SAFETY IS ESSENTIAL FOR RESPONSIBLE OPEN ENDED SYSTEMS

Anonymous authors

004

010 011

012

013

014

015

016

017

018

019

021

023

Paper under double-blind review

ABSTRACT

AI advancements have been significantly driven by a combination of foundation models and curiosity-driven learning aimed at increasing capability and adaptability. A growing area of interest within this field is Open-Endedness — the ability of AI systems to continuously and autonomously generate novel and diverse artifacts or solutions. This has become relevant for accelerating scientific discovery and enabling continual adaptation in AI agents. This position paper argues that the inherently dynamic and self-propagating nature of Open-Ended AI introduces significant, underexplored risks, including challenges in maintaining alignment, predictability, and control. This paper systematically examines these challenges, proposes mitigation strategies, and calls for action for different stakeholders to support the safe, responsible and successful development of Open-Ended AI.

1 INTRODUCTION

025 Artificial Intelligence (AI) has achieved remarkable progress driven by foundation models Bommasani 026 et al. (2021). Across various modalities, these models have shown incredible performance in tasks for 027 which they were designed Ramesh et al. (2021); Rombach et al. (2022); Achiam et al. (2023); Radford et al. (2023); Brooks et al. (2024). However, they are not yet capable of autonomously and indefinitely 029 producing new creative, interesting and diverse discoveries. Such open-ended discovery is key to making progress on problems that cannot be solved by simply following a specified objective. Indeed humans use such open-ended processes to accumulate knowledge and solve difficult problems. Thus, 031 it has been argued that open-endedness is a key ingredient for Artificial Superintelligence Stanley (2019); Team et al. (2021); Jiang et al. (2023); Nisioti et al. (2024); Hughes et al. (2024), which could 033 outperform humans at a wide range of tasks Morris et al. (2024). 034

Specifically, Open-Ended (OE) AI continuously produces artifacts that are novel and learnable to humans. This enables it to generate new, complex, creative, and adaptive solutions over time Soros & Stanley (2014); Soros et al. (2017); Clune (2019); Sigaud et al. (2023); Lu et al. (2024); Akiba et al. (2025). Unlike traditional AI systems that optimize for fixed objectives, OE AI perpetually explores new solutions and adapts to changing circumstances without being given an explicit goal.

There is a large diversity of systems that aim to be open-ended. The Paired Open-Ended Trailblazer (POET) Wang et al. (2019) facilitates OE exploration by co-evolving environments and agents. The environments become increasingly diverse and complex based on the weaknesses of the agent, while the agent develops solutions that may transfer across environments. The Voyager method Wang et al. (2024a) is an

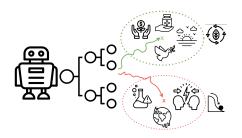


Figure 1: Open-Ended (OE) AI generates novel artifacts over time, potentially coevolving with environments and societal values to drive creativity and progress. However, this *position paper* argues that its unpredictability, difficulty in control, and cascading misalignment pose catastrophic risks to societal and global stability.

LLM-powered embodied agent for lifelong learning in Minecraft. It utilizes an automatic curriculum for OE exploration, a skill library to store and retrieve complex behaviors, and an iterative prompting mechanism incorporating feedback and self-verification to refine executable actions.

054 Historically, it has been a challenge to guide the exploration of OE AI toward artifacts that are 055 novel and interesting to humans, but recently Large Language Models (LLMs) have been applied to 056 accelerate this process. Since LLMs have been trained on large amounts of human data, they have 057 built an understanding of what is interesting and desirable to humans. Recent work has leveraged 058 LLMs as backbones for OE evolution and exploration Lehman et al. (2023); Zammit et al. (2024); Aki et al. (2024). This opens up many beneficial applications for OE AI. LLMs have shown emergent behaviors in OE scientific discovery Lu et al. (2024), navigating novel environments Wang et al. 060 (2024a), and eliciting truthful answers from LLMs Khan et al. (2024). However, with the growing 061 interest and potentially large-scale application of OE AI, we must evaluate and address the risks 062 coming from these systems. 063

While OE AI offers significant potential, it poses unique and substantial risks that must be addressed for a safe and responsible deployment. Its inherent unpredictability and uncontrolla bility necessitate dedicated research to ensure safety and alignment with societal values.

While discussions on AI safety are broadly relevant, this paper focuses on the unique safety challenges
posed by OE AI. Previously, Hughes et al. (2024) and Ecoffet et al. (2020) have touched on these.
However, this paper offers a deeper, more comprehensive, and up-to-date overview of the safety
challenges in OE AI and suggests concrete research directions and actions to address them.

We first define OE AI and argue that its safety depends on our ability to systematically identify, assess, and mitigate risks (Section 2). Building on this definition we identify that issues such as the unpredictability of future artifacts, the trade-off between creativity and control, and the difficulties of aligning OE AI with human values are key safety risks (Section 3). To address these, we suggest research directions to develop continuously adapting oversight, constraints, and safety evaluations for OE AI (Section 4). Lastly, we call for actions from various stakeholders - industry, academic researchers, governments, and funding bodies (Section 5).

078 079

2 WHAT IS OPEN-ENDEDNESS

- 081 Defining Open-Endedness remains an ongoing challenge, as no single definition fully captures its 082 scope Stanley & Soros (2016); Soros et al. (2017); Stanley & Lehman (2015); Lehman & Stanley 083 (2011). One definition frames OE as generating artifacts that are novel, and learnable for an external 084 observer Hughes et al. (2024). This definition introduces subjectivity, as novelty can be evaluated 085 differently depending on the observer, and excludes systems generating unintelligible artifacts (e.g., 086 TV noise). Another view models OE systems via evolutionary principles, prioritizing diversity and incremental complexity in behaviors or solutions Packard et al. (2019). Such systems autonomously 087 create and solve problems without direct human intervention, mimicking the processes of biological 880 evolution. Another perspective views OE as a search problem characterized by continuous exploration 089 across a vast and evolving state space, generating diverse and increasingly complex solutions without 090 explicit end goals Sigaud et al. (2023). We adopt the definition by Hughes et al. (2024), which frames 091 OE as generating novel and learnable artifacts to an external observer. This is particularly suited for 092 ML contexts and facilitates a structured approach to identifying risks w.r.t. the observer incurred by 093 the evolving nature.
- 094

Definition An open-ended AI system is one that continuously generates artifacts that are novel and learnable for an observer.

Consider a system S that generates a sequence of artifacts $A_{1:t}$ indexed by time t, where each artifact resides within a state space A. The observer O has a model M_t that has observed a sequence of artifacts $A_{1:t}$ up until t. M_t is a proxy for the observer's prediction capability. The observer judges the quality of M_t by a loss function $\mathcal{L}(M_t, A_{t'})$, where $A_{t'}$ is an artifact generated in future, t' > t.

Borrowing from Hughes et al. (2024) we consider a system to display **novelty** if it produces artifacts that become progressively less predictable as time advances. Formally:

104

105

$$\forall t < t' \; \exists t^* > t' : \mathbb{E}[\mathcal{L}(M_t, A_{t'})] < \mathbb{E}[\mathcal{L}(M_t, A_{t^*})]$$

(1)

This means for a static observer there will always be an artifact in the future that is worse at getting
 predicted. This ensures the system keeps generating outputs that introduce new and less predictable
 information over time.

