000 001 002 003 RECURSIVE ABSTRACTIVE PROCESSING FOR RE-TRIEVAL IN DYNAMIC DATASETS

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ABSTRACT

Recent retrieval-augmented models enhance basic methods by building a hierarchical structure over retrieved text chunks through recursive embedding, clustering, and summarization. The most relevant information is then retrieved from both the original text and generated summaries. However, such approaches face limitations with dynamic datasets, where adding or removing documents over time complicates the updating of hierarchical representations formed through clustering. We propose a new algorithm to efficiently maintain the recursive-abstractive tree structure in dynamic datasets, without compromising performance. Additionally, we introduce a novel post-retrieval method that applies query-focused recursive abstractive processing to substantially improve context quality. Our method overcomes the limitations of other approaches by functioning as a black-box postretrieval layer compatible with any retrieval algorithm. Both algorithms are validated through extensive experiments on real-world datasets, demonstrating their effectiveness in handling dynamic data and improving retrieval performance.

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1 INTRODUCTION

028 029 030 031 032 033 034 035 036 037 038 Large Language Models (LLMs) have established themselves as powerful tools across a wide range of natural language processing (NLP) tasks, thanks to their ability to store vast amounts of factual knowledge within their parameters [\(Petroni et al., 2019;](#page-11-0) [Jiang et al., 2020\)](#page-10-0). These models can be further fine-tuned to specialize in specific tasks [\(Roberts et al., 2020\)](#page-11-1), making them highly versatile. However, a key limitation of LLMs lies in their static nature: as the world evolves and new information emerges, the knowledge encoded within an LLM can quickly become outdated. A promising alternative to relying solely on parametric knowledge is retrieval augmentation [\(Gao et al., 2023\)](#page-10-1). This approach involves the use of external retrieval systems to supply relevant information in realtime. Instead of encoding all knowledge directly into the model, large text corpora are indexed, segmented into manageable chunks, and dynamically retrieved as needed [\(Lewis et al., 2020;](#page-10-2) [Gao](#page-10-1) [et al., 2023\)](#page-10-1). Retrieval-augmented methods not only improve model accuracy but also offer a practical solution for maintaining performance as knowledge evolves over time.

039 040 041 042 043 044 045 046 However, retrieval-augmented approaches also have limitations. Many existing methods only retrieve short, specific chunks as context, which restricts the model's ability to answer questions requiring a broader understanding of the text. To address this, RAPTOR was introduced [\(Sarthi et al.,](#page-11-2) [2024\)](#page-11-2). It recursively embeds, clusters, and summarizes text chunks, enabling the retrieval of relevant information from both original document chunks and generated summaries. Yet, RAPTOR introduces new challenges, especially with dynamic datasets where documents are frequently added or removed. The clustering component makes the tree structure sensitive to these updates, requiring a full re-computation of the tree after each change, which is computationally expensive.

047 048 049 050 051 052 053 To address these limitations, we introduce adRAP (adaptive Recursive Abstractive Processing), an algorithm designed to efficiently update RAPTOR's recursive-abstractive structure as new documents are added or removed. By incrementally adjusting the structure, adRAP avoids full recomputation, preserving retrieval performance while significantly reducing computational overhead. Furthermore, both RAPTOR and adRAP introduce memory overhead and require periodic maintenance when used with dynamic datasets. As an alternative, we propose postQFRAP, a post-retrieval method that applies query-focused recursive abstractive processing as a black-box layer, as illustrated in Figure [1.](#page-1-0) This post-processing method integrates seamlessly into any retrieval pipeline

Figure 1: Retrieval pipeline with postQFRAP: we first retrieve from a dataset k_0 chunks relevant to the query, then we build a query-focused recursive-abstractive tree on those chunks. Finally, we summarize the contents of the root layer of that tree to get the context that is passed to the LLM.

068 069 070 071 072 073 074 075 while significantly enhancing the quality of the retrieved context. For example, naïve RAG [\(Gao](#page-10-1) [et al., 2023\)](#page-10-1) can serve as the underlying model since it processes documents independently, allowing easy addition or removal of documents. Moreover, by initially retrieving enough documents, questions requiring a broader understanding can be answered by passing the generated summary to the LLM, rather than passing all potentially relevant documents, thus mitigating challenges like limited context window size and information loss in large contexts [\(Liu et al., 2024;](#page-11-3) [Yu et al., 2024\)](#page-11-4). Through extensive experiments on real-world datasets, we demonstrate that adRAP provides a good approximation of the RAPTOR tree, while postQFRAP effectively enhances retrieval quality.

077 2 RELATED WORK

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079 080 081 082 083 084 085 086 Retrieval Algorithms In the context of LLMs, retrieval-augmented generation (RAG) involves retrieving relevant information from external sources and appending it to the LLM's context along-side the original query [\(Ram et al., 2023\)](#page-11-5). Naïve RAG methods [\(Gao et al., 2023\)](#page-10-1) address this challenge by converting documents into text, splitting it into chunks, and embedding these chunks in a vector space where semantically similar chunks are mapped to nearby vectors. The query is similarly embedded, and the k -nearest vectors are retrieved to augment the LLM's context. However, segmenting text into contiguous chunks may fail to capture its full semantic richness, and retrieving overly granular segments can overlook key information [\(Gao et al., 2023\)](#page-10-1).

