

# 000 001 002 003 004 005 FG-CLIP 2: A BILINGUAL FINE-GRAINED VISION- 006 LANGUAGE ALIGNMENT MODEL 007 008 009

010 **Anonymous authors**  
011 Paper under double-blind review  
012  
013  
014  
015  
016  
017  
018  
019  
020  
021  
022  
023  
024  
025  
026  
027

## ABSTRACT

028  
029 Fine-grained vision-language understanding requires precise alignment between  
030 visual content and linguistic descriptions, a capability that remains limited in  
031 current models, particularly in non-English settings. While models like CLIP  
032 perform well on global alignment, they often struggle to capture fine-grained  
033 details in object attributes, spatial relations, and linguistic expressions, with limited  
034 support for bilingual comprehension. To address these challenges, we introduce  
035 FG-CLIP 2, a bilingual vision-language model designed to advance fine-grained  
036 alignment for both English and Chinese. Our approach leverages rich fine-grained  
037 supervision, including region-text matching and long-caption modeling, alongside  
038 multiple discriminative objectives. We further introduce the Textual Intra-modal  
039 Contrastive (TIC) loss to better distinguish semantically similar captions. Trained  
040 on a carefully curated mixture of large-scale English and Chinese data, FG-CLIP 2  
041 achieves powerful bilingual performance. To enable rigorous evaluation, we present  
042 a new benchmark for Chinese multimodal understanding, featuring long-caption  
043 retrieval and bounding box classification. Extensive experiments on 29 datasets  
044 across 8 tasks show that FG-CLIP 2 outperforms existing methods, achieving  
045 state-of-the-art results in both languages. We will release the model, code, and  
046 benchmark to facilitate future research on bilingual fine-grained alignment.  
047

## 1 INTRODUCTION

048 Vision-language alignment models (Tschannen et al., 2025; Chuang et al., 2025) have undergone  
049 rapid evolution in recent years, driven by pioneering works such as CLIP (Radford et al., 2021), which  
050 introduced large-scale contrastive pre-training on image-text pairs and demonstrated remarkable  
051 success in learning joint multimodal representations. These models excel at global alignment tasks  
052 such as zero-shot image classification and image-text retrieval, forming the foundation for a wide  
053 range of multimodal understanding systems (Zhu et al., 2025; Team et al., 2025a; Li et al., 2025a;  
Wu et al., 2025; Team et al., 2025b). Their ability to align visual and linguistic concepts without  
054 explicit supervision has enabled strong generalization to diverse scenarios, including visual question  
055 answering (Lu et al., 2025; Wang et al., 2025a), image captioning (Bai et al., 2025; Li et al., 2025b),  
056 and content-based retrieval (Zhang et al., 2024a; Wei et al., 2024). However, their performance  
057 often degrades on fine-grained understanding tasks that require discriminating between similar object  
058 attributes, spatial configurations, or semantic distinctions. Such tasks demand precise alignment at  
059 both visual and linguistic levels: visually, they involve recognizing objects, attributes, and their spatial  
060 arrangements; linguistically, they require distinguishing between semantically similar expressions.  
061 This performance gap stems from reliance on coarse-grained image-text pairs during training, which  
062 encourages thematic alignment while failing to capture the fine-grained correspondences essential for  
063 robust visual grounding or attribute recognition.

064 Several recent works have sought to address these limitations. Approaches such as FineCLIP (Jing  
065 et al., 2024) and LongCLIP (Zhang et al., 2024a) improve fine-grained understanding by incorporating  
066 region-level signals or supporting longer textual inputs. FG-CLIP (Xie et al., 2025) significantly  
067 advances the state of fine-grained modeling through large-scale data curation and attribute-based hard  
068 negative sampling. On the language side, Chinese-CLIP (Yang et al., 2022) and R2D2 (Xie et al.,  
069 2023) have laid the groundwork for Chinese vision-language alignment, yet they primarily focus  
070 on short-caption retrieval and lack support for fine-grained or region-level tasks. The development  
071 of fine-grained capabilities has thus remained largely confined to English, whereas Chinese models  
072

054 operate at a coarser semantic level. No existing framework unifies these directions, and there is a  
 055 notable absence of comprehensive benchmarks for evaluating fine-grained understanding in Chinese,  
 056 which hinders systematic progress in bilingual multimodal research.

057 To address these challenges, we propose FG-CLIP 2, a unified framework for bilingual fine-grained  
 058 vision-language alignment. Our training strategy employs a two-stage paradigm to progressively  
 059 refine model capabilities. In the first stage, we perform initial global alignment with both short and  
 060 long textual descriptions to capture coarse and detailed semantic content at the early phase of training.  
 061 In the second stage, we incorporate fine-grained learning objectives that improve regional alignment,  
 062 discriminative capability, and cross-modal ranking performance. To further refine the model’s ability  
 063 to distinguish similar region-level descriptions, we propose the Textual Intra-modal Contrastive (TIC)  
 064 loss, which learns from filtered hard negatives among high-similarity text pairs. FG-CLIP 2 is trained  
 065 on large-scale, high-quality bilingual datasets with careful curation, enabling strong performance in  
 066 both English and Chinese across diverse fine-grained vision-language tasks.

067 We further contribute a new benchmark suite to advance evaluation in Chinese multimodal under-  
 068 standing, featuring challenging tasks such as long caption image-text retrieval and bounding box  
 069 classification in Chinese that go beyond conventional short-text retrieval and assess fine-grained  
 070 comprehension more rigorously. Extensive experiments show that FG-CLIP 2 outperforms existing  
 071 models on 29 datasets across 8 vision-language tasks in both Chinese and English, demonstrating  
 072 powerful bilingual fine-grained vision-language alignment capability. To support future research and  
 073 real-world deployment, our model, code and benchmark will be made publicly available.

## 075 2 RELATED WORK

076 Vision-language alignment models trained on large-scale data, such as CLIP (Radford et al., 2021),  
 077 EVA-CLIP (Sun et al., 2023), SigLIP (Zhai et al., 2023), MetaCLIP (Xu et al., 2024) and DFN (Fang  
 078 et al., 2024) have demonstrated strong zero-shot capabilities but primarily focus on global semantic  
 079 alignment and are often trained on English-only corpora. While these models serve as backbones for  
 080 downstream tasks including multimodal reasoning (Bai et al., 2025), open-vocabulary detection (Fu  
 081 et al., 2025), and segmentation (Cho et al., 2024; Wang et al., 2025b), their lack of fine-grained and  
 082 multilingual understanding limits broader applicability.

083 Recent efforts aim to improve localization capability and dense feature alignment through region-  
 084 level supervision. Methods like AlphaCLIP (Sun et al., 2024), [UMG-CLIP \(Shi et al., 2024\)](#),  
 085 FineCLIP (Jing et al., 2024), and FG-CLIP (Xie et al., 2025) leverage bounding boxes or masked  
 086 regions to enhance local correspondence, while CLOC (Chen et al., 2024a), TIPS (Maninis et al.,  
 087 2025), and SigLIP 2 (Tschanne et al., 2025) introduce architectural or training enhancements for  
 088 richer feature generation. On the multilingual front, Chinese-CLIP (Yang et al., 2022) and R2D2 (Xie  
 089 et al., 2023) target Chinese understanding, and MetaCLIP 2 (Chuang et al., 2025) scales multilingual  
 090 data collection for broader language coverage. However, these works often treat fine-grained and  
 091 multilingual understanding separately, and none explicitly optimize both in a unified framework. This  
 092 gap inspires our work.

## 094 3 APPROACH

095 Figure 1 illustrates FG-CLIP 2, a vision-language model supporting Chinese and English. Our ap-  
 096 proach follows a two-stage hierarchical learning framework: the first stage establishes strong semantic  
 097 alignment by training on large-scale image-text pairs, each associated with both a short caption and  
 098 a long caption; the second stage extends this learning by incorporating region-level alignment and  
 099 fine-grained contrastive signals, enabling the model to preserve holistic scene understanding while  
 100 enhancing its ability to discriminate fine-grained visual-language correspondences in both languages.

### 103 3.1 ARCHITECTURE

104 We build upon the SigLIP 2 (Tschanne et al., 2025) dual-encoder framework, introducing key  
 105 adaptations for fine-grained understanding and bilingual alignment. For the text encoder, we extend  
 106 the maximum input length from 64 to 196 tokens to accommodate longer descriptions. We employ  
 107 the multilingual Gemma tokenizer (Team et al., 2024) with a 256K vocabulary. On the vision side, we

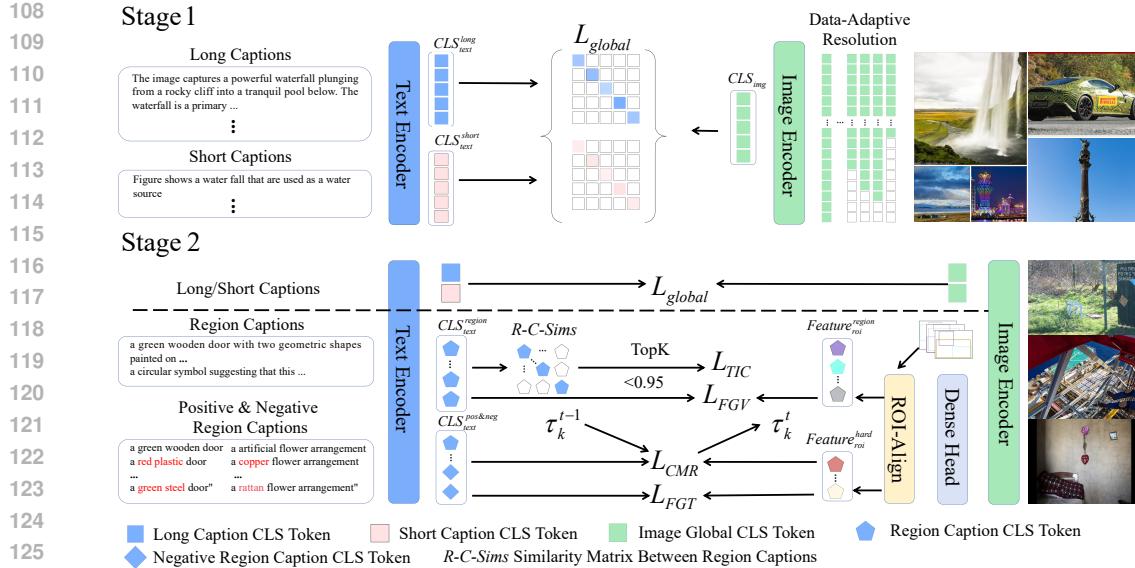


Figure 1: Overview of the FG-CLIP 2.

adopt a data-adaptive resolution strategy: the target resolution is selected from  $\{128, 256, 576, 784, 1024\}$  based on the maximum image size per mini-batch, avoiding the stochastic sampling of SigLIP 2 and ensuring consistent training and inference behavior with minimal upscaling or downscaling. Vision features are aggregated using a masked attention pooling (MAP) head (Zhai et al., 2022). We implement three model variants (Base, Large, and So400M (Alabdulmohsin et al., 2023)) to evaluate performance across different scales.

### 3.2 TRAINING OBJECTIVES

Our training proceeds in two stages. In Stage I, we optimize only the global alignment objective. In Stage II, we jointly optimize five complementary objectives:

$$\mathcal{L} = \lambda_1 \mathcal{L}_{\text{Global}} + \lambda_2 \mathcal{L}_{\text{FGV}} + \lambda_3 \mathcal{L}_{\text{FGT}} + \lambda_4 \mathcal{L}_{\text{CMR}} + \lambda_5 \mathcal{L}_{\text{TIC}}, \quad (1)$$

with fixed weights  $\lambda_1 = 1.0$ ,  $\lambda_2 = 0.1$ ,  $\lambda_3 = 0.5$ ,  $\lambda_4 = 0.4$ ,  $\lambda_5 = 0.1$ , chosen to ensure stable and effective multi-objective optimization. The following paragraphs detail each component. [The selection strategy for loss weights is detailed in Appendix G.](#)

**Global Alignment Learning.** We adopt the sigmoid loss from SigLIP (Zhai et al., 2023), which treats image-text matching as a binary classification. For each image-text pair, similarity scores are computed across all pairs in the batch, and logistic regression is applied to distinguish positive from negative pairs. To enrich textual supervision, we include both original short captions and long captions generated by Large Multimodal Models (LMMs). This dual-caption strategy provides complementary signals: concise labels for global semantics and detailed descriptions for richer context.

**Fine-Grained Visual (FGV) Learning.** To enable sub-image alignment, we generate dense image embeddings by introducing an additional self-attention module, circumventing the information bottleneck caused by CLS-only pooling in SigLIP 2. For each annotated region, we extract patch-level embeddings and apply ROIAlign (He et al., 2017) to obtain region-specific features. Corresponding text embeddings are derived from phrase-level descriptions aligned to each bounding box. The regional contrastive loss encourages alignment between matched region-text pairs, promoting fine-grained cross-modal understanding.

**Fine-Grained Textual (FGT) Learning.** Following FG-CLIP (Xie et al., 2025), we leverage hard negatives from the FineHARD dataset. Each positive region-text pair is paired with 10 semantically similar negatives, constructed by perturbing key attributes (e.g., color, count, action) while preserving

162 syntactic structure. The model is trained with a binary classification loss over the 1 positive and 10  
 163 negatives, encouraging the model to assign higher scores to the matched pair. This objective enhances  
 164 the model’s ability to discriminate subtle textual differences.  
 165

166 **Cross-modal Rank Loss with Global Threshold Synchronization.** We adopt the Cross-modal  
 167 Rank (CMR) loss (Zhang et al., 2024b) to enforce a margin between positive and hard negative pairs,  
 168 thereby strengthening the model’s discrimination of semantic boundaries. For a positive pair  $(I, T)$   
 169 and hard negative  $T_k$ , the loss is defined as:

$$170 \quad \mathcal{L}_{\text{CMR}} = \max(0, S(I, T_k) - S(I, T) + \tau_k), \quad (2)$$

172 where  $S(\cdot, \cdot)$  denotes cosine similarity. At training step  $t$ , the margin  $\tau_k$  is synchronized globally  
 173 across all GPUs via all-reduce, where  $\mathcal{B}_{\text{global}}$  denotes the union of all local batches across GPUs:

$$174 \quad \tau_k^t = \frac{1}{|\mathcal{B}_{\text{global}}|} \sum_{(I, T) \in \mathcal{B}_{\text{global}}} (S^{t-1}(I, T) - S^{t-1}(I, T_k)), \quad (3)$$

177 with  $S^{t-1}(\cdot, \cdot)$  denoting similarities computed at the previous step. This design ensures stable and  
 178 consistent thresholding in distributed training.  
 179

180 **Textual Intra-modal Contrastive Loss.** While cross-modal alignment ensures image-text corre-  
 181 spondence, the text encoder itself often lacks sufficient discriminative pressure to separate semanti-  
 182 cally similar but distinct region descriptions, which is critical for fine-grained visual grounding. To  
 183 address this, we propose the Textual Intra-modal Contrastive (TIC) loss, which operates purely within  
 184 the text modality to sharpen the text encoder’s representation space. Given a batch of region texts, we  
 185 compute pairwise similarities and filter out pairs with  $\text{sim} > 0.95$  to avoid over-penalization. The  
 186 top-10 most similar texts per sample are selected as hard negatives. The TIC loss is then defined as:

$$187 \quad \mathcal{L}_{\text{TIC}} = - \sum_{i=1}^N \log \frac{1}{\sum_{T_m \in \mathcal{T}_i} \exp(S(T_i, T_m))}, \quad (4)$$

190 where  $\mathcal{T}_i$  denotes the set of filtered hard negatives for text  $T_i$ . This encourages the text encoder to  
 191 assign lower similarity to hard negative pairs, thereby improving its ability to separate semantically  
 192 close but distinct region descriptions.  
 193

### 194 3.3 TRAINING DATA

196 In the first stage, we train on image-text pairs from diverse sources, with a particular emphasis on  
 197 enhancing semantic depth and linguistic coherence. For English, we adopt an enhanced version  
 198 of the LAION-2B dataset (Xie et al., 2025), where we augment the original short captions with  
 199 detailed long captions generated by LMMs. The original captions are often fragmented and contain  
 200 keyword stacking or irrelevant noise, making them insufficient for training models to understand  
 201 rich, compositional language. We retain original captions to preserve diversity of natural language  
 202 expressions, while simultaneously training on their enhanced long-caption counterparts. This dual-  
 203 caption strategy enables the model to learn from both concise, real-world descriptions and semantically  
 204 dense, contextually coherent narratives. For Chinese, we combine three datasets: Wukong (100  
 205 million pairs) (Gu et al., 2022), Zero (250 million pairs) (Xie et al., 2023), and a large-scale in-house  
 206 dataset (500 million pairs).

