

BOUNDS ON L_p ERRORS IN DENSITY RATIO ESTIMATION VIA f -DIVERGENCE LOSS FUNCTIONS

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ABSTRACT

Density ratio estimation (DRE) is a fundamental machine learning technique for identifying relationships between two probability distributions. f -divergence loss functions, derived from variational representations of f -divergence, are commonly employed in DRE to achieve state-of-the-art results. This study presents a novel perspective on DRE using f -divergence loss functions by deriving the upper and lower bounds on L_p errors. These bounds apply to any estimator within a class of Lipschitz continuous estimators, irrespective of the specific f -divergence loss functions utilized. The bounds are formulated as a product of terms that include the data dimension and the expected value of the density ratio raised to the power of p . Notably, the lower bound incorporates an exponential term dependent on the Kullback–Leibler divergence, indicating that the L_p error significantly increases with the Kullback–Leibler divergence for $p > 1$, and this increase becomes more pronounced as p increases. Furthermore, these theoretical findings are substantiated through numerical experiments.

1 INTRODUCTION

Density ratio estimation (DRE) is a key technique in machine learning that calculates the density ratio $r^*(\mathbf{x}) = q(\mathbf{x})/p(\mathbf{x})$ between two probability distributions based on samples drawn independently from p and q . DRE is integral to various machine learning methods such as generative modeling (Goodfellow et al., 2014; Nowozin et al., 2016; Uehara et al., 2016), mutual information estimation and representation learning (Belghazi et al., 2018; Hjelm et al., 2018), energy-based modeling (Gutmann & Hyvärinen, 2010), and covariate shift and domain adaptation (Shimodaira, 2000; Huang et al., 2006).

Recent advancements in DRE have been driven by neural network-based methods, which utilize neural networks as density ratio estimators. These methods employ loss functions derived from variational representations of f -divergence (Nguyen et al., 2010; Sugiyama et al., 2012), where the optimal function corresponds to the density ratio through the Legendre transform, achieving state-of-the-art results.

Amidst their success, ongoing research has started to elucidate the theoretical relationship between the optimization of f -divergence loss functions and DRE accuracy. For integral probability metric (IPM) loss functions, the upper and lower bounds of the L_p error in DRE have been established as the minimax bounds of their optimization (Liang, 2017; Niles-Weed & Berthet, 2022). More recent studies have focused on f -divergence loss functions to derive the upper bounds (Belomestny et al., 2021) and the minimax upper and lower bounds for the optimization of Shannon divergence loss (Belomestny et al., 2021; Puchkin et al., 2024).

However, several aspects of this relationship remain unresolved. First, the minimax lower bounds do not represent the true lower bound of estimation accuracy for the actual density ratio. Second, the connection between the true magnitudes of f -divergences and the sample size requirements for DRE using divergence loss functions is not completely understood. Specifically, the impact of the

true amount of Kullback–Leibler (KL) divergence on the sample size needed for DRE using the KL-loss function is unclear, despite known exponential increases in sample size requirements for KL-divergence estimation as the true KL-divergence widens (Poole et al., 2019; Song & Ermon, 2019; McAllester & Stratos, 2020). Finally, it is not understood whether the L_p errors, e.g., the root mean square errors (RMSE), of DRE are statistically equivalent, regardless of the choice of f -divergence loss function, such as the total variation loss or the KL-divergence loss function.

This study aims to address uncertainties in DRE using f -divergence loss functions by deriving the upper and lower bounds that are independent of the choice of f -divergence. However, the theoretical optimization of f -divergence loss functions is challenging owing to their reliance on sample sets from two distributions. The lack of overlap in these sample sets leads to unstable optimization points, causing the losses to fall below their theoretical optimal values. Practically, this issue is often mitigated by implementing early stopping while monitoring validation losses.

We integrate this practical approach into our theoretical analysis framework through a conceptual reformulation of the loss functions, thus bridging the gap between practical and theoretical behaviors of these functions. Subsequently, we derive upper and lower bounds for the L_p error in DRE by optimizing f -divergence loss functions. These bounds are derived from the expectation of the distance between the nearest neighbors in observations, assuming the L -Lipschitz continuity of the energy function of the distributions and the compactness of the support.

The upper and lower bounds are formulated as a product of terms involving the data dimension and the expectation of the density ratio raised to the power of p . Notably, the lower bound includes an exponential term of the KL-divergence, indicating that the L_p error significantly increases as the KL-divergence increases for $p > 1$, with the rate of increase accelerating for larger values of p . These bounds are applicable to a group of Lipschitz continuous estimators, irrespective of the specific f -divergence loss functions employed. The theoretical implications are validated through numerical experiments.

To summarize, the key contributions of this study are as follows: (1) We provide common upper and lower bounds for the L_p error in DRE through optimizations of variational representations of f -divergences, introducing a novel understanding of DRE using f -divergence loss functions. (2) We empirically investigate the relationship between KL-divergence, data dimension, and the estimation accuracy of DRE through optimizations of variational representations of f -divergences. Specifically, we discover that the L_p error significantly increases with the rise in KL-divergence when $p > 1$, and this increase is exacerbated by the magnitude of the order p .

Related Work. This study provides upper and lower bounds on convergence rates for nonparametric density ratio estimation using f -divergence optimization. Relevant prior work includes studies on the minimax convergence rates for density estimation within the context of GAN optimization, specifically for Wasserstein GANs (Arjovsky & Bottou, 2017) and vanilla GANs (Goodfellow et al., 2014). For Wasserstein GAN optimization, Liang (2017) and Singh & Póczos (2018) established the minimax convergence rates for the IPW loss, which encompasses the total variation among f -divergences. Additionally, Niles-Weed & Berthet (2022) extended these results to the Wasserstein- p distance for $p > 1$. In the context of vanilla GAN optimization, Belomestny et al. (2021) and Puchkin et al. (2024) presented minimax upper and lower convergence rates for the Shannon divergence loss, providing an upper bound for the L_2 error. Beyond GAN-related research, Nguyen et al. (2010) presented an upper bound for the Hellinger distance in DRE using the KL-divergence loss, thereby providing a minimax upper bound for the L_1 error in DRE. Additionally, foundational work by Stone (1980) established a minimax convergence rate for nonparametric regression, which is also applicable to an upper bound for the L_1 error in nonparametric density estimation.

2 PRELIMINARIES: NOTATION, SETUP, AND f -DIVERGENCE LOSS FUNCTIONS

In this section, we introduce the notation, problem setup, and the variational representation of f -divergence, along with the corresponding loss functions that underpin the analysis in subsequent sections.

2.1 NOTATION, PRELIMINARY CONCEPTS, AND SETUP

Notation. Random variables are denoted by uppercase letters, such as X . Lowercase letters represent specific values of these random variables; for instance, x denotes a value of the random variable X . Boldface letters, \mathbf{X} and \mathbf{x} , denote the sets of random variables and their corresponding values, respectively. $\|\mathbf{y} - \mathbf{x}\|_\infty$ denotes the maximum norm in \mathbf{R}^d . i.e., $\|\mathbf{y} - \mathbf{x}\|_\infty = \max_{1 \leq i \leq d} |y_i - x_i|$ for $\mathbf{y} = (y_1, y_2, \dots, y_d)$ and $\mathbf{x} = (x_1, x_2, \dots, x_d)$. $\text{diag}(\Omega)$ denotes the diameter of Ω . Specifically, let $\text{diag}(\mathcal{B}) = \inf_{r \in \mathbb{R}} \{\mathcal{B} \subseteq \Delta(\mathbf{a}, r) \mid \exists \mathbf{a} \in \mathcal{B}\}$, where $\Delta(\mathbf{a}, r)$ denotes the d -dimensional interval centered at \mathbf{a} with each side of length r : $\Delta(\mathbf{a}, r) = \{\mathbf{x} \in \mathbb{R}^d \mid \|\mathbf{x} - \mathbf{a}\|_\infty < r/2\}$. $O_p(a_n)$ denotes stochastic boundedness with rate a_n in μ . i.e., $\mathbf{X} = O_p(a_n)$ (as $N \rightarrow \infty$) \Leftrightarrow for all $\varepsilon > 0$, there exist $\delta(\varepsilon) > 0$ and $N(\varepsilon) > 0$ such that $\mu(\|\mathbf{X}\|/a_n \geq \delta(\varepsilon)) < \varepsilon$ for all $n \geq N(\varepsilon)$.

Preliminary Concepts. P and Q are used as the probability measures on (Ω, \mathcal{F}) , where \mathcal{F} denotes the σ -algebra on Ω . P is called *absolutely continuous* with respect to Q , $P(A) = 0$ whenever $Q(A) = 0$ for any $A \in \mathcal{F}$, which is represented as $P \ll Q$. $\frac{dP}{dQ}$ denotes the Radon–Nikodým derivative of P with respect to Q for P and Q with $P \ll Q$. μ denotes a probability measure on Ω with $P \ll \mu$ and $Q \ll \mu$. An example of μ is $(P + Q)/2$. $E_P[\cdot]$ denotes the expectation under the distribution P , i.e., $E_P[\phi(\mathbf{x})] = \int_{\Omega_p} \phi(\mathbf{x}) dP(\mathbf{x})$, where $\phi(\mathbf{x})$ represents a measurable function over Ω .

Setup. P and Q are probability distributions on $\Omega \subset \mathbb{R}^d$ with unknown probability densities p and q , respectively. We assume $p(\mathbf{x}) > 0 \Leftrightarrow q(\mathbf{x}) > 0$ almost everywhere $\mathbf{x} \in \Omega$.¹

2.2 DRE WITH f -DIVERGENCE VARIATIONAL REPRESENTATION

Herein, we introduce the f -divergence variational representation along with the corresponding loss functions used for DRE.

Definition 2.1 (f -divergence). The f -divergence D_f between two probability measures P and Q is induced by a convex function f that satisfies $f(1) = 0$, which can be defined as $D_f(Q||P) = E_P[f(dQ/dP(\mathbf{x}))]$.

Various divergences are specific instances derived by choosing an appropriate generator function f . For example, the function $f(u) = u \cdot \log u$ yields the Kullback–Leibler divergence.

We then derive the variational representations of f -divergences using the Legendre transform of the convex conjugate of a twice differentiable convex function f , $f^*(\psi) = \sup_{u \in \mathbb{R}} \{\psi \cdot u - f(u)\}$ (Nguyen et al., 2007):

$$D_f(Q||P) = \sup_{\phi \geq 0} \left\{ E_Q[f'(\phi)] - E_P[f^*(f'(\phi))] \right\}, \quad (1)$$

where the supremum is required over all measurable functions $\phi : \Omega \rightarrow \mathbb{R}$ with $E_Q[|f'(\phi)|] < \infty$ and $E_P[|f^*(f'(\phi))|] < \infty$. The maximum value is achieved at $\phi(\mathbf{x}) = dQ/dP(\mathbf{x})$. Pairs of the terms $f'(\phi)$ and $f^*(f'(\phi))$ in Equation (1) for major f -divergences, along with their corresponding convex functions f , are provided in Table 2 in the Appendix.

By substituting ϕ with a neural network model ϕ_θ and replacing the expectation E with sample means \hat{E} , the optimal function for Equation (1) is trained through back-propagation using an f -divergence loss function.

$$\mathcal{L}_f(\phi_\theta) = - \left\{ \hat{E}_Q[f'(\phi_\theta)] - \hat{E}_P[f^*(f'(\phi_\theta))] \right\}. \quad (2)$$

Formally, we define the f -divergence loss function within a probabilistic theoretical framework as follows:

Definition 2.2 (f -Divergence Loss). Let $\hat{\mathbf{X}}_{P[R]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^R\}$, $\mathbf{X}_P^i \stackrel{\text{iid}}{\sim} P$ denote R i.i.d. random variables from P , and let $\hat{\mathbf{X}}_{Q[S]} = \{\mathbf{X}_Q^1, \mathbf{X}_Q^2, \dots, \mathbf{X}_Q^S\}$, $\mathbf{X}_Q^i \stackrel{\text{iid}}{\sim} Q$ denote S i.i.d. random variables from Q . Thereafter, for a twice differentiable convex function f , f -divergence loss $\mathcal{L}_f^{(R,S)}(\cdot)$

¹In this study, $q(\mathbf{x})/p(\mathbf{x})$ is written for $\frac{dQ}{dP}(\mathbf{x})$ using the Radon–Nikodým density representation for readability.

is defined as follows:

$$\mathcal{L}_f^{(R,S)}(\phi) = \frac{1}{S} \cdot \sum_{i=1}^S -f'(\phi(\mathbf{X}_Q^i)) + \frac{1}{R} \sum_{i=1}^R f^*(f'(\phi(\mathbf{X}_P^i))), \quad (3)$$

where ϕ denotes a measurable function over Ω such that $\phi : \Omega \rightarrow \mathbb{R}_{>0}$.

3 MAIN RESULTS

The key findings of this study are twofold. First, we establish common upper and lower bounds for the L_p error in DRE by employing variational f -divergence optimization. Second, we empirically investigate the relationship between KL-divergence, data dimension, and the estimation accuracy of DRE through variational f -divergence optimization. Specifically, we discover that the L_p error significantly increases with the rise in KL-divergence when $p > 1$, and this increase is exacerbated by the magnitude of the order p .

3.1 THEORETICAL RESULTS.

In this study, we outline the assumptions necessary for deriving the upper and lower bounds of the DRE. The assumptions are straightforward and primarily involve the consideration of Lipschitz continuous estimators. Specifically, we assume the L -Lipschitz continuity of the energy function of the distributions, $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$.

Assumption 3.1 (Assumption for the Upper Bound). The following assumption is imposed on the probability distributions P and Q .

U1. $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$ is L -Lipschitz continuous with $L > 0$ on Ω .

Assumption 3.2 (Assumptions for the Lower Bound). The following assumptions are imposed on the probability distributions P and Q .

L1. $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$ is L -bi-Lipschitz continuous with $L > 1$ on Ω .

L2. $E_P[(dQ/dP)^p] < \infty$ where $p \leq d$.

For the probability distributions P and Q , Assumption L1 is crucial for deriving the lower bound of the L_p error in DRE. Further details on this assumption can be found in Remark 4.6 in Section 4.2.

Additionally, Assumptions 3.3 and 3.4 are necessary for deriving both the upper and lower bounds of the DRE.

Assumption 3.3 (Assumptions for the Convex Function f). The convex function f is assumed to satisfy the following: (F1) f is three-times differentiable; (F2) $f''(u) > 0$ for all $u > 0$; and (F3) $E_P[f''(dQ/dP)] < \infty$.

Assumption 3.4 (Assumption for the Support). The support Ω is assumed to satisfy the following: (O1) $\text{diag}(\Omega) < \infty$.

Under these conditions, we obtain the upper and lower bounds for the L_p error in DRE through variational f -divergence optimization.

Theorem 3.5 (Informal. See Theorem 4.5 and 4.8). Assume Ω is a compact set in \mathbb{R}^d , where $d \geq 3$, and f satisfies Assumption 3.3. Let P and Q denote the probability measures on Ω , and let ϕ represent a K -Lipschitz function that minimizes the f -divergence loss functions. Let ϕ be a K -Lipschitz function that minimizes the f -divergence loss functions $\mathcal{L}_f^{(R,S)}(\cdot)$ defined as Equation (3) using early stopping. Additionally, let $N = \min\{R, S\}$.

(Upper Bound) Assume Assumption 3.1: Thereafter, Equation (4) holds for $1 \leq p \leq d/2$ such that

$$\left\| \frac{q(\mathbf{x})}{p(\mathbf{x})} - \phi(\mathbf{x}) \right\|_{L_p(\Omega, P)} \lesssim \frac{\text{diag}(\Omega)}{N^{1/d}} \cdot \left\{ L \cdot E \left[\left(\frac{dQ}{dP} \right)^{2 \cdot p} \right]^{1/(2 \cdot p)} + K \right\}. \quad (4)$$

(Lower Bound) Assume Assumption 3.2: Equations (5) and (6) hold for $1 \leq p \leq d$ such that

$$E_{\mathbf{x}_P^1 \dots \mathbf{x}_P^N} \left[\left\| \frac{q(\mathbf{x})}{p(\mathbf{x})} - \phi(\mathbf{x}) \right\|_{L_p(\Omega, P)} \right] \gtrsim \frac{1}{N^{1/d}} \cdot \left\{ \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - K \cdot \text{diag}(\Omega) \right\} \quad (5)$$

$$\gtrsim \frac{1}{N^{1/d}} \cdot \left\{ \frac{1}{L} \cdot e^{\frac{(p-1)}{p} \cdot KL(P||Q)} - K \cdot \text{diag}(\Omega) \right\}, \quad (6)$$

where $\|\cdot\|_{L_p(\Omega, P)}$ denotes the L_p norm on Ω and the Lebesgue integral on P and $KL(P||Q)$ denotes the KL-divergence between P and Q .

These bounds are applicable to all K -Lipschitz continuous estimators optimized using the f -divergence loss functions with early stopping, as discussed in Section 4.3 and supported by Theorem 4.8.

Theorem 3.5 indicates that the curse of dimensionality occurs when $p = 1$. For $p > 1$, both the curse of dimensionality and the large sample requirement for high KL-divergence data occur concurrently. Equation (6) demonstrates that the L_p error escalates significantly with increasing KL-divergence for $p > 1$, and this increase accelerates as p increases. These theoretical findings are corroborated by numerical experiments, which are discussed in the subsequent section.

3.2 EXPERIMENTAL RESULTS.

We empirically verified the relationship among KL-divergence, data dimension, and estimation accuracy of DRE through variational f -divergence optimization. The results, which support the implications of Theorem 3.5, are detailed in Section D in the Appendix.

L_p Errors vs. the KL-Divergence in Data We conducted the experiments on the relationship between L_1 , L_2 , and L_3 errors in DRE and the KL-divergence of the data. In the experiments, we generated 100 sets of 5-dimensional datasets with the KL-divergence of 1, 2, 4, 6, 8, 10, 12, and 14. For each dataset, DRE was conducted using α -divergence and KL-divergence loss functions, then L_1 , L_2 , and L_3 errors were observed. We reported the results as Figure 1. The details of the experimental settings and neural network training are provided in Section D in the Appendix.

As displayed in Figure 1, the estimation errors for $p > 0$ increased significantly, which accelerates as p becomes larger. In contrast, when $p = 0$, a relatively mild increase was observed. As indicated by Theorem 3.5, these results highlight the impact of the KL-divergence in the data on L_p error with $p > 1$ in DRE f -divergence loss functions.

L_p Errors vs. the Dimensions of Data We conducted experiments to investigate the relationship between L_1 , L_2 , and L_3 errors in DRE and the dimensionality of the data. In the experiments, we generated 100 sets of datasets of 50, 100 and 200 dimensions with the KL-divergence amounts of 3. For each dataset, DRE was conducted using α -divergence and KL-divergence loss functions, then L_1 , L_2 , and L_3 errors were observed. We reported the results as Figure 2. The details of the experimental settings and neural network training are provided in Section D in the Appendix.

As depicted in Figure 2, the estimation errors L_1 , L_2 , and L_3 for $p > 0$ increased as the data dimensionality increased for both the α -divergence and KL-divergence loss functions. These results indicate that the curse of dimensionality occurs equally across the L_p errors, as stated by Theorem 3.5.

4 OVERVIEW OF UPPER AND LOWER BOUND DERIVATIONS

In this section, we outline the derivation of the upper and lower bounds. We begin by introducing a conceptual reformulation of the f -divergence loss function, which forms the basis of our theoretical framework. Next, we derive the upper and lower bounds for DRE in terms of L_P error, based on this reformulation. Finally, we extend these results to the optimization of the f -divergence loss function, incorporating early stopping and monitoring validation losses, which constitutes the core theoretical contribution of this study. Detailed statements and proofs for the theorems mentioned in this section are provided in Section C of the Appendix.

