FINGERTIP 20K: A BENCHMARK FOR PROACTIVE AND PERSONALIZED MOBILE LLM AGENTS

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ABSTRACT

Mobile GUI agents are becoming critical tools to improve user experience on smart devices, with multimodal large language models (MLLMs) emerging as the dominant paradigms in this domain. Current agents, however, rely on explicit human instructions, overlooking the potential to leverage the contextual information (like location, time, previous interactions) for proactive task suggestions. Besides, previous works focus on optimizing the success rate during task execution, but pay less attention to the personalized execution trajectory, thereby neglecting potentially vast differences in user preferences. To address these challenges, we introduce the FingerTip 20K benchmark. We collected 20K unique human demonstrations of multi-step Android device interactions across a variety of everyday apps. These demonstrations are not isolated but are continuously acquired from the users' long-term usage in their real lives, and encompass essential user-related contextual information. The benchmark contains two new tracks: proactive task suggestions by analyzing environment observation and users' previous intents, and personalized task execution by catering to users' action preferences. Our experiments reveal that the tracks we propose pose significant challenges for leveraging user-related information in GUI tasks. We also performed a human study to show that there exists a huge gap between existing agents and humans. The model fine-tuned with the data we collected effectively utilized user information and achieved good results, highlighting the potential of our approach in building more user-oriented mobile LLM agents. Our code is open-source at https://anonymous.4open.science/r/FingerTip-57B8 for reproducibility.

1 Introduction

Recent studies have explored how to utilize multimodal large language models (MLLMs) to build graphical user interface (GUI) control agents (Koh et al., 2024; Zheng et al., 2024; Yan et al., 2023; Kim et al., 2023; Deng et al., 2023), with a significant direction being mobile phone GUI control agents. These mobile LLM agents have the potential to tremendously improve user experience with mobile devices, since GUI is a universal interface across various applications. These agents receive a natural language task instruction, such as "Set an alarm for 7:30 for me", and then perceive the device state by observing the device screen (via screenshots or textual UI trees), and generate actions (click, type, scroll, etc.) to interact with the device environment to fulfill human instructions.

Despite rapid progress, currently, most existing mobile LLM agents are confined to a completely passive paradigm: they only perform tasks upon receiving a clear instruction. This paradigm restricts their ability to proactively offer task suggestions and assistance in the absence of direct human instructions. If users have to formulate detailed instructions for every intent when interacting with mobile LLM agents, it will significantly increase the cognitive burden of mobile phone usage. Moreover, humans sometimes may not clearly express some latent needs. Therefore, mobile LLM agents need to be more proactive to provide users with more comprehensive and seamless services. Furthermore, the existing agents utilize almost exclusively user instructions as textual information when performing tasks, without taking into account any additional user-related information (e.g., time and location, user profile, user historical intents and actions), thus failing to provide personalized services to users. We argue that these limitations stem largely from the lack of suitable training data and standardized evaluation benchmarks that incorporate rich user-related information.



Figure 1: An overview task example in FingerTip 20K.

To comprehensively evaluate the proactive and personalized capabilities of mobile LLM agents, we propose the FingerTip 20K benchmark, which includes two new tracks: (i) proactive task suggestion, where the agent needs to integrate the user's past intents and the current environmental state to infer the user's potential current intent; (ii) personalized task execution, where the agent needs to refer to the user's past action preferences to execute current instructions. The overall task scenario we envision is shown in Figure 1. Since existing benchmarks do not provide such user-related contextual information, we spent two months collecting new diverse data from 95 users in their daily mobile phone usage, including 21,437 episodes covering 506 apps. We then conducted experiments on the FingerTip 20K benchmark to evaluate the capabilities of generalist models and GUI-control agents built on specifically designed models and found that there is still much room for improvement in their proactive and personalized capabilities. Current agents still find it hard to reach or surpass the human level. The best-performing model achieved a success rate of 7.2%, while humans reached 30.3%. We fine-tuned a small model using the collected data and achieved better results.

In summary, the main contributions of this work include:

- We propose the FingerTip 20K benchmark, which includes two brand-new tracks, to evaluate the ability of mobile LLM agents to proactively predict user intents and offer suggestions, as well as their ability to personalize task execution in accordance with user preferences.
- We collect large-scale user-oriented mobile GUI-control data, derived from scenarios in users' daily lives, which includes user-related contextual information and users' long-term mobile phone usage patterns.
- We evaluated the capabilities of generalist models and GUI-control-specific models on the FingerTip 20K benchmark, demonstrating the difficulty of the tracks we propose. The excellent performance of the model fine-tuned with our collected data highlights the potential of our approach in building more proactive and personalized mobile agents.