207 In the second stage, we extend training with fine-grained region-text pairs to further improve spatial  
 208 grounding. For English, we use the FineHARD dataset (Xie et al., 2025), which includes 12 million  
 209 images, 40 million bounding boxes with fine-grained region descriptions, and 10 million hard negative  
 210 samples. For Chinese, we use an in-house dataset containing 12 million images. An overview of our  
 211 training datasets is provided in Table A in Appendix.

### 212 3.4 BILINGUAL EVALUATION PROTOCOLS

214 Existing multimodal benchmarks in English are diverse and well-established, covering a broad spec-  
 215 trum of vision-language tasks such as fine-grained object-level understanding (e.g., FG-OVD (Bianchi  
 et al., 2024)), open-vocabulary object detection (e.g., LVIS (Gupta et al., 2019), COCO (Lin et al.,

216 2014)), and image-text retrieval (e.g., Flickr30K (Young et al., 2014), DCIUrbanek et al. (2024)).  
 217 These resources enable comprehensive evaluation of model capabilities across different granularities  
 218 and semantic complexities. In contrast, Chinese multimodal datasets remain limited in scope and  
 219 diversity, with most focusing on short-caption retrieval tasks such as COCO-CN (Li et al., 2019)  
 220 and Flickr30k-CNA (Xie et al., 2023). Such benchmarks are insufficient for evaluating fine-grained  
 221 cross-modal alignment, particularly at the region level or with long, descriptive textual inputs.

222 To address this gap, we introduce a suite of Chinese evaluation benchmarks tailored for fine-grained  
 223 vision-language tasks. We first construct three long-caption image-text retrieval datasets: LIT-CN,  
 224 DCI-CN, and DOCCI-CN. These datasets support the evaluation of cross-modal alignment with rich  
 225 and descriptive textual inputs. We then present BoxClass-CN, a region-based classification dataset  
 226 designed to assess region-level vision-language alignment in Chinese.

227 LIT-CN integrates diverse sources: 15,000 images from AI-Challenger Caption (Wu et al., 2019),  
 228 3,230 from MUGE (Lin et al., 2021), and 20,000 from curated web images. All images are uniformly  
 229 re-captioned using Qwen2.5-VL-32B-Instruct-AWQ (Bai et al., 2025), prompted to generate rich,  
 230 context-aware descriptions with an average length of 131 tokens. Images below 256×256 resolution  
 231 are filtered, resulting in 33,010 high-quality image-text pairs. DCI-CN is derived from the Densely  
 232 Captioned Images (DCI) dataset (Urbanek et al., 2024), with English captions translated into Chinese  
 233 using the same LMM. The translations are validated by native speakers to ensure linguistic fluency and  
 234 alignment with the original semantics. Similarly, DOCCI-CN is constructed from the DOCCI (Onoe  
 235 et al., 2024) dataset, following an identical translation and validation pipeline.

236 BoxClass-CN is a region classification dataset that evaluates the alignment between image regions and  
 237 their corresponding Chinese textual descriptions. It complements existing Chinese benchmarks by  
 238 providing region-level supervision and serves as an evaluation suite for assessing models' fine-grained  
 239 understanding of visual content. We construct this dataset through a scalable automated pipeline  
 240 based on the LAION-2B corpus (Schuhmann et al., 2022). We first sample 200,000 images and  
 241 generate detailed captions using a LMM (Hong et al., 2024). These captions are parsed to extract  
 242 referring expressions, which are then localized using a pretrained object detector (Cheng et al., 2024)  
 243 to produce bounding box proposals. Non-maximum suppression removes overlapping boxes, and  
 244 only those with region-text similarity above 0.15 (computed by FG-CLIP (Xie et al., 2025)) are  
 245 retained. Detected categories undergo semantic clustering and merging, resulting in 566 semantically  
 246 refined categories. These categories are translated into Chinese, and the final dataset consists of  
 247 24,221 images and 66,258 high-quality region-text pairs.

248 Together, these datasets provide a more rigorous and comprehensive assessment for bilingual vision-  
 249 language alignment models, supporting deeper evaluation of fine-grained understanding capability.

## 251 4 EXPERIMENTS

### 253 4.1 IMPLEMENTATION DETAILS

255 The first stage is conducted on 160×ASCEND 910B NPUs, and the second stage uses 16×NVIDIA  
 256 H800 GPUs. We use three vision encoder configurations: ViT-B/16, ViT-L/16, and ViT-So/16,  
 257 initialized with SigLIP 2 (Tschannen et al., 2025) pre-trained weights. We employ the AdamW  
 258 optimizer with a learning rate of  $1 \times 10^{-6}$  and a weight decay coefficient of 0.001. The momentum  
 259 parameters  $\beta_1$  and  $\beta_2$  are set to 0.9 and 0.98, respectively. A learning rate warmup strategy is applied  
 260 during the first 300 iterations for stability. To accelerate training, we employ Zero-2 (Rajbhandari  
 261 et al., 2020), CUDA TF32 precision, FlashAttention (Dao, 2023), and BFloat16 mixed-precision  
 262 training. Batch sizes are set based on model size and training stage. In the first stage, the global batch  
 263 sizes are 61,440 for ViT-B, 30,720 for ViT-L, and 18,432 for ViT-So. In the second stage, they are  
 264 reduced to 4,096, 3,072, and 2,560, respectively. All models are trained for one epoch per stage.

### 265 4.2 LOCALIZATION TASKS

#### 267 4.2.1 FINE-GRAINED UNDERSTANDING

268 269 We evaluate open-source image-text alignment models on FG-OVD (Bianchi et al., 2024), a fine-  
 270 grained benchmark emphasizing grounding in specific local image regions. Each region is paired

270  
271 Table 1: Performance comparison on fine-grained understanding and bounding box classification  
272 tasks using Top-1 accuracy.

274 Method	275 Backbone	276 Fine-Grained Understanding				277 COCO <sup>80</sup>	278 BBox Classification	
		279 Hard	280 Medium	281 Easy	282 Trivial		283 LVIS <sup>1203</sup>	284 BoxClass-CN <sup>566</sup>
CLIP	ViT-B/16	12.0	23.1	22.2	58.5	44.2	20.9	-
EVA-CLIP	ViT-B/16	14.0	30.1	29.4	58.3	30.6	14.4	-
Long-CLIP	ViT-B/16	9.2	18.4	16.2	51.8	36.7	18.2	-
FineCLIP	ViT-B/16	26.8	49.8	50.4	71.9	48.4	23.3	-
SigLIP 2	ViT-B/16	24.9	46.5	48.7	85.0	53.4	20.6	57.9
FG-CLIP	ViT-B/16	46.1	66.6	68.7	83.4	52.3	28.6	-
FG-CLIP 2	ViT-B/16	<b>52.3</b>	<b>76.3</b>	<b>80.3</b>	<b>92.0</b>	<b>74.9</b>	<b>47.3</b>	<b>60.7</b>
CLIP	ViT-L/14	15.4	25.3	25.7	38.8	33.8	9.3	-
EVA-CLIP	ViT-L/14	18.3	38.4	35.2	62.7	32.1	18.3	-
Long-CLIP	ViT-L/14	9.6	19.7	16.0	39.8	35.6	10.4	-
FineCLIP	ViT-L/14	22.8	46.0	46.0	73.6	54.5	22.5	-
SigLIP 2	ViT-L/16	24.1	47.1	47.4	84.1	54.7	25.9	56.6
<b>CLOC</b>	ViT-L/14	-	-	-	-	72.9	32.6	-
FG-CLIP	ViT-L/14	48.4	69.5	71.2	89.7	63.2	38.3	-
FG-CLIP 2	ViT-L/16	<b>55.5</b>	<b>77.5</b>	<b>83.1</b>	<b>92.5</b>	<b>74.0</b>	<b>41.9</b>	<b>68.6</b>
Meta CLIP 2	ViT-H/14	16.5	36.6	34.7	79.6	52.0	24.4	55.2
SigLIP 2	ViT-So/16	26.0	48.7	49.9	87.4	62.0	31.4	63.6
FG-CLIP 2	ViT-So/16	<b>54.0</b>	<b>77.4</b>	<b>79.8</b>	<b>93.5</b>	<b>77.4</b>	<b>43.9</b>	<b>66.5</b>

293 Table 2: Open-vocabulary object detection results on LVIS<sup>minival</sup> and LVIS. AP is reported across all  
294 categories and frequency splits.

296 Method	297 Backbone	298 LVIS <sup>minival</sup>				299 LVIS		
		299 AP	AP <sub>r</sub>	AP <sub>c</sub>	AP <sub>f</sub>	299 AP	AP <sub>r</sub>	AP <sub>c</sub>
YOLO-World-L (Cheng et al., 2024)	YOLOv8-L	35.5	24.4	34.0	38.8	28.7	22.9	24.9
OWL-ST (Ye et al., 2023)	ViT-B/16	34.4	38.3	-	-	28.6	30.3	-
DetCLIP v3 (Yao et al., 2024)	Swin-T	47.0	45.1	47.7	46.7	38.9	37.2	37.5
T-Rex2 (Jiang et al., 2024)	Swin-T	42.8	37.4	39.7	46.5	34.8	29.0	31.5
OV-DINO (Wang et al., 2024)	Swin-T	40.1	34.5	39.5	41.5	32.9	29.1	30.4
LLMDet	Swin-T	44.7	37.3	39.5	50.7	34.9	26.0	30.1
GLIP (Li et al., 2022)	Swin-L	37.3	28.2	34.3	41.5	26.9	17.1	23.3
Grounding-DINO (Liu et al., 2023b)	Swin-L	33.9	22.2	30.7	38.8	-	-	-
OWL-ST (Ye et al., 2023)	ViT-L/14	40.9	41.5	-	-	35.2	36.2	-
MM-GDINO (Zhao et al., 2024)	Swin-L	36.8	28.1	31.8	42.8	29.1	19.7	25.6
LLMDet	Swin-L	51.1	45.1	46.1	56.6	42.0	31.6	38.8
LLMDet + FG-CLIP	Swin-T + ViT-B/16	48.0	40.6	47.7	51.4	41.0	35.1	38.9
LLMDet + SigLIP 2	Swin-T + ViT-B/16	47.9	42.4	45.6	51.0	41.8	36.1	39.9
LLMDet + FG-CLIP 2	Swin-T + ViT-B/16	<b>51.6</b>	<b>47.5</b>	<b>50.7</b>	<b>53.2</b>	<b>44.0</b>	<b>37.4</b>	<b>42.8</b>
LLMDet + FG-CLIP	Swin-T + ViT-L/14	50.5	41.9	49.3	53.1	43.1	37.0	41.3
LLMDet + SigLIP 2	Swin-T + ViT-L/16	49.9	46.9	48.9	51.3	43.6	40.4	42.0
LLMDet + FG-CLIP 2	Swin-T + ViT-L/16	<b>52.6</b>	<b>48.6</b>	<b>51.8</b>	<b>54.0</b>	<b>45.5</b>	<b>41.0</b>	<b>44.2</b>
LLMDet + SigLIP 2	Swin-T + ViT-So/16	50.2	48.4	49.0	51.7	44.3	41.1	42.7
LLMDet + Meta CLIP 2	Swin-T + ViT-H/14	52.2	50.5	51.1	53.5	44.5	41.7	42.9
LLMDet + FG-CLIP 2	Swin-T + ViT-So/16	<b>53.1</b>	<b>50.8</b>	<b>52.3</b>	<b>54.2</b>	<b>45.9</b>	<b>42.1</b>	<b>44.6</b>

316 with one positive description and ten synthetically perturbed negatives, forming a challenging  
317 discrimination task. The benchmark comprises four subsets: trivial, easy, medium, and hard, arranged  
318 by increasing linguistic subtlety between correct and distractor texts, requiring finer-grained reasoning  
319 for accurate matching. Following FineCLIP (Jing et al., 2024), we extract dense visual features and  
320 use ROIAlign with provided bounding boxes to obtain region-specific representations. Similarity  
321 scores are computed between region features and textual descriptions, with Top-1 accuracy used as the  
322 evaluation metric. Results on the left side of Table 1 show that FG-CLIP 2 achieves significant gains  
323 over prior models. This demonstrates its superior capability in distinguishing subtle visual-linguistic  
correspondences, a key requirement for fine-grained understanding.

324  
 325 Table 3: Comparisons on English image-level tasks, including long/short caption image-text retrieval,  
 326 and zero-shot image classification.

327 328 329 330 331 332 333 334 335 336 337 338 339 340 341 342 343 344 345	Method	Backbone	ShareGPT4V		DCI		MSCOCO		Flickr30k		IN-1K	IN-v2
			I→T	T→I	I→T	T→I	I→T	T→I	I→T	T→I	Top-1	Top-1
CLIP	ViT-B/16	78.2	79.6	45.5	43.0	51.8	32.7	82.2	62.1	68.4	61.9	
EVA-CLIP	ViT-B/16	90.5	85.5	41.9	41.2	58.7	41.6	85.7	71.2	74.7	67.0	
Long-CLIP	ViT-B/16	94.7	93.4	51.7	57.3	57.6	40.4	85.9	70.7	66.8	61.2	
FineCLIP	ViT-B/16	70.6	73.3	35.5	34.4	54.5	40.2	82.5	67.9	55.7	48.8	
<b>UMG-CLIP</b>	ViT-B/16	-	-	-	-	64.7	51.6	91.4	78.6	-	66.5	
FG-CLIP	ViT-B/16	<b>96.7</b>	94.9	61.8	60.6	64.1	45.4	90.7	76.4	69.0	61.8	
SigLIP 2	ViT-B/16	66.0	67.9	32.3	34.2	71.2	55.2	92.6	78.0	<b>81.2</b>	<b>74.5</b>	
FG-CLIP 2	ViT-B/16	95.8	<b>95.4</b>	<b>64.5</b>	<b>64.9</b>	<b>72.1</b>	<b>54.5</b>	<b>94.1</b>	<b>81.9</b>	79.5	72.2	
CLIP	ViT-L/14	86.5	83.6	37.2	36.4	58.0	37.1	87.4	67.3	76.6	70.9	
EVA-CLIP	ViT-L/14	91.5	89.4	47.2	47.8	64.2	47.9	89.2	77.9	80.4	73.8	
Long-CLIP	ViT-L/14	95.8	95.6	44.2	52.5	62.8	46.3	90.0	76.2	73.5	67.9	
FineCLIP	ViT-L/14	73.4	82.7	40.1	46.2	-	-	-	-	60.8	53.4	
<b>UMG-CLIP</b>	ViT-L/14	-	-	-	-	68.9	54.6	93.4	83.1	-	71.6	
FG-CLIP	ViT-L/14	<b>97.4</b>	<b>96.8</b>	66.7	66.1	68.9	50.9	93.7	81.5	76.1	69.0	
<b>CLOC</b>	ViT-L/14	-	-	-	-	74.8	54.4	-	-	80.1	73.2	
SigLIP 2	ViT-L/16	84.4	83.0	46.7	47.1	71.6	53.4	93.1	81.4	82.8	75.2	
FG-CLIP 2	ViT-L/16	96.9	96.6	<b>70.0</b>	<b>71.6</b>	<b>75.1</b>	<b>58.6</b>	<b>96.6</b>	<b>84.8</b>	<b>83.1</b>	<b>77.4</b>	
SigLIP 2	ViT-So/16	78.6	79.5	46.0	47.1	71.3	56.0	94.1	82.5	<b>84.3</b>	<b>79.1</b>	
Meta CLIP 2	ViT-H/14	93.9	89.2	53.0	50.2	66.8	47.7	91.9	77.0	81.7	75.7	
FG-CLIP 2	ViT-So/16	<b>97.5</b>	<b>96.7</b>	<b>70.6</b>	<b>72.1</b>	<b>74.6</b>	<b>56.7</b>	<b>95.9</b>	<b>85.0</b>	84.1	77.8	

346  
 347 Table 4: Performance on Chinese image-text retrieval benchmarks, covering both long-text and  
 348 short-text settings. Results are reported in terms of Recall@1 (%).