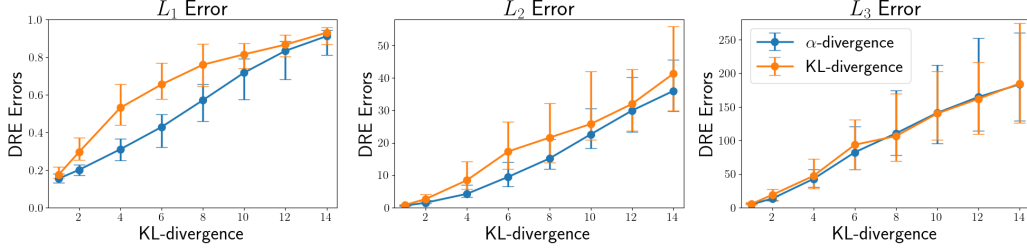


Figure 1: Experimental results of L_p errors versus the amount of KL-divergence in the data are presented, as detailed in Section 3.2. The x -axis represents the amount of KL-divergence in synthetic datasets of fixed dimension. The y -axes of the left, center, and right graphs correspond to the L_1 , L_2 , and L_3 errors in DRE, respectively. The plots show the median y -axis values, while the error bars represent the interquartile range (25th to 75th percentiles). The blue line shows errors using the α -divergence loss function, and the orange line shows errors using the KL-divergence loss function.

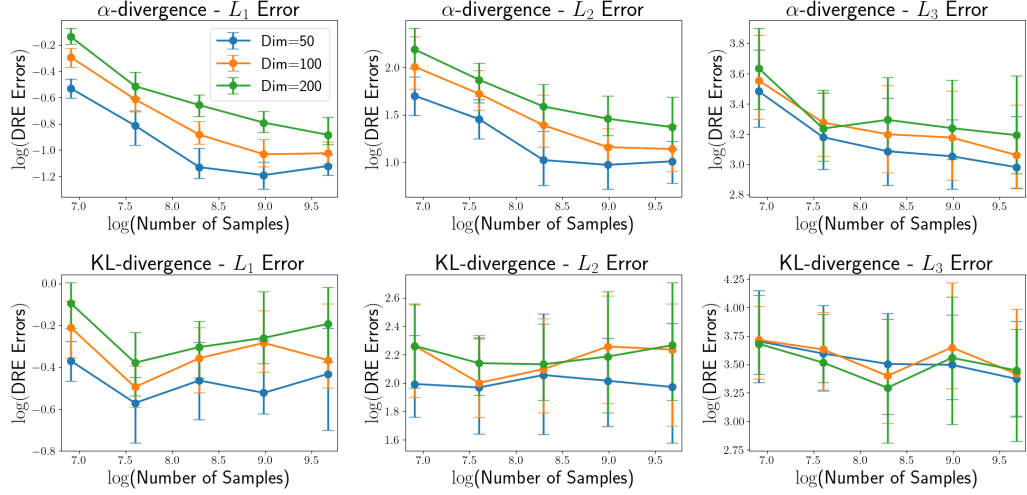


Figure 2: Experimental results on L_p errors versus the dimensionality of the data are presented, as detailed in Section 3.2. The top row displays results using the α -divergence loss function, whereas the bottom row presents results using the KL-divergence loss function. The x -axis represents the logarithm of the number of samples utilized in the optimizations of DRE. The y -axes of the left, center, and right graphs correspond to the L_1 , L_2 , and L_3 errors in DRE, respectively. The plots show the median y -axis values, while the error bars represent the interquartile range (25th to 75th percentiles). The blue, orange, and green lines show results for data dimensions of 50, 100, and 200, respectively.

4.1 CONCEPTUAL REFORMULATION OF THE f -DIVERGENCE LOSS FUNCTIONS

The optimization of f -divergence loss functions, denoted as $\mathcal{L}_f^{(R,S)}(\phi)$ in Equation (3), presents both practical and theoretical challenges owing to their tendency to overfit the training data.

To more deeply understand this issue, let us consider a deterministic setting as described in Definition 2.2, where $(\mathbf{x}_P^1, \mathbf{x}_P^2, \dots, \mathbf{x}_P^R) = (1, 2, \dots, R)$ and $(\mathbf{x}_Q^1, \mathbf{x}_Q^2, \dots, \mathbf{x}_Q^S) = (R+1, R+2, \dots, R+S)$. Notably, $\{\mathbf{x}_P^i\}_{i=1}^R \cap \{\mathbf{x}_Q^j\}_{j=1}^S = \emptyset$. In this setup, we observe that $\hat{\mathcal{L}}_f^{(R,S)}(\phi) \rightarrow -\infty$ as $f^*(f'(\phi(\mathbf{x}_P^i))) \rightarrow -\infty$ and $-f'(\phi(\mathbf{x}_Q^j)) \rightarrow -\infty$ for all $1 \leq i \leq R$ and $1 \leq j \leq S$. In practice, this issue is addressed by implementing early stopping based on monitoring validation losses during optimization. The present theoretical framework accommodates this practical strategy, which facilitates an analysis of both the optimization process and its implications for downstream tasks such as DRE.

To reconcile the practical and theoretical behaviors of f -divergence loss functions within our framework, we introduce a conceptual reformulation of the loss function.

Definition 4.1 (μ -Representation f -Divergence Loss). Let μ be a probability measure with $P \ll \mu$ and $Q \ll \mu$, and let $\hat{\mathbf{X}}_{\mu[N]} = \{\mathbf{X}_{\mu}^1, \dots, \mathbf{X}_{\mu}^N\}$ denote N i.i.d. random variables from μ . For a twice differentiable convex function f , let

$$\tilde{l}_f(u; \mathbf{x}) = -f'(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + f^*(f'(u)) \cdot \frac{dP}{d\mu}(\mathbf{x}), \quad (7)$$

where f^* denotes the Legendre transform of f : $f^*(\psi) = \sup_{u \in \mathbb{R}} \{\psi \cdot u - f(u)\}$. Additionally, let $N = \min\{R, S\}$.

The μ -representation of the f -divergence loss $\mathcal{L}_f^{(R,S)}(\cdot)$ in Equation (3) at the points $\hat{\mathbf{X}}_{\mu[N]}$ is defined as

$$\tilde{\mathcal{L}}_f^{(N)}(\phi) = \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi; \mathbf{X}_{\mu}^i), \quad (8)$$

where ϕ is a measurable function over Ω such that $\phi : \Omega \rightarrow \mathbb{R}_{>0}$.

This representation introduces an error of $1/\sqrt{N}$ between the practical f -divergence loss function $\mathcal{L}_f^{(R,S)}(\phi)$ and the μ -representation f -divergence loss $\tilde{\mathcal{L}}_f^{(N)}(\phi)$. However, this error is negligible when $d \geq 3$, which will be discussed in Section 4.3.

The optimization properties of this conceptual loss function are encapsulated in Proposition 4.2.

Proposition 4.2. Assume that f satisfies Assumption 3.3. Let $\phi_* = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$. Then, $\phi_*(\mathbf{X}_{\mu}^i) = \frac{dQ}{dP}(\mathbf{X}_{\mu}^i)$, for $i = 1, 2, \dots, N$.

This reformulation ensures that the conceptual loss function does not diverge. Furthermore, all optimal points in the conceptual loss function are aligned with the ideal density ratios.

4.2 DERIVATION OF UPPER AND LOWER BOUNDS FOR OPTIMAL FUNCTIONS OF THE μ -REPRESENTATION f -DIVERGENCE LOSS FUNCTIONS

In this section, we derive upper and lower bounds for the L_p error in DRE for the optimal function of $\mathcal{L}_f^{(N)}(\cdot)$ defined in the previous section, based on the expected distance between the nearest neighbors of each \mathbf{X}_{μ}^i , $1 \leq N$.

Hereafter, $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ denotes the nearest neighbor of \mathbf{x} in $\hat{\mathbf{X}}_{\mu[N]} = \{\mathbf{X}_{\mu}^1, \dots, \mathbf{X}_{\mu}^N\}$. Specifically, define $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ as \mathbf{X}_{μ}^i in $\hat{\mathbf{X}}_{\mu[N]}$ such that $\|\mathbf{X}_{\mu}^l - \mathbf{x}\|_{\infty} > \|\mathbf{X}_{\mu}^i - \mathbf{x}\|_{\infty}$, for all $l < i$, and $\|\mathbf{X}_{\mu}^u - \mathbf{x}\|_{\infty} \geq \|\mathbf{X}_{\mu}^i - \mathbf{x}\|_{\infty}$ for all $u > i$. As in the previous section, let $\phi_* = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$.

As presented in Proposition 4.2, the optimal points of the μ -representation f -divergence loss functions $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ coincide with the ideal density ratios. This fact provides the following equation, serving as the key bridge between the density ratio and its estimation.

$$\phi_*(\mathbf{X}_{\mu}^i) = \frac{dQ}{dP}(\mathbf{X}_{\mu}^i) = \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_{\mu}^i)). \quad (9)$$

Based on this equation, we can obtain

$$\left| \phi_*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p = \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p. \quad (10)$$

Using the triangle inequality in the L_p norm for the density ratios at \mathbf{x} and its nearest neighbor, we obtain

$$\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right\}^{1/p} - \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p \right\}^{1/p}$$

$$\begin{aligned}
&\leq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi_*(\mathbf{x}) \right|^p \right\}^{1/p} \\
&\leq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right\}^{1/p} + \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p \right\}^{1/p}. \quad (11)
\end{aligned}$$

Assuming the L -bi-Lipschitz continuity of the energy function of the density ratio, $T^*(\mathbf{x}) = -\log q(\mathbf{x})/p(\mathbf{x})$, we yield

$$\begin{aligned}
&\frac{1}{L^p} \left(\frac{dQ}{dP}(\mathbf{x}) \right)^p \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p + O_p \left(\frac{1}{N^{1/(2d)}} \right) \\
&\leq \left| \frac{dQ}{dP}(\mathbf{x}) - \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \\
&\leq L^p \cdot \left(\frac{dQ}{dP}(\mathbf{x}) \right)^p \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p + O_p \left(\frac{1}{N^{1/(2d)}} \right). \quad (12)
\end{aligned}$$

Additionally, from the K -Lipschitz continuity of $\phi_*(\cdot)$ and Equation (9),

$$\left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p = \left| \phi_*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi_*(\mathbf{x}) \right|^p \leq K^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p. \quad (13)$$

Equations (12) and (13) provide the upper and lower bounds of the difference in density ratios between \mathbf{x} and its nearest neighbor $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ using their distance.

To evaluate the expectation of the distance between \mathbf{x} and its nearest neighbor $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$, we present the following theorems: Theorem 4.3 provides an upper bound for the expectation on the right side of Equation (12); Theorem 4.4 establishes a lower bound for the expectation on the left-hand side.

Theorem 4.3. Assume that Ω is a compact set. Then, for $1 \leq p \leq d/2$,

$$\begin{aligned}
&\overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\
&\leq \text{diag}(\Omega) \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)}. \quad (14)
\end{aligned}$$

Theorem 4.4. Let P and Q be probability measures on a compact set Ω in \mathbb{R}^d with $d \geq 1$. Assume that $P \ll \lambda$ and $Q \ll \lambda$, where λ denotes the Lebesgue measure on \mathbb{R}^d . Let p be a positive constant such that $p \geq 1$. Assume $E[(dQ/dP)^p] < \infty$. Then,

$$\begin{aligned}
&\lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right] \right\}^{1/p} \\
&\geq e^{-1} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p}, \quad (15)
\end{aligned}$$

where $E_{\hat{\mathbf{X}}_{P[N]}}[\cdot]$ denotes the expectation over each variable in $\hat{\mathbf{X}}_{P[N]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^N\}$.

Notably, using Jensen's inequality on the right-hand side of Equation (15) in Theorem 4.4, the KL-divergence between P and Q appears in the lower bound such that

$$\begin{aligned}
e^{-1} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} &= e^{-1} \cdot \left\{ E_Q \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{p-1} \right] \right\}^{1/p} \\
&= e^{-1} \cdot \left\{ E_Q \left[e^{(p-1) \cdot \log \frac{dQ}{dP}(\mathbf{x}) - 1} \right] \right\}^{1/p} \\
&\geq e^{-1} \cdot \left\{ e^{E_Q[(p-1) \cdot \log \frac{dQ}{dP}(\mathbf{x})]} \right\}^{1/p} = e^{\frac{p-1}{p} \cdot KL(Q||P) - 1}. \quad (16)
\end{aligned}$$

We derive the upper and lower bounds for the L_p error in DRE for the optimally estimated functions $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$, as stated in Theorem 4.5.

Theorem 4.5. Assume Ω is a compact set in \mathbb{R}^d with $d \geq 3$, and that f satisfies Assumption 3.3. Let P and Q be probability measures on Ω , assuming that $P \ll \lambda$ and $Q \ll \lambda$, where λ denotes the Lebesgue measure on \mathbb{R}^d . Let $T^*(\mathbf{x})$ be the energy function of $dQ/dP(\mathbf{x})$ defined as $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$. Let $\tilde{\mathcal{F}}_{K-Lip}^{(N)}$ denote the set of all K -Lipschitz continuous functions on Ω that minimize $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$. Specifically, define

$$\tilde{\mathcal{F}}^{(N)} = \left\{ \phi_* : \Omega \rightarrow \mathbb{R}_{>0} \mid \tilde{\mathcal{L}}_f^{(N)}(\phi_*) = \min_{\phi} \tilde{\mathcal{L}}_f^{(N)}(\phi) \right\}, \quad (17)$$

and

$$\mathcal{F}_{K-Lip} = \left\{ \phi : \Omega \rightarrow \mathbb{R}_{>0} \mid |\phi(\mathbf{y}) - \phi(\mathbf{x})| \leq K \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty} \text{ for all } \mathbf{y}, \mathbf{x} \in \Omega \right\}. \quad (18)$$

Subsequently, let $\tilde{\mathcal{F}}_{K-Lip}^{(N)} = \tilde{\mathcal{F}}^{(N)} \cap \mathcal{F}_{K-Lip}$.

(Upper Bound) Assume that $T^*(\mathbf{x})$ satisfies Assumption 3.1. Thereafter, Equation (19) holds for $1 \leq p \leq d/2$, such that for any $\phi \in \tilde{\mathcal{F}}_{K-Lip}^{(N)}$, such that

$$\begin{aligned} & \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\ & \leq L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} + K \cdot \text{diag}(\Omega). \end{aligned} \quad (19)$$

(Lower Bound) Assume that $T^*(\mathbf{x})$ satisfies Assumption 3.2. Then, Equations (20) and (21) hold for any $\phi \in \tilde{\mathcal{F}}_{K-Lip}^{(N)}$, such that

$$\begin{aligned} & \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\tilde{\mathbf{x}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\ & \geq \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - K \cdot \text{diag}(\Omega) \end{aligned} \quad (20)$$

$$\geq \frac{1}{L} \cdot e^{\frac{p-1}{p} \cdot KL(Q||P)-1} - K \cdot \text{diag}(\Omega) \quad (21)$$

Remark 4.6. Equation (12) when $L = 1$ suggests that $|dQ/dP(\mathbf{y}) - dQ/dP(\mathbf{x})| = \|\mathbf{y} - \mathbf{x}\|_{\infty}$, for all \mathbf{x} and \mathbf{y} in Ω . This typical case is when $dQ/dP(x_1, x_2, \dots, x_d) \equiv dQ/dP(x_1, x_2, \dots, x_{d'})$ with $d' < d$. Therefore, this case typically occurs when $dQ/dP(\mathbf{x})$ is a replication of its lower-dimensional distribution. In this case, the upper and lower bounds for the L_p error in DRE are considered to follow the lower dimension.

4.3 DERIVATION OF UPPER AND LOWER BOUNDS FOR OPTIMAL FUNCTIONS OF THE f -DIVERGENCE LOSS FUNCTIONS

To establish upper and lower bounds for practical DRE using f -divergence loss function optimization, we initially statistically evaluate the discrepancy between the outputs from the practically optimized functions $\mathcal{L}_f^{(R,S)}(\cdot)$, employing early stopping based on validation losses, and the theoretically optimized functions $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$. Next, we demonstrate that this discrepancy is negligible when $d \geq 3$. Finally, the upper and lower bounds for DRE are expressed in terms of L_p error for the f -divergence loss function optimization using early stopping, which constitutes the final theoretical result of this study.

First, according to the central limit theorem, an error of order $1/\sqrt{N}$ in probability occurs when measuring validation losses.

$$\mathcal{L}_f^{(R,S)}(\phi) - E_{\mu} [\mathcal{L}_f^{(R,S)}(\phi)] = O_p \left(\frac{1}{\sqrt{N}} \right). \quad (22)$$

Equation (22) implies that there is an error margin of $O_p\left(\frac{1}{\sqrt{N}}\right)$ when monitoring the validation losses for early stopping in the optimization of $\mathcal{L}_f^{(R,S)}(\phi)$.

Subsequently, we utilize the following theorem to demonstrate that the optimization of Equation (22), employing early stopping based on validation losses, is governed by the optimization of the μ -representation f -divergence loss functions $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$.

Theorem 4.7. *Assume the same assumptions as in Proposition 4.2. Let $\phi_* = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$. Therefore, for any measurable function $\phi: \Omega \rightarrow \mathbb{R}_{>0}$,*

$$\begin{aligned} \phi(\mathbf{X}_\mu^i) - \phi_*(\mathbf{X}_\mu^i) &= O_p\left(\frac{1}{\sqrt{N}}\right), \quad \text{for } 1 \leq i \leq N, \\ \iff \mathcal{L}_f^{(R,S)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_\mu \left[\mathcal{L}_f^{(R,S)}(\phi) \right] &= O_p\left(\frac{1}{\sqrt{N}}\right), \end{aligned} \quad (23)$$

where $\{\mathbf{X}_\mu^1, \mathbf{X}_\mu^2, \dots, \mathbf{X}_\mu^N\}$ is defined in Definition 4.1.

In Equation (23), the first term on the right-hand side denotes the empirical risk of $\mathcal{L}_f^{(R,S)}(\phi)$ using validation data, whereas the second term represents the minimum value of its true error. This equation illustrates that when $\mathcal{L}_f^{(R,S)}(\phi)$ is within the actual early stopping margin, specifically $O_p\left(\frac{1}{\sqrt{N}}\right)$, the function ϕ deviates from the optimal function of $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ by no more than $O_p\left(\frac{1}{\sqrt{N}}\right)$.

Based on Equation (23), we define the optimal function of $\mathcal{L}_f^{(R,S)}(\phi)$ for use with early stopping while monitoring validation losses as follows:

$$\begin{aligned} \phi_{\text{val}} \text{ is optimal in the optimization of } \mathcal{L}_f^{(R,S)}(\phi) \text{ using early stopping} \\ \triangleq \phi_* + O_p\left(\frac{1}{\sqrt{N}}\right), \quad \text{where } \phi_* = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_\mu \left[\tilde{\mathcal{L}}_f^{(N)}(\phi) \right]. \end{aligned} \quad (24)$$

The difference $O_p\left(\frac{1}{\sqrt{N}}\right)$, appearing in Equation (24), is negligible for DRE when $d \geq 3$. Indeed, using the triangle inequality in the L_p norm for $\phi_* = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$ and Equation (20), we observe

$$\begin{aligned} \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi_{\text{val}}(\mathbf{x}) \right|^p \right\}^{1/p} &\geq \underbrace{\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi^*(\mathbf{x}) \right|^p \right\}^{1/p}}_{=O\left(\frac{1}{N^{1/d}}\right)} - \underbrace{\left\{ E_P \left| \phi_{\text{val}}(\mathbf{x}) - \phi^*(\mathbf{x}) \right|^p \right\}^{1/p}}_{=O\left(\frac{1}{\sqrt{N}}\right) \ll \frac{1}{N^{1/d}}}. \end{aligned} \quad (25)$$

Therefore, we finally obtain the following Theorem 4.8.

Theorem 4.8. *Assume the same assumptions and notations as in Theorem 4.5. Additionally, define*

$$\mathcal{F}_{K\text{-Lip}}^{(N)} = \left\{ \phi \in \mathcal{F}_{K\text{-Lip}} \mid \exists \phi_* \in \tilde{\mathcal{F}}_{K\text{-Lip}}^{(N)} \text{ such that } \phi = \phi_* + O_p\left(\frac{1}{\sqrt{N}}\right) \right\}. \quad (26)$$

That is, $\mathcal{F}_{K\text{-Lip}}^{(N)}$ denotes the set of all functions that differ by at most $O_p\left(\frac{1}{\sqrt{N}}\right)$ from some functions that minimize $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$. Therefore, the same results as in Theorem 4.5 hold for all $\phi \in \mathcal{F}_{K\text{-Lip}}^{(N)}$.