087 088 089 090 091 092 The recursive-abstractive summarization method by [Wu et al.](#page-11-6) [\(2021\)](#page-11-6) addresses this issue by breaking down tasks to summarize smaller text segments, which are then integrated to form summaries of larger sections. While effective at capturing broader themes, it may miss finer details. RAPTOR [\(Sarthi et al., 2024\)](#page-11-2) improves on this technique by recursively grouping and summarizing similar chunks, retaining both summaries and initial chunks. This approach captures a representation of the text at multiple levels of detail while preserving inter-dependencies within the text.

093 094 095 096 097 098 099 100 101 Post-Retrieval Algorithms To optimize retrieval algorithms, post-retrieval strategies are commonly employed. These include re-ranking retrieved chunks and compressing the context [\(Gao](#page-10-1) [et al., 2023\)](#page-10-1), as large contexts fed directly into LLMs often result in information loss, particularly in the middle sections [\(Liu et al., 2024;](#page-11-3) [Yu et al., 2024\)](#page-11-4). The closest approach to our setting is the query-focused summarization algorithm by [Zhang et al.](#page-11-7) [\(2024\)](#page-11-7). They retrieve relevant documents which they also summarize using a prompt designed to extract key information before generating the summary. The latter is then passed as context to the LLM. In contrast, we construct a hierarchical tree over the retrieved documents, allowing us to recursively filter noise by focusing on smaller, manageable chunks at each step. This yields a more refined and relevant summary.

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- **103** 3 PRELIMINARIES
- **105** 3.1 CLUSTERING WITH GAUSSIAN MIXTURE MODELS (GMMS)
- **107** Gaussian Mixture Models assume that data points are generated from a mixture of multiple Gaussian distributions. They have two key advantages: they allow non-isotropic Gaussians, enabling varied

108 109 110 111 112 113 114 115 116 cluster shapes and orientations, and they support soft clustering, where a data point can belong to multiple clusters. Let K represent the number of clusters, and x_1, \ldots, x_n be the data points. Each cluster k is defined by its mean μ_k , covariance matrix Σ_k , and mixture weight π_k , which represents the prior probability of a data point belonging to cluster k . The probability density function (PDF) for a data point x is given by $p(x) = \sum_{k=1}^{K} \pi_k \mathcal{N}(x|\mu_k, \Sigma_k)$ where $\mathcal{N}(x_i|\mu_k, \Sigma_k)$ is PDF of a multivariate normal distribution with mean μ_k and covariance Σ_k . The cluster parameters are learned by maximizing the log-likelihood using the Expectation-Maximization (EM) algorithm [\(Moon, 1996\)](#page-11-8), which iterates the two following steps until convergence, i.e., when the change in log-likelihood between consecutive iterations becomes negligibly small.

Expectation step: Compute the posterior probability (responsibility) that the k-th Gaussian component generated the data point x_i :

$$
\gamma(z_{ik}) = \frac{\pi_k \mathcal{N}(x_i | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_i | \mu_j, \Sigma_j)},\tag{1}
$$

Maximization step: Update the parameters π_k , μ_k , and Σ_k by maximizing the expected loglikelihood given the responsibilities:

$$
\pi_k = \frac{1}{n} \sum_{i=1}^n \gamma(z_{ik}), \quad \mu_k = \frac{\sum_{i=1}^n \gamma(z_{ik}) x_i}{\sum_{i=1}^n \gamma(z_{ik})}, \quad \Sigma_k = \frac{\sum_{i=1}^n \gamma(z_{ik}) (x_i - \mu_k)(x_i - \mu_k)^\top}{\sum_{i=1}^n \gamma(z_{ik})} \tag{2}
$$

3.2 DIMENSIONALITY REDUCTION WITH UMAP

130 131 132 133 134 135 Clustering algorithms often struggle with the curse of dimensionality, where data becomes sparse, and distances between points lose distinction in high dimensions. To address this, Uniform Manifold Approximation and Projection (UMAP) [\(McInnes et al., 2018\)](#page-11-9) reduces the dimensionality of embeddings, significantly enhancing clustering performance [\(Allaoui et al., 2020\)](#page-10-3). UMAP learns a low-dimensional representation that preserves both local and global structures, with the key parameter *n neighbors* controlling the trade-off between local and global structure preservation.

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3.3 RECURSIVE-ABSTRACTIVE TREE CONSTRUCTION

138 139 140 141 The process of building the recursive-abstractive tree is outlined first, as it is key to understanding our new algorithms. The construction, based on [Sarthi et al.](#page-11-2) [\(2024\)](#page-11-2) with minor adjustments, consists of four steps: dataset chunking, clustering, summarizing, and recursive construction.