2 Related work

2.1 Mobile GUI-control datasets and benchmarks

Table 1 compares FingerTip 20K to existing mobile GUI-control datasets and benchmarks (Xu et al., 2024a; Chai et al., 2024; Li et al., 2024; Rawles et al., 2023; Chai et al., 2025; Ran et al., 2025; Chen et al., 2024). These datasets typically represent each data instance through two core components: a textual task instruction and its corresponding operational demonstration. The demonstration is encoded as a sequence of interface interactions (e.g., clicking, typing, scrolling) accompanied by

relevant screenshots. What differentiates them is mainly whether they are single-step (grounding instructions to UI elements on the screen), and whether they have supplemental View Hierarchy (VH) data for each screenshot. These datasets share some common drawbacks. Firstly, their task instructions are either pre-defined by authors or generated by LLMs, and it is questionable to what extent they can reflect the real intents of people using mobile phones in their daily lives. Additionally, they collect task demonstrations mainly by having annotators operate simulators on computers, which is not the real scenario of people using mobile phones. Finally, each data instance is isolated, lacking temporal correlation and contextual information related to the user.

Table 1: Comparison of FingerTip 20K to existing mobile GUI-control datasets and benchmarks.

Dataset &	#Episode	# A ====	#Avg	User-defined	Contextual	Historical	Task
Benchmark	#Episode	#Apps	steps	tasks?	info?	data?	setting
Android Instruct	10.5k	-	9.0	X	X	X	execution
AMEX	3046	192	12.8	X	X	X	execution
AndroidControl	15283	833	5.5	X	X	X	execution
AitW	715142	357	6.5	X	X	X	execution
AndroidLab	138	9	-	Х	X	X	execution
A3	201	20	-	X	X	X	execution
SPHINX	-	100	8.1	X	X	X	execution
SPA-Bench	340	58	-	X	X	X	execution
FingerTip 20K	21437	506	11.1	✓	✓	✓	proactive task suggestion & personalized task execution

For benchmarks, the success rate is the most commonly used metric, and some studies also consider efficiency and cost. A common approach to assessing the success of a task is to determine whether essential states have been reached (Rawles et al., 2024; Zhang et al., 2024; Lee et al., 2024). Some studies also compare agents' actions to golden actions (Xing et al., 2024). However, these golden actions do not take into account potentially vast differences in user preferences, that is, the action sequences of different users to complete similar tasks may be very different. In addition, current benchmarks have similar task forms, that is, given an existing instruction, how to perform actions to complete it. To the best of our knowledge, there is no mobile LLM agent benchmark that discusses how to proactively suggest tasks based on user-related information when instructions are unknown.

2.2 Mobile GUI-control agents

Mobile GUI agents are designed to understand the UI and automate tasks on mobile apps in a manner similar to that of humans. Current agents leverage the extensive world knowledge and powerful embodied capabilities of multimodal large language models (MLLMs) for complex task planning and reasoning in multi-step GUI-control tasks. One notable approach is to directly guide generalist models like GPT-4v to perform tasks through extensive prompt engineering (Yan et al., 2023; Rawles et al., 2023; He et al., 2024; Koh et al., 2024; Kim et al., 2023; Zheng et al., 2023). However, these methods require meticulously designed prompts to achieve the best results. Another research direction focuses on fine-tuning smaller models (Nakano et al., 2022; Qin et al., 2025; Hong et al., 2024; Xu et al., 2024b; Gur et al., 2023) on GUI-specific datasets to endow them with GUI grounding capabilities and the ability to break down high-level instructions, thereby enhancing their operational efficiency. Despite these advancements, most current agents are still confined to passively following explicit instructions and are unable to proactively predict user needs. Moreover, they do not take into account any user preferences when performing tasks. Some studies focus on proactively clarifying users' ambiguous instructions (Wu et al., 2021; Chen et al., 2020; Qian et al., 2024); however, these studies still require users to provide initial instructions. Proactive Agent (Lu et al., 2024) predicts potential tasks by monitoring user activities and environmental states, but the input is text-only, and the task scenarios are mainly limited to computer or web environments rather than mobile ones.

3 Problem formulation

3.1 Proactive task suggestion

In the FingerTip 20K benchmark we propose, unlike the evaluation tasks of traditional mobile LLM agent benchmarks that rely entirely on explicit instructions, we introduce a new task where the agent

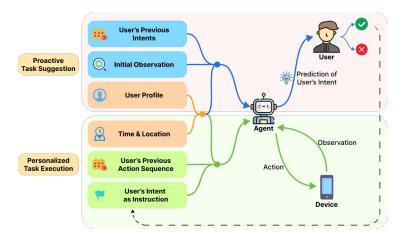


Figure 2: Demonstration of proactive task suggestion and personalized task execution.

proactively predicts the user's current intent and proposes tasks suggestion that the user might want to perform, as shown in Figure 2. The agent's task is to generate an intent prediction I based on the user profile U, the current time T, the current scenario S, the user's historical intents I_{history} , and the partial screenshots O observed at present. This can be formalized as:

$$I = f(U, T, S, I_{\text{history}}, O) \tag{1}$$

where f represents the agent. I is a sentence that unambiguously predicts the intent of the user. It should clearly state the name of the app that the user wants to use, and the final effect that the user wants to achieve. U includes common user attributes such as age, sex, occupation, etc. T represents the current timestamp, accurate to the second. S represents the current scenario, expressed in common location categories. I_{history} contains the user's historical intents in the recent period, up to 20 items, which may include the potential patterns and preferences of the user's mobile phone usage. O includes the first few screenshots of the user's current actions (e.g., opening the home page of a certain app). We hope that the agent can utilize the above-mentioned user-related contextual information to infer the user's potential intents, and thereby proactively offer helpful task suggestions.