5 CONCLUSIONS

We have established upper and lower bounds on the L_p errors in DRE through the optimization of f -divergence loss functions. These bounds are applicable to any member of a group of Lipschitz continuous estimators, regardless of the specific f -divergence loss function used. These bounds provide new insights into how the dimensionality of data and the KL divergence between distributions affect

the accuracy of DRE. Furthermore, the numerical experiments corroborate these theoretical findings, demonstrating that the relationship between L_p errors, KL divergence, and data dimensionality aligns with the theoretical implications derived from the bounds. This research faces limitations, particularly in high-dimensional settings where the curse of dimensionality and large sample requirements pose challenges. Future studies could refine the theoretical framework to explore loss functions that improve DRE in complex, high-dimensional tasks.

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A ORGANIZATION OF THE SUPPLEMENTARY DOCUMENT

The organization of this supplementary document is as follows: Section B provides a list of notations used in this study. Section C presents the proofs referenced in Sections 3 and 4. Section D provides details of the experiments conducted. Section E explores further discussions related to this study.

Additionally, the code used in the numerical experiments is included as supplementary material.

B NOTATIONS

We list all notations used in the Appendix used in this study in Table 1.

C PROOFS

In this section, we present the theorems and proofs referenced in this study. We begin by summarizing all definitions and assumptions stated in previous sections. Then, we provide the theorems and proofs used throughout this study.

C.1 DEFINITIONS AND ASSUMPTIONS IN SECTIONS 2, 3, AND 4

C.1.1 DEFINITIONS

Definition C.1 (f -Divergence (Definition 2.1 restated)). The f -divergence D_f between two probability measures P and Q , which is induced by a convex function f satisfying $f(1) = 0$, is defined as $D_f(Q||P) = E_P[f(q(\mathbf{x})/p(\mathbf{x}))]$.

Definition C.2 (f -Divergence Loss (Definition 2.2 restated)). Let $\hat{\mathbf{X}}_{P[R]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^R\}$, $\mathbf{X}_P^i \stackrel{\text{iid}}{\sim} P$ denote R i.i.d. random variables from P , and let $\hat{\mathbf{X}}_{Q[S]} = \{\mathbf{X}_Q^1, \mathbf{X}_Q^2, \dots, \mathbf{X}_Q^S\}$, $\mathbf{X}_Q^i \stackrel{\text{iid}}{\sim} Q$ denote S i.i.d. random variables from Q . Then, for a twice differentiable convex function f , f -divergence loss $\mathcal{L}_f^{(R,S)}(\cdot)$ is defined as follows:

$$\mathcal{L}_f^{(R,S)}(\phi) = \frac{1}{S} \cdot \sum_{i=1}^S -f'(\phi(\mathbf{X}_Q^i)) + \frac{1}{R} \sum_{i=1}^R f^*(f'(\phi(\mathbf{X}_P^i))), \quad (27)$$

where ϕ is a measurable function over Ω such that $\phi : \Omega \rightarrow \mathbb{R}_{>0}$.

Definition C.3 (μ -Representation f -Divergence Loss (Definition 4.1 restated)). Let f be a twice differentiable convex function f . Then, μ -representation function of f for $u > 0$ at a point $\mathbf{x} \in \Omega$, which is written for $\tilde{l}_f(u)$ in an abbreviated form, is defined as

$$\tilde{l}_f(u; \mathbf{x}) = -f'(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + f^*(f'(u)) \cdot \frac{dP}{d\mu}(\mathbf{x}), \quad (28)$$

where f^* denotes the Legendre transform of f : $f^*(\psi) = \sup_{u \in \mathbb{R}} \{\psi \cdot u - f(u)\}$. Let $N = \min\{R, S\}$, and let $\hat{\mathbf{X}}_{\mu[N]} = \{\mathbf{X}_{\mu}^1, \dots, \mathbf{X}_{\mu}^N\}$ denote N i.i.d. random variables from μ . Then, μ -representation of the f -divergence loss $\mathcal{L}_f^{(R,S)}(\cdot)$ in Equation (27) at the points $\hat{\mathbf{X}}_{\mu[N]}$ is defined as

$$\tilde{\mathcal{L}}_f^{(N)}(\phi) = \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(u; \mathbf{X}_{\mu}^i) \quad (29)$$

where ϕ is a measurable function over Ω such that $\phi : \Omega \rightarrow \mathbb{R}_{>0}$.

C.1.2 ASSUMPTIONS

Assumption C.4 (Assumption for the Upper Bound (Assumption 3.1 restated)). The following assumption is imposed on the probability distributions P and Q .

- U1. $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$ is L -Lipschitz continuous with $L > 0$ on Ω . i.e., $\exists L > 0$ s.t. $|T^*(\mathbf{y}) - T^*(\mathbf{x})| \leq L \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty}$ for any $\mathbf{y}, \mathbf{x} \in \Omega$.

Table 1: Notations and definitions used in the proofs

Notations	Definitions, Meanings
(Capital, small, and bold letters)	Random variables are denoted by capital letters; for example, A . Small letters are used for values of the random variables corresponding to the capital letters. Bold letters \mathbf{A} and \mathbf{a} represent sets of random variables and their values.
\mathbb{R}, \mathbb{R}^d	The set of all real numbers and the d -dimensional vector space over the real numbers, respectively.
$\mathbb{R}_{>0}$	The set of all positive real numbers: $\mathbb{R}_{>0} = \{x \in \mathbb{R} \mid x > 0\}$.
Ω	A subset of \mathbb{R}^d : $\Omega \subset \mathbb{R}^d$.
$f(x) = O(g(x))$, as $x \rightarrow a$	Asymptotic boundedness with rate $g(x)$ as $x \rightarrow a$: $f(x) = O(g(x)) \Leftrightarrow \limsup_{x \rightarrow a} f(x)/g(x) \leq C$, where $C > 0$.
$f(x) = o(g(x))$, as $x \rightarrow a$	Asymptotic domination with rate $g(x)$ as $x \rightarrow a$: $f(x) = o(g(x)) \Leftrightarrow \lim_{x \rightarrow a} f(x)/g(x) = 0$.
$\mathbf{X} = O_p(a_N)$, as $N \rightarrow \infty$	Stochastic boundedness with rate a_N in μ : $\mathbf{X} = O_p(a_N) \Leftrightarrow$ for all $\varepsilon > 0$, there exist $\delta(\varepsilon) > 0$ and $N(\varepsilon) > 0$ such that $\mu(\mathbf{X} /a_N \geq \delta(\varepsilon)) < \varepsilon$ for all $N \geq N(\varepsilon)$.
$\mathbf{X} = o_p(a_N)$, as $N \rightarrow \infty$	Convergence in probability with rate a_N in μ : $\mathbf{X} = o_p(a_N) \Leftrightarrow$ for all $\varepsilon > 0$, for all $\delta > 0$, there exists $N(\varepsilon, \delta) > 0$ such that $\mu(\mathbf{X} /a_N \geq \delta) < \varepsilon$ for all $N \geq N(\varepsilon)$.
$P \ll Q$	P is absolutely continuous with respect to Q .
P, Q	A pair of probability measures with $P \ll Q$ and $Q \ll P$.
μ	A probability measure with $P \ll \mu$ and $Q \ll \mu$.
$\frac{dP}{dQ}$	The Radon–Nikodým derivative of P with respect to Q .
$\hat{\mathbf{X}}_{P[R]}$	R i.i.d. random variables from P : $\hat{\mathbf{X}}_{P[R]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^R\}$, where $\mathbf{X}_P^i \stackrel{\text{iid}}{\sim} P$.
$\hat{\mathbf{X}}_{Q[S]}$	S i.i.d. random variables from Q : $\hat{\mathbf{X}}_{Q[S]} = \{\mathbf{X}_Q^1, \mathbf{X}_Q^2, \dots, \mathbf{X}_Q^S\}$, where $\mathbf{X}_Q^i \stackrel{\text{iid}}{\sim} Q$.
N	$N = \min\{R, S\}$.
$\hat{\mathbf{X}}_{\mu[N]}$	N i.i.d. random variables from μ : $\hat{\mathbf{X}}_{\mu[N]} = \{\mathbf{X}_\mu^1, \mathbf{X}_\mu^2, \dots, \mathbf{X}_\mu^N\}$, where $\mathbf{X}_\mu^i \stackrel{\text{iid}}{\sim} \mu$.
$\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$	The nearest neighbor variable of \mathbf{x} in $\hat{\mathbf{X}}_{\mu[N]}$: $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ is the \mathbf{X}_μ^i such that $\ \mathbf{X}_\mu^i - \mathbf{x}\ < \ \mathbf{X}_\mu^j - \mathbf{x}\ $ for all $j \neq i$.
$D_f(Q P)$	f -divergence: $D_f(Q P) = E_P[f(q(\mathbf{x})/p(\mathbf{x}))]$. See Definition C.1.
$\mathcal{L}_f^{(R,S)}(\cdot)$	f -divergence loss function. See Definition C.2.
$\tilde{l}_f(u; \mathbf{x})$	μ -representation of the f -divergence loss function at \mathbf{x} : $\tilde{l}_f(u; \mathbf{x}) = -f'(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + f^*(f'(u)) \cdot \frac{dP}{d\mu}(\mathbf{x})$.
$\tilde{\mathcal{L}}_f^{(N)}(\cdot)$	μ -representation of the f -divergence loss function $\mathcal{L}_f^{(R,S)}(\cdot)$. See Definition 4.1.
$\bar{\mathcal{L}}_f(\phi)$	The expectation of the μ -representation of the f -divergence loss on μ . See Lemma C.11.
$\ \cdot\ $	The Euclidean norm.
$\ \cdot\ _\infty$	The maximum norm in \mathbb{R}^d : $\ \mathbf{y} - \mathbf{x}\ _\infty = \max_{1 \leq i \leq d} y_i - x_i $.
$\Delta(\mathbf{a}, r)$	The d -dimensional interval centered at \mathbf{a} with each side of length r : $\Delta(\mathbf{a}, r) = \{\mathbf{x} \in \mathbb{R}^d \mid \ \mathbf{x} - \mathbf{a}\ _\infty < r/2\}$.
$\text{diag}(\mathcal{B})$	The diameter of \mathcal{B} : $\text{diag}(\mathcal{B}) = \inf_{r \in \mathbb{R}} \{\mathcal{B} \subseteq \Delta(\mathbf{a}, r) \mid \exists \mathbf{a} \in \mathcal{B}\}$.

Assumption C.5 (Assumptions for the Lower Bound (Assumption 3.2 restated)). The following assumptions are imposed on the probability distributions P and Q .

L1. $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$ is L -bi-Lipschitz continuous on Ω . i.e., $\exists L > 1$ s.t. $(1/L) \leq |T^*(\mathbf{y}) - T^*(\mathbf{x})| \leq L \cdot \|\mathbf{y} - \mathbf{x}\|_\infty$ for any $\mathbf{y}, \mathbf{x} \in \Omega$.

L2. $E_P [(dQ/dP)^p] < \infty$ where $p \leq d$.

Assumption C.6 (Assumptions for the Convex Function f (Assumption 3.3 restated)). The following assumptions are assumed for the convex function f .

F1. f is three-time differentiable.

F2. $f''(u) > 0$. for all $u > 0$.

F3. $E_P [f''(dQ/dP)] < \infty$.

Assumption C.7 (Assumption for the Support (Assumption 3.4 restated)). The following assumption is assumed for Ω .

O1. $\text{diag}(\Omega) < \infty$.

C.2 THEOREMS AND PROOFS IN SECTIONS 2, 3, AND 4

Lemma C.8. Let f be a twice differentiable function. Consider $\tilde{l}_f(u; \mathbf{x})$ defined as in Equation (28). Then, the first derivative of $\tilde{l}_f(u; \mathbf{x})$ with respect to u is given by:

$$\frac{d}{du} \tilde{l}_f(u; \mathbf{x}) = \left\{ u - \frac{dQ}{dP}(\mathbf{x}) \right\} \cdot f''(u) \cdot \frac{dP}{d\mu}(\mathbf{x}). \quad (30)$$

Additionally, if $\tilde{l}_f(u; \mathbf{x})$ is thrice differentiable, the second derivative with respect to u is given by:

$$\frac{d^2}{du^2} \tilde{l}_f(u; \mathbf{x}) = \left\{ \left(u - \frac{dQ}{dP}(\mathbf{x}) \right) \cdot f'''(u) + f''(u) \right\} \cdot \frac{dP}{d\mu}(\mathbf{x}). \quad (31)$$

Proof of Lemma C.8. First, note that

$$\begin{aligned} \tilde{l}_f(u; \mathbf{x}) &= -f'(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + f^*(f'(u)) \cdot \frac{dP}{d\mu}(\mathbf{x}) \\ &= -f'(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + \{f'(u) \cdot u - f(u)\} \cdot \frac{dP}{d\mu}(\mathbf{x}). \end{aligned} \quad (32)$$

Differentiating Equation (32) with respect to u , we obtain the first and second derivatives of $\tilde{l}_f(u; \mathbf{x})$ as follows:

$$\begin{aligned} \frac{d}{du} \tilde{l}_f(u; \mathbf{x}) &= -f''(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + u \cdot f''(u) \cdot \frac{dP}{d\mu}(\mathbf{x}) \\ &= \left\{ u - \frac{dQ}{dP}(\mathbf{x}) \right\} \cdot f''(u) \cdot \frac{dP}{d\mu}(\mathbf{x}), \end{aligned} \quad (33)$$

and

$$\begin{aligned} \frac{d^2}{du^2} \tilde{l}_f(u; \mathbf{x}) &= -f'''(u) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + f''(u) \cdot \frac{dP}{d\mu}(\mathbf{x}) + u \cdot f'''(u) \cdot \frac{dP}{d\mu}(\mathbf{x}) \\ &= \left\{ \left(u - \frac{dQ}{dP}(\mathbf{x}) \right) \cdot f'''(u) + f''(u) \right\} \cdot \frac{dP}{d\mu}(\mathbf{x}). \end{aligned} \quad (34)$$

This completes the proof. \square

Theorem C.9. Assume that f satisfies Assumption C.6. Then, $\tilde{l}_f(u; \mathbf{x})$, as defined in Equation (28), is minimized only when $u^*(\mathbf{x}) = \frac{dQ}{dP}(\mathbf{x})$. In addition, for $u > 0$, the following holds:

$$\begin{aligned} \tilde{l}_f(u; \mathbf{x}) - \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) \\ = \frac{1}{2} \cdot f''\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}) \cdot \left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2 + o\left(\left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2\right), \end{aligned} \quad (35)$$

where $f(a) = o(a)$ (as $a \rightarrow 0$) denotes asymptotic domination such that $\lim_{a \rightarrow 0} \frac{f(a)}{a} \rightarrow 0$.

Proof of Theorem C.9. Let $\text{sign}(x)$ denote the sign of the value x : specifically, $\text{sign}(x) = 1$ if $x > 0$, $\text{sign}(x) = -1$ if $x < 0$, and $\text{sign}(x) = 0$ if $x = 0$.

From Equation (30) in Lemma C.8, we have

$$\begin{aligned} \text{sign}\left(\frac{d}{du} \tilde{l}_f(u; \mathbf{x})\right) &= \text{sign}\left(\left\{u - \frac{dQ}{dP}(\mathbf{x})\right\} \cdot f''(u) \cdot \frac{dP}{d\mu}(\mathbf{x})\right) \\ &= \text{sign}\left(\left\{u - \frac{dQ}{dP}(\mathbf{x})\right\}\right) \cdot \text{sign}(f''(u)) \cdot \text{sign}\left(\frac{dP}{d\mu}(\mathbf{x})\right) \\ &= \text{sign}\left(u - \frac{dQ}{dP}(\mathbf{x})\right). \end{aligned} \quad (36)$$

Thus, $\tilde{l}_f(u; \mathbf{x})$ is minimized only when $u^* = \frac{dQ}{dP}(\mathbf{x})$.

Next, from Equation (30),

$$\frac{d}{du} \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) = 0, \quad (37)$$

and from Equation (31),

$$\frac{d^2}{du^2} \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) = f''\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}). \quad (38)$$

Thus, using the second-order Taylor expansion of $\tilde{l}_f(u; \mathbf{x})$ around $u = \frac{dQ}{dP}(\mathbf{x})$, we have

$$\begin{aligned} \tilde{l}_f(u; \mathbf{x}) - \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) \\ = \frac{1}{2} \cdot f''\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}) \cdot \left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2 + o\left(\left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2\right). \end{aligned} \quad (39)$$

This completes the proof. \square

Proposition C.10 (Proposition 4.2 restated). Assume that f satisfies Assumption C.6. Let $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ denote the μ -representation f -divergence loss as defined in Definition C.3. Then, the minimum value of $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ over all measurable functions $\phi: \Omega \rightarrow \mathbb{R}_{>0}$ is achieved if and only if ϕ satisfies

$$\phi(\mathbf{X}_\mu^i) = \frac{dQ}{dP}(\mathbf{X}_\mu^i), \quad \text{for } i = 1, 2, \dots, N. \quad (40)$$

proof of Proposition C.10. From Theorem C.9, we observe that, for $i = 1, 2, \dots, N$,

$$\min_{u>0} \tilde{l}_f(u; \mathbf{X}_\mu^i) = \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right), \quad (41)$$

where the minimum value is archived only at $u = \frac{dQ}{dP}(\mathbf{X}_\mu^i)$.

Thus,

$$\begin{aligned}
\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) &= \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\
&= \min_{\substack{\phi(\mathbf{X}_\mu^i) > 0, \\ i=1,2,\dots,N}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\
&= \min_{\substack{u_i > 0, \\ i=1,2,\dots,N}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(u_i; \mathbf{X}_\mu^i) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right). \tag{42}
\end{aligned}$$

Suppose that $\tilde{\phi}(\mathbf{x})$ is a function on Ω that satisfies Equation (40), we have, from Equation (42),

$$\begin{aligned}
&\tilde{\mathcal{L}}_f^{(N)}(\tilde{\phi}) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\tilde{\phi}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) \\
&= 0. \tag{43}
\end{aligned}$$

Here, we show that the minimum value of $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ over all measurable functions $\phi: \Omega \rightarrow \mathbb{R}_{>0}$ is archived if $\phi: \Omega \rightarrow \mathbb{R}_{>0}$ satisfies Equation (40).

Next, we show that the minimum value of $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ over all measurable functions $\phi: \Omega \rightarrow \mathbb{R}_{>0}$ is archived only if $\phi: \Omega \rightarrow \mathbb{R}_{>0}$ satisfies Equation (40).

We have, for any function $\phi: \Omega \rightarrow (0, \infty)$,

$$\begin{aligned}
&\tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f\left(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \frac{1}{N} \cdot \sum_{i=1}^N \min_{\substack{u_i > 0, \\ i=1,2,\dots,N}} \tilde{l}_f(u_i; \mathbf{X}_\mu^i) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \left\{ \tilde{l}_f\left(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \min_{u > 0} \tilde{l}_f(u; \mathbf{X}_\mu^i) \right\}. \tag{44}
\end{aligned}$$

Suppose that $\phi(\mathbf{X}_\mu^i) \neq \frac{dQ}{dP}(\mathbf{X}_\mu^i)$. Then, from Equation (41), we have

$$\tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) > \min_{u > 0} \tilde{l}_f(u; \mathbf{X}_\mu^i). \tag{45}$$

From Equations (44) and (45), we observe that

$$\begin{aligned}
&\tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \left\{ \tilde{l}_f\left(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \min_{u > 0} \tilde{l}_f(u; \mathbf{X}_\mu^i) \right\} \\
&\geq \frac{1}{N} \cdot \left\{ \tilde{l}_f\left(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) - \min_{u > 0} \tilde{l}_f(u; \mathbf{X}_\mu^i) \right\} \\
&> 0 \tag{46}
\end{aligned}$$

Thus, we see that the minimum value of $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ over all measurable functions $\phi : \Omega \rightarrow \mathbb{R}_{>0}$ is archived only if $\phi : \Omega \rightarrow \mathbb{R}_{>0}$ satisfies Equation (40).

