

KLoB: a Benchmark for Assessing Knowledge Locating Methods in Language Models

Anonymous ACL submission

Abstract

001 Recently, Locate-Then-Edit paradigm has
002 emerged as one of the main approaches in
003 changing factual knowledge stored in the Lan-
004 guage models. However, there is a lack of re-
005 search on whether present locating methods
006 can pinpoint the exact parameters embedding
007 the desired knowledge. Moreover, although
008 many researchers have questioned the valid-
009 ity of locality hypothesis of factual knowl-
010 edge, no method is provided to test the a hypothe-
011 sis for more in-depth discussion and research.
012 Therefore, we introduce KLoB, a benchmark
013 examining three essential properties that a reli-
014 able knowledge locating method should sat-
015 isfy. KLoB can serve as a benchmark for
016 evaluating existing locating methods in lan-
017 guage models, and can contribute a method
018 to reassessing the validity of locality hypothe-
019 sis of factual knowledge. KLoB is publicly
020 available at an anonymous GitHub: <https://github.com/anon6662/KLoB>.
021

022 1 Introduction

023 Language models have exhibited a significant ca-
024 pability to store factual knowledge (Roberts et al.,
025 2020). Yet, as language models scale larger, the
026 need to uphold the correctness and contemporane-
027 ity of stored knowledge becomes increasingly criti-
028 cal (Sinitsin et al., 2020), thus sparking a new area
029 of research: knowledge editing. Among current
030 knowledge editing techniques, **Locate-Then-Edit**
031 paradigm (Dai et al., 2022; Meng et al., 2022a,b;
032 Li et al., 2023) has emerged as one of the main
033 approaches and garnered significant attention (Yao
034 et al., 2023).

035 As depicted in Figure 1, by first locating pa-
036 rameters associated with specific knowledge and
037 modifying while keeping the remaining parameters
038 unchanged, Locate-Then-Edit methods can facili-
039 tate alterations to the model with very low cost (Yao
040 et al., 2023). However, there is currently no method

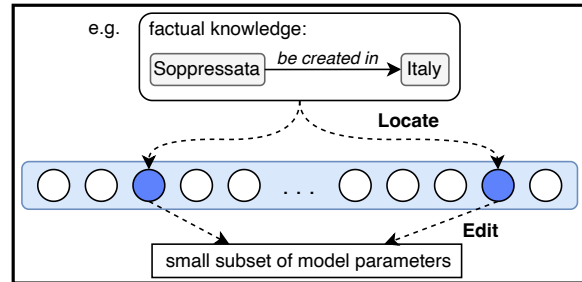


Figure 1: Illustration of Locate-Then-Edit method.

041 for evaluating the locating results. It’s still ambigu-
042 ous whether current locating methods can pinpoint
043 the exact parameters embedding the desired knowl-
044 edge. Moreover, the **locality hypothesis of factual**
045 **knowledge**, which posits that factual knowledge is
046 predominantly embedded within a small subset of
047 parameters, has encountered a degree of skepticism
048 and warrants further investigation. Yet, there’s a
049 noticeable absence of established methods to study
050 and validate this concern.

051 Therefore, we introduce KLoB (**K**nowledge
052 **L**ocating **B**enchmark), a novel benchmark for eval-
053 uating locating methods in language models. KLoB
054 delineates three essential criteria that a reliable
055 knowledge locating method should satisfy and then
056 evaluates the efficacy of locating methods by ex-
057 amining these criteria. The delineated criteria are
058 as follows:

- 059 • **Consistency:** Locating results should remain
060 consistent across different expressions of the
061 same factual knowledge.
- 062 • **Relevance:** Locating results for related fac-
063 tual knowledge should exhibit higher similar-
064 ity than those for unrelated knowledge.
- 065 • **Unbiasedness:** Parameter scores should be
066 more uniform for inputs lacking explicit fac-
067 tual knowledge than those for inputs with ex-
068 plicit knowledge.