OE AI is learnable if incorporating a longer history of artifacts improves the observer's ability to predict future outputs. This is formalized as:

$$\forall t < t' < t^* : \mathbb{E}[\mathcal{L}(M_t, A_{t^*})] > \mathbb{E}[\mathcal{L}(M_{t'}, A_{t^*})]$$
(2)

Here, the loss decreases as the observer integrates more past artifacts, indicating improved under standing over time.

In contrast, we use the term "traditional" to refer to all AI systems that are not open-ended. This also
 includes systems that act autonomously or continually adapt, such as LLM agents or RL algorithms,
 as long as they are not open-ended.

Applications OE AI has been proposed as the pathway for agents to evolve skills and knowledge 119 in diverse, rich task environments across infinite horizons, often as a way to achieve ASI Team 120 et al. (2021); Hughes et al. (2024); Nisioti et al. (2024). Systems like REAL-X Cartoni et al. (2020; 121 2023) demonstrate the potential of OE architectures for sensorimotor skill acquisition, where robots 122 autonomously learn how to interact with their environments and generalize these skills to new tasks. 123 OE learning has been applied to games to create evolving game scenarios Che et al. (2024). It can 124 serve as a complementary tool in human-led innovation, augmenting creativity by generating a new 125 environment. Genie Bruce et al. (2024) produces an OE array of unique, action-controllable virtual 126 worlds from various prompts. Lu et al. (2024) demonstrated the potential of using LLMs in an OE 127 setting to follow the scientific discovery paradigm: from hypothesis to paper generation. Finally, there 128 is a stream of work that uses the MAP-Elites framework Mouret & Clune (2015) to generate diverse 129 adversarial prompts to improve model robustness via iterative adversarial fine-tuning Samvelyan et al. (2024); Deep Pala et al. (2024); Han et al. (2024). 130

131

111

118

Safety of Open-Ended AI Several definitions of safety exist, originating from domains with a long 132 history of safety research, such as aerospace, healthcare, and critical infrastructure Suyama (2005); 133 Kafka (2012). In AI, safety aims to prevent AIs from being used to cause harm or themselves causing 134 harm. Thus safety for AI is often tied to error-based definitions, where safety violations occur due to 135 identifiable faults or deviations from intended behavior. However, applying these definitions to OE 136 AI presents unique challenges. For OE AI, which evolves unpredictably and generates novel outputs, 137 errors cannot be predefined as it operates beyond the boundaries of prior design specifications. As a 138 result, error-based definitions of safety are inapplicable to OE. Instead, we adopt a risk management 139 perspective to define safety for OE AI Leveson (2012). Here, safety is the ability to systematically 140 *identify, assess, and mitigate risks*, even when the system's artifacts are novel. This definition implies 141 that under high-stakes scenarios, the absence of risk management itself is a risk.

142 143 144

3 CHALLENGES AND RISKS

OE AI exhibits emergent behavior, where outputs may deviate significantly from expectations due to vast input spaces, complex internal dynamics, or adaptation to changing conditions. They may develop unsafe, unethical, or misaligned behaviors. We discuss their inherent unpredictability challenges, trade-offs, difficulty to control, and broader consequential societal factors.

150 3.1 UNPREDICTABILITY

OE AI is necessarily unpredictable, due to its propensity for generating novel artifacts. As artifacts become increasingly novel they become even more unpredictable. Imagine an OE system S that produces increasingly novel scientific discoveries $A \in A$. Some of these artifacts, e.g., the recipe for a novel, dangerous viruses, are unsafe. However, when starting to run this system at time t it will be difficult for us to foresee which discoveries it will produce at a later time t' and predict their safety.

Formally, we assume that a lower loss of the model on an artifact corresponds to a higher probability of predicting that artifact: $\mathcal{L}(M_t, A_{t'}) < \mathcal{L}(M_t, A_{t^*}) = P_{M_t}(A_{t'}) > P_{M_t}(A_{t^*})$, with $P_{M_t}(a)$ denoting the probability the model puts on artifact *a*. This assumption holds for loss functions such as Cross-Entropy. From this, it becomes clear that the novelty definition (Definition 1) implies that there is always a more unpredictable artifact that will be generated in the future: $\forall t < t' \exists t^* > t'$: $\mathbb{E}[P_{M_t}(A_{t'})] > \mathbb{E}[P_{M_t}(A_{t^*})].$ ¹⁶² Unpredictability makes it difficult for us to anticipate whether trajectories of future artifacts $\{A_t\}_{t=n}^{\infty}$ ¹⁶³ will be safe. This undermines our ability to conduct solid risk management, thus, reducing the trust ¹⁶⁴ we can put in such a system to behave safely.

In traditional Reinforcement Learning (RL) the reward function provides a handle to predict future trajectories. RL agents are trained to create trajectories that achieve high rewards on a clearly defined reward function. From this we can derive that highly rewarded trajectories are more likely to be generated than trajectories with low reward. In contrast, OE AI lacks such an objective. Additionally, the novelty criteria Lehman & Stanley (2011) or evolutionary developments Lehman & Stanley (2010); Dharna et al. (2022) in OE AI encourage divergence, making it more complex to anticipate the safety of future artifacts.

172 173

174

3.2 CREATIVITY VS. CONTROL

OE AI creates a fundamental tension between creativity and control in OE search Ecoffet et al. (2020).

Lack of Explicit Guidance. OE AI often operates without predefined boundaries, constraints, or
 clear objectives. This allows it to explore vast and uncharted regions of the state space freely and
 generate creative solutions that are not reachable by simply specifying the desired state. While this
 promotes novelty and creativity, it makes it difficult to predict or control the direction of the system
 to ones we deem valuable and safe.

Evolving Model and Environment. Unlike traditional systems, the agent gains new skills and capabilities, generating new artifacts and adapting over time. The evolving nature of the OE AI requires adapting the guidance given to it since the constraints on objectives given earlier might become outdated as the model and its environment change.

- 186 187
- 3.3 MISALIGNMENT
- 188

189 The ability to align AI systems with human values is a grand challenge within the field of AI Safety Hendrycks et al. (2021); Ji et al. (2024) that is essential for ensuring the safety and usefulness of AI 190 systems. The aim is to align the goals that an AI system intrinsically values and pursues with those of 191 its human designers. This can include intended objectives, ethical guidelines, or safety requirements. 192 AI alignment is usually formulated for AI systems that optimize an explicit, human-designed reward 193 function. In such a setting misalignment can occur because the reward function does not precisely 194 match the designers' objective Krakovna et al. (2020) or because the AI internalizes goals that are 195 different from the explicit incentives Shah et al. (2022); Di Langosco et al. (2022). 196

However, OE AI does not optimize an explicitly defined reward function with a focus on diversity.
Instead, the designers may provide implicit incentives by structuring the search process in ways that
are likely to lead to artifacts that they value highly. This necessitates a different lens for analyzing the
alignment of OE AI Ecoffet et al. (2020).

The designer might not correctly specify their values in the structure of the OE AI or process. The result would be an OE AI being driven towards an undesired goal. OE AI could still learn to intrinsically pursue goals that are different from those specified in the OE process. For example, humans evolved by evolution, which is an OE process whose structure causes it to optimize for inclusive fitness. However, humans do not value inclusive fitness intrinsically but have intrinsic drives towards sugary foods or protected sex.

Alignment of Evolving Systems. Another difference is that the goals pursued by an OE AI can
 evolve throughout its lifetime, while the goals pursued by a traditional ML system remain static. This
 means that tests or guarantees about the alignment of an OE AI at one time become outdated as the
 system keeps evolving. Additionally, as OE AI explores novel situations, we cannot be sure that
 alignment training performed initially will generalize to new situations.