142 143 144 145 146 147 Dataset Chunking Given a dataset, the first step is to divide the text into sentences using the NLTK Punkt Sentence Tokenizer^{[1](#page-2-0)}. These sentences are then grouped into chunks of up to 250 tokens, with a 50-token overlap between consecutive chunks, resulting in chunks of up to 300 tokens. To maintain coherence, sentences are kept intact between chunks: if a sentence exceeds 250 tokens, it is included in the next chunk. Sentences longer than 250 tokens are split at punctuation marks. Token counts are determined using the cl100k_base tokenizer from the $\texttt{tiktoken}^2$ $\texttt{tiktoken}^2$ library.

148 149 150 Note that we use 250 tokens with a 50-token overlap instead of the 100-token chunks used by [\(Sarthi](#page-11-2) [et al., 2024\)](#page-11-2). Preliminary experiments (not included in this work) suggest that the larger chunk size with overlap improves output quality.

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152 153 154 155 156 157 Clustering The goal is to group n chunks c_1, \ldots, c_n into k clusters C_1, \ldots, C_k , where k is to be determined. Clustering is performed on the embeddings, not the raw text. So, using an encoder model, embeddings v_1, \ldots, v_n are generated for the chunks. Then, dimensionality reduction is performed using UMAP, followed by clustering with Gaussian Mixture Models (GMMs). This process is repeated twice, varying UMAP's *n neighbors* parameter to create a hierarchical clustering, an approach shown to be effective for this task [\(Sarthi et al., 2024\)](#page-11-2).

158 159 First, *n_neighbors* is set to \sqrt{n} , generating 10-dimensional embeddings v_1^g, \ldots, v_n^g . GMMs are then applied, yielding global clusters $C_1^g, \ldots, C_{k_g}^g$. Next, refinement occurs within each global cluster.

¹<https://www.nltk.org/api/nltk.tokenize.punkt.html>

²<https://github.com/openai/tiktoken>

162 163 164 165 166 UMAP is applied with *n_neighbors* set to 10, resulting in reduced embeddings v_1^l, \ldots, v_m^l , where m is the size of the current global cluster. GMMs are then used to form local clusters $C_1^l, \ldots, C_{k_l}^l$. The final clustering is the union of all local clusters. To determine k_g , values from 1 to $\max(50, \sqrt{n})$ are evaluated, and we select the value that minimizes the Bayesian Information Criterion (BIC) [\(Schwarz, 1978\)](#page-11-10). A similar approach is used to determine k_l .

168 169 170 171 Summarizing After clustering, a large language model generates summaries for each cluster, providing a concise overview of the content. The summary length is limited to 1,000 tokens to ensure the summaries remain manageable. The specific prompt used for summarization is provided in the appendix (Table [4\)](#page-18-0).

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173 174 Recursive Construction The clustering and summarization process is repeated recursively to obtain a multi-layered representation of the dataset. This approach is outlined in Algorithm [1.](#page-3-0)

- **175 176** Algorithm 1 Recursive-Abstractive Tree Construction
	- 1: Input: Dataset
		- 2: Output: Recursive-Abstractive Tree
	- 3: Chunk the dataset, initializing the leaf nodes as these chunks.
	- 4: while the top layer contains more than 10 nodes and there are fewer than 5 layers do
	- 5: Compute embeddings for the nodes in the top layer.
	- 6: Apply the two-step clustering process to group these nodes.
	- 7: Generate a summary for each cluster.
	- 8: Form a new layer with one new node per cluster.
- **184 185** 9: end while
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3.4 RETRIEVING DOCUMENTS

189 190 191 192 Given a query and a tree constructed over a relevant dataset, the goal is to retrieve k documents that are helpful in answering the query. [Sarthi et al.](#page-11-2) [\(2024\)](#page-11-2) compared tree-based retrieval with a collapsed-tree approach, where all nodes are considered simultaneously. The latter performed better, and is the method used in our experiments.

193 194 195 196 In the collapsed-tree approach, the tree is flattened, and the k most similar documents are retrieved using cosine similarity on the embeddings. This method can be seen as augmenting the dataset with document summaries, followed by applying naïve RAG to the expanded dataset. The pseudo-code for the retrieval algorithm is provided in Appendix [A.](#page-12-0)

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4 ADRAP: ADAPTIVE RECURSIVE-ABSTRACTIVE PROCESSING

4.1 OVERVIEW

202 203 204 205 The problem we are addressing can be formally described as follows. Let T_0 represent a recursiveabstractive tree built on an initial dataset D_0 . Given an updated dataset $D = D_0 \cup D_1$, where $|D_0| \gg$ $|D_1|$, let T be the tree constructed over D. The goal is to efficiently update T_0 to approximate T without fully recomputing the tree on D.

206 207 208 209 To achieve this, UMAP is used to reduce the dimensionality of the new documents, which are then assigned to clusters, potentially updating the existing clustering. We first examine these components individually, then explain how they are combined to create a dynamic data structure.