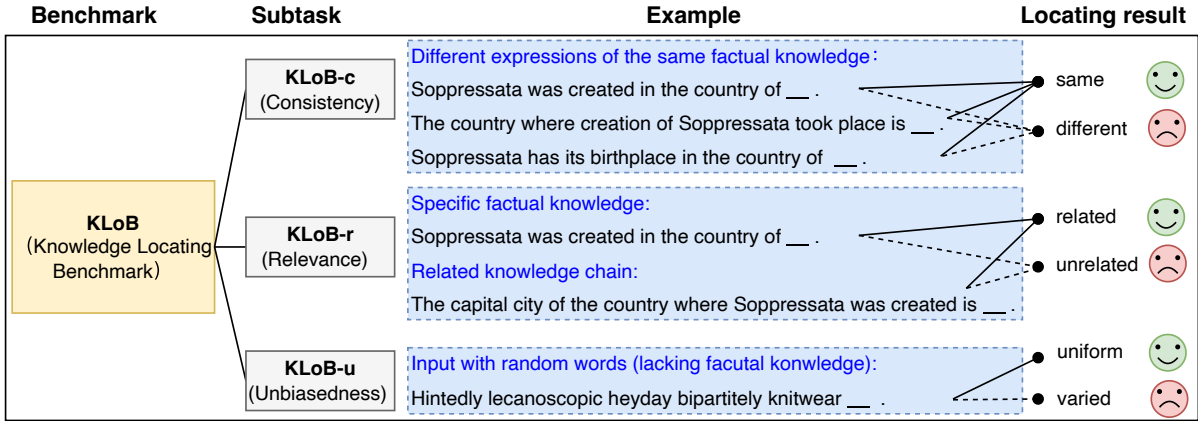


Figure 2: Examples of three subtasks in KLoB. KLoB-c: Each example comprises multiple expressions of the same factual knowledge; KLoB-r: Each example includes a sentence with specific factual knowledge and another with a related knowledge chain; KLoB-u: Each example features a sentence composed of random words.

As illustrated in Figure 2, the KLoB benchmark comprises three subtasks, each examining one of the aforementioned criteria. As the first benchmark for evaluating knowledge locating methods in language models, KLoB can play a crucial role in facilitating a comprehensive evaluation of whether current locating methods can accurately pinpoint model parameters associated with specific factual knowledge. Furthermore, KLoB can also contribute a method to study and reassess the validity of the locality hypothesis of factual knowledge.

2 Preliminary

2.1 Knowledge Editing

The factual knowledge embedded within a language model can be incorrect or become outdated over time. Knowledge editing aims to hold the correctness and contemporaneity of factual knowledge, without incurring excessive retraining costs. Current knowledge editing methods can be mainly categorized into three ways (Yao et al., 2023):

- **Locate-Then-Edit:** Locating and modifying model parameters that are associated with specific knowledge (Dai et al., 2022; Meng et al., 2022a,b; Li et al., 2023).
- **Meta-learning:** Utilizing a hyper network to learn how to change parameters of a language model (De Cao et al., 2021; Mitchell et al., 2021).
- **Memory Model:** Storing edits in an additional model while keeping the original model frozen (Mitchell et al., 2022; Huang et al., 2023b; Dong et al., 2022).

2.2 Locate-Then-Edit Method

Based on the locality hypothesis of factual knowledge, which posits that knowledge is primarily embedded within a subset of the model’s parameters, Locate-Then-Edit methods operate in a pipeline manner: first locate a small subset of model parameters, which are associated with specific knowledge, and then modify those parameters. Because Locate-Then-Edit methods only change the located parameters while keeping the rest unchanged, they can effectively modify the model in a more targeted manner and have garnered significant attention.

3 KLoB: Knowledge Locating Benchmark

3.1 Design Philosophy

KLoB is designed for evaluating whether parameters selected by locating methods embed the desired knowledge. The underlying philosophy in constructing KLoB is to examine whether the locating results possess the desired properties. Assuming the validity of the locality hypothesis of factual knowledge, we define three criteria that a reliable knowledge locating method should satisfy: Consistency, Relevance, and Unbiasedness.