Alignment of Interactive Components. OE AI systems often include multiple components. This
 might be an LLM with additional components, multiple agents or an agent in an evolving environment.
 Even though these individual components might be aligned, their dynamic interactions can result in
 emergent behaviors that are misaligned. For example, in an OE process with multiple agents who do
 not want to cause harm, incentives and inter-agent dynamics can force them into equilibria where

harming others is necessary. Due to the unpredictable nature of each component, predicting such dynamics is not possible.

219 3.4 TRACEABILITY

220

Tracking and reproducing an OE AI's processes and outcomes generated is a challenging task. This could be coupled with a negative cascading effect that small changes in artifacts or system states can trigger, causing the system to diverge from its intended trajectory.

Lack of Reproducibility. Reproducing the evolving OE AI at a certain time is significantly more
 challenging than traditional AI due to 1) the lack of clear training objectives, and 2) not being able to
 reproduce the intermediate environmental feedback and states Flageat & Cully (2023); Flageat et al.
 (2024), making it hard to trace and attribute the exploration paths. For example, evolving to images
 that resemble real objects from random initial images is like "finding needles in a haystack" Secretan
 et al. (2008) given the astronomically large search space. This can hinder the rigorous scientific
 progress in this domain which requires transparent, open-source, and auditable technologies.

231 **Difficulties in Attribution.** A research direction that helps enable oversight, and evaluate and 232 improve the correctness of solutions is self-consistency checks. Wang et al. (2023) used a prompting 233 strategy that samples a diverse set of reasoning paths and then selects the most consistent answer. 234 Fluri et al. (2024) proposed a framework to evaluate superhuman models by checking if they follow 235 interpretable human rules, e.g., counterfactuals should flip the predicted decisions. Creating similar tests for OE AI is more difficult. One can change the parameters of the initial state of an OE AI 236 to create a counterfactual environment; however, due to compounded cascading effects, the effects 237 of the changed parameters cannot be easily isolated and are entangled with other novelty-related 238 randomized intermediate states. 239

240 241

3.5 RESOURCE CONSTRAINTS

242 As the OE AI runs longer, it generates increasingly complex artifacts that require more computational 243 and human resources to evaluate. Unlike traditional ML models, OE AI requires more continuous 244 evaluation without clear guarantees of utility. OE AI is run for a longer time before producing 245 useful results since it involves much exploration and is not targeted toward specific useful results. 246 Furthermore, it is difficult to predict whether an OE AI will produce valuable artifacts. Thus, the 247 significant computational resources might not be justified. These issues are exacerbated in OE 248 AI that employs an LLM as a backbone since their large parameter size makes them expensive to run compared to smaller specialized models. Therefore, developing OE AI with adaptive resource 249 constraints is important. 250

251 252

3.6 TRADE-OFFS

253 As the OE AI systems evolve, they must balance compet-254 ing priorities, often resulting in trade-offs that make the 255 deployment of these systems challenging. As explained 256 in Figure 2, OE AI inherently faces a trade-off between 257 speed, novelty, and safety, creating a trilemma where op-258 timizing two of these dimensions often compromises the 259 third. Speed refers to the rate at which the system can 260 generate new artifacts. Novelty measures the degree of 261 uniqueness or originality in each newly generated artifact. Safety represents the system's adherence to predefined 262 constraints, ensuring outputs avoid harmful, unethical, or 263 undesirable outcomes. 264



Figure 2: The Impossible Triangle of OE AI illustrates that safety, speed, and novelty cannot be maximized together.

Application-Specific Needs. Trade-offs can be difficult to navigate because they can depend on
 the types of problems we use OE AI for, which may require specific emphasis on one of these
 dimensions. In safety-critical applications such as drug discovery or medical diagnosis, safety is the
 foremost concern, often necessitating slower exploration to ensure rigorous validation and prevent
 harm, limiting novelty and speed. Conversely, in applications like gaming or art, novelty is prioritized
 to foster creativity, where the associated risks are generally lower, allowing safety to be sacrificed

in favor of rapid, diverse output generation. Lastly, in autonomous vehicles or real-time industrial systems, the focus is on quick, reliable responses, with novelty being a secondary concern to ensure the system can operate effectively in dynamic, time-sensitive environments.

273 274

275 3.7 SOCIAL AND HUMAN RISKS

276 277

It is crucial to consider the societal risks of OE AI. While all new technologies may have negative
 societal consequences, the unpredictable and evolving nature of OE AI may amplify known AI harms
 or introduce unanticipated ones.

The Rate of Novelty. OE AI generates more novel artifacts than traditional AI and the rate of innovation and disruption is harder to anticipate. This might outpace society's ability to adapt, integrate, and understand new developments. History provides examples of the disruptive effects of excessive novelty, such as the Industrial Revolution, which, while transformative, led to widespread social upheaval, labor displacement, and the erosion of traditional ways of life. Purely AI-led innovation can result in a loss of human agency in shaping scientific and societal progress, leaving individuals feeling disconnected from the process of discovery and creation.

Uninteresting Artifacts. OE AI should produce results that are interesting and useful to the observer. 288 Quantifying "interestingly new" progress has been one of the grand challenges in OE research. 289 Foundation models have been used as a Model-of-Interestingness (MoI) Zhang et al. (2024b) to 290 denote the human notion of what can be considered "novel" and at the same time "interesting". 291 However, OE AI could still produce uninteresting artifacts. This could be because its sense of 292 interestingness might be misaligned with ours or because it may get stuck in a narrow set of artifacts 293 without exploring more widely. Also, as artifacts can be very complex it can be difficult for humans 294 to determine whether they are truly interesting and useful. This could lead to situations where an OE 295 AI produces useless, uninteresting artifacts, while humans do not recognize this. If such a system is 296 kept running it will be a waste of resources. Furthermore, it might limit human creativity if human 297 ideas are biased by generated artifacts or if humans think there is nothing more to explore. Such problems are now discussed with LLMs and how they can homogenize individuals' beliefs and lead 298 to a false impression of consensus Burton et al. (2024). 299

Difficulty to Plan. As discussed in Section 3.5, it is intractable to foresee, plan, or track the OE AI's progress or whether it would produce valuable solutions. Given limited resources, we may need to prioritize which problems we delegate to OE AI. This has a resemblance to funding decisions for research proposals. Our society needs transparent, fairways of deciding on appropriate allocations.

304 **Reshaping Human Values.** LLMs may learn to mislead humans as a result of reward hacking Wen 305 et al. (2024), wrongly convincing human evaluators that performance has increased. Persuasion, 306 deception, or drifting to rogue goals are examples of the catastrophic risks of AI discussed in the 307 literature with anticipation of becoming more likely when AI is adaptive Hendrycks et al. (2023), 308 such as the case in OE AI. Due to cascading effects, OE AI may generate solutions that are initially, 309 and then increasingly, misaligned, such as inaccurate scientific findings or biased policies. Values within societies may also drift over time, sometimes for the worse Hendrycks et al. (2023). As 310 humans continue to get exposed to these proliferating artifacts, they might get normalized and set 311 harmful precedence, i.e, OE AI may gradually change societal and human values instead of getting 312 OE AI aligned to human values. 313

Accountability. Assigning accountability for the actions of traditional AI is an ongoing legal and ethical debate. However, it is even more complicated for OE systems, since they act autonomously and inherently behave in ways they were not designed to. This makes it unclear whether developers can be blamed for the wrongdoings of the model. Furthermore, OE AI does not follow traditional procedures for training and data collection, requiring new frameworks for assigning responsibility.