3.2 Personalized task execution

In addition to proactive task suggestion, we also aim to evaluate the agent's ability to carry out tasks under the condition of explicit instructions, that is, when the user's intent is known. The setting of this part is similar to the existing benchmarks. The difference lies in that we additionally assess the agent's ability to execute tasks in a personalized manner specifically catering to the action preferences of different users. Given user profile U, user intent $I_{\rm true}$, user's historical actions $A_{\rm history}$, agent's action sequence $A_{\rm agent}$, and the current screenshot O_t and the corresponding accessibility tree AT_t , the agent needs to perform the next action A_{t+1} , and then observe O_{t+1} and AT_{t+1} . This can be formalized as:

$$A_{t+1}, O_{t+1}, AT_{t+1} = f(U, I_{\text{true}}, A_{\text{history}}, A_{\text{agent}}, O_t, AT_t)$$
 (2)

where f represents the agent. $I_{\rm true}$ is equivalent to the user's true intent that needs to be predicted in proactive task suggestion, and here it serves as the instruction to be executed. $A_{\rm history}$ is the complete action sequence of the user when performing a similar task in the past, provided to the agent for in-context learning to imitate the user's action preferences. $A_{\rm agent}$, on the other hand, is the action sequence $\{A_1,...,A_t\}$ that the agent has already executed in the current task, helping the agent determine the progress of the task. The agent needs to constantly interact with the mobile phone environment until it believes that $I_{\rm true}$ has been fulfilled. We hope that the final sequence of agent actions $A_{\rm agent}$ can reflect the user's action preferences.

4 THE FINGERTIP 20K BENCHMARK

4.1 OVERVIEW

The motivation for FingerTip 20K data collection is to evaluate the dual tracks we have proposed, namely proactive task suggestion and personalized task execution. To this end, the most distinctive feature of the data should be user-oriented, containing sufficient user-related contextual information and being able to reflect the patterns and preferences of users in terms of intents and actions.

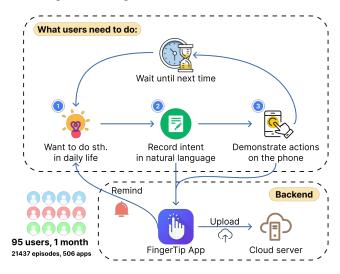


Figure 3: Data collection pipeline.

4.2 Data collection

The data collection pipeline is shown in Figure 3. We first recruited 95 data collectors (hereinafter referred to as users) using Android phones through crowdsourcing, covering a wide range of device types and Android versions. Users were required to download an APP developed by us on their own daily used phones and use it to collect data. Specifically, whenever users had a real intent to use their phones in their daily lives, they could open the FingerTip APP, record their intent at that moment in one sentence, and select the location category they were in. Then, users needed to switch to the app involved in the intent they recorded and demonstrate the specific action sequence to complete this intent.

The FingerTip APP will automatically upload the intent they fill in (including time and location) and the demonstration process they provide (including screenshot sequences, corresponding accessibility tree XML file sequences, and UI action sequences) to the cloud server. This is regarded as the user collecting one piece of data. The APP may remind the user to collect data when they wake up the phone screen to prevent them from forgetting. Each user is required to use their phone to collect data for one month, with a maximum of 12 pieces of data uploaded per day. In this way, users can fully customize the data they upload. See Appendix A.3 and A.4 for more details on data collection and data format.

FingerTip APP is developed based on the accessibility features of the Android system. It can automatically record the type and coordinates, as well as optional text descriptions of each user action. The actions we collect are unified into an action space, as shown in Table 2. Among them, finish is uniformly added to the last screenshot of all episodes.

4.3 Data statistics

The summary of data statistics is presented in Table 1. Additionally, Figure 4 reports the distribution of user intent length, episode length, intent categories, and app name in all data. The intent categories are determined by DeepSeek-V3 (Liu et al., 2024).

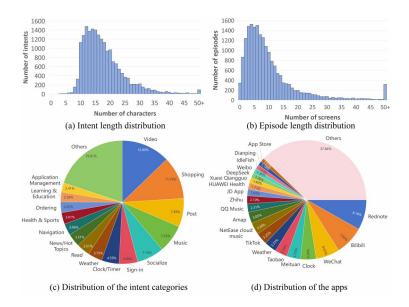


Figure 4: Dataset statistics and distribution.

4.4 Personalized action analysis

Table 2: Action space.

