m-Eternal Domination and Variants on Some Classes of Finite and Infinite Graphs

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Abstract. We study the m-ETERNAL DOMINATION problem, which is the following two-player game between a defender and an attacker on a graph: initially, the defender positions k guards on vertices of the graph; the game then proceeds in turns between the defender and the attacker, with the attacker selecting a vertex and the defender responding to the attack by moving a guard to the attacked vertex. The defender may move more than one guard on their turn, but guards can only move to neighboring vertices. The defender wins a game on a graph G with G guards if the defender has a strategy such that at every point of the game the vertices occupied by guards form a dominating set of G and the attacker wins otherwise. The G is the smallest value of G for which G is a defender win.

We show that m-ETERNAL DOMINATION is NP-hard, as well as some of its variants, even on special classes of graphs. We also show structural results for the DOMINATION and m-ETERNAL DOMINATION problems in the context of four types of infinite regular grids: square, octagonal, hexagonal, and triangular, establishing tight bounds.

Keywords: Eternal Domination \cdot Roman Domination \cdot Italian Domination \cdot NP-hardness \cdot Bipartite Graphs \cdot Split Graphs \cdot Infinite Grids.

1 Introduction

A subset S of vertices in a simple undirected graph G is called a *dominating* set if every vertex outside of S has a neighbor in S. Finding a smallest-sized dominating set is a fundamental computational problem, and indeed, several variations of this basic premise have been considered in the literature [19].

In this work, our focus is on the *m*-eternal version of the DOMINATION problem, where we think of the vertices of the dominating set as being occupied by "guards" that can move in response to "attacks" on the vertices. Specifically, we consider the following two-player graph game. To begin with, the defender

places k guards on the vertices of the graph. The game continues with alternating turns between the attacker and the defender. On each turn, the attacker chooses a vertex to attack, and the defender responds by repositioning guards, ensuring at least one guard moves onto the attacked vertex. The defender may relocate multiple guards during a turn, but each guard can only move to an adjacent vertex. The defender wins if there exists a strategy that maintains a dominating set of vertices occupied by guards throughout the entire game. Otherwise, the attacker wins. The m-eternal domination number of a finite graph G is the smallest value of k for which the defender wins.

Two variations of the domination problem are ROMAN DOMINATION and ITALIAN DOMINATION. A Roman dominating function on a graph G=(V,E) is a function $f:V\to\{0,1,2\}$ such that every vertex v with f(v)=0 has at least one neighbor u with f(u)=2. The weight of a Roman dominating function is the sum $\sum_{v\in V} f(v)$. The Roman domination number $\gamma_R(G)$ is the minimum weight of a Roman dominating function on G. This concept is inspired by the defensive strategy of the Ancient Roman Empire, where guards were stationed such that every unguarded position was adjacent to a doubly guarded position. An Italian dominating function on a graph G=(V,E) is a function $f:V\to\{0,1,2\}$ such that for every vertex v with f(v)=0, the sum of f(u) over all neighbors u of v is at least 2. The weight of an Italian dominating function is the sum $\sum_{v\in V} f(v)$. The Italian domination number $\gamma_I(G)$ is the minimum weight of an Italian dominating function on G. This concept generalizes Roman domination by allowing more flexible assignments of resources to vertices and their neighbors.

Given the context of warfare, it is very natural to propose studying the "eternal" variations of Roman and Italian domination: presumably, regions will be attacked more than once, and the guards will have to find ways of reconfiguring themselves so that they maintain the defense invariants that they started with.

Our Contributions. In Section 3, we consider the computational complexity of the *m*-ETERNAL DOMINATION problem and the Roman and Italian variants in the *m*-eternal setting. We show that *m*-ETERNAL DOMINATION (and its connected variant, where we require the locations of the guards to induce a connected subgraph) is NP-hard even on bipartite graphs of diameter four (Theorem 1); and the *m*-ETERNAL ROMAN DOMINATION and *m*-ETERNAL ITALIAN DOMINATION problems are NP-hard even on split graphs (Theorems 2 and 3).