Environmental Factors. Current AI models use exuberant amounts of energy. Training GPT-3
 consumed 1287 MWh of electricity, resulting in 502 metric tons of carbon emission Patterson et al.
 (2021). Data centers use around 2.5 percent of global electricity, rivaling the aviation industry
 in greenhouse gas emissions Pfeiffer (2023). The current paradigm of OE AI uses LLMs as a
 backbone; running these models continuously requires a high amount of computation, which can
 have a significant environmental impact.

³²⁴ 4 TECHNICAL MITIGATIONS OF RISKS

To address the risks and challenges, we explore and suggest research directions that enhance safety against catastrophic risks while responsibly maintaining the benefits of OE exploration.

4.1 Oversight

326

327

328

330

As it is hard to anticipate the safety of OE processes, it is critical to oversee, either by humans or
 another system, their behavior during execution. Oversight provides a mechanism to monitor, guide,
 and correct system behavior, ensuring outputs align with human values and safety expectations.

334 Human-in-the-Loop Oversight. Ultimately, only humans can define safety and desirable values. 335 Thus it is critical to have a human in the loop when OE AI is run. This could mean that a human 336 actively monitors new artifacts. The human overseer could intervene when unsafe artifacts are 337 generated or filter which artifacts should be propagated to future iterations of the system. Furthermore, 338 a human overseer could provide feedback and guidance that steers the OE process in interesting 339 directions. OE can involve AI and human components working together Secretan et al. (2008). However, humans are limited in their capacity and might not be able to accurately judge complex 340 artifacts, but should nevertheless set standards to remain in control. 341

342 Interpretable Decision-Making. To facilitate humans in providing oversight, future research needs 343 to create interpretable OE AI whose decisions and reasoning traces are transparent to a human 344 observer. Forcing OE AI to reason about its decisions in natural language, makes it inherently interpretable to humans, allowing inspection and failure detection Hu & Clune (2024); Betley et al. 345 (2025). Systems can be trained to explain their artifacts to a weaker model to simulate a human 346 overseer. Furthermore, interpretability tools can be used to understand which input features Wang 347 et al. (2024b) or inner representations Alain & Bengio (2018); Cunningham et al. (2023) were relevant 348 to a decision. 349

Hierarchical Oversight. Oversight can be expensive when a human or a large model needs to check
 every artifact. Hierarchical oversight can structure the supervision into layers, where a less expensive
 monitoring process oversees every artifact and reports artifacts or behaviors to higher levels with
 more expensive supervisors. Works such as Christiano et al. (2018); Chavan & Chavan (2024)
 propose mechanisms where higher layers guide or intervene in the functioning of lower layers. By
 analyzing the system's outputs at multiple levels of abstraction, hierarchical oversight can identify
 risks before they escalate while being resource efficient.

Scalable Oversight. Providing effective oversight is difficult for humans when generated artifacts 357 become too complex for them to evaluate accurately. Scalable oversight seeks to align AI systems 358 whose outputs surpass human expertise or are too numerous for humans to evaluate properly Burns 359 et al. (2023). Approaches such as Iterated Distillation and Amplification (IDA) Christiano et al. 360 (2018), Debate Irving et al. (2018) or Recursive Reward Modeling (RRM) Ibarz et al. (2018) could 361 be applied to ensure the safety of OE AI. For example, OE AI could be forced to justify its actions 362 in a debate with another agent, RRM could be used to align an overseer AI that can accurately 363 evaluate new artifacts, or OE AI could be trained via IDA to internalize human notions of safety and 364 interestingness. Furthermore, self-diagnostic tools such as Kamoi et al. (2024); Huang et al. (2024) can be applied to OE AI to detect vulnerabilities in the system. 366

OE AI for Adaptive Oversight. For OE AI, oversight should not only scale to complex artifacts but also accommodate the dynamic nature of OE AI by developing adaptable evaluation and uncertainty thresholds. An overseer needs to be able to generalize to novel, possibly OOD artifacts. OE AI itself can be used to develop new safety-specialized mechanisms that work in tandem with the diversity-driven OE AI. An example is an overseer OE AI that co-evolves and judges safety.

OE AI for Risk Extrapolation. Similarly, a specialized OE AI can be used to anticipate and simulate
 in advance the future trajectories of artifacts and assess their risks and cascading effects. This OE AI
 could be optimized to generate novel but specifically harmful artifacts. This would need quantification
 and uncertainty methods to measure how close the main artifact is to the hypothesized harmful ones,
 based on this, an abortion or intervention step can follow.

Consequential Actions. As OE AI continues to evolve and explore, it may intervene in its environments. We already observe strong progress in autonomous and embodied agents. However, for

risky applications, e.g., scientific experiments, we would need to limit the OE AI from performing
catastrophically consequential actions where we cannot yet anticipate their outcomes. An alternative
is to build simulations and models that are faithful to our world that would enable sand-boxed artifact
generation. Given the challenges posed by novel and emergent artifacts, exploring causal models is a
promising direction, as they exhibit greater robustness on novel data Richens & Everitt (2024).

4.2 CONSTRAINTS

Most existing safety frameworks focus on structured environments with predefined goals. However,
 building guardrails to prevent the OE AI from exploring unsafe artifacts will be crucial to ensure the
 safety of these systems.

388 Constrained Exploration. Since OE AI often pursues diversity, the exploration process can inadver-389 tently drive the system into unsafe or misaligned state spaces. By constraining exploration to an ϵ -ball, 390 the system can balance novelty with safety, similar to safe exploration in RL Garcia & Fernández 391 (2015). This requires constrained novelty metrics that evaluate novelty relative to both past behaviors 392 and predefined safety constraints. In simple, discrete domains, such a novelty metric could be 393 formally specified, while LLM-based judges could quantify novelty in more complex domains. Based on the novelty scores of new artifacts, it would be possible to penalize novel behaviors that exceed 394 a probabilistic safety threshold or confidence bound, as modeled using techniques like Gaussian 395 Processes Sui et al. (2015); Turchetta et al. (2016) or reachability analysis Krakovna et al. (2018); 396 Fisac et al. (2018). Furthermore, novelty search can be combined with shielding mechanisms Dawood 397 et al. (2024) to dynamically reject unsafe actions. Finally, safety constraints also can be introduced in 398 Minimal Criterion Coevolution Brant & Stanley (2017). 399

Artifact Complexity Budget. Setting a complexity budget might help balance novelty and exploration
 with the ability of humans to understand, evaluate, and digest new artifacts. This budget serves as a
 safeguard, preventing excessive unpredictability and mitigating the risk of negative compounding
 effects that may arise from unrestrained exploration. By dynamically adjusting this budget it is
 possible to navigate the creativity-control trade-off.