210 211 4.2 ADAPTIVE UMAP

212 213 214 215 Let $d \in D_1$ be a new document with embedding v. The first step is to reduce the dimensionality of v to 10. To do this, we find the n_neighbors nearest neighbors of v in the original high-dimensional space and interpolate their positions in the previously learned low-dimensional embedding to obtain the reduced embedding v' . This preserves the local relationships of v with its neighbors, maintaining the structure learned during fitting. Given $|D_0| \gg |D_1|$, we assume this property holds for all new

216 217 218 documents. This process requires storing the fitted UMAP models (both global and local) with our tree. We use the UMAP-learn^{[3](#page-4-0)} library for UMAP fitting and dynamic transformations.

4.3 ADAPTIVE GMM

221 222 223 224 225 226 227 228 229 A key component of the recursive-abstractive tree construction (Algorithm [1\)](#page-3-0) is its clustering algorithm, which poses challenges when handling dynamic datasets. Given a fitted Gaussian Mixture Model (GMM) *I* with *K* clusters defined by their means $\{\mu_k\}_{k=1}^K$, covariance matrices $\{\Sigma_k\}_{k=1}^K$, and mixing coefficients $\{\pi_k\}_{k=1}^K$, and given points $\{x_i\}_{i=1}^n$ assigned to these clusters, the goal is to assign a new point x_{n+1} to one or more clusters. This may involve updating the clustering structure or introducing new clusters. While prior work addresses online GMMs [\(Song & Wang, 2005;](#page-11-11) [Declercq & Piater, 2008;](#page-10-4) [Zhang & Scordilis, 2008\)](#page-11-12), our setting differs in that we start with a GMM fit on a dataset, we have access to all the points and we want to minimize the number of updated clusters, as each update requires multiple re-generated summaries.

230 231 232 First, assume n is large, i.e., many points have already been clustered. Given a new point x_{n+1} , we compute its posterior probability $\gamma(z_{n+1,k})$ for $k \in [K]$, and approximate the maximization step by updating the parameters with the new point's contribution as follows:

$$
\mu_k \leftarrow \frac{n\pi_k\mu_k + \gamma(z_{n+1,k})x_{n+1}}{n\pi_k + \gamma(z_{n+1,k})}, \quad \Sigma_k \leftarrow \frac{n\pi_k\Sigma_k + \gamma(z_{n+1,k})(x_{n+1} - \mu_k)(x_{n+1} - \mu_k)^\top}{n\pi_k + \gamma(z_{n+1,k})}
$$
\n
$$
\pi_k \leftarrow \frac{n\pi_k + \gamma(z_{n+1,k})}{n\pi_k + \gamma(z_{n+1,k})} \tag{3}
$$

 $n+1$

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\frac{236}{237}
$$

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239 240 242 243 245 246 The updated parameters match those from applying Equation [2](#page-2-2) to the points ${x_i}_{i=1}^{n+1}$. After updating the cluster parameters, we recompute the posterior for x_{n+1} and assign it to clusters ${k : \gamma(z_{n+1,k}) > 0.1}$, without affecting other point assignments. Although this remains an approximation, it has been shown to be an effective way to incrementally fit a GMM [\(Neal & Hinton,](#page-11-13) [1998\)](#page-11-13). The update is efficient, as its time is independent of n , with only a few clusters being updated (those assigned to x_{n+1}). When n is small, we perform full EM steps instead of updating using only the new point, as the smaller number of clusters makes this affordable. This also yields more significant improvements, as clusterings with fewer points are more sensitive to new data.

247 248 249 250 251 252 253 254 At this stage, an issue may arise as the number of clusters k remains fixed, whether we use approximate or full EM steps. If points are repeatedly added to the same cluster, it may grow too large, causing a node at layer 1 to resemble one at layer 3, which undermines the hierarchical structure. To address large clusters, we attempt to split them, thereby increasing k . The splitting approach varies with n. For large n , we focus on the large clusters independently of other clusters. We attempt to subdivide these large clusters by applying a GMM to them with $k' = 1, 2, 3$ subclusters, and we select the best model according to the Bayesian Information Criterion (BIC). This method has a runtime independent of n , and at most 3 clusters are updated or created. For small n , we explore larger values of k and fit a new GMM from scratch, selecting the k that optimizes the BIC.

255 256 257 258 We summarize these ideas in Algorithm [2.](#page-5-0) The parameter τ_n controls the trade-off between quality and computation time, determining whether to perform full or approximate EM updates based on n . Similarly, τ_c sets the cluster size threshold for triggering a potential split.

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4.4 ADRAP ALGORITHM

261 262 263 The process starts with an initial tree T_0 and a new data chunk $d \in D_1$. First, d's embedding v is computed, and a corresponding leaf node is created in T_0 . The first layer above the leaves (call it layer 1) is then updated to account for the new node.

264 265 266 267 268 To do so, the global reduced embedding v_q is derived from v using the global UMAP model and assigned to the most probable cluster in the global clustering. Since the global clustering includes all $|D_0|$ nodes, it is considered stable and no dynamic adjustments are made. Next, we focus on the global cluster to which v_q was assigned, applying the local UMAP model to compute a reduced local embedding v_l . The local clustering is updated using Algorithm [2,](#page-5-0) potentially creating new nodes.