This completes the proof. \square

Lemma C.11. Assume that f satisfies Assumption C.6. Let $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ denote the μ -representation f -divergence loss as defined in Definition C.3. Define

$$\begin{aligned}\bar{\mathcal{L}}_f(\phi) &= E_\mu \left[\tilde{\mathcal{L}}_f^{(N)}(\phi) \right] \\ &= \frac{1}{N} \cdot \sum_{i=1}^N E_\mu \left[-f'(\phi(\mathbf{x}_i)) \cdot \frac{dQ}{d\mu}(\mathbf{x}_i) \right] \\ &\quad + \frac{1}{N} \cdot \sum_{i=1}^N E_\mu \left[f^*(f'(\phi(\mathbf{x}_i))) \cdot \frac{dP}{d\mu}(\mathbf{x}_i) \right].\end{aligned}\quad (47)$$

Then,

$$E_\mu \left[\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \right] = \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) = \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_\mu \left[\mathcal{L}_f^{(R,S)}(\phi) \right], \quad (48)$$

where the infimum are taken over all measurable functions $\phi : \Omega \rightarrow \mathbb{R}_{>0}$ such that $E_P[f(\phi(\mathbf{X}))] < \infty$. Additionally, the equality in Equation (48) hold when $\phi(\mathbf{x}) = \frac{dQ}{dP}(\mathbf{x})$.

proof of Lemma C.11. Let, $\tilde{l}_f^*(\mathbf{x}) = \min_{u \in \mathbb{R}_{>0}} \tilde{l}_f(u; \mathbf{x})$. From Theorem C.9, we see $\tilde{l}_f^*(\mathbf{x}) = \tilde{l}_f(dQ/dP(\mathbf{x}); \mathbf{x})$. Then, we have

$$\begin{aligned}\tilde{l}_f^*(\mathbf{x}) &= \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) \\ &= -f'\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dQ}{d\mu}(\mathbf{x}) + \left\{ f'\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dQ}{dP}(\mathbf{x}) - f\left(\frac{dQ}{dP}(\mathbf{x})\right) \right\} \cdot \frac{dP}{d\mu}(\mathbf{x}) \\ &= -f\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}).\end{aligned}\quad (49)$$

Now, we have

$$\begin{aligned}\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) &= \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\ &= \min_{\substack{\phi(\mathbf{X}_\mu^i) > 0, \\ i=1,2,\dots,N}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\ &= \min_{\substack{u_i > 0, \\ i=1,2,\dots,N}} \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(u_i; \mathbf{X}_\mu^i) \\ &= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f^*(\mathbf{X}_\mu^i).\end{aligned}\quad (50)$$

Additionally, we have

$$\begin{aligned}E_\mu \left[\tilde{\mathcal{L}}_f^{(N)}(\phi) \right] &= E_\mu \left[\frac{1}{N} \cdot \sum_{i=1}^N -f'(\phi(\mathbf{x}_i)) \cdot \frac{dQ}{d\mu}(\mathbf{x}_i) \right. \\ &\quad \left. + \frac{1}{N} \cdot \sum_{i=1}^N f^*(f'(\phi(\mathbf{x}_i))) \cdot \frac{dP}{d\mu}(\mathbf{x}_i) \right]\end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{N} \cdot \sum_{i=1}^N E_{\mu} \left[f'(\phi(\mathbf{x}_i)) \cdot \frac{dQ}{d\mu}(\mathbf{x}_i) \right] \\
&\quad + \frac{1}{N} \cdot \sum_{i=1}^N E_{\mu} \left[f^*(f'(\phi(\mathbf{x}_i))) \cdot \frac{dP}{d\mu}(\mathbf{x}_i) \right] \\
&= -\frac{1}{N} \cdot \sum_{i=1}^N E_Q[f'(\phi)] + \frac{1}{N} \cdot \sum_{i=1}^N E_P[f^*(f'(\phi))] \\
&= -E_Q[f'(\phi)] + E_P[f^*(f'(\phi))], \tag{51}
\end{aligned}$$

and

$$\begin{aligned}
E[\mathcal{L}_f^{(R,S)}(\phi)] &= E \left[\frac{1}{R} \cdot \sum_{i=1}^S -f'(\phi(\mathbf{x}_i^q)) \right. \\
&\quad \left. + \frac{1}{S} \cdot \sum_{i=1}^R f^*(f'(\phi(\mathbf{x}_i^p))) \right] \\
&= -\frac{1}{S} \cdot \sum_{i=1}^S E_Q[f'(\phi(\mathbf{x}_i))] \\
&\quad + \frac{1}{R} \cdot \sum_{i=1}^R E_P[f^*(f'(\phi(\mathbf{x}_i)))] \\
&= -\frac{1}{S} \cdot \sum_{i=1}^S E_Q[f'(\phi)] + \frac{1}{R} \cdot \sum_{i=1}^R E_P[f^*(f'(\phi))] \\
&= -E_Q[f'(\phi)] + E_P[f^*(f'(\phi))]. \tag{52}
\end{aligned}$$

Now, note that, from Equation (1) (Nguyen et al. (2007)), we see

$$\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} -E_Q[f'(\phi)] + E_P[f^*(f'(\phi))] = -D_f(Q||P), \tag{53}$$

where $D_f(Q||P)$ denotes f -divergence defined in Definition C.1 and the equality in Equation (53) holds for $\phi(\mathbf{x}) = dQ/dP(\mathbf{x})$.

From Equations (51), (52) and (53), we have

$$\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_{\mu}[\tilde{\mathcal{L}}_f^{(N)}(\phi)] = \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E[\mathcal{L}_f^{(R,S)}(\phi)] = -D_f(Q||P), \tag{54}$$

and the equality in Equation (54) holds for $\phi(\mathbf{x}) = dQ/dP(\mathbf{x})$.

Substituting Equation (49) into Equation (50), we have

$$\begin{aligned}
\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) &= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f^*(\mathbf{x}_{\mu}^i) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N -f \left(\frac{dQ}{dP}(\mathbf{x}_{\mu}^i) \right) \cdot \frac{dP}{d\mu}(\mathbf{x}_{\mu}^i). \tag{55}
\end{aligned}$$

Thus,

$$\begin{aligned}
E_{\mu} \left[\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \right] &= E_{\mu} \left[\frac{1}{N} \cdot \sum_{i=1}^N -f \left(\frac{dQ}{dP}(\mathbf{x}_i) \right) \cdot \frac{dP}{d\mu}(\mathbf{x}_i) \right] \\
&= -\frac{1}{N} \cdot \sum_{i=1}^N E_{\mu} \left[f \left(\frac{dQ}{dP}(\mathbf{x}_i) \right) \cdot \frac{dP}{d\mu}(\mathbf{x}_i) \right]
\end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{N} \cdot \sum_{i=1}^N D_f(Q||P) \\
&= -D_f(Q||P),
\end{aligned} \tag{56}$$

From Equations (54) and (56), we have

$$E_\mu \left[\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi) \right] = \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) = \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_\mu \left[\mathcal{L}_f^{(R,S)}(\phi) \right], \tag{57}$$

and the equality in each Equation (57) holds for $\phi(\mathbf{x}) = dQ/dP(\mathbf{x})$.

This completes the proof. \square

The following theorem presents the convergence rate of the expected value of the distance between two neighboring samples. Similar theorems have been presented in studies on order statistics of multidimensional continuous random variables (e.g., Biau & Devroye (2015), p. 17, Theorem 2.1).

Theorem C.12 (Theorem 4.3 restated). *Assume that Ω is a compact set, as stated in Assumption C.7. Let $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ denote the nearest neighbor of \mathbf{x} in $\hat{\mathbf{X}}_{\mu[N]}$. Specifically, let $\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ be \mathbf{X}_μ^i in $\hat{\mathbf{X}}_{\mu[N]}$ such that*

$$\|\mathbf{X}_\mu^i - \mathbf{x}\|_\infty < \|\mathbf{X}_\mu^j - \mathbf{x}\|_\infty \quad (\forall j < i), \quad \text{and} \quad \|\mathbf{X}_\mu^i - \mathbf{x}\|_\infty \leq \|\mathbf{X}_\mu^j - \mathbf{x}\|_\infty \quad (\forall j > i). \tag{58}$$

Additionally, let $\text{diag}(\Omega)$ denote the diameter of Ω . i.e, $\text{diag}(\mathcal{B}) = \inf_{r \in \mathbb{R}} \{\mathcal{B} \subseteq \Delta(\mathbf{a}, r) \mid \exists \mathbf{a} \in \mathcal{B}\}$, where $\Delta(\mathbf{a}, r)$ denotes the d -dimensional interval centered at \mathbf{a} with each side of length r : $\Delta(\mathbf{a}, r) = \{\mathbf{x} \in \mathbb{R}^d \mid \|\mathbf{x} - \mathbf{a}\|_\infty < r/2\}$.

Then, for $1 \leq \kappa \leq d$,

$$E_\mu \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^\kappa \leq \text{diag}(\Omega)^\kappa \cdot \left(\frac{1}{N+1} \right)^{\kappa/d}, \quad \text{for all } N \geq 1. \tag{59}$$

proof of Theorem C.12. Let us rewrite \mathbf{x} in Equation (59) as \mathbf{X}_μ^{N+1} . Subsequently, let $\hat{\mathbf{X}}_{\mu[N+1]} = \hat{\mathbf{X}}_{\mu[N]} \cup \{\mathbf{X}_\mu^{N+1}\}$. Let $\Delta_i = \Omega \cap \Delta(\mathbf{X}_\mu^i, \|\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i\|_\infty)$, where $\Delta(\mathbf{a}, r) = \{\mathbf{x} \in \mathbb{R}^d \mid \|\mathbf{x} - \mathbf{a}\|_\infty < r/2\}$. Note that, $\Delta_i \cap \Delta_j = \emptyset$ if $i \neq j$. Thus, $\sqcup_{i=1}^{N+1} \Delta_i \subseteq \Omega$.

Now, let λ denote the Lebesgue measure on \mathbb{R}^d . Then, we have

$$\sum_{i=1}^{N+1} \lambda(\Delta_i) = \lambda\left(\sqcup_{i=1}^{N+1} \Delta_i\right) \leq \lambda(\Omega) \leq \text{diag}(\Omega)^d, \tag{60}$$

Subsequently, since $\lambda(\Delta_i) = \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i \right\|_\infty^d$, we have

$$\sum_{i=1}^{N+1} \lambda(\Delta_i) = \sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i \right\|_\infty^d. \tag{61}$$

Thus, from Equations (60) and (61), we have

$$\sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i \right\|_\infty^d \leq \text{diag}(\Omega)^d. \tag{62}$$

Note that, it follows from Jensen's inequality that

$$\frac{1}{N+1} \sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i \right\|_\infty^\kappa \leq \left\{ \frac{1}{N+1} \sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_\mu^i) - \mathbf{X}_\mu^i \right\|_\infty^d \right\}^{\kappa/d}. \tag{63}$$

From Equations (62) and (63), we have

$$\begin{aligned}
\frac{1}{N+1} \sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_{\mu}^i) - \mathbf{X}_{\mu}^i \right\|_{\infty}^{\kappa} &\leq \left\{ \frac{1}{N+1} \sum_{i=1}^{N+1} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_{\mu}^i) - \mathbf{X}_{\mu}^i \right\|_{\infty}^d \right\}^{\kappa/d} \\
&\leq \left\{ \frac{1}{N+1} \cdot \text{diag}(\Omega)^d \right\}^{\kappa/d} \\
&= \text{diag}(\Omega)^{\kappa} \cdot \left(\frac{1}{N+1} \right)^{\kappa/d}.
\end{aligned} \tag{64}$$

Thus,

$$\frac{1}{N+1} \sum_{i=1}^{N+1} E_{\mathbf{X}_{\mu}^i} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa} \leq \text{diag}(\Omega)^{\kappa} \cdot \left(\frac{1}{N+1} \right)^{\kappa/d}, \tag{65}$$

where $E_{\mathbf{X}_{\mu}^i} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa}$ denotes the expectation of $\left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{X}_{\mu}^i) - \mathbf{X}_{\mu}^i \right\|_{\infty}^{\kappa}$ with respect to \mathbf{X}_{μ}^i .

Note that,

$$E_{\mu} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa} = E_{\mathbf{X}_{\mu}^i} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa}. \tag{66}$$

Therefore,

$$E_{\mu} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa} = \frac{1}{N+1} \sum_{i=1}^{N+1} E_{\mathbf{X}_{\mu}^i} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa}. \tag{67}$$

Finally, from Equations (65) and (67), we have

$$E_{\mu} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa} = \frac{1}{N+1} \sum_{i=1}^{N+1} E_{\mathbf{X}_{\mu}^i} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{\kappa} \leq \text{diag}(\Omega)^{\kappa} \cdot \left(\frac{1}{N+1} \right)^{\kappa/d}. \tag{68}$$

This completes the proof. \square

Corollary C.13. Assume the same assumption as in Theorem C.12. Then, for $1 \leq p \leq d$,

$$\overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\mu} \left[\left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right\}^{1/p} \leq \text{diag}(\Omega). \tag{69}$$

proof of Corollary C.13. First, from Theorem C.12 when $\kappa = p$,

$$E_{\mu} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \leq \text{diag}(\Omega)^p \cdot \left(\frac{1}{N+1} \right)^{p/d}, \quad \text{for all } N \geq 1. \tag{70}$$

Thus, for for all $N \geq 1$,

$$\begin{aligned}
\left\{ E_{\mu} \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right\}^{1/p} &\leq \left\{ \text{diag}(\Omega)^p \cdot \left(\frac{1}{N+1} \right)^{p/d} \right\}^{1/p} \\
&= \text{diag}(\Omega) \cdot \left(\frac{1}{N+1} \right)^{1/d}
\end{aligned} \tag{71}$$

Taking $\overline{\lim}_{N \rightarrow \infty}$ on both sides of the above inequality, we have

$$\begin{aligned}
&\overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\mu} \left[\left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right\}^{1/p} \\
&\leq \overline{\lim}_{N \rightarrow \infty} \left\{ N^{1/d} \cdot \text{diag}(\Omega) \cdot \left(\frac{1}{N+1} \right)^{1/d} \right\} \\
&= \text{diag}(\Omega).
\end{aligned} \tag{72}$$

This completes the proof. \square

Corollary C.14. Assume the same assumption as in Theorem C.12. Then, for $1 \leq p \leq d/2$,

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\ & \leq \text{diag}(\Omega) \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)}. \end{aligned} \quad (73)$$

proof of Corollary C.14. First from Theorem C.12 when $\kappa = 2 \cdot p$ and $\mu = P$,

$$E_P \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \leq \text{diag}(\Omega)^{2 \cdot p} \cdot \left(\frac{1}{N+1} \right)^{2 \cdot p/d}, \quad \text{for all } N \geq 1. \quad (74)$$

Thus, for for all $N \geq 1$,

$$\begin{aligned} \left\{ E_P \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right\}^{1/(2 \cdot p)} & \leq \left\{ \text{diag}(\Omega)^{2 \cdot p} \cdot \left(\frac{1}{N+1} \right)^{2 \cdot p/d} \right\}^{1/(2 \cdot p)} \\ & = \text{diag}(\Omega) \cdot \left(\frac{1}{N+1} \right)^{1/d} \end{aligned} \quad (75)$$

Now, using Hölder's inequality, we have

$$\begin{aligned} & E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \\ & \leq \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)} \cdot \left(E_P \left[\left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right)^{1/(2 \cdot p)} \\ & \leq \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)} \cdot \text{diag}(\Omega) \cdot \left(\frac{1}{N+1} \right)^{1/d} \end{aligned} \quad (76)$$

Taking $\overline{\lim}_{N \rightarrow \infty}$ on both sides of the above inequality, we have

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\ & \leq \overline{\lim}_{N \rightarrow \infty} \left\{ N^{1/d} \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)} \cdot \text{diag}(\Omega) \cdot \left(\frac{1}{N+1} \right)^{1/d} \right\} \\ & = \text{diag}(\Omega) \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right)^{1/(2 \cdot p)} \end{aligned} \quad (77)$$

This completes the proof. \square

Lemma C.15. Let μ be a probability measure on \mathbb{R}^d with $d \geq 1$. Assume that $\mu \ll \lambda$, where λ denotes the Lebesgue measure on \mathbb{R}^d . Let $\| \cdot \|_\infty$ denote the maximum norm in \mathbb{R}^d : $\| \mathbf{y} - \mathbf{x} \|_\infty = \max_{1 \leq i \leq d} |y^i - x^i|$, where $\mathbf{y} = (y^1, y^2, \dots, y^N)$ and $\mathbf{x} = (x^1, x^2, \dots, x^N)$. Additionally, let $\Delta(\mathbf{x}, r)$ denote the d -dimensional interval centered at \mathbf{x} with each side of length r : $\Delta(\mathbf{x}, r) = \{ \mathbf{x}' \in \mathbb{R}^d \mid \| \mathbf{x}' - \mathbf{x} \|_\infty \leq r/2 \}$.

Then, for any interior point \mathbf{x} in Ω ,

$$\mu(\Delta(\mathbf{x}, r)) = \frac{d\mu}{d\lambda}(\mathbf{x}) \cdot r^d + o(r^d), \quad \text{as } r \rightarrow 0, \quad (78)$$

where $f(r) = o(g(r))$, as $r \rightarrow 0$, denotes asymptotic domination such that $\lim_{r \rightarrow 0} f(r)/g(r) = 0$.

proof of Lemma C.15. Note that, if \mathbf{x} is an interior point in Ω , it holds that

$$\lim_{r \rightarrow \infty} \frac{\mu(\Delta(\mathbf{x}, r))}{\lambda(\Delta(\mathbf{x}, r))} = \frac{d\mu}{d\lambda}(\mathbf{x}). \quad (79)$$

From Equation (79), we have

$$\begin{aligned} \lim_{r \rightarrow \infty} \frac{\mu(\Delta(\mathbf{x}, r))}{r^d} &= \lim_{r \rightarrow \infty} \frac{\mu(\Delta(\mathbf{x}, r))}{r^d} \\ &= \lim_{r \rightarrow \infty} \frac{\mu(\Delta(\mathbf{x}, r))}{\lambda(\Delta(\mathbf{x}, r))} \end{aligned} \quad (80)$$

$$= \frac{d\mu}{d\lambda}(\mathbf{x}). \quad (81)$$

Here, we use an equation such that $\lambda(\Delta(\mathbf{x}, r)) = r^d$ in Equation (80).

From Equation (81), we observe that

$$\mu(\Delta(\mathbf{x}, r)) = \frac{d\mu}{d\lambda}(\mathbf{x}) \cdot r^d + o(r^d), \quad \text{as } r \rightarrow 0. \quad (82)$$

This completes the proof. \square

Corollary C.16. Assume the same assumptions as in Lemma C.15. Let \mathbf{X} be a random variable drawn from μ , and let $E_{\mathbf{X}}$ denote the expectation with respect to \mathbf{X} .