Action	Parameter		
click	coordinates=(x,y), content="		
long_click	coordinates=(x,y), content="		
type	text="		
scroll	coordinates=(x,y), direction="		
press_back	-		
press_home	-		
press_recent	-		
wait	-		
finish	-		

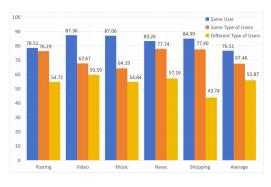


Figure 5: Personalized action analysis.

To verify the personalized differences in actions among different types of users, we first simply classified users into different categories based on age groups. Then, we randomly sampled one piece of data from each of the 40 intent categories. For the action sequence of such a piece of data, we calculated the Levenshtein similarity with the action sequence of the most intent-similar data from (i) the same user, (ii) the same type of users, and (iii) different type of users. All similarities were normalized to [0, 100] and plotted in Figure 5. It can be seen that even when performing similar intents, the similarity of action sequences with different types of users is significantly lower than that of the same user or the same type of users, indicating that user preferences on action sequences do exist and are measurable.

5 EXPERIMENTS

We conducted experiments on some generalist models and some GUI-control agents built on specifically designed models, evaluating their capabilities on the two tracks proposed in the FingerTip 20K benchmark and assessing their performance under different task difficulties. Additionally, we fine-tuned a model using the collected data. For details on the data splits (including the training set, validation set, and two test sets), please refer to Appendix A.5.

5.1 EXPERIMENTAL SETUP

Proactive task suggestion The LLMs we experiment with in this track include GPT-4.1, Qwen-VL-Max, DeepSeek-VL2 (Wu et al., 2024) and Qwen-2.5-VL-7B (Bai et al., 2025). We set the temperature to zero for all models. For proactive task suggestion, the agent only needs one query to output the predicted intent. Since this is a brand new track proposed in our benchmark, there is no mature agent design available for direct use. We have designed a simple prompt to provide to all models evaluated in this track. This prompt contains all necessary inputs (see Section 3.1 and Appendix A.7.1).

Personalized task execution In this track, in addition to the four generalist models mentioned above, we also experiment with three GUI-control agents built on specifically designed models, including Aguvis-7B (Xu et al., 2024b), CogAgent-9B (Hong et al., 2024) and UI-TARS-1.5-7B (Qin et al., 2025). For personalized task execution, the agent needs to interact with the environment in multiple steps to fulfill the user's instructions. We connect a physical phone to the computer via USB and use Android Debug Bridge (ADB) to provide this environment. Using an emulator would be a more convenient approach, but due to strict app control measures, most Chinese apps can only run on physical phones rather than emulators. For the generalist models, we designed a simple prompt to guide their output of the next action, with the action space consistent with Table 2. This prompt contains all necessary inputs (see Section 3.2 and Appendix A.7.2). For the three GUI-control agents, they have specific format requirements for input and output. To ensure normal output effects, their original prompts were used, and the input information in Section 3.2 was uniformly integrated into these original prompts. Their output was converted into a form consistent with the action space.

Metrics In proactive task suggestion track, the goal of the agent is to maximize the textual similarity between the output and the user's true intent. We use a pre-trained model, paraphrase-multilingual-MiniLM-L12-v2 (Reimers & Gurevych, 2019), to convert the agent's output and the user's true intent into embedding vectors and calculate their cosine similarity S_1 . And, we calculate the Levenshtein similarity S_2 of these two strings. Both similarities are normalized to the range of [0, 1]. Finally, we take $Sim_1 = (S_1 + S_2)/2$ to comprehensively represent the text similarity. In addition to this numerical metric, we also use DeepSeek-V3 (Liu et al., 2024) to directly determine whether the agent's output and the user's true intent can be regarded as the same intent and provide a binary value to evaluate whether the agent successfully predicted the user's intent, thereby calculating the success rate SR_1 .

In personalized task execution track, the primary goal of the agent is to successfully execute the user's instructions. We calculate the final success rate SR_2 by manually checking whether the environment state when the agent outputs finished() matches the user's instructions. In addition, when the agent steps exceed 2.5 times the golden steps, the task is automatically considered a failure. Note that the path to successfully execute the user's instructions is not unique. The agent should also make the action sequence reflect the user's action preferences as much as possible. We do not require the agent's action at each step to be exactly the same as the user's golden action. Instead, we calculate the Levenshtein similarity S_I of the agent's complete action sequence and the user's complete action sequence as two strings. Then, following the approach in Section 4.4, we take the data from the different type of users that is most similar to the current user's intent, and calculate the Levenshtein similarity $S_{\rm II}$ of the agent's complete action sequence and this data's complete action sequence. Finally, we take the value $Sim_2 = S_I/S_{II}$. It is obvious that the larger this value is, the more similar the agent's action sequence is to that of the current user, and the more different it is from that of different type of users. In addition, we measure execution efficiency by comparing the agent steps with the user's golden steps to calculate the step ratio when the agent successfully execute the user's instructions. For the two tracks, we also tallied the average time and token count consumed per query to assess the model's cost.