It is well known [1] that for split graphs, the eternal domination number is at most its domination number plus one, and a characterization of the split graphs which achieve equality is given. The authors also show that the decision versions of DOMINATION and m-ETERNAL DOMINATION are NP-complete, even on Hamiltonian split graphs. Moreover, computing the eternal domination number can be solved in polynomial time for any subclass of split graphs for which the domination number can be computed in polynomial time, in particular for strongly chordal split graphs.

In Section 4, we focus on structural results for the DOMINATION and m-ETERNAL DOMINATION problems in the context of four types of infinite regular grids: square, octagonal, hexagonal, and triangular. We prove m-eternal dominating sets that are optimal according to a parameter (that will be defined later) expressing the concept of minimality in infinite graphs.

We highlight that exact results for the eternal domination number are given in [13,17,25] and, more recently, in [14], for grids with either 2 or 3 rows, and in [3] for grids with 4, 5, or 6 rows. When G is a general $n \times m$ square grid, it is clear that the eternal domination number must be at least as large as the domination number, so by the result in [18], it must be at least $\lfloor \frac{(n-2)(m-2)}{5} \rfloor - 4$; the best-known upper bound was determined in [22], and is $\frac{m}{5} + O(n+m)$, thus showing that the eternal domination number is within O(m+n) of the domination number.

2 Preliminaries

In this section, we introduce definitions and terminology that will be relevant to our discussions later. We will be dealing with simple undirected graphs denoted by G = (V, E). The degree of a vertex v is the number of edges incident to v. An independent set or clique is a subset of vertices such that no or every possible edge is present, respectively. The neighborhood of a vertex v, denoted N(v), is the set of all vertices adjacent to v. The closed neighborhood of a vertex v, denoted N[v], is the set $N(v) \cup \{v\}$. A graph is bipartite if its vertex set V can be partitioned into two disjoint independent sets U and V. A split graph is a graph in which the vertex set V can be partitioned into a clique and an independent set. In this paper, we say that a graph G = (V, E) is infinite if V is countably infinite. For more detailed graph terminology, we refer to [11], while for computational complexity terminology, we refer to [15].

2.1 Domination, *m*-eternal dominations and variants

We first introduce the definitions of domination, Roman domination, and Italian domination. Then, we give the concept of an m-eternal domination game and define all the previous kinds of domination under this light.

Definition 1. [2,27] A dominating set for a graph G = (V, E) is a subset $D \subseteq V$ such that every vertex not in D is adjacent to at least one vertex in D. The domination number $\gamma(G)$ is the minimum cardinality of a dominating set in G. If the subgraph induced by D in G is connected, then D is said to be a connected dominating set.

The DOMINATION problem (which is to determine a minimum dominating set for graphs) is NP-hard even for planar graphs [15] and bipartite graphs of diameter three [24].

Definition 2. [28] A Roman dominating function on a graph G = (V, E) is a function $f: V \to \{0, 1, 2\}$ such that every vertex v for which f(v) = 0 is adjacent to at least one vertex u for which f(u) = 2. The Roman domination number $\gamma_R(G)$ is the minimum weight $\sum_{v \in V} f(v)$ of a Roman dominating function on G. If the subgraph induced by $D = \{v \mid f(v) \neq 0\}$ in G is connected, then D is said to be a connected Roman dominating set.

The ROMAN DOMINATION problem (which is to determine the Roman domination number of a graph) is NP-hard even for split graphs, bipartite graphs, and planar graphs [10], for chordal graphs [23], and for subgraphs of grids [26].

Definition 3. [8,20] An Italian dominating function on a graph G = (V, E) is a function $f: V \to \{0,1,2\}$ such that, for every vertex v for which f(v) = 0, the sum of the function values of the neighbors of v is at least 2. The Italian domination number $\gamma_I(G)$ is the minimum weight $\sum_{v \in V} f(v)$ of an Italian dominating function on G. If the subgraph induced by $D = \{v \mid f(v) \neq 0\}$ in G is connected, then D is said to be a connected Italian dominating set.

The Italian Domination problem (which is to determine the Italian domination number of a graph) is NP-hard even for bipartite planar graphs, chordal bipartite graphs [12], and split graphs [9].