Then, for any interior point \mathbf{x}_0 in Ω ,

$$E_{\mathbf{X}} \left[\|\mathbf{x}_0 - \mathbf{X}\|_{\infty}^p \cdot I(\Delta(\mathbf{x}_0, r))(\mathbf{X}) \right] = \frac{d\mu}{d\lambda}(\mathbf{x}_0) \cdot r^{p+d+1} + o(r^{p+d+1}), \quad \text{as } r \rightarrow 0, \quad (83)$$

where $I(A)(\cdot)$ is the indicator function for A : $I(A)(\mathbf{x}) = 1$ if $\mathbf{x} \in A$, and 0 otherwise.

proof of Corollary C.16. Consider the integration variable from \mathbf{x} to r such that

$$\|\mathbf{x}_0 - \mathbf{x}\|_{\infty}^p = r. \quad (84)$$

Then, from Lemma C.15, we have, as $r \rightarrow 0$,

$$I(\Delta(\mathbf{x}_0, r))(\mathbf{x}) \cdot \frac{d\mu}{d\lambda}(\mathbf{x}) d\mathbf{x} = \frac{d\mu}{d\lambda}(\mathbf{x}_0) \cdot r^d + o(r^d). \quad (85)$$

From the definition of expectation with the density $d\mu/d\lambda$ and Equation (85), we have, as $r \rightarrow 0$,

$$\begin{aligned} E_{\mathbf{X}} \left[\|\mathbf{x}_0 - \mathbf{X}\|_{\infty}^p \cdot I(\Delta(\mathbf{x}_0, r))(\mathbf{X}) \right] &= \int \|\mathbf{x}_0 - \mathbf{x}\|_{\infty}^p \cdot I(\Delta(\mathbf{x}_0, r))(\mathbf{x}) \cdot \frac{d\mu}{d\lambda}(\mathbf{x}) d\mathbf{x} \\ &= \int r^p \cdot \left(\frac{d\mu}{d\lambda}(\mathbf{x}_0) \cdot r^d + o(r^d) \right) dr \\ &= \frac{d\mu}{d\lambda}(\mathbf{x}_0) \cdot r^{p+d+1} + o(r^{p+d+1}). \end{aligned} \quad (86)$$

This completes the proof. \square

Theorem C.17 (Theorem 4.4 restated). Let P and Q be probability measures on a compact set Ω in \mathbb{R}^d with $d \geq 1$. Assume that $P \ll \lambda$ and $Q \ll \lambda$, where λ denotes the Lebesgue measure on \mathbb{R}^d . Let p be positive constant such that $p \geq 1$. Assume $E[(dQ/dP)^p] < \infty$.

Then,

$$\lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\mathbf{X}_{P[N]}} \left[E_P \left[\left\{ \frac{dQ}{dP} \left(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) \right) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right] \right\}^{1/p}$$

$$\geq e^{-1} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p}, \quad (87)$$

where $E_{\hat{\mathbf{X}}_{P[N]}}[\cdot]$ denotes the expectation on each variable in $\hat{\mathbf{X}}_{P[N]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^N\}$.

proof of Theorem C.17. Let

$$B_i = \left\{ \mathbf{x} \in \Omega \mid \|\mathbf{X}_P^i - \mathbf{x}\|_\infty \leq \left(\frac{1}{N} \right)^{1/d} \right\}. \quad (88)$$

Since $\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})$ is the nearest neighbor in $\{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^N\}$ for \mathbf{x} ,

$$\begin{aligned} 1 &\leq \exists i \leq N \text{ s.t. } \|\mathbf{X}_P^i - \mathbf{x}\|_\infty \leq \left(\frac{1}{N} \right)^{1/d} \\ \iff &\|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty \leq \left(\frac{1}{N} \right)^{1/d} \end{aligned} \quad (89)$$

Thus,

$$\begin{aligned} &\left\{ \mathbf{x} \in \Omega \mid \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty \leq \left(\frac{1}{N} \right)^{1/d} \right\} \\ &= \bigcup_{i=1}^N \left\{ \mathbf{x} \in \Omega \mid \|\mathbf{X}_P^i - \mathbf{x}\|_\infty \leq \left(\frac{1}{N} \right)^{1/d} \right\} = \bigcup_{i=1}^N B_i \end{aligned} \quad (90)$$

Next, define

$$Z_N(\mathbf{x}) = \sum_{i=1}^N I(B_i)(\mathbf{x}). \quad (91)$$

Let \mathbf{X}_P be a random variable drawn from P with $\mathbf{X}_P \perp\!\!\!\perp \mathbf{X}_P^i$, for $1 \leq i \leq N$.

From Lemma C.15,

$$\begin{aligned} P(I(B_i)(\mathbf{X}_P) = 1) &= P(B_i) \\ &= \frac{dP}{d\lambda}(\mathbf{X}_P) \cdot \left(\frac{1}{N^{1/d}} \right)^d + o\left(\frac{1}{N^{1/d}} \right)^d \\ &= \frac{dP}{d\lambda}(\mathbf{X}_P) \cdot \frac{1}{N} + o\left(\frac{1}{N} \right) \\ &= \frac{1}{N} + o\left(\frac{1}{N} \right), \end{aligned} \quad (92)$$

and $I(B_i)(\mathbf{X}_P) \in \{0, 1\}$ and $I(B_i)(\mathbf{X}_P) \perp\!\!\!\perp I(B_j)(\mathbf{X}_P)$ for $i \neq j$. Namely, $Z_N(\mathbf{X}_P)$ follows a binomial distribution with the number of trials N and success probability for each trial $1/N + o(1/N)$.

Then, we obtain

$$E_{\hat{\mathbf{X}}_{P[N]}}[I(\{Z_N(\mathbf{X}_P) = 0\})] = \left(1 - \frac{1}{N} - o\left(\frac{1}{N} \right) \right)^N. \quad (93)$$

Since $\lim_{N \rightarrow \infty} 1 - \frac{1}{N} - o\left(\frac{1}{N} \right) = 1$, we have

$$\left(1 - \frac{1}{N} - o\left(\frac{1}{N} \right) \right)^N = \left(1 - \frac{1}{N} - o\left(\frac{1}{N} \right) \right)^{N-1},$$

as $N \rightarrow \infty$.

Thus,

$$E_{\hat{\mathbf{X}}_{P[N]}} \left[I(\{Z_N(\mathbf{X}_P) = 0\}) \right] = \left(1 - \frac{1}{N} - o\left(\frac{1}{N}\right) \right)^{N-1} \quad (\text{as } N \rightarrow \infty). \quad (94)$$

Additionally, note that

$$Z_N(\mathbf{x}) \geq I\left(\bigcup_{i=1}^N B_i\right)(\mathbf{x}),$$

and

$$Z_N(\mathbf{x}) \geq 1 \implies I\left(\bigcup_{i=1}^N B_i\right)(\mathbf{x}) = 1.$$

In particular,

$$Z_N(\mathbf{x}) = 1 \implies \sum_{i=1}^N I(B_i)(\mathbf{x}) = 1.$$

Therefore,

$$Z_N(\mathbf{x}) = 1 \iff \sum_{i=1}^N I(B_i)(\mathbf{x}) = 1. \quad (95)$$

Now, we obtain

$$\begin{aligned} & N^{p/d} \cdot E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right] \\ & \geq N^{p/d} \cdot E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right. \\ & \quad \times I\left(\left\{ \mathbf{x} \in \Omega \mid \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty \leq \left(\frac{1}{N}\right)^{1/d} \right\}\right) \\ & \quad \times I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \Big] \\ & = N^{p/d} \cdot E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right. \\ & \quad \times I\left(\bigcup_{i=1}^N B_i\right) \cdot I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \Big] \quad (\text{by Equation (90)}) \\ & = N^{p/d} \cdot E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right. \\ & \quad \times \sum_{i=1}^N I(B_i) \cdot I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \Big] \quad (\text{by Equation (95)}) \\ & = N^{p/d} \cdot \sum_{i=1}^N E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right. \\ & \quad \times I(B_i) \cdot I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \Big] \\ & = N^{p/d} \cdot \sum_{i=1}^N E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_P^i) \right\}^p \cdot \|\mathbf{X}_P^i - \mathbf{x}\|_\infty^p \right] \end{aligned}$$

$$\times I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1\right\}\right). \quad (96)$$

Now, let

$$Z_N^{-j}(\mathbf{x}) = \sum_{i \neq j}^N I(B_i)(\mathbf{x}).$$

Then,

$$I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1\right\}\right) = I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N^{-i}(\mathbf{x}) = 0\right\}\right). \quad (97)$$

Additionally, let $\hat{\mathbf{X}}_{P[N]}^{-i}$ denote the subset of $\hat{\mathbf{X}}_{P[N]}$ excluding \mathbf{X}_P^i . i.e., $\hat{\mathbf{X}}_{P[N]}^{-i} = \hat{\mathbf{X}}_{P[N]} \setminus \{\mathbf{X}_P^i\}$. Let $E_N^{-i}[\cdot]$ denote the expectation over the variables in $\hat{\mathbf{X}}_{P[N]}^{-i}$, which is equivalent to $E_{\hat{\mathbf{X}}_{P[N]}^{-i}}$.

From Equation (94),

$$E_N^{-i}\left[I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N^{-i}(\mathbf{x}) = 0\right\}\right)\right] = \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2}. \quad (98)$$

From Equations (97) and (98), we have

$$\begin{aligned} & E_N^{-i}\left[E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1\right\}\right)\right]\right] \\ &= E_N^{-i}\left[E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x})^{-i} = 0\right\}\right)\right]\right] \\ &= E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i) \cdot E_N^{-i}\left[I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x})^{-i} = 0\right\}\right)\right]\right] \\ &= E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i) \times \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2}\right] \\ &= \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \times E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i)\right]. \end{aligned} \quad (99)$$

From Corollary C.16, we have

$$\begin{aligned} & E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i)\right] \\ &= \left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\{\frac{dP}{d\mu}(\mathbf{X}_P^i) \cdot \left(\frac{1}{N^{1/d}}\right)^{p+d+1} + o\left(\left(\frac{1}{N^{1/d}}\right)^{p+d+1}\right)\right\} \\ &= \frac{dP}{d\mu}(\mathbf{X}_P^i) \cdot \left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left(\frac{1}{N}\right)^{1+p/d} + o\left(\left(\frac{1}{N}\right)^{1+p/d}\right) \\ &= \left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left(\frac{1}{N}\right)^{1+p/d} + o\left(\left(\frac{1}{N}\right)^{1+p/d}\right). \end{aligned} \quad (100)$$

From Equations (99) and (100), we obtain

$$E_N^{-i}\left[E_P\left[\left\{\frac{dQ}{dP}(\mathbf{X}_P^i)\right\}^p \cdot \left\|\mathbf{X}_P^i - \mathbf{x}\right\|_\infty^p \times I(B_i) \cdot I\left(\left\{\mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1\right\}\right)\right]\right]$$

$$\begin{aligned}
&= \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \\
&\quad \times \left\{ \frac{dQ}{dP}(\mathbf{X}_P^i) \right\}^p \cdot \left(\frac{1}{N}\right)^{1+p/d} + o\left(\left(\frac{1}{N}\right)^{1+p/d}\right).
\end{aligned} \tag{101}$$

From Equations (96) and (101), we obtain, as $N \rightarrow \infty$,

$$\begin{aligned}
&N^{p/d} \cdot E_{\mathbf{X}_{P[N]}} \left[E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right] \right] \\
&\geq N^{p/d} \cdot E_{\mathbf{X}_{P[N]}} \left[\sum_{i=1}^N E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_P^i) \right\}^p \cdot \|\mathbf{X}_P^i - \mathbf{x}\|_\infty^p \right. \right. \\
&\quad \left. \left. \times I(B_i) \cdot I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \right] \right] \\
&= \sum_{i=1}^N N^{p/d} \cdot E_{\mathbf{X}_P^i} \left[E_N^{-i} \left[E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_P^i) \right\}^p \cdot \|\mathbf{X}_P^i - \mathbf{x}\|_\infty^p \right. \right. \right. \\
&\quad \left. \left. \times I(B_i) \cdot I\left(\left\{ \mathbf{x} \in \Omega \mid Z_N(\mathbf{x}) = 1 \right\}\right) \right] \right] \right] \tag{by Equation (96)} \\
&= \sum_{i=1}^N N^{p/d} \cdot E_{\mathbf{X}_P^i} \left[\left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \right. \\
&\quad \left. \times \left\{ \frac{dQ}{dP}(\mathbf{X}_P^i) \right\}^p \cdot \left(\frac{1}{N}\right)^{1+p/d} + o\left(\left(\frac{1}{N}\right)^{1+p/d}\right) \right] \\
&= N \cdot \left\{ \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \right. \\
&\quad \left. \times E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \cdot \left(\frac{1}{N}\right) + o\left(\frac{1}{N}\right) \right\} \tag{by Equation (101)} \\
&= \left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] + o(1) \right\}.
\end{aligned} \tag{102}$$

As $N \rightarrow \infty$, we observe

$$\left(1 - \frac{1}{N-1} - o\left(\frac{1}{N-1}\right)\right)^{N-2} \rightarrow e^{-1}. \tag{103}$$

Then, we obtain, from Equation (102)

$$\begin{aligned}
&\lim_{N \rightarrow \infty} N^{p/d} \cdot E_{\mathbf{X}_{P[N]}} \left[E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \|\mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x}\|_\infty^p \right] \right] \\
&\geq e^{-1} \cdot E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right].
\end{aligned} \tag{104}$$

This completes the proof. \square

Theorem C.18. Assume that f satisfies Assumption C.6. For $\tilde{\mathcal{L}}_f^{(N)}(\phi)$ defined in Defined C.3, let $\phi_*^{(N)} = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$.

Then, for any measurable function $\phi: \Omega \rightarrow \mathbb{R}_{>0}$, the following equivalence holds:

$$\phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i) = O_p\left(\frac{1}{\sqrt{N}}\right), \quad \text{for } 1 \leq i \leq N$$

$$\Longleftrightarrow \tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) = O_p\left(\frac{1}{\sqrt{N}}\right), \quad (105)$$

where $\{\mathbf{X}_\mu^1, \mathbf{X}_\mu^2, \dots, \mathbf{X}_\mu^N\}$ is defined in Definition C.3, and $\bar{\mathcal{L}}_f(\phi)$ is defined in Lemma C.11.

proof of Theorem C.18. First, we enumerate several facts used in this proof.

I. From the Central Limit Theorem, we have:

$$\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) - E_\mu[\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)})] = O_p\left(\frac{1}{\sqrt{N}}\right). \quad (106)$$

II. From Proposition C.10, we have, for all $\mathbf{x} \in \hat{\mathbf{X}}_{\mu[N]}$:

$$\phi_*^{(N)}(\mathbf{x}) = \frac{dQ}{dP}(\mathbf{x}), \quad (107)$$

where $\hat{\mathbf{X}}_{\mu[N]}$ is defined in Definition C.3.

III. From Equation (107), it follows that:

$$\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) = \tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right), \quad (108)$$

and

$$E_\mu[\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)})] = E_\mu[\tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right)]. \quad (109)$$

IV. From Lemma C.11, we have:

$$\min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) = \bar{\mathcal{L}}_f\left(\frac{dQ}{dP}\right) = E_\mu[\tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right)]. \quad (110)$$

V. From Lemma C.8, for $\tilde{l}_f(u; \mathbf{x})$ defined in Equation (28), we obtain:

$$\frac{d}{du} \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) = 0, \quad (111)$$

and

$$\frac{d^2}{du^2} \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) = f''\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}). \quad (112)$$

VI. From Theorem C.9, we have:

$$\begin{aligned} \tilde{l}_f(u; \mathbf{x}) - \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x}\right) &= \frac{1}{2} \cdot f''\left(\frac{dQ}{dP}(\mathbf{x})\right) \cdot \frac{dP}{d\mu}(\mathbf{x}) \cdot \left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2 \\ &\quad + o\left(\left|u - \frac{dQ}{dP}(\mathbf{x})\right|^2\right), \end{aligned} \quad (113)$$

where $f(a) = o(a)$ (as $a \rightarrow 0$) denotes asymptotic domination such that $\lim_{a \rightarrow 0} f(a)/a = 0$.

VII. From the assumption that $E_P[f''(dQ/dP)] < \infty$,

$$f''\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i)\right) \cdot \frac{dP}{d\mu}(\mathbf{X}_\mu^i) = O_p(1), \text{ as } N \rightarrow \infty. \quad (114)$$

Now, we show the direction “ \implies ” in Equation (105).

Assume that $\phi(\mathbf{X}_\mu^i) = \phi_*^{(N)}(\mathbf{X}_\mu^i) + O_p\left(1/\sqrt{N}\right)$ for $1 \leq i \leq N$.

From Equations (35) in Theorem C.9 and (114), we have

$$\begin{aligned}
& \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f(\phi_*^{(N)}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\
&= \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) \\
&= \frac{1}{2} \cdot f''\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i)\right) \cdot \frac{dP}{d\mu}(\mathbf{X}_\mu^i) \cdot \left|\phi(\mathbf{X}_\mu^i) - \frac{dQ}{dP}(\mathbf{X}_\mu^i)\right|^2 + o\left(\left|\phi(\mathbf{X}_\mu^i) - \frac{dQ}{dP}(\mathbf{X}_\mu^i)\right|^2\right) \\
&= \frac{1}{2} \cdot f''\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i)\right) \cdot \frac{dP}{d\mu}(\mathbf{X}_\mu^i) \cdot \left|\phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i)\right|^2 + o\left(\left|\phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i)\right|^2\right) \\
&= O_p(1) \cdot O_p\left(\left\{\frac{1}{\sqrt{N}}\right\}^2\right) \\
&= O_p\left(\frac{1}{N}\right).
\end{aligned} \tag{115}$$

Thus, we have:

$$\begin{aligned}
\tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) &= \frac{1}{N} \cdot \sum_{i=1}^N \left\{ \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f\left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i\right) \right\} \\
&= \frac{1}{N} \cdot \sum_{i=1}^N O_p\left(\frac{1}{N}\right) \\
&= O_p\left(\frac{1}{N}\right).
\end{aligned} \tag{116}$$

From Equations (106), (108), (110), and (116), we obtain:

$$\begin{aligned}
& \tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} + \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \right\} \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} + \left\{ \tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \right\} \quad (\text{by Equation (108)}) \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} + \left\{ \tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right) - E\left[\tilde{\mathcal{L}}_f^{(N)}\left(\frac{dQ}{dP}\right)\right] \right\} \quad (\text{by Equation (110)}) \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} + \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) - E\left[\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)})\right] \right\} \quad (\text{by Equation (108)}) \\
&= O_p\left(\frac{1}{N}\right) + O_p\left(\frac{1}{\sqrt{N}}\right) \quad (\text{by Equations (106) and (116)}) \\
&= O_p\left(\frac{1}{\sqrt{N}}\right).
\end{aligned} \tag{117}$$

Thus, we have proved “ \implies ”.

Next, we prove the direction “ \impliedby ” in Equation (105).

Suppose

$$\tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) = O_p\left(\frac{1}{\sqrt{N}}\right). \tag{118}$$

From Equations (106), (110), (109), and (118), we obtain

$$\begin{aligned}
& \tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \right\} + \left\{ \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \right\} + \left\{ E \left[\tilde{\mathcal{L}}_f^{(N)} \left(\frac{dQ}{dP} \right) \right] - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} \quad (\text{by Equation (110)}) \\
&= \left\{ \tilde{\mathcal{L}}_f^{(N)}(\phi) - \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \bar{\mathcal{L}}_f(\phi) \right\} + \left\{ E \left[\tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right] - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) \right\} \quad (\text{by Equation (109)}) \\
&= O_p \left(\frac{1}{\sqrt{N}} \right) + O_p \left(\frac{1}{\sqrt{N}} \right) \quad (\text{by Equations (106) and (118)}) \\
&= O_p \left(\frac{1}{\sqrt{N}} \right). \tag{119}
\end{aligned}$$

From Equation (107), we have

$$\begin{aligned}
\tilde{\mathcal{L}}_f^{(N)}(\phi) - \tilde{\mathcal{L}}_f^{(N)}(\phi_*^{(N)}) &= \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \frac{1}{N} \cdot \sum_{i=1}^N \tilde{l}_f(\phi_*^{(N)}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \\
&= \frac{1}{N} \cdot \sum_{i=1}^N \left\{ \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f(\phi_*^{(N)}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \right\}. \tag{120}
\end{aligned}$$

From Equations (119) and (120), we have

$$\frac{1}{N} \cdot \sum_{i=1}^N \left\{ \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i \right) \right\} = O_p \left(\frac{1}{\sqrt{N}} \right). \tag{121}$$

Let $a_N^i = E_P \left[\left| \phi(\mathbf{X}_\mu^i) - \phi_*^{(k)}(\mathbf{X}_\mu^i) \right| \right]$. Since \mathbf{X}_μ^i is identically distributed for $1 \leq i \leq N$, we have $a_N^i = a_N^1$ for any $1 \leq i \leq N$. Thus, define $A_N = \sup_{k \geq N} a_k^i = \sup_{k \geq N} a_k^1$.