5.2 OVERALL PERFORMANCE

The overall performance of the models we evaluated in proactive task suggestion is shown in Table 3. Note that here we set the number of O (the first few screenshots of the user's current actions) to 0. This makes the task quite challenging. GPT-4.1 performed the best among the generalist models, achieving $SR_1=7.2$ and $Sim_1=0.35$, but it also took the longest time. From SR_1 , it can be

intuitively seen that the success rate of all models in predicting the user's intent is very low, less than 10%. Additionally, we conducted a user study where 20 human annotators (distinct from the users who collected the data) labeled a subset of the test set (a total of 400 episodes), achieving a success rate of 30.3%. This highlights the significant gap between the existing models and human in proactive task suggestion capabilities.

Table 3: Overall performance of proactive task suggestion. Bold indicates the best performance among models.

Model	SR_1 (%)	Sim_1	Time (sec)	Token
GPT-4.1	7.2	0.35	5.64	796
Qwen-VL-Max	6.9	0.33	1.98	950
Deepseek-VL2	4.3	0.25	0.71	743
Qwen-2.5-vl-7B	3.1	0.25	0.78	943
Human	30.3	0.57	-	-

Table 4: Overall performance of personalized task execution. Bold indicate the best performance.

Model	SR_2 (%)	Sim_2	Step Ratio	Time (sec)	Token
GPT-4.1	5.5	0.98	1.98	8.02	2912
Qwen-VL-Max	4.5	1.07	2.06	4.17	2304
Deepseek-VL2	1.0	0.93	2.19	3.46	2130
Qwen-2.5-vl-7B	1.5	0.95	2.16	3.66	2213
Aguvis-7B	20.5	1.02	1.38	6.86	2494
CogAgent-7B	18.0	0.92	1.73	12.54	2808
UI-TARS-1.5-7B	38.5	1.06	1.22	10.15	2440

The overall performance of the models we evaluated in personalized task execution is shown in Table 4. GPT-4.1 and UI-TARS-1.5-7B achieved the best performance among the generalist models and GUI-control models respectively. The SR_2 of the generalist models were all very low, mainly due to their lack of precise GUI grounding ability, which led to incorrect UI coordinates being output even when they could correctly analyze the next action, thus failing to interact with the environment accurately. In contrast, the GUI-control models, having undergone targeted training, had stronger abilities to execute instructions and interact with the UI environment, resulting in higher SR_2 , with UI-TARS-1.5-7B having the highest at 38.5. However, the Sim_2 of all models were approximately 1, indicating that the agent's action sequence did not favor either the current user or different types of users. This might suggest that the agent tends to complete tasks in a general way without catering to the specific action preferences of users, thus failing to complete tasks in a personalized manner.

5.3 EFFECT OF TASK DIFFICULTY

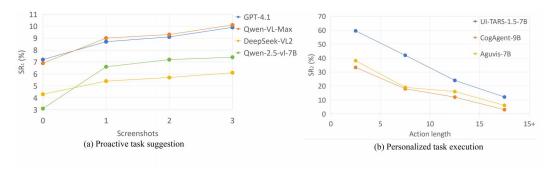


Figure 6: Performance under different task difficulties.

We experiment with the models' performance under different task difficulty levels. For proactive task suggestion (see Figure 6.a), we varied the number of O (the first few screenshots of the user's current

actions). The SR_1 of all models increased as the number of screenshots increased. This was expected. Clearly, if the agent knew the first screenshot of the user's current action, it could basically infer which app the user was using, thereby significantly narrowing the range of the user's intent. With the second and third screenshots, the agent could further narrow the user's intent range by analyzing the actions therein (e.g. clicking the search box).

For personalized task execution (see Figure 6.b), we calculated the SR_2 of GUI-control models on different subsets of action lengths in the test set (we did not calculate the SR_2 of generalist models because their SR_2 were all too low). It can be seen that as the action length increases, the SR_2 decreases. This is in line with expectations, as the greater the action length required to complete a certain instruction, the more complex the instruction is, and the more difficult it is to complete.

5.4 Effect of fine-tuning

Table 5: Performance of fine-tuned model. Bold indicate the best performance.

Model	Proactive ta	isk suggestion	Personalized task execution			
Model	$SR_1(\%)$	Sim_1	$SR_2(\%)$	Sim_2	Step Ratio	
Qwen-2.5-vl-7B	3.1	0.25	1.5	0.95	2.16	
Qwen-2.5-vl-7B-FT	9.7 [+6.6]	0.49 [+0.24]	12.5 [+11.0]	1.21 [+0.26]	1.17 [-0.99]	
GPT-4.1	7.2	0.35	5.5	0.98	1.98	
UI-TARS-1.5-7B	-	-	38.5	1.06	1.22	

To save resources, we only fine-tuned Qwen-2.5-VL-7B and adopted the parameter-efficient fine-tuning method of LoRA, with the LoRA rank set to 4. Following the method of sampling the test set, we randomly sampled 1,000 data episodes from the training set for fine-tuning. These data covered all users, and the proportion of data for each user was the same as their proportion in the training set. These 1,000 data episodes were reorganized according to the input and output formats of the two tracks, respectively. The prompts used in fine-tuning are the same as those we designed for generalist models. Finally, we trained separately on two tracks and obtained two fine-tuned models, each suitable for one of the two tracks.