The *m*-eternal domination game is a two-player turn-based game on graph G: a team of guards initially occupies a dominating set on a graph G. An attacker then assails a vertex without a guard on it; the defender exploits the guards to defend against the attack: one of the guards has to move to the attacked vertex from one of its neighbors, while the defender can choose whether to move or not the remaining guards to one of its neighbor vertices. This attack-defend procedure continues eternally. The defender wins if they can eternally maintain a dominating set against any sequence of attacks; otherwise, the attacker wins.

Definition 4. [16] An m-eternal domination set for a graph G = (V, E) is a subset $D \subseteq V$ where a defender can place its guard and win the m-eternal domination game. The m-eternal domination number of G, denoted by $\gamma^{\infty}(G)$, is the minimum number of guards required to defend an indefinite sequence of attacks.

We use the term *configuration* to refer to the position of guards during the *m*-eternal domination game. Note that when configurations correspond to dominating functions rather than sets, the value of the function at a vertex indicates the number of guards occupying the vertex, and again multiple guards are allowed to move in one round; no vertex accommodates more than two guards in a configuration, and guards can only move to neighbor vertices. By requiring the configuration of guards at every step to correspond to a Roman dominating function or to an Italian dominating function instead of a dominating set, we obtain the *m*-eternal Roman domination and *m*-eternal Italian domination

games, and the minimum numbers of guards necessary to defend forever G are the m-eternal Roman domination and m-eternal Italian domination numbers and denoted by $\gamma_R^{\infty}(G)$ and $\gamma_I^{\infty}(G)$, respectively. Similarly to what we did for m-domination, Roman and Italian domination, it is possible to define m-eternal connected domination and m-eternal Roman and Italian connected domination.

In this paper, we do not consider variations of these games where only one guard is allowed to move in one step (as, e.g., in [5]). To distinguish from this variation, the m- prefix highlights that multiple guards are allowed to move.

We focus on the m-ETERNAL DOMINATION computational problem, consisting in taking as input a graph G and determining $\gamma^{\infty}(G)$. The m-ETERNAL ROMAN DOMINATION and m-ETERNAL ITALIAN DOMINATION problems are defined analogously.

When we refer to the m-ETERNAL DOMINATION problem (and variants), unless mentioned otherwise, we are referring to the optimization version of the question, as opposed to explicitly calling it the minimization problem.

2.2 Infinite Regular Grids

We work with four kinds of infinite regular grids, shown in Figure 1. In the following definitions and the rest of the paper, we adopt the following convention. We imagine that the vertices of the infinite grids occupy integer coordinates of the Cartesian plane. Despite this, we do not mean to consider the grids as graphs embedded in a metric space. We make this assumption to describe the moving strategies in an easier way.

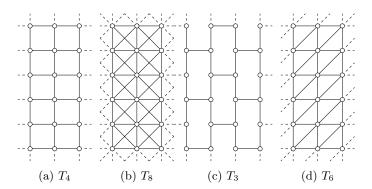


Fig. 1: The four considered infinite regular grid graphs.

We formally define the infinite regular grids as follows:

- **infinite square grid** T_4 (see Figure 1a): every vertex (x, y) is connected with (x + 1, y), (x - 1, y), (x, y + 1) and (x, y - 1);

- infinite octagonal grid T_8 (see Figure 1b): every vertex (x, y) is connected with (x + 1, y), (x 1, y), (x, y + 1), (x, y 1), (x 1, y 1), (x + 1, y + 1), (x 1, y + 1) and (x + 1, y 1);
- infinite hexagonal grid T_3 (see Figure 1c): every vertex (x, y) is connected both with (x, y + 1) and with (x, y 1); moreover, every vertex (x, y) is connected to (x + 1, y) if x + y is even and to (x 1, y) otherwise;
- **infinite triangular grid** T_6 (see Figure 1d): every vertex (x, y) is connected with (x+1, y), (x-1, y), (x, y+1), (x, y-1), (x-1, y-1) and (x+1, y+1).

2.3 Optimal Domination

For infinite graphs, the meaning of a minimum set with respect to a set of properties is far from clear. Some related work uses notions of density that can be applied to infinite graphs with respect to different properties, e.g., for cops configurations in Cops and Robber games [4] or for eternal vertex cover configurations on regular grids [6]. In the context of dominating sets for infinite graphs, we choose to avoid working with a density-based approach and instead adopt a local cardinality-based approach to determine when a proposed dominating set is optimal. Given two dominating sets S and T, we say that S is at least as good as T if there is an injective map from S to T, that is, the cardinality of S is smaller or equal to that of T. A dominating set is optimal if it is at least as good as every other dominating set of G. We now turn to a stronger notion of optimality.