349 350 351 352 353 354 355 356 357 358 359 360	Method	Backbone	LIT-CN		DCI-CN		DOCCI-CN		Flickr-CNA		COCO-CN	
			I→T	T→I	I→T	T→I	I→T	T→I	I→T	T→I	I→T	T→I
R2D2	ViT-B/16	35.7	27.4	25.9	27.3	36.1	36.9	69.7	51.1	60.1	45.5	
Chinese-CLIP	ViT-B/16	45.7	35.6	30.1	27.9	44.6	43.1	75.8	62.4	68.8	54.9	
SigLIP 2	ViT-B/16	4.5	3.2	5.0	3.9	7.6	5.7	71.7	49.1	68.5	46.2	
FG-CLIP 2	ViT-B/16	<b>82.4</b>	<b>81.1</b>	<b>53.9</b>	<b>55.7</b>	<b>71.2</b>	<b>75.4</b>	<b>85.4</b>	<b>69.9</b>	<b>77.2</b>	<b>62.9</b>	
R2D2	ViT-L/14	48.3	33.3	35.6	34.2	49.5	46.3	78.8	60.0	69.6	52.7	
Chinese-CLIP	ViT-L/14	48.6	38.9	31.4	32.7	49.7	50.8	82.9	69.6	74.3	59.9	
SigLIP 2	ViT-L/16	16.0	13.6	13.9	13.4	25.1	24.2	76.6	51.2	71.6	51.3	
FG-CLIP 2	ViT-L/16	<b>86.3</b>	<b>85.9</b>	<b>60.4</b>	<b>62.2</b>	<b>77.6</b>	<b>81.9</b>	<b>90.3</b>	<b>75.0</b>	<b>82.8</b>	<b>66.5</b>	
SigLIP 2	ViT-So/16	16.3	11.2	13.4	12.0	25.0	21.3	78.4	51.7	72.0	50.7	
Meta CLIP 2	ViT-H/14	77.2	67.6	53.8	52.1	73.8	77.2	89.3	72.2	80.1	63.1	
FG-CLIP 2	ViT-So/16	<b>87.6</b>	<b>86.3</b>	<b>62.7</b>	<b>65.1</b>	<b>79.7</b>	<b>84.0</b>	<b>91.5</b>	<b>77.2</b>	<b>83.2</b>	<b>68.1</b>	

#### 4.2.2 BOUNDING BOX CLASSIFICATION

We evaluate zero-shot bounding box classification on COCO-val2017 (Lin et al., 2014), LVIS (Gupta et al., 2019), and our proposed BoxClass-CN dataset, following the protocol of (Xie et al., 2025). While the former focus on English category recognition within localized regions, BoxClass-CN targets Chinese, enabling a bilingual assessment of fine-grained vision-language alignment. As shown in the right part of Table 1, FG-CLIP 2 achieves state-of-the-art performance in both languages and significantly outperforms all compared open-source models. These results demonstrate its robust ability to align local visual content with semantic concepts across linguistic boundaries.

#### 4.2.3 OPEN-VOCABULARY OBJECT DETECTION

To assess the impact of vision-language alignment models on open-vocabulary detection (OVD), we adopt a training-free evaluation protocol that avoids biases from detector fine-tuning. Unlike prior approaches (Wu et al., 2024) that require small-scale detector training on fixed categories, our method directly leverages the zero-shot generalization of alignment models to calibrate confidence scores and category predictions in the final OVD output. This allows for a cleaner analysis of the contribution of image-text alignment to OVD performance. We adopt a fusion strategy that leverages the vision-language alignment model to refine the class predictions and confidence scores of a pre-trained

378 detector. Specifically, similarity scores from the alignment model are combined with the detector’s  
 379 original confidences via geometric averaging, enabling more semantically accurate and calibrated  
 380 open-vocabulary detection. We use LLMDet (Fu et al., 2025) as the base detector and evaluate on  
 381 the challenging LVIS dataset (Gupta et al., 2019), which contains 1,203 categories. Categories are  
 382 split into frequent, common, and rare based on occurrence frequency, and AP is reported per group.  
 383 As shown in Table 2, FG-CLIP 2 combined with LLMDet achieves the best performance among  
 384 open-source methods, demonstrating strong practical utility and validating its superior generalization  
 385 in detection scenarios.

### 386 4.3 IMAGE-LEVEL TASKS

#### 387 4.3.1 LONG/SHORT CAPTION IMAGE-TEXT RETRIEVAL

390 To comprehensively evaluate image-text alignment under varying linguistic complexity, we conduct  
 391 experiments on both short and long caption retrieval tasks. Short-text retrieval (Flickr30k (Young  
 392 et al., 2014), MSCOCO (Lin et al., 2014)) assesses basic semantic matching, while long-text retrieval  
 393 requires fine-grained understanding of detailed descriptions and complex visual scenes. For short-text  
 394 retrieval, we employ the validation set of MSCOCO and the test set of Flickr30k, which are widely  
 395 used benchmarks for assessing image-text alignment models. For long-text retrieval in English, we  
 396 use the 1K subset of ShareGPT4V (Chen et al., 2024b) and the full test set of DCI (Urbanek et al.,  
 397 2024) following the protocol of Long-CLIP (Zhang et al., 2024a). For Chinese, we evaluate on  
 398 LIT-CN, DCI-CN, and DOCCI-CN for long-text, and Flickr-CNA (Xie et al., 2023) and COCO-  
 399 CN (Li et al., 2019) for short-text. We employ the validation set of COCO-CN and the test set of  
 400 Flickr-CNA. These datasets cover diverse content and caption styles, providing a robust evaluation  
 401 of multilingual performance. As shown in Table 3 and Table 4, FG-CLIP 2 achieves consistent  
 402 improvements across all settings, with particularly strong gains on long-text retrieval, highlighting  
 403 its superior capability in fine-grained vision-language alignment. Notably, FG-CLIP 2 outperforms  
 404 Meta CLIP 2 (Chuang et al., 2025), the current multilingual SOTA, on both language settings, despite  
 405 using a smaller ViT-L/16 backbone with 1.0 billion parameters compared to Meta CLIP 2’s 1.8 billion  
 406 parameter ViT-H/14. This highlights the effectiveness of our training paradigm in achieving stronger  
 407 performance with reduced model scale.

#### 408 4.3.2 ZERO-SHOT IMAGE CLASSIFICATION

409 We evaluate zero-shot image classification on ImageNet-1K (Deng et al., 2009) and ImageNet-  
 410 v2 (Recht et al., 2019) using standard prompts (Radford et al., 2021). As shown in Table 3, FG-CLIP  
 411 2 achieves competitive performance compared to SigLIP 2 (Tschannen et al., 2025), and outperforms  
 412 EVA-CLIP (Sun et al., 2023), Long-CLIP (Zhang et al., 2024a), FineCLIP (Jing et al., 2024), **UMG-  
 413 CLIP (Shi et al., 2024)**, and **CLOC (Chen et al., 2024a)**. This confirms that the improvements in  
 414 fine-grained alignment do not come at the cost of standard recognition accuracy, demonstrating a  
 415 well-balanced representation capability.

### 416 4.4 DENSE PREDICTION TASKS

417 We evaluate dense prediction through open-vocabulary segmentation, a task that requires models  
 418 to segment object categories beyond a fixed training set. We adopt Cat-Seg (Cho et al., 2024) as  
 419 the base framework, trained on COCO-Stuff-164k (172 categories), and evaluate on datasets with  
 420 diverse category schemas: ADE20k (847 or 150 categories, denoted A-847/A-150), Pascal Context  
 421 (PC-459/PC-59), and Pascal VOC (VOC-20/VOC-21). As shown in Table 5, FG-CLIP 2 achieves  
 422 the best performance across models of various scales, delivering consistent improvements over the  
 423 baseline. This demonstrates its strong capability in enabling pixel-level generalization, crucial for  
 424 downstream dense understanding tasks.

### 425 4.5 LARGE MULTIMODAL MODEL TASKS

426 We employ FG-CLIP 2 as a vision encoder in large multimodal models (LMMs) to assess its  
 427 compatibility and utility in advanced multimodal reasoning. We integrate FG-CLIP 2 into a standard  
 428 LLaVA-style LMM architecture, following the pre-training and supervised fine-tuning protocol of  
 429 LLaVA-1.5 (Liu et al., 2023a). Results in Table 6 show that LMMs equipped with FG-CLIP 2

Table 5: Performance on dense prediction tasks.

Model	Backbone	A-847	PC-459	A-150	PC-59	VOC-20	VOC-21
CLIP	ViT-B/16	8.4	16.6	27.2	57.5	93.7	78.3
CLIPSelf	ViT-B/16	10.1	-	29.7	55.3	-	-
FineCLIP	ViT-B/16	12.2	-	32.4	56.0	-	-
<b>UMG-CLIP</b>	ViT-L/14	13.8	21.1	34.6	58.2	-	-
FG-CLIP	ViT-B/16	12.3	19.1	33.4	58.2	95.3	77.9
SigLIP 2	ViT-B/16	10.4	17.0	28.5	55.4	94.4	75.8
FG-CLIP 2	ViT-B/16	<b>16.6</b>	<b>24.0</b>	<b>38.5</b>	<b>61.2</b>	<b>97.1</b>	<b>81.1</b>
CLIP	ViT-L/14	10.8	20.4	31.5	62.0	96.6	81.8
CLIPSelf	ViT-L/14	13.6	-	34.9	59.1	-	-
FineCLIP	ViT-L/14	14.1	-	36.1	59.9	-	-
<b>UMG-CLIP</b>	ViT-L/14	15.4	23.2	36.1	58.7	-	-
FG-CLIP	ViT-L/14	14.6	23.3	36.9	61.4	97.4	81.8
SigLIP 2	ViT-L/16	14.3	24.1	38.8	62.4	97.0	82.3
FG-CLIP 2	ViT-L/16	18.8	26.6	41.2	62.4	97.6	81.8
FG-CLIP 2	ViT-So/16	<b>20.0</b>	<b>27.5</b>	<b>42.2</b>	<b>63.3</b>	<b>97.8</b>	<b>83.2</b>

Table 6: Comparisons on large multimodal model benchmarks.

outperform those using other open-source encoders, including SigLIP 2 and Meta CLIP 2. This indicates that the fine-grained and bilingual capabilities of FG-CLIP 2 effectively transfer to higher-level multimodal tasks, making it a strong candidate for integration into next-generation LMMs.

## 4.6 ABLATION STUDY

As our training framework leverages global-level, region-level, and hard-negative data through complementary learning mechanisms, we adopt a baseline model that incorporates global alignment alongside fine-grained visual and textual learning. This allows us to specifically evaluate the impact of the Cross-modal Rank Loss with Global Threshold Synchronization ( $\mathcal{L}_{CMR}$ ) and the Textual Intra-modal Contrastive Loss ( $\mathcal{L}_{TIC}$ ). As shown in Table 7, removing  $\mathcal{L}_{TIC}$  leads to a 4.8-point drop in COCO Top-1 accuracy (to 70.1%) and a decrease in FG-OVD Hard performance from 52.3% to 51.6%, confirming its critical role in distinguishing semantically similar texts. Removing  $\mathcal{L}_{CMR}$  also degrades performance, with FG-OVD Hard falling to 50.9%, indicating its importance in cross-modal alignment. When both losses are removed, COCO Top-1 drops sharply to 62.7%, demonstrating their complementary benefits. The full model achieves consistent gains across all tasks, **especially in bounding box classification and fine-grained understanding**, validating the effectiveness of our proposed training objectives. **Additionally, visualizations demonstrating the semantic separability improvement from TIC loss are provided in Appendix I.**

To examine how different data compositions affect the model’s bilingual capability, we conduct an ablation study comparing two variants trained under identical settings except for the data used in the second stage: one uses English-only data, while the other uses both English and Chinese data. Results in Table 8 show that the bilingual variant not only achieves higher accuracy on Chinese benchmarks but also consistently improves performance on English-only evaluation sets, confirming a mutually promoting effect between the two languages.

## 5 CONCLUSION AND LIMITATIONS

In this work, we present FG-CLIP 2, a bilingual vision-language model that advances fine-grained understanding for both English and Chinese. Our two-stage training paradigm progressively re-

486  
487  
488 Table 7: Ablation study results for the training objectives of FG-CLIP 2.  
489  
490

Method	Flickr30k		ImageNet-V2 Top-1	COCO <sup>80</sup>			FG-OVD		
	I→T	T→I		Top-1	Top-5	Hard	Medium	Easy	Trivial
FG-CLIP 2	94.1	81.9	72.2	74.9	95.7	52.3	76.3	80.3	92.0
w/o $\mathcal{L}_{CMR}$	93.3	81.9	72.1	74.0	94.9	50.9	75.1	77.8	93.5
w/o $\mathcal{L}_{TIC}$	93.7	81.8	72.1	70.1	94.8	51.6	75.1	79.1	92.1
w/o $\mathcal{L}_{CMR}$ , $\mathcal{L}_{TIC}$	93.5	81.6	72.0	62.7	93.4	51.7	76.0	77.6	90.7

494  
495  
496 Table 8: **Ablation study on data Composition for bilingual capability.** FG-CLIP 2\* (marked with \*)  
497 uses English-only data in the second stage, while FG-CLIP 2 uses both English and Chinese data.  
498

Method	DCI		MSCOCO		DOCCI-CN		Flickr30k-CNA		COCO <sup>80</sup>			Fine-Grained Understanding		
	I→T	T→I	I→T	T→I	I→T	T→I	I→T	T→I	Top-1	Top-5	Hard	Medium	Easy	Trivial
FG-CLIP 2*	64.4	64.7	71.4	54.5	57.8	58.6	84.5	68.0	71.3	95.2	52.2	75.9	80.1	91.0
FG-CLIP 2	64.5	64.9	72.1	54.5	71.2	75.4	85.4	69.9	74.9	95.7	52.3	76.3	80.3	92.0

502  
503  
504 fines alignment by leveraging both short and long captions, region-text supervision, and multiple  
505 discriminative objectives, including the proposed Textual Intra-modal Contrastive (TIC) loss to  
506 better distinguish semantically similar descriptions. Trained on large-scale, high-quality English  
507 and Chinese datasets, FG-CLIP 2 achieves superior performance across 29 datasets and 8 tasks,  
508 demonstrating strong bilingual generalization. To advance evaluation in non-English settings, we  
509 introduce a new benchmark for Chinese multimodal understanding with challenging tasks such as  
510 long caption image-text retrieval and bounding box classification. We release the model, code, and  
511 benchmark to support future research in bilingual fine-grained vision-language understanding. In  
512 future work, we will focus on extending the model to handle longer textual inputs and explicitly  
513 model relational structures among objects, enabling richer fine-grained multimodal understanding.  
514

515  
ETHICS STATEMENT

516  
517 This submission adheres to the ICLR Code of Ethics and Code of Conduct. In this study, no human  
518 subjects or animal experiments are involved. All datasets are sourced in compliance with relevant  
519 usage guidelines, ensuring no violation of privacy. No experiments conducted in this work pose  
520 risks to privacy, security, or societal well-being. We are committed to maintaining transparency and  
521 integrity throughout the research process.