Using Chebyshev's inequality, we have for any $\varepsilon > 0$,

$$\begin{aligned}
& P \left(\left| \phi(\mathbf{X}_\mu^i) - \phi_*^{(k)}(\mathbf{X}_\mu^i) \right| / A_N > \frac{1}{\varepsilon} \right) \\
&\leq \frac{\varepsilon \cdot E_P \left[\left| \phi(\mathbf{X}_\mu^i) - \phi_*^{(k)}(\mathbf{X}_\mu^i) \right| \right]}{A_N} \\
&\leq \frac{\varepsilon \cdot a_N^i}{A_N} \\
&\leq \varepsilon. \tag{122}
\end{aligned}$$

Thus, $\phi(\mathbf{X}_\mu^i) - \phi_*^{(k)}(\mathbf{X}_\mu^i) = O_p(A_N)$.

Now, we calculate

$$\begin{aligned}
& \frac{1}{N} \sum_{i=1}^N \left\{ \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f(\phi_*^{(N)}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) \right\} \\
&= \frac{1}{N} \sum_{i=1}^N \left\{ \tilde{l}_f(\phi(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i) - \tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{X}_\mu^i); \mathbf{X}_\mu^i \right) \right\} \\
&= \frac{1}{N} \sum_{i=1}^N \left\{ \frac{1}{2} \cdot \lambda(\mathbf{X}_\mu^i) \cdot O_p \left(\left| \phi(\mathbf{X}_\mu^i) - \frac{dQ}{dP}(\mathbf{X}_\mu^i) \right|^2 \right) + o_p \left(\left| \phi(\mathbf{X}_\mu^i) - \frac{dQ}{dP}(\mathbf{X}_\mu^i) \right|^4 \right) \right\}
\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{N} \sum_{i=1}^N \left\{ \frac{1}{2} \cdot \lambda(\mathbf{X}_\mu^i) \cdot O_p \left(\left| \phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i) \right|^2 \right) + o_p \left(\left| \phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i) \right|^4 \right) \right\} \\
&= \frac{1}{N} \cdot N \cdot \frac{1}{2} \cdot O_p(\sqrt{N}) \cdot O_p(A_N^2) + \frac{1}{N} \cdot N \cdot \frac{1}{2} \cdot o_p(A_N^4) \\
&= O_p(\sqrt{N}) \cdot O_p(A_N^2) + o_p(A_N^4). \tag{123}
\end{aligned}$$

Here, $\mathbf{X} = o_p(a_N)$ denotes the convergence in probability with rate a_N in μ as $N \rightarrow \infty$: $\mathbf{X} = o_p(a_N)$ (as $N \rightarrow \infty$) $\Leftrightarrow \forall \varepsilon, \forall \delta > 0, \exists N(\varepsilon, \delta) > 0$ such that $\mu(|\mathbf{X}|/a_N \geq \delta) < \varepsilon$ for $\forall N \geq N(\varepsilon, \delta)$.

From Equations (121) and (123), we have

$$O_p\left(\frac{1}{\sqrt{N}}\right) \geq O_p(\sqrt{N}) \cdot O_p(A_N^2) + o_p(A_N^4). \tag{124}$$

From the definition of A_N , we observe that A_N decreases as N increases. Thus, $\lim_{N \rightarrow \infty} A_N$ exists and $0 \leq \lim_{N \rightarrow \infty} A_N < \infty$.

Suppose that $\lim_{N \rightarrow \infty} A_N > 0$. Then, we have

$$O_p(\sqrt{N}) \cdot O_p(A_N^2) + o_p(A_N^4) = O_p(\sqrt{N}) + o_p(1). \tag{125}$$

This contradicts Equation (124). Therefore, $\lim_{N \rightarrow \infty} A_N = 0$.

From Equation (124), we have

$$\begin{aligned}
O_p\left(\frac{1}{N}\right) &\geq O_p(A_N^2) + o_p\left(\frac{A_N^4}{\sqrt{N}}\right) \\
&= O_p(A_N^2). \tag{126}
\end{aligned}$$

Thus, $A_N = O(1/\sqrt{N})$.

Finally, we have

$$\phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i) = O_p(A_N) = O_p\left(\frac{1}{\sqrt{N}}\right). \tag{127}$$

Here, we have proved the direction “ \Leftarrow ”.

This completes the proof. \square

Corollary C.19 (Theorem 4.7 restated). *Assume the same assumption as in Theorem C.18. let $\phi_*^{(N)} = \arg \min_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} \tilde{\mathcal{L}}_f^{(N)}(\phi)$.*

Then, for any measurable function $\phi: \Omega \rightarrow \mathbb{R}_{>0}$,

$$\begin{aligned}
\phi(\mathbf{X}_\mu^i) - \phi_*^{(N)}(\mathbf{X}_\mu^i) &= O_p\left(\frac{1}{\sqrt{N}}\right), \quad \text{for } 1 \leq i \leq N. \\
&\iff \mathcal{L}_f^{(R,S)}(\phi) - \inf_{\phi: \Omega \rightarrow \mathbb{R}_{>0}} E_\mu \left[\mathcal{L}_f^{(R,S)}(\phi) \right] = O_p\left(\frac{1}{\sqrt{N}}\right), \tag{128}
\end{aligned}$$

where $\{\mathbf{X}_\mu^1, \mathbf{X}_\mu^2, \dots, \mathbf{X}_\mu^N\}$ is defined in Definition C.3, and $\mathcal{L}_f^{(R,S)}(\phi)$ is defined in Definition C.2.

proof of Corollary C.19. From Lemma C.11, we have $\mathcal{L}_f^{(R,S)}(\phi) = \tilde{\mathcal{L}}_f(\phi)$.

Therefore, Equation (128) follows directly from Equation (105).

This completes the proof. \square

Theorem C.20 (Theorem 4.5 restated). Assume that Ω is a compact set in \mathbb{R}^d with $d \geq 3$ and that f satisfies Assumption C.6. Let P and Q be probability measures on Ω . Assume that $P \ll \lambda$ and $Q \ll \lambda$, where λ denotes the Lebesgue measure on \mathbb{R}^d . Let $T^*(\mathbf{x})$ be the energy function of $dQ/dP(\mathbf{x})$ defined as $T^*(\mathbf{x}) = -\log dQ/dP(\mathbf{x})$.

Let $\tilde{\mathcal{F}}_{K-Lip}^{(N)}$ denote the set of all K -Lipschitz continuous functions on Ω that minimize $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$. Specifically, define

$$\tilde{\mathcal{F}}^{(N)} = \left\{ \phi_* : \Omega \rightarrow \mathbb{R}_{>0} \mid \tilde{\mathcal{L}}_f^{(N)}(\phi_*) = \min_{\phi} \tilde{\mathcal{L}}_f^{(N)}(\phi) \right\}, \quad (129)$$

and

$$\mathcal{F}_{K-Lip} = \left\{ \phi : \Omega \rightarrow \mathbb{R}_{>0} \mid |\phi(\mathbf{y}) - \phi(\mathbf{x})| \leq K \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty} \text{ for all } \mathbf{y}, \mathbf{x} \in \Omega \right\}. \quad (130)$$

Subsequently, let

$$\tilde{\mathcal{F}}_{K-Lip}^{(N)} = \tilde{\mathcal{F}}^{(N)} \cap \mathcal{F}_{K-Lip}. \quad (131)$$

(Upper Bound) Assume Assumption C.4: there exists $L > 0$ such that $|T^*(\mathbf{y}) - T^*(\mathbf{x})| \leq L \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty}$ for any $\mathbf{y}, \mathbf{x} \in \Omega$, i.e., $T^*(\mathbf{x})$ is L -Lipschitz continuous on Ω .

Then, Equation (132) holds for $1 \leq p \leq d/2$, such that for any $\phi \in \tilde{\mathcal{F}}_{K-Lip}^{(N)}$,

$$\begin{aligned} & \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\ & \leq L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} + K \cdot \text{diag}(\Omega). \end{aligned} \quad (132)$$

(Lower Bound) Assume Assumption C.5: there exists $L > 1$ such that $(1/L) \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty} \leq |T^*(\mathbf{y}) - T^*(\mathbf{x})| \leq L \cdot \|\mathbf{y} - \mathbf{x}\|_{\infty}$ for any $\mathbf{y}, \mathbf{x} \in \Omega$, i.e., $T^*(\mathbf{x})$ is L -bi-Lipschitz continuous on Ω ; and $E_P[dQ/dP] < \infty$ with $1 \leq p \leq d$.

Then, Equation (133) holds for any $\phi \in \tilde{\mathcal{F}}_{K-Lip}^{(N)}$, such that

$$\begin{aligned} & \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\mathbf{x}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\ & \geq \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - K \cdot \text{diag}(\Omega) \end{aligned} \quad (133)$$

$$\geq \frac{1}{L} \cdot e^{\frac{p-1}{p} \cdot KL(Q||P) - 1} - K \cdot \text{diag}(\Omega) \quad (134)$$

proof of Theorem C.20. First, we list the equations used in this proof.

I. By Taylor's theorem for the second-order Taylor polynomial of e^{-t} , we have

$$e^{-t} = 1 - t + \frac{1}{2} \cdot e^{-c(t)} \cdot t^2, \quad \text{where } 0 \leq |c(t)| \leq |t|. \quad (135)$$

II. From Equation (135), it follows that

$$\begin{aligned} & \left| \frac{dQ}{dP}(\mathbf{y}) - \frac{dQ}{dP}(\mathbf{x}) \right| \\ & = e^{-T^*(\mathbf{y})} \cdot \left| 1 - e^{T^*(\mathbf{y}) - T^*(\mathbf{x})} \right| \\ & = e^{-T^*(\mathbf{y})} \left\{ (T^*(\mathbf{y}) - T^*(\mathbf{x})) + \frac{1}{2} \cdot e^{C(\mathbf{y}, \mathbf{x}, T^*)} \cdot (T^*(\mathbf{y}) - T^*(\mathbf{x}))^2 \right\} \end{aligned}$$

$$= \frac{dQ}{dP}(\mathbf{y}) \left\{ (T^*(\mathbf{y}) - T^*(\mathbf{x})) + \frac{1}{2} \cdot e^{C(\mathbf{y}, \mathbf{x}, T^*)} \cdot (T^*(\mathbf{y}) - T^*(\mathbf{x}))^2 \right\},$$

where $0 \leq |C(\mathbf{y}, \mathbf{x}, T^*)| \leq |T^*(\mathbf{y}) - T^*(\mathbf{x})|$.

(136)

III. From Corollary C.13, for $0 \leq p \leq d/2$,

$$\overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right\}^{1/p} \leq \text{diag}(\Omega).$$
(137)

IV. From Corollary C.14, for $0 \leq p \leq d/2$,

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right\}^{1/p} \\ & \leq \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} \end{aligned}$$
(138)

V. From Equation (138), for $0 \leq p \leq d/2$,

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{2 \cdot p} \right] \right\}^{1/p} \\ & \leq \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} \left\{ E_P \left[\left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{4 \cdot p} \right] \right\}^{1/(2 \cdot p)} \\ & \leq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} \cdot \text{diag}(\Omega) \cdot \overline{\lim}_{N \rightarrow \infty} \frac{N^{1/d}}{N^{2/d}} \\ & = 0. \end{aligned}$$
(139)

VI. From Theorem C.17, for $0 \leq p \leq d$,

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{P[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{P[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right] \right\}^{1/p} \\ & \geq e^{-1} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p}, \end{aligned}$$
(140)

where $E_{\hat{\mathbf{X}}_{P[N]}}[\cdot]$ denotes the expectation on each variable in $\hat{\mathbf{X}}_{P[N]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^N\}$.

VII. Let $\hat{\mathbf{X}}_{\mu[N]}$ denote the set of random variables defined in Proposition C.10. From Proposition C.10,

$$\phi \in \tilde{\mathcal{F}}_{K-Lip}^{(N)} \iff \phi(\mathbf{X}_{\mu}^i) = \frac{dQ}{dP}(\mathbf{X}_{\mu}^i), \quad \text{for } 1 \leq \forall i \leq N. \quad (141)$$

Now, we prove Equation (132). Let $\phi(\mathbf{x})$ be a member of $\tilde{\mathcal{F}}_{K-Lip}^{(N)}$.

By applying the triangle inequality in the L_p norm, we have

$$\begin{aligned} & \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\ & \leq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right\}^{1/p} + \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi(\mathbf{x}) \right|^p \right\}^{1/p}. \end{aligned}$$
(142)

From the K -Lipschitz continuity of ϕ and Equation (141),

$$\begin{aligned} \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} &= \left\{ E_P \left| \phi(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \quad (\text{by Equation 141}) \\ &\leq K \cdot \left\{ E_P \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right\}^{1/p}. \end{aligned} \quad (143)$$

From Equations (137) and (143),

$$\lim_{N \rightarrow \infty} \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \leq K \cdot \text{diag}(\Omega). \quad (144)$$

Next, by substituting $\mathbf{y} = \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ and multiplying by $\frac{dP}{d\mu}(\mathbf{x})$ in Equation (136), and using the L -Lipschitz continuity of T^* , we have

$$\begin{aligned} &\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \frac{dQ}{dP}(\mathbf{x}) \right|^p \right\}^{1/p} \\ &= \left[E_P \left| \frac{dQ}{dP}(\mathbf{x}) \times \left\{ \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right) \right. \right. \right. \\ &\quad \left. \left. \left. + \frac{1}{2} \cdot e^{C_1(\mathbf{x})} \cdot \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right)^2 \right\} \right|^p \right]^{1/p}, \\ &\quad \text{where } 0 \leq C_1(\mathbf{x}) \leq \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|. \\ &= \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) \times \left\{ \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right) \right\} \right. \right. \\ &\quad \left. \left. + \frac{dQ}{dP}(\mathbf{x}) \times \left\{ \frac{1}{2} \cdot e^{C_1(\mathbf{x})} \cdot \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right)^2 \right\} \right|^p \right\}^{1/p} \\ &\leq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^p \right] \right\}^{1/p} \\ &\quad + \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \frac{1}{2^p} \cdot e^{p \cdot C_1(\mathbf{x})} \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^{2 \cdot p} \right] \right\}^{1/p} \\ &\leq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^p \right] \right\}^{1/p} \\ &\quad + \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right. \right. \\ &\quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|} \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^{2 \cdot p} \right] \right\}^{1/p} \\ &\quad \left(\because C_1(\mathbf{x}) \leq \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right| \right) \\ &\leq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\ &\quad + \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right. \right. \\ &\quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot L \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty} \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right\}^{1/p} \\ &\leq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \end{aligned}$$

$$\begin{aligned}
& + \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right. \right. \\
& \quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot L \cdot \text{diag}(\Omega)} \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{2 \cdot p} \right] \right\}^{1/p} \\
& = L \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right\}^{1/p} \\
& \quad + \frac{1}{2} \cdot e^{L \cdot \text{diag}(\Omega)} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{2 \cdot p} \right] \right\}^{1/p} \\
& \tag{145}
\end{aligned}$$

From Equations (138), (139) and (145), we have

$$\begin{aligned}
& \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right\}^{1/p} \\
& \leq \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot L \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^p \right] \right\}^{1/p} \\
& \quad + \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \frac{1}{2} \cdot e^{L \cdot \text{diag}(\Omega)} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_{\infty}^{2 \cdot p} \right] \right\}^{1/p} \\
& = L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)}. \\
& \tag{146}
\end{aligned}$$

Finally, from Equations (144), (142), and (146), we have

$$\begin{aligned}
& \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\
& \leq L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} + \text{diag}(\Omega) \cdot K. \\
& \tag{147}
\end{aligned}$$

Thus, it is shown that Equation (132) holds.

Next, we prove Equation (133). By applying the triangle inequality in the L_p norm, we have

$$\begin{aligned}
& \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\
& \geq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right\}^{1/p} - \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \phi(\mathbf{x}) \right|^p \right\}^{1/p}. \\
& \tag{148}
\end{aligned}$$

By substituting $\mathbf{y} = \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})$ and multiplying by $\frac{dP}{d\mu}(\mathbf{x})$ in Equation (136) and the L -bi-Lipschitz continuity of T^* , we have

$$\begin{aligned}
& \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - \frac{dQ}{dP}(\mathbf{x}) \right|^p \right\}^{1/p} \\
& = \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right. \right. \\
& \quad \times \left. \left. \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right) \right. \right. \\
& \quad \left. \left. + \frac{1}{2} \cdot e^{C_1(\mathbf{x})} \cdot \left(T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right)^2 \right|^p \right\}^{1/p}
\end{aligned}$$

$$\begin{aligned}
& \text{where } 0 \leq C_1(\mathbf{x}) \leq \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right| \\
& \geq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^p \right] \right\}^{1/p} \\
& \quad - \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \right. \right. \\
& \quad \quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot |T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x})|} \cdot \left| T^*(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) - T^*(\mathbf{x}) \right|^{2 \cdot p} \right] \right\}^{1/p} \\
& \geq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \frac{1}{L^p} \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\
& \quad - \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \right. \right. \\
& \quad \quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot L \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty} \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right\}^{1/p} \\
& \geq \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \frac{1}{L^p} \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\
& \quad - \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \right. \right. \\
& \quad \quad \left. \left. \times \frac{1}{2^p} \cdot e^{p \cdot L \cdot \text{diag}(\Omega)} \cdot L^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right\}^{1/p} \\
& = \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right\}^{1/p} \\
& \quad - \frac{1}{2} \cdot e^{\text{diag}(\Omega)} \cdot L \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right\}^{1/p} \tag{149}
\end{aligned}$$

From Equations (138), (139) and (149), we have

$$\begin{aligned}
& \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[\left(E_P \left[\left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right|^p \right] \right)^{1/p} \right] \right\} \\
& \geq \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[\frac{1}{L^p} \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right)^{1/p} \right. \right. \\
& \quad \left. \left. - \frac{1}{2} \cdot e^{\text{diag}(\Omega)} \cdot L \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right)^{1/p} \right] \right\} \\
& \geq \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[\frac{1}{L} \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right)^{1/p} \right] \right. \\
& \quad \left. - \lim_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_{\hat{\mathbf{X}}_{P[N]}} \left[\frac{1}{2} \cdot e^{\text{diag}(\Omega)} \right. \right. \right. \\
& \quad \quad \left. \left. \times L \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right)^{1/p} \right] \right\} \\
& \geq \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\hat{\mathbf{X}}_{P[N]}} \left[\frac{1}{L} \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^p \right] \right)^{1/p} \right]
\end{aligned}$$

$$\begin{aligned}
& - E_{\mathbf{X}_{P[N]}} \left[\overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ \frac{1}{2} \cdot e^{\text{diag}(\Omega)} \right. \right. \\
& \quad \left. \left. \times L \cdot \left(E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x})) \right\}^p \cdot \left\| \mathbf{X}_{\mu[N]}^{(1)}(\mathbf{x}) - \mathbf{x} \right\|_\infty^{2 \cdot p} \right] \right)^{1/p} \right\} \right] \\
& = e^{-1} \cdot \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p}.
\end{aligned} \tag{150}$$

Finally, from Equations (144), (148), and (150), we have

$$\begin{aligned}
& \lim_{N \rightarrow \infty} N^{p/d} \cdot E_{\mathbf{X}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\
& \geq e^{-1} \cdot \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - \text{diag}(\Omega) \cdot K.
\end{aligned} \tag{151}$$

Thus, it is shown that Equation (133) holds.

Next, we prove Equation (134).