Consider an infinite graph G with finite maximum degree. Given a subset S of V(G) and a vertex $v \in V(G)$, we define the domination index of v with respect to S as $|S \cap N[v]|$. A dominating set S is strongly optimal if, for every vertex v of the graph, the domination index of v with respect to S is exactly one⁴. Note that a strongly optimal dominating set may not exist: for example, consider the infinite complete bipartite graph S with S with S and S and S are S and S and S are S and S are S and S are S as a strongly optimal dominating set, if it exists, is also optimal:

Lemma 1. If S is a strongly optimal dominating set and T is any dominating set of an infinite graph G with finite maximum degree, then S is at least as good as T.

Proof. Consider the following map $f: S \to T$ defined as follows: for every vertex $v \in S$, let f(v) be an arbitrarily chosen vertex from $N[v] \cap T$.

We first show that f is well-defined. Since T is a dominating set, for every $v \in S$, we have $N[v] \cap T \neq \emptyset$, so there always exists a vertex to which v can be mapped.

⁴ In the context of finite graphs, a dominating set such that every vertex is uniquely dominated is called an *exact dominating set*, and because of connections with coding theory, in some settings such dominating sets are called *perfect codes*.

Next, we prove that f is injective. Suppose, by contradiction, that there exist two distinct vertices $u, v \in S$ such that f(u) = f(v) = w for some $w \in T$. This implies that $w \in N[u] \cap N[v]$, and consequently, the domination index of w with respect to S would be at least two. However, this contradicts the fact that S is a strongly optimal dominating set, where every vertex must have a domination index of exactly one. Therefore, f is an injective map from S to T, proving that S is at least as good as T.

To recap, we have the following definitions:

Definition 5. Let G be an infinite graph with finite maximum degree and $S \subseteq V(G)$. The domination index of a vertex $v \in V(G)$ with respect to S is defined as $|S \cap N[v]|$. A dominating set S is optimal if for any other dominating set S of S, there exists an injective map from S to S. A dominating set S is strongly optimal if for every vertex S is exactly one.

3 Complexity Results for Variants of the m-Eternal Domination

In this section, we prove that the considered problems are all NP-hard, even for interesting subclasses of graphs. Due to space restrictions, we omitted some proofs and refer the reader to the full version [7].

We preliminarily give a property whose analogous for the m-eternal vertex cover problem has been proved in [21].

Lemma 2. Let G be a graph and Z be a connected dominating set of G. Then $\gamma^{\infty}(G) \leq |Z| + 1$.

Proof. Initially, place a guard on each vertex of $Z \cup \{v\}$, where v is any vertex not belonging to Z. We prove that this configuration is an m-eternal dominating set. At every step of the attacking sequence, we will maintain the following invariant: there are guards on Z and one extra guard anywhere else, which we will refer to as the floating guard, positioned on vertex v. Whenever any vertex v' that does not have a guard is attacked, let $v_0, \ldots v_k$ be any path such that $v_0 = v$, $v_k = v'$ and $v_i \in Z$ for every $i = 1, \ldots, k-1$, for some $k \geq 1$. For every i < k, the guard on v_i moves to v_{i+1} . After that, each vertex of $Z \cup \{v'\}$ is occupied by a guard, thus restoring both the invariant and successfully defending the attack. The size of $Z \cup \{v\}$ is |Z| + 1 by construction, and since G is finite, the size is preserved through sequences of dominating sets defending the attack sequence.

Theorem 1. The m-Eternal Domination and m-Eternal Connected Domination problems are NP-hard, even on bipartite graphs of diameter 4.