522  
523 REPRODUCIBILITY STATEMENT

524  
525 We have made every effort to ensure that the results presented in this paper are reproducible. The  
526 source code is included in the Supplementary Material, and trained model weights are provided via  
527 an anonymous repository to support independent verification. The experimental setup, including  
528 training steps, model configurations, and hardware details, is described in detail in the main paper  
529 and supplementary sections. We believe these measures will enable other researchers to reproduce  
530 our work and further advance the field.

531  
532 REFERENCES

533  
534 Ibrahim M Alabdulmohsin, Xiaohua Zhai, Alexander Kolesnikov, and Lucas Beyer. Getting vit  
535 in shape: Scaling laws for compute-optimal model design. *Advances in Neural Information  
536 Processing Systems*, 36:16406–16425, 2023.

537  
538 Shuai Bai, Keqin Chen, Xuejing Liu, Jialin Wang, Wenbin Ge, Sibo Song, Kai Dang, Peng Wang,  
539 Shijie Wang, Jun Tang, et al. Qwen2. 5-vl technical report. *arXiv preprint arXiv:2502.13923*,  
2025.

540 Lorenzo Bianchi, Fabio Carrara, Nicola Messina, Claudio Gennaro, and Fabrizio Falchi. The  
 541 devil is in the fine-grained details: Evaluating open-vocabulary object detectors for fine-grained  
 542 understanding. In *CVPR*, pp. 22520–22529, 2024.

543

544 Hong-You Chen, Zhengfeng Lai, Haotian Zhang, Xinze Wang, Marcin Eichner, Keen You, Meng  
 545 Cao, Bowen Zhang, Yinfai Yang, and Zhe Gan. Contrastive localized language-image pre-training.  
 546 *arXiv preprint arXiv:2410.02746*, 2024a.

547 Lin Chen, Jinsong Li, Xiaoyi Dong, Pan Zhang, Conghui He, Jiaqi Wang, Feng Zhao, and Dahu Lin.  
 548 Sharegpt4v: Improving large multi-modal models with better captions. In *ECCV*, pp. 370–387,  
 549 2024b.

550

551 Tianheng Cheng, Lin Song, Yixiao Ge, Wenyu Liu, Xinggang Wang, and Ying Shan. Yolo-world:  
 552 Real-time open-vocabulary object detection. In *CVPR*, pp. 16901–16911, 2024.

553 Seokju Cho, Heeseong Shin, Sunghwan Hong, Anurag Arnab, Paul Hongsuck Seo, and Seungryong  
 554 Kim. Cat-seg: Cost aggregation for open-vocabulary semantic segmentation. In *Proceedings of  
 555 the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 4113–4123, 2024.

556

557 Yung-Sung Chuang, Yang Li, Dong Wang, Ching-Feng Yeh, Kehan Lyu, Ramya Raghavendra, James  
 558 Glass, Lifei Huang, Jason Weston, Luke Zettlemoyer, et al. Metaclip 2: A worldwide scaling  
 559 recipe. *arXiv preprint arXiv:2507.22062*, 2025.

560 Tri Dao. Flashattention-2: Faster attention with better parallelism and work partitioning. *arXiv  
 561 preprint arXiv:2307.08691*, 2023.

562

563 Jia Deng, Wei Dong, Richard Socher, Li-Jia Li, Kai Li, and Li Fei-Fei. Imagenet: A large-scale  
 564 hierarchical image database. In *CVPR*, pp. 248–255, 2009.

565

566 Alex Fang, Albin Madappally Jose, Amit Jain, Ludwig Schmidt, Alexander Toshev, and Vaishaal  
 567 Shankar. Data filtering networks. In *ICLR*, 2024.

568

569 Shenghao Fu, Qize Yang, Qijie Mo, Junkai Yan, Xihan Wei, Jingke Meng, Xiaohua Xie, and Wei-Shi  
 570 Zheng. Llmdet: Learning strong open-vocabulary object detectors under the supervision of large  
 571 language models. In *Proceedings of the Computer Vision and Pattern Recognition Conference*, pp.  
 14987–14997, 2025.

572

573 Jiaxi Gu, Xiaojun Meng, Guansong Lu, Lu Hou, Niu Minzhe, Xiaodan Liang, Lewei Yao, Runhui  
 574 Huang, Wei Zhang, Xin Jiang, et al. Wukong: A 100 million large-scale chinese cross-modal  
 575 pre-training benchmark. *Advances in Neural Information Processing Systems*, 35:26418–26431,  
 2022.

576

577 Agrim Gupta, Piotr Dollar, and Ross Girshick. Lvis: A dataset for large vocabulary instance  
 578 segmentation. In *CVPR*, pp. 5356–5364, 2019.

579

580 Kaiming He, Georgia Gkioxari, Piotr Dollár, and Ross Girshick. Mask r-cnn. In *ICCV*, pp. 2961–2969,  
 2017.

581

582 Wenyi Hong, Weihan Wang, Ming Ding, Wenmeng Yu, Qingsong Lv, Yan Wang, Yean Cheng,  
 583 Shiyu Huang, Junhui Ji, Zhao Xue, et al. Cogvilm2: Visual language models for image and video  
 584 understanding. *arXiv preprint arXiv:2408.16500*, 2024.

585

586 Qing Jiang, Feng Li, Zhaoyang Zeng, Tianhe Ren, Shilong Liu, and Lei Zhang. T-rex2: Towards  
 587 generic object detection via text-visual prompt synergy. In *European Conference on Computer  
 588 Vision*, pp. 38–57. Springer, 2024.

589

590 Dong Jing, Xiaolong He, Yutian Luo, Nanyi Fei, Guoxing Yang, Wei Wei, Huiwen Zhao, and Zhiwu  
 591 Lu. Fineclip: Self-distilled region-based clip for better fine-grained understanding. In *NeurIPS*,  
 2024.

592

593 Jiaqi Li, Junshu Tang, Zhiyong Xu, Longhuang Wu, Yuan Zhou, Shuai Shao, Tianbao Yu, Zhiguo  
 Cao, and Qinglin Lu. Hunyuan-gamecraft: High-dynamic interactive game video generation with  
 hybrid history condition, 2025a. URL <https://arxiv.org/abs/2506.17201>.

594 Liunian Harold Li, Pengchuan Zhang, Haotian Zhang, Jianwei Yang, Chunyuan Li, Yiwu Zhong,  
 595 Lijuan Wang, Lu Yuan, Lei Zhang, Jenq-Neng Hwang, et al. Grounded language-image pre-training.  
 596 In *CVPR*, pp. 10965–10975, 2022.

597

598 Xirong Li, Chaoxi Xu, Xiaoxu Wang, Weiyu Lan, Zhengxiong Jia, Gang Yang, and Jieping Xu. Coco-  
 599 cn for cross-lingual image tagging, captioning, and retrieval. *IEEE Transactions on Multimedia*,  
 600 21(9):2347–2360, 2019.

601 Zhiqi Li, Guo Chen, Shilong Liu, Shihao Wang, Vibashan VS, Yishen Ji, Shiyi Lan, Hao Zhang,  
 602 Yilin Zhao, Subhashree Radhakrishnan, et al. Eagle 2: Building post-training data strategies from  
 603 scratch for frontier vision-language models. *arXiv preprint arXiv:2501.14818*, 2025b.

604

605 Junyang Lin, Rui Men, An Yang, Chang Zhou, Ming Ding, Yichang Zhang, Peng Wang, Ang Wang,  
 606 Le Jiang, Xianyan Jia, et al. M6: A chinese multimodal pretrainer. In *Proceedings of the 27th ACM SIGKDD Conference on Knowledge Discovery and Data Mining*, pp. 3251–3261, 2021.

607

608 Tsung-Yi Lin, Michael Maire, Serge Belongie, James Hays, Pietro Perona, Deva Ramanan, Piotr  
 609 Dollár, and C Lawrence Zitnick. Microsoft coco: Common objects in context. In *ECCV*, pp.  
 610 740–755, 2014.

611

612 Haotian Liu, Chunyuan Li, Qingyang Wu, and Yong Jae Lee. Visual instruction tuning. *Advances in  
 613 neural information processing systems*, 36:34892–34916, 2023a.

614

615 Shilong Liu, Zhaoyang Zeng, Tianhe Ren, Feng Li, Hao Zhang, Jie Yang, Chunyuan Li, Jianwei  
 616 Yang, Hang Su, Jun Zhu, et al. Grounding dino: Marrying dino with grounded pre-training for  
 617 open-set object detection. *arXiv preprint arXiv:2303.05499*, 2023b.

618

619 Shiyin Lu, Yang Li, Yu Xia, Yuwei Hu, Shanshan Zhao, Yanqing Ma, Zhichao Wei, Yinglun Li,  
 620 Lunhao Duan, Jianshan Zhao, Yuxuan Han, Haijun Li, Wanying Chen, Junke Tang, Chengkun  
 621 Hou, Zhixing Du, , et al. Ovis2.5 technical report. *arXiv:2508.11737*, 2025.

622

623 Kevis-Kokitsi Maninis, Kaifeng Chen, Soham Ghosh, Arjun Karpur, Koert Chen, Ye Xia, Bingyi  
 624 Cao, Daniel Salz, Guangxing Han, Jan Dlabal, et al. Tips: Text-image pretraining with spatial  
 625 awareness. In *ICLR*, 2025.

626

627 Yasumasa Onoe, Sunayana Rane, Zachary Berger, Yonatan Bitton, Jaemin Cho, Roopal Garg,  
 628 Alexander Ku, Zarana Parekh, Jordi Pont-Tuset, Garrett Tanzer, et al. Docci: Descriptions of  
 629 connected and contrasting images. In *ECCV*, pp. 291–309, 2024.

630

631 Alec Radford, Jong Wook Kim, Chris Hallacy, Aditya Ramesh, Gabriel Goh, Sandhini Agarwal,  
 632 Girish Sastry, Amanda Askell, Pamela Mishkin, Jack Clark, et al. Learning transferable visual  
 633 models from natural language supervision. In *ICML*, pp. 8748–8763, 2021.

634

635 Samyam Rajbhandari, Jeff Rasley, Olatunji Ruwase, and Yuxiong He. Zero: Memory optimizations  
 636 toward training trillion parameter models. In *SC20: International Conference for High Performance  
 637 Computing, Networking, Storage and Analysis*, pp. 1–16. IEEE, 2020.

638

639 Benjamin Recht, Rebecca Roelofs, Ludwig Schmidt, and Vaishaal Shankar. Do imagenet classifiers  
 640 generalize to imagenet? In *ICML*, pp. 5389–5400, 2019.

641

642 Christoph Schuhmann, Romain Beaumont, Richard Vencu, Cade Gordon, Ross Wightman, Mehdi  
 643 Cherti, Theo Coombes, Aarush Katta, Clayton Mullis, Mitchell Wortsman, et al. Laion-5b: An  
 644 open large-scale dataset for training next generation image-text models. *Advances in neural  
 645 information processing systems*, 35:25278–25294, 2022.

646

647 Bowen Shi, Peisen Zhao, Zichen Wang, Yuhang Zhang, Yaoming Wang, Jin Li, Wenrui Dai, Junni  
 648 Zou, Hongkai Xiong, Qi Tian, et al. Umg-clip: A unified multi-granularity vision generalist for  
 649 open-world understanding. In *European Conference on Computer Vision*, pp. 259–277. Springer,  
 650 2024.

651

652 Quan Sun, Yuxin Fang, Ledell Wu, Xinlong Wang, and Yue Cao. Eva-clip: Improved training  
 653 techniques for clip at scale. *arXiv preprint arXiv:2303.15389*, 2023.

648 Zeyi Sun, Ye Fang, Tong Wu, Pan Zhang, Yuhang Zang, Shu Kong, Yuanjun Xiong, Dahua Lin, and  
 649 Jiaqi Wang. Alpha-clip: A clip model focusing on wherever you want. In *Proceedings of the*  
 650 *IEEE/CVF conference on computer vision and pattern recognition*, pp. 13019–13029, 2024.

651 Gemma Team, Thomas Mesnard, Cassidy Hardin, Robert Dadashi, Surya Bhupatiraju, Shreya Pathak,  
 652 Laurent Sifre, Morgane Rivière, Mihir Sanjay Kale, Juliette Love, et al. Gemma: Open models  
 653 based on gemini research and technology. *arXiv preprint arXiv:2403.08295*, 2024.

654 Gemma Team, Aishwarya Kamath, Johan Ferret, Shreya Pathak, Nino Vieillard, Ramona Merhej,  
 655 Sarah Perrin, Tatiana Matejovicova, Alexandre Ramé, Morgane Rivière, et al. Gemma 3 technical  
 656 report. *arXiv preprint arXiv:2503.19786*, 2025a.

657 V Team, Wenyi Hong, Wenmeng Yu, Xiaotao Gu, Guo Wang, Guobing Gan, Haomiao Tang, Jiale  
 658 Cheng, Ji Qi, Junhui Ji, Lihang Pan, Shuaiqi Duan, et al. Glm-4.5v and glm-4.1v-thinking:  
 659 Towards versatile multimodal reasoning with scalable reinforcement learning, 2025b. URL  
 660 <https://arxiv.org/abs/2507.01006>.

661 Michael Tschannen, Alexey Gritsenko, Xiao Wang, Muhammad Ferjad Naeem, Ibrahim Alabdul-  
 662 mohsin, Nikhil Parthasarathy, Talfan Evans, Lucas Beyer, Ye Xia, Basil Mustafa, et al. Siglip 2:  
 663 Multilingual vision-language encoders with improved semantic understanding, localization, and  
 664 dense features. *arXiv preprint arXiv:2502.14786*, 2025.

665 Jack Urbanek, Florian Bordes, Pietro Astolfi, Mary Williamson, Vasu Sharma, and Adriana Romero-  
 666 Soriano. A picture is worth more than 77 text tokens: Evaluating clip-style models on dense  
 667 captions. In *CVPR*, pp. 26700–26709, 2024.

668 Bin Wang, Chunyu Xie, Dawei Leng, and Yuhui Yin. Iaa: Inner-adaptor architecture empowers  
 669 frozen large language model with multimodal capabilities. In *AAAI*, volume 39, pp. 21035–21043,  
 670 2025a.

