved alignments improve per- 136  
formance on a downstream task for a low resource 137  
language. **iv)** We propose a new method to infer 138  
alignments from the alignment probability matrix. 139  
**v)** We will make our code publicly available. 140

## 2 Graph Analysis with Community 141 Detection (CD) 142

The nodes in the alignment graph are words that 143  
are translations of each other. If the initial bilingual 144  
alignments are of good quality, we expect these 145  
translated words to form densely connected regions 146  
or *communities*; see Figure 1. We expect these 147  
communities to be generally disconnected, each 148  
corresponding to a distinct connected component. 149  
In other words, ideally, words representing a con- 150  
cept should be densely connected, but there should 151  
be no links between different concepts. Clearly, 152  
this intuition will not be true for all concepts be- 153  
tween all possible language pairs. Nonetheless, we 154  
hypothesize that identifying distinct concepts in 155  
a multiparallel word alignment graph can provide 156  
useful information. 157

To examine to what extent this expectation is 158  
met, we count the components in the original 159

Eflomal-generated (Östling and Tiedemann, 2016) graph. Table 1 shows that the average number of components per sentence is less than three (“Eflomal intersection”, columns #CC). But intuitively, the number of components should roughly correspond to sentence length (i.e., the number of content words). This indicates that there are many links that incorrectly connect different concepts. To detect such links, we use community detection (CD) algorithms.

CD algorithms find subnetworks of nodes that form tightly knit groups that are only loosely connected with a small number of links (Girvan and Newman, 2002). CD algorithms maximize the modularity measure (Newman and Girvan, 2004). Modularity measures how beneficial a division of a community into two communities is, in the sense that there are many links within communities and only a few between them. Given a graph  $G$  with  $n$  nodes and  $m$  edges and  $G$ ’s adjacency matrix  $A \in \mathbb{R}^{n \times n}$ , modularity is defined as:

$$mod = \frac{1}{2m} \sum_{ij} \left( A_{ij} - \gamma \frac{d_i d_j}{2m} \right) I(c_i, c_j) \quad (1)$$

$d_i$  is the degree of node  $i$ .  $I(c_i, c_j)$  is 1 if nodes  $i$  and  $j$  are in the same community, 0 otherwise.

We experiment with two CD algorithms:

- Greedy modularity communities (GMC). This method uses Clauset-Newman-Moore greedy modularity maximization (Clauset et al., 2004). GMC begins with each node in its own community and greedily joins the pair of communities that most increases modularity until no such pair exists.
- Label propagation communities (LPC). This method finds communities in a graph using label propagation (Cordasco and Gargano, 2010). It begins by giving a label to each node of the network. Then each node’s label is updated by the most frequent label among its neighbors in each iteration. It performs label propagation on a portion of nodes at each step and quickly converges to a stable labeling.

After detecting communities, we link all nodes inside a community and remove all inter-community links. GMC (LPC) on average removes 3% (7%) of the edges. Table 1 reports the average number of graph components per sentence before and after running GMC and LPC, as well as the corresponding  $F_1$  for word alignment. We see that the

	FIN-HEB		FIN-GRC		ENG-FRA	
	#CC	$F_1$	#CC	$F_1$	#CC	$F_1$
Eflomal intersection	2.2	0.404	1.6	0.646	2.2	0.678
GMC	13.7	0.396	10.1	0.375	13.5	0.411
LPC	41.5	0.713	37.1	0.754	46.0	0.767
Sentence length	25.7		23.2		27.4	

Table 1: Effect of community detection algorithms on alignment prediction. #CC: average number of connected components.  $F_1$ : word alignment performance.

number of communities found is lower for GMC than for LPC; therefore, LPC identifies more candidate links for deletion.<sup>2</sup> Comparing the number of communities detected with the average sentence length, GMC seems to have failed to detect enough communities to split different concepts properly. The  $F_1$  scores confirm this observation and show that LPC performs well at detecting the communities we are looking for.

These results indicate that CD algorithms can provide valuable information. To exploit this in our GNN model, we add a node’s community information as a GNN node feature; see §3.1.2.

## 3 Methods

### 3.1 GNN in MPWA

GNNs can be used in transductive or inductive settings. Transductively, the final model can only be used for inference over the same graph that it is trained on. In an inductive setting, which we use here, nodes are represented as feature vectors, and the final model has the advantage of being applicable to a different graph in inference.