Proof. We describe here a reduction from the DOMINATING SET problem. Let $\langle G=(V,E);k\rangle$ be an instance of DOMINATING SET, and let $V=\{v_1,\ldots,v_n\}$. Construct a bipartite graph $H=(A\cup B,F)$ as follows: let $U=\{u_1,\ldots,u_n\}$ and $W=\{w_1,\ldots,w_n\}$ be two copies of V; let $\{p_1,\ldots,p_{n+1}\}=P$ and w be new vertices. We define $A=U\cup P$ and $B=W\cup \{w\}$. The set of edges F is defined as follows: u_i is adjacent to w_j iff $(v_i,v_j)\in E$ or i=j; moreover, (w,u_i) and (w,p_j) are both in F for each $i=1,\ldots,n$ and $j=1,\ldots,n+1$. An example of this construction is shown in Figure 2. Now we consider the instance $\langle H;k+2\rangle$ for the m-ETERNAL DOMINATION and argue the equivalence of these instances.

Forward Direction. Let $S \subseteq V$ be a dominating set of G of size at most k. Initially, place a guard on each u_i for every $v_i \in S$. Denote this set of vertices which are occupied by guards in A as T. The set $T \cup \{w\}$ induces a connected subgraph on H because every vertex in A is adjacent to w. This set also forms a dominating set of H because every vertex in A is adjacent to w, and every vertex in B has a neighbor in T because S is a dominating set of G. By Lemma 2, $\gamma^{\infty}(H) \leq |T \cup \{w\}| + 1 = k + 2$.

Reverse Direction. Suppose H has a winning strategy with k+2 guards, and consider one of its configurations such that P and the vertex w have exactly one guard each: such configuration can be obtained from any other configuration after a vertex of P that does not have a guard is attacked. Let S be the subset of $V \colon v_i \in S$ if and only if u_i or w_i has a guard. Clearly, S has size at most k and is a dominating set for S. Indeed, suppose there exists a vertex $v_i \in V \setminus S$ that has no neighbor in S; thus, w_i has no guard, and has no neighbor that has a guard, and that the considered configuration is not part of a winning strategy, a contradiction.

Finally, we consider the instance $\langle H; k+2 \rangle$ for the *m*-Eternal Connected Domination. To prove the equivalence of these instances, we reuse the previous proof and note that all configurations in a winning strategy are connected. \Box

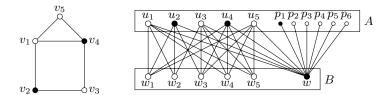


Fig. 2: The construction for the proof of Theorem 1. On the left, graph G for which the black vertices represent a (minimum size) dominating set. On the right, auxiliary bipartite graph H = (A, B; F) for which the black vertices represent a configuration of an m-eternal dominating set.

Lemma 3. Let G be a graph and Z be a connected dominating set of G. Then $\gamma_R^{\infty}(G) \leq 2|Z| + 1$.

Theorem 2. The m-Eternal Roman Domination and m-Eternal Connected Roman Domination problems are NP-hard, even on split graphs.

Proof. We describe here a reduction from the DOMINATING SET problem. Let $\langle G=(V,E);k\rangle$ be an instance of DOMINATING SET and let $V=\{v_1,\ldots,v_n\}$. Construct a split graph $H=(A\cup B,F)$ as follows: let $A=\{u_1,\ldots,u_n\}$ be a copy of V and let $B=\{w_i^{(j)}\}$ for $1\leqslant i\leqslant n$ and $1\leqslant j\leqslant 2n+2$ contain 2n+2 copies of V. The edge set F is defined as follows: A induces a clique and B induces an independent set; moreover, u_i is adjacent to $w_k^{(j)}$ for all j iff $(v_i,v_k)\in E$ and u_i is adjacent to $w_i^{(j)}$ for all i,j. An example of this construction is shown in Figure 3. Now we consider the instance $\langle H;2k+1\rangle$ for the m-ETERNAL ROMAN DOMINATION and argue on the equivalence of these instances.

Forward Direction. Let $S \subseteq V$ be a dominating set of size at most k. Let T be the set of vertices in A that corresponds to S, *i.e.* $u_i \in T$ if and only if $v_i \in S$. The set T induces a connected subgraph because it is a subset of A, which induces a clique in H. By construction, T is also a dominating set of H, because S is a dominating set of G. By Lemma S, $\gamma_{R}^{\infty}(H) \leq 2|T| + 1 \leq 2k + 1$.