The performance of the fine-tuned model on the two tracks is shown in Table 5. Despite using a smaller model and less training data, the fine-tuned model achieved significant performance improvements in all main metrics. In proactive task suggestion, compared with the best-performing generalist model GPT-4.1, our fine-tuned model achieved better performance in both SR_1 and Sim_1 . In proactive task suggestion, compared with the best-performing UI-TARS-1.5-7B, our fine-tuned model had a lower success rate SR_2 . We consider this acceptable because UI-TARS is a model specifically designed and extensively trained for GUI grounding and GUI control, and thus has a more general instruction execution capability. However, our fine-tuned model had a significantly higher Sim_2 , indicating that the action paths it selects may not be optimal but are closer to the user's action preferences. Overall, the model fine-tuned on our collected data demonstrated stronger proactivity and personalization capabilities, being able to utilize user-related contextual information to extract potential intent patterns and action preferences from the user's past intents and actions, which existing models have not or find it difficult to consider.

More experiments In Appendix A.6 we conducted more experiments to study the influence of other factors.

6 CONCLUSIONS

We present FingerTip 20K, a benchmark advancing mobile LLM agents toward proactive task suggestion and personalized task execution. Our data captures longitudinal user interactions, enriched with contextual information to model user-specific patterns. Experiments reveal significant gaps in existing models' ability to leverage such contextual information. Fine-tuning Qwen-2.5-VL-7B on our data improved suggestion success rate while better aligning actions with user preferences, demonstrating the value of user-oriented training. This work establishes critical infrastructure for developing mobile agents that anticipate user needs and adapt to user action preferences.

7 ETHICS STATEMENT

Our data collection involves human participants. We detail our data collection process and the multiple measures we have taken to reduce the risk of privacy leakage in Appendix A.3. We also discuss the broader impacts of this study in Appendix A.2.

8 Reproducibility statement

To ensure the reproducibility of our work, we provide all the necessary resources and code used in this paper. All adopted models are fully open source or publicly accessible. Our project code, including the data format, data splits, and evaluation process of FingerTip 20K, can be publicly accessed via the following anonymous link: https://anonymous.4open.science/r/FingerTip-57B8.

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A APPENDIX

A.1 LIMITATIONS

Our study has several limitations. Firstly, all 91 contributors live in mainland China, and mainly interact with Chinese third-party apps. The recorded linguistic habits, UI layouts and action patterns may differ markedly from other regions. Secondly, our LoRA fine-tuning uses only 1000 episodes and a single 7B model. Due to cost constraints, we did not conduct larger-scale fine-tuning experiments nor verify its generalization. Finally, we assume that screenshots can be stored and shared after anonymization. In practice, fine-grained UI traces can still contain unique visual features that allow re-identification. Techniques such as selective redaction or synthetic replay should be explored before large-scale deployment.

A.2 Broader impacts

FingerTip 20K aims to advance mobile agents that anticipate user needs and adapt to individual preferences. If developed responsibly, such agents could reduce the interaction barrier for elderly or motor-impaired users, reduce screen time by automating repetitive tasks, and serve as a test bed for privacy-preserving personalization research. At the same time, the technology entails risks. Continuous screen capture combined with explicit user profiles gives models an intimate view of personal life. An attacker compromising the agent, or a service provider lacking strong governance, could reconstruct sensitive behaviors, contacts or locations. We encourage future work on on-device processing, differential privacy and audit mechanisms.

A.3 DATA COLLECTION

The data collection was carried out through crowdsourcing, and participants were paid in accordance with the living wage laws of their country. Participants consist of one-third undergraduates, one-third postgraduates, and one-third employed individuals, with an average age of 25.9. Participants filled out a questionnaire, which collected their user profiles. Participants were informed of the expected use of the collected data and signed a data usage agreement. They were asked not to upload any data related to private information. We provided participants with detailed guidance documents and video tutorials on how to operate the FingerTip APP for data collection. All participants went through a training phase during which they became familiar with the FingerTip APP and received targeted feedback from our manually checked data. They were encouraged to avoid using overly simplified or ambiguous language to collect clear and useful intent descriptions. It should be noted that the FingerTip APP only collects data when participants actively use it. It does not automatically collect data at other times. Participants can check or delete the data they upload at any time. We manually inspected the data and removed those that obviously involved privacy.

Our primary goal for collecting the data was to capture deep, longitudinal user interactions in daily life settings. We believe this context-rich dataset, even from a single region, provides a crucial foundation for the novel tasks of proactive task suggestion and personalized task execution. Considering the cost and the instability of cross-regional data transmission, we did not collect data in other regions. To our knowledge, the annotators of previous datasets or benchmarks such as Rawles et al. (2023); Li et al. (2024); Chen et al. (2024) also came from a single region. We believe this is a sufficient start for a first-of-its-kind study. To facilitate broader research, we plan to open source our APP for data collection. It can run on any (new version) Android personal phones, providing support for data collection in other regions.