3.1.1 Consistency

Since the goal of locating methods is selecting parameters associated with specific factual knowledge, the locating result should be associated solely with the targeted knowledge, and should not be affected by other factors such as syntactic structure or synonym substitution. Therefore, we propose consistency as a criterion: **for the same factual**

133 **knowledge, locating results should remain in-**
134 **variant despite variations in expression.**

135 3.1.2 Relevance

136 Huang et al. (2023a) introduced the concept of
137 multi-hop knowledge editing, where an input may
138 be linked to a chain of interconnected factual
139 knowledge. Locating methods should be able
140 to recognize the correlation between the specific
141 knowledge and the knowledge chain that includes
142 it. Therefore, we propose relevance as a crite-
143 rion: **the locating results for specific knowledge**
144 **and its related knowledge chain should exhibit**
145 **greater similarity compared to those for unre-**
146 **lated knowledge.**

147 3.1.3 Unbiasedness

148 Knowledge locating methods score and rank pa-
149 rameters based on their association with the tar-
150 geted knowledge. Since the differences in param-
151 eter scores arise from the knowledge present in the
152 input, for inputs that do not align with any factual
153 knowledge, the parameter scores should be more
154 uniform compared to those aligned with specific
155 factual knowledge. Therefore, we propose unbi-
156 asedness as a criterion: **compared to inputs ex-**
157 **PLICITLY pointing to factual knowledge, param-**
158 **eter scores for inputs devoid of factual knowledge**
159 **should be more uniform.**

160 3.2 Data Format

161 As depicted in Figure 2, KLoB consists of three sub-
162 tasks, each examining one of the aforementioned
163 criteria:

- 164 • KLoB-c (consistency): In this subtask, each
165 example comprises three sentences of the
166 same factual knowledge. As shown in Fig-
167 ure 2, both '*Soppressata was created in the*
168 *country of _*' and '*The country where the cre-*
169 *ation of Soppressata took place is _*' include
170 the factual knowledge [Soppressata $\xrightarrow{\text{created in}}$
171 Italy].
- 172 • KLoB-r (relevance): Here, each example com-
173 prises a sentence that includes specific fac-
174 tual knowledge and another one associated
175 with its related knowledge chain. As depicted
176 in Figure 2, the sentences '*Soppressata was*
177 *created in the country of _*' and '*The capital*
178 *city of the country where Soppressata was cre-*
179 *ated is _*' correspond to the factual knowledge
180 [Soppressata $\xrightarrow{\text{created in}}$ Italy] and its related

subtask	relations	avg length	examples
KLoB-c	32	8.75	13675
KLoB-r	35	20.4	9548
KLoB-u	/	10.1	25470

Table 1: Data statistics of KLoB benchmark.

181 knowledge chain [Soppressata, $\xrightarrow{\text{created in}}$ Italy,
182 $\xrightarrow{\text{capital}}$ Rome]] respectively.

- 183 • KLoB-u (unbiasedness): Each example in this
184 subtask features a sentence composed of ran-
185 dom words, which is considered devoid of
186 factual knowledge.

187 As depicted in Figure 2, the answer entity in
188 factual knowledge is positioned at the end of the
189 sentence in KLoB. This design distinguishes KLoB
190 from previous benchmarks (Elazar et al., 2021;
191 Huang et al., 2023a) that utilize sentences with
192 ['MASK'] or question sentences as input text. Con-
193 sequently, examples in KLoB are compatible with
194 both auto-regressive models, such as GPT (Rad-
195 ford et al., 2018, 2019) and Llama (Touvron et al.,
196 2023), and autoencoding models, such as BERT
197 (Kenton and Toutanova, 2019) and ALBERT (Lan
198 et al., 2019).

199 3.3 Data Construction

200 KLoB is constructed based on Wikidata (Vrandečić
201 and Krötzsch, 2014) and MQUAKE benchmark
202 (Zhong et al., 2023). Table 1 summarizes the statis-
203 tics of KLoB benchmark.