Reverse Direction. Suppose that H has a winning strategy with at most 2k+1 guards, and consider an initial configuration induced by a Roman dominating function f of H such that the weight is equal to 2k+1. For every $1 \leq j \leq 2n+2$, let $W^{(j)} := \{w_i^{(j)} \mid 1 \leq i \leq n\}$. Moreover, let $S \subseteq A$ be the set of vertices in A that have value two each, i.e., $s \in S$ if and only if f(s) = 2. By the pigeon-hole principle, there exists a $1 \leq j \leq 2n+2$ such that $W^{(j)}$ contains only zero value vertices, i.e., $f(w_i^{(j)}) = 0$ for every $i \leq n$. Since $W^{(j)}$ only has neighbors in A, set S must be a dominating set of G, and this means that G has a dominating set S of size at most k.

Finally, we consider the instance $\langle H; 2k+1 \rangle$ for the *m*-Eternal Connected Roman Domination. To prove the equivalence of these instances, we reuse the previous proof and note that all considered configurations involved in a winning strategy are connected.

The proof of our next hardness result uses a construction in the same style as the one used for proving Theorem 2.

Lemma 4. Let G be a graph and f be an Italian dominating function of G such that the vertices with non-zero value induce a connected subgraph; moreover, let t_f denote the weight of f. Then $\gamma_I^{\infty}(G) \leq t_f + 1$.

Theorem 3. The m-Eternal Italian Domination and m-Eternal Connected Italian Domination problems are NP-hard, even on split graphs.

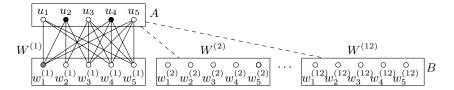


Fig. 3: The construction for the proof of Theorem 2 for graph G of Figure 2. In the auxiliary split graph H=(A,B;F), the edges between A and $W^{(1)}$ are shown in the figure, while the edges between A and every other $W^{(j)}$, $j \in [2,12]$, are dashed lines and those within A are omitted. The color of the vertices represents a configuration of an m-eternal Roman dominating function of H: two, one, and zero guards are placed on black, grey, and white vertices, respectively.

4 m-Eternal Domination on Infinite Regular Grids

In this section, we provide a starting configuration and a strategy for the *m*-domination of infinite regular grids. We show that in all cases, we are able to obtain strongly optimal dominating sets that are also *m*-eternal dominating sets. We start with infinite square grids first.

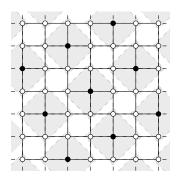
Theorem 4 (m-Eternal Domination on the infinite Square Grid). There is a strongly optimal dominating set for the infinite square grid T_4 that is also an m-eternal dominating set.

Proof. We define vertex set S_4 on the infinite square grid T_4 as follows: $(0,0) \in S_4$; moreover, if $(x,y) \in S_4$ then also (x+2,y+1), (x-1,y+2), (x-2,y-1) and (x+1,y-2) belong to S_4 . This vertex set can be visualized in the left graph in Figure 4.

Note that the infinite set of closed neighborhoods N[s] with $s \in S_4$ forms a partition of the vertices of T_4 ; therefore, we claim that S_4 is a dominating set of T_4 . Indeed, observe that for any guard at (x, y) there is a guard at (x', y') = (x + 2, y + 1), a guard at (x'', y'') = (x' + 1, y' - 2) = (x + 3, y - 1) and a guard at (x''', y''') = (x'' + 2, y'' + 1) = (x + 5, y); hence, looking at the rows of T_4 , for each guard at (x, y), the four vertices to its right do not contain any guard. Nevertheless, (x + 1, y) is dominated by the guard at (x, y); (x + 2, y) is dominated by the guard at (x', y') = (x + 2, y + 1); (x + 3, y) is dominated by the guard at (x'', y'') = (x + 3, y - 1); (x + 4, y) is dominated by (x''', y''') = (x + 5, y). The generality of the reasoning proves that S_4 is a dominating set of T_4 .