#### 3.1.1 Model Architecture

Our model is inspired by the Graph Auto Encoder (GAE) model of Kipf and Welling (2016b) for link prediction. The architecture consists of an encoder and a decoder. We make changes to this model to improve the model’s quality and reduce its computation cost. We use GATConv layers (Veličković et al., 2018) for encoder instead of GCNConv (Kipf and Welling, 2016a) and a more sophisticated decoder instead of simple dot product for a stronger model. We also introduce a more efficient training procedure.

The **encoder** is a graph attention network (GAT) (Veličković et al., 2018) with two GATConv layers

<sup>2</sup>LPC may detect more communities than average sentence length because of null words: words that have no translation in the other languages, giving rise to separate communities.

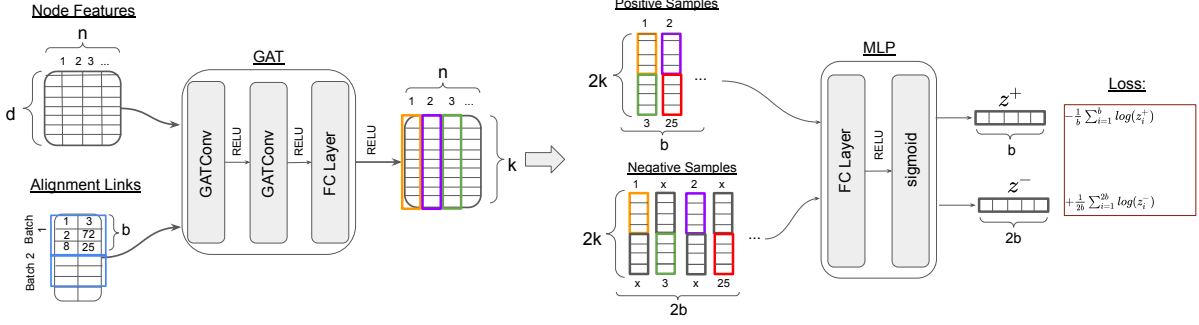


Figure 2: GNN training. At each training step, node features and links of a multiparallel sentence are fed to a graph attention network (GAT) that creates hidden representations for all nodes. On the decoder side, at each step, one batch of alignment links and hidden node representations is used to create positive and negative samples, which are then processed and classified by a multi-layer perceptron (MLP). Parameters of GAT and MLP are updated for each batch. FC = fully connected.

244 followed by a fully connected layer. Layers are  
 245 connected by RELU non-linearities. A GATConv  
 246 layer computes its output  $\mathbf{x}'_i$  for a node  $i$  from its  
 247 input  $\mathbf{x}_i$  as

$$248 \quad \mathbf{x}'_i = \alpha_{i,i} \mathbf{W} \mathbf{x}_i + \sum_{j \in \mathcal{N}(i)} \alpha_{i,j} \mathbf{W} \mathbf{x}_j, \quad (2)$$

249 where  $\mathbf{W}$  is a weight matrix,  $\mathcal{N}(i)$  is some *neigh-*  
 250 *borhood* of node  $i$  in the graph, and  $\alpha_{i,j}$  is the  
 251 attention coefficient indicating the importance of  
 252 node  $j$ 's features to node  $i$ .  $\alpha_{i,j}$  is computed as

$$253 \quad \alpha_{i,j} = \frac{\exp(g(\mathbf{a}^\top [\mathbf{W} \mathbf{x}_i \parallel \mathbf{W} \mathbf{x}_j]))}{\sum_{k \in \mathcal{N}(i) \cup \{i\}} \exp(g(\mathbf{a}^\top [\mathbf{W} \mathbf{x}_i \parallel \mathbf{W} \mathbf{x}_k]))} \quad (3)$$

254 where  $\parallel$  is concatenation,  $g$  is LeakyReLU, and  $\mathbf{a}$   
 255 is a weight vector. Given the features for the nodes  
 256 and their alignment edges, the encoder creates a  
 257 contextualized hidden representation for each node.

258 Based on the hidden representations of two  
 259 nodes, the **decoder** predicts whether a link con-  
 260 nects them. The decoder architecture consists of a  
 261 fully connected layer, a RELU non-linearity and a  
 262 sigmoid layer.