671 Hao Wang, Pengzhen Ren, Zequn Jie, Xiao Dong, Chengjian Feng, Yinlong Qian, Lin Ma, Dongmei  
 672 Jiang, Yaowei Wang, Xiangyuan Lan, et al. Ov-dino: Unified open-vocabulary detection with  
 673 language-aware selective fusion. *arXiv preprint arXiv:2407.07844*, 2024.

674 Hao Wang, Limeng Qiao, Zequn Jie, Zhijian Huang, Chengjian Feng, Qingfang Zheng, Lin Ma,  
 675 Xiangyuan Lan, and Xiaodan Liang. X-sam: From segment anything to any segmentation. *arXiv*  
 676 *preprint arXiv:2508.04655*, 2025b.

677 Dafeng Wei, Tian Gao, Zhengyu Jia, Changwei Cai, Chengkai Hou, Peng Jia, Fu Liu, Kun Zhan,  
 678 Jingchen Fan, Yixing Zhao, et al. Bev-clip: Multi-modal bev retrieval methodology for complex  
 679 scene in autonomous driving. *arXiv preprint arXiv:2401.01065*, 2024.

680 Chenfei Wu, Jiahao Li, Jingren Zhou, Junyang Lin, Kaiyuan Gao, Kun Yan, Sheng ming Yin, Shuai  
 681 Bai, Xiao Xu, Yilei Chen, Yuxiang Chen, Zecheng Tang, Zekai Zhang, Zhengyi Wang, An Yang,  
 682 Bowen Yu, Chen Cheng, Dayiheng Liu, Deqing Li, Hang Zhang, Hao Meng, Hu Wei, Jingyuan Ni,  
 683 Kai Chen, Kuan Cao, Liang Peng, Lin Qu, Minggang Wu, Peng Wang, Shuteng Yu, Tingkun Wen,  
 684 Wensen Feng, Xiaoxiao Xu, Yi Wang, Yichang Zhang, Yongqiang Zhu, Yujia Wu, Yuxuan Cai,  
 685 and Zenan Liu. Qwen-image technical report, 2025. URL <https://arxiv.org/abs/2508.02324>.

686 Jiahong Wu, He Zheng, Bo Zhao, Yixin Li, Baoming Yan, Rui Liang, Wenjia Wang, Shipei Zhou,  
 687 Guosen Lin, Yanwei Fu, et al. Ai challenger: A large-scale dataset for going deeper in image  
 688 understanding. In *IEEE International Conference on Multimedia and Expo*, 2019.

689 Size Wu, Wenwei Zhang, Lumin Xu, Sheng Jin, Xiangtai Li, Wentao Liu, and Chen Change Loy.  
 690 CLIPSelf: Vision transformer distills itself for open-vocabulary dense prediction. In *ICLR*, 2024.  
 691 URL <https://openreview.net/forum?id=DjzvJCRsVf>.

692 Chunyu Xie, Heng Cai, Jincheng Li, Fanjing Kong, Xiaoyu Wu, Jianfei Song, Henrique Morimitsu,  
 693 Lin Yao, Dexin Wang, Xiangzheng Zhang, et al. Ccmb: A large-scale chinese cross-modal  
 694 benchmark. In *ACM MM*, pp. 4219–4227, 2023.

695 Chunyu Xie, Bin Wang, Fanjing Kong, Jincheng Li, Dawei Liang, Gengshen Zhang, Dawei Leng,  
 696 and Yuhui Yin. Fg-clip: Fine-grained visual and textual alignment. In *ICML*, 2025.

702 Hu Xu, Saining Xie, Xiaoqing Ellen Tan, Po-Yao Huang, Russell Howes, Vasu Sharma, Shang-Wen  
 703 Li, Gargi Ghosh, Luke Zettlemoyer, and Christoph Feichtenhofer. Demystifying clip data. In  
 704 *ICLR*, 2024.

705 An Yang, Junshu Pan, Junyang Lin, Rui Men, Yichang Zhang, Jingren Zhou, and Chang Zhou.  
 706 Chinese clip: Contrastive vision-language pretraining in chinese. *arXiv preprint arXiv:2211.01335*,  
 707 2022.

708 Lewei Yao, Renjie Pi, Jianhua Han, Xiaodan Liang, Hang Xu, Wei Zhang, Zhenguo Li, and Dan Xu.  
 709 Detclipv3: Towards versatile generative open-vocabulary object detection. In *Proceedings of the*  
 710 *IEEE/CVF conference on computer vision and pattern recognition*, pp. 27391–27401, 2024.

711 Qinghao Ye, Haiyang Xu, Guohai Xu, Jiabo Ye, Ming Yan, Yiyang Zhou, Junyang Wang, Anwen  
 712 Hu, Pengcheng Shi, Yaya Shi, Chaoya Jiang, Chenliang Li, Yuanhong Xu, Hehong Chen, Junfeng  
 713 Tian, Qian Qi, Ji Zhang, and Fei Huang. mplug-owl: Modularization empowers large language  
 714 models with multimodality, 2023. *arXiv preprint arXiv:2304.14178*.

715 Peter Young, Alice Lai, Micah Hodosh, and Julia Hockenmaier. From image descriptions to visual  
 716 denotations: New similarity metrics for semantic inference over event descriptions. *Transactions*  
 717 *of the Association for Computational Linguistics*, 2:67–78, 2014.

718 Xiaohua Zhai, Alexander Kolesnikov, Neil Houlsby, and Lucas Beyer. Scaling vision transformers.  
 719 In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition*, pp.  
 720 12104–12113, 2022.

721 Xiaohua Zhai, Basil Mustafa, Alexander Kolesnikov, and Lucas Beyer. Sigmoid loss for language  
 722 image pre-training. In *Proceedings of the IEEE/CVF international conference on computer vision*,  
 723 pp. 11975–11986, 2023.

724 Beichen Zhang, Pan Zhang, Xiaoyi Dong, Yuhang Zang, and Jiaqi Wang. Long-clip: Unlocking the  
 725 long-text capability of clip. In *ECCV*, pp. 310–325, 2024a.

726 Le Zhang, Rabiul Awal, and Aishwarya Agrawal. Contrasting intra-modal and ranking cross-modal  
 727 hard negatives to enhance visio-linguistic compositional understanding. In *CVPR*, pp. 13774–  
 728 13784, 2024b.

729 Xiangyu Zhao, Yicheng Chen, Shilin Xu, Xiangtai Li, Xinjiang Wang, Yining Li, and Haian Huang.  
 730 An open and comprehensive pipeline for unified object grounding and detection. *arXiv preprint*  
 731 *arXiv:2401.02361*, 2024.

732 Jinguo Zhu, Weiyun Wang, Zhe Chen, Zhaoyang Liu, Shenglong Ye, Lixin Gu, Hao Tian, Yuchen  
 733 Duan, Weijie Su, Jie Shao, et al. Internvl3: Exploring advanced training and test-time recipes for  
 734 open-source multimodal models. *arXiv preprint arXiv:2504.10479*, 2025.

735

736

737

738

739

740

741

742

743

744

745

746

747

748

749

750

751

752

753

754

755

756 **A TRAINING DATA DETAILS**  
757758 Table A summarizes the datasets used in our two-stage training pipeline.  
759762 Table A: Overview of the training datasets used in two stages.  
763

Data Type	Dataset	Language	Size
Image-text	LAION-2B-enhanced	English	1.6B
	Wukong	Chinese	100M
	Zero	Chinese	250M
	In-house Data	Chinese	500M
Region-text	FineHARD	English	12M
	In-house Data	Chinese	12M

773 **B OPEN-VOCABULARY OBJECT DETECTION EXPERIMENTAL DETAILS**  
774775  
776 In our experiments, we adopt LLMDet as the base open-vocabulary object detection model. Its output  
777 consists of bounding boxes, each associated with a predicted category and a confidence score. To  
778 improve category accuracy, we recalibrate these predictions using vision-language alignment models,  
779 such as FG-CLIP 2, without modifying LLMDet’s parameters.780 For each detected bounding box, we extract its visual feature by applying ROI-Align on the dense  
781 ViT feature map produced by FG-CLIP 2. We also encode all candidate category names into text  
782 embeddings using the same model. We then compute the cosine similarity between the region’s visual  
783 feature and each category’s text embedding, followed by Softmax normalization to obtain a category-  
784 wise alignment similarity distribution. To produce the final prediction, we combine LLMDet’s original  
785 confidence score with FG-CLIP 2’s normalized similarity score through a weighted multiplicative  
786 fusion. The resulting fused score reflects both the detector’s localization confidence and the alignment  
787 model’s semantic relevance. We then select the category with the highest fused score as the final  
788 predicted class, and assign the corresponding fused value as the final confidence output.789 This approach leverages FG-CLIP 2’s fine-grained understanding to recalibrate LLMDet’s predictions  
790 across the entire category space. It ensures that categories with strong semantic alignment but initially  
791 low detection scores can still be correctly selected if their fused confidence is highest. This global  
792 recalibration significantly improves performance on novel categories, while maintaining compatibility  
793 with the original detector’s structure.795 Table B: Detailed parameters for training with Cat-Seg.  
796

Parameter name	Value	Parameter name	Value
Text Guidance Proj Dim	128	Min Size Train	384
Appearance Guidance Proj Dim	128	Min Size Train Sampling	Choice
Decoder Dims	[64, 32]	Min Size Test	640
Decoder Guidance Dims	[256, 128]	Size Divisibility	384
Decoder Guidance Proj Dims	[32, 16]	Format	RGB
Num Layers	2	Dataset Mapper Name	MaskFormer Semantic
Num Heads	4	Images Per Batch	8
Hidden Dims	128	LR Scheduler Name	WarmupCosineLR
Pooling Sizes	[2, 2]	Base Learning Rate	0.0002
Feature Resolution	[24, 24]	Max Iterations	80,000
Window Sizes	12	Backbone Multiplier	0.0
Attention Type	Linear	CLIP Multiplier	0.01

810 C DENSE PREDICTION TASKS EXPERIMENTAL DETAILS  
811812 We adopt Cat-Seg (Cho et al., 2024) as the base model for open-vocabulary segmentation, which  
813 supports plug-and-play integration of various image-text models. A unified training configuration is  
814 used across different ViT backbones, with detailed hyperparameters provided in Table B.  
815816 D VISUALIZATION OF SEMANTIC ALIGNMENT CAPABILITY FOR DENSE  
817 VISUAL FEATURES  
818819 We present the alignment capability of FG-CLIP 2 between dense visual features and text in both  
820 Chinese and English contexts. The results are shown in Figure A, where warmer colors indicate  
821 higher similarity between image regions and the matched text. Compared to the previous version,  
822 FG-CLIP 2 supports denser visual feature output and achieves strong bilingual semantic alignment  
823 and fine-grained perception capabilities.  
824825 E EXAMPLES OF CHINESE LONG CAPTION IMAGE-TEXT PAIRS  
826827 In Table C, we provide examples of long caption image-text pairs from the LIT-CN dataset, covering  
828 diverse scene categories such as indoor, outdoor, animals, products, and buildings. These captions  
829 not only describe fine-grained subject attributes (e.g., appearance, posture, spatial layout), but also  
830 detail the surrounding context, reflecting the dataset’s semantic richness and descriptive complexity.  
831832 F BOXCLASS-CN CATEGORY SCHEMA AND EXAMPLE EXPLANATION  
833834 Table D.1 and D.2 provide the complete list of categories in the BoxClass-CN dataset, separated by  
835 commas. We further present some examples from BoxClass-CN in Figure B.  
836837 G HYPERPARAMETER ABLATION STUDY  
838839 In addition to the global alignment learning objective, our model incorporates four auxiliary losses:  
840 Fine-Grained Visual Learning (FGV), Fine-Grained Textual Learning (FGT), Textual Intra-modal  
841 Contrastive Loss (TIC), and Cross-Modal Rank Loss (CMR). The weights for these losses are set  
842 using a sequential tuning strategy: starting from the base model trained with only the global alignment  
843 loss, we introduce each auxiliary loss one at a time, tune its weight while keeping previously added  
844 losses fixed (and excluding any future ones), and selected the value that yields the highest average  
845 performance on the validation set.  
846847 The figure C shows the average performance curves over different hyperparameter values for each  
848 loss, where the average is computed across several representative evaluation tasks: DCI, MSCOCO,  
849 DOCCI-CN, Flickr30k-CNA, Bbox Classification (COCO<sup>80</sup>), and Fine-Grained Understanding.  
850851 H EXAMPLES OF BILINGUAL TRAINING DATA  
852853 We present examples of the Chinese and English training data in Figures D and E, respectively.  
854855 I VISUAL ANALYSIS OF THE TEXTUAL INTRA-MODAL CONTRASTIVE LOSS  
856857 We conduct an embedding visualization comparing text representations with and without the TIC  
858 loss. As shown in the visualization at Table E.1 and Table E.2, when TIC is enabled, semantically  
859 similar but distinct phrases become better separated in the embedding space. This suggests that TIC  
860 indeed enhances semantic separability among fine-grained textual descriptions.  
861

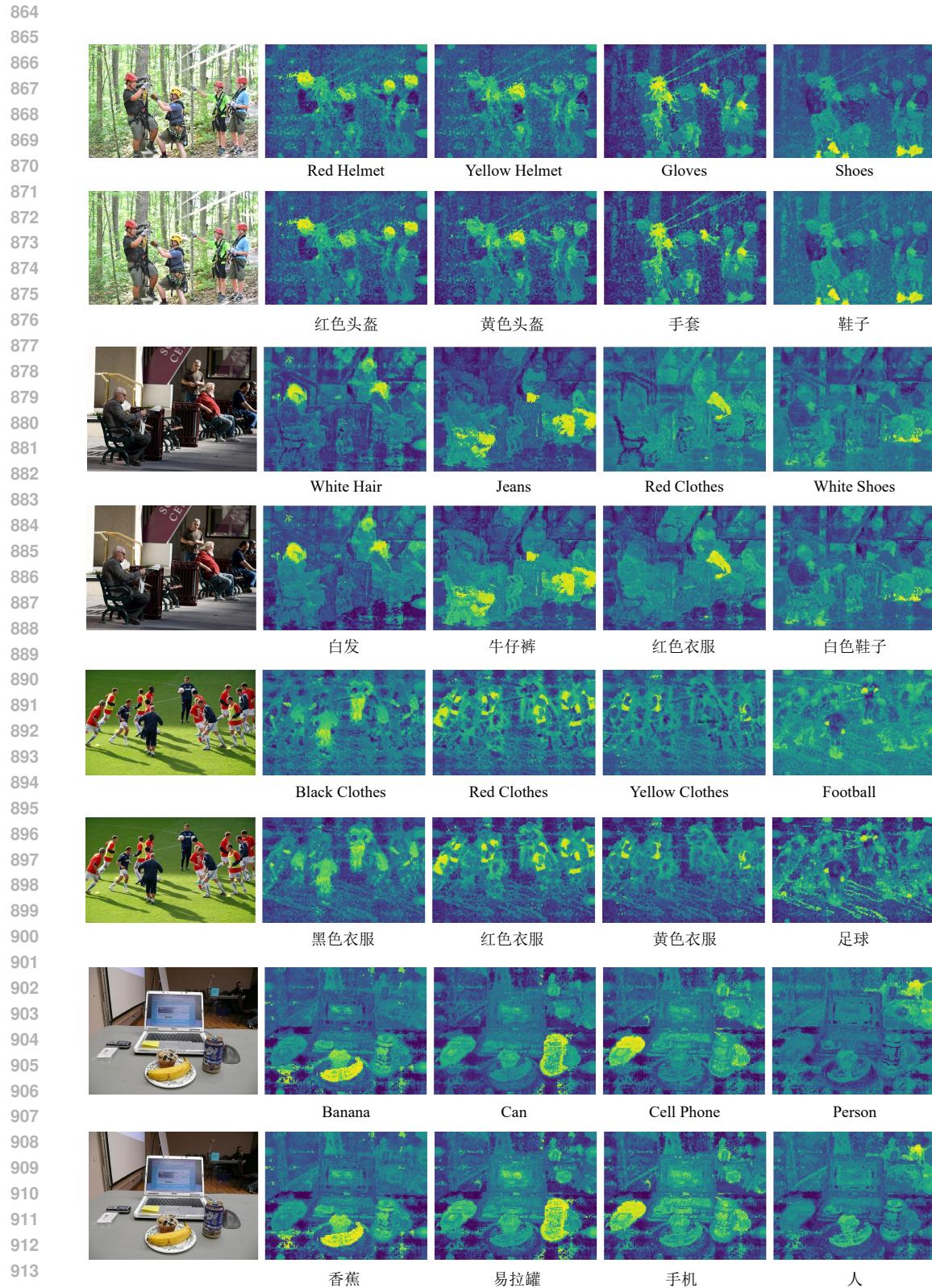


Figure A: Visualization of FG-CLIP 2's dense feature maps and semantic alignment capability in bilingual scenarios.