Moreover, by construction, it holds $|N[v] \cap S_4| = 1$ for every $v \in V$: this means that S_4 is strongly optimal. Next, we show that S_4 is a configuration of an m-eternal dominating set of T_4 . Indeed, consider an attack on a vertex $v \in V \setminus S_4$. Since S_4 is a dominating set and, by construction, there exists a unique vertex $s \in S_4$ that is a neighbor of v. It is not restrictive to consider the case $s = (i^*, j^*)$ and $v = (i^* + 1, j^*)$ (the other three cases are analogous). For every $(i, j) \in S_4$

(including (i^*, j^*)), the guard in (i, j) moves to (i + 1, j). The new position of the guards is a translation of S_4 by one unit in the same direction, and thus still forms a dominating set. Therefore, with this strategy, the guards move along configurations of an m-eternal dominating set.



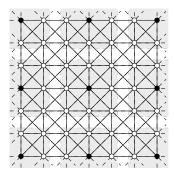


Fig. 4: On the left, graph T_4 and, on the right, graph T_8 . In both figures, the black vertices represent the dominating set S described in the proof of Theorems 4 and of 5, respectively, while the shadowed zones represent how vertices of S dominate their neighbors, thus creating a partition of the vertices of the graph.

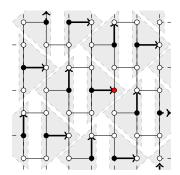
We next turn to infinite octagonal grids. The following theorem shows that we can come up with a strongly optimal dominating set that is also an eternal dominating set. The argument here is similar in spirit to square grids. The proposed solution can be visualized in the right graph in Figure 4.

Theorem 5 (m-Eternal Domination on the infinite Octagonal Grid). octagonalGrid There is a strongly optimal dominating set for the infinite octagonal grid T_8 that is also an m-eternal dominating set.

Also for the infinite hexagonal and triangular grids we obtain strongly optimal eternal dominating sets for both cases. While the proofs are deferred to the full version [7], we refer the reader to Figures 5 and 6 for an intuition of how our dominating sets are constructed.

Theorem 6 (m-Eternal Domination on the infinite Hexagonal Grid). There is a strongly optimal dominating set for the infinite hexagonal grid T_3 that is also an eternal dominating set.

Theorem 7 (m-Eternal Domination on the infinite Triangular Grid). There is a strongly optimal dominating set for the infinite triangular grid T_6 that is also an eternal dominating set.



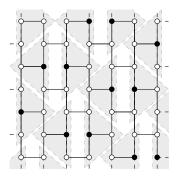
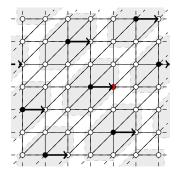


Fig. 5: The graph T_3 . In both figures, the black vertices represent the dominating set S described in the proof of Theorem 6, while the shadowed zones represent how vertices of S dominate their neighbors, thus creating a partition of the vertices of the graph. On the left, the thick arrowed edges represent the movement of the guards along the edges when the red vertex is attacked.



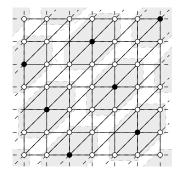


Fig. 6: The graph T_6 . In both figures, the black vertices represent the dominating set S described in the proof of Theorem 7, while the shadowed zones represent how vertices of S dominate their neighbors, thus creating a partition of the vertices of the graph. On the left, the thick arrowed edges represent the movement of the guards along the edges when the red vertex is attacked.

5 Conclusions and Open Problems.

We studied the *m*-ETERNAL DOMINATION problem and variants on classes of finite graphs and infinite regular grids. In particular, we showed that *m*-ETERNAL DOMINATION is NP-hard even on bipartite graphs of diameter four. Moreover, the *m*-ETERNAL ROMAN DOMINATION and *m*-ETERNAL ITALIAN DOMINATION problems are NP-hard even on split graphs. Finally, we showed optimal results for the DOMINATION and *m*-ETERNAL DOMINATION problems when considering four types of infinite regular grids: square, octagonal, hexagonal, and triangular.

For future work, we propose the following directions. We would like to consider infinite grids with vertex replacement, i.e., each vertex in the grid is replaced with a fixed graph H and carrying across edges as complete bipartite graphs or matchings, or boundary-based connections. This preserves the overall infinite grid structure, but is also more intricate because, locally, the structure of H would come into play. We have some preliminary observations for simple choices of H and believe this to be a rich direction for future work. It is also interesting to determine the m-eternal dominating set for infinite grids with 1,2, or 3 bounded directions, and also extend our results to other domination variants (including the Roman and Italian questions).

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