³<https://umap-learn.readthedocs.io/en/latest/>

In T_0 , nodes with updated children regenerate their summaries and recompute embeddings, with updates propagated to their ancestors (up to five levels). If new clusters are created at layer i , this procedure is recursively applied at layer $i + 1$. By design, only a few clusters are affected, minimizing the need for summary re-computation. To illustrate this, we compare in Appendix [H.2](#page-20-0) the runtime and number of generated summaries between adRAP and a full re-computation of the tree. Moreover, the pseudo-code of adRAP is presented in Appendix [A.](#page-12-0)

291 292 293 294 Though we focused on adding documents, the algorithm easily handles deletions by removing the chunk from the tree and recomputing summaries for its ancestors. For frequent deletions, one can either recompute the local clustering by trying smaller values for K or leave the clusters unchanged.

5 POSTQFRAP: POST-RETRIEVAL QUERY-FOCUSED RECURSIVE-ABSTRACTIVE PROCESSING

5.1 MOTIVATION

301 302 303 304 Maintaining adRAP is costly, as it requires updating clusters and summaries with each new document. Moreover, when many documents are added, the entire tree has to be recomputed to maintain solution quality. Integrating this system poses significant development challenges, and companies with established retrieval algorithms may be hesitant to adopt a completely new system.

305 306 307 308 To address this, we propose a modified version of the recursive-abstractive tree as a black-box postretrieval solution that can be integrated with retrieval algorithms handling dynamic datasets (e.g., naïve RAG). This approach enhances the initial construction by incorporating query-focused summaries, improving the context relevance of the output.

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5.2 POSTQFRAP ALGORITHM

311 312 313 Let R be a retrieval algorithm that takes as input an integer $k \in \mathbb{N}^+$ and a query q, and returns k documents relevant to the query. A simple example is the naïve RAG algorithm [\(Gao et al., 2023\)](#page-10-1).

314 315 316 317 318 319 320 321 322 We augment R as follows. First, we retrieve k_0 documents without imposing a token limit. Then, we apply a query-focused version of Algorithm [1](#page-3-0) to these k_0 documents to build a recursive-abstractive tree. The key modification is using query-focused summarization (see prompt in Appendix, Table [5\)](#page-18-1). Since the tree is constructed to answer q, summarizing information relevant to q ensures that key details are preserved while recursively filtering out irrelevant content. Additionally, we modify the clustering to rely solely on local embeddings, as retrieving k_0 documents already serves as a global filtering step. In other words, we assume the retrieved documents belong to the same global cluster. We demonstrate in Appendix [B](#page-12-1) that using the simpler one-step clustering preserves the quality of the generated context compared to the two-step approach.

323 Finally, a summarization step is applied to all nodes at the last layer of the tree, instead of using a top-k retrieval approach, to reduce redundancy in the results. This process is detailed in Algorithm [3.](#page-6-0)

377 To evaluate our algorithms, we use two methods: a rating-based evaluation, providing a score for each model independently, and a head-to-head comparison. Since the model is restricted to using **378 379 380 381 382 383** only the retrieved context, measuring faithfulness is unnecessary. Instead, we focus on ensuring the context provides sufficient information to answer the question. Thus, we compute the proportion of answered questions and measure context relevance [\(Es et al., 2023\)](#page-10-6). The latter acts as context precision, while the former is analogous to context recall, as it checks whether the necessary chunks are retrieved. However, we avoid using context recall directly, as it is difficult to formally define with summarized chunks.

384 385 386 387 388 389 Some generated answers may lack coherence, either in their internal structure or in relation to the question. Providing summarized content as context may help the model generate more coherent responses. To evaluate this, we introduce a novel metric called Human Coherence Rating, which prompts an LLM to assess whether an answer is coherent and resembles one that could plausibly be generated by a human expert. The specific prompt used for this evaluation is shown in the appendix (Table [6\)](#page-18-2), with a qualitative analysis of the metric provided in Appendix [C.](#page-14-0)

390 391 392 393 394 395 396 397 To gain deeper insights into our algorithms, we conduct a head-to-head evaluation. Given our focus on questions requiring a global understanding, we adopt the evaluation metrics from [Edge et al.](#page-10-7) [\(2024\)](#page-10-7), which assess comprehensiveness, diversity, empowerment, and directness. For each comparison, the evaluator LLM is given the question, a prompt describing the target metric, and two answers. The LLM evaluates which answer is superior or if it is a tie, providing a rationale for its decision. To mitigate position bias [\(Zheng et al., 2024\)](#page-11-17), the evaluation is repeated for each pair of answers with their positions swapped. If the same answer wins both trials, it is declared the winner; otherwise, the result is a tie.