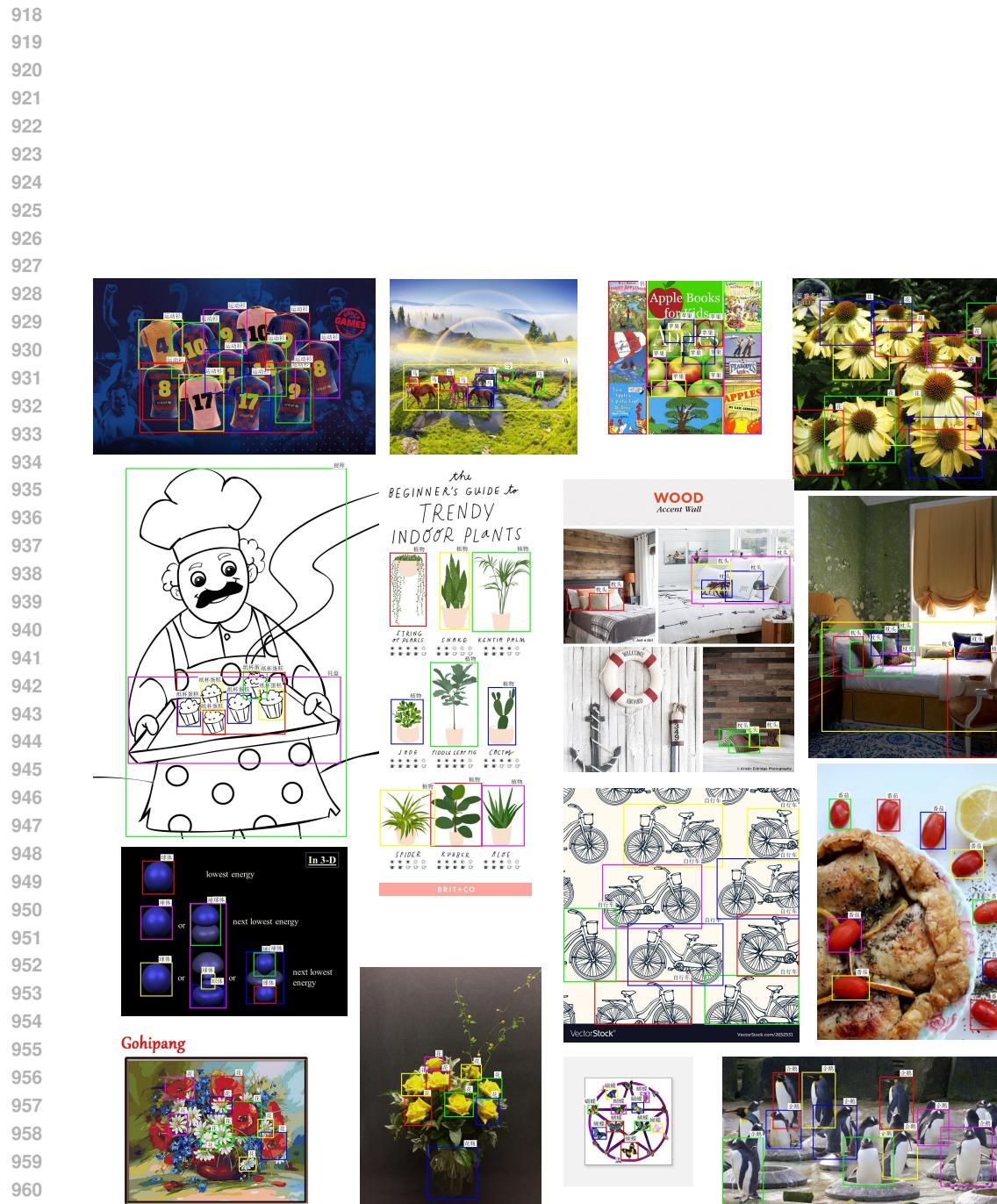


Figure B: Examples from BoxClass-CN.

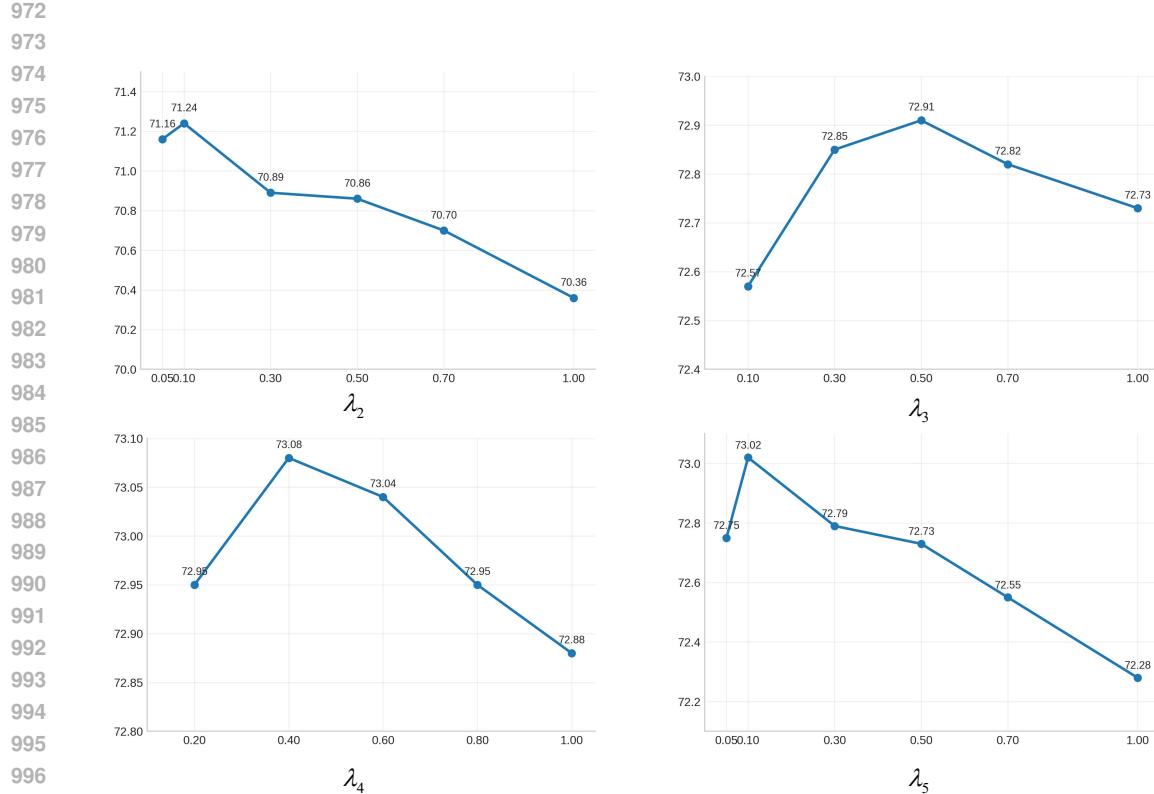
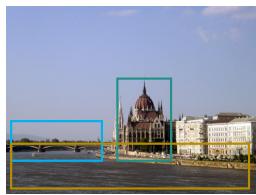


Figure C: The average performance curves over different hyperparameter values for each loss.



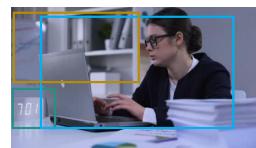
-----long caption-----  
 这幅图像呈现出一座欧洲风格大型城市的美丽景致。画面的主体是一座哥特复兴风格的宏伟建筑，拥有尖塔、飞扶壁以及巨大的圆顶，坐落在一条平静河流的岸边。从其庄严华丽的建筑风格来看，这座建筑很可能属于议会或政府综合建筑群。背景天空晴朗，点缀着轻薄的云彩，显示出一个阳光明媚、天气宜人的白天。画面前景中的河面十分平静，可见一艘小船，为画面增添了一丝悠闲与宁静的氛围。远处可以看到一座横跨河流的桥梁，将城市的两岸紧密相连，丰富了整体的城市景观。从光线来看，建筑右侧有柔和的阴影，推测拍摄时间可能在正午附近，阳光较高且明亮。整张图像呈现为高分辨率摄影风格，不仅展现了建筑的复杂细节，也清晰捕捉了天空与水面的柔美质感。画面中没有人物，重点在于建筑之美与自然环境的和谐共存。图像传达的情绪是一种庄严、宏伟与宁静的结合，既体现了历史建筑的力量与工程智慧，又融入了水面与蓝天带来的平静与悠然。

-----short caption-----  
 布达佩斯：从河上的船只视角拍摄的议会大厦另一景观。

-----region caption-----  
 一座位于平静河岸的建筑，带有尖塔、飞扶壁和巨大的圆顶。

-----region caption-----  
 一座远处的桥梁连接着城市的两岸，完善了整个城市景观。

-----region caption-----  
 平静河流



-----long caption-----  
 这幅图像呈现的是一个专业办公场景。一位身穿深色西装外套、戴着眼镜的人正在专注地使用笔记本电脑工作。画面左侧有一个时钟，时间显示为 7:01，暗示可能属于加班时段或面对紧迫的工作截止时间。桌面上摆放着一些文件和文件夹，表明正在处理工作或研究任务。背景中可以看到一个书架，上面摆放着多个文件夹，以及一块白板，上面有一些图表或书写的痕迹，进一步烘托出典型办公环境的氛围。整幅图采用真实、高清的摄影风格，光线柔和，细节丰富，对物体的质感和阴影呈现自然。画面中没有其他人物，也没有任何互动动作或文字信息。人物保持端坐姿态，双手放在笔记本电脑的键盘上，表现出专注、投入的工作状态。光线来自柔和的环境光源，可能是天花板灯或办公室台灯，没有明显的强烈阴影。整体氛围体现出一种高效、专注、富有工作压力但又专业有序的办公状态。

-----short caption-----  
 股票类素材描述：一位女办公室员工因工作量过大感到不开心，没有时间休息。

-----region caption-----  
 时钟，时间显示为 7:01

-----region caption-----  
 一位身穿深色西装外套、戴着眼镜的人正在专注地使用笔记本电脑工作

-----region caption-----  
 一个书架，上面摆放着多个文件夹，以及一块白板，上面有一些图表或书写的痕迹

Figure D: Example of Chinese Training Data.

1026

1027

1028

1029

1030

1031

1032

1033

1034

1035

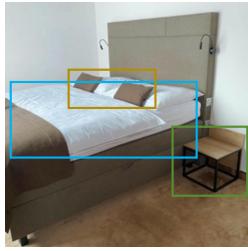
1036

1037

1038

1039

1040



-----long caption-----

The image presents a bedroom scene centered on a large bed with a tall, upholstered headboard. The headboard is light brown and has a smooth texture without any visible patterns. Two reading lights are mounted on the wall on each side of the headboard, extending outward with a flexible arm and a small light at the end. These lights are positioned at a height that seems suitable for reading. The bed frame is also light brown and has a contemporary design. On the bed, there is a white duvet and a couple of pillows, with one of them being a smaller pillow that matches the color of the reading lights, and the other being a larger pillow that appears to have a different color, possibly a neutral tone. At the foot of the bed, there is a small wooden side table with a black metal frame, which has a minimalistic design with a flat surface and a single visible drawer. The table's color palette includes brown and black, complementing the overall room tones. The lighting within the image is not discernible due to the lack of shadows or highlights that could indicate a specific light source. Instead, the room appears to be lit by ambient light that creates a soft glow, giving the space a cozy atmosphere. The style of the image is a photograph. The edges and shadows suggest a natural light source and the clarity of the objects points towards a high-resolution image captured by a camera.

-----short caption-----

Modern bedside table in a simple style in the hotel room – metal furniture

-----region caption-----

a small wooden side table with a black metal frame which has a minimalistic design with a flat surface and a single visible drawer

-----region caption-----

a white duvet and a couple of pillows with one of them

-----region caption-----

a smaller pillow that matches the color of the reading lights and a larger that appears to have a different color

-----long caption-----

This image depicts an aerial view of an oil rig's platform. In the foreground, there is a worker engaged in an activity on the edge of the platform, wearing safety gear such as jeans, a yellow hard hat, knee pads, and brown work boots. The worker appears to be suspended or working at height, secured by a safety harness and other equipment. The rig's infrastructure is comprised of metal beams, pipes, and various work platforms. The background reveals a large body of water, which could be the ocean. On the water's surface, there is a green helipad with a circular symbol, suggesting that this is a designated area for landing helicopters. The helipad is connected to the rig by a walkway. The weather appears to be clear, with bright sunlight casting shadows on the structure of the rig. The image is taken from a high vantage point, looking downwards towards the worker and the rig's platform, highlighting the scale and complexity of the offshore oil operation. The style of the image is a high-resolution photograph, capturing the intricate details of the industrial setting. There are no people or characters other than the worker, so there are no emotions to convey. The description is factual and does not include any subjective interpretations or personal opinions about the image.

-----short caption-----

An overhead view of the legs and harness of an industrial painter suspended from the underside of an offshore rig derrick, high above the deck below.

-----region caption-----

a worker engaged in an activity on the edge of the platform wearing safety gear such as jeans a yellow hard hat knee pads and brown work boots

-----region caption-----

a circular symbol suggesting that this is a designated area for landing helicopters

-----region caption-----

a high vantage point looking downwards towards the worker and the rig's platform highlighting the scale and complexity of the offshore oil operation

Figure E: Example of English Training Data.

1065

1066

1067

1068

1069

1070

1071

1072

1073

1074

1075

1076

1077

1078

1079

1080

1081

1082

1083

1084

1085

1086

1087

1088

1089

1090

1091

1092

1093

1094

1095

1096

1097

1098

1099

1100

1101

1102

1103

1104

1105

1106

1107

1108

1109

1110

1111

1112

1113

1114

1115

1116

1117

1118

1119

1120

1121

1122

1123

1124

1125

1126

1127

1128

1129

1130

1131

1132

1133

Table C: Examples from LIT-CN.