263 **Training.** By default, GAE models are trained  
 264 using full batches with random negative samples.  
 265 This approach requires at least tens of epochs over  
 266 training dataset to converge and a lot of GPU mem-  
 267 ory for graphs as big as ours. We train our model  
 268 using mini-batches and an adversarial loss to de-  
 269 crease memory requirements and improve the per-  
 270 formance. Using our training approach the model  
 271 converges after one epoch. The negative samples  
 272 are selected more elegantly, as described below.  
 273 Figure 2 displays our GNN model and the training

274 process. The outer loop iterates over the multipar-  
 275 allel sentences in the training set. The training set  
 276 contains one graph for each sentence; the graph  
 277 is constructed using the bilingual alignment edges  
 278 between all language pairs.

279 Each graph is divided into multiple batches. Each  
 280 batch contains a random subset of the graph's  
 281 edges as positive samples. The negative sam-  
 282 ples are created as follows. Given a sentence  
 283  $u_1 u_2 \dots u_n$  in language  $U$  and its translation  
 284  $v_1 v_2 \dots v_m$  in language  $V$ , for each alignment  
 285 edge  $u_i : v_j$  in the current batch, two negative  
 286 edges  $u_i : v'_j$  and  $u'_i : v_j$  ( $j' \neq j, i' \neq i$ )  
 are randomly sampled.

287 For each training batch, the encoder takes the  
 288 batch's whole graph (i.e., node features for all  
 289 graph nodes and all graph edges) as input and  
 290 computes hidden representations for the nodes. On  
 291 the decoder side, for each link of the batch, the  
 292 hidden representations of the attached nodes are  
 293 concatenated to create the decoder's input. The  
 294 decoder's target is the link's class: 1 (resp. 0) for  
 295 positive (resp. negative) links. We train with a  
 296 binary classification objective:

$$297 \quad \mathcal{L} = -\frac{1}{b} \sum_{i=1}^b \log(p_i^+) + \frac{1}{2b} \sum_{i=1}^{2b} \log(p_i^-) \quad (4)$$

298 where  $b$  is the batch size and  $p_i^+$  and  $p_i^-$  are the  
 299 model predictions for the  $i^{\text{th}}$  positive and nega-  
 300 tive samples within the batch. Parameters of the  
 301 encoder and decoder as well as the node-embed-  
 302 ding feature layer are updated after each training  
 step.

### 3.1.2 Node Features 303

304 We use three main types of node features: (i) graph  
 305 structural features, (ii) community-based features  
 306 and (iii) word content features.



**Graph structural features.** We use *degree*, *closeness* (Freeman, 1978), *betweenness* (Brandes, 2001), *load* (Newman, 2001) and *harmonic centrality* (Boldi and Vigna, 2014) features as additional information about the graph structure. These features are continuous numbers, providing information about the position and connectivity of the nodes within the graph. We standardize (i.e., z-score) each feature across all nodes, and train an embedding of size four for each feature.<sup>3</sup>

**Community-based features.** One way to incorporate community information into our model is to train the model based on the refined edges after the community detection step. This approach hobbles the GNN model by making decisions about many of the edges before the GNN gets to see them. Our initial experiments also confirmed that training the GNN over CD refined edges does not help. Therefore, we add community information as node features and let the GNN use them to improve its decisions. We use the community detection algorithms GMC and LPC (see §2) to identify communities in the graph. Then we take the community membership information of the nodes as one-hot vectors and learn an embedding of size 32 for each of the two algorithms.

**Word content features.** We train embeddings for *word position* (size 32) and *word language* (size 20). We learn 100-dimensional multilingual *word embeddings* using Levy et al. (2017)’s sentence-ID method on the 84 PBC languages selected by Imani et al. (2021). Word embeddings serve as initialization and are updated during GNN training.

After concatenating these features, each node is represented by a 236 dimensional vector that is then fed to the encoder.

### 3.1.3 Inducing Alignment Edges

When our trained GNN model is used to predict alignment edges between a source sentence  $\hat{x} = x_1, x_2, \dots, x_m$  in language  $X$  and a target sentence  $\hat{y} = y_1, y_2, \dots, y_l$  in language  $Y$ , it produces a symmetric alignment probability matrix  $S^4$  of size  $m \times l$  where  $S_{ij}$  is the predicted alignment probability between words  $x_i$  and  $y_j$ . Using these values directly to infer alignment edges is usually suboptimal; therefore, more sophisticated methods

<sup>3</sup>Learning a size-four embedding instead of a single number gives the feature a weight similar to other features – which have a feature vector of about the same size.