- 204 • KLoB-c is built upon Wikidata, a knowledge
205 base consisting of millions of factual triples.
206 We select relationships from Wikidata and
207 manually construct three templates for each
208 relationship. These templates are manually
209 written by human experts, ensuring diversity
210 in grammatical structures and words. Table
211 3 in the Appendix lists all templates for con-
212 structing KLoB-c. Then, we use these tem-
213 plates and corresponding entities in Wikidata
214 to generate sentences.
- 215 • KLoB-r is constructed based on MQUAKE, a
216 dataset comprising multi-hop questions corre-
217 sponding to chains of facts. We select two-hop
218 fact chains from MQUAKE and use the first
219 fact in chains to generate sentences containing
220 single fact, employing the same template as

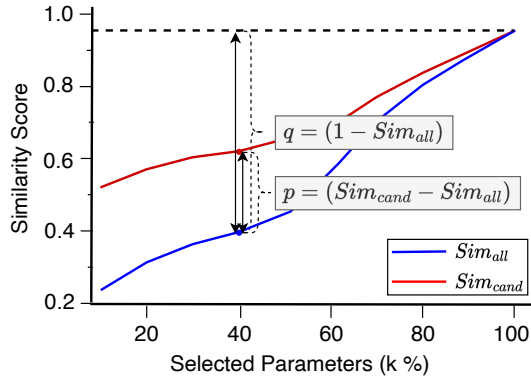


Figure 3: *RSim*: evaluation metrics for KLoB-c and KLoB-r. *RSim* is given by $RSim = \max(\frac{p}{q}, 0)$.

utilized in KLoB-c. For entire fact chains, sentences are generated by rephrasing the multi-hop questions in MQUAKE.

- KLoB-u is constructed by replacing the words in the examples from KLoB-c and KLoB-r with random words and punctuation. The replacement words are sourced from the English word list of the NLTK (Natural Language Toolkit) library (Bird et al., 2009).

We utilize Llama2-7b (Touvron et al., 2023) to filter out factual knowledge that is hard to recall. We query Llama2-7b using an in-context learning approach with 8 demonstration examples and retain only the factual knowledge for which the model can correctly predict the answers.

3.4 Evaluation Metrics

In this work, we introduce the Relative Similarity (*RSim*) metric for KLoB-c and KLoB-r, assessing the extent to which the similarity within certain locating results exceeds the similarity between these and other locating results. Similarly, we introduce the Relative Standard Deviation (*RSD*) metric for KLoB-u, assessing how much more uniform the locating results are for sentences devoid of factual knowledge (KLoB-u) compared to those with explicit factual knowledge (KLoB-c and KLoB-r).

- **Relative Similarity:** The *RSim* metric operates by considering only the selected parameters in locating results. The first step in the *RSim* metric is to calculate the intra-similarity of the candidate locating results (e.g., locating results for sentences in one KLoB-c example), which is denoted as Sim_{cand} . Then, *RSim* calculates the similarity between the candidate locating results

and locating results of all samples in the subtask, which is denoted as Sim_{all} . As depicted in Figure 3, the *RSim* metric is calculated using the formula: $RSim = \max(\frac{Sim_{cand} - Sim_{all}}{1 - Sim_{all}}, 0)$. Given that the upper bound of similarity value Sim is 1, this formula quantifies the extent to which Sim_{cand} is closer to the upper bound compared to Sim_{all} . If the candidate locating results are all identical, meaning that Sim_{cand} equals 1, then *RSim* is equal to 1. If Sim_{cand} is less than or equal to Sim_{all} , then *RSim* is equal to 0. The detailed formula for calculating *RSim* is elaborated in Appendix Section A.

- **Relative Standard Deviation:** Unlike *RSim*, the *RSD* metric operates by considering all model parameters. *RSD* utilizes the standard deviation to quantify the variability of parameter scores in one locating result, denoted as SD . *RSD* first calculates the average SD of sentences in KLoB-c and KLoB-r (sentences with factual knowledge), denoted as $SD_{factual}$. Then, it calculates the average SD of sentences in KLoB-u (sentences without factual knowledge), denoted as $SD_{nonfactual}$. *RSD* is given by $RSD = \max(1 - \frac{SD_{nonfactual}}{SD_{factual}}, 0)$. *RSD* measures the relationship between of $SD_{nonfactual}$ and $SD_{factual}$ by calculating the proportion between them. If the parameter scores for sentences without knowledge are all identical, $SD_{nonfactual}$ equals 0, which means *RSD* equals 1. Conversely, if the parameter scores for sentences without knowledge are more variable than those with factual knowledge, meaning that $SD_{nonfactual} > SD_{factual}$, then *RSD* equals 0.