- **398** We also conduct a qualitative analysis of postQFRAP, detailed in Appendix [D.](#page-14-1)
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6.3 HYPERPARAMETER SELECTION

403 404 405 406 A key hyperparameter to consider is the context size, or equivalently, the number of documents to retrieve. [Sarthi et al.](#page-11-2) [\(2024\)](#page-11-2) evaluated different context lengths on a subset of the QASPER dataset, finding that 2,000 output tokens yielded the best results. Based on this, we set the output context size to 2,000 tokens for all algorithms unless stated otherwise.

407 408 409 410 To select k_0 for the postQFRAP algorithm, we compare different values on two validation datasets. We choose $k_0 = 20$, as larger values increase computational complexity without significant quality gains, while smaller values substantially reduce context relevance. Details of this study are provided in Appendix [E.](#page-15-0)

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6.4 BASELINES

414 415 416 417 418 419 420 We compare the adRAP algorithm against Naïve RAG, RAPTOR, and a greedy variant of adRAP, which assigns each new point to its most probable cluster without updating the GMM fit. To compute adRAP, we first construct a full tree using 70% of the dataset. The remaining 30% is added using the adRAP algorithm (Section [4.4\)](#page-4-1) where we set $\tau_c = 11$ and $\tau_n = \max(100, \sqrt{|D_0|})$ for Algorithm [2.](#page-5-0) The choice of τ_c is based on the average cluster size in the full RAPTOR tree, which is always less than 10 (see appendix, Table [12\)](#page-22-1). For the greedy variant, a similar procedure is used. To simulate a challenging scenario, we remove the last 30% of documents instead of random sampling.

421 422 423 424 425 426 427 We compare postQFRAP with other post-retrieval methods: no processing (naïve RAG) with $k = 7, 20$ retrieved documents, one-shot summarization, re-ranking, and postRAP. One-shot summarization uses the controller from [Zhang et al.](#page-11-7) [\(2024\)](#page-11-7) to directly generate 2,000 tokens (see prompt in Appendix, Table [8\)](#page-19-1). For re-ranking, we use the ms-marco-MiniLM-L-12-v2^{[4](#page-7-0)} cross-encoder from HuggingFace, retrieving 20 documents via naïve RAG, then re-ranking them to keep the top 7. Finally, postRAP is a variant of postQFRAP without query-focused summarization which retrieves the top-k most similar chunks from the tree built on the k_0 chunks.

428 429 We also tried adding query expansion [\(Jagerman et al., 2023\)](#page-10-8) to our postQFRAP algorithm, but this barely affected the results. So, we report the details of those experiments in Appendix [F.](#page-16-0)

⁴<https://huggingface.co/cross-encoder/ms-marco-MiniLM-L-12-v2>

432 433 434 435 We use OpenAI's text-embedding-3-large^{[5](#page-8-0)} for embeddings and $gpt-4$ o-mini-2024-07-18^{[6](#page-8-1)} for all LLM tasks. All retrieval algorithms use a chunk size of 300 tokens with a 50-token overlap. To account for the non-determinism of LLM evaluators, we repeat each experiment three times, reporting the average and standard error.

6.5 RESULTS

Figure [2](#page-8-2) shows that adRAP's performance is generally on par with RAPTOR across most metrics, with the exception of context relevance, where adRAP falls short by at least 3%. However, adRAP outperforms both the naïve RAG and the greedy algorithm, particularly in the QuALITY dataset. These findings are further corroborated by the head-to-head evaluations in Figures [3,](#page-8-3) [4,](#page-8-4) and [5.](#page-8-5) Notably, in the QuALITY dataset, adRAP exceeds RAPTOR in metrics such as comprehensiveness, diversity, and empowerment, despite its lower performance in context relevance. On the other hand, adRAP underperforms compared to RAPTOR in the MultiHop and QASPER datasets.

approaches across all metrics. While one-shot summarization scores slightly higher in answered questions and human coherence, postQFRAP excels in context relevance, demonstrating the effectiveness of recursive summarization in filtering noise from input chunks. The superiority of postQFRAP as a post-retrieval algorithm becomes apparent in head-to-head evaluations. As shown in Figures [7,](#page-9-1) [8,](#page-9-2) and [9,](#page-9-3) postQFRAP excels in comprehensiveness, diversity, and empowerment. The lower directness scores are expected, as directness often contrasts with these qualities, as noted by [Edge et al.](#page-10-7) [\(2024\)](#page-10-7). Overall, postQFRAP's recursive extraction produces a more diverse, comprehensive, and empowering context, enhancing the quality of the final answer.

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⁵<https://platform.openai.com/docs/guides/embeddings> ⁶<https://platform.openai.com/docs/models/gpt-4o-mini>

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32.6	60.4	20.0 17 . U	72.3		25.1	66.8	l8.:		90.3		One Shot Summarize
	80.9	19.0	69.7	29.8	69.7		29.8	18.9	66.2	14.9	postRAP
	95.2	-8	94.7			92.2		24.8	44.1	31.1	Naive RAG $k = 20$
	94.1	58	90.7	9.6		91.2	8.6	25.1	41.0	33.9	reRanker
	93.9	6.1	92.2	7.8		90.7	9.0	24.4	41.4	34.1	Naive RAG $k = 7$
Comprehensiveness			Diversity			Empowerment	Directness				

Figure 9: Percentage of Wins, Ties and Losses for postQFRAP vs other algorithms on QuALITY.