<sup>4</sup>For inference, we feed all possible alignment links between source and target to the decoder.

have been suggested (Ayan and Dorr, 2006; Liang et al., 2006). Here we propose a new approach: it combines Koehn et al. (2005)’s Grow-Diag-Final-And (GDFA) with Dou and Neubig (2021)’s probability thresholding. We modify the latter to account for the variable size of the probability matrix (i.e., length of source/target sentences). Our method is not limited to adding new edges to some initial bilingual alignments, a limitation of prior work. As we predict each edge independently, some initial links can be discarded from the final alignment.

We start by creating a set of *forward* (source-to-target) alignment edges and a set of *backward* (target-to-source) alignment edges. To this end, first, inspired by probability thresholding (Dou and Neubig, 2021), we apply softmax to  $S$ , and zero out probabilities below a threshold to get a source-to-target probability matrix  $S^{XY}$ :

$$S^{XY} = S * (\text{softmax}(S) > \frac{\alpha}{l}) \quad (5)$$

Analogously, we compute the target-to-source probability matrix  $S^{YX}$ :

$$S^{YX} = S^T * (\text{softmax}(S^T) > \frac{\alpha}{m}) \quad (6)$$

where  $\alpha$  is a sensitivity hyperparameter, e.g.,  $\alpha = 1$  means that we pick edges with a probability higher than average. We experimentally set  $\alpha = 2$ . Next, from each row of  $S^{XY}$  ( $S^{YX}$ ), we pick the cell with the highest value (if any exists) and add this edge to the *forward* (*backward*) set.

We create the final set of alignment edges by applying the GDFA symmetrization method (Koehn et al., 2005) to *forward* and *backward* sets. The gist of GDFA is to use the intersection of *forward* and *backward* as initial alignment edges and add more edges from the union of *forward* and *backward* based on a number of heuristics. We call this method *TGDFA* (Thresholding GDFA).

We also experiment with combining *TGDFA* with the original bilingual GDFA alignments. We do so by adding bilingual GDFA edges to the union of *forward* and *backward* before performing the GDFA heuristics. We refer to these alignments as *TGDFA+orig*.

We evaluate the resulting alignments using  $F_1$  score and alignment error rate (AER), the standard evaluation measures in the word alignment literature.

Method	FIN-HEB				FIN-GRC				ENG-FRA			
	Prec.	Rec.	$F_1$	AER	Prec.	Rec.	$F_1$	AER	Prec.	Rec.	$F_1$	AER
Eflomal (intersection)	<b>0.818</b>	0.269	0.405	0.595	<b>0.897</b>	0.506	0.647	0.353	<b>0.971</b>	0.521	0.678	0.261
Eflomal (GDFA)	0.508	0.448	0.476	0.524	0.733	0.671	0.701	0.300	0.856	0.710	0.776	0.221
WAdAd (intersection)	0.781	0.612	0.686	0.314	0.849	0.696	0.765	0.235	0.938	0.689	0.794	0.203
NMF (intersection)	0.780	0.576	0.663	0.337	0.864	0.669	0.754	0.248	0.948	0.624	0.753	0.245
WAdAd (GDFA)	0.546	<b>0.693</b>	0.611	0.389	0.707	<b>0.783</b>	0.743	0.257	0.831	<b>0.796</b>	0.813	0.186
NMF (GDFA)	0.548	0.646	0.593	0.407	0.720	0.759	0.739	0.261	0.844	0.767	0.804	0.195
GNN (TG DFA)	0.811	0.648	<b>0.720</b>	<b>0.280</b>	0.845	0.724	<b>0.780</b>	<b>0.220</b>	0.926	0.711	0.804	0.192
GNN (TG DFA+orig)	0.622	0.683	0.651	0.349	0.738	0.780	0.758	0.242	0.863	0.789	<b>0.824</b>	<b>0.174</b>

Table 2: Word alignment results on PBC for GNN and baselines. The best result in each column is in bold. GNN outperforms the baselines as well as the graph algorithms WAdAd and NMF on  $F_1$  and AER.