4 Conclusion

In this work, we introduce KLoB, the first benchmark for evaluating locating methods in language models. KLoB delineates three essential properties a reliable knowledge locating method should satisfy: Consistency, Relevance, and Unbiasedness. Thus, the evaluation of locating methods can be conducted by examining these properties. We hope KLoB can serve as a benchmark for evaluating existing locating methods, and contributes a quantitative analysis methods for reassessing the validity of locality hypothesis of factual knowledge.

5 Limitations

There are two primary limitations in this study that remain unexplored: (i) KLoB is only applicable for comparing knowledge locating methods with the same parameter granularity. For instance, a method with neuron-level granularity versus another at a model layer level cannot be effectively compared using KLoB. (ii) While this work introduces KLoB for evaluating the effectiveness of knowledge locating methods, it did not conduct experiments based on existing methods, which will be the primary focus of our subsequent research efforts.

References

- Steven Bird, Ewan Klein, and Edward Loper. 2009. *Natural language processing with Python: analyzing text with the natural language toolkit*. " O'Reilly Media, Inc."
- Damai Dai, Li Dong, Yaru Hao, Zhifang Sui, Baobao Chang, and Furu Wei. 2022. Knowledge neurons in pretrained transformers. In *Proceedings of the 60th Annual Meeting of the Association for Computational Linguistics (Volume 1: Long Papers)*, pages 8493–8502.
- Nicola De Cao, Wilker Aziz, and Ivan Titov. 2021. Editing factual knowledge in language models. In *Proceedings of the 2021 Conference on Empirical Methods in Natural Language Processing*, pages 6491–6506.
- Qingxiu Dong, Damai Dai, Yifan Song, Jingjing Xu, Zhifang Sui, and Lei Li. 2022. Calibrating factual knowledge in pretrained language models. *arXiv preprint arXiv:2210.03329*.
- Yanai Elazar, Nora Kassner, Shauli Ravfogel, Abhishava Ravichander, Eduard Hovy, Hinrich Schütze, and Yoav Goldberg. 2021. Measuring and improving consistency in pretrained language models. *Transactions of the Association for Computational Linguistics*, 9:1012–1031.
- Jen-tse Huang, Man Ho Lam, Eric John Li, Shujie Ren, Wenxuan Wang, Wenxiang Jiao, Zhaopeng Tu, and Michael R Lyu. 2023a. Emotionally numb or empathetic? evaluating how llms feel using emotionbench. *arXiv preprint arXiv:2308.03656*.
- Zeyu Huang, Yikang Shen, Xiaofeng Zhang, Jie Zhou, Wenge Rong, and Zhang Xiong. 2023b. Transformer-patcher: One mistake worth one neuron. *arXiv preprint arXiv:2301.09785*.
- Jacob Devlin Ming-Wei Chang Kenton and Lee Kristina Toutanova. 2019. Bert: Pre-training of deep bidirectional transformers for language understanding. In *Proceedings of NAACL-HLT*, pages 4171–4186.