这张图片展示了一片海滨小镇的风景。前景是波光粼粼的海水，水面上有几块岩石。海岸边是一片沙滩，有几个人在沙滩上活动。背景是一排色彩柔和的建筑，主要为浅黄色、粉色和米色，建筑风格带有地中海风情。建筑后方是绿树覆盖的小山丘，山顶上有一座古老的城堡或堡垒。天空晴朗，呈现出淡蓝色，没有明显的云层。整体画面给人一种宁静、悠闲的感觉。

(This image depicts a seaside town. In the foreground is shimmering water with several rocks scattered across the surface. Along the shore lies a stretch of sandy beach, where a few people are engaged in activities. In the background stands a row of softly colored buildings in shades of light yellow, pink, and beige, featuring Mediterranean-style architecture. Behind the buildings are gently sloping hills covered with green trees, crowned by an ancient castle or fortress at the summit. The sky is clear and pale blue, with no noticeable clouds. The overall scene conveys a sense of tranquility and relaxation.)



这张图片展示了一组红酒的场景。前景中有两瓶标有“LOUIS LAFON”字样的红酒，瓶身上印有“QUALITÉ SELECTIONNÉE”字样，以及产区和酿酒信息等内容。两瓶红酒均配有深红色的蜡封瓶盖。旁边摆放着一个醒酒器，内有部分红酒，以及两只倒满红酒的透明酒杯。背景中可以看到一个浅灰色的桌面，桌面上还摆放着一小束粉色花卉和一个黄色的柠檬。整个画面背景为浅色，突出前景物体，风格简洁明了，以实物展示为主，无繁杂装饰。

(This image presents a scene featuring a selection of red wine. In the foreground are two bottles labeled “LOUIS LAFON,” with inscriptions including “QUALITÉ SELECTIONNÉE,” as well as information about the region and winemaking details. Both bottles are sealed with deep red wax closures. Beside them sits a decanter containing some red wine, along with two clear glasses filled with the wine. In the background, a light gray tabletop is visible, on which a small pink floral arrangement and a yellow lemon are placed. The overall background is light-colored, emphasizing the foreground objects. The style is simple and clean, focusing on the physical presentation of the items with no elaborate decorations.)



这张图片展示了两只蓝黄金刚鹦鹉。它们的羽毛主要是鲜艳的蓝色，胸部和腹部有黄色的羽毛。头部有绿色的羽毛，眼睛周围有白色和黑色的斑纹。两只鹦鹉面对面，喙部相触，似乎在互动或交流。背景是模糊的绿色，可能是树木或植被。鹦鹉站在一根木头上，姿态自然，显得亲密友好。

(This image shows two blue-and-gold macaws. Their feathers are predominantly bright blue, with yellow plumage on the chest and belly. The head features green feathers, and the area around the eyes has white and black markings. The two birds are facing each other, their beaks touching, appearing to interact or communicate. The background is a blurred green, likely representing trees or foliage. The parrots are perched on a wooden branch, positioned naturally, conveying a sense of closeness and friendliness.)



这张图片展示了一只手持金属镂空枫叶书签的特写。书签呈枫叶形状，由细致的金属镂空工艺制成，叶脉清晰，边缘有锯齿状设计。枫叶的主色调为金色，表面反射出一些光线。手指指甲涂有红色指甲油，末端略带光泽，握着书签的柄部。手的背景模糊，焦点集中在手和书签上。背景为一张白色纸张，纸张下方有一条粉色条纹，可能是书封或纸张的一部分。书签的阴影投射在纸张上，形状与书签一致。整体呈现出细腻的手工艺感和自然的枫叶形态。

(This image features a close-up of a hand holding a metal filigree maple leaf bookmark. The bookmark is shaped like a maple leaf and crafted with intricate metal openwork artistry, showcasing clearly defined veins and serrated edges. It is primarily golden in color, with its surface reflecting subtle highlights. The fingers hold the stem of the bookmark, and the nails are painted red with a slight sheen. The background of the hand is softly blurred, keeping the focus on the hand and the bookmark. The backdrop is a white sheet of paper with a pink stripe along the bottom, likely part of a book cover or decorative paper. The shadow of the bookmark is cast clearly onto the paper, matching its shape. The overall scene conveys fine craftsmanship and the natural beauty of a maple leaf form.)



图片展示了一位行人在路边的情景。前景中有两位主要人物：一位是身穿长款黑色风衣、搭配白色运动鞋和红色眼镜的女性，她肩上背着一个黑色包，手中拿着一杯白色的饮料，表情较为认真；另一位是一位穿蓝色和白色制服、戴着白色头盔的交警，他左手拿着一张纸状物品，站立姿态端正，面向前方。背景中有一棵绿叶树木，树叶有一些黄色的枯叶，显示出季节可能是秋季。路边有灰色的金属栏杆，地上散落着一些落叶。远处可以看到绿色的建筑物墙面和一个红色上衣的行人。整体环境为室外的街道路边场景，光线自然。

(The image depicts a scene of pedestrians by the roadside. In the foreground, there are two main figures: one is a woman wearing a long black trench coat, white sneakers, and red glasses. She carries a black bag over her shoulder and holds a white cup containing a beverage, with a serious expression on her face. The other figure is a traffic police officer dressed in a blue and white uniform and wearing a white helmet. He stands upright, facing forward, holding a sheet of paper-like object in his left hand. In the background, there is a tree with green leaves and some yellow, withered foliage, suggesting that the season may be autumn. A gray metal railing runs along the roadside, and fallen leaves are scattered on the ground. In the distance, a green building wall and another pedestrian wearing a red jacket can be seen. The overall setting is an outdoor street-side environment with natural lighting.)



这张图片展示了一个室内的场景，特别是客厅的一部分。前景中有一个浅色沙发，搭配棕色和蓝色抱枕，旁边放置了一条蓝色毯子。沙发旁有一张透明玻璃茶几，茶几上摆放着几本书和一束绿色植物，整体显得简洁而现代。背景是一扇带有白色百叶窗的三角形窗户，窗户两侧是深色窗帘。窗帘上方挂着一根细绳，带有金色环扣，下方悬挂着一盏简约的吊灯。地板上铺有黑白几何图案的地毯，角落里可以看到一个白色装饰凳和部分金色边框的画框。墙面为白色，带有简洁的线条装饰，整体色调以中性色为主，风格简约大气。画面中没有文字或特别的照明效果。

(This image depicts an indoor scene, specifically a part of a living room. In the foreground is a light-colored sofa adorned with brown and blue cushions, accompanied by a blue blanket placed beside it. Adjacent to the sofa stands a transparent glass coffee table, on which several books and a potted green plant are arranged, contributing to a clean and modern aesthetic. In the background is a triangular window fitted with white blinds, flanked by dark curtains on both sides. Above the curtains, a thin cord with golden ring attachments runs across, from which hangs a minimalist pendant lamp. The floor is covered with a black-and-white geometric-patterned rug. In the corner, a white decorative stool and part of a picture frame with a gold trim are visible. The walls are white, accented with simple linear details, and the overall color palette consists mainly of neutral tones, reflecting a sleek and sophisticated style. There is no text or special lighting effects in the image.)

1134

1135

1136

1137

1138

1139

1140

1141

1142

1143

Table D.1: All categories in BoxClass-CN, grouped and displayed by ID (1-300).

1144

id:1-100

1145

连衣裙, 书桌, 花瓶, 花, 壁纸, 椅子, 指甲油, 台灯, 花瓣, 床, 衬衫, 瓶子, 长沙发, 微波炉, 袋子, 眼镜, 靴子, 自行车, 可动人偶, 头盔, 植物, 领结, 毯子, 胶带, 枕头, 纸张, 领带, 吊坠, 链条, 太阳镜, 长裤, 房子, 屋顶, 葡萄酒杯, 胡子, 耳环, 草莓, 救生衣, 自动售货机, 口罩, 玩具枪, 展台, 麦克风, 电脑键盘, 老鼠, 橙子, 樱桃, 花束, 饼子, 咖啡, 饰物, 企鹅, 南瓜, 护目镜, 熊, 星星, 头发, 制服, 洗衣机, 运动衫, 棚屋, 院子, 横幅, 甜点, 车道, 卡车, 床头板, 灯, 叶子, 照片, 衣柜, 雨伞, 拱门, 汽车, 轮子, 外套, 电话, 储物柜, 辣椒, 窗帘, 工人, 奶牛, 露天平台, 苹果, 地球仪, 油瓶, 树, 三角形, 书, 车库, 商店, 罐子, 凳子, 楼梯, 门口, 控制面板, 消防栓, 雕塑, 跑步的人, 太阳能板

Dress, desk, vase, flower, wallpaper, chair, nail polish, table lamp, petal, bed, shirt, bottle, sofa, microwave, bag, glasses, boots, bicycle, action figure, helmet, plant, bow tie, blanket, tape, pillow, paper, tie, pendant, necklace, sunglasses, pants, house, roof, wine glass, beard, earrings, strawberry, life jacket, vending machine, mask, toy gun, display stand, microphone, computer keyboard, mouse, orange, cherry, bouquet, dice, coffee, ornament, penguin, pumpkin, goggles, bear, star, hair, uniform, washing machine, sweatshirt, shed, yard, banner, dessert, driveway, truck, headboard, lamp, leaf, photo, wardrobe, umbrella, arch, car, wheel, coat, telephone, locker, chili pepper, curtain, worker, cow, patio, apple, globe, oil bottle, tree, triangle, book, garage, store, jar, stool, staircase, doorway, control panel, fire hydrant, sculpture, running person, solar panel

id:101-200

1156

1157

原木, 地毯, 小提琴, 指甲, 骆驼, 篮球, 跑道, 厨师, 碗, 枝形吊灯, 袍子, 哑铃, 雕像, 冰块, 烤箱, 发带, 餐具, 郁金香, 马, 藤椅, 戒指, 托盘, 杯子, 购物袋, 拖拉机, 乌龟, 纪念碑, 甜甜圈, 鹿, 玩具, 玩具车, 行进乐队, 女人, 手提包, 卧室, 软管, 手套, 剪刀, 叉子, 桶, 眼睛, 托特包, 笔记本电脑, 缝纫机, 光线, 钢琴, 跑车, 滑梯, 柠檬, 摄像机, 车头灯, 蜜蜂, 飘虫, 刀, 披萨, 蝴蝶, 小雕像手办, 人行步道, 门, 走廊, 水族馆, 场地, 口袋, 枪, 宠物牵引绳, 围栏, 链条, 钱包, 兰花, 轮胎, 铅笔, 耳机, 柱子, 长椅, 灌木丛, 赛车, 花盆, 葡萄, 桨, 木筏, 岩石, 番茄, 柜台, 指甲油瓶, 鼓, 玩具拖拉机, 操作台, 镜头, 小鸟, 婚宴场地, 头巾, 健身器械, 茶包, 灯泡, 帽子, 精灵, 橡胶圈, 黄油, 立方体, 棒球手套

Log, carpet, violin, fingernail, camel, basketball, runway, chef, bowl, chandelier, robe, dumbbell, statue, ice cube, oven, hairband, cutlery, tulip, horse, rattan chair, ring, tray, cup, shopping bag, tractor, turtle, monument, donut, deer, toy, toy car, marching band, woman, handbag, bedroom, hose, gloves, scissors, fork, bucket, eye, tote bag, laptop, sewing machine, light ray, piano, sports car, slide, lemon, camera, headlight, bee, ladybug, knife, pizza, butterfly, figurine, sidewalk, door, corridor, aquarium, venue, pocket, gun, pet leash, fence, chain, wallet, orchid, tire, pencil, headphones, pillar, bench, bush, race car, flowerpot, grape, paddle, raft, rock, tomato, counter, nail polish bottle, drum, toy tractor, workbench, lens, bird, wedding venue, headscarf, fitness equipment, tea bag, light bulb, hat, elf, rubber band, butter, cube, baseball glove

id:201-300

1168

1169

1170

1171

1172

1173

1174

1175

1176

1177

1178

1179

1180

1181

1182

1183

1184

1185

1186

1187

1188

1189

1190

1191

1192

1193

1194

1195

1196

Table D.2: All categories in BoxClass-CN, grouped and displayed by ID (301-566).

1197

id:301-400

1198

后院, 人像模型, 火车, 毕业礼服, 猴子, 灯笼, 红酒架, 四轮越野车, 风车, 豆袋椅, 汤, 乐高人偶, 树桩, 圣诞树, 钳子, 绳子, 袖扣, 黑板, 连帽衫, 头冠, 眉毛, 报纸, 婴儿车, 婴儿连衣裙, 鸡尾酒, 毛巾架, 瑜伽垫, 狼, 山, 香槟, 埃菲尔铁塔, 阳台, 喷泉, 冠军腰带, 山羊, 面罩, 平底锅, 消防车, 爆米花机, 实验服, 风衣, 船坞, 信封, 啤酒瓶, 冲浪板, 面板, 塑料袋, 飞机, 窗台, 画笔, 洗漱包, 百叶窗, 婴儿床, 杏仁, 餐巾纸, 工具箱, 高尔夫球手, 香槟杯, 帆船, 干花, 行李, 瓷砖, 垃圾桶, 购物车, 梨, 密尔沃基工具包, 拖鞋, 山脉, 恐龙, 壁画, 高速公路, 梳子, 人字拖, 雪地靴, 士兵, 徒步旅行者, 叉车, 海绵, 燕尾服, 橄榄油, 齿轮, 加拿大国家电视塔, 小屋, 游戏机, 电线, 插头, 松鼠, 猕猴桃, 饼干, 躺椅, 音乐家, 老虎, 沙滩椅, 咖啡袋, 网球拍, 吊灯, 蘑菇, 昆虫, 家庭办公室, 煎饼

1199

Backyard, mannequin, train, graduation gown, monkey, lantern, wine rack, ATV, windmill, bean bag chair, soup, Lego minifigure, tree stump, Christmas tree, pliers, rope, cufflinks, blackboard, hoodie, crown, eyebrow, newspaper, stroller, baby dress, cocktail, towel rack, yoga mat, wolf, mountain, champagne, Eiffel Tower, balcony, fountain, championship belt, goat, face mask, frying pan, fire truck, popcorn machine, lab coat, trench coat, boat dock, envelope, beer bottle, surfboard, panel, plastic bag, airplane, windowsill, paintbrush, toiletry bag, blinds, crib, almond, napkin, toolbox, golfer, champagne flute, sailboat, dried flowers, luggage, tile, trash can, shopping cart, pear, Milwaukee tool kit, slippers, mountain range, dinosaur, mural, highway, comb, flip-flops, snow boots, soldier, hiker, forklift, sponge, tuxedo, olive oil, gear, CN Tower, cabin, game console, wire, plug, squirrel, kiwi, pie, recliner, musician, tiger, beach chair, coffee bag, tennis racket, chandelier, mushroom, insect, home office, pancake

1200

1201

1202

1203

1204

1205

1206

1207

1208

1209

1210

id:401-500

1211

编织吊椅, 玩具轨道, 花环, 茶, 钩针编织的苹果, 柠檬水, 火车车厢, 交通信号灯, 落地灯, 放大镜, 钩针编织花, 旋钮, 摆椅, 拳击袋, 眼线笔, 吧台凳, 棒球, 吉普车, 雨靴, 茎, 油量表, 柠檬角, 钢笔, 飞盘, 灭火器, 轮胎压力计, 面条, 长颈鹿, 煎锅, 菠萝, 加油站, 酒店, 香蕉, 拳击台, 车顶行李架, 纸巾, 电脑鼠标, 围巾, 考拉熊, 北极熊, 防水包, 3D眼镜, 婚纱, 甜椒, 刷子, 游乐场, 拳击手套, 音乐键盘, 泥塑人像, 防毒面具, 电影, 船, 海星, 医用口罩, 杯子架, 滑雪靴, 化妆包, 香槟瓶, 毛绒玩具, 老虎机, 狮子, 海岸, 碗碟架, 发电站, 鞋架, 越野摩托车, 雪滑板, 起重船, 素描, 花园水管, 牛仔靴, 汽车发动机, 棒球戒指, 锅架, 胶带卷, 校车, 高架床, 衣架, 双层巴士, 电视屏幕, 烤面包机专用袋, 汽车脚垫, 金属花, 警车, 医疗包, 油, 玩具火车, 床单, 急救包, 餐垫, 旅行袋, 乐高汽车, 高脚椅, 高尔夫球车, 精油, 肉桂棒, 烘焙用冷却架, 雏菊, 垃圾袋, 机油