### 3.2 Annotation Projection

Annotation projection automatically creates linguistically annotated corpora for low-resource languages. A model trained on data with “annotation-projected” labels can perform better than full unsupervision. Here, we focus on universal part-of-speech (UPOS) tagging (Petrov et al., 2012) for the low resource target language Yoruba; this language only has a small set of annotated sentences in Universal Dependencies (Nivre et al., 2020) and has poor POS results in unsupervised settings (Konratyuk and Straka, 2019).

The quality of the target annotated corpus depends on the quality of the annotations in the source languages and the quality of the word alignments between sources and target. We use the Flair (Akbiik et al., 2019) POS taggers for three high resource languages, English, German and French (Akbiik et al., 2018), to annotate 30K verses whose Yoruba translations are available in PBC. We then transfer the POS tags from source to target using three different approaches: (i) We directly transfer annotations from English to the target. (ii) For each word in the target, we get its alignments in the three source languages and predict the majority POS to annotate the target word. (iii) We repeat (ii) using alignments from our GNN (TG DFA) model instead of the original bilingual alignments. In all three approaches, we discard any target sentence from the POS tagger training data if more than 50% of its words are annotated with the “X” (other) tag.

We train a Flair SequenceTagger model on the target annotated data using mBERT embeddings (Devlin et al., 2019) and evaluate on Yoruba test from Universal Dependencies.<sup>5</sup>

<sup>5</sup><https://universaldependencies.org/>

## 4 Experimental Setup

### 4.1 Word Alignment Datasets

Following Imani et al. (2021), we use PBC, a multiparallel corpus of 1758 sentence-aligned editions of the Bible in 1334 languages.

**Evaluation data.** For our main evaluation, we use the two word alignment gold datasets for PBC published by Imani et al. (2021): Blinker (Melamed, 1998) and HELFI (Yli-Jyrä et al., 2020). **The HELFI dataset** contains the Hebrew Bible, Greek New Testament and their translations into Finnish. For HELFI, we use Imani et al. (2021)’s train/dev/test splits. **The Blinker dataset** provides word level alignments between English and French for 250 Bible verses.

**Training data.** The graph algorithms used by Imani et al. (2021) operate on each multiparallel sentence separately. In contrast, our approach allows for an inductive setting where a model is trained on a training set and then evaluated on a separate test set. We combine the verses in the training sets of Finnish-Hebrew and Finnish-Greek for a combined train set size of 24,159.

### 4.2 Initial Word Alignments

We use the Eflomal statistical word aligner to obtain bilingual alignments. We train it for every language pair in our experiments. We do not consider SimAlign (Jalili Sabet et al., 2020) since it is shown to perform poorly for languages whose representations in the multilingual pretrained language model are of low quality. We use Eflomal asymmetrical alignments post-processed with the intersection heuristic to get high precision bilingual alignments as input to the GNN. We use the same subset of 84 languages as Imani et al. (2021).

### 4.3 Training Details

We use PyTorch Geometric<sup>6</sup> to construct and train the GNN. The model’s hidden layer size is 512 for both GATConv and Linear layers. We train for one epoch on the train set – a small portion of the train set is enough to learn good embeddings (see §5.1.1). For training, we use a batch size of 400 and learning rate of .001 with AdamW (Loshchilov and Hutter, 2017). The whole training process takes less than 4 hours on a GeForce GTX 1080 Ti and the inference time is on the order of milliseconds per sentence.

## 5 Experiments and Results

### 5.1 Multiparallel corpus results

Table 2 shows results on Blinker and HELFI for our GNNs and the baselines: bilingual alignments and the traditional graph algorithms WAdAd and NMF from Imani et al. (2021). Our GNNs provide a better trade-off between precision and recall, most likely thanks to their ability to remove edges, and achieve the best  $F_1$  and AER on all three datasets, outperforming WAdAd and NMF.

GNN (TG DFA) achieves the best results on HELFI (FIN-HEB, FIN-GRC) while GNN (TG DFA+orig) is best on Blinker (ENG-FRA). As argued in Imani et al. (2021), this is mostly due to the different ways these two datasets were annotated. Most HELFI alignments are one-to-one, while many Blinker alignments are many-to-many: phrase-level alignments where every word in a source phrase is aligned with every word in a target phrase. This suggests that one can choose between GNN (TG DFA) and GNN (TG DFA+orig) based on the characteristics of the desired alignments.