A.4 DATA FORMAT

Our data is publicly released at https://anonymous.4open.science/r/FingerTip-57B8. The data contains several folders named with numbers (i.e. user IDs), and each of these folders contains multiple folders named with timestamps (e.g., 20250309_133115), representing all the data episodes submitted by that user. For each data episode, the following information is included:

• screenshots: a list of screenshots for each observation encoded as JPGs.

- accessibility trees: a list of Android accessibility tree XML files for each observation.
- *actions*: a list of actions represented in the form of JSON dictionaries. Each screenshot corresponds to an action.
- *intent_description*: the user's true intent in this episode.
- *user_id*: the unique integer identifier of the user to whom this episode belongs. This information can be used to retrieve the corresponding user's user profile.
- time: the timestamp when this episode was collected.
- scenario: the category of location where the user was when this episode was collected.
- *app*: the name of the activity running when the episode was collected. This information is only used to launch the corresponding app in personalized task execution and is not provided to the LLM agent.

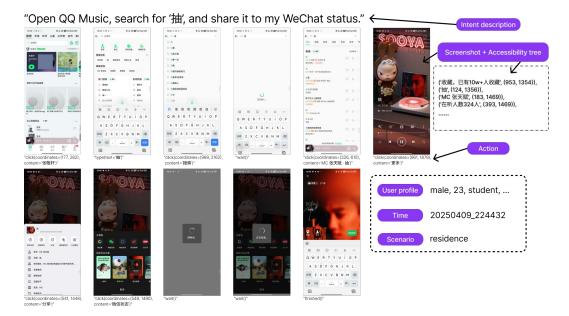


Figure 7: An example episode from FingerTip 20K.

The example of an episode from FingerTip 20K is shown in Figure 7.

Accessibility trees Note that when using accessibility trees, the LLM agent utilizes a list of all accessible UI elements and their coordinates corresponding to a certain screenshot, which is extracted from the metadata XML file through a Python function.

Table 6: User profile example.

Field	user_id	sex	age	occupation	address	marital_status	phone_brand
Example	55	male	20	student	Beijing	single	Huawei

User profile The types of information included in user profiles and an example can be seen in Table 6.

Scenario When users record their intents with the FingerTip APP, they need to select the category of the location they are in. Specifically, they can choose from the following 12 common categories: residence, office, school, dining place, shopping mall, medical institution, entertainment and leisure venue, sports venue, cultural venue, transportation, urban street, and natural outdoor spaces. If users think that none of these categories can describe the location they are in, they can fill in a new category on their own.

A.5 DATA SPLITS

Table 7: Details on FingerTip 20K train, validation and test splits.

Split	# Episodes	# Screens	# Apps	# Categories
Train	16000	177674	460	40
Vali	4411	32859	41	27
Test-suggestion	1000	10412	155	38
Test-execution	200	2074	68	31

We created a training set, a validation set, and two test sets. The number of episodes and features in these sets are detailed in Table 7. Please note that the two test sets contain partially overlapping episodes. The test sets were formed by randomly sampling the last 20% of the data sorted by time of each user, and then concatenated to ensure coverage of all users and that the proportion of data from each user in the test sets is equal to their proportion in all data. These test sets were used in all experiments. The collection method of the training set is similar to that of the test sets, except that it is sampled from the first 60% of the data.

A.6 SUPPLEMENTARY EXPERIMENT RESULTS

A.6.1 CONTRIBUTION OF SCREENSHOTS AND HISTORICAL INTENTS

Our intention for the main results in Table 3 was to establish a baseline for the most challenging version of proactive task suggestion, where the agent has zero screenshots and must rely solely on historical and contextual data. This highlights the inherent difficulty of the task. To explore the performance of the agent under more screenshots or more historical information, we supplemented the experiments and obtained the following data in Table 8 (all using GPT4.1). Besides, we have already demonstrated the variation of performance with the number of screenshots in Figure 6.a.

Table 8: Performance of proactive task suggestion under different number of input screenshots or historical intents.

Setting	SR_1 (%)	Sim_1
0 screenshot + $20 I_{history}$	7.2	0.35
0 screenshot + All I_{history}	9.6	0.38
3 screenshots + No $I_{history}$	4.3	0.45
3 screenshots + 20 $I_{history}$	9.9	0.53
3 screenshots + All $I_{history}$	13.8	0.55

0 screenshot + $20\ I_{\rm history}$ are the results we present in Table 3. For All $I_{\rm history}$, we use DeepSeek-V3 (Liu et al., 2024) to summarize the 20 most relevant historical intents of the user to the current time and scenario among all historical intents. Additionally, we also tested the results of providing 3 initial screenshots and mixing them with All $I_{\rm history}$. Both providing more screenshots and historical information can improve performance, but there is still much room for improvement. Offering more screenshots would lose the predictive meaning of this task and significantly increase costs. We hope that the agent can complete proactive task suggestion by relying on as few screenshots and historical information as possible. When $I_{\rm history}$ was removed (cold-start users) while keeping three screenshots visible, the success rate dropped to 4.3%, indicating a significant performance decline. It is evident that historical intents are crucial for predicting current intents, and relying solely on screenshots cannot effectively accomplish proactive task suggestion.