7 LIMITATIONS

While adRAP is more efficient than repeatedly recomputing the full RAPTOR tree for dynamic datasets, it introduces some overhead. It requires extra memory to store multiple UMAP and GMM models and adds complexity to the retrieval pipeline, as it must be triggered when new documents are added. Additionally, a full tree recomputation may still be needed if a large volume of new documents is introduced, increasing implementation effort. With postQFRAP, generated summaries can make it harder to trace original sources. Additionally, multiple summarization calls are required during inference, although this follows the current trend of shifting more computational workload to inference time, as seen with OpenAI's o1 model [\(OpenAI, 2024;](#page-11-18) [Brown et al., 2024\)](#page-10-9).

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8 CONCLUSION

533 534 535 536 In this paper, we introduced adRAP, an adaptive extension of the RAPTOR algorithm, designed to efficiently approximate clustering when documents are added or removed. Our experiments show that adRAP performs comparably to RAPTOR, making it a viable solution for dynamic datasets.

537 538 539 We also presented postQFRAP, a novel post-retrieval algorithm that applies query-focused, recursive-abstractive processing to refine large contexts. By filtering out irrelevant information, postQFRAP produces highly relevant summaries. Our results demonstrate that postQFRAP consistently outperforms traditional methods, proving its effectiveness for post-retrieval processing.

540 541 9 REPRODUCIBILITY STATEMENT

544 Language Model Used Open AI's $gpt-4o-mini-2024-07-18^7$ $gpt-4o-mini-2024-07-18^7$ $gpt-4o-mini-2024-07-18^7$ is used for both question answering and summarization in all our experiments. Open AI's text-embedding-3-large^{[8](#page-10-11)} is used to generate embeddings.

Prompts All used prompts are presented in Appendix [G.](#page-18-3)

Hyperparameters All hyperparameters and model configurations used in the experiments are clearly detailed in Sections [6.3](#page-7-1) and [6.4.](#page-7-2)

Datasets All four datasets used in our experiments are publicly available: [MultiHop,](https://github.com/yixuantt/MultiHop-RAG) [NarrativeQA,](https://github.com/google-deepmind/narrativeqa) [QuALITY,](https://github.com/nyu-mll/quality) and [QASPER.](https://allenai.org/data/qasper) Details of the preprocessing steps are provided in Appendix [H.5.](#page-22-2)

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⁷<https://platform.openai.com/docs/models/gpt-4o-mini>

⁸<https://platform.openai.com/docs/guides/embeddings>

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756 757 C QUALITATIVE ANALYSIS OF HUMAN COHERENCE RATING

To qualitatively analyze the newly proposed Human Coherence Rating, we consider an example of a question from the MultiHop dataset where using na¨ıve RAG led to a low rating. The results are summarized in Table [1.](#page-14-2)

Table 1: Comparison of Human Coherence Ratings for generated answers to a MultiHop dataset question, evaluating the performance of Naïve RAG versus postQFRAP models.

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D QUALITATIVE ANALYSIS OF POSTQFRAP

To qualitatively analyze the postQFRAP algorithm, we examine a question from the MultiHop dataset. Table [2](#page-14-3) presents the contexts and answers generated by postQFRAP and naïve RAG. The context produced by naïve RAG is scattered and often irrelevant to the question, causing the QA model to fail in providing an answer. In contrast, postQFRAP generates a coherent and highly relevant context, resulting in significant portions of the final answer being directly extracted from this context.

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E SELECTION OF k_0 for postQFRAP

To determine the optimal value of k_0 for our main experiments, we evaluated five different values, $k_0 \in \{10, 20, 40, 60, 80\}$, by comparing the performance on 100 questions from the validation **864 865 866 867 868 869** sets of the NarrativeQA and QASPER datasets. It is important to emphasize that these questions are entirely distinct from the data used in our main experiments. As in our primary experiments, we limited the final summary size to 2,000 tokens and considered three metrics: the number of answered questions, context relevance, and human coherence. To account for the non-deterministic nature of the LLM evaluators, we repeated the evaluation process three times and reported the average performance along with the standard error in Figure [12.](#page-16-1)

870 871 872 As expected, context relevance increases with higher k_0 values, as including more documents allows additional potentially relevant content to be retained while ensuring irrelevant content is excluded from the summaries.

873 874 875 876 877 878 In both validation sets, we observe that the fraction of answered questions and human coherence peaks at $k_0 = 20$. Although $k_0 \in \{60, 80\}$ provides higher context relevance compared to $k_0 = 20$, we select $k_0 = 20$ for our experiments as it optimizes the number of answered questions and human coherence without sacrificing too much context relevance. Additionally, this choice ensures a more efficient post-retrieval process compared to larger values.