405 Setting Specific Rules. While OE AI continuously evolves and faces new challenges, there are rules 406 we never want it to break. Although such rules cannot cover all unsafe behaviors, they can still 407 prevent some failures. While constraints do limit the creativity of the OE AI by cutting off some of the search space, the system is still able to openly explore the remaining space, thus retaining 408 its open-endedness. To take a more abstract and flexible view, rules could be specified as general 409 principles in a constitution Bai et al. (2022) that can be reinterpreted in new situations, or dynamically 410 created and updated by AI. An LLM guiding the OE AI's decisions can either reason about these 411 rules Guan et al. (2025) or causally Kıcıman et al. (2024). Recent work Zaremba et al. (2025) shows 412 the potential and promise of LLMs, when given enough intermediate reasoning steps, to reason in 413 compliance tasks. This also provides an effective framework for overseers to judge new artifacts. 414

415 4.3 ADAPTIVE ALIGNMENT

416 Current alignment techniques assume a model and its environment remain static, thus only requiring 417 safety training once. New continual alignment algorithms could allow us to adapt safety as the 418 model and its circumstances change Zhang et al. (2024a). While Moskovitz et al. (2024) composite 419 reward weighting dynamically and Hong et al. (2024) address overoptimization and ambiguity, they 420 lack robust mechanisms for long-term feedback loops. Multi-agent RL for co-evolving alignment 421 dynamics in OE systems can be a promising research direction. Using dynamic reward functions 422 can adjust the reward signals to reflect the evolving human preferences or system performance. 423 Adaptive preference scaling Fang et al. (2024); Hong et al. (2024), and distributional preference 424 reward modeling Li et al. (2024) have been used to refine reward functions in RL-based systems 425 by adjusting reward weights in response to shifting human feedback or performance degradation. 426 For OE AI, dynamic reward calibration must go beyond simple reward adjustments to handle the continuous and diverse outputs produced by such systems. 427

428 429

430

4.4 SAFETY EVALUATIONS

Finally, continuous safety evaluation of OE AI is important for understanding the extent of unsafe behaviors.

Benchmarking OE Safety. Developing benchmarks specifically for OE AI is crucial for quantifying
 its risks and evaluating failure modes. Existing benchmarks, such as those on multi-agent risks and
 unintended consequences Rivera et al. (2020), provide some insights but fail to incorporate the unique
 characteristics of OE algorithms. A dynamic benchmark explicitly designed for OE AI would need
 to address its continuous evolution, novelty generation, and dynamic complexity. For example, the
 difficulty of tests could be adjusted to the OE AI's changing capabilities.

438 Redteaming OE Systems. The previously outlined direction of "extrapolating risks" is beneficial 439 to anticipate future risks even if the OE system is aligned. On the other hand, targeted red teaming 440 can reveal failures for individual components or the entire system. Red teaming allows us to 441 stress-test OE systems by actively probing their vulnerabilities and finding situations in which they 442 behave unsafely. This could involve manually or adversarially finding inputs on which the OE system misbehaves. Lehman et al. (2023); Bradley et al. (2023); Liu et al. (2024) uses LLMs to enhance 443 genetic programming by generating diverse, functional artifacts. These outputs could serve as 444 adversarial artifacts to test and evaluate system robustness like in Samvelyan et al. (2024), but here 445 the aim would be to test the entire OE systems. Further, one could construct an environment in which 446 the OE system is being led to produce unsafe artifacts. 447

448

450

449 5 CALL FOR ACTION

Ensuring the responsible deployment of OE AI requires active engagement from various stakeholders.

Funding bodies can shape research priorities. They could urge OE researchers to consider and address the safety risks of their work. Further, they could dedicate resources toward robust safety mechanisms and evaluations for OE AI.

Research on the intersection of safety and OE research is crucial, impactful and under-explored. We argue that safety should be a critical part of OE research. This requires general awareness of the risks and dedicated research on safety problems. Additionally, the AI safety community should dedicate research to the specific risks of OE AI. We hope this paper can provide a bridge to foster exchange and collaboration between these communities.

460
 461
 461
 462
 462
 463
 463
 464
 465
 465
 465
 466
 466
 467
 468
 468
 469
 469
 469
 469
 460
 460
 460
 460
 460
 460
 460
 461
 462
 463
 464
 465
 465
 465
 466
 467
 468
 468
 469
 469
 469
 460
 460
 460
 460
 460
 460
 460
 460
 460
 461
 462
 463
 464
 465
 465
 465
 465
 466
 467
 467
 468
 468
 469
 469
 469
 469
 469
 469
 460
 460
 461
 462
 462
 463
 463
 464
 465
 465
 465
 466
 467
 467
 468
 468
 469
 469
 469
 469
 469
 469
 469
 469
 460
 460
 461
 462
 462
 463
 464
 465
 465
 466
 467
 468
 468
 469
 469
 469
 469
 469
 469
 469
 460
 460
 460
 460
 460
 460
 460

Policy Makers should mandate audits of sufficiently capable OE AI to ensure adherence to safety
 standards and societal values. Comprehensive auditing protocols must account for the dynamic and
 emergent nature of these systems.

Industry deploying OE AI must implement and rigorously test oversight mechanisms and guardrails
 for OE systems. Furthermore, comprehensive evaluation of societal and catastrophic risks should be
 conducted in collaboration with third-parties, academia and governments.

470
471
471
472
472
474
475
475
476
476
476
477
477
477
478
478
479
479
479
470
470
471
471
472
472
472
473
474
474
474
475
475
476
476
477
477
478
478
478
479
479
471
471
471
472
471
472
472
472
473
474
474
474
474
474
474
475
475
476
476
477
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478
478

473 474

475

6 CONCLUSION

476 Open-Ended AI is a promising paradigm for generating novel, adaptive solutions in complex and 477 dynamic environments, driving interest across research and applied domains. However, its open-ended 478 nature introduces specific safety challenges that must be addressed to enable responsible deployment 479 and maximize its societal benefits. We argue that the inherent unpredictability and uncontrollability of 480 OE AI, challenges in ensuring and maintaining alignment, traceability, and societal impacts, as well 481 as trade-offs in resource use and safety. We highlight the critical importance of human and automated 482 oversight over OE AI. Further, we suggest ways of giving adaptive guidelines to OE AI that retain its 483 creativity and co-evolve with it. Lastly, we call for targeted safety evaluations and provide concrete suggestions on how different stakeholders can contribute to the responsible development of OE AI. 484 Ultimately, we hope this paper will lead the OE and safety communities and other stakeholders to 485 consider safety a priority in the development and deployment of OE AI.

486 REFERENCES 487

522

527

529

- 488 Josh Achiam, Steven Adler, Sandhini Agarwal, Lama Ahmad, Ilge Akkaya, Florencia Leoni Aleman, Diogo Almeida, Janko Altenschmidt, Sam Altman, Shyamal Anadkat, et al. Gpt-4 technical report. 489 arXiv, 2023. 490
- 491 Fuma Aki, Riku Ikeda, Takumi Saito, Ciaran Regan, and Mizuki Oka. Llm-poet: Evolving com-492 plex environments using large language models. In the Genetic and Evolutionary Computation 493 Conference Companion, 2024. 494
- 495 Takuya Akiba, Makoto Shing, Yujin Tang, Qi Sun, and David Ha. Evolutionary optimization of model merging recipes. Nature Machine Intelligence, pp. 1-10, 2025. 496
- 497 Guillaume Alain and Yoshua Bengio. Understanding intermediate layers using linear classifier probes. 498 arXiv, 2018. 499