- Zhenzhong Lan, Mingda Chen, Sebastian Goodman, Kevin Gimpel, Piyush Sharma, and Radu Soricut. 2019. Albert: A lite bert for self-supervised learning of language representations. *arXiv preprint arXiv:1909.11942*.
- Xiaopeng Li, Shasha Li, Shezheng Song, Jing Yang, Jun Ma, and Jie Yu. 2023. Pmet: Precise model editing in a transformer. *arXiv preprint arXiv:2308.08742*.
- Kevin Meng, David Bau, Alex Andonian, and Yonatan Belinkov. 2022a. Locating and editing factual associations in gpt. *Advances in Neural Information Processing Systems*, 35:17359–17372.
- Kevin Meng, Arnab Sen Sharma, Alex Andonian, Yonatan Belinkov, and David Bau. 2022b. Mass-editing memory in a transformer. *arXiv preprint arXiv:2210.07229*.
- Eric Mitchell, Charles Lin, Antoine Bosselut, Chelsea Finn, and Christopher D Manning. 2021. Fast model editing at scale. *arXiv preprint arXiv:2110.11309*.
- Eric Mitchell, Charles Lin, Antoine Bosselut, Christopher D Manning, and Chelsea Finn. 2022. Memory-based model editing at scale. In *International Conference on Machine Learning*, pages 15817–15831. PMLR.
- Alec Radford, Karthik Narasimhan, Tim Salimans, Ilya Sutskever, et al. 2018. Improving language understanding by generative pre-training.
- Alec Radford, Jeffrey Wu, Rewon Child, David Luan, Dario Amodei, Ilya Sutskever, et al. 2019. Language models are unsupervised multitask learners. *OpenAI blog*, 1(8):9.
- Adam Roberts, Colin Raffel, and Noam Shazeer. 2020. How much knowledge can you pack into the parameters of a language model? In *Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing (EMNLP)*, pages 5418–5426.
- Anton Sinitsin, Vsevolod Plokhotnyuk, Dmitriy Pyrkin, Sergei Popov, and Artem Babenko. 2020. Editable neural networks. *arXiv preprint arXiv:2004.00345*.
- Hugo Touvron, Thibaut Lavril, Gautier Izacard, Xavier Martinet, Marie-Anne Lachaux, Timothée Lacroix, Baptiste Rozière, Naman Goyal, Eric Hambro, Faisal Azhar, et al. 2023. Llama: Open and efficient foundation language models. *arXiv preprint arXiv:2302.13971*.
- Denny Vrandečić and Markus Krötzsch. 2014. Wikidata: a free collaborative knowledgebase. *Communications of the ACM*, 57(10):78–85.
- Yunzhi Yao, Peng Wang, Bozhong Tian, Siyuan Cheng, Zhoubo Li, Shumin Deng, Huajun Chen, and Ningyu Zhang. 2023. Editing large language models: Problems, methods, and opportunities. *arXiv preprint arXiv:2305.13172*.

Zexuan Zhong, Zhengxuan Wu, Christopher D Manning, Christopher Potts, and Danqi Chen. 2023. Mquake: Assessing knowledge editing in language models via multi-hop questions. *arXiv preprint arXiv:2305.14795*.

A Detailed Description for calculating RSim

Suppose we have two locating results x_i and x_j , each contains $k\%$ of the model parameters. The similarity between these two locating results is given by $Sim = overlap_{ij}/(N * k\%)$, where $overlap_{ij}$ denotes the number of overlapping parameters between x_i and x_j , N is the total number of model parameters. For each example in KLoB-c, comprising three sentences, the similarity Sim_{cand} is calculated as the average of the pairwise similarities among these sentences." Similarly, Sim_{all} represents the average similarity between the selected locating result x_{cand} and all other locating results in the subtask, and is defined as $Sim_{all} = \frac{1}{M} \sum_{i=1}^M Sim(x_i, x_{cand})$, where M denotes the number of examples in the subtask. To streamline the calculations, we approximate Sim_{all} as $Sim(x_{all}, x_{cand})$, where x_{all} refers to a locating result derived by selecting parameters based on their average scores across the entire subtask.

B Templates of KLoB-c

Table 3 shows the relationship templates in KLoB-c, and Table 2 shows example counts for each relation.

relation	example counts
P103 (native)	851
P1001 (legal-term)	526
P101 (work)	198
P106 (by-profession)	292
P108 (works-for)	263
P127 (owned-uy)	330
P1303 (play)	264
P131 (located-in)	137
P136 (plays-music)	521
P1376 (capital)	140
P138 (is-name-after)	214
P1412 (communicate)	120
P159 (headquarter)	590
P17 (is-located)	783
P176 (produce)	831
P178 (develop)	702
P19 (born)	245
P276 (locate)	324
P36 (capital)	377
P37 (official-language)	667
P39 (position)	280
P407 (write)	662
P413 (play)	649
P449 (air)	567
P495 (create)	649
P26 (spouse)	266
P50 (author)	828
P112 (founded by)	181
P69 (educated at)	116
P140 (affiliated-with)	349
P175 (performer)	386
P641 (sport)	367