1212

1213

1214

1215

1216

1217

1218

1219

1220

1221

1222

1223

id:501-566

1224

1225

玩具屋, 维京船, 蛋卷, 高性能经典跑车, 玩具键盘, 香水, 砂轮, 正装衬衫, 独木舟, 马球衬衫, 风扇, 啤酒杯, 雕刻人像, 录像带, 浴帘, 浴室防滑垫, 喷枪, 威士忌瓶, 方向盘, 耳机线, 刹车灯, 自动提款机, 拐杖, 战术腰带, 厕纸卷, 滑雪杖, 身体按摩油, 折叠椅, 奶瓶, 充电站, 狗窝, 存钱罐, 火车站, 面包卷, 冰淇淋机, 公文包, 旅行包, 蔬菜卷, 面部精油, 乳液瓶, 沙滩巾, 金属板, 烈酒杯, 邮差包, 电视摄像机, 猫窝, 杏仁糖花, 茶叶, 洗衣袋, 午餐包, 方糖, 眉笔, 威士忌杯, 芹菜条, 牙科椅, 电源线, 咖啡机, 沙发床, 温度计, 睡袋, 护肤油, 传送带, 西尔斯大厦, 曲棍球手套, 食品杂货袋, 卡车货厢

1226

1227

1228

1229

1230

1231

1232

1233

1234

1235

1236

1237

1238

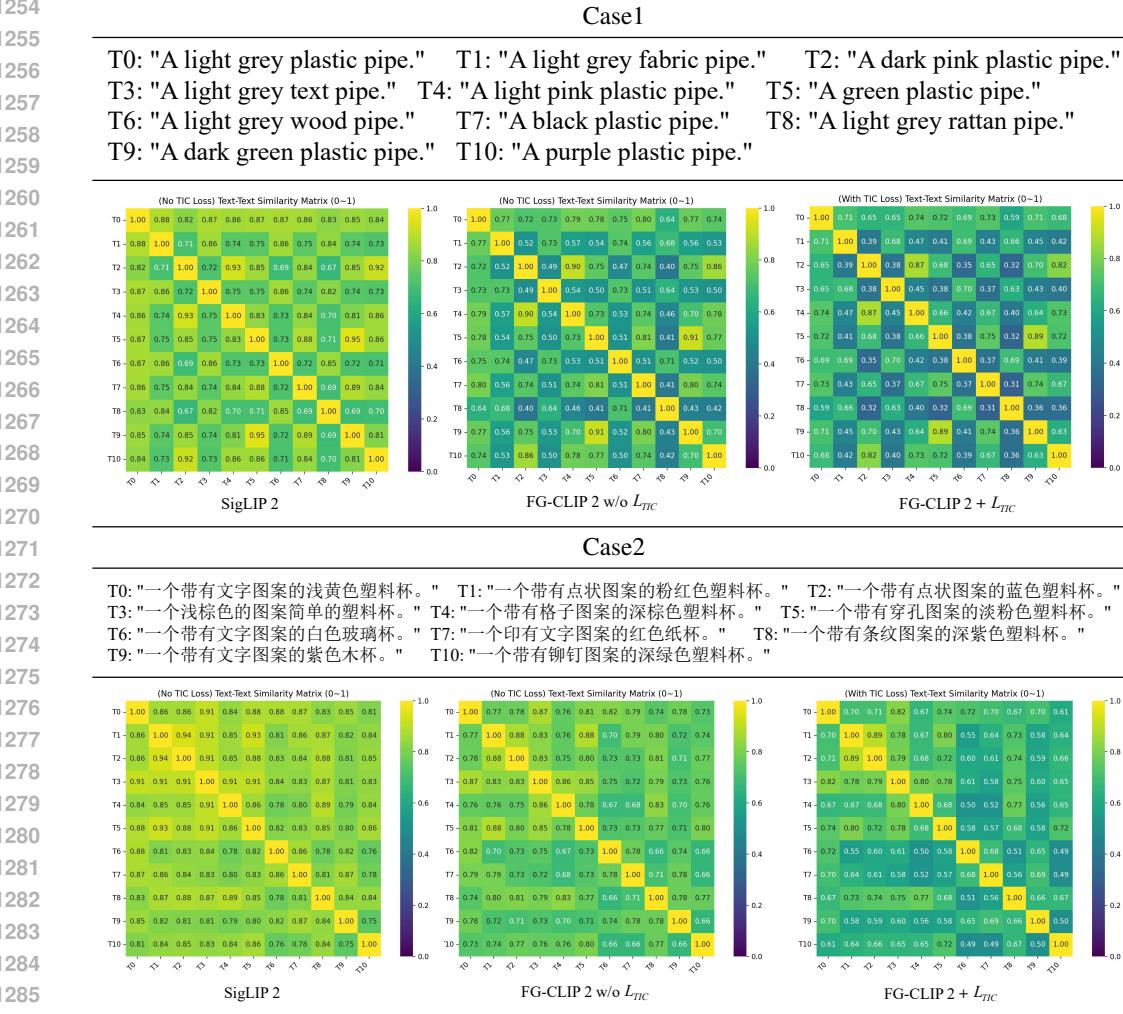
1239

1240

1241

1242  
1243  
1244  
1245  
1246  
1247  
1248  
1249  
1250  
1251  
1252  
1253  
1254  
1255  
1256  
1257  
1258  
1259

Table E.1: The Effectiveness of the Textual Intra-modal Contrastive Loss. (Case1 and Case2)



1270  
1271  
1272  
1273  
1274  
1275  
1276  
1277  
1278  
1279  
1280  
1281  
1282  
1283  
1284  
1285  
1286  
1287  
1288  
1289  
1290  
1291  
1292  
1293  
1294  
1295

1296

1297

1298

1299

1300

1301

1302

1303

1304

1305

1306

1307

Table E.2: The Effectiveness of the Textual Intra-modal Contrastive Loss. (Case3 and Case4)

1308

## Case3

1309

T0: "一个由布料制成的深红色枕头。" T1: "一个轻橙色的玻璃枕头。" T2: "一个暗棕色的纸质枕头。"  
 T3: "一种由文字组成的浅蓝色枕头。" T4: "一根轻蓝色的藤制枕头。" T5: "一个浅灰色的塑料枕头。"  
 T6: "一个轻紫色的天鹅绒枕头。" T7: "一个轻紫色的金属枕头。" T8: "一个蓝色的皮革枕头。"  
 T9: "一个塑料制成的黄色枕头。" T10: "一个羊毛制成的棕色枕头。"

1310

(No TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.87	0.84	0.93	0.92	0.88	0.88	0.89	0.88	0.88
T1	0.87	1.00	0.82	0.87	0.86	0.87	0.83	0.86	0.78	0.89
T2	0.84	0.82	1.00	0.84	0.84	0.89	0.82	0.85	0.79	0.87
T3	0.93	0.87	0.84	1.00	0.95	0.89	0.88	0.90	0.76	0.89
T4	0.92	0.86	0.84	0.95	1.00	0.89	0.90	0.90	0.81	0.89
T5	0.88	0.87	0.89	0.89	1.00	0.85	0.90	0.81	0.95	0.85
T6	0.88	0.83	0.82	0.88	0.90	1.00	0.91	0.91	0.81	0.85
T7	0.89	0.88	0.85	0.90	0.90	0.90	1.00	0.81	0.89	0.84
T8	0.80	0.78	0.79	0.81	0.81	0.81	0.81	1.00	0.82	0.78
T9	0.88	0.89	0.87	0.89	0.89	0.95	0.85	0.89	0.82	1.00
T10	0.88	0.82	0.87	0.88	0.89	0.85	0.86	0.84	0.78	0.85

SigLIP 2

(No TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.66	0.81	0.73	0.74	0.75	0.83	0.73	0.78	0.77	0.87
T1	0.66	1.00	0.70	0.67	0.68	0.76	0.69	0.75	0.67	0.75	0.66
T2	0.81	0.70	1.00	0.72	0.72	0.82	0.76	0.76	0.76	0.80	0.82
T3	0.73	0.67	0.72	1.00	0.83	0.76	0.75	0.74	0.81	0.72	0.70
T4	0.74	0.68	0.72	0.83	1.00	0.75	0.78	0.74	0.77	0.71	0.74
T5	0.75	0.76	0.82	0.76	0.75	1.00	0.79	0.80	0.77	0.89	0.76
T6	0.83	0.69	0.76	0.75	0.78	0.79	1.00	0.85	0.76	0.72	0.81
T7	0.73	0.75	0.76	0.74	0.74	0.80	0.85	1.00	0.74	0.70	0.70
T8	0.78	0.67	0.76	0.81	0.77	0.77	0.76	0.75	1.00	0.76	0.74
T9	0.77	0.75	0.80	0.82	0.72	0.71	0.89	0.72	0.74	1.00	0.75
T10	0.87	0.66	0.82	0.76	0.74	0.76	0.81	0.70	0.74	0.75	1.00

FG-CLIP 2 w/o  $L_{TIC}$ 

(With TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.55	0.71	0.60	0.62	0.62	0.74	0.66	0.65	0.64	0.79
T1	0.55	1.00	0.61	0.59	0.57	0.68	0.57	0.67	0.57	0.66	0.52
T2	0.71	0.61	1.00	0.59	0.57	0.71	0.62	0.65	0.63	0.71	0.69
T3	0.60	0.58	0.59	1.00	0.72	0.62	0.60	0.64	0.65	0.60	0.53
T4	0.62	0.57	0.57	0.72	1.00	0.59	0.66	0.66	0.66	0.59	0.59
T5	0.62	0.68	0.71	0.62	0.59	1.00	0.64	0.71	0.64	0.68	0.59
T6	0.74	0.57	0.62	0.60	0.66	0.64	1.00	0.74	0.59	0.56	0.70
T7	0.60	0.67	0.65	0.64	0.66	0.71	0.74	1.00	0.63	0.64	0.53
T8	0.65	0.57	0.63	0.65	0.66	0.64	0.59	0.65	1.00	0.65	0.57
T9	0.64	0.66	0.71	0.60	0.56	0.88	0.56	0.64	0.65	1.00	0.59
T10	0.79	0.52	0.68	0.53	0.59	0.59	0.70	0.53	0.57	0.59	1.00

FG-CLIP 2 +  $L_{TIC}$ 

## Case4

1325

T0: "A black wooden table with a flat surface on top." T1: "A brown rattan table with a flat surface on top." T2: "A dark pink paper table with a flat surface on top."  
 T3: "A light grey plastic table with a flat surface on top." T4: "A orange leather table with a flat surface on top." T5: "A dark purple velvet table with a flat surface on top."  
 T6: "A blue stone table with a flat surface on top." T7: "A light pink paper table with a flat surface on top." T8: "A white crochet table with a flat surface on top."  
 T9: "A purple leather table with a flat surface on top." T10: "A dark red leather table with a flat surface on top."

1326

(No TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.79	0.73	0.76	0.72	0.70	0.84	0.71	0.73	0.73	0.74
T1	0.79	1.00	0.72	0.76	0.75	0.68	0.78	0.70	0.72	0.76	0.76
T2	0.73	0.72	1.00	0.70	0.73	0.72	0.73	0.95	0.69	0.78	0.79
T3	0.76	0.76	0.70	1.00	0.70	0.64	0.79	0.74	0.78	0.69	0.69
T4	0.72	0.75	0.73	0.70	1.00	0.65	0.74	0.71	0.68	0.82	0.84
T5	0.70	0.68	0.72	0.64	0.65	1.00	0.71	0.69	0.65	0.85	0.76
T6	0.84	0.70	0.79	0.74	0.73	1.00	0.72	0.74	0.76	0.74	0.74
T7	0.71	0.70	0.95	0.74	0.71	0.73	1.00	0.77	0.72	0.71	0.71
T8	0.73	0.77	0.69	0.78	0.68	0.65	0.74	1.00	0.67	0.68	0.68
T9	0.73	0.72	0.76	0.69	0.82	0.85	0.76	0.72	0.67	1.00	0.86
T10	0.74	0.76	0.79	0.69	0.84	0.76	0.74	0.71	0.68	0.86	1.00

SigLIP 2

(No TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.74	0.73	0.76	0.72	0.73	0.77	0.72	0.71	0.71	0.76
T1	0.74	1.00	0.71	0.74	0.74	0.69	0.69	0.70	0.73	0.70	0.74
T2	0.73	0.71	1.00	0.71	0.75	0.76	0.71	0.92	0.70	0.80	0.81
T3	0.76	0.74	0.73	1.00	0.71	0.60	0.75	0.78	0.77	0.71	0.70
T4	0.72	0.74	0.75	0.71	1.00	0.69	0.71	0.75	0.68	0.83	0.86
T5	0.73	0.69	0.76	0.68	0.69	1.00	0.71	0.68	0.65	0.85	0.87
T6	0.77	0.69	0.71	0.75	0.71	0.77	1.00	0.71	0.69	0.72	0.70
T7	0.72	0.70	0.92	0.78	0.75	0.68	0.61	1.00	0.73	0.75	0.73
T8	0.73	0.73	0.70	0.77	0.68	0.68	0.69	0.73	1.00	0.68	0.68
T9	0.71	0.70	0.80	0.71	0.83	0.85	0.72	0.75	0.65	1.00	0.88
T10	0.76	0.74	0.81	0.70	0.86	0.79	0.70	0.73	0.61	0.88	1.00

FG-CLIP 2 w/o  $L_{TIC}$ 

(With TIC Loss) Text-Text Similarity Matrix (0~1)

T0	1.00	0.48	0.54	0.54	0.52	0.45	0.58	0.51	0.36	0.51	0.48
T1	0.48	1.00	0.49	0.49	0.42	0.47	0.35	0.47	0.40	0.38	0.43
T2	0.54	0.49	1.00	0.49	0.42	0.46	0.47	0.50	0.48	0.36	0.44
T3	0.54	0.49	0.62	1.00	0.44	0.49	0.41	0.45	0.39	0.42	0.44
T4	0.52	0.42	0.50	0.44	1.00	0.47	0.45	0.48	0.43	0.37	0.47
T5	0.45	0.47	0.59	0.49	0.47	1.00	0.39	0.52	0.33	0.62	0.64
T6	0.58	0.35	0.46	0.41	0.50	0.39	1.00	0.44	0.39	0.51	0.42
T7	0.51	0.47	0.92	0.65	0.48	0.52	0.44	1.00	0.44	0.49	0.48
T8	0.36	0.40	0.41	0.39	0.36	0.33	0.39	0.44	1.00	0.37	0.31
T9	0.31	0.38	0.54	0.42	0.82	0.62	0.51	0.49	0.37	1.00	0.81
T10	0.48	0.43	0.57	0.44	0.77	0.64	0.42	0.48	0.31	0.81	1.00

FG-CLIP 2 +  $L_{TIC}$ 

1340

1341

1342

1343

1344

1345

1346

1347

1348

1349