Figure 12: Comparison of different values of k_0 for the postQFRAP algorithm on NarrativeQA and QASPER validation sets.

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F QUERY EXPANSION

A possible extension to the postQFRAP algorithm is to first expand the query q before retrieving k_0 initial documents. This would lead to broader documents being retrieved before the clusteringsummarization process, potentially leading to an improved context.

To test this approach, we use the query expansion algorithm from [\(Jagerman et al., 2023\)](#page-10-8) with the Q2E/PRF prompt. It consists of first retrieving the top-3 documents using naïve RAG. Then, we ask an LLM to extract key words from those documents relevant to the question. We append those to the query that is duplicated 5 times to get the augmented query q' :

$$
q' = \text{Concat}(q, q, q, q, q, \text{LLM}(\text{prompt}_q))
$$

908 909 910 where $LLM(prompt_q)$ is the output of the Q2E/PRF prompt. The latter is found in Table [9.](#page-19-2) Then we use postQFRAP as before, by replacing q with the augmented query q' .

911 912 913 914 We use this particular query expansion algorithm instead of the simpler Q2D/ZS algorithm that just asks an LLM to answer the query and use that answer as a new query because we do not want to exploit the LLM's parametric knowledge. Instead, we ground the extension on the retrieved documents.

915 916 917 We present the results in Figures [13](#page-17-0) and [14.](#page-17-1) We observe that adding Query Expansion to postQFRAP does not improve performance and, in fact, reduces the comprehensiveness and coherence of the generated answers.

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Table 4: Prompt for Text Summarization

Table 5: Prompt for Query-Focused Text Summarization

Table 6: Prompt for Computing Human Coherence Rating

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1080 1081 H DETAILED EXPERIMENTS

1082 1083 H.1 COMPUTING RESOURCES

1084 1085 We implement our algorithms in Python 3.10 and run our experiments on a standard laptop with 16GB of RAM and 12th Gen Intel(R) Core(TM) i7-1250U CPU.

1087 H.2 ADRAP RUNTIME

We present in Table [10](#page-20-3) the time taken and the number of summary calls made on each of the QASPER and QuALITY dataset for two different algorithms:

- Build the full tree on the first 70% of the dataset, then use the adRAP algorithm to add the remaining 30%.
- • Build the full tree on the first 70% of the dataset, then re-compute the full tree from scratch on the full dataset.

1096 1097 1098 1099 Table 10: Comparison of time taken and the number of summary calls between building a tree on 70% of the dataset followed by adRAP, and computing the full tree twice: once on 70% of the dataset and again on the entire dataset.

1104 1105 1106 It is clear that using adRAP requires significantly less time and fewer summary calls compared to re-computing the full tree, even when the latter is done only once. If the full tree were to be re-computed each time a new document is added, the difference would become substantially larger.

1107 1108 H.3 GENERATING QUESTIONS

1109 1110 1111 1112 1113 1114 1115 To create more challenging questions that require a broader understanding of the dataset, we take the following approach. First, we construct a RAPTOR tree on top of the dataset. Then, to generate a new question, we sample a node from the tree and prompt a LLM to create a question based on the text from that node. We provide the LLM a few high quality questions to improve its output. The key idea is that some RAPTOR nodes contain summaries of various chunks, meaning the generated question requires synthesizing and summarizing information from different documents to be answered. The prompt used for generating these questions can be found in Table [3.](#page-18-4)

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1117 H.4 ADDITIONAL DATASET: *NarrativeQA*

1118 1119 1120 1121 *NarrativeQA* consists of complete stories and questions designed to assess a deep, comprehensive understanding of the narratives (Kočiský et al., 2017). From this dataset, we select the first 300 questions along with their corresponding documents.

1122 1123 Figures [15](#page-21-0) and [16](#page-21-1) show that, on the NarrativeQA dataset, adRAP performs comparably to RAPTOR and Greedy adRAP, while consistently outperforming Naïve RAG.

1124 1125 1126 1127 Figure [17](#page-21-2) demonstrates that query-focused algorithms clearly outperform the baselines on the NarrativeQA dataset. Notably, postQFRAP and one-shot summarization achieve comparable results. However, as shown in Figure [18,](#page-21-3) postQFRAP continues to significantly outperform all other algorithms in terms of comprehensiveness, diversity, and empowerment of the generated answers.

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 H.5 DATASET PREPROCESSING

 For datasets with HTML symbols (NarrativeQA and QuALITY), we use the BeautifulSoup ^{[9](#page-22-3)} library to convert them to text. For all datasets, we standardize the formatting by cleaning new lines, ensuring that only two new lines separate different paragraphs.

H.6 DATASETS STATISTICS

 In Table [11,](#page-22-4) we present the sizes of the datasets used in our experiments. In Table [12,](#page-22-1) we present various statistics regarding the recursive-abstractive trees constructed from our datasets. The number of internal nodes is approximately $n/6$, where n represents the total number of chunks in the dataset. Additionally, most cluster sizes range between 4 and 15, with nodes rarely belonging to more than one cluster.