#### 5.1.1 Effect of Training Set Size

To investigate the effect of training set size, we train the GNN on subsets of our training data with increasing sizes. Figure 3 shows results. Performance improves fast until around 2,000 verses; then it stays mostly constant. Indeed, using more than 6,400 samples does not change the performance at all. Therefore, in the other experiments we use 6,400 randomly sampled verses from the training set to train GNNs.

#### 5.1.2 Ablation Experiments

To examine the importance of node features, we ablate language, position, centrality, community

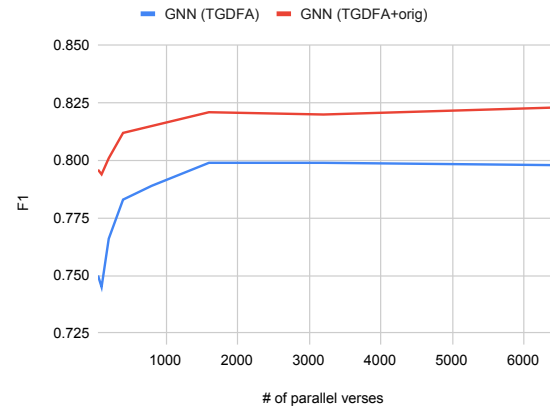


Figure 3:  $F_1$  of GNN (TG DFA) and GNN (TG DFA+orig) on Blinker as a function of train size

and word embedding features. Table 3 shows that removal of graph structural features drastically reduces performance. Community features and language information are also important. Removal of word position information and word embeddings – which store semantic information about words – has the least effect. Based on these results, it can be argued that the lexical information contained in the initial alignments and in the community features provides a strong signal regarding word relatedness. The novel information that is crucial is about the overall graph structure which goes beyond the local word associations that are captured by word position and word embeddings.

#### 5.1.3 Effect of Word Frequency

We investigate the effect of word frequency on alignment performance where frequency is calculated based on the source word in the PBC; the first bin has the highest frequency. Figure 4 shows that the performance of Eflomal drops with frequency and it struggles to align very rare words. In contrast, GNN is not affected by word frequency as severely and its performance gains are even greater for rare words. WAdad which is the multilingual baseline from (Imani et al., 2021) has the same trend as GNN method, but GNN is more robust.

### 5.2 Annotation Projection

Table 4 presents accuracies for POS tagging in Yoruba. Unsupervised baseline performance is 50.86%. Supervised training using pseudo-labels mostly outperforms the unsupervised baseline. Projecting the majority POS labels to Yoruba improves over projecting English labels. Using the GNN model to project labels works best and outperforms

<sup>6</sup>[pytorch-geometric.readthedocs.io](https://pytorch-geometric.readthedocs.io)

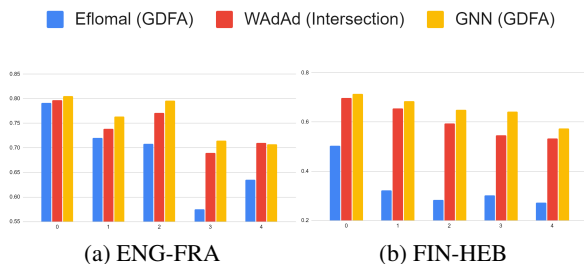


Figure 4:  $F_1$  for different frequency bins.

	FIN-HEB	FIN-GRC	ENG-FRA
GNN (TG DFA)	0.720	0.780	0.804
- language	-0.323	-0.280	-0.370
- position	-0.068	-0.045	-0.066
- centrality	-0.636	-0.730	-0.772
- community	-0.204	-0.238	-0.253
- word-embedding	-0.139	-0.103	-0.129
GNN (TG DFA+orig)	0.651	0.758	0.824
- language	-0.238	-0.077	-0.162
- position	-0.088	+0.029	-0.032
- centrality	-0.556	-0.530	-0.617
- community	-0.156	-0.039	-0.083
- word-embedding	-0.135	+0.002	-0.058

Table 3:  $F_1$  for GNNs and  $\Delta F_1$  for five ablations

Eflomal-GDFA-majority (the unsupervised baseline) by 5% (15%) absolute improvement.