First, we have

$$\begin{aligned}
\left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} & = \left\{ E_P \left[\frac{dQ}{dP}(\mathbf{x}) \cdot \left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{p-1} \right] \right\}^{1/p} \\
& = \left\{ E_Q \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{p-1} \right] \right\}^{1/p} \\
& = \left\{ E_Q \left[e^{(p-1) \cdot \log \frac{dQ}{dP}(\mathbf{x})} \right] \right\}^{1/p}.
\end{aligned} \tag{152}$$

From Jensen's inequality,

$$\begin{aligned}
\left\{ E_Q \left[e^{(p-1) \cdot \log \frac{dQ}{dP}(\mathbf{x})} \right] \right\}^{1/p} & \geq \left\{ e^{E_Q \left[(p-1) \cdot \log \frac{dQ}{dP}(\mathbf{x}) \right]} \right\}^{1/p} \\
& = \left\{ e^{(p-1) \cdot E_Q \left[\log \frac{dQ}{dP}(\mathbf{x}) \right]} \right\}^{1/p} \\
& = e^{\frac{p-1}{p} \cdot E_Q \left[\log \frac{dQ}{dP}(\mathbf{x}) \right]} \\
& = e^{\frac{p-1}{p} \cdot KL(Q||P)}.
\end{aligned} \tag{153}$$

From Equations (151), (152) and (153),

$$\begin{aligned}
& \lim_{N \rightarrow \infty} N^{p/d} \cdot E_{\mathbf{X}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\
& \geq e^{-1} \cdot \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - \text{diag}(\Omega) \cdot K \\
& \geq \frac{1}{L} \cdot e^{\frac{p-1}{p} \cdot KL(Q||P) - 1} - \text{diag}(\Omega) \cdot K.
\end{aligned} \tag{154}$$

This completes the proof. \square

Theorem C.21 (Theorem 4.8 restated). *Assume the same assumptions and notations as in Theorem C.20. Additionally, define*

$$\mathcal{F}_{K-Lip}^{(N)} = \left\{ \phi \in \mathcal{F}_{K-Lip} \mid \exists \phi_* \in \widetilde{\mathcal{F}}_{K-Lip}^{(N)} \text{ such that } \phi = \phi_* + O_p \left(\frac{1}{\sqrt{N}} \right) \right\}. \tag{155}$$

That is, $\mathcal{F}_{K-Lip}^{(N)}$ denotes the set of all functions that differ by at most $O_p(1/\sqrt{N})$ from some functions that minimize $\tilde{\mathcal{L}}_f^{(N)}(\cdot)$.

Then, the same results as in Theorem C.20 hold for all $\phi \in \mathcal{F}_{K-Lip}^{(N)}$. Specifically:

(Upper Bound) Under Assumption C.4, Equation (132) holds for $1 \leq p \leq d/2$ such that for any $\phi \in \mathcal{F}_{K-Lip}^{(N)}$,

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\ & \leq L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} + K \cdot \text{diag}(\Omega). \end{aligned} \quad (156)$$

(Lower Bound) Under Assumption C.5, Equation (133) holds for any $\phi \in \mathcal{F}_{K-Lip}^{(N)}$, such that

$$\begin{aligned} & \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\tilde{\mathbf{x}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\ & \geq \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - K \cdot \text{diag}(\Omega) \end{aligned} \quad (157)$$

$$\geq \frac{1}{L} \cdot e^{\frac{p-1}{p} \cdot KL(Q||P)-1} - K \cdot \text{diag}(\Omega) \quad (158)$$

Proof of Theorem C.21. First, we prove Equation (156).

Let $\tilde{\phi}$ be a member of $\mathcal{F}_{K-Lip}^{(N)}$. Then, there exists $\phi \in \mathcal{F}_{K-Lip}^{(N)}$ such that $\tilde{\phi} = \phi + O_p(1/\sqrt{N})$.

Using the triangle inequality in the L_p norm, we obtain

$$\begin{aligned} \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \tilde{\phi}(\mathbf{x}) \right|^p \right\}^{1/p} &= \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) + O_p\left(\frac{1}{\sqrt{N}}\right) \right|^p \right\}^{1/p} \\ &\leq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} + \left\{ E_P \left| O_p\left(\frac{1}{\sqrt{N}}\right) \right|^p \right\}^{1/p} \\ &= \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} + O\left(\frac{1}{\sqrt{N}}\right). \end{aligned} \quad (159)$$

From Equations (132) and (159), we have

$$\begin{aligned} & \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \tilde{\phi}(\mathbf{x}) \right|^p \right\}^{1/p} \\ & \leq \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} + O\left(\frac{1}{\sqrt{N}}\right) \right] \\ & = \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} + \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot O\left(\frac{1}{\sqrt{N}}\right) \\ & = \overline{\lim}_{N \rightarrow \infty} N^{1/d} \cdot \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \\ & = L \cdot \text{diag}(\Omega) \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^{2 \cdot p} \right] \right\}^{1/(2 \cdot p)} + K \cdot \text{diag}(\Omega). \end{aligned} \quad (160)$$

Therefore, Equation (156) is proven.

Next, we prove Equation (157).

By applying the triangle inequality in the L_p norm, we obtain

$$\begin{aligned} \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \tilde{\phi}(\mathbf{x}) \right|^p \right\}^{1/p} &= \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) + O_p \left(\frac{1}{\sqrt{N}} \right) \right|^p \right\}^{1/p} \\ &\geq \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} - \left\{ E_P \left| O_p \left(\frac{1}{\sqrt{N}} \right) \right|^p \right\}^{1/p} \\ &= \left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} - O \left(\frac{1}{\sqrt{N}} \right). \end{aligned} \quad (161)$$

In a similar manner to the derivation of Equation (160), we have

$$\begin{aligned} &\lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\hat{\mathbf{X}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \tilde{\phi}(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\ &\geq \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\hat{\mathbf{X}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} - O \left(\frac{1}{\sqrt{N}} \right) \right] \\ &= \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\hat{\mathbf{X}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] - \lim_{N \rightarrow \infty} N^{1/d} \cdot O \left(\frac{1}{\sqrt{N}} \right) \\ &= \lim_{N \rightarrow \infty} N^{1/d} \cdot E_{\hat{\mathbf{X}}_{P[N]}} \left[\left\{ E_P \left| \frac{dQ}{dP}(\mathbf{x}) - \phi(\mathbf{x}) \right|^p \right\}^{1/p} \right] \\ &= \frac{1}{L} \cdot \left\{ E_P \left[\left\{ \frac{dQ}{dP}(\mathbf{x}) \right\}^p \right] \right\}^{1/p} - K \cdot \text{diag}(\Omega). \end{aligned} \quad (162)$$

Therefore, Equation (157) is proven.

Equation (158) is obtained in the same manner as in the proof of Theorem C.20.

This completes the proof. \square

D DETAILS OF THE EXPERIMENTS IN SECTION 3

In this section, we provide details of the experiments reported in Section 3. Each dataset, experimental method, experimental result, and the neural network settings used in the experiments are described in separate subsections.

D.1 DATASETS.

In both experiments investigating the relationship between L_p errors and KL-divergence in the data, and the relationship between L_p errors and the dimensionality of the data, the datasets were generated from the following distributions: the numerator distribution is a multidimensional multimodal normal distribution, and the denominator distribution is a multidimensional standard normal distribution.

Denominator Distribution: The denominator datasets $\hat{\mathbf{X}}_{P[R]} = \{\mathbf{X}_P^1, \mathbf{X}_P^2, \dots, \mathbf{X}_P^R\}$ were generated from the following d -dimensional standard normal distribution:

$$\mathbf{X}_P^i \stackrel{\text{iid}}{\sim} \mathcal{N}(\mathbf{0}, I_d), \quad (163)$$

where I_d denotes the d -dimensional identity matrix.

Numerator Distribution: The numerator datasets $\hat{\mathbf{X}}_{Q[S]} = \{\mathbf{X}_Q^1, \mathbf{X}_Q^2, \dots, \mathbf{X}_Q^S\}$ were generated from the following d -dimensional, M -multimodal normal distribution:

$$\mathbf{X}_Q^i \stackrel{\text{iid}}{\sim} \prod_{m=1}^M \mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)^{Z_m}, \quad (164)$$

where for each mode m :

- $Z_m \sim \text{Bernoulli}(1/M)$ and $\sum_{m=1}^M Z_m = 1$.
- $\mathbf{r}_m \sim \text{Uniform}(\mathbb{S}^{d-1})$.

Here, $\text{Bernoulli}(1/M)$ denotes the Bernoulli distribution with parameter $1/M$, and $\text{Uniform}(\mathbb{S}^{d-1})$ denotes the uniform distribution on the d -dimensional unit surface $\mathbb{S}^{d-1} = \{\mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\| = 1\}$.

In the aforementioned setting when $M = 1$, the KL-divergence of the datasets is calculated as:

$$\begin{aligned}
KL(P||Q) &= E_P \left[\log \left(\frac{dP}{dQ} \right) \right] \\
&= E_{\mathcal{N}(\mathbf{0}, I_d)} \left[\log \left(\frac{\mathcal{N}(\mathbf{0}, I_d)}{\mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)} \right) \right] \\
&= \frac{1}{2} \cdot \left[\log \frac{|\Sigma_p|}{|\Sigma_q|} - d + \text{Tr}(\Sigma_p^{-1} \cdot \Sigma_q) + (\mu_p - \mu_q)^T \cdot \Sigma_p^{-1} \cdot (\mu_p - \mu_q) \right] \\
&= \frac{1}{2} \cdot \left[\log \frac{|I_d|}{|I_d|} - d + \text{Tr}(I_d \cdot I_d) + (\mu \cdot \mathbf{r}_m)^T \cdot I_d \cdot (\mu \cdot \mathbf{r}_m) \right] \\
&= \frac{1}{2} \cdot (0 - d + d + \mu^2 \cdot \mathbf{r}_m^T \cdot \mathbf{r}_m) \\
&= \frac{1}{2} \cdot \mu^2.
\end{aligned} \tag{165}$$

From Equation (165), the KL-divergence of the datasets for $M > 1$ is calculated as:

$$\begin{aligned}
KL(P||Q) &= E_P \left[\log \left(\frac{dP}{dQ} \right) \right] \\
&= E_{\mathcal{N}(\mathbf{0}, I_d)} E_{Z_m \sim \text{Bernoulli}(1/M)} \left[\log \left(\frac{\mathcal{N}(\mathbf{0}, I_d)}{\prod_{m=1}^M \mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)^{Z_m}} \right) \right] \\
&= E_{\mathcal{N}(\mathbf{0}, I_d)} E_{Z_m \sim \text{Bernoulli}(1/M)} \left[\log \prod_{m=1}^M \left(\frac{\mathcal{N}(\mathbf{0}, I_d)}{\mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)} \right)^{Z_m} \right] \\
&= E_{\mathcal{N}(\mathbf{0}, I_d)} E_{Z_m \sim \text{Bernoulli}(1/M)} \left[\sum_{m=1}^M \log \left(\frac{\mathcal{N}(\mathbf{0}, I_d)}{\mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)} \right) \right] \\
&= E_{\mathcal{N}(\mathbf{0}, I_d)} \left[\log \left(\frac{\mathcal{N}(\mathbf{0}, I_d)}{\mathcal{N}(\mu \cdot \mathbf{r}_m, I_d)} \right) \right] \\
&= \frac{1}{2} \cdot \mu^2.
\end{aligned} \tag{166}$$

Thus, we set $\mu = \sqrt{2 \cdot KL(P||Q)}$ in Equation (164) for $M = 1, 2, 3$, and 4, where $KL(P||Q)$ denotes the KL-divergence of the datasets.

D.2 EXPERIMENTAL PROCEDURE.

We trained neural networks using the training datasets by optimizing KL-divergence and α -divergence loss functions. Details of the two functions used in the experiments are provided below.

KL-divergence loss function. We used the following KL-divergence loss function, $\mathcal{L}_{\text{KL}}(\cdot)$, in our experiments:

$$\begin{aligned}
\mathcal{L}_{\text{KL}}(T) &= \hat{E}_P [e^T] - \hat{E}_Q [T] \\
&= \frac{1}{S} \cdot \sum_{i=1}^S e^{T(\mathbf{x}_Q^i)} - \frac{1}{R} \cdot \sum_{i=1}^R T(\mathbf{x}_P^i).
\end{aligned} \tag{167}$$

α -divergence loss function. We utilized an α -divergence loss function proposed in a separate unpublished study, currently under anonymous review. The α -divergence loss function is defined as:

$$\begin{aligned}\mathcal{L}_{\alpha\text{-divergence}}^{(R,S)}(T; \alpha) &= \frac{1}{\alpha} \cdot \hat{E}_{Q[S]}[e^{\alpha \cdot T_\theta}] + \frac{1}{1-\alpha} \cdot \hat{E}_{P[R]}[e^{(\alpha-1) \cdot T_\theta}] \\ &= \frac{1}{\alpha} \cdot \frac{1}{S} \cdot \sum_{i=1}^S e^{\alpha \cdot T(\mathbf{x}_Q^i)} + \frac{1}{1-\alpha} \cdot \frac{1}{R} \cdot \sum_{i=1}^R e^{(\alpha-1) \cdot T(\mathbf{x}_P^i)}.\end{aligned}\quad (168)$$

For further details and theoretical derivations of the loss function, we refer the reader to the anonymized supplementary material included in this submission (see Anonymous (2024)). This material contains a full explanation of the theoretical framework and the optimization process of the loss function used here.

L_p Errors vs. KL-Divergence in Data. We initially created 100 training, validation, and test datasets, each consisting of 10000 samples, with a data dimensionality of 5 and KL-divergence values of 1, 2, 4, 8, 10, 12, and 14, and the numerator datasets of modalities of 1, 2, 3, and 4. The numerator datasets had modalities of 1, 2, 3, and 4, generated from the aforementioned distributions. We trained neural networks using the training datasets by optimizing both the α -divergence and KL-divergence loss functions. Training was halted if the validation loss, measured using the validation datasets, did not improve over an entire epoch. After training the neural networks, we measured the L_p errors of the estimated density ratios for $p = 1, 2$, and 3, using the test datasets. A total of 100 trials were conducted, and we reported the median L_p errors along with the interquartile range (25th to 75th percentiles) for each KL-divergence and α -divergence function.

L_p Errors vs. the Dimensions of Data. We initially created 100 training datasets, each consisting of 20000 samples, and 100 validation and test datasets, each consisting of 5000 samples, with data dimensionalities of 50, 100, and 200, and a KL-divergence value of 3. We trained neural networks using the training datasets of sizes 1000, 2000, 4000, 8000, and 16000, by optimizing both the α -divergence and KL-divergence loss functions. The numerator datasets had modalities of 1, 2, 3, and 4, generated from the aforementioned distributions. Training was halted if the validation loss, measured using the validation datasets, did not improve over an entire epoch. After training the neural networks, we measured the L_p errors of the estimated density ratios for $p = 1, 2$, and 3, using the test datasets. A total of 100 trials were conducted, and we reported the median L_p errors along with the interquartile range (25th to 75th percentiles) for each KL-divergence and α -divergence function.

D.3 RESULTS.

L_p Errors vs. the KL-Divergence in Data. The results for each multimodal case $M = 1, 2, 3$, and 4 of the numerator datasets are shown in Figure 3. The results of $M = 1$ were reported in Section 3.

As shown in Figure 3, the estimation errors for $p > 0$ increased significantly, which accelerates as p becomes larger. In contrast, when $p = 0$, a relatively mild increase was observed. As indicated by Theorem 3.5, these results highlight the impact of the KL-divergence in the data on L_p error with $p > 1$ in DRE f -divergence loss functions. Additionally, little difference was observed in the results among the modalities of the numerator datasets.

L_p Errors vs. the Dimensions of Data. The results for each multimodal case $M = 1, 2, 3$, and 4 of the numerator datasets are shown in Figure 4 and 5. The results of $M = 1$ (the first and second rows in Figure 4) were reported in Section 3.

As shown in Figure 2, the L_1 , L_2 , and L_3 errors in DRE deteriorated as the data dimensionality increases for both the α -divergence and KL-divergence loss functions. These results indicate that the curse of dimensionality occurs equally across the L_p errors, as indicated by Theorem 3.5. Additionally, little difference was observed in the results among the modalities of the numerator datasets.

D.4 NEURAL NETWORK ARCHITECTURE, OPTIMIZATION ALGORITHM, AND HYPERPARAMETERS.

L_p Errors vs. the KL-Divergence in Data. The same neural network architecture, optimization algorithm, and hyperparameters were used for both the KL-divergence and α -divergence loss func-

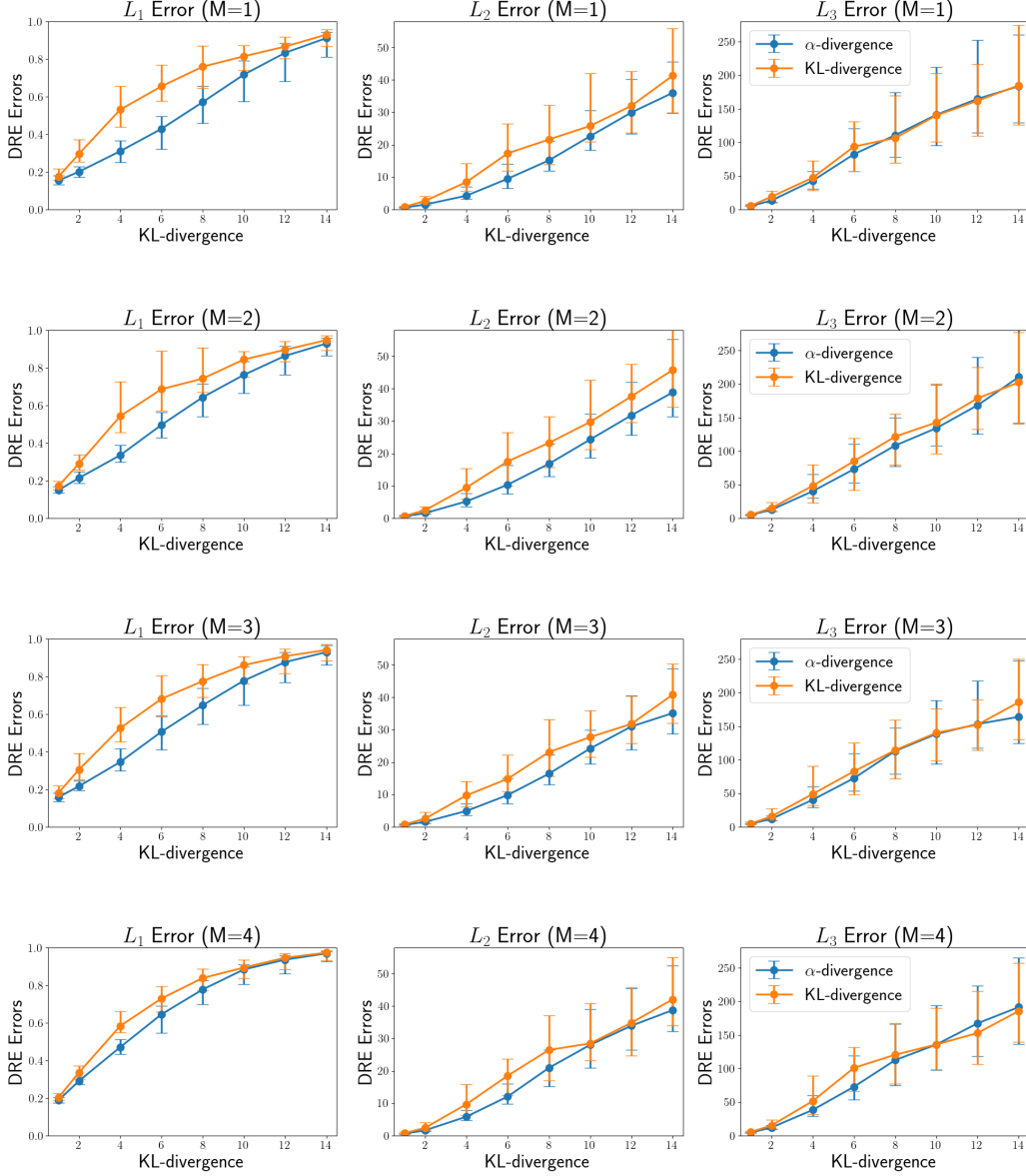


Figure 3: Experimental results of L_p errors versus the KL-divergence in the data for each multimodal case $M = 1, 2, 3$, and 4 of the numerator datasets, as discussed in Sections 3 and D. The results for $M = 1$ were reported in Section 3. The x -axis represents the KL-divergence of synthetic datasets with fixed dimension. The y -axes of the left, center, and right graphs represent the L_1 , L_2 , and L_3 errors in DRE, respectively. The blue line represents errors using the α -divergence loss function, and the orange line represents errors using the KL-divergence loss function. The error bars represent the interquartile range (25th to 75th percentiles) of the y -axis values. The plots show the median y -axis values corresponding to the KL-divergence levels in the synthetic datasets.