Table 2: Number of examples of each relation in KLoB-c

relation	templates
P103	The native language of [X] is [Y] The mother tongue of [X] is [Y] The language [X] speaks at hometown is [Y]
P1001	[X] is a legal term in [Y] [X] serves as one of the legal term for [Y] [X] : the legal term for [Y]
P101	[X] works in the field of [Y] [X] specializes in the field of [Y] The domain of activity of [X] is [Y]
P106	[X] works as [Y] [X] 's occupation is [Y] the profession of [X] is [Y]
P108	[X] works for the company: [Y] The company that employs [X] is [Y] The company providing employment to [X] is [Y]
P127	[X] belongs to [Y] the company that owns [X] is [Y] the owner company of [X] is [Y]
P1303	[X] plays the musical instrument known as the [Y] [X] is known for playing the [Y] In the hands of [X] , music emerges from the [Y]
P131	[X] is located in [Y] [X] can be found in [Y] The location of [X] is [Y]
P136	[X] composes in the genre of [Y] [X] engages in the performance of [Y] The music genre that [X] performs is [Y]
P1376	[X] is the capital of [Y] [X] holds the status of being the capital of [Y] [X] , the capital city of [Y]
P138	[X] is the capital of [Y] [X] holds the status of being the capital of [Y] [X] , the capital city of [Y]
P1412	[X] used to communicate in the language of [Y] [X] expressed himself through the language of [Y] In language [X] utilizes for communication is [Y]
P159	The headquarters of [X] is located in [Y] [X] , whose headquarters is in [Y] [X] has established its headquarters in [Y]
P17	The headquarters of [X] is located in [Y] [X] , whose headquarters is in [Y] [X] has established its headquarters in [Y]
P176	[X] is produced by the company: [Y] The company behind [X] Lumia 800 [Y] [X] is one among products crafted by [Y]
P178	[X] , a product manufactured by the company: [Y] The company that developed [X] is [Y] The company that stands behind the creation of [X] is [Y]
P19	[X] was born in [Y] The place of birth for [X] is [Y] The birth of [X] occurred in [Y]
P276	[X] is located in [Y] [X] can be found in [Y] The location of [X] is [Y]
P36	[X] is the capital of [Y] [X] holds the status of being the capital of [Y] [X] , the capital city of [Y]
P37	The official language of [X] is [Y] In terms of official language, [X] uses [Y] Under [X] law, the official language is recognized as [Y]
P39	[X] assumed the role of [Y] [X] holds the position of [Y] [X] served in the capacity of [Y]
P407	The language of [X] is [Y] The [X] was penned in [Y] [X] was written with the language of [Y]

P413	[X] plays in the position of a [Y] [X] 's role on the team involves him serving as a [Y] When on the field, [X] is positioned as a [Y]
P449	[X] was originally aired on [Y] [X] , initially, was broadcasted on [Y] [X] was originally presented to audiences on [Y]
P495	[X] was created in the country of [Y] The country where creation of [X] took place is [Y] [X] has its birthplace in the country of [Y]
P26	[X] is married to [Y] The spouse of [X] is none other than [Y] In matrimony, [X] is bound to [Y]
P50	The author of [X] is [Y] [X] was written by [Y] Credited with the creation of [X] is [Y]
P112	[X] was founded by [Y] The [X] owes its existence to the person of [Y] The person behind the inception of the [X] is [Y]
P69	[X] was educated at a university named [Y] [X] received his education from the institution known as [Y] The university where [X] was educated is [Y]
P140	[X] is affiliated with the religion of [Y] [X] is a follower of the faith known as the [Y] The religion that [X] adheres to is [Y]
P175	[X] was performed by [Y] [X] was presented to audiences by [Y] In the performance of [X] , the artist is [Y]
P641	[X] is associated with the sport of [Y] The sport that [X] is linked to is association [Y] [X] pertains to the sport known as association [Y]

Table 3: Templates of KLoB-c, where [X] refers to the head entity of fact triples in Wikidata, and [Y] refers to the tail entity.