## 6 Related Work

**Bilingual Word Aligners.** Much work on bilingual word alignment is based on probabilistic models, mostly implementing variants of the IBM models of Brown et al. (1993): e.g., Giza++ (Och and Ney, 2003), fast-align (Dyer et al., 2013) and Eflomal (Östling and Tiedemann, 2016). More recent work, including SimAlign (Jalili Sabet et al., 2020) and SHIFT-ATT/SHIFT-AET (Chen et al., 2020), uses pretrained neural language and machine translation models. Although neural models achieve superior performance compared to statistical aligners, they are only applicable for less than two hundred high-resource languages that are supported by multilingual language models like BERT (Devlin et al., 2019) and XLM-R (Conneau et al., 2020). This makes statistical models the only option for the majority of the world’s languages.

**Multiparallel Corpora.** Prior applications of using multiparallel corpora include reliable translations from small datasets (Cohn and Lapata, 2007), and phrase-based machine translation (PBMT) (Kumar et al., 2007). Multiparallel corpora are also used for language comparison (Mayer and Cysouw, 2012), typological studies (Östling, 2015; Asgari

Model	Yoruba YTB
Unsupervised (Kondratyuk and Straka, 2019)	50.86
Eflomal Inter - eng	43.45
Eflomal GDFA - eng	55.13
Eflomal Inter - majority	54.13
Eflomal GDFA - majority	60.27
GNN (TG DFA) - majority	<b>65.74</b>
GNN (TG DFA+orig) - majority	64.55

Table 4: POS tagging with annotation projection for Yoruba. Apart from “Unsupervised”, all lines show a sequence tagger trained on pseudo-labels induced by word alignments. GNN-based pseudo-labels outperform prior work by 5%.

and Schütze, 2017) and PBMT (Nakov and Ng, 2012; Bertoldi et al., 2008; Dyer et al., 2013).

To the best of our knowledge Östling (2014)<sup>7</sup> is the only word alignment method designed for multiparallel corpora. However, this method is outperformed by Eflomal (Östling and Tiedemann, 2016), a “biparallel” method from the same author. Recently, Imani et al. (2021) proposed MPWA, which we use as our baseline.

**Graph Neural Networks (GNNs)** have been used to address many problems that are inherently graph-like such as traffic networks, social networks, and physical and biological systems (Liu and Zhou, 2020). GNNs achieve impressive performance in many domains, including social networks (Wu et al., 2020) and natural science (Sanchez-Gonzalez et al., 2018) as well as NLP tasks like sentence classification (Huang et al., 2020), question generation (Pan et al., 2020), and summarization (Fernandes et al., 2019).

## 7 Conclusion and Future Work

We introduced graph neural networks and community detection algorithms for multiparallel word alignment. By incorporating signals from diverse sources as node features, including community features, our GNN model outperformed the baselines and prior work, establishing new state-of-the-art results on three PBC gold standard datasets. We also showed that our GNN model improves downstream task performance in low-resource languages through annotation projection.

We have only used node features to provide signals to GNNs. In the future, other signals can be added in the form of edge features to further boost the performance.

<sup>7</sup>[github.com/robertostling/eflomal](https://github.com/robertostling/eflomal)



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943

## **A Appendix**

944

### **A.1 Languages**



Afrikaans	Albanian	Arabic	Armenian	Azerbaijani	Bashkir
Basque	Belarusian	Bengali	Breton	Bulgarian	Burmese
Catalan	Cebuano	Chechen	Chinese	Chuvash	Croatian
Czech	Danish	Dutch	English	Estonian	Finnish
French	Georgian	German	Greek	Gujarati	Haitian
Hebrew	Hindi	Hungarian	Icelandic	Indonesian	Irish
Italian	Japanese	Javanese	Kannada	Kazakh	Kirghiz
Korean	Latin	Latvian	Lithuanian	Low Saxon	Macedonian
Malagasy	Malay	Malayalam	Marathi	Minangkabau	Nepali
Norwegian (Bokmal)	Norwegian (Nynorsk)	Punjabi	Persian	Polish	Portuguese
Punjabi	Romanian	Russian	Serbian	Slovak	Slovenian
Spanish	Swahili	Sundanese	Swedish	Tagalog	Tajik
Tamil	Tatar	Telugu	Turkish	Ukrainian	Urdu
Uzbek	Vietnamese	Waray-Waray	Welsh	West Frisian	Yoruba

Table 5: List of the 84 languages we used in our experiments.