tions. A 6-layer perceptron with ReLU activation was employed, with each hidden layer consisting of 1024 nodes. For optimization with the both the KL-divergence and α -divergence loss functions, the learning rate was 0.0001, and the batch size was 128. Early stopping was applied with a patience of 3 epochs, and the maximum number of epochs was set to 5000. the value of α for the α -divergence loss function was set to 0.5, Pytorch (Paszke et al., 2017) library in Python was used to implement all

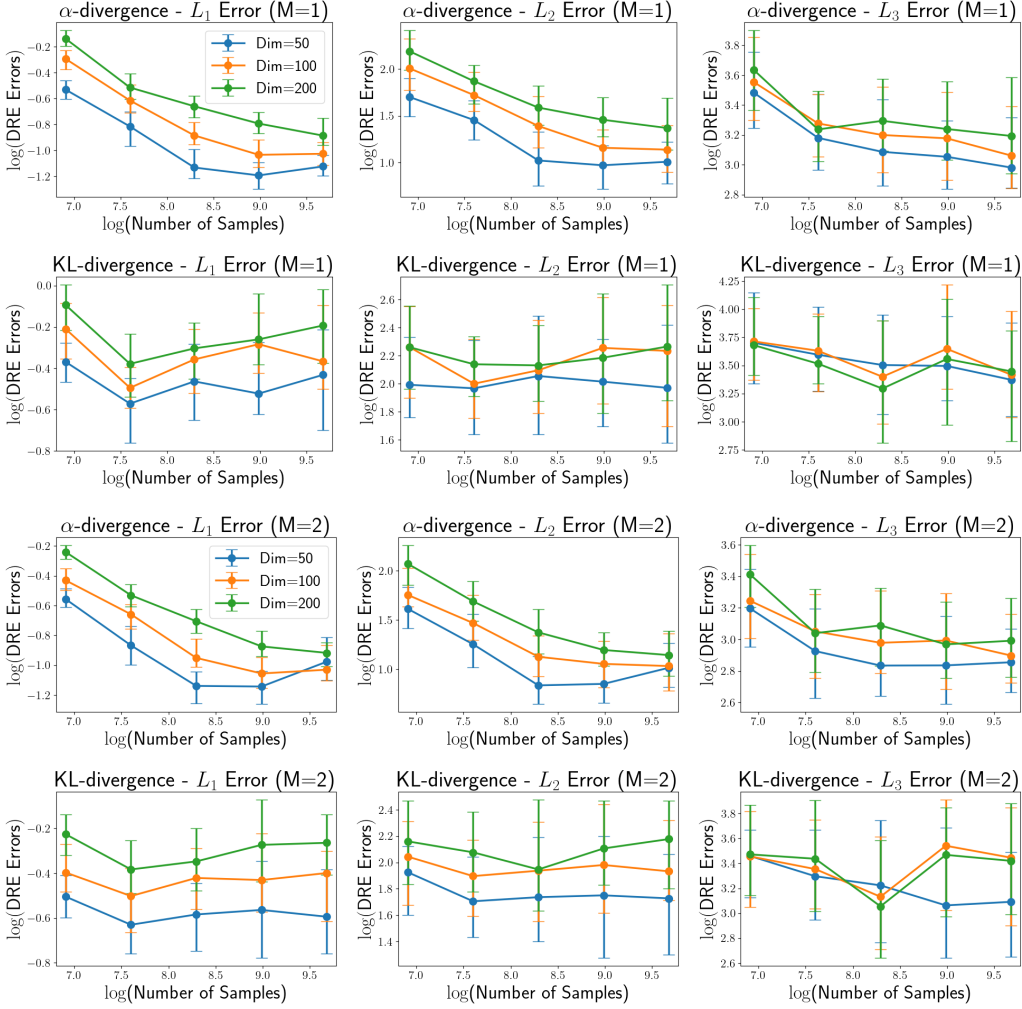


Figure 4: Experimental results of L_p errors versus the dimensionality of the data for the multimodal case $M=1$ and $M=2$ in the numerator datasets, as discussed in Sections 3 and D. The results for $M=1$ were reported in Section 3. The top row shows the results using the α -divergence loss function, and the bottom the results using the KL-divergence loss function. The x -axis represents the logarithm of the number of samples used for the optimizations for DRE. The y -axes of the left, center, and right graphs represent the L_1 , L_2 , and L_3 errors in DRE, respectively. The blue, orange, and green lines represent the results for data dimensionalities of 50, 100, and 200, respectively. The plots show the median y -axis values, and the error bars indicate the interquartile range (25th to 75th percentiles) of the y -axis values for the logarithm of the number of samples used for the optimizations of DRE.

models for DRE, with the Adam optimizer (Kingma, 2014) in PyTorch and an NVIDIA T4 GPU used for training the neural networks.

L_p Errors vs. the Dimensions of Data. The same neural network architecture, optimization algorithm, and hyperparameters were used for the KL-divergence and α -divergence loss functions. A 6-layer perceptron with ReLU activation was employed, with each hidden layer consisting of 1024 nodes. For optimization with the both the KL-divergence and α -divergence loss functions, the learning rate was 0.0001, and the batch size was 128. Early stopping was applied with a patience of 1 epochs, and the maximum number of epochs was set to 5000. the value of α for the α -divergence loss function was set to 0.5, Pytorch (Paszke et al., 2017) library in Python was used to implement all

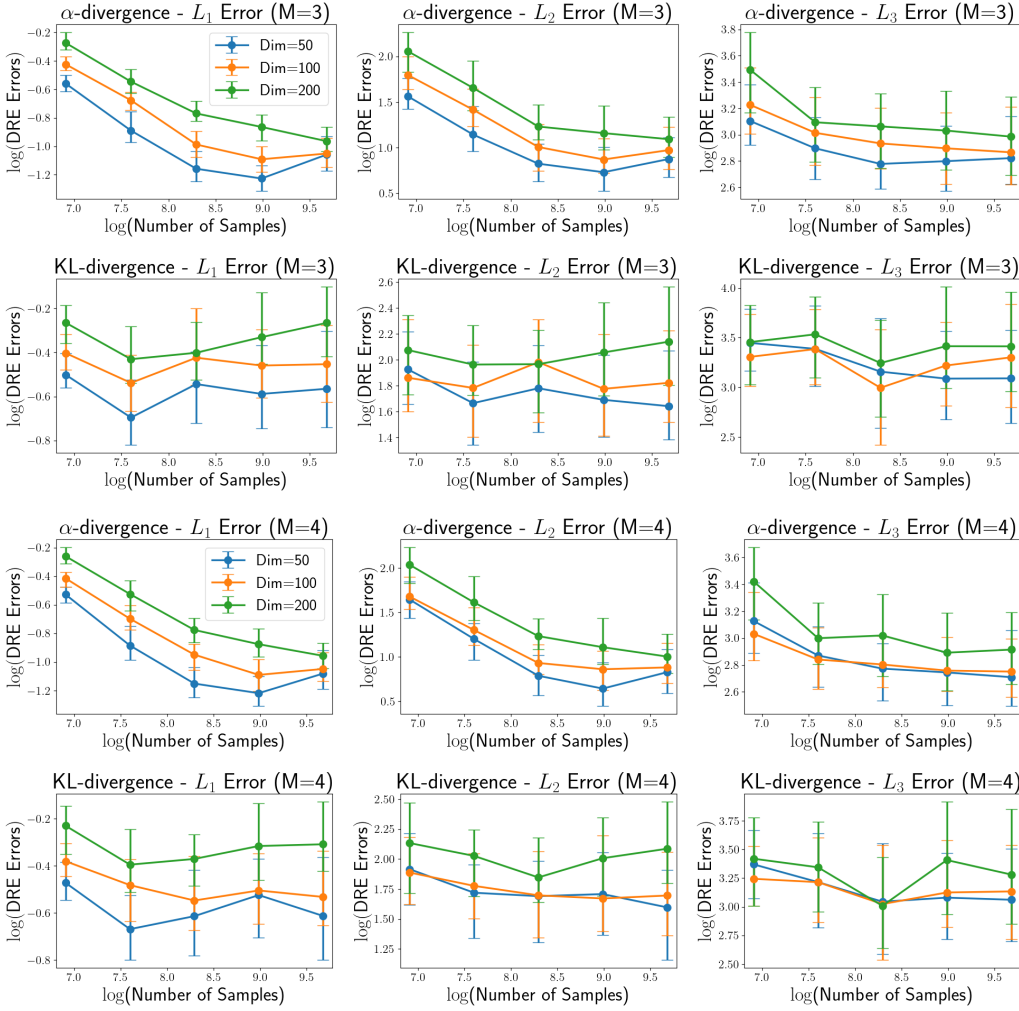


Figure 5: Experimental results of L_p errors versus the dimensionality of the data for the multimodal case $M = 3$ and 4 in the numerator datasets, as discussed in Sections D. The top row shows the results using the α -divergence loss function, and the bottom the results using the KL-divergence loss function. The x -axis represents the logarithm of the number of samples used for the optimizations for DRE. The y -axes of the left, center, and right graphs represent the L_1 , L_2 , and L_3 errors in DRE, respectively. Blue, orange, and green lines represent the results for data dimensionalities of 50, 100, and 200, respectively. The plots show the median y -axis values, and the error bars indicate the interquartile range (25th to 75th percentiles) of the y -axis values for the logarithm of the number of samples used for the optimizations of DRE.

models for DRE, with the Adam optimizer (Kingma, 2014) in PyTorch and an NVIDIA T4 GPU used for training the neural networks.

E FURTHER DISCUSSIONS RELATED TO THIS STUDY

In this section, we explore further discussions related to this study. First, we compare the upper DRE bound derived in this study with those reported in previous research. Next, we provide remarks on Assumption 3.3, comparing it with related assumptions in prior work. Finally, we highlight the potential applications suggested by this study.

E.1 COMPARISON WITH EXISTING DRE BOUNDS

In this section, we compare our L_p upper bound in Equation (4) in Theorem 3.5 to known DRE bounds from other methods.

The terms related to data dimensionality in our upper bound are tighter than the existing non-parametric minimax upper bounds in DRE. Additionally, to the best of our knowledge, no prior work has provided a term like ours regarding the exponential of the KL-divergence in Equation (6) in Theorem 3.5.

Nguyen et al. (2010) presented a minimax upper bound rate of $O(1/N^{\frac{1}{2+d}})$ for the Hellinger distance between the true and estimated density ratio, obtained by optimizing a KL-divergence loss function. Since the Hellinger distance serves as an upper bound for the total variation distance (Sason & Verdú, 2016), the result from Nguyen et al. (2010) provides an upper bound on the L_1 error in DRE using the KL-divergence loss function. Kanamori et al. (2012) provided an upper bound of $O(1/N^{\frac{1}{2+d}})$ for DRE using kernel unconstrained least-squares importance fitting (KuLSIF), their proposed DRE method. Under an assumption on the β -Hölder continuity of the probability ratio function, Kpotufe (2017) presented an upper bound of $O_P(\log N/N^{\frac{\beta}{\beta+d}})$ for DRE using an empirical distribution-based estimator, where our case corresponds to $\beta = 1$. A recent study (Lin et al., 2023) provided L_1 and L_2 error upper bounds of $O(1/N^{\frac{1}{2+d}})$ in DRE for an estimator using the M -th nearest neighbor, as M increases along with the sample size.

In terms of comparison with our L_p lower bound, a minimax L_1 lower bound of $O(1/N^{\frac{1}{2+d}})$, for example, was provided by Lin et al. (2023). This lower bound is larger than our lower bound in Equation (5) in Theorem 3.5 and appears tighter than ours. However, minimax lower bounds may not represent the true lower bounds and cannot be directly compared to our lower bound, as discussed in Section 1.

E.2 REMARKS ON ASSUMPTION 3.3 AND RELATED ASSUMPTIONS IN PRIOR WORK

In this section, we provide remarks on Assumption 3.3 by comparing it with related assumptions in prior work.

An assumption closely related to Assumption 3.3 can be found in the pseudo self-concordance property of losses introduced by Bach (2010). While the pseudo self-concordance assumption guarantees that the original loss function is smooth and strongly convex proportional to its second derivative, Assumption 3.3 ensures the same properties only for the expectation of the loss function.

First, we briefly review the pseudo self-concordance assumption, along with a key property of loss functions that follows from it. Bach (2010) introduced the following pseudo self-concordance assumption.²

Assumption E.1 (Pseudo self-concordance). For any $u > 0$ and for any $r \in \mathbb{R}$, the loss $g(u)$ satisfies

$$|g'''(u+r)| \leq R \cdot r^2 \cdot g''(u), \quad (169)$$

for some $R > 0$.

²In our discussion, we consider the pseudo self-concordance assumption only for loss functions defined on a one-dimensional variable, whereas Bach (2010) introduced it for loss functions in a multidimensional domain. For a precise formulation, please refer to Propositions 1 and 2 in Bach (2010).

According to Proposition 1 in Bach (2010), under Assumption E.1, we have, for a sufficiently small $r_0 > 0$,

$$e^{-R \cdot r^2} \leq \frac{g''(u+r)}{g''(u)} \leq e^{R \cdot r^2}, \text{ for } 0 < r < r_0. \quad (170)$$

Now, let $G_u(r) = \{g(u+r) - g(u)\}/g''(u)$. From Equation (170),

$$\frac{1}{L} \leq G_u''(r) \leq L, \text{ for } 0 < r < r_0, \quad (171)$$

where $L = e^{R \cdot r_0^2}$.

Therefore, the pseudo self-concordance property implies that $G_u(r)$ is both L -smooth and $1/L$ -strongly convex on any interval of fixed length r_0 , with L independent of u , which is believed to be a key property of loss functions under the pseudo self-concordance assumption.

Next, we discuss the properties of the loss function derived from our assumptions. Theorem C.9 in the appendix characterizes the local convexity of the loss function as follows:

$$\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) - \tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right) = \frac{1}{2} \cdot f'' \left(\frac{dQ}{dP}(\mathbf{x}) \right) \cdot \frac{dP}{d\mu}(\mathbf{x}) \cdot r^2 + o(r^2). \quad (172)$$

Additionally, from Theorem C.8,

$$\tilde{l}_f'' \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right) = f'' \left(\frac{dQ}{dP}(\mathbf{x}) \right) \cdot \frac{dP}{d\mu}(\mathbf{x}), \quad (173)$$

where

$$\tilde{l}_f''(u; \mathbf{x}) = \frac{d^2}{dr^2} \tilde{l}_f(u+r; \mathbf{x}) \Big|_{r=0}.$$

From Equations (172) and (173), as $r \rightarrow 0$,

$$\frac{\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) - \tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right)}{\tilde{l}_f'' \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right)} = \frac{r^2}{2} + o_{\mathbf{x}}(1), \quad (174)$$

where $o_{\mathbf{x}}(1)$ denotes a quantity that converges to 0 as $r \rightarrow 0$, though not uniformly in \mathbf{x} ; that is, $f(r) = o_{\mathbf{x}}(1)$ if and only if, for every $\varepsilon > 0$, there exists $\delta_{\mathbf{x}} > 0$ (depending on \mathbf{x}) such that $|f(r)| < \varepsilon$ for all $0 < r < \delta_{\mathbf{x}}$.

Now, let $G_{u(\mathbf{x})}(r) = \{\tilde{l}_f(u(\mathbf{x})+r; \mathbf{x}) - \tilde{l}_f(u(\mathbf{x}); \mathbf{x})\} / \tilde{l}_f''(u(\mathbf{x}); \mathbf{x})$, where $u(\mathbf{x}) = dQ/dP(\mathbf{x})$. From Equation (174), we have, for some $\delta_{\mathbf{x}} > 0$ and $L_{\mathbf{x}} \geq 1$,

$$\frac{1}{L_{\mathbf{x}}} \leq G_{u(\mathbf{x})}''(r) \leq L_{\mathbf{x}}, \text{ for } 0 < r < \delta_{\mathbf{x}}, \quad (175)$$

where $\delta_{\mathbf{x}} > 0$ and $L_{\mathbf{x}} \geq 1$ are determined at each point $\mathbf{x} \in \Omega$. Because $\delta_{\mathbf{x}}$ and $L_{\mathbf{x}}$ depend on \mathbf{x} , Equation (175) does not imply that $G_{u(\mathbf{x})}$ is L -smooth or $1/L$ -strongly convex on any interval of a fixed length.

However, taking the expectation with respect to μ on both sides of Equation (172) yields

$$E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) \right] - E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right) \right] = \frac{1}{2} \cdot E_P \left[f'' \left(\frac{dQ}{dP} \right) \right] \cdot r^2 + o(r^2). \quad (176)$$

From Equation (176), we have

$$\frac{d^2}{dr^2} \left\{ E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) \right] \right\} \Big|_{r=0} = E_P \left[f'' \left(\frac{dQ}{dP} \right) \right]. \quad (177)$$

Thus,

$$\bar{G}(r) = \frac{r^2}{2} + \frac{o(r^2)}{E_P \left[f'' \left(\frac{dQ}{dP} \right) \right]}, \quad (178)$$

where

$$\bar{G}(r) = \frac{E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) \right] - E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}); \mathbf{x} \right) \right]}{\frac{d^2}{dr^2} \left\{ E_{\mu} \left[\tilde{l}_f \left(\frac{dQ}{dP}(\mathbf{x}) + r; \mathbf{x} \right) \right] \right\} \Big|_{r=0}}.$$

From Equation (178), we deduce that, for some $r_0 > 0$,

$$\bar{G}''(r) = \frac{1}{2}, \text{ for } 0 < r < r_0. \quad (179)$$

Equation (179) implies that the expectation of the loss function is locally both smooth and strongly convex, with magnitudes proportional to its second derivative. In contrast, under the pseudo self-concordance assumption, the original loss function is guaranteed to possess these properties (see Equation (171)).

In summary, under Assumption 3.3, the expectation of the loss function exhibits the same local smoothness and strong convexity properties (proportional to its second derivative) as those guaranteed by the pseudo self-concordance assumption.

Furthermore, we note that the expression $E_P[f''(dQ/dP)]$ in Assumption 3.3 resembles the Fisher information when $f(u) = -\log u$, as shown in Equations (176) and (177). Thus, as an alternative perspective, we propose that Assumption 3.3 establishes an information-theoretic bound for estimation using f -divergence optimization.

E.3 APPLICATIONS OF THIS STUDY

In this section, we provide a brief discussion of potential applications highlighted by our findings. The following two key applications can be derived from our results.

Selecting a benchmark index for evaluating DRE methods. When evaluating the accuracy of DRE methods using synthetic datasets, the root mean squared error (RMSE) or mean squared error (MSE) is recommended rather than the mean absolute error (MAE). Prior works did not carefully consider the differences in their behavior regarding the KL divergence of the datasets. For example, Kimura & Bondell (2024) used MAE, whereas Kato & Teshima (2021) used MSE.

Fitting the distribution of base noise for f -GAN and Normalizing Flow. Optimization of f -GANs (Nowozin et al., 2016) could benefit from adjusting the base noise distribution to better match the data. Since the optimization of f -GANs is equivalent to DRE by optimizing the f -divergence (Uehara et al., 2016), the accuracy of generative models could be improved by fitting the base parametric models to the data in terms of KL divergence minimization (i.e., likelihood maximization). A similar approach could also be applied to the base models in Normalizing Flow (Papamakarios et al., 2021).

Table 2: List of $f'(\phi)$ and $f^*(f'(\phi))$ in Equation (1) together with convex functions, as discussed Section 2.2. Part of the list of divergences and their convex functions is based on Nowozin et al. (2016).

Name	convex function f	$f'(\phi)$	$f^*(f'(\phi))$
KL	$u \cdot \log u$	$\log(\phi) + 1$	ϕ
Pearson χ^2	$(u - 1)^2$	$2 \cdot \phi - 2$	$\phi^2 - 1$
Squared Hellinger	$(\sqrt{u} - 1)^2$	$1 - \phi^{-1/2}$	$\phi^{1/2} - 1$
GAN	$u \cdot \log u - (u + 1) \cdot \log(u + 1)$	$-\log(1 + \phi^{-1})$	$\log(1 + \phi)$