500 Yuntao Bai, Saurav Kadavath, Sandipan Kundu, Amanda Askell, Jackson Kernion, Andy Jones, 501 Anna Chen, Anna Goldie, Azalia Mirhoseini, Cameron McKinnon, Carol Chen, Catherine Olsson, 502 Christopher Olah, Danny Hernandez, Dawn Drain, Deep Ganguli, Dustin Li, Eli Tran-Johnson, Ethan Perez, Jamie Kerr, Jared Mueller, Jeffrey Ladish, Joshua Landau, Kamal Ndousse, Kamile 504 Lukosuite, Liane Lovitt, Michael Sellitto, Nelson Elhage, Nicholas Schiefer, Noemi Mercado, Nova DasSarma, Robert Lasenby, Robin Larson, Sam Ringer, Scott Johnston, Shauna Kravec, 505 Sheer El Showk, Stanislav Fort, Tamera Lanham, Timothy Telleen-Lawton, Tom Conerly, Tom 506 Henighan, Tristan Hume, Samuel R. Bowman, Zac Hatfield-Dodds, Ben Mann, Dario Amodei, 507 Nicholas Joseph, Sam McCandlish, Tom Brown, and Jared Kaplan. Constitutional ai: Harmlessness 508 from ai feedback, 2022. 509

- 510 Jan Betley, Xuchan Bao, Martín Soto, Anna Sztyber-Betley, James Chua, and Owain Evans. Tell me 511 about yourself: Llms are aware of their learned behaviors. arXiv, 2025. 512
- Rishi Bommasani, Drew A Hudson, Ehsan Adeli, Russ Altman, Simran Arora, Sydney von Arx, 513 Michael S Bernstein, Jeannette Bohg, Antoine Bosselut, Emma Brunskill, et al. On the opportuni-514 ties and risks of foundation models. arXiv, 2021. 515
- 516 Herbie Bradley, Andrew Dai, Hannah Benita Teufel, Jenny Zhang, Koen Oostermeijer, Marco 517 Bellagente, Jeff Clune, Kenneth Stanley, Gregory Schott, and Joel Lehman. Quality-diversity 518 through AI feedback. In Second Agent Learning in Open-Endedness Workshop, 2023. 519
- 520 Jonathan C Brant and Kenneth O Stanley. Minimal criterion coevolution: a new approach to 521 open-ended search. In the Genetic and Evolutionary Computation Conference, 2017.
- Tim Brooks, Bill Peebles, Connor Holmes, Will DePue, Yufei Guo, Li Jing, David Schnurr, Joe 523 Taylor, Troy Luhman, Eric Luhman, et al. Video generation models as world simulators. [LINK], 524 2024. 525
- Jake Bruce, Michael D Dennis, Ashley Edwards, Jack Parker-Holder, Yuge Shi, Edward Hughes, Matthew Lai, Aditi Mavalankar, Richie Steigerwald, Chris Apps, et al. Genie: Generative 528 interactive environments. In ICML, 2024.
- Collin Burns, Pavel Izmailov, Jan Hendrik Kirchner, Bowen Baker, Leo Gao, Leopold Aschenbrenner, 530 Yining Chen, Adrien Ecoffet, Manas Joglekar, Jan Leike, et al. Weak-to-strong generalization: 531 Eliciting strong capabilities with weak supervision. arXiv, 2023. 532
- Jason W Burton, Ezequiel Lopez-Lopez, Shahar Hechtlinger, Zoe Rahwan, Samuel Aeschbach, 534 Michiel A Bakker, Joshua A Becker, Aleks Berditchevskaia, Julian Berger, Levin Brinkmann, et al. 535 How large language models can reshape collective intelligence. Nature human behaviour, 8(9): 536 1643-1655, 2024. 537
- Emilio Cartoni, Davide Montella, Jochen Triesch, and Gianluca Baldassarre. Real-x-robot open-538 ended autonomous learning architectures: Achieving truly end-to-end sensorimotor autonomous learning systems. arXiv, 2020.

- 540 Emilio Cartoni, Davide Montella, Jochen Triesch, and Gianluca Baldassarre. Real-x-robot open-541 ended autonomous learning architecture: Building truly end-to-end sensorimotor autonomous 542 learning systems. Transactions on Cognitive and Developmental Systems, 15(4):2014–2030, 2023. 543 Parikshit Chavan and Peeyusha Chavan. Automation of ad-ohc dashbord and monitoring of cloud 544 resources using genrative ai to reduce costing and enhance performance. In the IEEE International Conference on Innovations and Challenges in Emerging Technologies (ICICET), 2024. 546 547 Haoxuan Che, Xuanhua He, Quande Liu, Cheng Jin, and Hao Chen. Gamegen-x: Interactive 548 open-world game video generation. arXiv, 2024. 549 Paul Christiano, Buck Shlegeris, and Dario Amodei. Supervising strong learners by amplifying weak 550 experts. arXiv, 2018. 551 552 Jeff Clune. Ai-gas: Ai-generating algorithms, an alternate paradigm for producing general artificial intelligence. arXiv, 2019. 553 554 Hoagy Cunningham, Aidan Ewart, Logan Riggs, Robert Huben, and Lee Sharkey. Sparse autoen-555 coders find highly interpretable features in language models. arXiv, 2023. 556 Murad Dawood, Ahmed Shokry, and Maren Bennewitz. A dynamic safety shield for safe and efficient reinforcement learning of navigation tasks. arXiv, 2024. 558 559 Tej Deep Pala, Vernon YH Toh, Rishabh Bhardwaj, and Soujanya Poria. Ferret: Faster and effective 560 automated red teaming with reward-based scoring technique. arXiv, 2024. 561 Aaron Dharna, Amy K. Hoover, J. Togelius, and L. Soros. Transfer dynamics in emergent evolutionary 562 curricula, 2022. 563 564 Lauro Langosco Di Langosco, Jack Koch, Lee D Sharkey, Jacob Pfau, and David Krueger. Goal 565 misgeneralization in deep reinforcement learning. In ICML, 2022. 566 Adrien Ecoffet, Jeff Clune, and Joel Lehman. Open questions in creating safe open-ended ai: tensions 567 between control and creativity. In Artificial Life Conference Proceedings 32, pp. 27–35. MIT Press, 568 2020. 569 570 Feiteng Fang, Liang Zhu, Xi Feng, Jinchang Hou, Qixuan Zhao, Chengming Li, Xiping Hu, Ruifeng 571 Xu, and Min Yang. Clha: A simple yet effective contrastive learning framework for human alignment. In the Joint International Conference on Computational Linguistics, Language Resources 572 and Evaluation (LREC-COLING), 2024. 573 574 Jaime F Fisac, Anayo K Akametalu, Melanie N Zeilinger, Shahab Kaynama, Jeremy Gillula, and 575 Claire J Tomlin. A general safety framework for learning-based control in uncertain robotic 576 systems. Transactions on Automatic Control, 64(7):2737–2752, 2018. 577 Manon Flageat and Antoine Cully. Uncertain quality-diversity: evaluation methodology and new 578 methods for quality-diversity in uncertain domains. Transactions on Evolutionary Computation, 579 2023. 580 581 Manon Flageat, Hannah Janmohamed, Bryan Lim, and Antoine Cully. Exploring the performance-582 reproducibility trade-off in quality-diversity. arXiv, 2024. 583 Lukas Fluri, Daniel Paleka, and Florian Tramèr. Evaluating superhuman models with consistency 584 checks. In SaTML, 2024. 585 586 Javier Garcia and Fernando Fernández. A comprehensive survey on safe reinforcement learning. Journal of Machine Learning Research, 16(1):1437–1480, 2015. 588 Melody Y. Guan, Manas Joglekar, Eric Wallace, Saachi Jain, Boaz Barak, Alec Helyar, Rachel Dias, 589 Andrea Vallone, Hongyu Ren, Jason Wei, Hyung Won Chung, Sam Toyer, Johannes Heidecke, 590 Alex Beutel, and Amelia Glaese. Deliberative alignment: Reasoning enables safer language models, 2025. 592
- ⁵⁹³ Vernon Toh Yan Han, Rishabh Bhardwaj, and Soujanya Poria. Ruby teaming: Improving quality diversity search with memory for automated red teaming. *arXiv*, 2024.

602

607

613

619

624

631

632

633

- Dan Hendrycks, Nicholas Carlini, John Schulman, and Jacob Steinhardt. Unsolved problems in ml safety. *arXiv*, 2021.
- Dan Hendrycks, Mantas Mazeika, and Thomas Woodside. An overview of catastrophic ai risks.
 arXiv, 2023.
- Ilgee Hong, Zichong Li, Alexander Bukharin, Yixiao Li, Haoming Jiang, Tianbao Yang, and Tuo
 Zhao. Adaptive preference scaling for reinforcement learning with human feedback. In *NeurPS*, 2024.
- 603 Shengran Hu and Jeff Clune. Thought cloning: Learning to think while acting by imitating human thinking. *NeurIPS*, 2024.
- Jie Huang, Xinyun Chen, Swaroop Mishra, Huaixiu Steven Zheng, Adams Wei Yu, Xinying Song, and Denny Zhou. Large language models cannot self-correct reasoning yet. In *ICLR*, 2024.
- Edward Hughes, Michael Dennis, Jack Parker-Holder, Feryal Behbahani, Aditi Mavalankar, Yuge
 Shi, Tom Schaul, and Tim Rocktaschel. Open-endedness is essential for artificial superhuman intelligence. *ICML*, 2024.
- Borja Ibarz, Jan Leike, Tobias Pohlen, Geoffrey Irving, Shane Legg, and Dario Amodei. Reward
 learning from human preferences and demonstrations in atari. In *NeurIPS*, 2018.
- 614 Geoffrey Irving, Paul Christiano, and Dario Amodei. Ai safety via debate. *arXiv*, 2018.
- Jiaming Ji, Tianyi Qiu, Boyuan Chen, Borong Zhang, Hantao Lou, Kaile Wang, Yawen Duan, Zhonghao He, Jiayi Zhou, Zhaowei Zhang, Fanzhi Zeng, Kwan Yee Ng, Juntao Dai, Xuehai Pan, Aidan O'Gara, Yingshan Lei, Hua Xu, Brian Tse, Jie Fu, Stephen McAleer, Yaodong Yang, Yizhou Wang, Song-Chun Zhu, Yike Guo, and Wen Gao. Ai alignment: A comprehensive survey, 2024.
- Minqi Jiang, Tim Rocktäschel, and Edward Grefenstette. General intelligence requires rethinking exploration. *Royal Society Open Science*, 10(6):230539, 2023.
- P. Kafka. The automotive standard iso 26262, the innovative driver for enhanced safety assessment & technology for motor cars. *Procedia Engineering*, 45:2–10, 2012.
- Ryo Kamoi, Yusen Zhang, Nan Zhang, Jiawei Han, and Rui Zhang. When can llms actually correct their own mistakes? a critical survey of self-correction of llms. *Transactions of the Association for Computational Linguistics*, 12:1417–1440, 2024.
- Akbir Khan, John Hughes, Dan Valentine, Laura Ruis, Kshitij Sachan, Ansh Radhakrishnan, Edward
 Grefenstette, Samuel R. Bowman, Tim Rocktäschel, and Ethan Perez. Debating with more
 persuasive llms leads to more truthful answers. In *ICML*, 2024.
 - Emre Kıcıman, Robert Ness, Amit Sharma, and Chenhao Tan. Causal reasoning and large language models: Opening a new frontier for causality. *TMLR*, 2024.
- Victoria Krakovna, Laurent Orseau, Ramana Kumar, Miljan Martic, and Shane Legg. Penalizing side
 effects using stepwise relative reachability. *arXiv*, 2018.
- Victoria Krakovna, Jonathan Uesato, Vladimir Mikulik, Matthew Rahtz, Tom Everitt, Ramana Kumar, Zac Kenton, Jan Leike, and Shane Legg. Specification gaming: the flip side of ai ingenuity. [LINK], 2020.
- Joel Lehman and Kenneth O Stanley. Revising the evolutionary computation abstraction: minimal
 criteria novelty search. In *the 12th annual conference on Genetic and evolutionary computation*,
 2010.
- Joel Lehman and Kenneth O Stanley. Abandoning objectives: Evolution through the search for novelty alone. *Evolutionary computation*, 19(2):189–223, 2011.
- Joel Lehman, Jonathan Gordon, Shawn Jain, Kamal Ndousse, Cathy Yeh, and Kenneth O Stanley.
 Evolution through large models. In *Handbook of Evolutionary Machine Learning*, pp. 331–366.
 Springer, 2023.

648 649 650	Nancy G. Leveson. Engineering a Safer World: Systems Thinking Applied to Safety. MIT Press, 2012.
651 652	Dexun Li, Cong Zhang, Kuicai Dong, Derrick Goh Xin Deik, Ruiming Tang, and Yong Liu. Aligning crowd feedback via distributional preference reward modeling. <i>arXiv</i> , 2024.
653 654 655 656	Shengcai Liu, Caishun Chen, Xinghua Qu, Ke Tang, and Yew-Soon Ong. Large language models as evolutionary optimizers. In 2024 IEEE Congress on Evolutionary Computation (CEC), pp. 1–8. IEEE, 2024.
657 658	Chris Lu, Cong Lu, Robert Tjarko Lange, Jakob Foerster, Jeff Clune, and David Ha. The ai scientist: Towards fully automated open-ended scientific discovery. <i>arXiv</i> , 2024.
659 660 661 662	Meredith Ringel Morris, Jascha Sohl-Dickstein, Noah Fiedel, Tris Warkentin, Allan Dafoe, Aleksan- dra Faust, Clement Farabet, and Shane Legg. Position: Levels of agi for operationalizing progress on the path to agi. In <i>ICML</i> , 2024.
663 664 665	Ted Moskovitz, Aaditya K Singh, DJ Strouse, Tuomas Sandholm, Ruslan Salakhutdinov, Anca Dra- gan, and Stephen Marcus McAleer. Confronting reward model overoptimization with constrained RLHF. In <i>ICLR</i> , 2024.
666 667	Jean-Baptiste Mouret and Jeff Clune. Illuminating search spaces by mapping elites. arXiv, 2015.
668 669 670 671 672	Eleni Nisioti, Claire Glanois, Elias Najarro, Andrew Dai, Elliot Meyerson, Joachim Winther Pedersen, Laetitia Teodorescu, Conor F Hayes, Shyam Sudhakaran, and Sebastian Risi. From text to life: On the reciprocal relationship between artificial life and large language models. In <i>Artificial Life</i> <i>Conference Proceedings 36</i> , volume 2024, pp. 39. MIT Press, 2024.
673 674 675	Norman Packard, Mark A Bedau, Alastair Channon, Takashi Ikegami, Steen Rasmussen, Kenneth O Stanley, and Tim Taylor. An overview of open-ended evolution: Editorial introduction to the open-ended evolution ii special issue. <i>Artificial life</i> , 25(2):93–103, 2019.
676 677 678 679	David Patterson, Joseph Gonzalez, Quoc Le, Chen Liang, Lluis-Miquel Munguia, Daniel Rothchild, David So, Maud Texier, and Jeff Dean. Carbon emissions and large neural network training. <i>arXiv</i> , 2021.
680 681	Eric Pfeiffer. Wired - the true cost of generative ai: Data centers and energy consumption. [LINK], 2023.
682 683 684	Alec Radford, Jong Wook Kim, Tao Xu, Greg Brockman, Christine McLeavey, and Ilya Sutskever. Robust speech recognition via large-scale weak supervision. In <i>ICML</i> , 2023.
685 686	Aditya Ramesh, Mikhail Pavlov, Gabriel Goh, Scott Gray, Chelsea Voss, Alec Radford, Mark Chen, and Ilya Sutskever. Zero-shot text-to-image generation. In <i>ICML</i> , 2021.
687 688	Jonathan Richens and Tom Everitt. Robust agents learn causal world models. ICLR, 2024.
689 690 691 692	Corban G Rivera, Olivia Lyons, Arielle Summitt, Ayman Fatima, Ji Pak, William Shao, Robert Chalmers, Aryeh Englander, Edward W Staley, I Wang, et al. Tanksworld: a multi-agent environment for ai safety research. <i>arXiv</i> , 2020.
693 694	Robin Rombach, Andreas Blattmann, Dominik Lorenz, Patrick Esser, and Björn Ommer. High-resolution image synthesis with latent diffusion models. In <i>CVPR</i> , 2022.
695 696 697 698 699	Mikayel Samvelyan, Sharath Chandra Raparthy, Andrei Lupu, Eric Hambro, Aram H. Markosyan, Manish Bhatt, Yuning Mao, Minqi Jiang, Jack Parker-Holder, Jakob Nicolaus Foerster, Tim Rock- täschel, and Roberta Raileanu. Rainbow teaming: Open-ended generation of diverse adversarial prompts. In <i>NeurIPS</i> , 2024.
700 701	Jimmy Secretan, Nicholas Beato, David B D Ambrosio, Adelein Rodriguez, Adam Campbell, and Kenneth O Stanley. Picbreeder: evolving pictures collaboratively online. In <i>the SIGCHI conference</i> <i>on human factors in computing systems</i> , 2008.

702 703 704	Rohin Shah, Vikrant Varma, Ramana Kumar, Mary Phuong, Victoria Krakovna, Jonathan Uesato, and Zac Kenton. Goal misgeneralization: Why correct specifications aren't enough for correct goals. <i>arXiv</i> , 2022.
705 706 707 708	Olivier Sigaud, Gianluca Baldassarre, Cédric Colas, Stephane Doncieux, Richard Duro, Pierre-Yves Oudeyer, Nicolas Perrin-Gilbert, and Vieri Giuliano Santucci. A definition of open-ended learning problems for goal-conditioned agents. <i>arXiv</i> , 2023.
709 710 711	Lisa Soros and Kenneth Stanley. Identifying necessary conditions for open-ended evolution through the artificial life world of chromaria. In <i>Artificial Life Conference Proceedings</i> , pp. 793–800. MIT Press, 2014.
712 713 714	Lisa B Soros, Joel Lehman, and Kenneth O Stanley. Open-endedness: The last grand challenge you've never heard of, 2017.
715	Kenneth O Stanley. Why open-endedness matters. Artificial life, 25(3):232-235, 2019.
716 717 718	Kenneth O Stanley and Joel Lehman. <i>Why greatness cannot be planned: The myth of the objective.</i> Springer, 2015.
719 720 721	Kenneth O Stanley and L Soros. The role of subjectivity in the evaluation of open-endedness. In <i>Presentation delivered in OEE2: The Second Workshop on Open-Ended Evolution, at ALIFE 2016</i> , 2016.
722 723 724	Yanan Sui, Alkis Gotovos, Joel Burdick, and Andreas Krause. Safe exploration for optimization with gaussian processes. In <i>ICML</i> , 2015.
725 726	K. Suyama. Probabilistic safety assessment and management of control laws. In <i>the 35th Annual Conference of IEEE Industrial Electronics</i> , 2005.
727 728 729	Open Ended Learning Team, Adam Stooke, Anuj Mahajan, Catarina Barros, Charlie Deck, Jakob Bauer, Jakub Sygnowski, Maja Trebacz, Max Jaderberg, Michael Mathieu, et al. Open-ended learning leads to generally capable agents. <i>arXiv</i> , 2021.
730 731 732	Matteo Turchetta, Felix Berkenkamp, and Andreas Krause. Safe exploration in finite markov decision processes with gaussian processes. <i>NeurIPS</i> , 2016.
733 734 735	Guanzhi Wang, Yuqi Xie, Yunfan Jiang, Ajay Mandlekar, Chaowei Xiao, Yuke Zhu, Linxi Fan, and Anima Anandkumar. Voyager: An open-ended embodied agent with large language models. <i>Transactions on Machine Learning Research</i> , 2024a.
736 737 738	Rui Wang, Joel Lehman, Jeff Clune, and Kenneth O Stanley. Paired open-ended trailblazer (poet): Endlessly generating increasingly complex and diverse learning environments and their solutions. <i>arXiv</i> , 2019.
739 740 741 742	Xuezhi Wang, Jason Wei, Dale Schuurmans, Quoc V Le, Ed H. Chi, Sharan Narang, Aakanksha Chowdhery, and Denny Zhou. Self-consistency improves chain of thought reasoning in language models. In <i>ICLR</i> , 2023.
743 744	Yongjie Wang, Tong Zhang, Xu Guo, and Zhiqi Shen. Gradient based feature attribution in explainable ai: A technical review, 2024b. URL https://arxiv.org/abs/2403.10415.
745 746 747	Jiaxin Wen, Ruiqi Zhong, Akbir Khan, Ethan Perez, Jacob Steinhardt, Minlie Huang, Samuel R Bowman, He He, and Shi Feng. Language models learn to mislead humans via rlhf. <i>arXiv</i> , 2024.
748 749 750	Marvin Zammit, Antonios Liapis, and Georgios N Yannakakis. Map-elites with transverse assessment for multimodal problems in creative domains. In <i>International Conference on Computational Intelligence in Music, Sound, Art and Design (Part of EvoStar)</i> . Springer, 2024.
751 752 753 754	Wojciech Zaremba, Evgenia Nitishinskaya, Boaz Barak, Stephanie Lin, Sam Toyer, Yaodong Yu, Rachel Dias, Eric Wallace, Kai Xiao, and Johannes Heidecke Amelia Glaese. Trading inference-time compute for adversarial robustness. 2025.
755	Han Zhang, Yu Lei, Lin Gui, Min Yang, Yulan He, Hui Wang, and Ruifeng Xu. Cppo: Continual learning for reinforcement learning with human feedback. In <i>ICLR</i> , 2024a.

756	Jenny Zhang, Joel Lehman, Kenneth Stanley, and Jeff Clune. OMNI: Open-endedness via models of
757	human notions of interestingness. In ICLR, 2024b.
758	-
759	
760	
761	
762	
763	
764	
765	
766	
767	
768	
769	
770	
771	
772	
773	
774	
775	
776	
777	
778	
779	
780	
781	
782	
783	
784	
785	
786	
787	
788	
789	
790	
791	
792	
793	
794	
795	
796	
797	
798	
799	
800	
801	
802	
803	
804	
805	
806	
807	
808	
809	