A.6.2 CONTRIBUTION OF CONTEXTUAL INFORMATION

To study the contribution of each contextual information in the input to the proactive task suggestion, we supplemented the ablation study (all using GPT4.1) and obtained the following results in Table 9.

w/ User profile, Time, Scenario are the results we present in Table 3. Eliminating User profile, Scenario, and Time all lead to performance degradation, among which the elimination of Time causes

Table 9: Performance of proactive task suggestion under different contextual information.

Setting	SR_1 (%)	Sim_1
w/ User profile, Time, Scenario	7.2	0.35
w/o User profile	6.5	0.32
w/o Scenario	6.1	0.31
w/o Time	4.1	0.28

the most significant decline, indicating that time might be the most crucial factor in the patterns of user intent.

A.6.3 Performance of Personalized Task execution

In personalized task execution, we provide the agent with an action sequence of a similar task for in-context learning. However, this similar task might be the same as the current one, as the user has performed the same task before, and the agent might cheat on the same task. We used DeepSeek-V3 (Liu et al., 2024) to determine whether the retrieved similar tasks and the current task could be regarded as the same task. If they were the same, we moved on to the next similar task until they could no longer be considered the same. Using this method, we re-conducted the experiment on UI-TARS-1.5-7B, and the performance in Table 10 showed no significant difference from the original. Therefore, we believe there is no obvious cheating phenomenon. While tasks may be the same, the exact UI states are unlikely to be identical, so is the action sequence. The goal is for the agent to generalize a user's style of interaction, not replicate a specific trace.

Table 10: Performance of personalized task execution under different in-context learning.

Setting	SR_2 (%)	Sim_2	Step Ratio
most similar task	38.5	1.06	1.22
most similar (not the same) task	37.5	1.03	1.23

A.7 PROMPTS FOR THE LLM AGENTS

864

865 866

867

885 886

887

A.7.1 PROMPT FOR PROACTIVE TASK SUGGESTION

```
868
      You are an Android GUI agent. You are given the first few screenshots of
      the user's action (arranged in chronological order) and some
869
      supplementary information. You need to infer the user's intent.
870
871
      ## Input
872
      User_profile: {profile}
873
      Time: {time}
      Scenario: {scenario}
874
      Previous_intents: {previous_intents}
875
876
      ## Note
877
       - Express the user's intent unambiguously in one Chinese sentence,
      including all necessary information.
878
       - Clearly state the name of the app which the user is using, and the
879
      final effect the user wants to achieve.
880
      - Previous_intents contains the user's intents at certain times and in
881
      certain scenarios in the past.
882
       - Do not output anything other than the user's intent.
883
      The user's intent:
884
```

A.7.2 PROMPT FOR PERSONALIZED TASK EXECUTION

```
888
      You are an Android GUI agent. You are given an instruction and current
      screenshot and some supplementary information. You need to perform the
890
      next action to complete the instruction.
891
892
      ## Input
      User_instruction: {instruction}
893
      User_profile: {profile}
894
      Screen_width_height: {size}
895
      Screen_description: {screen_description}
896
      Actions_reference: {actions_reference}
897
      Previous_actions: {previous_actions}
898
      ## Action Space
899
      click(coordinates=(x,y), content='')
900
      long_click(coordinates=(x,y), content='')
901
      type (text='')
902
      scroll(coordinates=(x,y), direction='down or up or right or left')
      press_back()
903
      press_home()
904
      press_recent()
905
      wait()
906
      finished()
907
      ## Note
908
       - 'coordinates' should represent the coordinates of the click point. The
909
      origin is the upper left corner of the screenshot, with x increasing to
910
      the right and y increasing downward.
911
       - 'content' should represent the original text at the click point or the
912
      description of the icon, usually in Chinese.
       - 'text' should represent all the original text that the user intends to
913
      input. (usually in Chinese, and usually included in User_instruction)
914
       - 'press_back()', 'press_home()', 'press_recent()' means that go to
915
      previous screen, home screen, recent apps screen, respectively.
916
        'wait()' means that wait until the next observation is received. This
917
      usually occurs during loading or switching windows.
      - 'finished()' means that the instruction is completed.
```

- Screen_description contains some correct 'content' and 'coordinates' of the UI, which can be directly referenced.

- Actions_reference represents the complete sequence of actions that the user performed when executing a similar instruction in the past, which can be used for reference.
- ${\hspace{0.25cm}\text{-}\hspace{0.25cm}}$ Previous_actions contains the sequence of actions you have already performed under the current instruction.
- $\mbox{-}$ Only one action in Action Space can be taken. Do not output anything other than the action to take.

The action to take: